

Way to Electromagnetic (EM) waves

Outline

- Last review of Maxwell's equations: How all terms fit together
- How does the charge conservation law became sacred !
- Orthogonality of \vec{E} and \vec{B} and transverse character of EM waves
- Travelling Electric and Magnetic fields: Plane wave
- Solving Maxwell's equations
- Poynting vector: Energy – Momentum
- Propagation, Polarization and incidence of EM waves on matter: conductor vs dielectric

Summarizing

Time independent ($\frac{\partial}{\partial t} = 0$)
No current or steady

Time dependent ($\frac{\partial}{\partial t} \neq 0$)
Acceleration

Electrostatics

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

→ Gauss's law

$$\vec{\nabla} \cdot \vec{E}(t) = \frac{\rho(t)}{\epsilon_0} \rightarrow \text{Will be proven}$$

$$\vec{\nabla} \times \vec{E} = 0$$

→ Poisson equation
 $\vec{E} = -\vec{\nabla} V$

$$\vec{\nabla} \times \vec{E}(t) = -\frac{\partial \vec{B}(t)}{\partial t} \rightarrow \text{Faraday's law}$$

Magnetostatics

$$\vec{\nabla} \cdot \vec{B} = 0$$

→ Gauss's law

$$\vec{\nabla} \cdot \vec{B}(t) = 0$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

→ Ampere's law

$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J}(t) + \frac{1}{c^2} \frac{\partial \vec{E}(t)}{\partial t} \rightarrow \text{Maxwell's law}$$

IN WHAT FOLLOWS

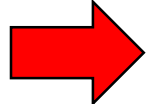
$$\begin{array}{cc} \rho(t) & \vec{E}(t) \\ \vec{j}(t) & \vec{B}(t) \end{array}$$

All these functions are time variable besides their spatial dependence

But for a sake of simplicity the variable t is dropped

A special attention must be paid to the forth Maxwell's equation

How the charge conservation law became sacred !

Ampere's law $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$  Maxwell's questioning

$$\underbrace{\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B})}_{\substack{|| \\ 0}} = \mu_0 \vec{\nabla} \cdot \vec{J} \quad \xrightarrow{\text{red arrow}} \quad \vec{\nabla} \cdot \vec{J} = 0 \quad ! \quad \text{The flux of a current out of a closed surface is zero}$$

COMON SENSE

The flux of a current flowing out of a closed surface

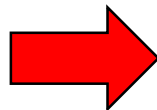


DECREASE of charge inside



So it cannot be in general zero

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$



Something is wrong with Ampere's law

Maxwell's correction

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 \vec{\nabla} \cdot \vec{J} + \frac{1}{c^2} \frac{\partial \vec{\nabla} \cdot \vec{E}}{\partial t}$$

From Gauss law

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 \vec{\nabla} \cdot \vec{J} + \frac{1}{\epsilon_0 c^2} \frac{\partial \rho}{\partial t} = 0$$

$\underbrace{\hspace{10em}}_{=0} \qquad \underbrace{\hspace{10em}}_{=0}$

$$\frac{1}{\epsilon_0 \mu_0} = c^2$$

Charge conservation law
Or continuity equation

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

To date no one has found an experiment that disagrees with this statement

Charge conservation

$$\vec{\nabla} \cdot \vec{j} = -\frac{\partial \rho}{\partial t}$$

If charges are flowing out of closed surface it means that their density inside the volume bounded by this surface is decreasing **UNLESS** the difference is supplied by an external source (closed circuit)

Reminder

- Differential forms of Maxwell's equations manipulate vectors
- Integral forms of Maxwell's equations manipulate scalars

Let's look at equation (1) $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

What if things are varying with time ?

$$\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) = \frac{1}{\epsilon_0} \frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial t} = -\vec{\nabla} \cdot \vec{J} \Rightarrow \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) = -\vec{\nabla} \cdot \vec{J} \Rightarrow \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) + \vec{\nabla} \cdot \vec{J} = 0$$

Charge conservation law

Let's now take a look at equation (4) $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$

$$\underbrace{\vec{\nabla} \cdot [c^2 \vec{\nabla} \times \vec{B}]}_{=0} = \frac{\vec{\nabla} \cdot \vec{J}}{\epsilon_0} + \frac{\partial \vec{\nabla} \cdot \vec{E}}{\partial t} \Rightarrow \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) + \vec{\nabla} \cdot \vec{J} = 0$$

||

0

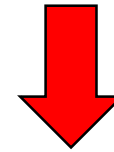
$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \text{Valid all the time}$$

A beautiful experiment illustrating the pertinence of Maxwell's approach

The charge source $Q(r, t)$ is leaky radially (symmetrically)

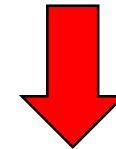
Radioactive source

$$\frac{\partial Q(r, t)}{\partial t} = -4\pi r^2 j(r) \quad \text{Current is a scalar field}$$

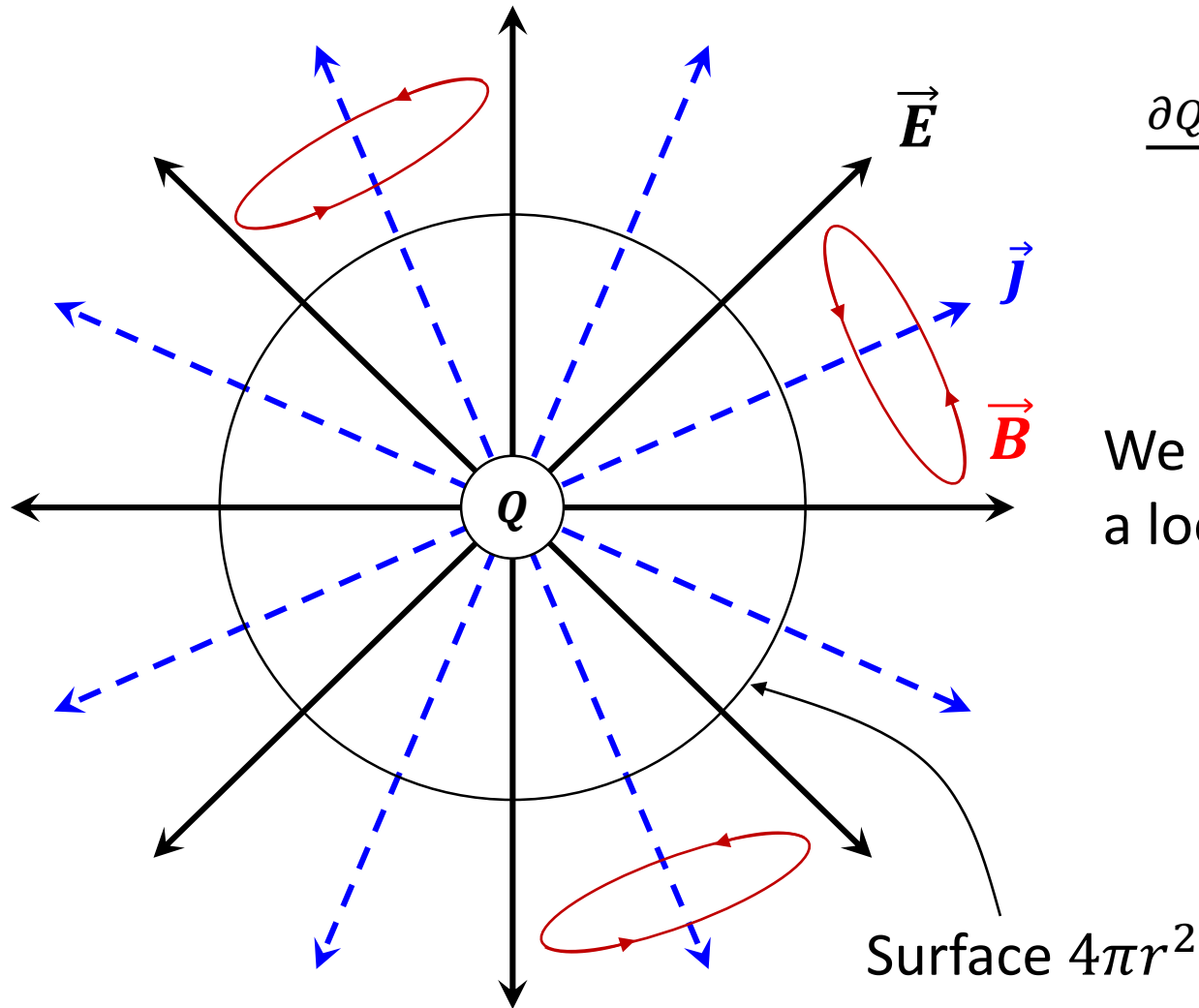


We should expect a magnetic field circulating along a loop surrounding the current density vectors

Biot & Savart's and Ampere's laws



How can a field change direction ?



Maxwell finding saves the situation

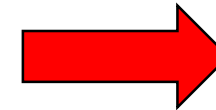
$$E(r, t) = \frac{Q(r, t)}{4\pi\epsilon_0 r^2}$$



$$\frac{\partial E}{\partial t} = \frac{1}{4\pi\epsilon_0 r^2} \frac{\partial Q(r, t)}{\partial t} = -\frac{j(r)}{\epsilon_0}$$

$$j(r) = \frac{I}{A} \quad \begin{aligned} A &= 4\pi r^2 \\ I &= \frac{\partial Q(r, t)}{\partial t} \end{aligned}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J} - \frac{\vec{J}}{\epsilon_0 c^2} = \vec{0}$$



$$\vec{B} = \vec{0}$$

Fourth Maxwell's equation

No magnetic field

Two sources of magnetic fields cancel each other out
 \Rightarrow There can be no magnetic field

Electromagnetic (EM) waves

Maxwell's theory

1865

$\frac{\partial B}{\partial t} \rightarrow$ Source of $E(x, t)$
 $\frac{\partial E}{\partial t} \rightarrow$ Source of $B(x, t)$

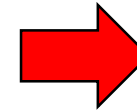
+

Hertz's experiments

1888 (23 years later !)



EM waves



- Energy
- Momentum

Mechanical waves need medium to propagate

EM waves **do not** need any medium to propagate

BUT both are based on the same equations

Maxwell equations and EM waves

Faraday's law $\Rightarrow \frac{\partial B}{\partial t} \rightarrow$ Source of $E(x, t)$ proved by emf induction

Ampere's and Maxwell's law $\Rightarrow \frac{\partial E}{\partial t} \rightarrow$ Source of $B(x, t)$ proved by displacement current

$$\begin{array}{ccc} \frac{\partial E}{\partial t} & \leftrightarrow & \frac{\partial B}{\partial t} \\ \downarrow & & \downarrow \\ \varepsilon_0 & & \mu_0 \end{array}$$

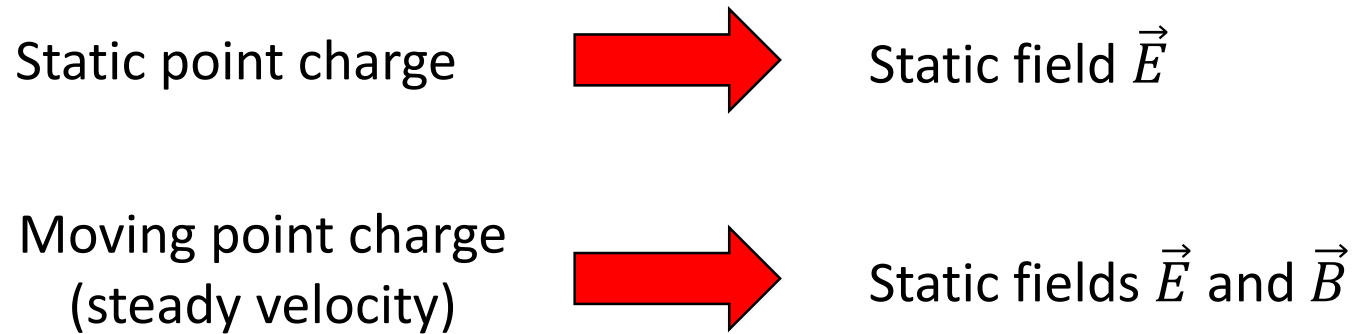
$\underbrace{\hspace{1.5cm}}$



$$\frac{1}{\varepsilon_0 \mu_0} = c^2$$

Maxwell motivation (1864) was to understand this extraordinary result

Characteristics of the medium



To produce EM wave, the charge MUST accelerate

$$\frac{\partial E}{\partial t} \leftrightarrow \frac{\partial B}{\partial t}$$

Every accelerated charge radiates EM energy

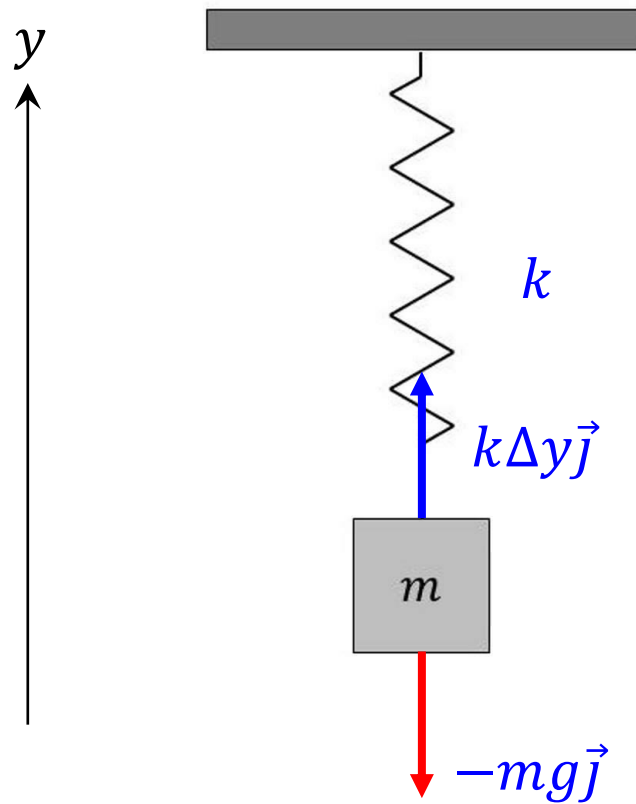


- This makes classical atom unstable
- The orbiting electron has a centripetal acceleration

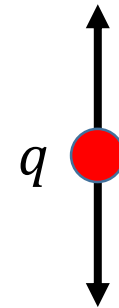
Quantum mechanics handles this issue

How can we accelerate a charge ?

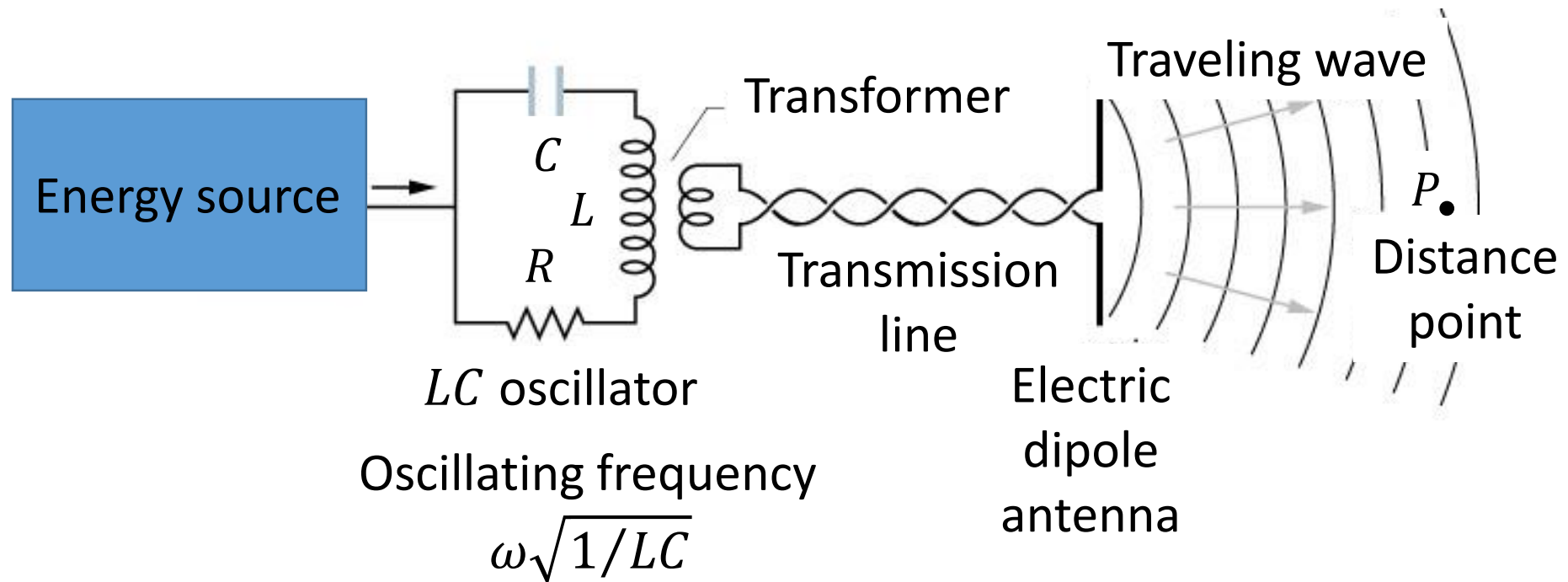
Simple harmonic oscillation



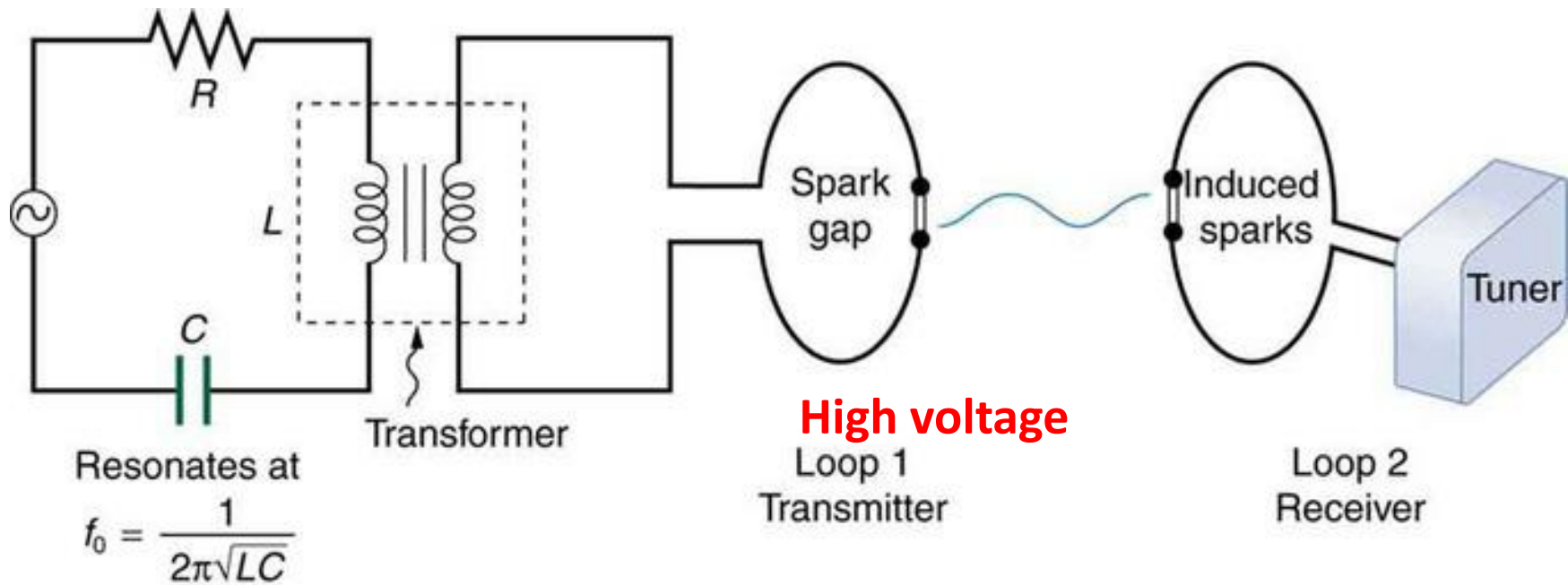
The two systems are in permanent acceleration



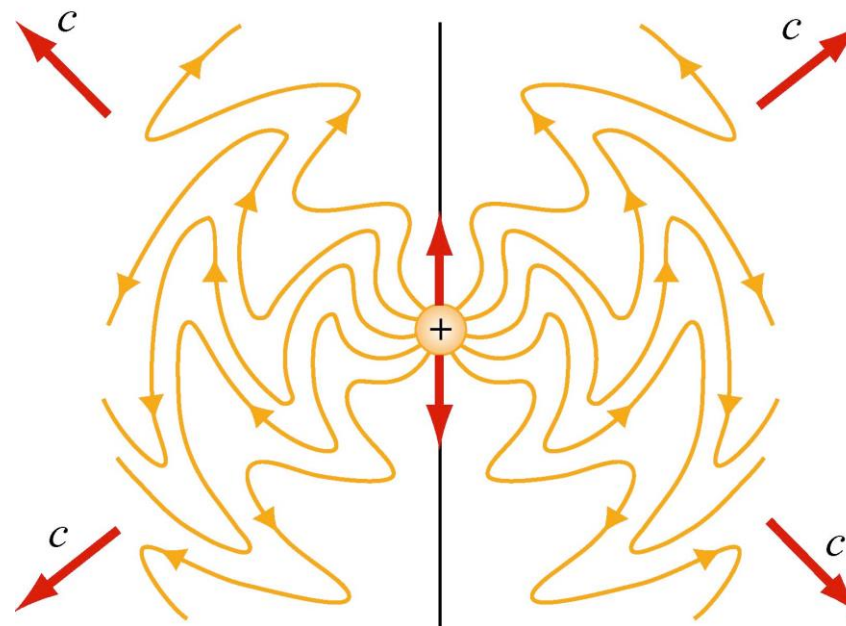
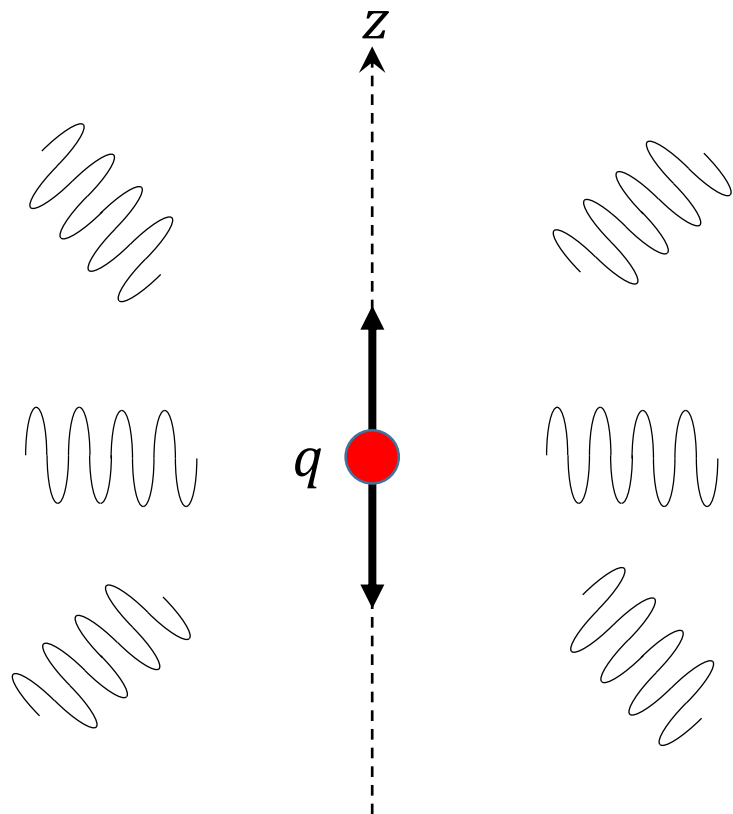
Today's circuit



Original Hertz experiment 1888



= ***RLC*** circuit that can be tuned to resonance

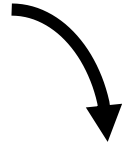


Question:

- 1) Is it possible to have a purely Electric wave or Magnetic wave propagating through empty space ?
- 2) No wave along the z axis: Why?

Electrostatic

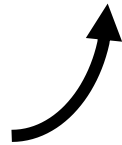
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \vec{e}_r$$



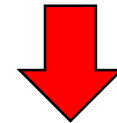
Both perpendicular to each other but **NOT ALWAYS**
whether the charges are static or in uniform motion

Magnetostatic

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q}{r^2} \vec{v} \times \vec{e}_r$$



Maxwell's equations require **ORTHOGONALITY ALL THE TIME**



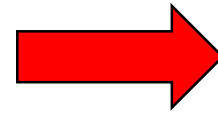
ONLY ONE SOLUTION: THE CHARGES MUST ACCELERATE

Orthogonality of \vec{E} and \vec{B} and transverse character of EM waves

To avoid confusion between

\vec{k} as a wave vector

\vec{k} as a unit vector along z –axis



$$(\vec{i}, \vec{j}, \vec{k},) \rightarrow (\hat{i}, \hat{j}, \hat{k})$$

Expressing the traveling \vec{E} and \vec{B} in complex exponential forms

$$\vec{E} = \sum_1^3 E_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = \sum_1^3 B_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$m = (x, y, z)$$

$$\hat{u} = (\hat{i}, \hat{j}, \hat{k})$$

$$\vec{E} = (E_{0x}\hat{i} + E_{0y}\hat{j} + E_{0z}\hat{k}) e^{i(k_x x + k_y y + k_z z - \omega t)}$$

$$\vec{B} = (B_{0x}\hat{i} + B_{0y}\hat{j} + B_{0z}\hat{k}) e^{i(k_x x + k_y y + k_z z - \omega t)}$$

Each component of \vec{E} and \vec{B} may depend on (x, y, z) !

$$\vec{k} = k_x \vec{i} + k_y \vec{j} + k_z \vec{k}$$

\vec{k} direction of propagation)

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$



$$\vec{k} \cdot \vec{r} = k_x x + k_y y + k_z z$$

Orthogonality of \vec{E} and \vec{B} : Demonstration based on Faraday's and Maxwell's laws

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

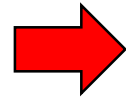
From Faraday's law

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

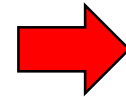
Expressing the traveling \vec{E} and \vec{B} in complex exponential forms

$$\vec{E} = \sum_1^3 E_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = \sum_1^3 B_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$



$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$



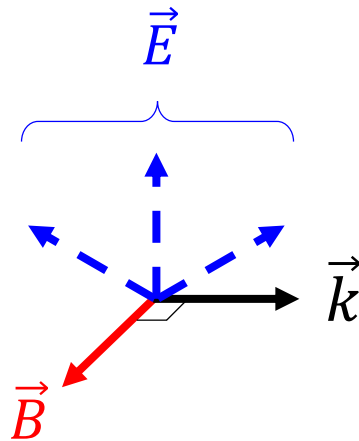
$$\vec{k} \times \vec{E} = \omega \vec{B}$$



$$\vec{B} \perp \vec{k} \text{ and } \vec{B} \perp \vec{E}$$



What about \vec{E} and \vec{k} ?

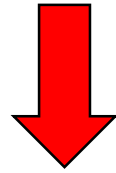


\vec{k} indicate the direction of propagation

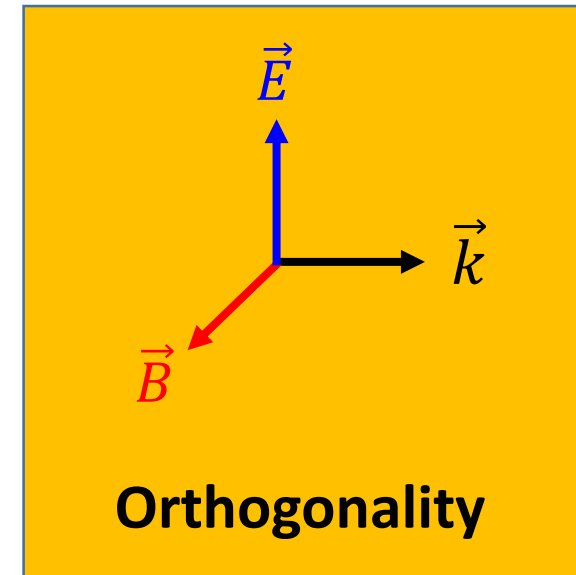
From Maxwell's (Ampere's corrected) law

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \quad \rightarrow \quad \text{in free space} \quad \rightarrow \quad \vec{\nabla} \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

The same treatment as in previous slide



$$\begin{aligned} \vec{k} \times \vec{B} &= -\frac{\omega}{c^2} \vec{E} \\ \vec{k} \times \vec{E} &= \omega \vec{B} \end{aligned}$$



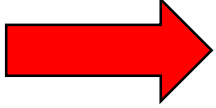
Transverse character of the EM wave: Demonstration based on Gauss's laws


$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

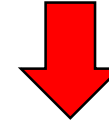
$$\vec{\nabla} \cdot \vec{B} = 0$$

From Gauss's law in a charge free space

$$\vec{\nabla} \cdot \vec{E} = 0$$


$$\frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} = 0$$


$$i(k_x E_x + k_y E_y + k_z E_z) = 0$$



$$\vec{k} \cdot \vec{E} = 0$$

The electric field \vec{E} is orthogonal
to the direction of propagation

From Gauss's law applied to \vec{B}



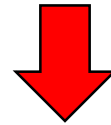
$$\vec{k} \cdot \vec{B} = 0$$

The magnetic field \vec{B} is orthogonal
to the direction of propagation

Important property of nature



Orthogonality and Transverse character of the electric and magnetic fields



Obtained from vector analysis

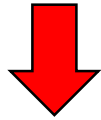
Expressing universality

Consequence on the relation between E and B

$$\vec{k} \times \vec{E} = \omega \vec{B}$$

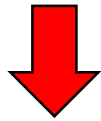


$$kE = \omega B$$



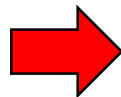
$$E = \frac{\omega}{k} B$$

Assuming **NO** dispersion \Leftrightarrow homogeneous medium



In vacuum

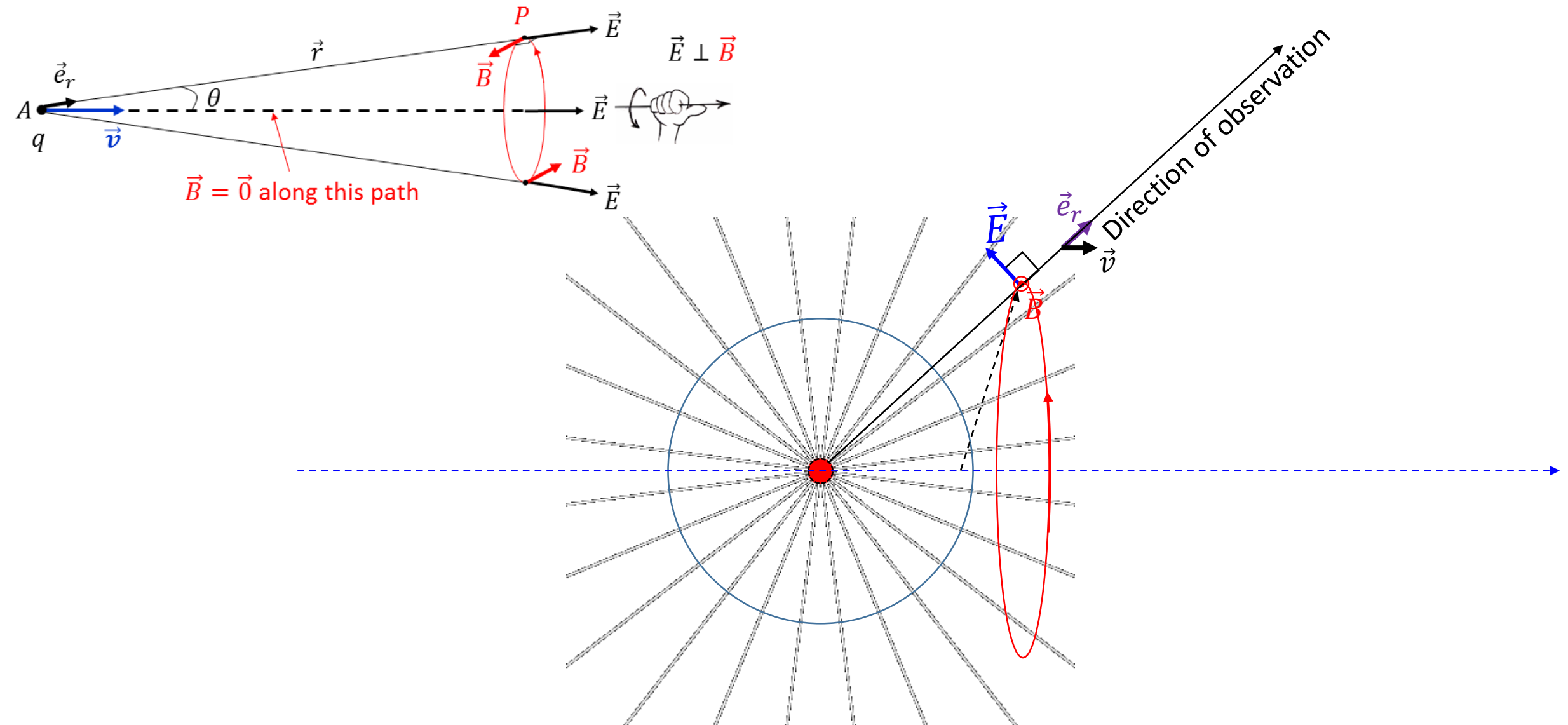
$$E = cB$$



$$B \ll E$$

In most practical cases it is E that matters

Acceleration creates a transverse wave



Remark on vectors

In general a vector has 3 components and each component depends on four variables (x, y, z, t)

$$\vec{V} = V_x(x, y, z, t)\hat{i} + V_y(x, y, z, t)\hat{j} + V_z(x, y, z, t)\hat{k}$$


If the vector has only one single component $\vec{V} = V_y(x, y, z, t)\hat{j}$

BUT

Still this component can be function of the four variables (x, y, z, t)

Plane wave

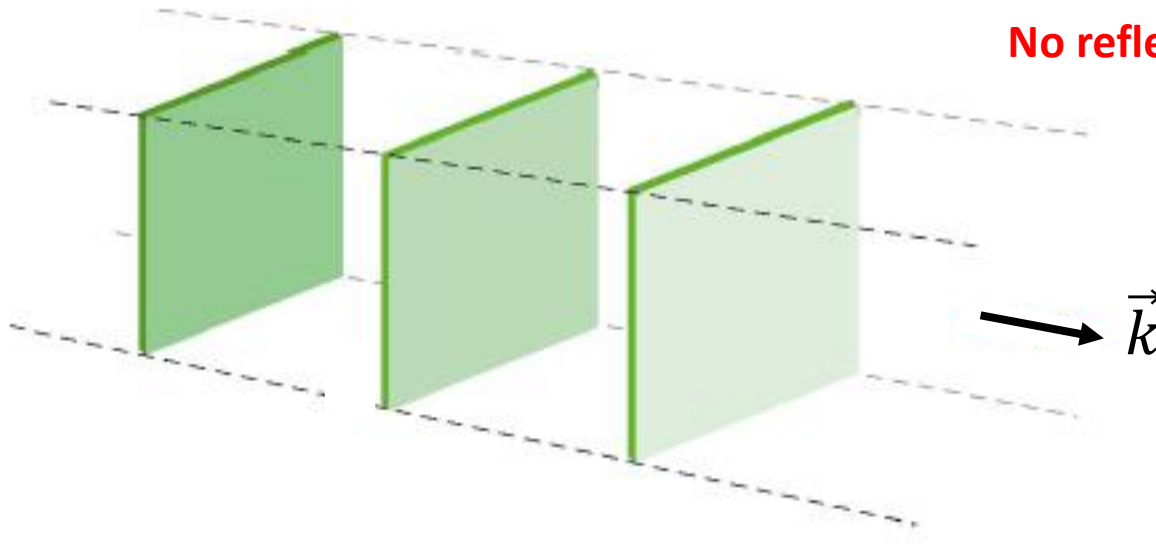
Assumptions

- **Homogeneous** unbounded medium (vacuum):  No **absorption** and no **reflection**
- Source of EM wave consists of **an infinite plane perpendicular** to the direction of propagation
On every plane, \vec{E} and \vec{B} keep the **same direction, same magnitude and same phase**

No reflection

No absorption

Homogeneous



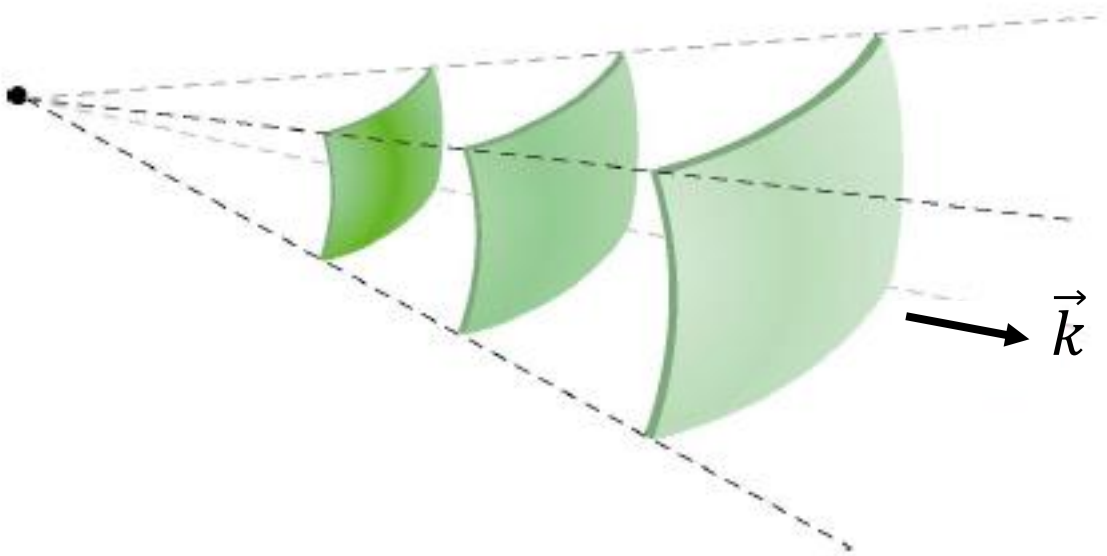
Plane wave

Not realistic because it
assumes an infinite source

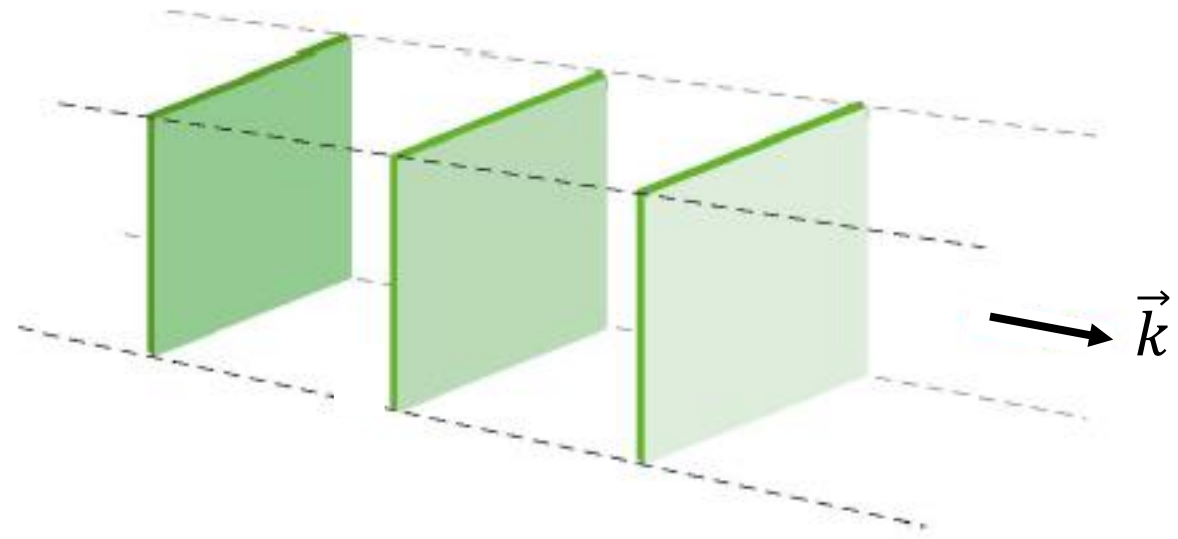
A more realistic approach to the plane wave

Away from a spatially limited source, a spherical wave is more realistic...

Spherical wave



Plane wave

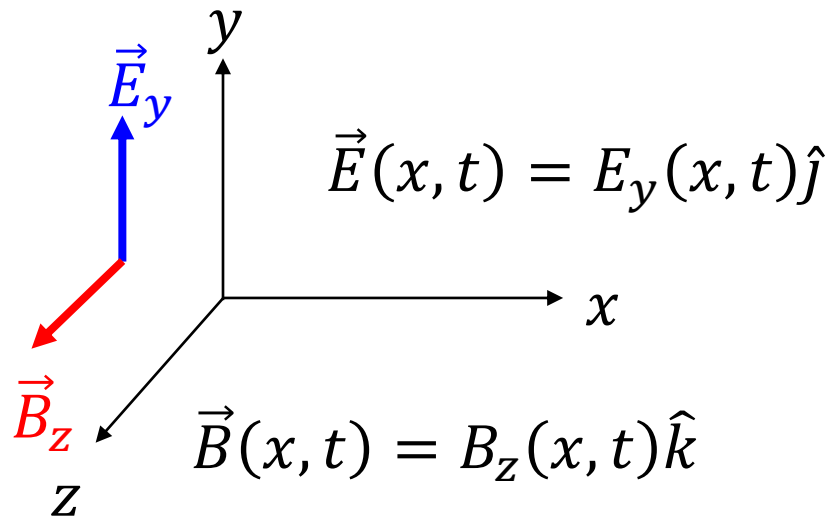


... And very far away from the source it may look like a plane wave...

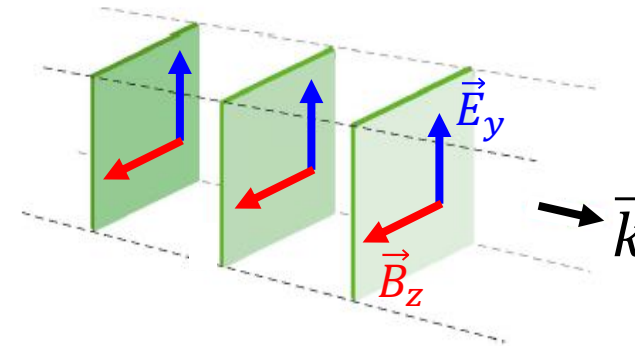
Plane wave

Assumptions

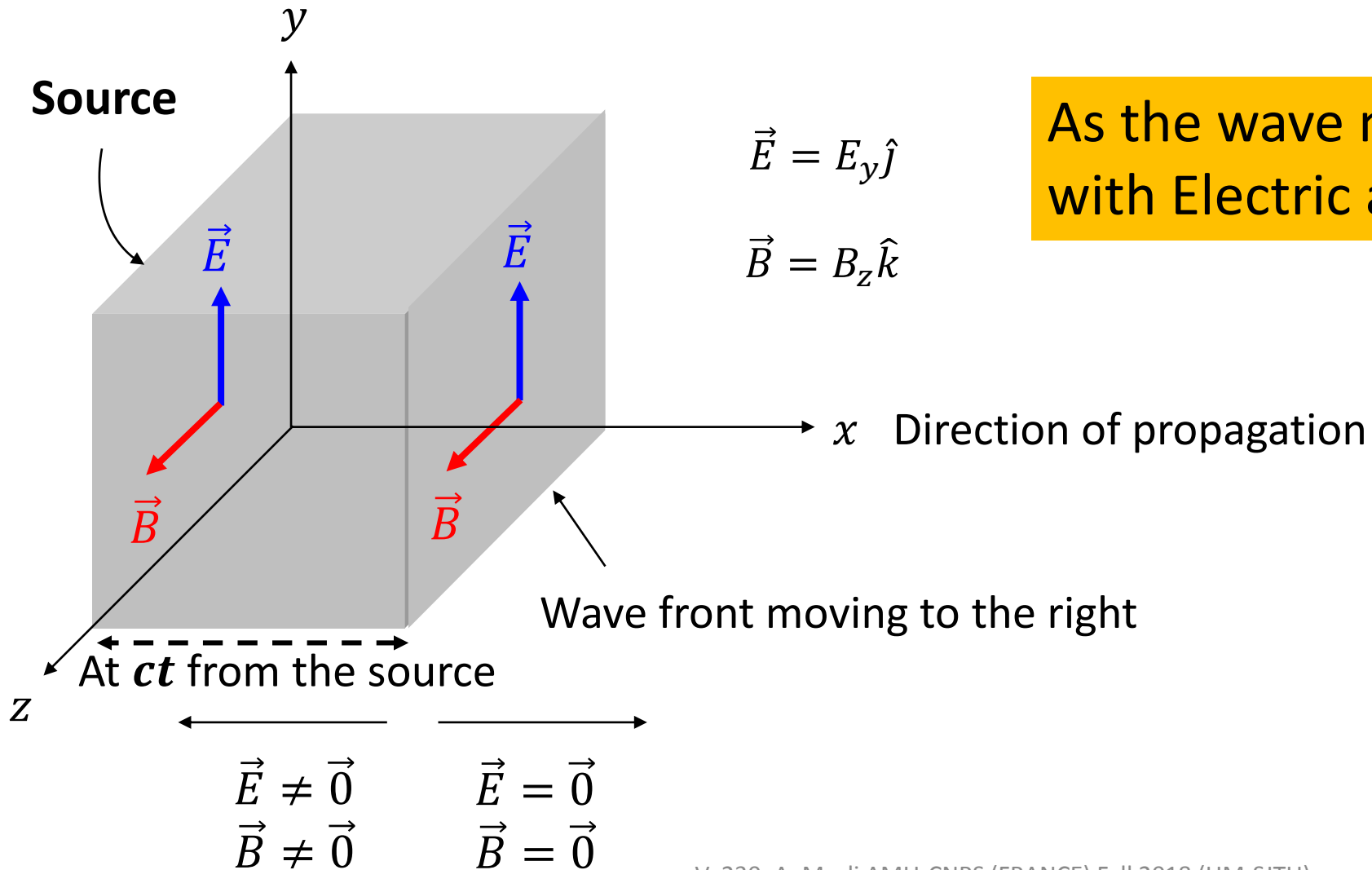
- For a plane wave each field has one component which depends on only two variables (x, t)



$$\frac{\partial E_y}{\partial y} = 0 \text{ and } \frac{\partial B_z}{\partial z} = 0$$



Plane EM wave and the relation $c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$



As the wave moves the space is filled with Electric and magnetic field

Postulating a configuration for a Plane wave

- E_y and B_z are constant in every point in a **given plane at a given position x**
- Both fields move together in the $+x$ -direction with a speed c (unknown)

Is this configuration of a plane wave
consistent with the four Maxwell's equations ?

Could \vec{E} or \vec{B} have an x – component ?

A) Gauss's law: Flux of the fields

$\vec{\nabla} \cdot \vec{E} = 0$ when no net charges inside the Gaussian surface

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{E} = E_y \hat{j}$$

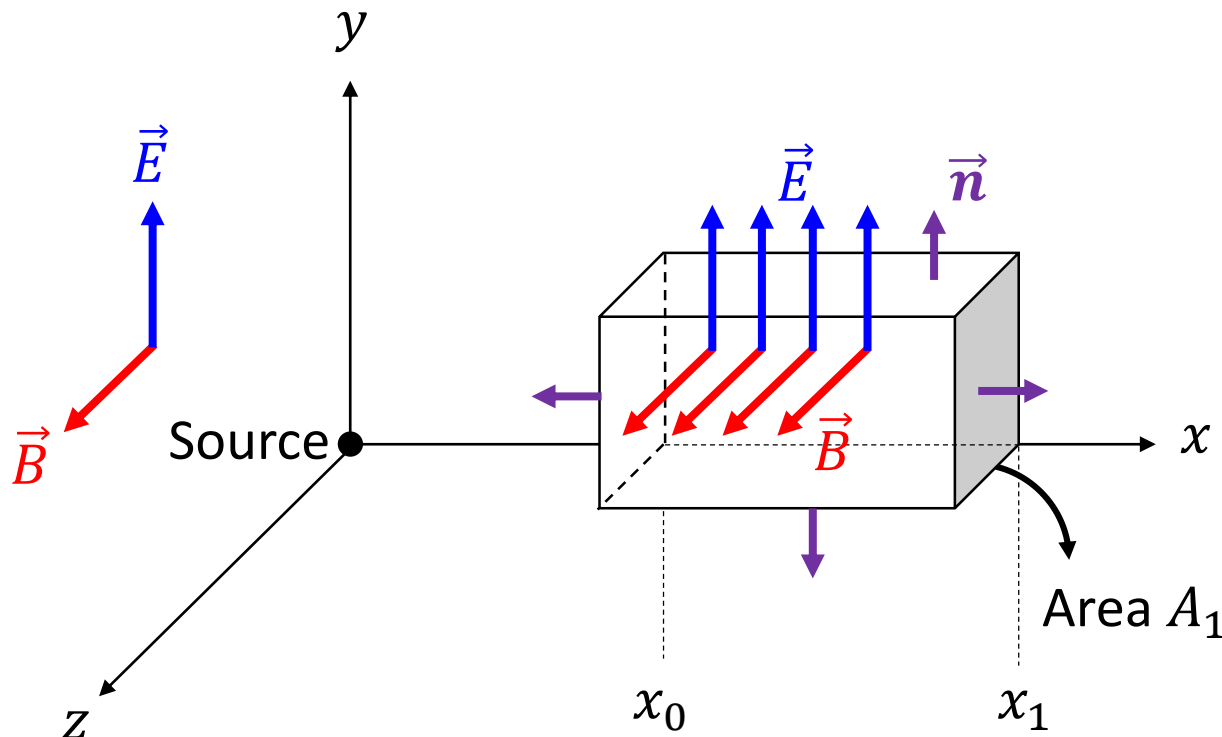
$$\vec{B} = B_z \hat{k}$$

$$E_z = 0$$

$$B_y = 0$$

$$\vec{E} \perp \vec{B}$$

$$\vec{E} \perp \vec{B}$$



What about E_x and B_x ?

Gauss's law would be violated if \vec{E} and \vec{B} had each a x – component. **Why ?**

Gauss law requires that

$$\vec{\nabla} \cdot \vec{E} = \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} = 0$$

\parallel

0

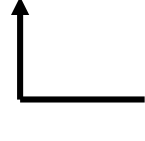
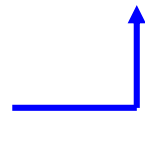
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0

E_x MUST be either constant or = 0



$$\vec{E} \perp \vec{B} \Rightarrow E_z = 0 \Rightarrow \frac{\partial E_z}{\partial z} = 0$$

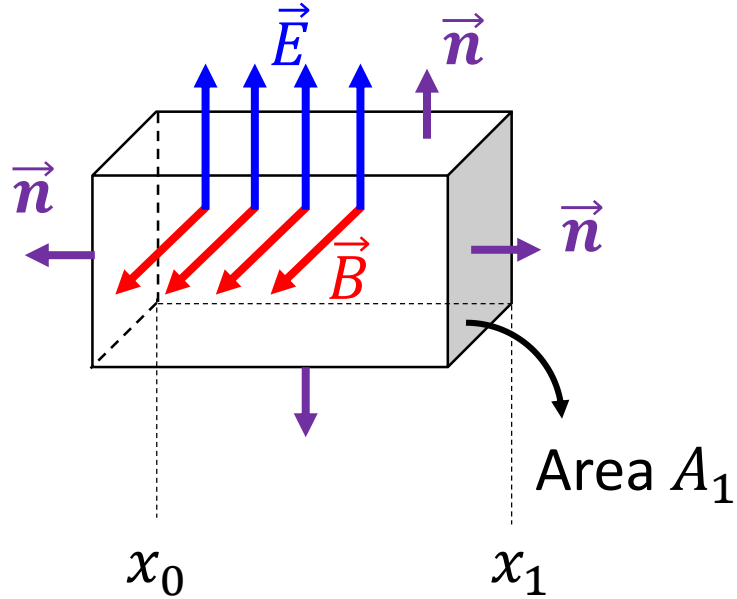
E_y MUST be constant
in the whole yz plane
 $\vec{E}(x, t) = E_y(x, t)\hat{j}$



See slide #32

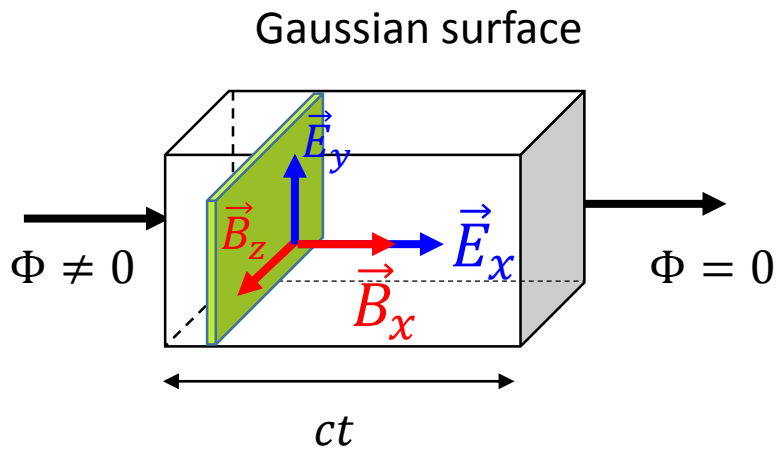
If E_x exists and because it must be constant \Rightarrow

$$\oint_A \vec{E} \cdot d\vec{A} = E_x(x_1)A_1 - E_x(x_0)A_1 = 0 \text{ (No charge enclosed)}$$

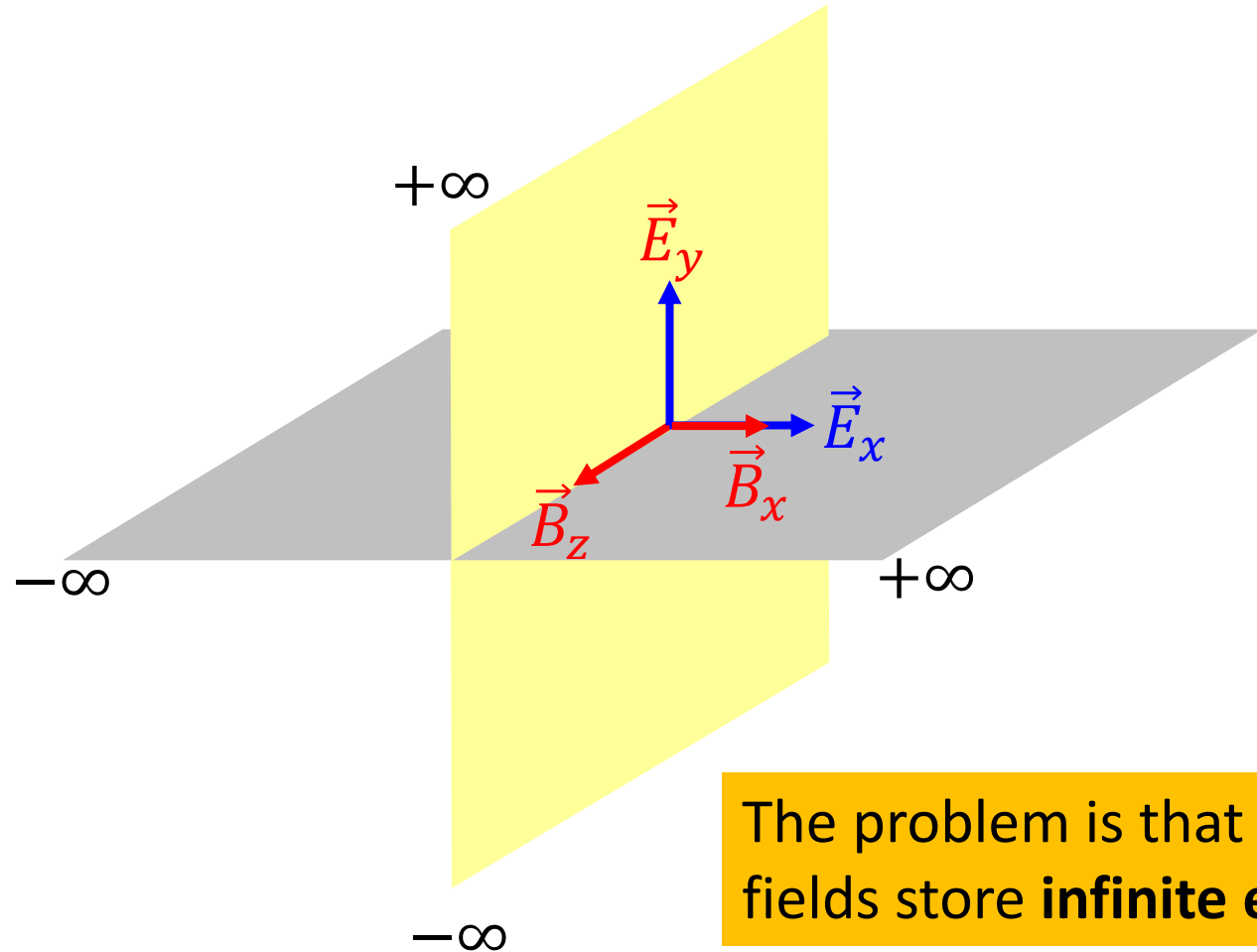


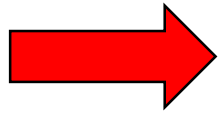
$$E_x(x_1) = E_x(x_0)$$

For all values of x_1 and x_0 !



Violation of Gauss law
Net flux $\neq 0$!
 No charge in the box



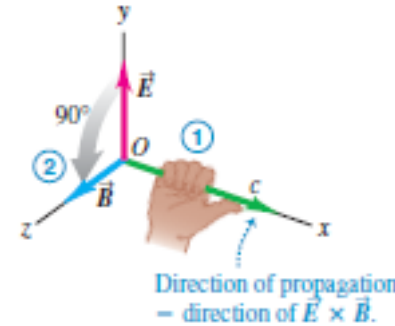


$$E_x = 0$$

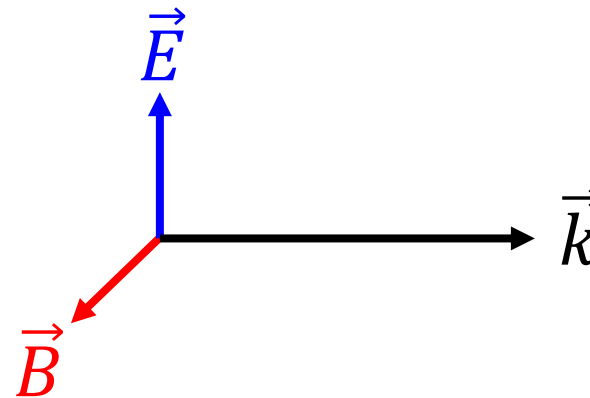
\vec{E} and \vec{B} MUST be perpendicular to each other
AND perpendicular to the direction of propagation

The same result holds for magnetic field

$$B_x = 0$$



EM waves are transverse

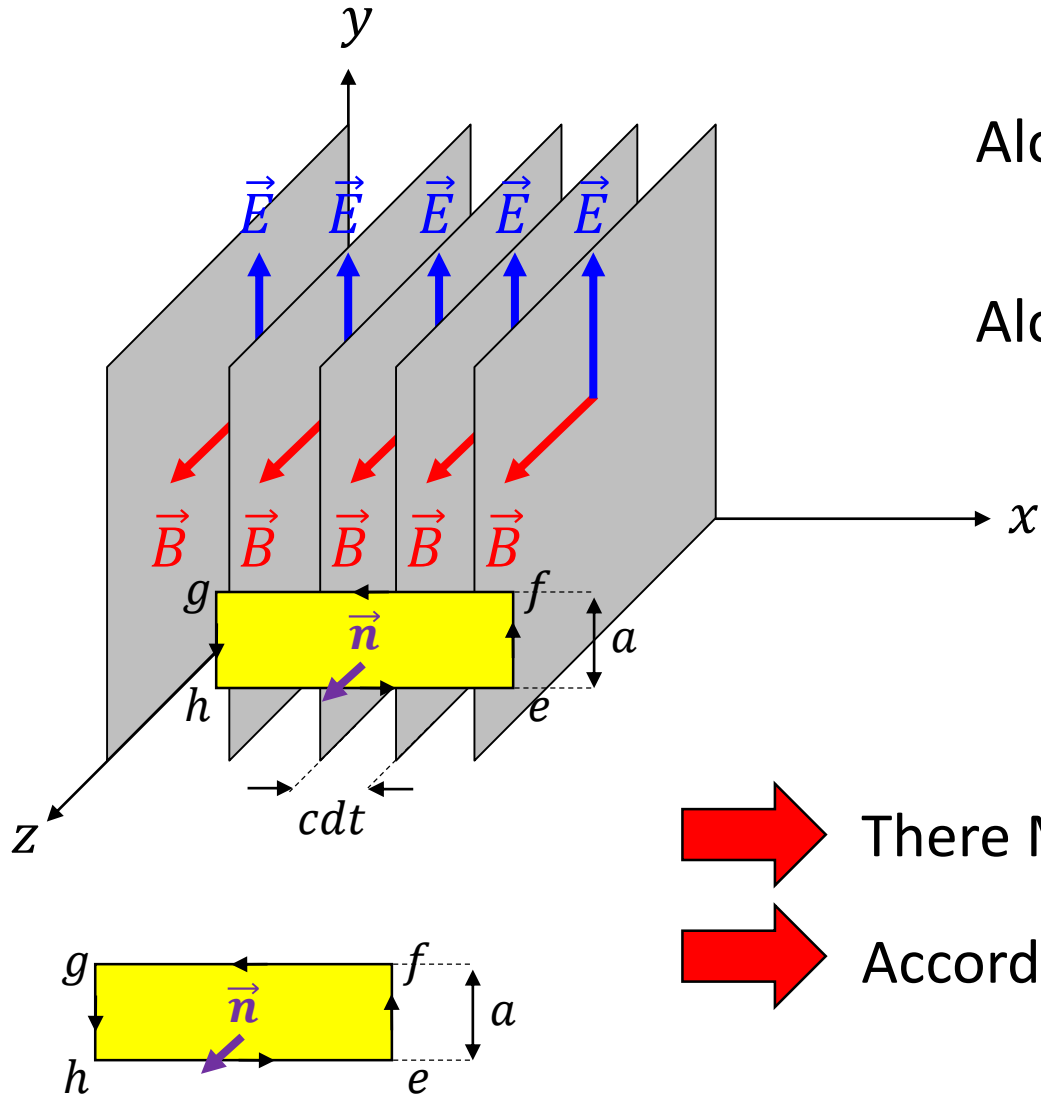


Direction of propagation

Other major properties of the fields \vec{E} and \vec{B}
resulting from Maxwell's equations

B) Faraday's law: circulation of the \vec{E} field

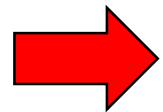
$$\oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$



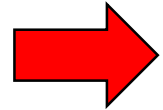
Along ef : the wave front still did not reach $\Rightarrow \int \vec{E} \cdot d\vec{l} = 0$

Along fg and he : $\vec{E} \perp d\vec{l} \Rightarrow \int \vec{E} \cdot d\vec{l} = 0$

$$\text{Along } gh: \int_g^h \vec{E} \cdot d\vec{l} = -Ea$$



There MUST be a magnetic flux Φ_B through the rectangle



According to right hand rule \vec{B} must be along +z axis and $\perp \vec{E}$

$$\oint \vec{E} \cdot d\vec{l} = -Ea = -\frac{d\Phi_B}{dt}$$

During time dt the front wave moves cdt

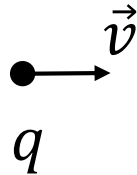
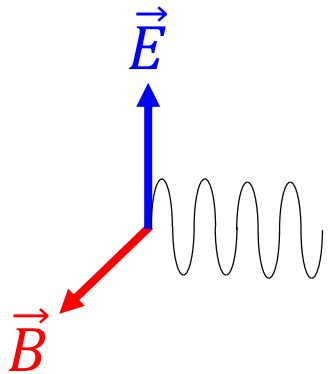
Area changes by $acdt$ $\rightarrow \frac{d\Phi_B}{dt} = Bac$

$$E = cB$$

Required by
Faraday's law

Consequence of $E = Bc$

Consider a free charge interacting with an electromagnetic wave



$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B}) \rightarrow \frac{F_B}{F_E} = \frac{vB}{E} = \frac{v}{c}$$

Unless the charge is relativistic $F_B \ll F_E$

In most situations electromagnetic waves are essentially an **electric phenomenon**

C) Ampere's law: circulation of the \vec{B} field (Maxwell's part)

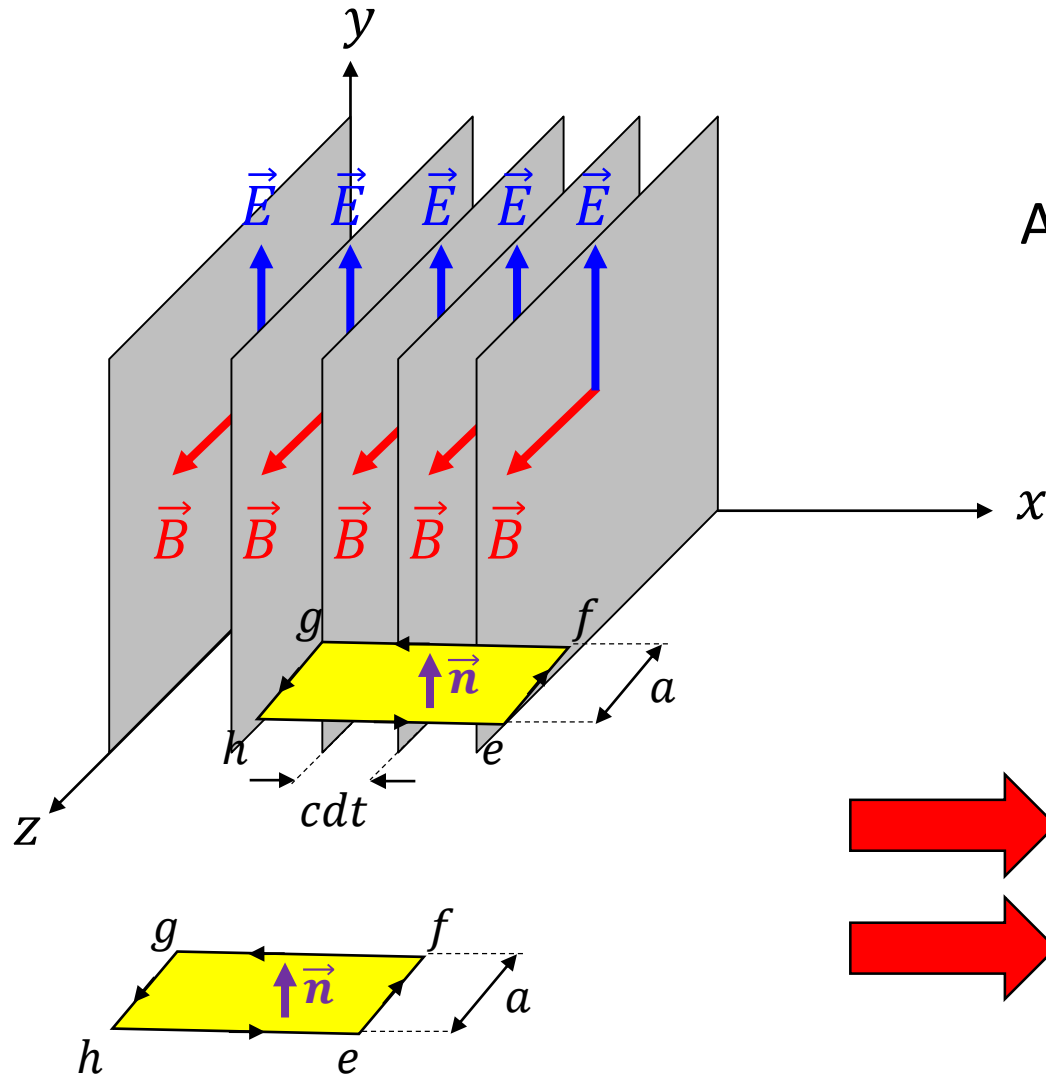
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$$

There is no current $\vec{J} = \vec{0}$

Along ef : the wave front still did not reach $\Rightarrow \int \vec{B} \cdot d\vec{l} = 0$

Along fg and he : $\vec{E} \perp d\vec{l} \Rightarrow \int \vec{B} \cdot d\vec{l} = 0$

$$\text{Along } gh: \int_g^h \vec{B} \cdot d\vec{l} = Ba$$



There MUST be a electric flux Φ_E through the rectangle



According to right hand rule \vec{E} must be along $+y$ axis

$$\oint \vec{B} \cdot d\vec{l} = Ba = \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$$

During time dt the front wave moves $c dt$

Area changes by $a c dt$ $\Rightarrow \frac{d\Phi_E}{dt} = E a c$

$$B = \mu_0 \epsilon_0 c E$$

Required by
Maxwell's law

Faraday's law

and

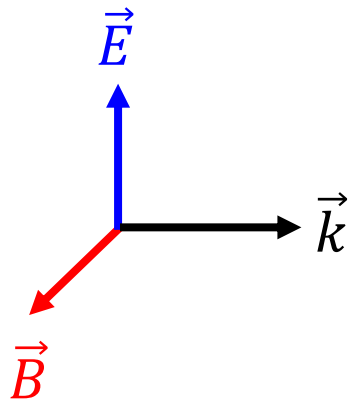
Maxwell's law

$$E = c B$$

$$B = \mu_0 \epsilon_0 c E$$

$$c = \frac{1}{\mu_0 \epsilon_0 c}$$

$$c \Rightarrow \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$



Direction of
propagation

$\vec{E}(x, t)$ **AND** $\vec{B}(x, t)$ **MUST** be in phase in space and time

- Unlike all the other types of waves, EM waves require **NO MEDIUM** through/along which to travel. **EM waves can travel through empty space (vacuum)!**
- Speed of light is independent of speed of observer! We could be heading toward a light beam at the speed of light, but we would still measure c as the speed of the beam!

$$c = 299\,792\,458 \text{ m/s}$$

Not intuitive at all !

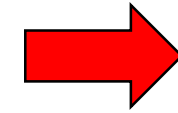
Summary

Time depended Maxwell's equations

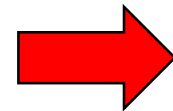
$$\begin{aligned}\vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \\ \vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \vec{\nabla} \cdot \vec{B} &= 0 \\ \vec{\nabla} \times \vec{B} &= \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}\end{aligned}$$

Charge conservation

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$



Concept of flow of charge



EM wave generation

$$m = (x, y, z) \quad \vec{u} = (\vec{i}, \vec{j}, \vec{k})$$

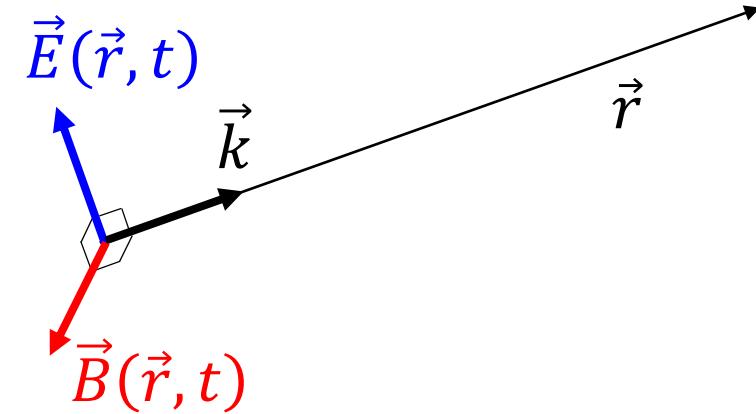
$$\left\{ \begin{aligned}\vec{E} &= \sum_1^3 E_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)} \\ \vec{B} &= \sum_1^3 B_{0m} \hat{u} e^{i(\vec{k} \cdot \vec{r} - \omega t)}\end{aligned}\right.$$

Solution not necessarily a ***sin wave***

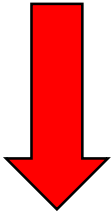
$$f(\vec{r}, t) = g(\vec{k} \cdot \vec{r} - \omega t) + h(\vec{k} \cdot \vec{r} - \omega t)$$

$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

$$\vec{k} \times \vec{E} = \omega \vec{B}$$

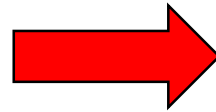


Transverse waves



$$B = \frac{E}{c}$$

$$B = \mu_0 \epsilon_0 c E$$



$$\frac{1}{\epsilon_0 \mu_0} = c^2$$

With these we are now ready to obtain the wave equations !

Dimension equation

$$\vec{k} \times \vec{E} \quad \vec{B} + \vec{k} \perp \vec{E} \quad \longrightarrow \quad [kE] = \frac{VL^{-1}}{L} = VL^{-2}$$

$$[B] = \left[\frac{E}{v} \right] = \frac{VL^{-1}}{LT^{-1}} = (VL^{-2})/T^{-1}$$

$$[B] = [kE] / T^{-1}$$

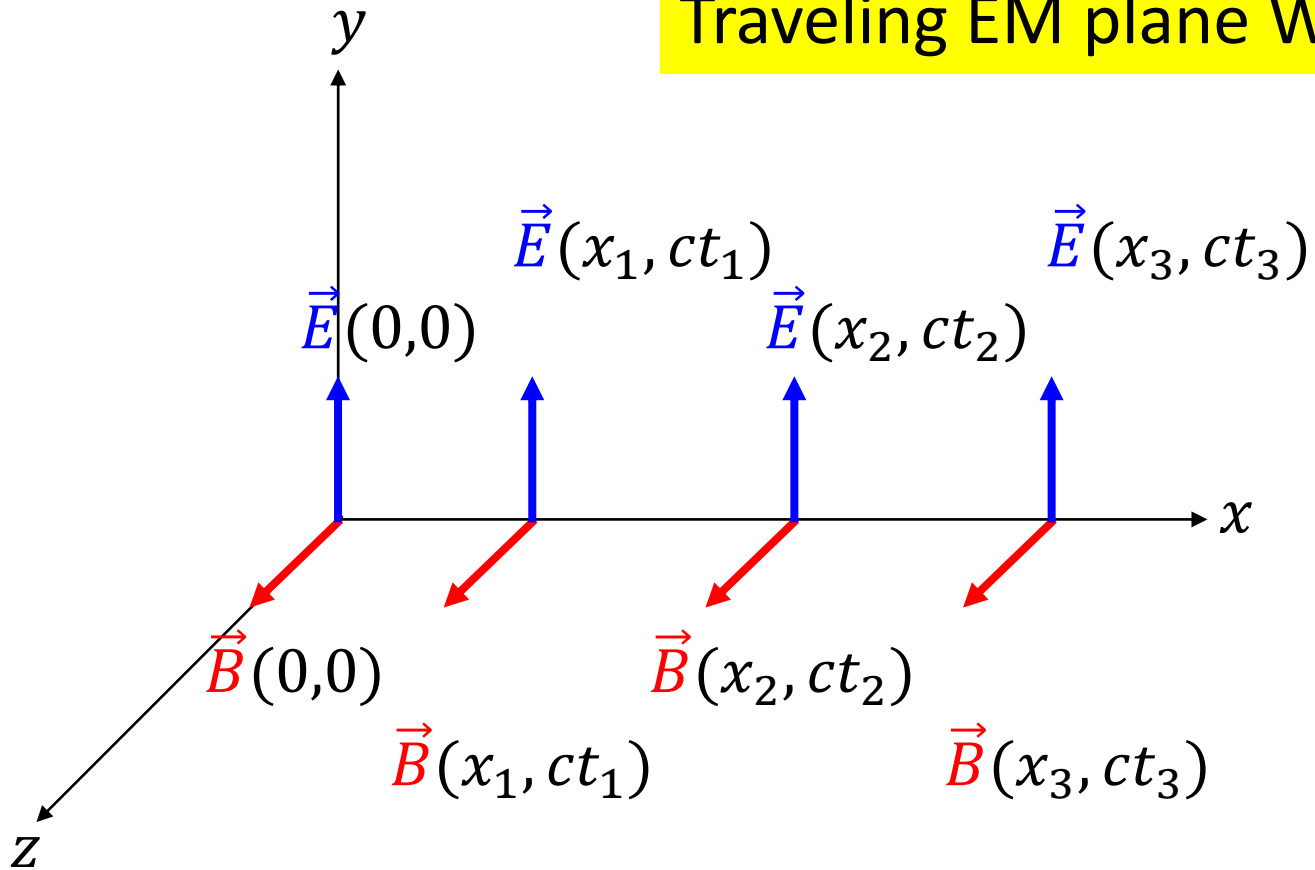
$$\vec{k} \times \vec{E} = \omega \vec{B}$$

$$[kB] = [k^2 E] / T^{-1} = \frac{VL^{-1}}{L^2 T^{-1}} = \frac{T^{-1}}{(LT^{-1})^2} [E]$$

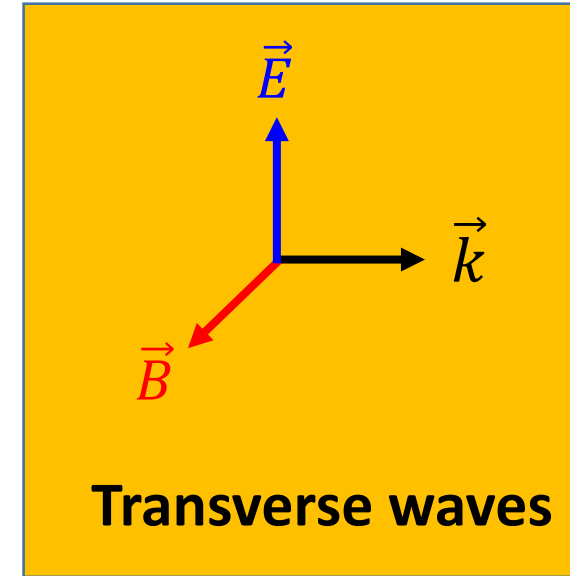
— Sign comes from the right hand rule

$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

Traveling EM plane Wave equation



Field amplitudes are **constant** in the same plane
BUT
may **change** from plane to plane



$$\vec{E}(x, t) = E_y(x, t)\hat{j}$$

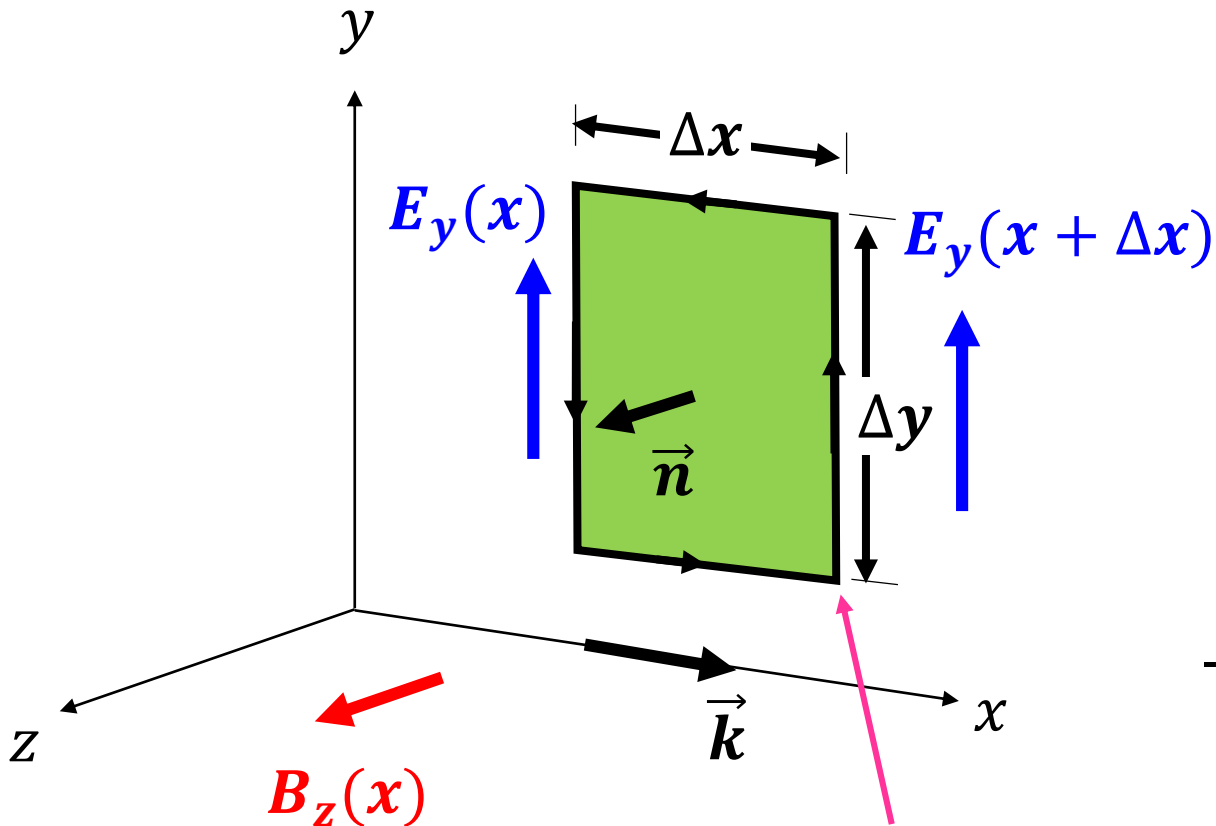
$$\vec{B}(x, t) = B_z(x, t)\hat{k}$$

WAVE EQUATIONS

...From integral forms of Maxwell's equation...

Faraday's law: circulation of the \vec{E} field

Stokes' vs Gauss's theorem



We start here ($x + \Delta x$) and go counterclockwise

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{l} = E_y(x + \Delta x)\Delta y - E_y(x)\Delta y$$

$$E_y(x + \Delta x) = E_y(x) + \frac{\partial E_y}{\partial x} \Delta x + \dots$$

$$\oint \vec{E} \cdot d\vec{l} = \frac{\partial E_y}{\partial x} \Delta x \Delta y$$

$$-\frac{d}{dt} \iint \vec{B} \cdot d\vec{A} = -\frac{\partial B_z}{\partial t} \Delta x \Delta y$$

$$\frac{\partial E_y}{\partial x} = -\frac{\partial B_z}{\partial t}$$

Ampere's law: circulation of the \vec{B} field (Maxwell's part)

Again Stokes' vs Gauss's theorem

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d}{dt} \iint \vec{E} \cdot d\vec{A}$$

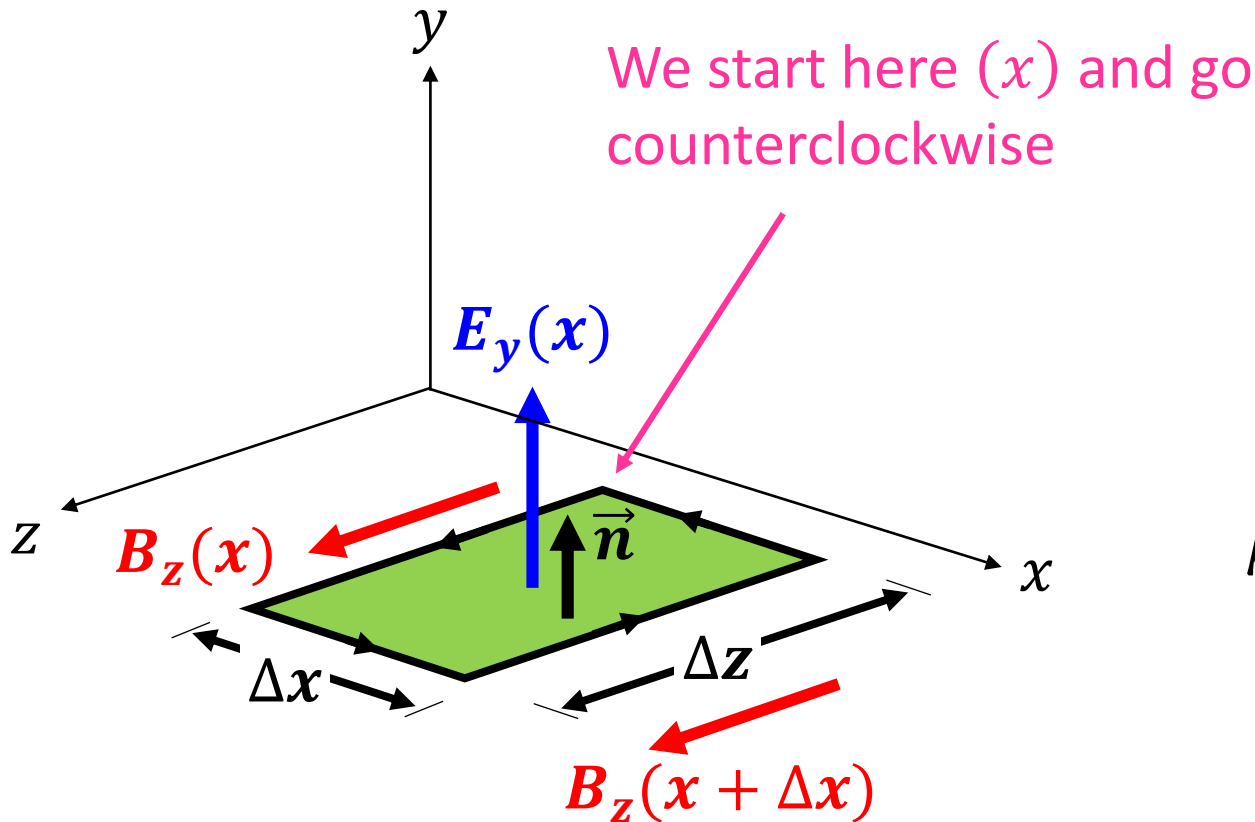
$$\oint \vec{B} \cdot d\vec{l} = B_z(x) \Delta z - B_z(x + \Delta x) \Delta z$$

$$B_z(x + \Delta x) = B_z(x) + \frac{\partial B_z}{\partial x} \Delta x + \dots$$

$$\oint \vec{B} \cdot d\vec{l} = -\frac{\partial B_z}{\partial x} \Delta x \Delta z$$

$$\mu_0 \epsilon_0 \frac{d}{dt} \iint \vec{E} \cdot d\vec{A} = \mu_0 \epsilon_0 \frac{\partial E_y}{\partial t} \Delta x \Delta y$$

$$-\frac{\partial B_z}{\partial x} = \mu_0 \epsilon_0 \frac{\partial E_y}{\partial t}$$



Plane traveling EM Wave equation

$$\frac{\partial E_y}{\partial x} = -\frac{\partial B_z}{\partial t}$$

$$\frac{\partial^2 E_y}{\partial x^2} = -\frac{\partial}{\partial x} \left(\frac{\partial B_z}{\partial t} \right) = -\frac{\partial}{\partial t} \left(\frac{\partial B_z}{\partial x} \right)$$

$$\frac{\partial}{\partial t} \left(\frac{\partial E_y}{\partial x} \right) = -\frac{\partial^2 B_z}{\partial t^2}$$

$$\frac{\partial^2 E_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_y}{\partial t^2}$$

$$\mu_0 \epsilon_0 = \frac{1}{c^2}$$

$$-\frac{\partial B_z}{\partial x} = \mu_0 \epsilon_0 \frac{\partial E_y}{\partial t}$$

$$-\frac{\partial^2 B_z}{\partial x^2} = \mu_0 \epsilon_0 \frac{\partial}{\partial x} \left(\frac{\partial E_y}{\partial t} \right) = \mu_0 \epsilon_0 \frac{\partial}{\partial t} \left(\frac{\partial E_y}{\partial x} \right)$$

$$-\frac{\partial}{\partial t} \left(\frac{\partial B_z}{\partial x} \right) = \mu_0 \epsilon_0 \frac{\partial^2 E_y}{\partial t^2}$$

$$\frac{\partial^2 B_z}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2}$$


Compare these wave equations to a mechanical wave equation

Electromagnetic wave

$$\frac{\partial^2 E_y}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 E_y}{\partial t^2}$$

$$\frac{\partial^2 B_z}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 B_z}{\partial t^2}$$



$$E = E_y(x, t)$$


$$\vec{E} = \vec{E}_y(\vec{r}, t)$$

Mechanical wave

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$$


$$B = B_z(x, t)$$


$$\vec{B} = \vec{B}_z(\vec{r}, t)$$

For more complex waves



Superposition principle applies

Superposing many waves



Superposing many \vec{E}' 's and \vec{B}' 's

$$\vec{E} = \sum \vec{E}'_s \quad \vec{B} = \sum \vec{B}'_s$$

Remark:

- The wave equation is dispersionless. Thus any function of the form $f(\vec{k} \cdot \vec{r} - \omega t)$ satisfies the equation provided Maxwell's constraints apply (**cross products between \vec{k} , \vec{E} and \vec{B}**)

$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E} \quad \text{and} \quad \vec{k} \times \vec{E} = \omega \vec{B}$$

- \vec{E} and \vec{B} waves do not have to be sinusoidal. As the wave equation is linear the solution could be any linear combination of sinusoidal function by Fourier transform

Energy and momentum in electromagnetic waves

The Poynting vector \vec{S}

We already know that both \vec{E} and \vec{B} fields carry energy

Waves contain energy

- Microwave ovens
- Radio transmitters
- Laser for eye surgery
- Etc...



From electro and magnetostatic

u = Total energy density

$$u = \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2\mu_0} B^2$$

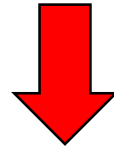
$$B = \mu_0 \epsilon_0 c E$$

Slide #44

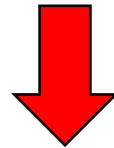
The energy density due to \vec{E} is equal to the energy density due to \vec{B} field

$$u = \epsilon_0 E^2 = \frac{B^2}{\mu_0}$$

As both \vec{E} and \vec{B} fields vary in space and time, \mathbf{u} also depends on space and time



Concept of flow of energy and momentum \equiv flow of charges \equiv flow of heat



Poynting vector and Poynting theorem

Electromagnetic energy flow and the Poynting vector

Energy transferred / unit time / unit area = power transferred / unit area

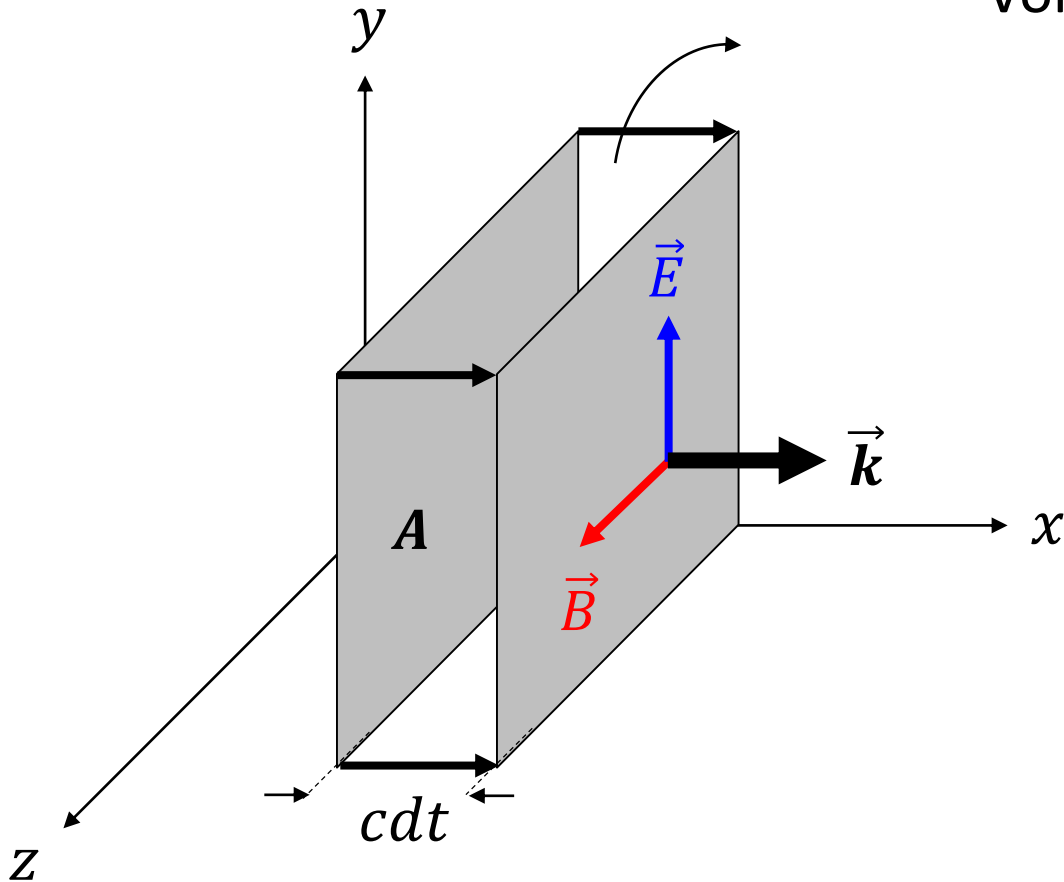
$$\text{Volume } dV = Acdt$$

The energy contained in this volume after the wave has traveled the distance cdt

$$dW = u dV = (\epsilon_0 E^2)(Acdt)$$

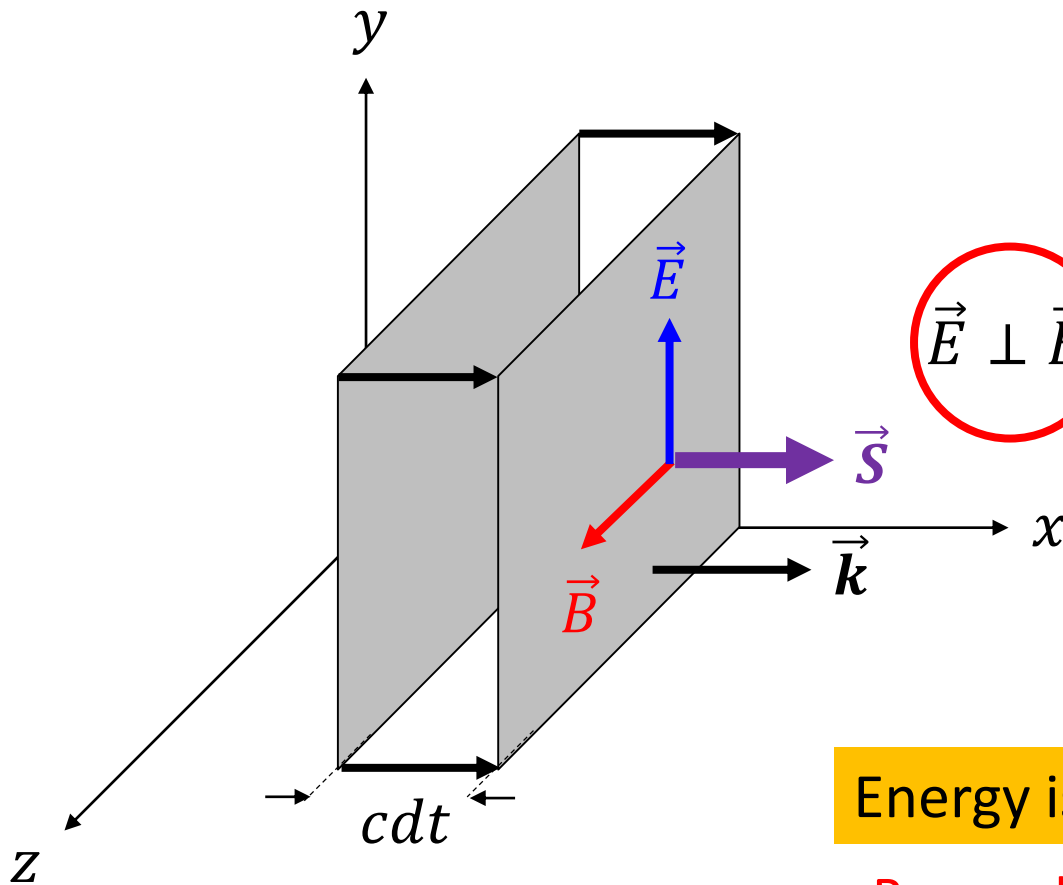
Energy flow / unit area / unit time
or power transferred / unit area

$$S = \frac{1}{A} \frac{dW}{dt} = \epsilon_0 c E^2$$



Concept of flow of energy

$$S = \frac{1}{A} \frac{dW}{dt} = \epsilon_0 c E^2 = \epsilon_0 (cE) E = \epsilon_0 (c\mathbf{E}) c \frac{\mathbf{E}}{c} = \epsilon_0 (c\mathbf{E}) c \mathbf{B} = \epsilon_0 c^2 \mathbf{E} \mathbf{B}$$

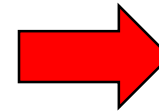


CROSS PRODUCT

$$\vec{E} \perp \vec{B}$$

and

$$\epsilon_0 c^2 = \frac{1}{\mu_0}$$



$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

Universal character

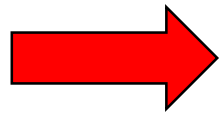
Poynting vector

Energy is **SCALAR BUT** the **FLOW** of energy is a **VECTOR**

Remember! Heat is a scalar BUT the flow of heat is a vector

$$\vec{S}(x, t) = \frac{1}{\mu_0} \vec{E}(x, t) \times \vec{B}(x, t) = \frac{1}{\mu_0} [\hat{j} E_{max} \cos(kx - \omega t)] \times [\hat{k} B_{max} \cos(kx - \omega t)]$$

$$S_x(x, t) = \frac{E_{max} B_{max}}{\mu_0} \cos^2(kx - \omega t) = \frac{E_{max} B_{max}}{2\mu_0} [1 + \cos 2(kx - \omega t)]$$



$$\vec{S}_{av} = S_{av} \vec{l}$$

$$S_{av} = \frac{E_{max} B_{max}}{2\mu_0}$$

This expresses the intensity of sinusoidal EM wave in vacuum

$$I = S_{av} = \frac{1}{2} \epsilon_0 c E_{max}^2$$

Question: The Poynting vector **does** vary with time. Why our eyes do not see this variation when hit by light coming from a bulb?

Answer: Because the oscillation frequency is too high ! $5 \times 10^{14} \text{ Hz}$

What about waves propagating in a dielectric?

Vacuum

$$u = \frac{1}{2} \epsilon_0 E^2 + \frac{1}{2\mu_0} B^2 = u_E + u_B$$

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

$$I = S_{av} = \frac{1}{2} \epsilon_0 c E_{max}^2$$

Dielectric (linear homogeneous isotropic)

$$\epsilon_0 \rightarrow \epsilon = \epsilon_0 \epsilon_r$$

$$\mu_0 \rightarrow \mu = \mu_0 \mu_r$$

$$c \rightarrow v = \frac{1}{\sqrt{\epsilon\mu}} \quad E = vB \quad B = \epsilon\mu vE$$

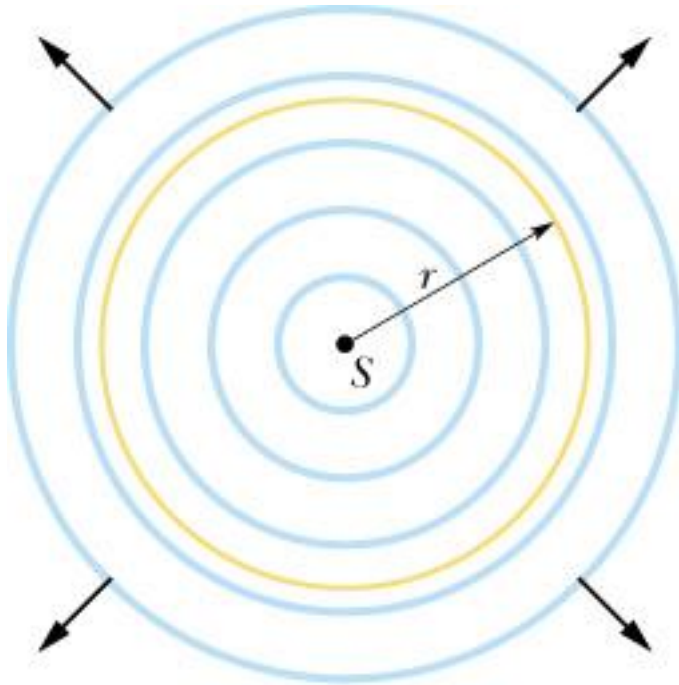
In vacuum $u_E^0 = u_B^0$



In Dielectric $u_E^D = u_B^D$

Question: How does the intensity (power/area) change with distance r ?

Consider a point source S that is emitting EM waves isotropically (equally in all directions) at a rate P_S . Assume energy of waves is conserved as they spread from source.



$$I = \frac{\text{Power}}{\text{Area}} = \frac{P_S}{4\pi r^2}$$

Ex: $E_0 = 100\text{V/m}$
(visible light)

$$\langle \vec{S} \rangle = 13\text{W/m}^2$$

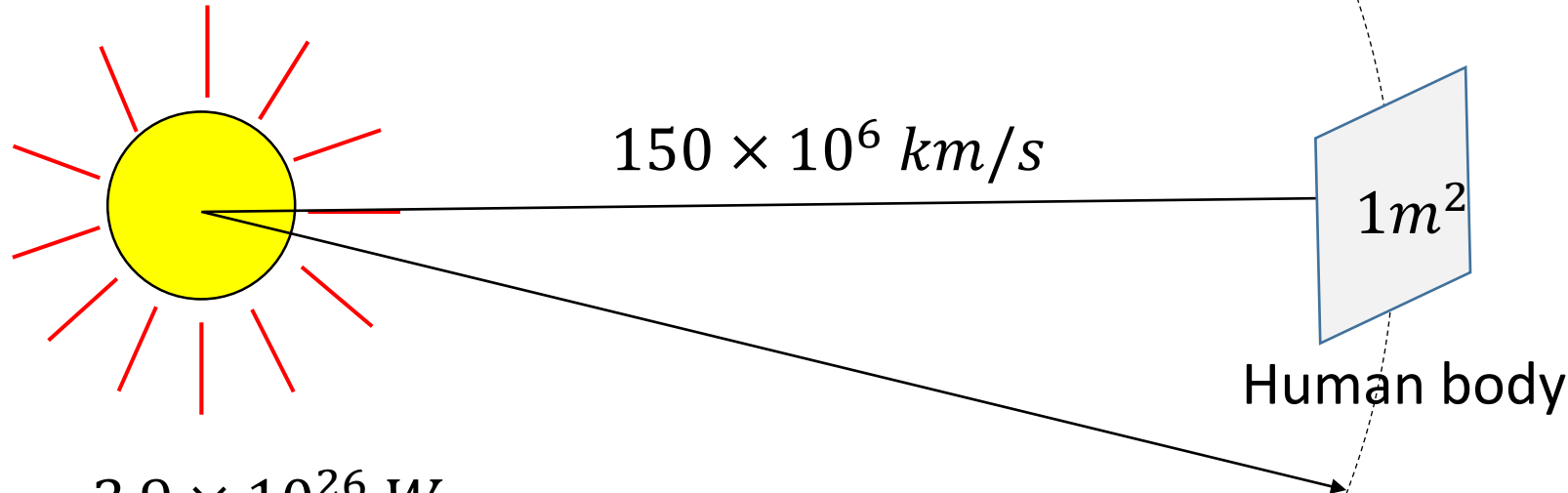


This is not harmful

Ex: $E_0 = 1000V/m$

$$\langle |\vec{S}| \rangle = 1.3kW/m^2$$

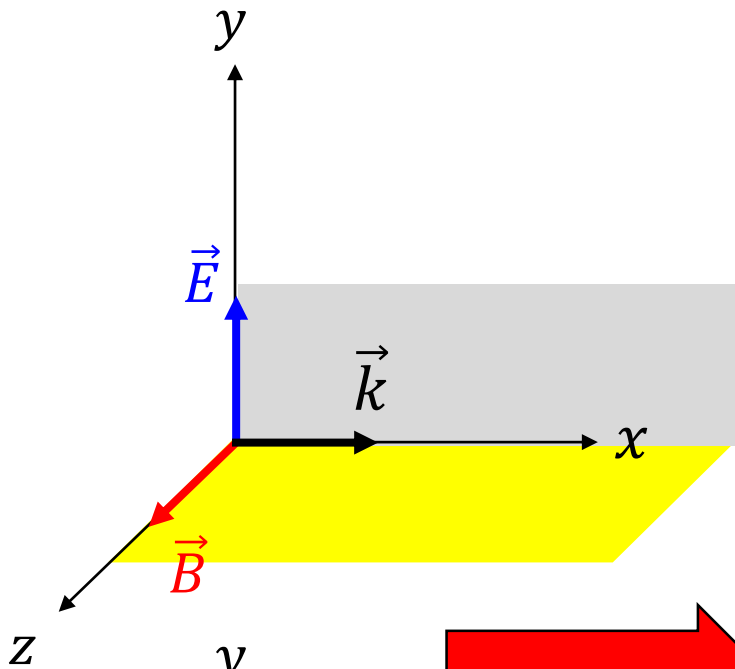
$$\langle |\vec{S}| \rangle = \frac{3.9 \times 10^{26}W}{(150 \times 10^9)^2 m^2}$$



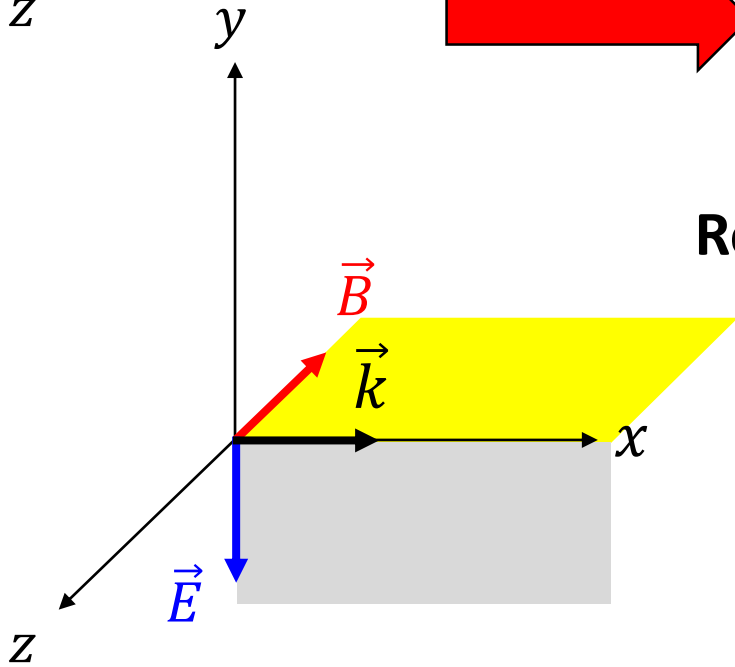
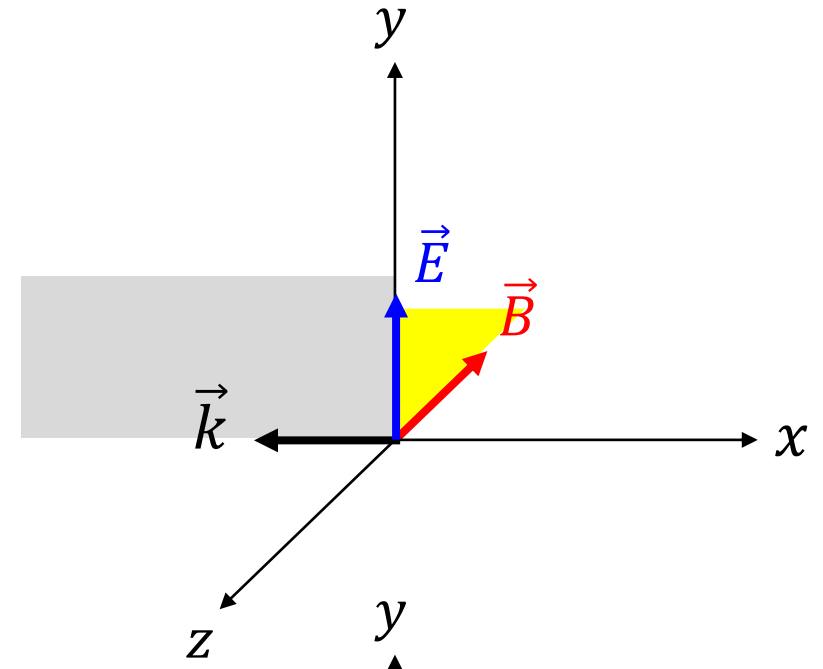
$$\langle |\vec{S}| \rangle = 1.4kW/m^2$$

Exposing to sun rays could be very dangerous

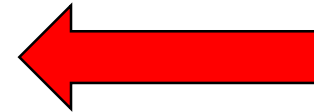
Propagation, Polarization and incidence of EM waves on matter: conductor vs dielectric



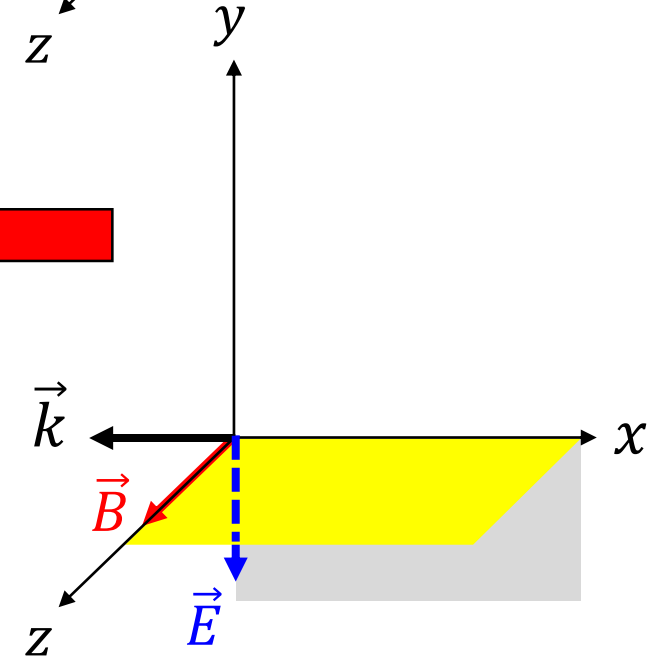
$$\begin{aligned}\vec{k} \cdot \vec{E} &= 0 & \vec{k} \times \vec{E} &= \omega \vec{B} \\ \vec{k} \cdot \vec{B} &= 0 & \vec{k} \times \vec{B} &= -\frac{\omega}{c^2} \vec{E}\end{aligned}$$



Two opposite directions
of propagation
Rotation = π around the y -axis

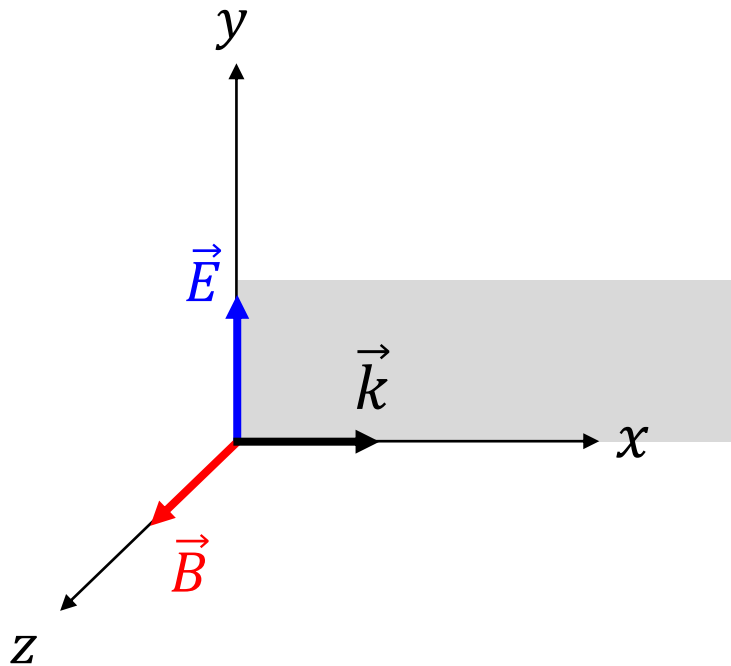


In all four cases \vec{E} is vertical



Definition of polarization

The direction of the linear polarization = The axis along which the \vec{E} field points



The polarization plane is defined by the two vectors

\vec{E} and \vec{k}

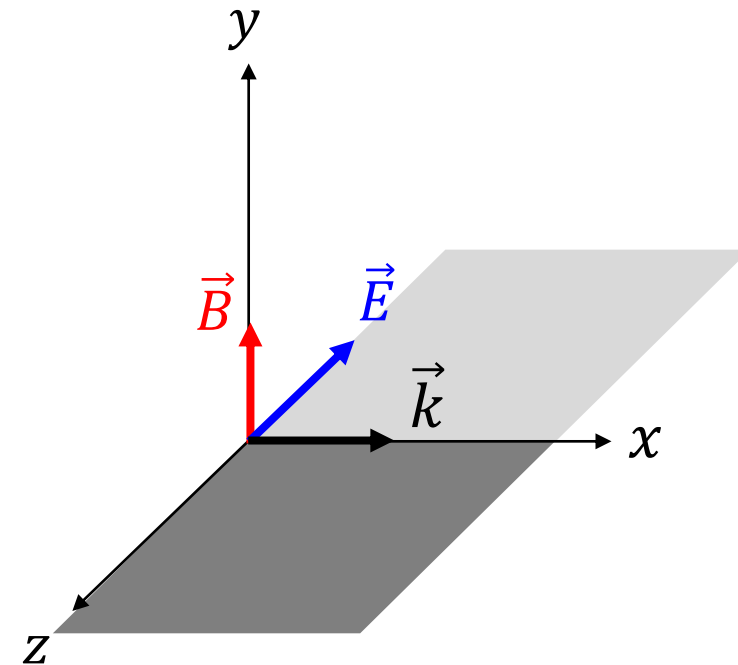
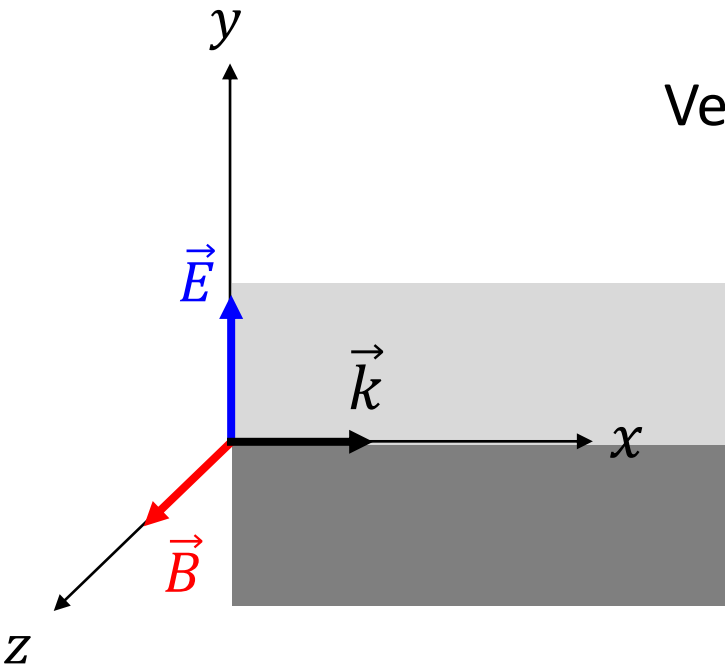
This is a linear vertical polarization

Two particular types of linear polarization

Vertical

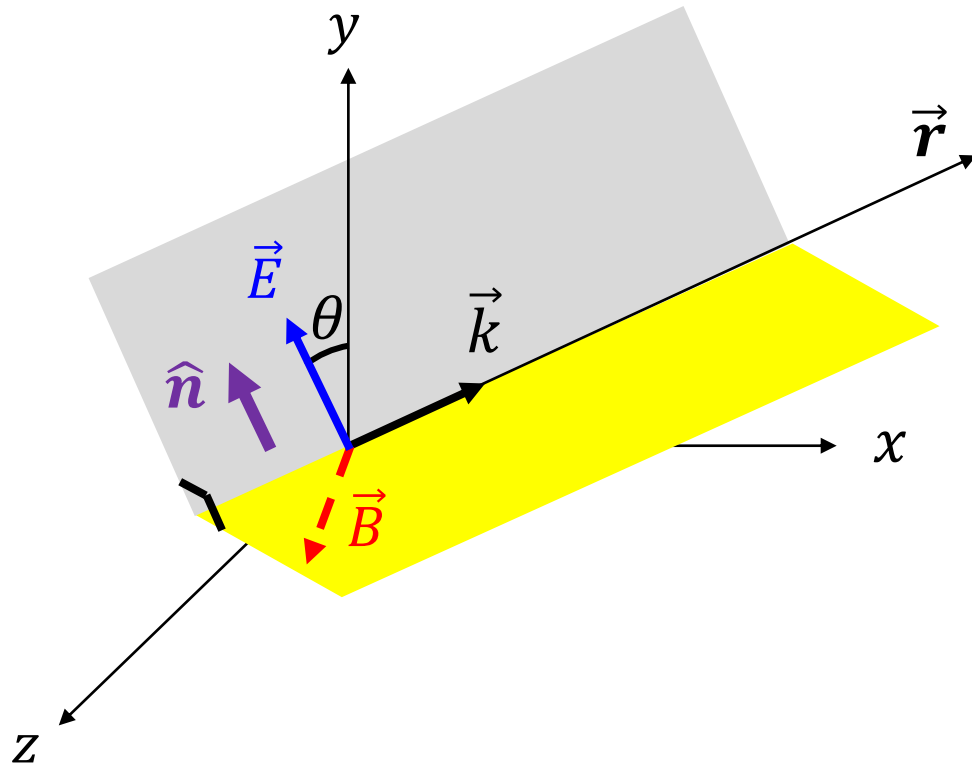
Horizontal

Propagation along x -axis
Rotation = $\pi/2$ around the x -axis



Two distinct and \perp planes of \vec{E} vibration

Polarization along any arbitrary direction



$$\hat{\mathbf{n}} \cdot \vec{\mathbf{k}} = 0$$

and

$$\vec{\mathbf{k}} \cdot \vec{\mathbf{E}} = 0$$

$\hat{\mathbf{n}}$ and $\vec{\mathbf{k}}$ define the plane of vibration of $\vec{\mathbf{E}}$

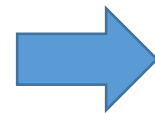
$$\hat{\mathbf{n}} = \cos\theta \hat{\mathbf{j}} + \sin\theta \hat{\mathbf{k}}$$



$$\vec{\mathbf{E}}(\vec{\mathbf{r}}, t) = E_0 e^{i(\vec{\mathbf{k}} \cdot \vec{\mathbf{r}} - \omega t)} \hat{\mathbf{n}}$$

$$\vec{\mathbf{B}}(\vec{\mathbf{r}}, t) = B_0 e^{i(\vec{\mathbf{k}} \cdot \vec{\mathbf{r}} - \omega t)} (\vec{\mathbf{k}} \times \hat{\mathbf{n}})$$

$$\mathbf{E} = c\mathbf{B}$$



$$\vec{\mathbf{B}}(\vec{\mathbf{r}}, t) = \frac{E_0}{c} e^{i(\vec{\mathbf{k}} \cdot \vec{\mathbf{r}} - \omega t)} (\vec{\mathbf{k}} \times \hat{\mathbf{n}}) = \frac{1}{c} \vec{\mathbf{k}} \times \vec{\mathbf{E}}$$

\vec{E} field along any direction in the xy – plane

$\vec{E} \perp \vec{B} \Rightarrow$ and both fields have two components.

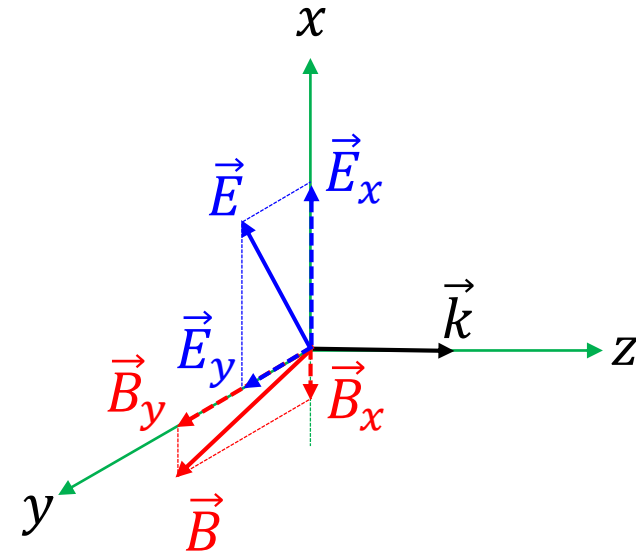
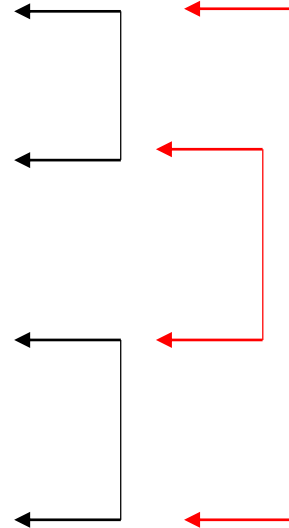
Linear combination: $\vec{E} = E_x \hat{i} + E_y \hat{j}$ and $\vec{B} = B_x \hat{i} + B_y \hat{j}$ is also a solution of Maxwell's equation

$$\vec{E}_x = E_{0x} \cos(\omega t - kz) \hat{i}$$

$$\vec{E}_y = E_{0y} \cos(\omega t - kz + \delta) \hat{j}$$

$$\vec{B}_x = -\frac{1}{c} E_{0x} \cos(\omega t - kz + \delta) \hat{i}$$

$$\vec{B}_y = \frac{1}{c} E_{0y} \cos(\omega t - kz) \hat{j}$$



$(\vec{E}_x$ and $\vec{B}_y)$ or $(\vec{E}_y$ and $\vec{B}_x)$ fields are in phase

The two components of the **SAME** field are not necessarily in phase

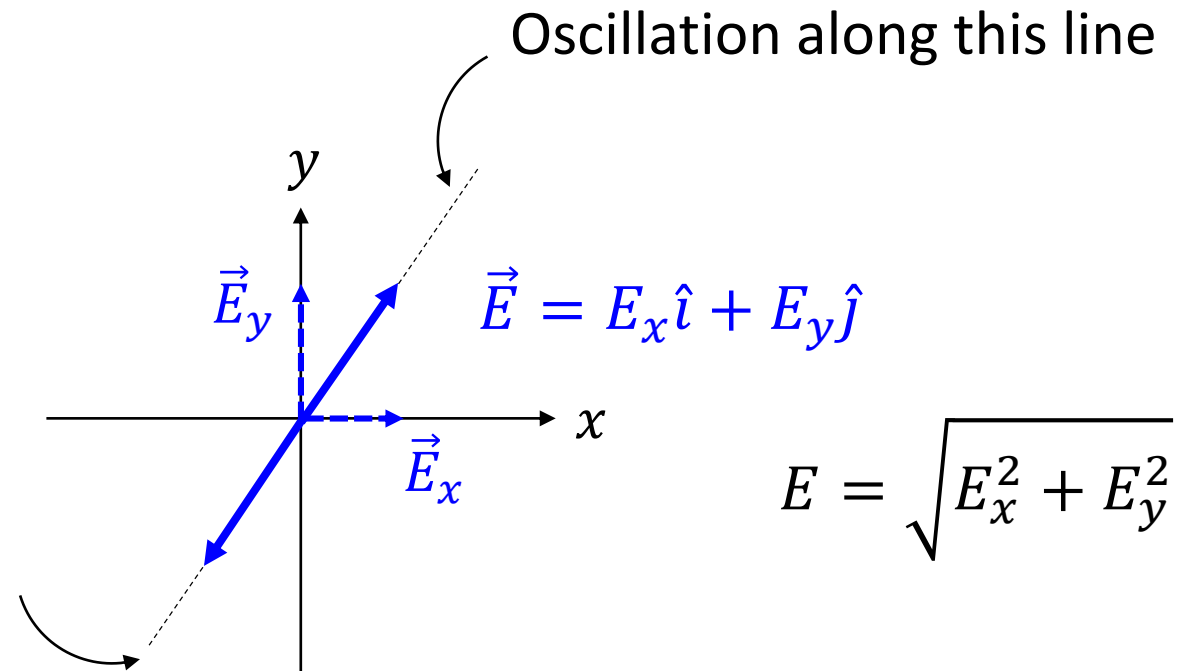
$(\vec{E}_x$ and $\vec{E}_y)$ or $(\vec{B}_x$ and $\vec{B}_y)$

Special case #1

$x - y$ plane

$\delta = 0$ no dephasing between \vec{E}_x and \vec{E}_y
both reach max and min at the same time

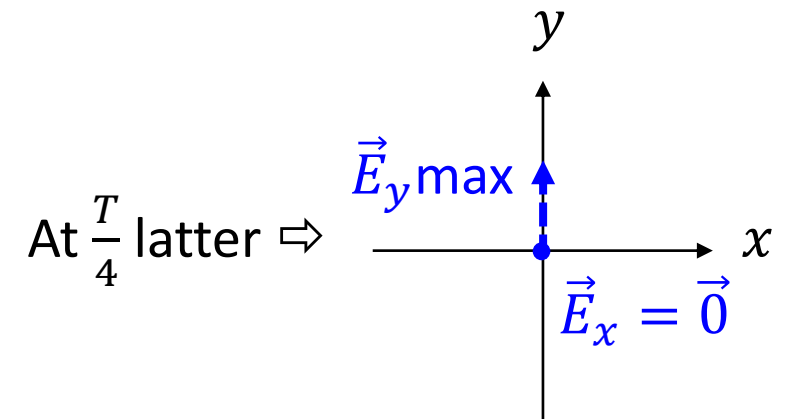
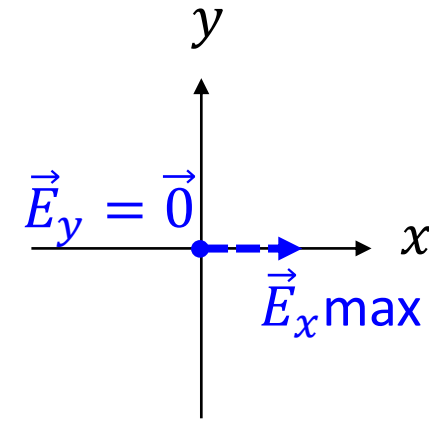
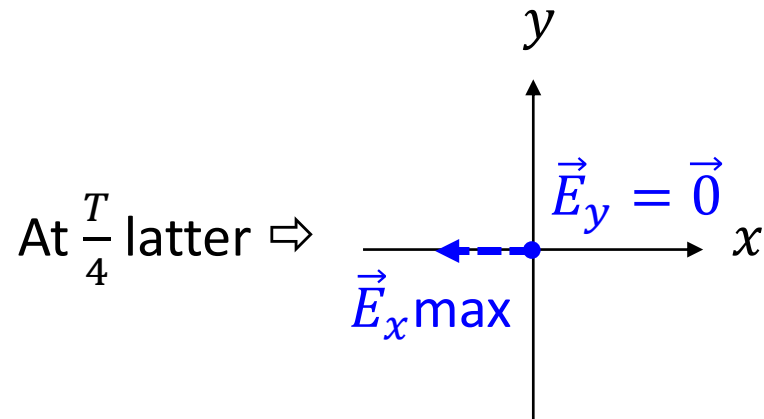
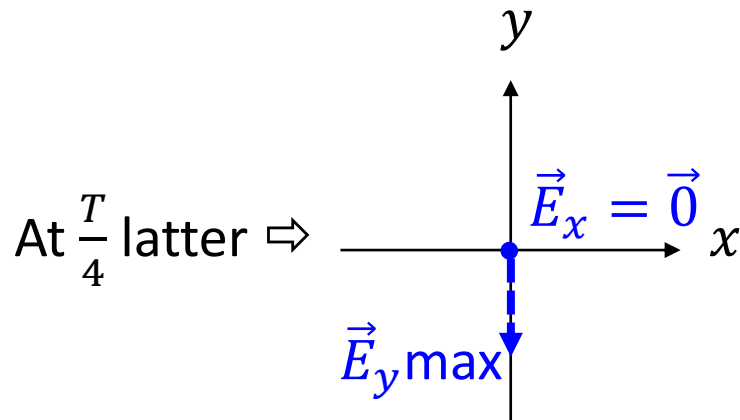
\vec{E} is linearly polarized in the this direction



Special case #2

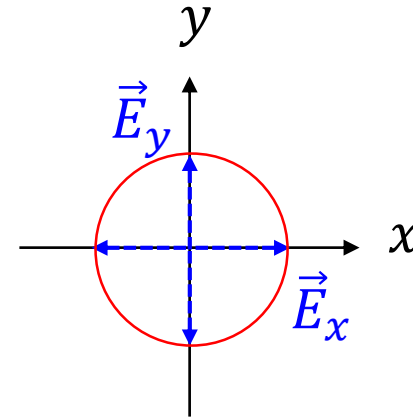
$\delta = \frac{\pi}{2}$ quadrature of phase between \vec{E}_x and \vec{E}_y

When \vec{E}_x is max, \vec{E}_y is zero and vice versa



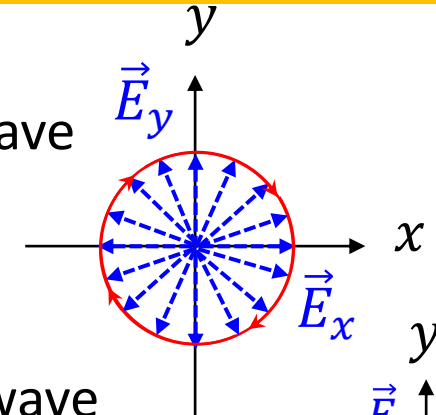
$$\vec{E} = E_{0x} \cos(\omega t - kz) \hat{i} + E_{0y} \cos\left(\omega t - kz + \frac{\pi}{2}\right) \hat{j}$$

$$\vec{B} = -B_{0x} \cos\left(\omega t - kz + \frac{\pi}{2}\right) \hat{i} + B_{0y} \cos(\omega t - kz) \hat{j}$$

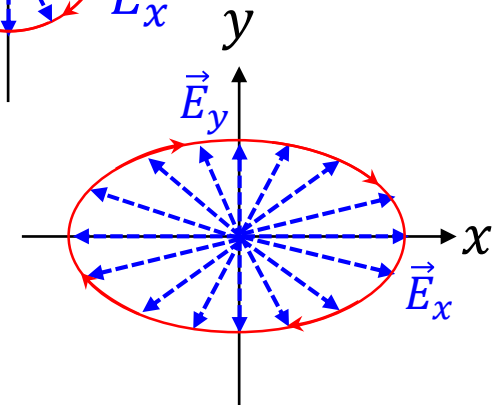


Although \vec{E}_x or \vec{E}_y may be zero at any moment, they are never zero at the same time: \vec{E} is never zero

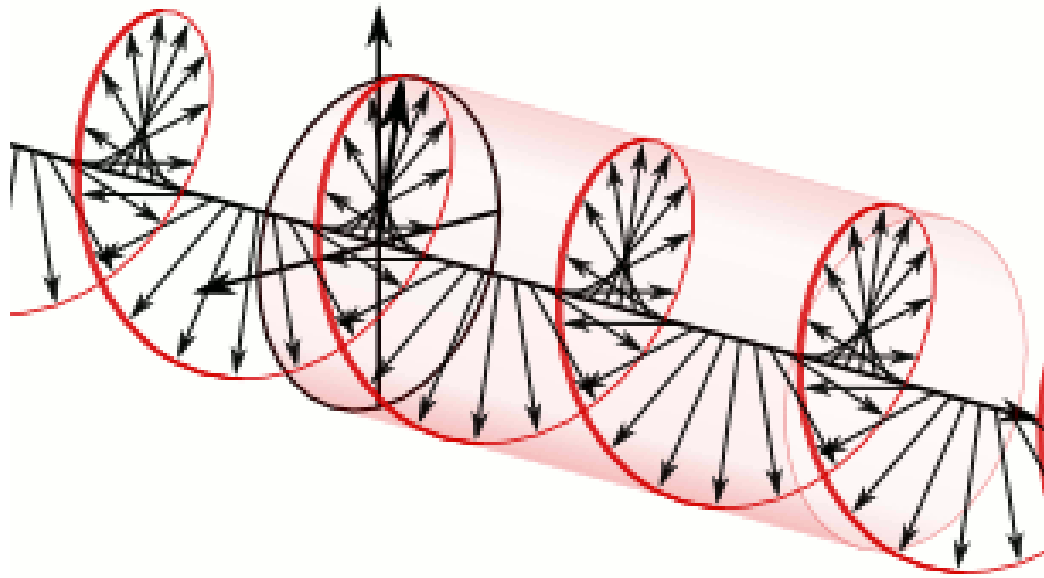
$E_{0x} = E_{0y}$ and $B_{0x} = B_{0y}$  Clockwise circularly polarized EM wave



$E_{0x} \neq E_{0y}$ and $B_{0x} \neq B_{0y}$  Clockwise elliptically polarized EM wave

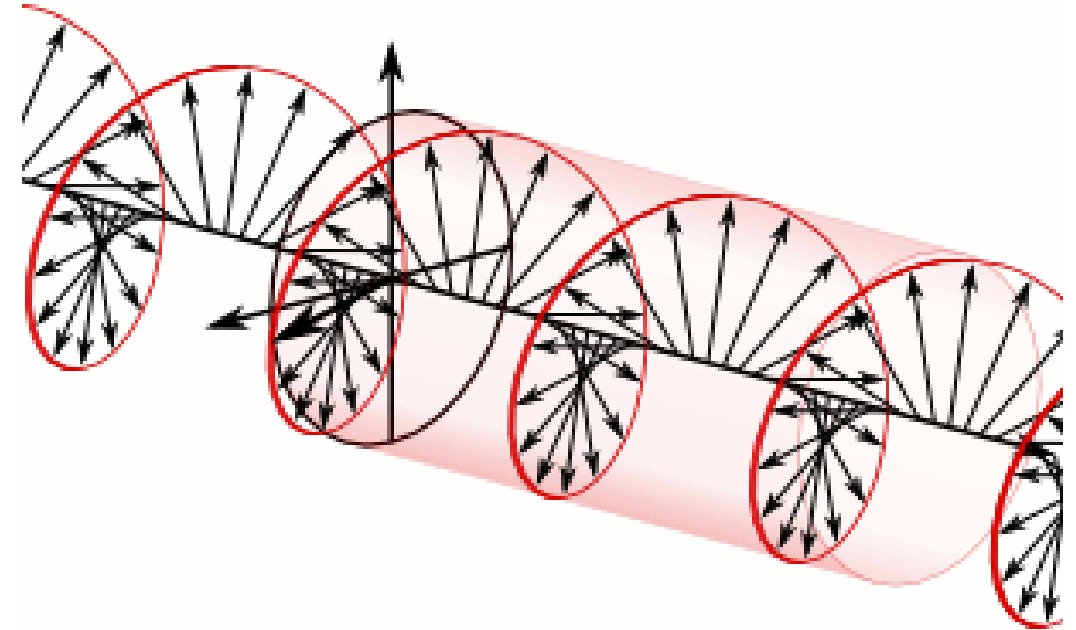


$\delta = -\frac{\pi}{2}$  Polarization counterclockwise



From the source: left-handed / anti-clockwise circularly polarized wave.

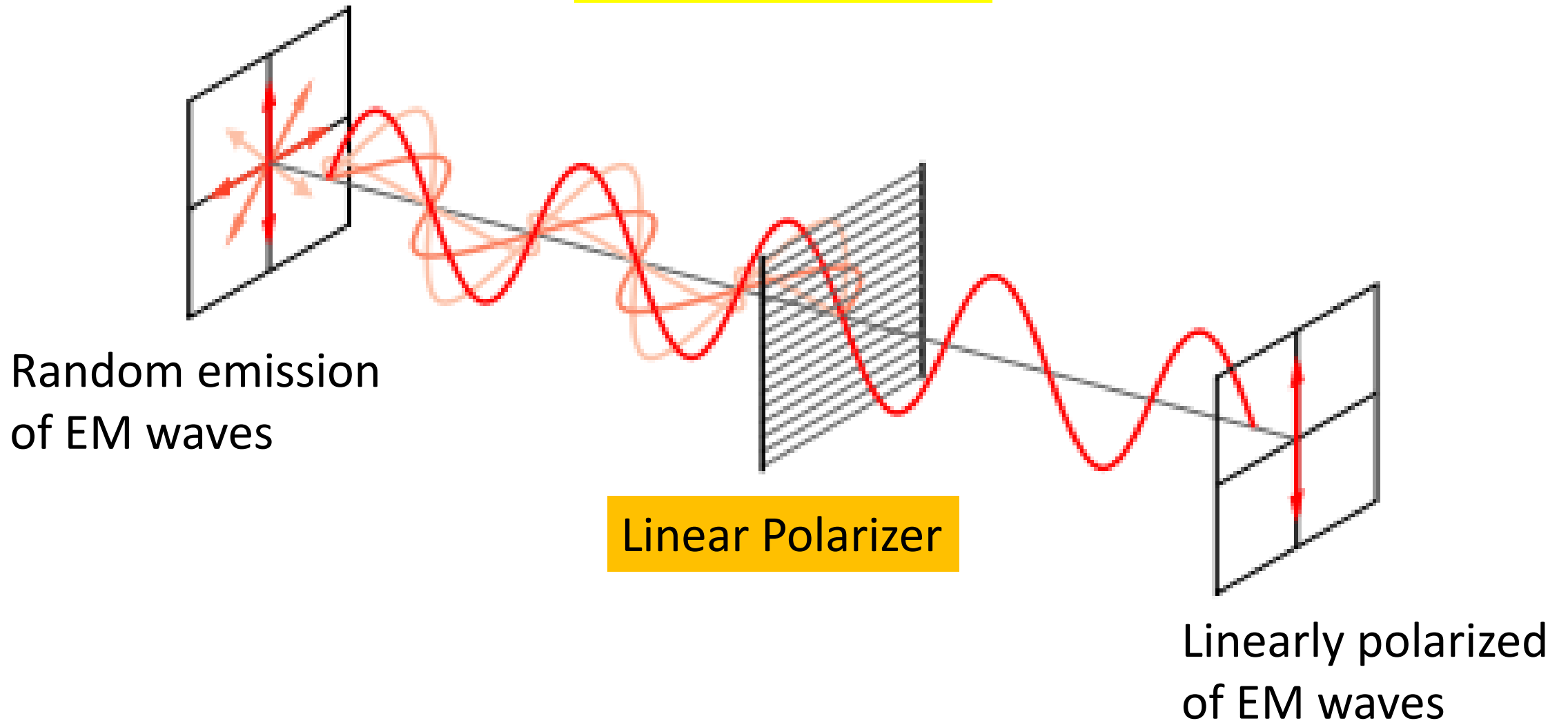
From the receiver: right-handed / clockwise circularly polarized wave



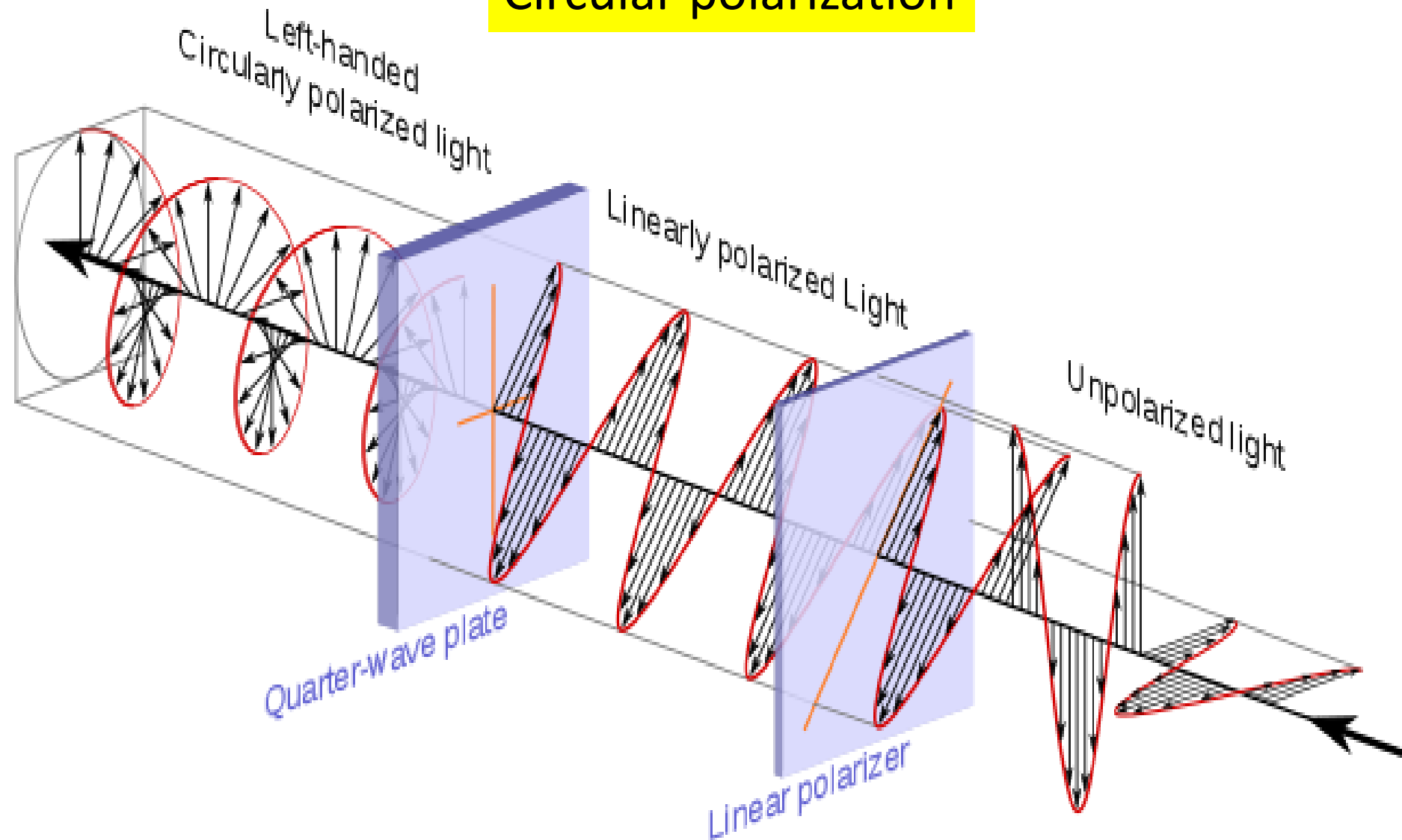
From the source: right-handed / clockwise circularly polarized wave.

From the receiver: left-handed / anti-clockwise circularly polarized wave

Linear polarization



Circular polarization



Propagation and incidence of EM waves on conductors and dielectric

Normal incidence of an EM wave: The case vacuum/matter

Vacuum / Conductor

Vacuum / Dielectric

Given an EM wave propagating
along a given direction

+

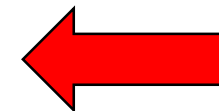
Interpose a medium along
the direction of propagation

Boundary condition
at the surface

+

AND

Full description of the interaction

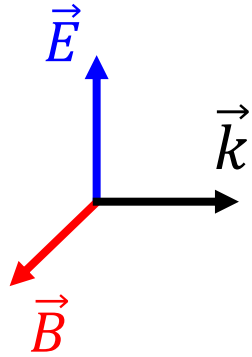


$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

$$\vec{k} \times \vec{E} = \omega \vec{B}$$

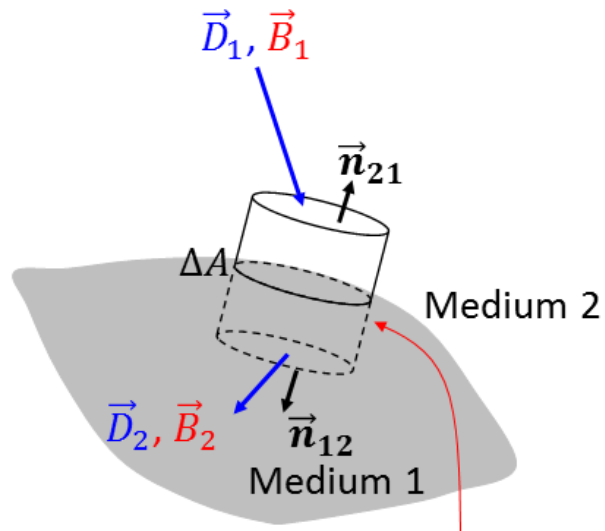
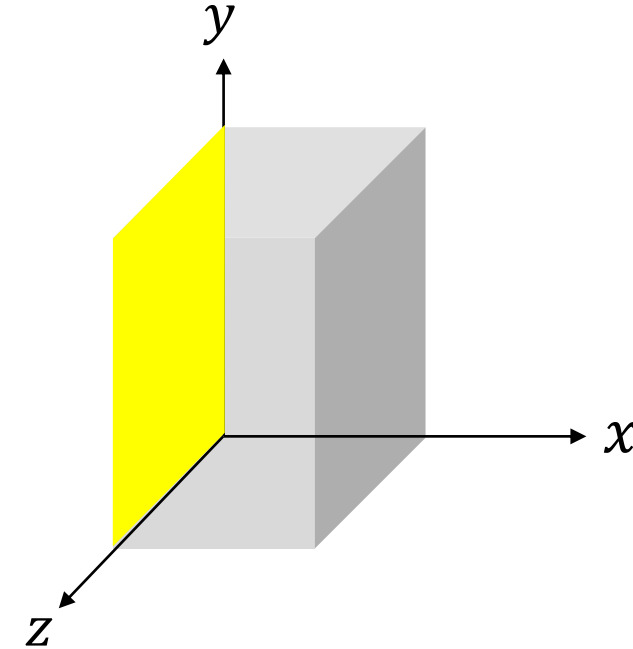
A vertical EM wave propagating along the x -direction

Boundary conditions at the surface



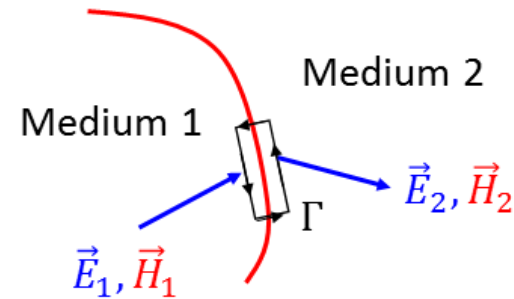
For Normal components
we use Gauss theorem

For Tangential components
we use Stokes theorem



Gaussian surface = Pillbox

$$D = \epsilon E$$



$$H = \frac{B}{\mu}$$

Boundary conditions at the surface

No free charges ($\rho_{free} = 0$) and no current $J_{free} = 0$

For electric field $D = \epsilon E$

Gauss theorem $\vec{\nabla} \cdot \vec{D} = 0$
(deals with the normal components)

Stokes theorem $\oint \vec{E} \cdot d\vec{l}$
(deals with the tangential components)

For magnetic field $H = \frac{B}{\mu}$

Gauss theorem $\vec{\nabla} \cdot \vec{B} = 0$

Stokes theorem

$$D_1^\perp = D_2^\perp$$

$$H_1^\parallel = H_2^\parallel$$

Reminder $\vec{\nabla} \cdot \vec{D} = \rho_{free}$

$$\epsilon_1 E_1^\perp = \epsilon_2 E_2^\perp$$

$$E_1^\parallel = E_2^\parallel$$

Reminder $\oint \frac{\vec{B}}{\mu} \cdot d\vec{l} = J_{free}$

$$B_1^\perp = B_2^\perp$$

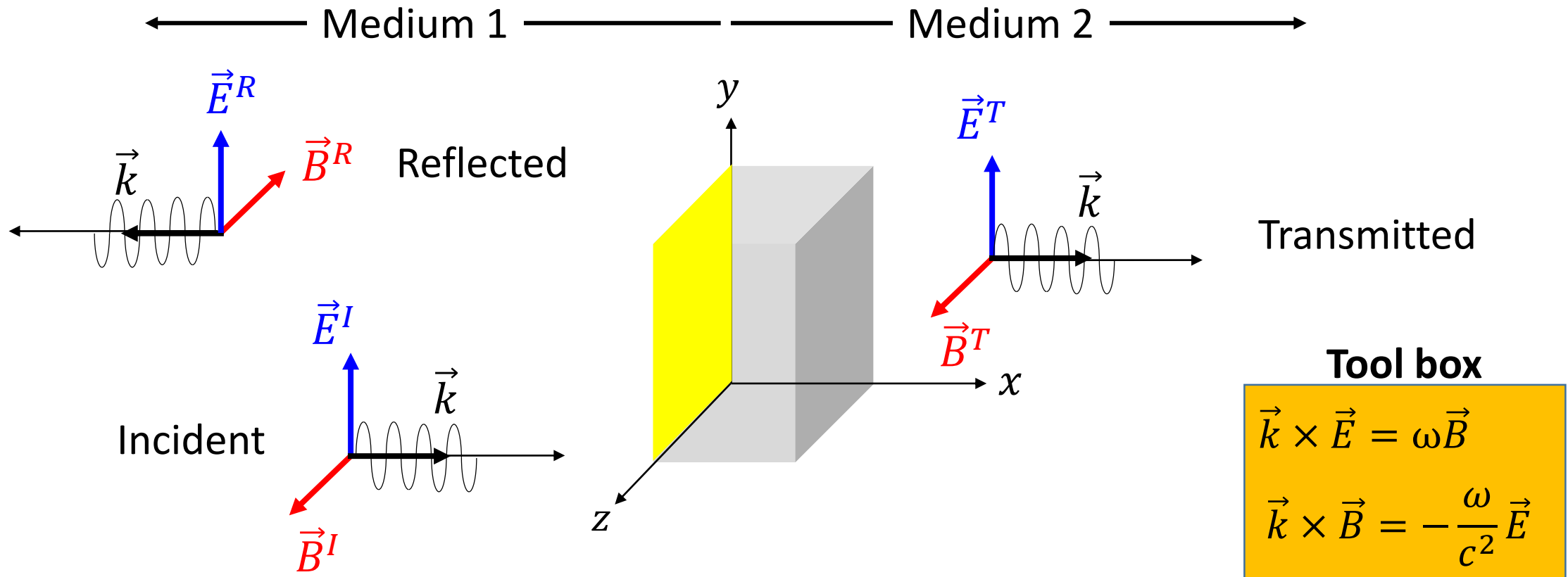
$$\frac{B_1^\parallel}{\mu_1} = \frac{B_2^\parallel}{\mu_2}$$

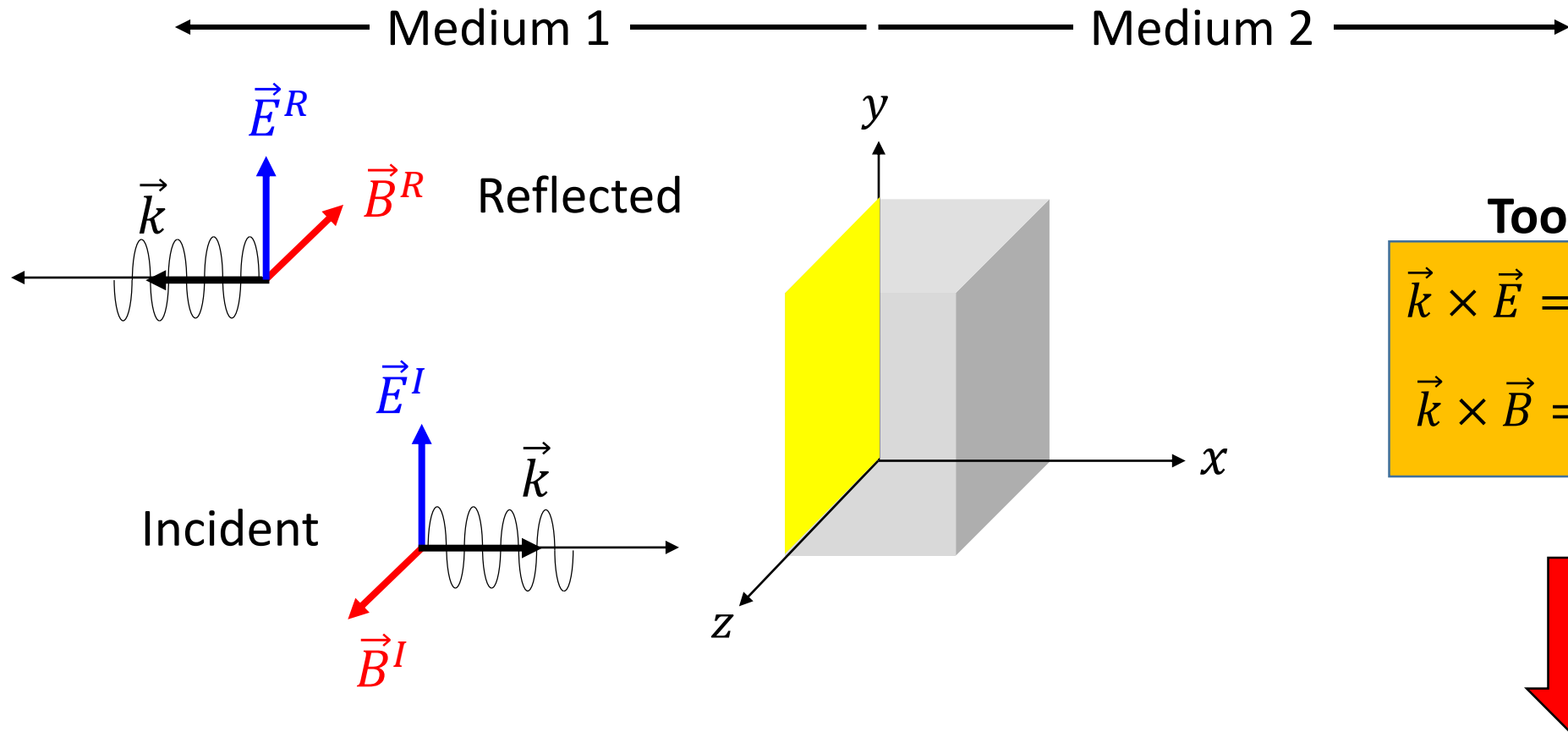
Normal incidence of a linear polarized EM wave:
Reflection and Transmission

Normal incidence of a linear polarized EM wave: Reflection and Transmission

Do conductor and dielectric behave similarly ?

Intuitive vs deductive approaches





The electric field has not changed direction

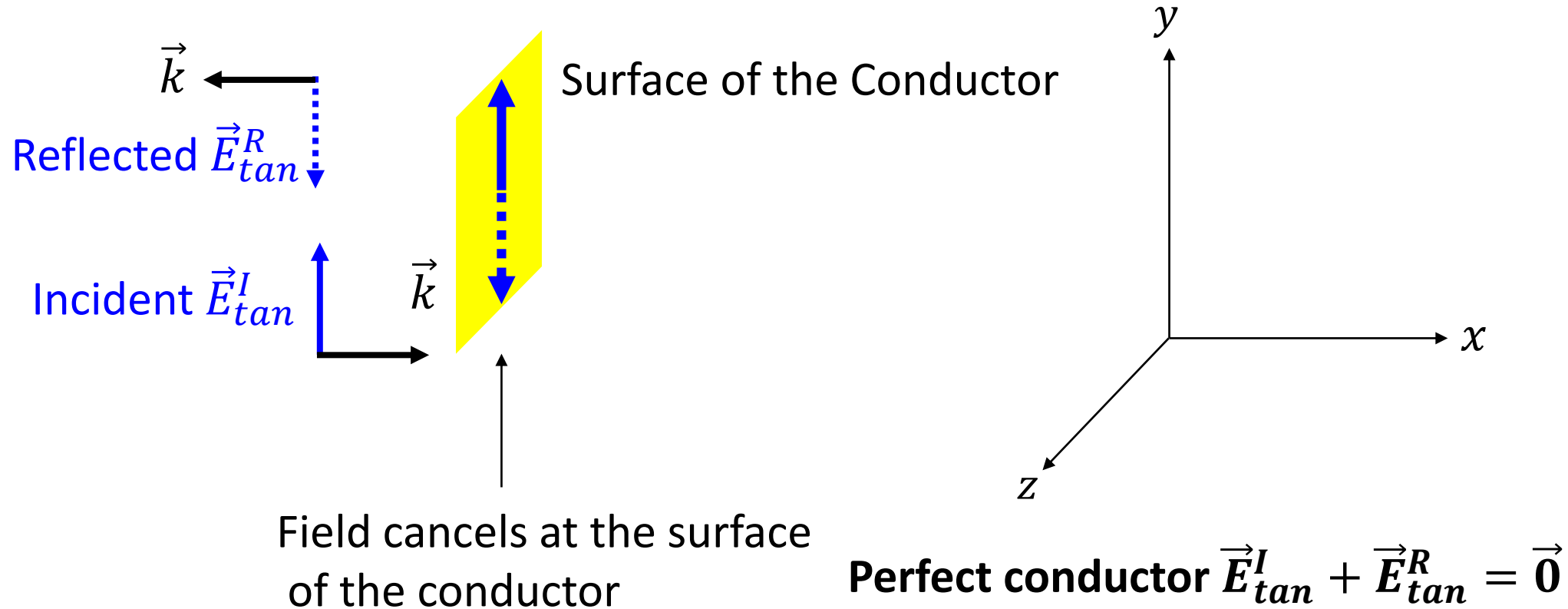
Is it the only possibility ?



$$\vec{E}^R // \vec{E}^I$$

Intuitive approach

The superposition principle applied to an incident and a reflected wave



$$|\vec{E}_{tan}^I| = |\vec{E}_{tan}^R|$$

Question: What produces the reflected Electric and magnetic field?

Answer:

The surface currents that must be present to make \vec{E} exactly zero at the surface is the source of the magnetic field.

Deductive approach

Incidence

$$\vec{E}^I(x, t) = E_0^I e^{i(k_1 x - \omega t)} \hat{j}$$

$$\vec{B}^I(x, t) = B_0^I e^{i(k_1 x - \omega t)} \hat{k} = \frac{E_0^I}{\underset{\textcolor{red}{v}_1}} e^{i(k_1 x - \omega t)} \hat{k}$$

If medium 1 = vacuum $\textcolor{red}{v}_1 = c$

If medium 2 = conductor $\textcolor{red}{v}_2 = 0$

Transmission

$$\vec{E}^T(x, t) = E_0^T e^{i(k_2 x - \omega t)} \hat{j}$$

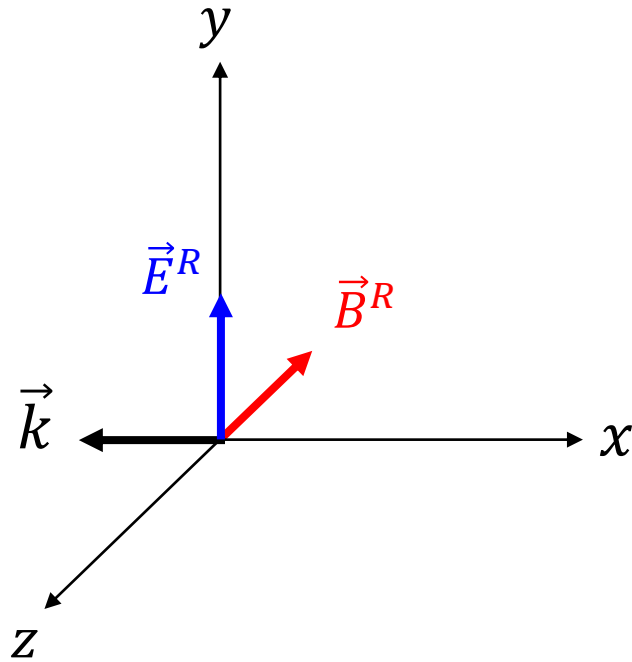
$$\vec{B}^T(x, t) = B_0^T e^{i(k_2 x - \omega t)} \hat{k} = \frac{E_0^T}{\underset{\textcolor{red}{v}_2}} e^{i(k_2 x - \omega t)} \hat{k}$$



Why ?

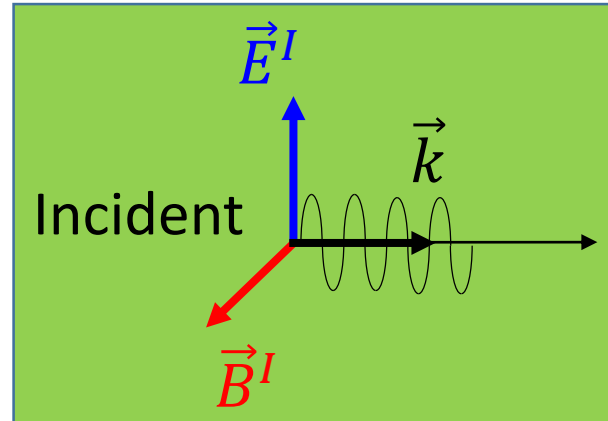
Reflection

The wave number vector \vec{k} changes to opposite direction



$$\vec{E}^R(x, t) = E_0^R e^{i(-k_1 x - \omega t)} \hat{j}$$

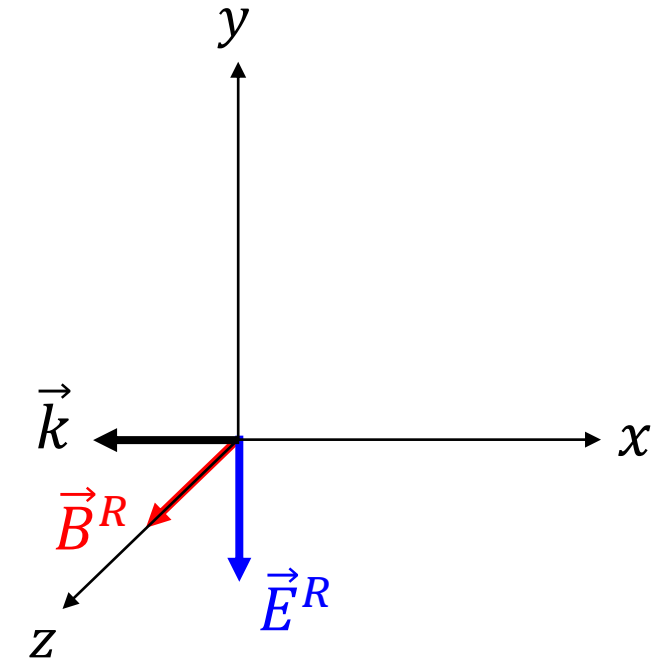
$$\vec{B}^R(x, t) = -\frac{E_0^R}{v_1} e^{i(-k_1 x - \omega t)} \hat{k}$$



$$\vec{k} \times \vec{E} = \omega \vec{B}$$

$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

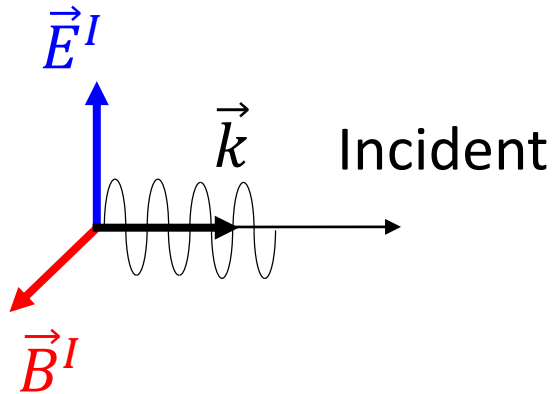
two possible configurations



$$\vec{E}^R(x, t) = -E_0^R e^{i(-k_1 x - \omega t)} \hat{j}$$

$$\vec{B}^R(x, t) = \frac{E_0^R}{v_1} e^{i(-k_1 x - \omega t)} \hat{k}$$

Which one of the two reflection configurations holds for a conductor and for a dielectric?



$$\vec{E}^I(x, t) = E_0^I e^{i(k_1 x - \omega t)} \hat{j}$$

$$\vec{B}^I(x, t) = \frac{E_0^I}{\underset{\textcolor{red}{v}_1}{c}} e^{i(k_1 x - \omega t)} \hat{k}$$

Tool box

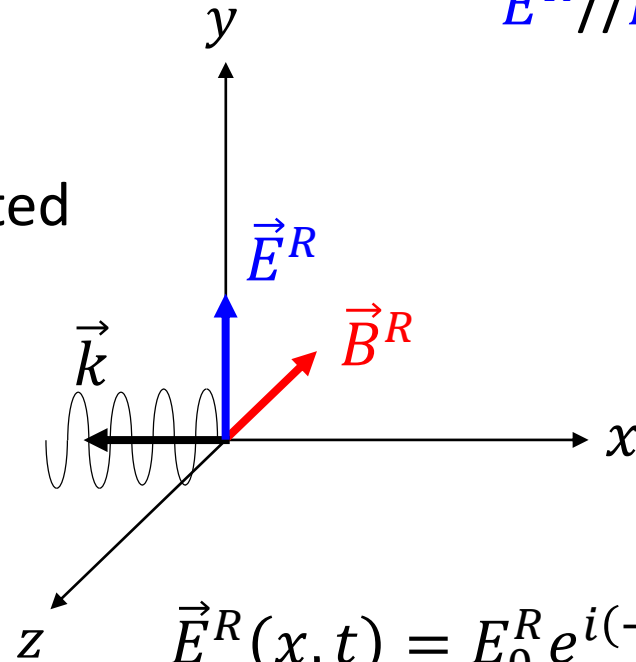
$$\vec{k} \times \vec{E} = \omega \vec{B}$$

$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

Let's take the first configuration

$$\vec{E}^R // \vec{E}^I$$

Reflected



$$\vec{E}^R(x, t) = E_0^R e^{i(-k_1 x - \omega t)} \hat{j}$$

$$\vec{B}^R(x, t) = -\frac{E_0^R}{\textcolor{red}{v}_1} e^{i(-k_1 x - \omega t)} \hat{k}$$

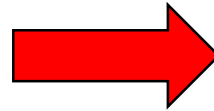
Which one of the two reflection configurations holds for a conductor and for a dielectric

Boundary conditions

In normal incidence, only tangential components matter

$$\vec{E}^I(\perp) = \vec{E}^R(\perp) = \vec{E}^T(\perp) = \vec{0}$$

$$\vec{B}^I(\perp) = \vec{B}^R(\perp) = \vec{B}^T(\perp) = \vec{0}$$



$$\vec{E}^R(x, t) = E_0^R e^{i(-k_1 x - \omega t)} \hat{j}$$

$$\vec{B}^R(x, t) = -\frac{E_0^R}{\underline{v}_1} e^{i(-k_1 x - \omega t)} \hat{k}$$

$$\vec{E}^I + \vec{E}^R = \vec{E}^T \quad \Rightarrow \quad E^I + E^R = E^T$$

$$\vec{H}^I + \vec{H}^R = \vec{H}^T \quad \Rightarrow \quad \frac{1}{\mu_1} \left(\frac{E_0^I}{\underline{v}_1} \right) - \frac{1}{\mu_1} \left(\frac{E_0^R}{\underline{v}_1} \right) = \frac{1}{\mu_2} \left(\frac{E_0^T}{\underline{v}_2} \right)$$

Solving for E^R and E^T

Reflection

$$\vec{E}^R(x, t) = \left(\frac{1 - \beta}{1 + \beta} \right) E_0^I e^{i(-k_1 x - \omega t)} \hat{\mathbf{j}} \quad \text{and} \quad \vec{B}^R(x, t) = -\frac{1}{\textcolor{red}{v}_1} \left(\frac{1 - \beta}{1 + \beta} \right) E_0^I e^{i(-k_1 x - \omega t)} \hat{\mathbf{k}}$$

$$\vec{B}^R(x, t) = -\left(\frac{1 - \beta}{1 + \beta} \right) B_0^I e^{i(-k_1 x - \omega t)} \hat{\mathbf{k}}$$

$$\beta = \frac{\mu_1 v_1}{\mu_2 v_2}$$

Transmission

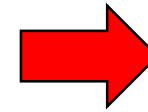
$$\vec{E}^T(x, t) = \left(\frac{2}{1 + \beta} \right) E_0^I e^{i(k_2 x - \omega t)} \hat{\mathbf{j}} \quad \text{and} \quad \vec{B}^T(x, t) = B_0^T e^{i(k_2 x - \omega t)} \hat{\mathbf{k}} = \frac{E_0^T}{\textcolor{red}{v}_2} e^{i(k_2 x - \omega t)} \hat{\mathbf{k}}$$

$$\vec{B}^T(x, t) = \frac{\textcolor{red}{v}_1}{\textcolor{red}{v}_2} \left(\frac{2}{1 + \beta} \right) B_0^I e^{i(k_2 x - \omega t)} \hat{\mathbf{k}}$$

Case of vacuum / conductor

$$\beta = \frac{\mu_0 c}{\mu_2 v_2}$$

$v_2 = 0$ wave does not penetrate the conductor

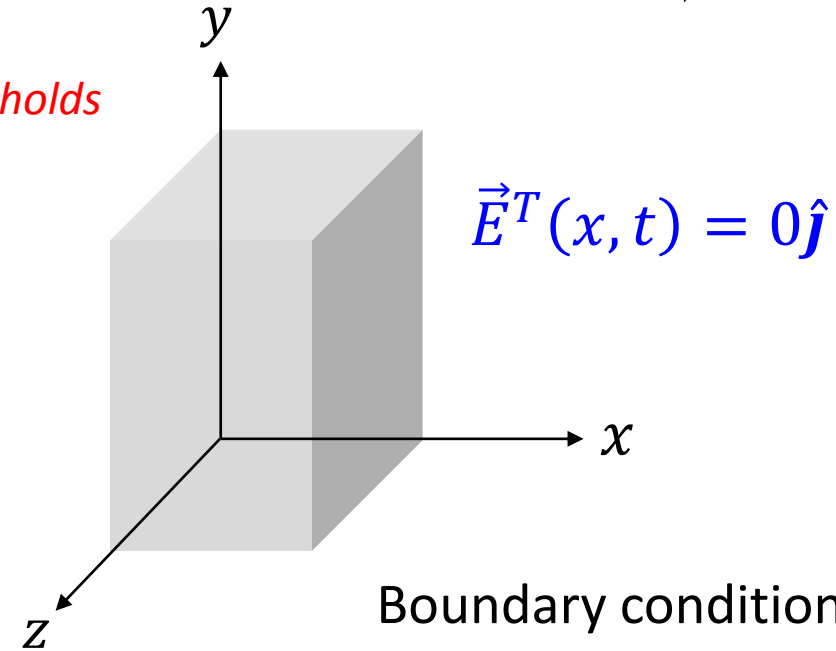


$$\beta = \infty$$

It is the second configuration of slide#85 that holds

$$\vec{E}^R(x, t) = -E_0^I e^{i(-k_1 x - \omega t)} \hat{j}$$

$$\vec{E}^I(x, t) = E_0^I e^{i(k_1 x - \omega t)} \hat{j}$$



Boundary conditions are necessary

The tool box

$$\vec{k} \times \vec{E} = \omega \vec{B}$$


$$\vec{k} \times \vec{B} = -\frac{\omega}{c^2} \vec{E}$$

is not enough

At the surface of the **conductor** the electric field cancels as expected from electrostatic and from the intuitive approach

\Rightarrow **The reflected electric field must be inverted**

What fraction of the incident energy is reflected and what fraction is transmitted

Poynting vector $\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$  $I = S_{av} = \frac{1}{2} \epsilon v E_{max}^2$

$$R = \frac{I_R}{I_I} = \left(\frac{E_0^R}{E_0^I} \right)^2 = \left(\frac{1 - \beta}{1 + \beta} \right)^2$$

$$T = \frac{I_T}{I_I} = \beta \left(\frac{2}{1 + \beta} \right)^2$$

$$R + T = 1$$

Energy conservation

$$\beta = \infty$$



$$T = 0$$



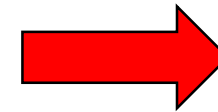
$$R = 1$$

Metal is a good reflector

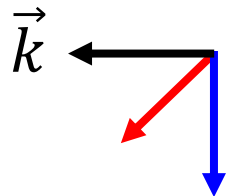
What happens to the magnetic field at the surface of the conductor?

$$\beta = \frac{\mu_0 c}{\mu_2 v_2}$$

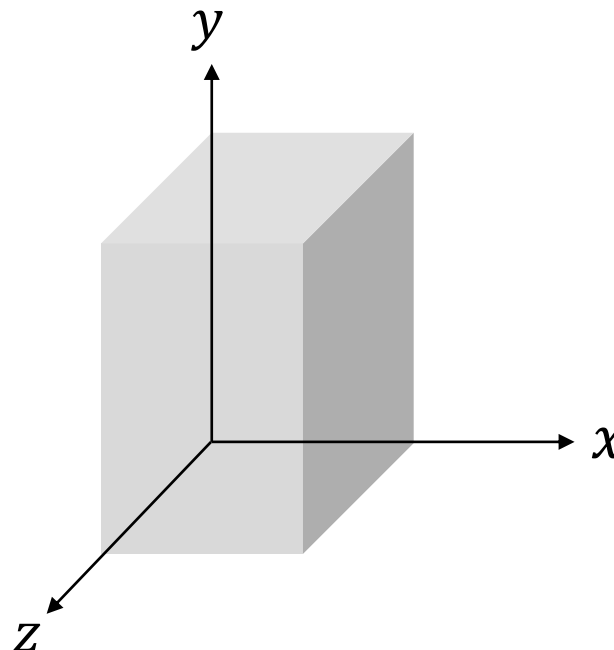
$v_2 = 0$ does not penetrate the conductor



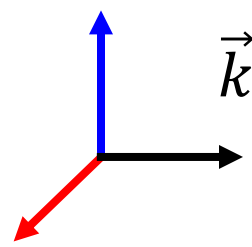
$$\beta = \infty$$



$$\vec{B}^R(x, t) = B_0^I e^{i(-k_1 x - \omega t)} \hat{k}$$



$$\vec{B}^T(x, t) = 0 \hat{k}$$

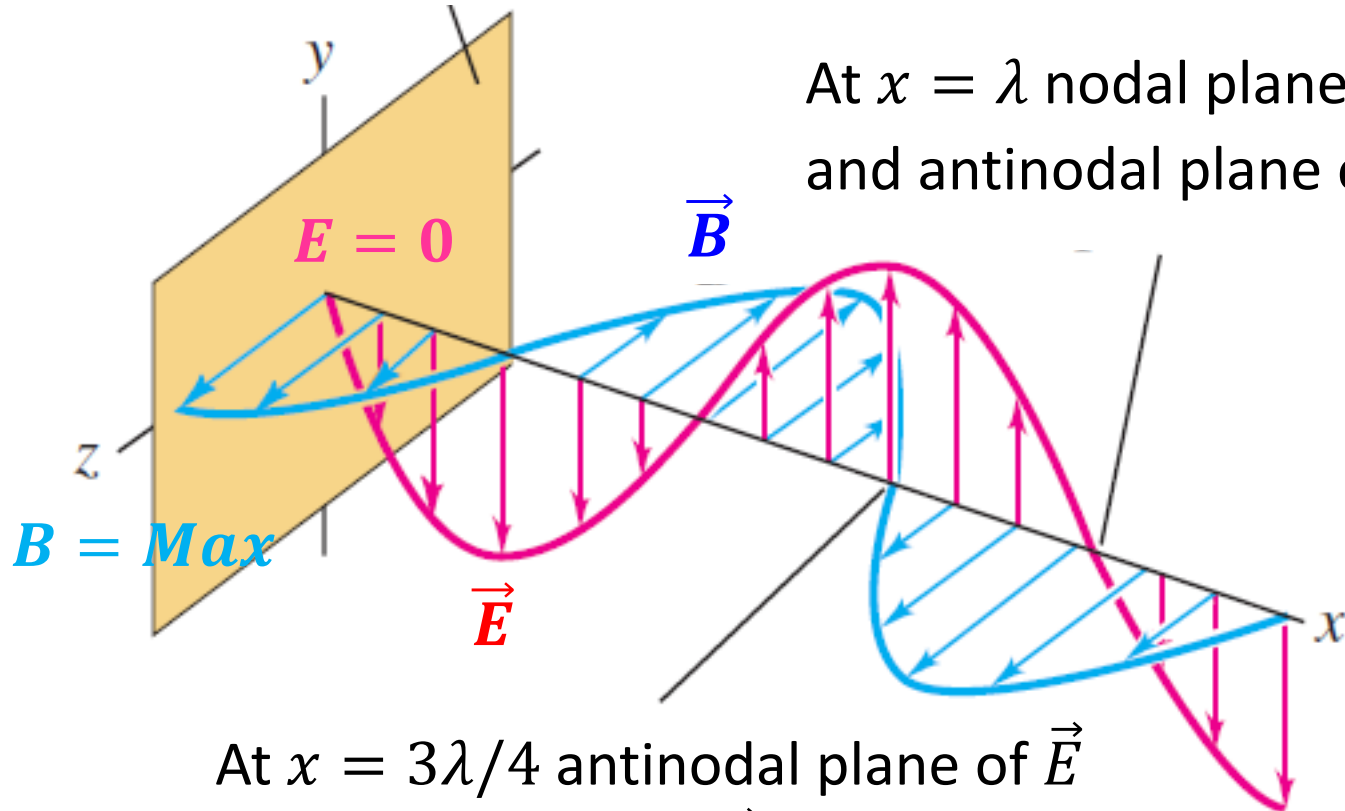
$$\vec{B}^I(x, t) = B_0^I e^{i(k_1 x - \omega t)} \hat{k}$$


At the surface the direction of the magnetic field remains unchanged

The conductor induces a quadrature phase shift

Perfect conductor ($\sigma_e = \infty, \rho_e = 0$)

At $x = \lambda$ nodal plane of \vec{E}
and antinodal plane of \vec{B}



At $x = 3\lambda/4$ antinodal plane of \vec{E}
and nodal plane of \vec{B}

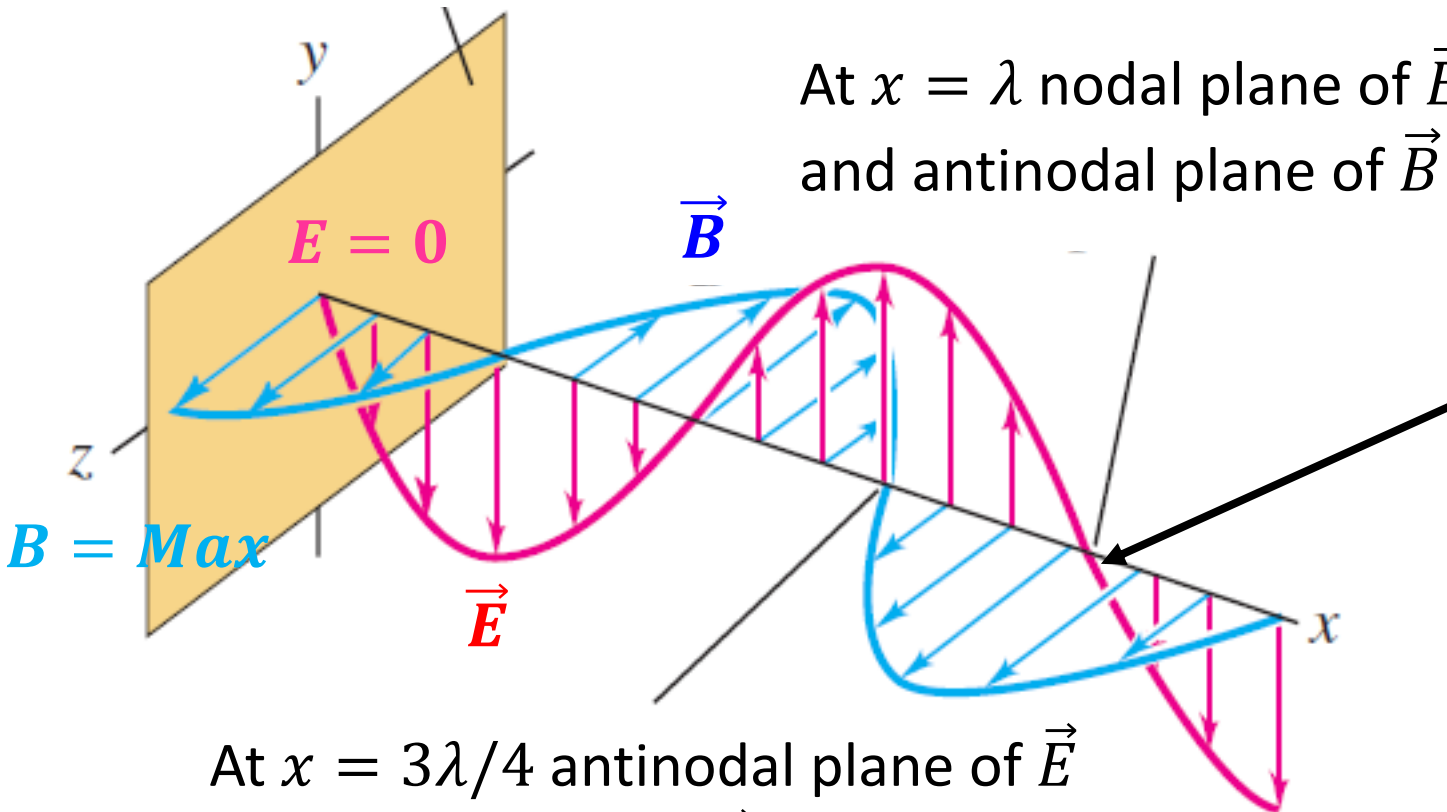
Perfect conductor $\Rightarrow \vec{E}_{tan} = \vec{0}$

Dephasing $\frac{\pi}{2}$

The conductor induces a quadrature phase shift

Perfect conductor ($\sigma_e = \infty, \rho_e = 0$)

At $x = \lambda$ nodal plane of \vec{E}
and antinodal plane of \vec{B}



To obtain standing waves the second conductor **MUST** be placed at a **nodal** plane of \vec{E} like this one and parallel to the first conductor

At $x = 3\lambda/4$ antinodal plane of \vec{E}
and nodal plane of \vec{B}

Question: What is the energy contained in a standing wave?

What is the intensity in a standing wave?

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} \quad + \quad \begin{aligned} E_y(x, t) &= +2E_{max} \sin kx \sin \omega t \\ B_z(x, t) &= +2B_{max} \cos kx \cos \omega t \end{aligned}$$

$$S_x = \frac{E_{max} B_{max} \sin 2kx \sin 2\omega t}{\mu_0}$$

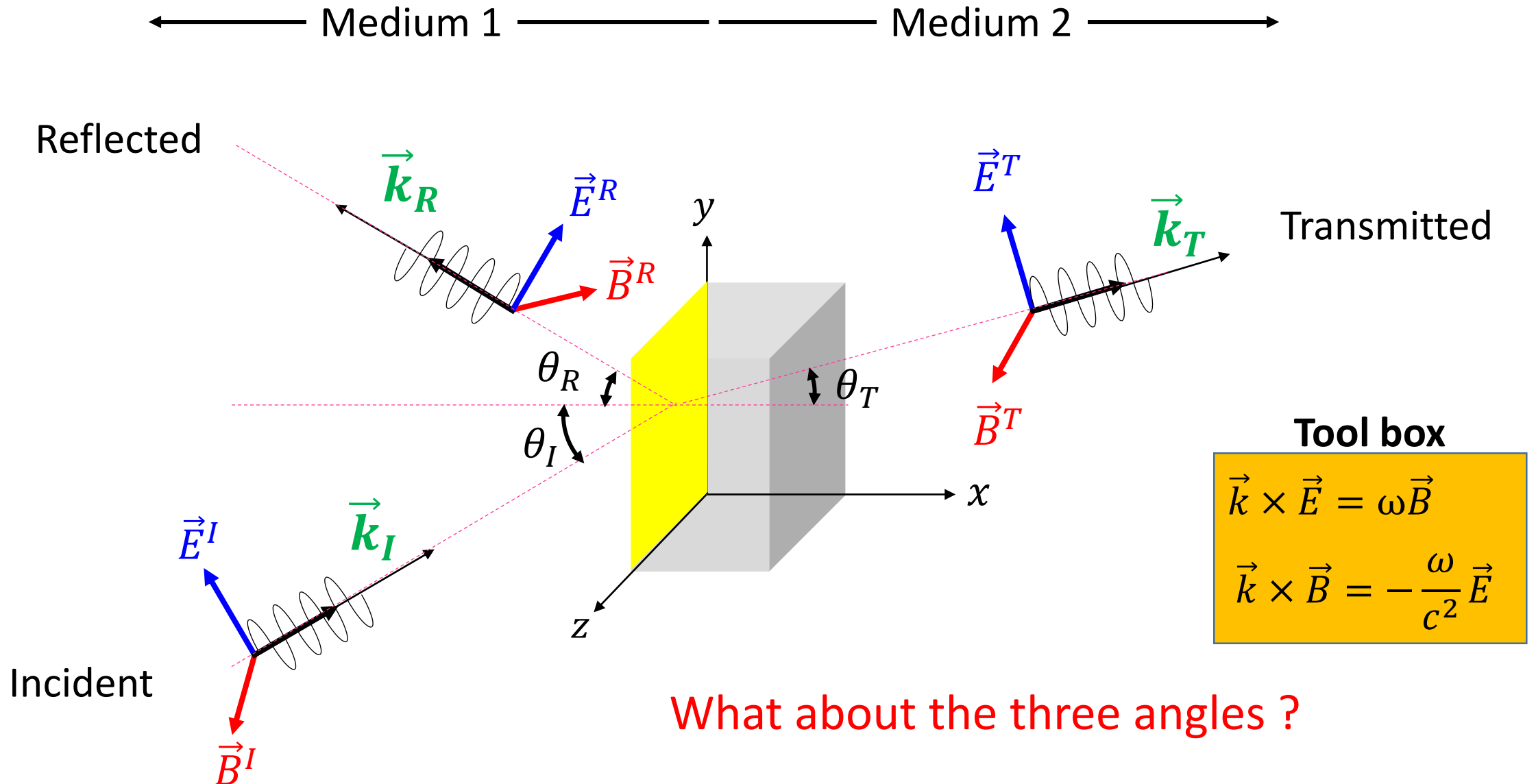
As expected from two equal waves traveling in opposite directions, each transporting energy

$$I = S_{av} = \langle S_x \rangle_t = 0$$

$$\vec{S}^I + \vec{S}^R = \vec{0}$$

While using waves to transmit power, it is important to avoid reflections that give rise to standing waves

Oblique incidence of a linear polarized EM wave:
Reflection and Transmission

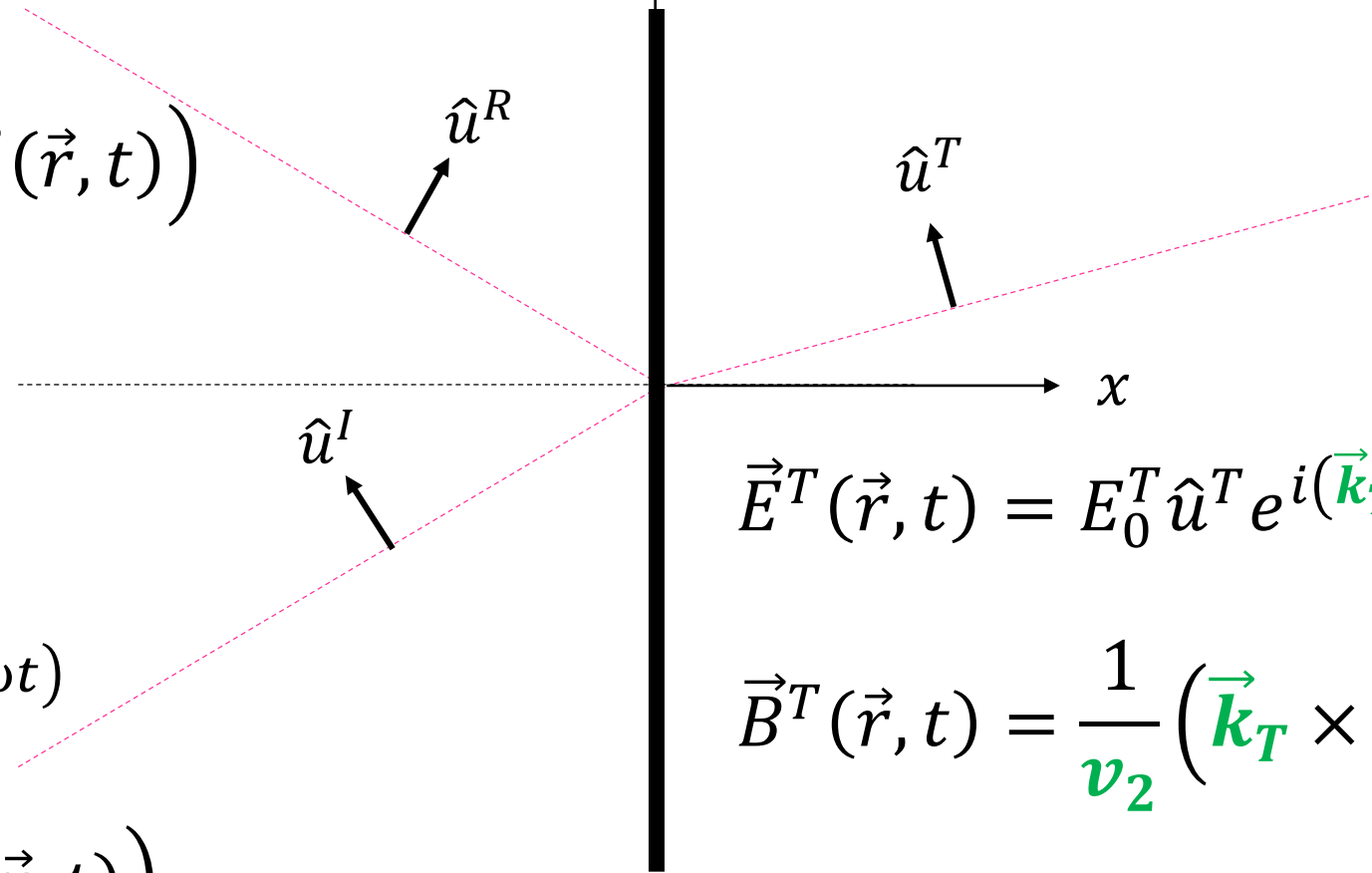


← Medium 1 ————— Medium 2 —————→

$$\vec{E}^R(\vec{r}, t) = E_0^R \hat{u}^R e^{i(\vec{k}_R \cdot \vec{r} - \omega t)}$$

$$\vec{B}^R(\vec{r}, t) = \frac{1}{v_1} (\vec{k}_R \times \vec{E}^R(\vec{r}, t))$$

\hat{u}^i ($i = I, R, T$) = unit vectors
along the \vec{E} field



$$\vec{E}^I(\vec{r}, t) = E_0^I \hat{u}^I e^{i(\vec{k}_I \cdot \vec{r} - \omega t)}$$

$$\vec{B}^I(\vec{r}, t) = \frac{1}{v_1} (\vec{k}_I \times \vec{E}^I(\vec{r}, t))$$

$$\vec{E}^T(\vec{r}, t) = E_0^T \hat{u}^T e^{i(\vec{k}_T \cdot \vec{r} - \omega t)}$$

$$\vec{B}^T(\vec{r}, t) = \frac{1}{v_2} (\vec{k}_T \times \vec{E}^T(\vec{r}, t))$$

Monochromatic wave  $\omega = kv$ is the same for all three waves 

$$k_I \cdot v_1 = k_R \cdot v_1 = k_T \cdot v_2 \quad \img alt="red arrow" data-bbox="388 224 472 297" \quad k_I = k_R = \frac{v_2}{v_1} k_T = \frac{n_1}{n_2}$$

$$n_i = \text{index of refraction of medium } i = \frac{c}{v_i}$$

Boundary conditions at the plane of separation

$$\vec{E}^I(\vec{r}, t) + \vec{E}^R(\vec{r}, t)$$

$$\vec{E}^T(\vec{r}, t)$$

$$\vec{B}^I(\vec{r}, t) + \vec{B}^R(\vec{r}, t)$$

$$\vec{B}^T(\vec{r}, t)$$

$$E_0^I e^{i(\vec{k}_I \cdot \vec{r} - \omega t)} + E_0^R e^{i(\vec{k}_R \cdot \vec{r} - \omega t)} = E_0^T e^{i(\vec{k}_T \cdot \vec{r} - \omega t)}$$

Boundary

At $x = 0$

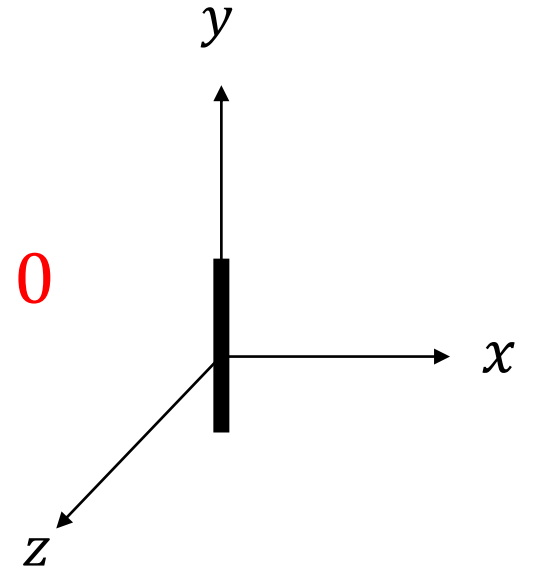
$$\vec{k}_I \cdot \vec{r} = \vec{k}_R \cdot \vec{r} = \vec{k}_T \cdot \vec{r}$$



$$y \cdot k_{Iy} + z \cdot k_{Iz} = y \cdot k_{Ry} + z \cdot k_{Rz} = y \cdot k_{Ty} + z \cdot k_{Tz}$$



$$\begin{aligned} k_{Iy} &= k_{Ry} = k_{Ty} \\ k_{Iz} &= k_{Rz} = k_{Tz} \end{aligned}$$

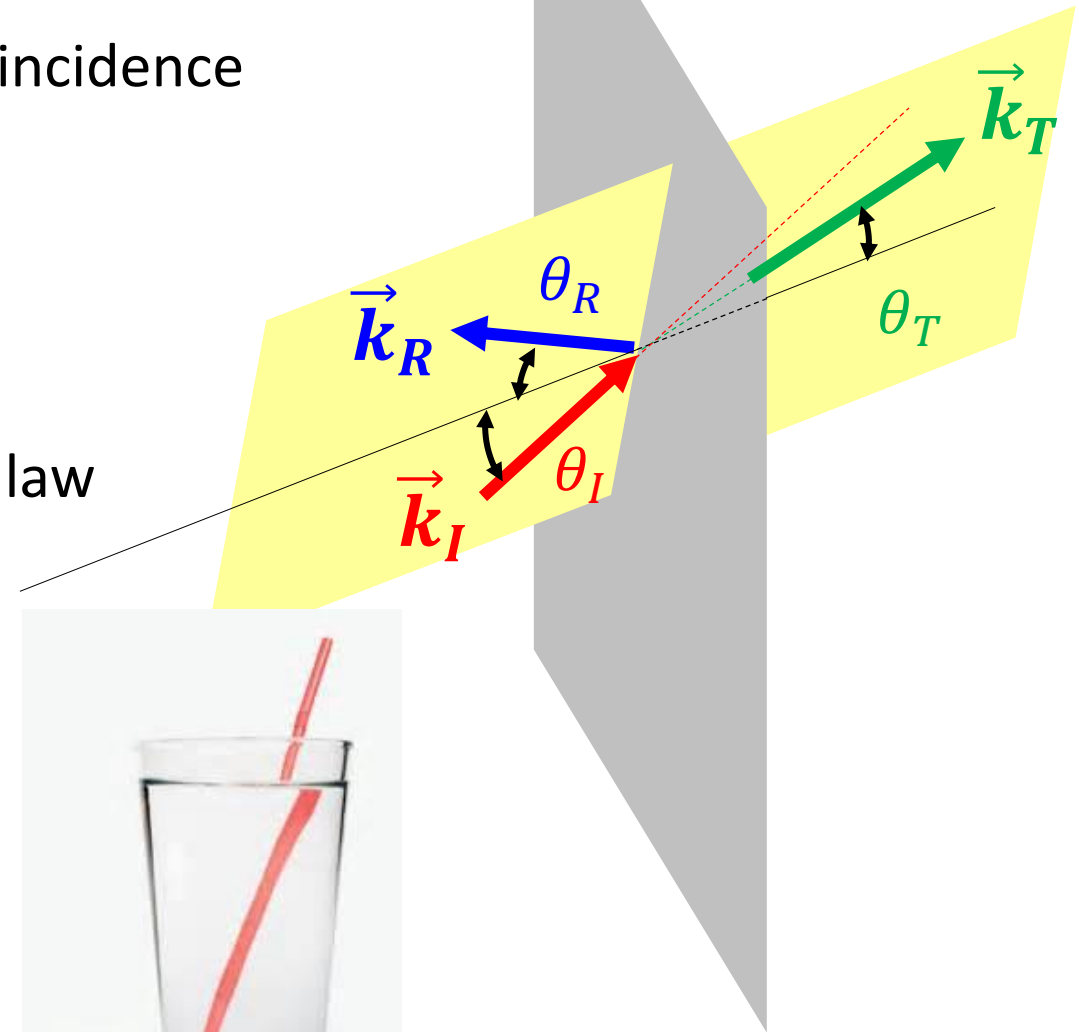


Three laws follow

1) \vec{k}_I, \vec{k}_R and \vec{k}_T form a single plane: plane of incidence

2) $\theta_I = \theta_R$ Law of reflection or Fermat's law

3) $\frac{\sin \theta_T}{\sin \theta_I} = \frac{n_1}{n_2}$ Law of refraction



$$\vec{k}_I \cdot \vec{r} = \vec{k}_R \cdot \vec{r} = \vec{k}_T \cdot \vec{r} \quad \Rightarrow \quad \left. \begin{aligned} \vec{E}^I(\vec{r}, t) &= E_0^I e^{i(\vec{k}_I \cdot \vec{r} - \omega t)} \\ \vec{E}^R(\vec{r}, t) &= E_0^R e^{i(\vec{k}_R \cdot \vec{r} - \omega t)} \\ \vec{E}^T(\vec{r}, t) &= E_0^T e^{i(\vec{k}_T \cdot \vec{r} - \omega t)} \end{aligned} \right\} \text{Exponent factors are all equal}$$

Boundary conditions (slide #79)

$$\left. \begin{aligned} \varepsilon_1(E_0^I + E_0^R)_x &= \varepsilon_2(E_0^T)_x \\ (B_0^I + B_0^R)_x &= (B_0^T)_x \end{aligned} \right\} \text{Normal components at the interface}$$

$$\left. \begin{aligned} (E_0^I + E_0^R)_{y,z} &= (E_0^T)_{y,z} \\ \frac{1}{\mu_1}(B_0^I + B_0^R)_{y,z} &= \frac{1}{\mu_2}(B_0^T)_{y,z} \end{aligned} \right\} \text{Tangential components at the interface}$$

Reflection

$$\vec{E}^R(x, t) = \left(\frac{\alpha - \beta}{\alpha + \beta} \right) E_0^I e^{i(-k_1 x - \omega t)} \hat{u}^R \quad \text{and} \quad \vec{B}^R(x, t) = -\frac{1}{v_1} \left(\frac{1 - \beta}{1 + \beta} \right) E_0^I e^{i(-k_1 x - \omega t)} \left(\frac{\vec{k}_R}{|\vec{k}_R|} \times \hat{u}^R \right)$$

$$\vec{B}^R(x, t) = -\left(\frac{\alpha - \beta}{\alpha + \beta} \right) B_0^I e^{i(-k_1 x - \omega t)} \left(\frac{\vec{k}_R}{|\vec{k}_R|} \times \hat{u}^R \right)$$

$$\alpha = \frac{\cos \theta_T}{\cos \theta_I}$$

Normal incidence

$$\beta = \frac{\mu_1 v_1}{\mu_2 v_2}$$

$$\alpha = 1$$

Transmission

$$\vec{E}^T(x, t) = \left(\frac{2}{\alpha + \beta} \right) E_0^I e^{i(k_2 x - \omega t)} \hat{u}^T \quad \text{and} \quad \vec{B}^T(x, t) = B_0^T e^{i(k_2 x - \omega t)} \hat{k} = \frac{E_0^T}{v_2} e^{i(k_2 x - \omega t)} \left(\frac{\vec{k}_T}{|\vec{k}_T|} \times \hat{u}^T \right)$$

$$\vec{B}^T(x, t) = \frac{v_1}{v_2} \left(\frac{2}{\alpha + \beta} \right) B_0^I e^{i(k_2 x - \omega t)} \left(\frac{\vec{k}_T}{|\vec{k}_T|} \times \hat{u}^T \right)$$