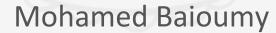
3.0

Recap - Inspection



Fundamental concepts

- ROS Nodes:Data/information processing software units
 - Python/C++, modularity in big projects.
- ROS Topics: Transport information between nodes.

ROS Inspection commands

List currently running nodes on the terminal

\$ rosnode list

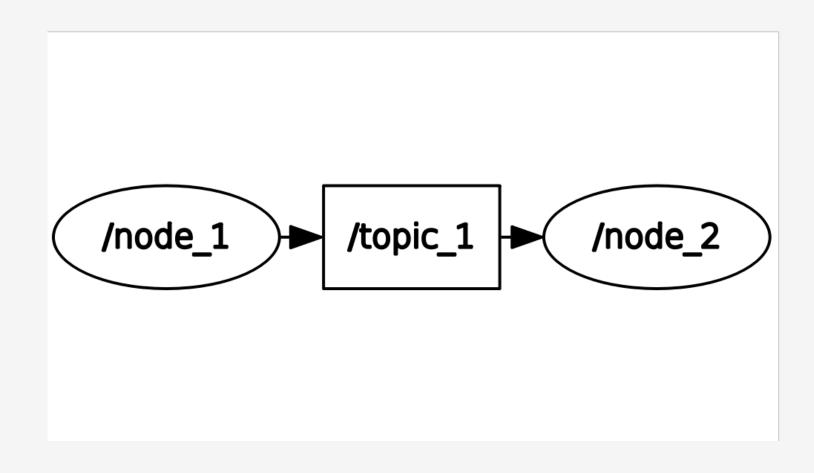
List currently running topics on the terminal

\$ rostopic list

Visual representation of the ROS "Node Graph"

\$ rosrun rqt_graph rqt_graph

rqt_graph



ROS Inspection commands (2)

Node specific information on the terminal

\$ rosnode info <node_name>

Service specific information on the terminal

\$ rosservice info <service name>

Get the value of a specific ROS Parameter

\$ rosparam get <parameter_name>