

Bill Cai

Machine Learning Engineer, Cloud Architect

Work Experience

- Sep 2019
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Present
- **Engineering Lead, Machine Learning Architect**
Data Science and AI Division, Government Technology Agency Singapore
 - Govtech Singapore is the technology arm of the Singapore government. The Video Analytics team works on developing and deploying computer vision and video understanding models for social good.
 - Lead for AI modelling efforts in few-shot object detection, video activity recognition, and captioning models. Deployed and implemented using REST APIs in Python, with K8s backends for infrastructure abstraction.
 - Tech lead on 24/7 COVID-19 crowd analytics project for 200+ cameras deployed on AWS. Designed and implemented full Terraform infrastructure-as-code, serverless architecture using AWS Lambda, API Gateway, and cloud-native solutions including AWS Rekognition, S3, ECR, API Gateway.
 - Main cloud architect and DevSecOps lead for large-scale end-to-end cloud-native computer vision platform for image and video analytics. Designed fully security-compliant system, and main representative for successfully completed 3rd party security assessment for IM8 and security risk assessment.
 - Extensive use and knowledge of cloud-native tools, as well as building customised toolkits around them. Including customised Kubernetes jobs for video analytics, automating Docker image vulnerability scans as part of CICD pipelines, secure authentication for frontend automation testing.
- Sep 2018
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Sep 2019
- **Data Scientist, Computer Vision and Deep Learning**
One Concern Menlo Park, California
 - One Concern is a benevolent AI company that provides trusted insights that positively impact our communities. Our mission is to drive deep social impact through benevolent intelligence to save lives and livelihoods.
 - Lead in-house inference of key features from unstructured data. Extensive use of Keras, Tensorflow, PyTorch to build deep learning tools. Wrote and built Docker images, with deployment in Kubernetes.
 - Customization of open-source Javascript/HTML/CSS image annotation libraries, and deployment on Apache servers on AWS, with integration to Amazon Mechanical Turk.
- Sep 2017
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Sep 2018
- **Graduate Research Assistant, Computer Vision**
MIT Senseable City Lab Cambridge, Massachusetts
 - Data mining and labelling, deep learning and computer vision models training, and large-scale deployment to quantify urban canopy cover and parking utilization on large city-wide scales
 - Sensor-fusion of lidar and camera data for obstacle detection in autonomous marine vehicle applications in Amsterdam and Boston/Cambridge
 - Implemented state-of-the-art CNN architectures for classification, semantic segmentation and instance segmentation, including residual network, Mask-RCNN, PSPNet. Utilized gradient class activation (Grad-CAM) maps to understand learned features
 - Extensive use of ROS, including Google Cartographer for SLAM, Velodyne lidar, IMU, USB cameras, for sponsored project by SNCF in Paris
- Jun 2017
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Sep 2017
- **Summer Associate, Product Analytics**
Thumbtack San Francisco, California
 - Built live dashboards with Python, R, SQL, Javascript/HTML/CSS to track key metrics
 - Modeled two-sided matching and dynamic marketplaces in Python. Our [engineering blog post](#) that explains more!
 - Analyzed A/B test results, including using quasi-experimental methods, to understand impact of product feature changes on customer behavior
 - Worked closely with product managers, engineers and designers to shape product decisions
- Jan 2014
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Aug 2014
- **Business Development Lead**
Arcstone Singapore
 - In-bound sales strategy and investment pitch strategy, obtained a seven figure Series AA funding from VCs

Education

- Sep 2017
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Sep 2018
- **M.S. in Computation for Design and Optimization**
Center for Computational Engineering, Massachusetts Institute of Technology Cambridge, Massachusetts
 - GPA: 5.00/5.00, thesis on applying computer vision and deep learning for large-scale quantification of urban and city dynamics (advised by [Carlo Ratti](#))
 - Selected Coursework: Advances in Computer Vision, Statistical Learning Theory and Applications, Numerical Methods in Partial Differential Equations, Optimization Methods
- Sep 2014
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Jun 2017
- **B.A. in Economics**
University of Chicago Chicago, Illinois
 - GPA: 3.87/4.00, Graduated with Phi Beta Kappa (highest honors) and Dean's List from 2014-2017
 - Selected Coursework: Planning, Learning and Estimation for AI, Machine Learning, Market Design, Inequality: A Perspective from Macroeconomics, Honors Econometrics, Applied Statistical Modeling

Contact Info

Website and Projects:

billcai.com

LinkedIn Profile:

[linkedin.com/in/billcai77](https://www.linkedin.com/in/billcai77)

Email Address:

me@billcai.com

Skills

Certified AWS Solutions Architect Professional, DevSecOps
Python, Javascript
Tensorflow, Keras, PyTorch
Docker, Kubernetes
Julia, MATLAB, R, Stata, SQL
Terraform, Selenium, Serverless

Interests

Coding, Programming
Applied Mathematics (Optimization, Numerical PDEs)
Economic Theory (Market Design, Computational Macro)
Reading (Non-fiction)
Basketball (Celtics)
Football (Arsenal)

Academic Service/Talks

NeurIPS 2020 Climate Change AI Program Committee
ICLR 2020 Climate Change AI Program Committee
Reviewer for NeurIPS 2020, ICLR 2020, IEEE Internet of Things Journal
IEEE BigData Congress 2018 Paper Presentation
MIT CCE Student Seminar 2018

Ongoing Research, Journal and Conference Publications

- Oct 2019 ● Quantifying Urban Canopy Cover with Deep Convolutional Neural Networks
[Published in NeurIPS Workshop on Climate Change AI](#)
Bill Yang Cai, Xiaojiang Li, Carlo Ratti
- Dec 2018 ● Quantifying Legibility in Indoor Spaces Using Deep Convolutional Neural Networks: A Case Study in Train Stations
[Published in Building and Environment](#)
Wang Zhoutong, Liang Qianhui, **Bill Yang Cai**, Louis Charron, Fabio Duarte, Carlo Ratti
- Dec 2018 ● Deep Learning Architect: Classification for Architectural Design through the Eye of Artificial Intelligence
[Published in Computational Urban Planning and Management for Smart Cities](#)
Yuji Yoshimura, **Bill Yang Cai**, Wang Zhoutong, Carlo Ratti
- Aug 2018 ● Deep Learning Based Video System for Accurate and Real-Time Parking Measurement
[Published in IEEE Internet of Things Journal](#)
[Special Issue on Enabling a Smart City: Internet of Things Meets AI](#)
Bill Yang Cai, Ricardo Alvarez, Michelle Sit, Fabio Duarte, Carlo Ratti
- Apr 2018 ● Treepedia 2.0: Applying Deep Learning for Large-scale Quantification of Urban Tree Cover
[Published in IEEE BigData Congress 2018](#), [arXiv preprint](#)
Bill Yang Cai, Xiaojiang Li, Ian Seiferling, Carlo Ratti
- Feb 2018 ● Using Street-level Images and Deep Learning for Urban Landscape Analysis
[Published in Landscape Architecture Frontiers](#)
Xiaojiang Li, **Bill Yang Cai**, Carlo Ratti

Research Projects

- Sep 2017 | Sep 2018 ● [Treepedia](#)
Role: Computer Vision and Deep Learning Lead
Treepedia is a project by the MIT Senseable City Lab in partnership with the World Economic Forum to measure canopy cover and green spaces in cities globally. This project has inspired planners and policymakers to design greener cities, and has been featured on the [Wall Street Journal](#), [Time](#), [Wired](#), and [Forbes](#). I developed the Tensorflow-based deep learning algorithms used to detect and quantify canopy cover from Google Street View images, from data annotation to model training/hyperparameter tuning to eventual [trained model/library](#).
- Jan 2018 | Sep 2018 ● [Roboat](#)
Role: Computer Vision Engineer
Roboat is a 5 year research project and collaboration between the Amsterdam Institute for Advanced Metropolitan Solutions and MIT to develop the world's first fleet of urban autonomous floating vessels. Our project has been featured on [CNBC](#), [The Verge](#), [Reuters](#), [Quartz](#), and [Fortune](#). I tuned and deployed Tensorflow-based instance segmentation and object detection models on boat-based GPUs/mini PCs to detect live obstacles, and provide estimated obstacle locations and types to the ROS-based motion planner.
- Apr 2018 | Sep 2018 ● [Space Legibility](#)
Role: Robotics and Computer Vision Lead
Space Legibility is a 2 year project between SNCF, France's national state-owned railway company, and MIT to investigate the interactions between space design and commuter usage in train stations based in Paris. I adapted [Google's ROS-based Cartographer library](#) which uses our lab's Velodyne VLP16 Lidar and IMU, in order to provide dense 3D maps of train stations in Paris (Gare De Lyon, Gare St Lazare) as well as MIT's famous infinite corridor.