**Keshav Bimbraw**

Google CSRMP 2021B | [bimbraw.github.io](file:///C:\Users\Keshav%20Bimbraw\OneDrive\Desktop\Job\Verily\bimbraw.github.io) | (678)-436-9426 | [bimbrawkeshav@gmail.com](mailto:bimbrawkeshav@gmail.com) | [linkedin.com/in/bimbraw/](http://www.linkedin.com/in/bimbraw/) | F1 Student

******EDUCATION**

**Worcester Polytechnic Institute (WPI)**, Worcester, MA

Ph. D. student in Robotics Engineering (Medical FUSION Lab) Aug ‘20 – now

Concentration – Ultrasound Image Processing, Medical Robotics & Human Computer Interaction 4.00/4.00 GPA

**Georgia Institute of Technology**, Atlanta, GA

M. S. with Robotics Focus (Music Technology, Computer Software & Media Applications) Aug ‘17 – May ‘19

Concentration – Human Augmentation, Medical Robotics & Robotic Musicianship 3.56/4.00 GPA

**Thapar University,** Patiala, India

B. E. in Mechatronics Engineering (Research Intern - IIT Delhi, Jan – Jul ‘16) July ‘13 – June ‘17

Concentration – Robotics & Mechatronics GPA - 4.00/4.00 GPA (8.34 CGPA)

**EXPERIENCE**

**Nokia Bell Labs** New Providence, NJ

**Augmented Human Sensing Intern (Data and Devices Group, AI Research Lab)** June ‘22 – now

* Developing low latency pipelines using biological data (sEMG, etc.) to estimate limb movements for Human-Machine Interaction.

**WPI** Worcester, MA

**Research Assistant (Medical FUSION Lab)** March ‘20 – now

* Developed a deep learning and machine learning based pipeline to predict finger joint angles & hand configurations from forearm ultrasound images. Achieved an error of 7.35⁰ for finger joint angle prediction (IEEE ICRA ’22). [ArXiv preprint](https://arxiv.org/abs/2109.11093). [Video](https://www.youtube.com/watch?v=YdhpU829e-M).
* Developed a novel augmented reality based lung ultrasound scanning guidance system (MICCAI ASMUS ‘20). [Paper](https://link.springer.com/chapter/10.1007/978-3-030-60334-2_11). [Video](https://vimeo.com/463333665).
* Helped develop a real-time ultrasound data acquisition software framework for a tele-operative low-cost lung ultrasound robot. [Paper](https://pubmed.ncbi.nlm.nih.gov/34532570/).
* Mentoring and assisting undergraduate teams for their major qualifying projects and independent research studies.

**Agile Resources Inc.** Peachtree City, GA

**Audio DSP Engineer (Panasonic Automotive Systems of America)**  Oct ‘19 – March ‘20

* Worked on Qualcomm’s Hexagon SDK for audio applications in Eclipse on Android framework development.
* Utilized Qualcomm tools to evaluate audio modules such as Bass Mid Treble, Parametric Equalizer, Fade & Balance etc.

**Bose Corporation** Stow, MA

**Active Noise Control Engineering Intern (Automotive Systems Division)**  May ‘19 – Oct ‘19

* Worked on sound synthesis for electric vehicles and implementing processor optimized signal processing algorithms.
* Developed a physical car sound simulation system using Logitech pedals to evaluate models and reduce testing time.

**Georgia Tech** Atlanta, GA

**Research Assistant (Robotic Musicianship Lab)**  Aug ‘17 – May ‘19

* Lead the [Skywalker project](https://gtcmt.gatech.edu/skywalker) from Aug ‘18 – May ‘19. My robot and code were featured in the first episode of The Age of A.I. [Link](https://youtu.be/UwsrzCVZAb8?t=1079).
* Investigated a combination of Ultrasound & EMG data using supervised learning algorithms to enhance assistive robot control. [Link](https://drive.google.com/file/d/1PYHPMrOLP6-12o97rCuxAX5ZVvhJofBY/view?usp=sharing).
* Assisted a team to improve the expressivity of Shimon (a marimba playing robot) by replacing its actuators & control scheme. [Link](https://smartech.gatech.edu/handle/1853/60602).
* Translated Piano playing to robots using a single DOF system and designed a robotic hand with one DOF per finger. [Link](https://drive.google.com/file/d/1bLGMaNiJcKgj9wzIZIy0YlRz8Kj3OJXE/view?usp=sharing).
* Developed an ultrasound in the loop tendon based wearable exoskeleton for upper extremity rehabilitation of stroke survivors. [Link](https://drive.google.com/file/d/10ZK2K1fI90I0AVr5jjTlthfDECNXcPIK/view?usp=sharing).
* Computer-Aided Design (CAD), Fusion 360, 3D printing and Mechatronics Instructor for Project Studio Course. [Link](https://vimeo.com/444132536).

**IIT Delhi** New Delhi, India

**Research Intern (Autonomous Robotics Lab)** Jan ‘16 – Aug ‘16

* Programmed two KUKA KR-5 robotic arms to collaboratively play a guitar. [Link](https://vimeo.com/174093155).
* Developed a Control Module for RoboAnalyzer using C# to simulate control of mass spring damper & single-link robotic arm systems.
* Improved performance of a 6 DOF motion platform at Simulator Development Division, Secunderabad, India. [Link](https://ieeexplore.ieee.org/abstract/document/7931899).
* Helped with the development of a Teach pendant to control virtual robots in RoboAnalyzer software. [Link](https://ieeexplore.ieee.org/abstract/document/7931881).
* Modified the mechanical and electrical design of Tulsi Bead making device under the rural development initiative of IIT Delhi.

**SKILLS**

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**Software Skills** Python, MATLAB, TensorFlow, ROS, Linux, NumPy, matplotlib, OpenCV, C++

**3D Design/3D printing** SolidWorks, Autodesk Inventor, Autodesk Fusion 360, Tinkercad, PreForm

**Electrical/Electronic skills** Arduino, Raspberry Pi, Motors, Actuators, Hardware & software interfacing

**ACADEMIC PROJECTS**

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**Comparing low & high-dimensional forearm ultrasound based hand state classification (WPI, Machine Learning)**  Spring ‘22

* Investigated the feasibility of using image compression techniques for extracting latent structure of ultrasound images. [Link](https://drive.google.com/file/d/17gE6GYWe8PWJ5g-VtjKLZz2YO8X6IP-3/view?usp=sharing).
* Designed a real-time ML pipeline for training and testing models for hand motion classification based on forearm ultrasound.

**Navigation of a Raspberry-Pi based Robot using camera and Lidar data (Georgia Tech, Intro. To Robotics Research)** Fall ‘18

* Used camera data to [find center of a ball](https://drive.google.com/file/d/1MWnO-YQMQrfbNgStuxxBOtb2QV0ZW2Ag/view?usp=sharing) and track it by actuating Dynamixel motors attached to a mobile robot. Used Lidar data to avoid obstacles and maintaining a specific distance from them while [moving towards a goal](https://drive.google.com/file/d/1i_43mzUJ2jsxBCk5GGfe513W0Ntd9T-z/view?usp=sharing) (waypoint classification using SVM).

**Design of an ultrasound guided vein cannulation robot (Georgia Tech, Medical Robotics)** Spring ‘18

* Oversaw a 5-person multi-discipline team to develop a medical robot that can hold an ultrasound probe to detect jugular vein. [Link](https://drive.google.com/file/d/1QYiNKyen9jId7NcDo363wpNWQYtSj841/view?usp=sharing).
* Designed and programmed a PRRRP configuration robot for its end effector to reach specific positions in the robot workspace.

**LEADERSHIP**

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**Leadership Experience** at WPI Fall ’20 – now

* Senator and representative of the Robotics Engineering Department for the Graduate Student Government at WPI.
* Member of the Rho Beta Epsilon Robotics Engineering society at WPI. Hosted a C++ workshop for beginners at WPI.
* Graduate Student Officer at The Alliance: the social, educational, & professional support network of LGBTQIAP+ students at WPI.

**Vertically Integrated Projects (VIP) Instructor** at Robotic Musicianship Lab at Georgia Tech Fall ‘17 – Spring ‘19

* Lead teams of undergraduates to involve them in robotics and mechatronics research.
* Mentored students to work on real life robotics projects & improving their project presentation skills.

**HONORS & AWARDS**

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| |  | | --- | | • Selected for 2021B cohort of Google Research’s CSRMP program. First person at WPI to have ever been selected. | | September ‘21 |
| • Awarded PhD positions at WPI & Georgia Tech. Accepted the WPI offer. (Tuition support & $31824 yearly award) | March ‘20 |
| • Selected to be Diversity and Inclusion Fellow by Georgia Tech Institute Diversity ($1000 award) | February ‘19 |
| • Selected as NSF-NRT ARMS (Accessibility, Rehabilitation, & Movement Science) Trainee ($1500 award) | August ‘18 |
| • Scholarship to pursue masters at Georgia Tech (Tuition support & $14100 yearly award) | August ‘17 |
| • Awarded merit scholarships and grants totaling INR 336,000 at Thapar University. | June ‘17 |

**PUBLICATIONS**

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1. **Bimbraw, K.**, Nycz, C. J., Schueler, M., Zhang, Z., & Zhang, H. K. (2021). Prediction of Metacarpophalangeal joint angles and Classification of Hand configurations based on Ultrasound Imaging of the Forearm. In: *arXiv preprint:2109.11093*. [Link](https://arxiv.org/abs/2109.11093). [Video](https://youtu.be/YdhpU829e-M).
2. Tsumura, R., Hardin, J.W., **Bimbraw, K.**, Grossestreuer, A.V., Odusanya, O.S., Zheng, Y., Hill, J.C., Hoffmann, B., Soboyejo, W. and Zhang, H.K., 2021. Tele-Operative Low-Cost Robotic Lung Ultrasound Scanning Platform for Triage of COVID-19 Patients. *IEEE Robotics and Automation Letters, 6*(3), pp.4664-4671. [Paper Link](https://pubmed.ncbi.nlm.nih.gov/34532570/). [Video](https://www.youtube.com/watch?v=_Zr0HbDOzEc).
3. **Bimbraw, K.**, Ma, X., Zhang, Z., Zhang, H. (2020). Augmented Reality-Based Lung Ultrasound Scanning Guidance. In: *Medical Ultrasound, and Preterm, Perinatal and Paediatric Image Analysis. ASMUS 2020, PIPPI 2020*. Lecture Notes in Computer Science, vol 12437. Springer, Cham. doi.org/10.1007/978-3-030-60334-2\_11. [Paper Link](https://link.springer.com/chapter/10.1007/978-3-030-60334-2_11). [Video](https://vimeo.com/463333665).
4. **Bimbraw, K.**, Fox, E., Weinberg, G. and Hammond, F. L. (2020). Towards Sonomyography-Based Real-Time Control of Powered Prosthesis Grasp Synergies. In: *2020 42nd Annual International Conference of the IEEE Engineering in Medicine & Biology Society (EMBC)*, Montreal, QC, Canada, 2020, pp. 4753-4757, doi: 10.1109/EMBC44109.2020.9176483. [Paper Link](https://ieeexplore.ieee.org/document/9176483). [Video](https://vimeo.com/444131445).
5. Mehta, I., **Bimbraw, K.**, Chittawadigi, R. G., & Saha, S. K. (2016). A teach pendant to control virtual robots in Roboanalyzer. In: *2016 Int. Conference on Robotics and Automation for Humanitarian Applications (RAHA)* (pp. 1-6). IEEE. [Paper Link](https://ieeexplore.ieee.org/abstract/document/7931881).
6. **Bimbraw, K.**, Mehta, I., Venkatesan, V., Joshi, U., Sabherwal, G. S., & Saha, S. K. (2016). Performance improvements of a 6-DOF motion platform. In: *2016 Int. Conference on Robotics & Automation for Humanitarian App. (RAHA)* (pp. 1-5). IEEE. [Paper Link](https://ieeexplore.ieee.org/document/7931899).
7. Kaur, M., Singh, G., **Bimbraw, K.**, & Uniyal, P. (2015). Study of phase transformation and microstructure of alcohol washed titania nanoparticles for thermal stability. In: *AIP Conference Proceedings* (Vol. 1675, No. 1, p. 030049). AIP Publishing. [Paper Link](https://aip.scitation.org/doi/10.1063/1.4929265).
8. **Bimbraw, K.** (2015). Autonomous cars: Past, present, and future. In: *2015 12th International Conference on Informatics in* *Control, Automation and Robotics (ICINCO)* (Vol. 1, pp. 191-198). IEEE. [Paper Link](https://ieeexplore.ieee.org/document/7350466).