Math 381 - Fall 2022

Jay Newby

University of Alberta

Week 5

Last Time

$$D[f](a) = f'(x)$$

$$Dp = p'$$



1 Differentiation of Lagrange polynomials

Today

- 1 Finish differentiation of Lagrange polynomials
- ② Integration of Lagrange polynomials

Differentiation with Lagrange polynomials

We will represent differentiation with a matrix

$$q(x_i) = \sum_{j=0}^n d_{ij} p(x_j),$$

where

Step 2
$$d_{ij} = \frac{w_j}{w_i(x_i - x_j)}, \quad i \neq j$$

 $d_{ii} = -\sum_{\substack{k=0 \ k \neq i}}^n d_{ik}.$

Proof: preliminaries

Definition we will use this week

Recall
$$L_{j}(x) = w_{j}l_{j}(x), \qquad l_{j}(x) = \prod_{\substack{i=0\\i\neq j}} (x-x_{i})$$

$$L_{j}(x_{i}) = \delta_{ij}$$

$$w_{j} = \frac{1}{\prod_{\substack{i=0\\i\neq j}}^{n} (x_{j}-x_{i})}$$

$$Q_{j}(x_{i}) = \sum_{j=0}^{n} p(x_{j})w_{j}l_{j}(x)$$

$$p'(x) = \sum_{j=0}^{n} p(x_{j})w_{j}l'_{j}(x)$$

Proof:
$$(i \neq j)$$

We will use $l_j(x_j) = 1/w_j$, $l_j(x_i) = 0$.

$$q(x_i) = p'(x_i) = \sum_{j=0}^{n} p(x_j) w_j l_j'(x_i).$$

When $t = t_0$ is $t_0 = t_0$ is $t_0 = t_0$.

$$q(x_i) = p'(x_i) = \sum_{j=0}^{n} p(x_j) w_j l_j'(x_i).$$

Constitution $t_0 = t_0$ is $t_0 = t_0$.

$$q(x_i) = p'(x_i) = \sum_{j=0}^{n} p(x_j) w_j l_j'(x_i).$$

Constitution $t_0 = t_0$ is $t_0 = t_0$.

$$q(x_i) = t_0 = t_0$$

$$q(x_i)$$



Proof:
$$(i = j)$$

Recall Homework
$$\sum_{k=0}^{n} L_k(x) = \sum_{k=0}^{n} W_k l_k(x) = 1$$

$$\Rightarrow \sum_{k=0}^{n} w_{k} l_{k}'(x) = 0 = \sum_{k=0}^{n} w_{k} l_{k}'(x_{i})$$

$$\Rightarrow$$
 $W_i l_i(x_i) + \sum_{k=0}^{k} W_k l_k(x_i) = 0$

$$W_{i} \int_{i}^{i} (x_{i}) = -\sum_{k=0}^{N} W_{k} \int_{k}^{i} (x_{i})$$

$$d_{ii} = -\sum_{k=0}^{N} d_{ik}$$

We will study solving linear systems of equations in Week 7-9

$$x = \text{solve}(A, b)$$

When solving a linear system of equations Ax = b, we do not compute the matrix inverse A^{-1} explicitly. It is more efficient to employ a solver algorithm that computes x given A and b.

Goal for integration of Lagrange polynomials

Goal: compute indefinite integral

For Lagrange polynomial q(x), compute

$$p(x) = \int_{a}^{x} q(u) du.$$

From calculus

$$\frac{d}{dx}p(x)=q(x)$$

$$\int q(x)dx = \int \frac{d}{dx}p(x)dx = \langle x \rangle + C$$

$$\int_{a}^{x} q(u)du = \int_{a}^{x} \frac{d}{dx} p(u)du = p(x) - p(a)$$

Can we follow the same approach as polynomial differentiation?

$$\int_{a}^{x} q(u)du = p(x) - p(a)$$

$$R = b - b(a)$$

$$R = \frac{a(x_0)}{a(x_0)} = \frac{p(x_0)}{b(x_0)} - b(a)$$

$$R = \frac{a(x_0)}{a(x_0)} = \frac{p(x_0)}{b(x_0)} - b(a)$$

$$r_{ij} = \frac{1}{l_i^{\prime}(x_i)} \int_{\alpha}^{x_i} l(x) dx$$

But there a better way...

$$\mathcal{D}[p](x) = q(x) \quad \Rightarrow \quad p(x) = \mathcal{D}^{-1}[q](x) ???$$

Recall: for some pto

$$D1 = \sum_{i=0}^{\infty} d_{i} \cdot 1 = 0$$

Next time...

Next Time:

- Derive linear system for integration
- Analysis of integration approximation accuracy
- Roots of Lagrange polynomials (maybe)
- Solving differential equations
- The PyCheb package (from the makers of Chebfun for Matlab)