University of California, Berkeley College of Engineering Computer Science Division — EECS

Spring 2020

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Midterm I Solutions

February 27th, 2020

CS162: Operating Systems and Systems Programming

| Your Name: | |
|--------------------------------|--|
| SID AND 162 Login (e.g. s042): | |
| TA Name: | |
| Discussion Section Time: | |

General Information:

This is a **closed book** exam. You are allowed 1 page of notes (both sides). You may use a calculator. You have 110 minutes to complete as much of the exam as possible. Make sure to read all of the questions first, as some of the questions are substantially more time consuming.

Write all of your answers directly on this paper. *Make your answers as concise as possible*. On programming questions, we will be looking for performance as well as correctness, so think through your answers carefully. If there is something about the questions that you believe is open to interpretation, please ask us about it!

| Problem | Possible | Score |
|---------|----------|-------|
| 1 | 18 | |
| 2 | 12 | |
| 3 | 19 | |
| 4 | 26 | |
| 5 | 15 | |
| 6 | 10 | |
| Total | 100 | |

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Problem 1: True/False [18 pts]

Please *EXPLAIN* your answer in TWO SENTENCES OR LESS (Answers longer than this may not get credit!). Also, answers without an explanation *GET NO CREDIT*.

Problem 1a[2pts]: Threads within the same process *can* share data (since they live in the same address space), but threads in different processes *cannot* share data.

□ True ☑ False

Explain: There are many ways for processes to share information including: (1) opening a shared file, (2) opening a pipe between them (before forking, for instance), (3) opening sockets between them (works even across machines), (4) setting up a shared-memory segment between them (we only mentioned this in the first couple of lectures, more later in the term.

Problem 1b[2pts]: Let n be the size of the virtual address space. On a fork() call, the OS does O(n) work to duplicate the parent's address space for the child process.

☑ True □ False

Explain: The OS copies all of the parent's page table entries (to perform copy-of-write), which mostly scales with the size of the parent's virtual address space. Note, however, that the question **does** say "virtual address space." So, if the virtual address space is very sparsely populated (most of the virtual space is not mapped to actual physical addresses), then multi-level page tables would not have a number of page table entries that scale directly with the size of the virtual address space. If you point this out, we will take "False" as an answer.

Problem 1c[2pts]: A zombie process is one that got hung up trying to access a disk which is experiencing permanent read errors.

□ True ☑ False

Explain: A zombie process is one that is not running anymore (has exited) but nas not yet relayed its exit code to its parent (i.e. the parent hasn't executed a "wait()" call on it yet). Thus, this process' PCB must wait around to hold the exit code.

Problem 1d[2pts]: The pipe() system call creates a file and returns file descriptors to read and write to it. Child processes created with fork() share file descriptors with their parents, so both parent and child now have access to this file through the pipe file descriptors.

□ True ☑ False

Explain: Pipes are implemented as buffers in memory, not as files. Some people pointed out that file descriptors are copied, not shared; we also gave credit for this.

Problem 1e[2pts]: Dual mode operation is an important mechanism for providing memory-level isolation between processes on the same machine.

☑ True □ False

Explain: As discussed in class, Dual-mode operation permits distinguishing between the kernel and user, thus allowing the hardware to restrict the ability to change the virtual memory mappings to the kernel (i.e. when code is running in kernel mode). This, in turn, means that user-code running in processes cannot change their own mappings to violate process isolation.

Problem 1f[2pts]: One of the first things that Pintos (running on an Intel processor) does after a user executes a system call is to replace the user's stack with the kernel's special "system call stack."

□ True ☑ False

Explain: There are at least two reasons that this is false. First, PintOS provides a kernel thread (and kernel stack) for every user thread. So, rather than a single, special "system call stack", PintOS starts running on the particular kernel stack associated with the calling user process. Second, with a modern Intel processor, the system call instruction causes the stack to be switched automatically, before entering PintOS. So, PintOS on an Intel processor doesn't have to manipulate the stack – this has already been done.

Problem 1g[2pts]: The test&set instruction consists of *two* independent operations: (1) read the value from memory and (2) replace it with the value "1". Thus, it must be used in a loop to protect against the case in which multiple threads execute test&set simultaneously and end up interleaving these two operations from different threads.

□ True ☑ False

Explain: The test&set instruction is atomic (that is the whole point), so there is no way for different test&set operations from different threads to interleave. If it were possible for this to happen, then test&set would be no better than a load followed by a store, and we would be back to the complexity of the "too much milk #3" solution from class...

Problem 1h[2pts]: When using a *Monitor*, a programmer must remember to release the lock before going to sleep (waiting) on a condition variable.

□ True ☑ False

Explain: The Monitor programming paradigm requires that programmers only sleep on condition variables inside the critical section, i.e. with the lock held. Thus, the programmer should never release the lock before waiting on a condition variable.

Problem 1i[2pts]: TCP/IP makes it possible for a server with IP address X and well-known port Y to simultaneously communicate with multiple remote clients without intermixing response streams.

Explain: Each unique connection is defined by a "5-tuple" of an [IP address:port] at the client side, an [IP address:port] at the server side, and a protocol (which is TCP in this case). The socket layer can distinguish between connections as long as one of these pieces of information are different. In the case of the server using TCP/IP with [IP address X:port Y], it could have many streams, as long as they have different client IP addresses, different client ports, or both.

Problem 2: Multiple Choice [12pts]

Problem 2a[2pts]: What needs to be saved and restored on a context switch between two threads in two different processes (*choose all that apply*):

| A: ⊻ | Computational registers (integer and floating point) |
|-------------|---|
| B: ☑ | The Page-table root pointer |
| C: □ | Buffered data in streams that have been opened with fopen() |
| D: □ | Contents of the file descriptor table |
| E: 🗹 | Stack pointer register |
| | a 2b[2pts]: What are some reasons that overuse of threads is bad (<i>i.e.</i> using too many threads me time)? (<i>choose all that apply</i>): |
| A: □ | The thread name-space becomes too large and fragmented, making it very difficult to efficiently track the current executing thread. |
| B: ☑ | The overhead of switching between too many threads can waste processor cycles such that the overhead outweighs actual computation (i.e. thrashing) |
| C: ☑ | Excessive threading can waste memory for stacks and TCBs |
| D: □ | Most schedulers have a scheduling cost (overhead) that is quadratic in the number threads, thus making the mechanism for choosing the next thread to run extremely expensive. |
| E: 🗹 | There might not be enough parallelism in the algorithm to justify the additional threads. |
| | a 2c[2pts]: What are the disadvantages of disabling interrupts to serialize access to a critical (<i>choose all that apply</i>): |
| A: ☑ | User code cannot utilize this technique for serializing access to critical sections. |
| В: □ | Interrupt controllers have a limited number of physical interrupt lines, thereby making it problematic to allocate them exclusively to critical sections. |
| C: ☑ | This technique would lock out other hardware interrupts, potentially causing critical events to be missed. |
| D: ☑ | This technique is a very coarse-grained method of serializing, yielding only one such lock for the whole machine. |
| E: 🗹 | This technique could not be used to enforce a critical section on a multiprocessor. |

| | n 2d[2pts]: In PintOS, every user thread is matched with a corresponding kernel thread te with a kernel stack). What is true about this arrangement (choose all that apply): |
|------------------------|---|
| A: ☑ | When the user-thread makes a system call that must block (e.g. a read to a file that must go to disk), the thread can be blocked at any time by putting the kernel thread (with its stack) to sleep and waking another kernel thread (with its stack) from the ready queue. |
| В: □ | The presence of the matched kernel thread makes the user thread run twice as fast as it would otherwise. |
| C: ☑ | The kernel thread helps to make sure that the page table is constructed properly so that the user thread's address space is protected from threads in other processes. |
| D: □ | While user code is running, the kernel thread manages cached data from the file system to make sure the most recent items are stored in the cache and ready when the user needs them. |
| E: 🗹 | The kernel gains safety because it does not have to rely on the correctness of the user's stack pointer register for correct behavior. |
| Probler apply): | n 2e[2pts]: Kernel mode differs from User mode in the following ways (choose all that |
| A: ☑ | The CPL (current processor level) is 0 in kernel mode and 3 in user mode for Intel processors |
| B: ☑ | In Kernel mode, additional instructions become available, such as those that modify page table registers and those that enable/disable interrupts. |
| C: □ | Specialized instructions for security-related operations (such as for cryptographic signatures) are only available from Kernel mode. |
| D: 🗹 | Control for I/O devices (such as the timer, or disk controllers) are only available from kernel mode |
| E: ☑ | Pages marked as Kernel-mode in the PTEs are only available in kernel mode. |
| Probler | n 2f[2pts]: Which of the following are true about semaphores (choose all that apply): |
| A: □ | Semaphores can be initialized to any 32-bit values in the range -2 ³¹ to 2 ³¹ -1 |
| B: ☑ | Semaphore.V() increments the value of the semaphore and wakes a sleeping thread if the value of the semaphore is ≥ 0 |
| C: □ | Semaphores cannot be used for locking. |
| D: □ | The interface for Semaphore.P() is specified in a way that prevents its implementation from busywaiting, even for a brief period of time. |
| E: 🗹 | The pure semaphore interface does not allow querying for the current value of the semaphore. |

Problem 3: Readers-Writers Access to Database [19 pts]

```
Reader() {
                                             Writer() {
   //First check self into system
                                                // First check self into system
   lock.acquire();
                                                lock.acquire();
   while ((AW + WW) > 0) {
                                                while ((AW + AR) > 0) {
      WR++;
      okToRead.wait(&lock);
                                                   okToWrite.wait(&lock);
      WR--;
                                                   WW--;
   }
                                                }
   AR++;
                                                AW++;
   lock.release();
                                                lock.release();
   // Perform actual read-only access
                                                // Perform actual read/write access
   AccessDatabase(ReadOnly);
                                                AccessDatabase(ReadWrite);
   // Now, check out of system
                                                // Now, check out of system
   lock.acquire();
                                                lock.acquire();
   AR--;
                                                AW--;
   if (AR == 0 \&\& WW > 0)
                                                if (WW > 0){
                                                   okToWrite.signal();
      okToWrite.signal();
   lock.release();
                                                } else if (WR > 0) {
}
                                                   okToRead.broadcast();
                                                lock.release();
```

Problem 3a[2pts]: Above, we show the Readers-Writers example given in class. It used two condition variables, one for waiting readers and one for waiting writers. Suppose that *all* of the following requests arrive in very short order (while R_1 and R_2 are still executing):

```
Incoming stream: R<sub>1</sub> R<sub>2</sub> W<sub>1</sub> R<sub>3</sub> W<sub>2</sub> W<sub>3</sub> R<sub>4</sub> R<sub>5</sub> R<sub>6</sub> W<sub>4</sub> R<sub>7</sub> W<sub>5</sub> W<sub>6</sub> R<sub>8</sub> R<sub>9</sub> W<sub>7</sub> R<sub>10</sub>
```

In what order would the above code process the above requests? If you have a group of requests that are equivalent (unordered), indicate this clearly by surrounding them with braces '{}'. You can assume that the wait queues for condition variables are FIFO in nature (i.e. signal() wakes up the oldest thread on the queue). Explain how you got your answer.

```
SOLN: Processed as follows: {R<sub>1</sub> R<sub>2</sub>} W<sub>1</sub>W<sub>2</sub> W<sub>3</sub> W<sub>4</sub> W<sub>5</sub> W<sub>6</sub> W<sub>7</sub> { R<sub>3</sub> R<sub>4</sub> R<sub>5</sub> R<sub>6</sub> R<sub>7</sub> R<sub>8</sub> R<sub>9</sub> R<sub>10</sub>}
```

Since this algorithm gives precedence to writes over reads, although the first two reads get to execute together and right away, the remaining reads are deferred until each write is processed (one at a time). After all writes are finished, then the reads execute as a group.

Problem 3b[2pts]: Let us define the *logical arrival order* by the order in which threads first acquire the monitor lock. Suppose that we wanted the results of reads and writes to the database to be the same as if they were processed one at a time – in their logical arrival order; for example, W₁ W₂ R₁ R₂ R₃ W₃ W₄ R₄ R₅ R₆ would be processed as W₁ W₂ {R₁ R₂ R₃} W₃ W₄ {R₄ R₅ R₆} regardless of the speed with which these requests arrive. Explain why the above algorithm does not satisfy this constraint.

Once it starts buffering items (i.e. putting requests to sleep on condition variables), the above algorithm does not keep track of the arrival order. Or, to say it another way, the above algorithm loses all ordering between buffered reads and buffered writes. Thus, it cannot guarantee that reads execute after earlier writes and before later writes (as defined by logical arrival order) unless it never buffers items (in which case it is not really doing anything at all).

Assume that our system uses Mesa scheduling and that condition variables have FIFO wait queues. Also assume that the only reason that a thread will wake up on a condition variable is because of a signal() or broadcast().

Below is a sketch of a solution that uses only two condition variables and that *does* return results as if requests were processed in logical arrival order. Rather than separate methods for Reader() and Writer(), we have a single method which takes a "NewType" variable (0 for read, 1 for write):

```
    Lock MonitorLock;

                                      // Methods: acquire(),release()

    Condition waitQueue, onDeckQueue; // Methods:wait(),signal(),broadcast()

 3. int Queued = 0, onDeck = 0;  // Counts of sleeping threads
4. int CurType = 0, NumAccessing = 0;// About current DataBase Accessors
                                      // type = 0 for read, 1 for write
 5. Accessor (int NewType) {
       /* Monitor to control entry so that one writer or multiple readers */
 6.
 7.
       MonitorLock.acquire();
       /* Missing wait condition */
8.
9.
       { Queued++;
10.
          waitQueue.wait();
          Queued--;
11.
12.
       }
       /* Missing wait condition */
13.
       { onDeck++;
14.
          onDeckQueue.wait();
15.
          onDeck--;
16.
17.
       }
       /* Missing code */
18.
19.
       MonitorLock.release();
       // Perform actual data access
20.
       AccessDatabase(NewType);
21.
22.
       /* Missing code */
23. }
```

The waitQueue condition variable keeps unexamined requests in FIFO order. The onDeckQueue keeps a single request that is currently incompatible with requests that are executing. We want to allow as many parallel requests to the database as possible, subject to the constraint of obeying logical arrival order. Here, logical arrival order is defined by the order in which requests acquire the lock at line #7.

Problem 3c[2pts]: Explain why you might not want to use a "while()" statement in Line #8 – despite the fact that the system has Mesa scheduling:

Because a while loop will potentially reorder requests on the waitQueue condition variable—and we want to keep requests in their original logical arrival order. Thus whatever we do, we do not want to execute waitQueue.wait() more than once per thread.

Problem 3d[2pts]: What is the missing code in Line #8? *Hint: it is a single "if" statement.*

If anyone in the system is waiting, then we want to wait so that we don't get ahead of others (i.e. so that we preserve the logical arrival order):

```
if (Queued + onDeck > 0) // Wait unless no one waiting to be evaluated
```

Problem 3e[2pts]: What is the missing code in Line #13? This should be a single line of code.

If the current request is incompatible with the set of executing requests, then we have to wait:

```
while ((NumAccessing > 0) && (NewType == 1 || CurType == 1))
```

You could also use an "if" here, but then you would need to conditionalize the "onDeckQueue.signal()" statement in (3g).

Problem 3f[2pts]: What is the missing code in Line #18? You should not have more than three (3) actual lines of code.

By the time that a thread has fallen through to line #18, we know that it will access the database, and that it represents the new access type. Further, in case this thread came from the onDeckQueue, we should see if someone waiting in the waitQueue can make forward progress:

```
NumAccessing++; // Have another thread accessing the database
CurType = NewType; // In case we are first of new group
waitQueue.signal(); // Wake up next thread (if they exist)
```

Problem 3g[3pts]: What is the missing code in Line #22? You should not have more than five (5) actual lines of code.

```
MonitorLock.acquire();
NumAccessing--;  // One less accessing
onDeckQueue.signal();  // Wake up someone stalled on conflict
MonitorLock.release();
```

If you use an "if" in (3e), then need to conditionalize your signaling of the onDeskQueue in this way (making sure there are no additional accessors):

```
if(NumAccessing ==0)
  onDeckQueue.signal(); // Wake up someone stalled on conflict
```

Problem 3h[4pts]: Suppose that condition variables did not have FIFO ordered wait queues. What changes would you have to make to your code? Be explicit (you should not need more than 6 new or changed lines). *Hint: consider assigning a sequentially increasing ID to each thread.*

New variables to track sequential IDs added to Line #4:

```
int HeadID = 0, TailID = 0; // NEW: "Take a number"
```

New code for Line #8 (one new line, one changed line):

```
int MyCurrentID = TailID++; // NEW: Next logical ID to new request
while (MyCurrentID != HeadID) // CHANGED: Threads exit queue in order.
```

Finally, code for Line #18 is slightly different (only added 1 line, changed 1 line):

```
NumAccessing++; // (UNCHANGED LINE)
CurType = NewType; // (UNCHANGED LINE)
HeadID++; // NEW: Next in-order thread can wake
waitQueue.broadcast(); // CHANGED: Wake up next thread in order
// (All wake, but only HeadID advance)
```

See next page for some notes on the grading of 3h:

Grading notes for 3h: We accepted non-code answers for this question, HOWEVER, we did not just give credit for copying the hint. Further, although using a new data structure (such as a queue) and iterating to choose a thread to signal might be feasible, very few people who mentioned this actually did it correctly.

Problem 4: Pintos Word Count System Calls [26pts]

In this question you will partially implement a word count feature for Pintos! Word count is meant to be a feature for user programs. Here's how it works.

There are 3 syscall handler functions with the following signatures:

```
void wc_open(char *word); // Open a word for the given thread
int wc_inc(); // Increment opened-word's count return result
void wc_close(); // Close the current word
```

The count for a word is shared between all user programs. A user must open a word to get access to it. Each program must open a word before it can increment it and a program can only have one word open. When a word is incremented, the count is incremented for all user programs on the system. When a process exits, it should implicitly close the word. If all processes have closed the word, then it should no longer use any system resources.

Before we start, we'll provide you with a few modifications to the Pintos TCB.

```
struct thread {
    ...
#ifdef USERPROG
    /* You can assume init_thread will initialize this to null */
    word_count_t *wc;
#endif
    unsigned magic;
}
```

Remember, word counts are shared across programs. We will also use 2 global variables which are provided below. You may assume they are initialized in syscall_init.

Problem 4a[4pts]: We'll start by defining our word count structure. There will be one of these per word that is currently being counted. Define the word-count structure (shown below). Keep in mind that each word_count structure could be open (and shared) by multiple threads at once.

Note: the count_lock is important to have on every word_count_t structure to allow for fine-grained parallelism as multiple threads access words (otherwise, using word_count_list_lock on everything would cause serious blocking, since only one thread could be incrementing at a time).

Problem 4b[2pts]: Consider the following skeleton for the system call handler:

```
static void syscall_handler (struct intr_frame *f UNUSED) {
   uint32_t* args = ((uint32_t*) f->esp);
   switch (args[0]) {
   case SYS_EXIT:
     thread_exit ();
     break;
   case SYS WC OPEN: // open new word
     validate_wc_open(args);
     wc_open(args[1]);
     break;
   case SYS WC INC: // increment opened word's count, return new count
     f->eax = wc inc(); // Return value to user
     break;
   case SYS_WC_CLOSE:// close word
     wc close();
     break;
   . . .
   }
```

Fill in the blank, above, to finish the increment system call handler.

Problem 4c[2pts]: Assuming that the above syscall_handler() is written correctly, which of the following MUST be true when the SYS_WC_OPEN case begins to execute? (*choose all that apply*):

- A: ☑ The syscall number is valid
- B: \square The pointer to the word is valid
- $C: \square$ The array of characters that constitutes the word is valid
- D: The syscall number is stored on the user stack

Problem 4d[4pts]: Now write the validate_wc_open() function. Assume you have access to a function void validate_region(void *ptr, size_t len) which correctly validates a fixed size region of memory. You should be able to write this function in six(6) or less lines.

```
void validate_wc_open(uint32_t *args) {
    // Validate storage for actual arguments
    validate_region(args, sizeof(int) + sizeof(char*));

    // Validate word string (we can't ask for length until validated)
    char *str = (char*) &args[1];
    do {
       validate_region(str, 1);
    } while (*(str++) != '\0');
}
```

Problem 4e[4pts]: Define a helper function to aid in opening a word. This function should attempt to find a pre-existing word_count_t structure (if it exists) or allocate a new one. Remember, word count structures are shared across programs. (Hint: this function doesn't need to be thread safe):

list_push_front(list, &wc->elem);
return wc;
}

Problem 4f[3pts]: Now, please write wc_open(), given your implementation of find_or_add(). This function *does* need to be thread-safe. You should be able to write this function in six(6) lines or less. Hint: Don't forget synchronization!

Problem 4g[3pts]: Next, write wc_inc(), keeping in mind that this function must be thread safe. You should be able to write this function in six (6) lines or less. Hint: Don't forget synchronization!

```
int wc_inc() {
   ASSERT(thread_current()->wc);

   word_count_t *wc = thread_current()->wc;
   lock_acquire(&wc->count_lock);  // Get access to count
   int my_count = ++wc->count;  // Increment and save my result
   lock_release(&wc->count_lock);
   return my_count;
}
```

Notes: (1) By saving count inside critical section, we return the value ocount at time that we incremented. This is not strictly part of the specification. You could just "return wc->count;" Also, (2) We acquire lock inside structure only to update count. The reference counter is considered locked when we lock the global list instead.

Problem 4h[4pts]: Finally, write wc_close(), keeping in mind that this function must be thread safe. You should be able to write this function in eight (8 lines or less). Remember that a word_count_t structure is deallocated when the last thread closes it. Hint: Don't forget synchronization!

Note: we are treating the closing brace as a content-less line. Alternatively, could avoid the assignment of wc and make the lines a lot more verbose to fit everything into 8 lines...

Problem 5: Scheduling Potpourri [15pts]

Problem 5a[3pts]: Prove that SRTF is the optimal algorithm to reduce average response time (wait time):

Consider a schedule of jobs, including A and B for which A is run before B, but for which A has a longer runtime than B. If we swap A and B, then the total wait time for each of the jobs inbetween A and B would be reduced by T(A) - T(B). Further, the total wait time for A and B together would also be reduced by T(A) - T(B). Consequently, swapping jobs to put a shorter one in front of a longer one would decrease total wait time. SRTF is the result of performing this swapping until you cannot do it any more, resulting in a total wait time that is smaller than the original schedule. Consequently SRTF is optimal with respect to total wait time (and thus average wait time).

Problem 5b[2pts]: Which scheduling algorithm maximizes throughput and why?

FCFS/FIFO maximizes throughput: Each thread runs to completion (or to its next I/O operation), maximizing the efficiency of the pipeline (cache state, speculative execution state, branch prediction, etc) by letting each job run for an extended period. FCFS/FIFO also minimizes overhead of scheduling (in the kernel) by minimizing number of context switches.

Problem 5c[2pts]: Define Hyperthreading and explain why it might improve the performance of two concurrently executing threads over that of one thread.

Hyperthreading (or Simultaneous Multithreading) is a hardware technique that allows multiple threads to execute within a single pipeline simultaneously. This technique places multiple copies of registers and program counters into the processor, thus allowing multiple threads to be loaded into the processor at the same time. Hyperthreading will fill wasted pipeline slots from one thread with operations from another thread, thus ostensibly getting more done with the same physical pipeline resources. Consequently, one might view these operations from the second thread as occurring "for free", i.e. that more is getting done (higher performance) than one might get with a single thread on a non-hyperthreaded processor.

| | 5d[2pts]: Which of the following scheduling algorithms can suffer from starvation? <i>all that apply):</i> |
|-------------|---|
| A: □ | FIFO Scheduler |
| B: ☑ | Shortest Remaining Time First (SRTF) Scheduler |
| C: □ | Lottery Scheduler |
| D: □ | Round Robin Scheduler |
| E: 🗹 | Priority Scheduler |

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Problem 5e[6pts]: Suppose we have the following set of processes, with their respective CPU burst times and priorities (here, processes with a higher priority value have higher priority).

| Process ID | Arrival Time | CPU Burst (running) Time | Priority |
|------------|--------------|--------------------------|----------|
| A | 0 | 3 | 4 |
| В | 1 | 1 | 2 |
| С | 3 | 5 | 5 |
| D | 6 | 2 | 6 |
| Е | 8 | 2 | 1 |

For each of the three scheduling algorithms, fill in the table below with the processes that are running on the CPU at each time tick. Assume the following:

- The time quantum for RR is 1 clock tick and when RR quantum expires, the currently running thread is added to the end of the ready list before any newly arriving threads.
- Assume that context switch overhead is 0, and that new processes are available for scheduling as soon as they arrive.

| Time | RR | SRTF | Priority |
|----------------------|-------------------|-------------------|-------------------|
| 0 | A | A | A |
| 1 | A | В | \boldsymbol{A} |
| 2 | В | A | A |
| 3 | A | A | С |
| 4 | С | С | С |
| 5 | С | С | С |
| 6 | С | D | D |
| 7 | D | D | D |
| 8 | С | E | С |
| 9 | D | E | C |
| 10 | E | C | В |
| 11 | C | C | E |
| 12 | E | C | E |
| Average Wait Time | (1+1+4+2+3)/5=2.2 | (1+0+5+0+0)/5=1.2 | (0+9+2+0+3)/5=2.8 |

Problem 6: FileSystems/Sockets API [10pts]

You have been tasked with implementing the Central Galactic Floopy Network (CGFN), to send happy messages to clients (to ensure that clients remain satisfied with their service and leave high reviews). The CGFN trial implementation is simple. It works as a basic TCP/IP network server running on port 555. When clients send requests, the server is guaranteed to accept the requests. The server then writes back a random happy phrase to the client and closes the connection, leaving a happy client.

As their principle engineer, the CGFC requests you to implement the trial run for them. They have already tested a random happy message generator with signature:

```
char *get_happy_message(); // return statically allocated string
```

This function returns a statically allocated message (which does not need to be freed).

Problem 6a[5pts]: Assume no failures occur in any function calls and that reads and writes to sockets will always result in the entire message being received or sent. Complete the missing code in the following (you should only write one statement of code per line):

```
struct addrinfo *setup_address(char *server_name, char *port_name) {
  struct addrinfo *server;
  struct addrinfo hints;
  memset(&hints, 0, sizeof(hints));
  hints.ai family = AF UNSPEC;
  hints.ai socktype = SOCK STREAM;
  hints.ai flags = AI PASSIVE;
  getaddrinfo(server name, port name, &hints, &server);
  return server;
}
int main() {
  struct addrinfo *server = setup address(NULL, "555");
  struct sockaddr *address = server->ai addr;
  socklen t addrlen = server->ai addrlen;
  int serverfd =
     socket(server->ai_family, server->ai_socktype, server->ai_protocol);
  bind(<u>serverfd, address, addrlen</u>);
  listen(<u>serverfd</u>,1024);
  while (1) {
     char *happy = <u>get happy message()</u>;
     int clientfd = accept(serverfd, address, &addrlen ;
     write(clientfd, happy, strlen(happy)+1) ;
     close(clientfd);
  close(serverfd);
  return 0;
}
```

Problem 6b[5pts]: To test if the trial implementation works, the CGFC wants trial clients to save the happy message they received in an existing text file in the local file called "/messages/happy message.txt". Assume that the entire contents of a single happy message is no larger than 1000 bytes (including null terminator).

Complete the following client program to contact the floopy server ("galactic.floopy.net") on port 555. Assume no failures occur in any function calls and that reads and writes to sockets will always result in the entire message being received or sent.

You should only write one statement per line.

}

```
#define BUFFER_SIZE <u>1000</u>
int main() {
  char *server_name = "qalactic.floopy.net"
  struct addrinfo *server = setup_address(server_name, "555");
  struct sockaddr *address = server->ai addr;
  socklen_t addrlen = server->ai_addrlen;
  int newsockfd =
     socket(server->ai_family, server->ai_socktype, server->ai_protocol);
  connect(newsockfd, address, addrlen);
  send(newsockfd, NULL, NULL, 0);
  // Read happy message from server
  char readbuffer[BUFFER SIZE] ;
  size t bytesread = read(newsockfd, readbuffer, BUFFER SIZE) ;
  // Write happy message to disk
  int wfd = open("/messages/happy message.txt", O WRONLY|O APPEND);
  write(wfd, readbuffer, bytesread)
  <u>close(wfd)</u>
  close(newsockfd);
  return 0;
```

[Function Signature Cheat Sheet]

```
int pthread create(pthread t *thread, const pthread attr t *attr,
void *(*start_routine) (void *), void *arg);
int pthread_join(pthread_t thread, void **retval);
int pthread_mutex_init(pthread_mutex_t *restrict mutex,
const pthread_mutexattr_t *restrict attr);
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread mutex unlock(pthread mutex t *mutex);
int sem init(sem t *sem, int pshared, unsigned int value);
int sem_post(sem_t *sem);
int sem_wait(sem_t *sem);
pid_t fork(void);
pid_t wait(int *status);
pid_t waitpid(pid_t pid, int *status, int options);
int execv(const char *path, char *const argv[]);
FILE *fopen(const char *path, const char *mode);
FILE *fdopen(int fd, const char *mode);
size_t fread(void *ptr, size_t size, size_t nmemb, FILE *stream);
size_t fwrite(const void *ptr, size_t size, size_t nmemb, FILE *stream);
int fclose(FILE *stream);
int socket(int domain, int type, int protocol);
int bind(int sockfd, struct sockaddr *addr, socklen t addrlen);
int listen(int sockfd, int backlog);
int accept(int sockfd, structure sockaddr *addr, socklen_t *addrlen);
int connect(int sockfd, struct sockaddr *addr, socklen t addrlen);
ssize_t send(int sockfd, const void *buf, size_t len, int flags);
/******************** Low-Level I/O **********************/
int open(const char *pathname, int flags);
ssize t read(int fd, void *buf, size t count);
ssize_t write(int fd, const void *buf, size_t count);
int dup(int oldfd);
int dup2(int oldfd, int newfd);
int pipe(int pipefd[2]);
int close(int fd);
```

[Function Signature Cheat Sheet (con't)]

```
void list init(struct list *list);
struct list elem *list head(struct list *list)
struct list_elem *list_tail(struct list *list)
struct list_elem *list_begin(struct list *list);
struct list_elem *list_next(struct list_elem *elem);
struct list_elem *list_end(struct list *list);
struct list elem *list remove(struct list elem *elem);
bool list empty(struct list *list);
#define list_entry(LIST_ELEM, STRUCT, MEMBER) ...
void list_insert(struct list_elem *before, struct list_elem *elem);
void list_push_front(struct list *list, struct list_elem *elem);
void list push back(struct list *list, struct list elem *elem);
void sema_init(struct semaphore *sema, unsigned value);
void sema down(struct semaphore *sema);
void sema_up(struct semaphore *sema);
void lock_init(struct lock *lock);
void lock acquire(struct lock *lock);
void lock_release(struct lock *lock);
```

[Scratch Page: Do not put answers here!]

[Scratch Page: Do not put answers here!]