Recorded at time: 1745162640.6575255 world Broadcaster: default\_authority Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base link ground\_plane Broadcaster: default authority Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 base\_link\_inertia base Broadcaster: default\_authority Average rate: 20.143 Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 shoulder link Broadcaster: default authority Average rate:  $2\overline{0}.143$ Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 upper\_arm\_link Broadcaster: default authority Average rate: 20.143 Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 forearm\_link Broadcaster: default\_authority Average rate: 20.143 Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 wrist\_1\_link Broadcaster: default\_authority Average rate: 20.143 Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 wrist\_2\_link Broadcaster: default authority Average rate: 20.143 Buffer length: 3.922 Most recent transform: 130.546 Oldest transform: 126.624 wrist 3 link Broadcaster: default authority Broadcaster: default\_authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 flange ft\_frame Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 tool0 Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 gripper\_robotiq\_85\_base\_link Broadcaster: default\_authority Broadcaster: default authority Broadcaster: default\_authority Broadcaster: default authority Average rate:  $2\overline{0.143}$ Average rate: 20.143 Average rate: 20.143 Average rate:  $2\overline{0.143}$ Buffer length: 3.922 Buffer length: 3.922 Buffer length: 3.922 Buffer length: 3.922 Most recent transform: 130.546 Most recent transform: 130.546 Most recent transform: 130.546 Most recent transform: 130.546 Oldest transform: 126.624 Oldest transform: 126.624 Oldest transform: 126.624 Oldest transform: 126.624 gripper robotiq 85 right inner knuckle link gripper\_robotiq\_85\_left\_knuckle\_link gripper\_robotiq\_85\_left\_inner\_knuckle\_link gripper\_robotiq\_85\_right\_knuckle\_link Broadcaster: default authority Broadcaster: default\_authority Average rate: 10000.0 Buffer length: 0.0 Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 gripper robotiq 85 right finger link gripper\_robotiq\_85\_left\_finger\_link Broadcaster: default authority Broadcaster: default authority Average rate: 20.143 Buffer length: 3.922 Average rate:  $2\overline{0.143}$ Buffer length: 3.922 Most recent transform: 130.546 Most recent transform: 130.546 Oldest transform: 126.624 Oldest transform: 126.624 gripper\_robotiq\_85\_left\_finger\_tip\_link gripper\_robotiq\_85\_right\_finger\_tip\_link

view frames Result