```
?
C
active
                      u
u
açtive
                             u,
v
active
inactive
                                     v',
u'_{\iota}
       \begin{array}{l} \theta = ||\theta_1 - \theta_2|| = ||Angle(p_1) - Angle(p_2)| \\ Angle \\ p_i \in \\ \{p_y, p_x, p_{-y}, p_{-x}\} \\ \theta_i \in \\ \{0, 90, 180, 270\} \\ \theta_a \\ p_a \\ p_b \\ p_b
                       \begin{cases} \{p_x, p_{-x}\} \\ \{p_y, p_{-y}\} \\ \vec{p}_x^2 \\ \vec{p}_x^2 \\ \vec{p}_x^2 \\ \vec{q}_x^2 \\ \vec{q}_x^
```