

# MAXIMA PRACTICALS



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**Subject:** Maths For computing

**Topic:** Practical's Performed on Maxima

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● **Practical 1:** - Create and transform vectors and matrices (the transpose vector (matrix) conjugate transpose of a vector (matrix))

**1. Creating a vector(V) and matrix(M):**

1.1. To create a vector and matrix we use 'matrix' function.

→ `/* Practical 1 by Mozahidul Islam;;`

(%i1) `V:matrix([1],[2],[3]); /* Vector V`

$$V = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

(%i2) `M:matrix([1,2,3],[4,5,6],[7,8,9]); /*The Matrix M*/`

$$M = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

**2. Calculating transpose of vector(V) and matrix(M):**

2.1. To calculate transpose of a vector and a matrix we use 'transpose' function.

→ `conjugate(V);`

$$(\%o6) \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

→ `conjugate(M);`

$$(\%o7) \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

**3. Calculating conjugate of vector(V) and matrix(M)**

3.1. To calculate conjugate of a vector and a matrix we use 'conjugate' function.

→ `transpose(V);`

$$(\%o4) \begin{pmatrix} 1 & 2 & 3 \end{pmatrix}$$

→ `transpose(M);`

$$(\%o5) \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$$

**4. Calculating conjugate transpose of a matrix**

4.1. To calculate conjugate transpose of a matrix we use transpose (conjugate ()) function.

→ `transpose(conjugate(M));`

$$(\%o8) \begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$$

## ● Practical 2: - Generate the matrix into echelon form and find its rank.

- Creating matrix

→ `/*Practical 2 by mozahidul islam*/;`

(%i2) **M: matrix**([1,2,3],[4,5,6],[7,8,9]); `/*The Matrix M*/`

M 
$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

- Echelon form

(%i7) **echelon**(M);

(%o7) 
$$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

- Finding Rank

(%i8) **rank**(M);

(%o8) 2

- **Practical 3:** - Find cofactors, determinant, adjoint and inverse of a matrix.

(%o9) C:/maxima-5.47.0/share/maxima/5.47.0/share/contrib/gentran/test/matrix.mac

(%i13) **A: matrix([2,3,1],[0,-3,4],[5,2,3]); /\*The Matrix A\*/**

A 
$$\begin{pmatrix} 2 & 3 & 1 \\ 0 & -3 & 4 \\ 5 & 2 & 3 \end{pmatrix}$$

(%i14) **determinant(A);**

(%o14) 41

(%i15) **adjoint(A);**

(%o15) 
$$\begin{pmatrix} -17 & -7 & 15 \\ 20 & 1 & -8 \\ 15 & 11 & -6 \end{pmatrix}$$

(%i16) **invert(A);**

(%o16) 
$$\begin{pmatrix} -\left(\frac{17}{41}\right) & -\left(\frac{7}{41}\right) & \frac{15}{41} \\ \frac{20}{41} & \frac{1}{41} & -\left(\frac{8}{41}\right) \\ \frac{15}{41} & \frac{11}{41} & -\left(\frac{6}{41}\right) \end{pmatrix}$$

- **Practical 4:** - Solve a system of Homogeneous and non-homogeneous equations using Gauss elimination method.

→ /\* practical 4 by Mozahidul Islam

```
(%i35) eqn1:read("equation 1 is=");
      eqn2:read("equation 2 is=");
      eqn3:read("equation 3 is=");
      eqn4:read("equation 4 is=");
      block(D:augcoefmatrix([eqn1,eqn2,eqn3,eqn4],[x,y,z,a]),
            S:echelon(D),
            [p,q],X:[x,y,z,a,1],[p,q]:matrix_size(S),
            for i:1 thru p do(for n:1 thru q do(d(i):=sum(S[i,n]-X[n],n,1,q)=0),
            s:makelist(d(i),i,1,p)),
            solve(s,[x,y,z,a]));
/*if solve(s)= [] then print("system of given equations is inconsistent and have no solution")
else print("system of given equations is consistent")$*/
equation 1 is= 2·x + y + 2·z + a = 6;
eqn1 2 z+y+2 x+a=6
equation 2 is= 6·x - 6·y + 6·z+ 12·a = 36;
eqn2 6 z-6 y+6 x+12 a=36
equation 3 is= 4·x + 3·y + 3·z - 3·a = - 1;
eqn3 3 z+3 y+4 x-3 a=-1
equation 4 is= 2·x + 2·y - z + a = 10;
eqn4 -z+2 y+2 x+a=10
(%o38) [[x=2,y=1,z=-1,a=3]]
```

- **Practical 5:** - Solve a system of Homogeneous equations using the Gauss Jordan method.

1. Assigning the value of matrix to a variable named Coefficient\_Matrix.

```
(%i39)/* practical 5 by mozahidul islam*/
/* 5. Solve a system of Homogeneous equations using the Gauss Jordan method*/
Coefficient_Matrix: matrix([1,1,1],[2,-3,4],[3,4,5]);
```

$$\text{Coefficient\_Matrix} \begin{pmatrix} 1 & 1 & 1 \\ 2 & -3 & 4 \\ 3 & 4 & 5 \end{pmatrix}$$

2. Assigning the value of Column matrix to a variable named Column\_martix.

```
(%i2) /*Column Matrix */
Column_Matrix: matrix([9,13,40]);
```

$$\text{Column\_Matrix} \begin{pmatrix} 9 & 13 & 40 \end{pmatrix}$$

3. We will use the function invert for inversion process of matrix.

```
(%i3) /*Finding inverse of coefficient matrix*/
Inv_of_Coefficient_Matrix: invert(Coefficient_Matrix);
```

$$\text{Inv\_of\_Coefficient\_Matrix} \begin{pmatrix} -\frac{31}{12} & \frac{1}{12} & -\left(\frac{7}{12}\right) \\ -\left(\frac{1}{6}\right) & -\left(\frac{1}{6}\right) & \frac{1}{6} \\ -\left(\frac{17}{12}\right) & \frac{1}{12} & \frac{5}{12} \end{pmatrix}$$

4. We will multiply the Inversed Matrix with the Column Matrix

```
(%i4) /*Solution of system of matrix*/
Solution_of_the_system_of_Equations: Inv_of_Coefficient_Matrix . Column_Matrix;
```

$$\text{Solution\_of\_the\_system\_of\_Equations} \begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix}$$

● **Practical 6:** -Generate basis of column space, null space, row space and left null space of a matrix space

1. Create a matrix.

```
(%i40)/* practical 6 by mozahidul islam*/
A: matrix([-1,3,1],[1,1,0],[1,1,0]);
```

$$A = \begin{pmatrix} -1 & 3 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

5. Left null space.

```
(%i7) leftnullspace(A);
```

$$(\%o7) \text{ leftnullspace} \begin{pmatrix} -1 & 3 & 2 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

2. Basis of column space.

```
(%i4) columnspace(A);
```

$$(\%o4) \text{ span} \left( \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix} \right)$$

3. Create null space.

```
(%i5) nullspace(A);
```

$$(\%o5) \text{ span} \left( \begin{pmatrix} 2 \\ -2 \\ 4 \end{pmatrix} \right)$$

4. Row space.

```
(%i6) rowspace(A);
```

$$(\%o6) \text{ rowspace} \begin{pmatrix} -1 & 3 & 2 \\ 1 & 1 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$



- **Practical 7:** - Check the linear dependence of vectors. Generate a linear combination of given vectors of  $R^n$ / matrices of the same size and find the transition matrix of given matrix space.

### 1. Checking linear dependence of vector.

- Here determinant is zero, so the vectors are linearly dependent.

```
(%i40)/* practical 7 by mozahidul islam*/
```

```
(%i32) v1:[1,2,3];  
      v2:[4,5,6];  
      v3:[7,8,9];
```

```
v1    [1,2,3]  
v2    [4,5,6]  
v3    [7,8,9]
```

```
(%i36) a:transpose(matrix(v1,v2,v3));
```

```
a       $\begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$ 
```

```
(%i39) determinant(a);
```

```
(%o39) 0
```

### Output:

```
v: V . c;  
v1  $\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$   
v2  $\begin{pmatrix} 4 \\ 5 \\ 6 \end{pmatrix}$   
v3  $\begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix}$   
c1 2  
c2 -1  
c3 3  
V  $\begin{pmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{pmatrix}$   
c  $\begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix}$   
v  $\begin{pmatrix} 19 \\ 23 \\ 27 \end{pmatrix}$ 
```

### 2. Generate a linear combination of given vectors of $R^n$ / matrices.

```
(%i9) v1: matrix([1], [2], [3]);  
      v2: matrix([4], [5], [6]);  
      v3: matrix([7], [8], [9]);
```

```
c1: 2;
```

```
c2: -1;
```

```
c3: 3;
```

```
V: matrix([v1, v2, v3]);
```

```
c: matrix([c1], [c2], [c3]);
```

```
v: V . c;
```

- **Practical 8:** - Find the orthonormal basis of a given vector space using the Gram-Schmidt orthogonalization process.

→ /\* practical 8 by mozahidul islam\*/

→ Find The Orthonormal Basis Of A Given Vector Space Using The Gram-schmidt Orthogonalization Process.

(%i2) **load(eigen);**

**Matrix\_A: matrix([2,1,0,-1],[1,0,2,-1],[0,-2,1,0]);**

(%o1) C:/maxima-5.47.0/share/maxima/5.47.0/share/matrix/eigen.mac

Matrix\_A  $\begin{pmatrix} 2 & 1 & 0 & -1 \\ 1 & 0 & 2 & -1 \\ 0 & -2 & 1 & 0 \end{pmatrix}$

(%i3) **Orthogonal\_Basis:gramschmidt(Matrix\_A);**

Orthogonal\_Basis  $\left[ \begin{bmatrix} 2 \\ 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ -\left(\frac{1}{2}\right) \\ 2 \\ -\left(\frac{1}{2}\right) \end{bmatrix}, \begin{bmatrix} \frac{2}{3} \\ -\left(\frac{2^2}{3}\right) \\ -\left(\frac{1}{3}\right) \\ 0 \end{bmatrix} \right]$

(%i24) **A:((2^2)+(1^2)+((-1)^2)+(0^2))^0.5;**

**B:[2,1,0,-1]/A;**

A 2.449489742783178

B [0.8164965809277261, 0.4082482904638631, 0, -0.4082482904638631]

(%i26) **C:((0^2)+((-1/2)^2)+(2^2)+((-1/2)^2))^0.5;**

**D:[0,-1/2,2,-1/2]/C;**

C 2.1213203435596424

D [0, -0.23570226039551587, 0.9428090415820635, -0.23570226039551587]

(%i28) **E:((-2/3)^2+(2^2/3)^2+(1/3)^2+0^2)^0.5;**

**F:[-(2/3),2^2/3,1/3,0]/E;**

E 1.5275252316519468

F [-0.4364357804719847, 0.8728715609439694, 0.21821789023599236, 0]

(%i29) **Orthonormal\_Basis:matrix(B,D,F);**

Orthonormal\_Basis  $\begin{pmatrix} 0.8164965809277261 & 0.4082482904638631 & 0 & -0.4082482904638631 \\ 0 & -0.23570226039551587 & 0.9428090415820635 & -0.23570226039551587 \\ -0.4364357804719847 & 0.8728715609439694 & 0.21821789023599236 & 0 \end{pmatrix}$

- **Practical 9:** - Check the diagonalizable property of matrices and find the corresponding eigenvalue and verify the Cayley- Hamilton theorem.

```
→ /* practical 9 by mozahidul islam*/
```

```
(%i15) load(eigen);
```

```
(%o15) C:/maxima-5.47.0/share/maxima/5.47.0/share/matrix/eigen.mac
```

```
(%i16) load(matrix);
```

```
(%o16) C:/maxima-5.47.0/share/maxima/5.47.0/share/contrib/gentran/test/matrix.mac
```

```
(%i17) A;
```

```
(%o17) 
$$\begin{pmatrix} 1 & 2 & 1 \\ 6 & -1 & 0 \\ -1 & -2 & -1 \end{pmatrix}$$

```

```
(%i20) nondiagonalizable(A);
```

```
apply: found nondiagonalizable evaluates to false where a function was expected.
```

```
-- an error. To debug this try: debugmode(true);
```

```
(%i18) load(nchrpl);
```

```
(%o18) C:/maxima-5.47.0/share/maxima/5.47.0/share/matrix/nchrpl.mac
```

```
(%i19) ncharpoly(A,lambda);
```

```
(%o19) 
$$\lambda^3 + \lambda^2 - 12\lambda$$

```

- **Practical 10:** - Application of Linear algebra: Coding and decoding of messages using nonsingular matrices

- code

→ `/* practical 9 by mozahidul islam*/`

```
(%i61)/*This is Practical 10 byMozahidul Islam*/
/* Define a nonsingular matrix for encoding and decoding */
A: matrix([2, 3], [1, 4]);

/* Define a message vector */
message: matrix([1], [2]);

/* Encoding: Multiply the message by the nonsingular matrix */
encoded_message: A. message;

/* Decoding: Multiply the encoded message by the inverse of the matrix */
A_inverse: invert(A);
decoded_message: A_inverse. encoded_message;

/* Display the results */ print("Original Message:");
print(message); print("Encoded Message:");
print(encoded_message); print("Decoded Message:");
print(decoded_message);
```

- Output

$$A = \begin{pmatrix} 2 & 3 \\ 1 & 4 \end{pmatrix}$$

$$\text{message} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\text{encoded\_message} = \begin{pmatrix} 8 \\ 9 \end{pmatrix}$$

$$A\_inverse = \begin{pmatrix} \frac{4}{5} & -\left(\frac{3}{5}\right) \\ -\left(\frac{1}{5}\right) & \frac{2}{5} \end{pmatrix}$$

$$\text{decoded\_message} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

```
(%)
Original Message:
(%o56) Original Message:

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

(%o57) 
$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

Encoded Message:
(%o58) Encoded Message:

$$\begin{pmatrix} 8 \\ 9 \end{pmatrix}$$

(%o59) 
$$\begin{pmatrix} 8 \\ 9 \end{pmatrix}$$

Decoded Message:
(%o60) Decoded Message:

$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

(%o61) 
$$\begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

```

- **Practical 11:** - Compute Gradient of a scalar field.

- Code

```
(%i66) /* Practical 11 By Mozahidul Islam*/;  
/* Defining variables*/  
  
load(vector);  
  
/* Define the scalar field in term of variables x, y, z */  
scalar_field: x^2 + 2*y - 3*z;  
  
/* Compute the gradient of the scalar field */  
gradient_field: gradient(scalar_field,[x,y,z]);  
  
/* Display the gradient field */  
print("gradient of the Scalar Field:");  
print(gradient_field);
```

- Output

(%o62) C:/maxima-5.47.0/share/maxima/5.47.0/share/vector/vector.mac

$$\text{scalar\_field} = (3z) + 2y + x^2$$
$$\text{gradient\_field}\left[\left[\frac{d^2}{dx^2}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dxdy}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dxdz}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right)\right],\left[\frac{d^2}{dxdy}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dy^2}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dydz}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right)\right],\left[\frac{d^2}{dxdz}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dydz}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right),\frac{d^2}{dz^2}\text{ient}\left(-(3z)+2y+x^2,[x,y,z]\right)\right]\right]$$

gradient of the Scalar Field:

(%o65) gradient of the Scalar Field:

$$\begin{aligned} & \left[ \left( \frac{d^2}{dx^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \frac{d^2}{dx dy} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \frac{d^2}{dx dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right], \left[ \frac{d^2}{dx dy} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \frac{d^2}{dy^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right], \right. \\ & \left. \frac{d^2}{dv dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right], \end{aligned}$$
$$\left[ \frac{d^2}{dx dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dy dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dz^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right] \quad (\%o66) \quad \left[ \frac{d^2}{dx^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dx dy} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \right.$$
$$\begin{aligned} \text{(%o66)} \quad & \left[ \left[ \frac{d^2}{dx^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dx dy} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dx dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right], \left[ \frac{d^2}{dx dy} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dy^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \right. \\ & \left. \frac{d^2}{dy dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \left[ \frac{d^2}{dx dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dy dz} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right), \frac{d^2}{dz^2} \text{ient} \left( -(3z) + 2y + x^2, [x, y, z] \right) \right] \right] \end{aligned}$$

- **Practical 12:** - Compute Divergence of a vector field.

```
(%i34)/* This practical 12 is done by Mozahidul Islam*/
/* Load vector*/
load("vector");

/* Define the variables */
[wx,wy,wz]:[x,y,z];

/*Define the vector field in terms of variables x, y and z */
vector_field: [2·x·y, x^2-z,-y^2·z];

/* Compute the divergence of the vector field */
divergence: Div(vector_field, wx, wy, wz);

print("Divergence of the Vector field: ");
print(divergence);

(%o29) C:/maxima-5.47.0/share/maxima/5.47.0/share/vector/vector.mac
(%o30) [x,y,z]
vector_field  $\left[ 2xy, x^2 - z, -\left(y^2 z\right) \right]$ 
divergence 0
Divergence of the Vector field:
(%o33) Divergence of the Vector field:
0
(%o34) 0
```

- **Practical 13:** - Compute Divergence of a vector field.

```
(%i99)/* This practical 13 is done by Mozahidul Islam*/
/* Load vector*/

/* Define the variables */
[wx,wy,wz]:[x,y,z];

/* Define the vector field in terms of variables x, y and z */
vector_field: [2*y, 3*x*z, x^2-y];
/* Compute the curl of the vector field */
c: curl(vector_field,wx,wy,wz);

/* Display the curl vector */
print("Curl of the Vector Field:");
print(c);
```

```
(%o95) [x,y,z]
vector_field [ 2 y, 3 x z, x^2 - y ]
c (0 0 0)
Curl of the Vector Field:
(%o98) Curl of the Vector Field:
(0 0 0)
(%o99) (0 0 0)
```