

The background features a light gray illustration of a robotic arm with a gripper, positioned over a table. On the table are several blocks: a red block with the number '1', a blue block with 'HELLO', a blue block with 'WORLD', a red block with '3', and a red block with the number '2'. A sign with the ROS logo and the text 'ROS' is visible in the bottom left. The entire scene is set against a light yellow background with a horizontal band.

6.4.3

Program a FlexBE State (2)

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After coding your state

- Build the catkin workspace.
- Source the workspace.

[SCREEN RECORDING]

[SCREEN RECORDING]

Summary

- Program simple state implementation
- FlexBE State Lifecycle