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Dynamic Models Problems and Solutions for Section 2.1 1.

Write the differential equations for the mechanical systems shown in Fig. 2.41. For (a) and (b), state whether you think the system will eventually de-cay so that it has no motion at all, given that there are non-zero initial conditions for both masses, and give a reason for your answer.

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The intent of this chapter is to expand on the design of control systems that will be implemented in a digital computer. The implementation leads to an average delay of half the sample period and to a phenomenon called aliasing, which need to be addressed in the controller design.

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Feedback Control of Dynamic Systems, Sixth Edition is perfect for practicing control engineers who wish to maintain their skills. This revision of a top-selling textbook on feedback control with the associated web site, FPE6e.com, provides greater instructor flexibility and student readability.

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in Chapter 8, which is a fundamental tool for understanding feedback systems. Using transfer functions, one can begin to analyze the stability of feedback systems using frequency domain analysis, including the ability to reason about the closed loop behavior of a system from its open loop characteristics. This is the subject of

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