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In classical mechanics, the Euler force is the fictitious tangential force that appears when a non-uniformly rotating reference frame is used for analysis of motion and there is variation in the angular velocity of the reference frame's axes. The Euler acceleration (named for Leonhard Euler), also known as azimuthal acceleration or transverse acceleration is that part of the absolute ...

Euler force - Wikipedia

A rotating frame of reference is a special case of a non-inertial reference frame that is rotating relative to an inertial reference frame. An everyday example of a rotating reference frame is the surface of the Earth. (This article considers only frames rotating about a fixed axis. For more general rotations, see Euler angles

Rotating reference frame - Wikipedia

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^David Morin (2008). Introduction to classical mechanics: with problems and solutions. Cambridge University Press. p. 469. ISBN 0-521-87622-2.. ^ Grant R. Fowles and George L. Cassiday (1999). Analytical Mechanics, 6th ed..

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