

VE281

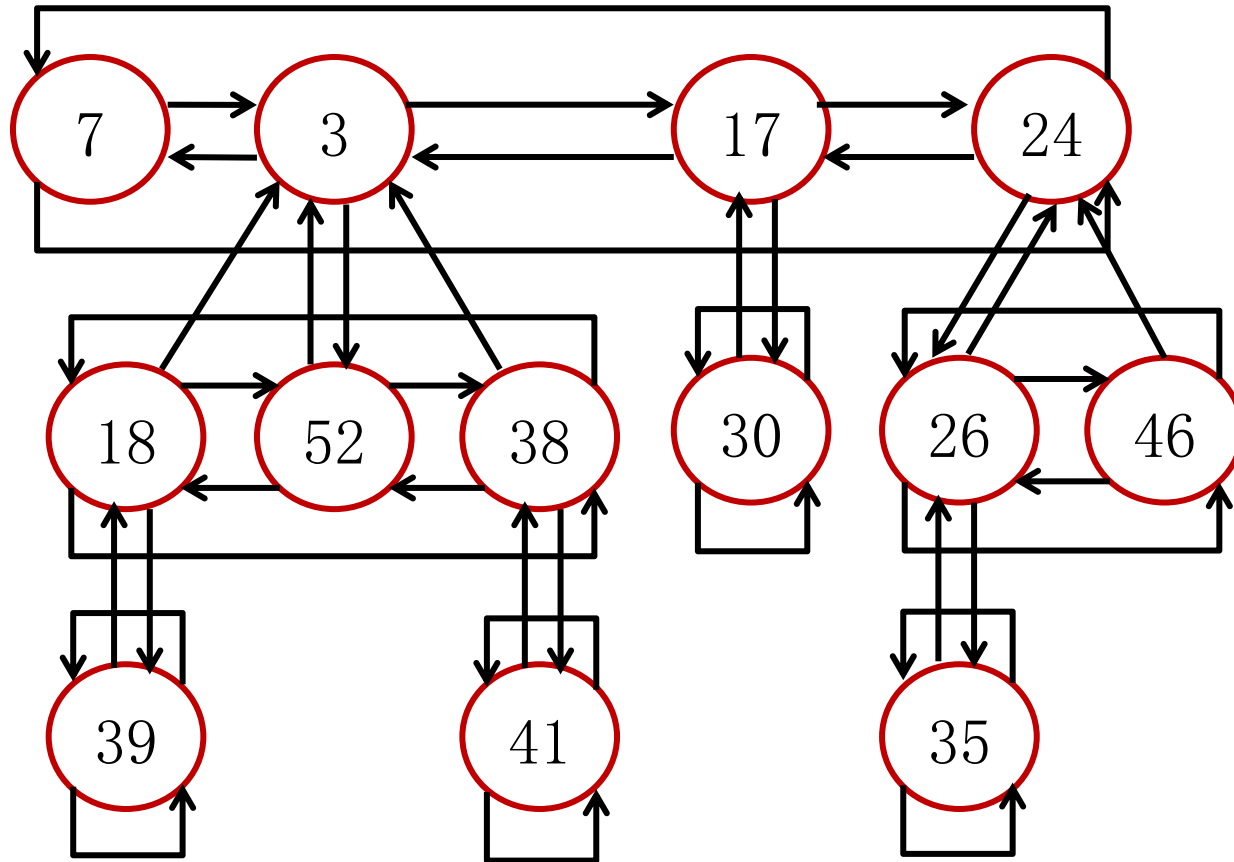
Data Structures and Algorithms

Recitation Class

Nov. 12 2018

VE281 TA Group

Fibonacci Heap



Fibonacci Heap

Operation	Binary Heap (worst case)	Fibonacci Heap (amortized analysis)
insert	$\Theta(\log n)$	$\Theta(1)$
extractMin	$\Theta(\log n)$	$O(\log n)$
getMin	$\Theta(1)$	$\Theta(1)$
makeHeap	$\Theta(1)$	$\Theta(1)$
union	$\Theta(n)$	$\Theta(1)$
decreaseKey	$\Theta(\log n)$	$\Theta(1)$

Fibonacci Heap

- **Insert:** Put into the root list
- **getMin:** Return H.min
- **makeHeap:** H.min = NULL and H.n = 0
- **extractMin:** Remove min and concatenate its children into root list
- **Union:** Connect the two root lists and determine the minimum
- **decreaseKey:**
 - min heap property **violated**
 - Cut between the node and its parent.
 - Move the subtree to the root list.
 - if a node n not in the root list has lost a child for the **second time**, cut again

Binary Search Tree

- Each node is associated with a **key**.
- The key of **any** node is greater than the keys of all nodes in its left subtree and smaller than the keys of all nodes in its right tree.
- Search, Insert, Remove by key $O(\log n)$

Binary Search Tree

- Search


```
node *search(node *root, Key k) {  
    if(root == NULL) return NULL;  
    if(k == root->item.key) return root;  
    if(k < root->item.key)  
        return search(root->left, k);  
    else return search(root->right, k);  
}
```

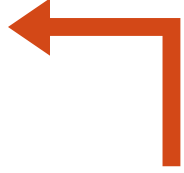
- Insert

```
void insert(node *&root, Item item) {  
    if(root == NULL) {  
        root = new node(item);  
        return;  
    }  
    if(item.key < root->item.key)  
        insert(root->left, item);  
    else if(item.key > root->item.key)  
        insert(root->right, item);  
}
```

Binary Search Tree

Remove:

- Remove a leaf: `delete root;`
`root = NULL;`
- Remove a degree-one node
 - With left child  `node *tmp = root;`
`root = root->left;`
 - With right child `delete tmp;`
- Remove a degree-two node

```
node *&replace = findMax(root->left); 
root->item = replace->item;
node *tmp = replace;
replace = replace->left;
delete tmp;
```

reference to pointer

```
node *&findMax(node *&root) {
    if(root->right == NULL) return root;
    return findMax(root->right);
}
```

Average-Case Time Complexity of BST

- If the **successful search** reaches a node at level d , the number of nodes visited is $d + 1$.
- depth of the i -th node d_i
- **Internal path length** $\sum_{i=1}^n d_i$
- **Average internal path length** of a tree containing n nodes $I(n)$
 - $I(1) = 0$.
- For a tree of n nodes, suppose it has l nodes in its left subtree.
 - The number of nodes in its right subtree is $n - 1 - l$.
 - The average internal path length for such a tree is
$$T(n; l) = I(l) + I(n - 1 - l) + n - 1$$
- $I(n)$ is average of $T(n; l)$ over $l = 0, 1, \dots, n - 1$.

Average-Case Time Complexity of BST

$$I(n) = \frac{1}{n} \sum_{l=0}^{n-1} T(n; l) = \frac{1}{n} \sum_{l=0}^{n-1} [I(l) + I(n-1-l) + n-1]$$

$$= \frac{2}{n} \sum_{l=0}^{n-1} I(l) + (n-1)$$

$$I(n-1) = \frac{2}{n-1} \sum_{l=0}^{n-2} I(l) + (n-2)$$

$$\sum_{l=0}^{n-2} I(l) = \frac{(n-1)[I(n-1) - (n-2)]}{2}$$

$$I(n) = \frac{n+1}{n} I(n-1) + \frac{2(n-1)}{n}$$

$$\frac{I(n)}{n+1} = \frac{I(n-1)}{n} + \frac{2(n-1)}{n(n+1)}$$

$$\leq \frac{I(n-1)}{n} + \frac{2}{n}$$

$$\leq 2 \sum_{k=2}^n \frac{1}{k} < 2 \ln n$$

$$I(n) = O(n \log n)$$

Average-Case Time Complexity of BST

Thus, the average complexity for a search is

$$\Theta\left(\frac{1}{n}I(n)\right) = O(\log n)$$

	Search	Insert	Remove
Linked List	$O(n)$	$O(n)$	$O(n)$
Sorted Array	$O(\log n)$	$O(n)$	$O(n)$
Hash Table	$O(1)$	$O(1)$	$O(1)$
BST	$O(\log n)$	$O(\log n)$	$O(\log n)$

BST Additional Operations

- Other Operations Supported by BST
 - Output in Sorted Order $O(n)$
 - Get Min/Max $O(\log n)$
 - Get Predecessor/Successor $O(\log n)$
 - Rank Search $O(\log n)$
 - Range Search $O(n)$

Note: Hash table does not support efficient implementation of the above methods.