

Midterm Answers – CS 343 Fall 2019

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These are not the only answers that are acceptable, but these answers come from the notes, assignments, or lectures.

1. (a) **5 marks**

```
1  bool flag = false;
1  while ( ! flag ) {
    S1;
1    if ( C ) flag = true;
1    else S2;
    }
1  if ( flag ) E;
```

(b) **1 mark** Code in the **else** clause is logically part of the loop body not part of the loop exit.

(c) **1 mark** Because flag variables can be set/reset/tested at arbitrary locations in a program.

(d) **1 mark** New nested control structures can be added without having to change existing code.

(e) **2 marks**

i. Cannot create a loop.

ii. Cannot branch into a control structure.

(f) **1 mark** To perform static multi-level exit when labelled break and continue are unavailable.

(g) **3 marks** `uNoCtor` allocates a dynamically-sized array on the stack without running the default constructor. Subsequently, any constructor with arguments can be run on the each array element. `unique_ptr` allocates the array in the heap.

(h) **2 marks** The $O(N)$ search for termination eliminates testing return codes in unwound routines. The $O(N)$ search for resumption eliminates passing fixup routines.

(i) **2 marks** Destructors are called during exception propagation, and C++ does not allow another exception to be raised during propagation.
A destruction can conditionally raise an exception only if it is not invoked during propagation (`uncaught_exceptions`).

(j) **1 mark** The exit from the resumption handle changes the dynamic return to a static return.

(k) **1 mark** A coroutine/task needs to execute to a safe point (e.g., **try**) so it can allow propagation of non-local exceptions.

2. (a) i. **1 mark** coroutine's starter

ii. **2 marks** provides guaranteed path for control to return to the program main

(b) **1 mark** To proceed into an initial state before the first member is called.

(c) **2 marks** last resumer, joiner

3. (a) **2 marks** A *concurrent bottleneck* is a hardware or software restriction that slows down or stops concurrent speedup.
- (b) **1 mark** The *scheduler* manages the ready queue and placement of tasks/processes on CPUs.
- (c) **2 marks** Speedup starts linear as more CPUs are added but then hits a bottleneck and begins to level out and/or drop.
- (d) **2 marks** implicit, explicit, implicit, explicit
- (e) **4 marks** Two threads arrive simultaneously. Both declare their intent to enter at lines 1. Then both wait at line 2 for the other thread to retract its intent, which cannot happen (empty loop bodies). livelock or indefinite postponement
- (f) **2 marks** RW-safe means an algorithm works even if simultaneous writes to the same location scramble the bits or simultaneous read during a write to the same location sees the bits flicker.
- (g) **1 mark** A lock is needed for each *independent* critical section.
- (h) **1 mark** The ability to *read* and *write* atomically.
- (i) **1 mark** *Barging* occurs when waiting threads are scheduled (overtaken) by arriving threads.
- (j) **2 marks** Task tells scheduler to release current timeslice and do not be put on the ready queue, and atomically release the lock.

4. 16 marks

```

    _Coroutine Bead {
        unsigned int id;
        Bead * part;

        void main() {
1            bool zombied = false;

1            suspend();
1            try {
1                _Enable {
1                    for ( ;; ) {
1                        clasp.lock( prng() );
1                        part->next();
1                    } // for
                } // _Enable
1            } _CatchResume( Zombie & ) {
1                zombied = true;
1            } catch( Won & ) {
1                cout << (zombied ? "Zombie cannot win " : "Won") << id << endl;
            } // try
        } // main
    public:
        Bead( unsigned int id, Bead * partner ) : id{ id }, part{ partner } { resume(); };
        void next() { resume(); }
}; // Beads

int main() {
    enum { N = 5 };
1    uNoCtor<Bead> beads[N];

1    for ( unsigned int b = 0; b < N - 1; b += 1 ) {
1        beads[b].ctor( b, &beads[b + 1] );
    } // for
1    beads[N - 1].ctor( N - 1, &beads[0] );

// 1    for ( int b = 0; b < N; b += 1 ) {
// 2        beads[b].ctor( b, &beads[(b + 1) % N] );
//
1    beads[0]->next();
} // main

```

-5 if not using coroutine state.

5. (a) **1 mark** The Halfway and manager threads must communicate during their lifetime or manager must stop workers part way to completion.

(b) **24 marks**

```

    _Actor Manager {
        enum { N = 10 };
        uNoCtor<Halfway> halfway[N];
        unsigned int completers = 0;
        bool completed[N] = {}; // set to false

        Allocation receive( Message & msg ) {
            Case ( Progress, msg ) {
                if ( prng( 5 ) == 0 ) msg_d->complWork -= 50;

                // Told to stop but work still has more work to do,
                // i.e, worker still processing start messages.
                if ( ! completed[msg_d->id] && msg_d->complWork < 1000 ) {
                    *halfway[msg_d->id] | uActor::startMsg;
                } else {
                    // If not told to stop already, i.e., receive spurious progress messages,
                    // then reply with complete message.
                    if ( ! completed[msg_d->id] ) {
                        *halfway[msg_d->id] | complete;
                        completers += 1;
                        completed[msg_d->id] = true;
                    } // if
                    if ( completers >= N / 2 ) {
                        for ( unsigned int w = 0; w < N; w += 1 ) {
                            if ( ! completed[w] ) {
                                completed[w] = true;
                                *halfway[w] | uActor::stopMsg;
                            } // if
                        } // for
                    } // if
                    // Cannot finish until all actors have been told to complete or stop.
                    if ( completers == N ) return Finished;
                } // if
            } // case
            return Nodelete;
        } // Manager::receive

    public:
        Manager() {
            for ( unsigned int w = 0; w < N; w += 1 ) {
                halfway[w].ctor( w, *this );
                *halfway[w] | uActor::startMsg;
            } // for
        } // Manager::Manager
    }; // Manager

    int main() {
        uActor::start();
        Manager manager;
        uActor::stop();
    } // main

```

(c) 25 marks

```

    _Task Halfway {
        void main() {
1           try {
1               _Enable {
1                   for ( unsigned int complWork = 100;; complWork += 100 ) {
1                       _Resume Progress( id, complWork, spin ) _At pgmMain;
1                       while ( spin ) yield();                // busy wait
1                       spin = true;
1                   }
1               }
1           } catch( Complete & ) {
1           } catch( Stop & ) {
1           } // try
1       } // main
    public:
        Halfway( unsigned int id, uBaseTask & pgmMain ) : id{ id }, pgmMain{ pgmMain } {};
    }; // Halfway

    int main() {
        enum { N = 10 };
1       uNoCtor<Halfway> workers[N];
        {
1           for ( unsigned int w = 0; w < N; w += 1 )           // create tasks
1               workers[w].ctor( w, uThisTask() );
1
1           unsigned int completers = 0;
1           bool completed[N] = {};                             // set to false
1           try {
1               _Enable {
1                   for ( ; completers < N / 2; ) {
1                       uThisTask().yield();                     // busy wait
1                   }
1               }
1           } _CatchResume( Progress & p ) {
1               if ( prng( 5 ) == 0 ) p.complWork -= 50;
1               if ( p.complWork >= 1000 ) {
1                   completers += 1;
1                   completed[p.id] = true;
1                   _Resume Complete() _At (uBaseCoroutine &)workers[p.id];
1               }
1               p.spin = false;                                   // restart worker
1           }
1           for ( unsigned int w = 0; w < N; w += 1 )
1               if ( ! completed[w] ) _Resume Stop() _At (uBaseCoroutine &)workers[w];
1       }
    } // main

```