

Calculations for Transverse and Truncated ray transform pseudo differential operators.

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(\* Use Alt 7 to make cells into comments \*)

Tensor product

**outer** = **Function**[{**t1**, **t2**}, **Outer**[**Times**, **t1**, **t2**]]

General::spell1: Possible spelling error: new  
symbol name "outer" is similar to existing symbol "Outer". More...

**Function**[{**t1**, **t2**}, **Outer**[**Times**, **t1**, **t2**]]

We want to make general symmetric rank two tensors as variables

**AA** = **Table**[**a**<sub>{i,j}</sub>, {**i**, 1, 3}, {**j**, 1, 3}]

{ {**a**<sub>{1,1}</sub>, **a**<sub>{1,2}</sub>, **a**<sub>{1,3}</sub>}, {**a**<sub>{2,1}</sub>, **a**<sub>{2,2}</sub>, **a**<sub>{2,3}</sub>}, {**a**<sub>{3,1}</sub>, **a**<sub>{3,2}</sub>, **a**<sub>{3,3}</sub>}}

Now make it symmetric matrix by hand

**A** = {{**a**<sub>{1,1}</sub>, **a**<sub>{1,2}</sub>, **a**<sub>{1,3}</sub>}, {**a**<sub>{1,2}</sub>, **a**<sub>{2,2}</sub>, **a**<sub>{2,3}</sub>}, {**a**<sub>{1,3}</sub>, **a**<sub>{2,3}</sub>, **a**<sub>{3,3}</sub>}}

{ {**a**<sub>{1,1}</sub>, **a**<sub>{1,2}</sub>, **a**<sub>{1,3}</sub>}, {**a**<sub>{1,2}</sub>, **a**<sub>{2,2}</sub>, **a**<sub>{2,3}</sub>}, {**a**<sub>{1,3}</sub>, **a**<sub>{2,3}</sub>, **a**<sub>{3,3}</sub>}}

**A** // **MatrixForm**

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

**Y** will be the FT variable

**Y** = {**Y**<sub>1</sub>, **Y**<sub>2</sub>, **Y**<sub>3</sub>}

{**Y**<sub>1</sub>, **Y**<sub>2</sub>, **Y**<sub>3</sub>}

Some times we want to check what happens when we substitute for a specific choice of **Y**. This is used mainly when something doesnt work and it is usually clear what is wrong by making this substitution rather than looking at an enormous expression in **ys**

**Y** /. {**y**<sub>1</sub> → 0, **y**<sub>2</sub> → 0, **y**<sub>3</sub> → 1}

{0, 0, 1}

Functions for d and delta in the FT variable normalized by powers of Laplacian (as these commute thats ok)

$\delta^2$

**delta2** = **Function**[**h**, **Y.h.Y** / (**Y.Y**)]

**Function**[**h**,  $\frac{\mathbf{Y.h.Y}}{\mathbf{Y.Y}}$ ]

**delta2**[**A**]

$$\frac{1}{Y_1^2 + Y_2^2 + Y_3^2} (Y_1 (a_{\{1,1\}} Y_1 + a_{\{1,2\}} Y_2 + a_{\{1,3\}} Y_3) + Y_2 (a_{\{1,2\}} Y_1 + a_{\{2,2\}} Y_2 + a_{\{2,3\}} Y_3) + Y_3 (a_{\{1,3\}} Y_1 + a_{\{2,3\}} Y_2 + a_{\{3,3\}} Y_3))$$

**d** $\delta$

```
ddelta = Function[h, (outer[Y, Y].h + h.outer[Y, Y]) / (2 (Y.Y)) // Simplify]
```

```
Function[h, Simplify[ $\frac{\text{outer}[Y, Y].h + h.\text{outer}[Y, Y]}{2 Y.Y}$ ]]]
```

```
ddelta[A] // MatrixForm
```

$$\begin{pmatrix} \frac{Y_1 (a_{(1,1)} Y_1 + a_{(1,2)} Y_2 + a_{(1,3)} Y_3)}{Y_1^2 + Y_2^2 + Y_3^2} & \frac{a_{(1,1)} Y_1 Y_2 + a_{(2,2)} Y_1 Y_2 + a_{(1,2)} (Y_1^2 + Y_2^2) + a_{(2,3)} Y_1 Y_3 + a_{(1,3)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{a_{(2,3)} Y_1 Y_2 + a_{(1,3)} Y_1 Y_3 + a_{(2,2)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{a_{(1,1)} Y_1 Y_2 + a_{(2,2)} Y_1 Y_2 + a_{(1,2)} (Y_1^2 + Y_2^2) + a_{(2,3)} Y_1 Y_3 + a_{(1,3)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{Y_2 (a_{(1,2)} Y_1 + a_{(2,2)} Y_2 + a_{(2,3)} Y_3)}{Y_1^2 + Y_2^2 + Y_3^2} & \frac{a_{(1,3)} Y_1 Y_2 + a_{(2,3)} Y_1 Y_3 + a_{(2,2)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{a_{(2,3)} Y_1 Y_2 + a_{(1,3)} Y_1 Y_3 + a_{(2,2)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{a_{(1,3)} Y_1 Y_2 + a_{(2,3)} Y_1 Y_3 + a_{(2,2)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{a_{(2,3)} Y_1 Y_2 + a_{(1,3)} Y_1 Y_3 + a_{(2,2)} Y_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \end{pmatrix}$$

$d^2 \delta^2$

```
d2delat2 = Function[h, delta2[h] outer[Y, Y] / (Y.Y) // Simplify]
```

```
Function[h, Simplify[ $\frac{\text{delta2}[h] \text{outer}[Y, Y]}{Y.Y}$ ]]]
```

```
d2delta2 = Function[h, Simplify[delta2[h] outer[Y, Y] / (Y.Y)]]
```

General::spell1: Possible spelling error: new symbol name "d2delta2" is similar to existing symbol "d2delat2". More...

```
Function[h, Simplify[ $\frac{\text{delta2}[h] \text{outer}[Y, Y]}{Y.Y}$ ]]]
```

```
d2delta2[A] // MatrixForm
```

$$\begin{pmatrix} \frac{Y_1^2 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_1 Y_2 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_1 Y_3 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} \\ \frac{Y_1 Y_2 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_2^2 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_2 Y_3 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} \\ \frac{Y_1 Y_3 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_2 Y_3 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} & \frac{Y_3^2 (a_{(1,1)} Y_1^2 + 2 a_{(1,2)} Y_1 Y_2 + a_{(2,2)} Y_2^2 + 2 a_{(1,3)} Y_1 Y_3 + 2 a_{(2,3)} Y_2 Y_3 + a_{(3,3)} Y_3^2)}{(Y_1^2 + Y_2^2 + Y_3^2)^2} \end{pmatrix}$$

Check some identities

```
Simplify[ddelta[d2delta2[A]] - d2delta2[A]] // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```
Simplify[ddelta[ddelta[A]] - ddelta[A] / 2 - d2delta2[A] / 2] // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```
ddelta[ddelta[A]] - (1/2) (ddelta[A] + d2delta2[A]) // Simplify
```

```
{{0, 0, 0}, {0, 0, 0}, {0, 0, 0}}
```

```
d2delta2[d2delta2[A]] - d2delta2[A] // Simplify
```

```
{{0, 0, 0}, {0, 0, 0}, {0, 0, 0}}
```

```
ddelta[ddelta[A]] - (1/2) ddelta[A] - (1/2) d2delta2[A] // Simplify
```

```
{{0, 0, 0}, {0, 0, 0}, {0, 0, 0}}
```

```
d2delat2[d2delta2[A]] - d2delta2[A] // Simplify
```

```
{{0, 0, 0}, {0, 0, 0}, {0, 0, 0}}
```

```
ddelta[eye delta2[A]] - d2delta2[A]
```

[illegible]





```
ddelta[eye delta2[A]] - d2delta2[A] // Simplify // MatrixForm
```

$$\begin{pmatrix} \left\{ \{Y_1^2, Y_1 Y_2, Y_1 Y_3\}, \{Y_1 Y_2, Y_2^2, Y_2 Y_3\}, \{Y_1 Y_3, Y_2 Y_3, Y_3^2\} \right\} \cdot \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 + 2 a_{[1,3]} Y_1 Y_3 + 2 a_{[2,3]} Y_2 Y_3 + a_{[3,3]} Y_3^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} + \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} \\ \left\{ \{Y_1^2, Y_1 Y_2, Y_1 Y_3\}, \{Y_1 Y_2, Y_2^2, Y_2 Y_3\}, \{Y_1 Y_3, Y_2 Y_3, Y_3^2\} \right\} \cdot \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 + 2 a_{[1,3]} Y_1 Y_3 + 2 a_{[2,3]} Y_2 Y_3 + a_{[3,3]} Y_3^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} + \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} \\ \left\{ \{Y_1^2, Y_1 Y_2, Y_1 Y_3\}, \{Y_1 Y_2, Y_2^2, Y_2 Y_3\}, \{Y_1 Y_3, Y_2 Y_3, Y_3^2\} \right\} \cdot \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 + 2 a_{[1,3]} Y_1 Y_3 + 2 a_{[2,3]} Y_2 Y_3 + a_{[3,3]} Y_3^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} + \frac{\text{eye} \left( a_{[1,1]} Y_1^2 + 2 a_{[1,2]} Y_1 Y_2 + a_{[2,2]} Y_2^2 \right)}{Y_1^2 + Y_2^2 + Y_3^2} \end{pmatrix}$$

Now checking that I can do 6.6.10 and 6.6.11 with MMA. First 6.6.10 define operators. This is my  $\Pi$  as an operator, Sharafutdinov's  $\varepsilon$

```
Proj = Function[a, a - outer[Y, Y].a / (Y.Y)]
```

$$\text{Function}\left[a, a - \frac{\text{outer}[Y, Y].a}{Y.Y}\right]$$

And  $\Pi$  as a matrix

```
Projm = Proj[IdentityMatrix[3]]
```

```
General::spell1:
```

Possible spelling error: new symbol name "Projm" is similar to existing symbol "Proj". More...

$$\left\{ \left\{ 1 - \frac{Y_1^2}{Y_1^2 + Y_2^2 + Y_3^2}, -\frac{Y_1 Y_2}{Y_1^2 + Y_2^2 + Y_3^2}, -\frac{Y_1 Y_3}{Y_1^2 + Y_2^2 + Y_3^2} \right\}, \left\{ -\frac{Y_1 Y_2}{Y_1^2 + Y_2^2 + Y_3^2}, 1 - \frac{Y_2^2}{Y_1^2 + Y_2^2 + Y_3^2}, -\frac{Y_2 Y_3}{Y_1^2 + Y_2^2 + Y_3^2} \right\}, \left\{ -\frac{Y_1 Y_3}{Y_1^2 + Y_2^2 + Y_3^2}, -\frac{Y_2 Y_3}{Y_1^2 + Y_2^2 + Y_3^2}, 1 - \frac{Y_3^2}{Y_1^2 + Y_2^2 + Y_3^2} \right\} \right\}$$

This is my tilde  $\Pi$  or Sharafutdinov's  $\varepsilon_2$ .

```
Proj2 = Function[a, (2 / 3) (Projm.a.Projm) + (1 / 3) Tr[Projm.a] Projm]
```

$$\text{Function}\left[a, \frac{2 \text{Projm.a.Projm}}{3} + \frac{1}{3} \text{Tr}[\text{Projm.a}] \text{Projm}\right]$$

The set of permutations on three symbols

```
perms = Permutations[{i, j, k, l}]
```

```
{ {i, j, k, l}, {i, j, l, k}, {i, k, j, l}, {i, k, l, j}, {i, l, j, k}, {i, l, k, j},
  {j, i, k, l}, {j, i, l, k}, {j, k, i, l}, {j, k, l, i}, {j, l, i, k}, {j, l, k, i},
  {k, i, j, l}, {k, i, l, j}, {k, j, i, l}, {k, j, l, i}, {k, l, i, j}, {k, l, j, i},
  {l, i, j, k}, {l, i, k, j}, {l, j, i, k}, {l, j, k, i}, {l, k, i, j}, {l, k, j, i}}
```

Here is the official definition of epsilon2 using symmetry

ie  $(1/24) \sum_{\pi} \sum_i \sum_j \Pi_{\pi(i)\pi(j)} \Pi_{\pi(k)\pi(l)} A_{ij}$

```
Proj2test = (1 / 24)
```

```
Table[Sum[Sum[Sum[ Projm[[perms[[m, 1]], perms[[m, 2]]]] Projm[[perms[[m, 3]],
  perms[[m, 4]]]] A[[i, j]], {i, 3}], {j, 3}], {m, 24}], {k, 3}, {l, 3}];
```

```
Proj2test - Proj2[A] // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Also notice the formula

```
Proj2[A] - ( (2 / 3) A + (-2 / 3) (outer[Y, Y].A + A.outer[Y, Y]) / (Y.Y) +
  (1 / 3) Tr[A] IdentityMatrix[3] + (1) (Y.A.Y) outer[Y, Y] +
  (-1 / 3) (Y.A.Y) IdentityMatrix[3] / (Y.Y) + (-1 / 3) Tr[A] outer[Y, Y] / (Y.Y)) /.
  {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```
eye = IdentityMatrix[3]; YoY = outer[Y, Y] / (Y.Y);
```

```
Proj2[A] - ( (2 / 3) A - (2 / 3) (YoY.A + A.YoY) + (Y.A.Y) YoY / (Y.Y) + (1 / 3) (Tr[A]) eye -
  (1 / 3) Y.A.Y / (Y.Y) eye - (1 / 3) (Tr[A]) YoY) // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

We have now checked the formula for curly pi a.k.a epsilon2.

Now for 6.6.10

```
D2i = Function[a, a - (1 / 2) (a.Projm + Projm.a) +
  (3 / 16) Proj2[a] + (1 / 4) Tr[Projm.a] IdentityMatrix[3]]
```

```
Function[a, a -  $\frac{1}{2}$  (a.Projm + Projm.a) +  $\frac{3 \text{Proj2}[a]}{16}$  +  $\frac{1}{4}$  Tr[Projm.a] IdentityMatrix[3]]
```

```
D2iY = Function[a, (1 / 8) a + (3 / 8) (outer[Y, Y].a + a.outer[Y, Y]) / (Y.Y) +
  (3 / 16) (Y.a.Y) outer[Y, Y] / ((Y.Y)^2) + (-5 / 16) (Y.a.Y) IdentityMatrix[3] / (Y.Y)]
```

General::spell1:

Possible spelling error: new symbol name "D2iY" is similar to existing symbol "D2i". More...

```
Function[a,
```

$$\frac{a}{8} + \frac{3 (\text{outer}[Y, Y].a + a.\text{outer}[Y, Y])}{8 Y.Y} + \frac{3 Y.a.Y \text{outer}[Y, Y]}{16 (Y.Y)^2} - \frac{5 Y.a.Y \text{IdentityMatrix}[3]}{16 Y.Y}$$

```
(D2i[Atf] - D2iY[Atf]) /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm
```

$$\begin{pmatrix} \frac{1}{16} (14 \text{Atf} - 6 \text{Atf}.\{\{0, 0, 0\}, \{0, 0, 0\}, \{0, 0, 1\}\} - 8 \text{Atf}.\{\{1, 0, 0\}, \{0, 1, 0\}, \{0, 0, 0\}\} - 6 \\ \frac{1}{8} (7 \text{Atf} - 3 \text{Atf}.\{\{0, 0, 0\}, \{0, 0, 0\}, \{0, 0, 1\}\} - 4 \text{Atf}.) \\ \frac{1}{8} (7 \text{Atf} - 3 \text{Atf}.\{\{0, 0, 0\}, \{0, 0, 0\}, \{0, 0, 1\}\} - 4 \text{Atf}.) \end{pmatrix}$$

And here is 6.6.11

```
D2 = Function[a, 2 (4 a - 3 (a.outer[Y, Y] / (Y.Y) + outer[Y, Y].a / (Y.Y)) +
  (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + (5 / 3) (Y.a.Y) IdentityMatrix[3] / (Y.Y))]
```

```
Function[a, 2
```

$$\left( 4a - 3 \left( \frac{a.\text{outer}[Y, Y]}{Y.Y} + \frac{\text{outer}[Y, Y].a}{Y.Y} \right) + \frac{Y.a.Y \text{outer}[Y, Y]}{(Y.Y)^2} + \frac{5 Y.a.Y \text{IdentityMatrix}[3]}{3 Y.Y} \right)$$

```
D2[D2i[A]] /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm
```

$$\begin{pmatrix} \frac{1}{3} (13 a_{\{1,1\}} + 10 (a_{\{2,2\}} + a_{\{3,3\}})) & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & \frac{1}{3} (10 a_{\{1,1\}} + 13 a_{\{2,2\}} + 10 a_{\{3,3\}}) & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & \frac{1}{3} (a_{\{1,1\}} + a_{\{2,2\}} + 4 a_{\{3,3\}}) \end{pmatrix}$$

Requires a trace free matrix

```
Atf = {{a_{1,1}, a_{1,2}, a_{1,3}}, {a_{1,2}, a_{2,2}, a_{2,3}}, {a_{1,3}, a_{2,3}, -a_{1,1} - a_{2,2}}}
{{a_{1,1}, a_{1,2}, a_{1,3}}, {a_{1,2}, a_{2,2}, a_{2,3}}, {a_{1,3}, a_{2,3}, -a_{1,1} - a_{2,2}}}
```

```
Tr[Atf]
```

```
0
```

```
D2i[D2[Atf]] /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,2} & a_{2,2} & a_{2,3} \\ a_{1,3} & a_{2,3} & -a_{1,1} - a_{2,2} \end{pmatrix}$$

```
D2i[D2[Atf]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,2} & a_{2,2} & a_{2,3} \\ a_{1,3} & a_{2,3} & -a_{1,1} - a_{2,2} \end{pmatrix}$$

```
D2[D2i[Atf]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,2} & a_{2,2} & a_{2,3} \\ a_{1,3} & a_{2,3} & -a_{1,1} - a_{2,2} \end{pmatrix}$$

```
maketracefree = Function[a, a - (1/3) Tr[a] IdentityMatrix[3]]
```

```
Function[a, a -  $\frac{1}{3}$  Tr[a] IdentityMatrix[3]]
```

```
maketracefree[Atf]
```

```
{{a_{1,1}, a_{1,2}, a_{1,3}}, {a_{1,2}, a_{2,2}, a_{2,3}}, {a_{1,3}, a_{2,3}, -a_{1,1} - a_{2,2}}}
```

```
D2[D2i[Atf]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,2} & a_{2,2} & a_{2,3} \\ a_{1,3} & a_{2,3} & -a_{1,1} - a_{2,2} \end{pmatrix}$$

```
Tr[D2[D2i[Atf]]] // Simplify
```

```
0
```

So now checking 6.6.11 is a solution of 6.6.10 by direct substitution

```
D2i[D2[Atf]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{1,2} & a_{2,2} & a_{2,3} \\ a_{1,3} & a_{2,3} & -a_{1,1} - a_{2,2} \end{pmatrix}$$

```
Tr[D2i[A]] // Simplify
```

```
a_{1,1} + a_{2,2} + a_{3,3}
```

```
Tr[D2i[Atf]] // Simplify
```

```
0
```

```
Tr[D2[Atf]] // Simplify
```

```
0
```

```
Tr[D2[A]] // Simplify
```

```
8 (a_{1,1} + a_{2,2} + a_{3,3})
```

Now testing the formula in Thm 6.6.2 for equivalence with (6.6.1)



```
D2d =
Function[a, 2 (4 a - 6 ddelta[a] + d2delta2[a] + (5 / 3) IdentityMatrix[3] delta2[a])]
```

```
Function[a, 2 (4 a - 6 ddelta[a] + d2delta2[a] +  $\frac{5}{3}$  IdentityMatrix[3] delta2[a])]
```

```
D2d[Atf] - D2[Atf] // Simplify // MatrixForm
```

```
 $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ 
```

And that is ok as well, giving us confidence in our d and delta opporators

Now for the TRT

Constructing a formula for D1 inverse (like 6.6.10)

```
D1i = Function[a, a - (1 / 2) (Projm.a + a.Projm) + (3 / 8) Proj2[a]]
```

```
Function[a, a -  $\frac{1}{2}$  (Projm.a + a.Projm) +  $\frac{3 \text{ Proj2[a]}}{8}$ ]
```

Now test with just Pi

```
D1i1 = Function[a,
a - (1 / 2) (Projm.a + a.Projm) + (1 / 4) Projm.a.Projm + (1 / 8) Tr[Projm.a] Projm]
```

```
Function[a, a -  $\frac{1}{2}$  (Projm.a + a.Projm) +  $\frac{\text{Projm.a.Projm}}{4}$  +  $\frac{1}{8}$  Tr[Projm.a] Projm]
```

```
D1i[A] - D1i1[A] // Simplify // MatrixForm
```

```
 $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ 
```

```
D1i2 = Function[a, (1 / 4) a + (1 / 4) (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) +
(3 / 8) (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + (1 / 8) Tr[a]
(IdentityMatrix[3] - outer[Y, Y] / (Y.Y)) - (1 / 8) (Y.a.Y) IdentityMatrix[3] / (Y.Y)]
```

```
Function[a,  $\frac{a}{4}$  +  $\frac{1}{4}$  ( $\frac{\text{outer[Y, Y].a}}{\text{Y.Y}} + \frac{\text{a.outer[Y, Y]}}{\text{Y.Y}}$ ) +  $\frac{3 \text{ Y.a.Y outer[Y, Y]}}{8 (\text{Y.Y})^2}$  +
 $\frac{1}{8}$  Tr[a] ( $\text{IdentityMatrix[3]} - \frac{\text{outer[Y, Y]}}{\text{Y.Y}}$ ) -  $\frac{\text{Y.a.Y IdentityMatrix[3]}}{8 \text{ Y.Y}}$ ]
```

```
D1i[A] - D1i2[A] // Simplify // MatrixForm
```

```
 $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ 
```

```
D1i[A] - D1i2[A] /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm
```

```
 $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ 
```

```
D1test = Function[{a, k1, k2, k3, k4, k5},
4 a - k4 (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) +
k1 (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + k2 Tr[a] (IdentityMatrix[3] - outer[Y, Y] / (Y.Y)) +
k3 (Y.a.Y) IdentityMatrix[3] / (Y.Y) + k5 (Y.a.Y) outer[Y, Y] / (Y.Y)^2]
```

```
Function[{a, k1, k2, k3, k4, k5}, 4 a - k4 ( $\frac{\text{outer[Y, Y].a}}{\text{Y.Y}} + \frac{\text{a.outer[Y, Y]}}{\text{Y.Y}}$ ) +
 $\frac{k1 \text{ Y.a.Y outer[Y, Y]}}{(\text{Y.Y})^2}$  + k2 Tr[a] ( $\text{IdentityMatrix[3]} - \frac{\text{outer[Y, Y]}}{\text{Y.Y}}$ ) +
 $\frac{k3 \text{ Y.a.Y IdentityMatrix[3]}}{\text{Y.Y}}$  +  $\frac{k5 \text{ Y.a.Y outer[Y, Y]}}{(\text{Y.Y})^2}$ ]
```

```
tst = D1i[D1test[A, k1, k2, k3, k4, k5]] - A /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify //
MatrixForm;
```

```
tst
```

$$\begin{pmatrix} \frac{1}{2} ((1+k2) a_{\{1,1\}} + (1+k2) a_{\{2,2\}} + (k2+k3) a_{\{3,3\}}) & 0 & \frac{1}{2} ((1+k2) a_{\{1,1\}} + (1+k2) a_{\{2,2\}} + (k2+k3) a_{\{3,3\}}) \\ 0 & \frac{1}{2} ((1+k2) a_{\{1,1\}} + (1+k2) a_{\{2,2\}} + (k2+k3) a_{\{3,3\}}) & -\frac{1}{2} (-2+k4) a_{\{2,3\}} \\ -\frac{1}{2} (-2+k4) a_{\{1,3\}} & -\frac{1}{2} (-2+k4) a_{\{2,3\}} & \end{pmatrix}$$

```
tst /. {k2 -> -1, k3 -> 1, k1 -> 4, k4 -> 2, k5 -> -4}
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

So Mathematica helped here to find D1

```
D1 = Function[a, 4 a - 2 (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) -
Tr[a] (IdentityMatrix[3] - outer[Y, Y] / (Y.Y)) + (Y.a.Y IdentityMatrix[3] / (Y.Y))]
```

$$\text{Function}\left[a, 4a - 2\left(\frac{\text{outer}[Y, Y].a}{Y.Y} + \frac{a.\text{outer}[Y, Y]}{Y.Y}\right) - \text{Tr}[a] \left(\text{IdentityMatrix}[3] - \frac{\text{outer}[Y, Y]}{Y.Y}\right) + \frac{Y.a.Y \text{IdentityMatrix}[3]}{Y.Y}\right]$$

```
D1i[D1[A]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

```
D1[D1i[A]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

So to me that looks like a left and right inverse!

```
dd = Function[a, outer[Y, Y] a / (Y.Y)]
```

$$\text{Function}\left[a, \frac{\text{outer}[Y, Y] a}{Y.Y}\right]$$

```
D1d = Function[a,
4 a - 4 ddelta[a] - Tr[a] IdentityMatrix[3] + dd[Tr[a]] + delta2[a] IdentityMatrix[3]]
```

```
Function[a,
4 a - 4 ddelta[a] - Tr[a] IdentityMatrix[3] + dd[Tr[a]] + delta2[a] IdentityMatrix[3]]
```

```
D1i[D1d[A]] // Simplify // MatrixForm
```

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

```
D1d = Function[a, (1/4) a + (1/2) ddelta[a]
+ (3/8) d2delta2[a] + (1/8) Tr[a] IdentityMatrix[3] -
(1/8) dd[Tr[a]] - (1/8) delta2[a] IdentityMatrix[3]]
```

General::spell: Possible spelling error: new symbol name "D1d" is similar to existing symbols {D1d, D1i}. More...

$$\text{Function}\left[a, \frac{a}{4} + \frac{\text{ddelta}[a]}{2} + \frac{3 \text{d2delta2}[a]}{8} + \frac{1}{8} \text{Tr}[a] \text{IdentityMatrix}[3] - \frac{1}{8} \text{dd}[\text{Tr}[a]] - \frac{1}{8} \text{delta2}[a] \text{IdentityMatrix}[3]\right]$$

**D1id[D1[A]] /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify // MatrixForm**

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

**D1[D1id[A]] // Simplify // MatrixForm**

$$\begin{pmatrix} a_{\{1,1\}} & a_{\{1,2\}} & a_{\{1,3\}} \\ a_{\{1,2\}} & a_{\{2,2\}} & a_{\{2,3\}} \\ a_{\{1,3\}} & a_{\{2,3\}} & a_{\{3,3\}} \end{pmatrix}$$

**Tr[D1i[A]] /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify**

$$\frac{1}{2} (a_{\{1,1\}} + a_{\{2,2\}} + 2 a_{\{3,3\}})$$

**Tr[D2[Atf]] /. {y1 -> 0, y2 -> 0, y3 -> 1}**

$$2 \left( 4 a_{\{1,1\}} + \frac{5}{3} (-a_{\{1,1\}} - a_{\{2,2\}}) \right) + 2 \left( \frac{5}{3} (-a_{\{1,1\}} - a_{\{2,2\}}) + 4 a_{\{2,2\}} \right) + 2 \left( -a_{\{1,1\}} - a_{\{2,2\}} + \frac{1}{3} (a_{\{1,1\}} + a_{\{2,2\}}) \right)$$

**Tr[D1i[A]] - ((1/2) Tr[A] + (1/2) Y.A.Y / (Y.Y)) /. {y1 -> 0, y2 -> 0, y3 -> 1} // Simplify**

0

**Tr[D1i[A]] - ((1/2) Tr[A] + (1/2) Y.A.Y / (Y.Y)) // Simplify**

0

Trace free version of D1 inverse

**D1itr = Function[a, (1/4) a + (1/4) (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) + (3/8) (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + (-1/24) Tr[a] IdentityMatrix[3] - (1/8) Tr[a] outer[Y, Y] / (Y.Y) - (7/24) (Y.a.Y) IdentityMatrix[3] / (Y.Y)]**

$$\text{Function}\left[a, \frac{a}{4} + \frac{1}{4} \left( \frac{\text{outer}[Y, Y].a}{Y.Y} + \frac{a.\text{outer}[Y, Y]}{Y.Y} \right) + \frac{3 Y.a.Y \text{ outer}[Y, Y]}{8 (Y.Y)^2} - \frac{1}{24} \text{Tr}[a] \text{IdentityMatrix}[3] - \frac{\text{Tr}[a] \text{ outer}[Y, Y]}{8 Y.Y} - \frac{7 Y.a.Y \text{ IdentityMatrix}[3]}{24 Y.Y} \right]$$

**Tr[D1itr[A]] // Simplify**

0

Now to calculate the composite of D2 with the trace free D1inverse

**d2 = Function[a, a outer[Y, Y] / (Y.Y)]**

$$\text{Function}\left[a, \frac{a \text{ outer}[Y, Y]}{Y.Y}\right]$$

**D2D1ttst =**

**Function[a, (2) a + (-8/9) IdentityMatrix[3] Tr[a] + (-2) ddelta[a] + (2/3) d2[Tr[a]] IdentityMatrix[3] + (4/9) IdentityMatrix[3] delta2[a] + (2/3) d2delta2[a]]**

$$\text{Function}\left[a, 2a - \frac{8}{9} \text{IdentityMatrix}[3] \text{Tr}[a] - 2 \text{ddelta}[a] + \frac{2}{3} \text{d2}[\text{Tr}[a]] \text{IdentityMatrix}[3] + \frac{4}{9} \text{IdentityMatrix}[3] \text{delta2}[a] + \frac{2 \text{d2delta2}[a]}{3} \right]$$

**(D2[D1itr[A]] - D2D1ttst[A]) // Simplify // MatrixForm**

$$\begin{pmatrix} 0 & \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_1 Y_2}{3 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_1 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_1 Y_2}{3 (Y_1^2 + Y_2^2 + Y_3^2)} & 0 & \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_2 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_1 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{2 (a_{\{1,1\}} + a_{\{2,2\}} + a_{\{3,3\}}) Y_2 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)} & 0 \end{pmatrix}$$

```
(D2[Dlitr[A]] - D2Dlittst[A]) /. {k1 -> k3 -> -2 / 3, k5 -> 4 / 9, k4 -> 2 / 3, k6 -> 2 / 3} //
Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 \end{pmatrix}$$

```
(D2[Dlitr[A]] - D2Dlittst[A]) /. {k1 -> 2, k2 -> 8 / 9, k3 -> -2} // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 \end{pmatrix}$$

```
(D2[Dlitr[A]] - D2Dlittst[A]) /. {k1 -> 2, k3 -> -2, k5 -> 4 / 9, k6 -> 2 / 3} /.
{Y1 -> 1, Y2 -> 0, Y3 -> 1} // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & \frac{1}{3}(a_{1,1}+a_{2,2}+a_{3,3}) \\ 0 & 0 & 0 \\ \frac{1}{3}(a_{1,1}+a_{2,2}+a_{3,3}) & 0 & 0 \end{pmatrix}$$

```
(D2[Dlitr[A]] - D2Dlittst[A]) /.
{k1 -> 2, k2 -> -8 / 9, k3 -> 2, k4 -> 2 / 3, k5 -> 4 / 9, k6 -> 4 / 3} // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_2}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} \\ \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_1Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & \frac{2(a_{1,1}+a_{2,2}+a_{3,3})Y_2Y_3}{3(Y_1^2+Y_2^2+Y_3^2)} & 0 \end{pmatrix}$$

```
D2Dlittst = Function[a, (k1) a + k2 IdentityMatrix[3] Tr[a] + (k3) ddelta[a] +
(k4) d2[Tr[a]] IdentityMatrix[3] + k5 IdentityMatrix[3] delta2[a] + k6 d2delta2[a] ]
```

```
Function[a, k1 a + k2 IdentityMatrix[3] Tr[a] + k3 ddelta[a] +
k4 d2[Tr[a]] IdentityMatrix[3] + k5 IdentityMatrix[3] delta2[a] + k6 d2delta2[a] ]
```

```
D2Dlittst =
Function[a, (2) a + (-8 / 9) IdentityMatrix[3] Tr[a] + (-2) ddelta[a] + (2 / 3) d2[Tr[a]]
IdentityMatrix[3] + (4 / 9) IdentityMatrix[3] delta2[a] + (2 / 3) d2delta2[a] ]
```

```
Function[a, 2 a - \frac{8}{9} IdentityMatrix[3] Tr[a] - 2 ddelta[a] +
```

$$\frac{2}{3} d2[Tr[a]] IdentityMatrix[3] + \frac{4}{9} IdentityMatrix[3] delta2[a] + \frac{2 d2delta2[a]}{3}]$$

```
D2Dlittst1 = Function[a, (k1) a + (k3) (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) / 2 +
(k6) (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + (k2) Tr[a] IdentityMatrix[3] +
(k4) Tr[a] outer[Y, Y] / (Y.Y) + (k5) (Y.a.Y) IdentityMatrix[3] / (Y.Y) ]
```

```
Function[a, k1 a + \frac{1}{2} k3 \left( \frac{outer[Y, Y].a}{Y.Y} + \frac{a.outer[Y, Y]}{Y.Y} \right) + \frac{k6 Y.a.Y outer[Y, Y]}{(Y.Y)^2} +
k2 Tr[a] IdentityMatrix[3] + \frac{k4 Tr[a] outer[Y, Y]}{Y.Y} + \frac{k5 Y.a.Y IdentityMatrix[3]}{Y.Y} ]
```

```
(D2[Dlitr[A]] - D2Dlittst1[A]) /.
{k1 -> 2, k2 -> -8 / 9, k3 -> -2, k4 -> 2 / 3, k5 -> 4 / 9, k6 -> 2 / 3} // Simplify // MatrixForm
```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

```

D2Dlit = Function[a, (2) a + (-2) (outer[Y, Y].a / (Y.Y) + a.outer[Y, Y] / (Y.Y)) / 2 +
  (2 / 3) (Y.a.Y) outer[Y, Y] / (Y.Y)^2 + (-8 / 9) Tr[a] IdentityMatrix[3] +
  (2 / 3) Tr[a] outer[Y, Y] / (Y.Y) + (4 / 9) (Y.a.Y) IdentityMatrix[3] / (Y.Y)]

```

```

Function[a, 2 a -  $\frac{2}{2} \left( \frac{\text{outer}[Y, Y].a}{Y.Y} + \frac{a.\text{outer}[Y, Y]}{Y.Y} \right) + \frac{2 Y.a.Y \text{outer}[Y, Y]}{3 (Y.Y)^2} -$ 
 $\frac{8}{9} \text{Tr}[a] \text{IdentityMatrix}[3] + \frac{2 \text{Tr}[a] \text{outer}[Y, Y]}{3 Y.Y} + \frac{4 Y.a.Y \text{IdentityMatrix}[3]}{9 Y.Y}$  ]

```

```

(D2[Dlitrf[A]] - D2Dlit[A]) // Simplify // MatrixForm

```

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Now we want to see if  $D2Dli \, du = du$  if  $\text{tr} \, du = 0$

```

u = {u1, u2, u3}

```

```

{u1, u2, u3}

```

```

Y

```

```

{Y1, Y2, Y3}

```

```

du = (outer[Y, u] + outer[u, Y]) / 2 / (Y.Y)

```

$$\left\{ \left\{ \frac{u_1 Y_1}{Y_1^2 + Y_2^2 + Y_3^2}, \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \right\}, \right. \\ \left. \left\{ \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_2 Y_2}{Y_1^2 + Y_2^2 + Y_3^2}, \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \right\}, \left\{ \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_3}{Y_1^2 + Y_2^2 + Y_3^2} \right\} \right\}$$

```

du // MatrixForm

```

$$\begin{pmatrix} \frac{u_1 Y_1}{Y_1^2 + Y_2^2 + Y_3^2} & \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{u_2 Y_2}{Y_1^2 + Y_2^2 + Y_3^2} & \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \\ \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} & \frac{u_3 Y_3}{Y_1^2 + Y_2^2 + Y_3^2} \end{pmatrix}$$

```

dut = Simplify[du - (1 / 3) Tr[du] IdentityMatrix[3]]

```

$$\left\{ \left\{ -\frac{2 u_1 Y_1 + u_2 Y_2 + u_3 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \right\}, \right. \\ \left\{ \frac{u_2 Y_1 + u_1 Y_2}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, -\frac{u_1 Y_1 - 2 u_2 Y_2 + u_3 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)} \right\}, \\ \left. \left\{ \frac{u_3 Y_1 + u_1 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, \frac{u_3 Y_2 + u_2 Y_3}{2 (Y_1^2 + Y_2^2 + Y_3^2)}, -\frac{u_1 Y_1 + u_2 Y_2 - 2 u_3 Y_3}{3 (Y_1^2 + Y_2^2 + Y_3^2)} \right\} \right\}$$

```

D2Dlittst1[dut] - dut /. {Y1 -> 0, Y2 -> 0, Y3 -> 1} // Simplify // MatrixForm

```

$$\begin{pmatrix} -\frac{1}{3} (-1 + k_1 - 2 k_5) u_3 & 0 & \frac{1}{4} (-2 + 2 k_1 + k_3) u_1 \\ 0 & -\frac{1}{3} (-1 + k_1 - 2 k_5) u_3 & \frac{1}{4} (-2 + 2 k_1 + k_3) u_2 \\ \frac{1}{4} (-2 + 2 k_1 + k_3) u_1 & \frac{1}{4} (-2 + 2 k_1 + k_3) u_2 & \frac{2}{3} (-1 + k_1 + k_3 + k_5 + k_6) u_3 \end{pmatrix}$$

**D1i[D2[dut]] - dut // Simplify // MatrixForm**

$$\begin{pmatrix} \frac{(u_1 y_1 + u_2 y_2 + u_3 y_3) (2 y_1^2 + y_2^2 + y_3^2)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{y_1 y_2 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{y_1 y_3 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} \\ \frac{y_1 y_2 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{(u_1 y_1 + u_2 y_2 + u_3 y_3) (y_1^2 + 2 y_2^2 + y_3^2)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{y_2 y_3 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} \\ \frac{y_1 y_3 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{y_2 y_3 (u_1 y_1 + u_2 y_2 + u_3 y_3)}{9 (y_1^2 + y_2^2 + y_3^2)^2} & \frac{(u_1 y_1 + u_2 y_2 + u_3 y_3) (y_1^2 + y_2^2 + 2 y_3^2)}{9 (y_1^2 + y_2^2 + y_3^2)^2} \end{pmatrix}$$