

## ***Solution Manual To Vector Mechanics For Engineers Statics 8th***

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**SOLUTION** Acceleration:  $a = kv^2$  Given  $v = 4 \text{ mm/s}$  at  $x = 0 \text{ mm}$ ,  $v = 16 \text{ mm/s}$  at  $x = 6 \text{ mm}$ ,  $v = 4 \text{ mm/s}$  at  $x = 12 \text{ mm}$ .  
 2.5 Separate variables  $k dx = v dv$  Integrate using  $x = 0 \text{ m}$  and  $v = 16 \text{ mm/s}$  as the lower limits of the integrals  $\int_{16}^v k dx = \int_{16}^v v dv$   
 $kx = \frac{1}{2}v^2 - \frac{1}{2}(16)^2$  Velocity and position: (1)  
 2 Now substitute  $v = 4 \text{ mm/s}$  and  $x = 6 \text{ mm}$  into (1) and solve for  $k$   
 $k(6) = \frac{1}{2}(4)^2 - \frac{1}{2}(16)^2$   
 $k = -0.0833 \text{ mm}^{-1} \text{ s}^2$   
 (a) Find velocity when  $x = 5 \text{ mm}$  using the equation (1) and the value of  $k$   
 $-0.0833(5) = \frac{1}{2}v^2 - \frac{1}{2}(16)^2$

**PROBLEM 2.1** Two forces are applied as shown to a hook. Determine graphically the magnitude and direction of their resultant using (a) the parallelogram law, (b) the triangle rule.

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Since one of the purposes of Chap. 3 is to familiarize students with the fundamental operations of vector algebra, students should be encouraged to solve all problems in this chapter (two-dimensional as well as three-dimensional) using the methods of vector algebra.

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