Introduction to Sensitivity Analysis

Thomas Santner

Department of Statistics The Ohio State University Columbus, Ohio

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Outline

Overview

Elementary Effects and Their Estimation

Global Sensitivity Analysis

Local Sensitivity Analysis

This talk will describe the Two Basic Forms of Sensitivity Analysis

• Local Sensitivity Analysis assesses change in $y(\mathbf{x})$ at each input (x_1, \dots, x_d)

Example Let $y(x_1, x_2) = x_1 + x_2$ with domain $(x_1, x_2) \in (0, 1) \times (0, 2)$. Then

$$\frac{\partial y(x_1^0, x_2^0)}{\partial x_1} = 1 = \frac{\partial y(x_1^0, x_2^0)}{\partial x_2}.$$
 (1)

Local Sensitivity Analysis concludes that $y(x_1, x_2)$ is equally sensitive to x_1 and x_2 (starting from any input, small changes in x_1 or x_2 parallel to the axes produce the same change in $y(x_1, x_2)$).

Global Sensitivity Analysis

• Global Sensitivity Analysis Assess change in range of $y(\mathbf{x})$ as each input x_i varies over its possible values **Example** For fixed x_1^0 , the change in $y(x_1^0, \cdot)$ as x_2 ranges over (0, 2), is

$$2 = \max_{x_2} y(x_1^0, x_2) - \min_{x_2} y(x_1^0, x_2) = y(x_1^0, 2) - y(x_1^0, 0)$$

which is twice as large as the change of

$$1 = \max_{x_1} y(\cdot, x_2^0) - \min_{x_1} y(x_1^0, x_2)$$

in $y(\cdot, x_2^0)$ for any fixed x_2^0 . Global SA concludes that $y(x_1, x_2)$ is **twice** as sensitive to x_2 as x_1 .



Standing Assumption

- We assume throughout that $y(\mathbf{x})$ has domain which is hyperrectangle, say $\prod_{i=1}^{d} [a_i, b_i]$;
- For examples of global SA, but not local SA, we assume that the input domain is $[0,1]^d$ because given $y^*(\cdot)$ with domain $\prod_{i=1}^d [a_i,b_i]$, one can apply the methods below to

$$y(x_1,...,x_d) = y^*(a_1 + x_1(b_1 - a_1),...,a_d + x_d(b_d - a_d)\cdot).$$

and the notation required to describe global SA methods are simplest to state for the case $[0,1]^d$.



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Elementary Effects and Their Estimation

Global Sensitivity Analysis

Elementary Effects

The **Elementary Effects** (EEs) of a function $y(\mathbf{x}) = y(x_1, \dots, x_d)$ having d inputs are measures of the sensitivity of $y(\mathbf{x})$ to each of the inputs x_j . EEs are based on the slopes of secant lines parallel to each of the input axes. Given $j \in \{1, \dots, d\}$, the j^{th} EE of $y(\mathbf{x})$ at distance δ is

$$d_j(\mathbf{x}) = \frac{y(x_1, \dots, x_{j-1}, x_j + \delta, x_{j+1}, \dots, x_d) - y(\mathbf{x})}{\delta} . \tag{2}$$

The ratio $d_j(\mathbf{x})$ is the slope of the secant line connecting \mathbf{x} and $\mathbf{x} + \delta \mathbf{e}_j$ where $\mathbf{e}_j = (0, 0, \dots, 1, 0, \dots, 0)$ is the j^{th} unit vector.

- For "small" δ , $d_j(\mathbf{x})$ is a numerical approximation to $\frac{\partial y(\mathbf{x}^o)}{\partial x_j}$ and is thus a local SA tool.
- ullet In most applications, EEs are evaluated for "large" δ (and a widely sampled set of inputs ${\bf x}$) and are thus not a local SA tool.

Elementary Effects

Example Suppose

$$y(\mathbf{x}) = 1.0 + 1.5x_2 + 1.5x_3 + .6x_4 + 1.7x_4^2 + .7x_5 + .8x_6 + .5(x_5 \times x_6),$$

where
$$\mathbf{x} = (x_1, x_2, x_3, x_4, x_5, x_6) \ 0 \le x_1, x_2, x_4, x_5, x_6 \le 1, 0 \le x_3 \le 5.$$

- $y(\mathbf{x})$ is functionally independent of (constant in) x_1 ,
- \blacktriangleright is linear in x_2 and x_3 (and x_3 has the wider range)
- \triangleright is non-linear in x_4 ,
- ightharpoonup contains an interaction in x_5 and x_6

Elementary Effects

Algebra gives

- 1. $d_1(\mathbf{x}) \equiv 0$: The EE of the totally inactive variable x_1 is zero because $y(\mathbf{x})$ is independent of x_1 .
- 2. $d_2(\mathbf{x}) \equiv 1.5 \equiv d_3(\mathbf{x})$: The EEs of the linear terms x_2 and x_3 are the same non-zero constant and thus act like a **local** SA measure. (true in general for additive linear terms.)
- 3. $d_4(\mathbf{x}) = +0.6 + 1.7\delta + 3.4x_4$: The EE of the quadratic term x_4 depends on *both* the starting x_4 and δ ; hence for *fixed* δ $d_4(\mathbf{x})$ will vary only with x_4
- 4. $d_5(\mathbf{x}) = +0.7 + 0.5x_6$, and
- 5. $d_6(\mathbf{x}) = +0.8 + 0.5x_5$: The EEs of the interacting x_5 and x_6 depends on other variables.



• For expensive-to-compute codes with (hyper-rectangular) input regions $[0,1]^d$, Morris (1991) proposed a one-at-a-time (OAT) design for evaluating $y(\mathbf{x})$ in order to estimate the EEs for every input based on $r \times (d+1)$ function evaluations **Example** Suppose $y(\mathbf{x}) = y(x_1, x_2, x_3, x_4)$ (d=4) inputs where

 $\mathbf{x} \in \mathcal{X} = [0,1]^4$. Suppose $\delta = 0.2$; starting with initial input (0.4,0.6,0.6,0.0), suppose that $y(\mathbf{x})$ is evaluated at the rows of the design

$$\left[\begin{array}{ccccc} 0.4 & 0.6 & 0.6 & 0.0 \\ 0.4 & 0.4 & 0.6 & 0.0 \\ 0.2 & 0.4 & 0.6 & 0.0 \\ 0.2 & 0.4 & 0.6 & 0.2 \\ 0.2 & 0.4 & 0.4 & 0.2 \end{array} \right] \ .$$

Then $d_2(0.4, 0.6, 0.6, 0.0)$ for $\delta = -0.2$ and $d_1(0.4, 0.4, 0.6, 0.0)$ for $\delta = -0.2$.

- The Morris design consists of r blocks, each $(d+1) \times d$, that are based on
 - ▶ a fixed **griding** of the input region (usually fixed for all blocks)
 - ▶ a fixed $\delta > 0$ which is a **multiple** of the grid spacing (usually fixed for all blocks)
 - ▶ a random permutation π of $1, \ldots, d$
 - ▶ a vector $\mathbf{s} = (s_1, \dots, s_d)$ of **randomly** selected directions with each $s_i \in \{-, +1\}, j \in \{1, ..., d\}$

Example Suppose that $[0,1]^4$ is the input space and a grid is selected that divides each input into 10 equal parts. Suppose $\delta = 0.2 = 2 \times \frac{1}{20}$ is selected, the EEs are to be constructed in the order $\pi = (2, 1, 4, 3)$, and in the directions $\mathbf{s} = (-1, -1, +1, -1)$, then starting at $\mathbf{x} = (0.4, 0.6, 0.6, 0.0)$ produces the design on the previous page

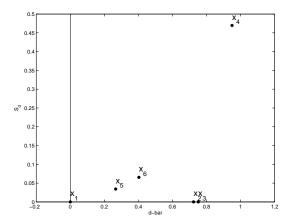
- Given $(\delta, \pi, \mathbf{s})$, Morris selects selects r starting points $\mathbf{x} \in [0, 1]^d$ randomly from among those points in the grid that satisfy
 - $\mathbf{x} + s_{\pi(1)} \times \delta \mathbf{e}_{\pi(1)} \in [0, 1]^d$
 - $\mathbf{x} + s_{\pi(1)} \delta \mathbf{e}_{\pi(1)} + s_{\pi(2)} \delta \mathbf{e}_{\pi(2)} \in [0, 1]^d$
 - etc.
- Summary The OAT design shifts each input coordinate $\pm \delta$ in a random order, until all inputs have been altered (called a complete tour starting at x).
- A complete tour is conducted from each starting point \mathbf{x} . A total of $r \times (d+1)$ function evaluations are required to produced r values of each elementary effect.



- Suppose each $d_j(\mathbf{x})$, j=1,...,d, has been computed at r inputs, say $\mathbf{x}_1^j, \ldots \mathbf{x}_r^j$, each for fixed δ .
- Let $\overline{d_j}$ denote the sample mean of $d_j(\mathbf{x}_1^j), \ldots, d_j(\mathbf{x}_r^j)$ and S_j their sample standard deviation.
- Plot $(\overline{d_j}, S_j)$, j = 1, ..., d.

Example (cont) Based on r = 5 values for each EE, the d = 6 input function examined above has $(\overline{d_j}, S_j)$ plot





which clearly shows the character of x_1 , x_2 , and x_3 and that x_4 , x_5 , and x_6 have EEs that depend on the values of other variables.

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Elementary Effects and Their Estimation

Global Sensitivity Analysis

• Given $y(\mathbf{x})$, $\mathbf{x} \in [0,1]^d$, define the *overall mean* of $y(\cdot)$ to be

$$y_0 \equiv \int_0^1 \cdots \int_0^1 y(x_1, \ldots, x_d) \prod_{i=1}^d dx_i.$$

- The overall mean can be interpreted as the expectation $y_0 = E[y(\mathbf{X})]$ where $\mathbf{X} = (X_1, \dots, X_d)$ has i.i.d. U(0, 1) component distributions.
- for any $i \in \{1, ..., d\}$, the i^{th} main effect function is defined to be the average $y(\mathbf{x})$, when x_i is **fixed**, i.e.,

$$u_i(x_i) = \int_0^1 \cdot \int_0^1 y(x_1, \dots, x_d) \prod_{\ell \neq i} dx_\ell = E[y(\mathbf{X})|X_i = x_i];$$



• Fix any nonempty subset Q of $\{1,\ldots d\}$ and $Q\setminus\{1,\ldots d\}$ are non-empty (so that the integral below are averages over at least one variable). Let \mathbf{x}_Q denote the vector of components x_i with $i\in Q$ in some linear order. Define the joint effect function of $y(\mathbf{x})$ with respect to x_Q to be

$$u_{\mathcal{Q}}(\mathbf{x}_{\mathcal{Q}}) = \int_0^1 \cdots \int_0^1 y(x_1, \ldots, x_d) \prod_{i \notin \mathcal{Q}} dx_i = E[y(\mathbf{X}) | \mathbf{X}_{\mathcal{Q}} = \mathbf{x}_{\mathcal{Q}}].$$

• For completeness, set

$$u_{12...d}(x_1,\ldots,x_d)\equiv y(x_1,\ldots,x_d).$$



- $u_Q(\mathbf{x}_Q)$ is the average change in $y(\mathbf{x})$; $u_Q(\mathbf{x}_Q)$ values are on the same scale and in the same range as $y(\mathbf{x})$.
- The standard global SA consists of two tools
 - 1. Plots of estimated main effect $(u_Q(\mathbf{x}_Q) \text{ with } Q = \{j\})$ or joint effect $(u_Q(\mathbf{x}_Q) \text{ with } Q = \{j_1, j_2\})$ functions versus \mathbf{x}_Q
 - 2. Numerical approximations of the variability of $u_Q(\mathbf{X}_Q)$ assuming that the components of \mathbf{X}_Q are i.i.d. U(0,1)

Example

Suppose
$$y(x_1, x_2) = 2x_1 + x_2$$
, $(x_1, x_2) \in [0, 1]^2$.

$$y_0 = \int_0^1 \int_0^1 (2x_1 + x_2) dx_2 dx_1 = 1.5$$

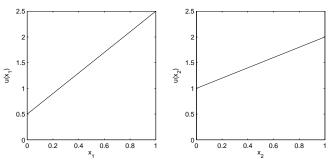
$$u_1(x_1) = \int_0^1 (2x_1 + x_2) dx_2 = 2x_1 + 0.5$$

$$u_2(x_2) = \int_0^1 (2x_1 + x_2) dx_1 = 1.0 + x_2$$

$$u_{12}(x_1, x_2) = y(x_1, x_2) = 2x_1 + x_2$$

Example

• The main effect functions for x_1 and x_2 are



• Aside It is simple to calculate that

$$\int_0^1 u_1(x_1) dx_1 = \int_0^1 u_2(x_2) dx_2 = \int_0^1 u_{12}(x_1, x_2) dx_1 dx_2 = 1.5 = y_0.$$

(and this is true in general)



Example

• The $u_Q(x_Q)$ terms include all influences of x_Q , not just linear ones.

Example Let $y(x_1, x_2) = x_1 + 2x_1^2 + x_1x_2$, $\mathbf{x} \in [0.1]^2$ then

- $u_1(x_1) = x_1 + 2x_1^2 + x_1/2$
- $u_2(x_2) = \frac{7}{6} + x_2/2$
- $u_{12}(x_1,x_2)=y(x_1,x_2)$

A Pathological Example

Suppose $y(x_1, x_2, x_3) = (x_1 + 1)\cos(\pi x_2) + 0x_3$ which is independent of x_3 but depends on the interaction of x_1 and $\cos(\pi x_2)$ has overall mean $y_0 = 0$. So

- ▶ $u_1(x_1) = \int_0^1 \int_0^1 y(x_1, x_2, x_3) dx_2 dx_3 = 0$, $x_1 \in [0, 1]$ which is non-intuitive since y(x) depends on x_1
- $u_2(x_2) = \int_0^1 \int_0^1 y(x_1, x_2, x_3) dx_1 dx_3 = \frac{3}{2} \cos(\pi x_2)$
- $u_3(x_3) = \int_0^1 \int_0^1 y(x_1, x_2, x_3) dx_1 dx_2 = 0$
- $u_{12}(x_1,x_2) = \int_0^1 y(x_1,x_2,x_3) dx_3 = y(x_1,x_2,0.5)$
- $u_{13}(x_1,x_3)=0$

A Pathological Example (cont)

- $u_{23}(x_2,x_3) = \frac{3}{2}\cos(\pi x_2)$
- $u_{123}(x_1,x_2,x_3)=0$
- Centering $u_Q(\mathbf{X}_Q)$: The function $u_Q(\mathbf{X}_Q) y_0$ is one way to create centered $u_Q(\mathbf{X}_Q)$ terms because $E\{u_Q(\mathbf{X}_Q)\} = y_0$.

- BUT the use of an ANOVA-like centering provides a stronger form of centering and terms with better statistical properties.
- ANOVA-centering of effect functions:
 - ▶ For any $i \in \{1, ..., d\}$ define

$$y_i(x_i) = u_i(x_i) - y_0$$
 (3)

For (i, j), $1 \le i < j \le d$, define

$$y_{ij}(x_i, x_j) = u_{ij}(x_i, x_j) - y_i(x_i) - y_j(x_j) - y_0$$
 (4)

to be the centered interaction effect function of x_i and x_j .



▶ Suppose that Q is a *non-empty* subset of $\{1, \ldots d\}$,

$$y_{\mathcal{Q}}(\mathbf{x}_{\mathcal{Q}}) = u_{\mathcal{Q}}(\mathbf{x}_{\mathcal{Q}}) - \sum_{E} y_{E}(\mathbf{x}_{E}) - y_{0}$$
 (5)

where the sum over all non-empty proper subsets E of Q $(E \subset Q \text{ is proper provided } E \neq Q)$, i.e., if $y(\mathbf{x})$ has three (or more) arguments,

$$y_{123}(x_1, x_2, x_3) = u_{123}(x_1, x_2, x_3) - y_{12}(x_1, x_2) - y_{13}(x_1, x_3) - y_{23}(x_2, x_3) - y_{1}(x_1) - y_{2}(x_2) - y_{3}(x_3) - y_{0}$$

Special Case Setting $Q = \{1, \dots, d\}$

$$y_{1,2,...,d}(x_1,x_2,...,x_d) = u_{1,2,...,d}(x_1,x_2,...,x_d) - \sum_{E} y_E(x_E) - y_0$$
$$= y(x_1,x_2,...,x_d) - \sum_{E} y_E(x_E) - y_0$$

• Application The Sobol decomposition of y(x)

$$y(\mathbf{x}) = y_0 + \sum_{i=1}^d y_i(x_i) + \sum_{1 \le i < j \le d} y_{ij}(x_i, x_j) + \dots + y_{1,2,\dots,d}(x_1, \dots, x_d)$$

Two Properties of ANOVA-centered Components

• The ANOVA-centered functions have **mean zero** wrt **any** single component, i.e., for any $Q = \{j_1, \ldots, j_s\} \subseteq \{1, \ldots, d\}$ and any $j_k \in Q$

$$\int_0^1 y_Q(\mathbf{x}_Q) dx_{j_k} = 0$$

and are **pairwise orthogonal**, i.e., for any $(k_1, ..., k_s) \neq (j_1, ..., j_t)$,

$$E[y_{k_1,...,k_s}(X_{k_1},...,X_{k_s})y_{j_1,...,j_t}(X_{j_1},...,X_{j_t})]$$

$$= \int y_{k_1,...,k_s}(x_{k_1},...,x_{k_s})y_{j_1,...,j_t}(x_{j_1},...,x_{j_t}) d\mathbf{x}_Q = 0. \quad (6)$$

where $Q = \{k_1, ..., k_s\} \cup \{j_1, ..., j_t\}.$



• Define the total variance of y(x) to be

$$v = E\left\{ (y(\mathbf{X}) - y_0)^2 \right\}$$

• For any subset $Q \subset \{1, \dots, d\}$, the variance of $y_Q(\mathbf{X}_Q)$ is

$$v_Q = Var(y_Q(\mathbf{X}_Q)) = E\{y_Q^2(\mathbf{X}_Q)\}$$

because $y_Q(\mathbf{X}_Q)$ has mean zero

Thus

$$v = E \left[(y(\mathbf{X}) - y_0)^2 \right]$$

$$= E \left[\left(\sum_{i=1}^d y_i(X_i) + \sum_{i < j} y_{ij}(X_i, X_j) + \dots + y_{1,2,\dots,d}(X_1, \dots, X_d) \right)^2 \right]$$

$$= \sum_{i=1}^d E \left[y_i^2(X_i) \right] + \sum_{i < j} E \left[y_{ij}^2(X_i, X_j) \right] + \dots$$

$$+ E \left[y_{1,2,\dots,d}^2(X_1, \dots, X_d) \right] + 0$$

$$= \sum_{i=1}^d v_i + \sum_{i < j} v_{ij} + \dots + v_{1,2,\dots,d}$$

where all cross product terms are zero by the pairwise orthogonality

• For any subset $Q \subset \{1, ..., d\}$, define the sensitivity index (SI) of $y(\mathbf{x})$ with respect the set of inputs x_i , $i \in Q$, to be

$$S_Q = \frac{v_Q}{v}$$
.

• By construction,

$$\sum_{i=1}^{d} S_i + \sum_{1 \leq i < j \leq d} S_{ij} + \dots + S_{1,2,\dots,d} = 1.$$

- S_i , corresponding to $Q = \{i\}$, is called the **first-order or main effect sensitivity index** of input x_i ; S_i measures the proportion of the variation v that is due to input x_i .
- S_{ij} is called the **second-order sensitivity index**; S_{ij} measures the proportion of v that is due to the joint effects of x_i and x_j .

The total sensitivity index

• The **total sensitivity index** (TSI) of $y(\mathbf{x})$ with respect to a given input x_i , denoted T_i , is meant to include the effect of x_i on $y(\mathbf{x})$ and all interactions of x_i with all other inputs. The TSI of $y(\mathbf{x})$ wrt x_i is defined to be

$$T_i = S_i + \sum_{j \neq i} S_{ij} + \dots + S_{1,2,\dots,d}$$
 (7)

Example When d = 3,

$$T_1 = S_1 + S_{12} + S_{13} + S_{123}. (8)$$

• By construction, $T_i \ge S_i$, i = 1, ..., d and the difference $T_i - S_i$ measures the influence of x_i due to its interactions with other variables.

Example (cont) For $y(x_1, x_2) = 2x_1 + x_2$, we calculate that

$$v = Var(y(X_1, X_2)) = Var(2X_1 + X_2) = 4/12 + 1/12 = 5/12$$
 $v_1 = Var(y_1(X_1)) = Var(-1 + 2X_1) = 4/12$
 $v_2 = Var(y_2(X_2)) = Var(-0.5 + X_2) = 1/12$
 $v_{12} = Var(y_{12}(X_1, X_2)) = Var(0) = 0$
 $\longrightarrow v = v_1 + v_2 + v_{12}$ and
 $S_1 = \frac{4/12}{5/12} = 0.8, \ S_2 = \frac{1/12}{5/12} = 0.2, \ \text{and} \ S_{12} = 0.0.$

- $T_1 = S_1$ and $T_2 = S_2$
- Interpretation: x_1 is more important than x_2 ; there is no interaction between x_1 and x_2 .
- Deviation from our intuition: based on the functional relationship, the reader might have assessed that x_1 was **twice** as important x_2 .

A Pathological Example $y(x_1, x_2, x_3) = (x_1 + 1)\cos(\pi x_2) + 0x_3$. Because $y_0 = 0$,

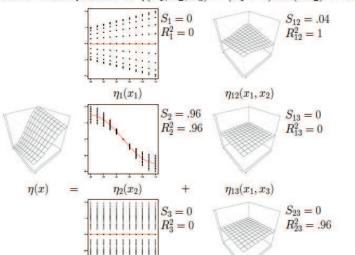
$$v = Var((X_1+1)\cos(\pi X_2)) = E\{(X_1+1)^2\cos^2(\pi X_2))\} = \frac{7}{3} \times \frac{1}{2} = \frac{7}{6}$$

- ▶ $y_1(x_1) = 0$, $y_3(x_3) = 0$, $y_{13}(x_1, x_3) = 0$, $y_{23}(x_2, x_3) = 0$, and $y_{123}(x_1, x_2, x_3) = 0$
- ▶ So $v_1 = v_3 = v_{13} = v_{23} = v_{123} = 0$
- $y_2(x_2) = \frac{3}{2}\cos(\pi x_2)$ so $v_2 = E\left\{\frac{9}{4}\cos^2(\pi X_2)\right\} = \frac{9}{8}$ and $s_2 = \frac{9/8}{7/6} = 0.96$
- ▶ $y_{12}(x_1, x_2) = (x_1 0.5)\cos(\pi x_2)$ so $v_{12} = E\{(X_1 0.5)^2\cos^2(\pi X_2)\} = \frac{1}{24}$ and $s_{12} = 0.04$



Example-Functional ANOVA decomposition

Sobol' decomposition of
$$\eta(x_1,x_2,x_3)=(x_1+1)\cos(\pi x_2)+0x_3$$



Inference for Effect Plots and SIs

• Method 1 Quadrature-based Estimation of Effect Plots

$$\widehat{u}_{Q}(\mathbf{x}_{Q}) = \int_{[0,1]^{d-|Q|}} \widehat{y}(\mathbf{x}_{1},\ldots,\mathbf{x}_{d}) \prod_{i \notin Q} d\mathbf{x}_{i} = \frac{1}{n} \sum_{\ell=1}^{n} \widehat{y}(\mathbf{x}_{Q},\mathbf{x}_{-Q,\ell}) w_{\ell}$$

where $\widehat{y}(\mathbf{x}_Q, \mathbf{x}_{-Q,\ell})$ is a REML or other EBLUP of $y(\mathbf{x}_Q, \mathbf{x}_{-Q,\ell})$; the weights $\{w_\ell\}$ and points $\{\mathbf{x}_{-Q,\ell}\}$ depend on the selected quadrature method.

Inference for Effect Plots and SIs

For the EBLUP based on the GP model

$$Y(\mathbf{x}) = \beta_0 + Z(\mathbf{x})$$

where β_0 is unknown and $Z(\mathbf{x})$ is a stationary GP on $[0,1]^d$ having zero mean, variance σ_Z^2 , and has **separable** correlation function

$$\prod_{\ell=1}^d R(h_\ell|\ \psi_\ell)$$

the integral $\widehat{u}_Q(\mathbf{x}_Q) = \int_{[0,1]^{d-|Q|}} \widehat{y}(x_1,\ldots,x_d) \prod_{i \notin Q} dx_i$ can be computed analytically.



Inference for Effect Plots and SIs

• **Method 2** Process-based Estimators of Sensitivity Indices For $Y(\mathbf{x}) \sim GP(\beta_0, \sigma_Y^2, R(\cdot))$, the integral

$$U_Q(\mathbf{x}_Q) \equiv \int_0^1 \cdots \int_0^1 Y(x_1, \ldots, x_d) \prod_{i \notin Q} dx_i = E[Y(\mathbf{X}) | \mathbf{X}_Q = \mathbf{x}_Q],$$

is (under mild conditions) a process for which

$$[(U_Q(\mathbf{x}_Q), Y(\mathbf{x}_1), \dots, Y(\mathbf{x}_n)) | \xi] = [(U_Q(\mathbf{x}_Q), Y^n) | \xi]$$

has the joint multivariate normal distribution

$$\mathit{N}_{1+n}\left[\left(\begin{array}{c}\beta_0\\\mathbf{1}_n\beta_0\end{array}\right)\;,\left(\begin{array}{cc}\sigma_u^2&\mathbf{\Sigma}_{nu}\\\mathbf{\Sigma}_{nu}&\mathbf{\Sigma}_{nn}\end{array}\right)\right]$$



Estimating Global Sensitivity Indices

ullet The posterior mean of $U_Q(\mathbf{x}_Q)$ given training data and parameters is

$$\widehat{u}_Q = E_P \left\{ U_Q(\mathbf{x}_Q) | \mathbf{Y}^n = \mathbf{y}^n, \boldsymbol{\xi} \right\} = \beta_0 + \boldsymbol{\Sigma}_{nu} \boldsymbol{\Sigma}_{nn}^{-1} (\mathbf{Y}^n - \mathbf{1}_n \beta_0)$$

is an estimator of $u_Q(\mathbf{x}_Q)$. In practice, \widehat{u}_Q is evaluated for plug-in $\boldsymbol{\xi}$ parameters or \widehat{u}_Q is averaged for a sample from $[\boldsymbol{\xi}|\mathbf{Y}^n=\mathbf{y}^n]$ under a Bayesian model.

• The posterior mean of the **variance** of $U_i(X_i)$ given training data and parameters,

$$\widehat{\mathbf{v}}_i = E_P \left\{ Var \left[U_i(X_i) \right] | \mathbf{Y}^n = \mathbf{y}^n, \mathbf{\xi} \right\},$$

can be used to estimate

$$v_i = Var(u_i(X_i)) = Var(u_i(X_i) - y_0) = Var(y_i(X_i))$$

and hence the ME S_i



Estimating Global Sensitivity Indices

- A similar estimator can be used to estimate the total effect sensitivity
- In practice, v_i is estimated by plugging estimated $\boldsymbol{\xi}$ parameters into \widehat{v}_i or by averaging \widehat{v}_i for a sample of $\boldsymbol{\xi}$ draws from $[\boldsymbol{\xi}|\mathbf{Y}^n=\mathbf{y}^n]$ under a Bayesian model.

• Sensitivity Analysis is a set of tools used to analyze the local and global sensitivity of a function $y(\mathbf{x})$ to individual inputs x_i .

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- How to form SIs for functional, as opposed to real-valued, output??



Experiments

gpmsa program

http://www.stat.lanl.gov/source/orgs/ccs/ccs6/gpmsa/gpmsa.