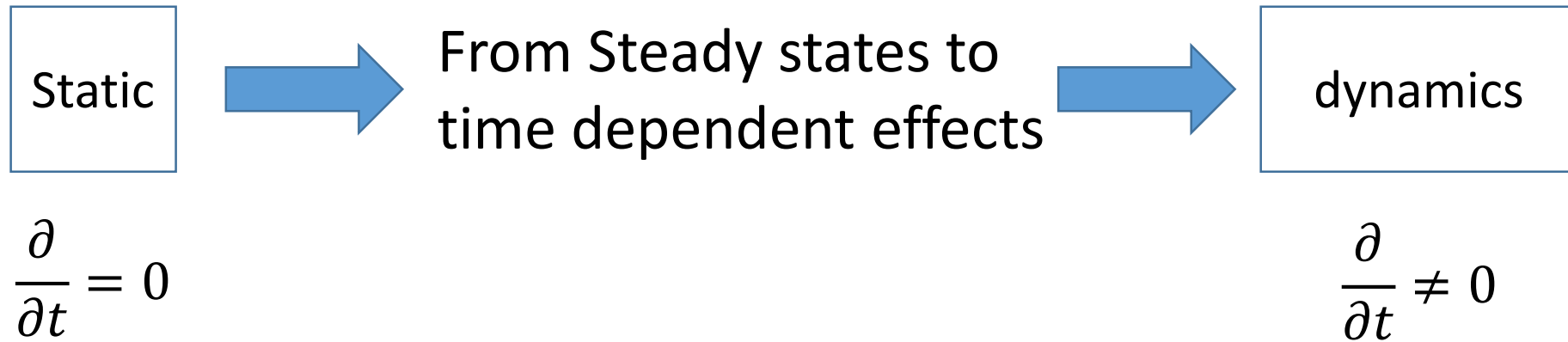


From Static to dynamics



Faraday's discovery and the **birth of electrical engineering**

Orsted 1820 and Faraday 1921:

Discovery of the close connection between electricity and magnetism

- Current in a wire creates a magnetic field (compass deviation)
 - Wire carrying current in a magnetic field manifests action - reaction
- } Involves steady current
- Changing magnetic creates a changing electric field
 - Changing electric field creates a changing magnetic field
- } Involves varying current

Can be used to produce **WORK**



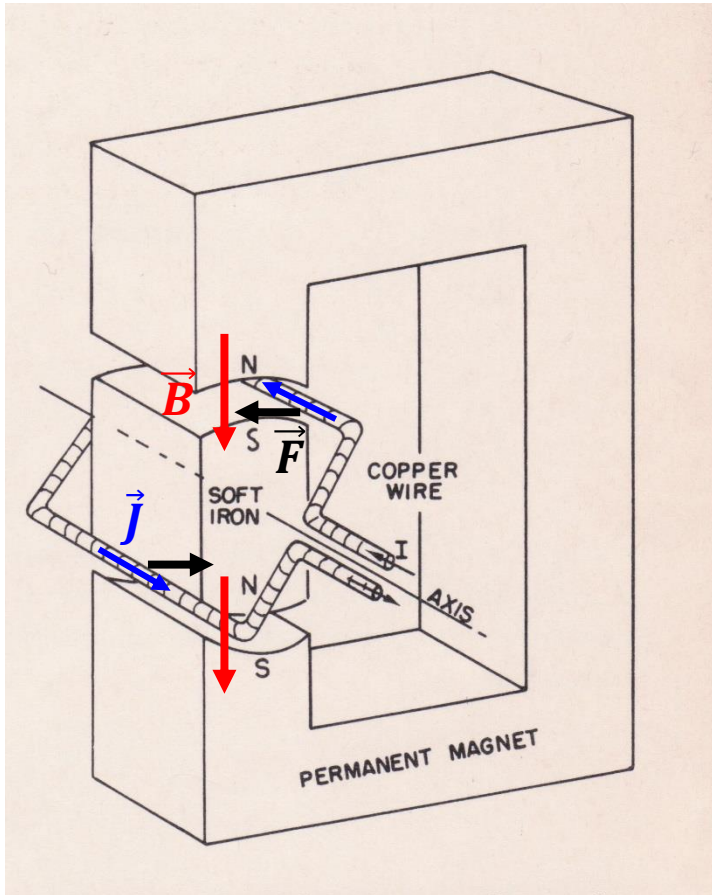
Birth of electrical engineering

FORCE and / or TORQUE



Magnetic field produces mechanical force

Application of Lorentz force

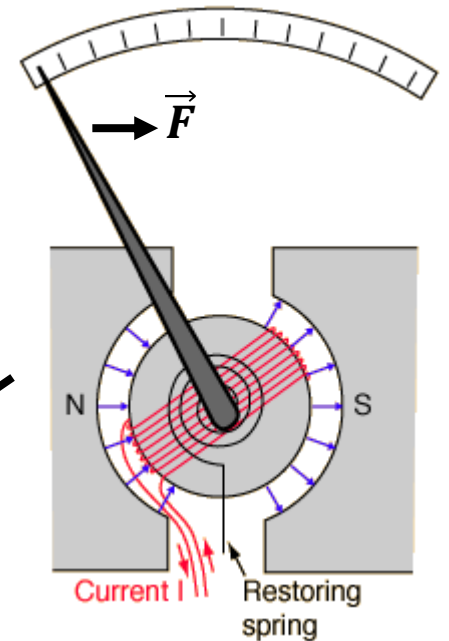


Electromagnetic Motor

Make a motor (current reversed each half-turn)

Torque in action

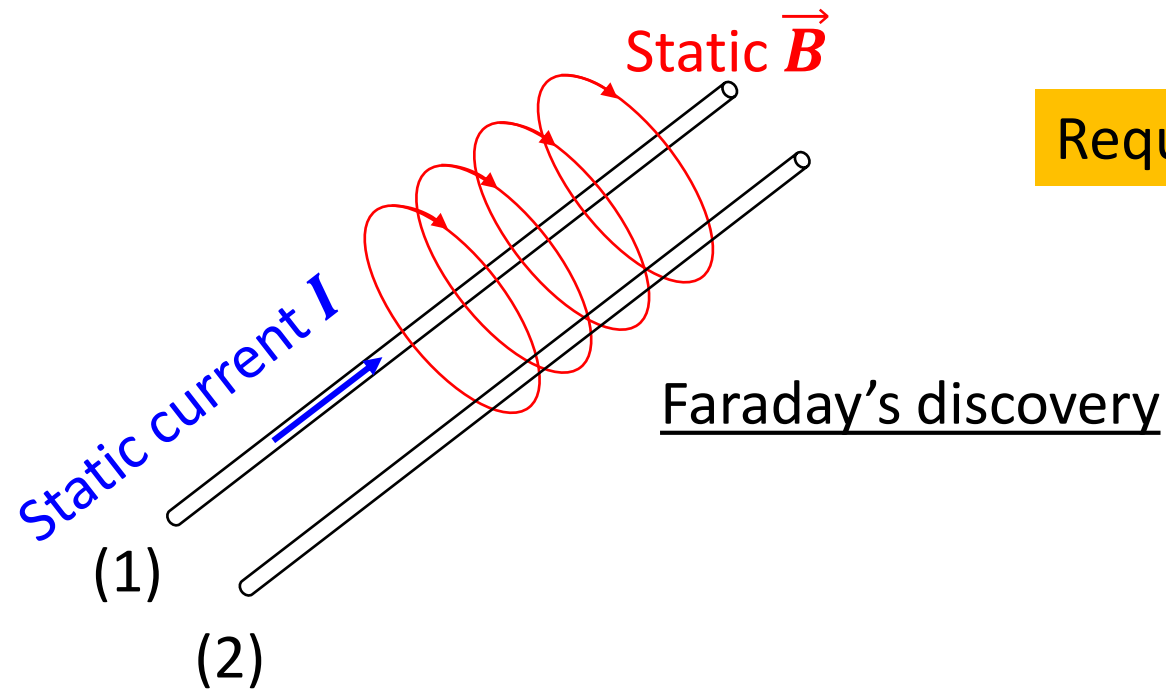
Make a sensitive instrument
for measuring current



Galvanometer

Orsted 1820: Current in a wire creates magnetic field

Faraday 1821: Magnetic field **MAY** create an electric field \Rightarrow Generating thus a current in wire (2)



Nothing appears in wire (2)

Requires that something is changing with **TIME**



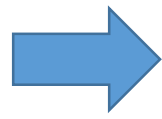
From Static to **dynamics**



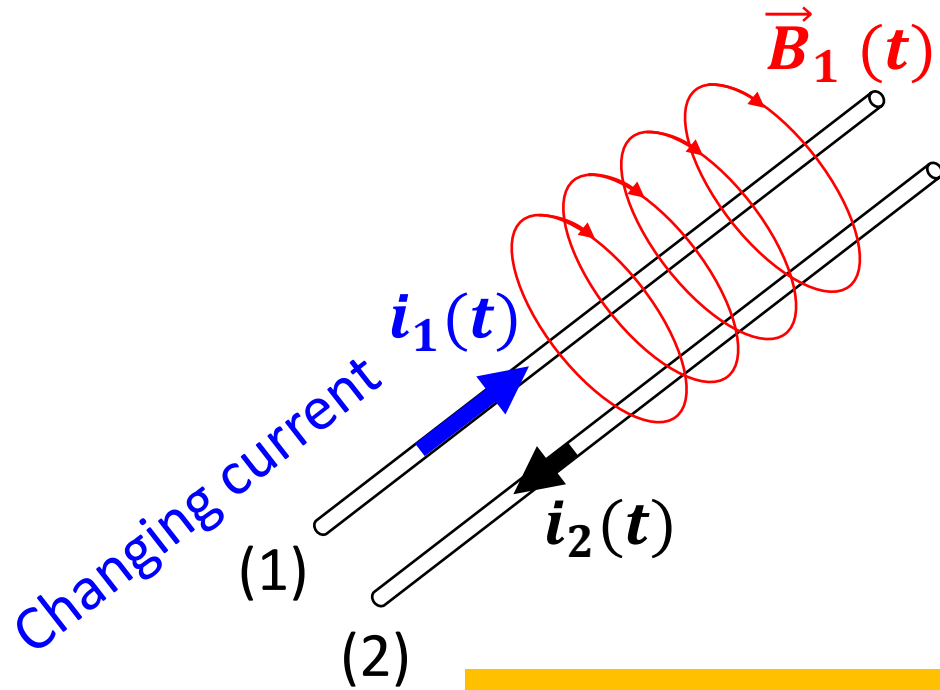
Current induction

No Current without \vec{E}

A varying current in wire (1)



A varying current $i_2(t)$ appears in wire (2)



Induction of electric field in wire (2) driving electrons creating thus a current



EMF (ElectroMotive Force)



$\vec{J}_1 = -\vec{J}_2 \longrightarrow$ Opposing magnetic field

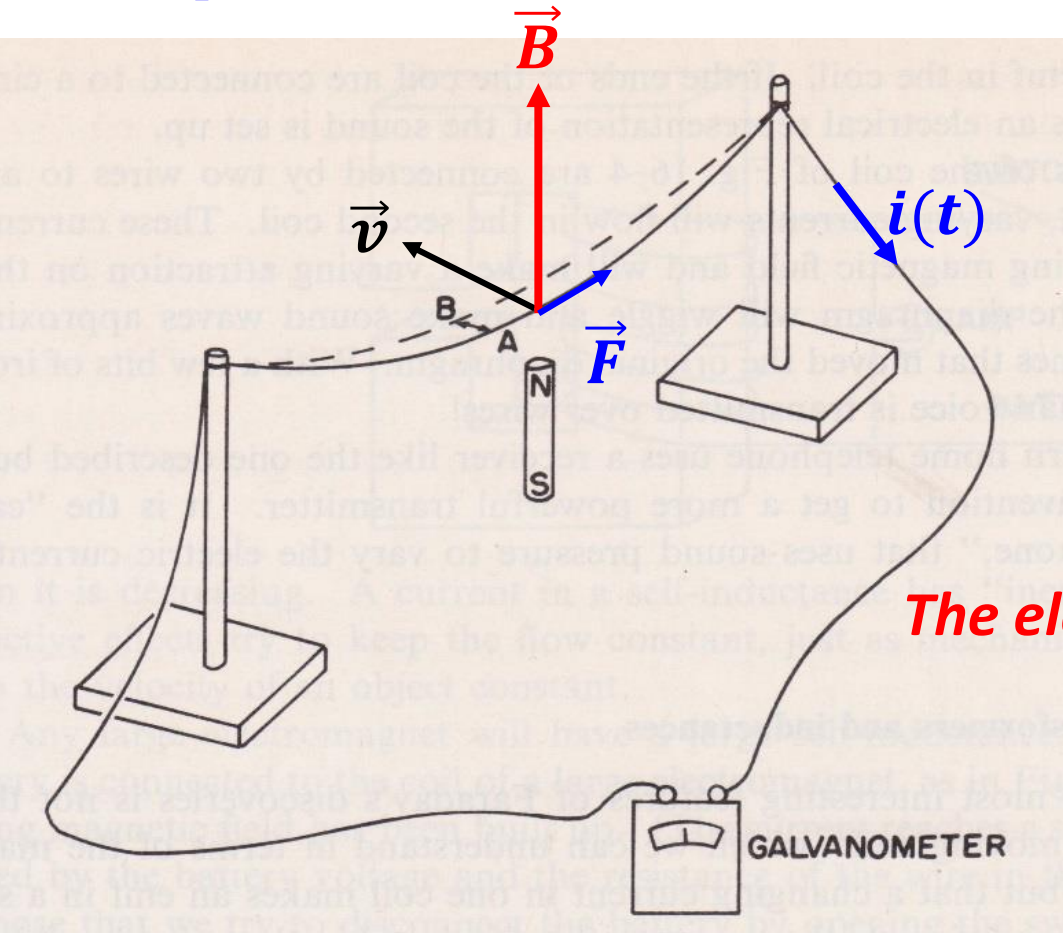
Essential feature discovered by Faraday: **Time changing processes**

Is something missing in this figure?

Yes: A second magnetic field is generated by wire (2)

Current induction: Lorentz force was not known to Faraday

$$\vec{F} = q\vec{v} \times \vec{B}$$



The electrons move by electric repulsion over long distances

\vec{v} = mechanical velocity

Current induced by Lorentz force



Concept of motional *emf*

Why the galvanometer shows a current while it is far from the Lorentz force ?

First telegraph discovered by Gauss and Weber

Another way of Current induction discovered by Faraday

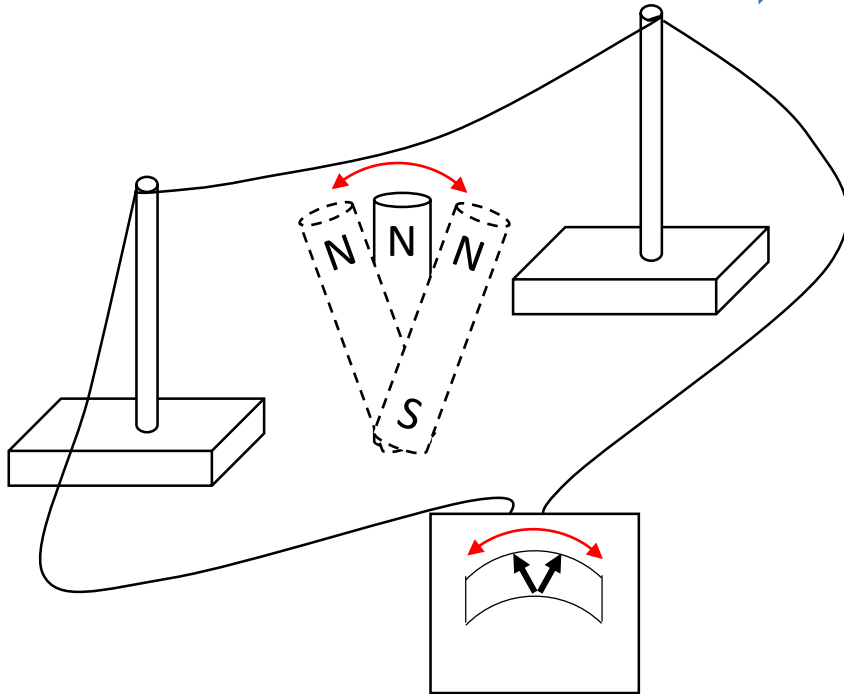
No Lorentz force



By shaking the magnet



Relativistic effect



- No current induction if magnet is static
- Current induced by change in magnetic field $\frac{\partial B}{\partial t}$

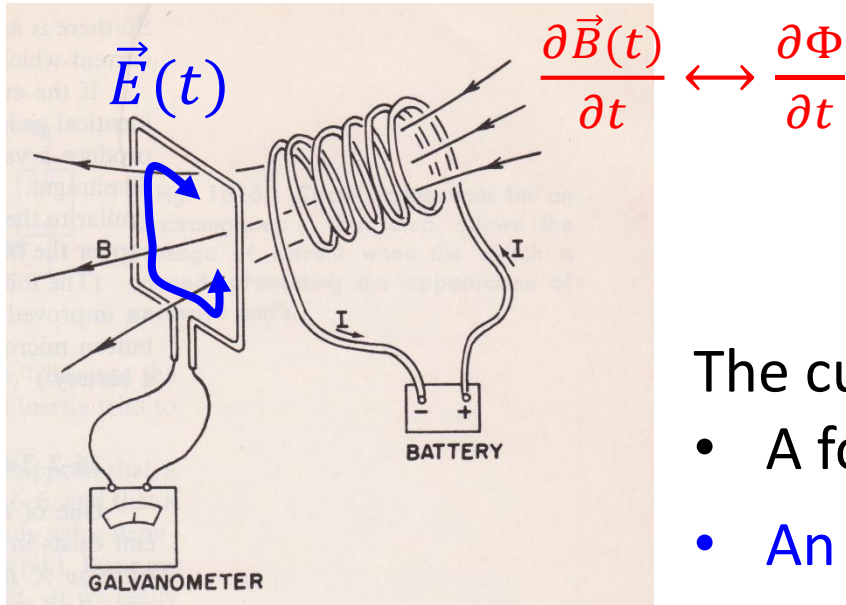


Concept of **nonmotional *emf***

Again why the galvanometer shows a current while it is far from the Lorentz force ?

There is a net integrated push around the complete circuit. This net push **MUST** come from an electric field which then leads to the repulsive push over long distance

Faraday's discovery: **emf**



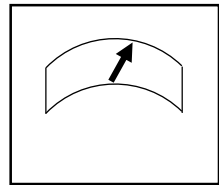
Current induced by **change in magnetic field** $\frac{\partial B}{\partial t}$

The current noticed in the loop is due to motion of electrons

- A force has pushed the electrons \Rightarrow
- An electric field has been generated by $\frac{\partial B}{\partial t}$

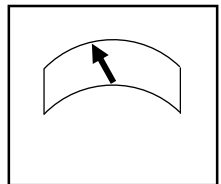
From Feynman lecture (Volume II)

1) We switch **ON** the battery



$$\vec{E}(t) \propto \frac{\partial \vec{B}(t)}{\partial t}$$

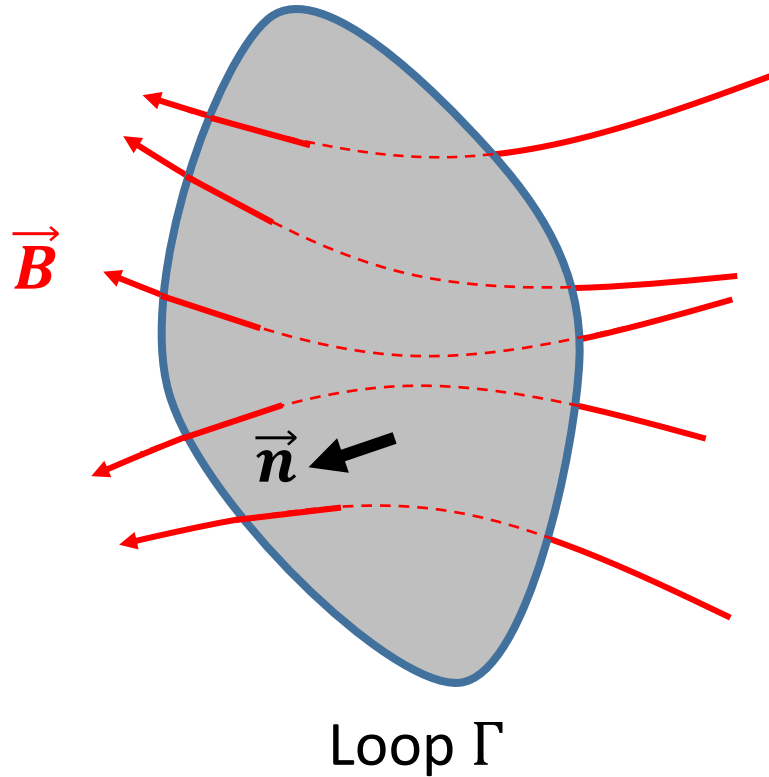
2) We switch **OFF** the battery



emf can be generated in a wire by:

- Moving mechanically the wire near a magnet or vice versa
- Changing current in a nearby wire

Faraday's rule: Is it the changing magnetic field or changing flux that matters?



$$\frac{\partial \vec{B}(t)}{\partial t} \longleftrightarrow \frac{\partial \Phi}{\partial t}$$

Area kept unchanged



$$\Phi = \int \vec{B} \cdot d\vec{A} = \int B_{\perp} dA$$

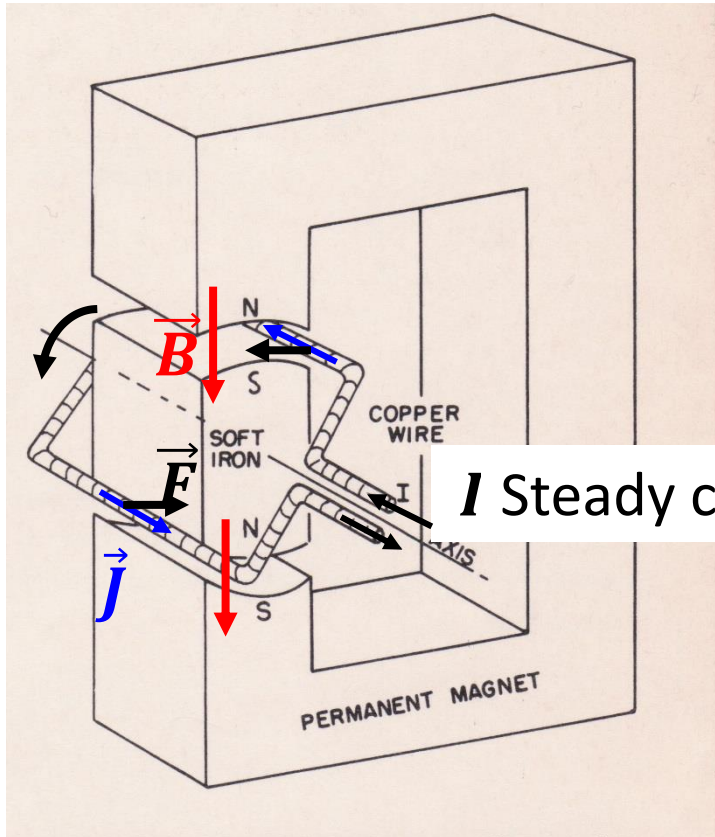
Normal component of \vec{B} integrated over the whole area of the loop

emf: ONLY and ONLY IF the flux is changing with time

- Changing \vec{B}
- Changing \vec{A}
- Changing both \vec{A} and \vec{B}

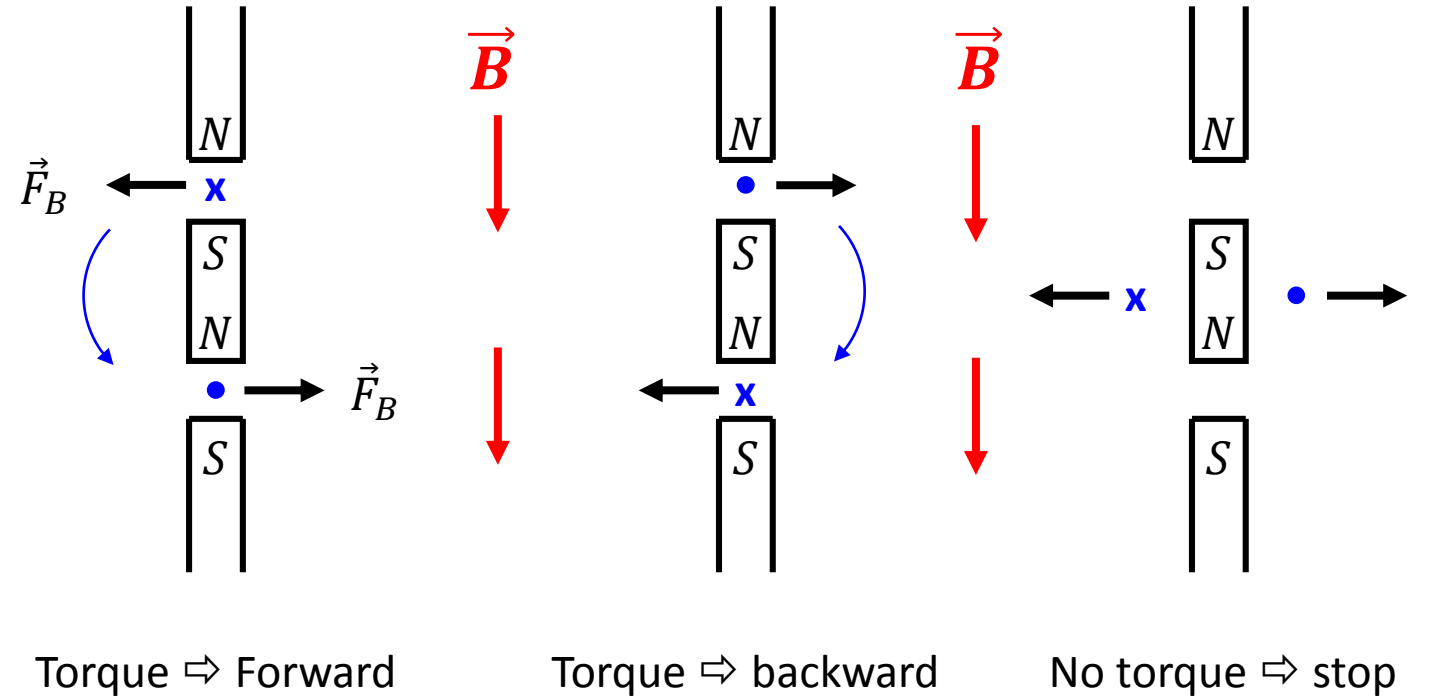
Motor

The loop rotates due to Lorentz force



I Steady current

From Feynman lecture (Volume II)



Forces acting along
the same line

Current **MUST** be reversed each half-turn
otherwise the loop stops rotating

From steady to variable current $I \rightarrow i(t)$

Alternating current generator

The loop rotates mechanically



Induction of an emf: **ElectroMotive Force**

- Area of the loop is fixed
- The normal component of $\vec{B}(t)$ is changing



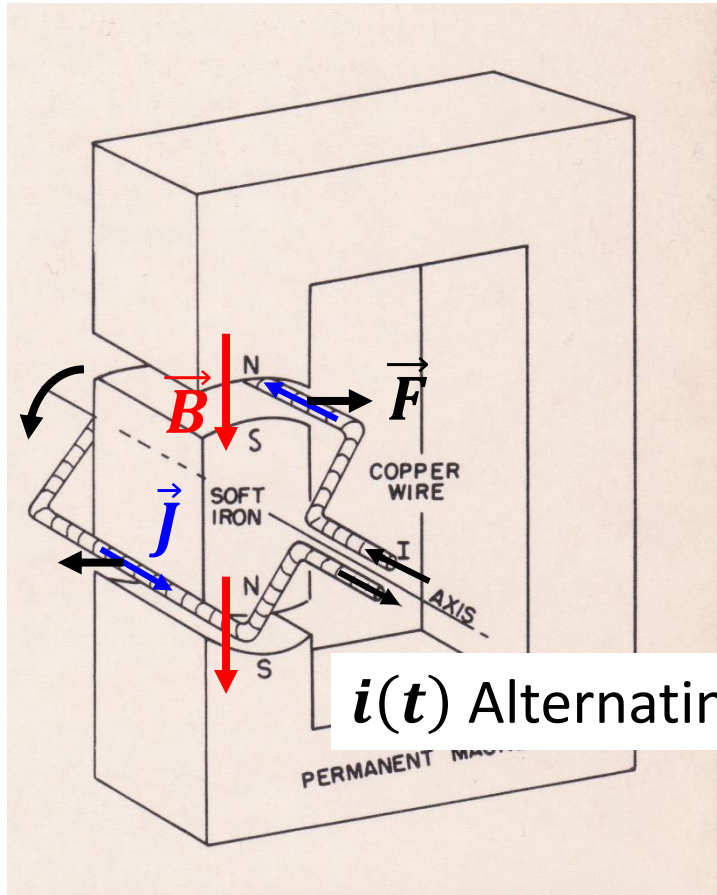
Changing flux $\Phi(t)$



Electric field generated in the wire
Circulation of $\vec{E}(t)$ along the loop



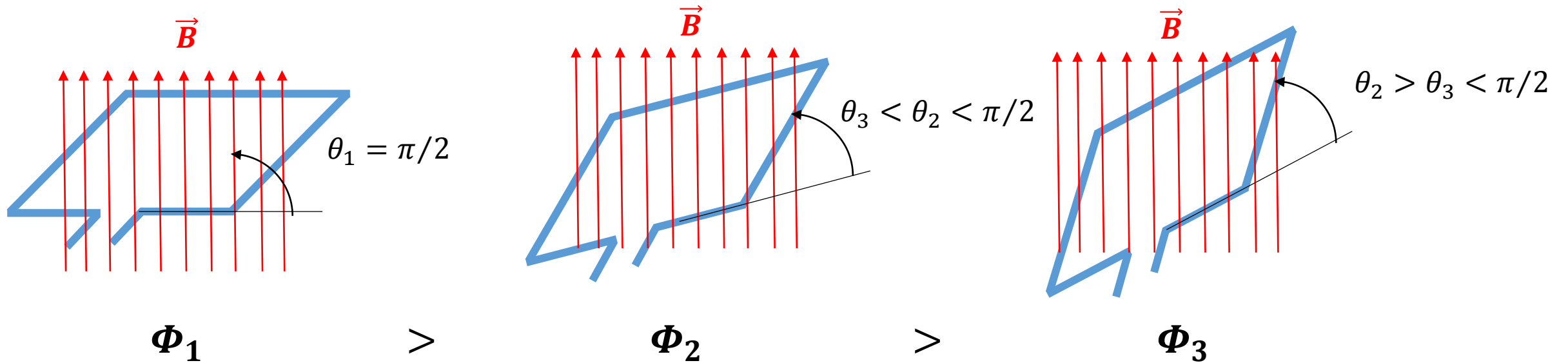
Generation of an alternating current $i(t)$ with
frequency = frequency to the mechanical rotation



$i(t)$ Alternating current

From Feynman lecture (Volume II)

Emf = rate of change of magnetic flux through the loop



What matters in the flux is the **normal component of the field** along the unit vector of the area

From Φ_1 to Φ_3

$$\frac{\partial \Phi}{\partial t} \rightarrow E(t) \rightarrow emf \rightarrow i(t)$$

Lenz's rule

- The induced emf creates a current
- This current generates a magnetic field
- This magnetic field tends to oppose the original one



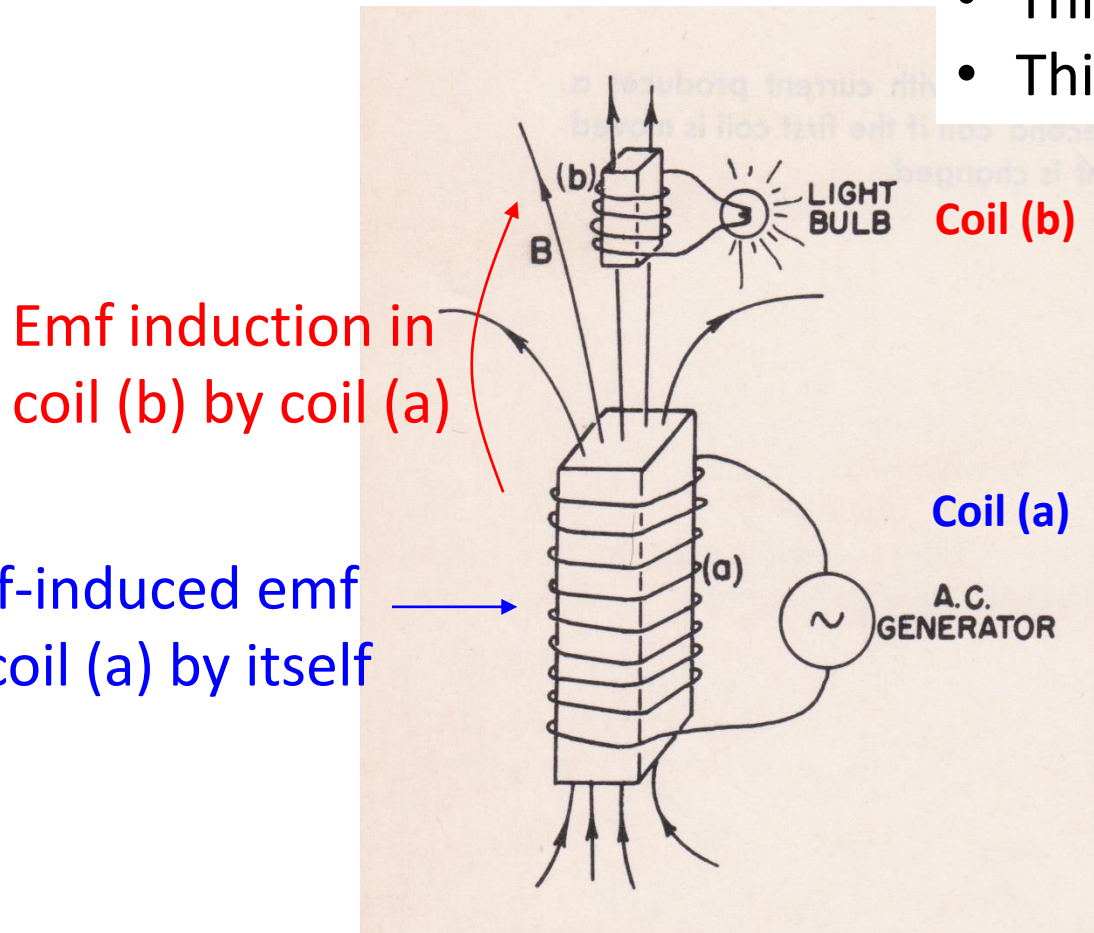
The polarity of the induced emf is **ALWAYS** such as to oppose the change of the flux of the original magnetic field

$$emf = -N \frac{d\Phi}{dt}$$

N = # of turns

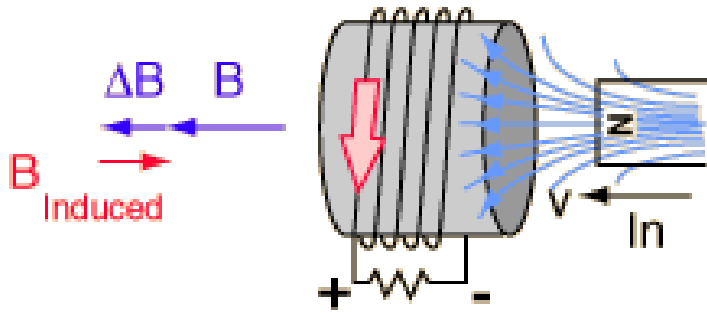
Φ = Flux of B through area A

Lenz's law



From Feynman lecture (Volume II)

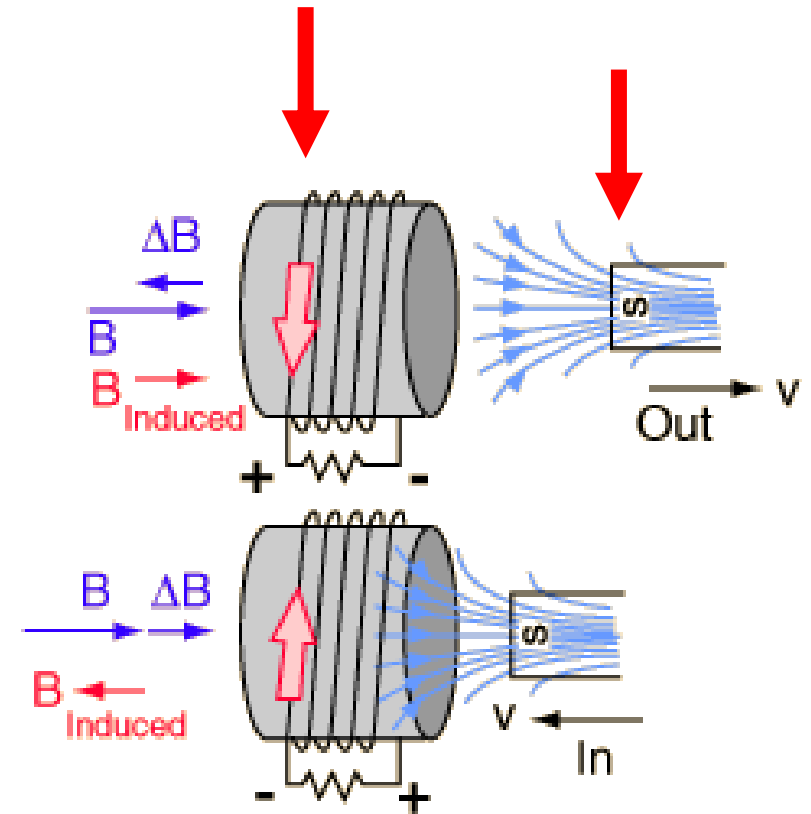
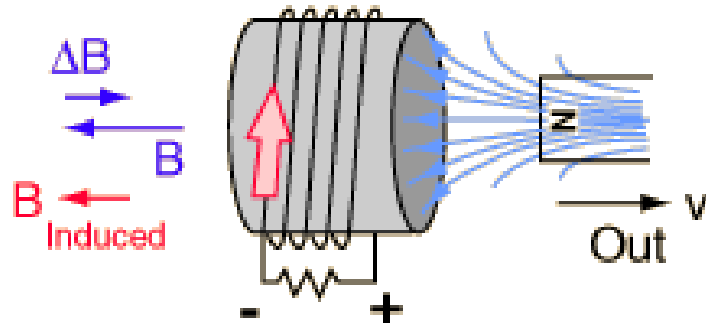
Lenz's law



Caution! Here the arrows are reversed as it is the south pole of the magnet that is moving in and out

⇒ Flux increases ⇒ B increases by ΔB

The current generated by the emf goes in a direction such as to induce a magnetic field in the opposite direction



⇒ When the flux is decreased the emf is reversed

Towards time dependent Maxwell's equations

$$\vec{\nabla} \cdot \vec{E}(t) = \frac{\rho(t)}{\epsilon_0}$$

Gauss' law

$$\vec{\nabla} \cdot \vec{B}(t) = 0$$

No magnetic charges

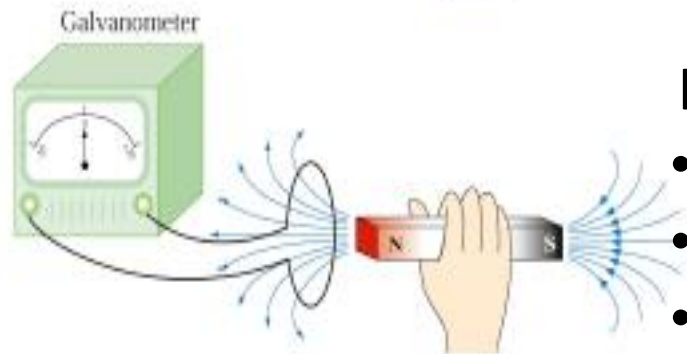
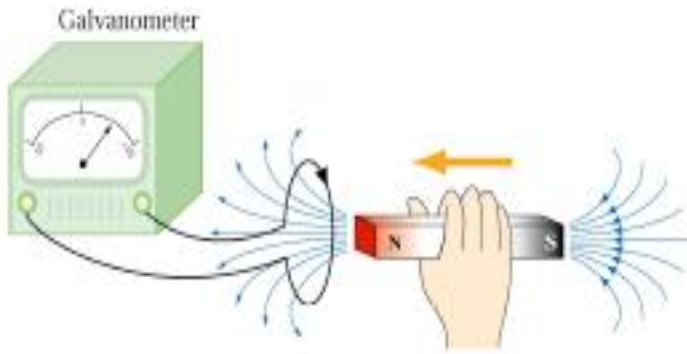
$$\vec{\nabla} \times \vec{E}(t) = -\frac{\partial \vec{B}(t)}{\partial t}$$

Faraday's law (\vec{E} is no longer conservative)

$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}(t)}{\partial t}$$

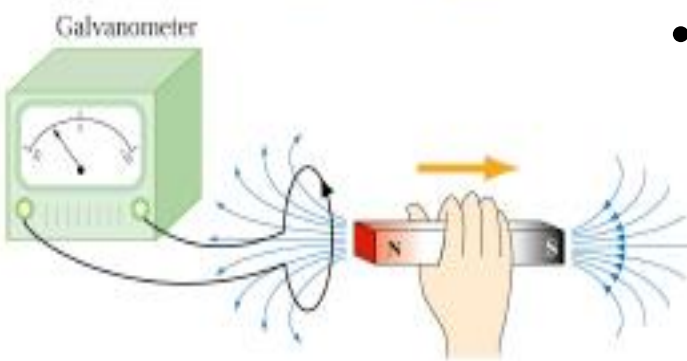
Ampere's law completed by Maxwell

Faraday's law of induction



If no motion of the loop and magnet

- **NO** change of the flux
- **NO** electric force
- **NO** motion of the free charges
- **NO** current in the loop



Relative motion induces current in the loop



There **MUST** be an induced electric field
Along the loop

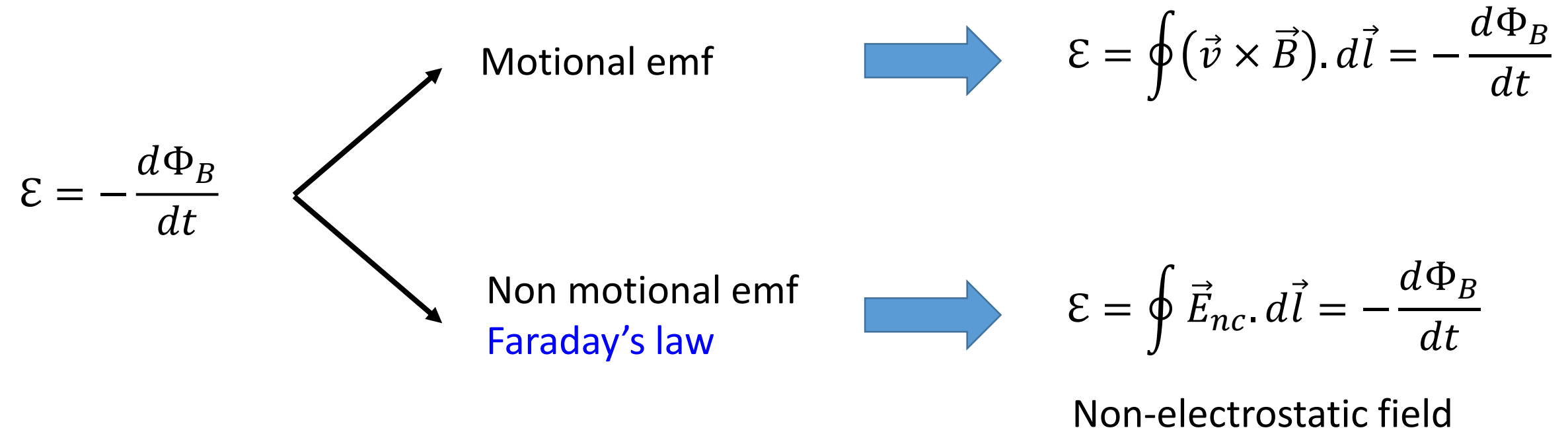


$$\oint \vec{E}_{nc} \cdot d\vec{l} \neq 0$$
$$\rightarrow i(t)$$

Electrostatic \Rightarrow Conservative field

$$\oint \vec{E}_c \cdot d\vec{l} = 0$$

Faraday's law: electromotive force



$$\oint \vec{E}_{nc} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$

Integral form

What is the link between these two relationships?

Faraday's law

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Differential form

$$\oint \vec{E}_{nc} \cdot d\vec{l} = -\frac{d\Phi_B}{dt} + \oint \vec{E}_c \cdot d\vec{l} = 0$$



$$\oint (\vec{E}_c + \vec{E}_{nc}) \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$

\vec{E} (superposition principle)

Stoke's theorem

$$\oint \vec{E} \cdot d\vec{l} = \iint (\vec{\nabla} \times \vec{E}) \cdot d\vec{A}$$

Gauss's theorem

$$-\frac{d\Phi_B}{dt} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{A} = -\iint \frac{d\vec{B}}{dt} \cdot d\vec{A}$$

$$\text{if } \frac{\partial \vec{B}}{\partial t} = \vec{0} \Rightarrow \oint (\vec{E}_c + \vec{E}_{nc}) \cdot d\vec{l} = 0$$

\parallel
 $\vec{0}$

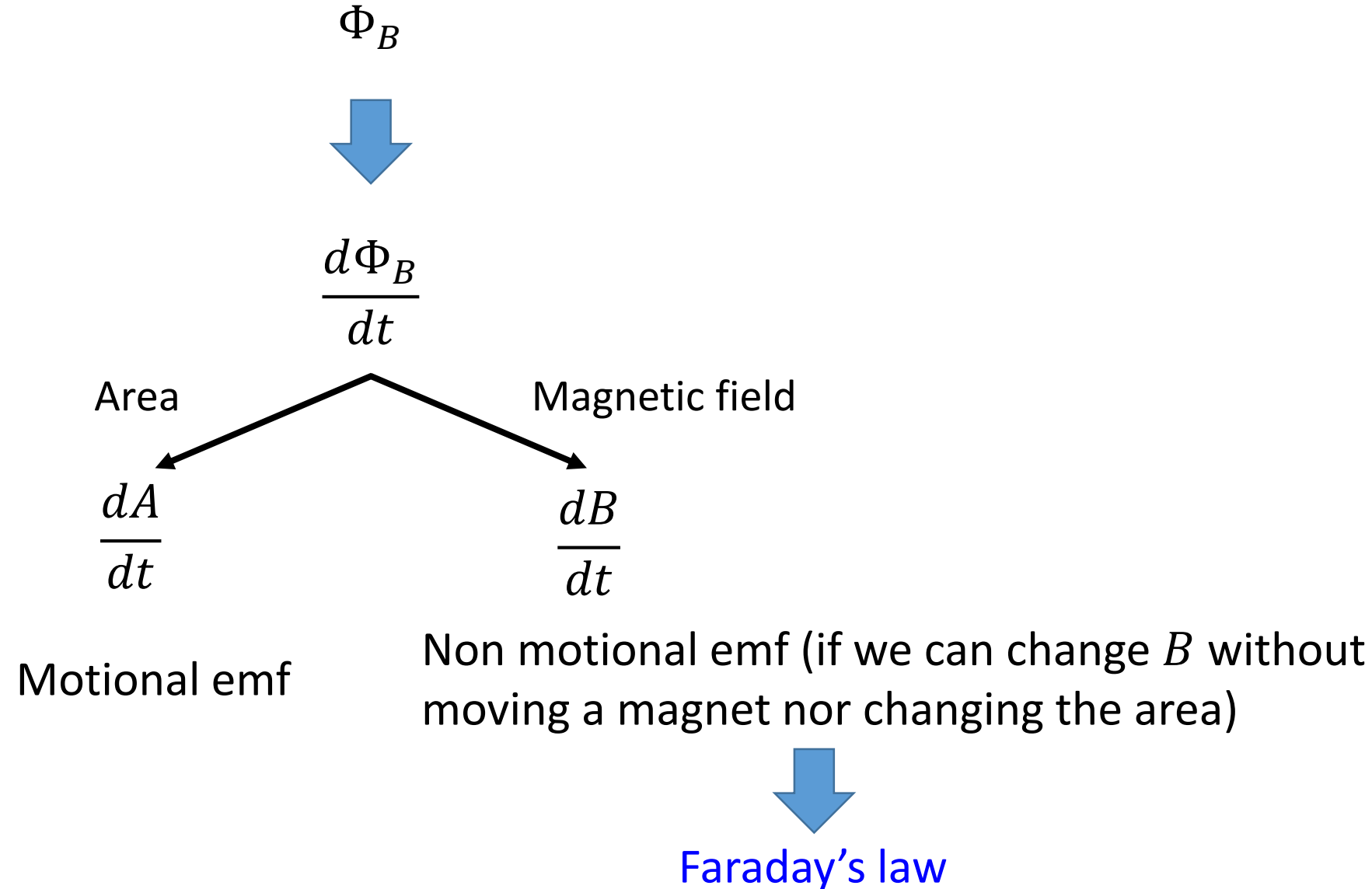


$$\vec{\nabla} \times \vec{E} = \vec{0} \quad \text{Electrostatic}$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

True always

The Heart of Faraday's law of induction



$$\frac{d\Phi_B}{dt} = \frac{dBA}{dt}$$

B constant

Part of the circuit is moving $\Rightarrow \vec{v} \times \vec{B} \neq \vec{0}$

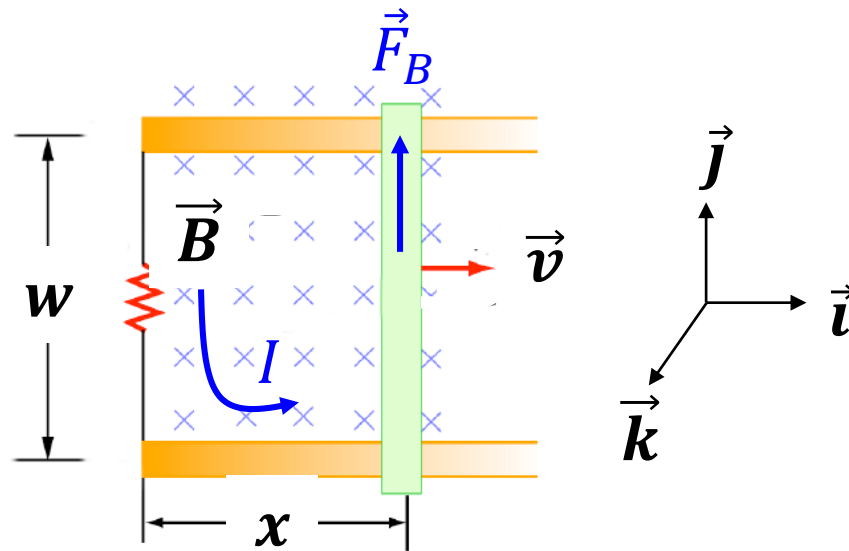
$$A \text{ changes} \Rightarrow \frac{dA}{dt} = w \frac{dx}{dt}$$

A constant

Circuit is immobile $\Rightarrow \vec{v} \times \vec{B} = \vec{0}$

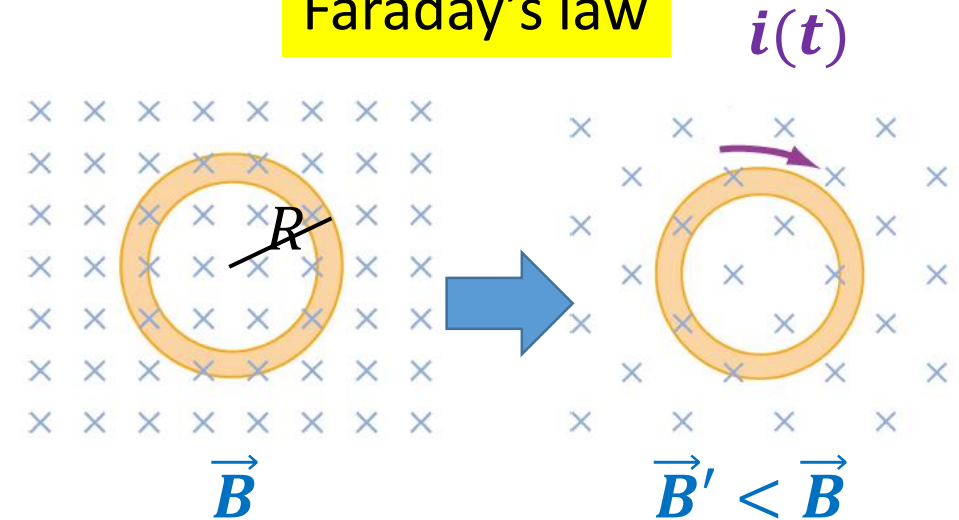
$$B \text{ changes} \Rightarrow \frac{dB}{dt} \rightarrow E(t) \rightarrow \vec{F} = q\vec{E}$$

In both cases electrons move due to Coulomb force



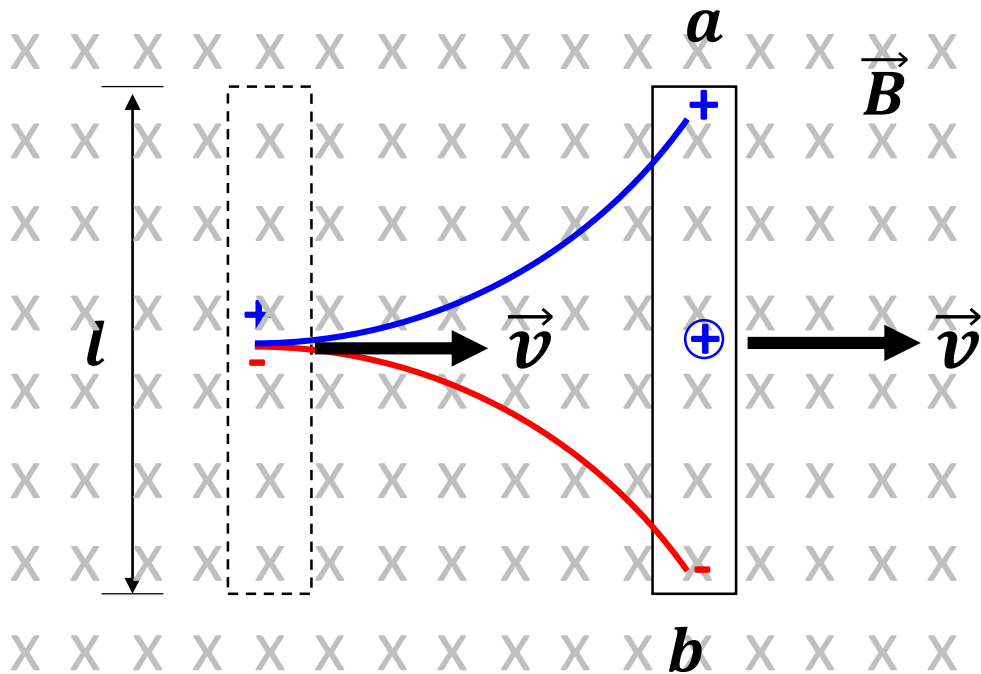
$$\text{Area } A = wx$$

Faraday's law

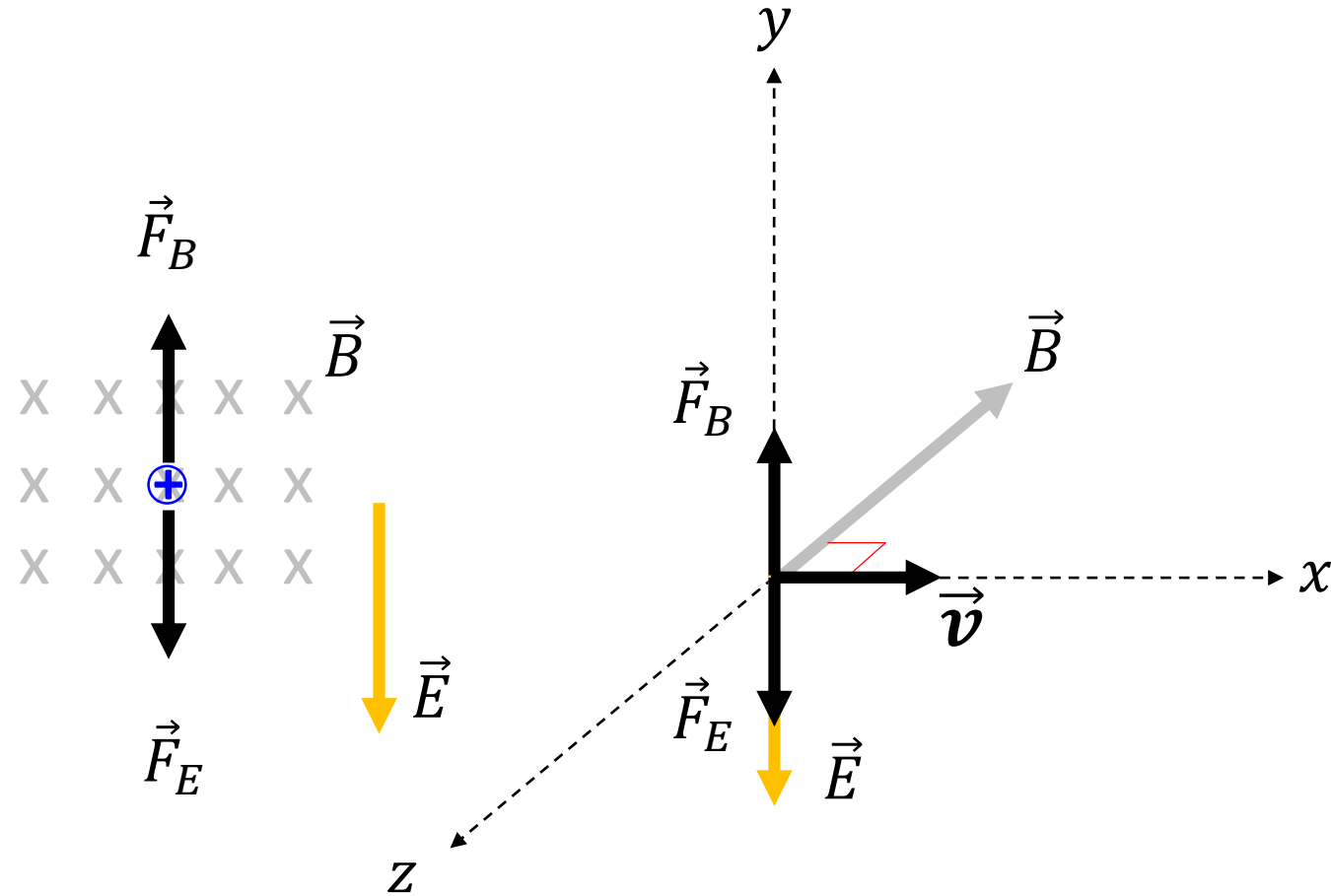


$$\text{Area } A = 2\pi R$$

Motional emf






An electric field is building up inside the conducting bar !



Equilibrium !

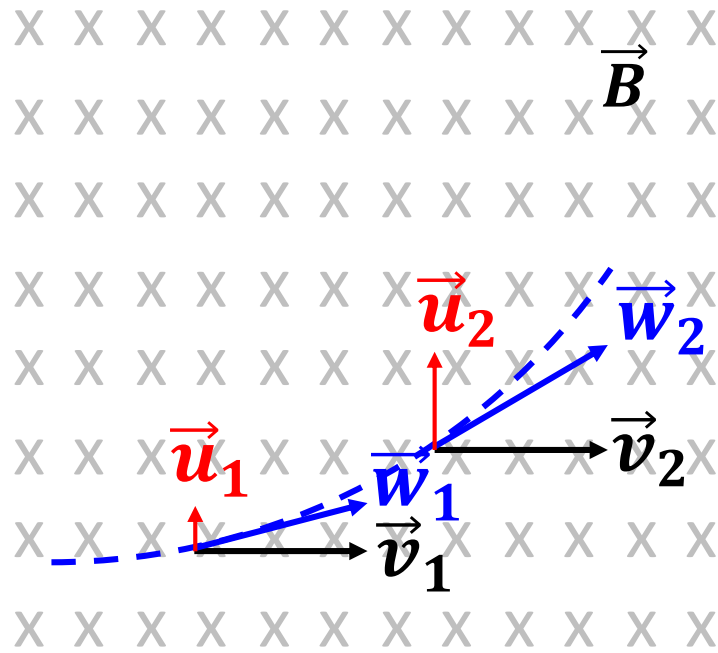
$$\vec{F}_B + \vec{F}_E = \vec{0}$$

Equilibrium  $qvB = qE$  $E = vB$  $\varphi_{ab} = \varphi_a - \varphi_b = El$

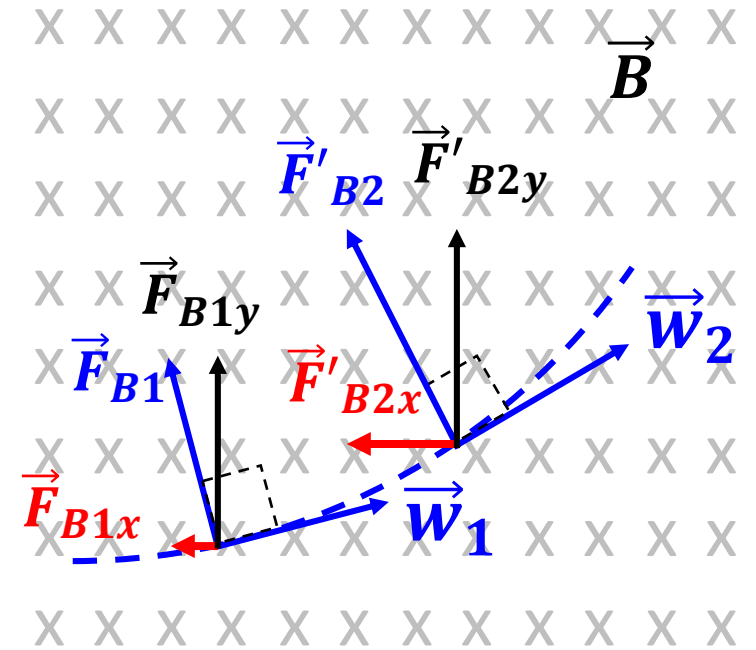
$$\varphi_{ab} = Blv$$

Motion  **Motional emf = Potential difference**  $\mathcal{E} = \varphi_{ab} = Blv$

For **Motional** emf both \mathbf{B} and \mathbf{v} are required to get a potential difference



$$\begin{aligned} \vec{F}_B &\perp \vec{w} \\ \vec{F}_{By} &\perp \vec{v} \\ \vec{F}_{Bx} &\perp \vec{u} \end{aligned}$$



None of these forces do work on the charge

BUT a force \vec{F}_{Bx} opposing the motion of the bar is building-up

Work **MUST** be done against this force to keep the bar moving at constant velocity \vec{v}

Opposite force $\vec{F}_{Bx} = -quB\vec{l}$

Work done per unit charge against this force must be $\frac{\Delta W}{q} = - \int_x^{x+\Delta x} -uB\vec{l} \cdot d\vec{x}$

$$\frac{\Delta W}{q} = -\Delta\varphi = \varphi_{ab} = - \int_x^{x+\Delta x} -uBdx = uB\Delta x$$

$$\Delta x = v\Delta t$$



$$\Delta x = \frac{v\Delta l}{u}$$



$$\Delta l = u\Delta t$$

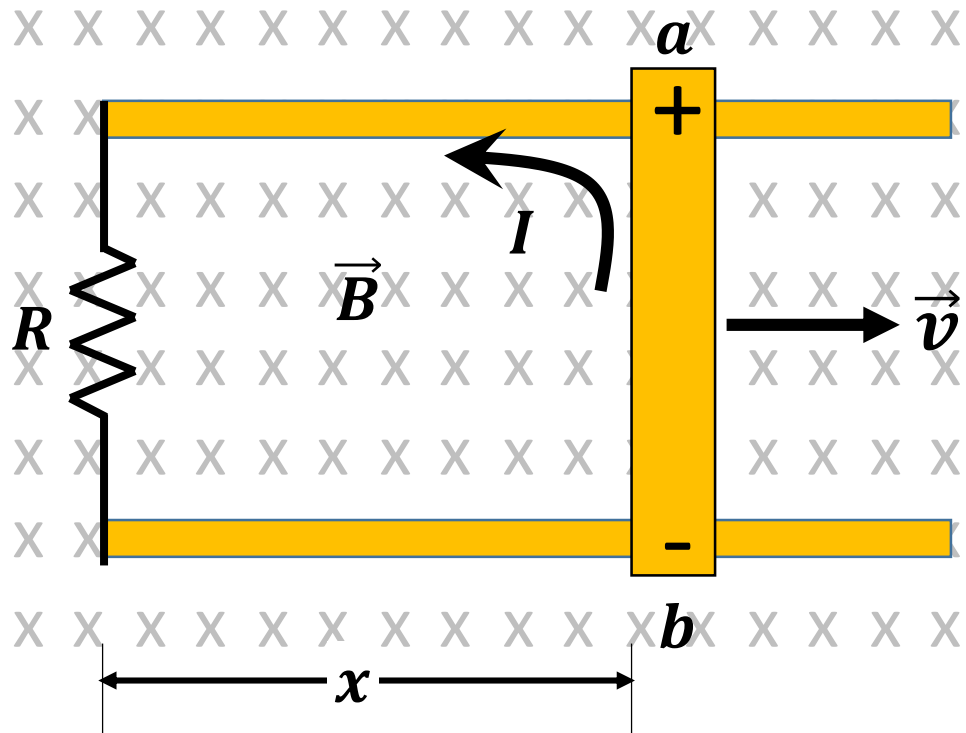
$$\frac{\Delta W}{q} = -\Delta\varphi = \varphi_{ab} = \mathcal{E} = Blv$$

Motional emf found in slide # 22

This work is useless because the circuit is **not complete** !

The circuit is complete and the bar moves at constant velocity

The charges will **no longer accumulate** at the ends of the bar and a current is generated
Counterclockwise: The motion of the charges in the circuit is due to coulomb repulsion

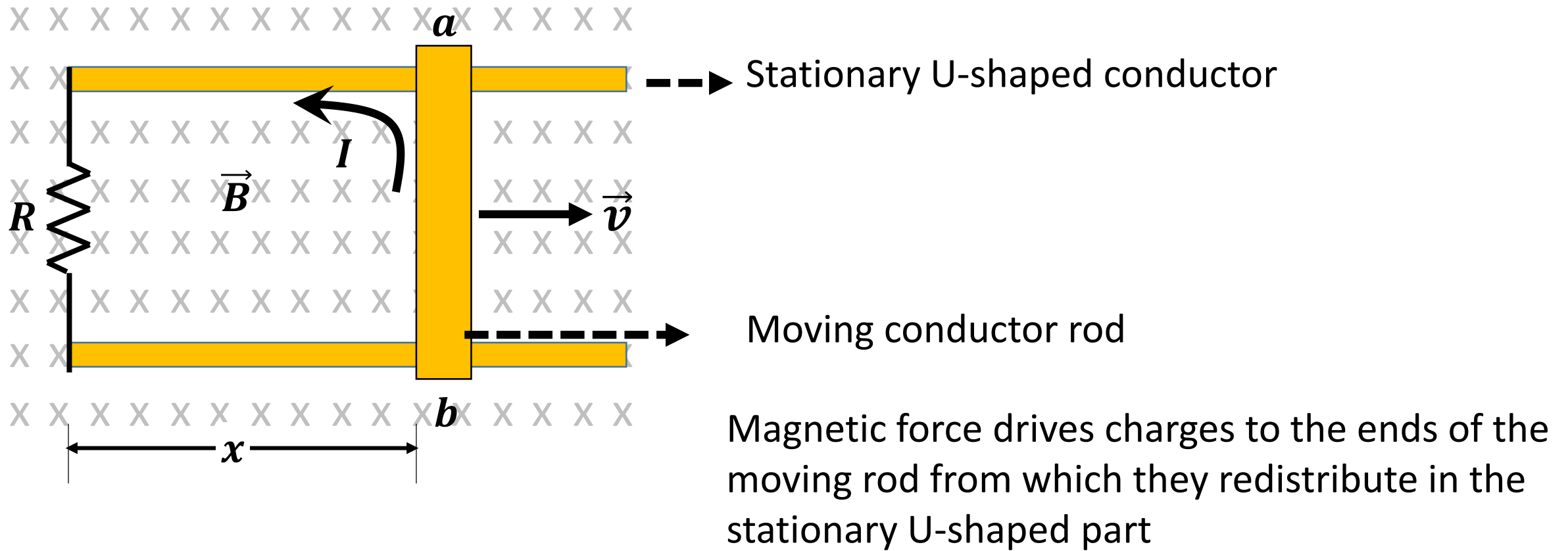


Question: Why putting a resistance R in the circuit ?

Answer: To reduce the current to a minimum in order to avoid generating an important magnetic field which may then disturb the external one

Remember: In electrostatic the test charge must be weak enough to avoid perturbing the source

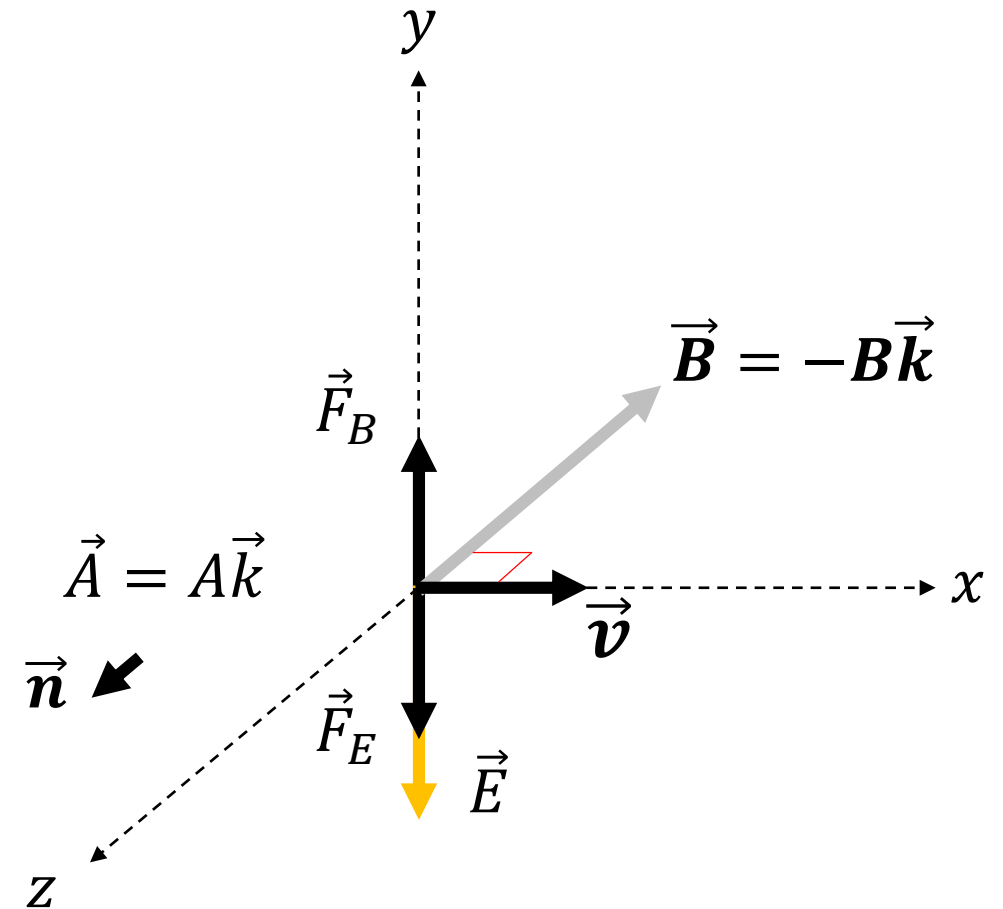
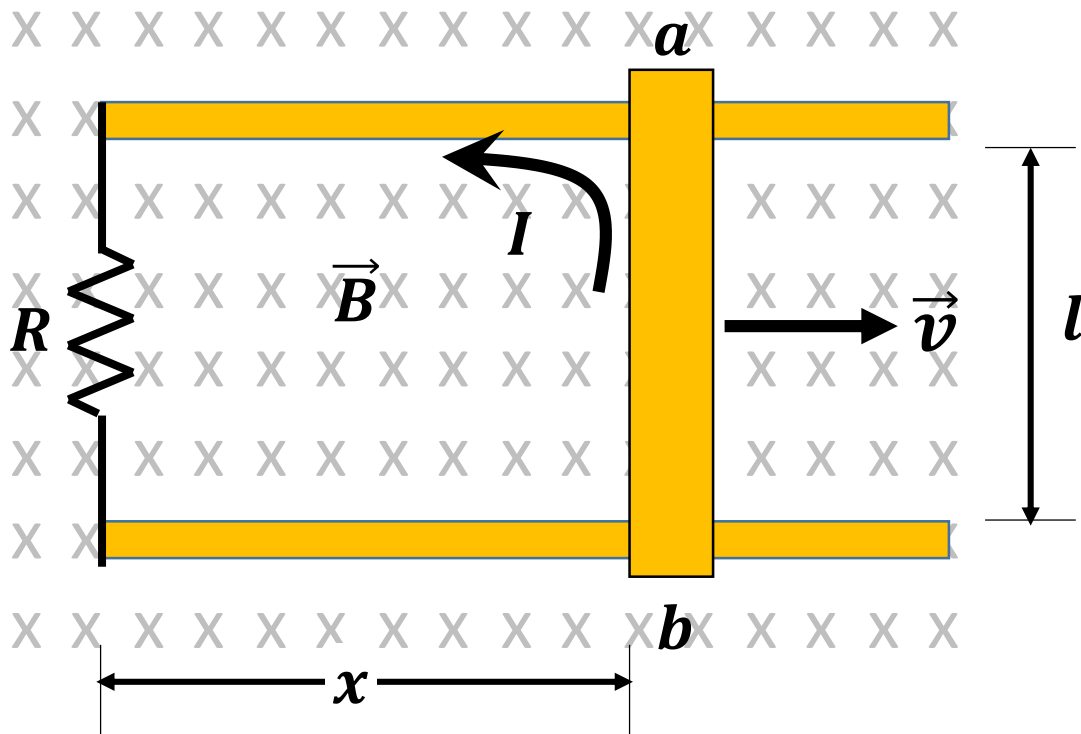
The circuit is complete and the bar moves at constant velocity



Moving rod = source of electromotive force

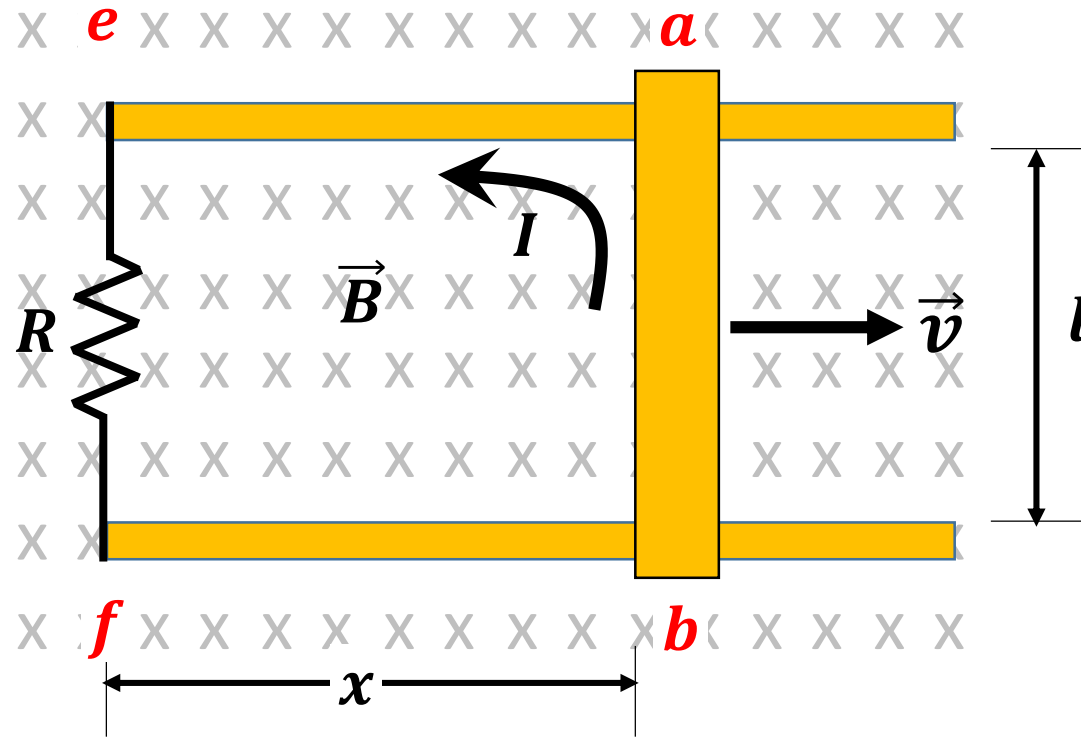
Faraday's law: electromotive force

$$\mathcal{E} = -\frac{d\Phi_B}{dt}$$



The magnetic flux changes because the area of the circuit is changing

$$\Phi_B = \vec{B} \cdot \vec{A} = -Blx \quad \Rightarrow \quad \frac{d\Phi_B}{dt} = \frac{d}{dt}(-Blx) = -Bl \frac{dx}{dt} \quad \Rightarrow \quad \frac{d\Phi_B}{dt} = -Blv$$



$$\frac{d\Phi_B}{dt} < 0$$

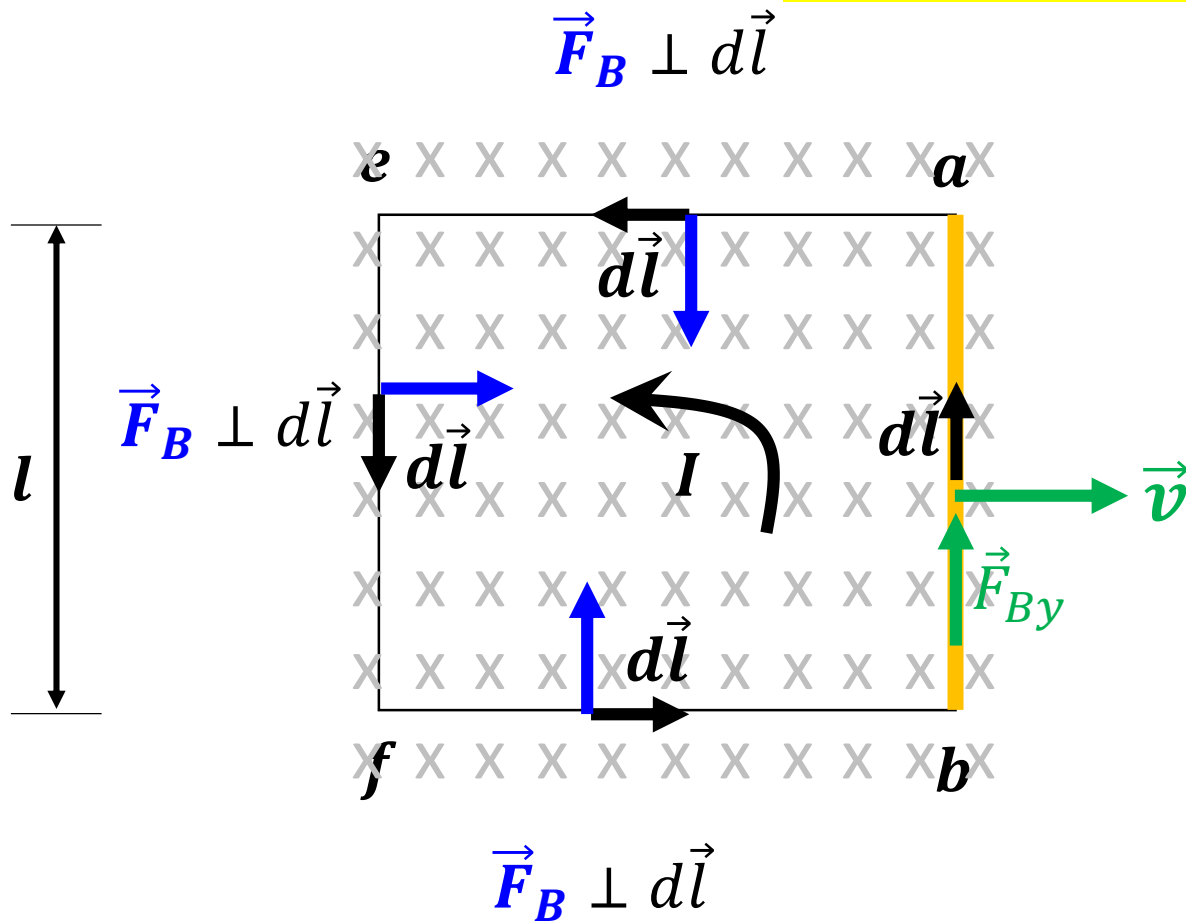
The closed path for the charges is $aefb$

From slides # 17

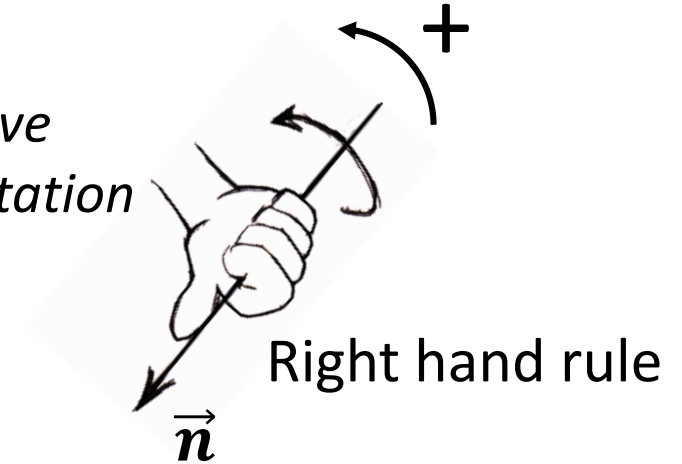
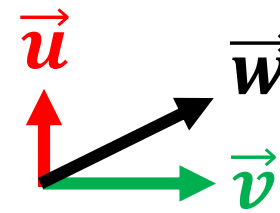
$$\mathcal{E} = -\frac{d\Phi_B}{dt}$$

The magnetic field generated by the induced current opposes the original

The electromotive force



Conventional positive trigonometry orientation



$$\vec{F}_{By} = q\vec{v} \times \vec{B} = qv\vec{i} \times B(-\vec{k}) = qvB\vec{j}$$

$\vec{F}_B \parallel d\vec{l}$ along the moving rod

The only contribution is along the moving bar

Slide #17

$$\varepsilon = \oint \frac{\vec{F}_{By}}{q} \cdot d\vec{l} = \oint vB\vec{j} \cdot dy\vec{j}$$

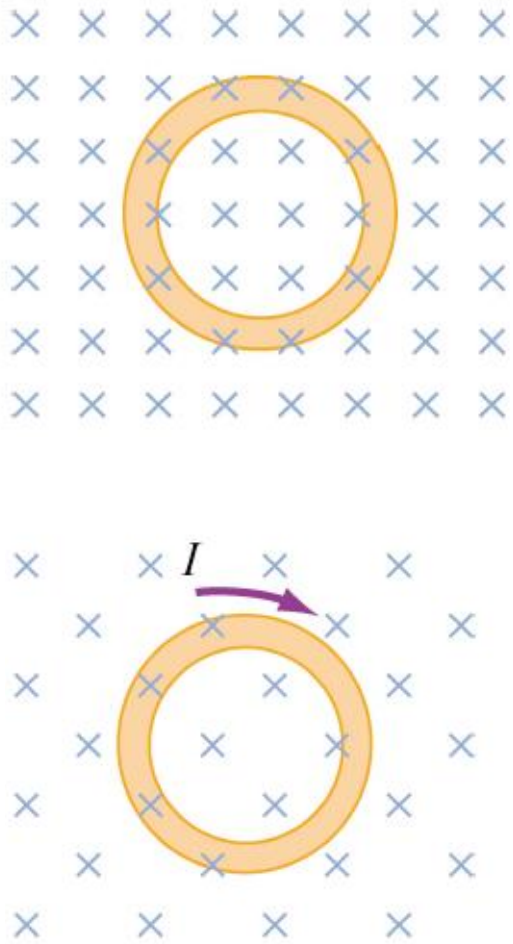
$$\varepsilon = Blv$$

Stationary closed conducting path (coil)

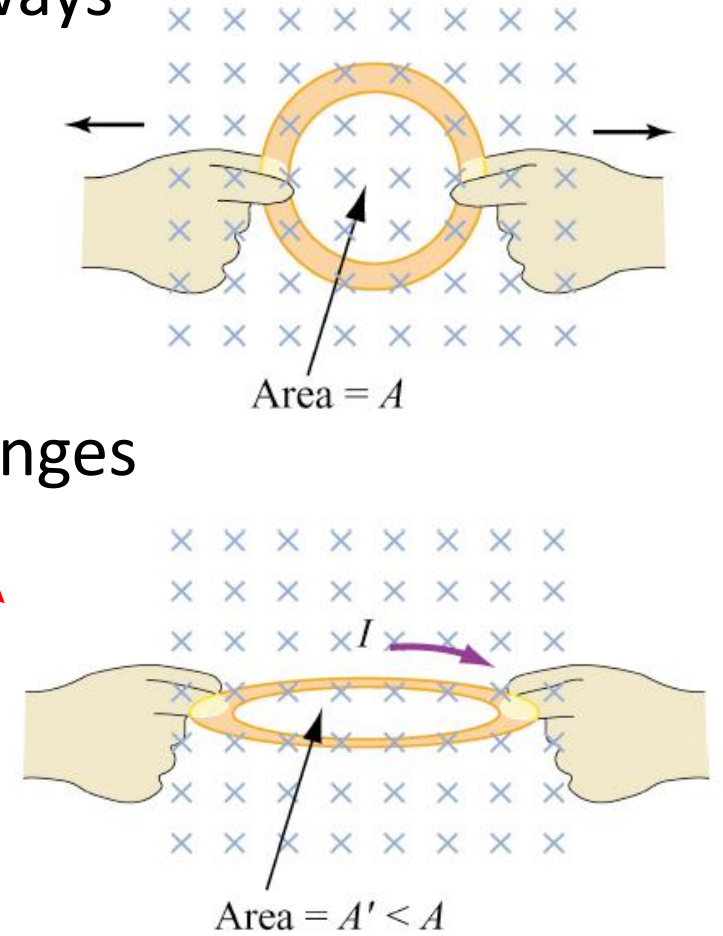
The flux can change following two ways

$$\Phi_B = \vec{B} \cdot \vec{A}$$

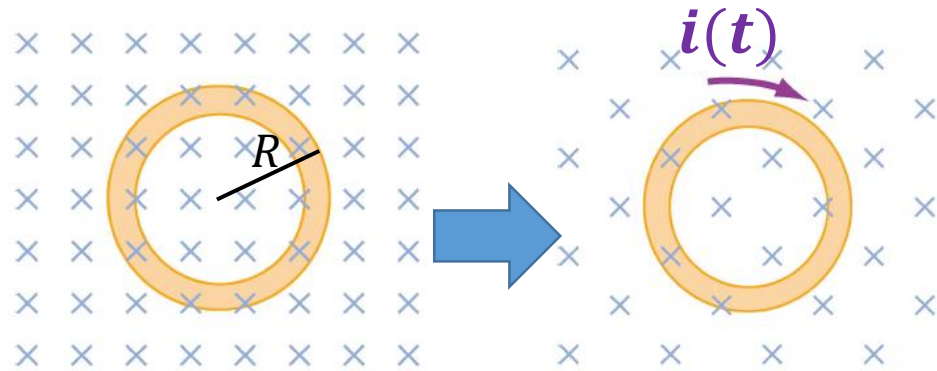
\vec{B} changes



\vec{A} changes



Genius conjecture of Faraday



\vec{B}

$$\frac{d\Phi_B}{dt} < 0$$

$B' < B$

The circuit is immobile $\Rightarrow \vec{v} = \vec{0} \Rightarrow \vec{F}_B = \vec{0}$

$$\vec{F} = q(\vec{E} + \underbrace{\vec{v} \times \vec{B}}_{\parallel \vec{0}})$$

$$\frac{d\Phi_B}{dt} \longrightarrow$$

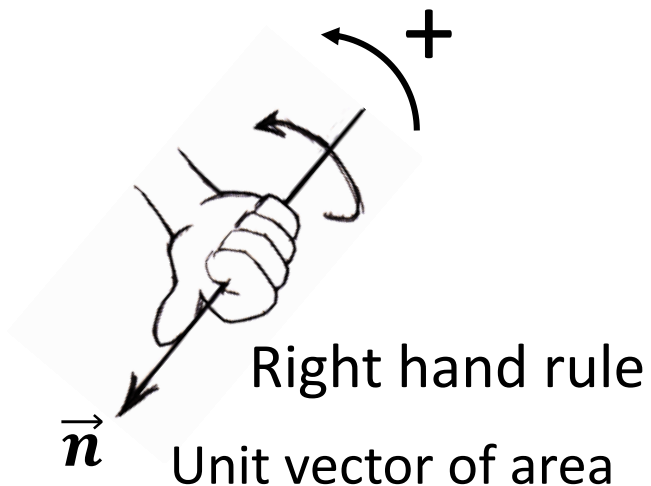
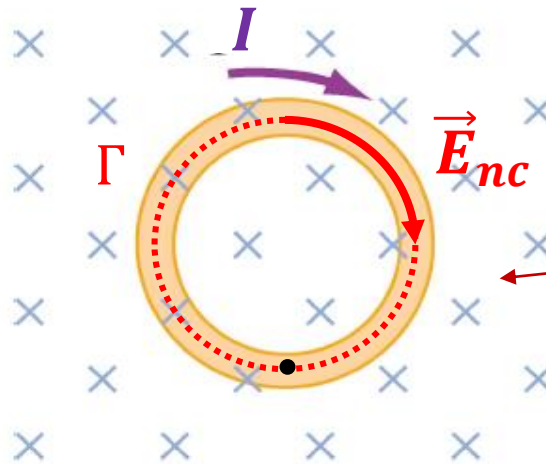
$$\mathcal{E}(\text{emf}) = \oint_{\Gamma} \vec{E}_{nc} \cdot d\vec{l}$$

Slide #17

Faraday's Conjecture

$$\vec{E} \perp \vec{B}$$

\vec{E}_{nc} circulates tangentially to the loop



Electromotive force for both motional and non motional case

$$\mathcal{E} = \oint (\vec{v} \times \vec{B}) \cdot d\vec{l}$$

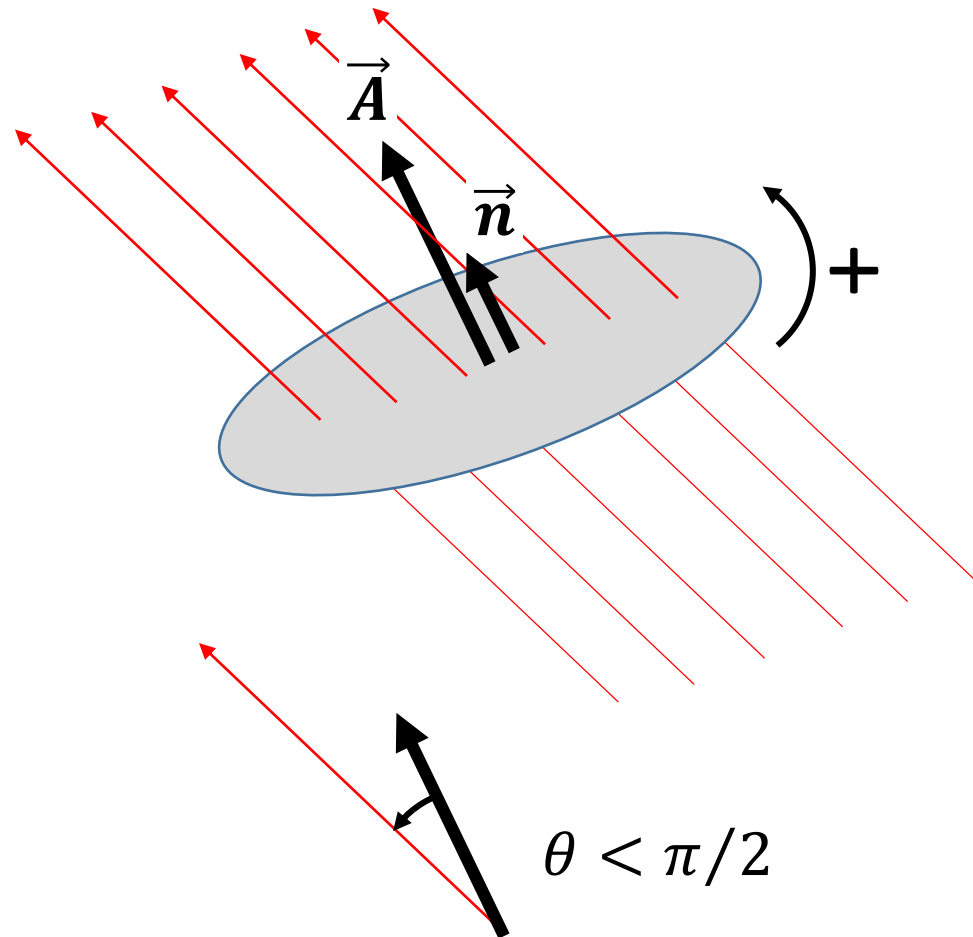
For motional electromotive force

$$\mathcal{E} = - \frac{d\Phi_B}{dt} = \oint_{\Gamma} \vec{E}_{nc} \cdot d\vec{l}$$

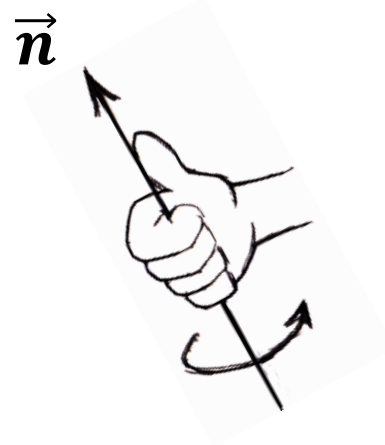
For non-motional electromotive force:
Faraday's law

Lenz's law

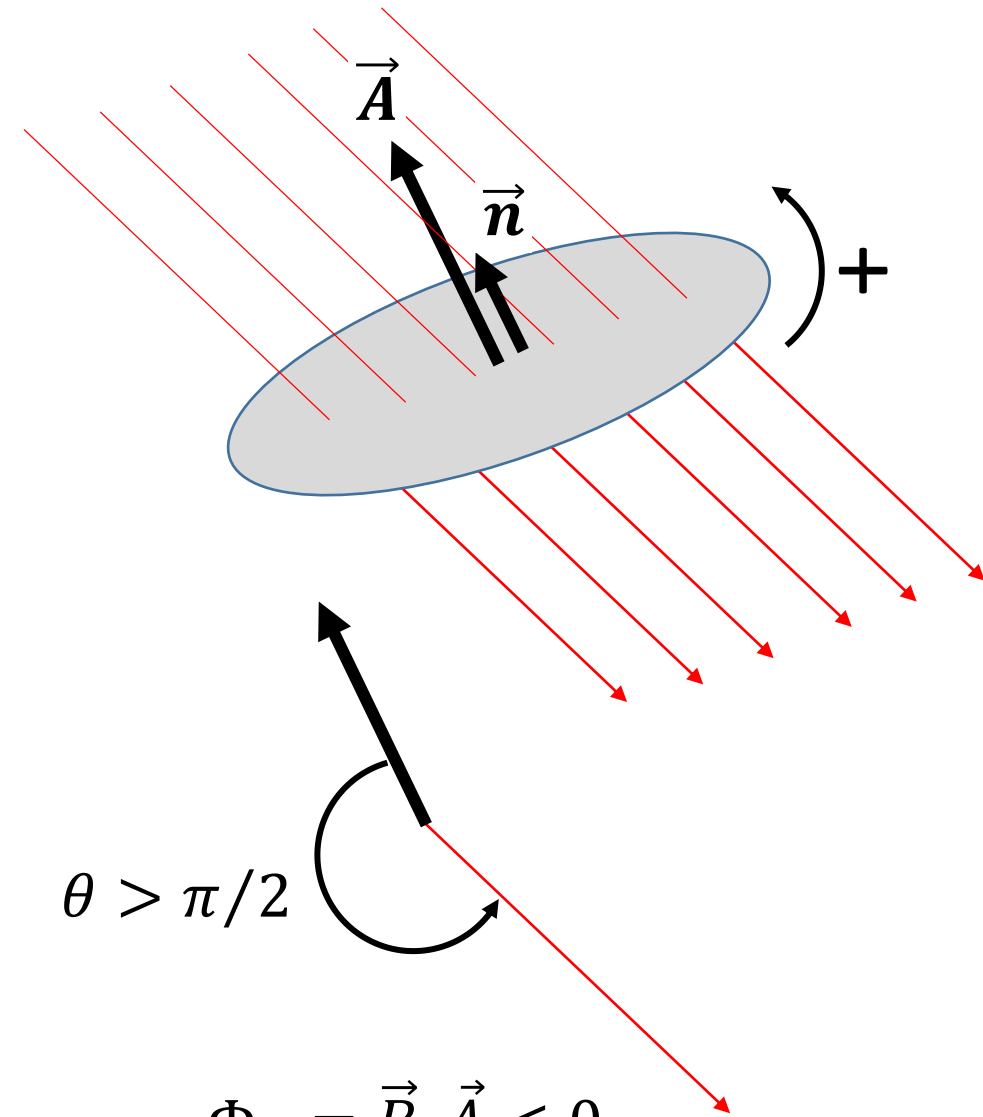
Lenz's law and sign convention for emf



$$\Phi_B = \vec{B} \cdot \vec{A} > 0$$

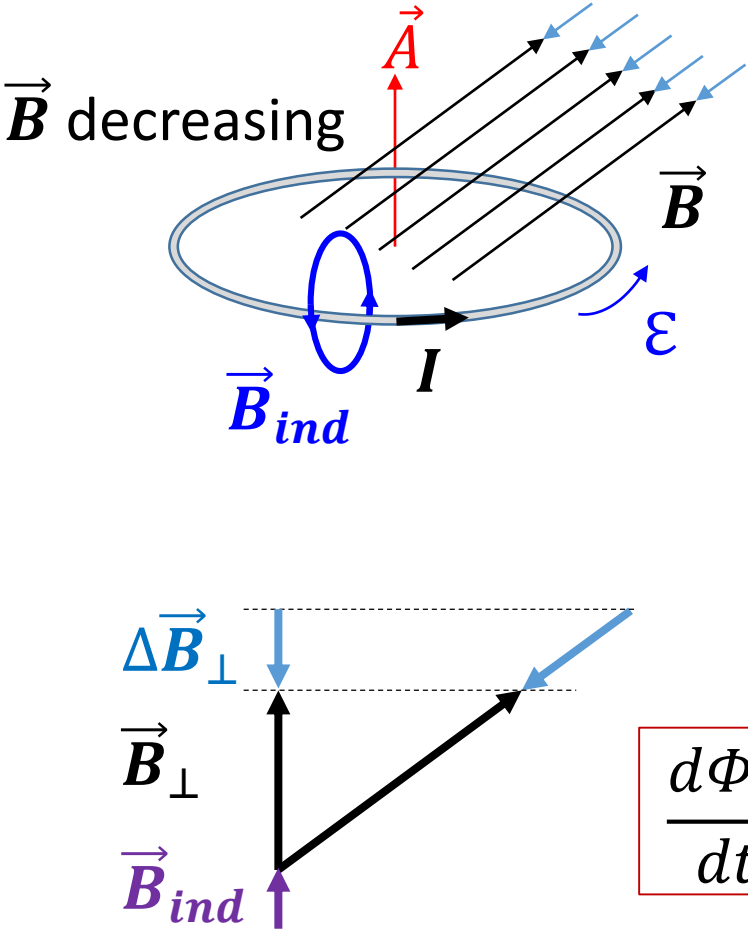
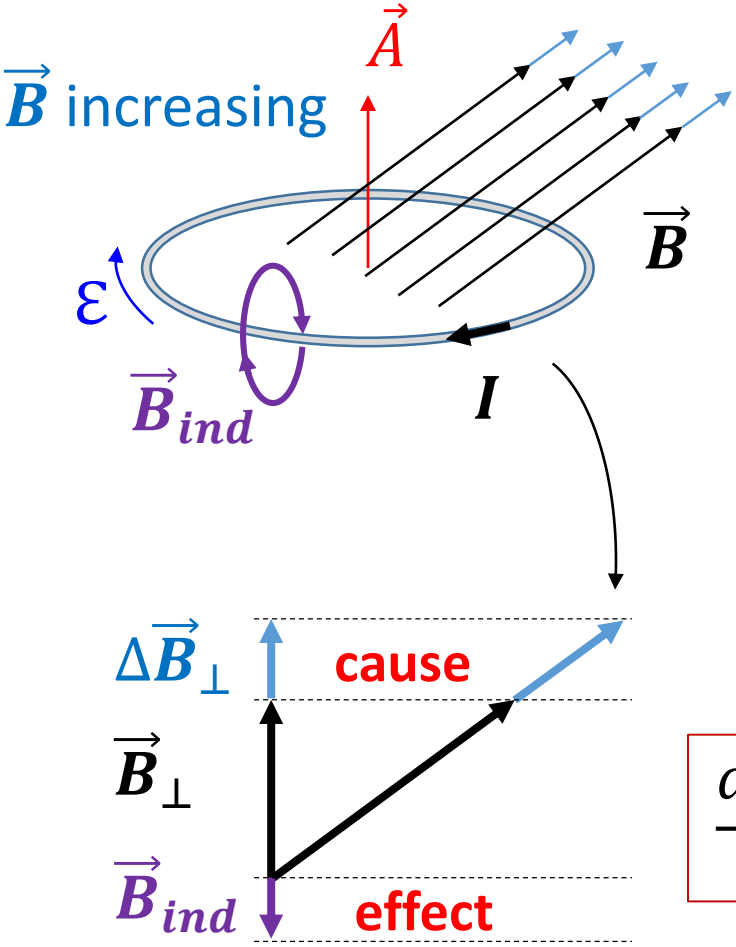


$$\vec{A} \equiv \textit{thumb}$$

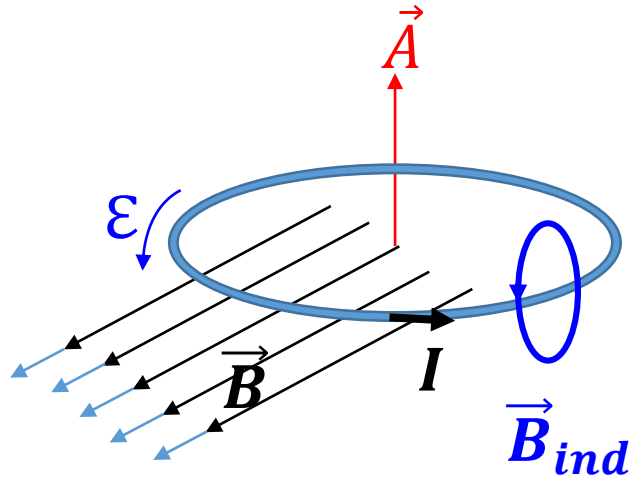


$$\Phi_B = \vec{B} \cdot \vec{A} < 0$$

$\cos\theta > 0$
 $\Phi_B > 0$



Induced emf \Rightarrow induces current \Rightarrow induces \vec{B}_{ind} \Rightarrow opposing the **cause of the effect**

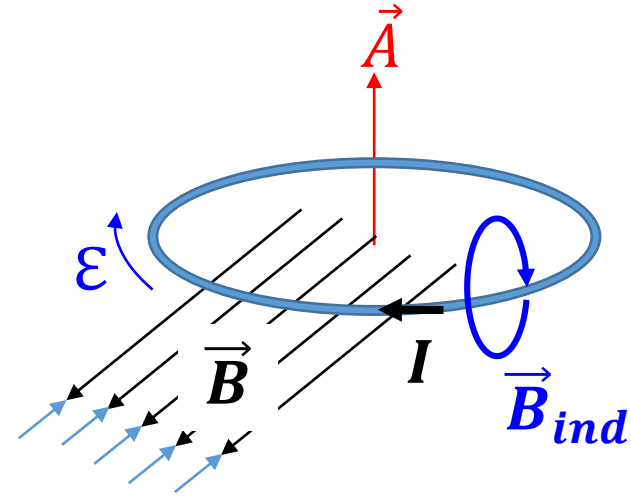


\vec{B} increasing

$$\frac{d\Phi_B}{dt} < 0$$

$$\cos\theta < 0$$

$$\Phi_B < 0$$



\vec{B} decreasing

$$\frac{d\Phi_B}{dt} > 0$$

\vec{B}_\perp parallel \vec{A}

$$\Phi_B = \vec{B} \cdot \vec{A} > 0$$
$$\theta < \pi/2$$

$$\frac{d\Phi_B}{dt} > 0$$

$$\frac{d\Phi_B}{dt} < 0$$

\vec{B}_\perp anti-parallel \vec{A}

$$\Phi_B = \vec{B} \cdot \vec{A} < 0$$
$$\theta > \pi/2$$

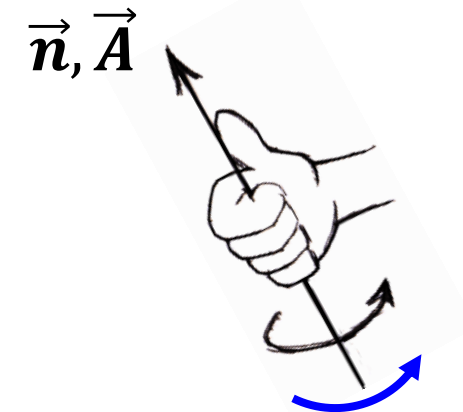
$$\frac{d\Phi_B}{dt} > 0$$

$$\frac{d\Phi_B}{dt} < 0$$



$$\mathcal{E} < 0$$

$\vec{A} \equiv \text{thumb}$



$$\mathcal{E} > 0$$

$\vec{A} \equiv \text{thumb}$

Summarizing Faraday's law

$$\mathcal{E} = -\frac{d\Phi_B}{dt}$$



$$\oint \vec{E}_{nc} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$



$$\oint \underbrace{(\vec{E}_c + \vec{E}_{nc})}_{\vec{E}} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$



Stoke's theorem

+

Gauss's theorem

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Faraday



Varying **magnetic field** gives rise to an induced **electric field**



Maxwell



Remarkable symmetry of nature

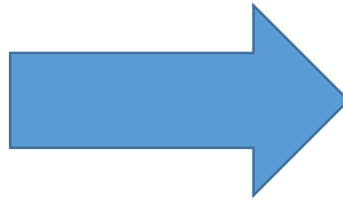


Varying **electric field** field gives rise to an induced **magnetic field**

Varying **electric field** gives rise to an induced **magnetic field**

$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J}$$

Ampere's law



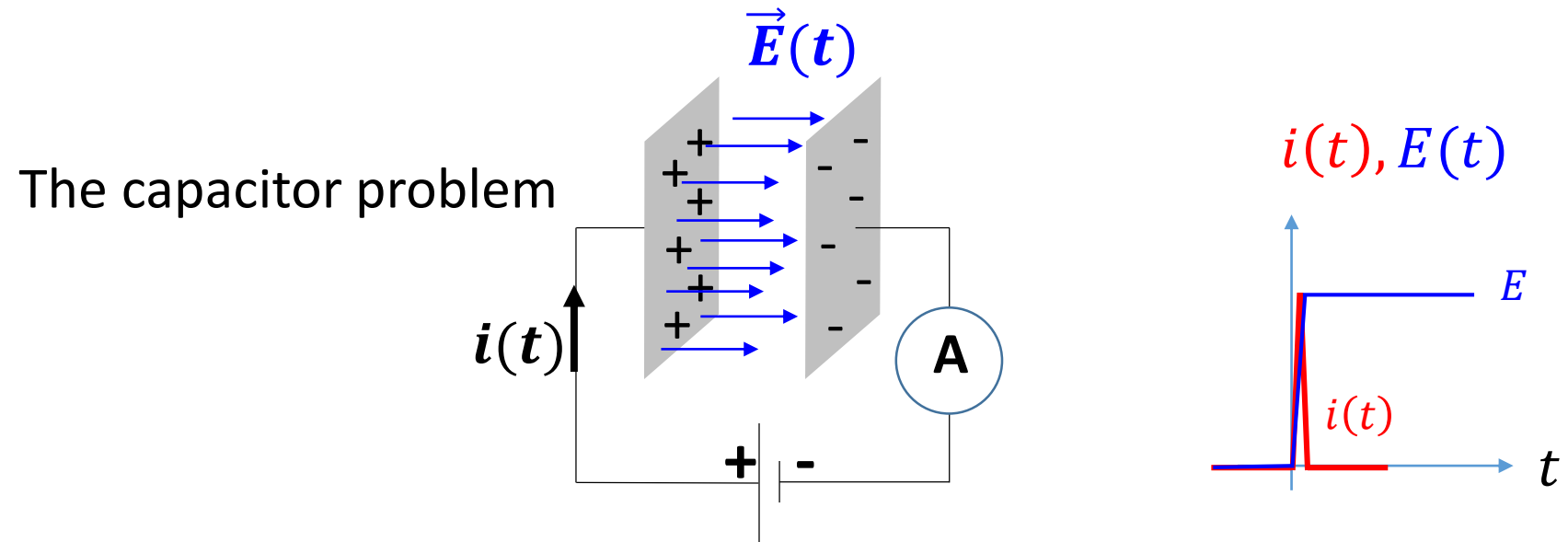
$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}(t)}{\partial t}$$

Maxwell's law

The term that brings symmetry

Displacement current

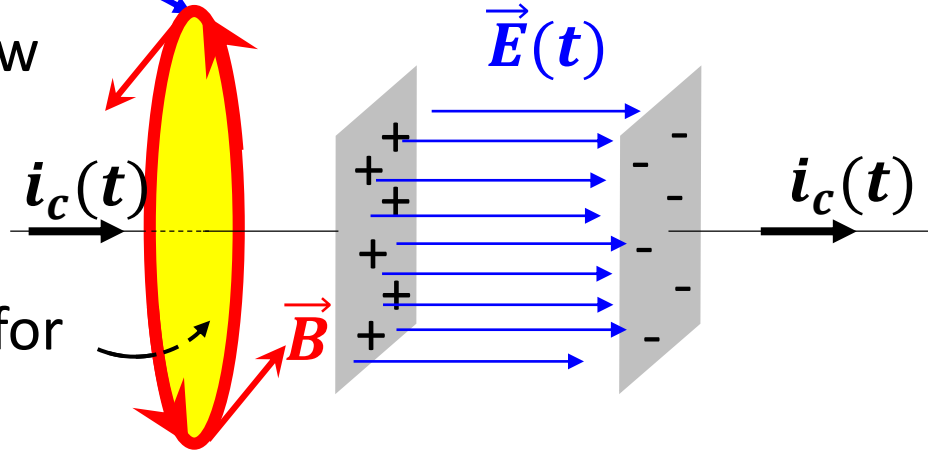
Displacement current or how Maxwell saved Ampere's law



This is not a closed loop **BUT** a current $\mathbf{i(t)}$ flows in the circuit
Clearly no electron is jumping from one plate to the other !

Displacement current or how Maxwell saved Ampere's paradoxical law

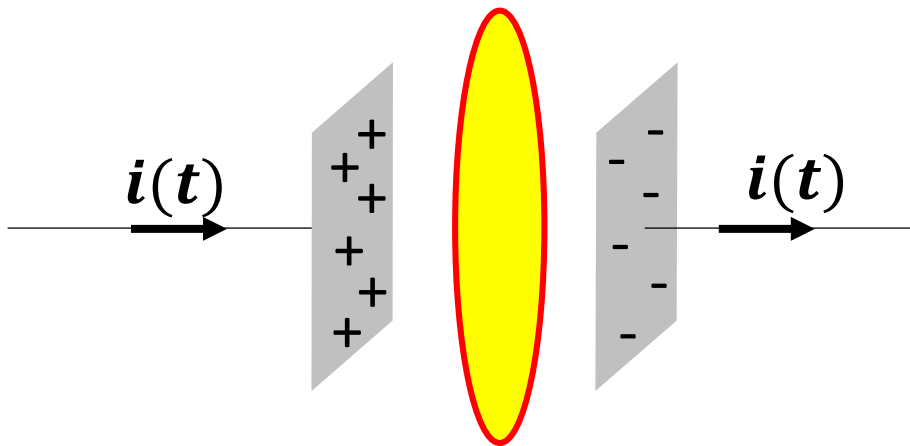
Loop path for
Ampere's law



Plane surface for
Ampere's law

$$\oint \vec{B}(t) \cdot d\vec{l} = \mu_0 I_{encl} = \mu_0 \vec{i}_c(t)_{encl}$$

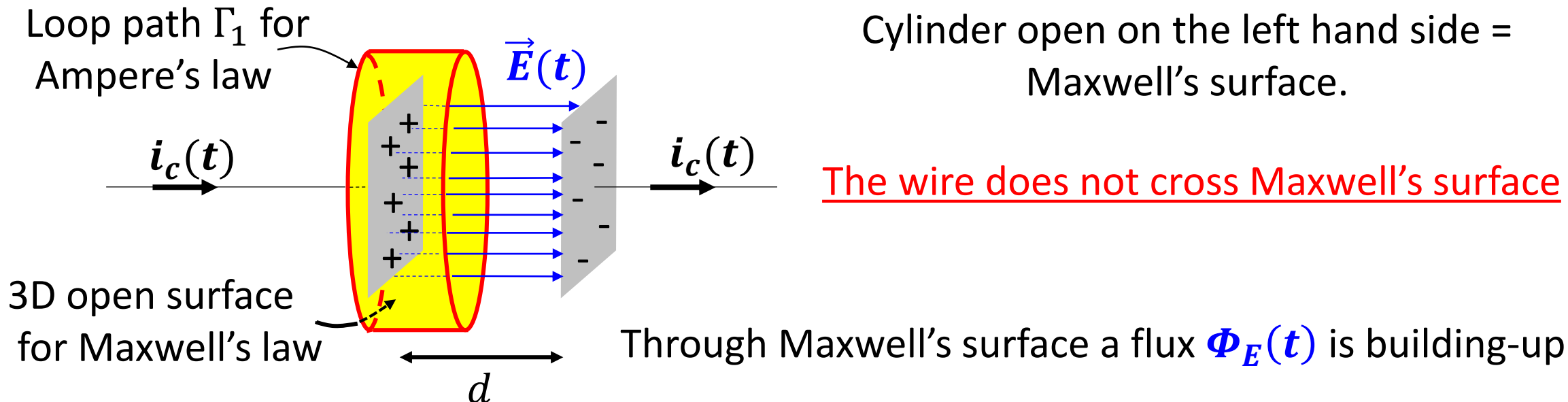
Disk crossed by the wire



No electron moving through the surface
thus **NO** magnetic field ?

$$\oint \vec{B}(t) \cdot d\vec{l} = 0$$

Disk **NOT** crossed by the wire



$$Q(t) = CV(t) = \frac{\epsilon_0 A}{d} E(t) d = \epsilon_0 A E(t) = \epsilon_0 \Phi_E(t)$$

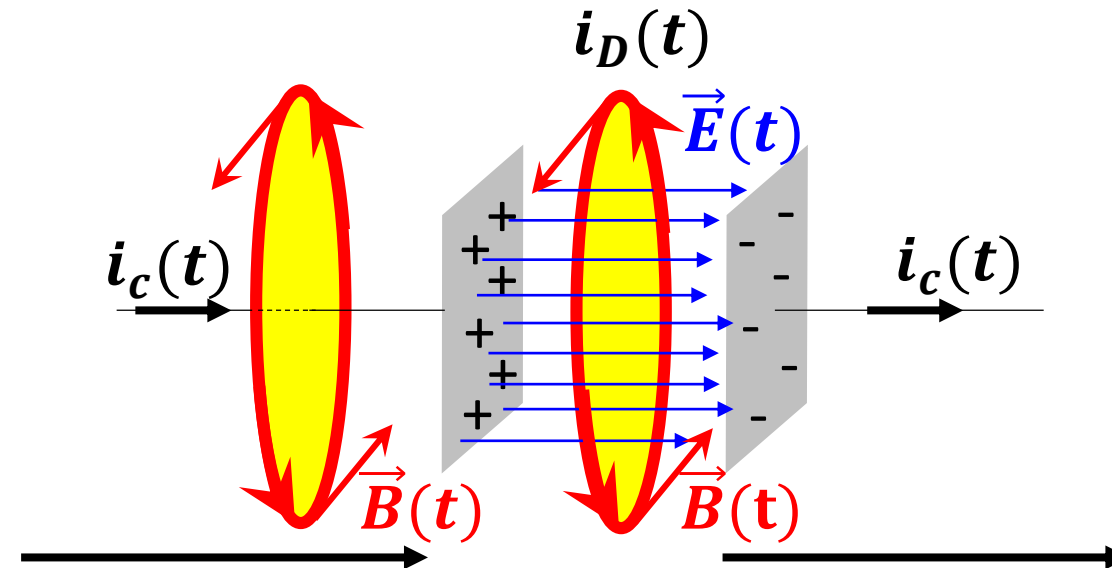
$$i(t) = \frac{dQ(t)}{dt} = \epsilon_0 \frac{d\Phi_E(t)}{dt}$$

$i_D(t)$

Maxwell's genius idea $\longrightarrow i_D(t) = \epsilon_0 \frac{d\Phi_E(t)}{dt}$

Final step: Fourth Maxwell's equation

$$\oint \vec{B}(t) \cdot d\vec{l} = \mu_0 I_{encl} = \mu_0 [i_c(t) + i_D(t)]_{encl}$$




Continuity \Rightarrow

$i_c(t) \neq 0$	$i_c(t) = 0$	$i_c(t) \neq 0$
$i_D(t) = 0$	$i_D(t) \neq 0$	$i_D(t) = 0$
$\vec{E}(t) = 0$	$\vec{E}(t) \neq 0$	$\vec{E}(t) = 0$

What is the major outcome of Maxwell's contribution?

Time-varying field of either kind induces a field of the other kind in neighboring region

Towards the prediction of electromagnetic **disturbances** consisting of \vec{E} and \vec{B} and propagating in free space without requiring any medium



Waves

How did Maxwell's correct Ampere?

$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}(t)}{\partial t}$$

Ampere's law ...

... completed by Maxwell

$$\oint \vec{B}(t) \cdot d\vec{l} = \mu_0 I_{encl} = \mu_0 [i_c(t) + i_D(t)]_{encl} \quad \Rightarrow \quad \oint \vec{B}(t) \cdot d\vec{l} - \mu_0 i_D(t)_{encl} = \mu_0 i_c(t)_{encl}$$

$$i_D(t) = \varepsilon_0 \frac{d\Phi_E(t)}{dt} \quad \Rightarrow \quad \oint \vec{B}(t) \cdot d\vec{l} - \mu_0 \varepsilon_0 \frac{d\Phi_E(t)}{dt} = \mu_0 i_c(t)_{encl}$$

Stoke's theorem

+

Gauss's theorem

$$\oint \vec{B} \cdot d\vec{l} = \iint (\vec{\nabla} \times \vec{B}) \cdot d\vec{A}$$

$$\mu_0 \varepsilon_0 \frac{d\Phi_E}{dt} = \mu_0 \varepsilon_0 \frac{d}{dt} \iint \vec{E} \cdot d\vec{A} = \mu_0 \varepsilon_0 \iint \frac{d\vec{E}}{dt} \cdot d\vec{A}$$

$$\vec{\nabla} \times \vec{B} - \mu_0 \varepsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J}$$

This is all the story with Maxwell's equations

$$\vec{\nabla} \cdot \vec{E}(t) = \frac{\rho(t)}{\epsilon_0}$$

Gauss' law

$$\vec{\nabla} \cdot \vec{B}(t) = 0$$

No magnetic charges

$$\vec{\nabla} \times \vec{E}(t) = -\frac{\partial \vec{B}(t)}{\partial t}$$

Faraday's law

$$\vec{\nabla} \times \vec{B}(t) = \mu_0 \vec{J} + \frac{1}{c^2} \frac{\partial \vec{E}(t)}{\partial t}$$

Ampere's law completed by Maxwell

In electric field, the stored energy is:

$$U = \frac{\epsilon_0}{2} \int E^2 dV$$

All space

$$\frac{\epsilon_0}{2} E^2 = \textit{energy density}$$

Slide #29 X_Lecture **not given**_Current resistance & Electromotive force

In a magnetic field, the stored energy stored:

$$U = \frac{1}{2\mu_0} \int B^2 dV$$

All space

$$\frac{1}{2\mu_0} B^2 = \textit{energy density}$$