

ALGO-101

Week 2 - Sorting Algorithms and Array Problems

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Topics

Topics covered at week 2:

- Sorting Algorithms
 - Insertion Sort
 - Selection Sort
 - Bubble Sort
 - Merge Sort
 - Quick Sort
- Array Problems
 - Prefix Sum
 - Two Pointers

Insertion Sort

Insertion Sort is one of the simplest algorithm with simple implementation.

Algorithm iterates through the array and at every iteration it keeps a key value in order then inserts that key value to the suitable place where its left hand side is smaller or equal and right hand side is greater or equal .

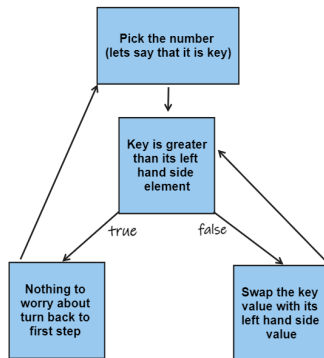
Main idea behind the insertion sort is that algorithm takes elements in order from the array and puts this element in a suitable position.

In suitable position elements on the left hand side are less (or greater) than or equal to our key value and the elements on the right hand side are greater (or less) than or equal to our key value .

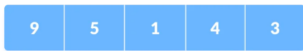
Insertion Sort

- Time Complexity : $O(n^2)$
- Space Complexity : $O(1)$

The insertion sort algorithm is one of the simplest algorithms to understand and easy to implement. Main idea of the algorithm is to insert every element into suitable position while iterating through the array . The process shown in the figure :



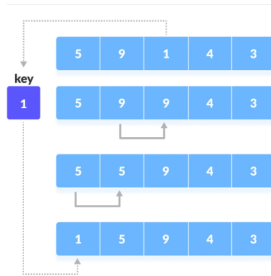
Steps of Insertion Sort



step = 1



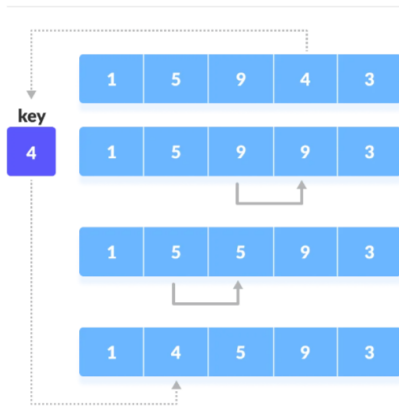
step = 2



Start from second element!..

Steps of Insertion Sort

step = 3



step = 4



Start from second element!..

Insertion Sort Code

```
1
2 void insertionSort(vector<int>&v){
3     for(int i=1;i<v.size();i++){
4         int key=v[i]; // Key is the element that we are going to compare
5         int position=i-1;
6
7         while( x>=0 && key < v[x] ){
8             v[x+1]=v[x]; // Shifting to the right
9             position--; // Decreasing position by one since we will check
the previous position to insert
10        }
11        v[position+1]=key;
12    }
13 }
```

Selection Sort

- Space Complexity : $O(1)$
- Time Complexity : $O(n^2)$

Selection Sort is a simple algorithm that divides array to two sub array .This sub arrays are sorted and unsorted sub array.Initially sorted sub array is empty and unsorted sub array is array's itself.

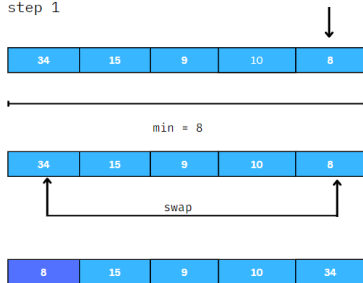
Algorithm works like this: Find the smallest value in the array and swap that value with array's first element and find the second smallest value in the array and swap that value with array's second element and that process goes until the end of the array.

As you have noticed left sub array(which is sorted) expanding and right sub array is narrowing as the process continues.At the end right sub array which is unsorted is empty.

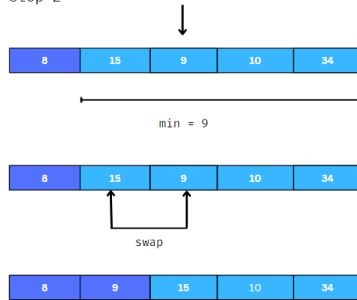
-Since the complexity of selection sort is $O(n^2)$ it is not suitable for large datasets.

Selection Sort

step 1

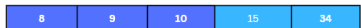
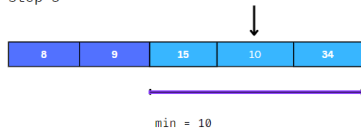


step 2

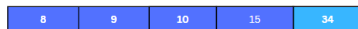
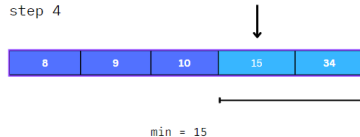


Selection Sort

step 3



step 4



Since there is no element to compare
34 stays at same place



Selection Sort Code

```
1 void swap(vector<int>& v,int i1,int i2){
2     int temp=v[i1];
3     v[i1]=v[i2];
4     v[i2]=temp;
5 }
6 void selectionSort(vector<int> &v){
7     int size=v.size();
8     for(int i=0; i<size ; i++){
9         int minIndex=i;
10        for(int s=i;s<size;s++){
11            // To sort in descending order you can change "<" with ">" in
12            this line
13            if(v[s]<v[minIndex]){
14                minIndex=s;
15            }
16        }
17        swap(v,i,minIndex);
18 }
```

Bubble Sort

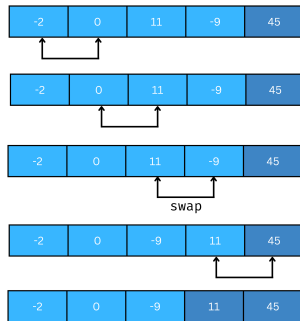
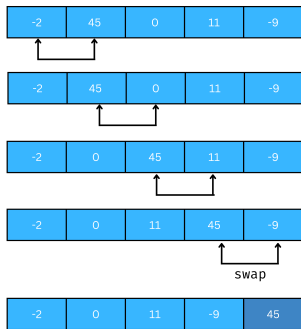
- Time Complexity : $O(n^2)$
- Space Complexity : $O(1)$

Bubble Sort is a simple (sorting??) algorithm that is comparison based.

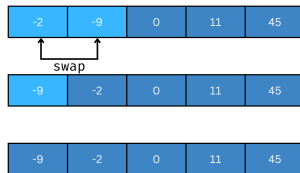
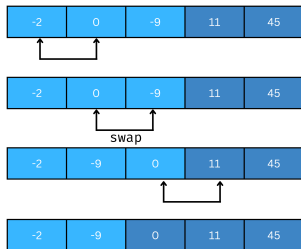
Adjacent elements compared and if they are not in the intended order (ascending or descending), they are swapped.

It is called bubble sort since the movement of array elements is just like the movement of air bubbles in the water.

Bubble Sort



Bubble Sort



Bubble Sort Code

```
1 void bubbleSort(vector<int> & v) {
2     int n = v.size(); // Size of the vector
3     for (int step = 0; step < n; step++ ) { // There will be total of n step.
4         // Since we want to sort n elements.
5         // For each step we place one element to the its right place.
6         // There is "n-step" iteration because when we done our x step we also
7         // sorted the last x elements.
8         // So we will not deal with that part again.
9         for (int i = 0; i < n - step; i++ ) {
10             // If an element is greater than its right adjacent then swap them
11             // Also if you want to make descending ordered array instead of
12             ascending make ">" sign "<" .
13             if (v[i] > v[i + 1]) {
14                 swap( v[i] , v[i+1] );
15             }
16         }
17     }
18 }
```

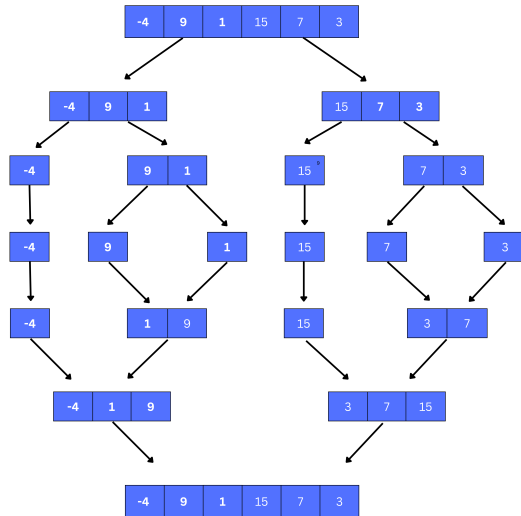
Merge Sort

- Time Complexity : $O(n.\log(n))$
- Space Complexity : $O(n)$

Merge sort is a divide and conquer algorithm. Divide and conquer is a technique for solving large problems by breaking the problems into smaller subproblems and solving these subproblems then combining them to reach the final solution. To use divide and conquer technique ,recursion is used.

Merge sort algorithms divide the array into halves repeatedly and get subarrays until the size of the subarray is 1. Then merge function pick these subarrays and merge them to sort the entire array.

Merge Sort



Merge Sort Code

```
1 void merge(vector<int> &v, int left, int mid, int right) {
2     // Getting the sizes of the left and right subarrays's size to create
   same sized vector
3     int size1 = mid - left + 1;
4     int size2 = right - mid;
5
6     vector<int> L(size1), R(size2);
7     // Storing elements in to L(left) and R(right) vectors
8     for (int i = 0; i < size1; i++){
9         L[i] = v[left + i];
10    }
11    for (int j = 0; j < size2; j++){
12        R[j] = v[mid + 1 + j];
13    }
14    int i, j, k;
15    i = 0;
16    j = 0;
17    k = left;
18    // Until we reach either end of L or R , we will pick greater elements
```

Merge Sort Code

```
1      // Until we reach either end of L or R , we will pick greater elements
2      // among the elements of L and R and put them in to our main vector v
      with correct positioning
3      while (i < size1 && j < size2) {
4          if (L[i] <= R[j]) {
5              v[k] = L[i];
6              i++;
7          }
8          else {
9              v[k] = R[j];
10             j++;
11         }
12         k++;
13     }
14     while (i < size1) {
15         v[k] = L[i];
16         i++;
17         k++;
18     }
```

Merge Sort Code

```
1     while (j < size2) {
2         v[k] = R[j];
3         j++;
4         k++;
5     }
6 }
7 void mergeSort(vector<int> &v , int left , int right) {
8     if (left < right) {
9         // mid is the point where is the array is divided in to two
10        subarray
11        int mid = (right + left)/ 2 ;
12        // recursively calling mergeSort function
13        mergeSort(v , left , mid);
14        mergeSort(v , mid + 1, right);
15
16        // Merge these two sorted subarrays
17        merge(v , left , mid , right);
18    }
```

Quick Sort

- Time Complexity : $O(n.\log(n))$
- Space Complexity : $O(\log(n))$

Quicksort is another sorting algorithm that uses divide and conquer approach. As we have learned before idea behind the divide and conquer approach is dividing problems to subproblems then solving these subproblems and finalizing the solution.

- Pivot : the most important part of something.

The main idea of the algorithm is to choose an array element as a pivot and then partition this array by comparing them to the pivot element. Now we have left and right subarray. Our array will be sorted when the same process is applied for these subarrays recursively. There are different ways of choosing pivot (First element, Last element, Random element, Median value). But today we will pick the last element as pivot.

Quick Sort

How do we do this partitioning ?

First of all, we will keep a pointer p for greater elements and initialize it as $(low-1)$ then traverse each element of the array. If an element is less than or equal to the pivot, p is incremented one and it is swapped with p . This process continued until we looked at every element of the array. Then pivot is swapped with $p+1$ since before the p every element is less than or equal to the pivot and after $p+1$ every element is greater than the pivot.

Quick Sort



pivot=3

iterator i=0 pointer p=-1



i=0
p=-1



i=0
p=-1 $\longrightarrow -4 \leq 3 \longrightarrow p++ \longrightarrow \text{swap}(p, i)$



i=1
p=-1



i=2
p=0 $\longrightarrow 1 \leq 3 \longrightarrow p++ \longrightarrow \text{swap}(p, i)$



i=3
p=1

Quick Sort



i=3
p=1



i=3
p=1 swap(p+1, pivot)



partition for left subarray



pivot=1



iterator i=0

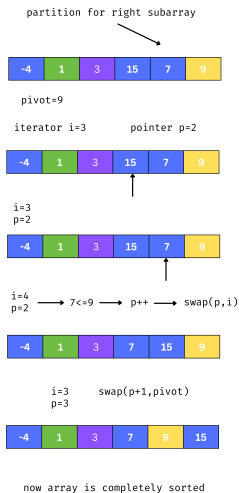
pointer p=-1



i=0
p=-1 $\longrightarrow -4 \leq 1 \longrightarrow p++ \longrightarrow \text{swap}(p, i)$



Quick Sort



Quick Sort Code

```
1 // Function to partition the array and return pivots index
2 int partition(vector<int> &v , int low, int high) {
3     // Select last element as pivot
4     int pivot = v[high];
5
6     // Pointer for greater elements
7     int i = (low - 1);
8
9     //Now iterate through the array and compare the elements with pivot
10    //Then put them in to right position in the array
11    for (int j = low; j < high; j++) {
12        if (v[j] <= pivot) {
13
14            // if element smaller than pivot is found
15            // swap it with the greater element pointed by i
16            i++;
17
18            // swap element at i with element at j
19            swap(v[i], v[j]);
```

Quick Sort Code

```
1         }
2     }
3     // Now partition is almost done but we need to put pivot to its
    position
4     // We will swap pivot with the greater element at i
5     // i+1 is always greater or equal to our pivot and belongs to right
    subarray
6     // so we can put our pivot freely there
7     swap(v[i + 1], v[high]);
8
9     // Return the partition point
10    // This is the point where our pivot is right now
11    return (i + 1);
12    // Actually what we have done right here is putting our pivot to its
    correct position in a sorted array
13    // and placing other elements at their right place compared to the
    pivot.
14 }
```

Quick Sort Code

```
1 void quickSort(vector<int> &v, int low, int high) {
2     if (low < high) {
3         // Find the pivot element such that
4         // elements less than or equal to pivot are on the left of pivot and
5         // elements greater than pivot are on right of pivot
6         int pi = partition(v, low, high);
7         // Array is partitioned ,so we will recursively call qucikSort
8         // function to
9         // sort left and right side of the pivot. This process goes until
10        // there is only one
11        // element in the subarray. (In this case low == high)
12        quickSort(v, low, pi - 1);
13    }
14 }
```

Complexities of Sorting Algorithms

Bubble Sort	Insertion Sort	Selection Sort	Merge Sort	Quick Sort
$O(n^2)$	$O(n^2)$	$O(n^2)$	$O(n \log(n))$	$O(n \log(n))$

Array Problems

- Prefix Sum
- Two Pointers

Prefix Sum

- Time Complexity : $O(n)$
- Space Complexity : $O(n)$

Given an array $arr[]$ of size n , its prefix sum array is another array $prefixSum[]$ of the same size, such that the value of $prefixSum[i]$ is equal to $arr[0] + arr[1] + arr[2] \dots arr[i]$.

To fill the prefix sum array, we run through index 1 to last and keep on adding the present element with the previous value in the prefix sum array.

It requires linear time preprocessing and is widely used due to its simplicity and effectiveness.

Prefix Sum

It is used for applications like:

- Find sum of all elements in a given range
- Find product of all elements in a given range
- Find maximum subarray sum
- Maximum subarray such that sum is less than some number

Prefix Sum Implementation

```
1 void fillPrefixSum(int arr[], int n, int prefixSum[])
2 {
3     prefixSum[0] = arr[0];
4
5     for (int i = 1; i < n; i++){
6         prefixSum[i] = prefixSum[i - 1] + arr[i];
7     }
8
9 }
```

Two Pointers

Two pointer approach is an essential part of a programmer's toolkit. It involves using two pointers to save time and space. (Here, pointers are basically array indexes). Just like Binary Search is an optimization on the number of trials needed to achieve the result, this approach is used for the same benefit. The idea here is to iterate two different parts of the array simultaneously to get the answer faster.

There are primarily two ways of implementing the two-pointer technique:

- One pointer at each end.
- Both pointers start from the beginning but one pointer moves at a faster pace than the other one.

Two Pointers

It is used for applications like:

- In a sorted array, find if a pair exists with a given sum S .
- Find the middle of a linked list .
- Reversing an array .
- Merging two sorted arrays.
- Partition function in quick sort.

Two Pointers

```
1 // This function returns if a pair exist with given sum S using two
  pointers method
2 bool pairExists(int arr[], int n, int S){
3     // Here i and j are our two pointers
4     int i = 0;
5     int j = n-1
6     while( i < j)
7     {
8         curr_sum = arr[i] + arr[j];
9         if ( curr_sum == S){
10             return true;
11         }else if ( curr_sum < X ){
12             i = i + 1;
13         }else if ( curr_sum > X ){
14             j = j - 1
15         }
16     }
17     return false;
18 }
```

References

Figures for insertion sort : <https://www.programiz.com/dsa/insertion-sort>

Quick Sort Algorithm's Code : <https://www.programiz.com/dsa/quick-sort>

(Changed partially)

Prefix Sum: <https://iq.opengenus.org/prefix-sum-array/>

<https://www.geeksforgeeks.org/prefix-sum-array-implementation-applications-competitive-programming/>

Two Pointers: <https://afteracademy.com/blog/what-is-the-two-pointer-technique>