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The intent of this chapter is to expand on the design of control systems that will be implemented in a digital computer. The implementation leads to an average delay of half the sample period and to a phenomenon called aliasing, which need to be addressed in the controller design.

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Dynamic Models Problems and Solutions for Section 2.1 1.

Writethedifferential equations forthemechanicalsystemsshowninFig.2.41. For (a) and (b), state

whether you think the system will eventually de-cay so that it has no motion at all, given that there are non-zero initial conditions for both masses, and give a reason for your answer.

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Contents 11 9.4 EquivalentGainAnalysisUsing Frequency Response: DescribingFunctions 678 9.4.1 Stability AnalysisUsing Describing Functions 685 A 9.5 Analysisand DesignBased onStability 690 9.5.1 ThePhasePlane 690 9.5.2 LyapunovStability Analysis 697 9.5.3 TheCircle Criterion 703 9.6 Historical Perspective 710 Summary 711 ReviewQuestions 711 Problems 712 10 ControlSystemDesign: PrinciplesandCase

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