

# Reverse Polish Notation Calculator

**Course: ENGG\*3640 Microcomputer Interfacing**

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Date: 08/10/2018

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## 1. Introduction

The Purpose of lab 1 was to get familiar more familiar with using the Kiel Uvision program interface, to complete Lab 2, it was mandatory to understand how the stack functions can be used in assembly to implement a calculator. The biggest problems presented by the lab were using the stack memory and board memory and being able to convert between number systems. The program designed in this lab used RPN, reverse polish notation, to perform the basic arithmetic operations (\*, +, /, -) through stack functions.

The RPN calculator, also known as Reverse Polish Notation, is a mathematical notation where operand is inputted first then their operators. For example, in regular algebraic notation;  $30 + 70 = 100$ . In RPN;  $30\ 70\ + = 100$ . The simplest way of building a calculator like this is using stacks in assembly. Each argument the user inputs will get stored in the stack, when the operator is inputted, the inputs gets popped from the stack and the required operation is performed.

### 1.1. Lab Description

In this experiment, the main task of the lab was implementing an RPN calculator using the assembly language and the skills learned from lectures and Lab 1. To implement the calculator, an input was obtained by the user through Putty, the input is then converted from ASCII characters to binary and saved in the stack. The program then performs the arithmetic operation by popping the values from the stack. After operation is completed, the resulting values are then pushed into the stack. The results are then converted from binary back to ASCII characters so they can be displayed. Finally the program prints out the result once the user requests the output.

## 1.2. System Requirements

During this lab, the tools and equipment that were used are enumerated below:

- Kiel Uvision Program was used to create instructions to the K60 Microcontroller
- FreeScale TWR-K60D100M Microcontroller was used to implement instructions sent
- A Hi Speed USB 2.0 Connection cable between PC and board was used to connect the Microcontroller to the PC.
- Putty displayed the results by receiving commands through the COM port in which the USB 2.0 was connected to.

## 2. Background

### 2.1. Equipment

- **Kiel Uvision Program:** The Kiel Uvision program is an IDE that combines project management, source code editing, program debugging, and run-time environment into a single powerful environment. Using this environment, the user is able to easily and efficiently test, verify, debug, and optimize the code developed. During the first lab, the debug functionality helped in understanding how the code is acting.
- **K60 Microcontroller:** The K60 Microcontroller (Figure 2.1) from NXP contains a low power MCU core ARM Cortex-M4 that features an analog integration, serial communication, USB 2.0 full-speed OTG controller and 10/100 Mbps Ethernet MAC. These characteristics makes this



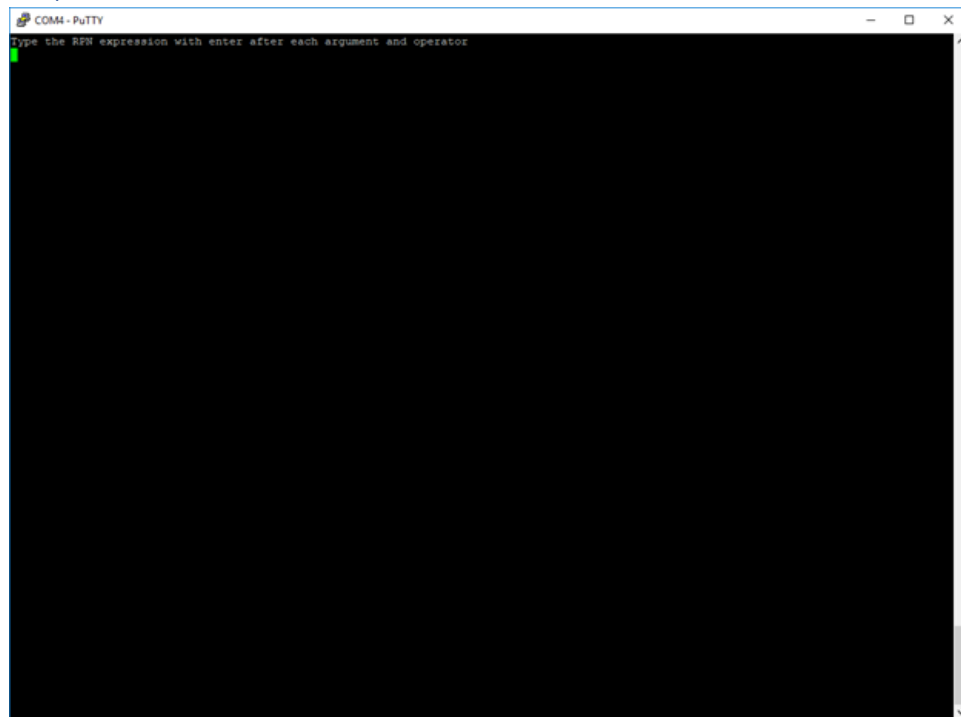
Figure 2.1 1K60 Microcontroller

Microcontroller suitable to perform task in a very efficient and fast manner. A USB connection was used to sync the microcontroller with the Keil uVision software that was provided by the teaching assistant.

### 3. Implementation

During the implementation of this lab many obstacles were encountered. To overcome these obstacles, the code outline was written on a paper and debugged before typing into Keil for execution. The code consisted of the startup statement receiving inputs. After that, the conversion from ASCII to integer took place so the arithmetic operations could be run.

#### 3.1. Lab Implementation Overview



*Figure 3 1Running the Code*

Figure 3. displays the main menu of the RPN Calculator. The main menu prompts the user to input the RPN expression with an 'enter' after each argument and operator. This menu makes it easier for the

user to interact with the program. Through this menu, the user can see the final results as the calculation's answer will be displayed on this screen

### 3.1.1. Software Implementation

In the `main.c`, we use collaborative programming to code functions using C-Programming. These functions were used to print out results/prompts on the main menu, collect input from the user and store values in registers. The following program is provided in figure A in the appendices section. A `print`, `getchar`, and `putchar` function were created for later use in *mymain.s*.

In *mymain.s* we have our assembly program that implements the lab. When the code is run, 64 bit space is immediately created and stored `r7`. Then the user is prompted to enter input. The input entered is loaded into registers `r0` and `r1` and then converted from its ASCII form to integer. After the inputs have been entered, the arithmetic operator is checked for, with the options being addition, subtraction, division, multiplication, and equal. If any of the four first options are selected first, as they should be, the function for that particular arithmetic operations is run on the entered inputs and the answer is stored in `r0`. If the input is equal then the result is converted from integer back to ASCII.

When converting from ASCII to hexadecimal it's a simple arithmetic function called *hexconversion* that subtracts `0x30` from the ASCII value giving us the hexadecimal equivalent. The back conversion however is not as simple. When the calculations are done the answer is left in binary and hence have to be converted back to ASCII to be displayed in Putty. The *BINtoASCII* function is where this happens.

### 3.1.2. Hardware Implementation

During the second lab, Implementation of hardware was minimal. The TWR-K60D100M microcontroller was to demonstrate the code implementation. Putty terminal was used to display the

results on screen as was it communicating serially with the board this display was possible. The on-board crystal frequency was valued at 100 MHz. The above frequency value was used to calculate the register preload values.

### 3.2. Block Diagram

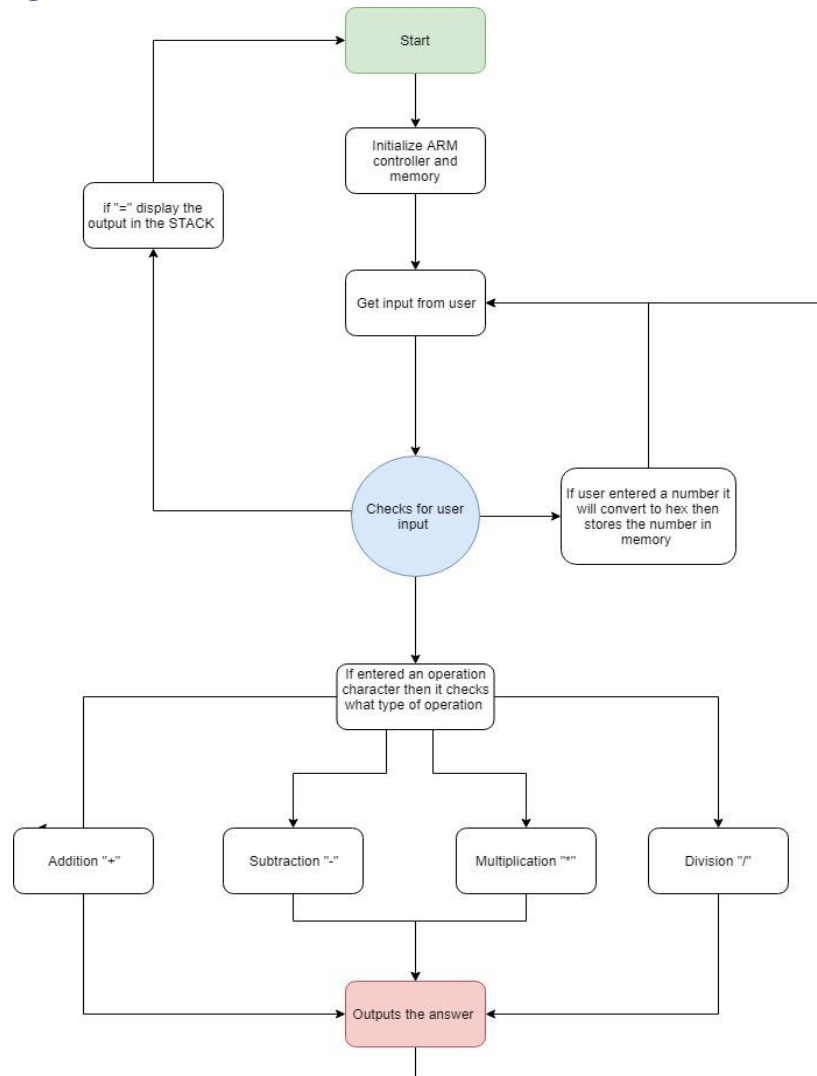


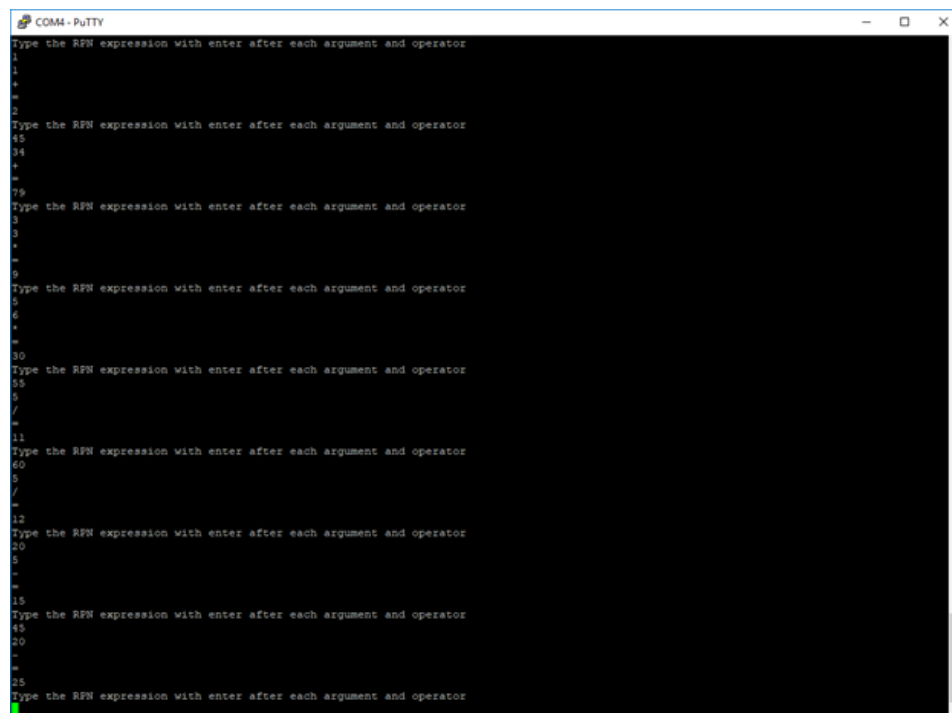
Figure 3. 1. Block Diagram

The first thing that the code does when it starts is to initialize the ARM controller and memory, after that it prompts the user to enter an input. If the user enters a number, then it will convert it hexa-

## RPN Calculator

decimal and stores the number in the stack and prompts the user again for input. But if the user enters an operation character, it will check what operation needs to be done and outputs the answer when the “=” is pressed and repeats the process.

### 3.3. Simulation Results



```
COM4-PuTTY
Type the RPN expression with enter after each argument and operator
1
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74
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76
77
78
79
80
81
82
83
84
85
86
87
88
89
90
91
92
93
94
95
96
97
98
99
100
```

Figure 3.3. 1 Results of running code with inputs

As it is shown in figure 3.3.1, after we run the code, the startup sentence will pop up alone. After the values are entered followed by the basic arithmetic operations the results will be shown after an “=” sign, and then it repeats itself with the startup sentence again.

### 3.4. Lab Requirements

After inputting the value 5 into the putty terminal. The value gets pushed to register 7. As shown above, the value 05 was stored in the stack pointer as seen in the memory address section above. This value can be changed manually using the debugger by changing the value or that specific register.



## RPN Calculator

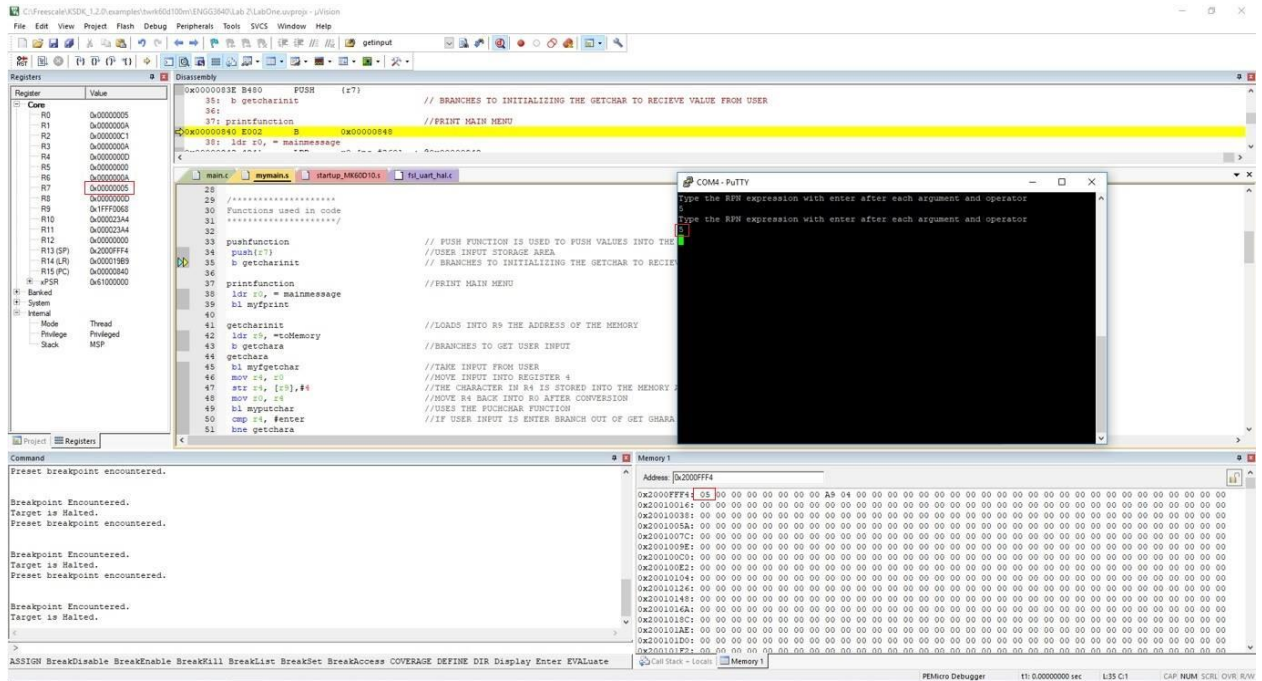


Figure 3.3 1 Stack Tracing 1

Register 7 is later set to 42 as the user inputs the second value. The second input is later pushed into the stack pointer, and shifted four bits for conversion purposes.

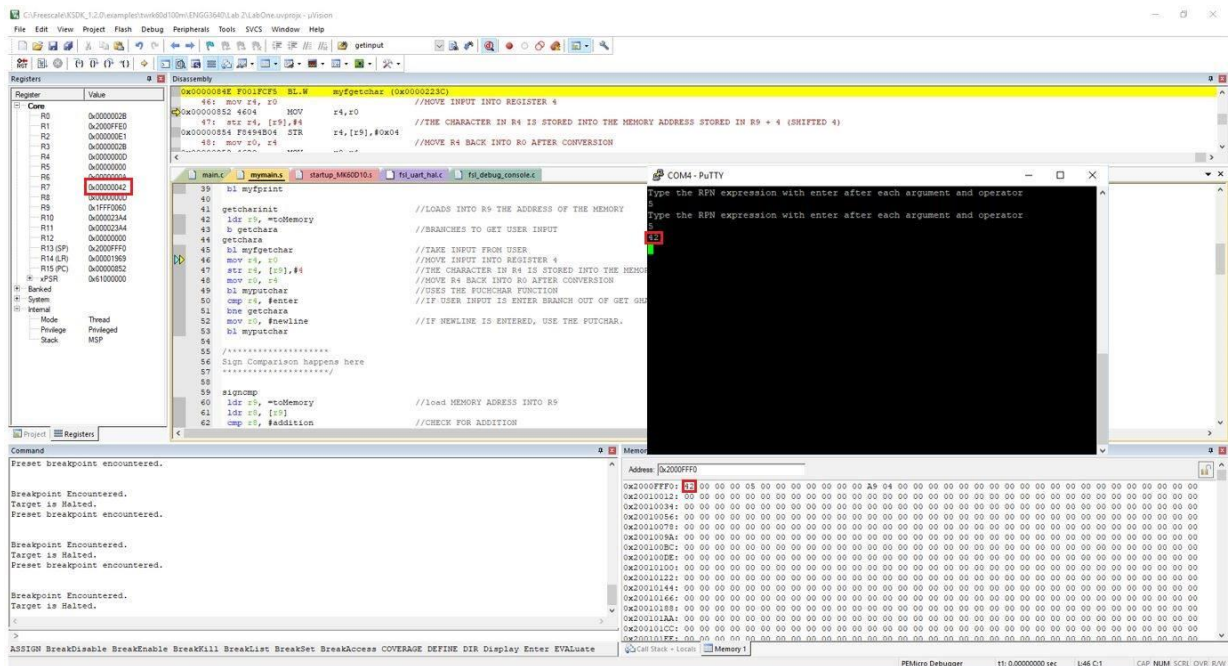


Figure 3.3 2 Stack Tracing 2

## 4. Conclusion

As a Conclusion, the reverse polish notation calculator is successfully implemented, it can receive and properly handle a large diversity of numeric input, including numbers of different lengths, up to 4 digits, as the digit is typed the source code pull each character once at a time and sends it to the board through assembly code. Once a carriage returns is encountered, the characters that are inputted are pulled into hex value and stored into the active stack. As any of the basic arithmetic operations (+, -, \*, /) is pressed, the stack pops off two entries and performs the calculation and then shows the results. This code was tested thoroughly to ensure results are true.

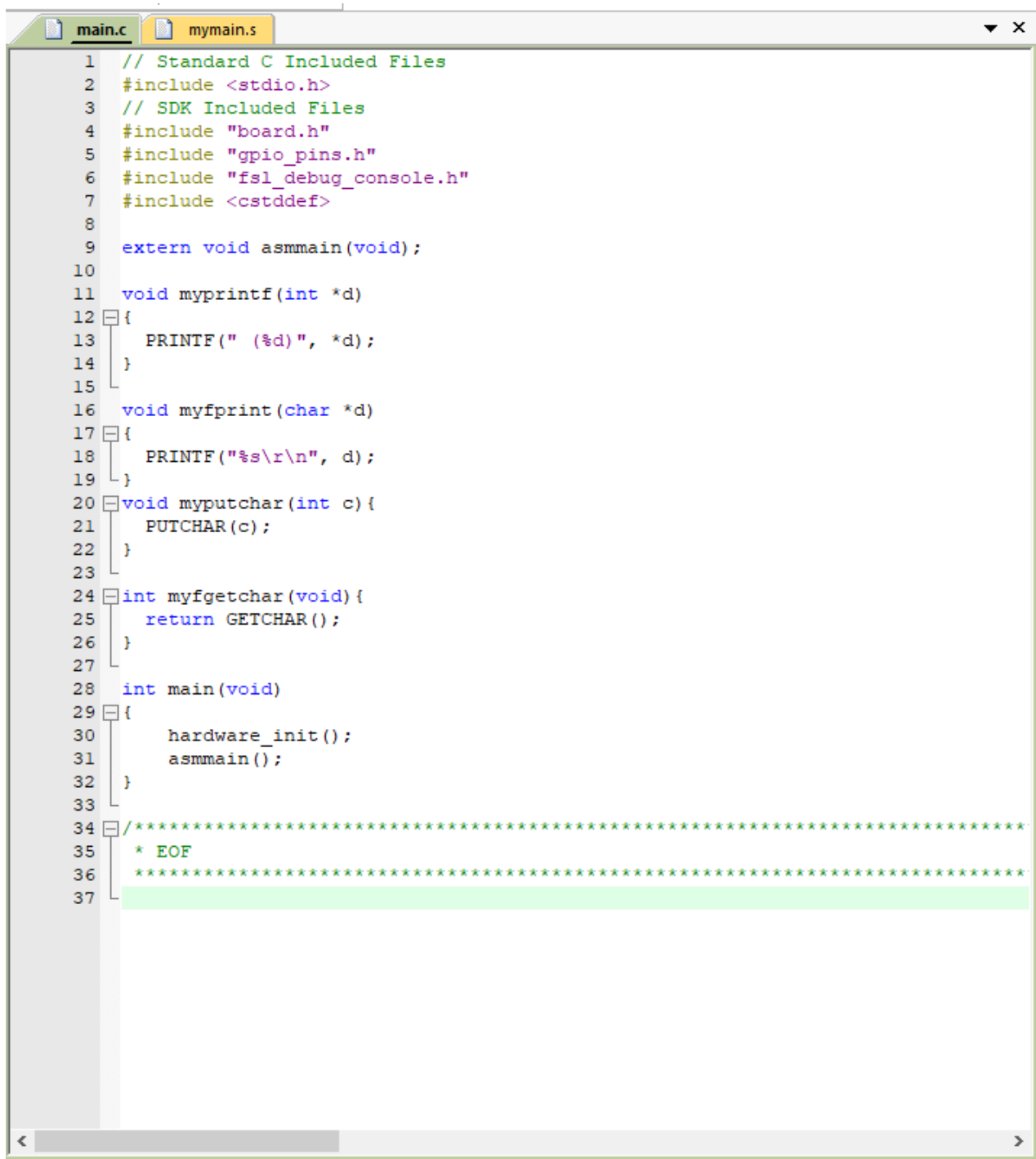
## References

[1] Radu Muresan, "ENGG3640: Microcomputer Interfacing Laboratory Manual, Version 2", University of Guelph, July 2016.



## Appendices

### A. Main.c



```
1 // Standard C Included Files
2 #include <stdio.h>
3 // SDK Included Files
4 #include "board.h"
5 #include "gpio_pins.h"
6 #include "fsl_debug_console.h"
7 #include <cstdint>
8
9 extern void asmmain(void);
10
11 void myprintf(int *d)
12 {
13     PRINTF(" (%d)", *d);
14 }
15
16 void myfprint(char *d)
17 {
18     PRINTF("%s\r\n", d);
19 }
20 void myputchar(int c) {
21     PUTCHAR(c);
22 }
23
24 int myfgetchar(void) {
25     return GETCHAR();
26 }
27
28 int main(void)
29 {
30     hardware_init();
31     asmmain();
32 }
33
34 /*****
35  * EOF
36  *****/
37
```

Figure A. 1Main.c

## B. myMain.s

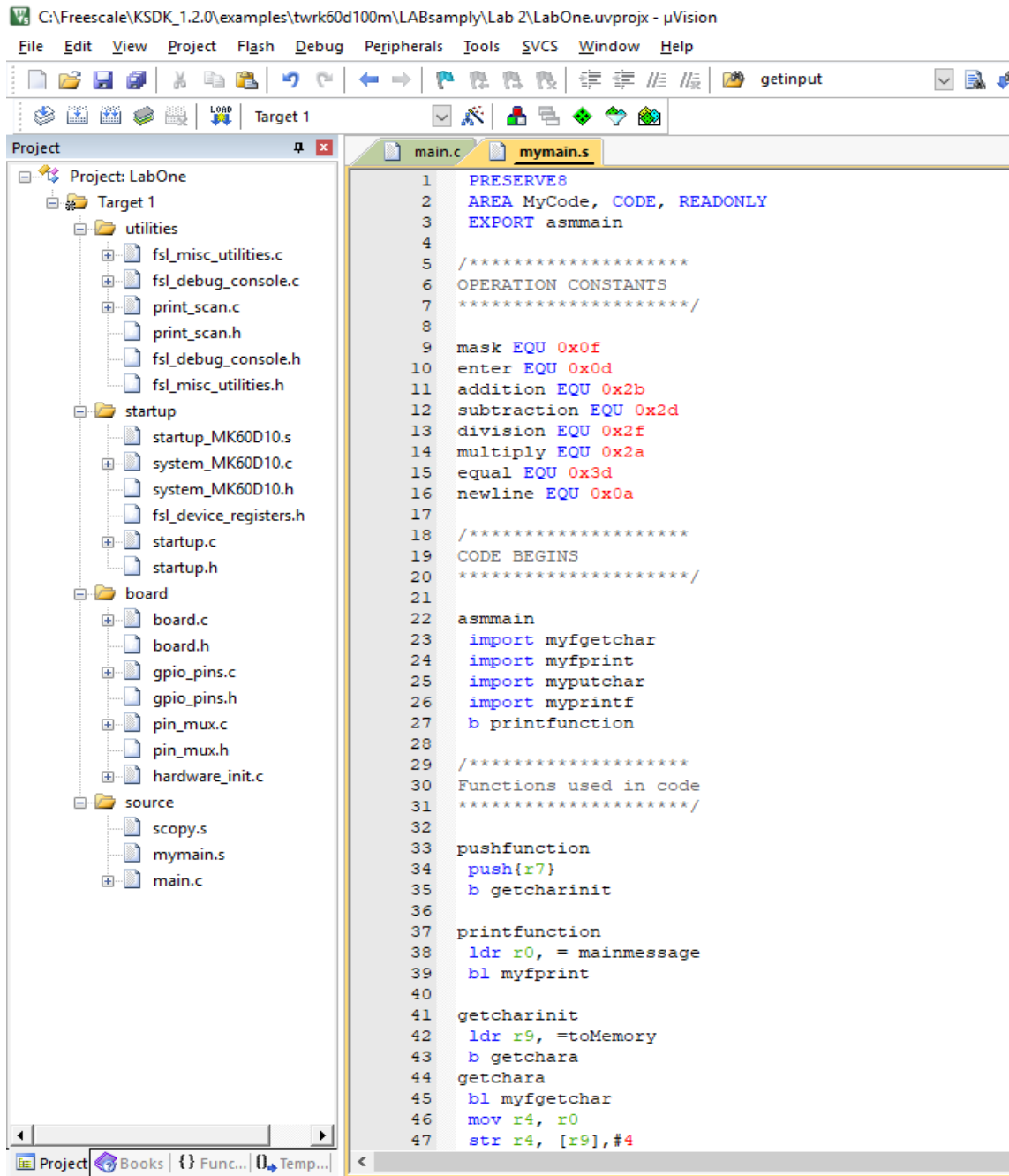


Figure B. 1 myMain.s

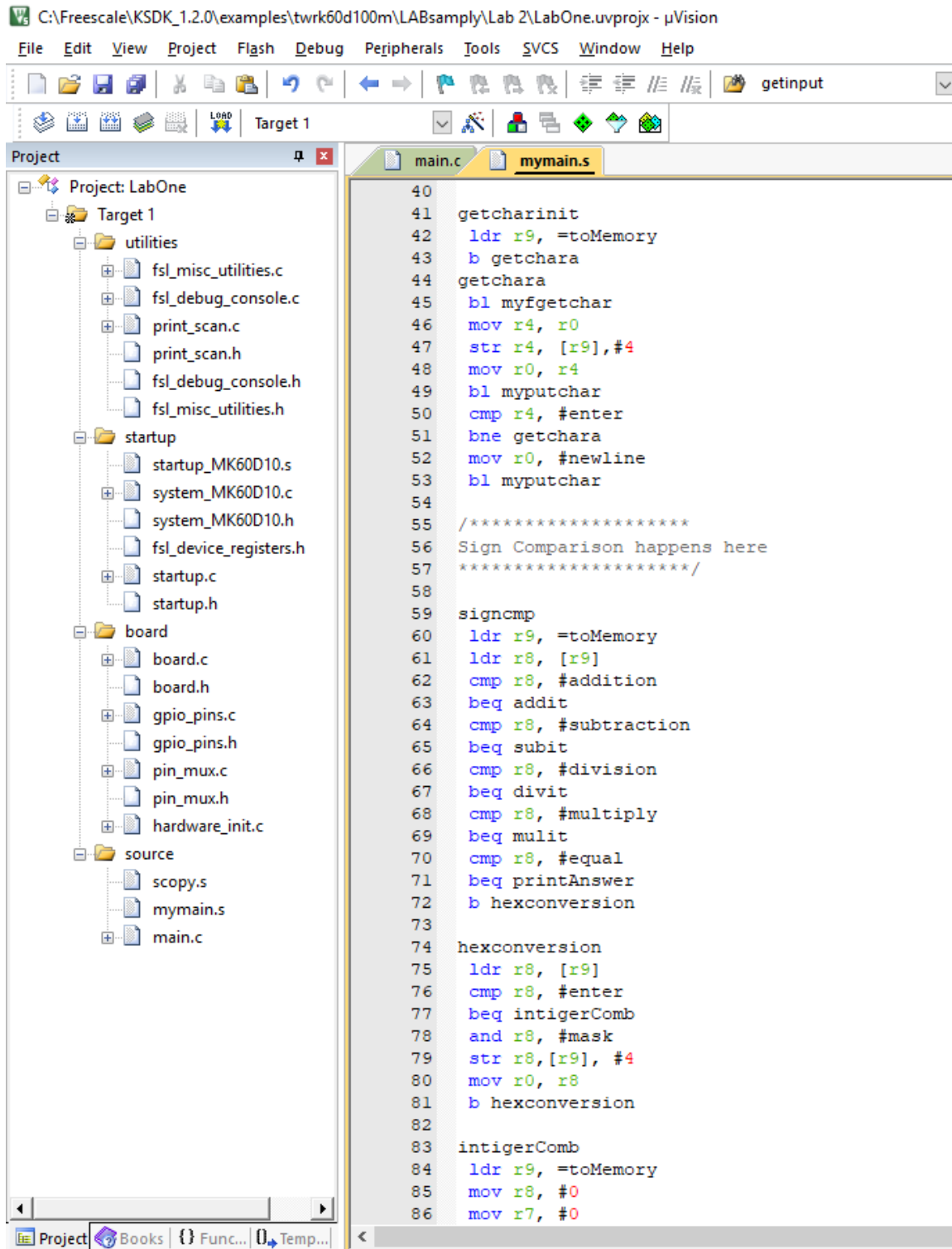


Figure B. 2 myMain.s

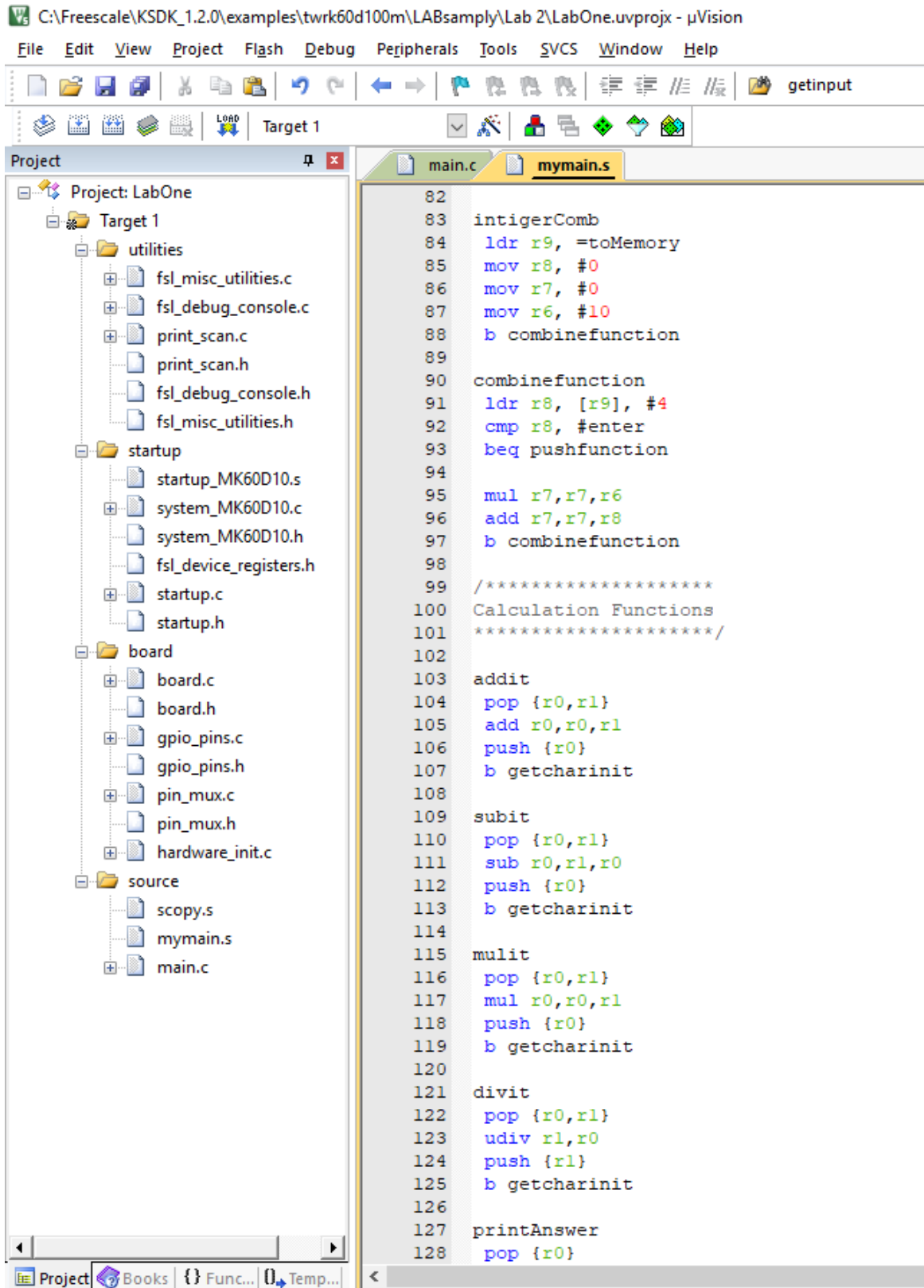


Figure B. 3 myMain.s

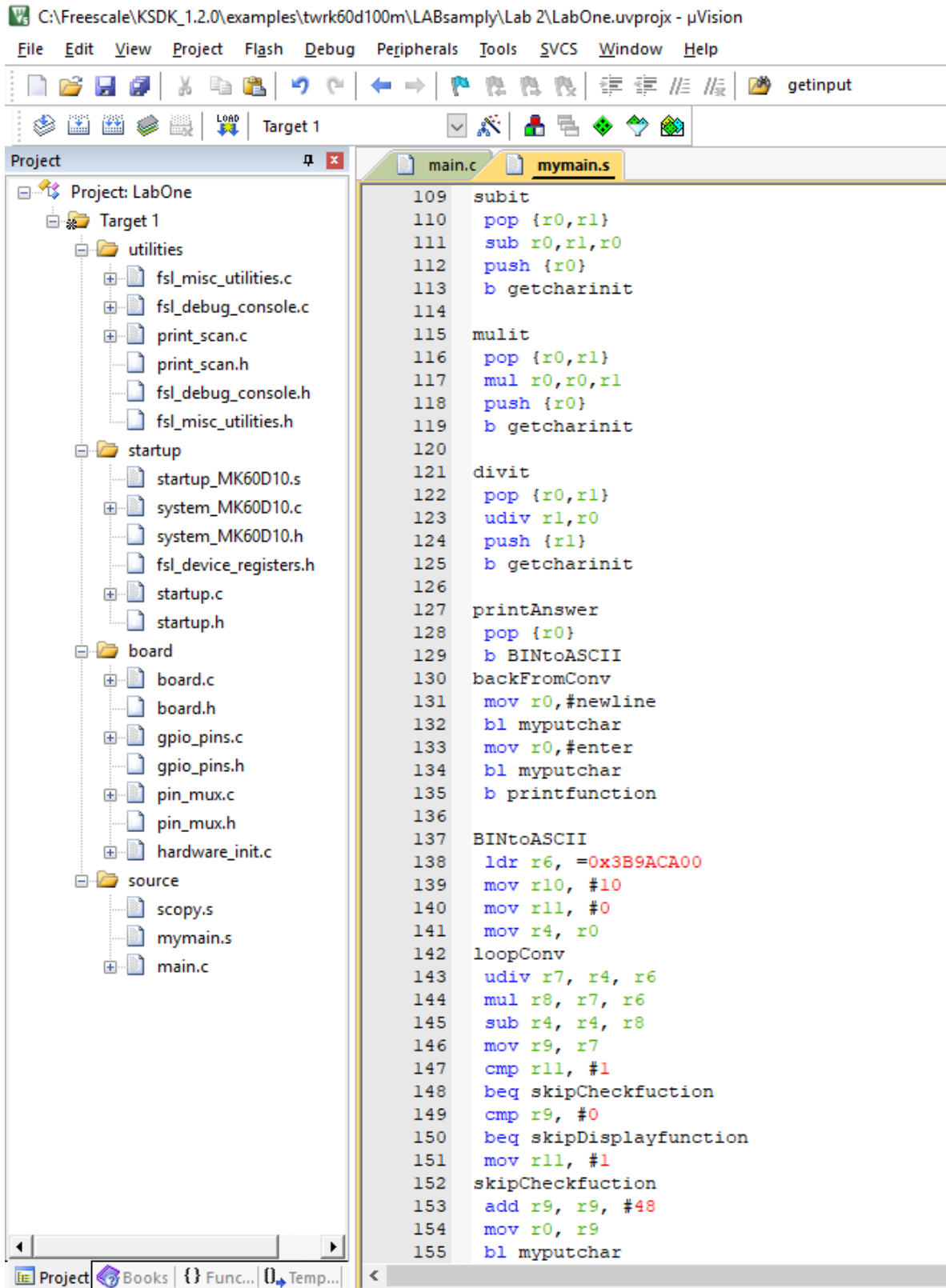


Figure B. 4 myMain.s



## RPN Calculator

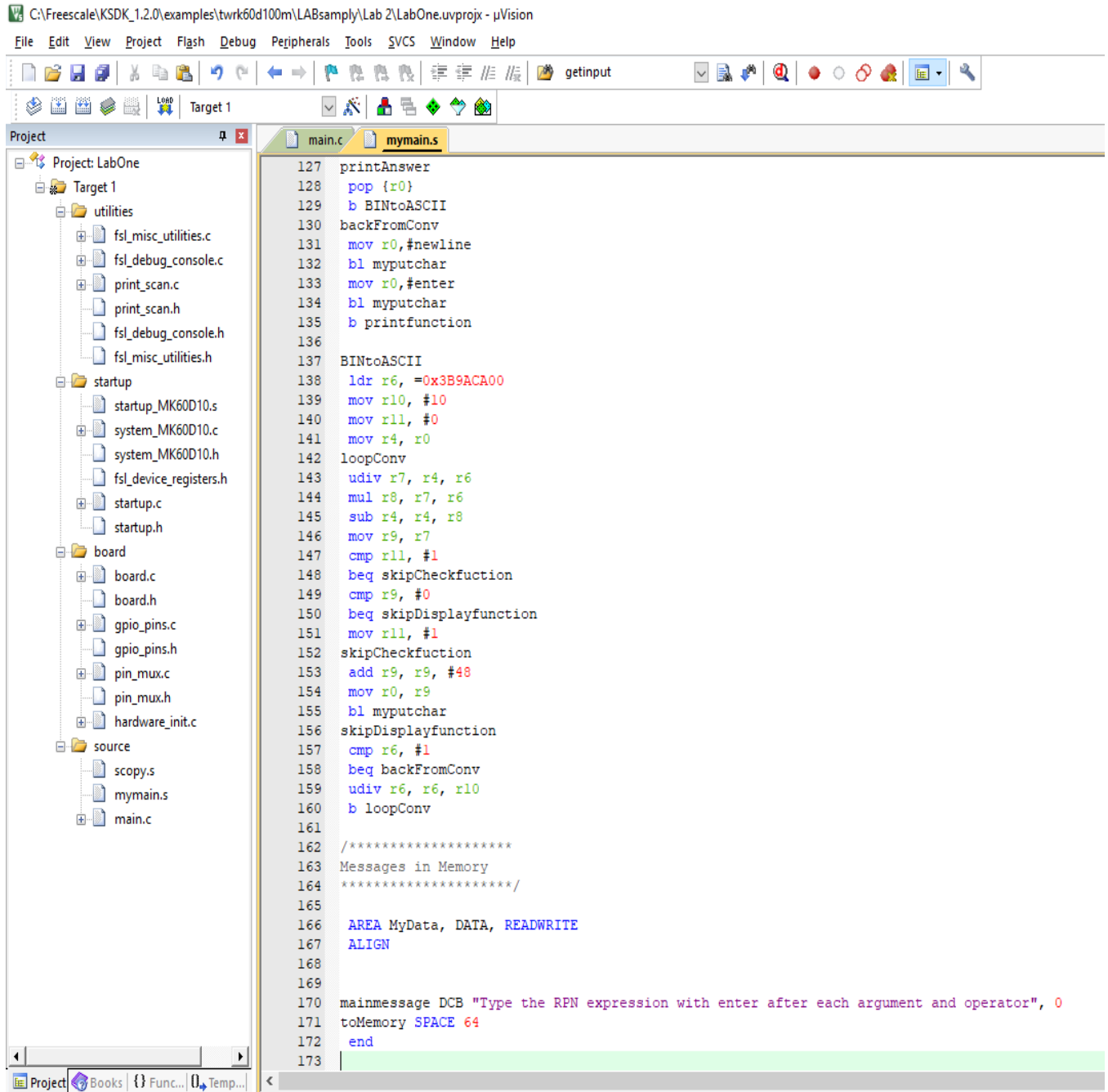


Figure B. 5 myMain.s