Bijun LI

CONTACT INFORMATION

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RESEARCH INTERESTS

Simultaneous localization and mapping, 3D Reconstruction, Computer Vision:

Stereo vision, Object recognition, Augmented Reality.

Reinforcement learning, Deep learning Machine Learning:

EDUCATION

Tsinghua University, Beijing, China

Sep. 2015 - Present

M.E., Department of Automation

- Major in Control Engineering
- Minored in Big Data Capability Improvement Project
- Advisor: Prof. Kai ZHANG, Prof. Bokui CHEN
- Digital Image Processing and its Applications, Data Ming: Theory and Algorithms, Core Courses:

Pattern Recognition, Big Data Analytics, Big Data System, Stochastic Process, Multi-

Sensor Fusion Theory and Application.

Overall GPA: 3.3/4.0

Northwestern Polytechnical University, Xi'an, China

Sep. 2011 - Jul. 2015

B.E., School of Power and Energy

- Major in Automation
- Advisor: Prof. Sanmai SU
- Overall GPA: 3.25/4.0 (82.5/100), Junior GPA: 3.75/4.0 (87.5/100)

PROJECTS EXPERIENCE

♦ Obstacle avoidance of logistics terminal delivery robots. (in start-up phase)

Sep. 2017- Present

- Obtain the location information of obstacles through visual simultaneous localization and mapping.

♦ Motion control system for omnidirectional wheeled mobile robot.

Nov. 2016 - Apr. 2017

- Build the omnidirectional mobile platforms model of AGV.
- According to the performance of the stepper motor, the omnidirectional PID controller is designed by combining the logic control with the PID control.
- Omnidirectional linear controller is designed according to the movement state of AGV.

♦ Visual positioning system for automated guided vehicle.

July. 2016 - Nov. 2016

- Design landmark for visual positioning system.
- Determine the AGV direction by template matching.
- By improving the Prewitt operator, the direction of the edge line is obtained, which is contribute to improve the accuracy of measured deviation.

♦ Face gender recognition based on Convolutional Neural Networks.

Apr. 2016 - May. 2016

Mar. 2016 - Apr. 2016

♦ The shortest path problem based on genetic algorithm and its MATLAB implementation.

♦ Application of Support Vector Machine to forecast the direction of stock index.
 ♦ Design of Robust Controller for Aero-Engine.
 May. 2016 – Jun. 2016
 Aug. 2014 – Jun. 2015

- The linear matrix inequality (LMI) robust controller is designed based on the multi-variable linear model of aeroengine
- According to the idea of optimal controller design, the hybrid Sensitivity Robust Controller for aero-engine is designed
- Analysis of the advantages and disadvantages of two kinds of controllers mentioned above.

♦ The design of the public bicycle service system in Xi'an Jing Kai District.

May. 2014

- Solving multiple traveling salesmen problem (MTSP) through genetic algorithm.
- Under the constraint of input fund, a model of double objective programming was set for the optimum value of the number of bicycle rental points and the number of bicycles.

TEACHING EXPERIENCE

Teaching Assistant

• Fundamentals of applied information theory

Tsinghua-Berkeley Shenzhen

2014

PUBLICATIONS

- 1. **Bijun LI**, Mingyao QI, Kai ZHANG, and Bokui CHEN*, "Landmark-Based Visual Positioning System for Automatic Guided Vehicle." IEEE Cota International Conference of Transportation Professionals (**CICTP**). [Abstract Accepted].2017.
- 2. **Bijun LI**, Mingyao QI, Yuhan DONG, Kai ZHANG, Bokui CHEN*. "Visual Positioning System and Motion Control Method for Automated Guided Vehicles." The Institution of Engineering and Technology (**IET**). [Submitted]. 2017.

HONORS AND AWARDS

 "Qingfeng" Pre-scholarship, Tsinghua University 	Tsinghua University	2017
2. Big data promotion project certificate	Tsinghua University	2017
3. The Third Prize Scholarship	Graduate School at Shenzhen, Tsinghua University	2016
4. The First Prize Scholarship	Northwestern Polytechnical University	2014
5. The First prize in Mathematical Modeling Contest	Northwestern Polytechnical University	2014
6. The First prize in C language programming skills comp	etition Northwestern Polytechnical University	2014
7. The Second prize in Digital Electronic Experiment Skill	Contest Northwestern Polytechnical University	
8. National Encouragement Scholarship	Northwestern Polytechnical University	2013
9. Excellent Student Cadre	Northwestern Polytechnical University	2013
10. The Second Prize in Mathematical Modeling Contest	Northwestern Polytechnical University	2013
11. The Third Prize in T-shirt Design Contest	Northwestern Polytechnical University	2013

SKILLS

Programming

Matlab, C/C++, Python, LATEX, OpenCV, Linux.