

60016 OPERATIONS RESEARCH

Game Theory Mixed Strategies

16 November 2020

Two-Person Zero-Sum Games

Two-person zero-sum games:

- ▶ m row strategies and n column strategies
- ▶ RP tries to maximise payoff, CP tries to minimise loss
- ▶ **Dominated strategies** are never played
- ▶ In a **Nash equilibrium**, players do not unilaterally change their strategy when told what the opponent would do
- ▶ Equilibrium exists if

$$\max_{i=1,\dots,m} \alpha_i = \min_{j=1,\dots,n} \beta_j$$

α_i and β_j being payoffs for row strategy i , column strategy j .

Example 1: Election Game (with different payoffs)

MAX

RP

CP

MIN

		L	B	S	α_i
L		0	-1	2	-1
B		5	4	3	-3
S		2	3	-4	-4
β_j		5	4	2	

Handwritten annotations: "NOT" with an arrow pointing to the cell (L, L) containing 0; "NOT" with an arrow pointing to the cell (B, B) containing 5; a bracket under the cell (B, S) containing 3.

- ▶ No Nash equilibrium in pure strategies
- ▶ CP would switch to strategy B if told RP's strategy

Example 2: Odds-and-Evens

MAX

		MIN		
		CP		
		1	2	α_i
RP	1	-1	-1	-1
	2	-1	-1	-1
	β_j	1	1	

Example 2: Odds-and-Evens

		CP		α_i
		1	2	
RP	1	-1	1	-1
	2	1	-1	-1
β_j		1	1	

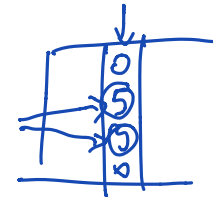
- ▶ No Nash equilibrium in pure strategies
- ▶ For any strategy pair, the losing player can **always improve** if told the strategy chosen by the winning player

Example: Odds-and-Evens (towards mixed strategies)

		CP	
		q_1 1	q_2 2
RP	p_1 1	-1	1
	p_2 2	1	-1

- ▶ Players **randomly** pick strategy with equal probabilities
- ▶ Each strategy pair is played with probability 0.25
- ▶ **Expected value of the game** is 0 for both players
 - ▶ No reason to unilaterally change probabilities
 - ▶ Example of **Nash equilibrium in mixed strategies**

Mixed Strategies

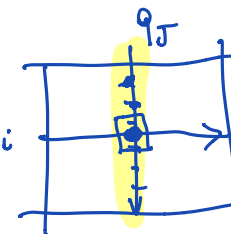


- ▶ In a **mixed strategy** $(p_1, \dots, p_m; q_1, \dots, q_n)$:
 - ▶ RP plays strategy i with probability p_i , $\sum_{i=1}^m p_i = 1$.
 - ▶ CP plays strategy j with probability q_j , $\sum_{j=1}^n q_j = 1$.
- ▶ If $p_k = 1$ or $q_k = 1$, then k is a pure strategy
- ▶ The payoff of the mixed strategy (p, q) will be

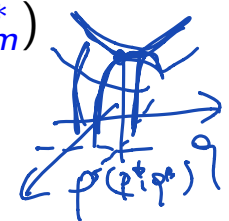
$$V(p, q) = \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij}$$

EXPECTED PAYOFF/COST

Handwritten annotations: (q_1, \dots, q_n) above the sum, (p_1, \dots, p_m) below the sum, and a_{ij} circled in the matrix element.



- ▶ RP seeks probabilities that maximise payoff (p_1^*, \dots, p_m^*)
- ▶ CP seeks probabilities that minimise loss (q_1^*, \dots, q_n^*)



Definition

A mixed Nash equilibrium is a pair of mixed strategies (p^*, q^*) such that $V(p, q^*) \leq V(p^*, q^*) \leq V(p^*, q)$ for all other mixed strategies (p, q) [i.e., no agent has any incentive in unilaterally deviating].

Example: Election Game (revised in mixed strategies)

		CP			
		L	B	S	
RP	L	0	-1	2	p_L
	B	5	4	-3	p_B
	S	2	3	-4	p_S
		q_L	q_B	q_S	

- ▶ The strategy pair (S,B) is played with probability $p_S q_B$
- ▶ (S,B) contributes $p_S q_B \cdot 3$ to the mixed strategy payoff
- ▶ How can player find their optimal probabilities?

Column Player's Perspective

- ▶ Remember the **Assumption**: “Each player chooses a strategy that enables him/her to do best, reasoning in face of the worst-case opponent”
- ▶ CP expects RP to respond with optimal p_i 's for any choice of q_j 's. How should CP choose the q_j 's?

$$\begin{aligned}
 V_{CP} &= \min_{q_1, \dots, q_n} \left[\max_{p_1, \dots, p_m} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij} \right] \\
 &\text{subject to} \\
 &\quad \sum_{j=1}^n q_j = 1, \quad \sum_{i=1}^m p_i = 1, \\
 &\quad q_j \geq 0, \quad p_i \geq 0
 \end{aligned}$$

Handwritten notes and simplifications:

- Below the constraints, a handwritten expression: $\min_q \left[\max_p V(p, q) \right]$
- At the bottom, a simplified handwritten expression: $= \min_q \max_p \sum_i p_i \left(\underbrace{\sum_j q_j a_{ij}}_{d_i} \right)$

Column Player's Perspective (inner program)

Goal: reduce optimisation problem to linear program

- ▶ Let us rewrite and focus on the inner problem

$$V_{CP} = \min_{q_1, \dots, q_n} V_{CP}^{in}(q_1, \dots, q_n)$$

subject to

$$\sum_{j=1}^n q_j = 1, \quad ,$$
$$q_j \geq 0,$$

Column Player's Perspective (inner program is trivial!)

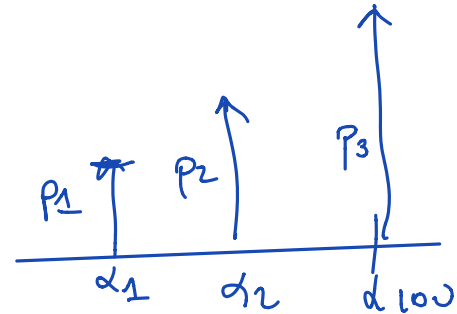
- ▶ For any choice of q_j 's, let $\alpha_i = \sum_{j=1}^n q_j a_{ij}$ be row payoffs
- ▶ Then the inner maximisation problem is:

$$V_{CP}^{in}(q_1, \dots, q_n) = \max_{p_1, \dots, p_m} \sum_{i=1}^m p_i \alpha_i$$

subject to

$$\sum_{i=1}^m p_i = 1,$$

$$p_i \geq 0$$



- ▶ The solution is $p_i = 1$ for the largest α_i , $p_k = 0$ for $k \neq i$.
- ▶ **Example:** maximise $3p_1 + 2p_2 + 5p_3 \Rightarrow p_3 = 1$.

Example 1: inner program is trivial

- ▶ CP evaluates a pure strategy $q_S = 1$

		CP			
		L	B	S	
RP	L	0	-1	2	p_L
	B	5	4	-3	p_B
	S	2	3	-4	p_S
		0.0	0.0	1.0	

- ▶ if RP plays L, $\alpha_L = 0.0 \times 0 + 0.0 \times -1 + 1.0 \times 2 = 2$
- ▶ if RP plays B, $\alpha_B = 0.0 \times 5 + 0.0 \times 4 + 1.0 \times -3 = -3$
- ▶ if RP plays S, $\alpha_S = 0.0 \times 2 + 0.0 \times 3 + 1.0 \times -4 = -4$
- ▶ RP optimal response to CP is $p_L = 1 \Rightarrow V_{CP}^{in} = 2$

Example 2: inner program is trivial

- ▶ CP changes guess and evaluates a mixed strategy

		CP			
		L	B	S	
RP	L	0	-1	2	p_L
	B	5	4	-3	p_B
	S	2	3	-4	p_S
		0.7	0.2	0.1	

- ▶ if RP plays L, $\alpha_L = 0.7 \times 0 + 0.2 \times -1 + 0.1 \times 2 = 0$
- ▶ if RP plays B, $\alpha_B = 0.7 \times 5 + 0.2 \times 4 + 0.1 \times -3 = 4$
- ▶ if RP plays S, $\alpha_S = 0.7 \times 2 + 0.2 \times 3 + 0.1 \times -4 = 1.6$
- ▶ RP optimal response to CP is $p_B = 1 \Rightarrow V_{CP}^{in} = 4$

Column Player (substitute inner in outer program)

- ▶ The inner maximisation optimal value is thus simply

$$V_{CP}^{in}(q_1, \dots, q_n) = \max \{ \alpha_1, \dots, \alpha_m \}$$

$\sum d_i p_i$

- ▶ Expanding the definitions of the α_i 's, we conclude that CP is in fact solving a min-max problem

$$V_{CP} = \min_{q_1, \dots, q_n} \left[\max \left\{ \sum_{j=1}^n q_j a_{1j}, \dots, \sum_{j=1}^n q_j a_{mj} \right\} \right]$$

inner

subject to

$$\sum_{j=1}^n q_j = 1,$$

$$q_j \geq 0$$

Column Player (final LP)

- ▶ The min-max problem is equivalent to a linear program

$$\begin{aligned} V_{CP} &= \min_{\tau, \mathbf{q}_1, \dots, \mathbf{q}_n} \tau \\ \text{subject to} \quad & \tau \geq \sum_{j=1}^n \mathbf{q}_j a_{ij}, \quad \forall i = 1, \dots, m \\ & \sum_{j=1}^n \mathbf{q}_j = 1, \\ & \mathbf{q}_j \geq 0, \end{aligned}$$

- Election Game: $q_L^* = 0, q_B^* = \frac{1}{2}, q_S^* = \frac{1}{2} \Rightarrow V_{CP}^* = \frac{1}{2}$
- Note: the optimal q_j^* 's are independent of the p_i^* 's

Row Player's Perspective

- ▶ A similar reasoning applies to the row player, who instead optimises

$$V_{RP} = \max_{p_1, \dots, p_m} \min_{q_1, \dots, q_n} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij}$$

subject to

$$\begin{aligned} \sum_{i=1}^m p_i &= 1, & \sum_{j=1}^n q_j &= 1, \\ p_i &\geq 0, & q_j &\geq 0 \end{aligned}$$

Row Player's Perspective

- ▶ The max-min problem can be shown equivalent to a linear program

$$V_{RP} = \max_{\tau, p_1, \dots, p_m} \tau$$

subject to

$$\tau \leq \sum_{i=1}^m p_i a_{ij}, \quad \forall j = 1, \dots, n$$

$$\sum_{i=1}^m p_i = 1,$$

$$p_i \geq 0,$$

- ▶ Election Game: $p_L^* = \frac{7}{10}, p_B^* = \frac{3}{10}, p_S^* = 0 \Rightarrow V_{RP}^* = \frac{1}{2}$
- ▶ Observation: p_i^* 's will be independent of the q_j^* 's.

Minimax Theorem

Theorem (Von Neumann, 1928). For every two-person zero-sum game, the RP and CP linear programs have the same optimal value, i.e.,

$$V_{RP} = \max_{p_1, \dots, p_m} \min_{q_1, \dots, q_n} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij} = \min_{q_1, \dots, q_n} \max_{p_1, \dots, p_m} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij} = V_{CP}$$

Proof: ideas?

Minimax Theorem

Theorem (Von Neumann, 1928). For every two-person zero-sum game, the RP and CP linear programs have the same optimal value, i.e.,

$$V_{RP} = \max_{p_1, \dots, p_m} \min_{q_1, \dots, q_n} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij} = \min_{q_1, \dots, q_n} \max_{p_1, \dots, p_m} \sum_{i=1}^m \sum_{j=1}^n p_i q_j a_{ij} = V_{CP}$$

Proof: ideas? Result follows by **strong duality** since the two programs are the **duals** of each other.

Consequences:

- ▶ A **Nash Equilibrium in mixed strategies** always exists!!!
 - ▶ Players **expect identical payoffs**
 - ▶ Neither player has an incentive to change p_i or q_j
- ▶ Statement generalises to M players (Nash, 1949).

Historical Notes

BACK @ 11:04

- In 1928, Von Neumann first proved the Minmax Theorem for zero-sum games. He later wrote:

"As far as I can see, there could be no theory of games ... without that theorem ... I thought there was nothing worth publishing until the Minimax Theorem was proved."

- In 1949, Nash gave a **one-page** proof (in 27-page thesis) that games with any number of players have a mixed equilibria.

Section	Page
Table of Contents	
1. Introduction	1
2. Formal Definitions and Terminology	2
3. Existence of Equilibrium Points	6
4. Symmetries of Games	7
5. Solutions	9
6. Generalized Form of Solutions	15
7. Continuity and Contradiction Methods	17
8. A Theorem on Other Games	21
9. Motivation and Interpretation	23
10. Applications	27
11. Bibliography	27
12. Acknowledgments	27

Existence of Equilibrium Points

I have previously published Existence of Equilibrium Points in Ann. of Math. (1950) 49-42, a proof of the result based on Kakutani's generalized fixed point theorem. The proof given here uses the Brouwer theorem.

The method is to set up a sequence of continuous mappings $\mathcal{A} \rightarrow \mathcal{A}^1(\mathcal{A}, \lambda); \mathcal{A} \rightarrow \mathcal{A}^2(\mathcal{A}, \lambda); \dots$ whose fixed points have an equilibrium point as limit point. A limit mapping exists, but is discontinuous, and need not have any fixed points.

THEM. 1: Every finite game has an equilibrium point.

Proof: Taking our standard notation, let \mathcal{A} be an n -tuple of mixed strategies, and $\beta_{\mathcal{A}}(\mathcal{A})$ the payoff to player i if he uses his pure strategy \mathcal{A}_i and the others use their respective mixed strategies in \mathcal{A} . For each integer λ we define the following continuous functions of \mathcal{A} :

$$q_i(\mathcal{A}) = \max_{\mathcal{A}_i} \beta_{\mathcal{A}}(\mathcal{A}_i, \mathcal{A}),$$

$$\phi_{ia}(\mathcal{A}, \lambda) = \beta_{\mathcal{A}}(\mathcal{A}_i, \mathcal{A}) - q_i(\mathcal{A}) + \frac{1}{\lambda}, \text{ and}$$

$$\phi_i^+(\mathcal{A}, \lambda) = \max \left[0, \phi_{ia}(\mathcal{A}, \lambda) \right].$$

Now $\sum_{\mathcal{A}_i} \phi_{ia}^+(\mathcal{A}, \lambda) \geq \max_{\mathcal{A}_i} \beta_{\mathcal{A}}(\mathcal{A}_i, \mathcal{A}) = \frac{1}{\lambda} > 0$ so that

$$C_i(\mathcal{A}, \lambda) = \frac{\phi_i^+(\mathcal{A}, \lambda)}{\sum_{\mathcal{A}_i} \phi_{ia}^+(\mathcal{A}, \lambda)}$$

is continuous.

Define $S_i^*(\mathcal{A}, \lambda) = \sum_{\mathcal{A}_i} C_i(\mathcal{A}, \lambda) \mathcal{A}_i$ and $\mathcal{A}^1(\mathcal{A}, \lambda) = (S_1^*, S_2^*, \dots, S_n^*)$. Since all the operations have preserved continuity, the mapping $\mathcal{A} \rightarrow \mathcal{A}^1(\mathcal{A}, \lambda)$ is con-

tinuous, and since the space of n -tuples, \mathcal{A} , is a cell, there must be a fixed point for each λ . Since there will be a subsequence \mathcal{A}_{λ_k} converging to \mathcal{A}^* , where \mathcal{A}_{λ_k} is fixed under the mapping $\mathcal{A} \rightarrow \mathcal{A}^1(\mathcal{A}, \lambda_{k_0})$. Now suppose \mathcal{A}^* were not an equilibrium point. Then if $\mathcal{A}^* = (S_1^*, S_2^*, \dots, S_n^*)$ some component S_i^* must be non-optimal against the others, which means S_i^* was some pure strategy \mathcal{A}_i which is non-optimal. [See (8), (9), (10)] This means that $\beta_{\mathcal{A}}(\mathcal{A}_i) < q_i(\mathcal{A}^*)$ which justifies writing $\beta_{\mathcal{A}}(\mathcal{A}_i) - q_i(\mathcal{A}^*) < -\epsilon$.

From continuity, if λ is large enough $\left| [\beta_{\mathcal{A}}(\mathcal{A}_i) - q_i(\mathcal{A}_{\lambda_k})] - [\beta_{\mathcal{A}}(\mathcal{A}_i) - q_i(\mathcal{A}^*)] \right| < \epsilon/2$ and $\frac{1}{\lambda_{k_0}} < \epsilon/2$.

Adding, $\beta_{\mathcal{A}}(\mathcal{A}_i) - q_i(\mathcal{A}_{\lambda_k}) + \frac{1}{\lambda_{k_0}} < 0$ which is simply $\phi_{ia}(\mathcal{A}_{\lambda_k}, \lambda_{k_0}) < 0$, whence $\phi_{ia}^+(\mathcal{A}_{\lambda_k}, \lambda_{k_0}) = 0$ whence $C_i(\mathcal{A}_{\lambda_k}, \lambda_{k_0}) = 0$. From this last equation we know that \mathcal{A}_{λ_k} is not used in \mathcal{A}_{λ_k} since $\mathcal{A}_{\lambda_k} = \sum_{\mathcal{A}_i} C_i(\mathcal{A}_{\lambda_k}, \lambda_{k_0}) \mathcal{A}_i$, because \mathcal{A}_{λ_k} is a fixed point.

And since $\mathcal{A}_{\lambda_k} \rightarrow \mathcal{A}^*$, \mathcal{A}^* is not used in \mathcal{A}^* , which contradicts our assumption.

Hence \mathcal{A}^* is indeed an equilibrium point.

- In 1994, Nash was awarded the Nobel Prize for this work