

5.2

Introduction to TF

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donne@tudelft: ~/ros/hrwros_ws

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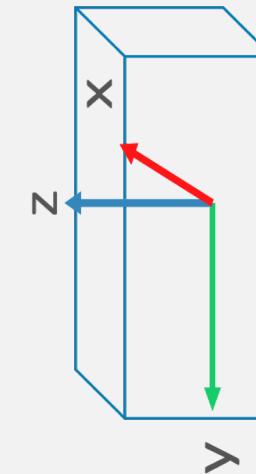
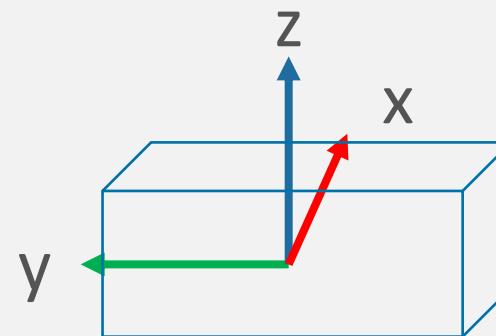
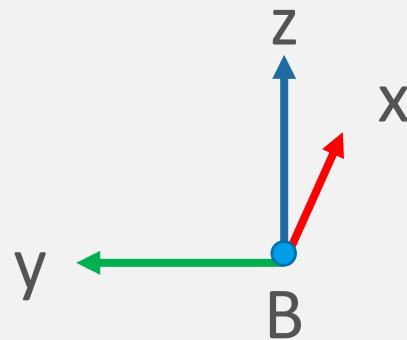
donne@tudelft: ~/ros/hrwros_code_ws/src/hrwros_code/hrwros_week5

donnie@tudelft:~/ros/hrwros_ws\$



ROS TF: main idea

- TF keeps track of spatial and temporal relationships between different objects in our working environment.
 - using reference frames in 3D.



TF Reference Frame: Right Hand Rule

