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Binbin Xu

Research Interests

Visual SLAM, and Computational Photography

Education

- 2017-2021 PhD student in Department of Computing, Imperial College London.
- Supervisors Dr. Stefan Leutenegger and Prof. Andrew Davison
- April 2015– M.Eng., Precision Engineering, University of Tokyo.
- March 2017 Graduated with 4.0/4.0 GPA and Outstanding Master's Thesis Award
 - Thesis Optical Flow-based Video Completion for a Moving Spherical Camera
- Supervisors Assoc. Prof. Atsushi Yamashita and Prof. Hajime Asama
- 2010-2014 B.Eng., Information Engineering, South China University of Technology.
 - GPA 88.07/100 (Ranking: TOP 6% (20/329))

Publications

- RA-L 2017 **Binbin Xu**, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita, Hajime Asama: *Spatiotemporal Video Completion in Spherical Image Sequences*. IEEE Robotics and Automation Letters, Vol. 2, No. 4, pp. 2032-2039, 2017
- ROBIO 2016 **Binbin Xu**, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita, Hajime Asama: Optical Flow-based Video Completion in Spherical Image Sequences. Proceedings of the 2016 IEEE International Conference on Robotics and Biomimetics, pp.388-395, 2016
- ICAM 2015 **Binbin Xu**, Sarthak Pathak, Hiromitsu Fujii, Atsushi Yamashita, Hajime Asama: Robot Body Occlusion Removal in Omnidirectional Video Using Color and Shape Information. Proceedings of the 2015 JSME/RMD International Conference on Advanced Mechatronics, pp.49-50, 2015 (Honorable Mention Award)
- ROBIO 2013 Ningjia Yang, Feng Duan, Yudi Wei, Chuang Liu, Jeffrey Too Chuan Tan, **Binbin Xu**, Jin Zhang: A study of the human-robot synchronous control system based on skeletal tracking technology. Proceedings of the 2013 IEEE International Conference on Robotics and Biomimetics, pp.2191-2196, 2013
- ROBIO 2012 Wenyu Li, Feng Duan, Bo Chen, Jing Yuan, Jeffrey Too Chuan Tan, **Binbin Xu**: *Mobile robot action based on QR code identification*. Proceedings of the 2012 IEEE International Conference on Robotics and Biomimetics, pp.860-865, 2012
- ROBIO 2012 Ningjia Yang, Feng Duan, Sicen Liu, Lili Dai, Jeffrey Too Chuan Tan, **Binbin Xu**: Ankle-angle analysis of drop-foot patients in walking with FES. Proceedings of the 2012 IEEE International Conference on Robotics and Biomimetics, pp.831-836, 2012

Experience

- Feb. Australian Robotic Vision Summer School and visiting at University of Adelaide.
- 2018 Hosts: ACRV, Professor Ian Reid, Dr. Yasir Latif
- May Aug. Participant Student, OpenCV in Google Summer of Code.

2017 Mentor: Dr. Gary Bradski

April – June Visiting Student, Department of Computer Science, University of Tokyo.

2017 Supervisor: Professor Takeo Igarashi

Sep. 2014 - Research Student, Department of Precision Engineering, UTokyo.

March 2015 Supervisors: Assoc. Prof. Atsushi Yamashita and Prof. Hajime Asama

Honors & Awards

- 2017–2020 **CSC-Imperial Scholarship**, sponsored equally by China Scholarship Council and Imperial College London together (15 students per year in the Imperial College)
 - 2017 Outstanding Master's Thesis Award, Department of Precision Engineering, University of Tokyo
 - 2016 **JSME Fellow Award for Outstanding Young Engineers**, The Japan Society of Mechanical Engineers (JSME)
- 2016 2017 Monbukagakusho Honors Scholarship for Privately-Financed International Students, Japan Student Services Organization (JASSO)
 - 2015 **Honorable Mention Award**, 2015 JSME/RMD International Conference on Advanced Mechatronics (ICAM 2015)
 - 2011 Second Grade Student Scholarship, South China University of Technology
 - 2009 First Prize of High School Chemical Olympiad, Jiangsu Province, China
 - 2009 Second Prize of High School Physics Olympiad, Jiangsu Province, China

Teaching

- 2017–2020 Graduate Teaching Assistant, Imperial College London.
- Autumn 2017 M.Sc. C++ Programming Integrated Lab, Instructor: Dr. Fidelis Perkonigg Computer Vision, Instructors: Dr. Su-lin Lee and Prof. Guang-Zhong Yang
- Spring 2018 Advanced Robotics, Instructor: Dr. Stefan Leutenegger
- Autumn 2018 Robotics, Instructor: Prof. Andrew Davison
 - 2015–2017 Teaching Assistant, University of Tokyo.
 - 2016 Academic English Writing, Instructor: Prof. Kumiko Morimura
 - Spring 2015 Mathematical Programming and Optimization, Instructor: Prof. Hajime Asama

Skills

Programming C++, Python, MATLAB with practical experiences.

Language Chinese Mandarin (native), English (fluent, TOEFL iBT 102, GRE 321+3.5), Japanese (proficiency, JLPT N1).

Professional Activities

Reviwers IROS 2018, ICRA2019