



Soil Temperature and Moisture (and/or conductivity) sensor

Mod. SM.x



Manual



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1. Packaging and mounting

The sensor is placed in its original packaging already mounted.



RS485/ModBus version

Includes:

- SM
- Cable 5-10m

Analog output version

Includes:

- SM
- cable 5-10m



2. Functioning and features

The SM-2 soil moisture sensor is a very precise sensor and integrates **temperature and soil moisture measurements (and conductivity for SM.3 model) in a single instrument**. The operating principle is based on the FDR (Frequency Domain Reflectometry 70MHz) system for a precise measurement of the soil dielectric constant and therefore to measure the volume of soil moisture content. For the temperature part it uses a PT100 thermo-resistance sensor. Steel spikes are inserted into the surface of the ground or in the section for a quick measurement of the ground parameters. This method is the main one for this type of measurement. It can be left permanently left in the ground or even just to make quick and accurate measurements.

This sensor is built according to the WMO standards (World Meteorological Organization) and is available with output **0÷2Vdc, 4÷20mA or RS485/Modbus**

Measure	Humidity (VWC)	Temperature	Conductivity
Range	0-100% m ³	-40°C ÷ +80°C	0 – 20 mS/cm
Accuracy	± 3% (0-50%)	± 0.2°C	± 2% FS
Resolution (m ³ /m ³)	<0.002 m ³ /m ³	<0.05°C	<0.001mS/cm
Signal Output	4÷ 20mA, 0÷2V, ModBus RS485		ModBus RS485
Response time	< 1s		
Power supply and consumption	12÷24Vdc (max 12mA ÷ 60mA)		
Measure area	7-10cm ray around probe		
Made of	ABS		
Size	71 x 45 x 16mm (spikes Ø4 x 55mm) 5m cable		
Operative range	-30 ÷ +70°C		
Protection	IP68		
Spikes	Inox 316L		

Features written in the table can be modified. For updating always see the latest version of the datasheet.

3. Available electrical outputs and interfacing

The sensor is usually available with 3 different outputs (pre-configured in factory), that correspond to 3 order codes:

Wire	Analog output	Modbus RS485 output
Red	+ 12/24 Vdc	+ 12/24 Vdc
Black	GND common	GND common
Blue	Out temperature °C	N.C.
Brown	Out humidity Rh%	N.C.
Yellow	N.C.	RS485A
White	N.C.	RS485B
Green	N.C.	N.C.

The sensor is usually available with 3 different outputs (pre-configured in factory), that correspond to 3 order codes, respectively (named SM-X the sensor code):



SM.x – **A** : Sensor with voltage output 0-2Vdc according to the chosen range

$$[\text{moisture} = (\text{mV}/2000 \cdot 100\%)]$$

$$[\text{temperature} = (\text{mV}/2000 \cdot 120^\circ) - |40^\circ|]$$

$$[\text{conductivity} = (\text{mV}/2000 \cdot 20\text{mS})]$$

SM.x – **B** : Sensor with current output 4-20mA according to the chosen range

$$[\text{moisture} = (100\%) \cdot (\text{mA} - 4)/16]$$

$$[\text{temperature} = (120^\circ) \cdot (\text{mA} - 4)/16 - |40^\circ|]$$

$$[\text{conductivity} = (20\text{mS}) \cdot (\text{mA} - 4)/16]$$

SM.x – **C** : Sensor with digital output RS485 o ModBus- see below.

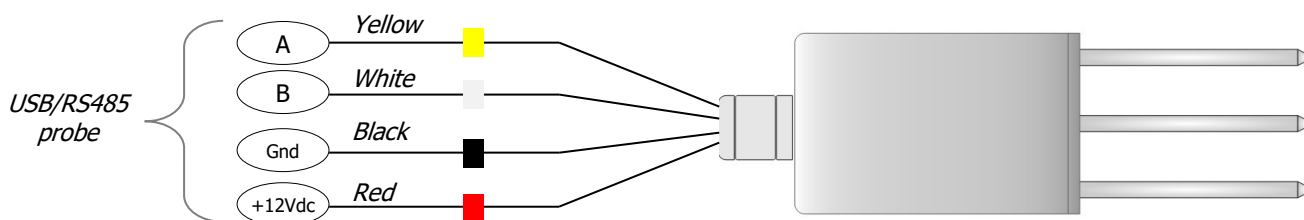
In case of sensors with digital output, consider this setting for **READING MODE** from sensor:

- **RS485-MODBUS Interface (Half duplex)**

We suggest to use a standard software like putty.exe (free software : [Download PuTTY - a free SSH and telnet client for Windows](#)) and set it for an RS485 communication, using an USB/RS485 interface:



- Connect the probe to an USB/RS485 interface as follows:



- Standard communication settings are:

baud rate: **9600**
parity: **N**
data bit: **8**
stop bit: **1**



- The sensor answers to ModBus RTU command only with **FUNCTION CODE 0x03** (Read Holding Register), on **the slave address is 01H (00H to FFHH)**; the protocol allows the reading of the measure value.
- The 04H Function Code

Example:

read the Temperature, Moisture and EC on: 0x01 address

Host scan command

01 04 00 00 00 03 B00B

Slave response

01 04 06 08 90 0E 93 02 4E D257

Temperature calculation:

$(0890)\text{Hex} < 0x8000 \rightarrow (0890)\text{Hex} = (2192)\text{Dec} \Rightarrow 2192/100 = 21,92^{\circ}\text{C}$

if the data $\geq 0x800$ (example 0xFF05) use this formula:

$0xFF05 - 0xFFFF - 0x01 = (65285)\text{Dec} - (65535)\text{Dec} - (1)\text{Dec} = (-251)\text{Dec} \Rightarrow -251/100 = -2,51^{\circ}\text{C}$

Moisture calculation:

$(0E93)\text{Hex} = (3731)\text{Dec} \Rightarrow 3731/100 = 37.31\%$

EC calculation:

$(024E)\text{Hex} = (590)\text{Dec} \Rightarrow 3731/1000 = 3,731\text{mS/cm}$

In case of sensors with digital output, consider this setting for **WRITING MODE** to the sensor:

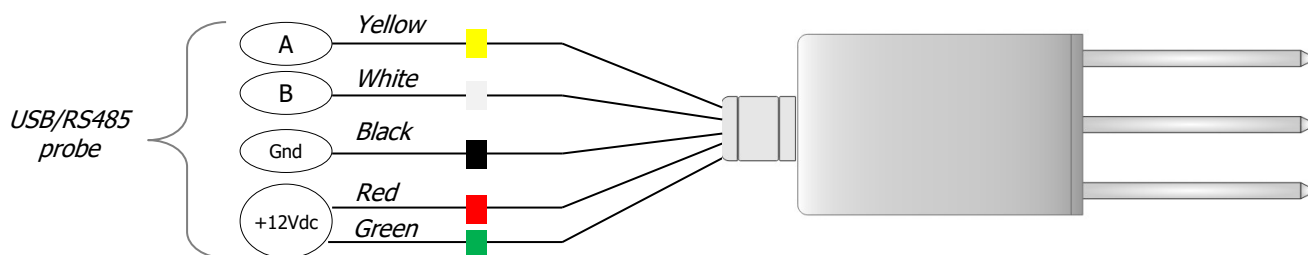
- **RS485-MODBUS Interface (Half duplex)**

We suggest to use a standard software like putty.exe (free software : [Download PuTTY - a free SSH and telnet client for Windows](#)) and set it for an RS485 communication, using an USB/RS485 interface:





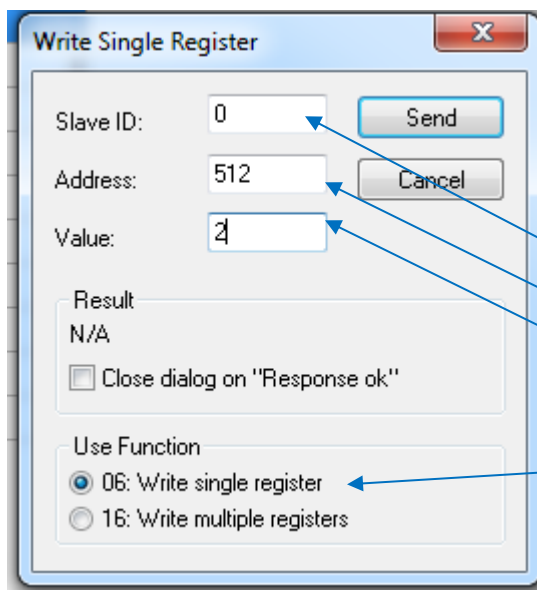
- Connect the probe to an USB/RS485 interface as follows:



- Standard communication settings are:
 baud rate: **9600**
 parity: **N**
 data bit: **8**
 stop bit: **1**

- **Change the slave address (only after the restart it will take effect)**

Set the putty mode into "write a single register"



Set:

- ID: 0
- Addr: 0x200 (**512**)
- New ID value
- Function: 06H

- Or use the the 06H Function Code

Example (change from 01 to 02H the ID):

Host set command

01 06 02 00 00 02 09B3

Slave response

01 06 02 00 00 02 09B3

NOTE: If you forget the address is possible to use the set mode to change address, using 00H as default address value.
After the ID change, disconnect the sensor and reconnect from the power supply



Table of register:

Parameters	Register Addr. HEX/DEC)	Data type	Modbus Function Code (DEC)	Range and Comments	Default Value
TEMPERATURE	0x0000/0	INT16 RO	3/4	-4000..8000 for -40,0°C to +80.0°C	N/A
VWC- Volumetric water content	0x0001/1	UINT16 RO	3/4	0-10000 for 0-100%	N/A
EC-Electrical Conductivity	0x0002/2	UINT16 RO	3/4	0-20000 for 0 to 20000µs/cm	N/A
SLAVE ADDRESS	0x0200/512	UINT16 R/W	3/6/16	0-255	1
BAUD RATE	0x0201/513	UINT16 R/W	3/6/16	0-6 equal to: 0: 1200bps 1: 2400bps 2: 4800bps 3: 9600bps 4: 19200bps 5: 38400bps	3: 9600bps

4. Calibration

Each instrument is calibrated and verified by comparison with a primary instrument with known behavior. This determines the dynamic of the sensor to be calibrated.

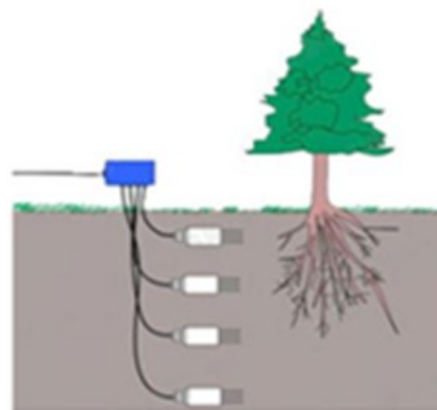
5. Cleaning and maintenance

None.

6. Installation

The installation can be made both horizontal or vertical position according to the area to be measured.

- Identify a measurement area where water does not stagnate. If the interested measure is superficial, insert the sensor vertically according to the depth of interest.
- If you want to make a measurement on several layers, the sensor or sensors must be positioned horizontally.
- Do not move the sensor after it has been positioned.
- When removing the sensor DO NOT pull it by the cable but dig with suitable tools until complete recovery
- If not in use, wash the sensor and store it in a dry and clean place, leaving it unplugged.





7. *Validity of certificates*

Unless otherwise indicated, the sensor warranty is 24 months from the manufacturing date, while the validity of the certification is 12 months from first use if stored in a depot suitably to the characteristics written on the datasheet.