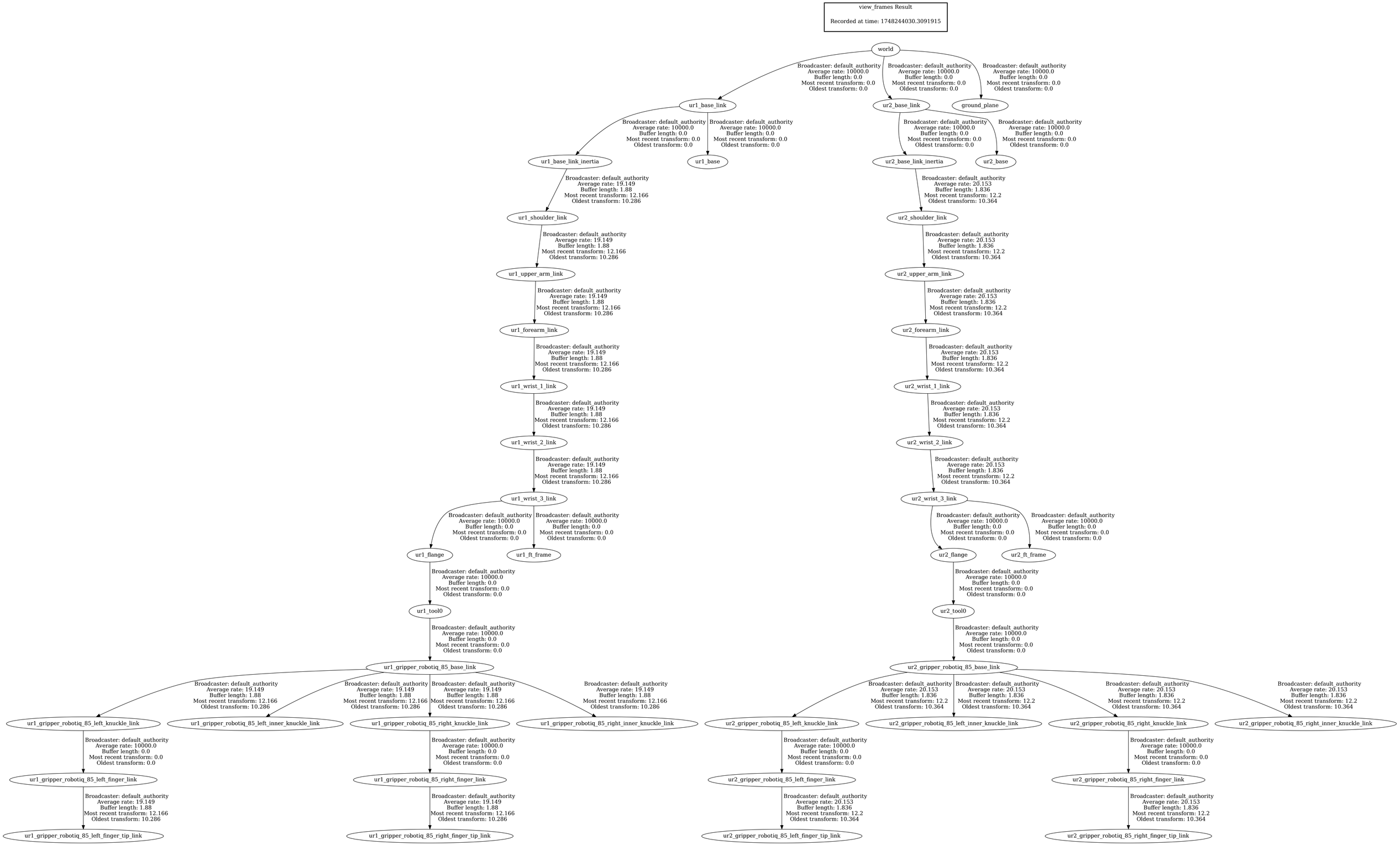
view_frames Result
Recorded at time: 1748244030.3091915
world
Broadcaster: default_authority Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0
ur1_base_link
ur2_base_link
ground_plane
ur1_base_link_inertia
ur1_base
ur2_base_link_inertia
ur2_base
Broadcaster: default_authority Average rate: 19.149 Buffer length: 1.88 Most recent transform: 12.166 Oldest transform: 10.286
Broadcaster: default_authority Average rate: 20.153 Buffer length: 1.836 Most recent transform: 12.2 Oldest transform: 10.364
ur1_shoulder_link
ur2_shoulder_link
ur1_upper_arm_link
ur2_upper_arm_link
ur1_forearm_link
ur2_forearm_link
ur1_wrist_1_link
ur2_wrist_1_link
ur1_wrist_2_link
ur2_wrist_2_link
ur1_wrist_3_link
ur2_wrist_3_link
ur1_flange
ur1_ft_frame
ur2_flange
ur2_ft_frame
ur1_tool0
ur2_tool0
ur1_gripper_robotiq_85_base_link
ur2_gripper_robotiq_85_base_link
ur1_gripper_robotiq_85_left_knuckle_link
ur1_gripper_robotiq_85_left_inner_knuckle_link
ur1_gripper_robotiq_85_right_knuckle_link
ur1_gripper_robotiq_85_right_inner_knuckle_link
ur2_gripper_robotiq_85_left_knuckle_link
ur2_gripper_robotiq_85_left_inner_knuckle_link
ur2_gripper_robotiq_85_right_knuckle_link
ur2_gripper_robotiq_85_right_inner_knuckle_link
ur1_gripper_robotiq_85_left_finger_link
ur1_gripper_robotiq_85_right_finger_link
ur2_gripper_robotiq_85_left_finger_link
ur2_gripper_robotiq_85_right_finger_link
ur1_gripper_robotiq_85_left_finger_tip_link
ur1_gripper_robotiq_85_right_finger_tip_link
ur2_gripper_robotiq_85_left_finger_tip_link
ur2_gripper_robotiq_85_right_finger_tip_link