

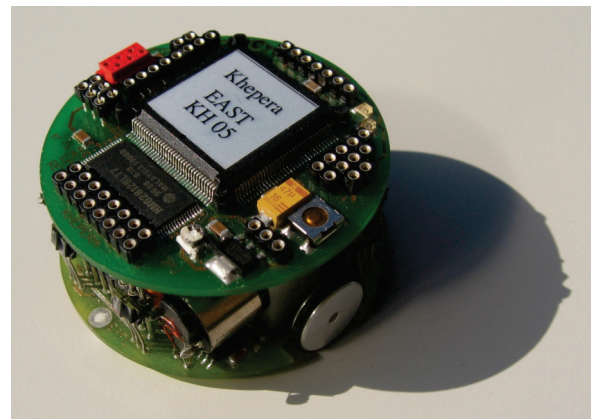
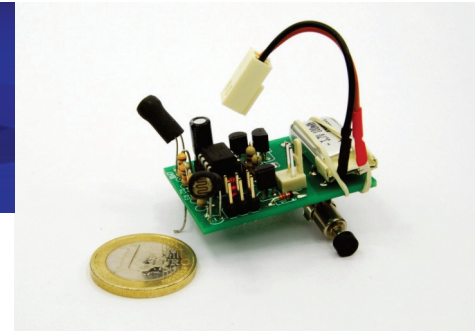
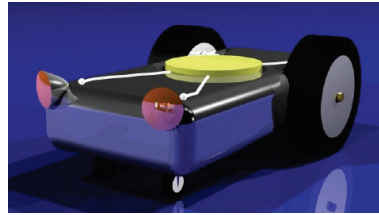
## ***Dataworld - Collegamenti***

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- Braitenberg vehicle***

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# Braitenberg vehicle

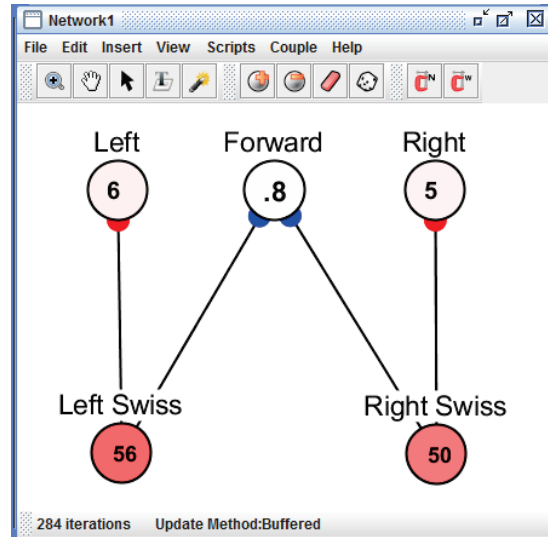
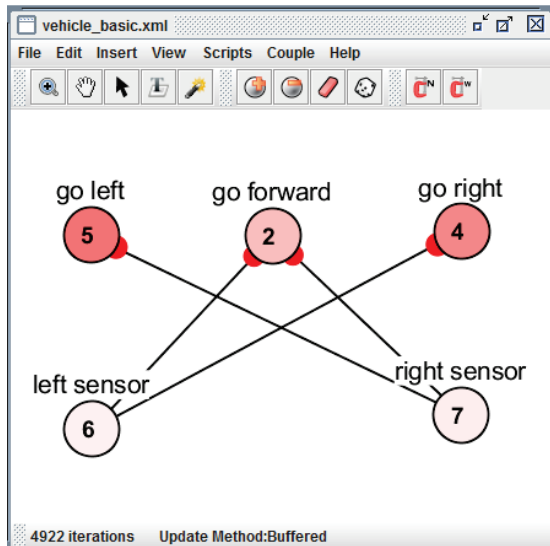


# Braitenberg vehicle

- The vehicle represents the simplest form of behavior based artificial intelligence and embodied cognition
  - intelligent behavior that emerges from sensorimotor interaction between the agent and its environment, without any need for an internal memory, representation of the environment, or inference
- A first example could be agent that has one light-detecting sensor that directly stimulates its single wheel, implementing the following rules:
  - More light produces faster movement
  - Less light produces slower movement
  - Darkness produces standstill
- This behavior can be interpreted as a creature that is afraid of the light and that moves fast to get away from it. Its goal is to find a dark spot to hide

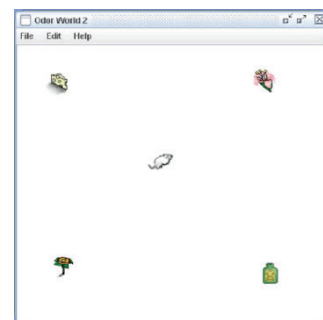
# Braitenberg vehicle

- Cosa potrebbero fare questi veicoli?



# Odorworld

- In Odor World, sensory stimulation is modeled by simulating the impact an environment will have on a creature's sensory receptors
- Each object in the Odor World is associated with a "stimulus vector"
  - the way this vector will impact an agent is controlled by the entity and world dialog boxes
- In general, the further apart the creature and an object are from each other, the smaller the input generated by the world component is



0.10
0.40
1.00
0.00
0.20
0.00
0.00



# Odorworld - agents

- An **agent** is a creature in Odor World that can be controlled by a neural network
  - the **neural network** can be thought of as the brain of the agent; without a network controlling the agent, it does nothing
- For a network to control an agent, it must be **coupled** to an agent by Output Commands and Input Sensors
  - **output commands** are the motor controls of an agent, like moving forward or backward, and turning left or right
  - an agent's **input sensor** abstractly model reaction to stimuli, though they were created with olfaction in mind
- Sensors at three positions relative to the agent detect stimulus values associated with different objects and other agents
  - Agents can "smell" other agents, but not themselves



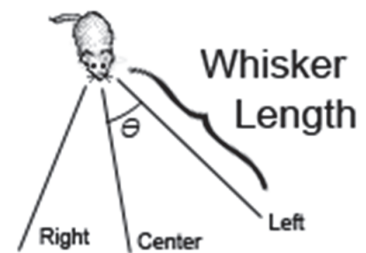
# Odorworld - agents

- **Output Commands** are essentially the motor controls of the agent. When coupling a neuron to an agent, one can choose between two styles of movement
  - **relative** movements
    - e.g. move forward, move to the right, move to the left
  - **absolute** movements
    - movements in directions that are independent of its orientation,
      - e.g. move to the north, move to the south-west
- All **movements are scaled** based on the **activity of the coupled neuron** and a fixed movement factor set in the entity dialog.
  - the larger the activation, the faster the agent
  - if a neuron is coupled with an agent and its activation becomes negative, the neuron will command the agent to do the opposite of what it would normally do (turn right → turn left)



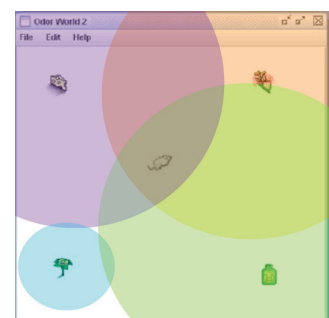
## Odorworld - agents

- **Input Commands** Each agent in an Odor World has a left whisker, a central nose, and a right whisker, each of which can sense independently
  - each of these sensors can detect parts of a broadcasted stimulus pattern, and depending on how well the signal is picked up, the neuron to which the neuron is coupled will be come active
  - although they are called whiskers, they are really just **abstract sensors**, which can respond to, e.g., olfactory stimuli
  - the location of the left and right whiskers can be set
- In the Odor World, there is a variable amount of **stimulus Dimensions**, set by default to be 8
  - all agents and objects broadcast customizable stimulus patterns during each iteration
  - an agent can pick up on these broadcasted signals, using its nose or whiskers, and send each to the coupled neuron
  - **each sensor neuron can only receive one dimension of the stimulus pattern at a time from one input sensor**



## Odorworld - objects

- **Objects** in the Odor World are stationary entities. They act as olfactory stimuli
  - which **emit chemicals** which **disperse** from the center of the object and for the most part diminish with distance
  - objects act as a **broadcasting center for a unique stimulus patterns**, whose dimension is set by default to 8
  - how the **signal disperses is based on a decay function** associated with that particular object, and a vector of stimulus values
- **Stimulus Dimensions**
  - stimulus patterns are designed to be sensed by an agent when a neuron is coupled with it
  - **a sensor can only receive one dimension of a stimulus pattern at a time**, so, each stimulus value of an object is completely independent of other stimulus values
- In each position of the Odor World **chemical patterns sum linearly**



# *Scripting - Library*

## □ Scripting

- to produce custom simulations or behaviors not possible using the Simbrain GUI, you can either create scripts
- all scripts are currently beanshell scripts (there is nothing to prevent other scripting languages, but none have been implemented yet)
- All public objects in the Simbrain code can be accessed via these scripts. The scripts by default have access to two variables:
  - workspace: the underlying model of all components in Simbrain
  - desktop: the graphical object which displays a workspace

## □ Using Simbrain as a library (Beta)

- Simbrain can be used as a library in a separate java program