

## 4 Class8-10 Illumination and Shading

### 1. Global vs. Local Illumination

Global: Models indirect illumination and occlusions Local: Only models direct illumination

### 2. Irradiance

$$E = \int_{\Omega} I(x, \omega) \cos \theta d\omega$$

Note:  $I(x, \omega)$  is the light intensity arriving from all directions and entering the hemisphere  $\Omega$  over unit surface area.

Also we only care the vertical(normal) part of the light, we dismiss all lights parallel to the surface by using  $\cos \theta$

### 3. Simplified lighting:

Assume all lights are distant-point light.

- Source have **uniform** intensity distribution
- Neglect distance fallout
- Direction to source is constant within scene
- Using 2 parameters to define a light:  
*direction*( $x, y, z$ ) vector from surface to light source  
*intensity*( $r, g, b$ ) of the light

### 4. specular reflection and diffuse reflection

- Color shift by attenuation of RGB components for all reflection
- Specular Reflection Model(View-Dependent):

$$L_j(V) = L_e \cdot K_s \cdot (V \cdot R)^{spec}$$

$$R = 2(N \cdot L)N - L$$

Note:  $V$  and  $R$  should be normalized.

Direction: Reflection occurs mainly in the "mirror"  $R$  direction, but there is some spread in similar directions  $V$ .

*spec* controls the distribution of intensity about  $R$ . Higher value of *spec* make the surface smoother

$K_s$  controls the color attenuation of Surface.

- Diffuse Reflection Models(View-Independent):

$$L_j = L_e \cdot K_d (L \cdot N)$$

Direction: All **output** directions are the same. But we only care vertical **input** light.

$L$  and  $N$  should be normalized.

$K_d$  is the surface attenuation component.

- Ambient Light

$$L_j = L_a \cdot K_a$$

Direction: All input and output directions are the same.

Only one ambient light is needed and allowed.

- Complete Shading Equation:

$$Color = (K_s \sum L_e \cdot (V \cdot R)^{spec}) + (K_d \sum L_e \cdot (L \cdot N)) + (L_a \cdot K_a)$$

### 5. Detail about HW4(Lighting Implementation)

- $\vec{L}$  denotes the direction to a infinity-far point-light source
- $\vec{E}$  denotes the camera direction. If camera is far away,  $\vec{E}$  is constant(In HW4.)
- $\vec{N}$  is specified at triangle vertices.
- $\vec{R}$  must be computed for each lighting calculation (at **a point**).  
Calculation of  $\vec{R}$ :

$$\vec{R} = 2(\vec{N} \cdot \vec{L})\vec{N} - \vec{L}$$

Avoiding sqrt-root in this calculation

- Choosing a Shading Space: We need all  $\vec{L}, \vec{E}, \vec{N}, \vec{R}$  in some affine(pre-perspective) space  
Suggest use **Image Space** for HW4.  
**Model space** is also a reasonable choice since Normal vectors are already in that space. This is most **efficient!**
- **Image Space Lighting (ISL)**  
Create a Transformation stack from model space to image space.  
Need to **normalized the Scale and delete translation** for each matrix, **only maintain the rotation**, before push into this stack!
- **Check** the sign of  $\vec{N} \cdot \vec{E}$  and  $\vec{N} \cdot \vec{L}$ :  
Both positive: Compute lighting model.  
Both negative: **Flip normal**( $\vec{N}$ ) and compute lighting model.  
Different sign: Skip it.
- **Check** the sign of  $\vec{R} \cdot \vec{E}$ : If negative, set to 0.
- **Check** color overflow(> 1.0): Set to 1.
- **Compute Color** at all pixels:  
**Per Face** - flat shading  
**Per Vertex** - interpolate vertex colors, Gouraud Shading(specular highlights are undersampled, aliased).  
**Per Pixel** - interpolate normals, Phong Shading (Expensive computation, but better sampling)  
Set **Shading Modes Parameter** for different lighting calculation.
- **Pitfall in Phong** Interpolation:  
Need to **normalize** the interpolation normal vector.

## 4.1 Class10: Something More About Shading

### 1. Non-Uniform Scaling:

**A non-uniform scaling alters the relationship between the surface orientation and the Normal Vector.**

So we **cannot** use the same matrix M for transformation of the Normals and the vertex coordinates.

We can fix this by using a different transformation  $Q = f(M)$  for transforming the Normals.

### 2. How to create a matrix for Normals:

In HW4, We create a matrix **dismiss all** scale matrix.

For Detail:

As the definition of Normals:

$$\vec{N}^T \cdot \vec{P} = 0$$

After include the transform matrix:

$$(Q\vec{N})^T \cdot (M\vec{P}) = 0$$

By Definition of Matrix Multiplier:

$$\vec{N}^T \cdot Q^T \cdot M \cdot \vec{P} = 0$$

Since we already know  $\vec{N}^T \cdot \vec{P} = 0$  we only need the inner part equal to identity matrix:

$$Q^T \cdot M = I, Q = (M^{-1})^T$$

Note that: If we only used uniform scaling:  $S = I$  after normalization.

If we compute  $Q$  for each  $M$  pushed on the  $X_{im}$  transform stack, the resulting  $X_n$  stack has  $Q$  and therefore allows non-uniform scaling.

### 3. Model Space Lighting(MSL):

Only need to transform Global lighting parameters once per models.

Also need to transform Eye/camera direction into model space.

## 5 Class 11-13: Texture Mapping

### 5.1 Screen-Space Parameter Interpolation

1. In Z-buffer interpolation, we know that linear interpolation for  $z$  is **wrong in image space**, we need to interpolate in **perspective space**.
2. Accurate interpolation of RGB color or Normal vectors should also take perspective into account. But we can ignore the color and normal interpolation error.
3. Interpolation for **Texture Function**: checkerboard Example: Using Linear Interpolation for  $u$  &  $v$  is also wrong!
4. How to compute perspective-correct interpolation of  $u, v$  at each pixel.

- For each parameter  $P$ , we used  $P^s$  to denote the value in perspective space.
- Note that: For Z interpolation  $V_z^s = \frac{V_z}{\frac{V_z}{d} + 1} = \frac{V_z \cdot d}{V_z + d}$
- Rescale  $V_z^s$  to  $V_z^s \in [0, Z_{max}]$

$$V_z^s = \frac{V_z \cdot d}{V_z + d} \cdot \left(\frac{Z_{max}}{d}\right) = \frac{V_z \cdot Z_{max}}{V_z + d}$$

- We can also get the invert equation:

$$V_z = \frac{V_z^s \cdot d}{Z_{max} - V_z^s}$$

- For parameter from image space to perspective space:

$$P^s = \frac{P}{\frac{V_z}{d} + 1} = \frac{Pd}{V_z + d}$$

- Also we can get inver equation:

$$P = \frac{P^s(V_z + d)}{d}$$

- We don't have  $V_z$  but we already calculated  $V_z^s$  in HW2, so we can used that:

$$P^s = \frac{P}{\left(\frac{V_z^s}{Z_{max} - V_z^s} + 1\right)}$$

$$P = P^s \cdot \frac{V_z^s}{Z_{max} - V_z^s} + 1$$

- Note that we only have  $V_z^s$  and  $Z_{max}$  in this equation that we already know the value, we don't need to care  $d$  and some other parameter.
- We used  $V_z' = \frac{V_z^s}{Z_{max} - V_z^s}$  to simplify the equation:

$$P^s = \frac{P}{V_z' + 1}$$

$$P = P^s \cdot (V_z' + 1)$$

5. The Step for Parameter interpolation:

Get  $V_z^P$  for each vertex.

Transform  $P$  to perspective space  $P^s$  for each vertex.

Interpolate  $V_z^P$  for each pixel.

Interpolate  $P^s$  for each pixel.

Transform  $P^s$  back to  $P$  by using  $V_z^P$  for each pixel.

## 5.2 Texture

1. Scale  $u, v$  to Texture Image Size:

$(u, v)$  coords range over  $[0, 1]$

2D Image is a pixel array of  $xs - 1, ys - 1$

But  $u * (xs - 1)$  might not be Integer so we need to interpolate the color for non-Integer  $(u, v)$  coordinate from nearest 4 Integer point.

$$Color(p) = (1 - s)(1 - t)A + s(1 - t)B + stC + (1 - s)tD$$

2. For Phong Shading, using texture function  $f(u, v)$  to replace  $k_d$  and  $k_a$
3. For Gouraud Shading, using  $f(u, v)$  to replace all  $k_s, k_d$  and  $k_a$
4. Procedural Texture
5. Bump Texture: Alter normals at each pixel to create bump.
6. Noise Texture: 3D Noise Volume, Tubulence
7. Environment(Reflection) Mapping: Cube Map  
Problems: Sampling problems and high curvature problems

## 5.3 Implementation Of Textutre(HW5)

1. Step1: Texture coordinates: surface point  $\rightarrow (u, v)$   
Input: vertex in image space  
Output:  $(u, v)$
2. Step2:  $(u, v) \rightarrow$  RGB color  
Input:  $(u, v)$  Output: RGB color from image LUT
3. Interpolation of  $(u, v)$  need to be in perspective space.
4. Interpolation of 4-corner for non-Integer  $(u, v)$  is needed.

## 6 Class14-15 Antialiasing

### 6.1 The Source of Aliasing

1. Quantization error arise from insufficient accuracy of sample
2. Aliasing error arise from insufficient samples
3. Nyquist Theorem: Sample at least twice the rate of highest frequency present in the signal.  
f(t) filtered for cutoff freq  $\omega_F$  (Remove high frequencies before sampling)  
Sample Rate  $\frac{1}{T_0}$  is greater than  $2\omega_F$   
Reconsturct(interpolate) with *sinc* function
4. Solution: Band-limit the input signal before sampling.

### 6.2 Implement Antialiasing(HW6)

1. Antialiasing by jitter supersampling
2. Sample a pixel several with different center and weight