The RISCV Sail Golden Model A Cookbook for the RISCV ISA

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List of programming examples (in increasing complexity)

The main purpose of this document, is to give the user a set of programming examples for working on the RISC-V Sail model (often referred to as the RISC-V Golden Model). The examples will show the user how to change or extend the model. And it will also show the user how to write a RISC-V program (in both assembler and C) and then run it on the Golden Model.

You should read and utilize this document after you have a good handle on the Sail programming language.

Platform Configuration example (Bill)

Chapter 1. Introduction

Chapter 2. How to contribute (Bill)

2.1. Coding and indentation style

2.2. Brevity

Program examples should be short, both in terms of number-of-lines and in terms of execution time. Each example should focus on one simple item. And the execution of the example item should be clear. The example should be short, standalone and easy to maintain.

2.3. Maintainership (when something breaks)

We would also ask that if you contribute a code example, that you would maintain it.

Chapter 3. Sail installation

TBD

3.1. Ubuntu (Bill Mc.)

TBD

3.2. MacOS (Martin)

TBD

3.3. Docker

Docker is used as a

3.4. Windows

3.5. Windows: Cygwin (Bill Mc., low priority)

3.6. Other?

Chapter 4. Basic description

4.1. What Sail is

Sail is a programming language that is targetted for specifying an ISA. Once specified, a set of instructions (usually found in a .elf file) can then be executed on the "model" and the results observed.

The model is a sequential model only; at this time, there are no semantics allowing for any type of parallel execution.

4.2. What sail is not

Sail is not an RTL (Register Transfer Language). There is no direct support for timing (as in clock timing) and there is no support for parallel execution, all things that an RTL contains.

4.3. version management and what to expect

TBD

Chapter 5. Platform Configuration example (Bill)

Chapter 6. Example: Add A New Extension and a New CSR

The main purpose of this cookbook, is to explain how someone can add an extension (and a CSR) to the RISC-V Sail model. This example attempts to add a very simple instruction and a very simple CSR to the model. One instruction will be added into the custom opcode space. And that instruction will be used to manipulate the new CSR, which can then be accessed by the existing CSR instructions.

This is an example of what **is**, not necessarily what it should be. This follows a pattern from the existing code.

First, we will walk through the pertinent sections of the RISC-V specifications to see what the specifications have to say about adding instructions.

Let's start with the Unprivileged Specification

The RISC-V Instruction Set Manual Volume I: Unprivileged ISA

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Chapter 26 of the Unpriv Spec ("Extending RISC-V") describes how you can extend the RISC-V instruction set.

See unpriv spec, chapter 26, "Extending RISC-V"

See unpriv spec, chapter 24, "RV32/64G Instruction Set Listings"

Chapter 24

RV32/64G Instruction Set Listings

One goal of the RISC-V project is that it be used as a stable software development target. For this purpose, we define a combination of a base ISA (RV32I or RV64I) plus selected standard extensions (IMAFD, Zicsr, Zifencei) as a "general-purpose" ISA, and we use the abbreviation G for the IMAFDZicsr_Zifencei combination of instruction-set extensions. This chapter presents opcode maps and instruction-set listings for RV32G and RV64G.

inst[4:2	000	001	010	011	100	101	110	111
inst[6:5	П	,						(> 32b)
0	LOAD	LOAD-FP	custom-0	MISC-MEM	OP-IMM	AUIPC	OP-IMM-32	48b
0	STORE	STORE-FP	custom-1	AMO	OP	LUI	OP-32	64b
10) MADD	MSUB	NMSUB	NMADD	OP-FP	reserved	custom-2/rv128	48b
1	BRANCH	JALR	reserved	JAL	SYSTEM	reserved	custom-3/rv128	$\geq 80b$

Table 24.1: RISC-V base opcode map, inst[1:0]=11

See unpriv spec, chapter 27, "ISA Extension Naming Convention", especially setion 27.10, "Non-Standard Extension Names".

See priv spec, chapter 2, "CSR Listings", Table 2.1

CSR Address		Hex	Use and Accessibility				
[11:10]	[9:8]	[7:4]					
Unprivileged and User-Level CSRs							
00	00	XXXX	0x000-0x0FF Standard read/write				
01	00	XXXX	0x400-0x4FF	Standard read/write			
10	00	XXXX	0x800-0x8FF	Custom read/write			
11	00	OXXX	0xC00-0xC7F	Standard read-only			
11	00	10XX	0xC80-0xCBF	Standard read-only			
11	00	11XX	0xCCO-0xCFF	Custom read-only			
Supervisor-Level CSRs							
00	01	XXXX	0x100-0x1FF	Standard read/write			
01	01	OXXX	0x500-0x57F	Standard read/write			
01	01	10XX	0x580-0x5BF	Standard read/write			
01	01	11XX	0x5C0-0x5FF	Custom read/write			
10	01	OXXX	0x900-0x97F	Standard read/write			
10	01	10XX	0x980-0x9BF	Standard read/write			
10	01	11XX	0x9C0-0x9FF	Custom read/write			
11	01	OXXX	0xD00-0xD7F	Standard read-only			
11	01	10XX	0xD80-0xDBF	Standard read-only			
11	01	11XX	0xDC0-0xDFF	Custom read-only			
	•		Hypervisor an	d VS CSRs			
00	10	XXXX	0x200-0x2FF	Standard read/write			
01	10	OXXX	0x600-0x67F	Standard read/write			
01	10	10XX	0x680-0x6BF	Standard read/write			
01	10	11XX	0x6C0-0x6FF	Custom read/write			
10	10	OXXX	0xA00-0xA7F	Standard read/write			
10	10	10XX	0xA80-0xABF	Standard read/write			
10	10	11XX	0xACO-0xAFF	Custom read/write			
11	10	OXXX	0xE00-0xE7F	Standard read-only			
11	10	10XX	0xE80-0xEBF	Standard read-only			
11	10	11XX	0xEC0-0xEFF	Custom read-only			
			Machine-Le				
00	11	XXXX	0x300-0x3FF	Standard read/write			
01	11	OXXX	0x700-0x77F	Standard read/write			
01	11	100X	0x780-0x79F	Standard read/write			
01	11	1010	0x7A0-0x7AF	Standard read/write debug CSRs			
01	11	1011	0x7B0-0x7BF	Debug-mode-only CSRs			
01	11	11XX	0x7C0-0x7FF	Custom read/write			
10	11	OXXX	0xB00-0xB7F	Standard read/write			
10	11	10XX	0xB80-0xBBF	Standard read/write			
10	11	11XX	0xBC0-0xBFF	Custom read/write			
11	11	OXXX	0xF00-0xF7F	Standard read-only			
11	11	10XX	0xF80-0xFBF	Standard read-only			
11	11	11XX	0xFC0-0xFFF	Custom read-only			

Table 2.1: Allocation of RISC-V CSR address ranges.

Other goals:

- Demonstrate the experimental switch
- Demonstrate how to code WARL fields based on settings in the YAML files.

So now that we've seen what the specifications say, let's take ka look at what that means for the Sail model.

First, we'll define a simple instruction, xmpl. This instruction

Example

Single instruction: xmpl CSR: xmpl_csr

- Takes an unsigned immediate and puts the value into the xmpl_csr
- The xmpl_csr can be read by the normal CSR instructions.
- xmpl_csr cannot be written with any form of the CSR instructions; it should generate an exception.

Files:

- (new) model/riscv_insts_custom_xampl.sail : the implmentation of the instruction and the CSR.
- (exists) Makefile: must add riscv_insts_xample.sail to the list of source files
- (exists) model/riscv_types.sail : need to add new instruction to the proper instruction opcode grouping.
- (exists) model/riscv csr map.sail: the address map of the CSR registers.
- (exists) mpodel/iscv_insts_zicsr.sail : need to add new CSR functionality.
- (exists) model/riscv csr map.sail: need to add new CSR name to the mapping
- (exists) model/riscv_sys_control.sail : need to add the new CSR name to the list found in is CSR defined().
- (new) cookbook/functional_code_examples/add_a_new_extension/test.S : for testing the new instruction features

riscv_insts_custom_xmpl.sail:

```
/* This file specifies an example custom instruction
                                                                  */
/* It can also be used as an example when adding other ratified
                                                                  */
/* extensions (while also using the ISA nomenclature).
                                                                  */
union clause ast = XTYPE : (bits(25), xop)
mapping encdec_x_xmpl : xop <-> bits(7) = {
 RISCV X XMPL <-> 0b0101011 // inst[6:5] == 01, inst[4:2] == 010 --> custom-0
}
mapping clause encdec = XTYPE(imm, xop)
 <-> imm @ encdec_x_xmpl(xop)
function clause execute (XTYPE(imm, xop)) = {
 let csr val : bitvector(25, dec) = imm;
 xmpl_csr_2->FieldWARL() = csr_val ;
 RETIRE_SUCCESS
}
mapping x_xmpl_mnemonic : xop <-> string = {
 RISCV_X_XMPL <-> "x.xmpl"
}
mapping clause assembly = XTYPE(imm, xop)
 <-> x_xmpl_mnemonic(xop) ^ " " ^ hex_bits_25(imm)
```

Makefile (around lines 26-37):

```
SAIL_DEFAULT_INST += riscv_insts_zba.sail
SAIL_DEFAULT_INST += riscv_insts_zbb.sail
SAIL_DEFAULT_INST += riscv_insts_zbc.sail
SAIL_DEFAULT_INST += riscv_insts_zbs.sail

SAIL_DEFAULT_INST += riscv_insts_zkn.sail

SAIL_DEFAULT_INST += riscv_insts_zkn.sail

SAIL_DEFAULT_INST += riscv_insts_zks.sail

SAIL_DEFAULT_INST += riscv_insts_zbkb.sail

SAIL_DEFAULT_INST += riscv_insts_zbkx.sail

# Example custom extension (do not include this in the # usual model build.)

SAIL_DEFAULT_INST += riscv_insts_custom_xmpl.sail
```

model/riscv_types.sail: need to add new instruction to the proper instruction opcode grouping.

```
TODO: What changes did I make to this file????
```

model/riscv_csr_map.sail (around lines 115-120):

```
.
.
mapping clause csr_name_map = 0xF11 <-> "mvendorid"
mapping clause csr_name_map = 0xF12 <-> "marchid"
mapping clause csr_name_map = 0xF13 <-> "mimpid"
mapping clause csr_name_map = 0xF14 <-> "mhartid"
mapping clause csr_name_map = 0xFC0 <-> "xmpl_csr" // Custom CSR example
mapping clause csr_name_map = 0xFC1 <-> "xmpl_2_csr" // Custom CSR example
.
.
```

model/iscv_insts_zicsr.sail (around line 137):

```
.
    /* machine mode, custom extension example */
    (0xFC0, _) => xmpl_csr, // error: Xmpl_csr is not a subtype of bitvector(32, dec)
    (0xFC1, _) => xmpl_csr_2.bits(),
.
```

model/riscv_sys_control.sail (within function is_CSR_defined()):

cookbook/functional_code_examples/add_a_new_extension/test.S : for testing the new instruction features

```
1 // vim: tabstop=2 shiftwidth=2 expandtab
2 //
-----
3 /// @file test.S
```

```
4 ///
    5 ///
    6 /// @brief
                     RISC-V asm code for testing an example custom instruction
    7 ///
    8 /// @author Bill McSpadden (RISC-V Internation) (bill@riscv.org)
    9 //
   10
   11 #ifndef CONFIG_BASE
   12 #error The C pre-processor variable, CONFIG_BASE, must be set.
   13 #endif
   14
   15 // -----
   16 // Support for a custom extension
   17
   18 #define X_XMPL_OPCODE (0x2b) // inst[6:5] == 01, inst[4:2] == 1011 -->
custom-0
   19 #define X_XMPL(__rd__, __imm__) .word (__imm__ << 12) | (__rd__ << 7) |
(X_XMPL_OPCODE << 0)
   20
   21 #define XO
                    (0)
   22 #define X1
                    (1)
   23 #define X2
                   (2)
   24 #define X3
                    (3)
   25 #define X4
                    (4)
   26 #define X5
                    (5)
   27 #define X6
                    (6)
   28 #define X7
                    (7)
   29 #define X8
                    (8)
   30 #define X9
                    (9)
   31 #define X10
                    (10)
   32 #define X11
                    (11)
   33 #define X12
                    (12)
   34 #define X13
                    (13)
   35 #define X14
                    (14)
   36 #define X15
                    (15)
   37 #define X16
                    (16)
   38 #define X17
                    (17)
   39 #define X18
                    (18)
   40 #define X19
                    (19)
   41 #define X20
                    (20)
   42 #define X21
                    (21)
   43 #define X22
                    (22)
   44 #define X23
                    (23)
   45 #define X24
                   (24)
   46 #define X25
                   (25)
   47 #define X26
                    (26)
   48 #define X27
                    (27)
   49 #define X28
                   (28)
   50 #define X29
                    (29)
```

```
51 #define X30
                 (30)
   52 #define X31 (31)
   53
   54
   55
   56
   57 // -----
   58 // Memory-mapped machine timer registers and other support
   59 // for generating a timer interrupt
   61 //#define MMR_MTIMEL (CONFIG_BASE + 0x0000)
   62 //#define MMR_MTIMEH (CONFIG_BASE + 0x0004)
   63 //#define MMR_MTIMECMPL (CONFIG_BASE + 0x0008)
   64 //#define MMR_MTIMECMPH (CONFIG_BASE + 0x000C)
   65
   66 #define MMR_MTIMEL
                         (CONFIG_BASE + 0xbff8)
   67 #define MMR MTIMEH
                         (CONFIG BASE + 0xbffc)
   68 #define MMR_MTIMECMPL
                         (CONFIG_BASE + 0x4000)
   69 #define MMR_MTIMECMPH
                         (CONFIG_BASE + 0x4004)
   70
   71 #define TIMER COUNT
                         (100)
   72 #define WATCHDOG_COUNT (100000)
   73
   74 #define MSTATUS_MIE
                         0x00000008
   75 #define MSTATUS_FS
                         0x00006000
   76 #define MSTATUS_XS
                         0x00018000
   77
   78 #define MIE_MTIE
                         0x80
   79
   80
   81 // -----
   82 // mcause bit definitions
   83
   84 #define MCAUSE_SUPERVISOR_SOFTWARE_INTERRUPT (0x1 << (__riscv_xlen - 1) +
1)
   85 #define MCAUSE_MACHINE_TIMER_INTERRUPT
                                             (0x1 << (__riscv_xlen - 1) +
7)
                                             (0x0 << (__riscv_xlen - 1) +
   86 #define MCAUSE_ILLEGAL_INSTRUCTION
2)
   87
   88 // -----
   89 // Support for tohost/fromhost
   90
   91 #define PASS_CODE
                         1
   92 #define FAIL_CODE
                        1337
   93
   94
   95 // -----
   96 // Support for 32/64 bit compilation.
   97
   98 #if __riscv_xlen == 64
```

```
99 # define LREG ld
100 # define SREG sd
101 # define REGBYTES 8
102 #else
103 # define LREG lw
104 # define SREG sw
105 # define REGBYTES 4
106 #endif
107
108 #define XMPL_CSR (0xfc0)
109 #define XMPL_CSR_2 (0xfc1)
110
111 // -----
112 // Following power-on reset, we start executing at _start.
113 // We jump to "reset_vector"
114 //
   .section ".text.init"
115
116 .globl _start
117 _start:
118
   la x5, reset_vector
119
    jr x5
120 // -----
121
122
123 // -----
124 // Initialization of the processor, starting with the
125 // register file.
126 reset_vector:
127
    li
          x1,
                  0
128
                  0
     li
          x2,
129
     li
         х3,
                  0
130
     li
                  0
         x4,
                  0
131
     li
          х5,
132
                  0
     li
          х6,
133
                  0
     li
          х7,
134
     li
                  0
          х8,
135
     li
                  0
          х9,
                  0
136
     li
          x10,
137
                  0
     li
          x11,
138
     li
          x12,
                  0
139
     li
          x13,
                  0
140
     li
          x14,
                  0
141
          x15,
                  0
     li
142
     li
                  0
          x16,
                  0
143
     li
          x17,
                  0
144
     li
          x18,
145
     li
          x19,
                  0
146
     li
                  0
          x20,
147
                  0
     li
          x21,
148
     li
          x22,
                  0
149
     li
          x23,
                   0
```

```
150
     li
         x24,
                 0
151
     li
         x25,
                 0
152
     li
         x26,
                 0
153
     li
         x27,
                 0
154
     li
        x28,
                 0
155
     li
         x29,
     li
         x30,
                 0
156
157
    li
         x31,
158
159 // -----
   // PMP configuration
160
161
162
     # configure pmp to enable all accesses
     li t0, 0x1f
163
     csrw pmpcfg0, t0
164
165
    li t0,
                 0xffffffff
     csrw pmpaddr0, t0
166
167
168 // -----
169 // initialize machine trap vector
170
         x5, machine_trap_entry
    la
171
     csrw mtvec,
                 х5
172
173
174 // -----
175 // The test!
176
177 the_test_begin:
178 X_XMPL(X2, 0x0dead)
179
   csrr x3, XMPL_CSR_2
180
181 // li x4, 0x76543210
182 // csrw XMPL_CSR_2, x4 // Q: What happens to a write to a read-only csr?
                         // A: illegal_instruction trap
183 //
184 the_test_end:
185
186
187
188
189 // -----
190 // PASS: The end of the test, if successful
191 j_target_end_pass:
192
   // exit code construction
193
    li x10, PASS_CODE
194
    la x13,
                tohost
     sw x10,
195
                 0(x13)
             j_target_end_pass
196
    la x5,
197
     jalr x5
    j j_target_end_fail
                                        // should never be taken
198
199
```

```
201
202 // -----
203 // FAIL: The end of the test, if unsuccessful
204 j_target_end_fail:
205
     // exit code construction
206
      li
           x10,
                    FAIL CODE
      la x13,
207
                   tohost
208
      sw x10,
                    0(x13)
      la x5,
209
                    j_target_end_fail
210
      jalr x5
211
212
213 // -----
214 // In support of vectored interrupt, although it's not
215 // being used in this test.
216
217
      .align 4
218 machine_trap_entry:
          machine_trap_entry_0
219
      j
220
      .align 2
221
          machine_trap_entry_1
      j
222
      .align 2
223
      j
            machine_trap_entry_2
224
      .align 2
225
      j
            machine_trap_entry_3
226
      .align 2
227
            machine_trap_entry_4
      j
228
      .align 2
229
      j
            machine_trap_entry_5
230
      .align 2
231
      j
            machine_trap_entry_6
232
      .align 2
233
            machine_trap_entry_7
      j
234
      .align 2
235
            machine_trap_entry_8
      j
236
      .align 2
237
            machine_trap_entry_9
      j
238
      .align 2
239
      j
            machine_trap_entry_10
240
      .align 2
            machine_trap_entry_11
241
      j
242
243
244
   // -----
245
246
      .align 2
247 machine_trap_entry_0:
248
      CSTT
             х7,
                      mcause
249
      li
             х6,
                      MCAUSE_MACHINE_TIMER_INTERRUPT
250
      bne
             х7,
                             not_a_timer_interrupt
                      хб,
251
      li
             х6,
                      0x1
```

```
252
        la
               х7,
                       timer_interrupt_flag
  253
               х6,
                       0(x7)
        SW
  254
  255
        // Turn off timer interrupt. No longer needed
  256
        addi
               х7,
                       x0, MIE_MTIE
  257
               mie,
                       x7
        CSTC
  258
  259
        // Clear interrupt
  260
        li
              х7,
                       MSTATUS MIE
  261
        CSTC
              mstatus, x7
  262
  263
        // and return
  264
        mret
  265
  266 not_a_timer_interrupt:
       // Do not try and correct the opcode, and do not
  267
        // do an mret. This should probably be the last
  268
       // part of this simple test.
  269
  270
        csrr x7, mcause
  271
        li
             x6, MCAUSE_ILLEGAL_INSTRUCTION
            j_target_end_fail
  272
       j
  273
  274
  275 // -----
  276 // None of these machine traps should have been taken
  277 // Jump to test failure
  278 machine_trap_entry_1:
  279 machine_trap_entry_2:
  280 machine_trap_entry_3:
  281 machine_trap_entry_4:
  282 machine_trap_entry_5:
  283 machine_trap_entry_6:
  284 machine_trap_entry_7:
  285 machine_trap_entry_8:
  286 machine_trap_entry_9:
  287 machine_trap_entry_10:
  288 machine_trap_entry_11:
        csrr x7, mcause // Do the read so that it appears in the log
  289
file for debug.
            j_target_end_fail
  290
      j
  291 // -----
  292
  293
  294
  295 // -----
  296 // Memory locations for specific usage.
  297 .section ".tdata.begin"
  298 .globl _tdata_begin
      _tdata_begin:
  299
  300
  301 .section ".tdata.end"
```

```
302 .globl _tdata_end
303 _tdata_end:
304
305 .section ".tbss.end"
306 .globl _tbss_end
307 _tbss_end:
308
309
    .section ".tohost","aw",@progbits
310
    .align 6
311 .globl tohost
312 tohost: .dword 0
313
314 .section ".fromhost", "aw", @progbits
315 .align 6
316 .globl fromhost
317 fromhost: .dword 0
318
319 .align 6
320 .global timer_interrupt_flag
321 timer_interrupt_flag: .dword 0
322
323
324
325
```

You will probably have to add command line switches to enable/disable extensions/functionality. Files that need to be touched are:

- (exists) c_emulator/riscv_sim.c : implements the longopts functionality
- (exists) model/riscv_sys_regs.sail : function signatures for sys_enable_XXX() functionms.
- (exists) c_emulator/riscv_platform_impl.*: global variables for holding enabled state vars
- (exists) c_emulator/riscv_platform.c : implements the C functions that will be made available to Sail; functions like sys_enable_zfinx().

What does the test.dump file look like? Remember, the RISC-V assembler knows nothing about the custom instruction we have added.

cookbook/functional_code_examples/add_a_new_extension/test.dump:

```
.
89 80000062 <the_test_begin>:
90 80000062: 0dead12b 0xdead12b
91 80000066: fc1021f3 csrr gp,0xfc1
.
```

What does the Sail log file look like?

```
424 model/riscv_step.sail
425 model/riscv_step.sail:75.25-75.32
426 entering step() function...
427
428 mem[X,0x80000062] -> 0xD12B
429 mem[X,0x80000064] -> 0x0DEA
430 [41] [M]: 0x80000062 (0x0DEAD12B) x.xmpl 1824162
431
432
433 model/riscv_step.sail
434 model/riscv_step.sail:75.25-75.32
435 entering step() function...
436
437 mem[X,0x80000066] -> 0x21F3
438 mem[X,0x80000068] -> 0xFC10
439 [42] [M]: 0x80000066 (0xFC1021F3) csrrs gp, xmpl_2_csr, zero
440 CSR xmpl_2csr \rightarrow 0x001BD5A2
441 x3 <- 0x001BD5A2
```

Chapter 7. FAQs (Frequently Asked Questions)

Following are a set of FAQs that were generated via set of questions to the Sail developers.

7.1. Frequently Asked Questions about the Sail RISC-V Golden Model

Q: Is there support for multi-HART or multi-Core simulation?

Q: What are .ml files? What are their purpose?

Q: Is there any support for MTIMER?

[qis_themain_loop__coded_in_Sail]

Q: Can gdb attach to the RISCV Golden Model to debug RISCV code?

Q: There are two C executables built: riscv_sim_RV32 and riscv_sim_RV64. Is there a reason why we need two executables? Can't XLEN be treated as a run-time setting rather than a compile time setting?

Q: Is there support in the model for misaligned memory accesses?

Q: What is the meaning of life, the universe and everything?

Q: What does the answer to "What is the meaning of life, the universe and everything" mean?

7.1.1. Q: Is there support for multi-HART or multi-Core simulation?

A: There is no inherent support for multi-HART or multi-Core within the existing RISC-V Sail model. There are future plans for adding this kind of simulation. It is needed in order to simulate (in a meaningful way) the atomic memory operations and to evaluate memory consistency and coherency.

The model isn't directly about testing. Testing is a separate activity. The point of the model is to be as clear as possible. and we should keep testing and the model separate.

7.1.2. Q: What are .ml files? What are their purpose?

A: These are OCaml files. They are to the ocaml emulator what the .c files are to the c emulator. I question the need for an OCaml emulator ,see also https://github.com/riscv/sail-riscv/issues/138

7.1.3. Q: Is there any support for MTIMER?

A: Yes. MTIMER functionality lives in riscv_platform.sail. At this date (2022-05-27) it lives at a fixed MMIO space as specified by the MCONFIG CSR. In the future, once the Golden Model supports the RISCV_config YAML structure, the MTIMER can be assigned any address.

7.1.4. Q: Is the "main loop" coded in Sail?

A: The initial answer to this question ("The main execution loop can be found in main.sail'.") is incorrect. main.sail is not executed in the RISC-V model, even though it is compiled into the model.

The main loop is actually found on the C side in the file c_emulator/riscv_sim.c in the function run_sail()'. In this function, the Sail function, zstep(), is called (which is the Sail function, step())

7.1.5. Q: Can gdb attach to the RISCV Golden Model to debug RISCV code?

A: Not at this time (2022-05-27). It is being looked at as an enhancement.

7.1.6. Q: There are two C executables built: riscv_sim_RV32 and riscv_sim_RV64. Is there a reason why we need two executables? Can't XLEN be treated as a run-time setting rather than a compile time setting?

A: (Response from Martin Berger) I think this would require a redesign of the Sail code because of the way Sail's liquid types work. Currently xlen is a global type constant, that is used, directly or indirectly, everywhere. As a type-constant it is used during type checking. The typing system might (note the subjunctive) be flexible enough to turn this into a type-parameter, but probably not without major code surgery. I think we should ask the Cambridge team why they decided on the current approach.

7.1.7. Q: Is there support in the model for misaligned memory accesses?

A: (Response from Martin Berger) Short answer: I don't know. Alignment stuff is distributed all over the code base. riscv_platform.sail has some configuration options for this. Maybe that's a place to start looking?

7.1.8. Q: What is the meaning of life, the universe and everything?

A: 42

7.1.9. Q: What does the answer to "What is the meaning of life, the universe and everything" mean?

A: One must construct an experimental, organic computer to compute the meaning. Project *Earth* is one such computer. Timeframe for an expected answer is... soon.

Chapter 8. Colophon

This document was prepared on an Ubuntu Linux workstation using Microsofts VSCode for editing and rendering the asciidoc text.

shutter was used for screenshots of various parts of the RISCV specifications and were saved in PNG format.

These screenshots were then edited using gimp to highlight the pertinent sections of the screenshot.

asciidoctor-reducer was used to combine and resolve all cross-document references and put them into one .adoc file, TheRISCVSailCookbook_Complate.adoc.

The pdf was created using asciidoctor-pdf.

See the Makefile, cookbook/doc/Makefile, for the recipe for building the document.