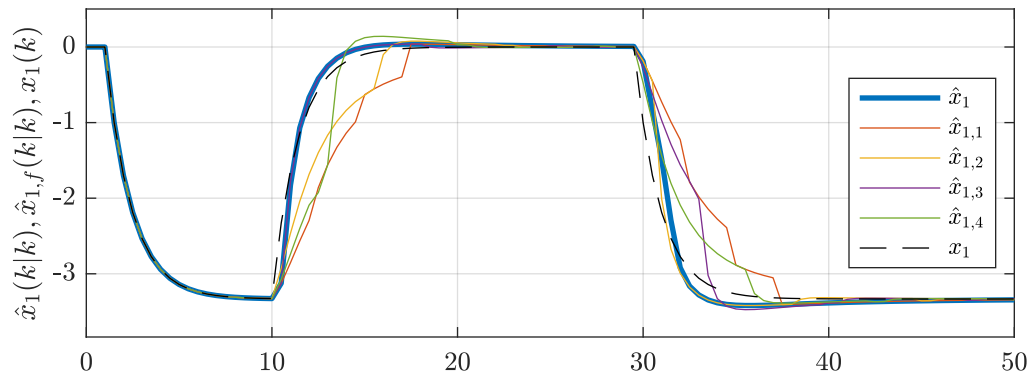


(a) Estimates of model state $x_1(k)$



(b) Estimates of model state $x_2(k)$

