view_frames Result Recorded at time: 1548892634.283 base_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1548892634.283 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1548892634.283 sec old) Buffer length: 0.000 sec top_box_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1548892634.283 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec laser_spinning_lidar_root_link Broadcaster: /camera_base_link1 Average rate: 10000.000 Hz Most recent transform: 0.000 (1548892634.283 sec old) Buffer length: 0.000 sec

