

Robot Modeling Spong Solution Manual

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1. Introduction. A manipulator (robot arm) is considered to be the most suitable tool for executing subsea intervention operations. Hence, unmanned underwater vehicles (UUVs) such as remotely operated vehicles (ROVs) and in some cases, autonomous underwater vehicles (AUVs) are equipped with one or more underwater manipulators.

Underwater manipulators: A review - ScienceDirect

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