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how linear state equations arise from the linearization of a nonlinear state equation about a nominal trajectory or equilibrium condition. This chapter also initiates our use of the MATLAB software package for computer-aided analysis and design of linear state-space control systems. Beginning here and continuing throughout the book, features of

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to motivate the introduction of state-space models. The state-space formalism provides a framework for computing linearized models from nonlinear differential equations, and sometimes relate the stability of the linearized model to the stability of a more complex nonlinear model. We finish with a discussion about possible issues that can arise when a linear controller is used in feedback

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