

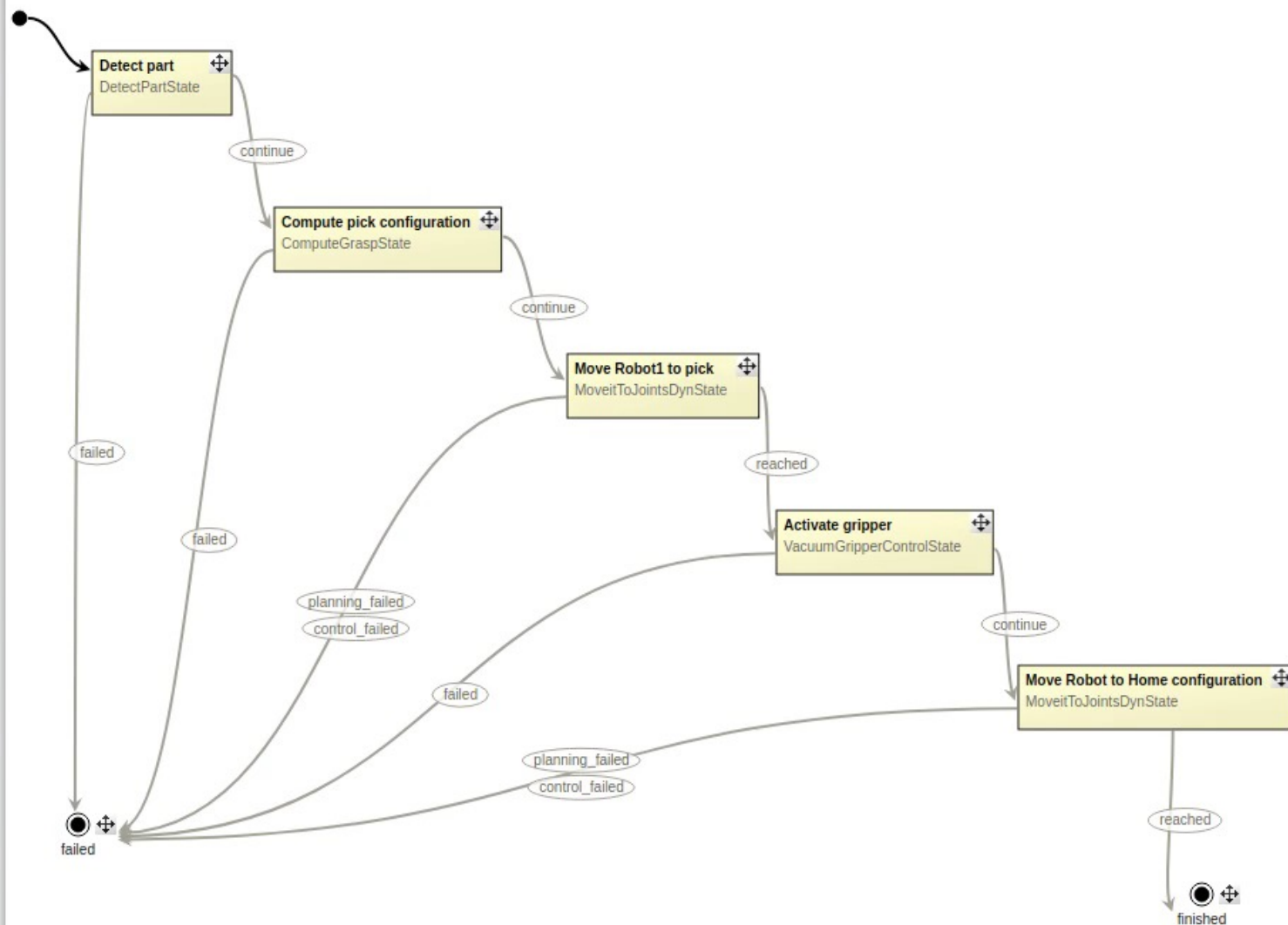
The background features a light gray illustration of a robotic arm with a gripper, positioned over a set of colorful blocks. The blocks are labeled with numbers 1, 2, and 3, and the words 'HELLO' and 'WORLD'. The entire scene is set against a light yellow background with a subtle grid pattern.

6.3.5

Executing a behavior with FlexBE

Carlos Hernandez

Pick part from conveyor (root)



Launch FlexBE for behavior execution

- Launch your **ROS application**:

```
$ roslaunch hrwros_gazebo hrwros_pick_demo.launch
```

- Launch the whole **FlexBE behavior engine**:

```
$ roslaunch flexbe_app flexbe_full.launch
```