Friederike Horn & Bileam Scheuvens Justify all your claims.

Exercise 1 (Principal Component Analysis)

a) Suppose λ is an eigenvalue to the eigenvector v of Σ .

$$\begin{split} \lambda\langle x,x\rangle &= \langle \lambda x,x\rangle\\ &= \langle \Sigma x,x\rangle\\ \text{Since } \Sigma &= \bar{\Sigma}\\ &= \langle x,\Sigma x\rangle\\ &= \langle x,\lambda x\rangle\\ &= \bar{\lambda}\langle x,x\rangle \end{split}$$

If $\lambda = \bar{\lambda}$ then λ must be in \mathbb{R} .

- b) By the Rayleigh coefficient, vector that maximizes the variance is the normed eigenvector $\frac{v_1}{||v_1||}$ corresponding to the largest eigenvalue λ_1 of X^TX . The resulting variance is $\sqrt{\lambda_1}$ i.e. the first singular value σ_1 of X.
- c) Analogously, the vector orthogonal to v_1 that maximizes the variance is the normed eigenvector $\frac{v_2}{||v_2||}$ corresponding to the largest eigenvalue λ_2 of X^TX . The resulting variance is the second singular value σ_2 of X.
- d) The k-th principal component is obtained by eigendecomposition of X^TX and ordering the eigenvalues such that $\lambda_1 < \lambda_2 < \cdots < \lambda_d$. Then the k-th principal component is $X * v_k$ with variance $\sqrt{\lambda_k}$. To obtain the lower dimensional representation \tilde{X} we multiply the matrix with the eigenvectors of XX^T as columns \tilde{U} by the matrix with diagonal elements $\tilde{\sigma_i} = \sqrt{\lambda_i} \; \tilde{\Sigma}$ and the matrix with eigenvectors of X^TX as rows \tilde{V}^T .

$$\tilde{X} = \tilde{U}\tilde{\Sigma}\tilde{V}^T$$

Exercise 2 (Singular Value Decomposition)

a) The singular values are equal to the ordered eigenvalues of MM^T and M^TM .

$$M^{T}M = \begin{bmatrix} -4 & 1 & 3 \\ 2 & 2 & 2 \end{bmatrix} \begin{bmatrix} -4 & 2 \\ 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{pmatrix} 26 & 0 \\ 0 & 12 \end{pmatrix}$$

Since the result is diagonal, the eigenvalues are easily determined as $\lambda_1 = 26, \lambda_2 = 12$ which results in the singular values $\sigma_1 = \sqrt{26}, \sigma_2 = \sqrt{12}, \sigma_3 = 0$.

b) The singular values of a matrix A are the union of the roots of the eigenvalues of A^TA and AA^T . Since the union is commutative, $eigs(AA^T) \cup eigs(A^TA) = eigs(A^TA) \cup eigs(AA^T)$, so the singular values are identical.

c) For $\Sigma^{\#}\Sigma\Sigma^{\#} = \Sigma^{\#}$ since Σ is diagonal, analogously for Σ .

$$AA^{\#}A \stackrel{!}{=} A$$

$$U\Sigma V^{T}V\Sigma^{\#}U^{T}U\Sigma V^{T} = A$$

$$U\Sigma \Sigma^{\#}\Sigma V^{T} = A$$

$$U\Sigma V^{T} = A$$

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$$A^{\#}AA^{\#} \stackrel{!}{=} A^{\#}$$

$$V\Sigma^{\#}U^{T}U\Sigma V^{T}V\Sigma^{\#}U^{T} = A^{\#}$$

$$V\Sigma^{\#}\Sigma\Sigma^{\#}U^{T} = A^{\#}$$

$$V\Sigma^{\#}U^{T} = A^{\#}$$

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$$(AA^{\#})^{T} \stackrel{!}{=} AA^{\#}$$

$$(U\Sigma V^{T}V\Sigma^{\#}U^{T})^{T} = AA^{\#}$$

$$U\Sigma^{\#}V^{T}V\Sigma U^{T} = AA^{\#}$$

$$U\Sigma^{\#}V^{T}V\Sigma U^{T} = U\Sigma V^{T}V\Sigma^{\#}U^{T}$$

$$U\Sigma^{\#}\Sigma U^{T} = U\Sigma\Sigma^{\#}U^{T}$$

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$$(A^{\#}A)^{T} \stackrel{!}{=} A^{\#}A$$

$$(V\Sigma^{\#}U^{T}U\Sigma V^{T})^{T} = A^{\#}A$$

$$V\Sigma U^{T}U\Sigma^{\#}V^{T} = A^{\#}A$$

$$V\Sigma U^{T}U\Sigma^{\#}V^{T} = V\Sigma^{\#}U^{T}U\Sigma V^{T}$$

$$V\Sigma \Sigma^{\#}V^{T} = V\Sigma^{\#}\Sigma V^{T}$$

Exercise 3 (Condition Number)

a) First prove that $||Av|| \stackrel{!}{\leq} ||A||_2 \cdot ||v||$

$$||Av|| \leq \max_{x \neq 0} \frac{||Ax||}{||x||} ||v||$$

If ||v|| = 0 this holds since $0 = ||A||_2 \cdot 0$. Otherwise we divide by ||v|| to obtain:

$$\frac{||Av||}{||v||} \leq \max_{x \neq 0} \frac{||Ax||}{||x||}$$

This clearly holds.

Secondly,

$$||\Delta x|| = ||A^{-1}\Delta b|| \le ||A^{-1}||_2 ||\Delta b|| \frac{||b||}{||b||}$$

$$= ||A^{-1}||_2 ||\Delta b|| \frac{||Ax||}{||b||} \le ||A^{-1}||_2 ||\Delta b|| ||A||_2 ||x|| \frac{1}{||b||}$$
$$= \kappa(A) \frac{||\Delta b||}{||b||} \cdot ||x||.$$

From this the preposition directly follows.

b) An example where the relative noise on the output $\frac{||\Delta b||}{b} \le 0.001$ and the relative noise on the input $\frac{||\Delta x||}{||x||} \ge 1$ is given by the following matrix:

$$A = \begin{pmatrix} 10000 & 0 \\ 0 & 1 \end{pmatrix}$$

and the vector $\Delta b=(0,1)$. In this case the input vector is given by x=(1,0) and such $\Delta x=(0,1)$ and thus the relative noise of the input $\frac{||\Delta x||}{||x||}=1$ and the output noise is $\frac{1}{10000}\leq 0.001$.