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ods and software engineering associated with digital signal processing. The aim has been to provide the reader with the mathematical methods required for signal analysis which are then used to develop models and algorithms for processing digital signals and finally to encourage the reader to design software solutions for Digital Signal Processing (DSP).

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Hence,  $\lambda = 4, -1$  and  $y_h(n) = c_1(4)^n + c_2(-1)^n$ . Since 4 is a characteristic root and the excitation is  $x(n) = 4^n u(n)$ , we assume a particular solution of the form  $y_p(n) = k n 4^n u(n)$ . Then  $k n 4^n u(n) - 3k(n-1)4^{n-1}u(n-1) - 4k(n-2)4^{n-2}u(n-2) = 4^n u(n) + 2(4)^{n-1}u(n-1)$ . For  $n = 2$ ,  $k(32-12) = 42 + 8 = 24 \rightarrow k = 6/5$ .

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Chapter 4 focuses on FIR filters and its purpose is to introduce two basic signal processing methods:

block-by-block processing and sample-by-sample processing. In the block processing part, we discuss various approaches to convolution, transient and steady-state behavior of filters, and real-time processing on a block-by-block basis using

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