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where \mathbf{v} is a velocity vector for the bodies involved, \mathbf{J} is a "Jacobian" matrix with one row for every degree of freedom the joint removes from the system, and \mathbf{c} is a right hand side vector. At the next time step, a vector λ is calculated (of the same size as \mathbf{c}) such that the forces applied to the bodies to preserve the joint constraint are

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Aerodynamics - Wikipedia

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Manual - ODE

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The Global Positioning System (GPS), originally Navstar GPS, is a satellite-based radionavigation system owned by the United States government and operated by the United States Air Force. It is a global navigation satellite system that provides geolocation and time information to a GPS receiver anywhere on or near the Earth where there is an unobstructed line of sight to four or more GPS ...

Global Positioning System - Wikipedia

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Azure status history | Microsoft Azure

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