

# Math 381 - Fall 2022

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Week 9

# Last Week

- 1 Direct solvers for linear systems
- 2 Stability and backward stability
- 3 Error bounds
- 4 Backward/forward substitution
- 5 LU decomposition
- 6 Gaussian Elimination (tridiagonal matrices)
- 7 Gaussian Elimination (general case)
- 8 Gaussian Elimination with partial pivoting

# This Week

- 1 Linear least squares problems
- 2 Matrix subspaces (i.e., the range, nullspace, and orthogonal complements)
- 3 The pseudo inverse of a matrix
- 4 The QR decomposition
- 5 Gram-Schmidt orthogonalization

# Daily Linear Algebra

Permutation Matrix  
 $PP^T = I$

## Projection Matrices

A matrix  $P \in \mathbb{R}^{n \times n}$  is called a *projection matrix* if  $P = P^2$ .


## Complementary Projector

If  $P$  is a projection matrix then  $(I - P)$  is called its *Complementary Projector*.

## Orthogonal Projector (not to be confused with orthogonal matrix!)

Let  $P$  be a projection matrix. If  $P$  is also symmetric, so that  $P = P^T$ , then it is an *Orthogonal Projector*, with the property that  $y = Px$  and  $z = (I - P)x$  implies that  $y^T z = 0$  for any  $x \in \mathbb{R}^n$ .

Example:


$$z = [I - \hat{u}\hat{u}^T]v$$

$$z^T w = v^T [I - \hat{u}\hat{u}^T] \hat{u}\hat{u}^T v$$

$$= v^T \hat{u}\hat{u}^T v - v^T (\hat{u}\hat{u}^T)^2 v$$

$$= v^T \hat{u}\hat{u}^T v - v^T \hat{u}\hat{u}^T v = 0$$

$$\|\hat{u}\| = 1 \quad M = y\hat{u}^T \neq M^T = \hat{u}y^T$$

$$w = (v^T \hat{u}) \hat{u} = (\hat{u} \hat{u}^T) v$$

$$A = \hat{u}\hat{u}^T = A^T = \hat{u}\hat{u}^T$$

# Daily Linear Algebra

## Constructing orthogonal projectors

Any orthonormal set of vectors forming a matrix  $U$  can form a orthogonal projection matrix with

$$P = UU^T.$$

# Motivation: Linear Least Squares problems

## Linear least squares problem

Let  $A \in \mathbb{R}^{m \times n}$  be a singular matrix. We wish to find the vector  $x \in \mathbb{R}^n$  which yields

Full rank

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2.$$

residual  
 $r = Ax - b$

Overdetermined ( $m > n$ )

$$\begin{matrix} A & x & = & b \\ \boxed{\phantom{000}} & \boxed{\phantom{00}} & = & \boxed{\phantom{00}} \end{matrix}$$

can have exact soln

Underdetermined ( $m < n$ )

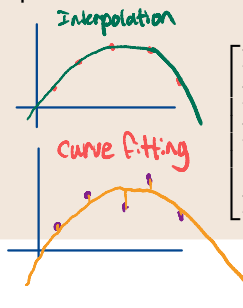
$$\begin{matrix} A & x & = & b \\ \boxed{\phantom{000}} & \boxed{\phantom{00}} & = & \boxed{\phantom{00}} \end{matrix}$$

cannot be full rank

# Motivation: Linear Least Squares problems

## Example: curve fitting (related to interpolation)

Suppose we want to fit a polynomial of degree  $n - 1$  to the  $m$  data points  $x_i, y_i$ , where it is assumed that  $n < m$ . This can be formulated as a least squares solution to


$$\begin{bmatrix} 1 & x_1 & \cdots & x_1^{n-1} \\ 1 & x_2 & \cdots & x_2^{n-1} \\ 1 & x_3 & \cdots & x_3^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & \cdots & x_m^{n-1} \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \end{bmatrix} \approx \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_m \end{bmatrix}$$

Vandermonde Matrix

# Review: matrix subspaces

## Range of a matrix

Let  $A \in \mathbb{R}^{m \times n}$ . The range of  $A$  is the space spanned by the column vectors of  $A$ . In other words, the vector  $Ax \in R(A)$  for all  $x \in \mathbb{R}^n$ .

## Nullspace of a matrix

The nullspace of a matrix  $A \in \mathbb{R}^{m \times n}$  contains all null vectors. In other words, if  $A\rho = 0$  then  $\rho \in N(A)$ .

$$\dim(R(A)) + \dim(N(A)) = n$$

$$\begin{aligned} \text{Full rank: } \dim(N(A)) &= 0 \\ \dim(R(A)) &= n \end{aligned}$$



$$A = U\Sigma V^T \Rightarrow AV = U\Sigma$$

## Singular value decomposition (SVD)

For every matrix  $A \in \mathbb{R}^{m \times n}$  there exists unitary matrices  $U \in \mathbb{R}^{m \times m}$ ,  $V \in \mathbb{R}^{n \times n}$  and a diagonal matrix  $\Sigma \in \mathbb{R}^{m \times n}$  such that  $A = U\Sigma V^T$ .

Full Rank case

$$AV = U\Sigma$$

$$A^T U = V \Sigma^T$$

$$N(A^T) = R(A)^\perp$$

### Theorem: Fredholm Alternative

Let  $A \in \mathbb{R}^{m \times n}$  and  $b \in \mathbb{R}^m$ . The equation  $Ax = b$  has a solution (not necessarily unique) if and only if  $\eta^T b = 0$  for every  $\eta \in N(A^T)$ .

$$b \in R(A)$$

### Corollary

If a solution to  $Ax = b$  exists, it is either the only solution or there are infinitely many solutions.

# Solution to the least squares problem

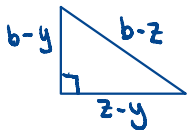
## Use projections to find the minimizer

The equation  $Ax = Pb$  has a solution if  $P$  is a projection onto  $R(A)$ . The length of residual  $r = Ax - b$  is minimized if  $P$  is an *orthogonal* projection onto  $R(A)$  so that  $r = (I - P)b \in R(A)^\perp$ .

Proof: Let  $y = Pb \in R(A)$ . Suppose there is a vector  $z \in R(A)$  :  $z \neq y$ . Want to show  $\|b - z\|_2^2 > \|b - y\|_2^2$ .

$$* [I - P]b = b - y \in R(A)^\perp$$

$$* z - y \in R(A) \quad (z - y \neq 0)$$



$$\|b - z\|_2^2 = \|b - y\|_2^2 + \|z - y\|_2^2 > \|b - y\|_2^2$$

unless  $\|z - y\|_2 = 0$

# Solution to the least squares problem

## Definition: Pseudo Inverse

For a given full rank matrix  $A \in \mathbb{R}^{m \times n}$ , its pseudo inverse  $A^+$  is a matrix such that  $x = A^+b$  is the unique solution to the least squares problem

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|_2^2.$$

The pseudo inverse can be written in many equivalent ways

# Normal equations

## Normal equations

For a given full rank matrix  $A \in \mathbb{R}^{m \times n}$  and  $b \in \mathbb{R}^n$ , the least squares solution to  $Ax = b$  is the solution to

$$A^T Ax = A^T b.$$

Proof:  $r = Ax - b$ , where  $r$  is the residual,

$$A^T r = A^T (Ax - b) = A^T Ax - A^T b = 0$$

$\Rightarrow$  either  $r=0$  so that  $Ax=b$  or  
 $r \in N(A^T) = R(A)^\perp$ . By slide 11,  $x$  is  
sol<sup>n</sup> to least squares problem.

# Normal equations

## Normal equations version of the pseudo Inverse

For a given full rank matrix  $A \in \mathbb{R}^{m \times n}$ , its pseudo inverse is given by

$$A^+ = (A^T A)^{-1} A^T.$$

Proof: If  $A^T A$  is nonsingular (see next slide), and if  $AA^+$  is an orthogonal projection for  $R(A)$  (see two slides down) then

$$Ax = AA^+b \quad Ax = y = Pb$$

has a solution that solves the LS problem. Then we have that

$$M = A^T A \in \mathbb{R} \quad Mx = A^T Ax = A^T AA^+b$$

has a unique solution given by

$$x = (A^T A)^{-1} (A^T A) A^+ b = A^+ b.$$

# Normal equations

## Claim:

If  $A \in \mathbb{R}^{m \times n}$  is full rank then  $A^T A$  is nonsingular

Proof: want to show  $A^T A p = 0 \Rightarrow p = 0$ .

Since  $A$  is full rank  $y = A p \neq 0$  if  $p \neq 0$ .

Then we want to show  $A^T y \neq 0$  if  $y \neq 0$ .

Since  $y \in R(A) \neq R(A)^\perp = N(A^T) \Rightarrow A^T y \neq 0$  if  $y \neq 0$ .

# Normal equations

For a given full rank matrix  $A \in \mathbb{R}^{m \times n}$ , an orthogonal projector onto  $R(A)$  is given by

$$P = AA^+.$$

- ①  $P^2 = P$   $A(A^+A)^{-1}A^T A(A^+A)^{-1}A^T = A(A^+A)^{-1}A^T = AA^+$
- ②  $P^T = P$   $(A(A^+A)^{-1}A^T)^T = A[(A^+A)^{-1}]^T A^T = A(A^+A)^{-1}A^T$
- ③  $Px \in R(A)$  for any  $x \in \mathbb{R}^n$

$$A(A^+x) \in R(A)$$



# General approach

Given an orthogonal projector  $P$  onto  $R(A)$ :

- 1 Compute  $y = Pb$
- 2 Solve  $Ax = y$