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(a) All three systems • have memory because of an integrating action performed on the input, • are causal because (in each case) the output does not appear before the input, and • are time-invariant. (b) H₁ is noncausal because the output appears before the input.

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Here the input $x(t)$ is the transmitted signal and the output $y(t)$ is the received signal. Assume the message is represented in binary format and that a "1" is communicated in an interval of length T by transmitting the symbol $p(t)$ depicted in Fig. P2.41 (b) in the pertinent interval and that a "0" is communicated by transmitting $-p(t)$...

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