

The background features a light gray illustration of a robotic arm with a gripper, positioned over a set of blocks. One block is labeled '1', and another is labeled '2'. A sign with the text 'HELLO WORLD' is visible. In the bottom left corner, there is a logo consisting of a grid of dots followed by the text 'ROS'.

6.5

Robot Behavior Design Wrap-up

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What we have learned

- Robot behavior design with state machines
- FlexBE
- Create a FlexBE behavior
- Program a FlexBE state