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Robot Modeling and Control - www-cvr.ai.uiuc.edu

Robot modeling and control M.W. Spong, S. Hutchinson, and M. Vidyasagar: Robot Modeling and Control –Covers the course well. –Has chapters on "Computer vision" and "Vision based control". –Uses the same notation as we will use in the lectures. L. Sciavicco and B. Siciliano: Modelling and Control of Robot Manipulators (2nd edition)

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Robot Dynamics and Control Second Edition Mark W. Spong, Seth Hutchinson, and M. Vidyasagar January 28, 2004. 2. ... A robot is a reprogrammable multifunctional manipulator designed to move material, parts, ... 1974 — Cincinnati Milacron introduced the T3 robot with computer control

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