$$T = 8$$
, $a_1 = j$ $a_5 = a_{-5} = 2$
 $a_1 = j$ $a_{-1} = -j$ $a_5 = 2$ $a_{-5} = 2$

$$x(t) = a_{1}e^{-j\omega_{1}t} + a_{2}e^{j\omega_{1}t} + a_{3}e^{-js\omega_{1}t} + 2e^{-js\omega_{1}t}$$

$$= j \cdot e^{-j\omega_{1}t} + a_{3} \cdot 2e^{-js\omega_{1}t} + 2e^{-js\omega_{1}t}$$

$$= 2j^{2} \left[\frac{e^{j\omega_{1}t} - e^{-j\omega_{1}t}}{2j} \right] + 4 \left[\frac{e^{js\omega_{1}t} + e^{-js\omega_{1}t}}{2} \right]$$

$$= 2 \sin(\omega_{1}t) + 4 \cos(5\omega_{1}t)$$

$$= 2 \cos(\omega_{1}t - \frac{\pi}{2}t) + 4 \cos(5\omega_{1}t)$$

$$x(t) = 2 \cos(\frac{\pi}{4}t - \frac{\pi}{2}t) + 4 \cos(\frac{5\pi}{4}t)$$

$$\begin{array}{c|c} \chi(t) \\ \hline -2 & -1 \\ \hline -1 & 0 \\ \hline \end{array}$$

$$T = 2$$
 $\omega_0 = \frac{2x}{T} = \frac{3x}{3} = x$

$$x(t) = t$$

$$\alpha(f) = f$$

$$a_0 = \frac{1}{T} \int_{T} x(t) dt = \frac{1}{2} \int_{T}^{T} t dt = \frac{1}{2} \frac{|t^2|}{2} - t = 0$$
 $\therefore a_0 = 0$

$$a_k = \frac{1}{T} \int_{T} \chi(t) e^{-jt\omega d} dt = \frac{1}{2} \int_{T}^{T} t e^{-jk\omega d} dt$$

$$\alpha_{k} = \frac{1}{2} \left\{ \left| \frac{1 \cdot e^{-jk\omega_{ck}}}{-jk\omega_{c}} \right|^{1} + \frac{1}{jk\omega_{c}} \int_{-jk\omega_{ck}}^{-jk\omega_{ck}} dt \right\}$$

$$=\frac{1}{2}\left\{\frac{e^{-j\omega_{ck}}+e^{j\omega_{ck}}}{-jk\omega_{c}}*-\frac{1}{(jk\omega_{c})^{2}}\left|e^{-jk\omega_{ck}}\right|^{1}\right\}$$

$$= \frac{1}{2} \frac{1}{|k\omega|} \left[\frac{e^{-j\omega \cdot k} + e^{j\omega \cdot k}}{2} \right] + \frac{1}{2k^2\omega^2} \left[e^{-j\omega \cdot k} - e^{j\omega \cdot k} \right]$$

$$a_{k} = \int \frac{\cos(\omega \cdot k)}{(|\omega \cdot \omega|)} = \frac{2 \int e^{j\omega \cdot k} e^{-j\omega \cdot k}}{|\omega \cdot \omega|}$$

$$a_k = \hat{J} \cdot \frac{\cos(\omega_{ok})}{(k\omega_{o})} - \frac{\hat{J}}{k^2\omega_{o}^2} \cdot \sin(\omega_{ok})$$

$$A_{s} = \frac{1}{k \cos s} = \frac{1}{k \kappa}$$

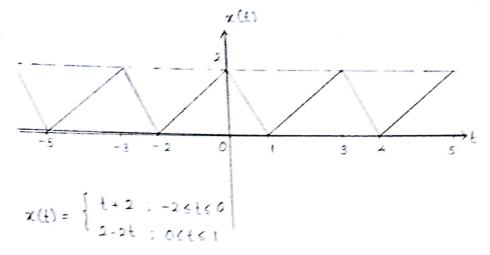
$$A_{s} = \frac{1}{k \kappa}$$

$$A_$$

$$-\frac{\left[e^{-jk\omega_{e}} - e^{-jk\omega_{e}}\right]}{jk\omega_{e}} - \frac{2}{jk\omega_{e}} \left[e^{-jk\omega_{e}} - e^{-jk\omega_{e}}\right] + \frac{\left[2e^{-j2\omega_{e}} - e^{-jk\omega_{e}}\right]}{jk\omega_{e}} + \frac{\left[e^{-j2k\omega_{e}} - e^{-jk\omega_{e}}\right]}{jk\omega_{e}}$$

$$+ \frac{\left[e^{-j2k\omega_{e}} - e^{-jk\omega_{e}}\right]}{(jk\omega_{e})^{2}}$$

$$+ \frac{1}{6} \left[\frac{1}{jk\omega_{e}} - \frac{1}{(jk\omega_{e})^{2}} - \frac{2}{jk\omega_{e}} + \frac{1}{jk\omega_{e}} + \frac$$



$$\omega_0 = \frac{2x}{T} = \frac{2x}{3}$$

$$0. = \frac{1}{7} \int_{7} x(t) dt = \frac{1}{3} \left\{ \int_{-2}^{0} (t+2) dt + 2 \int_{0}^{1} (t-1) dt \right\}$$

$$= \frac{1}{3} \left\{ \frac{|t^{2}|_{-2}^{0}}{2} + 2|t|_{-2}^{0} + 2|t|_{0}^{1} - 2|t^{2}|_{0}^{1} \right\}$$

$$= \frac{1}{3} \left[-2 + 3(2) - 1 \right]$$

$$0. = 1$$

$$\alpha_{k} = \frac{1}{T} \int_{T} x(t) e^{-jk\omega_{0}t} dt = \frac{1}{3} \left\{ \int_{-1}^{0} (t+2) e^{-jk\omega_{0}t} dt + \int_{0}^{0} (t+2) e^{-jk\omega_{0}t} dt \right\}$$

$$= \frac{1}{3} \left\{ \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right|_{-2}^{0} - \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right|_{-2}^{0} + 2 \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right\}$$

$$+ \frac{2}{3} \left\{ \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right|_{0}^{0} + \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right\}$$

$$= \frac{1}{3} \left\{ - \frac{2}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right] + 2 \left[\frac{1 - e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right]$$

$$+ \frac{2}{3} \left\{ \frac{1 - e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} \right] + \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}} + \frac{1}{T} \frac{e^{-jk\omega_{0}t}}{e^{-jk\omega_{0}t}}$$

$$= \frac{1}{3} \left[-\frac{2}{T} \frac{1}{T} \frac{1}{$$

$$\alpha_{k} = \frac{1}{k^{2}\omega_{e}^{2}} - \frac{\left[\cos\left(9k\omega_{e}\right) + j\sin\left(9k\omega_{e}\right)\right]}{3k^{2}\omega_{e}^{2}} - 2\left[\cos\left(k\omega_{e}\right) - j\sin\left(k\omega_{e}\right)\right]}{3k^{2}\omega_{e}^{2}}$$

$$3\left[\cos\left(9k\omega_{e}\right) + j\sin\left(9k\omega_{e}\right) + 2\cos\left(k\omega_{e}\right) - j\sin\left(k\omega_{e}\right)\right]$$

$$G_k = \frac{9}{4\pi^2 k^2} - 3\left[\cos(2k\omega_c) + j\sin(2k\omega_c) + 2\cos(k\omega_c) - j\sin(k\omega_c)\right]$$

$$5 + 4\pi^2 k^2$$

$$= x(1) = \sum_{k=-\infty}^{\infty} a_k e^{+j \cdot \frac{2\pi k}{3}t}$$
where $a_k = \begin{cases} 1 & \text{; } k \neq 0 \\ \frac{3}{4\pi^2 k^2} \left[3 - \cos(9k\omega_0) - j \sin(9k\omega_0) - 2\cos(9k\omega_0) + j \sin(9k\omega_0) \right] \\ + j \sin(9k\omega_0) \right] ; k \neq 0$

$$\Sigma) \qquad T = 2$$

$$\omega_{c} = \frac{9x}{T} = \frac{9x}{2} = x$$

$$T = 2$$

$$\omega_{i} = \frac{2x}{T} = \frac{2x}{2} = x$$

$$x(t) = \delta(t) - 2 \delta(t-1) : -1 < 0 < t < 2$$

$$a_{0} = \frac{1}{T} \int x(t) dt = \frac{1}{2} \int \left[\delta(t) - 2 \delta(t-1) \right] dt$$

$$= \frac{1}{2} \left\{ \int \delta(t) dt - 2 \int \delta(t-1) dt \right\}$$

$$= \frac{1}{2} \left\{ \int \delta(t) dt - 2 \int \delta(t-1) dt \right\}$$

$$= \frac{1}{2} \left(1 - 2 \right)$$

$$a_{0} = -\frac{1}{2}$$

$$a_{k} = \frac{1}{T} \int_{0}^{T} x(t) e^{-jk\omega t} dt = \frac{1}{T} \int_{0}^{T} [\delta(t) - 2\delta(t-1)] e^{-jk\omega t} dt$$

$$a_{k} = \frac{1}{T} \left\{ \int_{0}^{T} \xi(t) e^{-jk\omega t} dt - 2 \int_{0}^{3} \xi(t-1) e^{-jk\omega t} dt \right\} - 0$$

$$-\frac{1}{2} \leq t \leq \frac{1}{2};$$

$$t = 0, \quad e^{-jk\omega t} = e^{0} = 1$$

$$\vdots \quad \xi(t) e^{-jk\omega t} = e^{0} = e^{-jk\omega t} = -jk\omega$$

$$\vdots \quad k \text{ is even, } e^{-jk\omega t} = 1$$

$$k \text{ is odd } e^{-jk\omega t} = -jk\omega$$

$$\vdots \quad k \text{ is odd } e^{-jk\omega t} = -jk\omega$$

$$\vdots \quad \xi(t) e^{-jk\omega t} = 1$$

$$\vdots \quad \xi(t) e^{-jk\omega t}$$

$$0 := \frac{2x}{T} = \frac{x}{3}$$

$$a_{i} = \begin{cases} x(1) = \begin{cases} -1 & 1 \le 1 \le 2 \end{cases}$$

$$a_0 = \frac{1}{T} \int x(t) dt = \frac{1}{6} \left\{ \int_{-2}^{1} dt - \int_{-2}^{1} dt \right\} = \frac{1}{6} \left\{ |t|_{-2}^2 - |t|_{-2}^2 \right\}$$

$$a_{k} = \frac{1}{T} \int x(t) e^{-jk\omega_{k}t} dt$$

$$= \frac{1}{T} \left\{ \int_{-2}^{\infty} e^{-jk\omega_{k}t} dt - \int_{-2}^{\infty} e^{-jk\omega_{k}t} dt \right\}$$

$$= \frac{1}{6} \left\{ \left[\frac{e^{-jk\omega_{k}t}}{(-jk\omega_{k})} - \frac{\left[e^{-jk\omega_{k}t} \right]^{2}}{(-jk\omega_{k})} \right] \right\}$$

$$= \frac{1}{6jlc\omega_0} \left\{ e^{-2jk\omega_0} - e^{-jk\omega_0} - e^{jk\omega_0} + e^{2jk\omega_0} \right\}$$

$$= \frac{1}{6jlc\omega_0} \left\{ e^{2jk\omega_0} - e^{-jk\omega_0} - e^{jk\omega_0} + e^{-jk\omega_0} \right\}$$

$$= \frac{1}{3jk\omega_0} \left[\frac{e^{2jk\omega_0} + e^{-2jk\omega_0}}{2} + e^{-2jk\omega_0} - \left(\frac{e^{jk\omega_0} + e^{-jk\omega_0}}{2} \right) \right]$$

$$\therefore \alpha_{k} = \frac{\cos(2k\frac{1}{3}) - \cos(\frac{7k}{3})}{\int k x}$$

$$\chi(t) = \sum_{k = -\infty}^{\infty} a_k e^{-\frac{j\pi kt}{3}} \text{ where } a_k = \begin{cases} 0 & \text{; } k = 0 \\ \frac{\cos(2\pi k_3) - \cos(2\pi k_3)}{jk\pi} & \text{, } k \neq 0 \end{cases}$$

$$x(t) = \begin{cases} 2 : 0 \le t \le 1 \\ 1 : 1 \le t \le 2 \end{cases}$$

$$x(t) = \begin{cases} 2 : 0 \le t \le 1 \\ 1 : 1 \le t \le 2 \end{cases}$$

$$a_{s} = \frac{1}{7} \int_{\mathbb{R}} x(t) dt = \frac{1}{3} \int_{0}^{2} \int_{0}^{1} dt + \int_{0}^{1} dt \end{bmatrix}$$

$$= \frac{1}{3} \int_{-\frac{1}{7}k\omega_{s}}^{2} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right]$$

$$= \frac{1}{3} \left\{ \frac{2}{-\frac{1}{7}k\omega_{s}} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right] \right\}$$

$$= \frac{1}{3} \left\{ \frac{2}{-\frac{1}{7}k\omega_{s}} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right] \right\}$$

$$= \frac{1}{3} \left\{ \frac{2}{-\frac{1}{7}k\omega_{s}} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right] \right\}$$

$$= \frac{1}{3} \left\{ \frac{2}{-\frac{1}{7}k\omega_{s}} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right] \right\}$$

$$= \frac{1}{3} \left\{ \frac{2}{-\frac{1}{7}k\omega_{s}} \left[e^{-\frac{1}{7}k\omega_{s}} dt + \int_{0}^{2} e^{-\frac{1}{7}k\omega_{s}} dt \right] \right\}$$

$$= \frac{2}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{\frac{1}{7}k\omega_{s}} - \frac{e^{-\frac{1}{7}2\omega_{s}}}{\frac{1}{7}k\omega_{s}} \right\}$$

$$= \frac{2}{-\frac{1}{7}} \left[\cos(k\omega_{s}) + \cos(k\omega_{s}) - \sin(k\omega_{s}) \right] - \left[\cos(k\omega_{s}) + \sin(k\omega_{s}) \right]$$

$$= \frac{2}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{2}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{2}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{2}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right]$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{1}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right] \right\}$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{1}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right]$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{1}{3} \left[\cos(k\omega_{s}) - \sin(k\omega_{s}) - \sin(k\omega_{s}) \right]$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{1}{3} \left[\cos(k\omega_{s}) - \cos(k\omega_{s}) - \cos(k\omega_{s}) \right]$$

$$= \frac{1}{3} \left\{ e^{-\frac{1}{7}k\omega_{s}} + \frac{1}{3} \left[\cos(k\omega_{s$$

$$T = 2, \qquad x(t) = e^{-t}, \qquad -1 < t < 1$$

$$a_{t} = \frac{1}{T} \int_{T} x(t) dt = \frac{1}{2} \int_{0}^{t} e^{-t} dt$$

$$= \frac{1}{2} \int_{0}^{t} \frac{e^{-t}}{(-1)} dt$$

$$= \frac{1}{2} (e - e^{-t})$$

$$a_{t} = \frac{1}{T} \int_{T} x(t) e^{-jk\omega t} dt = \frac{1}{2} \int_{0}^{t} e^{-t} e^{-jk\omega t} dt$$

$$a_{t} = \frac{1}{2} \int_{0}^{t} e^{-(t-jk\omega t)} dt$$

$$a_{t} = \frac{1}{2} \int_{0}^{t} \frac{e^{-(t-jk\omega t)}}{-(t+jk\omega t)} dt$$

$$a_{t} = \frac{1}{2} \int_{0}^{t} \frac{e^{-(t-jk\omega t)}}{-(t+jk\omega t)} dt$$

$$a_{t} = \frac{e^{-(t+jk\omega t)}}{2(t+jk\omega t)} = \frac{e^{-(t+jxk)}}{2(t+jxk)}$$

$$\therefore x(t) = \sum_{k=-\infty}^{\infty} a_{k} e^{-jkxk} \text{ where,} \quad a_{k} = \frac{e^{-(t+jxk)}}{2(t+jxk)}$$

$$c) \quad T = 4, \qquad x(t) = \begin{cases} \sin(xt) & 0 \le t \le 2 & \text{we } = \frac{2x}{T} = \frac{x}{4} = \frac{x}{2} \end{cases}$$

$$a_{t} = \frac{1}{4} \int_{0}^{t} x(t) dt = \frac{1}{4} \int_{0}^{t} \sin(xt) dt = \frac{1}{4} \left[\frac{\cos(xt) - \cos(xt)}{x} \right]^{2},$$

$$a_{t} = \frac{1}{4} \cdot \frac{\left[\cos(xt) - \cos(xt)\right]^{2}}{x} = 0$$

$$a_{t} = 0$$

b)

$$a_{k} = \frac{1}{T} \int_{T}^{T} x(1) e^{-jk\omega_{k}} dt = \frac{1}{4} \int_{0}^{2} \sin(\pi 1) e^{-jk\omega_{k}} dt = 0$$

$$J = -\frac{1}{jk\omega_{k}} \left[\sin(\pi 1) e^{-jk\omega_{k}} \right]_{0}^{2} + \frac{\pi}{jk\omega_{k}} \int_{0}^{2} \sin(\pi 1) e^{-jk\omega_{k}} dt$$

$$J = -\frac{1}{jk\omega_{k}} (0) + \frac{\pi}{jk\omega_{k}} \int_{0}^{2} \cos(\pi 1) e^{-jk\omega_{k}} dt$$

$$J = \frac{\pi}{-(jk\omega_{k})^{2}} \left[\cos(\pi 1) e^{-jk\omega_{k}} \right]_{0}^{2} + \frac{\pi^{2}}{(jk\omega_{k})^{2}} \int_{0}^{2} \sin(\pi 1) e^{-jk\omega_{k}} dt$$

$$J = \frac{\pi}{-(jk\omega_{k})^{2}} \left[\cos(\pi 1) e^{-jk\omega_{k}} \right]_{0}^{2} + \frac{\pi^{2}}{(jk\omega_{k})^{2}} \int_{0}^{2} \sin(\pi 1) e^{-jk\omega_{k}} dt$$

$$J = \frac{\pi}{-(jk\omega_{k})^{2}} \left[e^{-jk2\omega_{k}} - 1 \right]$$

$$= \frac{-\pi}{\pi^{2} + (jk\omega_{k})^{2}} \left[e^{-jk2\omega_{k}} - 1 \right]$$

$$= \frac{-\pi}{4 \left[\pi^{2} e^{-k^{2}(\omega_{k})^{2}} \right]} \left[\cos(\pi k) - j \sin(\pi k) - 1 \right]$$

$$= \frac{-\pi}{4 \left[\pi^{2} e^{-k^{2}(\omega_{k})^{2}} \right]} \left[\cos(\pi k) - j \sin(\pi k) - 1 \right]$$

$$= \frac{1}{\pi} \left[e^{-jk^{2}(\omega_{k})} - j \sin(\pi k) - 1 \right]$$

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$$= \frac{1}{\pi} \left[e^{-jk^{2}(\omega_{k})} - j \sin(\pi k) - 1 \right]$$

$$= \frac{1}{\pi} \left[e^{-jk^{2}($$

$$x(1) = \sum_{k=-\infty}^{\infty} a_{ik} e^{+jk(x_{2})t}$$
 where, $a_{k} = \begin{cases} 0; & k=0\\ \frac{(-1)^{k}-1}{x(k^{2}-4)}; & k\neq 0 \end{cases}$

a) a)
$$a_{k} = \begin{cases} 0 : & |e = 0 \\ (j)^{k} \frac{sm(k \%_{k})}{kx} : & k \neq 0 \end{cases}$$
Suppose, $x(k) \stackrel{\text{def}}{=} a_{k}$

Consider, $b_{k} = \frac{sn(k \%_{k})}{kx} : k \neq 0$
Suppose, $x(k) \stackrel{\text{def}}{=} a_{k}$

This is of the form $\frac{sn(k \%_{k})}{kx}$ which is a coefficient of the following $\frac{1}{2} signal$.

$$f(k) = \begin{cases} 1 : |k| < \frac{\pi}{2} \\ 0 : \frac{\pi}{2} < |k| < \frac{\pi}{2} \end{cases}$$

$$0 : T_{k} < |k| < T_{k}$$

$$0 : T_{k} < T_{k}$$

$$0 : T_{k} < T_{k} < T_{k}$$

$$0 : T_{k} < T_{k} < T_$$

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$$a_k = (-1)^k \underline{sm(kx_g)}$$

Suppose
$$x(t) \stackrel{f3}{\longleftrightarrow} a_k$$

where,
$$b_k = \frac{\sin(kx_8)}{2kx}$$
; $k \neq 0$ then $\frac{3}{2}T_1 = \frac{3}{3} \Rightarrow T_1 = \frac{1}{4}$

$$y(t) = \begin{cases} \frac{1}{2} & |t| < \frac{1}{4} \\ 0 & \frac{1}{4} < |t| < 2 \end{cases}$$

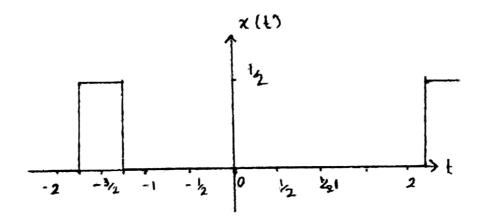
$$a_k = (-1)^k b_k = \left[(os(\pi k) + j sn(\pi k)) \right] b_k = e^{j\pi k} b_k$$

$$\Rightarrow a_k = e^{-j(\frac{\pi}{2})} e^{j\pi k}$$

$$\Rightarrow b_k = e^{-j(\frac{\pi}{2})} b_k = e^{j\pi k} b_k$$

$$x(t) = \begin{cases} \frac{1}{2} : |t+2| < \frac{1}{4} \\ 0 : \frac{1}{4} < |t+2| < 2 \end{cases}$$

$$\Rightarrow \chi(t) = \begin{cases} \frac{1}{2} : -\frac{9}{4} : t < -\frac{7}{4} \\ 0 : -\frac{1}{2} : t < -\frac{9}{4} : or -\frac{7}{4} = t < 2 \end{cases}$$



c)
$$a_{k} = \begin{cases} j^{k} : |k| < 3 \\ 0 : 3 + cotherwise \end{cases}$$

$$x(t) = \sum_{k=-2}^{2} j^{k} e^{jk} \binom{n}{k}!^{k}$$

$$= -2j e^{-j} e^{-j} e^{-j(\frac{n}{2})!} + j e^{j(\frac{n}{2})!} + 2j e^{jnt}$$

$$= 2j [e^{j(\frac{n}{2})!} - e^{-j(\frac{n}{2})!}] + 2j [e^{jnt} - e^{-jnt}]$$

$$= j \cdot 2j \cdot sn(\frac{n}{2}) + 2j \cdot 2j \cdot sn(\frac{n}{2})$$

$$= k \cdot s \cdot s \cdot sn(\frac{n}{2}) - 4 \cdot sn(\frac{n}{2})$$

$$= k \cdot s \cdot s \cdot sn(\frac{n}{2}) + 2 \cdot sn(\frac{n}{2}) + 2$$

 $= x(t) = 1 + 4 \cos(3t) + 2 \cos(xt) + 4 \cos(33t) + 2 \cos(3xt) + ...$

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+ [e i(2x1) + e-j(2xt)] + ...

$$x(t) = \begin{cases} t : 0 \le t \le 1 \\ 2-t : 1 \le t \le 2 \end{cases} \qquad T = 2 \qquad \omega_{1} = \frac{2\pi}{T} = \frac{2\pi}{2} = x$$

$$x(t) = \frac{t^{2}}{T} \Rightarrow a_{t}$$

$$a_{t} = \frac{1}{T} \int x(t) dt = \frac{1}{2} \int \int t dt + \int (0-t) dt \Big]$$

$$= \frac{1}{2} \left\{ \frac{t^{2}1}{2} + 2 - 2t + \frac{1}{2} \right\}$$

$$a_{t} = \frac{1}{2} \int \left\{ \frac{1}{2} + 2 - 2t + \frac{1}{2} \right\}$$

$$a_{t} = \frac{1}{2} \int \left\{ \frac{1}{2} + 2 - 2t + \frac{1}{2} \right\}$$

$$a_{t} = \frac{1}{2} \int \left\{ \frac{t^{2}1}{2} + 2 - 2t + \frac{1}{2} \right\}$$

$$b_{t} = \frac{1}{2} \int \left\{ \frac{t^{2}1}{2} + 2t + \frac{t^{2}1}{2} + \frac{t^{$$

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$$x(t) \xleftarrow{f_5} a_k$$

$$y(t) \xleftarrow{f_5} b_k$$

$$\Rightarrow a_k = \frac{1}{jk\omega_k}b_k$$

$$\therefore a_k = \frac{1}{jkx} \frac{\left[1 - \cos(xk)\right]}{jxk}$$

$$\therefore a_{1c} = \frac{\cos(\pi k) - 1}{k^2 \pi^2} ; k \neq 0$$

$$a_k = \begin{cases} \frac{1}{2} ; & k = 0 \\ \frac{\cos(ak) - 1}{k^2 \pi^2} ; & k \neq 0 \end{cases}$$

$$x(t) = \cos(4\pi t)$$

$$x(t) \stackrel{\text{dis}}{\longleftrightarrow} a_{t}$$

$$y(t) \stackrel{fs}{\longleftrightarrow} b_t$$

$$Z(t) = x(t).y(t)$$

$$x(t) = (os (4\pi t) = \frac{e^{j4\pi t} + e^{-j4\pi t}}{2} = \frac{1}{2}e^{j4\pi t} + \frac{1}{2}e^{-j4\pi t}$$

$$a_k = \begin{cases} \frac{1}{2} : |k| = 1 \\ 0 : \text{ otherwise} \end{cases}$$

$$y(t) = Sm(4xt) = \frac{e^{j4xt} - e^{-j4xt}}{2j} = \frac{1}{2j} e^{j4xt} - \frac{1}{2j} e^{-j4xt}$$

$$b_1 = \frac{1}{2j}$$
 $b_{-1} = -\frac{1}{2j}$ $b_k = 0$; otherwise

$$C_1 = \sum_{i=-1}^{1} a_i b_{i-i} = a_{-i} b_2 + a_0 b_1 + a_i b_0 = 0$$

$$C_{1} = \sum_{i=-1}^{k} a_{i}b_{1-i} = \frac{1}{2} \times \frac{1}{2j}$$

$$= \frac{1}{2} \times \frac{1}{2j}$$

$$\therefore C_2 = \frac{1}{4j}$$

$$C_{-2} = \sum_{i=-1}^{1} a_{i}b_{2-i} = a_{-1}b_{-1} + a_{0}b_{-2} + a_{1}b_{-3}$$

$$= \frac{1}{2} \times -\frac{1}{2j}$$

$$\vdots$$

$$\vdots$$

$$C_{k} = \begin{cases} \frac{1}{4j} : k = 2 \\ -\frac{1}{4j} : k = -2 \end{cases}$$
Or otherwise

d)
$$Z(1) = \cos(4\pi t) \cdot \sin(4\pi t) = \frac{1}{2} \cdot \sin(8\pi t)$$

$$Z(t) = \frac{1}{2} \cdot \left[\frac{e^{j s \pi t} - e^{-j s \pi t}}{2j} \right] = \frac{1}{4j} \cdot e^{-j 2(4\pi)t} - \frac{1}{4j} \cdot e^{j(-2)(4\pi)t}$$

$$C_{1} = \frac{1}{4j}$$
, $C_{-2} = -\frac{1}{4j}$, $C_{k} = 0$, othowise

$$a_k = \begin{cases} 2 : k = 0 \\ j(\frac{1}{2})^{|k|} : \text{ otherwise} \end{cases}$$

a)
$$x(1)$$
 is real $\Rightarrow x^*(1) = x(1) \Leftrightarrow a_k = a_{-k}^*$

$$a_{k} = j\left(\frac{1}{2}\right)^{|k|} - C$$
 $a_{-k} = j\left(\frac{1}{2}\right)^{|k|} \stackrel{\bigcirc}{=} a_{-k} = -j\left(\frac{1}{2}\right)^{|k|}$

b) 詳 xtl) is even
$$\Leftrightarrow$$
 x(t) = x(-1) \Leftrightarrow $a_k = a_{-k}$

By ① 8 ②, $a_k = a_{-k}$
 $x(t)$ is even

Suppose,
$$g(t) = \frac{d[x(t)]}{dt}$$
 $\Rightarrow b_k = jk\omega_k d_k$

$$\vdots b_k = \begin{cases} 0 : k = 0 \\ -k\omega_k \left(\frac{1}{2}\right)^{k!} & \text{otherwise} \end{cases}$$

$$b_k = -k\omega_k \left(\frac{1}{2}\right)^{k!} - 3 \quad b_{-k} = k\omega_k \left(\frac{1}{2}\right)^{k!} - 0$$

$$\Rightarrow g(t) \text{ is not even}$$

a)
$$x(t) \stackrel{f}{\rightleftharpoons} a_k$$

$$x(t-t_0) + x(t+t_0) \stackrel{f}{\rightleftharpoons} b_k$$

$$x(t-t_0) \stackrel{f}{\rightleftharpoons} c_k$$

$$c_k = \frac{1}{T} \int_T x(t-t_0) e^{-jk\omega_0 t} dt = \text{Substitute}, \quad t-t_0 = e^{-jk\omega_0 t} dt$$

$$= \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt = u a_k e^{-jk\omega_0 t}$$

$$\vdots b_k = a_k e^{-jk\omega_0 t} + a_k e^{-jk\omega_0 t}$$

$$= a_k \left[e^{jk(2\pi)t_0} + e^{-jk(2\pi)t_0} \right]$$

$$\vdots b_k = 2a_k \cos\left(\frac{2\pi k t_0}{T}\right)$$

$$\vdots b_k = 2a_k \cos\left(\frac{2\pi k t_0}{T}\right)$$

b)
$$f_{2} \{x(t)\} \xrightarrow{f_{3}} b_{t}$$

$$f_{2}\{x(t)\} = \frac{x(t) + x(-t)}{2}$$

$$f_{3}(t) = \frac{x(t) + x(-t)}{2}$$

$$C_{t} = \frac{1}{T} \int \chi(-t) \cdot e^{-jk\omega_{t}t} dt \qquad -t = \mathcal{X} \Rightarrow -dt = dc$$

$$= \frac{1}{T} \int \chi(\tau) \cdot e^{-j(-k)\omega_{t}\tau} d\tau$$

$$= \frac{1}{T} \int \chi(\tau) \cdot e^{-j(-k)\omega_{t}\tau} d\tau$$

$$\therefore C_k = a_{-k}$$

$$\therefore b_k = \frac{a_{k+a_{-k}}}{2}$$

c)
$$Re\{x(t)\} \stackrel{f3}{\longleftrightarrow} b_k$$
 $Re\{x(t)\} = \frac{x(t) + x'(t)}{2}$
Let, $x''(t) \stackrel{f3}{\longleftrightarrow} c_k$

$$C_k = \frac{1}{T} \int x^*(1) e^{-jk\omega_0 t} dt$$
 $\Rightarrow C_k^* = \frac{1}{T} \int x(1) e^{jk\omega_0 t} dt$
 $\Rightarrow C_k^* = a_{-k} \Rightarrow c_k = a_{-k}$

$$b_k = \frac{a_k + a_{-k}^*}{2}$$

$$y(t) = \frac{d^{2}[x(t)]}{dt^{2}} \xrightarrow{f^{*}} b_{k}$$

$$x(t) = \sum_{k=-\infty}^{\infty} a_{k} e^{jk\omega_{k}t}$$

$$\frac{d[x(t)]}{dt} = \sum_{k=-\infty}^{\infty} jk\omega_{0} \cdot a_{k} e^{jk\omega_{k}t}$$

$$\frac{d^{2}[x(t)]}{dt^{2}} = \sum_{k=-\infty}^{\infty} (jk\omega_{0})^{2} a_{k} e^{jk\omega_{k}t}$$

$$\therefore b_{k} = (jk\omega_{0})^{2} a_{k} = -k^{2} (2\pi)^{2} a_{k}$$

$$\therefore b_{k} = -\frac{4\pi^{2}k^{2}}{T^{2}} a_{k}$$

$$x(2t-1) \xleftarrow{f^{*}} a_{k}$$

$$x(2t-1) \xleftarrow{f^{*}} b_{k}$$

$$period of x(2t-1) = T/3$$

$$x(3t) \xleftarrow{f^{*}} a_{k}$$

$$\vdots b_{k} = a_{k} \cdot e^{-jk\omega_{0}(t)}$$

 \Rightarrow $b_k = a_k \cdot e^{-jk(2k_T)}$

26)
$$T = 3$$
 $x(1) \xrightarrow{f_{5}} a_{k}$
a) $a_{k} = a_{-k}$ c) $\int x(1) d1 = 1$
b) $a_{k} = a_{-k}$ d) $\int x(0) d1 = 2$

By b)
$$x(1)$$
 is one over signal

By a) $x(1) = \sum_{n=1}^{\infty} a_n e^{jn \cdot 1} + \sum_{m=1}^{\infty} a_{m+1} e^{jmn \cdot 1}$

By a)
$$x(t) = \sum_{k=-\infty}^{\infty} [a_{3k} e^{jk\omega t} + a_{2k+1} e^{jk\omega t}]$$

$$x(t) = \sum_{k=-\infty}^{\infty} [a_{3k} e^{jk\omega t} + a_{2k+1} e^{jk\omega t}]$$

$$1 = \sum_{k=-\infty}^{\infty} [a_{3k} e^{jk\omega t} + a_{2k+1} e^{jk\omega t}]$$

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$$1 = \sum_{k=-\infty}^{\infty} [a_{3k} e^{jk\omega t}]$$

By d),
$$x(t) = S(t)$$
, $-0.5 & t & 0.5$
By d), $x(t) = 2S(t-1)$; $0.5 & t & 1.5$

$$\chi(t) = - - + 28(t-1) + 5(t+2) + 25(t+1) + 8(t)$$

$$+ 25(t-1) + 5(t-2) + 26(t-3) + ...$$

$$\chi(1) = \sum_{k=-\infty}^{\infty} \left\{ 8(1-2k) + 28[1-(2k+1)] \right\}$$

a) If
$$x(1)$$
 is real, then
$$x(1) = x'(1) - 0$$

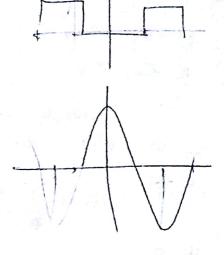
$$x'(1) = x'(1) - 0$$

$$a_i = \frac{1}{T} \int x(t) dt$$

$$a_{k} = \int_{T}^{T} x(t) \qquad \text{Let} \qquad x'(t) \stackrel{\text{pf}}{\longleftrightarrow} b_{k}$$

$$a_{k} = \frac{1}{T} \int_{T}^{T} x(t) e^{jk\omega t} dt$$

$$b_{k} = \frac{1}{T} \int_{T}^{T} x'(t) \cdot e$$



a = a-k

when
$$k = 0$$
, $a_0 = a_0^*$

When
$$a_{10} = a_{-10}$$
 | $Re \{a_{k}\} = Re \{a_{-k}\}$ and $Im \{a_{k}\} = -Im \{a_{-k}\}$

$$\frac{1}{k = -\infty} a_k e^{jk\omega t} + \sum_{k=1}^{\infty} a_k e^{jk\omega t} \text{ is real}$$

$$\Rightarrow \chi(t) - a_0 \text{ is real}$$

$$\Rightarrow a_0 \text{ is real} \quad (: \chi(t) \text{ is real})$$

b)
$$\chi(t)$$
 is even \Rightarrow $a_{1k} = a_{-k} - 0$
since $\chi(t)$ is real, $a_{1k} = a_{1k} - 2$
 $a_{1k} = a_{1k} - 2$
 $a_{1k} = a_{1k} - 2$

c) If
$$x(1)$$
 is odd, $x(1) = -x(-1)$

$$\frac{x(1)}{x(1)} = a_{k} = \frac{1}{T} \int x(1) e^{-\frac{1}{T}} dt - 0$$

$$\frac{x(1)}{x(1)} = \frac{1}{T} \int x(1) e^{-\frac{1}{T}} dt - 0$$

$$\frac{x(1)}{T} = a_{k}$$

$$\frac{1}{T} \int x(1) = -\frac{1}{T} \int x(1) e^{-\frac{1}{T}} dt - 0$$

$$\frac{1}{T} \int x(1) = -\frac{1}{T} \int x(1) e^{-\frac{1}{T}} dt - 0$$

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$$\frac{1}{T} \int x(1) = -\frac{1}{T} \int x(1) e^{-\frac{1}{T}} dt - 0$$

$$\frac{1}{T} \int x(1) e^{-\frac{1}{T}$$

Secause
$$x(t)$$
 is real, $x = a_k = a_k$

$$a_k = -a_k + \frac{x}{2}$$

Ev[x(1)] =
$$\frac{x(1) + x(-1)}{2}$$

Ev[x(1)] $\stackrel{gr}{\longleftrightarrow} \stackrel{a_{k} + \alpha_{-k}}{2}$

Since $x(1)$ is real, $\alpha_{k} = \alpha_{-k}$

$$\frac{\alpha_{k} + \alpha_{-k}}{2} = \frac{\alpha_{k} + \alpha_{k}^{2}}{2} = \frac{27}{2}$$

e) $Od[x(1)] = \frac{x(1) - x(-1)}{2}$
 $Od[x(1)] \stackrel{gr}{\longleftrightarrow} \frac{\alpha_{k} - \alpha_{k}}{2} = \frac{25m_{3}}{2}$

$$\alpha_{k} - \alpha_{k} = \alpha_{k} - \alpha_{k} = \frac{25m_{3}}{2}$$

$$\frac{\alpha_{k+\alpha_{-k}}}{2} = \frac{\alpha_{k+\alpha_{i}}}{2} = \frac{2Re_{i}^{2}\alpha_{k}^{2}}{2} = Re_{i}^{2}\alpha_{i}^{2}$$

e)
$$Od[x(1)] = \frac{2(1) - x(1)}{2}$$

$$Od[x(1)] = \frac{3}{2}$$

$$\frac{a_k - a_k}{2} = \frac{a_k - a_k}{2} = \frac{2 \operatorname{Im} \{a_{ik}\}}{2} \operatorname{Im} \{a_{ik}\}$$

$$\chi(4) = a_0 + 2 \sum_{k=1}^{\infty} \left[B_k \cos k\omega d - C_k \sin k\omega d \right] - 0$$

a)
$$z_{\nu}[x(1)] = \sum_{k=-\infty}^{\infty} \alpha_{k} e^{jk\omega k} - 0$$

$$E_{V}\left[\chi(t)\right] = \frac{\chi(t) + \chi(-t)}{2 \omega}$$

$$= \frac{a_{0} + 2 \sum_{k=1}^{\infty} B_{1k} \cos(k\omega_{0}t) - C_{k} \sin(k\omega_{0}t) + a_{0}}{+2 \sum_{k=1}^{\infty} B_{k} \cos(k\omega_{0}t) + C_{k} \sin(k\omega_{0}t)}$$

$$= a_0 + 2 \sum_{k=1}^{\infty} B_{1k} cos(k\omega_{n}l)$$

$$= a_0 e^{j(0)\omega_{n}l} + 2 \sum_{k=1}^{\infty} B_{1k} \left[e^{jk\omega_{n}l} + e^{jk\omega_{n}l}\right]$$