

Bill Cai

Computer Vision Engineer, Data Scientist

Work Experience

Sep
2018
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Present

Data Scientist, Computer Vision and Deep Learning

One Concern

Menlo Park, California

- One Concern is a benevolent AI company that provides trusted insights that positively impact our communities. Our mission is to drive deep social impact through benevolent intelligence to save lives and livelihoods.
- Technical lead for in-house project to infer built environment and socio-economic features of cities using satellite images. Extensive use of Keras, Tensorflow, PyTorch for deep learning tools. Wrote and built Docker images, with deployment in Kubernetes clusters.
- Coordinated data needs across seismic, flood and wildfire products, and provided technical oversight to deep learning efforts in wildfire prediction and flood modelling projects.
- Customization of open-source Javascript/HTML/CSS image annotation libraries, and deployment on Apache servers on AWS, with integration to Amazon Mechanical Turk.

Sep
2017
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Sep
2018

Graduate Research Assistant, Computer Vision

MIT Senseable City Lab

Cambridge, Massachusetts

- Data mining and labelling, deep learning and computer vision models training, and large-scale deployment to quantify urban canopy cover and parking utilization on large city-wide scales
- Sensor-fusion of lidar and camera data for obstacle detection in autonomous marine vehicle applications in Amsterdam and Boston/Cambridge
- Implemented state-of-the-art CNN architectures for classification, semantic segmentation and instance segmentation, including residual network, Mask-RCNN, PSPNet. Utilized gradient class activation (Grad-CAM) maps to understand learned features
- Extensive use of ROS, including Google Cartographer for SLAM, Velodyne lidar, IMU, USB cameras, for sponsored project by SNCF in Paris

Jun
2017
|
Sep
2017

Summer Associate, Product Analytics

Thumbtack

San Francisco, California

- Built live dashboards with Python, R, SQL, Javascript/HTML/CSS to track key metrics
- Modeled two-sided matching and dynamic marketplaces in Python. Our [engineering blog post](#) that explains more!
- Analyzed A/B test results to understand impact of product feature changes on customer behavior
- Worked closely with product managers, engineers and designers to shape product decisions

Jun
2016
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Sep
2016

Intern, Social Programmes Directorate

Ministry of Finance

Singapore

- Completed an in-depth study of Singapore's in-depth voluntary retirement scheme and designed A/B testing of potential improvements. Presented findings to Permanent Secretaries

Jun
2015
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Sep
2015

Intern, Futures and Strategy Division

Ministry of Trade and Industry

Singapore

- Analyzed and investigated emerging strategic issues to inform strategic planning

Jan
2014
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Aug
2014

Business Development Lead

Arcstone

Singapore

- Led pitching and sourcing efforts, obtained a seven figure Series AA funding from VCs

Education

Sep
2017
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Sep
2018

M.S. in Computation for Design and Optimization

Center for Computational Engineering, Massachusetts Institute of Technology

Cambridge, Massachusetts

- GPA: 5.00/5.00, thesis on applying computer vision and deep learning for large-scale quantification of urban and city dynamics (advised by [Carlo Ratti](#))
- Selected Coursework: Advances in Computer Vision, Statistical Learning Theory and Applications, Numerical Methods in Partial Differential Equations, Optimization Methods

Sep
2014
|
Jun
2017

B.A. in Economics

University of Chicago

Chicago, Illinois

- GPA: 3.87/4.00, Graduated with Phi Beta Kappa (highest honors) and Dean's List from 2014-2017
- Selected Coursework: Planning, Learning and Estimation for AI, Machine Learning, Market Design, Inequality: A Perspective from Macroeconomics, Honors Econometrics, Applied Statistical Modeling

Contact Info

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Skills

Python

Tensorflow, Keras, PyTorch

Docker, Kubernetes

Julia, MATLAB, R, Stata, SQL

AWS (EC2, RDS, S3), AWS CLI

ROS, C/C++

Flask, HTML/CSS

Interests

Coding, Programming

Applied Mathematics

(Optimization, Numerical PDEs)

Economic Theory (Market

Design, Computational Macro)

Reading (Non-fiction)

Basketball (Celtics)

Football (Arsenal)

Presentation and Talks

IEEE BigData Congress 2018

Paper Presentation

MIT CCE Student Seminar 2018

Ongoing Research, Journal and Conference Publications

- Dec 2018
Quantifying Legibility in Indoor Spaces Using Deep Convolutional Neural Networks: A Case Study in Train Stations
Submitted to Environment and Planning B: Planning and Design
Wang Zhoutong, Liang Qianhui, **Bill Yang Cai**, Louis Charron, Fabio Duarte, Carlo Ratti
- Dec 2018
Deep Learning Architect: Classification for Architectural Design through the Eye of Artificial Intelligence
Submitted to Environment and Planning B: Planning and Design, [arXiv preprint](#)
Yuji Yoshimura, **Bill Yang Cai**, Wang Zhoutong, Carlo Ratti
- Aug 2018
Deep Learning Based Video System for Accurate and Real-Time Parking Measurement
Accepted in IEEE Internet of Things Journal
Special Issue on Enabling a Smart City: Internet of Things Meets AI
Bill Yang Cai, Ricardo Alvarez, Michelle Sit, Fabio Duarte, Carlo Ratti
- Apr 2018
Treepedia 2.0: Applying Deep Learning for Large-scale Quantification of Urban Tree Cover
Published in IEEE BigData Congress 2018, [arXiv preprint](#)
Bill Yang Cai, Xiaojiang Li, Ian Seiferling, Carlo Ratti
- Feb 2018
Using Street-level Images and Deep Learning for Urban Landscape Analysis
Published in Landscape Architecture Frontiers
Xiaojiang Li, **Bill Yang Cai**, Carlo Ratti

Research Projects

- Sep 2017
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Sep 2018
[Treepedia](#)
Role: Computer Vision and Deep Learning Lead
Treepedia is a project by the MIT Senseable City Lab in partnership with the World Economic Forum to measure canopy cover and green spaces in cities globally. This project has inspired planners and policymakers to design greener cities, and has been featured on the [Wall Street Journal](#), [Time](#), [Wired](#), and [Forbes](#). I developed the Tensorflow-based deep learning algorithms used to detect and quantify canopy cover from Google Street View images, from data annotation to model training/hyperparameter tuning to eventual [trained model/library](#).
- Jan 2018
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Sep 2018
[Roboat](#)
Role: Computer Vision Engineer
Roboat is a 5 year research project and collaboration between the Amsterdam Institute for Advanced Metropolitan Solutions and MIT to develop the world's first fleet of urban autonomous floating vessels. Our project has been featured on [CNBC](#), [The Verge](#), [Reuters](#), [Quartz](#), and [Fortune](#). I tuned and deployed Tensorflow-based instance segmentation and object detection models on boat-based GPUs/mini PCs to detect live obstacles, and provide estimated obstacle locations and types to the ROS-based motion planner.
- Apr 2018
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Sep 2018
[Space Legibility](#)
Role: Robotics and Computer Vision Lead
Space Legibility is a 2 year project between SNCF, France's national state-owned railway company, and MIT to investigate the interactions between space design and commuter usage in train stations based in Paris. I adapted [Google's ROS-based Cartographer library](#) which uses our lab's Velodyne VLP16 Lidar and IMU, in order to provide dense 3D maps of train stations in Paris (Gare De Lyon, Gare St Lazare) as well as MIT's famous infinite corridor.