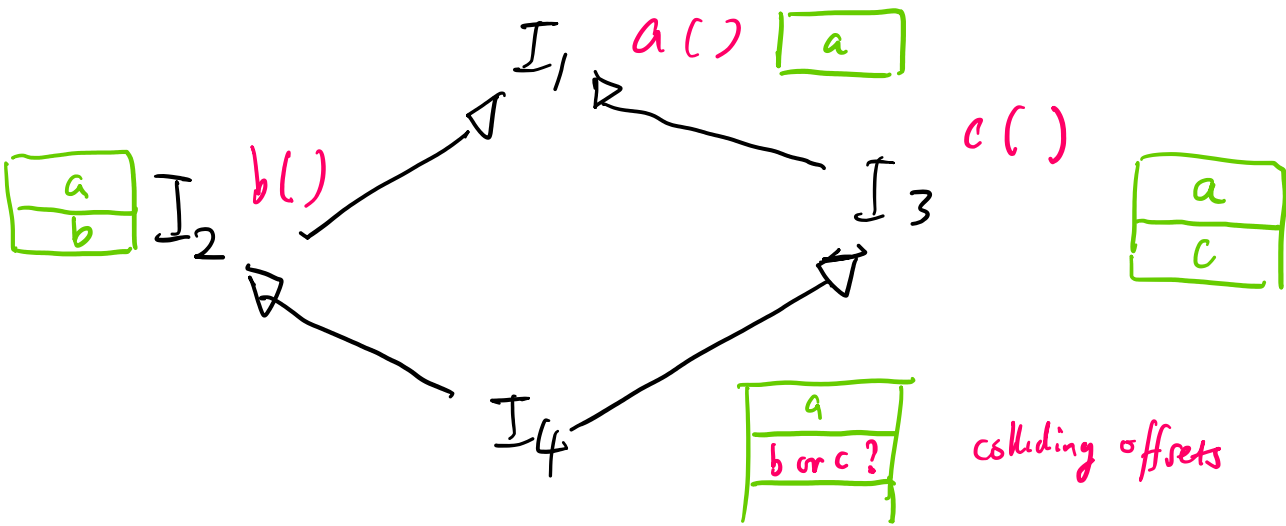


Compiling Interface Method Dispatch



Idea #1. Assign indices to not collide.

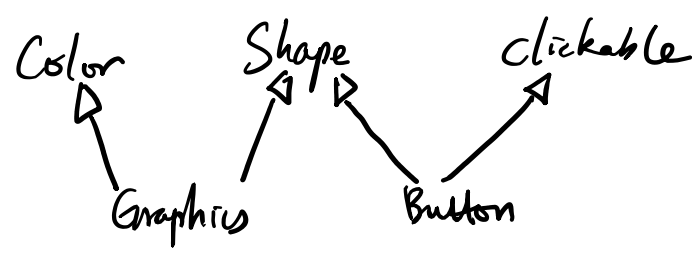
```
interface Color {
    RGB rgb()
    HSV hsv()
}

interface Clickable {
    void click()
}

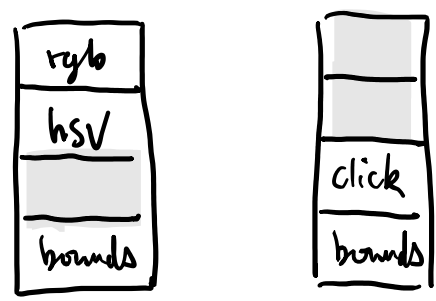
interface Shape {
    Box bounds
}
```

no separate compilation

```
class Graphics implements Shape, Colour { ... }
class Button ~ ~ ~ Shape, Clickable { .. }
```

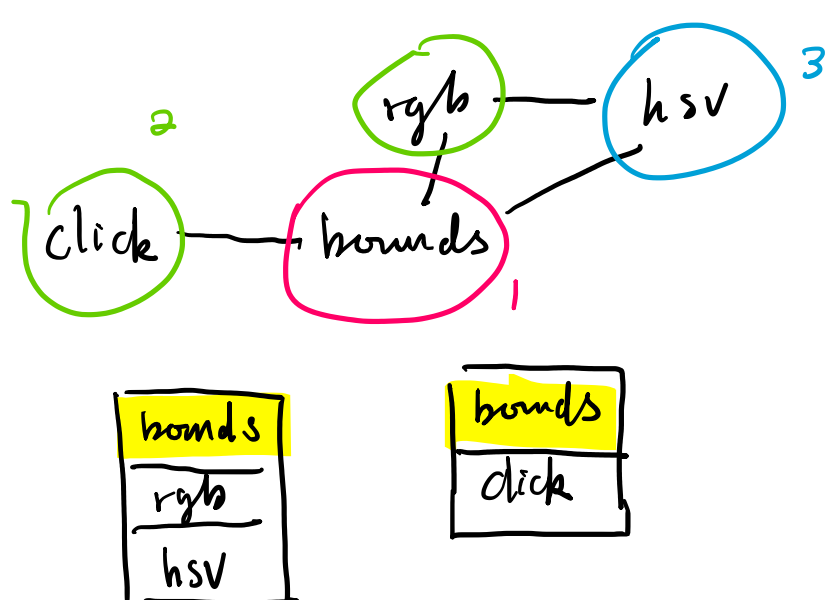


- rgb 1
- hsv 2
- click 3
- brands 4



Want: densely pack DRs.

Idea: draw interference graph



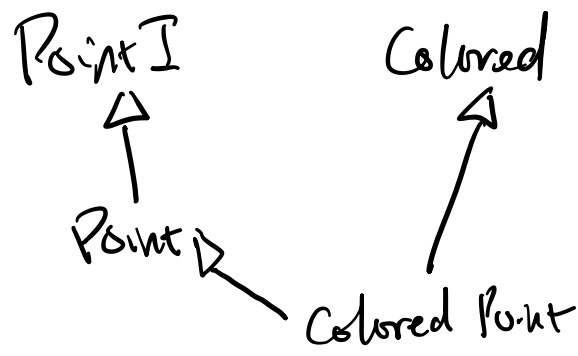
Idea #2 Compute indices by hashing.

```
interface PointI {
    void setX (int)
    void moveX (int)
}

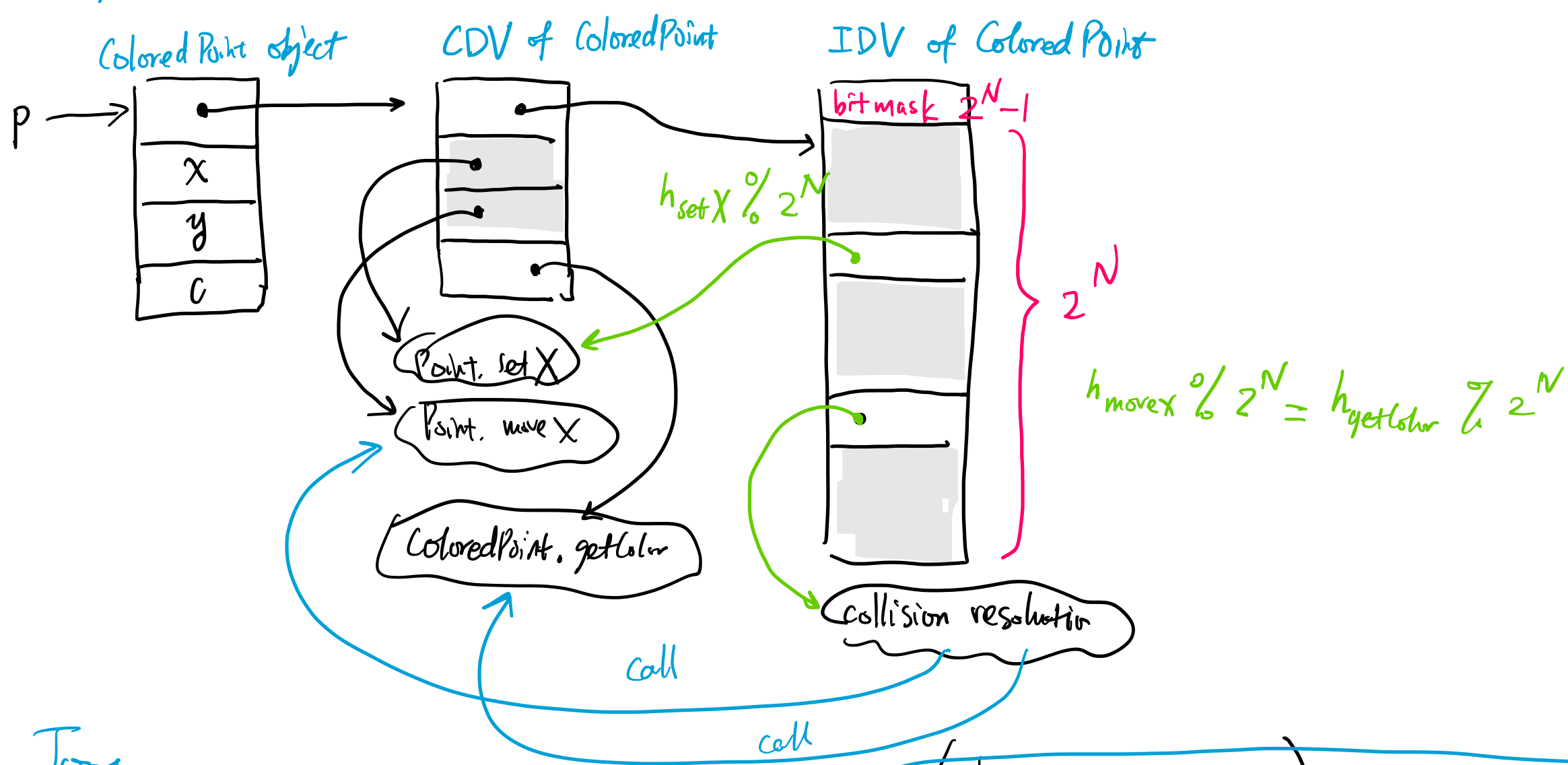
class Point implements PointI {
    int x, y ;
    ...
}

interface Colored {
    Color getColor();
}

class ColoredPoint
    extends Point implements Colored {
    ...
}
```



IDV \approx hash table

$$h_{\text{set } X} := \text{precomputed hash of } \text{PointI.set } X(\text{int})$$


Joos

```
Point I p = new ColoredPoint ();  
p.setX(42);
```

IR

$$\begin{aligned} & \text{MOVE}(t_{CDV}, \text{MEM}(p)) \\ & \text{MOVE}(t_{IDV}, \text{MEM}(t_{CDV})) \\ & \text{MOVE}(t_{setX}, \text{AND}(h_{setX}, \text{MEM}(t_{IDV} - 4))) \\ & \text{CALL}(\text{MEM}(t_{IDV} + 4 * t_{setX}), id_{setX}, p, A2) \end{aligned}$$

8 instructions vs. 4 instructions
interfaced. class m.d.

~ cache miss

Separate compilation ✓

```

mov    tcdv, [p]
mov    tidv, [tcdv]
mov    tsetX, hsetX
and    tsetX, [tidv - 4]
push   42
push   p
push   idsetX
call   [tidv + 4 * tsetX]

```

Optimization: inline caching.

slow Dispatch (o, m) assumed.

line 444 : o.m ()

cache is global data

```
line 444: mov tid, [0]
          cmp tid, [id444]
          jnz miss444
          call [code444]
```

id 444

code 444

class of o seen last time

code of m invoked --

done 444: ---

```
mis 444: call slowDispatch (0, m)
          mov [id444], tid
          mov [code444], ...
          jmp done444
```

} update cache

Instance of

o instance of C
(C) o
arr[i] = 0

Idea #1,

Use CUV as class identity
Store in CUV ptr to parent's CUV

store in CDV ptr to parents CDV

```
graph LR; 0 --> B1[ ]; B1 --> B2[D's CDV]; B2 --> B3[D's superclass CDV]; B3 --> Ellipsis[...];
```

- + separate compilation
- linear search / tree search

Idea #2

Use a global $M \times M$ table $M = \# \text{ types}$

$$\text{table}[i][j] = T_i \text{ is a subtype of } T_j$$

- + $O(1)$ + multiple inh
- $O(M^2)$ - separate compilation