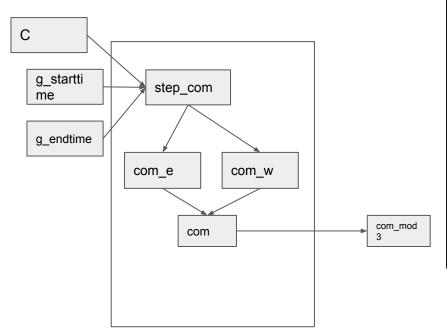
## Modules and their relationship

Bilal

datawiz

#### 2.combinations

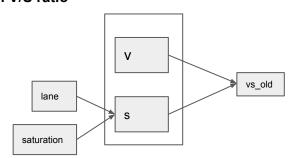


```
#start time of the green time g_s starttime c_s 
g_endtime1 - g_starttime[1]*phasing[phase2[1]
g_endtime2 - g_starttime[2]*phasing[phase2[2]
g_endtime3 - g_starttime[3]*phasing[phase1[3]*phasing[phase2[3]]
 g_endtime33<-g_starttime[3]+phasing$phase2[3]
 g_endtime4<- g_starttime[4]+phasing$phase2[4]
g_endtime44<-g_starttime[4]+phasing$phase1[4]+phasing$phase2[4]
 g_endtime_e<- c(g_endtime1,g_endtime2,g_endtime3,g_endtime4)
 g_endtime_w<- c(g_endtime1,g_endtime2,g_endtime33,g_endtime44)
 step_com<- function(C, g_starttime, g_endtime){
      step<- C-(g_endtime-g_starttime)
      step1 - as.vector(1:step[1]
      step2<- as.vector(1:step[2
      step3<- as.vector(1:step[3]
      step4<- as.vector(1:step[4])
      step_com<- expand.grid(step1,step2,step3,step4)
      return(step_com)
 com_e<- step_com(C, g_starttime, g_endtime_e)
 com_w<- step_com(C, q_starttime, q_endtime_w)
 com<- com_e[!(com_e$Var4>max(com_w$Var4)),]
 com<- com[1:10,]
com_mod<- com
 com_mod$diff12<- com_mod$var1- com_mod$var2
 com_mod$diff13<- com_mod$var1- com_mod$var3
 com_mod$diff14<- com_mod$var1- com_mod$var4
 com_mod2<- com_mod[!duplicated(com_mod[,5:7]),]</pre>
 com_mod3<- com_mod2[,c(1:4)]
 com_mod3<- com_mod3[c(1:10),]
```

## 3.Pedestrian time



#### 1. V/S ratio

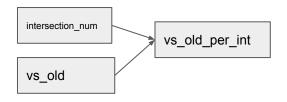


```
intersection_num<- 1
DS_phasing_standard<- 2
phasing$phase1m<- c("3","7",|"8,3","4,7")
phasing$phase2m<- c("8,4","8,4","8,4","8,4")
phasing$phase3m<- c("5","1","7","1")
phasing$phase4m<- c("0","0","0","2,5")
phasing$phase5m<- c("0","0","0","1,6")
phasing SET<- c(2820, 2616, 1730, 2495)
phasing$EL<- c(399,0,560,0)
phasing$wT<- c(1383,1372,1006,1878)
phasing$WL<- c(0,64,91,156)
phasing NT < -c(0,0,333,0)
 phasing NL<- c(0,193,130,126)
phasing$ST<- c(0,0,660,0)
phasing$SL<- c(137,0,979,0)
saturation<- data.frame("ET"=rep(2000,4),"wT"=rep(2000,4),"NT"=rep(2000,4),"ST"=rep(2000,4),
                                                                  "EL"=rep(1800,4), "wL"=rep(1800,4), "wL"=rep(1800,4), "SL"=rep(1800,4), "lane_ST" = c(1,0,4,0), "lane_ST" = c(1,0,4,0), "lane_ST" = c(1,0,4,0), "lane_ST" = c(1,0,4,0), "lane_ST" = rep(1,4), "lane_ML" = rep(1,4), "lane_ML" = rep(1,4), "lane_SL" = rep(1,4), "lane_SL
saturation$ET_s<- (saturation$ET*(saturation$lane_ET))
saturationSWT s<- (saturationSWT*(saturationSlane WT)
saturation NT_s<- (saturation NT*(saturation lane NT)
saturation$ST_s<- (saturation$ST*(saturation$lane_ST)
saturation$EL_s<- (saturation$EL*(saturation$lane_EL)
saturationSWL s<- (saturationSWL*(saturationSlane WL)
saturation NL_s<- (saturation NL*(saturation lane_NL)
saturation$SL_s<- (saturation$SL*(saturation$lane_SL))
vs_old<- data.frame("ET_v/s"=(phasing%ET/saturation%ET_s),"WT_v/s"=(phasing%WT/saturation%WT_s),
                                                "NT_v/s"=(phasing%NT/saturation%NT_s),"ST_v/s"=(phasing%ST/saturation%ST_s),
"EL_v/s"=(phasing%EL/saturation%EL_s),"WL_v/s"=(phasing%WL/saturation%WL_s),
                                                "NL_v/s"=(phasing$NL/saturation$NL_s), "SL_v/s"=(phasing$SL/saturation$SL_s)
```

### 5.Degree of Saturation green\_old DS old vs\_old DS needed DS seq green\_old!<- phasing[1,4:6] green\_old2<- phasing[2,4:6] green\_old3<- phasing[3,4:8] green\_old4<- phasing[4,4:6] DS green n ew diff\_green possible\_times ==0 slack\_time NO recommended green YES pd\_time green\_old = green\_old

```
Socials in contains of prescribing
Socials in contains of prescribing prescribing prescribing
Socials in contains of prescribing pres
```

## 4.V/s for each intersection



```
#V/S

vs_old<- data.frame("ET_v/s"=(phasing$ET/saturation$ET_s),"WT_v/s"=(phasing$WT/saturation$WT_s),

"NT_v/s"=(phasing$NT/saturation$NT_s),"ST_v/s"=(phasing$ST/saturation$ST_s),

"EL_v/s"=(phasing$EL/saturation$EL_s),"WL_v/s"=(phasing$ML/saturation$WL_s),

"NL_v/s"=(phasing$EL/saturation$NL_s),"SL_v/s"=(phasing$SL/saturation$WL_s),

vs_old[is.na(vs_old)] = 0

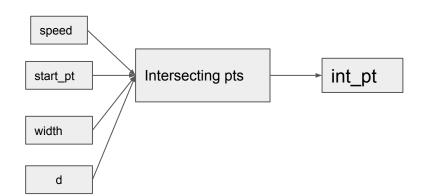
vs_old_vector<- as.matrix(vs_old[intersection_num,])#change to whichever intersection you want

vs_old_vector<- as.vector(vs_old_vector)

vs_old_movs<- c(8,4,6,2,3,7,1,5)

vs_old_per_int<- cbind.data.frame(vs_old_vector,vs_old_movs)
```

6.Point of intersection function



```
#function to find the intersection pts.

94 * intersect_pts <- function(speed,start_pt,width,dist) {

A<- matrix(c(speed,1,1,0), nrow = 2, ncol = 2, byrow = TRUE)

B<- matrix(c(start_pt+width,dist), nrow = 2, ncol = 1, byrow = TRUE)

invA<- solve(A)

int_pt<- invA %*% B

int_pt<- as.vector(int_pt)

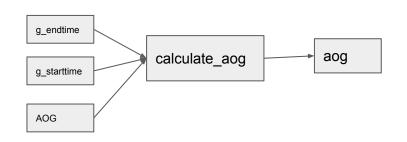
return(int_pt)

100

101 *

}
```

7.AOG calculation function



```
#function to find the location of max AOG position and number of web passing...

calculate_aog<- function(g_endtime,g_starttime,AOG){

vector10<-vector(mode = "numeric")

# c=l
while(!g_endtime>C-1){

g_starttime<- g_starttime+1

g_endtime<- g_endtime+1

count_before<- sum(AOG > g_starttime)

vector10<- append(vector10, count_before)

# b_count<- list("place" = which.max(vector10), "Arrival_num" = max(vector10))

return(vector10)

}

#function to find the location of max AOG position and number of veb passing...

ACG | Vector10<- | Vector10 | V
```

9.Start and end time of green

```
g_starttime ______ g_endtime
```

```
#start time of the green time

g_starttime<- c(0,0,0,0) #random choosing to match the combinations using int1 to 4

g_end time of green time of east bound # for overlapping phases we will add the phase for that movement

g_endtime1<- g_starttime[1]+phasing$phase2[1]

g_endtime2<- g_starttime[2]+phasing$phase2[2]

g_endtime3<- g_starttime[3]+phasing$phase1[3]+phasing$phase2[3]

g_endtime4<- g_starttime[3]+phasing$phase2[3]

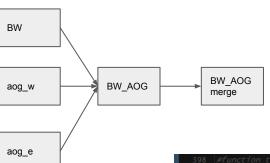
g_endtime4<- g_starttime[4]+phasing$phase2[4]

g_endtime44<-g_starttime[4]+phasing$phase1[4]+phasing$phase2[4]

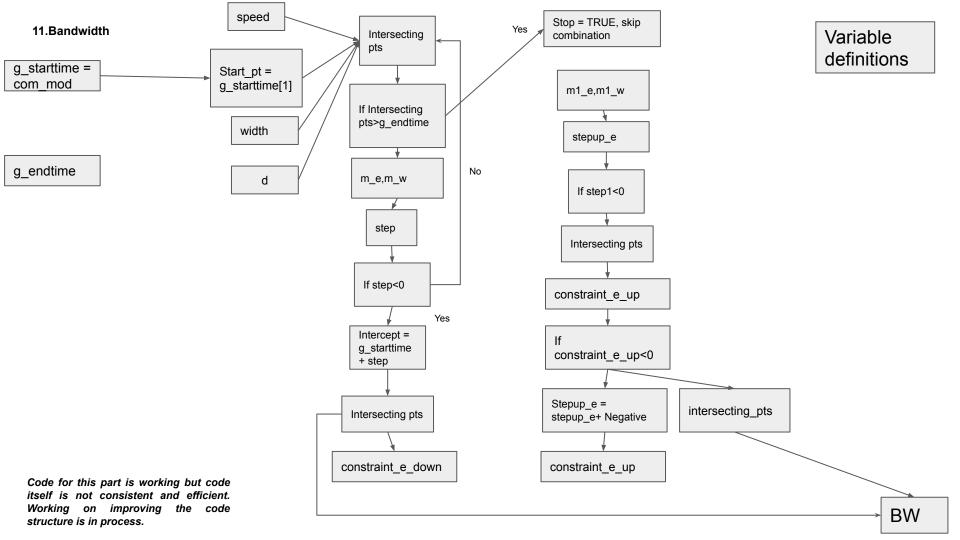
g_endtime_e<- c(g_endtime1,g_endtime2,g_endtime3,g_endtime4)

g_endtime_w<- c(g_endtime1,g_endtime2,g_endtime33,g_endtime44)
```

10.Merging AOG and BW



```
399 - BW_AOG<- function(BW,aog_e, aog_w){
        aog_e1<- as.data.frame(unlist(aog_e[1]))</pre>
        aog_e2<- as.data.frame(unlist(aog_e[[2]]))
        aog_e3<- as.data.frame(unlist(aog_e[[3]]))
        aog_e4<- as.data.frame(unlist(aog_e[[4]]))
        aog_e1$com1<- 1:length(aog_e[[1]])</pre>
        aog_e2$com2<- 1:length(aog_e[[2]])</pre>
        aog_e3$com3<- 1:length(aog_e[[3]])</pre>
        aog_e4$com4<- 1:length(aog_e[[4]])</pre>
        BW_AOGmerge<- merge(x = BW, y = aog_e1, by = "com1", all.x = TRUE)
        BW_AOGmerge<- merge(x = BW_AOGmerge, y = aog_e2, by = "com2", all.x = TRUE)
BW_AOGmerge<- merge(x = BW_AOGmerge, y = aog_e3, by = "com3", all.x = TRUE)
        BW AOGMerge - merge x = BW AOGmerge, y = aog e4. by = "com4", all.x = TRUE
        aog_w1<- as.data.frame(unlist(aog_w[[1]]))</pre>
        aog_w2<- as.data.frame(unlist(aog_w[[2]]))</pre>
        aog_w3<- as.data.frame(unlist(aog_w[[3]]))</pre>
        aoq_w4<- as.data.frame(unlist(aog_w[[4]]))</pre>
        aog_w1$com1<- 1:length(aog_w[[1]])</pre>
        aog_w2$com2<- 1:length(aog_w[[2]])
        aog_w3$com3<- 1:length(aog_w[[3]])
        aog_w4\$com4<-1:length(aog_w[[4]])
        BW_AOGmerge \leftarrow merge(x = BW_AOGmerge, y = aog_w1, by = "com1", all.x = TRUE)
        BW_AOGmerge<- merge(x = BW_AOGmerge, y = aog_w2, by = "com2", all.x = TRUE)
BW_AOGmerge<- merge(x = BW_AOGmerge, y = aog_w3, by = "com3", all.x = TRUE)
BW_AOGmerge<- merge(x = BW_AOGmerge, y = aog_w4, by = "com4", all.x = TRUE)
        BW_AOGmerge[, 5:14] <- sapply(BW_AOGmerge[, 5:14], as.numeric)
       return(BW_AOGmerge)
```



my\_vector\_e1 <- vector(mode="numeric")
my\_vector\_e2 <- vector(mode="numeric")
my\_vector\_e3 <- vector(mode="numeric")
my\_vector\_e4 <- vector(mode="numeric")</pre>

intpt\_en intpt\_e constraint\_e\_down intpt\_en g\_starttime

intpt\_en[i]<- intersect\_pts(-speed\_E,as.numeric(intercept\_e),0,d[i])[2]

f(intpt\_en[i]>g\_endtime\_e[i])
intpt\_en<- NULL
intercept\_e<- g\_starttime[1]
stop4<- TRUE</pre>

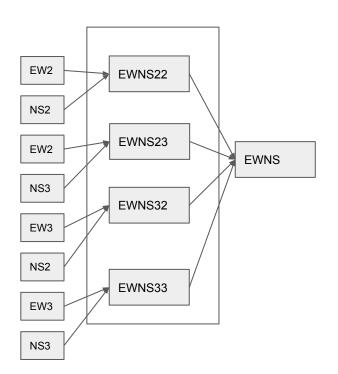
```
my_vector_w2 <- vector(mode="numeric"
my_vector_w3 <- vector(mode="numeric"
my_vector_w4 <- vector(mode="numeric"
count steps count step+1
            or (i in 1:nrow(com))
   action time - config.

continue - scattere();phasing;phase2();
g.entine(-config.entine();phasing;phase2();
g.entine(-config.entine();phasing;phase2();
g.entine(-config.entine();phasing;phase2();phasing;phase2();
g.entine(-config.entine();phasing;phase2();
g.entine(-config.entine();phasing;phase2();phasing;phase2();
g.entine(-config.entine();phasing;phase2();phasing;phase2();
g.entine(-config.entine();phasing;phase2();phasing;phase2();phasing;phase2();phasing;phase2();phasing;phase2();phasing;phase2();
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         (step1<0){
intpt_wn<-intpt_w
constraint_w_down<- intpt_wn-g_starttime
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            (step1>0){
intercept ws- start pt wistep1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     or (i in 1:4){
   intpt_wn[i]<- intersect_pts(speed_W,as.numeric(intercept_w),0,d[i])[2]
         intpt_e<- NULL
intpt_w<- NULL
stopl<- FALSE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              if(intpt_wn[i]>g_endtime_w[i])
intpt_wn<- NULL
intercept_w<- start_pt_w</pre>
            stop4<- FALSE
start_pt_w <- g_starttime[4]+(speed_w*d[4])
            stop5<- FALSE
stop_new<- FALSE
                           intpt efils- intersect pts(-speed E.as.numeric(g starttime[1]).0.d[i])[2]
                                     f(intpt_e[i]>q_endtime_e[i]){
                                     intpt_e<- NULL
stop1<- TRUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            constraint_w_down<- intpt_wn-q_starttime
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                ml - min(as.numeric(g_endtime_e))
p - as numeric(g_endtime_e) - mal
p - min(as.numeric(g_endtime_e))
min(as.numeric(g_endtime_e))
min(as.numeric(g_endtime_e))
stepu_es- abs(intpt_enimi_e) - as.numeric(g_endtime_e[ml_e])
intpt_e_upe- NOLL
                     (intpt_w[i])-g_endtime_w[i])
intpt_w<- NuLL
stop_new<- TRUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     - min(as.numeric(g_endtime_w))
- as.numeric(g_endtime_w)--m2
- which(p2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   pz<- wnich[pz]
m2_w<- max(pz)
stepup_w<- abs(intpt_wn[m2_w]-as.numeric(g_endtime_w[m2_w]))
intpt w up<- NULL
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     abiting(a=intercept_e-steam=e, b=speed_E, h=hull, v=hull, col="red", lmd = in(1 in 1:4)[
intpt_e_upils= intersect_pts(speed_E, as.numeric(intercept_e), stepup_e, d[i])[2]
intpt_w_upils= intersect_pts(speed_W, as.numeric(intercept_w), stepup_w, d[i])[2]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      constraint_e_up = as.numeric(g_endtime_e) -as.numeric(intpt_e_up)
constraint_w_up = as.numeric(g_endtime_w) -as.numeric(intpt_w_up)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            (any (5 negative constraint = up), na navalet()(
negative = nac(whitch(constraint = up))
negative = constraint = up | negative |
negative = constraint = up |
negative = const
Intpr.en intpr.e intpr.e intpr.en g.starttime controlled. As a starttime controlled as a starttime controlled. As a starttime intercept.e. g.starttime[1] intercept.e. starttime[1] intercept.e. starttime[intercept.e. starttime[intercept.e. g.starttime[in.e] intpr.en[in.e] step: g.starttime[in.e] intpr.en[in.e]
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            (amy (5 magnet we conservating a supply (5 magnet) (5 magnet we conservating a supply (6 magnet we conservating a supply (6 magnet we conservating a supply (6 magnet we) (7 magnet we conservating a supply (6 magnet we) (7 magnet we conservating a supply (6 magnet we conservating a supply (6 magnet we conservating a supply (6 magnet we conservation)) (7 magnet we conservation) (8 magnet we conserv
```

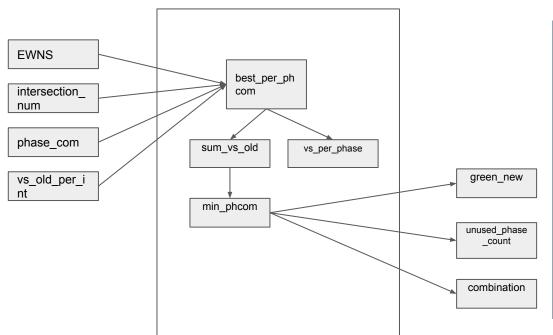
```
constraint_e_up<- as.numeric(g_endtime_e)-as.numeric(intpt_e_up)
width_e<- stepup_e
  intpt_w_up[i] - intersect_pts(speed_W,as.numeric(intercept_w),stepup_w,d[i])[2]
 constraint_w_up <- as.numeric(q_endtime_w)-as.numeric(intpt_w_up)
  intpt_w_up[i]<- intersect_pts(speed_W,as.numeric(intercept_w),stepup_w,d[i])[2]
 constraint_w_up<- as.numeric(g_endtime_w)-as.numeric(intpt_w_up)
width_w<- stepup_w
  intpt_w_up[i] - intersect_pts(speed_W,as.numeric(intercept_w),stepup_w,d[i])[2]
constraint_w_up<- as.numeric(g_endtime_w)-as.numeric(intpt_w_up) width_w<- stepup_w
my_vector_e1 <- append(my_vector_e1, width_e)
my_vector_e2 <- append(my_vector_e2, constraint_e_up)
my_vector_e3 <- append(my_vector_e2, constraint_e_down
my_vector_e4 <- append(my_vector_e4, g_starttime)
count_step-count_step)</pre>
my_vector_w1 <- append(my_vector_w1, width_w)
my_vector_w2 <- append(my_vector_w2, constraint_m_up)
my_vector_w3 <- append(my_vector_w2, constraint_m_down)
my_vector_w4 <- append(my_vector_w4, q_starttime)
myint(count_step)
```

```
 \begin{array}{lll} & \text{Re\_e} < & \text{cbind.data.frame} (combinations\_e,my\_vector\_ei,constraint\_e\_down,constraint\_e\_up) \\ & \text{Re\_e} < & \text{Re\_e}(.c(1:3)) \\ & \text{mass}(3k_w) < & \text{C}'(cosi',"cosi',"cosi',"cosi',"swe') \\ \end{array} 
contraint, a_{ij}, a_{
BM_W<- cbind.data.frame(combinations_w,my_vector_w1,constraint_w_down,constraint_w_up)
BM_W<- BM_W[_c(1:35)]
names(BM_W)<- c("cons", "cons", "cons", "cons", "cons", "BM_W")</pre>
8W<- merge.data.frame(8W_e,8M_w, by = c("com1","com2","com3","com4")
8W <- apply(8W,2,as.character)</pre>
```

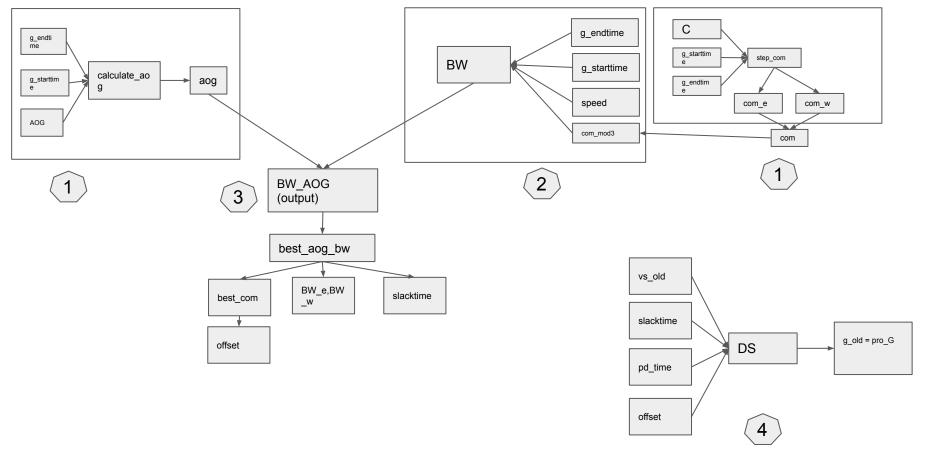
### 12.Phasing



### 12.Phasing

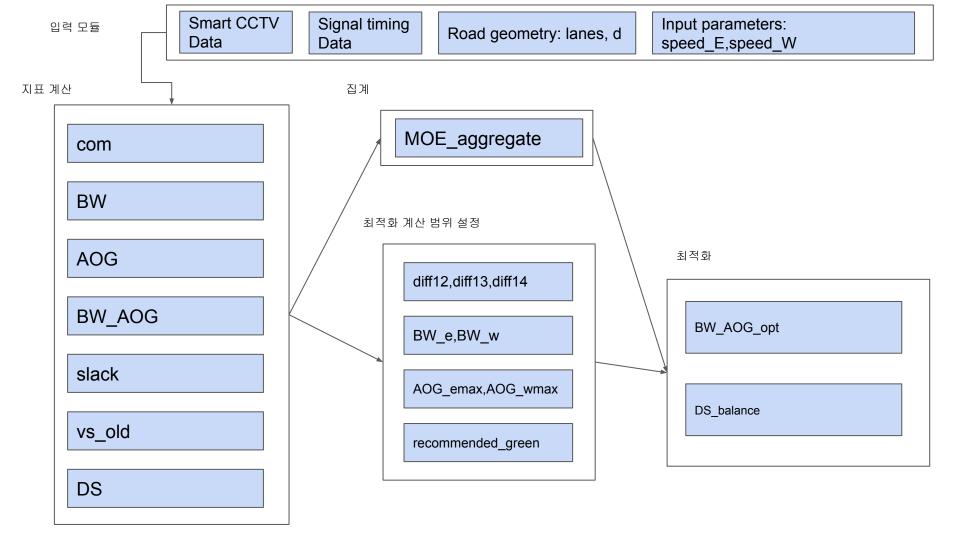


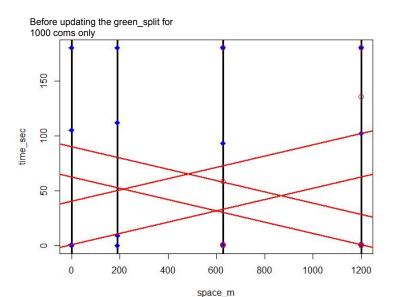
```
best_per_phcom<- function(EWNS, vs_old_per_int, phase_com, intersection_num)
   for (i in 1:nrow(EWNS)){
         xxxx<- EWNS[i,]
xxxx<- as.data.frame(as.vector(as.matrix(xxxx)))</pre>
         xxxx$id<-1:mrow(xxxx)
yye, merge(xxxx,vs_old_per_int, all = TRUE, by.x = "as.vector(as.matrix(xxxx))", by.y = "vs_old_movs")
yyy<- yyy|order(xyys_id), ]</pre>
               f(phase\_com == 22){}
              vs_sum<- sum(ph)
       phc - (pht,ph2,ph2,ph4,ph5)
vs_sume - sum(ph3)
vise | f(ph3e_com=3))
vise | f(ph3e_com=3)
vise | f(ph3e_com=5)
vis
                   vs_sum<- sum(ph)
             sum_vs_old <- append(sum_vs_old, vs_sum)
   vs_per_phase<- as.data.frame(matrix(ph,ncol = original_phase_count, byrow = TRUE), stringsAsFactors = FALSE) com_phasing<- cbind.data.frame(EWNS,sum_vs_old,vs_per_phase)
                        n(com_phasing)
```



Process 1: 1-(1,2)>3>4>3> end

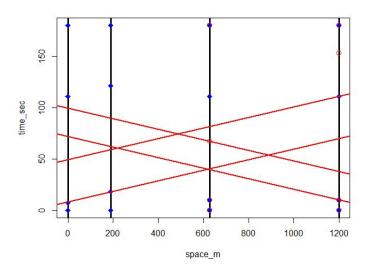
Process 2: 1-(1,2)>3>4>1-(1,2)>3>end





```
> print(width_e)
[1] 39.28571
> print(width_w)
[1] 27.58286
> print(slag_down)
[1] 0.000000 1.771429 32.297143 61.714286
> print(slag_up)
[1] 64.71429 61.94286 20.41714 0.00000
> print(slag_down_w)
[1] 61.71429 43.94286 29.41714 0.00000
> print(slag_up_w)
[1] 14.70286 31.47429 0.00000 106.41714
```

#### After updating the green\_split



```
[1] 41.05714

print(width_w)

[1] 27.58286

print(slag_down)

[1] 1.228571 0.000000 30.525714 59.942857

print(slag_up)

[1] 61.71429 61.94286 29.41714 0.00000

print(slag_down_w)

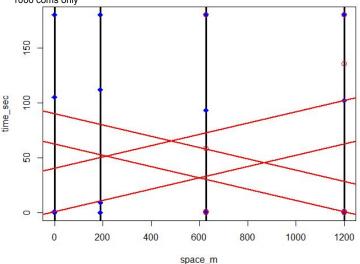
[1] 6.471429e+01 4.394286e+01 2.941714e+01 7.105427e-15

print(slag_up_w)

[1] 11.70286 31.47429 0.00000 115.41714
```

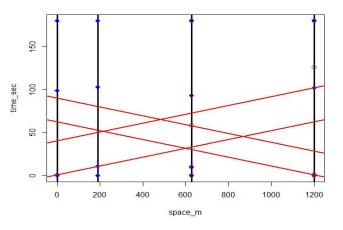
### Updated

Before updating the green\_split for 1000 coms only



```
> print(width_e)
[1] 39.28571
> print(width_w)
[1] 27.58286
> print(slag_down)
[1] 0.000000 1.771429 32.297143 61.714286
> print(slag_up)
[1] 64.71429 61.94286 20.41714 0.00000
> print(slag_down_w)
[1] 61.71429 43.94286 29.41714 0.00000
> print(slag_up_w)
[1] 14.70286 31.47429 0.00000 106.41714
```

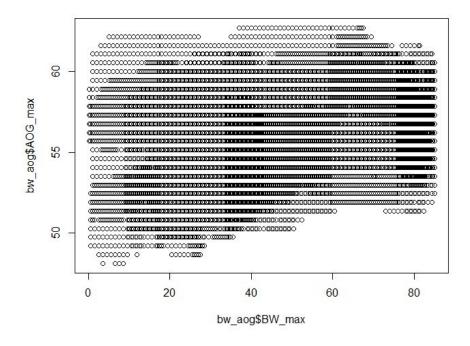
#### After updating the green split

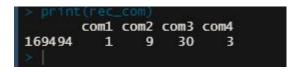


```
> print(width_e)
[1] 39.28571
> print(width_w)
[1] 27.58286
> print(slag_down)
[1] 0.00000 0.00000 23.29714 61.71429
> print(slag_up)
[1] 58.71429 52.94286 20.41714 0.00000
> print(slag_down_w)
[1] 61.71429 42.17143 20.41714 0.00000
> print(slag_up_w)
[1] 8.702857 22.474286 0.000000 97.417143
```

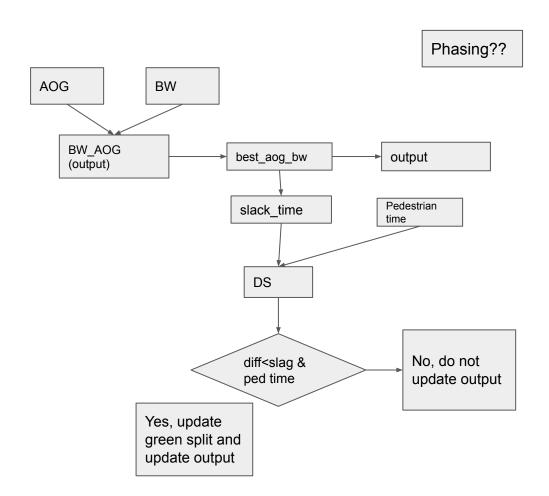
	교차로명	요일	*	시간 수	phase1	phase2	phase3	*	phase4	† phase5	
1	서대전나들목삼거리	주중		17:00~21:00	5	3 10	4	23	NA	NA	
2	서일고교삼거리	주중		17:00~21:00	4	7 10	3	30	NA	NA	
3	진잠네거리	주중		17:00~21:00	3	5 5	7	18	50	20	
4	구봉중삼거리	주중		17:00~21:00	3	3 10	1 .	46	NA	NA	
rearrar		ohasing	×								
a	☐ Y Filter		×	시간 수	nhase1	nhace?	nhase3	<b>‡</b>	nhaced	† nhace5	3
	▲ ▼ Filter 교차로명 ÷	요일		시간 후	phase1	phase2 \$	phase3	÷	phase4	† phase5	(8:
	☐ Y Filter	요일		시간 <sup>‡</sup> 17:00~21:00	phase1 <sup>†</sup>			÷ 23	phase4	† phase5	- (3:
1	▲ ▼ Filter 교차로명 ÷	요일				98			2012	The second	(3)
1 2	T Filter 교차로명 <sup>‡</sup> 서대전나들목삼거리	요일 주중		17:00~21:00	53	98			NA	NA	8

### Final plot









### BW\_Input:

- . Green time
- Distance between intersections
- Phasing scheme
- 4. Speed for east and west bound

### AOG Input:

- 1. Green time
- . Phasing scheme
- 3. AOG arrivals on B.S during Cycle time

### DS\_Input:

- Green time
- Volumes
- 3. Lanes of road
- 4. Width of road
- 5. Phasing scheme
- 6. Slack time
- 7. Standard phasing number