

Problem Sheet 2

Numerical Methods for CSE

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1. Lyapunov Equation

1.a. Linear Mapping

To prove (for $\mathbf{U}, \mathbf{V} \in \mathbb{R}^{n,n}$, $\alpha \in \mathbb{R}$ and a fixed \mathbf{A}):

- $L(\mathbf{U} + \mathbf{V}) = L(\mathbf{U}) + L(\mathbf{V})$
- $L(\alpha \cdot \mathbf{U}) = \alpha \cdot L(\mathbf{U})$

The first property:

$$\begin{aligned} L(\mathbf{U} + \mathbf{V}) &= \mathbf{A}(\mathbf{U} + \mathbf{V}) + (\mathbf{U} + \mathbf{V})\mathbf{A}^T \\ &= \mathbf{A}\mathbf{U} + \mathbf{A}\mathbf{V} + \mathbf{U}\mathbf{A}^T + \mathbf{V}\mathbf{A}^T \\ &= \mathbf{A}\mathbf{U} + \mathbf{U}\mathbf{A}^T + \mathbf{A}\mathbf{V} + \mathbf{V}\mathbf{A}^T \\ &= L(\mathbf{U}) + L(\mathbf{V}) \end{aligned}$$

And the second property:

$$\begin{aligned} L(\alpha \cdot \mathbf{U}) &= \mathbf{A}(\alpha \cdot \mathbf{U}) + (\alpha \cdot \mathbf{U})\mathbf{A}^T \\ &= \alpha \cdot (\mathbf{A}\mathbf{U}) + \alpha \cdot (\mathbf{U}\mathbf{A}^T) \\ &= \alpha \cdot (L(\mathbf{U})) \end{aligned}$$

1.c. Linear Equations

We have

$$\begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix} \mathbf{X} + \mathbf{X} \begin{bmatrix} 2 & 1 \\ -1 & 3 \end{bmatrix} = \mathbf{I}$$

This gives us the following equations:

$$\begin{aligned} 1 &= 2\mathbf{X}_{11} + \mathbf{X}_{21} + 2\mathbf{X}_{11} + \mathbf{X}_{11} = 4\mathbf{X}_{11} + \mathbf{X}_{21} + \mathbf{X}_{12} \\ 0 &= -\mathbf{X}_{11} + 5\mathbf{X}_{21} + \mathbf{X}_{22} \\ 0 &= -\mathbf{X}_{11} + 5\mathbf{X}_{12} + \mathbf{X}_{22} \\ 1 &= -\mathbf{X}_{21} - \mathbf{X}_{12} + 6\mathbf{X}_{21} \end{aligned}$$