6.3.1

Creating a behavior with FlexBE



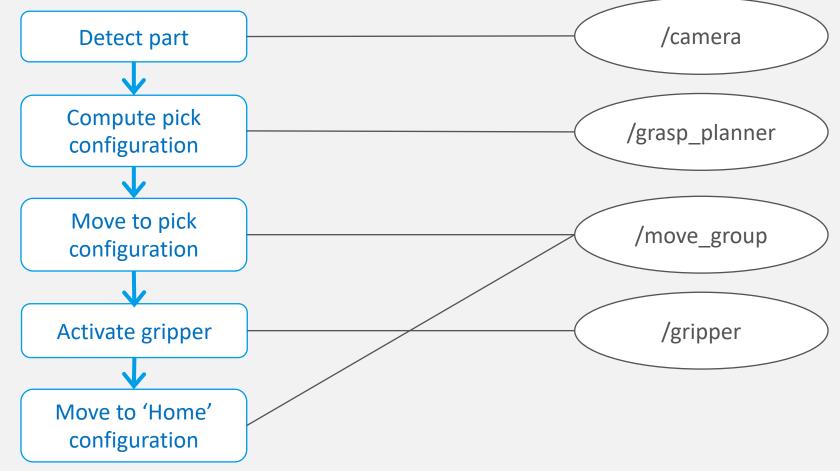
Simple behavior example

Behavior: Pick a part with Robot 1 from the conveyor belt.

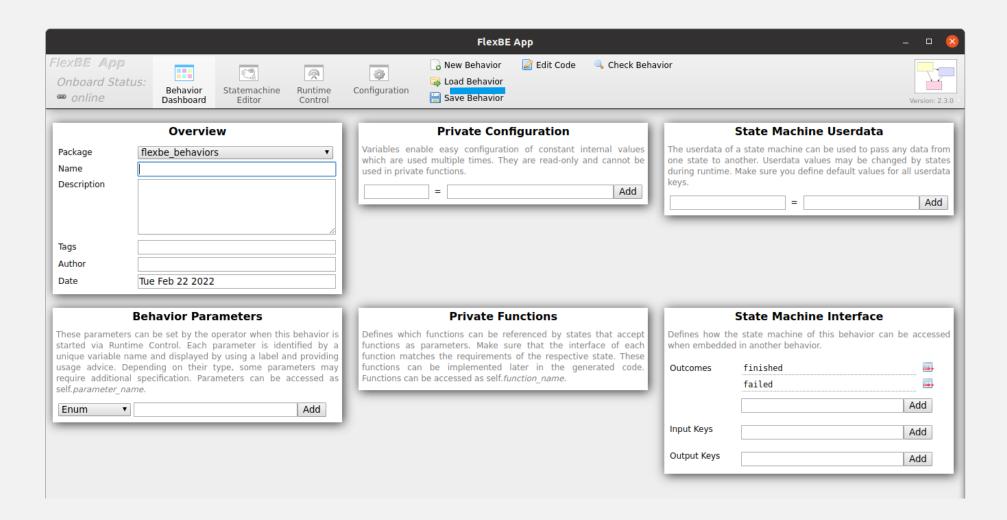
'R1Home' joint configuration defined in the SRDF file

Simple behavior example

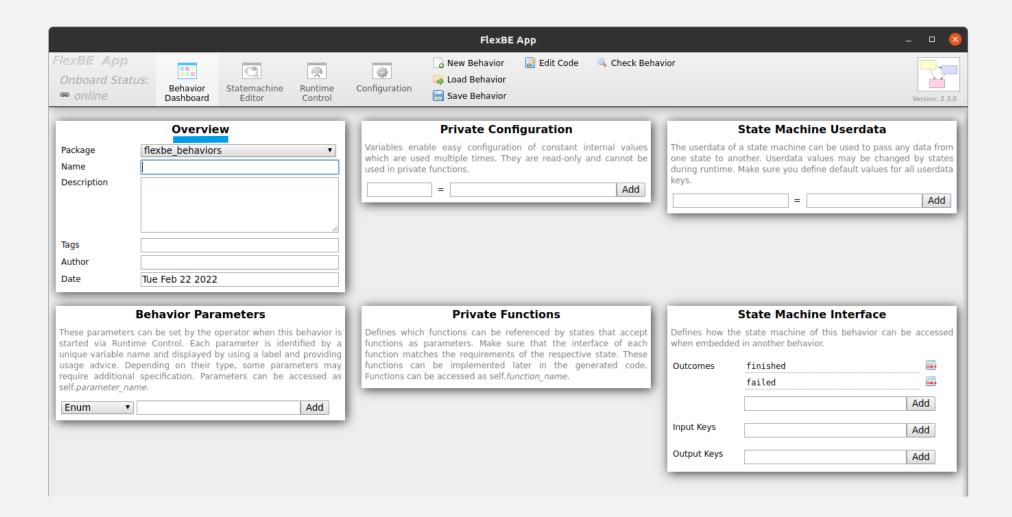
Behavior: Pick a part with Robot 1 from the conveyor belt.

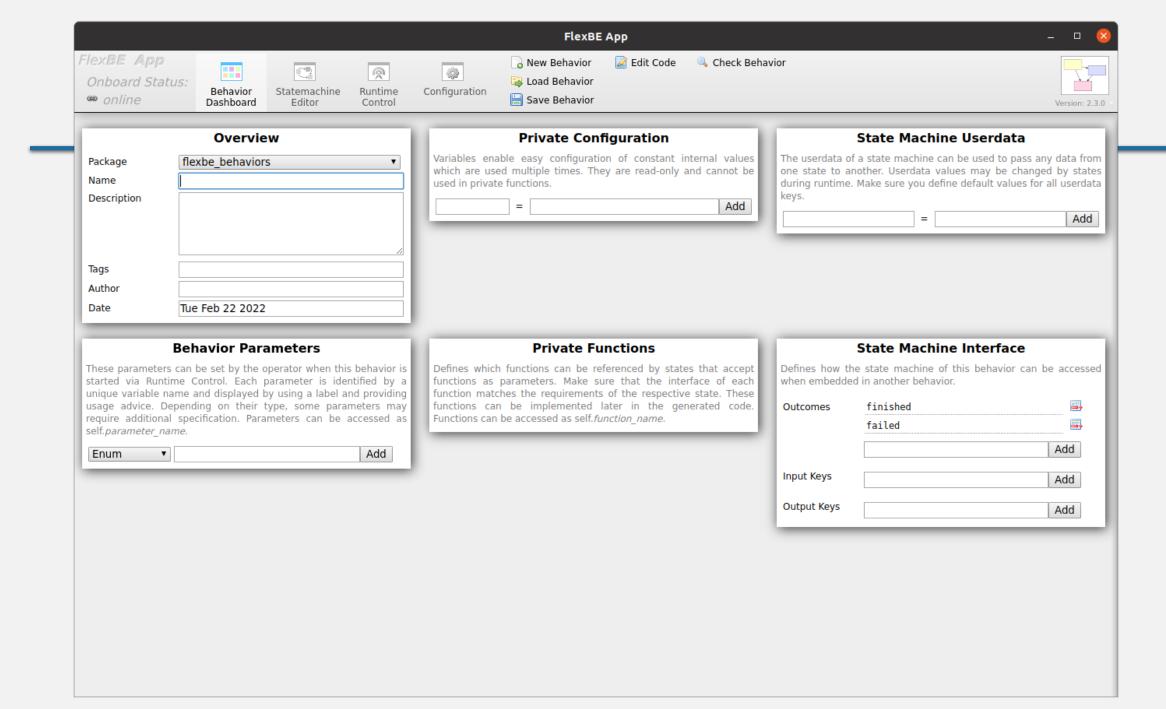


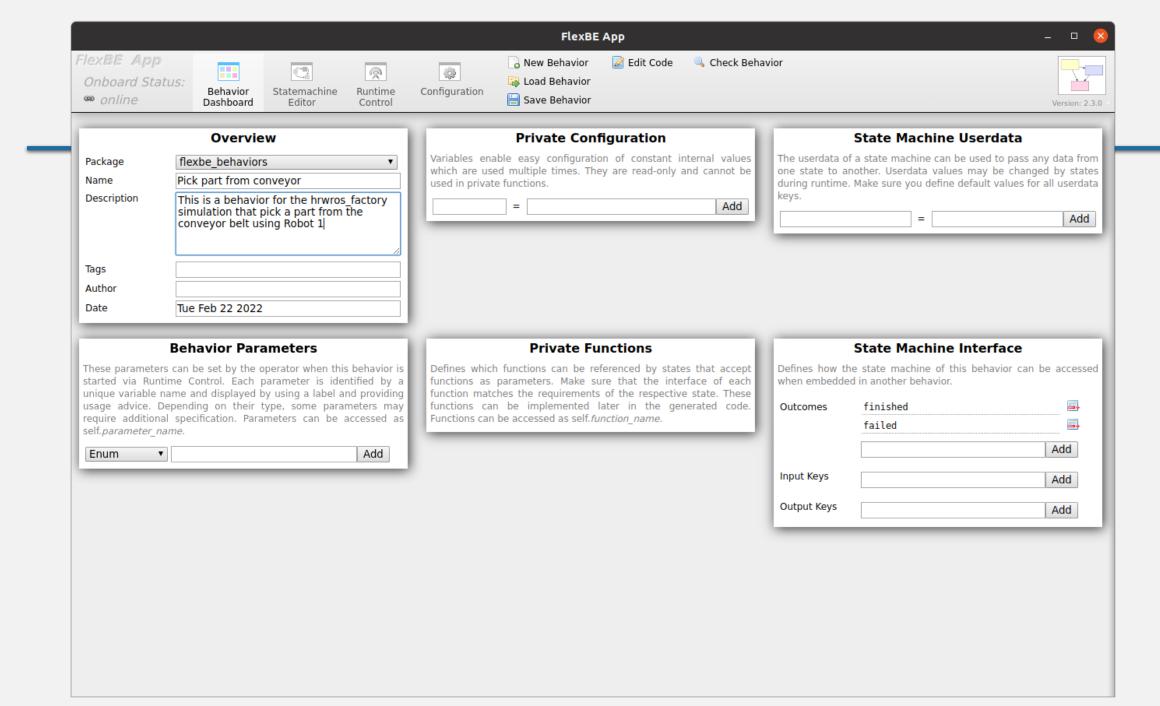
Behavior Dashboard

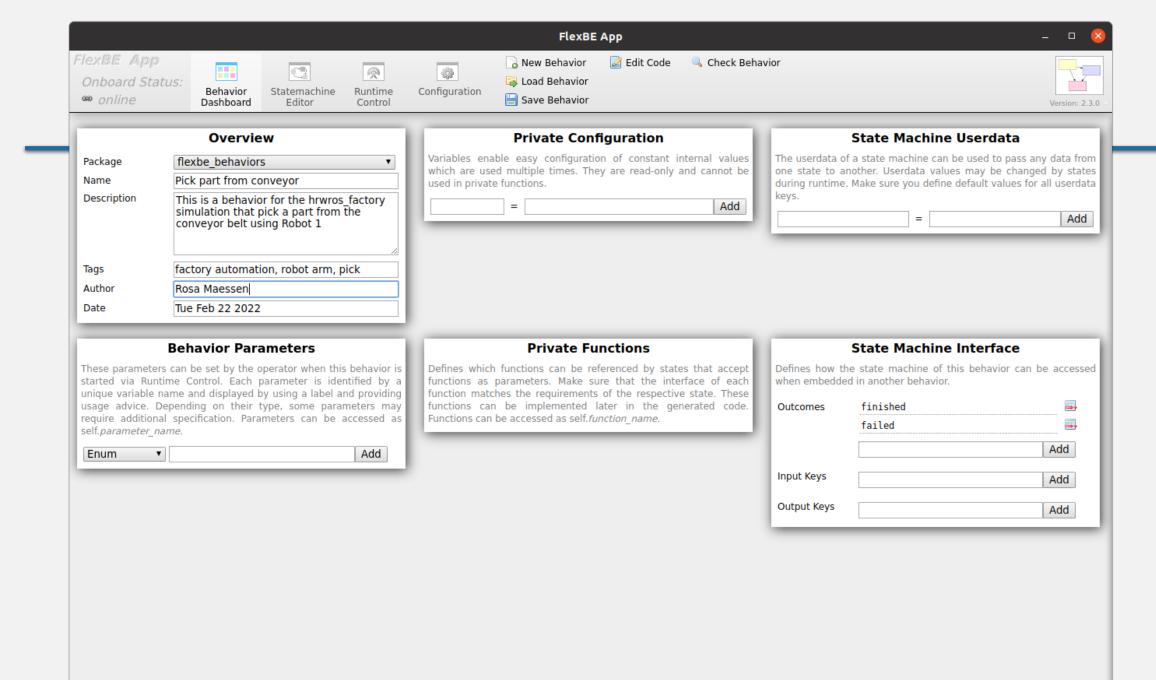


Behavior Dashboard

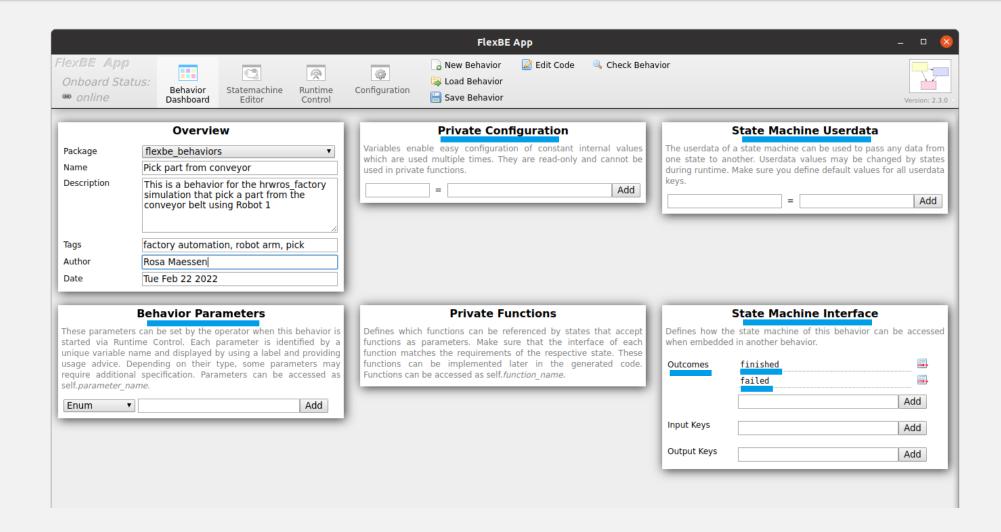




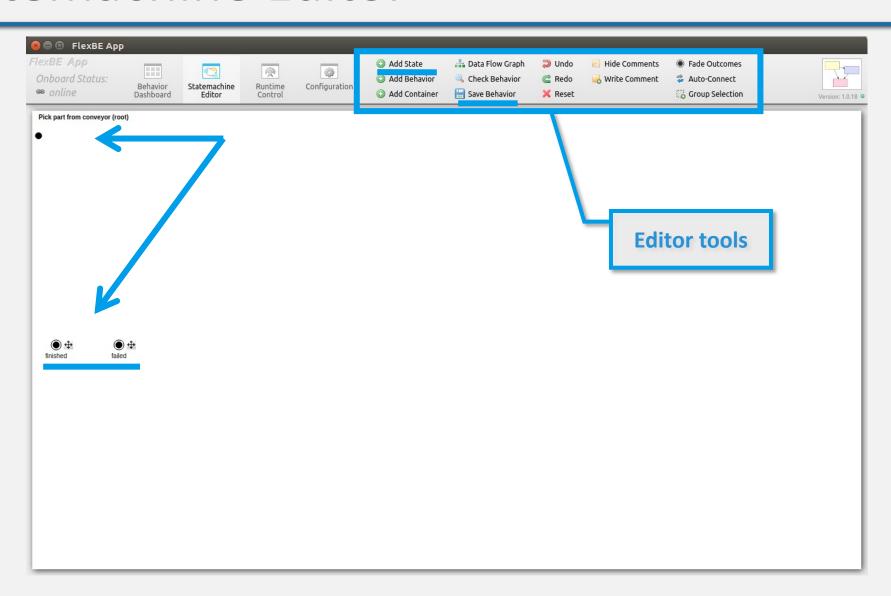




Behavior Dashboard



Statemachine Editor

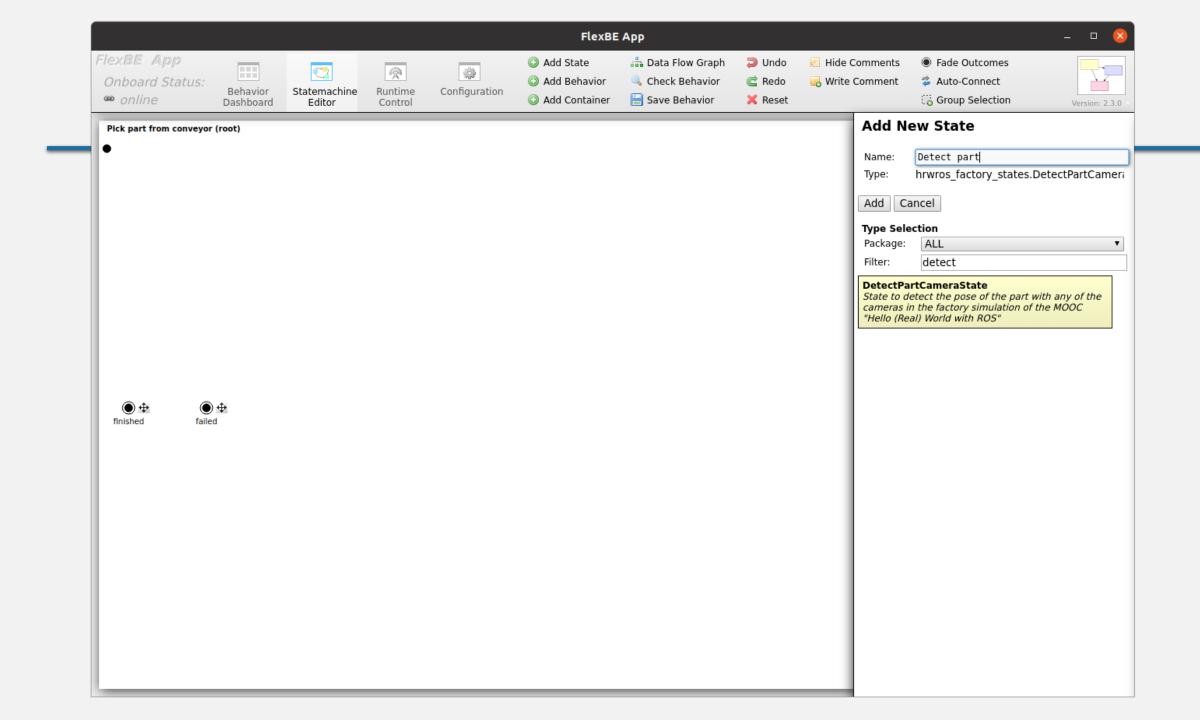


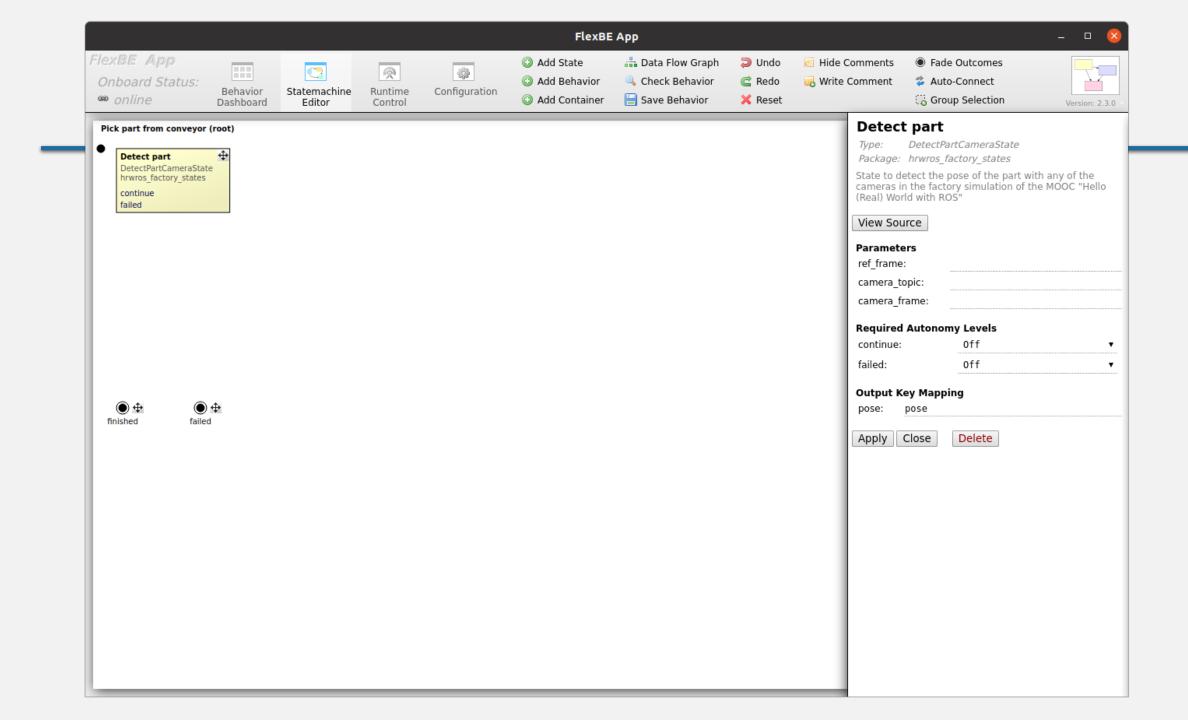


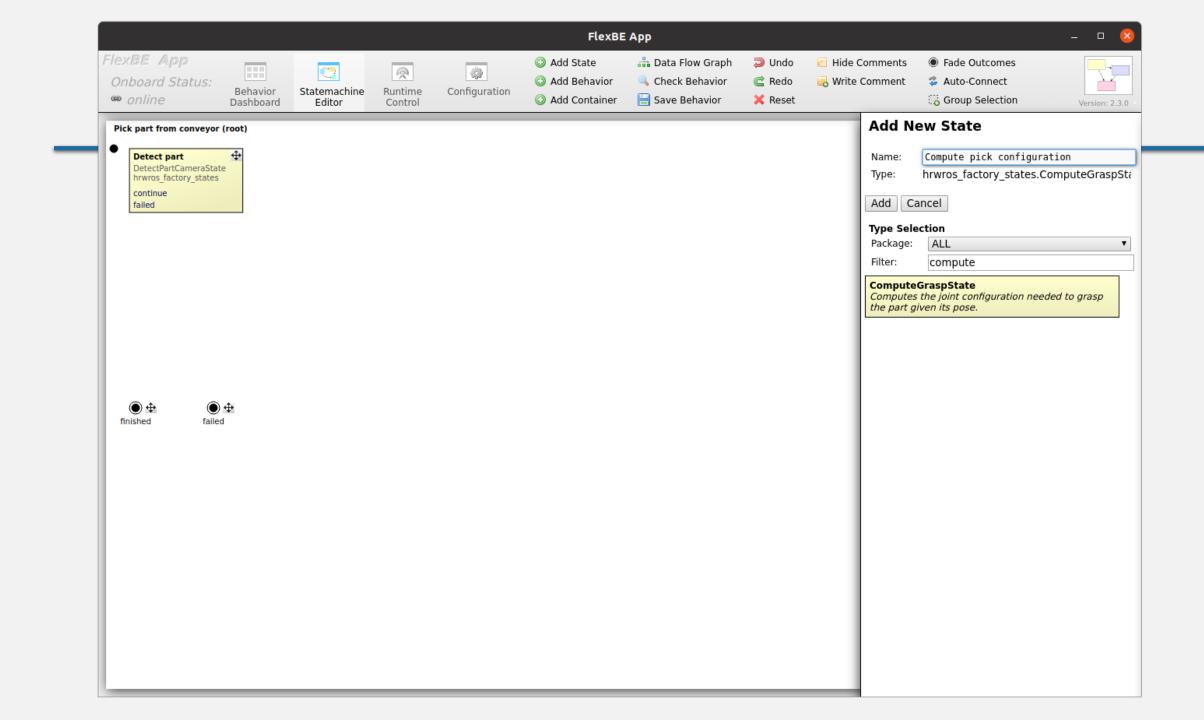


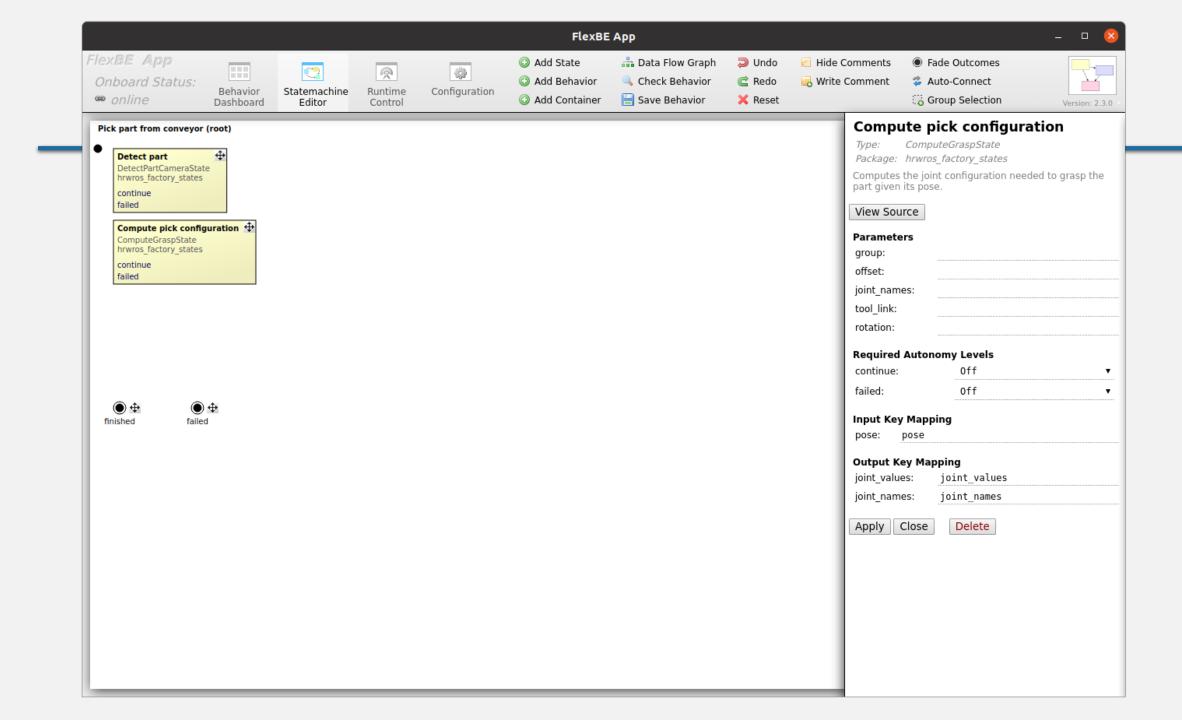


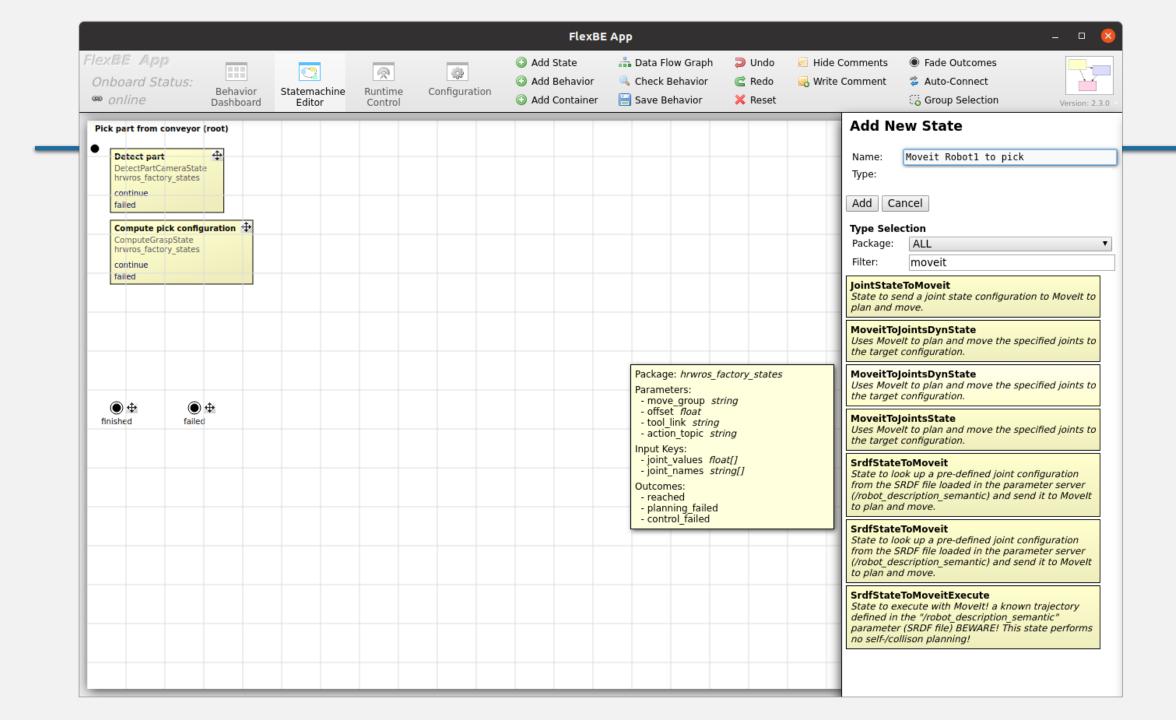


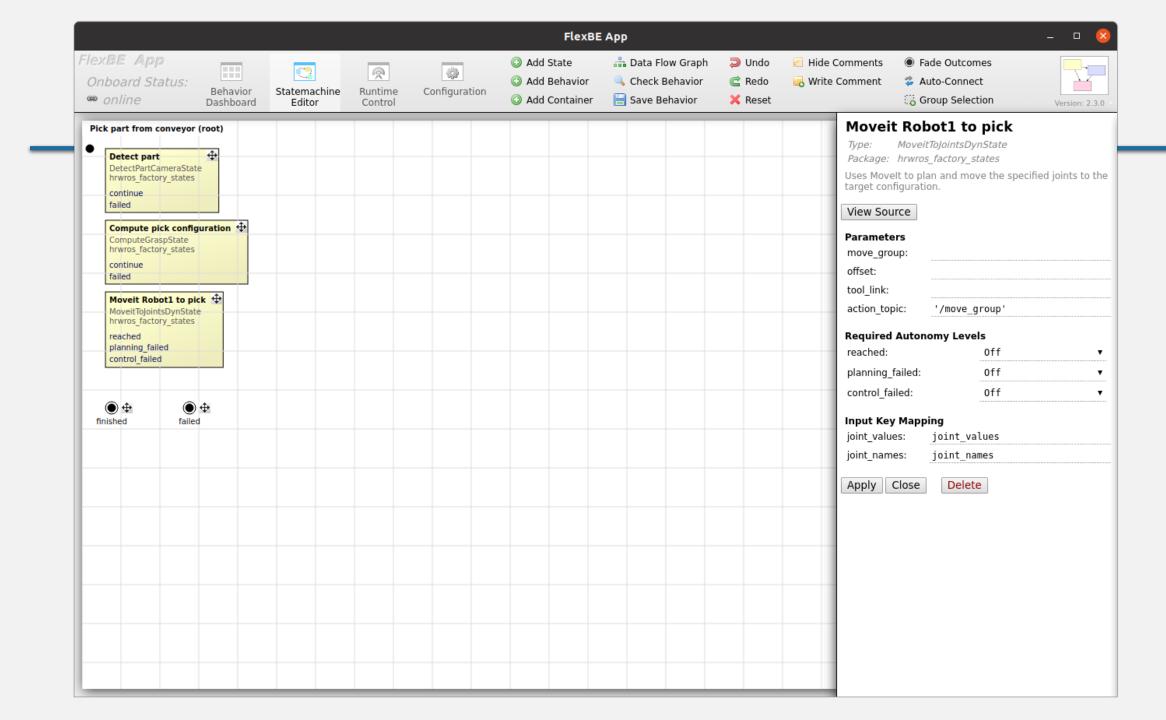


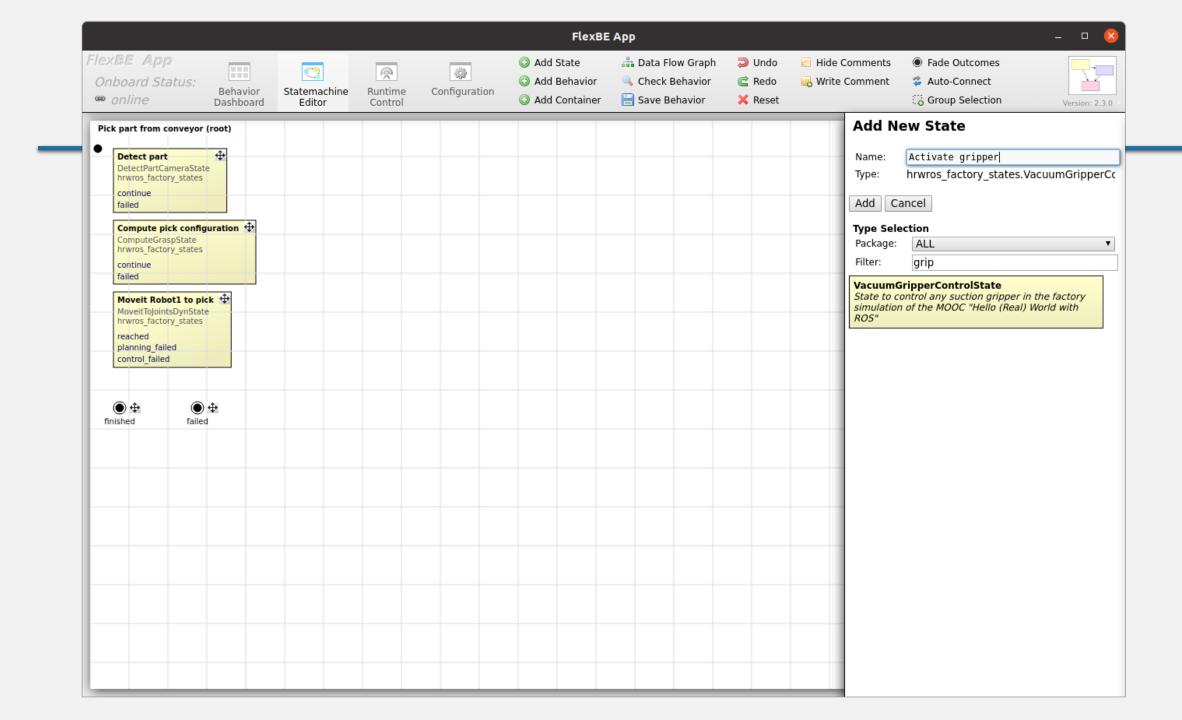


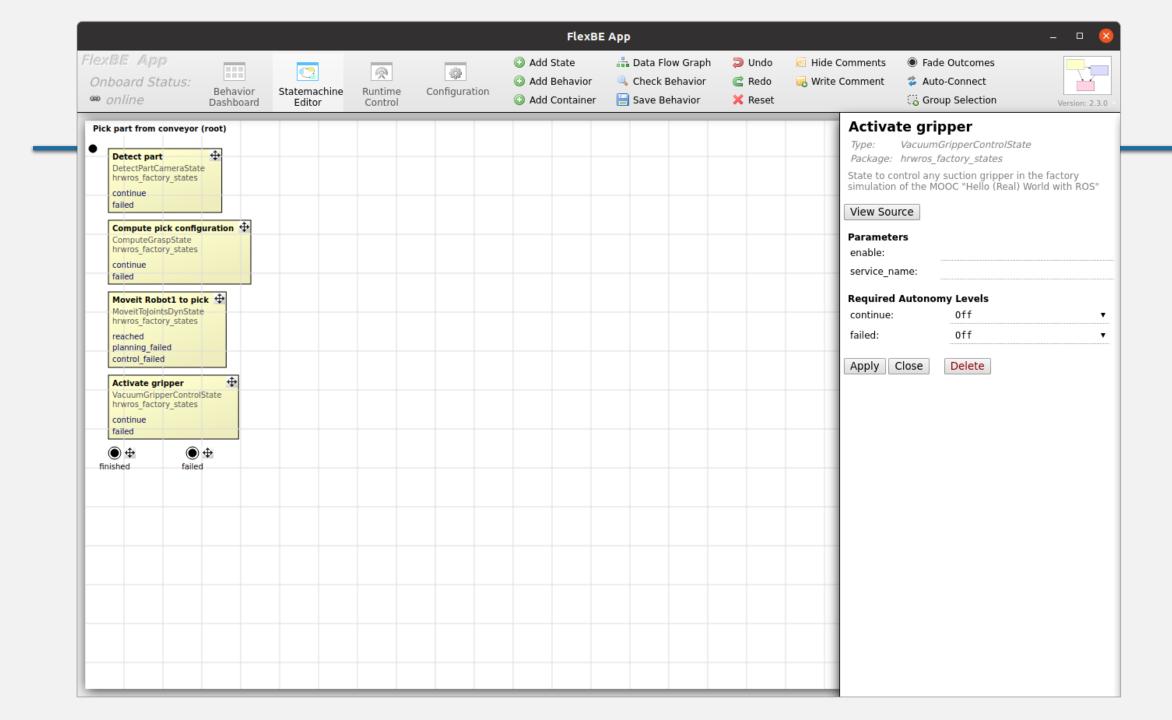




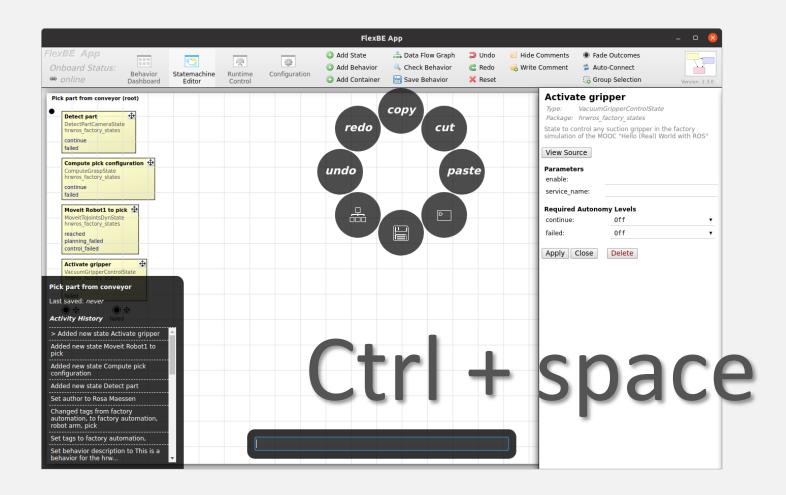


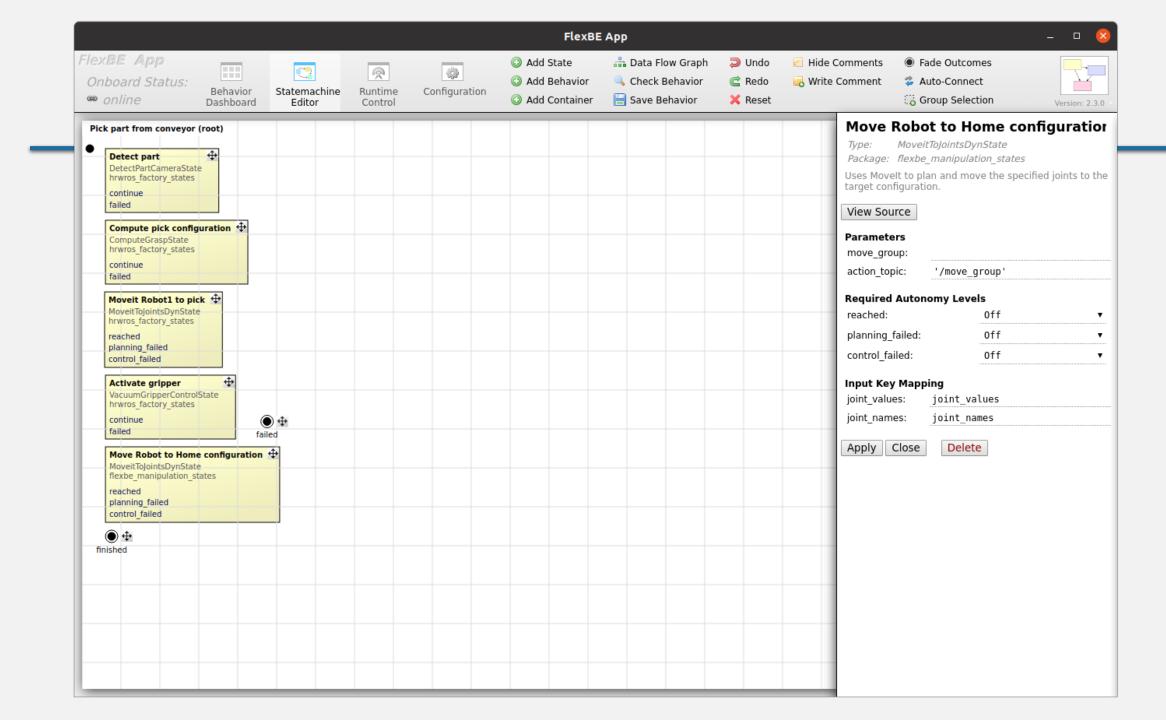






Tool Overlay





State Transitions

