

Qiuuzhen Lectures on Analysis

BIN GUI

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Sections on history include but are not limited to: [2.1](#) (point-set topology), [10.4](#) (Hilbert spaces, Riesz-Fischer theorem), [13.1](#) (integral theory, Fourier series), [17.5](#) (Banach-Alaoglu, Hahn-Banach), [17.7](#) (functional calculus, spectral theory), [17.10](#) (quotient Banach spaces, Hahn-Banach), [21.1](#) and most part of Ch. [22](#) (Hilbert spaces), [23.6](#) (measurable sets)

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0 Preface

0.1 Notations

Note: Topics marked with ****** are technical and/or their methods are rarely used in later studies. Topics marked with ***** are interesting, but not necessarily technical or difficult. They are not essential for understanding the rest of the notes. You can skim or skip the starred topics on first reading. When a chapter/section/subsection is starred, it means that all of the material in that chapter/section/subsection is starred.

We use frequently the abbreviations:

iff=if and only if
LHS=left hand side RHS=right hand side
 \exists =there exists \forall =for all
i.e.=id est=that is=namely e.g.=for example
cf.=compare/check/see/you are referred to
resp.=respectively WLOG=without loss of generality

If P, Q are properties, then

$$P \wedge Q = P \text{ and } Q \quad P \vee Q = P \text{ or } Q \quad \neg P = \text{Not } P$$

When we write $A := B$ or $A \stackrel{\text{def}}{=} B$, we mean that A is defined by the expression B . When we write $A \equiv B$, we mean that A and B are different symbols of the same object.

If \mathbb{F} is any field (e.g. $\mathbb{Q}, \mathbb{R}, \mathbb{C}$), we let $\mathbb{F}^\times = \mathbb{F} \setminus \{0\}$. If α is a complex number and $n \in \mathbb{N}$, we define the **binomial coefficient**

$$\binom{\alpha}{n} = \begin{cases} \frac{\alpha \cdot (\alpha - 1) \cdots (\alpha - n + 1)}{n!} & \text{if } n \geq 1 \\ 1 & \text{if } n = 0 \end{cases} \quad (0.1)$$

where $n! = n(n-1)(n-2) \cdots 2 \cdot 1$ and $0! = 1$. The bold letter **i** means

$$\mathbf{i} = \sqrt{-1}$$

If $z = a + b\mathbf{i}$ where $a, b \in \mathbb{R}$, we let

$$\operatorname{Re}(z) = a \quad \operatorname{Im}(z) = b$$

If x, y are two elements, we let

$$\delta_{x,y} = \begin{cases} 1 & \text{if } x = y \\ 0 & \text{if } x \neq y \end{cases} \quad (0.2)$$

We let $\overline{\mathbb{R}} = [-\infty, +\infty]$, $\overline{\mathbb{R}}_{\geq 0} = [0, +\infty]$, and $\mathbb{R}_{\geq 0} = [0, +\infty)$. Additions and multiplications in $\overline{\mathbb{R}}$ and $\overline{\mathbb{R}}_{\geq 0}$ are described in Def. [1.36](#).

If $f, g : X \rightarrow Y$ where X is a set and Y is a preordered set, we write

$$f \leq g$$

whenever $f(x) \leq g(x)$ for all $x \in X$. If Y is a totally ordered set where $a < b$ in Y means $a \leq b$ and $a \neq b$, we write

$$f < g$$

whenever $f(x) < g(x)$ for all $x \in X$.

1 Basic set theory and numbers

In this chapter, we discuss informally some of the basic notions in set theory and basic properties about numbers. A more thorough treatment can be found in [Mun, Ch. 1] (for set theory) and [Rud-P, Ch. 1] (for numbers).

1.1 Basic operations and axioms

Intuitively, a set denotes a collection of elements. For instance:

$$\mathbb{Z} = \{\text{all integers}\} \quad \mathbb{N} = \mathbb{Z}_{\geq 0} = \{n \in \mathbb{Z} : n \geq 0\} \quad \mathbb{Z}_+ = \{n \in \mathbb{Z} : n > 0\}$$

have infinitely many elements. (In this course, we will not be concerned with the rigorous construction of natural numbers and integers from Peano axioms.) We also let

$$\mathbb{Q} = \{\text{all rational numbers}\} \quad \mathbb{R} = \{\text{all real numbers}\}$$

if we that rational and real numbers exist and satisfy the properties we are familiar with in high school mathematics. (We will construct \mathbb{Q} and \mathbb{R} rigorously, by the way.)

Set theory is the foundation of modern mathematics. It consists of several Axioms telling us what we can do about the sets. For example, the following way of describing sets

$$\{x : x \text{ satisfies property...}\} \tag{1.1}$$

is illegal, since it gives **Russell's paradox**: Consider

$$S = \{A : A \text{ is a set and } A \notin A\} \tag{1.2}$$

If S were a set, then $S \in S \Rightarrow S \notin S$ and $S \notin S \Rightarrow S \in S$. This is something every mathematician doesn't want to happen.

Instead, the following way of defining sets is legitimate:

$$\{x \in X : x \text{ satisfies property...}\} \tag{1.3}$$

where X is a given set. For instance, we can define the **difference** of two sets:

$$A \setminus B = A - B = \{x \in A : x \notin B\}$$

So let us figure out the legal way of defining unions and intersections of sets. The crucial point is that we assume the following axiom:

Axiom. If \mathcal{A} is a set of sets, then there exists a set X such that $A \subset X$ for all $A \in \mathcal{A}$.

Thus, if \mathcal{A} is a set of sets, let X satisfy $A \subset X$ for all $A \in \mathcal{A}$, then we can define the **union** and the **intersection**

$$\bigcup_{A \in \mathcal{A}} A = \{x \in X : \text{there exists } A \in \mathcal{A} \text{ such that } x \in A\} \quad (1.4a)$$

$$\bigcap_{A \in \mathcal{A}} A = \{x \in X : \text{for all } A \in \mathcal{A} \text{ we have } x \in A\} \quad (1.4b)$$

It is clear that this definition does not rely on the particular choice of X .

Remark 1.1. In many textbooks, it is not uncommon that sets are defined as in (1.1). You should interpret such definition as (1.3), where the set X is omitted because it is clear from the context. For instance, if the context is clear, the set $\{x \in \mathbb{R} : x \geq 0\}$ could be simply written as $\{x : x \geq 0\}$ or even $\{x \geq 0\}$. By the same token, the phrase “ $\in X$ ” in (1.4) could be omitted. So we can also write

$$A \cup B = \{x : x \in A \text{ or } x \in B\} \quad A \cap B = \{x : x \in A \text{ and } x \in B\}$$

which are special cases of (1.4).

Remark 1.2. In the same spirit, when discussing subsets of a given “large” set X , and if X is clear from the context, we shall write $X \setminus A$ (where $A \subset X$) as A^c and call it the **complement** of A .

Example 1.3. We have

$$\bigcup_{x \in (1, +\infty)} [0, x) = [0, +\infty) \quad \bigcap_{n \in \mathbb{Z}_+} (0, 1 + 1/n) = (0, 1] \quad \bigcup_{n \in \mathbb{N}} (0, 1 - 1/n] = (0, 1)$$

The readers may notice that these examples are not exactly in the form (1.4). They are actually unions and intersections of indexed families of sets. (See Def. 1.10.) We need some preparation before discussing this notion.

Axiom. If A_1, \dots, A_n are sets, their **Cartesian product** exists:

$$A_1 \times \cdots \times A_n = \{(a_1, \dots, a_n) : a_i \in A_i \text{ for all } 1 \leq i \leq n\}$$

where two elements (a_1, \dots, a_n) and (b_1, \dots, b_n) of the Cartesian product are regarded equal iff $a_1 = b_1, \dots, a_n = b_n$. We also write

$$(a_1, \dots, a_n) = a_1 \times \cdots \times a_n$$

especially when a, b are real numbers and (a, b) can mean an open interval. We understand $A_1 \times \cdots \times A_n$ as \emptyset if some A_i is \emptyset .

If $A_1 = \cdots = A_n = A$, we write the Cartesian product as A^n . □

Example 1.4. Assume that the set of real numbers \mathbb{R} exists. Then the set of complex numbers \mathbb{C} is defined to be $\mathbb{R}^2 = \mathbb{R} \times \mathbb{R}$ as a set. We write $(a, b) \in \mathbb{C}$ as $a + bi$ where $a, b \in \mathbb{R}$. Define

$$\begin{aligned}(a + bi) + (c + di) &= (a + c) + (b + d)i \\ (a + bi) \cdot (c + di) &= (ac - bd) + (ad + bc)i\end{aligned}$$

Define the zero element 0 of \mathbb{C} to be $0 + 0i$. More generally, we consider \mathbb{R} as a subset of \mathbb{C} by viewing $a \in \mathbb{R}$ as $a + 0i \in \mathbb{C}$. This defines the usual arithmetic of complex numbers.

If $z = a + bi$, we define its **absolute value** $|z| = \sqrt{a^2 + b^2}$. Then $z = 0$ iff $|z| = 0$. We define the **(complex) conjugate** of z to be $\bar{z} = a - bi$. Then $|z|^2 = z\bar{z}$.

If $z \neq 0$, then there clearly exists a unique $z^{-1} \in \mathbb{C}$ such that $zz^{-1} = z^{-1}z = 1$: $z^{-1} = |z|^{-2} \cdot \bar{z}$. Thus, using the language of modern algebra, \mathbb{C} is a **field**.¹ \square

The axiom of Cartesian product allows us to define relations and functions:

Definition 1.5. If A, B are sets, a subset R of $A \times B$ is called a **relation**. For $(a, b) \in A \times B$, we write aRb iff $(x, y) \in R$. We understand “ aRb ” as “ a is related to b through the relation R ”.

Definition 1.6. A relation f of A, B is called a **function** or a **map** (or a **mapping**), if for every $a \in A$ there is a unique $b \in B$ such that afb . In this case, we write $b = f(a)$.

When we write $f : A \rightarrow B$, we always mean that A, B are sets and f is a function from A to B . A and B are called respectively the **domain** and the **codomain** of f . (Sometimes people also use the words “source” and “target” to denote A and B .)

If $E \subset A$ and $F \subset B$, we define the **image under f** of E and the **preimage under f** of F to be

$$\begin{aligned}f(E) &= \{b \in B : \exists a \in E \text{ such that } b = f(a)\} \\ f^{-1}(F) &= \{a \in A : f(a) \in F\}.\end{aligned}$$

$f(A)$ is simply called the **image** of f , or the **range** of f . If $b \in B$, $f^{-1}(\{b\})$ is often abbreviated to $f^{-1}(b)$. The function

$$f|_E : E \rightarrow B \quad x \mapsto f(x)$$

is called the **restriction** of f to E . \square

¹See Rem. 6.7 or [Rud-P, Def. 1.12] for the definition of fields. Rather than memorizing the full definition of fields, it is more important to keep in mind some typical (counter)examples: $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ are fields. \mathbb{Z} is not a field, because not every non-zero element of \mathbb{Z} has an inverse. The set of quaternions $\{a + bi + cj + dk : a, b, c, d \in \mathbb{R}\}$ is not a field because it is not commutative ($ij = -ji = k$). The set of rational functions $P(x)/Q(x)$, where P, Q are polynomials with coefficients in \mathbb{R} and $Q \neq 0$, is a field.

The intuition behind the definition of functions is clear: we understand functions as the same as their graphs. So a subset f of the “coordinate plane” $A \times B$ is the graph of a function iff it “intersects every vertical line precisely once”.

Remark 1.7. According to our definition, \emptyset (as a subset of $\emptyset \times B$) is the only function from \emptyset to B . (A false assumption implies any statement.) If $A \neq \emptyset$, there are no functions $A \rightarrow \emptyset$.

Definition 1.8. A function $x : \mathbb{Z}_+ \rightarrow A$ is called a **sequence in A** . We write $x(n)$ as x_n , and write this sequence as $(x_n)_{n \in \mathbb{Z}_+}$ (or simply $(x_n)_n$ or (x_n)).

Many people write such a sequence as $\{x_n\}_{n \in \mathbb{Z}_+}$. We do not use this notation, since it can be confused with $\{x_n : n \in \mathbb{Z}_+\}$ (the range of the function x).

Axiom. If X is a set, then the **power set** 2^X exists, where

$$2^X = \{\text{Subsets of } X\}$$

Example 1.9. The set $2^{\{1,2,3\}}$ has 8 elements: $\emptyset, \{1\}, \{2\}, \{3\}, \{1,2\}, \{1,3\}, \{2,3\}, \{1,2,3\}$. Surprisingly, $8 = 2^3$. As we shall see in Exp. 1.54 and Cor. 1.57, this relationship holds more generally, which explains the terminology 2^X .

Now we are ready to define indexed families of sets.

Definition 1.10. An **indexed family of sets** $(S_i)_{i \in I}$ is defined to be a function $S : I \rightarrow 2^X$ for some sets I, X . We write $S(i)$ as S_i . (So S_i is a subset of X .) I is called the **index set**. Define

$$\bigcup_{i \in I} S_i = \bigcup_{T \in S(I)} T \quad \bigcap_{i \in I} S_i = \bigcap_{T \in S(I)} T$$

Note that $S(I)$ is the image of the function S .

Example 1.11. In the union $\bigcup_{x \in (1, +\infty)} [0, x)$, the index set is $I = (1, +\infty)$, and X can be the set of real numbers \mathbb{R} . Then $S : I \rightarrow 2^X$ is defined to be $S_i = S(i) = [0, i)$.

Exercise 1.12. Let $f : A \rightarrow B$ be a function. We say that f is **injective** if for all $a_1, a_2 \in A$ satisfying $a_1 \neq a_2$ we have $f(a_1) \neq f(a_2)$. We say that f is **surjective** if for each $b \in B$ we have $f^{-1}(b) \neq \emptyset$. f is called **bijective** if it is both surjective and injective. Define the **identity maps** $\text{id}_A : A \rightarrow A, a \mapsto a$ and id_B in a similar way. Prove that

$$f \text{ is injective} \iff \text{there is } g : B \rightarrow A \text{ such that } g \circ f = \text{id}_A \quad (1.5a)$$

$$f \text{ is surjective} \iff \text{there is } g : B \rightarrow A \text{ such that } f \circ g = \text{id}_B \quad (1.5b)$$

$$f \text{ is bijective} \iff \text{there is } g : B \rightarrow A \text{ such that } g \circ f = \text{id}_A \text{ and } f \circ g = \text{id}_B \quad (1.5c)$$

Show that the g in (1.5a) (resp. (1.5b), (1.5c)) is surjective (resp. injective, bijective).

The equivalence (1.5b) is subtler, since its proof requires Axiom of Choice.

Axiom. Let $(S_i)_{i \in I}$ be an indexed family of sets. The **Axiom of Choice** asserts that if $S_i \neq \emptyset$ for all $i \in I$, then there exists a function (the **choice function**)

$$f : I \rightarrow \bigcup_{i \in I} S_i$$

such that $f(i) \in S_i$ for each $i \in I$.

Intuitively, the axiom of choice says that for each $i \in I$ we can choose an element $f(i)$ of S_i . And such choice gives a function f .

Example 1.13. Let $f : A \rightarrow B$ be surjective. Then each member of the family $(f^{-1}(b))_{b \in B}$ is nonempty. Thus, by axiom of choice, there is a choice function g defined on the index set B such that $g(b) \in f^{-1}(b)$ for each b . Clearly $f \circ g = \text{id}_B$.

Remark 1.14. Suppose that each member S_i of the family $(S_i)_{i \in I}$ has exactly one element. Then the existence of a choice function does not require Axiom of Choice: Let $X = \bigcup_{i \in I} S_i$ and define relation

$$f = \{(i, x) \in I \times X : x \in S_i\}$$

Then one checks easily that this relation between I and X is a function, and that it is the (necessarily unique) choice function of $(S_i)_{i \in I}$.

According to the above remark, one does not need Axiom of Choice to prove (1.5a) and (1.5c). Can you see why?

1.2 Partial and total orders, equivalence relations

Definition 1.15. Let A be a set. A **partial order** (or simply an **order**) \leq on A is a relation on $A \times A$ satisfying for all $a, b, c \in A$ that:

- (Reflexivity) $a \leq a$.
- (Antisymmetry) If $a \leq b$ and $b \leq a$ then $a = b$.
- (Transitivity) If $a \leq b$ and $b \leq c$ then $a \leq c$.

We write $b \geq a$ iff $a \leq b$. Write $a > b$ iff $a \geq b$ and $a \neq b$. Write $a < b$ iff $b > a$. So \geq is also an order on A . The pair (A, \leq) is called a **partially ordered set**, or simply a **poset**. A partial order \leq on A is called a **total order**, if for every $a, b \in A$ we have either $a \leq b$ or $b \leq a$.

Example 1.16. The following are examples of orders.

- Assume that \mathbb{R} exists. Then \mathbb{R} has the canonical total order, which restricts to the total order of \mathbb{Z} . This is the total order that everyone is familiar with.
- Let X be a set. Then $(2^X, \subset)$ is a poset.
- \mathbb{R}^2 is a poset, if we define $(a, b) \leq (c, d)$ to be $a \leq c$ and $b \leq d$.

Definition 1.17. A relation \sim on a set A is called an **equivalence relation**, if for all $a, b, c \in A$ we have

- (Reflexivity) $a \sim a$.
- (Symmetry) $a \sim b$ iff $b \sim a$.
- (Transitivity) If $a \sim b$ and $b \sim c$ then $a \sim c$.

Later, we will use the notions of partial orders and equivalence relation not just for a set, but for a collection of objects “larger” than a set. See Sec. 1.4.

Definition 1.18. Let A be a set, together with an equivalence relation \sim . Define a new set

$$A/\sim = \{[a] : a \in A\}$$

where the notion $[a]$ can be understood in the following two equivalent ways (we leave it to the readers to check the equivalence):

- (1) $[a]$ is a new symbol. We understand $[a]$ and $[b]$ as equal iff $a \sim b$.
- (2) $[a] = \{x \in A : x \sim a\}$

We call $[a]$ the **equivalence class** (or the **residue class**) of a , and call A/\sim the **quotient set** of A under \sim . The surjective map $\pi : a \in A \mapsto [a] \in A/\sim$ is called the **quotient map**.

Exercise 1.19. Prove that every surjective map is equivalent to a quotient map. More precisely, prove that for every surjection $f : A \rightarrow B$, there is an equivalence relation \sim on A and a bijective map $\Phi : A/\sim \rightarrow B$ such that the following diagram commutes (i.e. $f = \Phi \circ \pi$):

$$\begin{array}{ccc} & A & \\ \pi \swarrow & & \searrow f \\ A/\sim & \xrightarrow{\Phi} & B \end{array} \quad (1.6)$$

This is the first time we see commutative diagrams. Commutative diagrams are very useful for indicating that certain maps between sets are “equivalent” or are satisfying some more general relations. For example, (1.6) shows that the maps f and π are equivalent, and that this equivalence is implemented by the bijection Φ . The formal definition of commutative diagrams is the following:

Definition 1.20. A diagram (i.e. some sets denoted by symbols, and some maps denoted by arrows) is called a **commutative diagram**, if all directed paths in the diagram with the same start and endpoints lead to the same result.

Here is an example of commutative diagram in linear algebra. This example assumes some familiarity with the basic properties of vector spaces and linear maps.²

Example 1.21. Let V, W be vector spaces over a field \mathbb{F} with finite dimensions m, n respectively. Let e_1, \dots, e_m be a basis of V , and let $\varepsilon_1, \dots, \varepsilon_n$ be a basis of W . We know that there are unique linear isomorphisms $\Phi : \mathbb{F}^m \xrightarrow{\cong} V$ and $\Psi : \mathbb{F}^n \xrightarrow{\cong} W$ such that

$$\Phi(a_1, \dots, a_m) = a_1 e_1 + \dots + a_m e_m \quad \Psi(b_1, \dots, b_n) = b_1 \varepsilon_1 + \dots + b_n \varepsilon_n$$

Let $T : V \rightarrow W$ be a **linear map**, i.e., a map satisfying $T(a\xi + b\eta) = aT\xi + bT\eta$ for all $a, b \in \mathbb{F}, \xi, \eta \in V$. Then there is a unique $n \times m$ matrix $A \in \mathbb{F}^{n \times m}$ (viewed as a linear map $\mathbb{F}^m \rightarrow \mathbb{F}^n$ defined by matrix multiplication) such that the following diagram commutes:

$$\begin{array}{ccc} \mathbb{F}^m & \xrightarrow[\cong]{\Phi} & V \\ A \downarrow & & \downarrow T \\ \mathbb{F}^n & \xrightarrow[\cong]{\Psi} & W \end{array} \quad (1.7)$$

namely, $T\Phi = \Psi A$. This commutative diagram tells us that T is equivalent to its **matrix representation** A under the bases $e_\bullet, \varepsilon_\star$, and that this equivalence is implemented by the linear isomorphisms Φ (on the sources) and Ψ (on the targets).

Commutative diagrams are ubiquitous in mathematics. You should learn how to read commutative diagrams and understand their intuitive meanings. We will see more examples in the future of this course.

1.3 \mathbb{Q}, \mathbb{R} , and $\overline{\mathbb{R}} = [-\infty, +\infty]$

Using equivalence classes, one can construct rational numbers from integers, and real numbers from rationals. We leave the latter construction to the future, and discuss the construction of rationals here.

Example 1.22 (Construction of \mathbb{Q} from \mathbb{Z}). Define a relation on $\mathbb{Z} \times \mathbb{Z}^\times$ (where $\mathbb{Z}^\times = \mathbb{Z} \setminus \{0\}$) as follows. If $(a, b), (a', b') \in \mathbb{Z} \times \mathbb{Z}^\times$, we say $(a, b) \sim (a', b')$ iff $ab' = a'b$. It is a routine check that \sim is an equivalence relation. Let $\mathbb{Q} = (\mathbb{Z} \times \mathbb{Z}^\times) / \sim$, and write

²Again, we refer the readers to Internet or any Linear Algebra textbook (e.g. [Axl]) for the definition of vector spaces and linear maps.

the equivalence class of (a, b) as a/b or $\frac{a}{b}$. Define additions and multiplications in \mathbb{Q} to be

$$\frac{a}{b} + \frac{c}{d} = \frac{ad + bc}{bd} \quad \frac{a}{b} \cdot \frac{c}{d} = \frac{ac}{bd}$$

We leave it to the readers to check that this definition is **well-defined**: If $(a, b) \sim (a', b')$ and $(c, d) \sim (c', d')$ then $(ad + bc, bd) \sim (a'd' + b'c', b'd')$ and $(ac, bd) \sim (a'c', b'd')$.

We regard \mathbb{Z} as a subset of \mathbb{Q} by identifying $n \in \mathbb{Z}$ with $\frac{n}{1}$. (This is possible since the map $n \in \mathbb{Z} \mapsto \frac{n}{1} \in \mathbb{Q}$ is injective.) Each $a/b \in \mathbb{Q}$ has additive inverse $-\frac{a}{b}$. If $a/b \in \mathbb{Q}$ is not zero (i.e. $(a, b) \not\sim (0, 1)$), then a/b has multiplicative inverse b/a . This makes \mathbb{Q} a field: the field of **rational numbers**.

If $a/b \in \mathbb{Q}$, we say $a/b \geq 0$ if $ab \geq 0$. Check that this is well-defined (i.e., if $(a, b) \sim (a', b')$, then $ab \geq 0$ iff $a'b' \geq 0$). More generally, if $a/b, c/d \in \mathbb{Q}$, we say $\frac{a}{b} \geq \frac{c}{d}$ if $\frac{a}{b} - \frac{c}{d} \geq 0$. Check that \geq is a total order on \mathbb{Q} . Check that \mathbb{Q} is an Archimedean ordered field, defined below. \square

Definition 1.23. A field \mathbb{F} , together with a total order \leq , is called an **ordered field**, if for every $a, b, c \in \mathbb{F}$ we have

- (Addition preserves \leq) If $a \leq b$ then $a + c \leq b + c$.
- (Multiplication by $\mathbb{F}_{\geq 0}$ preserves ≥ 0) If $a, b \geq 0$ then $ab \geq 0$.

These two properties relate \leq to $+$ and \cdot respectively.

Remark 1.24. Many familiar properties about inequalities in \mathbb{Q} hold for an ordered field. For instance:

$$\begin{aligned} a \geq b \wedge c \geq d &\implies a + c \geq b + d \\ a \geq 0 &\iff -a \leq 0 \\ a \geq 0 \wedge b \geq c &\iff ab \geq ac \\ a \leq 0 \wedge b \geq c &\iff ab \leq ac \\ a^2 &\geq 0 \\ 0 < a \leq b &\implies 0 < b^{-1} \leq a^{-1} \end{aligned}$$

Check them yourself, or see [Rud-P, Prop. 1.18].

Definition 1.25. We say that an ordered field \mathbb{F} satisfies **Archimedean property** if for each $a, b \in \mathbb{F}$ we have

$$a > 0 \implies \exists n \in \mathbb{N} \text{ such that } na > b$$

where na means $\underbrace{a + \cdots + a}_n$.

Example 1.26. \mathbb{Q} satisfies Archimedean property. Indeed, let $a, b \in \mathbb{Q}$ and $a > 0$. Then $a = p/q$ and $b = r/s$ where $p, q, s \in \mathbb{Z}_+$ and $r \in \mathbb{Z}$. So $na > b$ where $n = q|r| + q$.

Prop. 1.29 gives an important application of Archimedean property. We will use this in the construction of \mathbb{R} from \mathbb{Q} , and in the proof that \mathbb{Q} is dense in \mathbb{R} .

Definition 1.27. Let \mathbb{F} be a field. A subset $\mathbb{E} \subset \mathbb{F}$ is called a **subfield** of \mathbb{F} , if \mathbb{E} contains the 1 of \mathbb{F} , and if \mathbb{E} is closed under the operations of addition, multiplication, taking negative, and taking inverse in \mathbb{F} (i.e. if $a, b \in \mathbb{E}$ then $a + b, ab, -a \in \mathbb{E}$, and $a^{-1} \in \mathbb{E}$ whenever $a \neq 0$). We also call \mathbb{F} a **field extension** of \mathbb{E} , since \mathbb{E} is clearly a field.

Note that if \mathbb{E} is a subfield of \mathbb{F} , the 0 of \mathbb{F} is in \mathbb{E} since $0 = 1 + (-1) \in \mathbb{E}$.

Definition 1.28. Let \mathbb{E} be an ordered field. A field extension \mathbb{F} of \mathbb{E} is called an **ordered field extension**, if \mathbb{F} is equipped with a total order \leq such that \mathbb{F} is an ordered field, and if the order \leq of \mathbb{F} restricts to that of \mathbb{E} . We also call \mathbb{E} an **ordered subfield** of \mathbb{F} .

Our typical example of ordered field extension will be $\mathbb{Q} \subset \mathbb{R}$.

Proposition 1.29. Let \mathbb{F} be an ordered field extension of \mathbb{Q} . Assume that \mathbb{F} is Archimedean. Then for every $x, y \in \mathbb{F}$ satisfying $x < y$, there exists $p \in \mathbb{Q}$ such that $x < p < y$.

Proof. Assume $x, y \in \mathbb{F}$ and $x < y$. Then $y - x > 0$ (since $y - x \neq 0$ and $-x + x \leq -x + y$). By Archimedean property, there exists $n \in \mathbb{Z}_+$ such that $n(y - x) > 1$. So $y - x > \frac{1}{n}$ and hence $x + \frac{1}{n} < y$.

Let us prove that the subset

$$A = \left\{ k \in \mathbb{Z} : \frac{k}{n} \leq x \right\}$$

is nonempty and bounded from above in \mathbb{Z} . By Archimedean property, there is $m \in \mathbb{Z}_+$ such that $m > nx$, i.e. $\frac{m}{n} > x$. So for each $k \in \mathbb{Z}_+$ satisfying $k \geq m$, we have $\frac{k}{n} = \frac{m}{n} + \frac{k-m}{n} > x$. Therefore, for each $k \in A$ we have $k < m$. So A is bounded above. By Archimedean property again, there is $l \in \mathbb{Z}_+$ such that $\frac{l}{n} > -x$. So $-\frac{l}{n} < x$, and hence A is nonempty.

We now use the fact that every nonempty subset of \mathbb{Z} bounded above has a maximal element. Let $k = \max A$. Since $k + 1 \notin A$, we have $x < \frac{k+1}{n}$. Since $\frac{k}{n} \leq x$, we have

$$\frac{k+1}{n} = \frac{k}{n} + \frac{1}{n} \leq x + \frac{1}{n} < y$$

This proves $x < p < y$ with $p = \frac{k+1}{n}$. □

To introduce \mathbb{R} formally, we need more definitions:

Definition 1.30. Let (X, \leq) be a poset and $E \subset X$. An **upper bound of E in X** is an element $x \in X$ satisfying $e \leq x$ for all $e \in E$. An upper bound $x \in X$ of E is called a **least upper bound** or a **supremum** if $x \leq y$ for every upper bound $y \in Y$ of E . In this case, we write the supremum as $\sup E$. It is not hard to check that supremums are unique if they exist.

We leave it to the readers to define **lower bounds** and the **greatest lower bound** (if exists) of E , also called the **infimum** and is denoted by $\inf E$. \square

Definition 1.31. Let (X, \leq) be a poset. We say that X satisfies the **least-upper-bound property**, if every every nonempty subset $E \subset X$ which is bounded above (i.e. E has an upper bound) has a supremum in X . The **greatest-lower-bound property** is defined in the opposite way.

Example 1.32. \mathbb{Z} satisfies the least-upper-bound and the greatest-lower-bound property: Let $A \subset \mathbb{Z}$. If A is bounded above (resp. below), then the maximum $\max A$ (resp. minimum $\min A$) exists and is the supremum (resp. infimum) of A .

Example 1.33. Let X be a set. Then $(2^X, \subset)$ satisfies the least-upper-bound and the greatest-lower-bound property: Let $\mathcal{A} \subset 2^X$, i.e., \mathcal{A} is a set of subsets of X . Then \mathcal{A} is bounded from above by X , and is bounded from below by \emptyset . Moreover,

$$\sup \mathcal{A} = \bigcup_{A \in \mathcal{A}} A \quad \inf \mathcal{A} = \bigcap_{A \in \mathcal{A}} A$$

Theorem 1.34. *There is an ordered field extension of \mathbb{Q} which is Archimedean and satisfies the least-upper-bound property. This field is denoted by \mathbb{R} . Its elements are called **real numbers**.*

Thm. 1.34 will be proved in Ch. 6. Note that by taking negative, we see that \mathbb{R} also satisfies the greatest-lower-bound property.

Remark 1.35. The ordered field extensions satisfying the conditions in Thm. 1.34 are unique “up to isomorphisms”. (The words “**isomorphism**” and “equivalence” are often interchangeable, though “isomorphism” is more often used in the algebraic setting, whereas “equivalence” can be used in almost every context. For example, in point-set topology, “equivalence” means “homeomorphism”.) We leave it to the readers to give the precise statement. We will not use this uniqueness in this course.

Note that to compare two extensions \mathbb{F}, \mathbb{R} of \mathbb{Q} , it is very confusing to regard \mathbb{Q} as a subset of both \mathbb{F} and \mathbb{R} . You’d better consider two different injective maps $\tau : \mathbb{Q} \rightarrow \mathbb{F}$ and $\iota : \mathbb{Q} \rightarrow \mathbb{R}$ preserving the algebraic operations and the order of \mathbb{Q} , and use a commutative diagram to indicate that τ and ι are equivalent. (Thus, what’s happening here is that we have an equivalence of maps, not just an equivalence of the fields \mathbb{F} and \mathbb{R} .) \square

Definition 1.36. Let $-\infty, +\infty$ be two different symbols, and extend the total order \leq of \mathbb{R} to the **extended real line**

$$\overline{\mathbb{R}} = \mathbb{R} \cup \{-\infty, +\infty\}$$

by letting $-\infty < x < +\infty$ for all $x \in \mathbb{R}$. Define for each $x \in \mathbb{R}$ that

$$\begin{aligned} x \pm \infty &= \pm\infty + x = \pm\infty & +\infty - (-\infty) &= +\infty \\ x \cdot (\pm\infty) &= \pm\infty \cdot x = \begin{cases} \pm\infty & \text{if } x > 0 \\ 0 & \text{if } x = 0 \\ \mp\infty & \text{if } x < 0 \end{cases} \\ \frac{x}{\pm\infty} &= 0 \\ \frac{\pm\infty}{x} &= x^{-1} \cdot (\pm\infty) \quad \text{if } x \neq 0 \end{aligned}$$

If $a, b \in \overline{\mathbb{R}}$ and $a \leq b$, we define **intervals** with endpoints a, b :

$$\begin{aligned} [a, b] &= \{x \in \overline{\mathbb{R}} : a \leq x \leq b\} & (a, b) &= \{x \in \overline{\mathbb{R}} : a < x < b\} \\ (a, b] &= \{x \in \overline{\mathbb{R}} : a < x \leq b\} & [a, b) &= \{x \in \overline{\mathbb{R}} : a \leq x < b\} \end{aligned} \tag{1.8}$$

So $\mathbb{R} = (-\infty, +\infty)$ and $\overline{\mathbb{R}} = [-\infty, +\infty]$. If a, b are in \mathbb{R} , we say that the corresponding interval is **bounded**.

In this course, unless otherwise stated, an interval always means one of the four sets in (1.8). The first two intervals are called respectively a **closed interval** and an **open interval**.

Remark 1.37. Clearly, every subset E of $\overline{\mathbb{R}}$ is bounded and has a supremum and an infimum. We have that $\sup E = +\infty$ iff E is not bounded above in \mathbb{R} , and that $\inf E = -\infty$ iff E is not bounded below in \mathbb{R} .

1.4 Cardinalities, countable sets, and product spaces Y^X

Definition 1.38. Let A and B be sets. We say that A and B have the same **cardinality** and write $\text{card}(A) = \text{card}(B)$ (or simply $A \approx B$), if there is a bijection $f : A \rightarrow B$. We write $\text{card}(A) \leq \text{card}(B)$ (or simply $A \lesssim B$) if A and a subset of B have the same cardinality.

Exercise 1.39. Show that $\text{card}(A) \leq \text{card}(B)$ iff there is an injection $f : A \rightarrow B$, iff there is a surjection $g : B \rightarrow A$. (You need either Axiom of Choice or its consequence (1.5b) to prove the last equivalence.)

It is clear that \approx is an equivalence relation on the collection of sets. It is also true that \lesssim is a partial order: Reflexivity and transitivity are easy to show. The proof of antisymmetry is more involved:

Theorem 1.40 (Schröder-Bernstein). *Let A, B be two sets. If $A \lesssim B$ and $B \lesssim A$, then $A \approx B$.*

★★ *Proof.* Assume WLOG that $A \subset B$. Let $f : B \rightarrow A$ be an injection. Let $A_n = f^n(A)$ defined inductively by $f^0(A) = A$, $f^n(A) = f(f^{n-1}(A))$. Let $B_n = f^n(B)$. Then

$$B_0 \supset A_0 \supset \cdots \supset B_n \supset A_n \supset B_{n+1} \supset \cdots$$

In particular, $C = \bigcap_{n \in \mathbb{N}} A_n$ equals $\bigcap_{n \in \mathbb{N}} B_n$. Note that f gives a bijection $B_n \setminus A_n \rightarrow B_{n+1} \setminus A_{n+1}$ (since f gives bijections $B_n \rightarrow B_{n+1}$ and $A_n \rightarrow A_{n+1}$). Therefore, we have a bijection $g : B \rightarrow A$ defined by

$$g(x) = \begin{cases} f(x) & \text{if } x \in B_n \setminus A_n \text{ for some } n \in \mathbb{N} \\ x & \text{otherwise} \end{cases}$$

where “otherwise” means either $x \in C$ or $x \in A_n \setminus B_{n+1}$ for some n . □

Intuition about the above proof: View B as an onion. The layers of B are $B_n \setminus A_n$ (the odd layers) and $A_n \setminus B_{n+1}$ (the even layers). The bijection g maps each odder layer to the subsequent odd one, and fixes the even layers and the core C .

Example 1.41. If $-\infty < a < b < +\infty$, then $(0, 1) \approx (a, b)$.

Proof. $f : (0, 1) \rightarrow (a, b)$ sending x to $(b - a)x + a$ is a bijection. □

Example 1.42. If $-\infty < a < b < +\infty$, then $\mathbb{R} \approx (a, b)$

Proof. By the previous example, it suffices to prove $\mathbb{R} \approx (-1, 1)$. The function

$$f : \mathbb{R} \rightarrow (-1, 1) \quad f(x) = \begin{cases} \frac{x}{1+x} & \text{if } x \geq 0 \\ -f(-x) & \text{if } x < 0 \end{cases} \quad (1.9)$$

is bijective. □

Alternatively, one may use the tangent function to give a bijection between $(-\pi/2, \pi/2)$ and \mathbb{R} . I have avoided this method, since (1.9) is more elementary than trigonometric functions. The mathematically rigorous definition of trigonometric functions and the verification of their well-known properties are far from easy tasks.

Proposition 1.43. *Let I be an interval with endpoints $a < b$ in $\overline{\mathbb{R}}$. Then $I \approx \mathbb{R}$.*

Proof. Let $A = (0, 1) \cup \{-\infty, +\infty\}$. By Exp. 1.42, we have

$$(a, b) \subset I \lesssim \overline{\mathbb{R}} \approx A \approx [0, 1] \subset (-2, 2) \approx (a, b)$$

So $I \approx \overline{\mathbb{R}}$ by Schröder-Bernstein Thm. 1.40. In particular, $\mathbb{R} = (-\infty, +\infty) \approx \overline{\mathbb{R}}$. □

Definition 1.44. A set A is called **finite** if $A \lesssim \{1, \dots, n\}$ for some $n \in \mathbb{Z}_+$. A is called **countable** if $A \lesssim \mathbb{N}$.

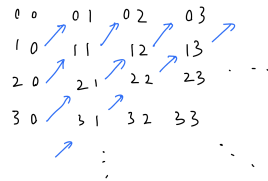
Clearly, a set A is finite iff either $A \approx \emptyset$ or $A \approx \{1, \dots, n\}$ for some $n \in \mathbb{Z}_+$.

Remark 1.45. Let $A \subset \mathbb{N}$. If A is bounded above, then $A \subset \{0, \dots, n\}$ and hence A is finite. If A is not bounded above, then we can construct a strictly increasing sequence $(x_n)_{n \in \mathbb{N}}$ in A . (Pick any $x_0 \in A$. Suppose we have $x_n \in A$. Since x_n is not an upper bound of A , there is $x_{n+1} \in A$ larger than x_n . So $(x_n)_{n \in \mathbb{N}}$ can be constructed inductively.) This gives an injection $\mathbb{N} \rightarrow A$. Therefore $A \gtrsim \mathbb{N}$, and hence $A \approx \mathbb{N}$ by Schröder-Bernstein.

It follows that if $B \lesssim \mathbb{N}$, then either B is a finite set, or $B \approx \mathbb{N}$. Therefore, “a set B is **countably infinite**” means the same as “ $B \approx \mathbb{N}$ ”. \square

Theorem 1.46. A countable union of countable sets is countable. In particular, $\mathbb{N} \times \mathbb{N} \approx \mathbb{N}$.

Proof. Recall Exe. 1.39. Let A_1, A_2, \dots be countable sets. Since each A_i is countable, there is a surjection $f_i : \mathbb{N} \rightarrow A_i$. Thus, the map $f : \mathbb{N} \times \mathbb{N} \rightarrow \bigcup_i A_i$ defined by $f(i, j) = f_i(j)$ is surjective. Therefore, it suffices to show that there is a surjection $\mathbb{N} \rightarrow \mathbb{N} \times \mathbb{N}$. This is true, since we have a bijection $g : \mathbb{N} \rightarrow \mathbb{N} \times \mathbb{N}$ where $g(0), g(1), g(2), \dots$ are $(0, 0), (1, 0), (0, 1), (2, 0), (1, 1), (0, 2), (3, 0), (2, 1), (1, 2), (0, 3)$, etc., as shown by the figure



\square

As an application, we prove the extremely important fact that \mathbb{Q} is countable.

Corollary 1.47. We have $\mathbb{N} \approx \mathbb{Z}_+ \approx \mathbb{Z} \approx \mathbb{Q}$.

Proof. Clearly $\mathbb{Z}_{<0} \approx \mathbb{N} \approx \mathbb{Z}_+$. By Thm. 1.46, $\mathbb{Z} = \mathbb{Z}_{<0} \cup \mathbb{N}$ is countably infinite, and hence $\mathbb{Z} \approx \mathbb{N}$. It remains to prove $\mathbb{Z} \approx \mathbb{Q}$. By Schröder-Bernstein, it suffices to prove $\mathbb{Q} \lesssim \mathbb{Z}$. By Thm. 1.46 again, $\mathbb{Z} \times \mathbb{Z} \approx \mathbb{Z}$. By Exp. 1.22, there is a surjection from a subset of $\mathbb{Z} \times \mathbb{Z}$ to \mathbb{Q} . So $\mathbb{Q} \lesssim \mathbb{Z} \times \mathbb{Z} \approx \mathbb{Z}$. \square

Later, when we have learned Zorn’s Lemma (an equivalent form of Axiom of Choice), we will be able to prove the following generalization of $\mathbb{N} \times \mathbb{N} \approx \mathbb{N}$. So we defer the proof of the following theorem to a later section.

Theorem 1.48. Let X be an infinite set. Then $X \times \mathbb{N} \approx X$.

Proof. See Thm. 16.7. □

Our next goal is to prove an exponential law $a^{b+c} = a^b \cdot a^c$ for cardinalities. For that purpose, we first need to define the set-theoretic operations that correspond to the summation $b + c$ and the exponential a^b .

Definition 1.49. We write $X = \bigsqcup_{\alpha \in \mathcal{A}} A_\alpha$ and call X the **disjoint union** of $(A_\alpha)_{\alpha \in \mathcal{A}}$, if $X = \bigcup_{\alpha \in \mathcal{A}} A_\alpha$ and $(A_\alpha)_{\alpha \in \mathcal{A}}$ is a family of pairwise disjoint sets (i.e. $A_\alpha \cap A_\beta = \emptyset$ if $\alpha \neq \beta$). If moreover $\mathcal{A} = \{1, \dots, n\}$, we write $X = A_1 \sqcup \dots \sqcup A_n$.

Definition 1.50. Let X, Y be sets. Then

$$Y^X = \{\text{functions } f : X \rightarrow Y\} \quad (1.10)$$

A more precise definition of Y^X (in the spirit of (1.3)) is $\{f \in X \times Y \mid f : X \rightarrow Y \text{ is a function}\}$. Note that by Rem. 1.7,

$$Y^\emptyset = \{\emptyset\} \quad (1.11)$$

This new notation is compatible with the old one $Y^n = Y \times \dots \times Y$:

Example 1.51. Let $n \in \mathbb{Z}_+$. We have $Y^{\{1, \dots, n\}} \approx Y^n$ due to the bijection

$$Y^{\{1, \dots, n\}} \rightarrow Y^n \quad f \mapsto (f(1), \dots, f(n))$$

Remark 1.52. The above example suggests that in the general case that X is not necessarily finite, we can view each function $f : X \rightarrow Y$ as $(f(x))_{x \in X}$, an **indexed family of elements** of Y with index set X . Thus, intuitively and hence not quite rigorously,

$$Y^X = \underbrace{Y \times Y \times \dots}_{\text{card}(X) \text{ pieces}} \quad (1.12)$$

This generalizes the intuition in Def. 1.8 that a function $f : \mathbb{Z}_+ \rightarrow Y$ is equivalently a sequence $(f(1), f(2), f(3), \dots)$.

The viewpoint that Y^X is a **product space** with index set X is very important and will be adopted frequently in this course. More generally, we can define: □

Definition 1.53. Let $(X_i)_{i \in I}$ be a family of sets with index set I . Their **product space** is defined by

$$\prod_{i \in I} X_i = \{f \in \mathfrak{X}^I : f(i) \in X_i \text{ for all } i \in I\}$$

where $\mathfrak{X} = \bigcup_{i \in I} X_i$. If each X_i is nonempty, then $\prod_{i \in I} X_i$ is nonempty by Axiom of Choice. An element of $\prod_{i \in I} X_i$ is also written as $(f_i)_{i \in I}$ when the i -th component of it is $f_i \in X_i$.

In particular, if all X_i are equal to X , then $X^I = \prod_{i \in I} X$.

Example 1.54. Let X be a set. For each $A \subset X$, define the **characteristic function** $\chi_A : X \rightarrow \{0, 1\}$ to be

$$\chi_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{if } x \notin A \end{cases}$$

Then we have

$$2^X \approx \{0, 1\}^X$$

since the following map is bijective:

$$2^X \rightarrow \{0, 1\}^X \quad A \mapsto \chi_A$$

Its inverse is $f \in \{0, 1\}^X \mapsto f^{-1}(1) \in 2^X$.

Proposition 1.55 (Exponential Law). *Suppose that $X = A_1 \sqcup \cdots \sqcup A_n$. Then*

$$Y^X \approx Y^{A_1} \times \cdots \times Y^{A_n}$$

Proof. We have a bijection

$$\begin{aligned} \Phi : Y^X &\rightarrow Y^{A_1} \times \cdots \times Y^{A_n} \\ f &\mapsto (f|_{A_1}, \dots, f|_{A_n}) \end{aligned} \tag{1.13}$$

where we recall that $f|_{A_i}$ is the restriction of f to A_i . □

Exercise 1.56. Assume that A_1, \dots, A_n are subsets of X . Define Φ by (1.13). Prove that Φ is injective iff $X = A_1 \cup \cdots \cup A_n$. Prove that Φ is surjective iff A_1, \dots, A_n are pairwise disjoint.

Corollary 1.57. *Let X, Y be finite sets with cardinalities $m, n \in \mathbb{N}$ respectively. Assume that $Y \neq \emptyset$. Then Y^X is a finite set with cardinality n^m .*

Proof. The special case that $m = 0$ (i.e. $X = \emptyset$, cf. (1.11)) and $m = 1$ is clear. When $m > 1$, assume WLOG that $X = \{1, \dots, m\}$. Then $X = \{1\} \sqcup \cdots \sqcup \{m\}$. Apply Prop. 1.55 to this disjoint union. We see that $Y^X \simeq Y \times \cdots \times Y \simeq \{1, \dots, n\}^m$ has n^m elements. □

We end this section with some (in)equalities about the cardinalities of product spaces. To begin with, we write $X \lesssim Y$ (or $\text{card}(X) < \text{card}(Y)$) if $X \lesssim Y$ and $X \not\approx Y$.

Proposition 1.58. *Let X, Y be sets with $\text{card}(Y) \geq 2$ (i.e. Y has at least two elements). Then $X \lesssim Y^X$. In particular, $X \lesssim 2^X$.*

Proof. The case $X = \emptyset$ is obvious since $0 < 1$. So we assume $Y \neq \emptyset$. Clearly $2^X \simeq \{0, 1\}^X$ is $\lesssim Y^X$. So it suffices to prove $X \lesssim 2^X$. Since the map $X \rightarrow 2^X$ sending x to $\{x\}$ is injective, $X \lesssim 2^X$. Let us prove $X \approx 2^X$.

Assume that $X \approx 2^X$. So there is a bijection $\Phi : X \rightarrow 2^X$ sending each $x \in X$ to a subset $\Phi(x)$ of X . Motivated by Russell's Paradox (1.2), we define

$$S = \{x \in X : x \notin \Phi(x)\}$$

Since Φ is surjective, there exists $y \in X$ such that $S = \Phi(y)$. If $y \in \Phi(y)$, then $y \in S$, and hence $y \notin \Phi(y)$ by the definition of S . If $y \notin \Phi(y)$, then $y \notin S$, and hence $y \in \Phi(y)$ by the definition of S . This gives a contradiction. \square

Remark 1.59. Write $\{1, \dots, n\}^X$ as n^X for short. Assuming that real numbers have decimal, binary, or (more generally) base- n representations where $n \in \mathbb{Z}_{\geq 2}$, then $\mathbb{R} \approx n^{\mathbb{N}}$. So by Prop. 1.58, $\mathbb{N} \lesssim \mathbb{R}$, i.e. \mathbb{R} is *uncountable*. The base- n representations of real numbers suggest that $\text{card}(n^{\mathbb{N}})$ is independent of n . This fact can be proved by elementary methods without resorting to the analysis of real numbers:

Theorem 1.60. *Let X be an infinite set. Then*

$$2^X \approx 3^X \approx 4^X \approx \dots \approx \mathbb{N}^X$$

Proof. First, we assume that $X = \mathbb{N}$. Clearly, for each $n \in \mathbb{Z}_{\geq 2}$ we have $2^X \lesssim n^X \lesssim \mathbb{N}^X$. Since elements of \mathbb{N}^X are subsets of $X \times \mathbb{N}$ (i.e. elements of $2^{X \times \mathbb{N}}$), we have

$$\mathbb{N}^X \subset 2^{X \times \mathbb{N}} \simeq 2^X$$

since $X \times \mathbb{N} \approx X$ by Thm. 1.46. So $2^X \approx n^X \approx \mathbb{N}^X$ by Schröder-Bernstein.

As pointed out earlier (cf. Thm. 1.48), it can be proved by Zorn's Lemma that $X \times \mathbb{N} \approx X$ for every infinite set X . So the same conclusion holds for such X . \square

2 Metric spaces

We first give an informal introduction to metric spaces, hoping to motivate the readers from a (relatively) historical perspective. It is okay if you do not understand all of the concepts mentioned in the introduction on the first read. Simply return to this section when you feel unmotivated while formally studying these concepts in later sections. (The same suggestion applies to all the introductory sections and historical comments in our notes.)

2.1 Introduction: what is point-set topology?

The method which has been used with success by Volterra and Hilbert consists in observing that a function (for instance a continuous one) can be replaced by a countable infinity of parameters. One treats the problem first as though one had only a finite number of parameters and then one goes to the limit... We believe that this method has played a useful role because it followed intuition, but that its time has passed... The most fruitful method in functional analysis seems to us to treat the element of which the functional depends directly as a variable and in the form in which it presents itself naturally.

— Fréchet, 1925 (cf. [Jah, Sec. 13.8])

In this chapter, we begin the study of point-set topology by learning one of its most important notions: metric spaces. Similar to [Rud-P], we prefer to introduce metric spaces and basic point-set topology at the early stage of our study. An obvious reason for doing so is that metric spaces provide a uniform language for the study of basic analysis problems in $\mathbb{R}, \mathbb{R}^n, \mathbb{C}^n$, and more generally in function spaces such as the space of continuous functions $C([a, b])$ on the interval $[a, b] \subset \mathbb{R}$. With the help of such a language, for example, many useful criteria for the convergence of series in \mathbb{R} and \mathbb{C} (e.g. root test, ratio test) are generalized straightforwardly to criteria for the *uniform* convergence of series of functions in $C([a, b])$.

Point-set topology was born in 1906 when Fréchet defined metric spaces, motivated mainly by the study of function spaces in analysis (i.e. *functional analysis*). Indeed, point-set topology and functional analysis are the two faces of the same coin: they both originated from the study of **functionals**, i.e., functions of functions. See for example (2.1). The core ideas of point-set topology are as follows:

- (1) Take X to be a set of functions defined on a “classical space” (e.g. the set of all continuous functions $f : [a, b] \rightarrow \mathbb{C}$). Then a functional is a function $S : X \rightarrow \mathbb{C}$. This is a generalization of functions on $\mathbb{R}, \mathbb{C}, \mathbb{R}^n, \mathbb{C}^n$ or on their subsets.

- (2) Unlike \mathbb{R}^n , a function space X is usually “infinite dimensional”. Thus, one may think that a functional S is a function with infinite variables. In point-set topology, this viewpoint is abandoned; the philosophy of point-set topology is diametrically opposed to that of multivariable calculus.¹ Instead, one should view a functional S as a function with one variable x , where x denotes a general point of the function space X .
- (3) Rather than looking at each variable/component and doing explicit multivariable calculations, one uses geometric intuitions to study the analytic properties of functionals.² These geometric intuitions (e.g. distances, open balls, convergence) are borrowed from \mathbb{R} and \mathbb{R}^n and are mostly irrelevant to dimensions or numbers of variables.

(Sequential) **compactness**, **completeness**, and **separability** are prominent geometric properties that are useful in the study of the analytic properties of functionals. The importance of these three notions was already recognized by Fréchet by the time he defined metric spaces. The study of these three properties will be a main theme of our course.

Consider sequential compactness for example. The application of compactness to function spaces originated from the problems in calculus of variations. For instance, let $L(x, y, z)$ be a polynomial or (more generally) a continuous function in 3 variables. We want to find a “good” (e.g. differentiable) function $f : [0, 1] \rightarrow \mathbb{R}$ minimizing or maximizing the expression

$$S(f) = \int_0^1 L(t, f(t), f'(t)) dt \quad (2.1a)$$

This is the general setting of Lagrangian mechanics. In the theory of integral equations, one considers the extreme values and points of the functional

$$S(f) = \int_0^1 \int_0^1 f(x) K(x, y) \overline{f(y)} dx dy \quad (2.1b)$$

where $K : [0, 1]^2 \rightarrow \mathbb{R}$ is continuous and $f : [0, 1] \rightarrow \mathbb{C}$ is subject to the condition $\int_0^1 |f(x)|^2 dx \leq 1$. Any f maximizing (resp. minimizing) $S(f)$ is an eigenvector of the linear operator $g \mapsto \int_0^1 K(x, y) g(y) dy$ with maximal (resp. minimal) eigenvalue.

As we shall learn, (sequential) compactness is closely related to the problem of finding (or proving the existence of) maximal/minimal values of a continuous

¹Very often, the formula of $S(f)$ involves an integral. See e.g. (2.1). Mathematicians (e.g. Volterra, Lévy, Fredholm, and early Hilbert) used to study $S(f)$ by discretizing $S(f)$, i.e., by approximating integrals by finite sums. Thus, S is approximated by a sequence of functions with n variables where $n \rightarrow \infty$. This viewpoint is abandoned in point-set topology.

²This is similar to linear algebra where one prefers vectors, linear subspaces, and linear operators to n -tuples, sets of solutions, and matrices.

function and the points at which the function attains its maximum/minimum. So, in 19th century, when people were already familiar with sequential compactness in \mathbb{R}^n (e.g. Bolzano-Weierstrass theorem, Heine-Borel theorem), they applied compactness to function spaces and functionals. The idea is simple: Suppose we are given X , a set of functions (say continuous and differentiable) from $[a, b]$ to \mathbb{R} . We want to find $f \in X$ maximizing $S(f)$. Here is an explicit process (see also the proof of Lem. 3.2):

- (A) Find a sequence $(f_n)_{n \in \mathbb{Z}_+}$ in X such that $S(f_n)$ increases to $M = \sup S(X)$.
- (B) Define convergence in X in a suitable way, and verify that $S : X \rightarrow \mathbb{R}$ is continuous (i.e. if f_n converges to f in the way we define, then $S(f_n) \rightarrow S(f)$).
- (C) Suppose we can find a subsequence $(f_{n_k})_{k \in \mathbb{Z}_+}$ converging to some $f \in X$, then S attains its maximum at f . In particular, $S(f) = M$ and hence $M < +\infty$.

To carry out step (B), we need to define suitable geometric structures for a function space X so that the convergence of sequences in X and the continuity of functions $S : X \rightarrow \mathbb{R}$ can be defined and studied in a similar pattern as that for \mathbb{R}^n . **Metric** (of a metric space) and **topology** (of a topological space) are such geometric structures. As we shall learn, the topology of a metric space is uniquely determined by the convergence of sequences in this space.

Step (C) can be carried out if every sequence in X has a convergent subsequence, i.e., if X is sequentially compact. Thus, we need a good criterion for sequential compactness for subsets of a function space. Arzelà-Ascoli theorem, the $C([a, b])$ -version of Heine-Borel theorem, is such a criterion. This famous theorem was proved in late 19th century (and hence before the birth of point-set topology), and it gave an important motivation for Fréchet to consider metric spaces in general. We will learn this theorem at the end of the first semester.

To summarize: Metric spaces are defined not just for fun. We introduce such geometric objects because we want to study the convergence of sequences and the analytic properties of continuous functions using geometric intuitions. And moreover, the examples we are interested in are not just subsets of \mathbb{R}^n , but also subsets of function spaces. With this in mind, we now begin our journey into point-set topology.

2.2 Basic definitions and examples

Definition 2.1. Let X be a set. A function $d : X \times X \rightarrow \mathbb{R}_{\geq 0}$ is called a **metric** if for all $x, y, z \in X$ we have

$$(1) \quad d(x, y) = d(y, x).$$

(2) $d(x, y) = 0$ iff $x = y$.

(3) (Triangle inequality) $d(x, z) \leq d(x, y) + d(y, z)$.

The pair (X, d) , or simply X , is called a **metric space**. If $x \in X$ and $r \in (0, +\infty]$,³ the set

$$B_X(x, r) = \{y \in X : d(x, y) < r\}$$

often abbreviated to $B(x, r)$, is called the **open ball** with center x and radius r . If $r \in [0, +\infty)$,

$$\overline{B}_X(x, r) = \{y \in X : d(x, y) \leq r\}$$

also abbreviated to $\overline{B}(x, r)$, is called the **closed ball** with center x and radius r .

We make some comments on this definition.

Remark 2.2. That “ $d(x, y) = 0$ iff $x = y$ ” is very useful. Think about X as a set of functions $[0, 1] \rightarrow \mathbb{R}$ and d is a metric on X . To show that $f, g \in X$ are equal, instead of checking that infinitely many values are equal (i.e. $f(t) = g(t)$ for all $t \in \mathbb{R}$), it suffices to check that one value (i.e. $d(f, g)$) is zero.

Remark 2.3. Triangle inequality clearly implies “polygon inequality”:

$$d(x_0, x_n) \leq \sum_{j=1}^n d(x_{j-1}, x_j) \quad (2.2)$$

Remark 2.4. Choose distinct points $x, y \in X$. Then x, y are separated by two open balls centered at them: there exists $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$. This is called the **Hausdorff property**.

To see this fact, note that $d(x, y) > 0$. Choose r, ρ such that $r + \rho \leq d(x, y)$. If $z \in B(x, r) \cap B(y, \rho)$, then $d(x, z) + d(y, z) < r + \rho \leq d(x, y)$, contradicting triangle inequality.

We will see (cf. Prop. 2.19) that Hausdorff property guarantees that any sequence in a metric space cannot converge to two different points. Intuition: one cannot find a point which is very close to x and y at the same time. \square

We give some examples, and leave it to the readers to check that they satisfy the definition of metric spaces. We assume that square roots of positive real numbers can be defined. (We will rigorously define square roots after we define e^x using the series $\sum_{n \in \mathbb{N}} x^n / n!$.)

Example 2.5. \mathbb{R} is a metric space if we define $d(x, y) = |x - y|$

³We want open and closed balls to be nonempty. So we assume $r \neq 0$ only for open balls.

Example 2.6. On \mathbb{R}^n , we can define **Euclidean metric**

$$d(x, y) = \sqrt{(x_1 - y_1)^2 + \cdots + (x_n - y_n)^2}$$

if x_\bullet, y_\bullet are the components of x, y . The following are also metrics:

$$\begin{aligned} d_1(x, y) &= |x_1 - y_1| + \cdots + |x_n - y_n| \\ d_\infty(x, y) &= \max\{|x_1 - y_1|, \dots, |x_n - y_n|\} \end{aligned}$$

Example 2.7. The **Euclidean metric** on \mathbb{C}^n is

$$d(z, w) = \sqrt{|z_1 - w_1|^2 + \cdots + |z_n - w_n|^2}$$

which agrees with the Euclidean metric on \mathbb{R}^{2n} . The following are also metrics:

$$\begin{aligned} d_1(z, w) &= |z_1 - w_1| + \cdots + |z_n - w_n| \\ d_\infty(z, w) &= \max\{|z_1 - w_1|, \dots, |z_n - w_n|\} \end{aligned}$$

Convention 2.8. Unless otherwise stated, the metrics on \mathbb{R}^n and \mathbb{C}^n (and their subsets) are assumed to be the Euclidean metrics.

Remark 2.9. One may wonder what the subscripts $1, \infty$ mean. This notation is actually due to the general fact that

$$d_p(z, w) = \sqrt[p]{|z_1 - w_1|^p + \cdots + |z_n - w_n|^p}$$

is a metric where $1 \leq p < +\infty$, and $d_\infty = \lim_{q \rightarrow +\infty} d_q$. It is not easy to prove that d_p satisfies triangle inequality: one needs Minkowski inequality. For now, we will not use such general d_p . And we will discuss Minkowski inequality in later sections.

Example 2.10. Let $X = X_1 \times \cdots \times X_N$ where each X_i is a metric space with metric d_i . Write $x = (x_1, \dots, x_N) \in X$ and $y = (y_1, \dots, y_N) \in Y$. Then the following are metrics on X :

$$\begin{aligned} d(x, y) &= d_1(x_1, y_1) + \cdots + d_N(x_N, y_N) \\ \delta(x, y) &= \max\{d_1(x_1, y_1), \dots, d_N(x_N, y_N)\} \\ \rho(x, y) &= \sqrt{d_1(x_1, y_1)^2 + \cdots + d_N(x_N, y_N)^2} \end{aligned}$$

With respect to the metric δ , the open balls of X are “polydisks”

$$B_X(x, r) = B_{X_1}(x_1, r) \times \cdots \times B_{X_N}(x_N, r)$$

There is no standard choice of metric on the product of metric spaces. d, δ, ρ are all good, and they are equivalent in the following sense:

Definition 2.11. We say that two metrics d_1, d_2 on a set X are **equivalent** and write $d_1 \approx d_2$, if there exist $\alpha, \beta > 0$ such that for any $x, y \in X$ we have

$$d_1(x, y) \leq \alpha d_2(x, y) \quad d_2(x, y) \leq \beta d_1(x, y)$$

This is an equivalence relation. More generally, we may write $d_1 \lesssim d_2$ if $d_1 \leq \alpha d_2$ for some $\alpha > 0$. Then $d_1 \approx d_2$ iff $d_1 \lesssim d_2$ and $d_2 \lesssim d_1$.

Example 2.12. In Exp. 2.10, we have $\delta \leq \rho \leq d \leq N\delta$. So $\delta \approx \rho \approx d$.

Convention 2.13. Given finitely many metric spaces X_1, \dots, X_N , the metric on their product space $X = X_1 \times \dots \times X_N$ is chosen to be any one that is equivalent to the ones defined in Exp. 2.10. In the case that each X_i is a subset of \mathbb{R} or \mathbb{C} , we follow Convention 2.8 and choose the metric on X to be the Euclidean metric (unless otherwise stated).

Definition 2.14. Let (X, d) be a metric space. Then a **metric subspace** denotes an object $(Y, d|_Y)$ where $Y \subset X$ and $d|_Y$ is the restriction of d to Y , namely, for all $y_1, y_2 \in Y$ we set

$$d|_Y(y_1, y_2) = d(y_1, y_2)$$

Convention 2.15. Suppose Y is a subset of a given metric space (X, d) . Unless otherwise stated, the metric of Y is chosen to be $d|_Y$ whenever Y is viewed as a metric space. For example, the metric of any subset of \mathbb{R}^n is assumed to be the Euclidean metric, unless otherwise stated.

2.3 Convergence of sequences

Definition 2.16. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X . Let $x \in X$. We say that x is the **limit** of x_n and write $\lim_{n \rightarrow \infty} x_n = x$ (or $x_n \rightarrow x$), if:

- For every real number $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for every $n \geq N$ we have $d(x_n, x) < \varepsilon$.

Equivalently, this means that every (nonempty) open ball centered at x contains **all but finitely many** x_n .⁴

Remark 2.17. The negation of $x_n \rightarrow x$ is clear:

- There exists $\varepsilon > 0$ such that for all $N \in \mathbb{Z}_+$ there exists $n \geq N$ such that $d(x_n, x) \geq \varepsilon$.

⁴“All but finitely many x_n satisfies...” means “for all but finitely many n , x_n satisfies...”. It does NOT mean that “all but finitely many elements of the set $\{x_n : n \in \mathbb{Z}_+\}$ satisfies...”.

Namely, one changes each “for all” to “there exists”, changes each “there exists” to “for all”, and negate the last sentence.

Exercise 2.18. Show that in the above definition of limits, it suffices to consider rational numbers $\varepsilon > 0$. (Note: You need to use Prop. 1.29.)

This exercise implies that the definition of limits does not require the existence of real numbers, i.e., does not assume Thm. 1.34. Indeed, we will use limits of sequences (and “double sequences”) to prove Thm. 1.34.

In many textbooks and research papers, you will see phrases such as

$$x_n \text{ satisfies property } P \text{ for sufficiently large } n \quad (2.3)$$

This means that “there exists $N \in \mathbb{Z}_+$ such that P holds for all $n \geq N$ ”. (We also say that x_n **eventually** satisfies P .) Then $\lim_{n \rightarrow \infty} x_n = x$ means that “for every $\varepsilon > 0$, we have $d(x_n, x) < \varepsilon$ for sufficiently large n ”.

Proposition 2.19. Any sequence $(x_n)_{n \in \mathbb{Z}_+}$ in a metric space X has at most one limit.

Proof. Suppose $(x_n)_{n \in \mathbb{Z}_+}$ converges to $x, y \in X$ where $x \neq y$. By Hausdorff property (Rem. 2.4), there exist $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$. By the definition of $x_n \rightarrow x$, there exists $N_1 \in \mathbb{Z}_+$ such that $x_n \in B(x, r)$ for all $n \geq N_1$. Similarly, $x_n \rightarrow y$ means that there is $N_2 \in \mathbb{Z}_+$ such that $x_n \in B(y, \rho)$ for all $n \geq N_2$. Choose any $n \geq N_1, N_2$ (e.g. $n = \max\{N_1, N_2\}$). Then $x_n \in B(x, r) \cap B(y, \rho) = \emptyset$, impossible. \square

2.3.1 Methods for proving convergence and computing limits

Example 2.20. $\lim_{n \rightarrow \infty} \frac{1}{n} = 0$.

Proof. Choose any $\varepsilon \in \mathbb{Q}_{>0}$. By Archimedean property, there exists $N \in \mathbb{Z}_+$ such that $N\varepsilon > 1$, i.e. $1/N < \varepsilon$. Thus, for all $n \geq N$ we have $1/n < \varepsilon$. \square

Proposition 2.21. Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}\}$ and $(x_n), (y_n)$ be sequences in \mathbb{F} converging to $x, y \in \mathbb{R}$. If $x_n \leq y_n$ for all n , then $x \leq y$.

Proof. If $y < x$, let $\varepsilon = x - y$. Then all but finitely many members of (x_n) are in $(x - \varepsilon/2, x + \varepsilon/2)$, and all but finitely many members of (y_n) are in $(y - \varepsilon/2, y + \varepsilon/2)$. Since $y + \varepsilon/2 < x - \varepsilon/2$, there must exist n such that $y_n < x_n$. \square

Definition 2.22. If A and B are posets (or more generally, preordered sets, see Def. 5.1), we say a function $f : A \rightarrow B$ is **increasing** (resp. **strictly increasing**), if for each $x, y \in A$ we have

$$x \leq y \quad \implies \quad f(x) \leq f(y)$$

$$\begin{array}{ccc} & \text{resp.} & \\ x < y & \implies & f(x) < f(y) \end{array}$$

We leave the definitions of **decreasing** and **strictly decreasing** to the readers. We say that f is **monotonic** (resp. **strictly monotonic**), if f is either increasing or decreasing (resp. either strictly increasing or strictly decreasing).

Proposition 2.23. *Let $(x_n)_{n \in \mathbb{Z}}$ be a sequence in $[a, b] \subset \mathbb{R}$. If (x_n) is increasing (resp. decreasing), then $\lim_{n \rightarrow \infty} x_n$ equals $\sup\{x_n : n \in \mathbb{Z}_+\}$ (resp. $\inf\{x_n : n \in \mathbb{Z}_+\}$).*

Proof. Assume (x_n) increases. (The case of decreasing is similar and hence its proof is omitted.) Let $A = \sup\{x_n : n \in \mathbb{Z}_+\} < +\infty$. Then for each $\varepsilon > 0$ there is N such that $x_N > A - \varepsilon$ (since $A - \varepsilon$ is not an upper bound). Since (x_n) is increasing, for all $n \in \mathbb{N}$ we have $A - \varepsilon < x_n \leq A$ and so $|x_n - A| < \varepsilon$. \square

Example 2.24. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X , and let $x \in X$. It is easy to see that

$$\lim_{n \rightarrow \infty} x_n = x \iff \lim_{n \rightarrow \infty} d(x_n, x) = 0$$

Example 2.25. Suppose that (a_n) and (b_n) are sequences in $\mathbb{R}_{\geq 0}$, that $a_n \leq b_n$ for all n , and that $b_n \rightarrow 0$. Then $a_n \rightarrow 0$.

Proof. For each $\varepsilon > 0$, $[0, \varepsilon)$ contains all but finitely many b_n , and hence all but finitely many a_n . \square

More generally, we have:

Proposition 2.26 (Squeeze theorem). *Suppose that (x_n) is a sequence in a metric space X . Let $x \in X$. Suppose that there is a sequence (a_n) in $\mathbb{R}_{\geq 0}$ such that $\lim_{n \rightarrow \infty} a_n = 0$ and that $d(x_n, x) \leq a_n$ for all n . Then $\lim_{n \rightarrow \infty} x_n = x$.*

Proof. This follows immediately from Exp. 2.24 and 2.25. \square

The above proposition explains why many people say that “analysis is the art of inequalities”: It transforms the problem of convergence to the problem of finding a sequence $(a_n) \in \mathbb{R}_{\geq 0}$ converging to 0 such that the inequality $d(x_n, x) \leq a_n$ holds. And very often, a good (hard) analyst is one who knows how to find such good sequences!

Proposition 2.27. *Let $X = X_1 \times \cdots \times X_N$ be a product of metric spaces (X_i, d_i) . Let d be any of the three metrics of X in Exp. 2.10. Let $\mathbf{x}_n = (x_{1,n}, \dots, x_{N,n})$ be a sequence in X . Let $\mathbf{y} = (y_1, \dots, y_N)$. Then*

$$\lim_{n \rightarrow \infty} \mathbf{x}_n = \mathbf{y} \iff \lim_{n \rightarrow \infty} x_{i,n} = y_i \quad (\forall 1 \leq i \leq N)$$

Proof. We let d be the metric δ in Exp. 2.10, i.e. defined by $\max_j d_j(x_j, y_j)$. Now choose a sequence (x_n) and an element y in X . Then

$$x_n \rightarrow y \iff d_X(x_n, y) \rightarrow 0 \iff \max_{1 \leq j \leq N} d_j(x_{j,n}, y_j) \rightarrow 0 \quad (2.4)$$

Suppose that the RHS of (2.4) is true. Fix any $1 \leq i \leq N$. Then $d_i(x_{i,n}, y_i) \leq \max_j d_j(x_{j,n}, y_j)$. So $x_{i,n} \rightarrow y_i$ by Prop. 2.26.

Conversely, assume that for every i we have $x_{i,n} \rightarrow y_i$. Then for every $\varepsilon > 0$ there is $K_i \in \mathbb{Z}_+$ such that $d_i(x_{i,n}, y_i) < \varepsilon$ for every $n \geq K_i$. Let $K = \max\{K_1, \dots, K_N\}$. Then for all $n \geq K$ we have $\max_j d_j(x_{j,n}, y_j) < \varepsilon$. This proves the RHS of (2.4).

If d is one of the other two metrics in Exp. 2.10, one can either use a similar argument, or use the following important (but easy) fact. \square

Proposition 2.28. *Let d, δ be two equivalent metrics on a set X . Let $(x_n)_{n \in \mathbb{Z}_+}$ and x be in X . Then (x_n) converges to x under the metric d iff (x_n) converges to x under δ . Namely, $d(x_n, x) \rightarrow 0$ iff $\delta(x_n, x) \rightarrow 0$.*

Proof. Prove it yourself. (Or see Prop. 2.62.) \square

More useful formulas about limit will be given in Exp. 4.24.

2.3.2 Criteria for divergence

Definition 2.29. A subset E of a metric space (X, d) is called **bounded** if either $E = \emptyset$ or there exist $p \in X$ and $R \in \mathbb{R}_{>0}$ such that $E \subset B_X(p, R)$. If X is bounded, we also say that d is a **bounded metric**.

Remark 2.30. Note that if E is bounded, then for any $q \in X$ there exists $\tilde{R} \in \mathbb{R}_{>0}$ such that $E \subset B_X(q, \tilde{R})$. (Indeed, choose $\tilde{R} = R + d(p, q)$, then by triangle inequality, $B(p, R) \subset B(q, \tilde{R})$.)

Some easy examples are as follows.

Example 2.31. In a metric space X , if $x \in X$ and $0 < r < +\infty$, then $B(x, r)$ is bounded. Hence $\overline{B}(x, r)$ is bounded (since it is inside $B(x, 2r)$).

Also, it is easy to see:

Example 2.32. A finite union of bounded subsets is bounded.

Proposition 2.33. *Let $(x_n)_{n \in \mathbb{Z}_+}$ be a convergent sequence in a metric space X . Then $(x_n)_{n \in \mathbb{Z}_+}$ is bounded.*

By saying that a sequence $(x_n)_{n \in \mathbb{Z}_+}$ in X is **bounded**, we mean that its range in X (namely $\{x_n : n \in \mathbb{Z}_+\}$) is bounded.

Proof. Suppose that $x_n \rightarrow x$. Then for each $\varepsilon > 0$, say $\varepsilon = 1$, all but finitely many elements of x_n (say x_1, \dots, x_N) are in $B(x, 1)$. So this whole sequence is in $A = \{x_1\} \cup \dots \cup \{x_N\} \cup B(x, 1)$. Since each $\{x_i\}$ is bounded, and since $B(x, 1)$ is bounded, A is bounded by Exp. 2.32. \square

Remark 2.34. Prop. 2.33 gives our first criterion on divergence: If a sequence is unbounded (e.g. $x_n = n^2$), then it does not converge. But there are many bounded and divergent sequences. (See Exp. 2.37.) In this case, we need the second criterion: If a sequence has two subsequences converging to two different points, then this sequence diverge. (See Prop. 2.36)

Definition 2.35. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a set X . If $(n_k)_{k \in \mathbb{Z}_+}$ is a strictly increasing sequence in \mathbb{Z}_+ , we say that $(x_{n_k})_{k \in \mathbb{Z}_+}$ is a **subsequence** of $(x_n)_{n \in \mathbb{Z}_+}$.

Thus, a subsequence of $(x_n)_{n \in \mathbb{Z}_+}$ is equivalently the restriction of the function $x : \mathbb{Z}_+ \rightarrow X$ to an infinite subset of \mathbb{Z}_+ .

Proposition 2.36. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X converging to $x \in X$. Then every subsequence $(x_{n_k})_{k \in \mathbb{Z}_+}$ converges to x .

Proof. For every $\varepsilon > 0$, $B(x, \varepsilon)$ contains all but finitely many $\{x_n : n \in \mathbb{Z}_+\}$, and hence all but finitely many $\{x_{n_k} : k \in \mathbb{Z}_+\}$. \square

Example 2.37. The sequence $x_n = (-1)^n$ in \mathbb{R} is divergent, because the subsequence $(x_{2k})_{k \in \mathbb{Z}_+}$ converges to 1, whereas $(x_{2k-1})_{k \in \mathbb{Z}_+}$ converges to -1 .

One may wonder if the two criteria in Rem. 2.34 are complete in order to determine whether a sequence diverges. This is true for sequences in \mathbb{R}^n . We will discuss this topic later. (See Cor. 3.17.)

2.4 Continuous maps of metric spaces

Continuous maps are a powerful tool for showing that a sequence converges.

Definition 2.38. Let $f : X \rightarrow Y$ be a map of metric spaces. Let $x \in X$. We say that f is **continuous at x** if one of the following equivalent conditions hold:

(1) For every sequence $(x_n)_{n \in \mathbb{Z}_+}$ in X , we have

$$\lim_{n \rightarrow \infty} x_n = x \quad \implies \quad \lim_{n \rightarrow \infty} f(x_n) = f(x)$$

(2) For every $\varepsilon > 0$, there exists $\delta > 0$ such that for every $p \in X$ satisfying $d(p, x) < \delta$, we have $d(f(p), f(x)) < \varepsilon$.

(2') For every $\varepsilon > 0$, there exists $\delta > 0$ such that $B_X(x, \delta) \subset f^{-1}(B_Y(f(x), \varepsilon))$.

We say that f is a **continuous map/function**, if f is continuous at every point of X .

Proof of the equivalence. (2) \Leftrightarrow (2'): Obvious.

(2) \Rightarrow (1): Assume (2). Assume $x_n \rightarrow x$. For every $\varepsilon > 0$, let $\delta > 0$ be as in (2). Then since $x_n \rightarrow x$, there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $d(x_n, x) < \delta$. By (2), we have $d(f(x_n), f(x)) < \varepsilon$ for all $n \geq N$. This proves $f(x_n) \rightarrow f(x)$.

$\neg(2) \Rightarrow \neg(1)$: Assume that (2) is not true. Then there exists $\varepsilon > 0$ such that for every $\delta > 0$, there exists $p \in X$ such that $d(p, x) < \delta$ and $d(f(p), f(x)) \geq \varepsilon$. Thus, for every $n \in \mathbb{Z}_+$, by taking $\delta = 1/n$, we see that there exists $x_n \in X$ such that $d(x_n, x) < 1/n$ and $d(f(x_n), f(x)) \geq \varepsilon$. By Squeeze theorem (Prop. 2.26), $x_n \rightarrow x$. But $f(x_n) \not\rightarrow f(x)$ (i.e. $d(f(x_n), f(x)) \not\rightarrow 0$). So (1) is not true. \square

Remark 2.39. One can compare Def. 2.38-(1) to the definition of linear maps. A map is continuous iff it *preserves the convergence of sequences*, i.e., iff it maps convergent sequences to convergent ones. A map (between vector spaces) is linear iff it preserves the addition and the scalar multiplication of vectors. In general, a good map between two sets with “structures” is a map which preserves the structures. (Thus, linear combinations encode the linear structures of vector spaces. Similarly, the convergence of sequences remembers the “topological” structures of metric spaces.) As another example, we will define an isometry of metric spaces to be one that preserves the metrics (the structures of metric spaces), see Exe. 2.63.

Remark 2.40. In this section, we mainly use Def. 2.38-(1) to study continuity. But in later sections we will also use Def. 2.38-(2'). An advantage of (2') is that it is more geometric. Indeed, if X is a metric space and $E \subset X$, we say that $x \in E$ is an **interior point of E in X** if there exists $\delta > 0$ such that $B_X(x, \delta) \subset E$. For example, a point $z \in \mathbb{C}$ is an interior point of the closed unit disk $\overline{B}_{\mathbb{C}}(0, 1) = \{w \in \mathbb{C} : |w| \leq 1\}$ iff $|z| < 1$.

Thus, Def. 2.38-(2') says that for any map of metric spaces $f : X \rightarrow Y$ and $x \in X$, the following are equivalent:

- (a) f is continuous at x .
- (b) For each $\varepsilon > 0$, every $x \in X$ is an interior point of $f^{-1}(B_Y(f(x), \varepsilon))$.

We say that a subset $U \subset X$ is **open** if each point of U is an interior point. For example, by triangle inequality, every open ball in a metric space is an open set. Thus, we have:

- A map of metric spaces $f : X \rightarrow Y$ is continuous iff the preimage under f of every open ball of Y is an open subset of X .

In the study of point-set topology, we will see that many properties can be studied in two approaches: using sequences (or using nets, the natural generalizations of sequences) and their convergence, and using open sets. The first example

of such property is continuity, as we have seen in Def. 2.38. Another prominent example is sequential compactness vs. compactness. These two approaches represent two (very) different intuitions: one is dynamic, while the other is static and more geometric. (So it is surprising that these two very things are actually equivalent!) Sometimes both approaches work for a problem, but sometimes only one of them works, or one of them is much simpler. If you are a beginner in analysis and point-set topology, I suggest that whenever you see one approach applied to a problem, try to think about whether the other approach also works and which one is better. \square

2.4.1 Methods for proving continuity

Lemma 2.41. *Let $f : X \rightarrow Y$ be a map of metric spaces. Let $(B_i)_{i \in I}$ be a collection of open balls in X such that $X = \bigcup_{i \in I} B_i$. Suppose that for each i , the restriction $f|_{B_i} : B_i \rightarrow Y$ is continuous. Then f is continuous.*

This lemma shows that if we can prove that f is “locally” continuous, then f is globally continuous.

Proof. Choose (x_n) in X converging to $x \in X$. We shall show $f(x_n) \rightarrow f(x)$. Choose i such that $x \in B_i$. Then one can find $\delta > 0$ such that $B(x, \delta) \subset B_i$. (In the language of point-set topology: x is an interior point of B_i .) To see this, write $B_i = B(y, r)$. Since $x \in B(y, r)$, we have $r - d(x, y) > 0$. Choose $0 < \delta \leq r - d(x, y)$. Then triangle inequality implies $B(x, \delta) \subset B(y, r)$.

Since $x_n \rightarrow x$, there is $N \in \mathbb{Z}_+$ such that $x_n \in B(x, \delta)$ for all $n \geq N$. Thus, $(x_{k+N})_{k \in \mathbb{Z}_+}$ converges in B_i to x . Since $f|_{B_i}$ is continuous, $\lim_{k \rightarrow \infty} f(x_{k+N}) = f(x)$. So $f(x_n) \rightarrow f(x)$. \square

Definition 2.42. A map of metric spaces $f : X \rightarrow Y$ is called **Lipschitz continuous** if there exists $L \in \mathbb{R}_{>0}$ (called **Lipschitz constant**) such that for all $x_1, x_2 \in X$,

$$d_Y(f(x_1), f(x_2)) \leq L \cdot d_X(x_1, x_2) \quad (2.5)$$

Lemma 2.43. *Lipschitz continuous maps are continuous.*

Proof. Suppose that $f : X \rightarrow Y$ is Lipschitz continuous with Lipschitz constant L . Suppose $x_n \rightarrow x$ in X . Then $L \cdot d(x_n, x) \rightarrow 0$. By (2.5) and Squeeze theorem (Prop. 2.26), $f(x_n) \rightarrow f(x)$. (You can also use Def. 2.38-(2) to prove this lemma.) \square

Example 2.44. Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. The map $z \in \mathbb{F} \setminus \{0\} \mapsto z^{-1} \in \mathbb{F}$ is continuous.

Proof. Let this map be f . Since \mathbb{F} is covered by open balls $B(z, \delta)$ where $z \in \mathbb{F} \setminus \{0\}$ and $0 < \delta < |z|$, by Lem. 2.41, it suffices to prove that f is continuous when restricted to every such $B(z, \delta)$. Let $\varepsilon = |z| - \delta > 0$. Choose $x, y \in B(z, \delta)$. Then $|x| = |x - z + z| \geq |z| - |z - x| > \varepsilon$ by triangle inequality. Similarly, $|y| > \varepsilon$. So

$$|f(x) - f(y)| = |x^{-1} - y^{-1}| = |x - y|/|xy| \leq \varepsilon^{-2}|x - y|$$

So $f|_{B(z, \delta)}$ has Lipschitz constant ε^{-2} , and hence is continuous. \square

(Question: in the above proof, is the map $f : \mathbb{F} \setminus \{0\} \rightarrow \mathbb{F}$ Lipschitz continuous?)

We have given a fancy way of proving that if (z_n) is a sequence in $\mathbb{F} \setminus \{0\}$ converging to $z \in \mathbb{F} \setminus \{0\}$, then $z_n^{-1} \rightarrow z^{-1}$. You should think about how to prove this fact directly using $\varepsilon - N$ language, and compare your proof with the above proof to find the similarities!

Proposition 2.45. *Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. Then the following maps are continuous:*

$$\begin{aligned} + : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto x + y \\ - : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto x - y \\ \times : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto xy \\ \div : \mathbb{F} \times \mathbb{F}^\times &\rightarrow \mathbb{F} & (x, y) &\mapsto x/y \end{aligned}$$

Recall our Convention 2.13 on the metrics of finite product spaces.

Proof. We only prove that the last two are continuous: the first two can be treated in a similar (and easier) way.

Denote the multiplication map by μ . We choose the metric on \mathbb{F}^2 to be $d(\mathbf{x}, \mathbf{x}') = \max\{|x_1 - x'_1|, |x_2 - x'_2|\}$. Since $\mathbb{F} \times \mathbb{F}$ is covered by open balls of the form $B(0, r) = \{(x, y) \in \mathbb{F}^2 : |x| < r, |y| < r\}$ where $0 < r < +\infty$, by Lem. 2.41 and 2.43, it suffices to show that $\mu|_{B(0, r)}$ is Lipschitz continuous. This is true, since for each $(x, y), (x', y') \in B(0, r)$, we have

$$\begin{aligned} |\mu(x, y) - \mu(x', y')| &= |xy - x'y'| \leq |(x - x')y| + |x'(y - y')| \\ &< 2r \cdot \max\{|x - x'|, |y - y'|\} = 2r \cdot d((x, y), (x', y')) \end{aligned} \quad (2.6)$$

By Exp. 2.44 and Prop. 2.47, the map $(x, y) \in \mathbb{F} \times \mathbb{F}^\times \mapsto (x, y^{-1}) \in \mathbb{F} \times \mathbb{F}$ is continuous. So its composition with the continuous map μ is continuous, thanks to Prop. 2.46. So \div is continuous. \square

Proposition 2.46. *Suppose that $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ are continuous maps of metric spaces. Then $g \circ f : X \rightarrow Z$ is continuous.*

Proposition 2.47. *Suppose that $f_i : X_i \rightarrow Y_i$ is a map of metric spaces, where $1 \leq i \leq N$. Then the product map*

$$\begin{aligned} f_1 \times \cdots \times f_N : X_1 \times \cdots \times X_N &\rightarrow Y_1 \times \cdots \times Y_N \\ (x_1, \dots, x_N) &\mapsto (f_1(x_1), \dots, f_N(x_N)) \end{aligned}$$

is continuous if and only if f_1, \dots, f_N are continuous.

Proof of Prop. 2.46 and 2.47. Immediate from Def. 2.38-(1) and Prop. 2.27. \square

Corollary 2.48 (Squeeze theorem). *Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}\}$ and $(x_n), (y_n), (z_n)$ be sequences in \mathbb{R} . Assume that $x_n \leq y_n \leq z_n$ for all n . Assume that x_n and z_n both converge to $A \in \mathbb{R}$. Then $\lim_{n \rightarrow \infty} y_n = A$.*

Proof. Let $a_n = y_n - x_n$ and $b_n = z_n - x_n$. Then $0 \leq a_n \leq b_n$, and $\lim_n b_n = \lim_n z_n - \lim_n x_n = 0$ because the subtraction map is continuous (Prop. 2.45). By Exp. 2.25, $a_n \rightarrow 0$. Since $x_n \rightarrow A$, $y_n = x_n + a_n$ converges to A , since the addition map is continuous by Prop. 2.45. \square

Again, this is a fancy way of proving Squeeze theorem. The readers should know how to prove it directly from the definition of limits of sequences.

We give some more examples of continuous maps.

Example 2.49. By Prop. 2.45, $f(x, y, z) = x^2y + 5y^4z^7 - 3xyz^2$ is a continuous function on \mathbb{C}^3 . Clearly $z \in \mathbb{C} \mapsto \bar{z} \in \mathbb{C}$ is continuous. So $g(x, y, z) = f(\bar{x}, \bar{y}, z) + 2f(z, x^2, xy^{-9}) - 5xy^{-2}z^{-3}$ is a continuous function on $\mathbb{C} \times \mathbb{C}^\times \times \mathbb{C}^\times$.

Example 2.50. Let $f, g : X \rightarrow \mathbb{F}$ be continuous functions where $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. Then by Prop. 2.45 and 2.46, $f \pm g$ and fg are continuous, and f/g is continuous when $0 \notin g(X)$. Here

$$(f \pm g)(x) = f(x) \pm g(x) \quad (fg)(x) = f(x)g(x) \quad (f/g)(x) = f(x)/g(x) \quad (2.7)$$

Example 2.51. Let $f : X \rightarrow Y$ be a map of metric spaces. Let E, F be subsets of X, Y respectively. (Recall that the metrics of subsets are chosen as in Def. 2.14.)

- The inclusion map $\iota_E : E \rightarrow X, x \mapsto x$ is clearly continuous. Thus, if f is continuous, then $f|_E : E \rightarrow Y$ is continuous, since $f|_E = f \circ \iota_E$.
- If $f(X) \subset F$, then we can restrict the codomain of f from Y to F : let $\tilde{f} : X \rightarrow F$ be $\tilde{f}(x) = f(x)$. Then it is clear that f is continuous iff \tilde{f} is continuous.

Proposition 2.52. Let X_1, \dots, X_N be metric spaces. The following projection is clearly continuous:

$$\pi_{X_i} : X_1 \times \dots \times X_N \rightarrow X_i \quad (x_1, \dots, x_N) \mapsto x_i$$

Proposition 2.53. Let $f_i : X \rightarrow Y_i$ be maps where X, Y_1, \dots, Y_N are continuous. Then

$$f_1 \vee \dots \vee f_N : X \rightarrow Y_1 \times \dots \times Y_N \quad x \mapsto (f_1(x), \dots, f_N(x))$$

is continuous iff f_1, \dots, f_N are continuous.

Example 2.54. Let X be a metric space. Then $d : X \times X \rightarrow \mathbb{R}, (x, y) \mapsto d(x, y)$ is Lipschitz continuous with Lipschitz constant 1 (by triangle inequality). So d is continuous.

Proposition 2.55. Let X be a metric space and $E \subset X$ is nonempty. Define **distance function**

$$d(\cdot, E) : X \rightarrow \mathbb{R}_{\geq 0} \quad d(x, E) = \inf_{e \in E} d(x, e)$$

Then $d(\cdot, E)$ has Lipschitz constant 1. So $d(\cdot, E)$ is continuous.

Proof. Choose any $x, y \in X$. By triangle inequality, for each $e \in E$ we have $d(x, e) \leq d(x, y) + d(y, e)$. Since $d(x, E) \leq d(x, e)$, we get $d(x, E) \leq d(x, y) + d(y, e)$. Applying $\inf_{e \in E}$ to the RHS gives $d(x, E) \leq d(x, y) + d(y, E)$. Hence $d(x, E) - d(y, E) \leq d(x, y)$. Exchanging x and y gives

$$|d(x, E) - d(y, E)| \leq d(x, y) \quad (2.8)$$

This proves that $d(\cdot, E)$ has Lipschitz constant 1. \square

Definition 2.56. More generally, if E, F are subsets of a metric space E , we can define

$$d(E, F) = \inf_{e \in E, f \in F} d(e, f) \quad (2.9)$$

to be the **distance between E and F** .

Exercise 2.57. Let $E, F \subset X$. Prove that

$$d(E, F) = \inf_{f \in F} d(E, f) \quad (2.10)$$

Example 2.58. If X is a metric space and $p \in X$, then by Prop. 2.55 (or simply by triangle inequality), the function $d_p : x \in X \mapsto d(x, p) \in \mathbb{R}$ has Lipschitz constant 1 and hence is continuous. In particular, if $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, the function $z \in \mathbb{F} \mapsto |z|$ is continuous (since $|z| = d_{\mathbb{F}}(z, 0)$). Thus, if $f : X \rightarrow \mathbb{F}$ is continuous, then $|f| : X \rightarrow \mathbb{R}_{\geq 0}$ is continuous where

$$|f|(x) = |f(x)| \quad (2.11)$$

Example 2.59. Let $N \in \mathbb{Z}_+$. Then the following function is continuous:

$$\max : \mathbb{R}^N \rightarrow \mathbb{R} \quad (x_1, \dots, x_N) \mapsto \max\{x_1, \dots, x_N\} \in \mathbb{R}$$

Similarly, the minimum function is continuous.

Proof. To avoid confusion, we write \max as \max_N . The case $N = 1$ is obvious. When $N = 2$, we have

$$\max(x_1, x_2) = \frac{x_1 + x_2 + |x_1 - x_2|}{2} \quad (2.12)$$

So \max_2 is continuous by Exp. 2.50 and 2.58.

We use induction. Suppose we have proved that \max_N is continuous. Then $\max_N \times \text{id}_{\mathbb{R}} : \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{R} \times \mathbb{R}$ is continuous. So $\max_{N+1} = \max_2 \circ (\max_N \times \text{id}_{\mathbb{R}})$ is continuous. \square

2.5 Homeomorphisms and isometric isomorphisms; convergence in $\overline{\mathbb{R}}$

2.5.1 General theory

Definition 2.60. A bijection of metric spaces $f : X \rightarrow Y$ is called a **homeomorphism** if one of the following equivalent (cf. Def. 2.38) statements holds:

- (1) $f : X \rightarrow Y$ and its inverse map $f^{-1} : Y \rightarrow X$ are continuous.
- (2) For each sequence (x_n) in X and each $x \in X$, we have $\lim_{n \rightarrow \infty} x_n = x$ iff $\lim_{n \rightarrow \infty} f(x_n) = f(x)$.

If such f exists, we say that X, Y are **homeomorphic**.

A special case of the above definition is:

Definition 2.61. Let X be a set with metrics d, δ . We say that d and δ induce the **same topology** on X (or that d, δ are **topologically equivalent**) if one of the following clearly equivalent statements holds:

- (1) The map $(X, d) \rightarrow (X, \delta), x \mapsto x$ is a homeomorphism.⁵
- (2) For each sequence (x_n) in X and each $x \in X$, (x_n) converges to x under the metric d iff (x_n) converges to x under δ .

Proposition 2.62. Suppose that d, δ are equivalent metrics on a set X . Then d, δ are topologically equivalent.

Proof. Suppose $\delta \leq \alpha d$ and $d \leq \beta \delta$ for some $\alpha, \beta > 0$. Then the map $f : (X, d) \rightarrow (X, \delta), x \mapsto x$ and its inverse f^{-1} have Lipschitz constants α and β respectively. So f, f^{-1} are continuous. \square

Exercise 2.63. Let $f : X \rightarrow Y$ be a map of metric spaces. We say that $f : X \rightarrow Y$ is an **isometry** (or is **isometric**) if for all $x_1, x_2 \in X$ we have

$$d_Y(f(x_1), f(x_2)) = d_X(x_1, x_2) \quad (2.13)$$

Show that an isometry is injective and continuous.

We say that f is an **isometric isomorphism** if f is a surjective isometry. If an isometric isomorphism between two metric spaces X, Y exists, we say that X and Y are **isometric metric spaces**. Show that an isometric isomorphism is a homeomorphism. \square

⁵We prefer not to call this map the identity map, because the metrics on the source and on the target are different.

Remark 2.64. Isometric isomorphisms are important examples of homeomorphisms. That $f : X \rightarrow Y$ is an isometric isomorphism means that X and Y are equivalent as metric spaces, and that this equivalence can be implemented by the bijection f .

We now look at isometric isomorphisms in a different direction. Suppose that $f : X \rightarrow Y$ is a bijection of sets. Suppose that Y is a metric space. Then there is unique metric d_X on X such that f is an isometric isomorphism: one defines d_X using (2.13). We write such d_X as f^*d_Y , i.e.,

$$f^*d_Y(x_1, x_2) = d_Y(f(x_1), f(x_2))$$

and call f^*d_Y the **pullback metric** of d_Y by f . □

Pullback metrics are a very useful way of constructing metrics on a set. We consider some examples below.

Exercise 2.65. Two metrics inducing the same topology are not necessarily equivalent metrics. For example, let $f : [0, 1] \rightarrow [0, 1]$ be $f(x) = x^2$. Let $X = [0, 1]$, and let d_X be the Euclidean metric: $d_X(x, y) = |x - y|$. So

$$f^*d_X(x, y) = |x^2 - y^2|$$

is a metric on X . It is not hard to check that $f : (X, d_X) \rightarrow (X, d_X)$ is a homeomorphism. So d_X and f^*d_X give the same topology on $[0, 1]$ (cf. Exe. 2.66). Show that f^*d_X and d_X are not equivalent metrics.

Exercise 2.66. Let $f : X \rightarrow Y$ be a bijection of sets with metrics d_X, d_Y . Show that d_X and f^*d_Y give the same topology on X iff $f : (X, d_X) \rightarrow (Y, d_Y)$ is a homeomorphism.

In particular, if $f : X \rightarrow X$ is a bijection, and d_X is a metric on X . Then d_X and f^*d_X give the same topology on X iff $f : (X, d_X) \rightarrow (X, d_X)$ is a homeomorphism.

2.5.2 Convergence in $\overline{\mathbb{R}}$

Our second application of pullback metrics is the convergence in $\overline{\mathbb{R}}$.

Definition 2.67. We say that a sequence (x_n) in $\overline{\mathbb{R}}$ **converges to** $+\infty$ (resp. $-\infty$), if for every $A \in \mathbb{R}$ there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $x_n > A$ (resp. $x_n < A$).

Suppose $x \in \mathbb{R}$. We say that a sequence (x_n) in $\overline{\mathbb{R}}$ **converges to** x , if there is $N \in \mathbb{Z}_+$ such that $x_n \in \mathbb{R}$ for all $n \geq N$, and that the subsequence $(x_{k+N})_{k \in \mathbb{Z}_+}$ converges in \mathbb{R} to x . □

This notion of convergence is weird: it is not defined by a metric. So one wonders if there is a metric d on $\overline{\mathbb{R}}$ such that convergence of sequences under d agrees with that in Def. 2.67. We shall now find such a metric.

Lemma 2.68. Let $-\infty \leq a < b \leq +\infty$ and $-\infty \leq c < d \leq +\infty$. Then there is a strictly increasing bijective map $[a, b] \rightarrow [c, d]$.

Note that this map clearly sends a to c and b to d . So it restricts to strictly increasing bijections $(a, b) \rightarrow (c, d)$, $(a, b] \rightarrow (c, d]$, $[a, b) \rightarrow [c, d)$.

Proof. We have a strictly increasing bijection $f : \mathbb{R} \rightarrow (-1, 1)$ defined by (1.9). f can be extended to a strictly increasing bijective map $\overline{\mathbb{R}} \rightarrow [-1, 1]$ if we set $f(\pm\infty) = \pm 1$. Thus, f restricts to a strictly increasing bijection $[a, b] \rightarrow [f(a), f(b)]$. Choose a linear function $g(x) = \alpha x + \beta$ (where $\alpha > 0$) giving an increasing bijection $[f(a), f(b)] \rightarrow [0, 1]$. Then $h = g \circ f : [a, b] \rightarrow [0, 1]$ is a strictly increasing bijection. Similarly, we have a strictly increasing bijection $k : [c, d] \rightarrow [0, 1]$. Then $k^{-1} \circ h : [a, b] \rightarrow [c, d]$ is a strictly increasing bijection. \square

Theorem 2.69. Let $\varphi : \overline{\mathbb{R}} \rightarrow [a, b]$ be a strictly increasing bijective map where $[a, b] \subset \mathbb{R}$ is equipped with the Euclidean metric $d_{[a,b]}$. Then a sequence (x_n) in $\overline{\mathbb{R}}$ converges to $x \in \overline{\mathbb{R}}$ in the sense of Def. 2.67 iff $\varphi(x_n)$ converges to $\varphi(x)$ under the metric $d_{[a,b]}$. In other words, the convergence in $\overline{\mathbb{R}}$ is given by the metric $\varphi^* d_{[a,b]}$.

Proof. Let $y = \varphi(x)$ and $y_n = \varphi(x_n)$. We need to prove that $x_n \rightarrow x$ (in the sense of Def. 2.67) iff $y_n \rightarrow y$ (under the Euclidean metric). Write $\psi = \varphi^{-1}$, which is a strictly increasing map $[a, b] \rightarrow \overline{\mathbb{R}}$. Note that $\varphi(+\infty) = b$ and $\varphi(-\infty) = a$.

Case 1: $x \in \mathbb{R}$. By discarding the first several terms, we may assume that (x_n) is always in \mathbb{R} . If $x_n \rightarrow x$, then for every $\varepsilon > 0$, all but finitely many x_n are inside the open interval $(\psi(y - \varepsilon), \psi(y + \varepsilon))$. So all but finitely many y_n are inside $(y - \varepsilon, y + \varepsilon)$. So $y_n \rightarrow y$. That $y_n \rightarrow y$ implies $x_n \rightarrow x$ is proved in a similar way.

Case 2: $x = \pm\infty$. We consider $x = +\infty$ only; the other case is similar. Note that if $0 < \varepsilon < b - a$, then $B_{[a,b]}(b, \varepsilon) = (b - \varepsilon, b]$. If $x_n \rightarrow +\infty$, then for each $0 < \varepsilon < b - a$, all but finitely many x_n are $> \psi(b - \varepsilon)$. So all but finitely many y_n are inside $(b - \varepsilon, b]$. This proves $y_n \rightarrow b$. Conversely, if $y_n \rightarrow b$, then for each $A \in \mathbb{R}$, all but finitely many y_n are inside $(\varphi(A), b]$ and hence $> \varphi(A)$. So all but finitely many x_n are $> A$. \square

Convention 2.70. Unless otherwise stated, a metric on $\overline{\mathbb{R}}$ is one that makes Def. 2.67 true, for instance $\varphi^* d_{[a,b]}$ in Thm. 2.69. Unless otherwise stated, we do NOT view \mathbb{R} (or any subset of \mathbb{R}) as a metric subspace of $\overline{\mathbb{R}}$. Namely, we do not follow Convention 2.15 for $\mathbb{R} \subset \overline{\mathbb{R}}$, or more generally for $\mathbb{R}^N \subset \overline{\mathbb{R}}^N$. Instead, we choose Euclidean metrics on \mathbb{R}^N , following Convention 2.8.

The main reason for not following Convention 2.15 here is that metrics on $\overline{\mathbb{R}}$ are all bounded (by Prop. 3.7). Thus, every subset of \mathbb{R} is bounded if we view \mathbb{R} as a metric subspace of $\overline{\mathbb{R}}$. However, we want a subset of \mathbb{R} to be bounded precisely when it is contained in $[a, b]$ for some $-\infty < a < b < +\infty$. (Recall also Def. 1.36.)

After learning topological spaces, we shall forget about the metrics on $\overline{\mathbb{R}}$ and only care about its topology. (See Conv. 7.18.)

Remark 2.71. By Thm. 2.69, the properties of $[a, b]$ about convergence of sequences and inequalities can be transported to $\overline{\mathbb{R}}$, for example:

1. If $(x_n), (y_n)$ are sequences in $\overline{\mathbb{R}}$ converging to $A, B \in \overline{\mathbb{R}}$, and if $x_n \leq y_n$ for all n , then $A \leq B$.
2. **Squeeze theorem:** Suppose that $(x_n), (y_n), (z_n)$ are sequences in $\overline{\mathbb{R}}$, $x_n \leq y_n \leq z_n$ for all n , and x_n and z_n both converge to $A \in \overline{\mathbb{R}}$. Then $y_n \rightarrow A$.
3. Prop. 2.23 also holds for $[-\infty, +\infty] = \overline{\mathbb{R}}$: if (x_n) is an increasing resp. decreasing sequence in $\overline{\mathbb{R}}$, then $\lim_n x_n$ exists in $\overline{\mathbb{R}}$ and equals $\sup_n x_n$ resp. $\inf_n x_n$.

We will see more examples when studying \limsup and \liminf in the future.

We have shown that there is a metric on $\overline{\mathbb{R}}$ which defines the convergence in Def. 2.67. However, there is no standard choice of such a metric on $\overline{\mathbb{R}}$. Even worse, two possible choices of metrics might not be equivalent: Let $\varphi, \psi : \overline{\mathbb{R}} \rightarrow [0, 1]$ be a strictly increasing bijections where $\psi \circ \varphi^{-1} : [0, 1] \rightarrow [0, 1]$ is $x \mapsto x^2$. Then by Exe. 2.65, $\varphi^*d_{[0,1]}$ and $\psi^*d_{[0,1]}$ are non-equivalent but topologically equivalent metrics on $\overline{\mathbb{R}}$. This is the first example that metrics are not convenient for the description of convergence. When studying the convergence in $\overline{\mathbb{R}}$, thinking about metrics is distracting. In the future, we will see a better notion for the study of convergence: the notion of topological spaces.

We end this section with a generalization of Thm. 2.69.

Theorem 2.72. Let φ be a strictly increasing bijection in one of the following forms

$$\begin{array}{ll} [a, b] \rightarrow [c, d] & (a, b) \rightarrow (c, d) \\ (a, b] \rightarrow (c, d] & [a, b) \rightarrow [c, d) \end{array}$$

where $-\infty \leq a \leq b \leq +\infty$ and $-\infty \leq c \leq d \leq +\infty$. Then φ is a homeomorphism, i.e., if (x_n) and x are in the domain, then $x_n \rightarrow x$ iff $\varphi(x_n) \rightarrow \varphi(x)$ (in the sense of Def. 2.67).

Proof. The case $a = b$ is obvious. So we consider $a < b$, and hence $c < d$. We consider the left-open-right-closed case for example. The other cases are treated in a similar way. If the theorem can be proved for $(-\infty, +\infty] \rightarrow (c, d]$, then it can also be proved $(-\infty, +\infty] \rightarrow (a, b]$. By composing the inverse of the second map with the first map, we see that the theorem holds for $(a, b] \rightarrow (c, d]$.

Let us consider $\varphi : (-\infty, +\infty] \rightarrow (c, d]$. φ can be extended to a strictly increasing bijection $\varphi : \overline{\mathbb{R}} \rightarrow [c, d]$ by letting $\varphi(-\infty) = c$. It suffices to prove that this φ is a homeomorphism. When $-\infty < c < d < +\infty$, then the theorem holds by Thm. 2.69. If one of c, d is $\pm\infty$, the same argument as in the proof of Thm. 2.69 proves that φ is a homeomorphism. We leave it to the readers to fill in the details. \square

2.6 Problems and supplementary material

Definition 2.73. Let A be a subset of \mathbb{R} satisfying $x + y \in A$ for all $x, y \in A$. (Or more generally, let A be an abelian semigroup.) We say that a function $f : A \rightarrow \mathbb{R}$ is **subadditive** if for every $x, y \in A$ we have $f(x + y) \leq f(x) + f(y)$.

Problem 2.1. Consider the following increasing functions:

$$\begin{aligned} f_1 : \mathbb{R}_{\geq 0} &\rightarrow [0, 1) & f_1(x) &= \frac{x}{1+x} \\ f_2 : \mathbb{R}_{\geq 0} &\rightarrow [0, 1] & f_2(x) &= \min\{x, 1\} \end{aligned}$$

Prove that they are subadditive functions.

Problem 2.2. Let $f : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ be an increasing subadditive function satisfying the following conditions:

- (1) $f^{-1}(0) = \{0\}$.
- (2) For any $(x_n)_{n \in \mathbb{Z}_+}$ in $\mathbb{R}_{\geq 0}$ we have $x_n \rightarrow 0$ iff $f(x_n) \rightarrow 0$.

Let (X, d) be a metric space. Define

$$\delta : X \times X \rightarrow [0, A) \quad \delta(x, y) = f \circ d(x, y)$$

Prove that δ is a metric, and that δ and d are topologically equivalent.

Proposition 2.74. Let (X, d) be a metric space. Then there is a bounded metric δ on X such that d and δ are topologically equivalent.

Proof. Let f be either f_1 or f_2 defined in Pb. 2.1. Then f satisfies the assumptions in Pb. 2.2. So $\delta = f \circ d$ is a desired metric due to Pb. 2.2. We write down the formulas explicitly:

$$\delta_1(x, y) = \frac{d(x, y)}{1 + d(x, y)} \quad \delta_2(x, y) = \min\{d(x, y), 1\}$$

□

Problem 2.3. Let $(X_i, d_i)_{i \in \mathbb{Z}_+}$ be a sequence of metric spaces. Assume that $d_i \leq 1$ for each i . Let $S = \prod_{i \in \mathbb{Z}_+} X_i$. For each elements $f = (f(i))_{i \in \mathbb{Z}_+}$ and $g = (g(i))_{i \in \mathbb{Z}_+}$ of S , define

$$d(f, g) = \sup_{i \in \mathbb{Z}_+} \frac{d_i(f(i), g(i))}{i} \tag{2.14}$$

Prove that d is a metric on S . Let $f_n = (f_n(i))_{i \in \mathbb{Z}_+}$ be a sequence in S . Let $g \in S$. Prove that the following are equivalent:

(a) $\lim_{n \rightarrow \infty} f_n = g$ under the metric d .

(b) f_n **converges pointwise** to g , namely, $\lim_{n \rightarrow \infty} f_n(i) = g(i)$ for every $i \in \mathbb{Z}_+$.

Remark 2.75. The above problem gives our first non-trivial example of function spaces as metric spaces, where the domain of functions is a countable set. After learning series, the readers can check that

$$\delta(f, g) = \sum_{i \in \mathbb{Z}_+} 2^{-i} d_i(f(i), g(i)) \quad (2.15)$$

also defines a metric, and that (a) (with d replaced by δ) and (b) are equivalent. So δ and d (defined by (2.14)) induce the same topology on X , called the **pointwise convergence topology** or simply **product topology**. Unfortunately, if the index set \mathbb{Z}_+ is replaced by an uncountable set, there is in general no metric inducing the product topology. We will prove this in Pb. 7.9.

★ **Problem 2.4.** Let $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ be a disjoint union of metric spaces (X_α, d_α) . Assume that $d_\alpha \leq 1$ for all i . For each $x, y \in X$, define

$$d(x, y) = \begin{cases} d_\alpha(x, y) & \text{if } x, y \in X_\alpha \text{ for some } \alpha \in \mathcal{A} \\ \frac{1}{2} & \text{otherwise} \end{cases}$$

1. Prove that d defines a metric on X .
2. Choose $(x_n)_{n \in \mathbb{Z}_+}$ in X and $x \in X$. What does $\lim_{n \rightarrow \infty} x_n = x$ mean in terms of the convergence in each X_α ?

Think about the question: Let X be a set. For each $x, y \in X$ define $d(x, y) = 0$ if $x = y$, and $d(x, y) = 1$ if $x \neq y$. What does convergence in (X, d) mean?

3 Sequential compactness and completeness

3.1 Sequential compactness

3.1.1 Basic properties of sequentially compact spaces

Definition 3.1. Let X be a metric space. We say that X is **sequentially compact** if every sequence in X has a subsequence converging to some point of X .

The notion of sequential compactness is extremely useful for finding solutions in an analysis problem. In general, suppose we want to find a point $x \in X$ which makes a property $P(x)$ to be true. Suppose that we can find an “approximate solution”, i.e. an $y \in X$ such that $P(y)$ is close to being true. Thus, we can find a sequence (x_n) in X such that $P(x_n)$ is closer and closer to being true when $n \rightarrow \infty$. Now, if X is sequentially compact, then (x_n) has a subsequence (x_{n_k}) converging to $x \in X$. Then $P(x)$ is true, and hence x is a solution for the problem. (See also Sec. 2.1.) Let us see an explicit example:

Lemma 3.2 (Extreme value theorem). *Let X be a sequentially compact metric space. Let $f : X \rightarrow \mathbb{R}$ be a continuous function. Then f attains its maximum and minimum at points of X . In particular, $f(X)$ is a bounded subset of \mathbb{R} .*

This extremely important result is the main reason for introducing sequentially compact spaces. We call this a lemma, since we will substantially generalize this result later. (See Exe. 3.6.)

Note that the **boundedness** of subsets of \mathbb{R} (or more generally, of \mathbb{R}^N) is always understood under the Euclidean metric of \mathbb{R} , not under any metric of $\overline{\mathbb{R}}$ or $\overline{\mathbb{R}}^N$. (Recall Convention 2.70.)

Proof. We show that f attains its maximum on X . The proof for minimum is similar. Let $A = \sup f(X)$. Then $A \in (-\infty, +\infty]$. If $A < +\infty$, then for each $n \in \mathbb{Z}_+$ there is $x_n \in X$ such that $A - 1/n < f(x_n) \leq A$ (since $A - 1/n$ is not an upper bound of $f(X)$). If $A = +\infty$, then for each n there is $x_n \in X$ such that $f(x_n) > n$. In either case, we have a sequence (x_n) in X such that $f(x_n) \rightarrow A$ in $\overline{\mathbb{R}}$.

Since X is sequentially compact, (x_n) has a subsequence $(x_{n_k})_{k \in \mathbb{Z}_+}$ converging to some $x \in X$. Now, consider f as a map $f : X \rightarrow \overline{\mathbb{R}}$, which is continuous (cf. Exp. 2.51). Since $f(x_n) \rightarrow A$, its subsequence $f(x_{n_k})$ also converges to A . But since $x_{n_k} \rightarrow x$ and f is continuous at x , we have $A = f(x)$. So f attains its maximum at x . Since $f(X) \subset \mathbb{R}$, we have $A \in \mathbb{R}$. \square

The following are some elementary examples of sequential compactness:

Exercise 3.3. Show that finite unions of sequentially compact spaces is sequentially compact. (In particular, a finite set is sequentially compact.)

More precisely, let X be a metric space. Assume $X = A_1 \cup \cdots \cup A_N$ where each metric subspace A_i is sequentially compact. Show that X is sequentially compact.

Proposition 3.4. Let X_1, \dots, X_N be sequentially compact metric spaces. Then $X = X_1 \times \dots \times X_N$ is sequentially compact.

Proof. Since $X = (X_1 \times \dots \times X_{N-1}) \times X_N$, by induction, it suffices to assume $N = 2$. So we write $X = A \times B$ where A, B are sequentially compact. Let (a_n, b_n) be a sequence in X . Since A is sequentially compact, (a_n) has a convergent subsequence (a_{n_k}) . Since B is sequentially compact, (b_{n_k}) has a convergent subsequence $(b_{n_{k_l}})$. So $(a_{n_{k_l}}, b_{n_{k_l}})$ is a convergent subsequence of (a_n, b_n) . \square

Proposition 3.5. Let $f : X \rightarrow Y$ be a continuous map of metric spaces. Assume that X is sequentially compact. Then $f(X)$, as a metric subspace of Y , is sequentially compact.

Proof. Choose any sequence (y_n) in $f(X)$. We can write $y_n = f(x_n)$ where $x_n \in X$. Since X is sequentially compact, (x_n) has a subsequence (x_{n_k}) converging to some $x \in X$. Since f is continuous, $y_{n_k} = f(x_{n_k})$ converges to $f(x)$. \square

Exercise 3.6. Prove that if Y is a sequentially compact subset of \mathbb{R} , then $\sup Y \in Y$ and $\inf Y \in Y$. Therefore, Prop. 3.5 generalizes Lem. 3.2.

Proposition 3.7. Let X be a sequentially compact metric space. Then X is bounded under its metric d .

Proof. Choose any $p \in X$. The function $d_p : x \in X \mapsto d(x, p) \in \mathbb{R}_{\geq 0}$ is continuous by Exp. 2.58. So, by Lem. 3.2, d_p is bounded by some $0 < R < +\infty$. So $X = \overline{B_X(p, R)} \subset B_X(p, 2R)$. \square

3.1.2 Limits inferior and superior, and Bolzano-Weierstrass

The goal of this subsection is to prove that closed intervals are sequentially compact.

Definition 3.8. Let (x_n) be a sequence in a metric space X . We say that $x \in X$ is a **cluster point** of (x_n) , if (x_n) has a subsequence (x_{n_k}) converging to x .

Warning: In a general topological space, the cluster points of a sequence will be defined in a different way. (See Pb. 7.2 and Rem. 7.117.)

Definition 3.9. Let (x_n) be a sequence in $\overline{\mathbb{R}}$. Define

$$\alpha_n = \inf\{x_k : k \geq n\} \quad \beta_n = \sup\{x_k : k \geq n\} \quad (3.1)$$

It is clear that $\alpha_n \leq x_n \leq \beta_n$, that (α_n) is increasing and (β_n) is decreasing. Define

$$\liminf_{n \rightarrow \infty} x_n = \sup\{\alpha_n : n \in \mathbb{Z}_+\} = \lim_{n \rightarrow \infty} \alpha_n \quad (3.2a)$$

$$\limsup_{n \rightarrow \infty} x_n = \inf\{\beta_n : n \in \mathbb{Z}_+\} = \lim_{n \rightarrow \infty} \beta_n \quad (3.2b)$$

(cf. Rem. 2.71), called respectively the **limit inferior** and the **limit superior** of (x_n) .

Remark 3.10. Let $(x_n), (y_n)$ be sequences in $\overline{\mathbb{R}}$. Suppose that $x_n \leq y_n$ for every n . It is clear that

$$\liminf_{n \rightarrow \infty} x_n \leq \limsup_{n \rightarrow \infty} x_n \quad \liminf_{n \rightarrow \infty} x_n \leq \liminf_{n \rightarrow \infty} y_n \quad \limsup_{n \rightarrow \infty} x_n \leq \limsup_{n \rightarrow \infty} y_n$$

Theorem 3.11. Let (x_n) be a sequence in $\overline{\mathbb{R}}$, and let S be the set of cluster points of (x_n) . Then $\liminf_{n \rightarrow \infty} x_n$ and $\limsup_{n \rightarrow \infty} x_n$ belong to S . They are respectively the minimum and the maximum of S .

In particular, every sequence in $\overline{\mathbb{R}}$ has at least one cluster point.

Proof. We use the notations in Def. 3.9. Let $A = (3.2a)$ and $B = (3.2b)$. If $x \in S$, pick a subsequence (x_{n_k}) converging to x . Since $\alpha_{n_k} \leq x_{n_k} \leq \beta_{n_k}$, we have $A \leq x \leq B$ by Rem. 2.71. It remains to show that $A, B \in S$. We prove $B \in S$ by constructing a subsequence (x_{n_k}) converging to B ; the proof of $A \in S$ is similar.

Consider first of all the special case that (x_n) is bounded, i.e., is inside $[a, b] \subset \mathbb{R}$. Choose an arbitrary $n_1 \in \mathbb{Z}_+$. Suppose $n_1 < \dots < n_k$ have been constructed. By the definition of β_{1+n_k} , there is $n_{k+1} \geq 1 + n_k$ such that $x_{n_{k+1}}$ is close to β_{1+n_k} , say

$$\beta_{1+n_k} - \frac{1}{k} < x_{n_{k+1}} \leq \beta_{1+n_k} \quad (3.3)$$

Since the left most and the right most of (3.3) both converge to B as $k \rightarrow \infty$, by Squeeze theorem (Cor. 2.48) we conclude $\lim_k x_{n_k} = B$.

In general, by Lem. 2.68 and Thm. 2.72, there is an increasing (i.e. order-preserving) homeomorphism (i.e. topopogy-preserving map) $\varphi : \overline{\mathbb{R}} \rightarrow [0, 1]$. Then $\varphi(\beta_n) = \sup\{\varphi(x_k) : k \geq n\}$ (cf. Exe. 3.13) and $\varphi(B) = \lim_n \varphi(\beta_n)$. So $\varphi(B) = \limsup_n \varphi(x_n)$. By the above special case, $(\varphi(x_n))$ has a subsequence $(\varphi(x_{n_k}))$ converging to $\varphi(B)$. So (x_{n_k}) converges to B . \square

Remark 3.12. One can also prove the above general case directly using a similar idea as in the special case. And you are encouraged to do so! (Pay attention to the case $B = \pm\infty$.)

The proof given above belongs to a classical proof pattern: To prove that a space X satisfies some property, one first prove it in a convenient case. Then, in the general case, one finds an “isomorphism” (i.e. “equivalence” in a suitable sense) $\varphi : X \rightarrow Y$ where Y is in the convenient case. Then the result on Y can be translated via φ^{-1} to X , finishing the proof.

For example, to solve a linear algebra problem about linear maps between finite-dimensional vector spaces V, W , one first proves it in the special case that $V = \mathbb{F}^m$ and $W = \mathbb{F}^n$. Then, the general case can be translated to the special case via an equivalence as in Exp. 1.21. \square

Exercise 3.13. Let X, Y be posets. Let $\varphi : X \rightarrow Y$ be an increasing bijection whose inverse is also increasing. (Namely, φ induces an equivalence of posets). Suppose $E \subset X$ has supremum $\sup E$. Explain why $\varphi(E)$ has supremum $\varphi(\sup E)$.

It is now fairly easy to prove the famous

Theorem 3.14 (Bolzano-Weierstrass). *Let $[a_1, b_1], \dots, [a_N, b_N]$ be closed intervals in $\overline{\mathbb{R}}$. Then $[a_1, b_1] \times \dots \times [a_N, b_N]$ is sequentially compact.*

Proof. By Prop. 3.4, it suffices to assume $N = 1$. Write $a_1 = a, b_1 = b$. Let (x_n) be a sequence in $[a, b]$. By Thm. 3.11, (x_n) has a subsequence (x_{n_k}) converging to some $x \in \overline{\mathbb{R}}$. (E.g. $x = \limsup_n x_n$.) Since $a \leq x_{n_k} \leq b$, we have $a \leq x \leq b$ by Rem. 2.71. \square

Bolzano-Weierstrass theorem illustrates why we sometimes prefer to work with $\overline{\mathbb{R}}$ instead of \mathbb{R} : $\overline{\mathbb{R}}$ is sequentially compact, while \mathbb{R} is not. That every sequence has limits superior and inferior in $\overline{\mathbb{R}}$ but not necessarily in \mathbb{R} is closely related to this fact. In the language of point-set topology, $\overline{\mathbb{R}}$ is a **compactification** of \mathbb{R} .

Bolzano-Weierstrass theorem (restricted to \mathbb{R}^N) will be generalized to **Heine-Borel theorem**, which says that a subset of \mathbb{R}^N is sequentially compact iff it is bounded and closed (cf. Def. 3.26 for the definition of closed subsets). See Thm. 3.55.

3.1.3 A criterion for convergence in sequentially compact spaces

At the end of Sec. 2.3, we have raised the following question: Suppose that (x_n) is a bounded sequence in a metric space X such that any two convergent subsequences converge to the same point. Does (x_n) converge?

When X is sequentially compact, (x_n) is automatically bounded due to Prop. 3.7. The answer to the above question is yes:

Theorem 3.15. *Let X be a sequentially compact metric space. Let (x_n) be a sequence in X . Then the following are equivalent.*

- (1) *The sequence (x_n) converges in X .*
- (2) *Any two convergent subsequences of (x_n) converge to the same point. In other words, (x_n) has only one cluster point.*

Proof. (1) \Rightarrow (2): By Prop. 2.36.

(2) \Rightarrow (1): Assume that (x_n) has at most one cluster point. Since X is sequentially compact, (x_n) has at least one cluster point $x \in X$. We want to prove $\lim_{n \rightarrow \infty} x_n = x$. Suppose not. Then there exists $\varepsilon > 0$ such that for every $N \in \mathbb{Z}_+$ there is $n \geq N$ such that $d(x_n, x) \geq \varepsilon$. Thus, one can inductively construct a subsequence (x_{n_k}) of (x_n) such that $d(x_{n_k}, x) \geq \varepsilon$ for all k . Since X is sequentially compact, (x_{n_k}) has a subsequence x'_n converging to $x' \in X$. So $d(x'_n, x) \geq \varepsilon$ for all n . Since the function $y \in X \mapsto d(y, x)$ is continuous (Exp. 2.58), we have $\lim_{n \rightarrow \infty} d(x'_n, x) = d(x', x)$. This proves that $d(x', x) \geq \varepsilon > 0$. However, x', x are both cluster points of (x_n) , and so $x = x'$. This gives a contradiction. \square

Remark 3.16. Thm. 3.15 can be used in the following way. Suppose that we want to prove that a given sequence (x_n) in a sequentially compact space X converges to x . Then it suffices to prove that if (x'_n) is a subsequence of (x_n) converging to some $y \in X$, then $y = x$. This is sometimes easier to prove than directly proving the convergence of (x_n) . We will use this strategy in the proof of L'Hôpital's rule, for example. (See Subsec. 12.1.2.)

Corollary 3.17. *Let (x_n) be a sequence in \mathbb{R}^N . The following are equivalent.*

- (1) *The sequence (x_n) converges in \mathbb{R}^N .*
- (2) *The sequence (x_n) is bounded. Moreover, any two convergent subsequences of (x_n) converge to the same point of \mathbb{R}^N .*

Proof. (1) \Rightarrow (2): By Prop. 2.33 and 2.36.

(2) \Rightarrow (1): Assume (2). Since (x_n) is bounded, it can be contained in $X = I_1 \times \cdots \times I_N$ where each I_i is a closed interval in \mathbb{R} . Clearly, any two cluster points of (x_n) are inside X , and are equal by (2). By Bolzano-Weierstrass, X is sequentially compact. Thus, by Thm. 3.15, (x_n) converges in X and hence in \mathbb{R}^N . \square

Corollary 3.18. *The following are true.*

1. *Let (x_n) be a sequence in $\overline{\mathbb{R}}$. Then (x_n) converges in $\overline{\mathbb{R}}$ iff $\limsup_{n \rightarrow \infty} x_n$ equals $\liminf_{n \rightarrow \infty} x_n$.*
2. *Let (x_n) be a sequence in \mathbb{R} . Then (x_n) converges in \mathbb{R} iff $\limsup_{n \rightarrow \infty} x_n$ equals $\liminf_{n \rightarrow \infty} x_n$ and (x_n) is bounded.*

Note that if (x_n) converges in $\overline{\mathbb{R}}$, we must have $\lim x_n = \limsup x_n = \liminf x_n$ by Thm. 3.11.

Proof. 1. Let $A = \liminf x_n$ and $B = \limsup x_n$. Let S be the set of cluster points of (x_n) . By Thm. 3.11, $A = \min S, B = \max S$. So $A = B$ iff S has only one element. This is equivalent to the convergence of (x_n) in $\overline{\mathbb{R}}$ due to Thm. 3.15 (since $\overline{\mathbb{R}}$ is sequentially compact by Bolzano-Weierstrass.)

2. If (x_n) converges, then $A = B$ by part 1. And (x_n) is bounded due to Prop. 2.33. Conversely, if $A = B$ and if (x_n) is bounded, say $\alpha \leq x_n \leq \beta$ for all n where $-\infty < \alpha < \beta < +\infty$. Then $\alpha \leq A \leq B \leq \beta$. So $A, B \in \mathbb{R}$. By part 1, (x_n) converges to $A \in \mathbb{R}$. \square

3.2 Outlook: sequentially compact function spaces

In Sec. 2.1, we mentioned that metric spaces and (more generally) point-set topology were introduced by mathematicians in order to study (typically infinite dimensional) function spaces with the help of the geometric intuition of \mathbb{R}^N . Now we have learned a couple of important results about sequentially compact spaces. But we have not met any example arising from function spaces. So let me show one example to the curious readers: The product space $[0, 1]^{\mathbb{Z}_+}$, equipped with the metric defined in Pb. 2.3, is sequentially compact. We will prove this result at the end of this chapter. (Indeed, we will prove a slightly more general version. See Thm. 3.54.) This is a famous result, not only because it has many important applications (some of which will be hinted at in this section), but also because its proof uses the clever “diagonal method”.

Moreover, we will later prove an even more surprising fact: every sequentially compact metric space is homeomorphic to a closed subset of $[0, 1]^{\mathbb{Z}_+}$. (See Thm. 8.45.) Thus, all sequentially compact metric spaces can be constructed explicitly, in some sense.

The readers may still complain that functions on \mathbb{Z}_+ are very different from those we often see and use in analysis and (especially) in differential equations: We are ultimately interested in functions on \mathbb{R} or on $[a, b]$, but not on countable sets. This is correct. But $[0, 1]^{\mathbb{Z}_+}$ (and its closed subsets) are in fact very helpful for the study of spaces of functions on \mathbb{R} and on $[a, b]$. In this course, we shall learn two major examples that the sequential compactness of $[0, 1]^{\mathbb{Z}_+}$ helps with:

1. $A = \mathbb{Q} \cap [a, b]$ is a countable dense subset of $[a, b]$. Thus, if we let $C([a, b])$ denote the set of continuous \mathbb{R} -functions on $[a, b]$, then the restriction map $f \in C([a, b]) \mapsto f|_A \in \mathbb{R}^A$ is injective. In many applications, we are interested in a subset $\mathcal{X} \subset C([a, b])$ of uniformly bounded functions, say all $f \in \mathcal{X}$ take values in $[-1, 1]$. Then we have an injective map

$$\Phi : \mathcal{X} \rightarrow [-1, 1]^A \quad f \mapsto f|_A$$

If \mathcal{X} satisfies a condition called “**equicontinuous**”, then a sequence f_n in \mathcal{X} converges *uniformly* to $f \in C([a, b])$ iff $f_n|_A$ converges *pointwise* to $f|_A$. (See Rem. 3.62.) Thus, from the sequential compactness of $[-1, 1]^A$ under pointwise convergence topology, one concludes that every sequence in \mathcal{X} has a subsequence converging uniformly in $C([a, b])$. This remarkable sequential compactness result on (the closure of) \mathcal{X} is called **Arzelà-Ascoli theorem**, and will be used to prove the fundamental Peano existence theorem in ordinary differential equations. We also see that the fact that $[a, b]$ has a countable dense subset A plays a crucial role. This property of metric spaces is called “**separable**” and will be studied later.

2. **Fourier series** are powerful for the study of partial differential equations. A continuous function $f : [-\pi, \pi] \rightarrow \mathbb{C}$ satisfying $f(-\pi) = f(\pi)$ has Fourier

series expansion $f(x) = \sum_{n \in \mathbb{Z}} a_n e^{inx}$ where $a_n \in \mathbb{C}$. However, for the sake of studying differential equations, one needs to consider series $\sum_{n \in \mathbb{Z}} a_n e^{inx}$ converging to a function much worse than a continuous function. For example, in the study of integral equations (which are closely related to certain partial differential equations), Hilbert and Schmidt discovered that one has to consider all $f(x) = \sum_{n \in \mathbb{Z}} a_n e^{inx}$ satisfying $\sum_n |a_n|^2 \leq 1$. Therefore, one lets $\overline{B} = \{z \in \mathbb{C} : |z| \leq 1\}$ and considers $\hat{f} : n \in \mathbb{Z} \mapsto a_n \in \mathbb{C}$ as an element of $\overline{B}^{\mathbb{Z}}$. The sequential compactness of $\overline{B}^{\mathbb{Z}}$ helps one find the \hat{f} such that the corresponding $f(x) = \sum_n \hat{f}(n) \cdot e^{inx}$ is a desired solution of the integral equation.

3.3 Complete metric spaces and Banach spaces

In this section, we let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and assume that all vector spaces are over \mathbb{F} .

3.3.1 Cauchy sequences and complete metric spaces

Definition 3.19. A sequence (x_n) in a metric space X is called a **Cauchy sequence**, if:

- For every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $m, n \geq N$ we have $d(x_m, x_n) < \varepsilon$.

Here, “ $\varepsilon > 0$ ” can mean either “ $\varepsilon \in \mathbb{R}_{>0}$ ” or “ $\varepsilon \in \mathbb{Q}_{>0}$ ”. The choice of this meaning does not affect the definition. The above definition can be abbreviated to “for every $\varepsilon > 0$, we have $d(x_m, x_n) < \varepsilon$ for sufficiently large m, n ”.

Remark 3.20. It is an easy consequence of triangle inequality that (x_n) is a Cauchy sequence iff

- For every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $d(x_n, x_N) < \varepsilon$.

Also, it is clear that every Cauchy sequence is bounded.

Proposition 3.21. *Every convergent sequence in a metric space X is a Cauchy sequence.*

Proof. Assume (x_n) converges to x in X . Then for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that $d(x, x_n) < \varepsilon/2$ for all $n \geq N$. Since this is true for every $m \geq N$, we have $d(x_m, x_n) \leq d(x, x_n) + d(x, x_m) < \varepsilon/2 + \varepsilon/2 = \varepsilon$. \square

Definition 3.22. A metric space X is called **complete** if every Cauchy sequence in X converges.

We have many examples of complete metric spaces:

Theorem 3.23. *If (x_n) is a Cauchy sequence in a metric space X with at least one cluster point, then (x_n) converges in X . Consequently, every sequentially compact metric space is complete.*

Proof. Let (x_n) be a Cauchy sequence in X with subsequence (x_{n_k}) converging to $x \in X$. Let us show that $x_n \rightarrow x$.

Since (x_n) is Cauchy, for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that $d(x_n, x_m) < \varepsilon/2$ for all $m, n \geq N$. Since $x_{n_k} \rightarrow x$, there is $k \geq N$ such that $d(x_{n_k}, x) < \varepsilon/2$. Since n_k is strictly increasing over k , we have $n_k \geq k$. So $n_k \geq N$. So we can let $m = n_k$. This gives $d(x_n, x_{n_k}) < \varepsilon/2$. Therefore $d(x_n, x) \leq d(x_n, x_{n_k}) + d(x_{n_k}, x) < \varepsilon$ for all $n \geq N$. \square

Example 3.24. Let $X = [a_1, b_1] \times \cdots \times [a_N, b_N]$ where each $[a_i, b_i]$ is a closed interval in \mathbb{R} , then X is sequentially compact by Bolzano-Weierstrass. Thus, by Thm. 3.23, X is complete.

Corollary 3.25. \mathbb{R}^N and \mathbb{C}^N are complete (under the Euclidean metrics).

Proof. Since \mathbb{C}^N is isometrically isomorphic to \mathbb{R}^{2N} , it suffices to prove that \mathbb{R}^N is complete. Choose a Cauchy sequence (x_n) in \mathbb{R}^N . Since (x_n) is bounded, (x_n) is contained inside $X = I_1 \times \cdots \times I_N$ where each $I_i = [a, b]$ is in \mathbb{R} . By Exp. 3.24, X is complete. So (x_n) converges to some $x \in X$. \square

Definition 3.26. We say that a subset A of a metric space X is **closed** if the following condition is true: For every sequence (x_n) in A converging to a point $x \in X$, we have $x \in A$.

Thus, the word “closed” here means “closed under taking limits”.

Proposition 3.27. *Let A be a metric subspace of a metric space X . Recall that the metric of A inherits from that of X (cf. Def. 2.14). Consider the statements:*

- (1) A is complete.
- (2) A is a closed subset of X .

Then (1) \Rightarrow (2). If X is complete, then (2) \Rightarrow (1).

Proof. First, assume that X is complete and (2) is true. Let (x_n) be a Cauchy sequence in A . Then it is a Cauchy sequence in X . So $x_n \rightarrow x \in X$ because X is complete. So $x \in A$ by the definition of closedness. This proves (1).

Next, we assume (1). Choose a sequence (x_n) in A converging to a point $x \in X$. By Prop. 3.21, (x_n) is a Cauchy sequence in X , and hence a Cauchy sequence in A . Since A is complete, there is $a \in A$ such that $x_n \rightarrow a$. So we must have $x = a$ because any sequence has at most one limit in a metric space. This proves $x \in A$. So (2) is proved. \square

A similar result holds for sequential compactness. See Pb. 3.4.

Example 3.28. Let $-\infty < a < b < +\infty$. Then (a, b) is not complete (under the Euclidean metric), because (a, b) is not closed in the metric space \mathbb{R} . (For sufficiently large n , $b - 1/n$ is in (a, b) , but $\lim_{n \rightarrow \infty} (b - 1/n) = b$ is not in b .)

Example 3.29. By Prop. 1.29, for each $x \in \mathbb{R} \setminus \mathbb{Q}$, we can choose an increasing sequence in \mathbb{Q} converging to x . So \mathbb{Q} is not closed in \mathbb{R} . So \mathbb{Q} is not complete under the Euclidean topology.

Example 3.30. Let X be a metric space. Let $p \in X$ and $0 \leq R < +\infty$. Then $\overline{B}_X(x, R)$ is a closed subset of X . Therefore, if X is complete, then $\overline{B}_X(p, R)$ is complete by Prop. 3.27.

Proof of closedness. Let (x_n) be a sequence in $\overline{B}(p, R)$ converging to $x \in X$. Then $d(p, x_n) \leq R$. Since the function $y \in X \mapsto d(p, y) \in \mathbb{R}$ is continuous (Exp. 2.58), we have $d(p, x) = \lim_{n \rightarrow \infty} d(p, x_n) \leq R$. So $x \in \overline{B}(p, R)$. \square

Exercise 3.31. Let d, δ be two equivalent metrics on a set X . Show that a sequence (x_n) in X is Cauchy under d iff (x_n) is Cauchy under δ .

Note that if, instead of assuming d, δ are equivalent, we only assume that d, δ are topologically equivalent. Then the above conclusion is not necessarily true:

Exercise 3.32. Find a non-complete metric δ on \mathbb{R} topologically equivalent to the Euclidean metric.

3.3.2 Normed vector spaces and Banach spaces

A major application of complete metric spaces is to show that many series converge without knowing to what exact values these series converge. A typical example is the convergence of $\sum_{n \in \mathbb{Z}_+} \sin(\sqrt{2}n)/n^2$ in \mathbb{R} . We are also interested in the convergence of series in function spaces, for instance: the uniform convergence of $f(x) = \sum_{n \in \mathbb{Z}_+} \sin(\sqrt{2}nx^3)/n^2$ on \mathbb{R} ; a suitable convergence of the Fourier series $\sum_{n \in \mathbb{Z}} a_n e^{inx}$. But we cannot take sum in a general metric space since it has no vector space structures. Therefore, we need a notion which combines complete metric spaces with vector spaces. Banach spaces are such a notion.

Definition 3.33. Let V be a vector space over \mathbb{F} with zero vector 0_V . A function $\|\cdot\| : V \rightarrow \mathbb{R}_{\geq 0}$ is called a **norm** if for every $u, v \in V$ and $\lambda \in \mathbb{F}$, the following hold:

- (Subadditivity) $\|u + v\| \leq \|u\| + \|v\|$.
- (Absolute homogeneity) $\|\lambda v\| = |\lambda| \cdot \|v\|$. In particular, (by taking $\lambda = 0$) we have $\|0_V\| = 0$.
- If $\|v\| = 0$ then $v = 0_V$.

We call $(V, \|\cdot\|)$ (often abbreviated to V) a **normed vector space**.

Remark 3.34. To check the absolute homogeneity, it suffices to check

$$\|\lambda v\| \leq |\lambda| \cdot \|v\|$$

for all λ and v . Then clearly $\|\lambda v\| = |\lambda| \cdot \|v\|$ when $\lambda = 0$. Suppose $\lambda \neq 0$. Then

$$\|v\| = \|\lambda^{-1}\lambda v\| \leq |\lambda|^{-1} \|\lambda v\|$$

which implies $\|\lambda v\| = |\lambda| \cdot \|v\|$.

Remark 3.35. Let V be a vector space. If V is a normed vector space, then

$$d(u, v) = \|u - v\| \tag{3.4}$$

clearly defines a metric. (Note that triangle inequality follows from subadditivity.) Unless otherwise stated, we always assume that the metric of a normed vector space is defined by (3.4).

Definition 3.36. Let V be a normed vector space. We say that V is a **Banach space** if V is a complete metric space where the metric is the canonical one (3.4). If V is over the field \mathbb{C} (resp. \mathbb{R}), we call V a **complex** (resp. **real**) **Banach space**.

Example 3.37. We always assume that the norm on \mathbb{F}^N is the **Euclidean norm**

$$\|(a_1, \dots, a_N)\| = \sqrt{|a_1|^2 + \dots + |a_N|^2} \tag{3.5}$$

The canonical metric it gives is the Euclidean metric. Thus, by Cor. 3.25, \mathbb{F}^N is a Banach space.

If (λ_n) is a sequence in \mathbb{F} converging to λ , and if (x_n) is a sequence in \mathbb{F}^N converging to x , then one can show that $\lambda_n x_n$ converges to λx by checking that each component of $\lambda_n x_n$ converges to the corresponding component of λx . This is due to Prop. 2.27. However, if (x_n) is in general a sequence in a normed vector space, this method fails. So we need a different argument:

Proposition 3.38. *Let V be a normed vector space. The following maps are continuous*

$$\begin{aligned} + : V \times V &\rightarrow V & (u, v) &\mapsto u + v \\ - : V \times V &\rightarrow V & (u, v) &\mapsto u - v \\ \times_{\mathbb{F}} : \mathbb{F} \times V &\rightarrow V & (\lambda, v) &\mapsto \lambda v \\ \|\cdot\| : V &\rightarrow \mathbb{R}_{\geq 0} & v &\mapsto \|v\| \end{aligned}$$

We didn't mention the continuity of the division map $(\lambda, v) \in \mathbb{F}^\times \times V \mapsto \lambda^{-1}v$ since it follows from that of $\times_{\mathbb{F}}$ and of the inversion map $\lambda \mapsto \lambda^{-1}$ by Exp. 2.44.

Proof. One can check that the addition map, the subtraction map, and the last map $\|\cdot\|$ are Lipschitz continuous.

Define metric $d((\lambda, v), (\lambda', v')) = \max\{|\lambda - \lambda'|, \|v - v'\|\}$ on $\mathbb{F} \times V$. Then $\mathbb{F} \times V$ is covered by open balls of the form $B(0, r) = \{(\lambda, v) \in \mathbb{F} \times V : |\lambda| < r, \|v\| < r\}$. Similar to the argument in (2.6), one uses subadditivity (i.e. triangle inequality) and absolute homogeneity to show that $\times_{\mathbb{F}}$ has Lipschitz constant $2r$ on $B(0, r)$. So $\times_{\mathbb{F}}$ is continuous by Lem. 2.41 and 2.43. \square

3.4 The Banach spaces $l^\infty(X, V)$ and $C(X, V)$

In this section, we let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$ and assume that the vector spaces V are over \mathbb{F} . As the title suggests, in this section we shall introduce two important examples of Banach spaces: the space of bounded functions $l^\infty(X, V)$ and its subspace of continuous functions $C(X, V)$ (when X is a sequentially compact metric space). In order for these two spaces to be Banach spaces, we must assume that V is also Banach.

In application, the main examples are $V = \mathbb{R}, \mathbb{C}, \mathbb{R}^N, \mathbb{C}^N$. Indeed, $C([a, b], \mathbb{R}^N)$ is one of the main examples of function spaces considered by Fréchet when he defined metric spaces. Therefore, the readers can assume that V is one of such spaces if they want to make life easier. Just keep in mind that we sometimes also consider the case where V itself is a function space.

Definition 3.39. Let X be a set and let V be a vector space. The set V^X is a vector space if we define for each $f, g \in V^X$ and $\lambda \in \mathbb{F}$:

$$\begin{aligned} f + g : X &\rightarrow V & (f + g)(x) &= f(x) + g(x) \\ \lambda f : X &\rightarrow V & (\lambda f)(x) &= \lambda f(x) \end{aligned}$$

We also define the **absolute value function**

$$|f| : X \rightarrow \mathbb{R}_{\geq 0} \quad x \in X \mapsto \|f(x)\| \quad (3.6)$$

The symbol $|f|$ is sometimes also written as $\|f\|$ when it will not be confused with $\|f\|_\infty$ or other norms of f .

Definition 3.40. Let X be a set and let V be a normed vector space. For each $f \in V^X$, define the **l^∞ -norm**

$$\|f\|_{l^\infty(X, V)} \equiv \|f\|_{l^\infty} \equiv \|f\|_\infty = \sup_{x \in X} \|f(x)\| \quad (3.7)$$

where $\|f(x)\|$ is defined by the norm of V . Define the **l^∞ -space**

$$l^\infty(X, V) = \{f \in V^X : \|f\|_\infty < +\infty\} \quad (3.8)$$

which is a vector subspace of V^X . Then $l^\infty(X, V)$ is a normed vector space under the l^∞ -norm. A function $f : X \rightarrow V$ is called **bounded** if $f \in l^\infty(X, V)$.

Exercise 3.41. Prove that for every $f, g \in V^X$ and $\lambda \in \mathbb{F}$ we have

$$\begin{aligned}\|f + g\|_\infty &\leq \|f\|_\infty + \|g\|_\infty \\ \|\lambda f\|_\infty &= |\lambda| \cdot \|f\|_\infty\end{aligned}\tag{3.9}$$

(Note that clearly we have that $\|f\|_\infty = 0$ implies $f = 0$.) Here, we understand $0 \cdot (+\infty) = 0$. Use these relations to verify that $l^\infty(X, V)$ is a linear subspace of V^X (i.e. it is closed under addition and scalar multiplication) and that $\|\cdot\|_\infty$ is a norm on $l^\infty(X, V)$. \square

Definition 3.42. Let V be a normed vector space. We say that a sequence (f_n) in V^X **converges uniformly** to $f \in V^X$ if $\lim_{n \rightarrow \infty} \|f - f_n\|_\infty = 0$. In this case, we write $f_n \rightrightarrows f$.

We say that (f_n) **converges pointwise** to $f \in V^X$ if for every $x \in X$ we have $\lim_{n \rightarrow \infty} f_n(x) = f(x)$, i.e. $\lim_{n \rightarrow \infty} \|f_n(x) - f(x)\| = 0$.

The same definition will be applied to nets $(f_\alpha)_{\alpha \in I}$ in V^X after learning net convergence in Sec. 5.2. \square

In more details, the uniform convergence of f_n to f means that “for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and for all $x \in X$, we have $\|f_n(x) - f(x)\| < \varepsilon$ ”. If we place the words “for all $x \in X$ ” at the very beginning of the sentence, we get pointwise convergence.

Uniform convergence implies pointwise convergence: If $\|f - f_n\|_\infty \rightarrow 0$, then for each $x \in X$ we have $\|f_n(x) - f(x)\| \rightarrow 0$ since $\|f(x) - f_n(x)\| \leq \|f - f_n\|_\infty$.

Example 3.43. Let $f_n : (0, 1) \rightarrow \mathbb{R}$ be $f_n(x) = x^n$. Then f_n converges pointwise to 0 (cf. Exp. 4.10). But $\sup_{x \in (0,1)} |x^n - 0| = 1$ does not converge to 0. So f_n does not converge uniformly to 0.

Remark 3.44. The uniform convergence of sequences in $l^\infty(X, V)$ is induced by the l^∞ -norm, and hence is induced by the metric $d(f, g) = \|f - g\|_\infty$. However, this formula cannot be extended to a metric on V^X , since for arbitrary $f, g \in V^X$, $\|f - g\|_\infty$ is possibly $+\infty$.

In fact, it is true that the uniform convergence of sequences in V^X is induced by a metric, see Pb. 3.6. When X is countable, we have seen in Pb. 2.3 that the pointwise convergence in V^X is also given by a metric. \square

Theorem 3.45. Let X be a set, and let V be a Banach space (over \mathbb{F}). Then $l^\infty(X, V)$ is a Banach space (over \mathbb{F}).

Proof. Let (f_n) be a Cauchy sequence in $l^\infty(X, V)$. Then for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that for all $m, n \geq N$ we have that $\sup_{x \in X} \|f_n(x) - f_m(x)\| < \varepsilon$, and hence $\|f_n(x) - f_m(x)\| < \varepsilon$ for each $x \in X$. This shows that for each $x \in X$, $(f_n(x))$ is a Cauchy sequence in V , which converges to some element $f(x) \in V$ because V is complete.

We come back to the statement that for each $\varepsilon > 0$, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and all x ,

$$\|f_n(x) - f_m(x)\| < \varepsilon$$

for every $m \geq N$. Let $m \rightarrow \infty$. Then by the continuity of subtraction and taking norm (cf. Prop. 3.38.), we obtain $\|f_n(x) - f(x)\| \leq \varepsilon$ for all $n \geq N$ and $x \in X$. In other words, $\|f_n - f\|_\infty \leq \varepsilon$ for all $n \geq N$. In particular, $\|f\|_\infty \leq \|f_N\|_\infty + \|f_N - f\|_\infty < +\infty$ by (3.9). This proves $f \in l^\infty(X, V)$ and $f_n \rightrightarrows f$. \square

Mathematicians used to believe that “if a sequence of continuous functions $f_n : [0, 1] \rightarrow \mathbb{R}$ converges pointwise to a function $f : [0, 1] \rightarrow \mathbb{R}$, then f is continuous”. Cauchy, one of the main figures in 19th century working on putting analysis on a rigorous ground, has given a problematic proof of this wrong statement. Counterexamples were later found in the study of Fourier series: Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a function with period 2π such that $f(x) = x$ when $-\pi < x < \pi$, and $f(x) = 0$ when $x = \pm\pi$. Then the Fourier series of this noncontinuous function f converges pointwise to f , yet the partial sums of this series are clearly continuous functions. Later, it was realized that uniform convergence is needed to show the continuity of the limit function. (See Thm. 3.48.) This was the first time the importance of uniform convergence was realized.

The following discussions about (resp. sequentially compact) metric spaces also apply to general (resp. compact) topological spaces. The reader can come back and check the proofs for these more general spaces after studying them in the future.

Definition 3.46. Let X, Y be metric spaces (resp. topological spaces). Then $C(X, Y)$ denotes the set of continuous functions from X to Y .

Lemma 3.47. Let X be a metric space (resp. a topological space), and let V be a normed vector space. Then $C(X, V)$ is a linear subspace of V^X . If X is sequentially compact (resp. compact), then $C(X, V)$ is a linear subspace of $l^\infty(X, V)$.

Proof. Using Prop. 3.38, one checks easily that $C(X, V)$ is a linear subspace of V^X . For any $f \in C(X, V)$, the absolute value function $|f| : x \in X \mapsto \|f(x)\|$ is continuous. Thus, assuming that X is sequentially compact, then by Lem. 3.2, $|f|$ is bounded on X . This proves that $\|f\|_\infty < +\infty$. Thus $C(X, V)$ is a subset (and hence a linear subspace) of $l^\infty(X, V)$. \square

Theorem 3.48. Let X be a metric space (resp. a topological space), and let V be a normed vector space. Then $C(X, V) \cap l^\infty(X, V)$ is a closed linear subspace of $l^\infty(X, V)$. In particular, if X is sequentially compact (resp. compact), then $C(X, V)$ is a closed linear subspace of $l^\infty(X, V)$.

Proof. Choose a sequence (f_n) in $C(X, V) \cap l^\infty(X, V)$ converging in $l^\infty(X, V)$ to f . Namely, $f_n \rightrightarrows f$. We want to prove that f is continuous. We check that f satisfies Def. 2.38-(2'). (One can also use Def. 2.38-(1). The proofs using these two definitions are not substantially different.)

Fix $p \in X$. Choose any $\varepsilon > 0$. Since $f_n \rightrightarrows f$, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and we have $\|f - f_n\|_\infty < \varepsilon$. Since f_N is continuous, there exists $r > 0$ such that for each $x \in B_X(p, r)$ we have $\|f_N(x) - f_N(p)\| < \varepsilon$. Thus, for each $x \in B_X(p, r)$ we have

$$\|f(x) - f(p)\| \leq \|f(x) - f_N(x)\| + \|f_N(x) - f_N(p)\| + \|f_N(p) - f(p)\| < 3\varepsilon$$

This finishes the proof. \square

Convention 3.49. Unless otherwise stated, if X is sequentially compact metric space (or more generally, a compact topological space to be defined latter), and if V is a normed vector space, the norm on $C(X, V)$ is chosen to be the l^∞ -norm.

Corollary 3.50. *Let X be a metric space (resp. a topological space), and let V be a Banach space. Then $C(X, V) \cap l^\infty(X, V)$ is a Banach space under the l^∞ -norm. In particular, if X is sequentially compact (resp. compact), then $C(X, V)$ is a Banach space.*

Proof. This follows immediately from Prop. 3.27, Thm. 3.48, and the fact that $l^\infty(X, V)$ is complete (Thm. 3.45). \square

3.5 Problems and supplementary material

Problem 3.1. Let (x_n) be a sequence in a metric space X . Let $x \in X$. Prove that the following are equivalent.

- (1) x is a cluster point of (x_n) , i.e., the limit of a convergent subsequence of (x_n) .
- (2) For each $\varepsilon > 0$ and each $N \in \mathbb{Z}_+$, there exists $n \geq N$ such that $d(x_n, x) < \varepsilon$.

(Note: in a general topological space, these two statements are not equivalent.)

Remark 3.51. Condition (2) is often abbreviated to “for each $\varepsilon > 0$, the sequence (x_n) is frequently in $B(x, \varepsilon)$ ”. In general, we say “ (x_n) **frequently** satisfies P” if for each $N \in \mathbb{Z}_+$ there is $n \geq N$ such that x_n satisfies P. We say that “ (x_n) **eventually** satisfies P” if there exists $N \in \mathbb{Z}_+$ such that for every $n \geq N$, x_n satisfies P.

Thus “ (x_n) eventually satisfies P” means the same as “all but finitely many x_n satisfies P”. Its negation is “ (x_n) frequently satisfies $\neg P$ ”. \square

Remark 3.52. Condition (2) of Pb. 3.1 is sometimes easier to use than (1). For example, compared to the original definition of cluster points, it is much easier to find an explicit negation of (2) by using the rule suggested in Rem. 2.17: There exist $\varepsilon > 0$ and $N \in \mathbb{Z}_+$ such that $d(x_n, x) \geq \varepsilon$ for all $n \geq N$. (Or simply: there exists $\varepsilon > 0$ such that x_n is eventually not in $B(x, \varepsilon)$.)

Problem 3.2. Use Pb. 3.1-(2) to prove that if (x_n) is a sequence in $\overline{\mathbb{R}}$, then $\limsup_{n \rightarrow \infty} x_n$ is a cluster point of (x_n) .

Remark 3.53. You will notice that your proof of Pb. 3.2 is slightly simpler than the proof we gave for Thm. 3.11. This is because our construction of subsequence as in (3.3) has been incorporated into your proof of (2) \Rightarrow (1) in Pb. 3.1.

Problem 3.3. Let $f : X \rightarrow Y$ be a continuous map of metric spaces. Assume that f is bijective and X is sequentially compact. Prove that f is a homeomorphism using the following hint.

Hint. You need to prove that if (y_n) is a sequence in Y converging to $y \in Y$, then $x_n = f^{-1}(y_n)$ converges to $x = f^{-1}(y)$. Prove that (x_n) has only one cluster point, and hence converges to some point $x' \in X$ (why?). Then prove $x' = x$. (In the future, we will use the language of open sets and closed sets to prove this result again. Do not use this language in your solution.) \square

Theorem 3.54 (Tychonoff theorem, countable version). Let $(X_n)_{n \in \mathbb{Z}_+}$ be a sequence of sequentially compact metric spaces. Then the product space $S = \prod_{n \in \mathbb{Z}_+} X_n$ is sequentially compact under the metric defined as in Pb. 2.3.

The method of choosing subsequence in the following proof is the renowned **diagonal method**. A different method will be given in Pb. 8.7.

Proof. Let $(x_m)_{m \in \mathbb{Z}_+}$ be a sequence in S . Since $(x_m(1))_{m \in \mathbb{Z}_+}$ is a sequence in the sequentially compact space X_1 , $(x_m)_{m \in \mathbb{Z}_+}$ has a subsequence $x_{1,1}, x_{1,2}, x_{1,3}, \dots$ whose value at $n = 1$ converges in X_1 . Since X_2 is sequentially compact, we can choose a subsequence $x_{2,1}, x_{2,2}, x_{2,3}, \dots$ of the previous subsequence such that its values at $n = 2$ converge in X_2 . Then pick a subsequence from the previous one whose values at 3 converge in X_3 .

By repeating this process, we get an $\infty \times \infty$ matrix $(x_{i,j})_{i,j \in \mathbb{Z}_+}$:

$$\begin{array}{cccc} x_{1,1} & x_{1,2} & x_{1,3} & \cdots \\ x_{2,1} & x_{2,2} & x_{2,3} & \cdots \\ x_{3,1} & x_{3,2} & x_{3,3} & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{array} \quad (3.10)$$

such that the following hold:

- The 1-st line is a subsequence of the original sequence $(x_m)_{m \in \mathbb{Z}_+}$.
- The $(i + 1)$ -th line is a subsequence of the i -th line.
- For each n , $\lim_{j \rightarrow \infty} x_{n,j}(n)$ converges in X_n .

Then the diagonal line $(x_{i,i})_{i \in \mathbb{Z}_+}$ is a subsequence of the original sequence $(x_m)_{m \in \mathbb{Z}_+}$. Moreover, for each n , $(x_{i,i})_{i \geq n}$ is a subsequence of the n -th line, whose value at n therefore converges in X_n . Thus $\lim_{i \rightarrow \infty} x_{i,i}(n)$ converges in X_n . Thus, by Pb. 2.3, $(x_{i,i})_{i \in \mathbb{Z}_+}$ converges under any metric inducing the product topology. \square

Problem 3.4. Let X be a sequentially compact metric space. Let $A \subset X$ be a metric subspace. Consider the statements:

- (1) A is sequentially compact.
- (2) A is a closed subset of X .

Prove that (1) \Rightarrow (2). Prove that if X is sequentially compact, then (2) \Rightarrow (1).

The above problem implies immediately:

Theorem 3.55 (Heine-Borel theorem). *Let A be a subset of \mathbb{R}^N . Then A is sequentially compact iff A is a bounded closed subset of \mathbb{R}^N .*

Proof. Suppose that A is sequentially compact. Then A is bounded under the Euclidean metric by Prop. 3.7. By Pb. 3.4, A is a closed subset of \mathbb{R}^N .

Conversely, assume that A is a bounded and closed subset of \mathbb{R}^N . Then $A \subset B$ where B is the product of N pieces of closed intervals in \mathbb{R} . Then B is sequentially compact by Bolzano-Weierstrass. Since A is closed in \mathbb{R}^N , it is not hard to check that A is closed in B .¹ Thus A is sequentially compact by Pb. 3.4. \square

Example 3.56. Choose any $p \in \mathbb{R}^N$ and $0 \leq R < +\infty$. Then $\overline{B}_{\mathbb{R}^N}(p, R)$ is a bounded closed subset of \mathbb{R}^N (Exp. 3.30), and hence is sequentially compact by Heine-Borel.

Remark 3.57. Think about the question: Equip $\mathbb{R}^{\mathbb{Z}_+}$ with metric

$$d(x, y) = \sup_{n \in \mathbb{Z}_+} \frac{\min\{|x(n), y(n)|, 1\}}{n}$$

What are the sequentially compact subsets of $\mathbb{R}^{\mathbb{Z}_+}$? (Namely, think about how to generalize Heine-Borel theorem to $\mathbb{R}^{\mathbb{Z}_+}$.)

Problem 3.5. Do Exercise 3.41.

Problem 3.6. Let V be a normed vector space. For every $f, g \in V^X$ define

$$d(f, g) = \min\{1, \|f - g\|_\infty\} \tag{3.11}$$

1. Show that d defines a metric on V^X .

¹If Z is a metric space, if $X \subset Y \subset Z$, and if X is closed in Z , then it is easy to check that X is closed in Y .

2. Show that for every sequence (f_n) in V^X and every $g \in V^X$, we have $f_n \rightarrow g$ under the metric d iff $f_n \rightrightarrows g$.

Definition 3.58. Let X be a set, and let V be a normed vector space. A metric on V^X is called a **uniform convergence metric** if it is equivalent to (3.11). Thus, by Def. 2.61, a uniform convergence metric is one such that a sequence (f_n) in V^X converges to f under this metric iff $f_n \rightrightarrows f$.

Problem 3.7. Let X, Y be metric spaces, and assume that Y is sequentially compact. Let V be a normed vector space. Choose $f \in C(X \times Y, V)$, i.e., $f : X \times Y \rightarrow V$ is continuous. For each $x \in X$, let

$$f_x : Y \rightarrow V \quad y \mapsto f(x, y)$$

Namely $f_x(y) = f(x, y)$. It is easy to check that $f_x \in C(Y, V)$. Define a new function

$$\Phi(f) : X \rightarrow C(Y, V) \quad x \mapsto f_x \quad (3.12)$$

Recall that $C(Y, V)$ is equipped with the l^∞ -norm.

1. Prove that $\Phi(f)$ is continuous. In other words, prove that if (x_n) is a sequence in X converging to $x \in X$, then $f_{x_n} \rightrightarrows f_x$ on Y , i.e.

$$\lim_{n \rightarrow \infty} \|f_{x_n} - f_x\|_{l^\infty(Y, V)} = 0$$

- ★ 2. Give an example of $f \in C(X \times Y, \mathbb{R})$ where Y is not sequentially compact, (x_n) converges to x in X , and f_{x_n} does not converge uniformly to f_x . (Note: you may consider $X = Y = \mathbb{R}$.)

Hint. In part 1, to prove that $\Phi(f)$ is continuous, one can prove the equivalent fact that for every fixed $x \in X$ the following is true:

- For every $\varepsilon > 0$ there exists $\delta > 0$ such that for all $p \in B_X(x, \delta)$, we have $\sup_{y \in Y} \|f(p, y) - f(x, y)\| < \varepsilon$.

(Cf. Def. 2.38.) Prove this by contradiction and by using the sequential compactness of Y appropriately. \square

Remark 3.59. Let $X = \mathbb{Z}_+ \cup \{\infty\}$, equipped with the metric

$$d(m, n) = |m^{-1} - n^{-1}|$$

In other words, the metric on X is $\tau^* d_{\mathbb{R}}$ where $d_{\mathbb{R}}$ is the Euclidean metric on \mathbb{R} , and $\tau : X \rightarrow \mathbb{R}, n \mapsto n^{-1}$. It is not hard to show that X is sequentially compact: either prove it directly, or apply Heine-Borel to $\tau(X)$.

Let Y be a metric space. Let $(y_n)_{n \in \mathbb{Z}_+}$ be a sequence in Y , and let $y_\infty \in Y$. It is not hard to see that the following two statements are equivalent:

- (1) The function $F : X \rightarrow Y, n \mapsto y_n$ is continuous.
- (2) The sequence $(y_n)_{n \in \mathbb{Z}_+}$ converges to y_∞ .

The following problem is a generalization of this equivalence. □

★ **Problem 3.8.** Let V be a normed vector space. Let Y be a metric space. Let $X = \mathbb{Z}_+ \cup \{\infty\}$ with metric defined as in Rem. 3.59. Let $(f_n)_{n \in \mathbb{Z}_+}$ be a sequence in $C(Y, V)$. Let $f_\infty \in V^Y$. Prove that the following are equivalent:

- (1) The following function is continuous:

$$F : X \times Y \rightarrow V \quad (n, y) \mapsto f_n(y) \quad (3.13)$$

In particular, by restricting F to $\infty \times Y$, we see that $f_\infty \in C(Y, V)$.

- (2) $(f_n)_{n \in \mathbb{Z}_+}$ converges pointwise to f_∞ . Moreover, $(f_n)_{n \in \mathbb{Z}_+}$ is **pointwise equicontinuous**, which means the following:
 - For every $y \in Y$ and every $\varepsilon > 0$, there exists $\delta > 0$ such that for all $p \in B_Y(y, \delta)$ we have

$$\sup_{n \in \mathbb{Z}_+} \|f_n(p) - f_n(y)\| < \varepsilon$$

Note. In part (1), the only nontrivial thing to prove is that F is continuous at (∞, y) for every $y \in Y$.

Remark 3.60. There is a concise way to define pointwise equicontinuity: a sequence $(f_n)_{n \in \mathbb{Z}_+}$ in V^Y is pointwise equicontinuous iff the function

$$Y \mapsto V^{\mathbb{Z}_+} \quad y \mapsto (f_1(y), f_2(y), \dots) \quad (3.14)$$

is continuous, where $V^{\mathbb{Z}_+}$ is equipped with any uniform convergence metric (cf. Def. 3.58).

★ **Remark 3.61.** In Pb. 3.8, there is a quick and tricky way to conclude (1)⇒(2): Use Pb. 3.7 and the sequential compactness of X . (Do not use this method in your solution. Prove (1)⇒(2) directly; it is a good exercise and is not difficult.)

★ **Remark 3.62.** Pb. 3.7 and 3.8, together with Thm. 3.48, imply the following fact (can you see why?):

- Let Y be a sequentially compact metric space. Let V be a normed vector space. Let $(f_n)_{n \in \mathbb{Z}_+}$ be a pointwise equicontinuous sequence of functions $Y \rightarrow V$ converging pointwise to some $f : Y \rightarrow V$. Then $f_n \rightrightarrows f$ on Y .

You can also try to give a straightforward proof of this fact without using Pb. 3.7 and 3.8.

4 Series

In this chapter, we assume that vector spaces are over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$ unless otherwise stated.

4.1 Definitions and basic properties

Definition 4.1. Let V be a Banach space (over \mathbb{F}). A **series** in V is an expression of the form

$$\sum_{i=1}^{\infty} v_i \quad (4.1)$$

where $(v_i)_{i \in \mathbb{Z}_+}$ is a sequence in V . If $s \in V$, we say that the series (4.1) **converges to s** if

$$s = \lim_{n \rightarrow \infty} \sum_{i=1}^n v_i$$

namely, $s_n \rightarrow s$ where s_n is the **partial sum** $s_n = \sum_{i=1}^n v_i$. In this case, we write

$$s = \sum_{i=1}^{\infty} v_i$$

Remark 4.2. Since V is complete, the series (4.1) converges iff the sequence of partial sum (s_n) is a Cauchy sequence: for every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n > m \geq N$ we have $\|s_n - s_m\| < \varepsilon$, i.e.,

$$\left\| \sum_{i=m+1}^n v_i \right\| < \varepsilon \quad (4.2)$$

Proposition 4.3. Suppose that $\sum_{i=1}^{\infty} v_i$ is a convergent series in a Banach space V . Then $\lim_{n \rightarrow \infty} v_n = 0$.

Proof. Let $s_n = v_1 + \cdots + v_n$, which converges to $s \in V$. Then $\lim_{n \rightarrow \infty} s_{n+1} = s$. So $v_n = s_{n+1} - s_n \rightarrow s - s = 0$ since subtraction in continuous (Prop. 3.38). \square

Thus, for example, $\sum_{n=1}^{\infty} (-1)^n$ diverges in the Banach space \mathbb{R} since $\lim_{n \rightarrow \infty} (-1)^n$ does not converge to 0.

Definition 4.4. Consider a **series** in $\overline{\mathbb{R}}_{\geq 0}$:

$$\sum_{i=1}^{\infty} a_i \quad (4.3)$$

namely, each a_i is in $\overline{\mathbb{R}}_{\geq 0}$. Note that the partial sum $s_n = \sum_{i=1}^n a_i$ is increasing. We say that $\lim_{n \rightarrow \infty} s_n$ (which exists in $\overline{\mathbb{R}}_{\geq 0}$ and equals $\sup\{s_n : n \in \mathbb{Z}_+\}$, cf. Rem. 2.71) is the value of the series (4.3) and write

$$\sum_{i=1}^{\infty} a_i = \lim_{n \rightarrow \infty} s_n$$

Definition 4.5. We say that a series $\sum_{i=1}^{\infty} a_i$ in $\mathbb{R}_{\geq 0}$ **converges** if it converges in \mathbb{R} (but not just converges in $\overline{\mathbb{R}}_{\geq 0}$, which is always true). Clearly, $\sum_{i=1}^{\infty} a_i$ converges iff

$$\sum_{i=1}^{\infty} a_i < +\infty$$

More generally, we say that a series $\sum_{i=1}^{\infty} v_i$ in a Banach space V **converges absolutely**, if

$$\sum_{i=1}^{\infty} \|v_i\| < +\infty$$

Remark 4.6. By the Cauchy condition of convergence, $\sum_{i=1}^{\infty} v_i$ converges absolutely iff for every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n > m \geq N$ we have

$$\sum_{i=m+1}^n \|v_i\| < \varepsilon \quad (4.4)$$

By comparing (4.4) with (4.2) and using the subadditivity of the norm (recall Def. 3.33), we immediately see:

Proposition 4.7. Let $\sum_{i=1}^{\infty} v_i$ be a series in a Banach space. The following are true.

1. If $\sum_{i=1}^{\infty} v_i$ converges absolutely, then it converges.
2. For each i we choose $a_i \in \mathbb{R}_{\geq 0}$ satisfying $\|v_i\| \leq a_i$. Suppose that $\sum_{i=1}^{\infty} a_i < +\infty$. Then $\sum_{i=1}^{\infty} v_i$ converges absolutely.

Proof. Part 1 has been explained above. In part 2, we have $\sum \|v_i\| \leq \sum a_i < +\infty$. So $\sum v_i$ converges absolutely. \square

Exercise 4.8. Suppose that $\sum_{i=1}^{\infty} u_i$ and $\sum_{i=1}^{\infty} v_i$ are convergent (resp. absolutely convergent) series in a Banach space V . Let $\lambda \in \mathbb{F}$. Show that the LHS of the following equations converges (resp. converges absolutely) in V , and that the following equations hold:

$$\begin{aligned} \sum_{i=1}^{\infty} (u_i + v_i) &= \sum_{i=1}^{\infty} u_i + \sum_{i=1}^{\infty} v_i \\ \sum_{i=1}^{\infty} \lambda v_i &= \lambda \cdot \sum_{i=1}^{\infty} v_i \end{aligned}$$

Remark 4.9. We have seen that absolute convergence implies convergence. In fact, at least when $V = \mathbb{F}^N$, absolute convergence is in many ways more natural than convergence. For example, we will learn that if a series $\sum_i v_i$ in \mathbb{F}^N converges absolutely, then the value of $\sum_i v_i$ is invariant under rearrangement of the series: for every bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$ we have $\sum_i v_i = \sum_i v_{\varphi(i)}$. In the next semester, we shall learn Lebesgue integral theory and, more generally, measure theory. When applying measure theory to infinite sums over the countable set \mathbb{Z}_+ , many good results (e.g. dominated convergence theorem, Fubini's theorem) hold only for absolute convergence series, but not for arbitrary convergent series in general. In fact, there is no analog of convergent (but not absolutely convergent) series in measure theory at all!

When V is not necessarily finite-dimensional, the situation is subtler: there is a version of convergence which lies between the usual convergence and absolute convergence, and which coincides with absolute convergence when $V = \mathbb{F}^N$. This version of convergence is defined using nets instead of sequences. Moreover, many good properties (as mentioned above) hold for this convergence, and these properties can be proved in a very conceptual way (rather than using brute-force computation). We will learn this convergence in the next chapter. \square

4.2 Basic examples

Let us study the **geometric series** $\sum_{n=0}^{\infty} z^n$ where $z \in \mathbb{C}$. We first note the famous **binomial formula**: for each $z, w \in \mathbb{C}$ and $n \in \mathbb{N}$,

$$(z + w)^n = \sum_{k=0}^n \binom{n}{k} z^k w^{n-k} \quad (4.5)$$

In particular,

$$(1 + z)^n = 1 + nz + \frac{n(n-1)}{2} z^2 + \frac{n(n-1)(n-2)}{6} z^3 + \cdots + nz^{n-1} + z^n \quad (4.6)$$

Example 4.10. Assume $z \in \mathbb{C}$ and $|z| < 1$. Then $\lim_{n \rightarrow \infty} z^n = 0$.

Proof. If $z = 0$ then it is obvious. Assume that $0 < |z| < 1$. Choose $\delta > 0$ such that $|z| = 1/(1 + \delta)$. By (4.6), $(1 + \delta)^n \geq 1 + n\delta$. So

$$0 \leq |z^n| \leq (1 + n\delta)^{-1}$$

Since $\lim_{n \rightarrow \infty} (1 + n\delta)^{-1} = 0$, we have $|z^n| \rightarrow 0$ by squeeze theorem. Hence $z^n \rightarrow 0$. \square

Example 4.11. Let $z \in \mathbb{C}$. If $|z| < 1$, then $\sum_{n=0}^{\infty} z^n$ converges absolutely, and

$$\sum_{n=0}^{\infty} z^n = \frac{1}{1 - z} \quad (4.7)$$

where 0^0 is understood as 1. If $|z| \geq 1$, then $\sum_{n=0}^{\infty} z^n$ diverges in \mathbb{C} .

Proof. The partial sum $s_n = 1 + z + z^2 + \cdots + z^n$ equals $(1 - z^{n+1})/(1 - z)$ when $z \neq 1$. Therefore, when $|z| < 1$, $s_n \rightarrow 1/(1 - z)$. When $|z| \geq 1$, we have $|z^n| \geq 1$ and hence $z^n \not\rightarrow 0$. So $\sum_{n=0}^{\infty} z^n$ diverges by Prop. 4.3. \square

Example 4.12. The harmonic series $\sum_{n=1}^{\infty} \frac{1}{n}$ diverges (in \mathbb{R}).

Proof. We want to show that the Cauchy condition (cf. Rem. 4.2) does not hold. Thus, we want to prove that there exists $\varepsilon > 0$ such that for every $N \in \mathbb{Z}_+$ there exist $n > m \geq N$ such that $|(m+1)^{-1} + (m+2)^{-1} + \cdots + n^{-1}| \geq \varepsilon$.

To see this, for each N we choose $m = 2^N$ and $n = 2^{N+1}$. Then $n > m > N$, and

$$\begin{aligned} \left| \sum_{i=m+1}^n i^{-1} \right| &= \left| \frac{1}{2^N + 1} + \frac{1}{2^N + 2} + \cdots + \frac{1}{2^N + 2^N} \right| \\ &\geq \underbrace{\left| \frac{1}{2^{N+1}} + \frac{1}{2^{N+1}} + \cdots + \frac{1}{2^{N+1}} \right|}_{2^N \text{ terms}} = \varepsilon \end{aligned}$$

where $\varepsilon = \frac{1}{2}$. \square

Exercise 4.13. Choose any $p \in \mathbb{Z}$. Prove that $\sum_{n=1}^{\infty} n^{-p}$ converges iff $p \geq 2$.

Hint. Use Prop. 4.7 and Exp. 4.12 to reduce the problem to the case $p = 2$. Prove this case by proving $\sum_{n=1}^{\infty} 1/n(n+1) = 1 < +\infty$. \square

Definition 4.14. Let V be a Banach space, let X be a set, and let (f_n) be a sequence in $l^\infty(X, V)$, and let $g \in l^\infty(X, V)$. We say that the series of functions $\sum_{i=1}^{\infty} f_i$ **converges uniformly to g** (on X) if it converges to g as a series in the Banach space $l^\infty(X, V)$ and under the l^∞ -norm. Equivalently, this means that the partial sum function $s_n = f_1 + \cdots + f_n$ converges uniformly to g as $n \rightarrow \infty$.

Example 4.15. The series of functions $\sum_{n=1}^{\infty} \frac{\sin |nz^3|}{n^2}$ converges uniformly on \mathbb{C} to a continuous function $g : \mathbb{C} \rightarrow \mathbb{R}$ which is bounded (i.e. $\sup_{z \in \mathbb{C}} |g(z)| < +\infty$).

Proof. Let $f_n(z) = \sin |nz^3|/n^2$. Then each f_n is in $\mathfrak{X} = C(\mathbb{C}, \mathbb{R}) \cap l^\infty(\mathbb{C}, \mathbb{R})$ where \mathfrak{X} is a real Banach space under the l^∞ -norm by Cor. 3.50. Note that $\|f_n\|_\infty \leq n^{-2}$. By Exe. 4.13, $\sum_{n=1}^{\infty} n^{-2} < +\infty$. Therefore, by Prop. 4.7, the series $\sum_n f_n$ converges in \mathfrak{X} , i.e., it converges uniformly to an element $g \in \mathfrak{X}$. (In particular, $\sum_n f_n(z) = g(z)$ for all $z \in \mathbb{C}$.) \square

4.3 Root test and ratio test; power series; construction of e^z

Root test and ratio test are useful criteria for proving the convergence or divergence of series, especially power series. In addition, the method of power series provides a unified and elegant proof for many useful formulas about limit (see Prop. 4.23 and Exp. 4.24). We begin our discussion with the following easy observation:

Remark 4.16. Let (x_n) be a sequence in $\overline{\mathbb{R}}$, and let $A \in \overline{\mathbb{R}}$. The following are true.

1. If $\limsup_{n \rightarrow \infty} x_n < A$, then $x_n < A$ is eventually true.
2. If $\limsup_{n \rightarrow \infty} x_n > A$, then $x_n > A$ is frequently true.

By taking negative, we obtain similar statements for \liminf .

Proof. Recall that $\limsup x_n = \inf_{n \in \mathbb{Z}_+} \alpha_n$ where $\alpha_n = \sup\{x_n, x_{n+1}, \dots\}$.

Assume that $\inf_{n \in \mathbb{Z}_+} \alpha_n < A$. Then A is not a lower bound of $\{\alpha_n : n \in \mathbb{Z}_+\}$. Thus, there exists $N \in \mathbb{Z}_+$ such that $\alpha_N < A$. Then $x_n < A$ for all $n \geq N$.

Assume that $\inf_{n \in \mathbb{Z}_+} \alpha_n > A$. Then for each $N \in \mathbb{Z}_+$ we have $\alpha_N > A$. So A is not an upper bound of $\{x_n, x_{n+1}, \dots\}$. So there is $n \geq N$ such that $x_n > A$. \square

We will heavily use $\sqrt[n]{x}$ (where $x \geq 0$ and $n \in \mathbb{Z}_+$) in the following discussions. $\sqrt[n]{x}$ will be rigorously constructed in Exp. 7.108, whose proof does not rely on the results of this section.

Proposition 4.17 (Root test). Let $\sum_{n=1}^{\infty} v_n$ be a series in a Banach space V . Let $\beta = \limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n\|}$. Then:

1. If $\beta < 1$, then $\sum v_n$ converges absolutely, and hence converges in V .
2. If $\beta > 1$, then $\sum v_n$ diverges in V .

Proof. Suppose $\beta < 1$. Then we can choose γ such that $\beta < \gamma < 1$. So $\limsup \sqrt[n]{\|v_n\|} < \gamma$. By Rem. 3.8, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$, we have $\sqrt[n]{\|v_n\|} < \gamma$, and hence $\|v_n\| < \gamma^n$. Since $\sum_{n=0}^{\infty} \gamma^n = (1 - \gamma)^{-1} < +\infty$ (Exp. 4.11), the series $\sum_{n=N}^{\infty} v_n$ converges absolutely by Prop. 4.7. So the original series converges absolutely.

Assume that $\beta > 1$. Then by Rem. 4.16, for each N there is $n \geq N$ such that $\sqrt[n]{\|v_n\|} > 1$ and hence $\|v_n - 0\| > 1$. So $v_n \not\rightarrow 0$. So $\sum v_n$ diverges by Prop. 4.3. \square

Example 4.18. Let $V = \mathbb{R}$ and $v_n = 1/n$ resp. $v_n = 1/n^2$. Then $\beta = 1$, and $\sum v_n$ diverges resp. converges absolutely due to Exe. 4.13. So Root test gives no information on the convergence of series when $\beta = 1$. The same can be said about ratio test.

Proposition 4.19 (Ratio test). Let $\sum_{n=1}^{\infty} v_n$ be a series in a Banach space V such that $v_n \neq 0$ for all n . Let $\alpha = \liminf_{n \rightarrow \infty} \frac{\|v_{n+1}\|}{\|v_n\|}$ and $\beta = \limsup_{n \rightarrow \infty} \frac{\|v_{n+1}\|}{\|v_n\|}$. Then:

1. If $\beta < 1$, then $\sum v_n$ converges absolutely, and hence converges in V .
2. If $\alpha > 1$, then $\sum v_n$ diverges in V .

Proof. Suppose $\beta < 1$. Choose γ such that $\beta < \gamma < 1$. Then by Rem. 4.16, there is N such that for all $n \geq N$ we have $\|v_{n+1}\|/\|v_n\| < \gamma$. So $\|v_n\| < \gamma^{n-N}\|v_N\|$. So $\sum_{n \geq N} \|v_n\| \leq \|v_N\| \cdot \sum_{n \geq N} \gamma^{n-N} = \|v_N\| \cdot (1 - \gamma)^{-1} < +\infty$. So $\sum v_n$ converges absolutely.

Suppose $\alpha > 1$. Then by Rem. 4.16, there is N such that for all $n \geq N$ we have $\|v_{n+1}\|/\|v_n\| > 1$. So $\|v_n\| \geq \|v_N\| > 0$ for all $n \geq N$. So $v_n \not\rightarrow 0$ and hence $\sum v_n$ diverges, as in the proof of root test. \square

Definition 4.20. A **power series** in a complex Banach space V is an expression of the form $\sum_{n=0}^{\infty} v_n z^n$ where the **coefficients** v_0, v_1, v_2, \dots are elements of V , and z is a **complex variable**, i.e., a symbol which can take arbitrary values in \mathbb{C} . If the power series $\sum v_n z^n$ converges at $z_0 \in \mathbb{C}$, we often let $\sum v_n z_0^n$ denote this limit.

Proposition 4.21. Let $\sum v_n z^n$ be a power series in a complex Banach space V . Then there is a unique $0 \leq R \leq +\infty$ satisfying the following properties:

- (a) If $z \in \mathbb{C}$ and $|z| < R$, then $\sum v_n z^n$ converges absolutely in V .
- (b) If $z \in \mathbb{C}$ and $|z| > R$, then $\sum v_n z^n$ diverges in V .

Such R is called the **radius of convergence** of $\sum v_n z^n$. Moreover, we have

$$R = \frac{1}{\limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n\|}} = \liminf_{n \rightarrow \infty} \frac{1}{\sqrt[n]{\|v_n\|}} \quad (4.8)$$

Proof. Clearly, there are at most one R satisfying (a) and (b). Let us define R using (4.8) (note that the second and the third terms of (4.8) are clearly equal), and prove that R satisfies (a) and (b). Let

$$\beta(z) = \limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n z^n\|}$$

Then $\beta(z) = |z|/R$. So (a) and (b) follow immediately from root test. \square

Remark 4.22. Note that if one can find $0 \leq r \leq R$ such that $\sum v_n z^n$ converges whenever $|z| < r$, then $r \leq R$ where R is the radius of convergence: otherwise, the series diverges for any positive z satisfying $R < z < r$, impossible.

It follows that if $\sum v_n z^n$ converges for all $|z| < r$, then $\sum v_n z^n$ converges *absolutely* for all $|z| < r$. \square

Prop. 4.21 provides a useful method for computing limits of a positive sequence:

Proposition 4.23. *Let (λ_n) be a sequence in $\mathbb{R}_{>0}$. Then*

$$\liminf_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \leq \liminf_{n \rightarrow \infty} \sqrt[n]{\lambda_n} \leq \limsup_{n \rightarrow \infty} \sqrt[n]{\lambda_n} \leq \limsup_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \quad (4.9)$$

In particular, (by Cor. 3.18) we have

$$\lim_{n \rightarrow \infty} \sqrt[n]{\lambda_n} = \lim_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \quad (4.10)$$

provided that the limit on the RHS of (4.10) exists in $\overline{\mathbb{R}}$.

The four numbers in (4.9) can be completely different. See [Rud-P, Exp. 3.35].

Proof. Let R be the radius of convergence of $\sum \lambda_n z^n$. Then $R = 1/\limsup \sqrt[n]{\lambda_n}$ by (4.10). Thus, by Prop. 4.21, if $|z| > R$ then $\sum \lambda_n z^n$ diverges, and hence $\limsup |\lambda_{n+1} z^{n+1}|/|\lambda_n z^n| \geq 1$ by ratio test. Therefore,

$$|z| > \frac{1}{\limsup \sqrt[n]{\lambda_n}} \implies |z| \cdot \limsup \frac{\lambda_{n+1}}{\lambda_n} \geq 1$$

This proves

$$\limsup \sqrt[n]{\lambda_n} \leq \limsup \frac{\lambda_{n+1}}{\lambda_n}$$

Replacing λ_n by λ_n^{-1} , we get

$$\frac{1}{\liminf \sqrt[n]{\lambda_n}} = \limsup \sqrt[n]{\lambda_n^{-1}} \leq \limsup \frac{\lambda_n}{\lambda_{n+1}} = \frac{1}{\liminf \frac{\lambda_{n+1}}{\lambda_n}}$$

This proves (4.9). □

Example 4.24. Let $a \in \mathbb{R}_{>0}$ and $p \in \mathbb{Z}$. The following formulas follow immediately from Prop. 4.23 (especially, from (4.10)):

$$\lim_{n \rightarrow \infty} \sqrt[n]{a} = 1 \quad (4.11a)$$

$$\lim_{n \rightarrow \infty} \sqrt[n]{n!} = +\infty \quad (4.11b)$$

$$\lim_{n \rightarrow \infty} \sqrt[n]{n^p} = 1 \quad (4.11c)$$

Note that (4.11c) follows from

$$\lim_{n \rightarrow \infty} \left(\frac{n}{n+1} \right)^p = 1 \quad (4.11d)$$

(This is clearly true when $p = \pm 1$, and hence is true for any p by induction.) By (4.11c), the radius of convergence of $\sum_n n^p z^n$ is 1. Therefore, by Prop. 4.21, $\sum n^p A^{-n}$ converges absolutely when $A > 1$. Thus, by Prop. 4.3,

$$\lim_{n \rightarrow \infty} \frac{n^p}{A^n} = 0 \quad (\text{if } A > 1) \quad (4.11e)$$

This means that “polynomials grow slower than exponentials”.

The same conclusions hold for arbitrary $p \in \mathbb{R}$ once we know how to define x^p and prove the continuity of $x \in \mathbb{R}_{>0} \mapsto x^p$. (See Sec. 7.8.) \square

★ **Exercise 4.25.** Prove (4.11a) directly. Then use (4.11a) to give a direct proof of Prop. 4.23. Do not use root test, ratio test, or any results about power series.

Definition 4.26. By (4.11b), the power series

$$\exp(z) \equiv e^z = \sum_{n=0}^{\infty} \frac{z^n}{n!}$$

has radius of convergence $+\infty$, and hence converges absolutely on \mathbb{C} . (In particular, $\lim_{n \rightarrow \infty} z^n/n! = 0$ for all $z \in \mathbb{C}$.) This gives a function $\exp : \mathbb{C} \rightarrow \mathbb{C}$, called the **exponential function**.

Part (a) of Prop. 4.21 can be strengthened in the following way.

Theorem 4.27. Let $\sum v_n z^n$ be a power series with coefficients in a complex Banach space V . Let R be its radius of convergence, and assume that $0 < R \leq +\infty$. For each $z \in B_{\mathbb{C}}(0, R)$, let $f(z)$ denote the value of this series at z (which is an element of V). Then $f : B_{\mathbb{C}}(0, R) \rightarrow V$ is continuous. Moreover, for each $0 < \rho < R$, the series of functions $\sum v_n z^n$ converges uniformly on $\overline{B}_{\mathbb{C}}(0, \rho)$ to f .

Note that by calling $\sum v_n z^n$ a series of functions, we understand each term $v_n z^n$ as a function $\mathbb{C} \rightarrow V$.

Proof. For each $0 < \rho < R$, let $X_\rho = \overline{B}_{\mathbb{C}}(0, \rho)$. Then X_ρ is clearly a bounded closed subset of \mathbb{C} , and hence is sequentially compact by Heine-Borel Thm. 3.55. Let $g_n = v_n z^n$, which is a continuous function $X_\rho \rightarrow V$. We view g_n as an element of the Banach space (cf. Cor. 3.50) $C(X_\rho, V)$. Then $\|g_n\|_\infty = \rho^n \|v_n\|$. Thus

$$\limsup_{n \rightarrow \infty} \sqrt[n]{\|g_n\|_\infty} = \limsup_{n \rightarrow \infty} \rho \sqrt[n]{\|v_n\|} = \rho/R < 1$$

Therefore, by root test, the series $\sum g_n$ converges in the Banach space $C(X_\rho, V)$ to some $f_\rho \in C(X_\rho, V)$.

We have proved that for each $0 < \rho < R$, the series of functions $\sum v_n z^n$ converges uniformly on X_ρ to a continuous function f_ρ . Let $f : B_{\mathbb{C}}(0, R) \rightarrow V$ whose value at each z is the value of the original series at z . Thus, if $|z| \leq \rho$, then

$f_\rho(z) = f(z)$. Namely, $f|_{X_\rho} = f_\rho$. This shows that $\sum v_n z^n$ converges uniformly on X_ρ to f . It also shows that $f|_{B_{\mathbb{C}}(0, \rho)}$ is continuous (because f_ρ is continuous). Therefore, since $B_{\mathbb{C}}(0, R)$ is covered by all open disks $B_{\mathbb{C}}(0, \rho)$ (where $0 < \rho < R$), we conclude from Lem. 2.41 that f is continuous on $B_{\mathbb{C}}(0, R)$. \square

Example 4.28. By Thm. 4.27, the exponential function $\exp : \mathbb{C} \rightarrow \mathbb{C}$ is continuous; moreover, $\sum_{n=0}^{\infty} z^n/n!$ converges uniformly to e^z on $\overline{B_{\mathbb{C}}}(0, R)$ for every $0 < R < +\infty$, and hence on every bounded subset of \mathbb{C} .

4.4 Problems and supplementary material

Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 4.1. Let W be a normed vector space. Prove that W is complete iff every absolutely convergent series in W is convergent (i.e. if $\sum_{n=1}^{\infty} \|w_n\| < +\infty$ then $\sum_{n=1}^{\infty} w_n$ converges).

Hint. “ \Rightarrow ” was proved in Prop. 4.7. To prove “ \Leftarrow ”, for each Cauchy sequence (w_n) in W , choose a subsequence (w_{n_k}) such that $\|w_{n_k} - w_{n_{k+1}}\| \leq 2^{-k}$. Apply Thm. 3.23. \square

Problem 4.2. Use the following discrete version of “integration by part”

$$\sum_{k=m+1}^n f_k g_k = F_n g_n - F_m g_m + \sum_{k=m}^{n-1} F_k (g_k - g_{k+1}) \quad (4.12)$$

(where $F_n = \sum_{j=1}^n f_j$) to prove the following Dirichlet’s test.

Theorem 4.29 (Dirichlet’s test). Let X be a set. Assume that (f_n) is a sequence in $l^\infty(X, V)$ such that $\sup_{n \in \mathbb{Z}_+} \|F_n\|_{l^\infty} < +\infty$ (where $F_n = \sum_{j=1}^n f_j$). Assume that (g_n) is a decreasing sequence (i.e. $g_1 \geq g_2 \geq g_3 \geq \dots$) in $l^\infty(X, \mathbb{R}_{\geq 0})$ converging uniformly to 0. Then $\sum_{n=1}^{\infty} f_n g_n$ converges uniformly on X .

Problem 4.3. Let $e_n : \mathbb{R} \rightarrow \mathbb{C}$ be $e_n(x) = e^{inx} = \cos(nx) + i \sin(nx)$. Show that for each $x \in \mathbb{R}$, $\sum_{n=1}^{\infty} e_n(x)/n$ does not converge absolutely. Use Dirichlet’s test to show that the series of functions $\sum_{n=1}^{\infty} e_n/n$ converges pointwise on $\mathbb{R} \setminus \{2k\pi : k \in \mathbb{Z}\}$, and uniformly on $[\delta, 2\pi - \delta]$ for every $0 < \delta < \pi$.

5 Nets and discrete integrals

5.1 Introduction: why do we need nets?

Nets were introduced by Moore and Smith in 1922 as a generalization of sequences. The most well-known motivation for introducing nets is that sequences are not enough for the study of non-metrizable topological spaces (i.e. topological spaces whose topologies are not induced by metrics). Here are two examples:

- In a general topological space, the definition of continuous maps using sequential convergence (as in Def. 2.38-(1)) is weaker than the definition using interior points and open sets (as in Def. 2.38-(2')), see also Rem. 4.23). Therefore, the dynamic intuition of sequences is not equivalent to the static intuition of open sets.
- Some important topological spaces are compact (i.e. every open cover has a finite subcover) but not sequentially compact. $[0, 1]^I$ (where I is uncountable), equipped with the “product topology” (i.e. “pointwise convergence topology”), is such an example.

As we shall see, nets provide a remedy for these issues: For a general topological space, the definition of continuity using net convergence is equivalent to that using open sets; compactness is equivalent to “net-compactness”, where the latter means that every net has a convergent subnet. Thus, by generalizing sequences to nets, the dynamic intuition and the static and geometric intuition are unified again.

Nevertheless, the most common topological spaces appearing in analysis are metrizable. This raises the question: Why should we care about nets, given that our primary interest is in metrizable topological spaces? Here is my answer: Even though we are mainly interested in metrizable spaces, we can still find nets helpful in the following aspects.

First of all, many convergence processes cannot be described by sequential convergence, but can be described by net convergence. For example, the following limits can be formulated and understood in the language of net convergence:

- (1) The limit of a function $\lim_{x \rightarrow x_0} f(x)$ where $f : X \rightarrow Y$ is a map of metric spaces and $x_0 \in X$.
- (2) The limit $\lim_{m, n \rightarrow \infty} a_{m, n}$ where $(a_{m, n})_{m, n \in \mathbb{Z}_+}$ is a **double sequence** in a metric space X . Note that this is not the same as (but is more natural than) the **iterated limit** $\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} a_{m, n}$. Moreover, the limit $\lim_{m, n \rightarrow \infty} a_{m, n}$ is the key to understanding the problem of commutativity of iterated integrals:

$$\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} a_{m, n} \stackrel{?}{=} \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} a_{m, n}$$

- (3) The Riemann integral $\int_a^b f(x)dx$. This is the limit of the Riemann sum $\lim \sum f(\xi_i)(a_i - a_{i-1})$ as the partition of the interval $[a, b]$ is getting finer and finer.

Moreover, as for (3), we shall see that the net version of Cor. 3.18 provides a quick and conceptual proof of the following fact: If the upper and lower Darboux integrals are equal, then the Riemann integral exists and are equal to the two Darboux integrals. Indeed, the upper and lower Darboux integrals are respectively the \limsup and \liminf of a net in \mathbb{R} .

Second, nets provide a conceptual solution to many problems about **double series**. Let $(a_{m,n})_{m,n \in \mathbb{Z}_+}$ be a double sequence in \mathbb{R} . Think about the following questions, which arise naturally when one is trying to prove $e^z e^w = e^{z+w}$.

- (a) When is it true that $\sum_{n=1}^{\infty} \sum_{m=1}^{\infty} a_{m,n} = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} a_{m,n}$?
- (b) Since $\text{card}(\mathbb{Z}_+ \times \mathbb{Z}_+) = \text{card}(\mathbb{Z}_+)$, why not use an ordinary series to study a double series? So let us **parametrize** $\mathbb{Z}_+ \times \mathbb{Z}_+$ by \mathbb{Z}_+ : choose a bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+ \times \mathbb{Z}_+$. When is it true that $\sum_{k=1}^{\infty} a_{\varphi(k)} = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} a_{m,n}$?
- (c) Choose another parametrization (i.e. bijection) $\psi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+ \times \mathbb{Z}_+$. When is it true that $\sum_{k=1}^{\infty} a_{\varphi(k)} = \sum_{k=1}^{\infty} a_{\psi(k)}$?
- (d) More generally, let X be a countably infinite set, and let $f : X \rightarrow \mathbb{R}$. Intuitively, we can take an infinite sum $\sum_{x \in X} f(x)$. How to define it rigorously? One may think about choosing a parametrization, i.e., a bijection $\varphi : \mathbb{Z}_+ \rightarrow X$. Then one defines the infinite sum by $\sum_{k=1}^{\infty} f(\varphi(k))$. Is this definition independent of the choice of parametrization?
- (e) As a special case of (d), when is a series invariant under **rearrangement**? Namely, choose a bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$, and choose a sequence (a_n) in \mathbb{R} , when is it true that $\sum_{n=1}^{\infty} a_n = \sum_{n=1}^{\infty} a_{\varphi(n)}$?

Modern differential geometry (whose “intrinsic” spirit stems from Gauss’s Theorema Egregium) teaches us that in order to answer these questions, one should first define the infinite sum $\sum_{x \in X} f(x)$ in a parametrization-independent way. (The reason we call a bijection $\varphi : \mathbb{Z}_+ \rightarrow X$ a parametrization is that we want the readers to compare it with the parametrizations of curves, surfaces, and more generally manifolds.) We will call this sum a **discrete integral**. Then, one tries to answer when this definition agrees with those that depend on parametrizations

(such as the sums in (a)-(e) above). These goals can be achieved with the help of nets.

5.2 Nets

5.2.1 Directed sets and nets

Definition 5.1. A relation \leq on a set I is called a **preorder** if for all $\alpha, \beta, \gamma \in I$, the following are satisfied:

- (Reflexivity) $\alpha \leq \alpha$.
- (Transitivity) If $\alpha \leq \beta$ and $\beta \leq \gamma$ then $\alpha \leq \gamma$.

The pair (I, \leq) (or simply I) is called a **preordered set**.

Therefore, a partial order is a preorder satisfying antisymmetry: $(\alpha \leq \beta) \wedge (\beta \leq \alpha) \Rightarrow (\alpha = \beta)$.

Definition 5.2. A preordered set (I, \leq) is called a **directed set** if

$$\forall \alpha, \beta \in I \quad \exists \gamma \in I \quad \text{such that } \alpha \leq \gamma, \beta \leq \gamma \quad (5.1)$$

If I is a directed set and X is a set, then a function $x : I \rightarrow X$ is called a **net** with directed set/index set I . We often write $x(\alpha)$ as x_α if $\alpha \in I$, and write x as $(x_\alpha)_{\alpha \in I}$.

Example 5.3. (\mathbb{Z}_+, \leq) is a directed set. A net with index set \mathbb{Z}_+ in a set X is precisely a sequence in X .

Definition 5.4. Suppose that (I, \leq_I) and (J, \leq_J) are preordered set (resp. directed set), then the **product** $(I \times J, \leq)$ is a preordered set (resp. directed set) if for every $\alpha, \alpha' \in I, \beta, \beta' \in J$ we define

$$(\alpha, \beta) \leq (\alpha', \beta') \iff \alpha \leq_I \alpha' \text{ and } \beta \leq_J \beta' \quad (5.2)$$

Unless otherwise stated, the preorder on $I \times J$ is assumed to be defined by (5.2).

Example 5.5. $\mathbb{Z}_+ \times \mathbb{Z}_+$ (or similarly, $\mathbb{N} \times \mathbb{N}$) is naturally a directed set whose preorder is defined by (5.2). A net $(x_{m,n})_{(m,n) \in \mathbb{Z}_+ \times \mathbb{Z}_+}$ with index set $\mathbb{Z}_+ \times \mathbb{Z}_+$ is called a **double sequence** and is written as $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ or simply $(x_{m,n})$. (We will even write it as (x_{mn}) when no confusion arises.)

More generally, we call $(x_{\alpha,\beta})_{(\alpha,\beta) \in I \times J} = (x_{\alpha,\beta})_{\alpha \in I, \beta \in J}$ a **double net** if its index set is $I \times J$ for some directed sets I, J . \square

Example 5.6. If X is a set, then $(2^X, \subset)$ and $(\text{fin}(2^X), \subset)$ are directed sets where

$$\text{fin}(2^X) = \{A \subset X : A \text{ is a finite set}\} \quad (5.3)$$

We will use nets with index set $\text{fin}(2^X)$ to study infinite sums.

Example 5.7. Let X be a metric space and $x \in X$. Then $X_x = (X, \leq)$ is a directed set if for each $p_1, p_2 \in X$ we define

$$p_1 \leq p_2 \text{ in } X_x \iff d(p_1, x) \geq d(p_2, x) \quad (5.4)$$

(Namely, a larger element of X_x is one closer to x .) Nets with this directed set can be used to study the limits of functions (cf. Rem. 7.83). Note that X_x is our first example of directed set which is not a poset! ($d(p_1, x) = d(p_2, x)$ does not imply $p_1 = p_2$.)

5.2.2 Limits of nets

If I is an preordered set and $\beta \in I$, we write

$$I_{\geq \beta} = \{\alpha \in I : \alpha \geq \beta\} \quad (5.5)$$

Definition 5.8. Let P be a property about elements of a set X , i.e., P is a function $X \rightarrow \{\text{true}, \text{false}\}$. Let $(x_\alpha)_{\alpha \in I}$ be a net in X .

We say that x_α **eventually** satisfies P (equivalently, we say that x_α satisfies P for **sufficiently large** α) if:

- There exists $\beta \in I$ such that for every $\alpha \in I_{\geq \beta}$, the element x_α satisfies P .

“Sufficiently large” is also called “**large enough**”.

We say that x_α **frequently** satisfies P if:

- For every $\beta \in I$ there exists $\alpha \in I_{\geq \beta}$ such that x_α satisfies P .

□

Remark 5.9. Note that unlike sequences, for a general net, “ x_α eventually satisfies P ” does not imply “all but finitely many x_α satisfy P ” because the complement of $I_{\geq \beta}$ is not necessarily a finite set.

Remark 5.10. Let P and Q be two properties about elements of X . Then

$$\neg(x_\alpha \text{ eventually satisfies } P) = (x_\alpha \text{ frequently satisfies } \neg P) \quad (5.6a)$$

By the crucial condition (5.1) for directed sets, we have

$$\begin{aligned} (x_\alpha \text{ eventually satisfies } P) \wedge (x_\alpha \text{ eventually satisfies } Q) \\ \Downarrow \\ x_\alpha \text{ eventually satisfies } P \wedge Q \end{aligned} \quad (5.6b)$$

By taking contraposition and replacing P, Q by $\neg P, \neg Q$, we have

$$\begin{aligned} x_\alpha \text{ frequently satisfies } P \vee Q \\ \Downarrow \\ (x_\alpha \text{ frequently satisfies } P) \vee (x_\alpha \text{ frequently satisfies } Q) \end{aligned} \quad (5.6c)$$

Definition 5.11. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space X . Let $x \in X$. We say that (x_α) **converges to** x and write

$$\lim_{\alpha \in I} x_\alpha \equiv \lim_{\alpha} x_\alpha = x$$

or simply $x_\alpha \rightarrow x$ if the following statement holds:

- For every $\varepsilon > 0$, x_α is eventually in $B_X(x, \varepsilon)$.

Clearly, $x_\alpha \rightarrow x$ iff $d(x_\alpha, x) \rightarrow 0$.

Definition 5.12. Let $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ be a double sequence in a metric space. Then we write

$$\lim_{(m,n) \in \mathbb{Z}_+ \times \mathbb{Z}_+} x_{m,n} \equiv \lim_{m,n \rightarrow \infty} x_{m,n} \quad (5.7)$$

and call it the **(double) limit** of $(x_{m,n})$.

Remark 5.13. Let us spell out the meaning of $\lim_{m,n \rightarrow \infty} x_{m,n} = x$: For each $\varepsilon > 0$ there exists $M, N \in \mathbb{Z}_+$ such that $d(x_{m,n}, x) < \varepsilon$ for all $m \geq M$ and $n \geq N$. Clearly, this is equivalent to the statement:

- For each $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that $d(x_{m,n}, x) < \varepsilon$ for all $m, n \geq N$.

Therefore, if (x_n) is a sequence in X , then

$$(x_n) \text{ is a Cauchy sequence} \iff \lim_{m,n \rightarrow \infty} d(x_m, x_n) = 0 \quad (5.8)$$

Thus, the Cauchy-ness of sequences can be studied in terms of double limits, and hence in terms of nets.

Proposition 5.14. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space X converging to x, y . Then $x = y$.

Proof. Suppose that $x \neq y$. Then there are $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$, say $r = \rho = d(x, y)/2$. Since $x_\alpha \rightarrow x$, the point x_α is eventually in $B(x, r)$. Since $x_\alpha \rightarrow y$, the point x_α is eventually in $B(y, \rho)$. Therefore, by the logic (5.6b), x_α is eventually in $B(x, r) \cap B(y, \rho)$, impossible. \square

Theorem 5.15. Let $f : X \rightarrow Y$ be map of metric spaces continuous at $x \in X$. Let $(x_\alpha)_{\alpha \in I}$ be a net in X converging to x . Then $\lim_{\alpha} f(x_\alpha) = f(x)$.

Proof. Choose any $\varepsilon > 0$. By Def. 2.38-(2) and the continuity of f at x , there exists $\delta > 0$ such that for all $p \in B(x, \delta)$ we have $f(p) \in B(f(x), \varepsilon)$. Since $x_\alpha \rightarrow x$, x_α is eventually in $B(x, \delta)$. Therefore $f(x_\alpha)$ is eventually in $B(f(x), \varepsilon)$. \square

This theorem implies, for example, that if (v_α) is a net in a complex normed vector space converging to v , and if (λ_α) is a net in \mathbb{C} converging to λ , then $\lambda_\alpha v_\alpha$ converges to λv because the scalar multiplication map is continuous (Prop. 3.38).

Exercise 5.16. Prove the generalization of Rem. 2.71:

1. If $(x_\alpha)_{\alpha \in I}, (y_\alpha)_{\alpha \in I}$ are nets in $\overline{\mathbb{R}}$ converging to $A, B \in \overline{\mathbb{R}}$, and if $x_\alpha \leq y_\alpha$ for all α , then $A \leq B$.
2. **Squeeze theorem:** Suppose that $(x_\alpha)_{\alpha \in I}, (y_\alpha)_{\alpha \in I}, (z_\alpha)_{\alpha \in I}$ are nets in $\overline{\mathbb{R}}$, $x_\alpha \leq y_\alpha \leq z_\alpha$ for all α , and x_α and z_α both converge to $A \in \overline{\mathbb{R}}$. Then $y_\alpha \rightarrow A$.
3. If (x_α) is an increasing resp. decreasing net in $\overline{\mathbb{R}}$, then $\lim_\alpha x_\alpha$ exists in $\overline{\mathbb{R}}$ and equals $\sup_\alpha x_\alpha$ resp. $\inf_\alpha x_\alpha$.

5.2.3 Subnets (in the sense of Willard)

Definition 5.17. A subset E of a directed set I is called **cofinal** if:

$$\forall \alpha \in I \quad \exists \beta \in E \quad \text{such that } \alpha \leq \beta$$

By the transitivity in Def. 5.1 and property (5.1), we clearly have

$$\forall \alpha_1, \dots, \alpha_n \in I \quad \exists \beta \in E \quad \text{such that } \alpha_1 \leq \beta, \dots, \alpha_n \leq \beta$$

Definition 5.18. Let $(x_\alpha)_{\alpha \in I}$ be a net in a set X . A **subnet** of $(x_\alpha)_{\alpha \in I}$ is, by definition, of the form $(x_{\alpha_s})_{s \in S}$ where S is a directed set, and

$$(\alpha_s)_{s \in S} : S \rightarrow I \quad s \mapsto \alpha_s$$

is an increasing function whose range $\{\alpha_s : s \in S\}$ is cofinal in I .

Remark 5.19. There are several different definitions of subnets that are equivalent for proving the main results in point-set topology. Unfortunately, there is no common agreement on the standard definition of subnets. The definition we gave is due to Willard [Wil], and is also the one given in the famous textbook of Munkres [Mun]. Some famous analysis and topology textbooks (e.g. [?, Kel, RS]) use a weaker definition, which does not assume that the map $S \rightarrow I$ is increasing.

Example 5.20. A subsequence of a sequence is a subnet of that sequence.

Example 5.21. Let $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ be a net with index set $\mathbb{Z}_+ \times \mathbb{Z}_+$. Then $(x_{k,k})_{k \in \mathbb{Z}_+}$ and $(x_{2k,k})_{k \in \mathbb{Z}_+}$ are subnets. $(x_{k,1})_{k \in \mathbb{Z}_+}$ is not a subnet, because the cofinal condition is not satisfied. More generally, it is not hard to show that for every function $\varphi, \psi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$, $(x_{\varphi(k), \psi(k)})_{k \in \mathbb{Z}_+}$ is a subnet iff φ, ψ are increasing and $\lim_{k \rightarrow \infty} \varphi(k) = \lim_{k \rightarrow \infty} \psi(k) = +\infty$.

Exercise 5.22. Prove the following facts:

- The cofinal subset of a cofinal subset of a directed set I is a cofinal subset of I .
- The subnet of a subnet of a net (x_α) is a subnet of (x_α) .

Note that in your proof you need to use the transitivity in Def. 5.1.

The biggest difference between subnets and subsequences is that the index set of a subnet is not necessarily a subset of the index set of the original net. Indeed, subnets are defined in this way mainly because we want to have a net version of Pb. 3.1 in any topological space. (This will be achieved in Pb. 7.2.) Let us see an elementary example of subnet whose index set is larger than that of the original net. Its importance is justified by the proofs of Exp. 5.28 and Prop. 5.34.

Example 5.23. Let J be a directed set. Then every net $(x_\alpha)_{\alpha \in I}$ has subnet $(x_\alpha)_{(\alpha, \beta) \in I \times J}$. The corresponding increasing map of directed sets is the projection $I \times J \rightarrow I$ onto the first component.

To appreciate the importance of cofinality (as well as transitivity), we prove the following generalization of Prop. 2.36. This result has a wide range of surprising applications that are unavailable when one only considers sequences. (We will see them soon in this chapter. For instance, this result explains why the values of absolutely convergent series are invariant under rearrangement.) So I call this result a theorem, even though its proof is simple.

Theorem 5.24. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space (or more generally, a topological space) X converging to $x \in X$. Then every subnet $(x_{\alpha_s})_{s \in S}$ converges to x .

The following proof for metric spaces can be generalized straightforwardly to topological spaces. The readers can come back and check the details after learning topological spaces.

Proof. Choose any $\varepsilon > 0$. Since $x_\alpha \rightarrow x$, there exists $\beta \in I$ such that for all $\alpha \geq \beta$ we have $d(x_\alpha, x) < \varepsilon$. By the cofinality, there exists $t \in S$ such that $\alpha_t \geq \beta$. Thus, since $s \in S \mapsto \alpha_s \in I$ is increasing, for every $s \geq t$, we have $\alpha_s \geq \alpha_t \geq \beta$ and hence $\alpha_s \geq \beta$ by the transitivity in Def. 5.1. So $d(x_{\alpha_s}, x) < \varepsilon$ for all $s \geq t$. This finishes the proof. \square

This proposition does not hold if one does not assume cofinality in the definition of subnets:

Example 5.25. Let (x_n) be a sequence in \mathbb{R} converging to $x \in \mathbb{R}$. Since (x_n) is a Cauchy sequence, we know that $\lim_{m, n \rightarrow \infty} x_m - x_n = 0$. We have seen in Exp. 5.21 that $(x_{2k} - x_k)_{k \in \mathbb{Z}_+}$ is a subnet of $(x_{m, n})$. Therefore, $\lim_{k \rightarrow \infty} x_{2k} - x_k = 0$. But

$(x_k - x_1)_{k \in \mathbb{Z}_+}$ is not a subnet since the cofinal condition is not satisfied. And if $x \neq x_1$, then $\lim_k (x_k - x_1) = x - x_1 \neq 0$, i.e.,

$$\lim_{k \rightarrow \infty} (x_k - x_1) \neq \lim_{m, n \rightarrow \infty} (x_m - x_n)$$

In Subsec. 2.3.2, we have seen two criteria for the divergence of sequence: a sequence diverges if it is unbounded, or if it has two subsequences converging to different points. By Thm. 5.24, the second criterion can be generalized to nets. However, the following example shows that the first criterion does not have its net version:

Example 5.26. A convergent net $(x_\alpha)_{\alpha \in I}$ in a metric space X is not necessarily **bounded**. Namely, it is not necessarily true that $\{x_\alpha : \alpha \in I\}$ is a bounded subset of X . Let $f : \mathbb{R}_{>0} \rightarrow \mathbb{R}$ be $f(x) = 1/x$. Then f is net in \mathbb{R} with directed set $(\mathbb{R}_{>0}, \leq)$. This net is not bounded, although $\lim f(x) = 0$.

Example 5.27. The double sequence $x_{m,n} = n/(m+n)$ in \mathbb{R} has subnets $x_{n,n} = n/(n+n) = 1/2$ and $x_{2n,n} = 1/3$. Since these two subnets converge to different values, Thm. 5.24 implies that $\lim_{m,n} x_{m,n}$ does not exist. However, the **iterated limits** exist and take different values:

$$\lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{n}{m+n} = 1 \quad \lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} \frac{n}{m+n} = 0$$

As we shall see, this gives another criterion for the divergence of double series: If the two iterated limits exist and are different, then the double series diverge.

Finally, we do an example of convergent double sequence:

Example 5.28. Let $x_{m,n} = (m^{-2} - n^{-1}) \sin \frac{\pi(m + \sqrt{n})}{4}$. Then $\lim_{m,n \rightarrow \infty} x_{m,n} = 0$.

Proof. The sequence $(m^{-2})_{m \in \mathbb{Z}_+}$ converges to 0. By Exp. 5.23, the double sequence $(m^{-2})_{m,n \in \mathbb{Z}_+}$ is its subnet, and hence converges to 0 by Thm. 5.24. Similarly, the double sequence $(n^{-1})_{m,n \in \mathbb{Z}_+}$ converges to 0. Therefore, $m^{-2} + n^{-1}$ converges to 0 due to Thm. 5.15 and the continuity of the addition map $(x, y) \in \mathbb{R} \rightarrow x + y \in \mathbb{R}$ (Prop. 2.45). Since $0 \leq |x_{m,n}| \leq m^{-2} + n^{-1}$, we conclude $|x_{m,n}| \rightarrow 0$ (and hence $x_{m,n} \rightarrow 0$) by squeeze theorem (Exe. 5.16). \square

5.2.4 Double limits and iterated limits

Theorem 5.29. Let $(x_{\alpha,\beta})_{\alpha \in I, \beta \in J}$ be a double net in a metric space X . Assume that the following are true:

- (1) The limit $\lim_{(\alpha,\beta) \in I \times J} x_{\alpha,\beta}$ exists in X .

(2) For each $\alpha \in I$, the limit $\lim_{\beta \in J} x_{\alpha, \beta}$ exists in X .

Then the LHS limit in the following equation exists and equals the RHS:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{(\alpha, \beta) \in I \times J} x_{\alpha, \beta} \quad (5.9)$$

In particular, suppose that the following is also true:

(3) For each $\beta \in J$, the limit $\lim_{\alpha \in I} x_{\alpha, \beta}$ exists in X .

Then the following limits exist and are equal:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{\beta \in J} \lim_{\alpha \in I} x_{\alpha, \beta} \quad (5.10)$$

Proof. Let $x_\alpha = \lim_{\beta} x_{\alpha, \beta}$ and $x = \lim_{\alpha, \beta} x_{\alpha, \beta}$. We want to show that $\lim_{\alpha} x_\alpha = x$. Choose any $\varepsilon > 0$. Then there exist $A \in I, B \in J$ such that for every $\alpha \geq A$ and $\beta \geq B$ we have $d(x_{\alpha, \beta}, x) < \varepsilon/3$. In particular, $d(x_{\alpha, \beta}, x) \leq \varepsilon/2$. Using Thm. 5.15 and the fact that $p \in X \mapsto d(p, x) \in \mathbb{R}$ is continuous (Exp. 2.58), we see that for every $\alpha \geq A$ we have $d(x_\alpha, x) = \lim_{\beta \in J_{\geq B}} d(x_{\alpha, \beta}, x) \leq \varepsilon/2 < \varepsilon$. \square

The readers may skip the next remark and proof and come back to them when they have learned about topological spaces.

★ **Remark 5.30.** Thm. 5.29 can be generalized to the case that X is a regular topological space. By saying that the topological space X is **regular**, we mean that for every $x \in X$ and every open set U containing x , there is a smaller open set V containing x such that the closure \overline{V} (cf. Def. 7.28) is contained in U .

★ *Proof.* Let $x_\alpha = \lim_{\beta} x_{\alpha, \beta}$ and $x = \lim_{\alpha, \beta} x_{\alpha, \beta}$. Choose any open set U containing x . We want to prove that x_α is eventually in U . Choose an open set V containing x such that $\overline{V} \subset U$. Then there are $A \in I, B \in J$ such that for all $\alpha \geq A$ and $\beta \geq B$ we have $x_{\alpha, \beta} \in V$. Thus, for each $\alpha \geq A$, since $x_{\alpha, \beta}$ approaches x_α , we have $x_\alpha \in \overline{V}$ and hence $x_\alpha \in U$. \square

Corollary 5.31. Let $(x_{\alpha, \beta})_{\alpha \in I, \beta \in J}$ be a double net in $\overline{\mathbb{R}}$. Assume that $x_{\bullet, \bullet}$ is increasing, i.e., $x_{\alpha, \beta} \leq x_{\alpha', \beta'}$ if $\alpha \leq \alpha'$ and $\beta \leq \beta'$. Then the following equation (5.11) hold, where all the limits (5.11) exist in $\overline{\mathbb{R}}$:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{\beta \in J} \lim_{\alpha \in I} x_{\alpha, \beta} = \lim_{(\alpha, \beta) \in I \times J} x_{\alpha, \beta} = \sup\{x_{\alpha, \beta} : \alpha \in I, \beta \in J\} \quad (5.11)$$

Clearly, a similar result holds for decreasing double nets in $\overline{\mathbb{R}}$.

Proof. By Exe. 5.16, the three limits $\lim_{\alpha} x_{\alpha, \beta}$, $\lim_{\beta} x_{\alpha, \beta}$, and $\lim_{\alpha, \beta} x_{\alpha, \beta}$ exist in $\overline{\mathbb{R}}$. Therefore, by Thm. 5.29, the three limits in (5.11) exist and are equal. The last equality in (5.11) is also due to Exe. 5.16. \square

5.2.5 Cauchy nets

Definition 5.32. A net $(x_\alpha)_{\alpha \in I}$ in a metric space X is called a Cauchy net if

$$\lim_{\alpha, \beta \in I} d(x_\alpha, x_\beta) = 0$$

Equivalently, this means that

$$\forall \varepsilon > 0 \quad \exists \gamma \in I \quad \text{such that } \forall \alpha, \beta \geq \gamma \quad \text{we have } d(x_\alpha, x_\beta) < \varepsilon \quad (5.12)$$

Exercise 5.33. Show that the subnet of a Cauchy net is Cauchy.

Proposition 5.34. A convergent net in a metric space is a Cauchy net.

Proof. Let $(x_\alpha)_{\alpha \in I}$ converge to x in a metric space X . Then $\lim_\alpha d(x_\alpha, x) = 0$. Since $(d(x_\alpha, x))_{\alpha, \beta \in I}$ is a subnet (cf. Exp. 5.23), we have $\lim_{\alpha, \beta} d(x_\alpha, x) = 0$ by Thm. 5.24. Similarly, we have $\lim_{\alpha, \beta} d(x, x_\beta) = 0$. Since $0 \leq d(x_\alpha, x_\beta) \leq d(x_\alpha, x) + d(x, x_\beta)$, by Squeeze theorem (Exe. 5.16) we have $\lim_{\alpha, \beta} d(x_\alpha, x_\beta) = 0$. \square

Proposition 5.35. Let $(x_\alpha)_{\alpha \in I}$ be a Cauchy net in a metric space X . Suppose that $(x_\alpha)_{\alpha \in I}$ has a convergent subnet $(x_{\alpha_s})_{s \in S}$ converging to $x \in X$. Then $(x_\alpha)_{\alpha \in I}$ converges to x .

Proof. Choose any $\varepsilon > 0$. Since (x_α) is a Cauchy net, there exists $\gamma \in I$ such that $d(x_\alpha, x_\beta) \leq \varepsilon$ for all $\alpha, \beta \geq \gamma$. Since $(\alpha_s)_{s \in S}$ has cofinal range, $\alpha_{s_0} \geq \gamma$ for some $s_0 \in S$. Thus $\alpha_s \geq \gamma$ for all $s \geq s_0$ because $(\alpha_s)_{s \in S}$ is increasing and because of the transitivity in Def. 5.1. Thus, for every $\beta \geq \gamma$, $d(x_{\alpha_s}, x_\beta) \leq \varepsilon$ for sufficiently large s . By taking limit over s and using the continuity of $y \in X \mapsto d(y, x_\beta)$ as well as Thm. 5.15, we get $d(x, x_\beta) \leq \varepsilon$ for all $\beta \geq \gamma$. \square

Definition 5.36. Two nets $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ in a metric space X are called **Cauchy-equivalent** if

$$\lim_{\alpha \in I} d(x_\alpha, y_\alpha) = 0$$

Two Cauchy nets are simply called **equivalent** if they are Cauchy-equivalent. It is not hard to see that Cauchy-equivalence is an equivalence relation (recall Def. 1.17) on X^I .

Exercise 5.37. Let $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ be nets in a metric space X .

1. Assume that $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ are Cauchy-equivalent. Prove that (x_α) is a Cauchy net iff (y_α) is a Cauchy net.
2. Assume that $(x_\alpha)_{\alpha \in I}$ converges to x . Prove that $(y_\alpha)_{\alpha \in I}$ converges to x iff $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ are Cauchy-equivalent.

Theorem 5.38. Every Cauchy net $(x_\alpha)_{\alpha \in I}$ in a complete metric space X is convergent.

We give a hint of the proof and leave the details to the readers as an exercise.

Hint. Construct an increasing sequence $(\alpha_n)_{n \in \mathbb{Z}_+}$ in I such that for every $\beta, \gamma \geq \alpha_n$ we have $d(x_\beta, x_\gamma) < 1/n$. Prove that $(x_{\alpha_n})_{n \in \mathbb{Z}_+}$ is a Cauchy sequence, and hence converges to some $x \in X$. Prove that $(x_\alpha)_{\alpha \in I}$ converges to x . (Warning: $(x_{\alpha_n})_{n \in \mathbb{Z}_+}$ is not necessarily a subnet of $(x_\alpha)_{\alpha \in I}$.) \square

5.3 Discrete integrals $\sum_{x \in X} f(x)$

In this section, we fix V to be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. We fix a (non-necessarily countable) set X . Note that if $f : X \rightarrow V$ is a function and X is finite, then $\sum_{x \in X} f(x)$ can be understood in its most obvious way.

Definition 5.39. Let $f : X \rightarrow V$ be a map. The expression

$$\sum_{x \in X} f(x)$$

(or simply $\sum_X f$) is called a **discrete integral**. If $v \in V$, we say that $\sum_{x \in X} f(x)$ equals (or converges to) v , if

$$\lim_{A \in \text{fin}(2^X)} \sum_{x \in A} f(x) = v \quad (5.13)$$

In this case, we write

$$\sum_{x \in X} f(x) = v \quad (5.14)$$

Remark 5.40. Recall from Exp. 5.6 that $\text{fin}(2^X)$ is the directed set of finite subsets of 2^X . Its preorder is “ \subset ”. So (5.14) means more precisely that:

- For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for every finite set A satisfying $B \subset A \subset X$, we have $\|v - \sum_{x \in A} f(x)\| < \varepsilon$.

Remark 5.41. Discrete integrals are one of the most important and representative examples in Moore and Smith’s original paper on nets (cf. [MS22]), explaining why nets are called nets: Imagine an infinitely large *fishing net* whose vertices form the set $X = \mathbb{Z}^2$. You grab the net with your hands and pull it up. As you pull it up, the lifted part $A \in \text{fin}(2^X)$ becomes larger and larger.

Remark 5.42. One of the advantages of discrete integrals over series is that discrete integrals are clearly invariant under rearrangement: For every bijection $\varphi : X \rightarrow X$, if one side of the following equation converges in V , then the other side converges, and the equation holds true:

$$\sum_{x \in X} f(x) = \sum_{x \in X} f(\varphi(x)) \quad (5.15)$$

or simply $\sum_X f = \sum_X f \circ \varphi$.

Remark 5.43. Let us spell out what Cauchyness means for the net $(\sum_A f)_{A \in \text{fin}(2^X)}$:

- (1) For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for any finite sets A_1, A_2 satisfying $B \subset A_1 \subset X, B \subset A_2 \subset X$, we have

$$\left\| \sum_{A_1 \setminus A_2} f - \sum_{A_2 \setminus A_1} f \right\| < \varepsilon$$

Note that the term inside the norm is $\sum_{A_1} f - \sum_{A_2} f$. This is also equivalent to:

- (2) For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for any finite set $E \subset X \setminus B$, we have

$$\left\| \sum_E f \right\| < \varepsilon$$

We shall mainly use (2) as the Cauchy criterion for the convergence of $\sum_X f$.

Proof of the equivalence. (2) follows from (1) by taking $A_1 = B$ and $A_2 = B \cup E$. (1) follows from (2) by taking $E_1 = A_1 \setminus A_2$ and $E_2 = A_2 \setminus A_1$ and then concluding $\|\sum_{E_1} f - \sum_{E_2} f\| < 2\varepsilon$. \square

Definition 5.44. Let $g : X \rightarrow \overline{\mathbb{R}}_{\geq 0}$ be a map. Note that the net $(\sum_A g)_{A \in \text{fin}(2^X)}$ is increasing. Hence, its limit exists in $\overline{\mathbb{R}}$ and equals $\sup_{A \in \text{fin}(2^X)} \sum_A g$ (by Exe. 5.16). We write this as $\sum_X g$, or more precisely:

$$\sum_X g \equiv \sum_{x \in X} g(x) \stackrel{\text{def}}{=} \lim_{A \in \text{fin}(2^X)} \sum_A g = \sup_{A \in \text{fin}(2^X)} \sum_A g \quad (5.16)$$

We say that $\sum_X g$ **converges** or **converges absolutely**, if $\sum_X g < +\infty$.

It is clear that $\sum_X g < +\infty$ iff there exists $C \in \mathbb{R}_{\geq 0}$ such that $\sum_A g < C$ for all $A \in \text{fin}(2^X)$.

Remark 5.45. Note that when $g : X \rightarrow \mathbb{R}_{\geq 0}$, the convergence in Def. 5.44 agrees with that in Def. 5.39. Therefore, Rem. 5.43 still gives a Cauchy criterion for convergence.

Definition 5.46. Let $f : X \rightarrow V$. We say that $\sum_X f$ **converges absolutely** if

$$\sum_{x \in X} \|f(x)\| < +\infty$$

Proposition 5.47. Let $f : X \rightarrow V$. If $\sum_X f$ converges absolutely, then it converges, and

$$\left\| \sum_{x \in X} f(x) \right\| \leq \sum_{x \in X} \|f(x)\| \quad (5.17)$$

We write this simply as $\|\sum_X f\| \leq \sum_X |f|$. (Recall Def. 3.39.)

Proof. (5.17) clearly holds when X is finite. In the general case, assume that $\sum_X f$ converges absolutely. Then by Cauchy criterion (Rem. 5.43-(2)), for every $\varepsilon > 0$ there is $A \in \text{fin}(2^X)$ such that for each finite $E \subset X \setminus A$ we have $\sum_E |f| < \varepsilon$, and hence $\|\sum_E f\| < \varepsilon$. Therefore $\sum_X f$ converges by Cauchy criterion again.

By the continuity of the norm function $v \in V \mapsto \|v\| \in \mathbb{R}_{\geq 0}$, and by Thm. 5.15, we have

$$\left\| \sum_X f \right\| = \left\| \lim_A \sum_A f \right\| = \lim_A \left\| \sum_A f \right\|$$

Since $\|\sum_A f\| \leq \sum_A |f|$, by Exe. 5.16, the above expression is no less than

$$\lim_A \sum_A |f| = \sum_X |f|$$

□

The following proposition gives another demonstration that discrete integrals are more natural than series. We leave the proof to the readers.

Proposition 5.48. *Let $f : X \rightarrow \mathbb{R}^N$ where $N \in \mathbb{Z}_+$. Then*

$$\sum_{x \in X} f(x) \text{ converges} \iff \sum_{x \in X} f(x) \text{ converges absolutely}$$

Hint. Reduce to the case $N = 1$. Consider $A = \{x \in X : f(x) \geq 0\}$ and $B = X \setminus A$. □

When \mathbb{R}^N is replaced by an infinite-dimensional Banach space, the convergence of a discrete integral may not imply absolute convergence. See Pb. 5.6.

5.4 Fubini's theorem for discrete integrals

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let X, Y be sets.

Theorem 5.49 (Fubini's theorem-A). *Let $f : X \times Y \rightarrow V$. Assume that $\sum_{X \times Y} f$ converges. Then $\sum_Y f(x, \cdot)$ converges for each $x \in X$, and $\sum_X f(\cdot, y)$ converges for each $y \in Y$, and*

$$\sum_{x \in X} \sum_{y \in Y} f(x, y) = \sum_{y \in Y} \sum_{x \in X} f(x, y) = \sum_{(x, y) \in X \times Y} f(x, y) \quad (5.18)$$

where all discrete integrals converge in V .

We abbreviate (5.18) to $\sum_X \sum_Y f = \sum_Y \sum_X f = \sum_{X \times Y} f$.

Proof. For each $x \in X$, let $f_x(y) = f(x, y)$. Let us prove that $\sum_Y f_x$ converges. Choose any $\varepsilon > 0$. Since $\sum_{X \times Y} f$ converges, by Cauchy criterion (Rem. 5.43-(2)), there exists a finite $S \subset X \times Y$ such that the sum of f over any finite subset outside S has norm $< \varepsilon$. The projection $X \times Y \rightarrow Y$ maps S to a finite set $B \subset Y$. Thus, for each finite $E \subset Y \setminus B$, we have $\|\sum_E f_x\| < \varepsilon$ since $x \times E$ is outside S . Therefore $\sum_Y f_x$ converges. By the same reasoning, $\sum_X f(\cdot, y)$ converges for all y .

Recall that $\sum_{X \times Y} f$ is the limit of the net $(\sum_S f)_{S \in \text{fin}(2^{X \times Y})}$. This net has subnet

$$\left(\sum_{(x,y) \in A \times B} f(x, y) \right)_{A \in \mathcal{I}, B \in \mathcal{J}} \quad \text{where } \mathcal{I} = \text{fin}(2^X) \quad \mathcal{J} = \text{fin}(2^Y)$$

(Its index set is $\mathcal{I} \times \mathcal{J}$.) Thus, by Thm. 5.24,

$$\sum_{(x,y) \in X \times Y} f(x, y) = \lim_{A \in \mathcal{I}, B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) \quad (5.19)$$

We are now going to use Thm. 5.29 to show that

$$\lim_{A \in \mathcal{I}, B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) = \lim_{A \in \mathcal{I}} \lim_{B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) \quad (5.20)$$

where the RHS limit exists. For that purpose, we need to check for each $A \in \mathcal{I}$ the convergence of $\lim_B \sum_{(x,y) \in A \times B} f(x, y)$. Since $\sum_Y f_x$ converges, we have

$$\begin{aligned} \lim_{B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) &= \lim_{B \in \mathcal{J}} \sum_{x \in A} \sum_{y \in B} f(x, y) \\ &= \sum_{x \in A} \lim_{B \in \mathcal{J}} \sum_{y \in B} f(x, y) = \sum_{x \in A} \sum_{y \in Y} f(x, y) \end{aligned} \quad (5.21)$$

(Note that \sum_A is a finite sum and hence commutes with \lim_B .) Thus, the assumption in Thm. 5.29 ensuring (5.20) has now been proved true. So (5.20) is true. Moreover, combining (5.19), (5.20), (5.21) together, we get

$$\sum_{(x,y) \in X \times Y} f(x, y) = \lim_{A \in \mathcal{I}} \sum_{x \in A} \sum_{y \in Y} f(x, y) = \sum_{x \in X} \sum_{y \in Y} f(x, y)$$

where the second and the third limits exist. This proves a half of (5.18). The other half can be proved in the same way. \square

Theorem 5.50 (Fubini's theorem-B). Let $g : X \times Y \rightarrow \overline{\mathbb{R}}_{\geq 0}$. Then the five discrete integrals in (5.22) exist in $\overline{\mathbb{R}}_{\geq 0}$, and equations (5.22) hold in $\overline{\mathbb{R}}_{\geq 0}$:

$$\sum_{x \in X} \sum_{y \in Y} f(x, y) = \sum_{y \in Y} \sum_{x \in X} f(x, y) = \sum_{(x,y) \in X \times Y} f(x, y) \quad (5.22)$$

Proof. The existence in $\overline{\mathbb{R}}_{\geq 0}$ of the five discrete integrals is clear. (Recall Def. 5.44.) Formula (5.22) can be proved in the same way as (5.18). Note that when applying Thm. 5.29 to prove (5.22), the assumption in Thm. 5.29 on the existence of limits is satisfied because all nets involved are increasing in $\overline{\mathbb{R}}$. (Recall Exe. 5.16.) \square

Corollary 5.51 (Fubini's theorem-C). *Let $f : X \times Y \rightarrow V$. Then the following are equivalent.*

- (1) $\sum_{X \times Y} f$ converges absolutely.
- (2) $\sum_{x \in X} \sum_{y \in Y} \|f(x, y)\| < +\infty$.
- (3) $\sum_{y \in Y} \sum_{x \in X} \|f(x, y)\| < +\infty$.

Proof. Immediate from Thm. 5.50. It is also not hard to prove it directly. \square

5.5 Parametrization theorem for discrete integrals

We fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. In the following sections, we shall apply the results about discrete integrals to the study of series and double series. For the convenience of applications (e.g. the proof of $e^z e^w = e^{z+w}$), we enlarge the concept of series a little:

5.5.1 Series over \mathbb{Z}

Definition 5.52. A **series over \mathbb{Z}** is an expression

$$\sum_{n=-\infty}^{+\infty} f(n)$$

where f is a function from \mathbb{Z} to either V or $\overline{\mathbb{R}}_{\geq 0}$. We say that this series **converges to** (or equals) $\mu \in V$ resp. equals $\mu \in \overline{\mathbb{R}}_{\geq 0}$, if

$$\lim_{m, n \rightarrow +\infty} \sum_{i=-m}^n f(i) = \mu \quad (5.23)$$

In this case, we write

$$\sum_{n=-\infty}^{+\infty} f(n) = \mu$$

We say that $\sum_{n=-\infty}^{+\infty} f(n)$ **converges absolutely** if $\sum_{n=-\infty}^{+\infty} \|f(n)\| < +\infty$.

Remark 5.53. Note that in the case of $\overline{\mathbb{R}}_{\geq 0}$, the limit on the LHS of (5.23) must exist in $\overline{\mathbb{R}}_{\geq 0}$. Again, this is due to the fact that the involved net is increasing, and so one can use Exe. 5.16.

Exercise 5.54. Let $\sum_{n=-\infty}^{+\infty} f(n)$ be a series in either V or $\overline{\mathbb{R}}_{\geq 0}$.

1. Fix $k \in \mathbb{Z}$. Prove that $\sum_{n=-\infty}^{+\infty} f(n)$ converges iff the following limits converge:

$$\sum_{n=k}^{+\infty} f(n) = \lim_{n \rightarrow +\infty} \sum_{i=k}^n f(i) \quad (5.24a)$$

$$\sum_{n=-\infty}^{k-1} f(n) = \lim_{m \rightarrow +\infty} \sum_{i=-m}^{k-1} f(i) \quad (5.24b)$$

Moreover, if these limits converge, then

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=k}^{+\infty} f(n) + \sum_{n=-\infty}^{k-1} f(n) \quad (5.25)$$

2. In the case that f has codomain V , prove that $\sum_{n=-\infty}^{+\infty} f(n)$ converges if it converges absolutely.
3. Prove that if f is zero outside \mathbb{Z}_+ , then

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=1}^{+\infty} f(n) \quad (5.26)$$

Thus, by (5.26), our following results about series over \mathbb{Z} can be directly applied to series over \mathbb{Z}_+ (or over $\mathbb{Z}_{\geq k}$ where $k \in \mathbb{Z}$).

5.5.2 Parametrization theorem

The following theorem relates series and discrete integrals. The structure of this theorem is similar to that of Fubini's theorem-A,B,C in Sec. 5.4.

Theorem 5.55 (Parametrization theorem). *Let X be an infinite countable set. Let $\varphi : \mathbb{Z} \rightarrow X$ be a bijection (called a **parametrization** of X). The following are true.*

1. *Let $f : X \rightarrow V$. If the RHS of (5.27) converges in V , then the LHS converges, and (5.27) holds:*

$$\sum_{n=-\infty}^{+\infty} f \circ \varphi(n) = \sum_{x \in X} f(x) \quad (5.27)$$

2. *Let $f : X \rightarrow \overline{\mathbb{R}}_{\geq 0}$. Then (5.27) holds in $\overline{\mathbb{R}}_{\geq 0}$.*

3. Let $f : X \rightarrow V$. Then the discrete integral $\sum_{x \in X} f(x)$ converges absolutely iff the

series $\sum_{n=-\infty}^{+\infty} f \circ \varphi(n)$ converges absolutely.

The same conclusions hold if we assume that $\varphi : \mathbb{Z}_+ \rightarrow X$ is a bijection.

Proof. We prove the case $\varphi : \mathbb{Z} \rightarrow X$; the other case is similar.

Assume that $\sum_X f$ converges, which means that the limit of the net $(\sum_A f)_{A \in \text{fin}(2^X)}$ converges to some $v \in V$. Therefore, by Thm. 5.24, the subnet

$$\left(\sum_{x \in A_{m,n}} f(x) \right)_{m,n \in \mathbb{Z}_+} = \left(\sum_{i=-m}^n f \circ \varphi(i) \right)_{m,n \in \mathbb{Z}_+}$$

converges to v , where $A_{m,n} = \{\varphi(i) : i \in \mathbb{Z}, -m \leq i \leq n\}$. This proves part 1. The same method proves part 2. Part 3 follows directly from part 2. \square

5.6 Application to (double) series and power series; $e^z e^w = e^{z+w}$

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

5.6.1 General results about series and double series

Corollary 5.56. Let $f : \mathbb{Z} \rightarrow V$, and let $\psi : \mathbb{Z} \rightarrow \mathbb{Z}$ be a bijection. Suppose that

$$\sum_{n=-\infty}^{+\infty} \|f(n)\| < +\infty \quad (5.28)$$

Then (5.29) holds true, where the RHS of (5.29) converges absolutely:

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=-\infty}^{+\infty} f \circ \psi(n) \quad (5.29)$$

The same conclusion clearly holds if \mathbb{Z} is replaced by \mathbb{Z}_+ .

Proof. By (5.28) and Thm. 5.55-3, the discrete integral $\sum_{\mathbb{Z}} f$ converges absolutely, and hence converges. By Thm. 5.55-1, the LHS resp. RHS of (5.29) converges to the value of $\sum_{\mathbb{Z}} f$ if we choose the parametrization to be $\text{id}_{\mathbb{Z}}$ resp. ψ . This proves (5.29) and the convergence of the RHS of (5.29). Applying the same conclusion to $\|f(\cdot)\|$ proves the absolute convergence of the RHS of (5.29). \square

Corollary 5.57. Let $f : \mathbb{Z}^2 \rightarrow V$. Let $\Phi : \mathbb{Z}^2 \rightarrow \mathbb{Z}^2$ be a bijection. Suppose that

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} \|f(m,n)\| < +\infty \quad (5.30)$$

Then (5.31) holds true, where the six series involved in (5.31) converge absolutely.

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} f(m, n) = \sum_{n=-\infty}^{+\infty} \sum_{m=-\infty}^{+\infty} f(m, n) = \sum_{k=-\infty}^{+\infty} \sum_{l=-\infty}^{+\infty} f \circ \Phi(k, l) \quad (5.31)$$

Similar results clearly hold if \mathbb{Z}^2 is replaced by \mathbb{Z}_+^2 : One extends the domain of f and the domain and codomain of Φ from \mathbb{Z}_+^2 to \mathbb{Z}^2 . Then one apply Cor. 5.57.

Also, note that the second term of (5.31) is redundant: it follows from the equality of the first and the third terms of (5.31) if we choose $\Phi(k, l) = (l, k)$.

Proof. By Thm. 5.55-2 and Thm. 5.50, we have

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} \|f(m, n)\| = \sum_{x \in \mathbb{Z}} \sum_{y \in \mathbb{Z}} \|f(x, y)\| = \sum_{(x, y) \in \mathbb{Z}^2} \|f(x, y)\| \quad (5.32)$$

where all the limits exist in $\overline{\mathbb{R}}_{\geq 0}$. Therefore, by (5.30), the discrete integral $\sum_{\mathbb{Z}^2} f$ is absolutely convergent and hence convergent.

Similar to the argument for (5.32), Thm. 5.55-1 and Thm. 5.49 imply that the first two terms of (5.31) exist and are both equal to the discrete integral $\sum_{\mathbb{Z}^2} f$. Since $\sum_{\mathbb{Z}^2} f = \sum_{\mathbb{Z}^2} f \circ \Phi$ (recall Rem. 5.42), by Thm. 5.55-1 and Thm. 5.49 again, the last term of (5.31) converges to $\sum_{\mathbb{Z}^2} f \circ \Phi$.

We have proved that the six series in (5.31) converge, and (5.31) holds. Replacing $f(\cdot, \cdot)$ with $\|f(\cdot, \cdot)\|$ and applying a similar argument, we see that the six series in (5.31) converge absolutely. \square

Remark 5.58. Using the same method as in the above proof, one can easily prove a more general version of Cor. 5.57: Let $N \in \mathbb{Z}_+$. Let $f : \mathbb{Z}^2 \rightarrow V$ such that (5.30) holds true. Let $\Psi : \mathbb{Z}^N \rightarrow \mathbb{Z}^2$ be a bijection. Then the N series involved in the expression of (5.33) (from innermost to outermost) converge absolutely:

$$\sum_{n_1=-\infty}^{+\infty} \cdots \sum_{n_N=-\infty}^{+\infty} f \circ \Psi(n_1, \dots, n_N) \quad (5.33)$$

Moverover, the outermost series of (5.33) converges to (5.31). And of course, a similar result holds if \mathbb{Z}^2 is replaced by \mathbb{Z}^M for every $M \in \mathbb{Z}_+$. We leave it to the readers to fill in the details.

Corollary 5.59. Assume that

$$A = \sum_{n=-\infty}^{+\infty} a_n \quad B = \sum_{n=-\infty}^{+\infty} b_n$$

are absolutely convergent series in \mathbb{C} . Then for each $k \in \mathbb{Z}$, the series

$$c_k = \sum_{l=-\infty}^{+\infty} a_{k-l} b_l$$

converges absolutely. Moreover, the LHS of the (5.34) converges absolutely to the RHS:

$$\sum_{k=-\infty}^{+\infty} c_k = AB \quad (5.34)$$

Proof. Apply Cor. 5.57 to the case that $f(m, n) = a_m b_n$ and $\Phi(k, l) = (k - l, l)$. \square

5.6.2 Application to power series

Corollary 5.60. Let $f(z) = \sum_{n=0}^{+\infty} a_n z^n$ and $g(z) = \sum_{n=0}^{+\infty} b_n z^n$ be power series in \mathbb{C} with radii of convergence R_1, R_2 respectively. Let $R = \min\{R_1, R_2\}$. For each $k \in \mathbb{Z}_+$, let

$$c_k = \sum_{l=0}^k a_{k-l} b_l$$

Then the power series $h(z) = \sum_{k=0}^{+\infty} c_k z^k$ has radius of convergence $\geq R$. Moreover, for each $z \in \mathbb{C}$ satisfying $0 \leq |z| < R$, we have

$$h(z) = f(z) \cdot g(z)$$

Proof. For each $0 \leq |z| < R$, apply Cor. 5.59 by replacing the a_n, b_n, c_k of Cor. 5.59 with $a_n z^n, b_n z^n, c_k z^k$. This shows that $h(z)$ converges absolutely to $f(z) \cdot g(z)$. Since this is true for all $|z| < R$, $h(z)$ must have radius of convergence at least R by Rem. 4.21. \square

The above result also holds more generally for Laurent series. See Exe. 5.66.

Corollary 5.61. For each $z, w \in \mathbb{C}$ we have

$$e^z e^w = e^{z+w}$$

Proof. Apply Cor. 5.59 to the case $a_n = z^n/n!$ and $b_n = w^n/n!$. (We set $a_n = b_n = 0$ if $n < 0$.) Then

$$c_k = \sum_{l=0}^k \frac{z^{k-l}}{(k-l)!} \cdot \frac{w^l}{l!} = \sum_{l=0}^k \binom{k}{l} \frac{z^{k-l} w^l}{k!} = \frac{(z+w)^k}{k!}$$

by (4.5). \square

5.7 Summary

The following are some fundamental questions about series and double series:

- (a) Are they invariant under rearrangement? (Cf. (5.29).)
- (b) Does the value of an iterated double series remain unchanged if the order of the two infinite sums is changed? (Cf. the first equality in (5.31).)
- (c) A mixture of the above two questions. (Cf. the last term of (5.31).)

We address these questions by relating them to discrete integral, a version of infinite sums which is parametrization-independent. The following are some key features of this theory.

- 1. (General principle) A discrete integral is to a series (defined by parametrization) as a net to a subnet.
- 2. (Net \Rightarrow Subnet) All subnets of a convergent net converge to the same value: the limit of the original net.
- 3. (Discrete integral \Rightarrow Series) Therefore, different series converge to the same value if they are different parametrizations of the same convergent discrete integral.
- 4. (Discrete integrals \Rightarrow Series) Fubini-type theorems (any theorems about exchanging the orders of iterated sums/integrals) hold for convergent double discrete integrals. Therefore, they hold when passing to subnets, in particular, when passing to double series.
- 5. (Subnet \Rightarrow Net) Every increasing net in $\overline{\mathbb{R}}_{\geq 0}$ has a limit in $\overline{\mathbb{R}}_{\geq 0}$. Therefore, if an increasing net in $\mathbb{R}_{\geq 0}$ has a subnet converging to a number $< +\infty$, then the original net converges in $\mathbb{R}_{\geq 0}$ (to a finite number).
- 6. (General principle) The discrete integral $\sum_{x \in X} \|f(x)\|$ is defined by the limit of an increasing net in $\overline{\mathbb{R}}_{\geq 0}$.
- 7. (Series \Rightarrow Discrete integral) Therefore, if any series or double series corresponds in a reasonable way to a discrete integral, then the absolute convergence of this (double) series (more specifically: (5.28) or (5.30)) implies the absolute convergence (and hence convergence) of the original discrete integral. This implies the absolute convergence of any other (double) series arising from that discrete integral.
- 8. (Conclusion) Thus, when a (double) series converges absolutely (in the form of (5.28) or (5.30)), the three problems (a), (b), (c) have satisfying answers. The reason absolutely convergent (double) series are so good is because increasing nets in $\overline{\mathbb{R}}_{\geq 0}$ are very good!

9. (Counterexamples) Non-absolutely convergent series in \mathbb{R} have rearrangements converging to different values. This is because non-convergent nets may have two subnets converging to different values, cf. Pb. 5.5. (Recall from Prop. 5.48 that for discrete integrals in \mathbb{R} , absolute convergence is equivalent to convergence.)

5.8 Problems and supplementary material

Let X be a set, and let V be a Banach space over $\mathbb{R} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 5.1. Compute $\lim_{p,q \rightarrow +\infty} a_{p,q}$ where $(a_{p,q})_{p,q \in \mathbb{Z}_+}$ are given below. Or explain why the limit does not exist.

$$a_{p,q} = \frac{(-1)^p \cdot p}{p+q} \quad a_{p,q} = \frac{(-1)^p}{p} \quad a_{p,q} = \frac{\cos(p\pi/4)}{p+q}$$

Problem 5.2. Prove Thm. 5.38. (Every Cauchy net in a complete metric space converges.)

Problem 5.3. Let $f : X \rightarrow V$. Define the **support** of f to be

$$\text{Supp}(f) = \{x \in X : f(x) \neq 0\} \quad (5.35)$$

Prove that if $\sum_X f$ converges absolutely, then $\text{Supp}(f)$ is a countable set.

Hint. Consider $\{x \in X : |f(x)| \geq \varepsilon\}$ where $\varepsilon > 0$. □

Problem 5.4. Prove Prop. 5.48.

★ **Problem 5.5.** Prove **Riemann rearrangement theorem**, which says the following: Let $\sum_{n=1}^{+\infty} x_n$ be a series in \mathbb{R} which converges and which does not converge absolutely. Choose any $A \in \mathbb{R}$. Then $\sum_{n=1}^{+\infty} x_n$ has a rearrangement converging to A (i.e., there is bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$ such that $\sum_{n=1}^{+\infty} f \circ \varphi(n) = A$).

Remark 5.62. By Riemann rearrangement theorem, it is clear that every convergent series in \mathbb{R}^N which is not absolutely convergent must have two rearrangements converging to two different points. However, when \mathbb{R}^N is replaced by an infinite dimensional Banach space, one may find a series $\sum_{n=1}^{+\infty} v_n$ which does not converge absolutely but converge to some v , and every rearrangement of $\sum_{n=1}^{+\infty} v_n$ converges to v . See Pb. 5.6.

Problem 5.6. Consider the case that V is the real Banach space $V = l^\infty(\mathbb{Z}_+, \mathbb{R})$. For each $n \in \mathbb{Z}_+$, let $e_n \in V$ be the characteristic function $\chi_{\{n\}}$. Namey, e_n takes value 1 at n , and takes 0 at the other points. Prove that the discrete integral

$$\sum_{n \in \mathbb{Z}_+} \frac{1}{n} e_n \quad (5.36)$$

converges in V , and find the limit. Prove that (5.36) does not converge absolutely.

Remark 5.63. A more important example that will be considered later is $V = l^2(\mathbb{Z}_+, \mathbb{C})$, the set of all functions $f : \mathbb{Z}_+ \rightarrow \mathbb{C}$ satisfying that the **l^2 -norm** $\|f\|_{l^2} = \sqrt{\sum_{n \in \mathbb{Z}_+} |f(n)|^2}$ is finite. Then V is in fact a Banach space. (Actually, it is a so-called **Hilbert space**.) Again, let $e_n = \chi_{\{n\}}$. (These e_n will be called an **orthonormal basis** of V .) Then for each $f \in V$, the discrete integral $\sum_{n \in \mathbb{Z}_+} f(n) \cdot e_n$ converges to f . But it does not converge absolutely if $\sum_{n \in \mathbb{Z}_+} |f(n)| = +\infty$. Take for example $f(n) = n^{-1}$. We will study these objects in the second semester.

Problem 5.7. Define $(x_{j,k})_{(j,k) \in \mathbb{Z}_+ \times \mathbb{Z}_+}$ to be

$$x_{j,k} = \begin{cases} \frac{1}{j^2 - k^2} & \text{if } j \neq k \\ 0 & \text{if } j = k \end{cases}$$

Prove that the discrete integral $\sum_{(j,k) \in \mathbb{Z}_+^2} x_{j,k}$ does not converge in \mathbb{R} .

Hint. Consider $(x_{j,k})$ as a net over \mathbb{Z}^2 . Find a good bijection $\Phi : \mathbb{Z}^2 \rightarrow \mathbb{Z}^2$. □

Definition 5.64. For each $f \in V^X$, define the **l^1 -norm**

$$\|f\|_{l^1(X,V)} \equiv \|f\|_{l^1} \equiv \|f\|_1 = \sum_{x \in X} \|f(x)\|$$

Define the l^1 -space

$$l^1(X, V) = \{f \in V^X : \|f\|_{l^1} < +\infty\}$$

Namely, $l^1(X, V)$ is the set of all $f \in V^X$ where $\sum_X f$ converges absolutely. In particular, $\sum_X f$ converges for such f .

Exercise 5.65. Prove that for each $f, g \in V^X$ and $\lambda \in \mathbb{F}$, we have

$$\|f + g\|_1 \leq \|f\|_1 + \|g\|_1 \quad \|\lambda f\|_1 = |\lambda| \cdot \|f\|_1 \quad (5.37)$$

Show that $l^1(X, V)$ is a linear subspace of $l^\infty(X, V)$, and that $\|\cdot\|_{l^1}$ is a norm on $l^1(X, V)$

Problem 5.8. Prove that $l^1(X, V)$ is a Banach space. Namely, prove that the metric on $l^1(X, V)$ defined by the l^1 -norm is complete.

Problem 5.9. Prove the **dominated convergence theorem** for discrete integrals: Let $(f_\alpha)_{\alpha \in I}$ be a net in V^X satisfying the following conditions:

- (1) There exists $g \in l^1(X, \mathbb{R})$ satisfying $g \geq 0$ (i.e. $g(x) \geq 0$ for all $x \in X$) such that for every $\alpha \in I, x \in X$ we have

$$\|f_\alpha(x)\| \leq g(x)$$

We simply write the above condition as $|f_\alpha| \leq g$.

- (2) $(f_\alpha)_{\alpha \in I}$ converges pointwise some $f \in V^X$. Namely, $\lim_\alpha f_\alpha(x) = f(x)$ for every $x \in X$.

Prove that $f \in l^1(X, V)$. Prove that the LHS of (5.38) exists and equals the RHS:

$$\lim_{\alpha \in I} \sum_{x \in X} f_\alpha(x) = \sum_{x \in X} f(x) \quad (5.38)$$

★ **Problem 5.10.** Assume $v_n \in V$ for each n . Let z be a complex variable. Then the expression

$$f(z) = \sum_{n=-\infty}^{+\infty} v_n z^n$$

is called a **Laurent series** in V .

Prove that there exist unique $r, R \in \overline{\mathbb{R}}_{\geq 0}$ such that $f(z)$ converges absolutely when $|r| < z < |R|$, and that $f(z)$ diverges when $|z| < r$ or $|z| > R$. Prove that

$$r = \limsup_{n \rightarrow +\infty} \sqrt[n]{\|v_{-n}\|} \quad R = \frac{1}{\limsup_{n \rightarrow +\infty} \sqrt[n]{\|v_n\|}} \quad (5.39)$$

(Recall that by Exe. 5.54, $f(z)$ diverges iff either $\sum_{n=0}^{\infty} v_n z^n$ or $\sum_{n=-\infty}^{-1} v_n z^n$ diverges.) We call r and R the **radii of convergence** of $f(z)$. \square

★ **Exercise 5.66.** Consider Laurent series $f(z) = \sum_{n=-\infty}^{+\infty} a_n z^n$ (with radii of convergence $r_1 < R_1$) and $g(z) = \sum_{n=-\infty}^{+\infty} b_n z^n$ (with radii of convergence $r_2 < R_2$) in \mathbb{C} . Let

$$r = \max\{r_1, r_2\} \quad R = \min\{R_1, R_2\}$$

Assume that $r < R$. Prove that for each $k \in \mathbb{Z}$, the series

$$c_k = \sum_{l=-\infty}^{+\infty} a_{k-l} b_l$$

converges absolutely. Prove that for each $z \in \mathbb{C}$ satisfying $r < |z| < R$, the LHS of the following equation converges absolutely to the RHS:

$$\sum_{k=-\infty}^{+\infty} c_k z^k = f(z)g(z) \quad (5.40)$$

6 ★ Construction of \mathbb{R} from \mathbb{Q}

The goal of this chapter is to construct real numbers from rationals. More precisely, our goal is to prove Thm. 1.34. We use the method of Cantor to construct real numbers using equivalence classes of Cauchy sequences in \mathbb{Q} . The idea is quite simple: If we admit the existence of \mathbb{R} satisfying Thm. 1.34, then by Prop. 1.29, each $x \in \mathbb{R}$ is the limit of a sequence (x_n) in \mathbb{Q} , which must be a Cauchy sequence. Moreover, if (y_n) is a sequence in \mathbb{Q} converging to $y \in \mathbb{R}$, then by Exe. 5.37 we have $x = y$ iff (x_n) and (y_n) are Cauchy equivalent. Motivated by this, we now do not assume the existence of \mathbb{R} , and make the following definition:

Definition 6.1. We let \mathcal{R} be the set of Cauchy sequences in \mathbb{Q} ,¹ namely, the set of $(x_n)_{n \in \mathbb{Z}_+} \in \mathbb{Q}^{\mathbb{Z}_+}$ satisfying

$$\lim_{m, n \rightarrow +\infty} (x_m - x_n) = 0$$

We say that two elements $(x_n), (y_n)$ of \mathcal{R} are Cauchy-equivalent and write $(x_n) \sim (y_n)$ if $\lim_{n \rightarrow \infty} (x_n - y_n) = 0$.

Note that the above definition does not rely on the existence of \mathbb{R} , because the limit of nets in \mathbb{Q} can be defined using only rational numbers: a net $(\xi_\alpha)_{\alpha \in I}$ converges to ξ iff for every $\varepsilon \in \mathbb{Q}_{>0}$, ξ_α is eventually satisfies $|\xi_\alpha - \xi| < \varepsilon$. The readers can check that all the properties about limit used in this chapter does not rely on the existence of \mathbb{R} .

Cauchy-equivalence is clearly an equivalence condition on \mathcal{R} : For example, if $\lim(x_n - y_n) = \lim(y_n - z_n) = 0$ then $|x_n - z_n| \leq |x_n - y_n| + |y_n - z_n| \rightarrow 0$. So $|x_n - z_n| \rightarrow 0$. This proves the transitivity. The other two conditions are obvious. Therefore, we can define:

Definition 6.2. We let $\mathbb{R} = \mathcal{R} / \sim$ where \sim is the Cauchy-equivalence relation. (Recall Def. 1.18). The equivalence class of $(x_n)_{n \in \mathbb{Z}_+}$ is denoted by $[x_n]_{n \in \mathbb{Z}_+} = [x_1, x_2, \dots]$, simply written as $[x_n]$. The zero element 0 of \mathbb{R} is defined to be $[0, 0, \dots]$.

Exercise 6.3. Choose $[x_n] \in \mathbb{R}$ (i.e. $(x_n) \in \mathcal{R}$). The following are equivalent:

- (1) $[x_n] \neq 0$. Namely, $\lim_n x_n$ does not converge to 0.
- (2) There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that either $x_n > \varepsilon$ eventually, or $x_n < -\varepsilon$ eventually. In particular, $x_n \neq 0$ eventually.

Consequently, the map $a \in \mathbb{Q} \mapsto [a, a, \dots] \in \mathbb{R}$ is injective. With the help of this injective map, \mathbb{Q} can be viewed as a subset of \mathbb{R} .

¹Only in this chapter do we use \mathcal{R} for this meaning.

Exercise 6.4. Let $[x_n] \in \mathbb{R}$ and $a \in \mathbb{Q}$. Suppose that $x_n \geq a$ (resp. $x_n \leq a$) frequently. Then for every $\varepsilon \in \mathbb{Q}_{>0}$, we have that $x_n \geq a - \varepsilon$ (resp. $x_n \leq a + \varepsilon$) eventually.

Definition 6.5. If $\xi, \eta \in \mathbb{R}$, write $\xi = [x_n]$ and $\eta = [y_n]$. In the case that $\eta \neq 0$, we assume $y_n \neq 0$ for all n , which is possible by Exe. 6.3. Define

$$\begin{aligned} [x_n] + [y_n] &= [x_n + y_n] \\ -[x_n] &= [-x_n] \\ [x_n] \cdot [y_n] &= [x_n y_n] \\ 1/[y_n] &= [1/y_n] \quad (\text{if } [y_n] \neq 0) \end{aligned}$$

Exercise 6.6. Prove that the above formulas are well-defined: For example, if $(x_n) \sim (x'_n)$ in \mathcal{R} , then $(x_n y_n) \sim (x'_n y_n)$. (You may need the easy fact that every Cauchy sequence is bounded.)

Remark 6.7. It is clear that Def. 6.5 makes \mathbb{R} a **field**, which means that for every $\alpha, \beta, \gamma \in \mathbb{R}$, the following are satisfied:

$$\begin{aligned} \alpha + \beta &= \beta + \alpha & (\alpha + \beta) + \gamma &= \alpha + (\beta + \gamma) & 0 + \alpha &= \alpha & \alpha + (-\alpha) &= 0 \\ \alpha\beta &= \beta\alpha & (\alpha\beta)\gamma &= \alpha(\beta\gamma) & 1 \cdot \alpha &= \alpha & (\alpha + \beta)\gamma &= \alpha\gamma + \beta\gamma \\ \alpha \cdot \frac{1}{\alpha} &= 1 & & & & & & (\text{if } \alpha \neq 0) \end{aligned}$$

Moreover, \mathbb{Q} is a subfield of \mathbb{R} where the addition, taking negative, multiplication, and inverse of \mathbb{R} restrict to those of \mathbb{Q} .

Definition 6.8. Let $[x_n], [y_n] \in \mathbb{R}$. We write $[x_n] < [y_n]$ if one of the following equivalent (due to Exe. 6.4) statements hold:

- There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that $y_n - x_n > \varepsilon$ eventually.
- There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that $y_n - x_n > \varepsilon$ frequently.

It is not hard show that “ $<$ ” is well-defined, and that (by Exe. 6.3) if $[x_n] < [y_n]$ then $[x_n] \neq [y_n]$. We write $[x_n] \leq [y_n]$ if $[x_n] < [y_n]$ or $x_n = y_n$.

Lemma 6.9. (\mathbb{R}, \leq) is a totally ordered set.

Proof. Choose $[x_n], [y_n], [z_n] \in \mathbb{R}$. If $[x_n] < [y_n]$ and $[y_n] < [z_n]$, then clearly $[x_n] < [z_n]$. This proves that \leq is a preorder.

Suppose $[x_n] \leq [y_n]$ and $[y_n] \leq [x_n]$. Let us prove $[x_n] = [y_n]$. Suppose not. Then $[x_n] < [y_n]$ and $[y_n] < [x_n]$ by the definition of “ \leq ”. So there is $\varepsilon > 0$ such that $y_n - x_n > \varepsilon$ eventually, and $x_n - y_n > \varepsilon$ eventually. Impossible. So \leq is a partial order.

Suppose $[x_n] \neq [y_n]$. Then $(x_n - y_n) \not\sim 0$. So Exe. 6.3 implies that either $[x_n] < [y_n]$ or $[y_n] < [x_n]$. So \leq is a total order. \square

Lemma 6.10. Let $[x_n], [y_n] \in \mathbb{R}$. Then the following are equivalent.

- $[x_n] \geq [y_n]$.
- For every $\varepsilon \in \mathbb{Q}_{>0}$, $x_n - y_n \geq -\varepsilon$ frequently.
- For every $\varepsilon \in \mathbb{Q}_{>0}$, $x_n - y_n \geq -\varepsilon$ eventually.

Proof. Since \leq is a total order, the negation of $>$ is \leq . So the statements follow immediately by negating Def. 6.8. \square

Lemma 6.11. \mathbb{R} is an ordered field extension of \mathbb{Q} , and \mathbb{R} is Archimedean.

Proof. The order of \mathbb{R} clearly restricts to that of \mathbb{Q} . We want to prove that \mathbb{R} is an ordered field. (Recall Def. 1.23). Clearly, if $[x_n] < [y_n]$ and $[z_n] \in \mathbb{R}$, then $[x_n] + [z_n] = [x_n + z_n] < [y_n + z_n] = [y_n] + [z_n]$. If $[x_n] > 0$ and $[y_n] > 0$, then there are $\varepsilon > 0$ such that $x_n > \varepsilon$ eventually and $y_n > \varepsilon$ eventually. So $x_n y_n > \varepsilon^2$ eventually. So $[x_n][y_n] > 0$. This proves that \mathbb{R} is an ordered field.

Now let $[x_n] > 0$ and $[y_n] \in \mathbb{R}$. So there exist $\varepsilon \in \mathbb{Q}_{>0}$ such that $x_n > \varepsilon$ eventually. Since (y_n) is Cauchy, one checks easily that (y_n) is bounded. So there is $M \in \mathbb{Q}_{>0}$ such that $|y_n| \leq M$ for all n . Since \mathbb{Q} is Archimedean, there exists $k \in \mathbb{Z}_+$ such that $k\varepsilon > M + 1$. So $kx_n > M + 1$ eventually. So $k[x_n] > M$. This proves that \mathbb{R} is Archimedean. \square

To finish the proof of Thm. 1.34, it remains to prove that \mathbb{R} satisfies the least-upper-bound property.

Lemma 6.12. Thm. 1.34 holds if every bounded increasing sequence in \mathbb{R} converges.

Proof. Suppose that every bounded increasing sequence in \mathbb{R} converges. Choose any nonempty $E \subset \mathbb{R}$ bounded from above. We shall show that E has a least upper bound.

Let F be the set of upper bounds of E . Namely, $F = \{\eta \in \mathbb{R} : \eta \geq \xi, \forall \xi \in E\}$. So $F \neq \emptyset$. We construct an increasing sequence (ξ_k) in E and an decreasing sequence (η_k) in F as follows. Since E, F are nonempty, we choose arbitrary $\xi_1 \in E$ and $\eta_1 \in F$. Then $\xi_1 \leq \eta_1$. Suppose $\xi_1 \leq \dots \leq \xi_k \in E$ and $\eta_1 \geq \dots \geq \eta_k \in F$ have been constructed. Let $\psi_k = (\xi_k + \eta_k)/2$. Let

$$\begin{cases} \xi_{k+1} = \psi_k, \eta_{k+1} = \eta_k & \text{if } \psi_k \in E \\ \xi_{k+1} = \xi_k, \eta_{k+1} = \psi_k & \text{if } \psi_k \in F \end{cases}$$

Then the sequences we have constructed satisfy $\lim_{k \rightarrow \infty} (\eta_k - \psi_k) = 0$.

By assumption, $\alpha = \lim_{k \rightarrow \infty} \xi_k$ exists, and it equals $\lim_k \eta_k$. So α is an upper bound of E . (If $\lambda \in E$, then $\lambda \leq \eta_k$ for all k since $\eta_k \in F$. So $\lambda \leq \lim_k \eta_k = \alpha$.) We now show that α is the least upper bound. Let $\varepsilon > 0$. Since $\xi_k \rightarrow \alpha$, there is k such that $\alpha - \xi_k < \varepsilon$. So $\xi_k > \alpha - \varepsilon$, and hence $\alpha - \varepsilon$ is not an upper bound of E . \square

Lemma 6.13. *Thm. 1.34 holds if every bounded increasing sequence in \mathbb{Q} converges to an element of \mathbb{R} .*

Proof. Suppose that every increasing sequence in \mathbb{Q} converges in \mathbb{R} . By Lem. 6.12, it suffices to prove that every increasing sequence (ξ_k) in \mathbb{R} converges. If $\{\xi_k : k \in \mathbb{Z}_+\}$ is a finite subset of \mathbb{R} , then (ξ_k) clearly converges. If $\{\xi_k : k \in \mathbb{Z}_+\}$ is infinite, then (ξ_k) clearly has a strictly increasing subsequence (ξ_{k_l}) . If we can prove that (ξ_{k_l}) converges to some $\psi \in \mathbb{R}$, then (ξ_k) converges to ψ . (Choose any $\varepsilon > 0$. Choose $L \in \mathbb{Z}_+$ such that $|\psi - \xi_{k_L}| < \varepsilon$ and hence $0 \leq \psi - \xi_{k_L} < \varepsilon$. Then for all $k \geq k_L$ we have $0 \leq \psi - \xi_k < \varepsilon$.)

Thus, it remains to prove that every strictly increasing sequence (η_k) in \mathbb{R} converges. Since we have proved that \mathbb{R} is an Archimedean ordered field extension of \mathbb{Q} , by Prop. 1.29, for each k , there exists $a_k \in \mathbb{Q}$ such that $\xi_k < a_k < \xi_{k+1}$. By assumption, (a_k) converges to some $\alpha \in \mathbb{R}$. Since $a_{k-1} < \xi_k < a_k$, by squeeze theorem, (ξ_k) converges to α . \square

Proof of Thm. 1.34. By Lem. 6.13, it suffices to show that every bounded increasing sequence (a_k) in \mathbb{Q} converges in \mathbb{R} . Let $M \in \mathbb{Q}$ such that $a_k \leq M$ for all k .

We first prove that (a_k) is a Cauchy sequence. If not, then there exists $\varepsilon \in \mathbb{Q}_{>0}$ such that for every $K \in \mathbb{Z}_+$ there is $k > K$ such that $|a_k - a_K| > \varepsilon$, and hence $a_k - a_K > \varepsilon$. Thus, we can find a subsequence (a_{k_l}) such that $a_{k_{l+1}} - a_{k_l} > \varepsilon$. By the Archimedean property for \mathbb{Q} , there is $l \in \mathbb{Z}_+$ such that $a_{k_1} + l \cdot \varepsilon > M$. So $a_{k_{l+1}} > M$, impossible.

Note that each a_k is identified with $\xi_k = [a_k, a_k, \dots]$. Let $\psi = [a_1, a_2, a_3, \dots]$, which is an element of \mathbb{R} since we just proved that $(a_n) \in \mathcal{R}$. Then for each k , $\psi - \xi_k = [a_1 - a_k, a_2 - a_k, \dots]$, where the terms are eventually ≥ 0 . So $\xi_k \leq \psi$ by Lem. 6.10. We have proved that ψ is an upper bound for the sequence (ξ_k) .

Let us prove that $\lim_k \xi_k = \psi$. Choose any $\varepsilon \in \mathbb{Q}_{>0}$. Let us prove that there exists k such that $\psi - \varepsilon < \xi_k$. Then for every $k' \geq k$ we have $\psi - \varepsilon < \xi_{k'} \leq \psi$, finishing the proof of $\lim_k \xi_k = \psi$.

We have proved that a_1, a_2, \dots is a Cauchy sequence in \mathbb{Q} . So there exists k such that $a_l - a_k < \varepsilon/2$ for all $l \geq k$. Thus, for all $l \geq k$ we have $a_k - (a_l - \varepsilon) > \varepsilon/2$. Thus, the l -th term of $\xi_k = [a_k, a_k, \dots]$ minus that of $\psi - \varepsilon = [a_1 - \varepsilon, a_2 - \varepsilon, \dots]$ is $> \varepsilon/2$ for sufficiently large l . By Def. 6.8, we have that $\psi - \varepsilon < \xi_k$. \square

7 Topological spaces

7.1 The topologies of metric spaces

In this chapter, we begin our study of topological spaces, which were introduced by Hausdorff in 1914 [Hau14] as a generalization of metric spaces. As we have seen, focusing on metrics in order to study convergence and continuity is often distracting. For example, in \mathbb{R} , we only care about how the convergence of sequences look like, but not about the particular metrics. The same is true about the countable product of metric spaces $S = \prod_{i \in \mathbb{Z}_+} X_i$: the metrics (2.14) and (2.15) give the same topology, although they look very different. Moreover, the shapes of the open balls defined by these two metrics are not very simple. This makes it more difficult to study the continuity of functions on S by using (2) or (2') of Def. 2.38.

Topological spaces generalize metric spaces by giving a set of axioms satisfied by the open sets of the spaces.

Definition 7.1. Let X be a metric space, and let $E \subset X$. A point $x \in E$ is called an **interior point** of E if $B_X(x, r) \subset E$ for some $r > 0$. We say that E is an **open (sub)set** of X , if every point of E is an interior point.

Definition 7.2. Let \mathcal{T} be the set of open sets of X . We call \mathcal{T} the **topology of the metric space** X .

Example 7.3. By triangle inequality, every open ball of a metric space X is open. \emptyset and X are open subsets of X . If $p, q \in \mathbb{R}^N$ and $d(p, x) = r$ (where $0 \leq r < +\infty$), then p is not an interior point of $\overline{B}_{\mathbb{R}^N}(x, r)$. So the closed balls of \mathbb{R}^N are not open sets. In particular, $[a, b]$ are not open subsets of \mathbb{R} since a, b are not interior points.

Example 7.4. It is not hard to see that a finite intersection of open sets is open.

In topological spaces, open sets play the role of open balls in metric spaces due to the following facts:

Exercise 7.5. Let (x_n) be a sequence in a metric space X . Let $x \in X$. Show that the following are equivalent:

- (1) (x_n) converges to x .
- (2) For every **neighborhood** U of x (i.e. every open set containing x) there is $N \in \mathbb{Z}_+$ such that for every $n \geq N$ we have $x_n \in U$.

Exercise 7.6. Let $f : X \rightarrow Y$ be a map of metric spaces. Let $x \in X$ and $y = f(x)$. Prove that the following are equivalent.

- (1) f is continuous at x .

- (2) For every neighborhood V of y there is a neighborhood U of x such that $f(U) \subset V$ (equivalently, $U \subset f^{-1}(V)$.)

But there is an important difference between the intuitions of open sets and open balls: We want the open balls at a point x to be small so that they can be used to describe the approximation to x . However, an arbitrary open set can be very large. For example, when studying convergence and continuity in \mathbb{R} , we really want a neighborhood of 1 to be $(1 - \varepsilon, 1 + \varepsilon)$ but not the more complicated and bigger one $(-\infty, -2) \cup (0, 100 - \varepsilon)$. Indeed, open sets can be very big:

Lemma 7.7. *Let X be a metric space. If $(U_\alpha)_{\alpha \in I}$ is a family of open subsets of X , then $W = \bigcup_{\alpha \in I} U_\alpha$ is open in X .*

Proof. Choose $x \in W$. Then $x \in U_\alpha$ for some α . So $B_X(x, r) \subset U_\alpha$ for some $r > 0$. So x is an interior point of W . \square

Thus, people very often choose a class \mathcal{B} of smaller open sets (such as the set of open balls) to study the analytic properties of a topological space.

Definition 7.8. Let \mathcal{B} be a set of open sets of a metric space (or more generally, a topological space) X . We say that \mathcal{B} is a **basis for the topology** \mathcal{T} of X if one of the following (clearly) equivalent statements holds:

- For every point $x \in X$ and every neighborhood W of x there exists $U \in \mathcal{B}$ such that $x \in U$ and $U \subset W$.
- Every open subset of X is a union of some members of \mathcal{B} .

Thus, according to Def. 7.1, the set of open balls of a metric space X form a basis for the topology of X . Nevertheless, even in the case of metric spaces, we sometimes consider more convenient bases than the set of open balls. We will see this when we study the topologies of infinite product spaces.

7.2 Topological spaces

7.2.1 Definitions and basic examples

Definition 7.9. We say that a pair (X, \mathcal{T}) (or simply X) is a **topological space** if X is a set, and if \mathcal{T} (called the **topology** of X) is a set of subsets of X satisfying the following conditions

- $\emptyset \in \mathcal{T}$ and $X \in \mathcal{T}$.
- (Union property) If $(U_\alpha)_{\alpha \in I}$ is a family of elements of \mathcal{T} , then $\bigcup_{\alpha \in I} U_\alpha$ is an element of \mathcal{T} .

- (Finite intersection property) If $n \in \mathbb{Z}_+$ and $U_1, \dots, U_n \in \mathcal{T}$, then $U_1 \cap \dots \cap U_n$ is an element of \mathcal{T} .

Elements of \mathcal{T} are called **open (sub)sets** of X .

Definition 7.10. Let X be a topological space, and $x \in X$. A subset $U \subset X$ is called a **neighborhood** of x , if U is an open subset of X containing x .¹ We define $(\text{Nbh}_X(x), \leq)$, the **directed set of neighborhoods of x** , to be

$$\begin{aligned} \text{Nbh}_X(x) &= \{\text{neighborhoods of } x \text{ in } X\} \\ U &\leq U' \iff U \supset U' \end{aligned} \tag{7.1}$$

(Note that one needs the finite intersection property to show that $\text{Nbh}_X(x)$ is a directed set.) We abbreviate this set to $\text{Nbh}_X(x)$ or simply $\text{Nbh}(x)$.

Example 7.11. In Subsec. 7.1, we have proved that the topology of a metric space satisfies the above axioms of a topological space.

In particular, if X is a normed vector space, the topology induced by the metric $d(x, x') = \|x - x'\|$ is called the **norm topology**. If X is a subset of \mathbb{R}^N or \mathbb{C}^N , the topology on X induced by the Euclidean metric is called the **Euclidean topology**. \square

Definition 7.12. A topological space (X, \mathcal{T}) is called **metrizable**, if there is a metric on X inducing the topology \mathcal{T} .

We have seen that the open balls of a metric space generate a topology. In general, one may ask what possible subsets of 2^X generate a topology on a set X . Here is a description, whose proof is left to the readers as an exercise.

Proposition 7.13. Let X be a set, and let $\mathcal{B} \subset 2^X$. Define

$$\mathcal{T} = \{\text{Unions of elements of } \mathcal{B}\} \tag{7.2}$$

The following are equivalent.

(1) (X, \mathcal{T}) is a topological space.

(2) The following are satisfied:

(2-a) $X = \bigcup_{U \in \mathcal{B}} U$.

(2-b) If $U_1, U_2 \in \mathcal{B}$, then $U_1 \cap U_2 \in \mathcal{T}$ (i.e., for each $x \in U_1 \cap U_2$ there exists $V \in \mathcal{B}$ such that $x \in V$ and $V \subset U_1 \cap U_2$).

¹We are following the convention in [Mun, Rud-R]. But many people refer to the word "neighborhood" with slightly different meaning: a subset A is called a neighborhood of x if there is an open set U such that $x \in U \subset A$. And our neighborhoods are called "open neighborhoods" by them.

When (1) or (2) holds, we call \mathcal{T} the **topology generated by \mathcal{B}** . Clearly, \mathcal{B} is a basis for \mathcal{T} (cf. Def. 7.8).

Exercise 7.14. Let X be a set. Let $\mathcal{B}, \mathcal{B}'$ be subsets of 2^X generating topologies $\mathcal{T}, \mathcal{T}'$ respectively. Prove that the following are equivalent.

- (1) $\mathcal{T} = \mathcal{T}'$.
- (2) Each $U \in \mathcal{B}$ is a union of elements of \mathcal{B}' . Each $U' \in \mathcal{B}'$ is a union of elements of \mathcal{B} .
- (3) For each $U \in \mathcal{B}$ and $x \in U$, there exists $U' \in \mathcal{B}'$ such that $x \in U' \subset U$. For each $U' \in \mathcal{B}'$ and $x \in U'$, there exists $U \in \mathcal{B}$ such that $x \in U \subset U'$.

Example 7.15. If (X, \mathcal{T}) is a topological space, then \mathcal{T} is a basis for \mathcal{T} .

Example 7.16. Let (X, d) be a metric space with topology \mathcal{T} . Let $\mathcal{B} = \{B_X(x, r) : x \in X, 0 < r < +\infty\}$. Then \mathcal{B} is a basis for \mathcal{T} . For each $\varepsilon > 0$, the set $\mathcal{B}' = \{B_X(x, r) : x \in X, 0 < r < \varepsilon\}$ is also a basis for \mathcal{T} .

Example 7.17. Let $\mathcal{B} \subset 2^{\overline{\mathbb{R}}}$ be defined by

$$\mathcal{B} = \{(a, b), (c, +\infty], [-\infty, d) : a, b, c, d \in \mathbb{R}\} \quad (7.3)$$

Using Prop. 7.13, one easily checks that \mathcal{B} is a basis for a topology \mathcal{T} . We call this the **standard topology** of $\overline{\mathbb{R}}$.

Let $\varphi : \overline{\mathbb{R}} \rightarrow [u, v]$ be a strictly increasing bijection where $-\infty < u < v < +\infty$. Let $d_{[u, v]}$ be the Euclidean metric, and let \mathcal{T}' be the topology on $\overline{\mathbb{R}}$ defined by $d_{\overline{\mathbb{R}}} = \varphi^* d_{[u, v]}$. Then the set of open balls under \mathcal{T}' is

$$\mathcal{B}' = \{(\varphi^{-1}(y - \varepsilon), \varphi^{-1}(y + \varepsilon)), (\varphi^{-1}(v - \varepsilon'), +\infty], [-\infty, \varphi^{-1}(u + \varepsilon'')) : y \in (u, v) \text{ and } \varepsilon, \varepsilon', \varepsilon'' \in \mathbb{R}_{>0}\}$$

(Note that the three types of intervals in the definition of \mathcal{B}' are open balls centered at $\varphi^{-1}(y)$, $+\infty$, $-\infty$ respectively.) Using Exe. 7.14, one easily checks $\mathcal{T} = \mathcal{T}'$. \square

Convention 7.18. Unless otherwise stated, the topology on $\overline{\mathbb{R}}$ is defined to be the standard one, i.e., the one generated by (7.3). We shall forget about the metric on $\overline{\mathbb{R}}$, and view $\overline{\mathbb{R}}$ only as a (metrizable) topological space.

Definition 7.19. Let A be a subset of a topological space (X, \mathcal{T}_X) . Then

$$\mathcal{T}_A = \{U \cap A : U \in \mathcal{T}_X\}$$

is clearly a topology on A , called the **subspace topology**. Unless otherwise stated, when viewing a subset as a topological subspace, we always choose the subspace topology for the subset.

Exercise 7.20. Let (X, d_X) be a metric space, inducing a topology \mathcal{T}_X . Let A be a metric subspace of X . (So $A \subset X$, and d_X restricts to d_A .) Prove that the topology on A induced by d_A is the subspace topology.

According to the above exercise, if X is a metric space, then viewing a subset A as a topological subspace is compatible with viewing A as a metric subspace.

Exercise 7.21. Let A be a subset of a topological space X . Let \mathcal{B} be a basis for the topology of X . Show that $\{U \cap A : U \in \mathcal{B}\}$ is a basis for the subspace topology of A .

7.2.2 Convergence of nets

Definition 7.22. Let $(x_\alpha)_{\alpha \in I}$ be a net in a topological space X . Let $x \in X$. We say that (x_α) **converges to** x and write

$$\lim_{\alpha \in I} x_\alpha \equiv \lim_{\alpha} x_\alpha = x$$

or simply write $x_\alpha \rightarrow x$, if the following statement holds:

- For every $U \in \text{Nbh}_X(x)$, we have that x_α is eventually in U .

Clearly, if \mathcal{B} is a basis for the topology, then $x_\alpha \rightarrow x$ iff:

- For every $U \in \mathcal{B}$ containing x , we have that x_α is eventually in U .

In the case that X is a metric space (and the topology of X is induced by the metric), the definition here agrees with Def. 5.11.

Exercise 7.23. Let (x_α) be a net in X converging to $x \in X$. Prove that every subnet of (x_α) converges to x .

Exercise 7.24. Let A be a subset of a topological space X , equipped with the subspace topology. Let (x_α) be a net in A , and let $x \in A$. Show that $x_\alpha \rightarrow x$ in A iff $x_\alpha \rightarrow x$ in X .

Example 7.25. Let X be a set. Let $\mathcal{T} = \{\emptyset, X\}$. Then every net in X converges to every point of X . Thus, if X has at least two elements, then the limit of a net in X is not unique. Therefore, a general topological space might be very pathological. To avoid this uniqueness issue, we introduce the following notion:

Definition 7.26. Let X be a topological space with a basis for the topology \mathcal{B} . We say that X is a **Hausdorff space** if the following equivalent conditions are satisfied:

- (1) (Hausdorff condition) If $x, y \in X$ and $x \neq y$, then there exist neighborhoods U of x and V of y such that $U \cap V = \emptyset$.

- (1') If $x, y \in X$ and $x \neq y$, then there exist $U \in \mathcal{B}$ containing x and $V \in \mathcal{B}$ containing y such that $U \cap V = \emptyset$.
- (2) If $(x_\alpha)_{\alpha \in I}$ is a net in X converging to both x and y , then $x = y$.

Proof of the equivalence. (1) \Leftrightarrow (1'): Obvious.

(1) \Rightarrow (2): Suppose that (x_α) converges to x and y . Suppose $x \neq y$. By (1), we have disjoint neighborhoods $U \ni x$ and $V \ni y$. Since $x_\alpha \rightarrow x$, x_α is eventually in U . Similarly, x_α is eventually in V . Therefore, by the logic (5.6b), x_α is eventually in $U \cap V = \emptyset$, impossible.

$\neg(1) \Rightarrow \neg(2)$: Suppose that (1) is not true. Then there exist $x \neq y$ such that every neighborhood of x intersects every neighborhood of y . Let $I = \text{Nbh}_X(x) \times \text{Nbh}_X(y)$. For each $\alpha = (U, V) \in I$, by assumption, there exists $x_\alpha \in U \cap V$. Then $(x_\alpha)_{\alpha \in I}$ is a net in X . We leave it to the readers to check that $x_\alpha \rightarrow x$ and $x_\alpha \rightarrow y$. \square

Remark 7.27. In Hausdorff's 1914 paper introducing topological spaces, the Hausdorff condition is one of the axioms of topological spaces. Non-Hausdorff topological spaces were studied much later. The reason that Hausdorff spaces appeared first may be as follows: The original motivation for topological spaces lies in the study of analysis (especially functional analysis). But in analysis, most spaces are Hausdorff, because we want the limits of sequences or nets to be unique.

In differential geometry and in topology², people are also mainly concerned with topological spaces that are Hausdorff. This is related to the fact that in these areas people often use tools from analysis. But in algebraic geometry, the main examples of topological spaces (e.g. varieties and schemes, whose topologies are called **Zariski topology**) are not Hausdorff. As a related fact, sequences and nets are not effective tools in the study of algebraic geometry. \square

7.3 Closures, interiors, and closed sets

In this section, we fix a topological space X .

7.3.1 Closure points; dense subsets

Definition 7.28. Let A be a subset of X . We say that $x \in X$ is a **closure point** of A , if the following equivalent conditions hold:

- (1) There is a net $(x_\alpha)_{\alpha \in I}$ in A converging to x .
- (2) Each $U \in \text{Nbh}_X(x)$ intersects A .

²Here, I mean genuine topology, such as algebraic topology, differential topology, geometric topology, etc., but not point-set topology, which is analysis under the guise of topology.

The **closure** of A is defined to be

$$\overline{A} \equiv \text{Cl}(A) \equiv \text{Cl}_X(A) = \{\text{closure points of } A\}$$

Clearly $A \subset \overline{A}$. Clearly, if $A \subset B \subset X$, then $\overline{A} \subset \overline{B}$.

Unless otherwise stated, if several subsets are involved, we always understand \overline{A} as $\text{Cl}_X(A)$ where X is the ambient topological space.

Proof of equivalence. (1) \Rightarrow (2): Assume (1). Choose any $U \in \text{Nbh}_X(x)$. Since $x_\alpha \rightarrow x$, we have that x_α is eventually in U . So U must contain some x_α . But $x_\alpha \in A$. So $U \cap A \neq \emptyset$.

(2) \Rightarrow (1): By (2), for each $U \in \text{Nbh}_X(x)$ we can choose $x_U \in U \cap A$. Then $(x_U)_{U \in \text{Nbh}_X(x)}$ is a net in A converging to x . \square

Exercise 7.29. Let \mathcal{B} be a basis for the topology of X . Show that $x \in X$ is a closure point of A iff every $U \in \mathcal{B}$ containing x must intersect A .

Exercise 7.30. Let A be a subset of a metric space. Show that $x \in X$ is a closure point of A iff there is a sequence $(x_n)_{n \in \mathbb{Z}_+}$ in A converging to x .

Exercise 7.31. Recall that if X is a metric space, then $\overline{B}_X(x, r) = \{y \in X : d(x, y) \leq r\}$. Show that

$$\overline{\overline{B}_X(x, r)} \subset \overline{B}_X(x, r) \tag{7.4}$$

and that these two sets are not necessarily equal.

Remark 7.32. Our proof of (2) \Rightarrow (1) in Def. 7.28 is an indirect proof, because it uses axiom of choice. (Given $U \in \text{Nbh}_X(x)$, the choice of $x_U \in U \cap A$ is highly arbitrary.) Here is a direct proof: Assume (2). Define a direct set (I, \leq) where

$$\begin{aligned} I &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U \cap A\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned}$$

The fact that I is a directed set is due to (2). Then $(p)_{(p, U) \in I}$ is a net in A converging to x .

We will often prove results about nets in topological spaces using axiom of choice, not only because it is simpler than direct proofs (as above), but also because it is parallel to our use of sequences in metric spaces. (For example, see the proof of (1) \Rightarrow (2) in Def. 2.38.) However, it is important to know how to give a direct proof. This is because the studies of topological spaces using nets and using open sets are often equivalent, and direct proofs using nets can be more easily translated into proofs using open sets and vice versa. \square

Exercise 7.33. Prove $\neg(1) \Rightarrow \neg(2)$ of Def. 7.26 without using axiom of choice.

Remark 7.34. There is a notion closely related to closure points, called accumulation points. Let A be a subset of X . A point $x \in X$ is called a **accumulation point** (or **limit point** or **cluster point**) of A , if x is a closure point of $A \setminus \{x\}$.

We will not use the notion of accumulation points, although this concept is widely used in many textbooks on analysis or point-set topology. We use closure points instead. (But note that if $x \notin A$, then x is a closure point iff x is an accumulation point.) On the other hand, the following opposite notion of accumulation points is important and has a clear geometric picture: \square

Definition 7.35. We say that $x \in X$ is an **isolated point** of X , if the following (clearly) equivalent conditions hold:

- (1) $x \notin \overline{X \setminus \{x\}}$.
- (2) There is no net in $X \setminus \{x\}$ converging to x .
- (3) There is a neighborhood of x disjoint from $X \setminus \{x\}$.

If X is a metric space, then x is an isolated point iff there is no sequence in $X \setminus \{x\}$ converging to x .

We return to the study of closures.

Proposition 7.36. Let A be a subset of X . Then $\overline{\overline{A}} = \overline{A}$.

Proof. Choose any $x \in \overline{\overline{A}}$. To prove $x \in \overline{A}$, we choose any $U \in \text{Nbh}_X(x)$, and try to prove $U \cap A \neq \emptyset$. Since x is a closure point of \overline{A} , U intersects \overline{A} . Pick $y \in U \cap \overline{A}$. Then y is a closure point of A , and $U \in \text{Nbh}_X(y)$. So U intersects A . \square

One should think of $\overline{\overline{A}} = \overline{A}$ not only as a “geometric” fact about closures. Instead, one should also understand its analytic content: A closure point of A is a point which can be approximated by elements of A . Thus, $\overline{\overline{A}} = \overline{A}$ says that “approximation is transitive”: If x can be approximated by some elements which can be approximated by elements of A , then x can be approximated by elements of A . Alternatively, one can use the language of density:

Definition 7.37. A subset A of X is called **dense** (in X) if $\overline{A} = X$.

Exercise 7.38. Show that A is dense in X iff every nonempty open subset of X intersects A .

Remark 7.39. Let $A \subset B \subset X$. From Def. 7.28-(1), it is clear that

$$\text{Cl}_B(A) = \text{Cl}_X(A) \cap B \tag{7.5}$$

Thus, A is dense in B iff $B \subset \text{Cl}_X(A)$.

Thus, the following property has the same meaning as $\overline{\overline{A}} = A$.

Corollary 7.40. *Let $A \subset B \subset X$. Assume that A is dense in B , and B is dense in X , then A is dense in X .*

Proof. Choose any $x \in X$. Then $x \in \text{Cl}_X(B)$ since B is dense in X . Since A is dense in B , we have $B \subset \text{Cl}_X(A)$. Therefore $x \in \text{Cl}_X(\text{Cl}_X(A))$, and hence $x \in \text{Cl}_X(A)$ by Prop. 7.36. \square

Example 7.41. Let $X = C([0, 1], \mathbb{R})$, equipped with the l^∞ -norm. Let B be the set of polynomials with real coefficients, regarded as continuous functions on $[0, 1]$. By Weierstrass approximation theorem (which will be studied in the future), B is a dense subset of X . Then the set A of polynomials with rational coefficients is clearly a dense subset of B under the l^∞ -norm. (Proof: Let $f(x) = a_0 + a_1x + \cdots + a_kx^k$. For each $0 \leq i \leq k$, choose a sequence $(a_{i,n})_{n \in \mathbb{Z}_+}$ in \mathbb{Q} converging to a_i . Let $f_n(x) = a_{0,n} + a_{1,n}x + \cdots + a_{k,n}x^k$. Then $f_n \rightrightarrows f$ on $[0, 1]$.) Therefore, A is dense in X . To summarize:

- Since each continuous function on $[0, 1]$ can be uniformly approximated by polynomials with \mathbb{R} -coefficients, and since each polynomial can be uniformly approximated polynomials with \mathbb{Q} -coefficients, therefore each continuous function on $[0, 1]$ can be uniformly approximated by polynomials with \mathbb{Q} -coefficients.

7.3.2 Interior points

Interior points are dual to closure points:

Definition 7.42. Let A be a subset of X . A point $x \in X$ is called an **interior point** of A if the following equivalent conditions hold:

- (1) There exists $U \in \text{Nbh}_X(x)$ such that $U \subset A$.
- (2) x is not a closure point of $X \setminus A$.

The set of interior points of A is called the **interior** of A and is denoted by $\text{Int}_X(A)$ or simply $\text{Int}(A)$. So

$$X \setminus \text{Int}(A) = \overline{X \setminus A} \quad (\text{or simply } \text{Int}(A)^c = \overline{A^c}) \quad (7.6)$$

according to (2). In particular, $\text{Int}(A) \subset A$.

Proof of equivalence. A contains no neighborhoods of x with respect to X iff A^c intersects every neighborhood of x iff x is a closure point of A^c . \square

It is clear that if \mathcal{B} is a basis for the topology, then $x \in \text{Int}(A)$ iff there exists $U \in \mathcal{B}$ such that $x \in U \subset A$.

In analysis, interior points are not as commonly used as closure points. The following property is an important situation where interior points are used:

Proposition 7.43. *Let U be a subset of X . Then U is open iff every point of U is an interior point.*

In other words, U is open iff $U = \text{Int}_X(U)$.

Proof. If U is open and $x \in U$, then $U \in \text{Nbh}_X(x)$. So x is an interior point of U .

Conversely, suppose that each $x \in U$ is interior. Choose $V_x \in \text{Nbh}_X(x)$. Then $U = \bigcup_{x \in U} V_x$. So U is open by the union property in Def. 7.9. \square

Note that this is the first time we seriously use the fact that a union of open sets is open.

7.3.3 Closed sets and open sets

Definition 7.44. We say that $A \subset X$ is a **closed (sub)set** of X if $\overline{A} = A$.

Exercise 7.45. Show that the above definition of closed subsets agrees with Def. 3.26 when X is a metric space.

Exercise 7.46. Show that a finite subset of a Hausdorff space is closed. Give an example of non-closed finite subset of a non-Hausdorff topological space.

Remark 7.47. The closure \overline{A} is the smallest closed set containing A . (Proof: By Prop. 7.36, \overline{A} is closed. If B is closed and contains A , then $\overline{A} \subset \overline{B} = B$.)

Theorem 7.48. *Let A be a subset of X . Then A is closed iff $X \setminus A$ is open.*

Proof. Let $B = X \setminus A$. Then A is closed iff every closure point of A is in A , iff every non-interior point of B is not in B , iff every point in B is an interior point of B . By Prop. 7.43, this is equivalent to that B is open. \square

Corollary 7.49. \emptyset and X are closed subsets of X . An intersection of closed subsets is closed. A finite union of closed subsets is closed.

Proof. Take the complement of Def. 7.9, and apply Thm. 7.48. (Of course, they can also be proved directly using the condition $A = \overline{A}$ for closedness.) \square

Corollary 7.50. X is Hausdorff iff for every distinct $x, y \in X$ there exists $U \in \text{Nbh}_X(x)$ such that $y \notin \overline{U}$.

Proof. “ \Leftarrow ”: Let $x \neq y$. Choose $U \in \text{Nbh}(x)$ such that $y \notin \overline{U}$. Then $X \setminus \overline{U} \in \text{Nbh}(y)$ by Thm. 7.48. So x and y are separated by neighborhoods $U, X \setminus \overline{U}$.

“ \Rightarrow ”: Let $x \neq y$. Choose disjoint $U \in \text{Nbh}(x)$ and $V \in \text{Nbh}(y)$. Then $X \setminus V$ is closed by Thm. 7.48. So $\overline{U} \subset X \setminus V$ by Rem. 7.47. So $y \notin \overline{U}$. \square

Corollary 7.51. *Let Y be a subset of X , and let $A \subset Y$. Then the following are equivalent.*

- (1) *A is a closed subset of Y .*
- (2) *$A = B \cap Y$ for some closed subset B of X .*

Note that the “open subset” version of this corollary is true due to the definition of the subspace topology of Y (cf. Def. 7.19).

First proof. A is closed in Y iff $Y \setminus A = Y \cap A^c$ is open in Y , iff $Y \cap A^c$ equals $Y \cap U$ for some open subset $U \subset X$, iff $Y \cap A$ (which is A) equals $Y \cap U^c$ for some open subset $U \subset X$. This finishes the proof, thanks to Thm. 7.48. \square

Second proof. Recall by (7.5) that $\overline{A} \cap Y$ is the closure of A in Y . Then A is closed in Y iff $A = \overline{A} \cap Y$. This proves (1) \Rightarrow (2) since \overline{A} is closed by Prop. 7.36. Assume (2). Then $A = B \cap Y$ where $B = \overline{B}$. So $\overline{A} \cap Y = \overline{B \cap Y} \cap Y \subset \overline{B} \cap Y = B \cap Y = A$. This proves (1). \square

As an immediate consequence of Def. 7.9 and Cor. 7.51, we have:

Exercise 7.52. Let $A \subset B \subset X$.

1. Prove that if B is open in X , then A is open in B iff A is open in X .
2. Prove that if B is closed in X , then A is closed in B iff A is closed in X .

Remark 7.53. Many people define a closed set to be the complement of an open set, and then proves that a set A is closed iff $A = \overline{A}$. I went the other way because I believe that $A = \overline{A}$ is more essential for understanding of closedness from the viewpoint of analysis. In Thm. 3.48, we have already seen a classical example of closed set in analysis: $C([0, 1], \mathbb{R})$ is a closed subset of $l^\infty([0, 1], \mathbb{R})$, which has the clear analytic meaning that the uniform limit of a sequence/net of continuous functions $[0, 1] \rightarrow \mathbb{R}$ is continuous. And we will see many more examples of this type in the future.

Remark 7.54. I defined closedness using $A = \overline{A}$, and hence using the limits of nets. This is because the intuition of closed sets is very closely related to the intuition of limits of nets/sequences. On the other hand, the intuition of open sets is very different. Let me say a few words about this.

Without a doubt, the keyword I give for the intuition of limits of nets is “approximation”: Limit is not only a dynamic process, but also gives an impression of “getting smaller and smaller”. When dealing with closed sets, we often do the same thing! We take an intersection of possibly infinitely many closed subsets, and the result we get is still a closed set (cf. Cor. 2.4).

The keyword I give for open sets is “local”, or more precisely, “local-to-global” (as opposed to “getting smaller and smaller”). This is not only because a union of

open sets is open, but also because open sets are very often used to prove a global result by reducing to local problems. One easy example is Exe. 7.119, which says that in order to prove that a function is continuous on the whole space X , it suffices to prove this locally. (We have already used this strategy in Sec. 2.4.) Here is a more advanced example: to define the integral for a function on a large set, one can first define it locally (i.e. on small enough open subsets), and then patch these local values together. We will see many examples in the future, for example, in the following chapter about compactness.

Remark 7.55. Very often, a theorem is an important result establishing two seemingly different (systems of) intuitions, and hence two different ways of mathematical thinking. This is why I call “closed sets are the complements of open sets” a theorem. The term “complement” implies that this theorem often manifests itself in the following way: If solving a problem using open sets is a direct proof, then solving the problem using limits of sequences/nets is a proof by contradiction/contrapositive. And vice versa.

7.4 Continuous maps and homeomorphisms

Unless otherwise stated, X and Y are topological spaces.

7.4.1 Continuous maps

Definition 7.56. Let $f : X \rightarrow Y$ be a map. Let $x \in X$. We say that f is **continuous at x** if the following equivalent conditions hold:

- (1) For every net $(x_\alpha)_{\alpha \in I}$ in X converging to x , we have $\lim_{\alpha \in I} f(x_\alpha) = f(x)$.
- (2) For every $V \in \text{Nbh}_Y(f(x))$, there exists $U \in \text{Nbh}_X(x)$ such that for every $p \in U$ we have $f(p) \in V$.
- (2') For every $V \in \text{Nbh}_Y(f(x))$, the point x is an interior point of $f^{-1}(V)$.

We say that f is a **continuous function/map**, if f is continuous at every point of X .

It is clear that “for every $V \in \text{Nbh}_Y(f(x))$ ” in (2) and (2') can be replaced by “for every $V \in \mathcal{B}$ containing $f(x)$ ” if \mathcal{B} is a basis for the topology of Y .

Note that in the case that (x_α) or $(f(x_\alpha))$ has more than one limits (which could happen when X or Y is not Hausdorff), condition (1) means that $f(x)$ is one of the limits of $(f(x_\alpha))_{\alpha \in I}$ if x is one of the limits of (x_α) .

Proof of equivalence. Clearly (2) is equivalent to (2'). The proof of (2) \Rightarrow (1) is similar to the case of sequences in metric spaces. (See Def. 2.38.) We leave the details to the reader.

$\neg(2) \Rightarrow \neg(1)$: Assume that (2) is not true. Then there is a neighborhood V of $f(x)$ such that for every neighborhood U of x there exists $x_U \in U$ such that $f(x_U) \notin V$. Then $(x_U)_{U \in \text{Nbh}_X(x)}$ is a net in X , and $\lim_U x_U = x$ since $x_U \in U$. However, for each U we have $f(x_U) \in Y \setminus V$. So $\lim_U f(x_U)$ cannot converge to $f(x)$. \square

Exercise 7.57. Show that when X, Y are metric spaces, Def. 7.56 agrees with Def. 2.38.

Exercise 7.58. Let $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ be maps of topological spaces. Assume that f is continuous at $x \in X$, and g is continuous at $f(x)$. Prove that $g \circ f : X \rightarrow Z$ is continuous at x .

The proof of (1) \Rightarrow (2) in Def. 7.56 is indirect, since it uses the axiom of choice. (The merit of this proof is that it is parallel to the proof for metric spaces in Sec. 2.4.) One can also give a direct proof. Indeed, there is a particular net (x_α) converging to x such that $\lim f(x_\alpha) = f(x)$ iff (2) is true:

Exercise 7.59. Define $(\text{PNbh}_X(x), \leq)$, the **directed set of pointed neighborhoods** of x , to be

$$\begin{aligned} \text{PNbh}_X(x) &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned} \quad (7.7)$$

For each $\alpha = (p, U) \in \text{PNbh}_X(x)$, let $x_\alpha = p$. Then $(x_\alpha)_{\alpha \in \text{PNbh}_X(x)}$ is a net in X converging to x . Prove that f is continuous at x iff $\lim_\alpha f(x_\alpha) = f(x)$.

Proposition 7.60. Let $f : X \rightarrow Y$ be a map. The following are equivalent:

- (1) f is continuous.
- (2) If $V \subset Y$ is open in Y , then $f^{-1}(V)$ is open in X .
- (3) If $F \subset Y$ is closed in Y , then $f^{-1}(F)$ is closed in X .

Proof. (1) \Leftrightarrow (2): By Def. 7.56-(2') and Prop. 7.43. (2) \Leftrightarrow (3): By Thm. 7.48 and the fact that $f^{-1}(B^c) = f^{-1}(B)^c$ for every $B \subset Y$. \square

Remark 7.61. We first defined the continuity of f at a point, and then used this to define a continuous function f to be one continuous at every point. However, it seems that the notion of continuity at a point is used only in analysis. In geometry and in topology, only continuous maps (but not a map continuous at a point) are used, and they are defined by Prop. 7.60-(2).

One might think that continuous functions are special cases of functions which are continuous at given points. But in fact, the latter notion can also be derived from the former: \square

Exercise 7.62. Let $f : (X, \mathcal{T}) \rightarrow (Y, \mathcal{T}')$ be a map of topological spaces. Let $x \in X$. Define a new topological space (X_x, \mathcal{T}_x) as follows. X_x equals X as a set. The topology \mathcal{T}_x of X_x is generated by the basis

$$\mathcal{B}_x = \text{Nbh}_X(x) \cup \{\{p\} : p \neq x\} \quad (7.8)$$

Prove that if X is Hausdorff, then X_x is Hausdorff. Prove that the following are equivalent:

- (1) $f : X \rightarrow Y$ is continuous at x .
- (2) $f : X_x \rightarrow Y$ is continuous.

Continuous functions are determined by their values on a dense subset:

Proposition 7.63. Let A be a subset of X , and let $f, g : \bar{A} \rightarrow Y$ be continuous. Then

$$f(\bar{A}) \subset \overline{f(A)} \quad (7.9a)$$

If Y is moreover Hausdorff, then

$$f = g \quad \Longleftrightarrow \quad f|_A = g|_A \quad (7.9b)$$

Proof. If $y \in f(\bar{A})$, then $y = f(x)$ for some $x \in \bar{A}$. Choose a net (x_α) in A converging to x . Then $\lim_\alpha f(x_\alpha) = f(x)$, and hence $f(x) \in \overline{f(A)}$.

Assume that Y is Hausdorff. If $f = g$ then clearly $f|_A = g|_A$. Assume that $f|_A = g|_A$. For each $x \in \bar{A}$, choose a net (x_α) in A converging to x . Then $f(x) = \lim f(x_\alpha) = \lim g(x_\alpha) = g(x)$. So $f = g$. \square

You are encouraged to prove Prop. 7.63 using open sets instead of using nets.

7.4.2 Homeomorphisms

Definition 7.64. A map $f : X \rightarrow Y$ is called **open** (resp. **closed**) if for every open (resp. closed) subset $A \subset X$, the image $f(A)$ is open (resp. closed) in Y .

Definition 7.65. A bijection $f : X \rightarrow Y$ is called a **homeomorphism** if the following clearly equivalent conditions hold:

- (1) f and f^{-1} are continuous.
- (2) For every net (x_α) in X and each $x \in X$, we have that $\lim_\alpha x_\alpha = x$ iff $\lim_\alpha f(x_\alpha) = f(x)$.
- (3) f is continuous and open.
- (4) f is continuous and closed.

If a homeomorphism $f : X \rightarrow Y$ exists, we say that X, Y are **homeomorphic**.

Recall from Def. 2.60 that when X, Y are metric spaces, the sequential version of (2) holds.

Remark 7.66. Let $\mathcal{T}_1, \mathcal{T}_2$ be two topologies on a set X . Clearly, we have $\mathcal{T}_1 = \mathcal{T}_2$ iff

$$\varphi : (X, \mathcal{T}_1) \rightarrow (X, \mathcal{T}_2) \quad x \mapsto x \quad (7.10)$$

is a homeomorphism. Thus, the following are equivalent:

- (1) $\mathcal{T}_1 = \mathcal{T}_2$.
- (2) For every net (x_α) in X and $x \in X$, we have that $\lim_\alpha x_\alpha = x$ under \mathcal{T}_1 iff $\lim_\alpha x_\alpha = x$ under \mathcal{T}_2 .

This equivalence implies that

topologies are determined by net convergence

Therefore, instead of using open sets or bases of topologies to describe a topology, one can also describe a topology \mathcal{T} on a set X in the following way:

$$\begin{aligned} \mathcal{T} \text{ is the unique topology on } X \text{ such that} \\ \text{a net } (x_\alpha) \text{ in } X \text{ converges to } x \in X \text{ iff ...} \end{aligned} \quad (7.11)$$

Similarly, by Def. 2.60, metrizable topologies are determined by sequential convergence. Therefore, metrizable topologies can be described in the following way:

$$\begin{aligned} \mathcal{T} \text{ is the unique metrizable topology on } X \text{ such that} \\ \text{a sequence } (x_n) \text{ in } X \text{ converges to } x \in X \text{ iff ...} \end{aligned} \quad (7.12)$$

7.5 Examples of topological spaces described by net convergence

Example 7.67. Let A be a subset of a topological space (X, \mathcal{T}_X) . Then the subspace topology \mathcal{T}_A of A is the unique topology such that a net (x_α) in A converges to $x \in A$ under \mathcal{T}_A iff it converges to x under \mathcal{T}_X .

★ **Example 7.68.** Let $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ be a disjoint union where each $(X_\alpha, \mathcal{T}_\alpha)$ is a topology space. Then

$$\mathcal{B} = \bigcup_{\alpha \in \mathcal{A}} \mathcal{T}_\alpha$$

is clearly a basis generating a topology \mathcal{T} on X , called **disjoint union topology**. \mathcal{T} is the unique topology on X such that for every net $(x_\mu)_{\mu \in I}$ in X and any $x \in X$, the following are equivalent:

(1) $(x_\mu)_{\mu \in I}$ converges to x under \mathcal{T} .

(2) There exists $\nu \in I$ such that for every $\mu \geq \nu$, the element x_μ belongs to the unique X_α containing x . Moreover, $\lim_{\mu \in I, \mu \geq \nu} x_\mu = x$ in X_α .

We call (X, \mathcal{T}) the **disjoint union topological space** of $(X_\alpha)_{\alpha \in \mathcal{A}}$.

The following exercise says that “disjoint union of topological spaces” is synonymous with “disjoint union of open subsets”.

★ **Exercise 7.69.** Assume that $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$. Assume that X has a topology \mathcal{T} , and equip each X_α with the subspace topology. Show that (X, \mathcal{T}) is the disjoint union topological space of $(X_\alpha)_{\alpha \in \mathcal{A}}$ iff each X_α is an open subset of (X, \mathcal{T}) .

Thus, for example, $\bigcup_{n \in \mathbb{N}} [2n, 2n+1)$ (under the Euclidean topology) is the disjoint union topological space of the family $([2n, 2n+1))_{n \in \mathbb{N}}$.

★ **Exercise 7.70.** In Exp. 7.68, assume that each $(X_\alpha, \mathcal{T}_\alpha)$ is metrizable. Prove that (X, \mathcal{T}) is metrizable. More precisely: Choose a metric d_α inducing \mathcal{T}_α , and assume that $d_\alpha \leq 1$ (cf. Prop. 2.74). Define a metric d on X as in Pb. 2.4. Solve the *net version* of part 2 of Pb. 2.4. Conclude from this that d induces the topology \mathcal{T} . (Warning: we cannot conclude this from the original sequential version of Pb. 2.4-2.)

Definition 7.71. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ be a family of topological spaces. Elements of the product space

$$S = \prod_{\alpha \in \mathcal{A}} X_\alpha$$

are denoted by $x = (x(\alpha))_{\alpha \in \mathcal{A}}$. One checks easily that

$$\mathcal{B} = \left\{ \prod_{\alpha \in \mathcal{A}} U_\alpha : \text{each } U_\alpha \text{ is open in } X_\alpha, \right. \\ \left. U_\alpha = X_\alpha \text{ for all but finitely many } \alpha \right\} \quad (7.13)$$

is a basis for a topology \mathcal{T} , called the **product topology** or **pointwise convergence topology** of S . We call (S, \mathcal{T}) the **product topological space**.

Equivalently, let

$$\pi_\alpha : S \rightarrow X_\alpha \quad x \mapsto x(\alpha) \quad (7.14)$$

be the **projection map onto the X_α component**. Then

$$\mathcal{B} = \left\{ \bigcap_{\alpha \in E} \pi_\alpha^{-1}(U_\alpha) : E \in \text{fin}(2^{\mathcal{A}}), U_\alpha \text{ is open in } X_\alpha \text{ for each } \alpha \in E \right\} \quad (7.15)$$

Unless otherwise stated, a product of topological spaces is equipped with the product topology. □

Example 7.72. Let $S = X_1 \times \cdots \times X_N$ be a finite product of topological spaces. Then the product topology has a basis

$$\mathcal{B} = \{U_1 \times \cdots \times U_N : \text{each } U_i \text{ is open in } X_i\} \quad (7.16)$$

Theorem 7.73. Let $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ be a product of topological spaces, equipped with the product topology. Then each projection map π_α is continuous. Moreover, for every net $(x_\mu)_{\mu \in I}$ in S and every $x \in S$, the following are equivalent.

- (1) $\lim_{\mu \in I} x_\mu = x$ in S .
- (2) For every $\alpha \in \mathcal{A}$, we have $\lim_{\mu \in I} x_\mu(\alpha) = x(\alpha)$ in X_α .

If (x_μ) satisfies (1) or (2), we say that x_μ **converges pointwise** to x if we view (x_μ) as a net of functions with domain \mathcal{A} .

Proof. We leave the proof to the readers. Note that the continuity of π_α follows easily from the basis-for-topology version of Prop. 7.60-(2). And from the continuity of π_α one easily deduce (1) \Rightarrow (2). \square

Remark 7.74. In the spirit of (7.11), one says that:

- The product topology \mathcal{T} on $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ is the unique topology such that a net (x_μ) converges to x under \mathcal{T} iff x_μ converges pointwise to x as a net of functions on \mathcal{A} .

Corollary 7.75. If each X_α is a Hausdorff space, then $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ is Hausdorff.

Proof. Either prove this directly using the basis for the topology, or prove that any net cannot converge to two different values using Thm. 7.73. \square

Corollary 7.76. Let X_1, X_2, \dots be a possibly finite sequence of metric spaces. Then $S = \prod_i X_i$ is metrizable. More precisely, for each i , choose a metric d_i on X_i topologically equivalent to the original one such that $d_i \leq 1$ (cf. Prop. 2.4). Then the metric d on S defined by

$$d(f, g) = \sup_i \frac{d_i(f(i), g(i))}{i} \quad (7.17)$$

induce the product topology.

We note that the product topology is also induced by

$$\delta(f, g) = \sum_i 2^{-i} d_i(f(i), g(i)) \quad (7.18)$$

Proof. The same method for solving Pb. 2.3 also applies to its net version: One shows that a net (f_α) in S converges to f under d (or under δ) iff (f_α) converges pointwise to f . Thus, by Thm. 7.73, d and δ induce the product topology. \square

The next example discusses the topologies induced by uniform convergence metrics. (Recall Def. 3.58.) In this example, Y is usually a normed vector space.

Example 7.77. Let X be a set, and let (Y, d_Y) be a metric space. Then there is a unique topology \mathcal{T} on Y^X such that for every net $(f_\alpha)_{\alpha \in I}$ in Y^X and every $f \in Y^X$, the following are equivalent:

- (1) The net (f_α) converges to f under \mathcal{T} .
- (2) We have $\lim_{\alpha \in I} \sup_{x \in X} d_Y(f_\alpha(x), f(x)) = 0$.

(If (f_α) satisfies (2), we say that f_α **converges uniformly** to f .) For example, one checks easily that \mathcal{T} is induced by any **uniform convergence metric**, i.e., any metric on Y^X equivalent to d where

$$d(f, g) = \min \left\{ 1, \sup_{x \in X} d_Y(f(x), g(x)) \right\} \quad (7.19)$$

So \mathcal{T} is metrizable. We call \mathcal{T} the **uniform convergence topology** on Y^X .

Theorem 7.78. Let Y be a complete metric space. Let X be a set. Then Y^X , equipped with the metric (7.19), is complete.

Proof. It can be proved in a similar way as Thm. 3.45. We leave the details to the readers. \square

Theorem 7.79. Let V be a normed vector space over \mathbb{R} or \mathbb{C} . Let X be a topological space. Equip V^X with the uniform convergence topology. Then $C(X, V)$ is a closed subset of V^X .

Proof. This is similar to the proof of Thm. 3.48. Let (f_α) be a net $C(X, V)$ converging uniformly to $f : X \rightarrow V$. Choose any $x \in X$ and $\varepsilon > 0$. Then there is $\alpha \in I$ such that $\sup_{p \in X} \|f(x) - f_\alpha(x)\| < \varepsilon$. Since f_α is continuous, there is $U \in \text{Nbh}_X(x)$ such that for each $p \in U$ we have $\|f_\alpha(x) - f_\alpha(p)\| < \varepsilon$. Thus, for each $p \in U$ we have

$$\|f(x) - f(p)\| \leq \|f(x) - f_\alpha(x)\| + \|f_\alpha(x) - f_\alpha(p)\| + \|f_\alpha(p) - f(p)\| < 3\varepsilon$$

So f is continuous. \square

Remark 7.80. Note that the uniform convergence topology depends on the equivalence class (not just the topological equivalence class) of d_Y . Thus, one needs metrics when talking about uniform convergence. On the other hand, the study of pointwise convergence does not require metrics.

7.6 Limits of functions

By Prop. 7.63, if $A \subset X$, and if $f : \bar{A} \rightarrow Y$ is continuous, then the value of f is uniquely determined by $f|_A$ provided that Y is Hausdorff (cf. Prop. 7.63). We now consider the opposite question of extension of continuous functions: Suppose that $f : A \rightarrow Y$ is continuous. Can we extend f to a continuous function $f : \bar{A} \rightarrow Y$? (We know that such extension must be unique if it exists.) The classical concept of the limits of functions can be understood in this light.

Definition 7.81. Let A be a subset of X . Let $f : A \rightarrow Y$ be a map. Let $x \in \bar{A} \setminus A$. Let $y \in Y$. We say that the **limit of the function** f at x is y and write

$$\lim_{\substack{p \in A \\ p \rightarrow x}} f(p) \equiv \lim_{p \rightarrow x} f(p) = y$$

if the following equivalent conditions hold:

- (1) If we extend f to a function $A \cup \{x\} \rightarrow Y$ satisfying $f(x) = y$, then $f : A \cup \{x\} \rightarrow Y$ is continuous at x .
- (2) For every $V \in \text{Nbh}_Y(y)$, there exists $U \in \text{Nbh}_X(x)$ such that for every $p \in U \cap A$, we have $f(p) \in V$.
- (3) For every net $(x_\alpha)_{\alpha \in I}$ in A converging to x , we have $\lim_{\alpha \in I} f(x_\alpha) = y$.

When X, Y are metric spaces, the above three conditions and the following two are equivalent:

- (2m) For every $\varepsilon > 0$, there exists $\delta > 0$ such that for every $p \in A$, if $d(p, x) < \delta$ then $d(f(p), y) < \varepsilon$.
- (3m) For every sequence $(x_n)_{n \in \mathbb{Z}_+}$ in A converging to x , we have $\lim_{n \rightarrow \infty} f(x_n) = y$.

Recall that by the definition of subspace topology, we have

$$\text{Nbh}_A(x) = \{U \cap A : A \in \text{Nbh}_X(x)\} \quad (7.20)$$

Proof of equivalence. Extend f to $\tilde{f} : A \cup \{x\} \rightarrow Y$ by setting $\tilde{f}(x) = y$. Then by Def. 7.56-(2), condition (1) of Def. 7.81 means that for every $V \in \text{Nbh}_Y(y)$ there is a neighborhood of x in $A \cup \{x\}$ (which, by (7.20), must be of the form $U \cap (A \cup \{x\})$ where $U \in \text{Nbh}_X(x)$) such that for every $p \in U \cap (A \cup \{x\})$ we have $\tilde{f}(p) \in V$. This is clearly equivalent to (2), since $\tilde{f}(x) = y \in V$. The equivalence (2) \Leftrightarrow (3) can be proved in a similar way as the equivalence of (1) and (2) in Def. 7.56. We leave the details to the readers. When X, Y are metric spaces, (2) is clearly equivalent to (2m). The equivalence (2m) \Leftrightarrow (3m) can be proved in a similar way as the equivalence of (1) and (2) in Def. 2.38. \square

The following remarks show that the limit of a function at a point is the limit of a single net, rather than the limit of many nets (as in Def. 7.81-(3)).

Remark 7.82. Assume the setting of Def. 7.81. In the same spirit of Exe. 7.59, define a directed set $(\text{PNbh}_A(x), \leq)$ where

$$\begin{aligned} \text{PNbh}_A(x) &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U \cap A\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned} \quad (7.21)$$

(That it is a directed set is due to $x \in \overline{A}$.) We have seen this directed set in Rem. 7.32. Then $(p)_{(p,U) \in \text{PNbh}_A(x)}$ is a net converging to x , and

$$\lim_{p \rightarrow x} f(p) = \lim_{(p,U) \in \text{PNbh}_A(x)} f(p) \quad (7.22)$$

where the convergence of the LHS is equivalent to that of the RHS.

Remark 7.83. In the setting of Def. 7.81, assume moreover that X is a metric space, then $\lim_{p \rightarrow x} f(p)$ can be described by the limit of a simpler net. Define a directed set (A_x, \leq) where

$$\begin{aligned} A_x &= A \text{ as sets} \\ p &\leq p' \iff d(p', x) \geq d(p, x) \end{aligned} \quad (7.23)$$

Then $(p)_{p \in A_x}$ is a net in A converging to x , and

$$\lim_{p \rightarrow x} f(p) = \lim_{p \in A_x} f(p) \quad (7.24)$$

where the convergence of the LHS is equivalent to that of the RHS.

Remark 7.84. Thanks to the above two remarks, limits of functions enjoy all the properties that limits of nets enjoy. For example, they satisfy Squeeze theorem; if $f : A \rightarrow \mathbb{F}$ and $g : A \rightarrow V$ (where V is a normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$), if $x \in \overline{A} \setminus A$, and if $\lambda = \lim_{p \rightarrow x} f(p)$ and $v = \lim_{p \rightarrow x} g(p)$ exist, then $\lim_{p \rightarrow x} f(p)g(p)$ converges to λv .

Of course, you can also conclude them by using Def. 7.81-(3) instead of Rem. 7.82. In practice, it makes no difference whether you view $\lim_{p \rightarrow x} f(p)$ as the limit of $f(x_\alpha)$ for an arbitrary net x_α in A converging to x , or whether you view $\lim_{p \rightarrow x} f(p)$ as the limit of the particular net in Rem. 7.82 or Rem. 7.83. The explicit constructions of nets in these two remarks are not important for proving results about limits of functions. \square

Remark 7.85. Let $f : A \rightarrow Y$, and let $x \in \overline{A} \setminus A$. Suppose that Y is Hausdorff. Assume that there exist two nets $(x_\alpha)_{\alpha \in I}$ and $(y_\beta)_{\beta \in J}$ in A converging to x such that $(f(x_\alpha))$ and $(f(y_\beta))$ converge to two different values. Then by Def. 7.81-(2), the limit $\lim_{p \rightarrow x} f(p)$ does not exist.

The above remark gives a useful criterion for the non-convergence of limits of functions. The following proposition, on the other hand, gives a method of computing limits of functions by decomposing the domain into (non-necessarily mutually disjoint) subsets.

Proposition 7.86. *Assume the setting of Def. 7.81. Assume that $A = A_1 \cup \cdots \cup A_N$. Then the following are equivalent.*

(1) We have $\lim_{p \rightarrow x} f(p) = y$.

(2) For every $1 \leq i \leq N$ such that $x \in \overline{A_i}$, we have $\lim_{p \rightarrow x} f|_{A_i}(p) = y$

Proof. (1) \Rightarrow (2): Assume (1). Extend $f : A \rightarrow Y$ to a function $\tilde{f} : A \cup \{x\} \rightarrow Y$ by setting $\tilde{f}(x) = y$. Then \tilde{f} is continuous by (1). Thus, if $x \in \overline{A_i}$, then $\tilde{f}|_{A_i \cup \{x\}}$ is continuous. This proves (2).

(2) \Rightarrow (1): Assume (2). Choose any $V \in \text{Nbh}_Y(y)$. By (2), for each i , either $x \in \overline{A_i}$ so that there is $U_i \in \text{Nbh}_X(x)$ satisfying $U_i \cap A_i \subset f^{-1}(V)$ (recall (7.20)), or that $x \notin \overline{A_i}$ so that there is $U_i \in \text{Nbh}_X(x)$ disjoint from A_i . In either case, we have $U_i \cap A_i \subset f^{-1}(V)$. Let $U = U_1 \cap \cdots \cap U_N$. Then

$$U \cap A = U \cap (A_1 \cup \cdots \cup A_N) = \bigcup_i U \cap A_i \subset \bigcup_i U_i \cap A_i$$

which is therefore a subset of $f^{-1}(V)$.

Another proof of $\neg(1) \Rightarrow \neg(2)$: Assume (1) is not true. Then there is a net $(x_\alpha)_{\alpha \in I}$ in A converging to x such that $f(x_\alpha)$ does not converge to y . So there exists $V \in \text{Nbh}_Y(y)$ such that $f(x_\alpha)$ is not eventually in V , i.e., $f(x_\alpha)$ is frequently in V^c . Then $(f(x_\alpha))$ has a subnet $(f(x_\beta))_{\beta \in J}$ which is always in V^c . For example, take

$$J = \{\beta \in I : f(x_\beta) \in V^c\}$$

Since $(x_\beta)_{\beta \in J}$ is always in A , by the logic (5.6c), there is $1 \leq i \leq N$ such that (x_β) is frequently in A_i . Thus, by the same argument as above, (x_β) has a subnet $(x_\gamma)_{\gamma \in K}$ which is always in A_i . Since $x_\alpha \rightarrow x$, we have $x_\gamma \rightarrow x$, and hence $x \in \overline{A_i}$. But $f(x_\gamma) \in V^c$. So we have found a net (x_γ) in A_i converging to x such that $(f(x_\gamma))$ does not converge to y . This disproves (2). \square

Remark 7.87. In many textbooks, $\lim_{p \rightarrow x} f(p)$ is also defined more generally when x is an accumulation point of A , i.e., when $x \in \overline{A \setminus \{x\}}$. In this case, the limit of f at x simply means

$$\lim_{p \rightarrow x} f(p) \stackrel{\text{def}}{=} \lim_{p \rightarrow x} f|_{A \setminus \{x\}}(p) \quad (7.25)$$

This more general case is important in classical analysis, but is less useful in abstract analysis. (As a matter of fact, accumulation points are less convenient than closure points.) In order not to deviate too far from the traditional analysis textbooks, let's take a look at some examples.

Definition 7.88. Let $A \subset \mathbb{R}$ and $x \in \mathbb{R}$. Let $f : A \rightarrow Y$ be a function. If x is a closure point of $A \cap \mathbb{R}_{<x}$ resp. $A \cap \mathbb{R}_{>x}$, we define the **left limit** resp. **right limit** to be

$$\lim_{t \rightarrow x^-} f(t) = \lim_{t \rightarrow x} f|_{A \cap \mathbb{R}_{<x}}(t) \quad (7.26a)$$

$$\lim_{t \rightarrow x^+} f(t) = \lim_{t \rightarrow x} f|_{A \cap \mathbb{R}_{>x}}(t) \quad (7.26b)$$

If $x \in \overline{\mathbb{R}}$ and x is a closure point of $A \setminus \{x\}$, then $\lim_{t \rightarrow x} f(t)$ is understood by (7.25).

Remark 7.89. In Def. 7.88, if $x \in \mathbb{R}$ is a closure point of $A \setminus \{x\}$, then by Prop. 7.86,

$$\lim_{p \rightarrow x} f(p) = y \quad \Longleftrightarrow \quad \lim_{p \rightarrow x^-} f(p) = \lim_{p \rightarrow x^+} f(p) = y \quad (7.27)$$

In particular, the existence of the limit on the LHS is equivalent to the existence and the equality of the two limits on the RHS.

Example 7.90. Let $g, h : \mathbb{R} \rightarrow \mathbb{R}$ be continuous functions. Let $c \in \mathbb{R}$. Define $f : \mathbb{R} \rightarrow \mathbb{R}$ to be

$$f(x) = \begin{cases} g(x) & \text{if } x < 0 \\ c & \text{if } x = 0 \\ h(x) & \text{if } x > 0 \end{cases}$$

Since $g|_{(-\infty, 0]}$ is continuous, by Def. 7.81-(1) we have that $\lim_{x \rightarrow 0^-} f(x) = \lim_{x \rightarrow 0, t < 0} g(t) = g(0)$. Similarly, $\lim_{x \rightarrow 0^+} f(x) = h(0)$. Therefore, by Rem. 7.89, $\lim_{x \rightarrow 0} f(x)$ exists iff $g(0) = h(0)$, and it converges to $g(0)$ if $g(0) = h(0)$. The value c is irrelevant to the limits.

Example 7.91. Let $f : X = \mathbb{R}^2 \setminus \{(0, 0)\} \rightarrow \mathbb{R}$ be $f(x, y) = \frac{x}{x+y}$. Then $(1/n, 0)$ and $(0, 1/n)$ are sequences in X converging to 0. But $f(1/n, 0) = 1$ and $f(0, 1/n) = 0$. So $\lim_{(x,y) \rightarrow (0,0)} f(x, y)$ does not exist by Rem. 7.85.

7.7 Connected spaces

Let X be a topological space. In this section, we shall define a notion of connected space. Based on our usual geometric intuition, one might attempt to define a connected space as one satisfying that any two points can be linked by a path. Such spaces are actually called **path-connected spaces** and is stronger than connected spaces. In fact, connected spaces arise from the study of intermediate value problem.

7.7.1 Connected \Leftrightarrow IVP

Definition 7.92. We say that the topological space X is **connected** if X can not be written as the disjoint of two nonempty open sets. Namely, if $X = U \sqcup V$ where U, V are open subsets of X , then either $U = \emptyset$ (and hence $V = X$) or $V = \emptyset$ (and hence $U = X$).

Equivalently (by Thm. 7.48), X is connected iff every $U \subset X$ which is both closed and open must be \emptyset or X .

Definition 7.93. We say that X satisfies the **intermediate value property** (abbreviated to **IVP**) if for every continuous function $f : X \rightarrow \mathbb{R}$ and every $x, y \in X$ we have

$$f(x) < f(y) \implies [f(x), f(y)] \subset f(X) \quad (7.28)$$

Theorem 7.94. X is connected iff X satisfies IVP. Moreover, if X is not connected, then there is a continuous $f : X \rightarrow \mathbb{R}$ such that $f(X) = \{0, 1\}$.

Proof. First, assume that X does not satisfy IVP. Choose a continuous $f : X \rightarrow \mathbb{R}$ with real numbers $a < b < c$ such that $a, c \in f(X)$ but $b \notin f(X)$. So $U = f^{-1}(-\infty, b)$ and $V = f^{-1}(b, +\infty)$ are disjoint non-empty open subsets of X , and $X = U \sqcup V$. They are open, because f is continuous (cf. Prop. 7.60). So X is not connected.

Next, assume that X is not connected. Then $X = U \sqcup V$ where U, V are open subsets of X . Define $f : X \rightarrow \mathbb{R}$ to be constantly 0 on U and constantly 1 on V . It is easy to check that f is continuous. (See also Rem. 7.120.) That $f(X) = \{0, 1\}$ means that X does not satisfy IVP. \square

We now give a couple of elementary examples.

7.7.2 Connected subsets of $\overline{\mathbb{R}}$ are precisely intervals

Proposition 7.95. Let A be a dense subset of X . Assume that A is connected. Then X is connected.

Proof. If $X = \overline{A}$ is not connected, then by Thm. 7.94, there exists a continuous surjection $f : \overline{A} \rightarrow \{0, 1\}$. By Prop. 7.63, $\overline{f(A)}$ contains $f(\overline{A})$. So $f(A)$ has closure $\{0, 1\}$. So $f(A) = \{0, 1\}$. A does not satisfy IVP, and hence is not connected. \square

Theorem 7.96. Let A be a nonempty subset of $\overline{\mathbb{R}}$. Then A is connected iff A is an interval.

Proof. Step 1. Suppose that A is connected. Let $a = \inf A$ and $b = \sup A$. To show that A is one of (a, b) , $(a, b]$, $[a, b)$, $[a, b]$, it suffices to show that every $c \in (a, b)$ belongs to A . Suppose that some $c \in (a, b)$ does not belong to A . Then A is the disjoint union of two nonempty open subsets $A \cap [-\infty, c)$ and $A \cap (c, +\infty]$, impossible.

Step 2. Every single point is clearly connected. Since every interval containing at least two points is homeomorphic to one of $[0, 1]$, $(0, 1]$, $[0, 1)$, $(0, 1)$, it suffices to prove that these four intervals are connected. Since $(0, 1)$ is dense in the other three intervals, by Prop. 7.95, it suffices to prove that $(0, 1)$ is connected.

Suppose that $(0, 1)$ is not connected. Then $(0, 1) = U \sqcup V$ where U, V are disjoint open nonempty subsets. Choose $x_1 \in U$ and $y_1 \in V$, and assume WLOG that $x_1 < y_1$. In the following, we construct an increasing sequence (x_n) in U and a decreasing one (y_n) in V satisfying $x_n < y_n$ for all n by induction. Suppose x_n, y_n has been constructed. Let $z_n = (x_n + y_n)/2$.

- If $z_n \in U$, then let $x_{n+1} = z_n$ and $y_{n+1} = y_n$.
- If $z_n \in V$, then let $x_{n+1} = x_n$ and $y_{n+1} = z_n$.

Then $y_n - x_n$ converges to 0. So x_n and y_n converge to the same point $\xi \in \mathbb{R}$. We have $\xi \in (0, 1)$ since $x_1 < \xi < y_1$. Since V is open, $U = (0, 1) \setminus V$ is closed in $(0, 1)$ by Thm. 7.48. So $\xi \in \text{Cl}_{(0,1)}(U) = U$. Similarly, $\xi \in \text{Cl}_{(0,1)}(V) = V$. This is impossible. \square

7.7.3 More examples of connected spaces

Definition 7.97. Let $x, y \in X$. A **path** in X from x to y is defined to be a continuous map $\gamma : [a, b] \rightarrow X$ where $-\infty < a < b < +\infty$, such that $\gamma(a) = x$ and $\gamma(b) = y$. Unless otherwise stated, we take $[a, b]$ to be $[0, 1]$. We call x and y respectively the **initial point** and the **terminal point** of γ .

Definition 7.98. We say that X is **path-connected** if for every $x, y \in X$ there is a path in X from x to y .

Example 7.99. \mathbb{R}^N is path-connected. $B_{\mathbb{R}^N}(0, R)$ and $\overline{B}_{\mathbb{R}^N}(0, R)$ (where $R < +\infty$) are path connected. $\{x \in \mathbb{R}^N : r < x < R\}$ (where $0 \leq r < R < +\infty$) are path connected. The region enclosed by a triangle is a connected subset of \mathbb{R}^2 . $[0, 1]^N$ is connected.

Theorem 7.100. Assume that X is path-connected. Then X is connected.

Proof. If X is not connected, then $X = U \sqcup V$ where U, V are nonempty open subsets of X . Since X is path-connected, there is a path γ from a point of U to a point of V . So $[0, 1] = \gamma^{-1}(U) \sqcup \gamma^{-1}(V)$ where $\gamma^{-1}(U), \gamma^{-1}(V)$ are open (by Prop. 7.60) and nonempty. This contradicts the fact that $[0, 1]$ is connected (cf. Thm. 7.96). \square

Proposition 7.101. Let $f : X \rightarrow Y$ be a continuous map of topological spaces. Suppose that X is connected. Then $f(X)$ is connected.

Proof. By replacing $f : X \rightarrow Y$ by the restricted continuous map $f : X \rightarrow f(X)$, it suffices to assume $Y = f(X)$. If Y is not connected, then $Y = U \sqcup V$ where U, V are open and nonempty. Then $X = f^{-1}(U) \sqcup f^{-1}(V)$ are open (by Prop. 7.60) and nonempty subsets of X . So X is not connected, impossible. (One can also use Thm. 7.94 to prove that $f(X)$ is connected.) \square

Remark 7.102. When $Y = \mathbb{R}$, Prop. 7.101 and Thm. 7.96 imply that $f(X)$ is an interval. So f satisfies (7.28). Therefore, Prop. 7.101 can be viewed as a generalization of IVP for connected spaces.

Corollary 7.103. *Let I be an interval, and let $f : I \rightarrow \overline{\mathbb{R}}$ be a strictly increasing continuous map. Then $J = f(I)$ is an interval, and the restriction $f : I \rightarrow J$ is a homeomorphism.*

Proof. By Thm. 7.96 and Prop. 7.101, J is connected and hence is an interval. Therefore, by Thm. 2.72, f is a homeomorphism. \square

★ **Example 7.104.** Not all connected spaces are path-connected. Let $f : (0, 1] \rightarrow \mathbb{R}^2$ be defined by $f(x) = (x, \sin(x^{-1}))$. Then the range $f((0, 1])$ is connected by Prop. 7.101. Since $f((0, 1])$ is a dense subset of $X = f((0, 1]) \cup \{(0, 0)\}$, by Prop. 7.95, X is connected. However, it can be checked that X is not path-connected. (Prove it yourself, or see [Mun, Sec. 24].) X is called the **topologist's sine curve**.

The following proposition can be used to decompose (for example) an open subset of \mathbb{R}^N into open connected subsets. (See Pb. 7.13.)

Proposition 7.105. *Assume that $X = \bigcup_{\alpha \in \mathcal{A}} X_\alpha$ where each X_α is connected. Assume that $\bigcap_{\alpha \in \mathcal{A}} X_\alpha \neq \emptyset$. Then X is connected.*

Proof. Suppose that X is not connected. By Thm. 7.94, there is a continuous surjection $f : X \rightarrow \{0, 1\}$. Let $p \in \bigcap_{\alpha} X_\alpha$. Then $f(p)$ is 0 or 1. Assume WLOG that $f(p) = 0$. Choose $x \in X$ such that $f(x) = 1$. Choose α such that $x \in X_\alpha$. Then $f|_{X_\alpha} : X_\alpha \rightarrow \{0, 1\}$ is a continuous surjection. So X_α does not satisfy IVP, and hence is not connected. \square

Exercise 7.106. Prove a path-connected version of Prop. 7.105.

Exercise 7.107. Prove Prop. 7.95 and 7.105 directly using Def. 7.92 (but not using IVP).

7.8 Rigorous constructions of $\sqrt[n]{x}$, $\log x$, and a^x

With the help of Cor. 7.103, one can construct a lot of well-known functions rigorously.

Example 7.108. Let $f : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ be $f(x) = x^n$ where $n \in \mathbb{Z}_+$. Then by Cor. 7.103, $J = f(\mathbb{R}_{\geq 0})$ is an interval. Clearly $J \subset [0, +\infty)$. Since $0 \in J$ and $\sup J = +\infty$, we have $J = [0, +\infty)$. Therefore f is a homeomorphism. Its inverse function is a homeomorphism: the n -th root function

$$\sqrt[n]{} : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0} \quad x \mapsto \sqrt[n]{x}$$

This gives the rigorous construction of $\sqrt[n]{x}$.

A similar method gives the rigorous construction of \log .

Example 7.109. By Exp. 4.28, the exponential function $\exp : \mathbb{R} \rightarrow \mathbb{R}$ is continuous. We claim that \exp is a strictly increasing homeomorphism from \mathbb{R} to $\mathbb{R}_{>0}$. Its inverse function is called the **logarithmic function**

$$\log : \mathbb{R}_{>0} \rightarrow \mathbb{R} \quad x \mapsto \log x$$

Proof. From $e^x = \sum_{n=0}^{\infty} x^n/n!$ we clearly have $e^0 = 1$ and $e^x > 1$ if $x > 0$. From $e^{x+y} = e^x e^y$ proved in Cor. 5.61, we have $e^x e^{-x} = e^0 = 1$, which shows that $e^x \in \mathbb{R}_{>0}$ for all $x \in \mathbb{R}$. If $x < y$, then $e^y > e^x > 0$ since $e^y = e^{y-x} e^x$ and $e^{y-x} > 1$. So \exp is strictly increasing. Thus, by Cor. 7.103, \exp is a homeomorphism from \mathbb{R} to $J = \exp(\mathbb{R})$, and J is an interval.

When $x \geq 0$, we have $e^x \geq x$ from the definition of e^x . So $\sup_{x \geq 0} e^x = +\infty$. When $x \leq 0$, since $e^x e^{-x} = 1$, we have $\inf_{x \leq 0} e^x = 1/\sup_{x \geq 0} e^x = 0$. So $\sup J = +\infty$ and $\inf J = 0$. Since $0 \notin \exp(\mathbb{R})$ (if $e^x = 0$, then $1 = e^x e^{-x} = 0$, impossible), we have $J = \mathbb{R}_{>0}$. \square

Example 7.110. Let $a \in \mathbb{R}_{>0}$. For each $z \in \mathbb{C}$, define

$$a^z = e^{z \log a} \tag{7.29}$$

By Exp. 7.109, if $a > 1$ (resp. $0 < a < 1$), the map

$$\mathbb{R} \rightarrow \mathbb{R}_{>0} \quad x \mapsto a^x \tag{7.30}$$

is an increasing (resp. decreasing) homeomorphism, since it is the composition of the increasing (resp. decreasing) homeomorphism $x \in \mathbb{R} \mapsto x \log a \in \mathbb{R}$ and the increasing one $\exp : \mathbb{R} \rightarrow \mathbb{R}_{>0}$. By the proof of Exp. 7.109, we have

$$a^0 = 1 \quad a^x a^{-x} = 1 \quad a^x a^y = a^{x+y} \tag{7.31}$$

And clearly

$$a^1 = a. \tag{7.32}$$

It follows that for every $n \in \mathbb{Z}_+$, $a^n = a^{1+\dots+1} = a \cdots a$. Namely, $a^n = e^{n \log a}$ agrees with the usual understanding of a^n . Thus, since $(a^{1/n})^n$ equals $a^{1/n} \cdots a^{1/n} = a^{1/n+\dots+1/n} = a^1 = a$, we conclude

$$a^{\frac{1}{n}} = \sqrt[n]{a}$$

Example 7.111. By Exp. 7.109, if $p > 0$ (resp. $p < 0$), then

$$\mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0} \quad x \mapsto x^p = e^{p \log x} \quad (7.33)$$

is an increasing (resp. decreasing) homeomorphism, since it is the composition of the increasing (resp. decreasing) homeomorphism $x \in \mathbb{R}_{>0} \rightarrow p \log x \in \mathbb{R}$ and the increasing homeomorphism $\exp : \mathbb{R} \rightarrow \mathbb{R}_{>0}$.

7.9 Problems and supplementary material

Let X and Y be topological spaces.

7.9.1 Open sets, closed sets, closures

Problem 7.1. Let $A, B \in X$. Let $(A_\alpha)_{\alpha \in \mathcal{A}}$ be a family of subsets of X . Prove that

$$\overline{A \cup B} = \overline{A} \cup \overline{B} \quad (7.34a)$$

$$\overline{\bigcap_{\alpha \in \mathcal{A}} A_\alpha} \subset \bigcap_{\alpha \in \mathcal{A}} \overline{A_\alpha} \quad (7.34b)$$

The following problem is crucial to the study of compactness. (See Sec. 8.3 for instance.)

Problem 7.2. Let $(x_\alpha)_{\alpha \in I}$ be a net in X . Let $x \in X$. Prove that the following statements are equivalent:

- (1) $(x_\alpha)_{\alpha \in I}$ has a subnet converging to x .
- (2) For every neighborhood U of x , we have that x_α is frequently in U .
- (3) x belongs to $\bigcap_{\alpha \in I} \overline{\{x_\beta : \beta \geq \alpha\}}$.

Any $x \in X$ satisfying one of these three conditions is called a **cluster point** of $(x_\alpha)_{\alpha \in I}$. (Compare Pb. 3.1.)

Hint. (2) \Leftrightarrow (3) is a direct translation. Assume (2). To prove (1), show that (J, \leq) is a directed set, where

$$\begin{aligned} J &= \{(\alpha, U) \in I \times \text{Nbh}_X(x) : x_\alpha \in U\} \\ (\alpha, U) &\leq (\alpha', U') \iff \alpha \leq \alpha' \text{ and } U \supset U' \end{aligned} \quad (7.35a)$$

Prove that $(x_\mu)_{\mu \in J}$ is a subnet of $(x_\alpha)_{\alpha \in I}$ if for each $(\alpha, U) \in J$ we set

$$x_{(\alpha, U)} = x_\alpha \quad (7.35b)$$

(Namely, the increasing map $J \rightarrow I$ is defined to be $(\alpha, U) \mapsto \alpha$.) Prove that $(x_\mu)_{\mu \in J}$ converges to x . You should point out where (2) is used in your proofs. \square

Remark 7.112. By Pb. 7.2-(3), the set of cluster points of (x_α) is a closed subset, since intersections of closed subsets are closed (cf. Cor. 7.49, or by (7.34b)).

For the reader's convenience, we present below the sequential version of Pb. 7.2. "(1) \Leftrightarrow (2)" is due to Pb. 3.1. "(2) \Leftrightarrow (3)" is due to Pb. 7.2.

Proposition 7.113. Assume that X is a metric space. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in X . Let $x \in X$. The following statements are equivalent:

- (1) $(x_n)_{n \in \mathbb{Z}_+}$ has a subsequence converging to x .
- (2) For every neighborhood U of x , we have that x_n is frequently in U .
- (3) x belongs to $\bigcap_{n \in \mathbb{Z}_+} \overline{\{x_k : k \geq n\}}$.

Any $x \in X$ satisfying one of these three conditions is called a **cluster point** of $(x_n)_{n \in \mathbb{Z}_+}$.

Prop. 7.113-(3) should remind you of the definitions of \limsup and \liminf .

★ **Remark 7.114.** It is not hard to show that the (1,2,3) of Prop. 7.113 are equivalent in the more general case that X is a first countable topological space (see below for the definition). The proof is similar to that for metric spaces, and is left to the readers as an exercise.

Definition 7.115. Let X be a topological space. A subset \mathcal{B}_x of $\text{Nbh}_X(x)$ is called a **neighborhood basis** of x , if for every $U \in \text{Nbh}_X(x)$ there exists $V \in \mathcal{B}_x$ such that $V \subset U$. We say that X **first countable** if every point x has a neighborhood basis \mathcal{B}_x which is a countable set.

Example 7.116. If X is a metric space, then X is first countable, since for every $x \in X$, $\{B_X(x, 1/n) : n \in \mathbb{Z}_+\}$ is a neighborhood basis of x .

Remark 7.117. By Pb. 7.2-(2) and Prop. 7.113-(2), if (x_n) is a sequence in a metric space X , then (x_n) has a subsequence converging to $x \in X$ iff (x_n) has a subnet converging to x . This is not necessarily true when X is a general topological space. Note that in the general case, cluster points of a sequence (x_n) mean cluster points of (x_n) as a net. Thus, they are not the limits of convergent *subsequences* of (x_n) .

Problem 7.3. Assume that X is a metric space. Let $E \subset X$. Recall that $d(x, E) = d(E, x) = \inf_{e \in E} d(e, x)$. Prove that

$$\{x \in X : d(x, E) = 0\} = \overline{E} \quad (7.36)$$

Remark 7.118. If E, F are disjoint subsets of a metric space X , a continuous function $f : X \rightarrow [0, 1]$ is called an **Urysohn function** with respect to E, F , if

$$f^{-1}(1) = E \quad f^{-1}(0) = F$$

For example, it is easy to check that

$$f : X \rightarrow [0, 1] \quad f(x) = \frac{d(x, F)}{d(x, E) + d(x, F)} \quad (7.37)$$

is an Urysohn function.

★ **Problem 7.4.** A topological space X is called **normal** if for every closed disjoint $E, F \subset X$, there exist disjoint open subsets $U, V \subset X$ such that $E \subset U$ and $F \subset V$.

1. Prove that X is normal iff for each $E \subset W \subset X$ where E is closed and W is open, there exists an open subset $U \subset X$ such that $E \subset U \subset \overline{U} \subset W$.
2. Prove that if X is metrizable, then X is normal.

7.9.2 Continuous maps

Exercise 7.119. Let $f : X \rightarrow Y$ be a map.

1. Suppose that F is a subset of Y containing $f(X)$. Show that $f : X \rightarrow Y$ is continuous iff $f : X \rightarrow F$ is continuous.
2. (Local to global principle) Suppose that $X = \bigcup_{\alpha \in I} U_\alpha$ where each U_α is an open subset of X , Prove that f is continuous iff $f|_{U_\alpha} : U_\alpha \rightarrow Y$ is continuous for every α .

Remark 7.120. The above local-to-global principle for continuous functions can be rephrased in the following way. Suppose that $X = \bigcup_{\alpha \in I} U_\alpha$ where each U_α is an open subset of X . Suppose that for each α we have a continuous map $f_\alpha : U_\alpha \rightarrow Y$. Assume that for each $\alpha, \beta \in I$ we have

$$f_\alpha|_{U_\alpha \cap U_\beta} = f_\beta|_{U_\alpha \cap U_\beta}$$

Then there is a (necessarily unique) continuous function $f : X \rightarrow Y$ such that $f|_{U_\alpha} = f_\alpha$ for every α .

Problem 7.5. Let $f : X \rightarrow Y$ be a map. Suppose that $X = A_1 \cup \dots \cup A_N$ where $N \in \mathbb{Z}_+$ and A_1, \dots, A_N are closed subsets of X . Suppose that $f|_{A_i} : A_i \rightarrow Y$ is continuous for each $1 \leq i \leq N$. Prove that f is continuous.

Does the conclusion remain true if A_1, \dots, A_N are not assumed closed? If no, find a counterexample. □

Note. Do not use Prop. 7.86 in your proof. But you can think about how this problem is related to Prop. 7.86. □

Definition 7.121. Let (I, \leq) be a directed set. Let ∞_I (often abbreviated to ∞) be a new symbol not in I . Then

$$I^* = I \cup \{\infty_I\}$$

is also a directed set if we extend the preorder \leq of I to I^* by setting

$$\alpha \leq \infty_I \quad (\forall \alpha \in I^*)$$

For each $\alpha \in I$, let

$$I_{\geq \alpha}^* = \{\beta \in I^* : \beta \geq \alpha\}$$

The **standard topology** on I^* is defined to be the one induced by the basis

$$\mathcal{B} = \{\{\alpha\} : \alpha \in I\} \cup \{I_{\geq \alpha}^* : \alpha \in I\} \quad (7.38)$$

Problem 7.6. Let (I, \leq) be a directed set. Let I^* be as in Def. 7.121.

1. Check that \mathcal{B} (defined by (7.38)) is a basis for a topology. (Therefore, \mathcal{B} generates a topology \mathcal{T} on I^* .)
2. Let $(x_\alpha)_{\alpha \in I}$ be a net in a topological space X . Let $x_\infty \in X$. (So we have a function $x : I^* \rightarrow X$.) Prove that

$$x \text{ is a continuous function} \quad \Longleftrightarrow \quad \lim_{\alpha \in I} x_\alpha = x_\infty \quad (7.39)$$

3. Is I^* Hausdorff? Prove it, or find a counterexample.

7.9.3 Product spaces

Problem 7.7. Prove Thm. 7.73.

Problem 7.8. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ and $(Y_\alpha)_{\alpha \in \mathcal{A}}$ be families of nonempty topological spaces. Let Z be a nonempty topological space. For each $\alpha \in \mathcal{A}$, choose maps $f_\alpha : X_\alpha \rightarrow Y_\alpha$ and $g_\alpha : Z \rightarrow X_\alpha$.

1. Use Thm. 7.73 to prove that

$$\prod_{\alpha \in \mathcal{A}} f_\alpha : \prod_{\alpha} X_\alpha \rightarrow \prod_{\alpha} Y_\alpha \quad (x(\alpha))_{\alpha \in \mathcal{A}} \mapsto (f_\alpha(x(\alpha)))_{\alpha \in \mathcal{A}} \quad (7.40)$$

is continuous iff each f_α is continuous.

2. Use Thm. 7.73 to prove that

$$\bigvee_{\alpha \in \mathcal{A}} g_\alpha : Z \rightarrow \prod_{\alpha} X_\alpha \quad z \mapsto (g_\alpha(z))_{\alpha \in \mathcal{A}} \quad (7.41)$$

is continuous iff each g_α is continuous.

Problem 7.9. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ be an uncountable family of metric spaces, where each X_α has at least two elements. Let $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ be the product space, equipped with the product topology. Prove that S is not first countable (recall Def. 7.115), and hence not metrizable.

7.9.4 Limits of functions

Problem 7.10. Prove the equivalence of (2) and (3) in Def. 7.81.

Problem 7.11. Find $\lim_{(x,y) \rightarrow (0,0)} f(x,y)$, or explain why it does not exist:

$$f(x,y) = \frac{x^2 - y^2}{x^2 + y^2}$$
$$f(x,y) = \frac{(xy)^2}{(xy)^2 + (x - y)^2}$$
$$f(x,y) = \frac{x^6 y^2}{(x^4 + y^2)^2}$$

7.9.5 Connectedness

Problem 7.12. Assume that X, Y are not empty. Prove that X and Y are connected iff $X \times Y$ is connected.

Hint. Write $X \times Y$ as a union of sets of the form $(X \times \{y\}) \cup (\{x\} \times Y)$. □

Definition 7.122. A topological space X is called **locally connected** if every $x \in X$ has a neighborhood basis \mathcal{B}_x (recall Def. 7.115) whose members are all connected.

Example 7.123. Every open subset of a locally connected space is clearly locally connected.

Example 7.124. \mathbb{R}^N is locally connected, since open balls are path-connected and hence connected (by Thm. 7.100). Therefore, every open subset of \mathbb{R}^N is locally connected.

Problem 7.13. Suppose that X is locally connected. Prove that X has a unique (disjoint) decomposition $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ where each X_α is a nonempty connected open subset of X . (Each X_α is called a **connected component** of X .)

Hint. For each $x \in X$, consider the union of all connected neighborhoods containing x . □

8 Compactness

8.1 Overture: two flavors of compactness

Let X be a topological space.

Definition 8.1. An **open cover** of X means a family $\mathfrak{U} = (U_\alpha)_{\alpha \in \mathcal{A}}$ of open subsets of X such that $X = \bigcup_{\alpha \in \mathcal{A}} U_\alpha$. \mathfrak{U} is called **finite** resp. **countable** if \mathcal{A} is finite resp. countable. A **subcover** of \mathfrak{U} means an open cover $\mathfrak{V} = (V_\beta)_{\beta \in \mathcal{B}}$ of X such that each V_β equals U_α for some $\alpha \in \mathcal{A}$.

Definition 8.2. We say that X is a **compact space** if every open cover of X has a finite subcover. We say that X is a **Lindelöf space** if every open cover of X has a countable subcover.

Remark 8.3. For the purpose of this chapter, it suffices to consider open covers $\mathfrak{U} = (U_\alpha)_{\alpha \in \mathcal{A}}$ such that $\alpha \in \mathcal{A} \mapsto U_\alpha \in 2^X$ is injective. (Namely, one can throw away repeated open sets.) In this case, we write

$$\mathfrak{U} \subset 2^X$$

and view \mathfrak{U} as a subset of 2^X . A **subcover** of such \mathfrak{U} is an open cover \mathfrak{V} such that $\mathfrak{V} \subset \mathfrak{U}$. The readers can check that this assumption does not affect the definition of compact spaces and Lindelöf spaces.

Remark 8.4. Compactness can also be formulated in a relevant version: If A is a compact subset of X , and if \mathfrak{U} is a set of open subsets of X such that $A \subset \bigcup_{U \in \mathfrak{U}} U$, then since $\{U \cap A : U \in \mathfrak{U}\}$ gives an open cover of A , we know that

$$A \subset U_1 \cup \cdots \cup U_n$$

some $U_1, \dots, U_n \in \mathfrak{U}$. Conversely, any A satisfying such property is a compact subspace of X .

Exercise 8.5. Show that a finite union of compact spaces is compact. Show that a finite set is compact.

Exercise 8.6. Show that X is compact iff X satisfies the **finite intersection property**: The intersection of a family of non-empty closed subsets is nonempty.

A main goal of this chapter is to prove the following theorem. Its proof will be finished at [the end](#) of Sec. 8.5. In fact, the formal proof will only be in Sec. 8.3 and Sec. 8.5.

Theorem 8.7. *Let X be a metric space. Then X is sequentially compact iff X is compact.*

This is the first fundamental theorem we prove in this course. Its significance lies in the fact that it connects two seemingly very different notions of compactness, and hence two strikingly different intuitions. We hope that the reader can not only follow the logical chains of the proofs, but also understand the pictures behind the proof. More precisely, we hope that the readers can have an intuitive understanding of the following questions:

- Why are these two compactness both powerful in solving certain problems? What roles do they play in the proof? How are the roles played by these two compactness related? (This is more important than just knowing why these notions are *logically* equivalent.)
- Why is one version of compactness more powerful than the other one in solving certain problems?

Thus, I feel that it is better to look at some applications of compactness before we prove Thm. 8.7 rigorously. For pedagogical purposes, we also introduce two related notions of compactness:

Definition 8.8. We say that X is **net-compact**, if every net $(x_\alpha)_{\alpha \in I}$ in X has at least one cluster point (recall Pb. 7.2), equivalently, at least one convergent subnet. We say that X is **countably compact**, if every countable open cover of X has a finite subcover.

Sequential compactness and net-compactness clearly share the same intuition. Countable compactness is intuitively similar to compactness. Also, compactness clearly implies countable compactness. But net-compactness does not imply sequential compactness in general: In a net-compact space, every sequence has a convergent subnet, but not necessarily a convergent subsequence.

The relationship between these four versions of compactness is as follows. (We will prove this in the course of proving Thm. 8.7.)

Metric spaces: all the four versions of compactness are equivalent (8.1a)

Topological spaces: $\text{net-compact} \iff \text{compact}$ (8.1b)

After proving (8.1), we will not use the notions of countable compactness and net-compactness. This is because net-compactness is equivalent to compactness, and countable compactness is more difficult to use than compactness. (Nevertheless, proving/using compactness by proving/using the existence of cluster points is often helpful.)

8.2 Act 1: case studies

8.2.1 Extreme value theorem (EVT)

Lemma 8.9 (Extreme value theorem). *Let X be a compact topological space. Let $f : X \rightarrow \mathbb{R}$ be a continuous function. Then f attains its maximum and minimum at points*

of X . In particular, $f(X)$ is a bounded subset of \mathbb{R} .

We have seen the sequential compactness version of EVT (extreme value theorem) in Lem. 3.2. There, we find the point $x \in X$ at which f attains its maximum by first finding a sequence (x_n) such that $f(x_n)$ converges to $\sup f(X)$. Then we choose any convergent subsequence (x_{n_k}) , which converges to the desired point x . The same method can be used to prove EVT for net-compact spaces if we replace sequences by nets.

For compact spaces, EVT is proved in a completely different way. In fact, without the tools of sequences and nets, one can not easily find x at which f attains its maximum. The argument is rather indirect:

Proof of Lem. 8.9. It suffices to prove that $f(X)$ is bounded for all continuous maps $f : X \rightarrow \mathbb{R}$. Then $a = \sup f(X)$ is in \mathbb{R} . If $a \notin f(X)$, we choose a homeomorphism $\varphi : (-\infty, a) \rightarrow \mathbb{R}$. So $\varphi \circ f : X \rightarrow \mathbb{R}$ is continuous but has no upper bound. This is impossible. \square

Thus, to prove EVT, it remains to prove:

Example 8.10. Assume that X is compact and $f : X \rightarrow \mathbb{R}$ is continuous. Then $f(X)$ is a bounded subset of \mathbb{R} .

Proof. For each $x \in X$, since f is continuous at x , there exists $U_x \in \text{Nbh}(x)$ such that $|f(p) - f(x)| < 1$ for all $p \in U_x$. In particular, $f(U_x)$ is bounded. Since $X = \bigcup_{x \in X} U_x$ is an open cover of X , by compactness, $X = U_{x_1} \cup \cdots \cup U_{x_n}$ for some $x_1, \dots, x_n \in X$. Thus $X = f(U_{x_1}) \cup \cdots \cup f(U_{x_n})$ is bounded. \square

The above proof is typical. It suggests that compactness is powerful for proving finiteness properties rather than finding solutions of functions satisfying certain requirements. Thus, if you want to prove a finiteness property using sequential or net-compactness, you have to prove it indirectly. For example, you need to prove by contradiction:

Example 8.11. Assume that X is net-compact or sequentially compact. Assume that $f : X \rightarrow \mathbb{R}$ is continuous. Then $f(X)$ is a bounded subset of \mathbb{R} .

Proof. Assume that X is net-compact. If $f(X)$ is not bounded above, then there is a sequence (x_α) in X (viewed as a net) such that $\lim_\alpha f(x_\alpha) = +\infty$. By net-compactness, (x_α) has a subnet (x'_β) converging to $x \in X$. So $f(x) = \lim_\beta f(x'_\beta) = +\infty$, impossible. So f is bounded above, and hence bounded below by a similar argument. The case where X is sequentially compact can be proved by a similar method. \square

Let us look at a more complicated example.

8.2.2 Uniform convergence in multivariable functions

Example 8.12. Let X, Y be topological spaces. Assume that Y is compact. Let V be a normed vector space. Choose $f \in C(X \times Y, V)$. For each $x \in X$, let

$$f_x : Y \rightarrow V \quad y \mapsto f(x, y)$$

Equip $C(Y, V)$ with the l^∞ -norm. Then the following map is continuous:

$$\Phi(f) : X \rightarrow C(Y, V) \quad x \mapsto f_x \quad (8.2)$$

Remark 8.13. Note that since Y is compact, each $g \in C(Y, V)$ is bounded by EVT (applied to $|g|$). So $C(Y, V) \subset l^\infty(Y, V)$.

The continuity of $\Phi(f)$ means that for each $x \in X$, the following statement holds:

⊗ For every $\varepsilon > 0$ there exists $U \in \text{Nbh}_X(x)$ such that for all $p \in U$ and all $y \in Y$ we have $\|f(p, y) - f(x, y)\| < \varepsilon$.

This is clearly a finiteness property. Thus, its sequentially compact version or net-compact version should be proved indirectly. Indeed, when X, Y are metric spaces and Y is sequentially compact, we have proved this in Pb. 3.7 by contradiction. The same method (with sequences replaced by nets) also works for the net-compact case:

Example 8.14. Example 8.12 is true, assuming that Y is net-compact rather than compact.

Proof. Suppose “⊗” is not true. Then there is $\varepsilon > 0$ such that for every $U \in \text{Nbh}_X(x)$ there is $x_U \in U$ and $y_U \in Y$ such that $\|f(x_U, y_U) - f(x, y_U)\| \geq \varepsilon$. Then $(x_\alpha)_{\alpha \in \text{Nbh}_X(x)}$ is a net converging to x , where $x_\alpha = x_U$ if $\alpha = U$. Since Y is net-compact, (y_α) has a subnet (y_β) converging to some $y \in Y$. Since the subnet (x_β) also converges to x , we have $\lim_\beta f(x_\beta, y_\beta) = f(x, y)$ and $\lim_\beta f(x, y_\beta) = f(x, y)$ by the continuity of f . This contradicts the fact that $\|f(x_\beta, y_\beta) - f(x, y_\beta)\| \geq \varepsilon$ for all β . \square

On the other hand, the solution of Exp. 8.12 using open covers is a direct proof:

Proof of Exp. 8.12. “⊗” is a finiteness property global over Y . We prove “⊗” by first proving it locally, and then passing to the global space Y using the compactness of Y .

Fix $x \in X$. Choose any $\varepsilon > 0$. For each $y \in Y$, since f is continuous at (x, y) , there is a neighborhood W of (x, y) such that for every $(p, q) \in W$ we have $\|f(p, q) - f(x, y)\| < \varepsilon/2$. By Exp. 7.72, we can shrink W to a smaller neighborhood of the form $U_y \times V_y$ where $U_y \in \text{Nbh}_X(x)$ and $V_y \in \text{Nbh}_Y(y)$. Then for each $p \in U_y$

and $q \in U_y$ we have $\|f(p, q) - f(x, y)\| < \varepsilon/2$, and hence $\|f(p, q) - f(x, q)\| < \varepsilon$. This proves the special case of “ \textcircled{D} ” where Y is replaced by U_y .

Now we pass from local to global in the same way as in the proof of Exp. 8.10. Since $Y = \bigcup_{y \in Y} U_y$ is an open cover of Y , by the compactness of Y , there is a finite subset $F \subset Y$ such that $Y = \bigcup_{y \in F} U_y$. Then “ \textcircled{D} ” is true if we let $U = \bigcap_{y \in F} U_y$. \square

8.2.3 Conclusions

1. Sequential compactness and net-compactness are useful for finding solutions of a function satisfying some given conditions.
2. Compactness is useful for proving finiteness properties. The proof is usually a local-to-global argument. It is usually a direct argument (rather than proof by contradiction).
3. If one uses sequential/net-compactness to prove a finiteness property, one usually proves it by contradiction: Assume that this finiteness is not true. Find a sequence/net (x_α) that violates this finiteness property, and pass to a convergent subsequence/subnet to find a contradiction.
4. Therefore, for sequential/net-compact spaces, the argument is in the direction of “getting smaller and smaller”, opposite to the argument for compact spaces.

Let me emphasize that the proof for sequentially/net-compact spaces is opposite to the one for compact spaces in two aspects: (1) If one argument is direct, the other is a proof by contradiction for the same problem. (2) The former has the intuition of “getting smaller”, while the latter local-to-global argument has the intuition of “getting larger”.

I have already touched on this phenomenon in Rem. 7.54: *The reason that sequences and nets run in the opposite direction to that of open sets is because closed sets are opposite to open sets*, as proved in Thm. 7.48. Thus, you can expect that the transition between closed and open sets plays a crucial role in the following proof of Thm. 8.7.

8.3 Act 2: “sequentially compact \Leftrightarrow countably compact” for metric spaces, just as “net-compact \Leftrightarrow compact”

The road up and the road down is one and the same.

Heraclitus

As mentioned before, our goal of this chapter is to prove “sequentially com-

compact \Leftrightarrow compact" for metric spaces. Our strategy is as follows: We reformulate the sequential compactness condition in terms of decreasing chains of closed sets, and reformulate the compactness condition in terms of increasing chains of open sets. Then we relate these two pictures easily using Thm. 7.48.

The following difficulty arises when carrying out this strategy. Sequences are countable by nature, whereas open covers can have arbitrarily large cardinality. Thus, sequences are related to countable decreasing chains, and hence countable open covers. Therefore, the above idea only implies the equivalence

$$\text{sequentially compact} \iff \text{countably compact} \quad (\text{for metric spaces}) \quad (8.3a)$$

Accordingly, it will only imply

$$\text{net-compact} \iff \text{compact} \quad (8.3b)$$

since there are no constraints on the cardinalities of indexed sets of nets. We will prove (8.3) in this section, and leave the proof of "countably compact \Leftrightarrow compact" for metric spaces to Sec. 8.5.

Since the proofs of (8.3a) and (8.3b) are similar, we first discuss (8.3b).

Proposition 8.15. *Let X be a topological space. Then the following are equivalent.*

- (1) X is compact.
- (2) (**Increasing chain property**) If $(U_\mu)_{\mu \in I}$ is an increasing net of open subsets of X satisfying $\bigcup_{\mu \in I} U_\mu = X$, then $U_\mu = X$ for some μ .
- (3) (**Decreasing chain property**) If $(E_\mu)_{\mu \in I}$ is a decreasing net of nonempty closed subsets of X , then $\bigcap_{\mu \in I} E_\mu \neq \emptyset$.

Here, "increasing net" means $U_\mu \subset U_\nu$ if $\mu \leq \nu$, and "decreasing net" means the opposite.

Proof. (1) \Rightarrow (2): Assume (1). Then $X = \bigcup_\mu U_\mu$ is an open cover of X . So, by the compactness of X , we have $X = U_{\mu_1} \cup \dots \cup U_{\mu_n}$ for some $\mu_1, \dots, \mu_n \in I$. Choose $\mu \in I$ which is $\geq \mu_1, \dots, \mu_n$. Then $X = U_\mu$.

(2) \Rightarrow (1): Assume (2). Let $X = \bigcup_{\alpha \in \mathcal{A}} W_\alpha$ be an open cover of X . Let $I = \text{fin}(2^{\mathcal{A}})$. For each $\mu = \{\alpha_1, \dots, \alpha_n\} \in I$, let $U_\mu = W_{\alpha_1} \cup \dots \cup W_{\alpha_n}$. Then $(U_\mu)_{\mu \in I}$ is an increasing net of open sets covering X . Thus, by (2), we have $U_\mu = X$ for some μ . This proves (1).

(2) \Leftrightarrow (3): If we let $E_\mu = X \setminus U_\mu$, then (2) says that if (E_μ) is a decreasing net of closed sets whose intersection is \emptyset , then $E_\mu = \emptyset$ for some μ . This is the contraposition of (3). \square

We now relate decreasing chain property and cluster points of nets using (8.4).

Theorem 8.16. *Let X be a topological space. Then X is net-compact iff X is compact.*

Proof. Assume that X is net-compact. By Prop. 8.15, it suffices to prove that X satisfies the decreasing chain property. Let $(E_\mu)_{\mu \in I}$ be a decreasing net of nonempty closed subsets of X . For each μ we choose $x_\mu \in E_\mu$, which gives a net $(x_\mu)_{\mu \in I}$ in X . The fact that (E_μ) is decreasing implies that $F_\mu \subset E_\mu$ if we set

$$F_\mu = \{x_\nu : \nu \in I, \nu \geq \mu\} \quad (8.4a)$$

Thus, the closure \overline{F}_μ is a subset of E_μ since E_μ is closed. It suffices to prove that $\bigcap_{\mu \in I} \overline{F}_\mu \neq \emptyset$. By Pb. 7.2,

$$\bigcap_{\mu} \overline{F}_\mu = \{\text{the cluster points of the net } (x_\mu)_{\mu \in I}\} \quad (8.4b)$$

which is nonempty because X is net-compact. This finishes the proof that X is compact.

Now we assume that X is compact. Let $(x_\mu)_{\mu \in I}$ be a net in X . Define F_μ by (8.4a). Then $(\overline{F}_\mu)_{\mu \in I}$ is a decreasing net of nonempty closed subsets. So $\bigcap_{\mu} \overline{F}_\mu$, the set of cluster points of $(x_\mu)_{\mu \in I}$, is nonempty by the decreasing chain property (cf. Prop. 8.15). So X is net-compact. \square

Proposition 8.17. *Let X be a topological space. Then the following are equivalent.*

- (1) X is countably compact.
- (2) (**Increasing chain property**) If $(U_n)_{n \in \mathbb{Z}_+}$ is an increasing sequence of open subsets of X satisfying $\bigcup_{n \in \mathbb{Z}_+} U_n = X$, then $U_n = X$ for some n .
- (3) (**Decreasing chain property**) If $(E_n)_{n \in \mathbb{Z}_+}$ is a decreasing sequence of nonempty closed subsets of X , then $\bigcap_{n \in \mathbb{Z}_+} E_n \neq \emptyset$.

Proof. Similar to the proof of Prop. 8.15. \square

Exercise 8.18. Fill in the details of the proof of Prop. 8.17.

Lemma 8.19. *Let X be a metric space. Then X is sequentially compact iff X is countably compact.*

Proof. This lemma can be proved in a similar way as Thm. 8.17. The only difference is that one should use the sequential version of Pb. 7.2, namely, Prop. 7.113. Note that the “(1) \Leftrightarrow (2)” of Prop. 7.113 does not hold for general topological spaces. Thus, sequential compactness is not equivalent to countable compactness for general topological spaces. \square

★ **Remark 8.20.** As pointed out in Rem. 7.114, Prop. 7.113 holds more generally for first countable topological spaces (Def. 7.115). Therefore, Lem. 8.19 also holds for such spaces:

$$\begin{aligned} \text{sequentially compact} &\iff \text{countably compact} \\ &\text{(for first countable spaces)} \end{aligned} \quad (8.5)$$

8.4 Intermezzo: elementary properties about compactness

Proposition 8.21. *Suppose that $X \subset Y$ where Y is a topological space. The following are true.*

1. *Assume that Y is compact and X is closed in Y . Then X is compact.*
2. *Assume that Y is Hausdorff and X is compact, then X is a closed subset of Y .*

Proof. Part 1. Let (x_α) be a net in X . Since Y is compact, (x_α) has a subnet (x'_β) converging to some $p \in Y$. Since (x'_β) is in X , we have $p \in \overline{X} = X$. So X is compact.

Part 2. To prove $\overline{X} = X$, we choose any net (x_α) in X converging to $p \in Y$ and show that $p \in X$. Indeed, since X is compact, (x_α) has a subnet (x'_β) converging to some $x \in X$. Since (x'_β) also converges to p , we have $p = x$ because Y is Hausdorff. So $p \in X$. \square

I have mentioned that non-Hausdorff spaces are not often used in analysis. Thus, we mainly use the following special case of Prop. 8.21:

Corollary 8.22. *Let Y be a Hausdorff space and $X \subset Y$. If X is compact, then X is closed in Y . If X is closed in Y and if Y is compact, then X is compact.*

Recall that a similar property holds for complete metric spaces, cf. Prop. 3.27.

Theorem 8.23. *Suppose that $f : X \rightarrow Y$ is a continuous map of topological spaces where X is compact. Then $f(X)$ is compact. Moreover, if f is injective and X, Y are Hausdorff, then f restricts to a homeomorphism $f : X \rightarrow f(X)$.*

Proof. Choose any net $(f(x_\alpha))$ in $f(X)$ where $x_\alpha \in X$. Since X is compact, (x_α) has a subnet (x'_β) converging to some $x \in X$. Then $f(x'_\beta)$ converges to $f(x)$. So $f(X)$ is compact.

Now assume that f is injective and Y is Hausdorff. Then the subspace $f(X)$ is also Hausdorff. By replacing Y by $f(X)$, we assume that f is bijective. To show that f^{-1} is continuous, by Prop. 7.60, it suffices to prove that f is a closed map, i.e., f sends every closed $E \subset X$ to a closed subset $f(E)$. Indeed, since X is compact, E is also compact by Cor. 8.22. So $f(E)$ is compact by the first paragraph. So $f(E)$ is closed in X by Cor. 8.22. \square

The second part of Thm. 8.23 can also be proved in a similar way as Pb. 3.3 by replacing sequences with nets. But that argument relies on the fact that every net in a compact Hausdorff space with only one cluster point is convergent. We leave the proof of this fact to the readers (cf. Pb. 8.1).

Exercise 8.24. The first part of Thm. 8.23 can be viewed as a generalization of extreme value theorem. Why?

Proposition 8.25. *Suppose that X, Y are compact topological spaces. Then $X \times Y$ is compact.*

Proof. Take a net (x_α, y_α) in $X \times Y$. Since X is compact, (x_α) has a convergent subnet (x_{α_β}) . Since Y is compact, (y_{α_β}) has a convergent subnet $(y_{\alpha_{\beta_\gamma}})$. So $(x_{\alpha_{\beta_\gamma}}, y_{\alpha_{\beta_\gamma}})$ is a convergent subnet of (x_α, y_α) . \square

Remark 8.26. Note that if $X \times Y$ is compact, then X , as the image of $X \times Y$ under the projection map, is compact by Thm. 8.23. Therefore, we conclude that $X \times Y$ is compact iff X and Y are compact.

8.5 Act 3: “countably compact \Leftrightarrow compact” for Lindelöf spaces

Assume in this section that X is a topological space. Recall that X is Lindelöf iff every open cover has a countable subcover. Thus, it is obvious that

$$\text{countably compact} \iff \text{compact} \quad (\text{for Lindelöf spaces}) \quad (8.6)$$

Thus, by Lem. 8.19, to prove that sequentially/countably compact metric spaces are compact, it suffices to prove that they are Lindelöf.

We introduce two related concepts that are more useful than Lindelöf spaces:

Definition 8.27. We say that a topological space X is **separable** if X has a countable dense subset. We say that X is **second countable** if the topology of X has a countable basis (i.e., a basis \mathcal{B} with countably many elements).

Example 8.28. \mathbb{R}^N is separable, since \mathbb{Q}^N is a dense subset.

As we shall immediately see, these two notions are equivalent for metric spaces. It is often easier to visualize and prove separability for concrete examples (such as Exp. 8.28). Indeed, Exp. 8.28 is the typical example that helps us imagine more general separable spaces. However, for general topological spaces, second countability behaves better than separability. The following property gives one reason.

Proposition 8.29. *If Y is a subset of a second countable space X , then Y is second countable.*

Proof. Let \mathcal{B} be a countable basis for the topology of X . Then $\{Y \cap U : U \in \mathcal{B}\}$ is a countable basis for the topology of Y . \square

Another reason that second countability is better is because it implies Lindelöf property. This is mainly due to the following fact:

Proposition 8.30. *Let \mathcal{B} be a basis for the topology of X . Then the following are equivalent.*

(1) X is Lindelöf (resp. compact).

(2) If X has open cover \mathfrak{U} where each member of \mathfrak{U} is an element of \mathcal{B} , then \mathfrak{U} has a countable (resp. finite) subcover.

Proof. “(1) \Rightarrow (2)” is obvious. Assume (2). Let \mathfrak{W} be an open cover of X . Let

$$\mathfrak{U} = \{U \in \mathcal{B} : U \subset W \text{ for some } W \in \mathfrak{W}\}$$

For each $x \in X$, since there is $W \in \mathfrak{W}$ containing x , and since \mathcal{B} is a basis, there is $U \in \mathcal{B}$ such that $x \in U \subset W$. This proves that \mathfrak{U} is an open cover of X . So \mathfrak{U} has a countable (resp. finite) subcover \mathfrak{U}_0 . For each $U \in \mathfrak{U}_0$, choose $W_U \in \mathfrak{W}$ containing U . Then $\{W_U : U \in \mathfrak{U}_0\}$ is a countable (resp. finite) subcover of \mathfrak{W} . \square

Corollary 8.31. *Every second countable topological space X is Lindelöf.*

Proof. Let \mathcal{B} be a countable basis for the topology of X . Let \mathfrak{U} be an open cover of X such that each member of \mathfrak{U} is in \mathcal{B} . Then by discarding duplicated terms, \mathfrak{U} becomes countable. This verifies (2) of Prop. 8.30. \square

Theorem 8.32. *Consider the following statements:*

(1) X is second countable.

(2) X is separable.

Then (1) \Rightarrow (2). If X is metrizable, then (1) \Leftrightarrow (2).

Proof. Assume that X is second countable with countable basis \mathcal{B} . For each $U \in \mathcal{B}$, choose $x_U \in U$. Then one checks easily that $\{x_U : U \in \mathcal{B}\}$ is dense by checking that it intersects every nonempty open subset of X . This proves (1) \Rightarrow (2).

Assume that X is a metric space with countable dense subset E . Let us prove that the countable set

$$\mathcal{B} = \{B_X(e, 1/n) : e \in E, n \in \mathbb{Z}_+\}$$

is a basis for the topology of X . Choose any open $W \subset X$ with $x \in W$. We want to show that some member of \mathcal{B} contains x and is in W . By shrinking W , we may assume that $W = B_X(x, 1/n)$ for some $n \in \mathbb{Z}_+$. Since E is dense, $B(x, 1/2n)$ contains some $e \in E$. So $d(x, e) < 1/2n$. Therefore, $B(e, 1/2n)$ contains x and is inside W by triangle inequality. \square

It can be proved that Lindelöf metric spaces are separable. (Therefore, the three notions agree for metric spaces.) We will not use this fact. So we leave its proof to the readers as an exercise (cf. Pb. 8.12). The following chart is a summary of the relationships between the various topological properties about countability.

$$\begin{array}{ll}
\text{Topological spaces:} & \text{second countable} \implies \begin{cases} \text{subset is second countable} \\ \text{separable} \\ \text{Lindelöf} \end{cases} \\
\text{Metric spaces:} & \text{second countable} \iff \text{separable} \iff \text{Lindelöf}
\end{array} \tag{8.7}$$

Example 8.33. Since \mathbb{R}^N is separable and hence second countable, every subset of \mathbb{R}^N is second countable, and hence is separable.

Theorem 8.34. *Let X be a sequentially compact metric space. Then X is separable, and hence second countable and Lindelöf.*

Proof. We claim that for every $\delta > 0$, there is a finite set $E \subset X$ such that for every $x \in E$, the distance $d(x, E) < \delta$. Suppose that there is no such a finite set for some given number $\delta > 0$. Pick any $x_1 \in X$. Suppose $x_1, \dots, x_k \in X$ have been constructed. Then there is a point $x_{k+1} \in X$ whose distance to $\{x_1, \dots, x_k\}$ is $\geq \delta$. This defines inductively a sequence $(x_k)_{k \in \mathbb{Z}_+}$ in X such that any two elements have distance $\geq \delta$. So (x_k) has no convergent subsequence, contradicting the sequential compactness of X .

Thus, for each $n \in \mathbb{Z}_+$, we can choose a finite $E_n \subset X$ satisfying $d(x, E_n) < 1/n$ for all $x \in X$. Let $E = \bigcup_{n \in \mathbb{Z}_+} E_n$, which is countable. Then for each $x \in X$, $d(x, E) \leq d(x, E_n) < 1/n$ for every n , which implies $d(x, E) = 0$ and hence $x \in \overline{E}$ by Pb. 7.3. So E is dense in X . \square

Remark 8.35. The above proof is indirect because it proves the existence of E_n by contradiction but not by explicit construction. However, if X is a bounded closed subset of \mathbb{R}^N , one can find an explicit countable basis for the topology of X :

$$\mathcal{B} = \{X \cap B(x, 1/n) : n \in \mathbb{Z}_+, x \in \mathbb{Q}^N\}$$

and hence has an explicit countable dense subset $\{x_U : U \in \mathcal{B}, U \neq \emptyset\}$ where for each U we choose some $x_U \in U$. More generally, if X is a closed subset of the sequentially compact space $[0, 1]^{\mathbb{Z}_+}$, one can find a countable basis for the topology of X and hence a countable dense subset of X in a similar way. (You will be asked to construct them in Pb. 8.13.)

We shall see in Thm. 8.45 that every sequentially compact metric space is homeomorphic to a closed subset of $[0, 1]^{\mathbb{Z}_+}$. Therefore, for any sequentially compact metric space X you will see in the real (mathematical) life, you don't need the indirect construction in the proof of Thm. 8.34 to prove the separability of X . So what is the point of giving an indirect proof of Thm. 8.34? Well, you need Thm. 8.34 to prove Thm. 8.45. \square

Proof of Thm. 8.7. Let X be a metric space. Assume that X is compact. Then X is clearly countably compact, and hence sequentially compact by Lem. 8.19. Conversely, assume that X is sequentially compact. Then by Lem. 8.19 and Thm. 8.34, X is countably compact and Lindelöf, and hence compact. \square

★ **Remark 8.36.** Since second countable spaces are first countable, by Rem. 8.20 and Cor. 8.31, we have

$$\begin{aligned} \text{sequentially compact} &\iff \text{countably compact} \iff \text{compact} \\ &\text{(for second countable topological spaces)} \end{aligned} \quad (8.8)$$

Relation (8.8) not only generalizes Thm. 8.7, but also tells us what are the crucial properties that ensure the equivalence of compactness and sequential compactness for metric spaces.

8.6 Problems and supplementary material

Let X, Y be topological spaces.

8.6.1 Compactness

Problem 8.1. Let $(x_\alpha)_{\alpha \in I}$ be a net in a compact Hausdorff space X . Prove that (x_α) is convergent iff (x_α) has exactly one cluster point.

Problem 8.2. Let $(x_\alpha)_{\alpha \in I}$ be a net in the compact space $\overline{\mathbb{R}}$. Let S be the (automatically nonempty) set of cluster points of (x_α) in $\overline{\mathbb{R}}$. Recall that S is a closed subset by Rem. 7.112. For each $\alpha \in I$, define

$$A_\alpha = \inf\{x_\beta : \beta \geq \alpha\} \quad B_\alpha = \sup\{x_\beta : \beta \geq \alpha\} \quad (8.9)$$

Then (A_α) is increasing and (B_α) is decreasing. So they converge in $\overline{\mathbb{R}}$. Define

$$\liminf_{\alpha \in I} x_\alpha = \sup\{A_\alpha : \alpha \in I\} = \lim_{\alpha \in I} A_\alpha \quad (8.10a)$$

$$\limsup_{\alpha \in I} x_\alpha = \inf\{B_\alpha : \alpha \in I\} = \lim_{\alpha \in I} B_\alpha \quad (8.10b)$$

Prove that

$$\liminf_{\alpha \in I} x_\alpha = \inf S \quad \limsup_{\alpha \in I} x_\alpha = \sup S \quad (8.11)$$

Note. You will get a quick proof by choosing the right one of the three equivalent definitions of cluster points in Pb. 7.2. A wrong choice will take you much more effort. \square

Corollary 8.37. Let (x_α) be a net in $\overline{\mathbb{R}}$. Then (x_α) converges in $\overline{\mathbb{R}}$ iff $\limsup_\alpha x_\alpha = \liminf_\alpha x_\alpha$.

Proof. $\overline{\mathbb{R}}$ is compact. Therefore, $\limsup_\alpha x_\alpha = \liminf_\alpha x_\alpha$ iff (x_α) has only one cluster point (by Pb. 8.2), iff (x_α) converges (by Pb. 8.1). \square

Problem 8.3. Given a general topological space X , which one implies the other between the conditions of “sequential compactness” and “countable compactness”? Prove your conclusion with details.

Hint. Check the proof of Thm. 8.16, and think about the question: If (x_n) is a sequence in X , what is the inclusion relation between $\bigcap_n \overline{\{x_k : k \geq n\}}$ and the set of limits of the convergent subsequences (rather than subnets) of (x_n) ? \square

Problem 8.4. Prove Prop. 8.21 using the original definition of compact spaces (i.e. every open cover has a finite subcover) instead of using nets.

★ **Problem 8.5.** Prove Prop. 8.25 using the original definition of compact spaces instead of using nets.

Problem 8.6. Assume that Y is compact. Let $(x_\alpha, y_\alpha)_{\alpha \in I}$ be a net in $X \times Y$. Assume that $x \in X$ is a cluster point of (x_α) . Prove that there exists $y \in Y$ such that (x, y) is a cluster point of (x_α, y_α) .

Problem 8.7. (Tychonoff theorem, countable version) Let $(X_n)_{n \in \mathbb{Z}_+}$ be a sequence of compact topological spaces. Prove that the product space $S = \prod_{n \in \mathbb{Z}_+} X_n$ (equipped with the product topology) is compact using the following hint.

Hint. Let $(f_\alpha)_{\alpha \in I}$ be a net in S where $f_\alpha = (f_\alpha(1), f_\alpha(2), \dots)$. Use Pb. 8.6 to construct inductively an element $x = (x(1), x(2), \dots) \in S$ such that for every $n \in \mathbb{Z}_+$, the element $(x(1), \dots, x(n))$ is a cluster point of $(f_\alpha(1), \dots, f_\alpha(n))_{\alpha \in I}$ in $X_1 \times \dots \times X_n$. Prove that x is a cluster point of $(f_\alpha)_{\alpha \in I}$ in S . \square

Remark 8.38. The same idea as above can be used to prove the general Tychonoff theorem (the version where the index set \mathbb{Z}_+ in Pb. 8.7 is replaced by an arbitrary set) by replacing mathematical induction by Zorn’s lemma.

★ **Problem 8.8.** Let X be the set of two elements: $X = \{0, 1\}$, viewed as a metric subspace of \mathbb{R} . Let $S = X^{[0,1]}$, the product space of uncountably many X , where the index set is the interval $[0, 1]$. S is equipped with the product topology. According to Tychonoff theorem (to be proved in the future), S is compact. Prove that S is not sequentially compact.

Hint. Use binary representations in $[0, 1]$. \square

8.6.2 LCH spaces

Definition 8.39. A subset A of a Hausdorff space X is called **precompact** if its closure \overline{A} is compact. This is equivalent to saying that A is contained in a compact subset of X .

Proof of equivalence. If \overline{A} is compact, then \overline{A} is a compact subset of X (cf. Cor. 8.22) containing A . Conversely, if $A \subset K$ where K is a compact subset of X , then K is closed by Cor. 8.22. Since \overline{A} is the smallest closed subset of X containing A , we have $\overline{A} \subset K$. By Exe. 7.52, \overline{A} is closed in K . By Cor. 8.22, \overline{A} is compact. \square

It is clear that a subset of a precompact set is precompact.

Problem 8.9. Suppose that X is metric space. Let $A \subset X$. Prove that the following are equivalent.

- (1) A is precompact, i.e., \overline{A} is compact.
- (2) Every sequence in A has a subsequence converging to some point of X .

Definition 8.40. A Hausdorff space X is called a **locally compact Hausdorff (LCH) space** if every point has a precompact neighborhood.

Proposition 8.41. Let X be an LCH space. Then the closed subsets and the open subsets of X are LCH.

Proof. Let $E \subset X$ be closed. Let $x \in E$. Then there is $U \in \text{Nbh}_X(x)$ with compact closure $\text{Cl}_X(U)$. So $\text{Cl}_X(U) \cap E$ is compact by Cor. 8.22. Note that $U \cap E \in \text{Nbh}_E(x)$, and $U \cap E$ is a subset of $\text{Cl}_X(U) \cap E$. So $U \cap E$ is precompact in E . This proves that E is LCH.

Next, we let W be an open subset of X . Let $x \in W$. We want to show that there exists $U \in \text{Nbh}_X(x)$ such that $\overline{U} = \text{Cl}_X(U)$ is compact and $\overline{U} \subset W$. Then U is clearly precompact in W .

Since X is LCH, there is $\Omega \in \text{Nbh}_X(x)$ with compact closure $\overline{\Omega} = \text{Cl}_X(\Omega)$. Then every open subset U of Ω containing x has compact closure in X . Thus, it suffices to prove that there exists $U \in \mathcal{I} = \text{Nbh}_\Omega(x)$ such that $\overline{U} \subset W$. Suppose that this is not true. Then for each $U \in \mathcal{I}$ there is $x_U \in \overline{U} \setminus W$. So $(x_U)_{U \in \mathcal{I}}$ is a net in $\overline{\Omega} \setminus W$, where $\overline{\Omega} \setminus W$ is compact by Cor. 8.22. So $(x_U)_{U \in \mathcal{I}}$ has a cluster point $y \in \overline{\Omega} \setminus W$. In particular, $y \neq x$.

Since X is Hausdorff, by Cor. 7.50, there is $V_0 \in \text{Nbh}_X(x)$ such that $y \notin \overline{V_0}$. Let $V = V_0 \cap \Omega$. Then $V \in \mathcal{I}$ and $y \notin \overline{V}$. For every $U \in \mathcal{I}$ satisfying $U \subset V$ we have $x_U \in \overline{V}$. So $(x_U)_{U \in \mathcal{I}}$ is eventually not in the neighborhood $X \setminus \overline{V}$ of y . This is impossible. \square

Definition 8.42. Let X be LCH. Let Y be a metric space. Let $(f_\alpha)_{\alpha \in I}$ be a net in Y^X . Let $f \in Y^X$. We say that (f_α) **converges locally uniformly** to f if the following equivalent conditions are satisfied:

- (1) For each $x \in X$, there exists $U \in \text{Nbh}_X(x)$ such that $(f_\alpha|_U)$ converges uniformly to $f|_U$.
- (2) For each precompact open subset $W \subset X$, the net $(f_\alpha|_W)$ converges uniformly to $f|_W$.

Problem 8.10. Prove that in Def. 8.42, conditions (1) and (2) are equivalent.

Exercise 8.43. Let X be LCH. Let \mathcal{V} be a normed vector space. Let $(f_\alpha)_{\alpha \in I}$ be a net in $C(X, \mathcal{V})$ converging pointwise to $f : X \rightarrow \mathcal{V}$. Assume that the net (f_α) converges locally uniformly on X (clearly to f). Prove that f is continuous.

An example of locally uniform convergence was given in Thm. 4.27.

8.6.3 Countability in topological spaces

Problem 8.11. Let (X, \mathcal{T}) be a second countable LCH space. Prove that the topology \mathcal{T} has a countable basis \mathcal{B} whose members are all precompact.

Hint. Use Lindelöf property for open subsets of X . □

★ **Problem 8.12.** Let X be a Lindelöf metric space. Prove that X is separable.

Problem 8.13. Let $(X_n)_{n \in \mathbb{Z}_+}$ be a sequence of topological spaces. Equip $S = \prod_{n \in \mathbb{Z}_+} X_n$ with the product topology.

1. Prove that S is second countable if each X_n is second countable.
2. Prove that S is separable if each X_n is separable

Recall from Pb. 7.13 the basic facts about connected components.

Problem 8.14. Let X be a locally connected topological space. Prove that if X is second countable, then X has countably many connected components. Use this result to show that every open subset of \mathbb{R} is a countable disjoint union of open intervals.

8.6.4 The problem of embedding

Definition 8.44. Let \mathcal{F} be a set of functions $X \rightarrow Y$. We say that \mathcal{F} **separates points** of X , if for every distinct $x_1, x_2 \in X$ there exists $f \in \mathcal{F}$ such that $f(x_1) \neq f(x_2)$.

Problem 8.15. Let X be a nonempty compact metric space.

1. Prove that there is a sequence of continuous functions $(f_n)_{n \in \mathbb{Z}_+}$ from X to $[0, 1]$ separating points of X .

2. Prove that

$$\Phi : X \rightarrow [0, 1]^{\mathbb{Z}_+} \quad x \mapsto (f_1(x), f_2(x), \dots)$$

gives a homeomorphism $\Phi : X \rightarrow \Phi(X)$ where $\Phi(X)$ is a closed subspace of $[0, 1]^{\mathbb{Z}_+}$ (equipped with the subspace topology).

The topological space $[0, 1]^{\mathbb{Z}_+}$, equipped with the product topology, is called the **Hilbert cube**.

Hint. Part 1: Choose an infinite countable basis $\mathcal{B} = (U_1, U_2, \dots)$ for the topology of X where each U_n is nonempty. (Why can you do so?) Use Urysohn functions (Rem. 7.118) to construct $f_n : X \rightarrow [0, 1]$ such that $f^{-1}(0) = X \setminus U_n$.

Part 2: Notice Pb. 7.8. □

Theorem 8.45. *Let X be a topological space. The following are equivalent.*

- (1) X is a compact metrizable space.
- (2) X is homeomorphic to a closed subset of the Hilbert cube $[0, 1]^{\mathbb{Z}_+}$.

Proof. (1) \Rightarrow (2): By Pb. 8.15. (2) \Rightarrow (1): By Cor. 7.76, $[0, 1]^{\mathbb{Z}_+}$ is metrizable. By countable Tychonoff theorem (Thm. 3.54 or Pb. 8.7), $[0, 1]^{\mathbb{Z}_+}$ is compact. So its closed subsets are compact by Cor. 8.22. □

★ **Exercise 8.46.** Let $N \in \mathbb{Z}_+$. Prove that the following are equivalent.

- (1) X is a compact Hausdorff space. Moreover, there exist $f_1, \dots, f_N \in C(X, \mathbb{R})$ separating points of X .
- (2) X is homeomorphic to a bounded closed subset of \mathbb{R}^N .

9 The injection $\Psi : C(X, C(Y, \mathcal{V})) \rightarrow C(X \times Y, \mathcal{V})$

In this chapter, unless otherwise stated, X, Y are topological spaces, all normed vector spaces are over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and \mathcal{V} is a normed vector space.

Remark 9.1. Let $\Phi : \mathcal{V} \rightarrow \mathcal{W}$ be a linear map of normed vector spaces. Recall that Φ is an isometry (in the category of metric spaces) iff $\|\Phi(u) - \Phi(v)\| = \|u - v\|$ for all $u, v \in \mathcal{V}$. By linearity, we have

$$\Phi \text{ is an isometry} \iff \|\Phi(v)\| = \|v\| \text{ for all } v \in \mathcal{V} \quad (9.1)$$

Definition 9.2. A linear map $\Phi : \mathcal{V} \rightarrow \mathcal{W}$ of normed vector spaces over \mathbb{F} is called an **isomorphism of normed vector spaces** if Φ is an isometric isomorphism. If Φ is an isomorphism, and if one of \mathcal{V}, \mathcal{W} is complete, then the other one is also complete. In this case, we call Φ an **isomorphism of Banach spaces**.

Recall that if X is compact, then the norm on $C(X, \mathcal{V})$ is assumed to be the l^∞ -norm (cf. Conv. 3.49).

9.1 Ψ is bijective when Y is compact

Theorem 9.3. Equip $C(Y, \mathcal{V})$ with the uniform convergence topology (cf. Exp. 7.77). Then there is a well-defined injective linear map

$$\begin{aligned} \Psi : C(X, C(Y, \mathcal{V})) &\rightarrow C(X \times Y, \mathcal{V}) \\ \Psi(F)(x, y) &= F(x)(y) \end{aligned} \quad (9.2)$$

(for each $F \in C(X, C(Y, \mathcal{V}))$). Moreover, the following are true:

- (a) If Y is compact, then Ψ is a linear isomorphism of vector spaces.
- (b) If X, Y are compact, then Ψ is an isomorphism of normed vector spaces.

Proof. Step 1. Write $\mathcal{W} = C(Y, \mathcal{V})$ for simplicity. To prove that (9.2) is a well-defined map, we need to prove that for each $F \in C(X, \mathcal{W})$, the map $f = \Psi(F) : X \times Y \rightarrow \mathcal{V}$ sending (x, y) to $f(x, y) = F(x)(y)$ is continuous.

The continuity of $F : X \rightarrow \mathcal{W}$ means that if $(x_\alpha)_{\alpha \in I}$ is a net in X converging to x , then $F(x_\alpha)$ converges to $F(x)$, i.e.,

$$\lim_{\alpha \in I} A_\alpha = 0 \quad (9.3a)$$

where each $A_\alpha \in \overline{\mathbb{R}}_{\geq 0}$ is

$$A_\alpha = \sup_{y \in Y} \|f(x_\alpha, y) - f(x, y)\| \quad (9.3b)$$

Now, suppose that $(x_\alpha, y_\alpha)_{\alpha \in I}$ is a net in $X \times Y$ converging to (x, y) . Then

$$\begin{aligned} \|f(x_\alpha, y_\alpha) - f(x, y)\| &\leq \|f(x_\alpha, y_\alpha) - f(x, y_\alpha)\| + \|f(x, y_\alpha) - f(x, y)\| \\ &\leq A_\alpha + \|f(x, y_\alpha) - f(x, y)\| \end{aligned}$$

Since $F(x) : y \in Y \mapsto f(x, y) \in \mathcal{V}$ is continuous, we have $\lim_\alpha \|f(x, y_\alpha) - f(x, y)\| = 0$. Therefore, by Squeeze theorem, we have

$$\lim_{\alpha \in I} \|f(x_\alpha, y_\alpha) - f(x, y)\| = 0 \quad (9.4)$$

Thus, f is continuous at every (x, y) .

Step 2. Clearly Ψ is linear and injective. Assume that Y is compact. Then the surjectivity of Ψ follows from Exp. 8.12. This proves (a). Assume that X is also compact. Choose any $F \in C(X, \mathcal{W})$ and write $f = \Psi(F)$. Then

$$\sup_{x \in X} \sup_{y \in Y} \|f(x, y)\| = \sup_{x \in X, y \in Y} \|f(x, y)\|$$

by the easy Lem. 9.4. This proves that Φ is an isometry, and hence proves (b). \square

Lemma 9.4. *Let $g : A \times B \rightarrow \mathbb{R}$ be a function where A, B are sets. Then*

$$\sup_{a \in A} \sup_{b \in B} g(a, b) = \sup_{(a, b) \in A \times B} g(a, b)$$

Proof. Write $\lambda_a = \sup_{b \in B} g(a, b)$ and $\rho = \sup_{(a, b) \in A \times B} g(a, b)$. Then, clearly $\lambda_a \leq \rho$ for each a . So $\sup_a \lambda_a \leq \rho$. For each a, b we have $g(a, b) \leq \lambda_a$, and hence $g(a, b) \leq \sup_a \lambda_a$. Taking sup over a, b yields $\rho \leq \sup_a \lambda_a$. \square

Remark 9.5. Thanks to Thm. 9.3, we can reduce many problems about multi-variable functions to problems about single-variable functions. Here is an example we will study in the future: If $I = [a, b], J = [c, d]$ are compact intervals and $F \in C(I \times J, \mathbb{R})$, then with the help of Thm. 9.3, the Fubini's theorem

$$\int_a^b \int_c^d F(x, y) dx dy = \int_c^d \int_a^b F(x, y) dx dy$$

for Riemann integrals follows directly from the easy general fact

$$\int_a^b \Lambda \circ f(x) dx = \Lambda \left(\int_a^b f(x) dx \right)$$

where $f : [a, b] \rightarrow \mathcal{W}$ is a continuous map to a real Banach space \mathcal{W} , and $\Lambda : \mathcal{W} \rightarrow \mathbb{R}$ is a continuous linear map.

Thm. 9.3 can be used the other way round: We will prove in the future that every Banach space \mathcal{V} is isomorphic to a closed linear subspace of $C(Y, \mathbb{F})$ for some compact Hausdorff space Y . Thus, a problem about continuous maps $X \rightarrow \mathcal{V}$ (where \mathcal{V} is an abstract Banach space) can be reduced to a problem about continuous scalar-valued functions $X \times Y \rightarrow \mathbb{F}$. \square

In the following sections, we give a surprising application of Thm. 9.3: We show that uniform-convergence and equicontinuity, two closely related but different notions, can be understood in the same context.

9.2 Equicontinuity

Let I be a set not necessarily preordered or directed.

Definition 9.6. Assume that Y is a metric space. A family of functions $(f_\alpha)_{\alpha \in I}$ from X to Y is called **equicontinuous at** $x \in X$ if the following equivalent conditions hold:

(1) The function

$$X \rightarrow Y^I \quad x \mapsto (f_\alpha(x))_{\alpha \in I} \quad (9.5)$$

is continuous at x , where Y^I is equipped with the uniform convergence topology (Exp. 7.77).

(2) For every $\varepsilon > 0$, there exists $U \in \text{Nbh}_X(x)$ such that for every $p \in U$ we have

$$\sup_{\alpha \in I} d_Y(f_\alpha(p), f_\alpha(x)) < \varepsilon$$

Clearly, if $(f_\alpha)_{\alpha \in I}$ is equicontinuous at x , then $f_\alpha : X \rightarrow Y$ is continuous at x for every $\alpha \in I$. We say that $(f_\alpha)_{\alpha \in I}$ is **(pointwise) equicontinuous** if it is equicontinuous at every point of X .

Proof of equivalence. This is immediate if we choose the uniform convergence metric on Y^I to be

$$d((y_\alpha), (y'_\alpha)) = \min \left\{ \sup_{\alpha \in I} d_Y(y_\alpha, y'_\alpha), 1 \right\}$$

and use (the base version of) Def. 7.56-(2). □

Remark 9.7. Warning: The above definition of equicontinuity is weaker than the one in Rudin's book [Rud-P, Ch. 7], which will be called **uniform equicontinuity** in this course (cf. Def. 10.11).

Example 9.8. Assume that X and Y are metric spaces. Fix $C \geq 0$. Then

$$\{f \in Y^X : f \text{ has Lipschitz constant } C\}$$

is an equicontinuous family of functions $X \rightarrow Y$.

In the future, we will see that if $f : [a, b] \rightarrow \mathbb{R}$ (where $[a, b] \subset \mathbb{R}$) is differentiable and satisfies $|f'(x)| \leq C$ for all $x \in [a, b]$, then f has Lipschitz constant C . (For example, if we assume moreover that f' is continuous, then for each $a \leq x < y \leq b$ we have $|f(y) - f(x)| = |\int_x^y f'| \leq \int_x^y |f'| \leq C(y - x)$.) Therefore, all such functions form an equicontinuous family of functions. □

Equicontinuity is important for several reasons. First, equicontinuity is closely related to compactness, both under the uniform convergence topology and under the pointwise convergence topology. This is hinted at in Rem. 9.22, and will be explored in more detail in a future chapter. Second, equicontinuity and uniform convergence are symmetric notions:

Remark 9.9. Note that if $x \in \overline{X \setminus x}$, a map $\varphi : X \rightarrow Y$ is continuous at x iff $\lim_{p \rightarrow x} \varphi(p) = \varphi(x)$, where $\lim_{p \rightarrow x} \varphi(p)$ is the limit of a net (cf. Rem. 7.82). Now, assume that Y is a metric space. Then we see that a family $(f_\alpha)_{\alpha \in I}$ in Y^X satisfies that

$$(f_\alpha)_{\alpha \in I} \text{ is equicontinuous at } x \iff \lim_{p \rightarrow x} \sup_{\alpha \in I} d(f_\alpha(p), f_\alpha(x)) = 0 \quad (9.6)$$

If we compare this with

$$f_\alpha \rightrightarrows f \iff \lim_{\alpha \in I} \sup_{x \in X} d(f_\alpha(x), f(x)) = 0 \quad (9.7)$$

(if I is a directed set and $f \in Y^X$), we see that equicontinuity and uniform convergence are “symmetric about the diagonal line of the Cartesian product $I \times X$ ”: Equicontinuity is a uniform convergence over the index set I , and the uniform convergence $f_\alpha \rightrightarrows f$ is uniform over X .

The symmetry of equicontinuity and uniform convergence will be further studied in Sec. 9.3. (Indeed, we will see that it is better to view “uniform convergence + continuity” and “pointwise convergence + equicontinuity” as symmetric conditions.) As an application, we will see that equicontinuity is equivalent to uniform convergence for any sequence (f_n) of pointwise convergent continuous functions on a compact topological space. (See Cor. 9.26.) Thus, in this case, one can prove the uniform convergence of (f_n) by proving for instance that it converges pointwise and has a uniform Lipschitz constant.

9.3 Uniform convergence and equicontinuity: two faces of Ψ

9.3.1 Main results

In this subsection, we fix a directed set I , and let

$$I^* = I \cup \{\infty_I\}$$

where ∞_I is a new symbol not in I . Write ∞_I as ∞ for simplicity. Equip I^* with the standard topology as in Def. 7.121. Recall that this topology has basis

$$\mathcal{B} = \{\{\alpha\} : \alpha \in I\} \cup \{I_{\geq \alpha}^* : \alpha \in I\}$$

Clearly $I \times X$ is dense in $I^* \times X$. Equip $C(X, \mathcal{V})$ and $C(I^*, \mathcal{V})$ with the uniform convergence topologies.

Throughout this subsection, we fix a net $(f_\alpha)_{\alpha \in I}$ in \mathcal{V}^X and an element $f_\infty \in \mathcal{V}^X$. Define

$$F : I^* \times X \rightarrow \mathcal{V} \quad F(\mu, x) = f_\mu(x) \quad (9.8)$$

The meaning of the title of this section is illustrated by the following theorem.

Theorem 9.10. *We have (a) \Leftrightarrow (b) and (1) \Leftrightarrow (2) where:*

- (a) $(f_\alpha)_{\alpha \in I}$ converges uniformly to f_∞ , and $f_\alpha : X \rightarrow \mathcal{V}$ is continuous for each $\alpha \in I$.
- (b) F gives rise to a continuous map $I^* \rightarrow C(X, \mathcal{V})$
- (1) $(f_\alpha)_{\alpha \in I}$ is equicontinuous and converges pointwise to f_∞ .
- (2) F gives rise to a continuous map $X \rightarrow C(I^*, \mathcal{V})$.

Proof. Assume (a). Then we have $f_\infty \in C(X, \mathcal{V})$ due to Thm. 7.79. So F gives rise to a map $I^* \rightarrow C(X, \mathcal{V})$. Since $f_\alpha \rightrightarrows f_\infty$, we see that F is continuous by Pb. 7.6-2. This proves (b).

Assume (b), then the fact that the map $I^* \rightarrow C(X, \mathcal{V})$ has range in $C(X, \mathcal{V})$ means precisely that each f_α and f_∞ are continuous. The continuity of the map $I^* \rightarrow C(X, \mathcal{V})$ at ∞ means $f_\alpha \rightrightarrows f_\infty$. This proves (a).

(1) \Rightarrow (2): Assume (1). The equicontinuity of (f_α) is equivalent to that

$$x \in X \mapsto (f_\alpha(x))_{\alpha \in I} \in \mathcal{V}^I \quad (9.9)$$

is continuous where \mathcal{V}^I is equipped with the uniform convergence topology. Equivalently, for each $x \in X$ and $\varepsilon > 0$ there is $U \in \text{Nbh}_X(x)$ such that for all $p \in U$ and all $\alpha \in I$ we have

$$\|f_\alpha(p) - f_\alpha(x)\| \leq \varepsilon \quad (9.10)$$

Since $(f_\alpha)_{\alpha \in I}$ converges pointwise to f_∞ , by applying $\lim_{\alpha \in I}$ to (9.10), we see that $\|f_\mu(p) - f_\mu(x)\| \leq \varepsilon$ for all $p \in U$ and $\mu \in I^*$. So

$$x \in X \mapsto (f_\mu(x))_{\mu \in I^*} \in \mathcal{V}^{I^*} \quad (9.11)$$

is continuous, where \mathcal{V}^{I^*} is given the uniform convergence metric. By Pb. 7.6-2, the pointwise convergence of $(f_\alpha)_{\alpha \in I}$ to f_∞ is equivalent to the continuity of

$$\mu \in I^* \rightarrow f_\mu(x) \in \mathcal{V} \quad (9.12)$$

for each $x \in X$. So the map (9.11) has range inside $C(I^*, \mathcal{V})$.

(2) \Rightarrow (1): Assume (2). The continuity of $X \rightarrow C(I^*, \mathcal{V})$ implies that of (9.9). So $(f_\alpha)_{\alpha \in I}$ is equicontinuous. Its pointwise convergence to f is due to the continuity of (9.12) for each x , which is clearly true by (2). \square

Remark 9.11. Conditions (a) and (1) in Thm. 9.10 are symmetric. Condition (a) says roughly that F converges uniformly under the limit over I , and converges pointwise under the limit over X . Condition (1) says roughly that F converges uniformly under the limit over X , and pointwise under the limit over I . The next theorem clarifies the relationship between these two symmetric conditions. We will see a similar condition in Thm. 9.28.

Theorem 9.12. *Consider the following statements:*

- (1) *The function $F : I^* \times X \rightarrow \mathcal{V}$ is continuous.*
- (2) *$(f_\alpha)_{\alpha \in I}$ converges uniformly to f_∞ , and $f_\alpha : X \rightarrow \mathcal{V}$ is continuous for each $\alpha \in I$.*
- (3) *$(f_\alpha)_{\alpha \in I}$ is equicontinuous and converges pointwise to f_∞ .*

Then we have

$$\begin{aligned} (2) &\implies (1) \iff (3) \\ (2) &\iff (1) \quad \text{if } X \text{ is compact} \\ (1) &\iff (3) \quad \text{if } I = \mathbb{N} \end{aligned}$$

where \mathbb{N} is equipped with the usual order.

A more explicit description of condition (1) will be given in Prop. 9.16.

Proof. This follows immediately from Thm. 9.10, Thm. 9.3, and the fact that I^* is compact if $I = \mathbb{N}$. \square

Remark 9.13. From the above proof, we see that the equivalence $(1) \Leftrightarrow (3)$ holds in the more general case that I^* is compact. See Pb. 9.1 for an equivalent description of the compactness of I^* .

Example 9.14. Define $f_n : (0, 1) \rightarrow \mathbb{R}$ by $f_n(x) = x^n$. Then $(f_n)_{n \in \mathbb{Z}_+}$ is equicontinuous (by Exp. 9.8) and pointwise convergent, but not uniformly convergent. Accordingly, $(0, 1)$ is not compact.

Example 9.15. Let $I = \mathbb{Z}_+ \times \mathbb{Z}_+$, equipped with the product preorder: $(k_1, n_1) \leq (k_2, n_2)$ means $k_1 \leq k_2$ and $n_1 \leq n_2$. Consider $(f_{k,n})_{(k,n) \in I}$, where $f_{k,n} : [0, 1] \rightarrow \mathbb{R}$ is defined by $f_{k,n}(x) = \frac{x^n}{k}$. Then $\lim_{(k,n) \in I} f_{k,n}$ converges uniformly to 0 by squeeze theorem and $0 \leq f_{k,n} \leq k^{-1}$. Thus, condition (1) of Thm. 9.12 is satisfied. However, this net of functions is not equicontinuous at $x = 1$. Moreover, for every $(k_0, n_0) \in I$, the net of functions $(f_{k,n})_{(k,n) \in I_{\geq (k_0, n_0)}}$ is not equicontinuous at 1.

Proof. Choose any $x \in [0, 1)$. Then (recalling Lem. 9.4)

$$\sup_{k \geq k_0} \sup_{n \geq n_0} |f_{k,n}(1) - f_{k,n}(x)| = \sup_{k \geq k_0} \sup_{n \geq n_0} \frac{1 - x^n}{k} = \sup_{k \geq k_0} \frac{1}{k} = \frac{1}{k_0}$$

\square

In the following, let me give a more explicit description of condition (1) of Thm. 9.12 in terms of (f_α) and f_∞ .

Proposition 9.16. *Assume that $f_\alpha : X \rightarrow \mathcal{V}$ is continuous for each $\alpha \in I$. Then part (1) of Thm. 9.12 is equivalent to both (1') and (1''), where*

(1') *For each $x \in X$, we have*

$$\lim_{\substack{(\alpha, p) \in I \times X \\ (\alpha, p) \rightarrow (\infty, x)}} f_\alpha(p) = f_\infty(x) \quad (9.13)$$

(1'') *For each $x \in X$ and $\varepsilon > 0$, there exist $\beta \in I$ and $U \in \text{Nbh}_X(x)$ such that*

$$\|f_\alpha(p) - f_\infty(x)\| < \varepsilon \quad (\text{for all } \alpha \in I_{\geq \beta} \text{ and } p \in U) \quad (9.14)$$

Note that one can make sense of the LHS of (9.13) because $I \times X$ is clearly dense in $I^* \times X$.

Proof. The equivalence of (1') and (1'') is clear by Def. 7.81. The continuity of f_α for all $\alpha \in I$ means precisely that $F|_{I \times X}$ is continuous. Therefore, (1') is equivalent to part (1) of Thm. 9.12, thanks to the following Thm. 9.17. \square

See Exp. 9.32 for an elementary example satisfying (1') of Prop. 9.16 (or equivalently, (1) of Thm. 9.12), but not satisfying (2) or (3) of Thm. 9.12. (See also Pb. 9.5 and Thm. 9.31 for related facts.)

9.3.2 Proving continuity using limits

Theorem 9.17. *Let $\varphi : X \rightarrow Y$ be a map of topological spaces where Y is metrizable. Let A be a dense subset of X . Then the following are equivalent.*

- (1) $\varphi : X \rightarrow Y$ is continuous.
- (2) *The restriction $\varphi|_A : A \rightarrow Y$ is continuous. Moreover, for each $x \in X \setminus A$, the restriction $\varphi|_{A \cup \{x\}}$ is continuous at x , namely (cf. Def. 7.81),*

$$\lim_{\substack{p \in A \\ p \rightarrow x}} \varphi(p) = \varphi(x) \quad (9.15)$$

Proof. Clearly (2) is equivalent to

$$\varphi|_{A \cup \{x\}} \text{ is continuous at } x \text{ for all } x \in X \quad (9.16)$$

So (1) \Rightarrow (2). Assume (2) and that Y is a metric space. Choose any $x \in X$. We want to show that $\varphi : X \rightarrow Y$ is continuous at x . Choose any $\varepsilon > 0$. Recall that an open

subset of A is precisely the intersection of A and an open subset of X . Thus, by (9.16), there is $U \in \text{Nbh}_X(x)$ such that for all $p \in A \cap U$ we have

$$d(\varphi(p), \varphi(x)) \leq \varepsilon/2 \quad (9.17)$$

It remains to prove (9.17) for all $p \in U$. Choose any $p \in U$. By Lem. 9.18, $A \cap U$ is dense in U . Thus, there is a net (p_α) in $A \cap U$ converging to p . In particular, for each α we have

$$d(\varphi(p_\alpha), \varphi(x)) \leq \varepsilon/2$$

Since $\varphi|_{A \cup \{p\}}$ is continuous (by (9.16)), we have $\lim_\alpha \varphi(p_\alpha) = \varphi(p)$. Thus, applying \lim_α to the above inequality proves (9.17) for $p \in U$. \square

Lemma 9.18. *Suppose that A is a dense subset of X . Let U be an open subset of A . Then $A \cap U$ is dense in U .*

This lemma is clearly false if U is not assumed to be open: simply take $U = X \setminus A$.

First proof. Choose any $x \in U$. We want to find a net in $A \cap U$ converging to x . Since A is dense in X , there is a net $(x_\alpha)_{\alpha \in J}$ in X converging to x . Since U is a neighborhood of x , (x_α) is eventually in U , say $x_\alpha \in U$ whenever $\alpha \geq \beta$. Then $(x_\alpha)_{\alpha \in J_{\geq \beta}}$ is a net in $A \cap U$ converging to x . \square

Second proof. We want to show that every nonempty open subset of U intersects $A \cap U$. But an open subset of U is precisely an open subset of X contained inside U (Exe. 7.52). So this set (when nonempty) must intersect A because A is dense in X . \square

★ **Exercise 9.19.** In Thm. 9.17, weaken the metrizability of Y to the condition that Y is regular. (See the definition below.) Prove the conclusion of Thm. 9.17.

★ **Definition 9.20.** A topological space Y is called **regular** if for every $y \in Y$ and every $U \in \text{Nbh}_Y(y)$ there exists $V \in \text{Nbh}_Y(y)$ such that $\text{Cl}_Y(V) \subset U$.

9.3.3 Immediate consequences of Thm. 9.12

The following result is parallel to Thm. 7.79 for uniformly convergent nets of continuous functions.

Corollary 9.21. *Let $(f_\alpha)_{\alpha \in I}$ be an equicontinuous net of functions $X \rightarrow \mathcal{V}$. Assume that (f_α) converges pointwise to $f : X \rightarrow \mathcal{V}$. Then f is continuous.*

Proof. Write $f_\infty = f$ and define F by (9.8). Then F is continuous by (3) \Rightarrow (1) of Thm. 9.12. So $f = f_\infty$ is continuous, since f is the composition of F with the inclusion map $x \in X \mapsto (\infty, x) \in I^* \times X$. \square

Remark 9.22. In the future, we will study the general Tychonoff theorem, which says for example that if $(f_\alpha)_{\alpha \in I}$ is a net of functions $X \rightarrow \mathbb{R}^N$ which is pointwise bounded, i.e. $\sup_{\alpha \in I} \|f_\alpha(x)\| < +\infty$ for all $x \in X$, then (f_α) has a subnet converging pointwise. However, if we assume moreover that each f_α is continuous, we cannot conclude in general that (f_α) has a subnet converging pointwise to a *continuous* function. But we can make such a conclusion when (f_α) is equicontinuous, thanks to Cor. 9.21. Therefore, Cor. 9.21 tells us that equicontinuity is useful for studying the problems of compactness of families of continuous functions (under the pointwise convergence topology). Cf. Thm. 17.7.

In fact, we have a slightly stronger version of Cor. 9.21:

Corollary 9.23. *Let $(f_\alpha)_{\alpha \in I}$ be a net of functions $X \rightarrow \mathcal{V}$ equicontinuous at x . Assume that (f_α) converges pointwise to $f : X \rightarrow \mathcal{V}$. Then f is continuous at x .*

Proof. Define X_x to be the same as X as a set, but has a different topology: the one generated by the basis

$$\mathcal{B}_x = \text{Nbh}_X(x) \cup \{\{p\} : p \neq x\}$$

(cf. Exe. 7.62). Define $g_\alpha : X_x \rightarrow \mathcal{V}$ and $g : X_x \rightarrow \mathcal{V}$ to be the same as f_α and f . Then (g_α) is a net of equicontinuous functions converging pointwise to g . Therefore, by Cor. 9.21, g is continuous. So f is continuous at x . \square

Remark 9.24. By a similar argument, we can generalize Thm. 7.79 to the following form: Let (f_α) be a net of functions $X \rightarrow \mathcal{V}$ converging uniformly to $f : X \rightarrow \mathcal{V}$. Suppose that each f_α is continuous at x . Then f is continuous at x .

Example 9.25. In this example, we pretend to know derivatives. Let (f_n) be a sequence of functions $\mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$ defined by $f_n(x) = x^{1/n}$. (We understand $0^{\frac{1}{n}} = 0$.) Find all $x \in \mathbb{R}_{\geq 0}$ at which (f_n) is equicontinuous.

Proof. We prove that $\mathbb{R}_{>0}$ is the set of all points at which (f_n) is equicontinuous. First, assume $x > 0$. Choose $0 < a < 1 < b$ such that $a < x < b$. Then, on $[a, b]$, $f'_n(x) = \frac{1}{n}x^{\frac{1}{n}-1}$ is bounded by $C = \max\{a^{-1}, b\}$. So $(f_n|_{[a,b]})$ has Lipschitz constant C by Exp. 9.8. So (f_n) is equicontinuous at x .

Note that (f_n) converges pointwise to f where $f(x) = 1$ if $x > 0$ and $f(0) = 0$. But f is not continuous at 0. So (f_n) is not equicontinuous at 0 due to Cor. 9.23. \square

One can also prove that (f_n) is equicontinuous on $(0, 1) \cup (1, +\infty)$ without using derivatives: See Thm. 9.31-1.

Corollary 9.26. *Let $(f_\alpha)_{\alpha \in I}$ be a net in $C(X, \mathcal{V})$ converging pointwise to $f \in \mathcal{V}^X$. Consider the following statements:*

- (1) $(f_\alpha)_{\alpha \in I}$ converges uniformly to f .

(2) $(f_\alpha)_{\alpha \in I}$ is equicontinuous.

Then the following are true.

1. If $(f_\alpha)_{\alpha \in I}$ is a sequence $(f_n)_{n \in \mathbb{Z}_+}$, then $(1) \Rightarrow (2)$.
2. If X is compact, then $(2) \Rightarrow (1)$.

Proof. Immediate from Thm. 9.12. □

9.4 Uniform convergence and double limits

In this section, we use Thm. 9.12 to study the problem of when the order of double limits can be exchanged. We first give a useful criterion on uniform convergence.

Proposition 9.27. *Assume that \mathcal{V} is a Banach space. Let $(f_\alpha)_{\alpha \in I}$ be a net in $C(X, \mathcal{V})$. Assume that (f_α) converges uniformly on a dense subset E of X . Then (f_α) converges uniformly on X to some $f \in C(X, \mathcal{V})$.*

The completeness of \mathcal{V} is important here.

Proof. Since E is dense, by (7.9a) (applied to the function $|f_\alpha - f_\beta|$), we have

$$\sup_{x \in X} \|f_\alpha(x) - f_\beta(x)\| = \sup_{x \in E} \|f_\alpha(x) - f_\beta(x)\|$$

where the RHS converges to 0 under $\lim_{\alpha, \beta}$. Thus, (f_α) is a Cauchy net in \mathcal{V}^X where \mathcal{V}^X is equipped with the uniform convergence metric as in Exp. 7.77. So $(f_\alpha)_{\alpha \in I}$ converges uniformly on X to some $f : X \rightarrow \mathcal{V}$ by Thm. 7.78. By Thm. 7.79, f is continuous. □

Theorem 9.28 (Moore-Osgood theorem). *Let $(f_{\alpha, \beta})_{(\alpha, \beta) \in I \times J}$ be a net in a Banach space \mathcal{V} with index set $I \times J$ where I, J are directed sets. Assume the following conditions:*

- (1) *For each $\alpha \in I$, there exists $f_{\alpha, \infty} \in \mathcal{V}$ such that*

$$\lim_{\beta \in J} f_{\alpha, \beta} = f_{\alpha, \infty} \tag{9.18}$$

- (2) *For each $\beta \in J$, there exists $f_{\infty, \beta} \in \mathcal{V}$ such that*

$$\lim_{\alpha \in I} \sup_{\beta \in J} \|f_{\alpha, \beta} - f_{\infty, \beta}\| = 0 \tag{9.19}$$

Then the following are true:

1. The following limits exist and are equal:

$$\lim_{(\alpha,\beta) \in I \times J} f_{\alpha,\beta} = \lim_{\alpha \in I} f_{\alpha,\infty} = \lim_{\beta \in J} f_{\infty,\beta} \quad (9.20)$$

2. If $I = \mathbb{N}$ where \mathbb{N} is equipped with the usual order, then

$$\limsup_{\beta \in J} \lim_{\alpha \in I} \|f_{\alpha,\beta} - f_{\alpha,\infty}\| = 0 \quad (9.21)$$

Conditions (1) and (2) in Thm. 9.28, which say that the limit of $f_{\alpha,\beta}$ is pointwise over one index and uniform in another index, should remind you of conditions (2) and (3) in Thm. 9.12 (cf. Rem. 9.11). In fact, we shall use Thm. 9.12 to understand and prove the Moore-Osgood theorem.

Proof. Part 1: By Thm. 5.29, it suffices to prove that $\lim_{\alpha,\beta} f_{\alpha,\beta}$ converges. Define topological spaces $I^* = I \cup \{\infty_I\}$ and $J^* = J \cup \{\infty_J\}$ as in Subsec. 9.3.1. Define

$$g_\alpha : J^* \rightarrow \mathcal{V} \quad g_\alpha(\nu) = f_{\alpha,\nu}$$

where $g_\alpha(\infty_J) = f_{\alpha,\infty}$. By (1), for each $\alpha \in I$, the function g_α is continuous at ∞_J , and hence $g_\alpha \in C(J^*, \mathcal{V})$. By (2), $(g_\alpha)_{\alpha \in I}$ converges uniformly on J . Since J is a dense subset of J^* , by Prop. 9.27, $(g_\alpha)_{\alpha \in I}$ converges uniformly on J^* to some $g_{\infty_I} : J^* \rightarrow \mathcal{V}$. Thus, by Thm. 9.12, the function

$$F : I^* \times J^* \rightarrow \mathcal{V} \quad F(\mu, \nu) = g_\mu(\nu)$$

is continuous. Its continuity at (∞_I, ∞_J) implies that $\lim_{\alpha \in I, \beta \in J} f_{\alpha,\beta} = \lim_{\alpha \in I, \beta \in J} F(\alpha, \beta)$ converges to $F(\infty_I, \infty_J)$.

Part 2: By Thm. 9.12, $(g_\alpha)_{\alpha \in I}$ is an equicontinuous family of functions $J^* \rightarrow \mathcal{V}$. Its equicontinuity at ∞_J means precisely (9.21). \square

Remark 9.29. Whenever you see a theorem stated in very plain language but proved using a huge machinery, you should always ask yourself if a direct proof is possible. A huge machinery or fancy language is not always necessary for the proof, but often helps to understand the nature of the problem.

Now, since Thm. 9.28 is stated without using the language of topological spaces and continuous maps, it is desirable to have a direct and elementary proof. It could be done by directly translating the above proof (and the proof of the results cited in that proof) into the pure language of nets. However, we prefer to give a simpler proof which is related to, but is not a direct translation of, the above topological proof. \square

A direct proof of Thm. 9.28. Part 1: By Thm. 5.29, it suffices to prove that $\lim_{\alpha,\beta} f_{\alpha,\beta}$ converges. Since V is complete, it suffices to prove the Cauchy condition:

- (i) For each $\varepsilon > 0$, there exists $(\alpha, \beta) \in I \times J$ such that for all $(\mu, \nu) \in I_{\geq \alpha} \times J_{\geq \beta}$, we have $\|f_{\alpha, \beta} - f_{\mu, \nu}\| < \varepsilon$.

Choose $\varepsilon > 0$. By condition (2) of Thm. 9.28, $(f_{\alpha, \beta})$, as a net of functions $J \rightarrow \mathcal{V}$ with index set I , converges uniformly. Thus, by the Cauchy condition for the uniform convergence metric as in Exp. 7.77 (which is available due to Thm. 7.78), we have:

- (ii) There exists $\alpha \in I$ such that for all $\mu \geq \alpha$, we have $\sup_{\nu \in J} \|f_{\alpha, \nu} - f_{\mu, \nu}\| < \varepsilon/2$.

Fix α as above. By condition (1), the limit $\lim_{\beta \in J} f_{\alpha, \beta}$ exists. Thus:

- (iii) There exists $\beta \in J$ such that for all $\nu \geq \beta$ we have $\|f_{\alpha, \beta} - f_{\alpha, \nu}\| < \varepsilon/2$.

Combining (ii) and (iii) and using triangle inequality, we see that for each $\mu \geq \alpha$ and $\nu \geq \beta$,

$$\|f_{\alpha, \beta} - f_{\mu, \nu}\| \leq \|f_{\alpha, \beta} - f_{\alpha, \nu}\| + \|f_{\alpha, \nu} - f_{\mu, \nu}\| < \varepsilon$$

This proves (i).

Part 2: Assume $I = \mathbb{N}$. Since $(f_{\alpha, \beta})$ is a Cauchy net, for each $\varepsilon > 0$ there exist $\alpha_0 \in I, \beta_0 \in J$ such that for all $\alpha \geq \alpha_0$ and $\beta, \nu \geq \beta_0$ we have $\|f_{\alpha, \beta} - f_{\alpha, \nu}\| < \varepsilon$. Applying \lim_{ν} gives

$$\|f_{\alpha, \beta} - f_{\alpha, \infty}\| \leq \varepsilon \quad (\forall \alpha \geq \alpha_0, \beta \geq \beta_0)$$

Since $I = \mathbb{N}$, there are finitely many α not $\geq \alpha_0$. For any such α , by condition (1) of Thm. 9.28, there exists $\beta_{\alpha} \in J$ such that for all $\beta \geq \beta_{\alpha}$, we have $\|f_{\alpha, \beta} - f_{\alpha, \infty}\| \leq \varepsilon$. Choose $\tilde{\beta}$ greater than or equal to β_0 and all these (finitely many) β_{α} . Thus, we have $\|f_{\alpha, \beta} - f_{\alpha, \infty}\| \leq \varepsilon$ for all $\alpha \in I$ and all $\beta \geq \tilde{\beta}$. This proves (9.21). \square

Remark 9.30. The main theme of this chapter is the study of the relationship between the convergence of $\lim_{\alpha, \beta} f_{\alpha, \beta}$ and the uniform convergence of $\lim_{\alpha} f_{\alpha, \beta}$ and $\lim_{\beta} f_{\alpha, \beta}$. The main results of this chapter (i.e. Thm. 9.3, Thm. 9.12 (together with Prop. 9.16), and Moore-Osgood Thm. 9.28) can be summarized as follows:

- (1) If one of $\lim_{\alpha} f_{\alpha, \beta}$ and $\lim_{\beta} f_{\alpha, \beta}$ converges uniformly and the other one converges pointwise, then $\lim_{\alpha, \beta} f_{\alpha, \beta}$ converges. (Consequently, by Thm. 5.29, we have $\lim_{\alpha} \lim_{\beta} f_{\alpha, \beta} = \lim_{\beta} \lim_{\alpha} f_{\alpha, \beta} = \lim_{\alpha, \beta} f_{\alpha, \beta}$.)
- (2) If $\lim_{\alpha} f_{\alpha, \beta}$, $\lim_{\beta} f_{\alpha, \beta}$, and $\lim_{\alpha, \beta} f_{\alpha, \beta}$ all converge pointwise, and if “there is a compactness on β ”, then $\lim_{\alpha} f_{\alpha, \beta}$ converges uniformly over all β .

The detailed statements of (1) and (2) are given in Thm. 9.12 ((together with Prop. 9.16)), or equivalently, in Thm. 9.3. (See also Rem. 9.11.) Although Thm. 9.3 and Thm. 9.12 look very different, they are actually telling the same story. (We have proved Thm. 9.12 from Thm. 9.3. But it is not hard to see that Thm. 9.3 also implies Thm. 9.12.) The Moore-Osgood theorem is only about part (1), but not about part (2). (Or, more accurately, the second part of Moore-Osgood corresponds to a very weak version of (2).)

9.5 Problems and supplementary materials

Recall from the beginning of this chapter that X is a topological space and \mathcal{V} is a normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 9.1. Let I be a directed set. Let $I^* = I \cup \{\infty\}$, equipped with the standard topology as in Subsec. 9.3.1. Prove that the following are equivalent:

- (1) I^* is compact.
- (2) For each $\alpha \in I$, the complement of $I_{\geq \alpha}^* = \{\beta \in I^* : \beta \geq \alpha\}$ is a finite set.

Note. Prop. 8.30 can make your proof shorter. □

Problem 9.2. Let (f_n) be a sequence of functions $\mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$ defined by $f(x) = x^{\frac{1}{n}}$ (as in Exp. 9.25). Give a direct proof that (f_n) is not equicontinuous at 0 using the definition of equicontinuity. Do not use Cor. 9.23.

Problem 9.3. Give a direct proof of Cor. 9.21 without using Thm. 9.3 (and its consequences) or using Thm. 9.28.

Problem 9.4. Give a direct proof of Cor. 9.26 without using Thm. 9.3 (and its consequences) or using Thm. 9.28.

★ **Problem 9.5.** Let $(f_\alpha)_{\alpha \in I}$ be a net in $C(X, \mathbb{R})$. Assume that $(f_\alpha)_{\alpha \in I}$ is increasing, i.e., $f_\alpha \leq f_\beta$ whenever $\alpha \leq \beta$. Assume that $(f_\alpha)_{\alpha \in I}$ converges pointwise to $f \in C(X, \mathbb{R})$. Prove that for every $x \in X$,

$$\lim_{\substack{\alpha \in I \\ p \rightarrow x}} f_\alpha(p) = f(x) \quad (9.22)$$

in the sense of Prop. 9.16. Namely, prove that for every $x \in X$ and $\varepsilon > 0$ there exist $\beta \in I$ and $U \in \text{Nbh}_X(x)$ such that $|f_\alpha(p) - f(x)| < \varepsilon$ for all $\alpha \geq \beta$ and all $p \in U$.

Note. Let $g_\alpha = f - f_\alpha$. Then $(g_\alpha)_{\alpha \in I}$ is a decreasing net of continuous functions converging pointwise to 0. It suffices to prove the easier statement that $\lim_{\alpha \in I, p \rightarrow x} g_\alpha(p) = 0$ for every $x \in X$. (Why is this sufficient?) □

★ **Theorem 9.31.** Let $(f_\alpha)_{\alpha \in I}$ be a net in $C(X, \mathbb{R})$. Assume that $(f_\alpha)_{\alpha \in I}$ is increasing and converges pointwise to $f \in C(X, \mathbb{R})$. The following statements are true.

1. If $(f_\alpha)_{\alpha \in I}$ is a sequence $(f_n)_{n \in \mathbb{Z}_+}$, then $(f_n)_{n \in \mathbb{Z}_+}$ is equicontinuous.
2. (*Dini's theorem*) If X is compact, then $(f_\alpha)_{\alpha \in I}$ converges uniformly to f .

Proof. By Pb. 9.5, $(f_\alpha)_{\alpha \in I}$ and $f_\infty = f$ satisfy (1') of Prop. 9.16. Therefore, the two statements follow directly from Thm. 9.12. □

Example 9.32. Let $f_n : (0, 1) \rightarrow \mathbb{R}$ be $f_n(x) = x^n$, where $n \in \mathbb{Z}$. Then $(f_n)_{n \in \mathbb{Z}}$ is a decreasing net of continuous functions converging pointwise to 0. Here, \mathbb{Z} is given the usual order " \leq ". By Pb. 9.5, (f_n) satisfies

$$\lim_{(n,p) \rightarrow (+\infty, x)} f_n(p) = f(x)$$

for all $x \in (0, 1)$. (So it satisfies condition (1) of Thm. 9.12.) However, $(f_n)_{n \in \mathbb{Z}}$ is neither equicontinuous (since $\sup_{n \in \mathbb{Z}} |f_n(p) - f_n(x)| = +\infty$ whenever $0 < p < x < 1$) nor converging uniformly to 0 (since $\sup_{x \in (0,1)} |f_n(x)| = 1$ if $n > 0$). Accordingly, $(0, 1)$ is not compact, and $I^* = I \cup \{\infty_I\}$ is not compact if $I = \mathbb{Z}$.

However, if we replace \mathbb{Z} by \mathbb{Z}_+ , then $(f_n)_{n \in \mathbb{Z}_+}$ is equicontinuous by Exp. 9.8 (applied to any compact subinterval of $(0, 1)$), or by Thm. 9.31. But $(f_n)_{n \in \mathbb{Z}_+}$ is still not uniformly convergent. \square

Problem 9.6. Let X_1, X_2, \dots be a sequence of nonempty topological spaces. Let $S = \prod_{n \in \mathbb{N}_+} X_n$, equipped with the product topology. Let $f : S \rightarrow \mathbb{R}$ be continuous. Fix $(p_n)_{n \in \mathbb{Z}_+} \in S$. For each $n \in \mathbb{Z}_+$, define

$$\begin{aligned} \varphi_n : S &\rightarrow S \\ (x_1, x_2, \dots, x_{n-1}, x_n, x_{n+1}, \dots) &\mapsto (x_1, x_2, \dots, x_{n-1}, p_n, p_{n+1}, \dots) \end{aligned}$$

Prove for every $x_\bullet = (x_n)_{n \in \mathbb{Z}_+}$ that

$$\lim_{\substack{(n, y_\bullet) \in \mathbb{Z}_+ \times S \\ (n, y_\bullet) \rightarrow (\infty, x_\bullet)}} f \circ \varphi_n(y_\bullet) = f(x_\bullet)$$

in the sense of Prop. 9.16. Conclude that $(f \circ \varphi_n)_{n \in \mathbb{Z}_+}$ is equicontinuous, and that if each X_n is compact then $(f \circ \varphi_n)$ converges uniformly to f . (Recall that in this case S is compact by the countable Tychonoff theorem, cf. Pb. 8.7.)

10 Extending continuous functions to the closures

10.1 Introduction

Let \tilde{X}, Y be topological spaces, let $X \subset \tilde{X}$, and let $f : X \rightarrow Y$ be a continuous map. The **extension problem** asks whether f can be extended to a continuous map $\tilde{f} : \tilde{X} \rightarrow Y$. “Extended” means that $\tilde{f}|_X = f$. Since we can try to first extend f from X to its closure $\text{Cl}_{\tilde{X}}(X)$, and then from $\text{Cl}_{\tilde{X}}(X)$ to \tilde{X} , the extension problem can naturally be divided into two cases: (1) X is dense in \tilde{X} . (2) X is closed in \tilde{X} .

In this chapter, we study the first case. (The second case will be discussed in Sec. 15.4.) Assume that X is dense in \tilde{X} . Then by Prop. 7.63, we know that f can have at most one extension if Y is Hausdorff. So there is essentially no uniqueness issue.

The study of extension problem in this case has a long history. As we have seen in Subsec. 7.6, the limits of functions can be understood in this light: If $x \in \tilde{X} \setminus X$, then f can be extended to a continuous function on $X \cup \{x\}$ iff $\lim_{p \rightarrow x} f(p)$ exists. Of course, this is simply a rephrasing of the definition of $\lim_{p \rightarrow x} f(p)$. But the idea of “extending f to \tilde{X} by first extending f to a slightly larger set with one extra point $\{x\}$ ” is helpful and can sometimes simplify proofs.

Indeed, recall that in the proof of Prop. 9.16 we used Thm. 9.17, which tells us that if $\lim_{p \rightarrow x} f(p)$ converges for all $x \in \tilde{X} \setminus X$, then f can be extended (necessarily uniquely) to a continuous $\tilde{f} : \tilde{X} \rightarrow Y$ where Y is assumed metrizable. Thus, the extensibility of f to \tilde{X} can be checked pointwise. Thm. 9.17 is our first important general result on the extension problem. Let me state Thm. 9.17 in the following equivalent way, which is more convenient for the study of extension problems.

Corollary 10.1. *Let $f : X \rightarrow Y$ be a continuous map of topological spaces where Y is metrizable and X is a dense subspace of a topological space \tilde{X} . The following are equivalent:*

- (1) *There exists a continuous map $\tilde{f} : \tilde{X} \rightarrow Y$ such that $\tilde{f}|_X = f$.*
- (2) *For each $x \in \tilde{X} \setminus X$, the limit $\lim_{p \rightarrow x} f(p)$ exists.*

Proof. If (1) is true, then $\tilde{f}|_{X \cup \{x\}}$ is continuous whenever $x \in \tilde{X} \setminus X$. This proves (2). Conversely, assume (2). Extend f to a map $\tilde{f} : \tilde{X} \rightarrow Y$ by setting $\tilde{f}(x) = \lim_{p \rightarrow x} f(p)$ if $x \in \tilde{X} \setminus X$. Then \tilde{f} is continuous by Thm. 9.17. \square

This chapter will focus on another useful method for extending continuous functions in the setting of metric spaces. A main result (cf. Cor. 10.9) is that if \tilde{X}, Y are metric spaces and Y is complete, then a sufficient condition for the extensibility of f onto \tilde{X} is that f is uniformly continuous. Moreover, uniform continuity

is also a necessary condition if \tilde{X} is compact. (Recall that compact metric spaces are complete, cf. Thm. 3.23.) It is worth mentioning that the extensibility of f is a purely topological question, whereas the uniform continuity of f depends on the metric on \tilde{X} .

10.2 Uniform continuity

Fix metric spaces \tilde{X}, Y and a dense subset $X \subset \tilde{X}$.

10.2.1 Basics

We first give some examples of $f \in C(X, Y)$ that cannot be extended to a continuous function on \tilde{X} . Since uniform continuity is a sufficient condition for the extensibility (when Y is complete), these examples are not uniformly continuous. Recall our convention that subsets of \mathbb{R} or \mathbb{R}^N are equipped with the Euclidean metrics.

Example 10.2. Assume $X = (0, +\infty)$, $\tilde{X} = [0, +\infty)$, $Y = \mathbb{R}$, and $f : X \rightarrow Y$ is defined by $f(x) = 1/x$. Then $\lim_{x \rightarrow 0} f(x)$ is $+\infty$ in \mathbb{R} , and hence does not converge in Y . So f cannot be extended onto \tilde{X} .

Example 10.3. $X = (0, 1]$, $\tilde{X} = [0, 1]$, $Y = \mathbb{R}$, $f : X \rightarrow Y$ is defined by $f(x) = \sin(1/x)$. Then $\lim_{n \rightarrow \infty} f(x_n)$ equals 0 if the sequence (x_n) in X converging to 0 is defined by $x_n = 1/2n\pi$, and equals 1 if $x_n = 1/(2n + \frac{1}{2})\pi$. Thus, by Rem. 7.85, $\lim_{x \rightarrow 0} f(x)$ does not exist in Y . So f cannot be extended onto \tilde{X} .

Definition 10.4. A map $f : X \rightarrow Y$ is called **uniformly continuous** if the following equivalent conditions are satisfied:

(1) For every $\varepsilon > 0$ there exists $\delta > 0$ such that for all $x, x' \in X$ we have

$$d(x, x') < \delta \quad \implies \quad d(f(x), f(x')) < \varepsilon \quad (10.1a)$$

(2) For every nets $(x_\alpha)_{\alpha \in I}, (x'_\alpha)_{\alpha \in I}$ in X (with the same index set I) we have

$$\lim_{\alpha \in I} d(x_\alpha, x'_\alpha) = 0 \quad \implies \quad \lim_{\alpha \in I} d(f(x_\alpha), f(x'_\alpha)) = 0 \quad (10.1b)$$

(3) For every sequences $(x_n)_{n \in \mathbb{Z}_+}, (x'_n)_{n \in \mathbb{Z}_+}$ in X we have

$$\lim_{n \rightarrow \infty} d(x_n, x'_n) = 0 \quad \implies \quad \lim_{n \rightarrow \infty} d(f(x_n), f(x'_n)) = 0 \quad (10.1c)$$

Uniformly continuous maps are clearly continuous. Def. 10.4-(2) says that uniformly continuous functions are those sending Cauchy-equivalent nets (cf. Def. 5.36) to Cauchy-equivalent nets.

Proof of equivalence. (1) \Rightarrow (2): Assume (1). Choose nets $(x_\alpha)_{\alpha \in I}, (x'_\alpha)_{\alpha \in I}$ in X . Choose any $\varepsilon > 0$. Choose $\delta > 0$ such that (10.1a) holds. If $d(x_\alpha, x'_\alpha) \rightarrow 0$, then $d(x_\alpha, x'_\alpha) < \delta$ for sufficiently large α . So $d(f(x_\alpha), f(x'_\alpha)) < \varepsilon$ for sufficiently large α . This proves (2).

(2) \Rightarrow (3): Obvious.

$\neg(1) \Rightarrow \neg(3)$: Assume that (1) is false. Then there exists $\varepsilon > 0$ such that for all $\delta > 0$ there exist $x, x' \in X$ with $d(x, x') < \delta$ such that $d(f(x), f(x')) \geq \varepsilon$. Thus, for each $n \in \mathbb{Z}_+$, there exist $x_n, x'_n \in X$ such that $d(x_n, x'_n) < 1/n$ and $d(f(x_n), f(x'_n)) \geq \varepsilon$. The sequences $(x_n), (x'_n)$ imply that (10.1c) is false. \square

Corollary 10.5. Assume that $f : X \rightarrow Y$ is uniformly continuous. Let $(x_\alpha)_{\alpha \in I}$ be a Cauchy net in X . Then $(f(x_\alpha))_{\alpha \in I}$ is a Cauchy net in Y .

Proof. Apply Def. 10.4-(2) to the nets $(x_\alpha)_{(\alpha, \beta) \in I^2}$ and $(x_\beta)_{(\alpha, \beta) \in I^2}$ of X . \square

10.2.2 Extensibility of uniformly continuous functions

The following theorem can be viewed as the uniform continuity version of Prop. 9.27. In particular, both results assume the completeness of the codomain.

Theorem 10.6. Let $f : X \rightarrow Y$ be uniformly continuous, and assume that Y is complete. Then there exists a (necessarily unique) uniformly continuous $\tilde{f} : \tilde{X} \rightarrow Y$ satisfying $\tilde{f}|_X = f$.

Proof. Choose any $x \in \tilde{X}$. Since X is dense in \tilde{X} , we can choose a sequence (x_n) in X converging to x in \tilde{X} . In particular, (x_n) is a Cauchy sequence. Therefore, by Cor. 10.5, $(f(x_n))$ is a Cauchy sequence in Y , which converges to some point $\tilde{f}(x) \in Y$ by the completeness of Y . If $x \in X$, we assume that (x_n) is the constant sequence x . This shows that $\tilde{f}(x) = f(x)$ if $x \in X$.

We have constructed a function $\tilde{f} : \tilde{X} \rightarrow Y$ satisfying $\tilde{f}|_X = f$. Let us prove that \tilde{f} is uniformly continuous. Choose any $\varepsilon > 0$. Since f is uniformly continuous, there is $\delta > 0$ such that for all $p, q \in X$ we have

$$d(p, q) < 2\delta \quad \implies \quad d(f(p), f(q)) < \varepsilon/2$$

Choose any $x, x' \in \tilde{X}$ satisfying $d(x, x') < \delta$. By our construction of \tilde{f} , there are sequences (x_n) in X converging to x and (x'_n) in X converging to x' such that $f(x_n) \rightarrow \tilde{f}(x)$ and $f(x'_n) \rightarrow \tilde{f}(x')$. Thus, there exist $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have

$$d(x, x_n) < \frac{\delta}{2} \quad d(x', x'_n) < \frac{\delta}{2} \quad d(\tilde{f}(x), f(x_n)) < \frac{\varepsilon}{4} \quad d(\tilde{f}(x'), f(x'_n)) < \frac{\varepsilon}{4}$$

Choose $n = N$. Then by triangle inequality, we have $d(x_n, x'_n) < 2\delta$, and hence $d(f(x_n), f(x'_n)) < \varepsilon/2$. So $d(\tilde{f}(x), \tilde{f}(x')) < \varepsilon$ by triangle inequality again. \square

We now study the other direction. The following theorem implies that if a continuous $f : X \rightarrow Y$ can be extended to a continuous $\tilde{f} : \tilde{X} \rightarrow Y$, and if \tilde{X} is compact, then f is uniformly continuous.

Theorem 10.7. *Suppose that $f : X \rightarrow Y$ is continuous and X is compact. Then f is uniformly continuous.*

In the same spirit as in Sec. 8.2, we give two proofs for this theorem, one using sequences and the other using open covers.

First proof. Assume that f is not uniformly continuous. By Def. 10.4-(3), there exist sequences (x_n) and (x'_n) in X such that $\lim_{n \rightarrow \infty} d(x_n, x'_n) = 0$, and that $d(f(x_n), f(x'_n)) \not\rightarrow 0$. The latter means that there is $\varepsilon > 0$ such that $d(f(x_n), f(x'_n))$ is frequently $\geq \varepsilon$. Thus, by passing to a subsequence, we may assume that $d(f(x_n), f(x'_n)) \geq \varepsilon$ for all n . Since $X \times X$ is sequentially compact, by replacing (x_n, x'_n) with a convergent subsequence, we assume that $x_n \rightarrow x$ and $x'_n \rightarrow x'$ where $x, x' \in X$. Since $d(x_n, x'_n) \rightarrow 0$, we must have $x = x'$. By the continuity of f , $f(x_n)$ and $f(x'_n)$ converge to $f(x) = f(x')$, contradicting the fact that $d(f(x_n), f(x'_n)) \geq \varepsilon$ for all n . \square

To prove Thm. 10.7 using open covers, we prove a more general result instead. The following theorem is useful for proving properties of the form “there exists $\delta > 0$ such that for all $x, x' \in X$ satisfying $d(x, x') < \delta$, we have ...”.

Theorem 10.8 (Lebesgue number lemma). *Assume that the metric space X is compact. Let $\mathfrak{U} \subset 2^X$ be an open cover of X . Then there exists $\delta > 0$ satisfying the following conditions:*

- For every $x \in X$ there exists $U \in \mathfrak{U}$ such that $B_X(x, \delta) \subset U$.

The number δ in Thm. 10.8 is called a **Lebesgue number** of \mathfrak{U} . In the following proof, we follow the local-to-global strategy as in Sec. 8.2.

Proof. Choose any $p \in X$. Then there is $U \in \mathfrak{U}$ containing p . So there is $\delta_p > 0$ such that $B(p, 2\delta_p) \subset U$. Therefore, there exists $V_p \in \text{Nbh}_X(p)$ such that for every x in V_p we have $B(x, \delta_p) \subset U$. (Simply take $V_p = B(p, \delta_p)$.) This solves the problem locally: for each $x \in V_p$, the ball $B(x, \delta_p)$ is a subset of some member of \mathfrak{U} .

Since $X = \bigcup_{p \in X} V_p$ and since X is compact, there is a finite subset $E \subset X$ such that $X = \bigcup_{p \in E} V_p$. Take $\delta = \min\{\delta_p : p \in E\}$. For each $x \in X$, choose $p \in E$ such that $x \in V_p$. Then $B(x, \delta_p)$ is a subset of some member of \mathfrak{U} by the last paragraph. So the same is true for $B(x, \delta)$. \square

Of course, similar to the examples studied in Sec. 8.2, Thm. 10.8 can also be proved by contradiction and by using sequential compactness. See Pb. 10.2.

Second proof of Thm. 10.7. Let us verify Def. 10.4-(1). Choose any $\varepsilon > 0$. For each $x \in X$, the set $U_x = f^{-1}(B_Y(f(x), \varepsilon/2))$ is a neighborhood of x by Prop. 7.60. So $\{U_x : x \in X\}$ is an open cover of X . Let δ be a Lebesgue number of \mathfrak{U} . Choose any $x, y \in X$ satisfying $d(x, y) < \delta$. Then $B_X(x, \delta) \subset U_z$ for some $z \in X$. So $x, y \in B_X(x, \delta)$ and hence $x, y \in U_z$. Therefore,

$$d(f(x), f(y)) \leq d(f(x), f(z)) + d(f(z), f(y)) < \varepsilon/2 + \varepsilon/2 = \varepsilon$$

□

Corollary 10.9. Choose $f \in C(X, Y)$. Consider the following statements:

- (1) f is uniformly continuous.
- (2) There exists $\tilde{f} \in C(\tilde{X}, Y)$ such that $\tilde{f}|_X = f$.

Then (1) \Rightarrow (2) if Y is complete, and (2) \Rightarrow (1) if \tilde{X} is compact.

Proof. Immediate from Thm. 10.6 and Thm. 10.7. □

Example 10.10. Let $D = B_{\mathbb{C}}(0, 1) = \{z \in \mathbb{C} : |z| < 1\}$ and $\mathbb{S}^1 = \{z \in \mathbb{C} : |z| = 1\}$. Let $f : D \rightarrow Y$ be a continuous function where Y is a complete metric space. Then f is uniformly continuous iff $\lim_{w \rightarrow z} f(w)$ exists for every $z \in \mathbb{S}^1$.

Proof. By Cor. 10.1, the limit $\lim_{w \rightarrow z} f(w)$ exists for every $z \in \mathbb{S}^1$ iff f can be extended to a continuous function $\tilde{f} : \overline{D} = D \cup \mathbb{S}^1 \rightarrow Y$. By Cor. 10.9, this is equivalent to that f is uniformly continuous (because \overline{D} is compact and Y is complete). □

10.2.3 Uniform equicontinuity

Although the notion of uniform equicontinuity will rarely be used in our notes, it is used in many textbooks. So let me give a brief account of uniform equicontinuity.

Definition 10.11. Let $(f_\alpha)_{\alpha \in I}$ be a family of functions $X \rightarrow Y$. (Here, the index set I is not necessarily directed.) Define a metric d on Y^I in a similar way as (7.19), namely, if $\mathbf{y}, \mathbf{y}' \in Y^I$ then

$$d(\mathbf{y}, \mathbf{y}') = \min \left\{ 1, \sup_{\alpha \in I} d_Y(\mathbf{y}(\alpha), \mathbf{y}'(\alpha)) \right\}$$

We say that $(f_\alpha)_{\alpha \in I}$ is **uniformly equicontinuous** if the map

$$X \rightarrow Y^I \quad x \mapsto (f_\alpha(x))_{\alpha \in I} \tag{10.2}$$

is uniformly continuous with respect to the metric d . Clearly, this is equivalent to saying that:

- For every $\varepsilon > 0$ there exists $\delta > 0$ such that for every $x, x' \in X$ satisfying $d(x, x') < \delta$, we have

$$\sup_{\alpha \in I} d_Y(f_\alpha(x), f_\alpha(x')) < \varepsilon$$

Uniformly equicontinuous families of functions are equicontinuous, because uniformly continuous functions are continuous. Conversely, we have:

Proposition 10.12. *Assume that X is compact and $(f_\alpha)_{\alpha \in I}$ is a family of functions $X \rightarrow Y$. Then $(f_\alpha)_{\alpha \in I}$ is equicontinuous iff it is uniformly equicontinuous.*

Proof. “ \Leftarrow ” is obvious, as mentioned above. “ \Rightarrow ” follows immediately by applying Thm. 10.7 to the continuous map (10.2). \square

10.3 Completion of metric spaces

Fix a metric space X in this section. We are going to apply uniform continuity to the study of completions of metric spaces. Roughly speaking, a completion of X is a complete metric space \hat{X} containing X as a dense subspace. However, completions are not unique, but are unique “up to equivalence”. So we want to show that two completions \hat{X}, \tilde{X} of the same metric space X are equivalent. However, it is confusing to view X as a subset of \hat{X} and \tilde{X} simultaneously. A better approach is to consider (automatically injective) isometries $\varphi : X \rightarrow \hat{X}, \psi : X \rightarrow \tilde{X}$, and to show that φ and ψ are equivalent using the language of commutative diagrams (cf. Sec. 1.2).

Definition 10.13. A **completion** of the metric space X is an isometry $\varphi : X \rightarrow \hat{X}$ where \hat{X} is a complete metric space, and $\varphi(X)$ is dense in \hat{X} . We sometimes just say that \hat{X} is a completion of X .

Thus, if A is a dense subset of a complete metric space B , then the inclusion map $A \hookrightarrow B$ is a completion. Therefore, \mathbb{R} is a completion of \mathbb{Q} , and $[0, 1]$ is a completion of $(0, 1), [0, 1), [0, 1] \cap \mathbb{Q}$.

Example 10.14. Let A be a dense subset of a metric space X . Suppose that $\varphi : X \rightarrow \hat{X}$ is a completion of X . Then $\varphi|_A : A \rightarrow \hat{X}$ is clearly a completion of A .

Example 10.15. Let X be a subset of a complete metric space Y . Then $X \hookrightarrow \text{Cl}_Y(X)$ is a completion of X because every closed subset of Y is complete (cf. Prop. 3.27), and hence $\text{Cl}_Y(X)$ is complete. For example, $\{(x, y) \in \mathbb{R}^2 : x \geq 0\}$ is a completion of both $A = \{(x, y) \in \mathbb{R}^2 : x > 0\}$ and $B = A \cap \mathbb{Q}^2$.

We want to prove that every metric space X has a completion \hat{X} . First, we need a lemma, which can be viewed as analogous to Pb. 8.9.

Lemma 10.16. Suppose that X is a dense subspace of a metric space \hat{X} . Suppose that every Cauchy sequence in X converges to an element of \hat{X} . Then \hat{X} is complete.

Proof. Let (x_n) be a Cauchy sequence in \hat{X} . Since X is dense, there exists $x'_n \in X$ such that $d(x_n, x'_n) < 1/n$. So (x'_n) is Cauchy-equivalent to (x_n) . Thus (x'_n) is a Cauchy sequence by Exe. 5.37. By assumption, (x'_n) converges to some $x \in X$. So (x_n) also converges to x by Exe. 5.37. \square

Theorem 10.17. Every metric space X has a completion $\varphi : X \rightarrow \hat{X}$. Moreover, any completion $\psi : X \rightarrow \tilde{X}$ is **equivalent** (also called **isomorphic**) to φ in the sense that there is an isometric isomorphism of metric spaces $\Phi : \hat{X} \rightarrow \tilde{X}$ such that the following diagram commutes:

$$\begin{array}{ccc} & X & \\ \varphi \swarrow & & \searrow \psi \\ \hat{X} & \xrightarrow[\simeq]{\Phi} & \tilde{X} \end{array} \quad (10.3)$$

Recall that the commutativity of (10.3) means that $\psi = \Phi \circ \varphi$.

Proof of existence. The construction of $\varphi : X \rightarrow \hat{X}$ is similar to the construction of \mathbb{R} from \mathbb{Q} in Ch. 6. Let \mathcal{C} be the set of Cauchy sequences in X . Let $\hat{X} = \mathcal{C} / \sim$ be the quotient set (cf. Def. 1.18) where \sim is the Cauchy-equivalence relation: $(x_n) \sim (y_n)$ iff $\lim_{n \rightarrow \infty} d(x_n, y_n) = 0$. We let $[x_n]_{n \in \mathbb{Z}_+}$ or simply let $[x_n]$ denote the equivalence class of (x_n) in \hat{X} . The map φ is defined by

$$\varphi : X \rightarrow \hat{X} \quad x \mapsto [x]_{n \in \mathbb{Z}_+}$$

where $[x]_{n \in \mathbb{Z}_+}$ is the equivalence class of the constant sequence (x, x, \dots) .

Step 1: Let us define a metric $d_{\hat{X}}$ on \hat{X} . Note that if $(x_n), (y_n) \in \mathcal{C}$, then by triangle inequality,

$$|d(x_m, y_m) - d(x_n, y_n)| \leq d(x_m, x_n) + d(y_m, y_n)$$

where the RHS converges to 0 as $m, n \rightarrow +\infty$. Therefore, the LHS also converges to 0. This shows that $(d(x_n, y_n))_{n \in \mathbb{Z}_+}$ is a Cauchy sequence in $\mathbb{R}_{\geq 0}$, and hence converges. Therefore, we define

$$\begin{aligned} d_{\hat{X}} : \hat{X} \times \hat{X} &\rightarrow \mathbb{R}_{\geq 0} \\ d_{\hat{X}}([x_n], [y_n]) &= \lim_{n \rightarrow \infty} d(x_n, y_n) \end{aligned}$$

This is well-defined: If $[x_n] = [x'_n]$, and $[y_n] = [y'_n]$, then

$$|d(x_n, y_n) - d(x'_n, y'_n)| \leq d(x_n, x'_n) + d(y_n, y'_n)$$

which converge to 0 as $n \rightarrow \infty$. So $(d(x'_n, y'_n))_{n \in \mathbb{Z}_+}$ and $(d(x_n, y_n))_{n \in \mathbb{Z}_+}$ are Cauchy-equivalent, and hence converge to the same number.

Clearly $d_{\hat{X}}([x_n], [y_n]) = 0$ iff $(x_n) \sim (y_n)$ iff $[x_n] = [y_n]$. And clearly $d_{\hat{X}}([x_n], [y_n]) = d_{\hat{X}}([y_n], [x_n])$. If $[x_n], [y_n], [z_n]$ are in \mathcal{C} , applying $\lim_{n \rightarrow \infty}$ to

$$d(x_n, z_n) \leq d(x_n, y_n) + d(y_n, z_n)$$

yields $d_{\hat{X}}([x_n], [z_n]) \leq d_{\hat{X}}([x_n], [y_n]) + d_{\hat{X}}([y_n], [z_n])$. So $d_{\hat{X}}$ is a metric.

Step 2. The map $\varphi : X \rightarrow \hat{X}$ is clearly an isometry. Let us show that it has dense range. Choose any $[x_n]_{n \in \mathbb{Z}_+} \in \hat{X}$. We shall show that $\varphi(x_k) = [x_k, x_k, \dots]$ approaches $[x_n]_{n \in \mathbb{Z}_+}$ as $k \rightarrow \infty$.

For each k , we have

$$d_{\hat{X}}(\varphi(x_k), [x_n]_{n \in \mathbb{Z}_+}) = \lim_{n \rightarrow \infty} d(x_k, x_n) \quad (10.4)$$

where the RHS converges because $d_{\hat{X}}$ is defined. Since $(x_n)_{n \in \mathbb{Z}_+}$ is a Cauchy sequence in X , we have

$$\lim_{k, n \rightarrow \infty} d(x_k, x_n) = 0 \quad (10.5)$$

Therefore, by (10.5) and the convergence of the RHS of (10.4), we can use Thm. 5.29 to conclude that

$$\lim_{k \rightarrow \infty} d_{\hat{X}}(\varphi(x_k), [x_n]_{n \in \mathbb{Z}_+}) = \lim_{k \rightarrow \infty} \lim_{n \rightarrow \infty} d(x_k, x_n) = \lim_{k, n \rightarrow \infty} d(x_k, x_n) = 0$$

Step 3. It remains to prove that \hat{X} is complete. By Lem. 10.16 (applied to $\varphi(X) \subset \hat{X}$) and the fact that φ is an isometry, it suffices to prove that for every Cauchy sequence $(x_k)_{k \in \mathbb{Z}_+}$ in X , the sequence $(\varphi(x_k))_{k \in \mathbb{Z}_+}$ converges in \hat{X} . But this is true: we have shown in Step 2 that $(\varphi(x_k))_{k \in \mathbb{Z}_+}$ converges to $[x_n]_{n \in \mathbb{Z}_+}$. \square

Proof of equivalence. Suppose that $\psi : X \rightarrow \tilde{X}$ is another completion. The map

$$\Phi : \varphi(X) \rightarrow \psi(X) \quad \varphi(x) \mapsto \psi(x)$$

is well-defined since φ is injective. Moreover, Φ is an isometry since φ and ψ are isometries. In particular, Φ is uniformly continuous. Therefore, by Cor. 10.9, Φ can be extended to a uniformly continuous map $\Phi : \hat{X} \rightarrow \tilde{X}$. Clearly $\psi = \Phi \circ \varphi$. The continuous map

$$\begin{aligned} \hat{X} \times \hat{X} &\rightarrow \mathbb{R} \\ (p, q) &\mapsto d_{\tilde{X}}(\Phi(p), \Phi(q)) - d_{\hat{X}}(p, q) \end{aligned}$$

is zero on the dense subset $\varphi(X) \times \varphi(X)$ of its domain. Therefore it is constantly zero by Prop. 7.63. This proves that Φ is an isometry.

It remains to prove that Φ is surjective. Since \hat{X} is complete and Φ restricts to an isometric isomorphism of metric spaces $\hat{X} \rightarrow \Phi(\hat{X})$, $\Phi(\hat{X})$ is a complete metric subspace of \tilde{X} . Thus, by Prop. 3.27, $\Phi(\hat{X})$ is a closed subset of \tilde{X} . But $\Phi(\hat{X})$ is dense in \tilde{X} since it contains $\psi(X)$. Therefore $\Phi(\hat{X}) = \tilde{X}$. \square

The proof of Thm. 10.17 is complete.

10.4 Why did Hausdorff believe in completion?

Thm. 10.17, the existence and uniqueness of completion of an arbitrary metric space, was proved by Hausdorff in his 1914 work introducing Hausdorff topological spaces [Hau14, Sec. 8.8, p.315]. The construction of completion using equivalence classes of Cauchy sequences is quite abstract: Although it mimics Cantor's construction of real numbers (cf. Ch. 6), its main application is not in the realm of finite-dimensional geometric objects, but in the world of function spaces. But what is the practical significance of the equivalence classes of Cauchy sequences of functions? In concrete analysis problems about functions, these objects are much more difficult to deal with than functions themselves.

Strangely enough, the only nontrivial examples we have now is $\mathbb{Q} \hookrightarrow \mathbb{R}$. Besides this, we do not yet have any exciting new metric spaces arising from completion. For example: we know that $[0, 1]$ is the completion of $(0, 1)$ under the Euclidean metric, and that $C([0, 1], \mathbb{R})$ is the completion of the set of real polynomials $\mathbb{R}[x]$ under the norm $\sup_{x \in [0, 1]} |f(x)|$. (The density of the set of polynomials in $C([0, 1], \mathbb{R})$ is due to Weierstrass.) But $[0, 1]$ and $C([0, 1], \mathbb{R})$ are examples we are already familiar with.

Mathematicians do not generalize just for the sake of generalization. They want to solve problems by generalizing old concepts to a broader context. Moreover, mathematicians do not randomly choose a way of generalization and then build a huge theory. Instead, they develop a theory only in the direction that has already proved useful in solving explicit problems. Thus, Hausdorff proved Thm. 10.17 because he was already convinced of the importance of abstract completion by certain powerful examples. For the moment, we are not ready to study these examples rigorously. (We will do this in the next semester.) But I want to give an informal introduction to one of these examples which historically has paved the way for many important ideas in analysis.

10.4.1 The Fourier series method in integral equations

In the years of 1900-1907, many important progress has been made in integral equations, which originated from the study of Dirichlet problems (finding solutions of harmonic equation $\Delta\varphi(x, y) = 0$ with given boundary condition,

where $\Delta = (\partial_x)^2 + (\partial_y)^2$. For example, one asks if there is $\lambda \in \mathbb{R}$ and a single-variable complex valued function $f : [0, 2\pi] \rightarrow \mathbb{C}$ satisfying the eigenvalue problem $Tf = \lambda f$ where

$$(Tf)(x) = \int_0^{2\pi} K(x, y)f(y)dy$$

and $K : [0, 2\pi]^2 \rightarrow \mathbb{R}$ is given. (Cf. also Sec. 2.1.)

Hilbert studied this problem using Fourier series. In the modern language, the theory of Fourier series claims that $C([0, 2\pi], \mathbb{C})$, under the L^2 -norm

$$\|f\|_{L^2} = \sqrt{\int_0^{2\pi} |f(x)|^2 \cdot \frac{dx}{2\pi}} \quad (10.6)$$

has a completion

$$\begin{aligned} \Phi : C([0, 2\pi], \mathbb{C}) &\rightarrow l^2(\mathbb{Z}, \mathbb{C}) \\ \Phi(f) &= \hat{f} \end{aligned}$$

(10.7)

where $l^2(\mathbb{Z}, \mathbb{C})$ is the space of all $g : \mathbb{Z} \rightarrow \mathbb{C}$ satisfying $\sqrt{\sum_{n \in \mathbb{Z}} |g(n)|^2} < +\infty$, and

$$\hat{f} : \mathbb{Z} \rightarrow \mathbb{C} \quad \hat{f}(n) = \int_0^{2\pi} f(x)e^{-inx} \cdot \frac{dx}{2\pi}$$

gives the **Fourier coefficients** of f . See Cor. 20.42.

Hilbert studied the eigenvalue problem $Tf = \lambda f$ by transforming it into a linear algebra problem on $l^2(\mathbb{Z}, \mathbb{C})$ (so that T becomes an $\infty \times \infty$ discrete matrix \hat{T}), finding the possible eigenvectors \hat{f} and eigenvalues λ satisfying

$$\hat{T}\hat{f} = \lambda\hat{f}$$

and returning to the original problems by finding the function f whose Fourier coefficients are \hat{f} . It is easy to return: if $f \in C([0, 2\pi], \mathbb{C})$, then one gets f from \hat{f} by the formula

$$f(x) = \sum_{n \in \mathbb{Z}} \hat{f}(n)e^{inx} \quad (10.8)$$

where the RHS is called the **Fourier series** of f .

Here comes the crucial point: the range of Φ , namely $\{\hat{f} : f \in C([0, 1], \mathbb{C})\}$, is not the whole space $l^2(\mathbb{Z}, \mathbb{C})$ but only its dense subspace. This remains true if we enlarge $C([0, 1], \mathbb{C})$ to the space of Riemann integrable functions $\mathcal{R}([0, 1], \mathbb{C})$. However, the eigenvectors of \hat{T} found by Hilbert were only known to be elements

of $l^2(\mathbb{Z}, \mathbb{C})$. If we use (10.8) to find the eigenvectors of the original T , namely, if for an arbitrary $g \in l^2(\mathbb{Z}, \mathbb{C})$ we write

$$\Psi(g) = \sum_{n \in \mathbb{Z}} g(n) e^{inx} \quad (10.9)$$

then $\Psi(g)$ is not necessarily continuous or even Riemann integrable. It seems that, in the light of the proof of Thm. 10.17, the only way to make sense of (10.9) is as follows:

- One views $\Psi(g)$ as the Cauchy-equivalence class of the Cauchy sequence $(s_n)_{n \in \mathbb{Z}_+}$ in $C([0, 2\pi], \mathbb{C})$ under the L^2 -norm, where $s_n(x) = \sum_{k=-n}^n g(k) e^{ikx}$.

But how can we understand $\Psi(g)$ as an actual function on $[0, 2\pi]$ solving the eigenvalue problem $T\Psi(g) = \lambda\Psi(g)$?

Therefore, (10.7) and (10.9) are the very first example of abstract completion, and also one of the most important examples motivating Hausdorff's study of completion in general.

10.4.2 Riesz-Fischer theorem

Hilbert established these results by 1906, the same year Fréchet defined metric spaces. The story was finished by Riesz and Fischer, who proved in 1907 that $\Psi(g)$ can actually be represented by a **Lebesgue measurable** $f : [0, 2\pi] \rightarrow \mathbb{C}$ satisfying $\|f\|_{L^2} < +\infty$, where the norm $\|f\|_{L^2}$ is defined by (10.6) using Lebesgue integral instead of Riemann integral. Let $L^2([0, 2\pi], \mathbb{C})$ denote the space of all such functions, and view $C([0, 2\pi], \mathbb{C})$ as its subspace. Then using the language of Thm. 10.17, we have a commutative diagram

$$\begin{array}{ccc} & C([0, 2\pi], \mathbb{C}) & \\ \Phi \swarrow & & \searrow \iota \\ l^2(\mathbb{Z}, \mathbb{C}) & \xrightarrow[\simeq]{\Psi} & L^2([0, 2\pi], \mathbb{C}) \end{array} \quad (10.10)$$

where ι is the inclusion map. Thus:

- The abstract completion $\Phi : C([0, 2\pi], \mathbb{C}) \rightarrow l^2(\mathbb{Z}, \mathbb{C})$ is equivalent to the concrete completion $C([0, 2\pi], \mathbb{C}) \subset L^2([0, 2\pi], \mathbb{C})$, where “concrete” means that it is function-theoretic.

This equivalence of abstract and concrete completions, connecting Hilbert's algebraic approach to integral equations and Lebesgue's function-theoretic approach

to measure theory, is the original form of **Riesz-Fischer theorem** (proved in 1907),¹ one of the most significant theorems in early 20th century.

Thanks to Riesz-Fischer theorem, people were convinced that abstract completions of function spaces could deepen one's understanding of analysis in much the same way that Lebesgue's measure theory broadened one's understanding of functions by harmonizing with Hilbert's l^2 theory. So what is the hesitation in trying to prove an abstract theorem like Thm. 10.17?

Hausdorff proved the existence and uniqueness of completion in general, but it was Riesz-Fischer theorem that proved the value of abstract completion.

10.5 Completion of normed vector spaces

Fix a normed vector space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Definition 10.18. A **completion of the normed vector space** V (or a **Banach space completion** of V) is a *linear isometry* $\varphi : V \rightarrow \widehat{V}$ such that \widehat{V} is a Banach space, and $\varphi(V)$ is dense in \widehat{V} .

Thus, if $\varphi : V \rightarrow \widehat{V}$ is a completion, then V is isomorphic to $\varphi(V)$ as normed vector spaces, and hence can be viewed as equivalently a dense normed subspace of \widehat{V} .

Theorem 10.19. Every normed vector space V has a completion $\varphi : V \rightarrow \widehat{V}$. Moreover, every completion $\psi : V \rightarrow \widetilde{V}$ is **isomorphic** to φ in the sense that there is an isomorphism of Banach spaces (cf. Def. 9.2) $\Phi : \widehat{V} \rightarrow \widetilde{V}$ such that the following diagram commutes:

$$\begin{array}{ccc} & V & \\ \varphi \swarrow & & \searrow \psi \\ \widehat{V} & \xrightarrow[\simeq]{\Phi} & \widetilde{V} \end{array} \quad (10.11)$$

Proof of existence. By Thm. 10.17, we have a completion $\varphi : V \rightarrow \widehat{V}$ in the context of metric spaces. So \widehat{V} is a completion of metric space with metric $d_{\widehat{V}}$, and φ is an isometry of metric spaces with dense range. We need to show that \widehat{V} is a complete normed vector space, and that φ is linear with dense range. Indeed, we shall identify V with $\varphi(\widehat{V})$ via φ so that V is the metric subspace of \widehat{V} . We shall extend the structure of normed vector space from V to \widehat{V} . In the following, the

¹More precisely, the original form of Riesz-Fischer theorem says that the Ψ in (10.10) (whose explicit description is as in (10.9)) is an isometric isomorphism. As a consequence, the space L^2 is complete, because it is fairly easy to show that l^2 is complete. However, most modern analysis textbooks present Riesz-Fischer theorem in the following simple form: " L^2 is a complete metric space".

convergence in \widehat{V} and the continuity of the maps about \widehat{V} are understood using the metric $d_{\widehat{V}}$.

The map

$$+ : V \times V \rightarrow V \quad (u, v) \mapsto u + v$$

is Lipschitz continuous, and hence uniformly continuous. Therefore, by Cor. 10.9, it can be extended (uniquely) to a continuous map $+ : \widehat{V} \times \widehat{V} \rightarrow \widehat{V}$. Similarly, if $\lambda \in \mathbb{F}$, the Lipschitz continuous map

$$V \rightarrow V \quad v \mapsto \lambda \cdot v$$

can be extended to a continuous map $\widehat{V} \rightarrow \widehat{V}$. Thus, we have defined the addition $+$ and the scalar multiplication \cdot for \widehat{V} . Similarly, the map

$$\| \cdot \| : V \rightarrow \mathbb{R}_{\geq 0} \quad v \mapsto \|v\|$$

is uniformly continuous and hence can be extended to a map $\widehat{V} \rightarrow \mathbb{R}_{\geq 0}$.

We want to show that the above addition, scalar multiplication, and norm function make \widehat{V} a normed vector space. For example, suppose that $\lambda \in \mathbb{F}$. We want to prove that $\lambda(u + v) = \lambda u + \lambda v$ for all $u, v \in \widehat{V}$, and we know that this is true when $u, v \in V$. Indeed, since $V \times V$ is dense in $\widehat{V} \times \widehat{V}$, and since the following two continuous maps

$$\begin{aligned} (u, v) \in \widehat{V} \times \widehat{V} &\mapsto \lambda(u + v) \in \widehat{V} \\ (u, v) \in \widehat{V} \times \widehat{V} &\mapsto \lambda u + \lambda v \in \widehat{V} \end{aligned}$$

are equal on $V \times V$, these two maps are the same by Prop. 7.63. The same argument proves that \widehat{V} is a vector space.

Since the following continuous map

$$\varphi : (u, v) \in \widehat{V} \times \widehat{V} \mapsto \|u\| + \|v\| - \|u + v\| \in \mathbb{R}$$

satisfies $\varphi(V \times V) \subset \mathbb{R}_{\geq 0}$, by $\varphi(\widehat{V} \times \widehat{V}) \subset \overline{\varphi(V \times V)}$ (due to Prop. 7.63 again), we conclude that $\varphi(\widehat{V} \times \widehat{V}) \subset \mathbb{R}_{\geq 0}$. So $\|u + v\| \leq \|u\| + \|v\|$ for all $u, v \in \widehat{V}$. A similar argument shows $\|\lambda v\| = |\lambda| \cdot \|v\|$.

Since the metric on V is induced by the norm of V , the map

$$\widehat{V} \times \widehat{V} \rightarrow \mathbb{R} \quad (u, v) \mapsto d_{\widehat{V}}(u, v) - \|u - v\|$$

is zero on the dense subset $V \times V$ of $\widehat{V} \times \widehat{V}$. Since this map is continuous, it is constantly zero. In particular, if $v \in \widehat{V}$ satisfies $\|v\| = 0$, then $d_{\widehat{V}}(v, 0) = 0$, and hence $v = 0$. So $\| \cdot \|$ is a norm on \widehat{V} , and the complete metric $d_{\widehat{V}}$ on \widehat{V} (arising from the metric-space-completion of V) is defined by this norm. So this norm is complete. Therefore, \widehat{V} is a Banach space. Since V is dense in \widehat{V} under $d_{\widehat{V}}$, V is dense in \widehat{V} under the norm of \widehat{V} . \square

Proof of uniqueness. By Thm. 10.17, there is a unique isometric isomorphism of metric spaces $\Phi : \hat{V} \rightarrow \tilde{V}$ such that $\psi = \Phi \circ \varphi$. Since φ and ψ are linear injections, Φ is a linear isomorphism when restricted to $\varphi(V) \rightarrow \psi(V)$. Since Φ is continuous and $\varphi(V)$ is dense in \hat{V} , we conclude that Φ is linear thanks to the following property. \square

Proposition 10.20. *Let $T : V \rightarrow W$ be a continuous map of normed vector spaces. Assume that V_0 is a dense linear subspace of V . Assume that $T|_{V_0} : V_0 \rightarrow W$ is linear. Then T is linear.*

Proof. This is same as the proof of the existence part of Thm. 10.19. Choose any $\alpha, \beta \in \mathbb{F}$. Then the following continuous map

$$(u, v) \in V \times V \mapsto T(\alpha u + \beta v) - (\alpha T(u) + \beta T(v))$$

is zero on the dense subset $V_0 \times V_0$. So it is zero on $V \times V$. \square

Exercise 10.21. Let V and W be normed vector spaces over \mathbb{F} , where $\mathbb{F} = \mathbb{R}$ (resp. $\mathbb{F} = \mathbb{C}$). Let $T : V \rightarrow W$ be a continuous map. Assume that V_0 is a dense \mathbb{K} -linear subspace of V , where $\mathbb{K} = \mathbb{Q}$ (resp. $\mathbb{K} = \mathbb{Q} + i\mathbb{Q}$). Assume that the restriction $T|_{V_0} : V_0 \rightarrow W$ is \mathbb{K} -linear. Prove that $T : V \rightarrow W$ is \mathbb{F} -linear.

Remark 10.22. So far in this course, we have proved a lot of results about functions whose codomains are normed vector spaces. Some results assume that these spaces are Banach (i.e. complete), some do not. Thanks to Thm. 10.19, we can assume that all these results are stated only for Banach spaces, and then check whether they also hold for normed vector spaces in general (which is not difficult). This will make us easier to remember theorems.

For example, suppose that we know that Thm. 7.79 holds only for Banach spaces: Namely, suppose we know that for any Banach space V and topological space X , if (f_α) is a net in $C(X, V)$ converging uniformly to $f : X \rightarrow V$, then f is continuous. Then we know that this result also holds when V is a normed vector space. To see this, consider the completion $V \subset \hat{V}$. Then (f_α) is a net of continuous functions $X \rightarrow \hat{V}$ converging uniformly to some $f : X \rightarrow \hat{V}$ (satisfying $f(X) \subset V$). Then $f : X \rightarrow \hat{V}$ is continuous. Hence $f : X \rightarrow V$ is continuous.

Consider Prop. 9.27 as another example. It tells us that if V is a Banach space and (f_α) is a net in $C(X, V)$ converging uniformly on a dense subset $E \subset X$, then (f_α) converges uniformly on X . Now assume that V is only a normed vector space, and take completion $V \subset \hat{V}$. Then (f_α) is a net in $C(X, \hat{V})$ converges uniformly on E to a function $E \rightarrow V$. Thus, by Prop. 9.27, it converges uniformly to a function $f : X \rightarrow \hat{V}$. Although we know $f(E) \subset V$ by assumption, we do not know whether $f(X) \subset V$. So we cannot prove the normed vector space version of Prop. 9.27. \square

10.6 Bounded linear maps

In this section, we consider normed vector spaces over a given field $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

We have seen that uniform continuity is crucial to the construction of addition and scalar multiplication in Thm. 10.19. Indeed, uniform continuity is ubiquitous in the world of normed vector spaces: We shall see that every continuous linear map of normed vector spaces is uniformly continuous.

Definition 10.23. Let $T : V \rightarrow W$ be a linear map of normed vector spaces. The **operator norm** $\|T\|$ is defined to be

$$\|T\| \stackrel{\text{def}}{=} \sup_{v \in \overline{B}_V(0,1)} \|Tv\| \quad (10.12)$$

Remark 10.24. $\|T\|$ is the smallest number in $\overline{\mathbb{R}}_{\geq 0}$ satisfying

$$\|Tv\| \leq \|T\| \cdot \|v\| \quad (\forall v \in V) \quad (10.13)$$

Proof. (10.13) is clearly true when $v = 0$. Assume $v \neq 0$. Since $v/\|v\| \in \overline{B}_V(0,1)$, we have $\|T(v/\|v\|)\| \leq \|T\|$. This proves (10.13).

Now suppose that $C \in \overline{\mathbb{R}}_{\geq 0}$ satisfies that $\|Tv\| \leq C\|v\|$ for all v . Then for each $v \in \overline{B}_V(0,1)$ we have $\|Tv\| \leq C$. So $\|T\| \leq C$. \square

Proposition 10.25. Let $T : V \rightarrow W$ be a linear map of normed vector spaces. Then the following are equivalent:

- (1) T is Lipschitz continuous.
- (2) T is continuous.
- (3) T is continuous at 0.
- (4) $\|T\| < +\infty$.

Moreover, if one of these conditions holds, then T has Lipschitz constant $\|T\|$.

Proof. Clearly (1) \Rightarrow (2) and (2) \Rightarrow (3). Suppose (3) is true. Note that $T0 = 0$. So there is $\delta > 0$ such that $Tv \in \overline{B}_W(0,1)$ for all $v \in \overline{B}_V(0,\delta)$. Namely, for all $v \in V$ satisfying $\|v\| \leq \delta$ we have $\|Tv\| = \|Tv - T0\| \leq 1$. Thus, if $\|v\| \leq 1$, then $\|\delta v\| \leq \delta$. So

$$\|Tv\| = \delta^{-1} \|T(\delta v)\| \leq \delta^{-1}$$

This proves $\|T\| \leq \delta^{-1}$. So (4) is proved.

Assume (4). By Rem. 10.24, for each $u, v \in V$ we have

$$\|Tu - Tv\| = \|T(u - v)\| \leq \|T\| \cdot \|u - v\|$$

This proves that T has Lipschitz constant $\|T\|$. \square

Due to Prop. 10.25-(4), we make the following definition:

Definition 10.26. Let V, W be normed vector spaces over \mathbb{F} . We call $T : V \rightarrow W$ to be a **bounded linear map** if T is a continuous linear map. We write

$$\mathfrak{L}(V, W) = \{\text{bounded linear maps } V \rightarrow W\} \quad \mathfrak{L}(V) = \mathfrak{L}(V, V) \quad (10.14)$$

Thus, the word “bounded” means that the linear map T is bounded on $\overline{B}_V(0, 1)$, but not that T is bounded on V .

Proposition 10.27. $\mathfrak{L}(V, W)$ is a linear subspace of W^V , and the operator norm $\|\cdot\|$ is a norm on $\mathfrak{L}(V, W)$.

Proof. By Rem. 10.24, for each linear $S, T : V \rightarrow W$ and $\lambda \in \mathbb{F}$, and for each $v \in V$ we have

$$\begin{aligned} \|(S + T)v\| &\leq \|Sv\| + \|Tv\| \leq (\|S\| + \|T\|)\|v\| \\ \|\lambda Tv\| &= |\lambda| \cdot \|Tv\| \leq |\lambda| \cdot \|T\| \cdot \|v\| \end{aligned}$$

Thus, by Rem. 10.24 again, we have

$$\|S + T\| \leq \|S\| + \|T\| \quad \|\lambda T\| \leq |\lambda| \cdot \|T\| \quad (10.15)$$

The proposition now follows easily from the above inequalities. (Notice Rem. 3.34) \square

Since Lipschitz continuous functions are uniformly continuous, we have:

Proposition 10.28. Let V_0 be a dense linear subspace of a normed vector space V . Let W be a Banach space. Let $T_0 : V_0 \rightarrow W$ be a bounded linear map. Then there is a unique bounded linear map $T : V \rightarrow W$ such that $T|_{V_0} = T_0$.

Proof. Uniqueness is clear from the density of V_0 . By Prop. 10.25, T_0 is uniformly continuous. Therefore, by Cor. 10.9, T_0 can be extended to a continuous map $T : V \rightarrow W$, which is linear by Prop. 10.20. \square

10.7 Problems and supplementary material

Problem 10.1. Give a direct proof of Thm. 10.7 using open covers instead of using subsequences. Do not use Lebesgue numbers.

The following Pb. 10.2 gives another proof that sequentially compact metric spaces are compact. Therefore, do not use this fact in your solution of Pb. 10.2.

*** Problem 10.2.** Let X be a sequentially compact metric space. Let $\mathfrak{U} \subset 2^X$ be an open cover of X .

1. Prove that \mathfrak{U} has a Lebesgue number. Namely, prove that there exists $\delta > 0$ such that for every $x \in X$ there is $U \in \mathfrak{U}$ satisfying $B_X(x, \delta) \subset U$.
2. In our proof that X is separable (cf. Thm. 8.34), we showed that for every $\delta > 0$ there exists a finite set $E \subset X$ such that $d(x, E) < \delta$ for all $x \in X$. Use this fact and Part 1 to prove that \mathfrak{U} has a finite subcover.

Definition 10.29. Two norms $\|\cdot\|_1$ and $\|\cdot\|_2$ on a vector space V over \mathbb{R} or \mathbb{C} are called **equivalent** if there exist $\alpha, \beta > 0$ such that for all $v \in V$ we have

$$\|v\|_1 \leq \alpha \|v\|_2 \quad \|v\|_2 \leq \beta \|v\|_1$$

Clearly, two equivalent norms induce equivalent metrics, and hence induce the same topology.

Problem 10.3. Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let $\|\cdot\|$ be the Euclidean norm on \mathbb{F}^n . Let $\nu : \mathbb{F}^n \rightarrow \mathbb{R}_{\geq 0}$ be a norm on \mathbb{F}^n .

1. Prove that there exists $\alpha > 0$ such that $\nu(\mathbf{x}) \leq \alpha \|\mathbf{x}\|$ for all $\mathbf{x} \in \mathbb{F}^n$. In particular, show that ν is continuous (under the Euclidean topology).
2. Let $\beta = \inf\{\nu(\mathbf{x}) : \mathbf{x} \in \mathbb{F}^n, \|\mathbf{x}\| \leq 1\}$. Prove that $\beta > 0$. Prove that $\|\mathbf{x}\| \leq \beta^{-1} \cdot \nu(\mathbf{x})$ for all $\mathbf{x} \in \mathbb{F}^n$.

The above problem proves

Theorem 10.30. Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Then any norm on \mathbb{F}^n is equivalent to the Euclidean norm. In particular, the operator norm on $\mathbb{F}^{m \times n}$ (if we view an $m \times n$ matrix as an element of $\mathfrak{L}(\mathbb{F}^n, \mathbb{F}^m)$) is equivalent to the Euclidean norm.

11 Derivatives

11.1 Basic properties of derivatives

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let Ω be a nonempty open subset of \mathbb{C} . The following assumption will be often considered:

Definition 11.1. Let $f : [a, b] \rightarrow V$ (where $-\infty < a < b < +\infty$) be a map with variable t , and let $x \in [a, b]$. The **derivative** of f at x is

$$f'(x) \equiv \frac{df}{dt}(x) \stackrel{\text{def}}{=} \lim_{\substack{t \in [a, b] \setminus \{x\} \\ t \rightarrow x}} \frac{f(t) - f(x)}{t - x} = \lim_{\substack{h \in [a-x, b-x] \setminus \{0\} \\ h \rightarrow 0}} \frac{f(x+h) - f(x)}{h}$$

provided that the limits converge. In other words (cf. Def. 7.81),

- $f'(x)$ converges to $v \in V$ iff for every $\varepsilon > 0$ there exists $\delta > 0$ such that for every $t \in [a, b]$ satisfying $0 < |t - x| < \delta$ we have

$$\left\| \frac{f(t) - f(x)}{t - x} - v \right\| < \varepsilon$$

If $f'(x)$ exists for some x , we say that f is **differentiable** at x . If $f'(x)$ exists for every $x \in [a, b]$, we say that f is a **differentiable function** and view f' as a function $[a, b] \rightarrow V$.

Derivatives on intervals $[a, b)$, $(a, b]$, (a, b) are understood in a similar way. \square

Definition 11.2. Let E be a subset of \mathbb{R}^n . Let $f : E \rightarrow V$ be a function with variables t_1, \dots, t_n , and $\mathbf{x} = (x_1, \dots, x_n) \in E$. Let $1 \leq i \leq n$. Suppose that there are a, b satisfying $-\infty < a < x_i < b < +\infty$ such that $(x_1, \dots, x_{i-1}, t, x_{i+1}, \dots, x_n)$ belongs to E for all $t \in [a, b]$. The derivative of the function $t_i \mapsto f((x_1, \dots, x_{i-1}, t_i, x_{i+1}, \dots, x_n))$ at $t = x_i$ is denoted by

$$\frac{\partial f}{\partial t_i}(\mathbf{x}) \equiv \partial_i f(\mathbf{x})$$

and called the **partial derivative** of f at \mathbf{x} with respect to the variable t_i .

Definition 11.3. If V is over \mathbb{C} , and if $f : \Omega \rightarrow V$ and $z \in \Omega$, we define the **derivative** of f at z to be

$$f'(z) = \lim_{\substack{w \in \Omega \setminus \{z\} \\ w \rightarrow z}} \frac{f(w) - f(z)}{w - z}$$

provided that the RHS exists, and simply write it as

$$\lim_{w \rightarrow z} \frac{f(w) - f(z)}{w - z} = \lim_{\zeta \rightarrow 0} \frac{f(z + \zeta) - f(z)}{\zeta}$$

Convention 11.4. Unless otherwise stated, when talking about derivatives of a function defined on an interval I , we always assume that I is inside \mathbb{R} and has at least two points. When talking about derivatives of a function $f : \Omega \rightarrow V$, we always assume that V is over \mathbb{C} .

Definition 11.5. Given a function $f : E \rightarrow V$ where E is an interval in \mathbb{R} with at least two points or $E = \Omega$, if $n \in \mathbb{N}$ and $x \in E$, we define the **n -th derivative** $f^{(n)}(x)$ inductively by $f^{(0)} = f$ and $f^{(n)}(x) = (f^{(n-1)})'(x)$ if $f^{(n-1)}$ exists on some neighborhood of x with respect to E . f'', f''', f''', \dots mean $f^{(2)}, f^{(3)}, f^{(4)}, \dots$.

The n -th partial derivative on the i -th variable is written as $\partial_i^n f$. \square

It is desirable to use sequences or nets to study derivatives. For that purpose, the following lemma is useful:

Lemma 11.6. Let E be an interval in \mathbb{R} with at least two elements, or let $E = \Omega$. Let $z \in E$. Let $f : E \rightarrow V$. Let $v \in V$. The following are equivalent.

(1) We have $f'(z) = v$.

(2) For any sequence $(z_n)_{n \in \mathbb{Z}_+}$ in $E \setminus \{z\}$ converging to z , we have $\lim_{n \rightarrow \infty} \frac{f(z_n) - f(z)}{z_n - z} = v$.

(3) For any net $(z_\alpha)_{\alpha \in \mathcal{I}}$ in E converging to z , we have $\lim_{\alpha \in \mathcal{I}} \varphi(z_\alpha) = v$, where $\varphi : E \rightarrow V$ is defined by

$$\varphi(w) = \begin{cases} \frac{f(w) - f(z)}{w - z} & \text{if } w \neq z \\ v & \text{if } w = z \end{cases} \quad (11.1)$$

Proof. The equivalence of (1) \Leftrightarrow (2) is due to Def. 7.81-(3m). Also, by Def. 7.81-(1), that $f'(z) = v$ is equivalent to that the function φ in (11.1) is continuous at z . So it is equivalent (3) by Def. 7.56-(1). \square

Proposition 11.7. Let E be an interval in \mathbb{R} or $E = \Omega$. If $f : E \rightarrow V$ is differentiable at $z \in E$, then f is continuous at z .

Proof. We consider the case $f : \Omega \rightarrow V$; the other case is similar. Choose any sequence (z_n) in $\Omega \setminus \{z\}$ converging to z . By Lem. 11.6, we have $\lim_n \frac{f(z_n) - f(z)}{z_n - z} = v$. Since $\lim_n (z_n - z) = 0$, by the continuity of scalar multiplication (Prop. 3.38), we have

$$\lim_{n \rightarrow \infty} f(z_n) - f(z) = 0 \cdot v = 0$$

Thus, by Def. 7.81-(3m), we obtain $\lim_{w \neq z, w \rightarrow z} f(w) = f(z)$, which means by Def. 7.81-(1) that f is continuous at z . \square

Proposition 11.8. Let E be an interval in \mathbb{R} or $E = \Omega$, and $x \in E$. Suppose that f, g are functions $E \rightarrow V$ such that $f'(x)$ and $g'(x)$ exist. Then $(f + g)'(x)$ exists, and

$$(f + g)'(x) = f'(x) + g'(x) \quad (11.2a)$$

If λ is a function $E \rightarrow \mathbb{F}$ such that $\lambda'(x)$ exists, then $(\lambda f)'(x)$ exists and satisfies the **Leibniz rule**

$$(\lambda f)'(x) = \lambda'(x)f(x) + \lambda(x)f'(x) \quad (11.2b)$$

Assume moreover that λ does not have value 0. Then

$$\left(\frac{1}{\lambda} \cdot f\right)'(x) = \frac{-\lambda'(x)f(x) + \lambda(x)f'(x)}{\lambda(x)^2} \quad (11.2c)$$

Proof. The first formula is easy. To compute the second one, we choose any sequence (x_n) in $[a, b] \setminus \{x\}$ or $\Omega \setminus \{x\}$ converging to x . Then

$$\frac{\lambda(x_n)f(x_n) - \lambda(x)f(x)}{x_n - x} = \frac{(\lambda(x_n) - \lambda(x))}{x_n - x} \cdot f(x_n) + \lambda(x) \frac{(f(x_n) - f(x))}{x_n - x}$$

which, by Lem. 11.6 and Prop. 3.38 and the continuity of f at x (Prop. 11.7), converges to the RHS of (11.2b). This proves (11.2b), thanks to Lem. 11.6.

The third formula will follow from the second one if we can prove that $1/\lambda$ has derivative $-\frac{\lambda'(x)}{\lambda(x)^2}$ at x . This is not hard: Choose any sequence $x_n \rightarrow x$ but $x_n \neq x$. Then

$$\left(\frac{1}{\lambda(x_n)} - \frac{1}{\lambda(x)}\right) / (x_n - x) = -\frac{\lambda(x_n) - \lambda(x)}{x_n - x} \cdot \frac{1}{\lambda(x_n)\lambda(x)}$$

converges to $-\lambda'(x) \cdot \frac{1}{\lambda(x)^2}$ as $n \rightarrow \infty$. Here, we have used the continuity of λ at x and Prop. 3.38 again. \square

Example 11.9. The derivative of a constant function is 0. Thus, by Leibniz rule, if λ is a scalar, and if $f'(z)$ exists, then $(\lambda f)'(z) = \lambda \cdot f'(z)$.

Example 11.10. The identity map $f : z \in \mathbb{C} \mapsto z \in \mathbb{C}$ has derivative $\lim_{w \rightarrow z} \frac{w-z}{w-z} = 1$. Thus, by induction and Prop. 11.8, we have $(z^n)' = nz^{n-1}$ if $n \in \mathbb{Z}_+$. If $-n \in \mathbb{Z}_+$, then when $z \neq 0$ we have

$$(z^n)' = (1/z^{-n})' = -\frac{(z^{-n})'}{z^{-2n}} = -\frac{-nz^{-n-1}}{z^{-2n}} = nz^{n-1}$$

We conclude that $(z^n)' = nz^{n-1}$ whenever $n \in \mathbb{N}$, or whenever $n = -1, -2, \dots$ and $z \neq 0$. The same conclusion holds for the real variable function x^n .

Example 11.11. Let $f : z \in \mathbb{C} \mapsto \bar{z} \in \mathbb{C}$. We claim that for every $z \in \mathbb{C}$, the limit

$$f'(z) = \lim_{w \rightarrow z} \frac{\bar{w} - \bar{z}}{w - z} = \lim_{h \rightarrow 0} \bar{h}/h \quad (11.3)$$

does not exist with the help of Rem. 7.85: Take $h_n = 1/n$. Then $h_n \rightarrow 0$ and $\bar{h}_n/h_n = 1 \rightarrow 1$ as $n \rightarrow \infty$. Take $h_n = i/n$. Then $h_n \rightarrow 0$ and $\bar{h}_n/h_n = -i/i = -1 \rightarrow -1$ as $n \rightarrow \infty$. So $f'(z)$ does not exist.

Theorem 11.12 (Chain rule). Let Ω, Γ be nonempty open subsets of \mathbb{C} . Assume that $f : \Omega \rightarrow \Gamma$ is differentiable at $z \in \Omega$, and that $g : \Gamma \rightarrow V$ is differentiable at $f(z)$. Then $g \circ f$ is differentiable at z , and

$$(g \circ f)'(z) = g'(f(z)) \cdot f'(z) \quad (11.4)$$

The same conclusion holds if Ω is replaced by an interval in \mathbb{R} , or if both Ω and Γ are replaced by intervals in \mathbb{R} .

Recall Conv. 11.4 for the assumption on the field \mathbb{F} .

Proof. Define a function $A : \Gamma \rightarrow \mathbb{C}$ by

$$A(\zeta) = \begin{cases} \frac{g(\zeta) - g \circ f(z)}{\zeta - f(z)} & \text{if } \zeta \neq f(z) \\ g'(f(z)) & \text{if } \zeta = f(z) \end{cases} \quad (11.5)$$

Choose any sequence (z_n) in $\Omega \setminus \{z\}$ converging to z . Then

$$\frac{g \circ f(z_n) - g \circ f(z)}{z_n - z} = A(f(z_n)) \cdot \frac{f(z_n) - f(z)}{z_n - z}$$

By Prop. 11.7, f is continuous at z . So $\lim_n f(z_n) = f(z)$. Thus, by Lem. 11.6-(3), the above expression converges to $g'(f(z))f'(z)$ as $n \rightarrow \infty$. \square

Proposition 11.13. Let Ω, Γ be nonempty open subsets of \mathbb{C} . Let $f : \Omega \rightarrow \Gamma$ be a bijection. Let $z \in \Omega$. Suppose that $f'(z)$ exists and $f'(z) \neq 0$. Suppose also that $f^{-1} : \Gamma \rightarrow \Omega$ is continuous at $f(z)$. Then f^{-1} is differentiable at $f(z)$, and

$$(f^{-1})'(f(z)) = \frac{1}{f'(z)} \quad (11.6)$$

The same conclusion holds if Ω and Γ are replaced by intervals of \mathbb{R} .

Proof. Choose any sequence (w_n) in $\Gamma \setminus \{f(z)\}$ converging to $f(z)$. Then, as $n \rightarrow \infty$, we have $f^{-1}(w_n) \rightarrow f^{-1}(f(z)) = z$ since f^{-1} is continuous at $f(z)$, and hence

$$\frac{f^{-1}(w_n) - f^{-1}(f(z))}{w_n - f(z)} = \frac{f^{-1}(w_n) - z}{f(f^{-1}(w_n)) - f(z)} \quad (11.7)$$

converges to $1/f'(z)$ by Lem. 11.6 and the continuity of the map $\zeta \in \mathbb{C}^\times \mapsto 1/\zeta \in \mathbb{C}$. This proves $(f^{-1})'(f(z)) = 1/f'(z)$, thanks to Lem. 11.6. \square

11.2 Rolle's and Lagrange's mean value theorems (MVT)

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Assume $-\infty < a < b < +\infty$.

11.2.1 MVTs

Definition 11.14. Let $f : X \rightarrow \mathbb{R}$ where X is a topological space. We say that f has a **local maximum** (resp. **local minimum**) at $x \in X$, if there exists $U \in \text{Nbh}_X(x)$ such that $f|_U$ attains its maximum (resp. minimum) at x . The word “**local extremum**” refers to either local maximum or local minimum.

You must know that derivatives can be used to find the monotonicity of real-valued real variable functions. Here is the precise statement:

Proposition 11.15. Assume that $f : [a, b] \rightarrow \mathbb{R}$ is differentiable at $x \in [a, b]$, and $f'(x) > 0$. Then there exists $\delta > 0$ such that for any $y \in (x - \delta, x + \delta) \cap [a, b]$, we have

$$y > x \Rightarrow f(y) > f(x) \quad y < x \Rightarrow f(y) < f(x) \quad (11.8)$$

We leave it to the readers to find the analogous statement for the case $f'(x) < 0$.

Proof. Let $A = f'(x) > 0$. Then there exists $\delta > 0$ such that for all $y \in (x - \delta, x + \delta) \cap [a, b]$ not equal to x , we have $\left| \frac{f(y) - f(x)}{y - x} - A \right| < \frac{A}{2}$, and hence $\frac{f(y) - f(x)}{y - x} > \frac{A}{2}$. This proves (11.8). \square

Corollary 11.16. Assume that $f : [a, b] \rightarrow \mathbb{R}$ has a local extremum at $x \in (a, b)$. Assume that $f'(x)$ exists. Then $f'(x) = 0$.

Proof. If $f'(x)$ is a non-zero number, then either $f'(x) > 0$ or $(-f)'(x) > 0$. In either case, Prop. 11.15 indicates that f cannot have a local extremum at x . \square

From Prop. 11.15, it is clear that if $f' > 0$ on (a, b) , then f is strictly increasing. However, to prove that if $f' \geq 0$ then f is increasing, we need more preparation.

Lemma 11.17 (Rolle's MVT). Suppose that $f \in C([a, b], \mathbb{R})$ is differentiable on (a, b) . Suppose moreover that $f(a) = f(b)$. Then there exists $x \in (a, b)$ such that $f'(x) = 0$.

Proof. If f is constant then $f' = 0$. Suppose that f is not constant. Then there is $x \in (a, b)$ at which f attains its maximum (if $f(t) > f(a)$ for some $t \in (a, b)$) or minimum (if $f(t) < f(b)$ for some $t \in (a, b)$). So $f'(x) = 0$ by Cor. 11.16. \square

Example 11.18. Rolle's MVT does not hold for vector-valued functions. Especially, it does not hold for functions to $\mathbb{C} \simeq \mathbb{R}^2$. Consider $f : [0, 2\pi] \rightarrow \mathbb{C}$ defined by $f(t) = e^{it} = \cos t + i \sin t$. We assume that $\sin' = \cos$ and $\cos' = -\sin$ are proved. Then $f(0) = f(2\pi) = 1$, whereas $f'(t) = -\sin t + i \cos t$ is never zero.

Theorem 11.19 (Lagrange's MVT). Suppose that $f \in C([a, b], \mathbb{R})$ is differentiable on (a, b) . Then there is $x \in (a, b)$ such that

$$f'(x) = \frac{f(b) - f(a)}{b - a} \quad (11.9)$$

Proof. The case $f(a) = f(b)$ is just Rolle's MVT. When $f(a) \neq f(b)$, we can "shift the function f vertically" so that its two end points have the same height. Technically, we consider $g(x) = f(x) - kx$ where $k = \frac{f(b)-f(a)}{b-a}$ is the slope of the interval from $(a, f(a))$ to $(b, f(b))$. Then $g(a) = g(b)$. By Rolle's MVT, there is $x \in (a, b)$ such that $g'(x) = 0$, i.e. $f'(x) - k = 0$. \square

11.2.2 Applications of MVTs

Corollary 11.20. Assume that $f \in C([a, b], \mathbb{R})$ is differentiable on (a, b) . Then

$$f' \geq 0 \text{ on } (a, b) \quad \Longleftrightarrow \quad f \text{ is increasing on } [a, b] \quad (11.10)$$

Moreover, if $f' > 0$ on (a, b) , then f is strictly increasing on $[a, b]$.

Proof. If $f'(x) < 0$ for some $x \in (a, b)$, then Prop. 11.15 implies that x has a neighborhood on which f is not increasing. Conversely, suppose that $f'(x) \geq 0$ for all $x \in (a, b)$. Choose $x, y \in [a, b]$ satisfying $a \leq x < y \leq b$. Then by Lagrange's MVT, there is $z \in (x, y)$ such that $f(y) - f(x) = f'(z)(y - x) \geq 0$. So f is increasing on $[a, b]$. We have finished proving (11.10).

Suppose that $f' > 0$ on (a, b) . Then by Prop. 11.15, f is strictly increasing on (a, b) . If $a < x < b$, then there is $\varepsilon > 0$ such that $f(a + 1/n) \leq f(x) - \varepsilon$ for sufficiently large n . Since f is continuous at a , by taking $\lim_{n \rightarrow \infty}$ we get $f(a) \leq f(x) - \varepsilon$ and hence $f(a) < f(x)$. A similar argument proves $f(b) > f(x)$. So f is strictly increasing on $[a, b]$. \square

Corollary 11.21. Suppose that $f \in C([a, b], \mathbb{R})$ is differentiable on (a, b) , and $f'(x) \neq 0$ for all $x \in (a, b)$. Then f is strictly monotonic (i.e. strictly increasing or strictly decreasing). In particular, by Cor. 11.20, either $f' \geq 0$ on (a, b) or $f' \leq 0$ on (a, b) .

Proof. Rolle's MVT implies $f(b) - f(a) \neq 0$, and similarly, $f(y) - f(x) \neq 0$ whenever $a \leq x < y \leq b$. Therefore f is injective. The strict monotonicity of f follows from the following general fact: \square

Proposition 11.22. Let $-\infty \leq a < b \leq +\infty$, and let $f : [a, b] \rightarrow \overline{\mathbb{R}}$ be a continuous injective function. Then f is strictly monotonic.

Proof. Choose a strictly increasing homeomorphism $\varphi : [0, 1] \rightarrow [a, b]$. It suffices to prove that $g = f \circ \varphi : [0, 1] \rightarrow \overline{\mathbb{R}}$ is strictly monotonic. Assume for simplicity that $g(0) \leq g(1)$. Let us show that g is increasing. Then the injectivity implies that g is strictly increasing.

We claim that for every $x \in (0, 1)$ we have $g(0) \leq g(x) \leq g(1)$. Suppose the claim is true. Then for every $0 < x < y < 1$ we have $g(0) \leq g(y) \leq g(1)$. Applying the claim to the interval $[0, y]$ shows $g(0) \leq g(x) \leq g(y)$. So f is increasing.

Let us prove the claim. Suppose the claim is not true. Then there is $x \in (0, 1)$ such that either $g(0) \leq g(1) < g(x)$ or $g(x) < g(0) \leq g(1)$. In the first case, by intermediate value theorem (applied to $f|_{[0,x]}$), there is $p \in [0, x]$ such that $g(p) = g(1)$. So g is not injective since $p < 1$. This is impossible. Similarly, the second case is also impossible. \square

Besides monotonicity, the uniqueness of antiderivatives is another classical application of MVT.

Definition 11.23. An **antiderivative** of a function $f : E \rightarrow V$ is a differentiable function $g : E \rightarrow V$ satisfying $g' = f$ on E .

The renowned fact that any two antiderivatives g_1, g_2 of $f : [a, b] \rightarrow V$ differ by a constant is immediate from the following fact (applied to $g_1 - g_2$):

Corollary 11.24. Suppose that $f \in C([a, b], V)$ is differentiable on (a, b) and satisfies $f' = 0$ on (a, b) . Then f is a constant function.

Proof for $V = \mathbb{F}^N$. Since $\mathbb{C}^N \simeq \mathbb{R}^{2N}$, it suffices to prove the case $V = \mathbb{R}^N$. Since a sequence in \mathbb{R}^N converges to a vector iff each component of the sequence converges to the corresponding component of the vector, it suffices to prove the case $f : [a, b] \rightarrow \mathbb{R}$.

Choose any $x \in (a, b]$. By Lagrange's MVT, there exists $y \in (a, x)$ such that $0 = f'(y) = \frac{f(x) - f(a)}{x - a}$. This proves $f(x) = f(a)$ for all $x \in (a, b]$. \square

Now we discuss the general case.

Remark 11.25. When V is not necessarily finite-dimensional, the method of reducing Cor. 11.24 to the case of scalar-valued functions is quite subtle: How should we understand the “components” of an element v in the Banach space V ? In fact, in the general case, we should view

$$\langle \varphi, v \rangle \equiv \langle v, \varphi \rangle \stackrel{\text{def}}{=} \varphi(v) \quad (11.11)$$

as a component of v , where φ is an element inside the **dual (Banach) space** of V , defined by

$$V^* = \mathfrak{L}(V, \mathbb{F}) \quad (11.12)$$

An element φ in V^* is called a **bounded linear functional** on V . (In general, a **linear functional** on a vectors space W over a field \mathbb{K} is simply a linear map $W \rightarrow \mathbb{K}$.)

The vector space V^* , equipped with the operator norm, is indeed a Banach space. (This is why we call V^* the dual *Banach* space.) For the moment we do not need this fact. And we will discuss this topic in a later chapter.

Remark 11.26. In the future, we will prove that V^* separates points of V . (Recall Def. 8.44.) By linearity, this is equivalent to saying that for any $v \in V$ we have

$$v = 0 \iff \langle \varphi, v \rangle = 0 \text{ for all } \varphi \in V^* \quad (11.13)$$

In fact, in the future we will prove the famous **Hahn-Banach extension theorem**, which implies (cf. Cor. 16.6) that if $v \in V$ then

$$\exists \varphi \in V^* \setminus \{0\} \quad \text{such that} \quad \langle \varphi, v \rangle = \|\varphi\| \cdot \|v\| \quad (11.14)$$

where $\|\varphi\|$ is the operator norm of φ . (Note that, by Rem. 10.24, we have $|\langle \varphi, v \rangle| \leq \|\varphi\| \cdot \|v\|$ for all $v \in V, \varphi \in V^*$. It is nontrivial that “ \leq ” can be “ $=$ ” for some $\varphi \neq 0$.)

Proof of Cor. 11.24 assuming Hahn-Banach. Let us prove that $f(x) = f(a)$ for any $x \in [a, b]$. Since V^* separates points of V , it suffices to choose an arbitrary $\varphi \in V^*$ and prove that $\varphi \circ f(x) = \varphi \circ f(a)$. Indeed, since φ is continuous, for each sequence (x_n) in $[a, b] \setminus \{x\}$ converging to x , in view of Lem. 11.6 we have

$$\lim_{n \rightarrow \infty} \frac{\varphi \circ f(x_n) - \varphi \circ f(x)}{x_n - x} = \varphi \left(\lim_{n \rightarrow \infty} \frac{f(x_n) - f(x)}{x_n - x} \right) = \varphi(f'(x)) = \varphi(0) = 0$$

if $a < x < b$. Thus $(\varphi \circ f)' = 0$ on (a, b) . Therefore, by the finite-dimensional version of Cor. 11.24, we have that $\varphi \circ f$ is constant on $[a, b]$. \square

Hahn-Banach theorem is extremely useful for reducing a problem about vector-valued functions to one about scalar-valued functions. In this course, we will also use Hahn-Banach to prove another fun fact: every Banach space over \mathbb{F} is isomorphic to a closed linear subspace of $C(X, \mathbb{F})$ where X is a compact Hausdorff space. However, in the following section we would like to give an elementary proof of Cor. 11.24 without using Hahn-Banach.

11.3 Finite-increment theorem

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Assume $-\infty < a < b < +\infty$.

Cor. 11.24 follows immediately from the following theorem by taking $g = 0$.

Theorem 11.27. Suppose that $f \in C([a, b], V)$ and $g \in C([a, b], \mathbb{R})$ are differentiable on (a, b) . Assume that for every $x \in (a, b)$ we have $\|f'(x)\| \leq g'(x)$. Then

$$\|f(b) - f(a)\| \leq g(b) - g(a) \quad (11.15)$$

Proof. By continuity, it suffices to prove $\|f(\beta) - f(\alpha)\| \leq g(\beta) - g(\alpha)$ for all α, β satisfying $a < \alpha < \beta < b$. Therefore, by replacing $[a, b]$ by $[\alpha, \beta]$, it suffices to assume that f, g are differentiable on $[a, b]$.

Step 1. For each $\varepsilon > 0$, consider the condition on $x \in [a, b]$:

$$\|f(x) - f(a)\| \leq g(x) - g(a) + \varepsilon(x - a) \quad (11.16)$$

The set

$$E_\varepsilon = \{x \in [a, b] : x \text{ satisfies (11.16)}\}$$

is nonempty because $a \in E_\varepsilon$. One checks easily that E_ε is a closed subset of $[a, b]$: This is because, for example, E_ε is the inverse image of the closed subset $(-\infty, 0]$ of \mathbb{R} under the map

$$[a, b] \rightarrow \mathbb{R} \quad x \mapsto \|f(x) - f(a)\| - g(x) + g(a) - \varepsilon(x - a) \quad (11.17)$$

We now fix $x = \sup E_\varepsilon$. Then $x \in E_\varepsilon$ because E_ε is closed. We shall prove that $x = b$. Then the fact that $b \in E_\varepsilon$ for all $\varepsilon > 0$ proves (11.15).

Step 2. Suppose that $x \neq b$. Then $a \leq x < b$. We shall prove that there exists $y \in (x, b)$ such that

$$\|f(y) - f(x)\| \leq g(y) - g(x) + \varepsilon(y - x) \quad (11.18)$$

Add this inequality to (11.16) (which holds because $x \in E_\varepsilon$). Then by triangle inequality, we obtain $y \in E_\varepsilon$, contradicting $x = \sup E_\varepsilon$.

Let us prove the existence of such y . For each $y \in (x, b)$, define $v(y) \in V, \lambda(y) \in \mathbb{R}$ such that

$$\begin{aligned} f(y) - f(x) &= f'(x)(y - x) + v(y)(y - x) \\ g(y) - g(x) &= g'(x)(y - x) + \lambda(y)(y - x) \end{aligned}$$

The definition of $f'(x)$ and $g'(x)$ implies that $v(y) \rightarrow 0$ and $\lambda(y) \rightarrow 0$ as $y \rightarrow x$. Therefore, there exists $y \in (x, b)$ such that $\|v(y)\| < \varepsilon/2$ and $|\lambda(y)| < \varepsilon/2$. Thus

$$\begin{aligned} &\|f(y) - f(x)\| - (g(y) - g(x)) \\ &\leq (\|f'(x)\| - g'(x))(y - x) + (\|v(y)\| - \lambda(y)) \cdot (y - x) \\ &\leq 0 \cdot (y - x) + \left(\frac{\varepsilon}{2} + \frac{\varepsilon}{2}\right) \cdot (y - x) = \varepsilon(y - x) \end{aligned}$$

This proves (11.18). □

Remark 11.28. If we apply Thm. 11.27 to the special case that $f = 0$, we see that if $g \in C([a, b], \mathbb{R})$ satisfies $g' \geq 0$ on (a, b) , then g is increasing. This gives another proof of (11.10) besides the one via Lagrange's MVT.

An important special case of Thm. 11.27 is:

Corollary 11.29 (Finite-increment theorem). *Suppose that $f \in C([a, b], V)$ is differentiable on (a, b) , and that there exists $M \in \mathbb{R}_{\geq 0}$ such that $\|f'(x)\| \leq M$ for all $x \in (a, b)$. Then*

$$\|f(b) - f(a)\| \leq M|b - a| \quad (11.19)$$

Proof. Choose $g(x) = Mx$ in Thm. 11.27. □

It is fairly easy to prove finite-increment theorem for complex-variable functions.

Definition 11.30. A subset E of a real vector space is called **convex**, if for every $x, y \in E$, the interval

$$[x, y] = \{tx + (1 - t)y : t \in [0, 1]\} \quad (11.20)$$

is a subset of E .

When talking about convex subsets of \mathbb{C} , we view \mathbb{C} as \mathbb{R}^2 . Then, for example, all open disks in \mathbb{C} are convex.

Corollary 11.31 (Finite-increment theorem). *Assume $\mathbb{F} = \mathbb{C}$. Let Ω be a nonempty open convex subset of \mathbb{C} . Let $f : \Omega \rightarrow V$ be differentiable on Ω . Choose any $z_1, z_2 \in \Omega$. Suppose that there exists $M \in \mathbb{R}_{\geq 0}$ such that $\|f'(z)\| \leq M$ for all z in the interval $[z_1, z_2]$. Then*

$$\|f(z_2) - f(z_1)\| \leq M|z_2 - z_1| \quad (11.21)$$

Proof. Define $\gamma : [0, 1] \rightarrow \mathbb{C}$ by $\gamma(t) = (1 - t)z_1 + tz_2$. Then $\gamma([0, 1]) \subset \Omega$ because Ω is convex. By chain rule (Thm. 11.12), we have

$$(f \circ \gamma)'(t) = f'(\gamma(t)) \cdot \gamma'(t) = (z_2 - z_1)f'(\gamma(t))$$

whose norm is bounded by $M|z_2 - z_1|$. Applying Cor. 11.29 to $f \circ \gamma$ finishes the proof. □

Example 11.32. Let X be an interval in \mathbb{R} , or let $X = \Omega$ where Ω is convex. Let \mathcal{A} be the set of differentiable functions $f : \Omega \rightarrow V$ satisfying $\|f'\|_{l^\infty} \leq M$. Then elements of \mathcal{A} have Lipschitz constant M by Finite-increment theorems. So \mathcal{A} is equicontinuous.

11.4 Commutativity of derivatives and limits

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let Ω be a nonempty open subset of \mathbb{C} . Recall Conv. 11.4. Recall Def. 8.42 for the meaning of locally uniform convergence.

11.4.1 Main theorem

Theorem 11.33. *Let X be Ω or an interval in \mathbb{R} . Let $(f_\alpha)_{\alpha \in I}$ be a net of differentiable functions $X \rightarrow V$. Suppose that the following are true:*

- (a) *The net $(f_\alpha)_{\alpha \in I}$ converges pointwise to some $f : X \rightarrow V$.*
- (b) *The net $(f'_\alpha)_{\alpha \in I}$ converges uniformly to some $g : X \rightarrow V$.*

Then f is differentiable on X , and $f' = g$.

Proof. We prove the case $X = \Omega$. The other case is similar. Choose any $z \in \Omega$. By shrinking Ω , we assume that Ω is an open disk centered at z . We know $\lim_{w \rightarrow z} \frac{f_\alpha(w) - f_\alpha(z)}{w - z}$ converges to $f'_\alpha(z)$ for each α . Therefore, if we can show that $\frac{f_\alpha(w) - f_\alpha(z)}{w - z}$ converges uniformly (over all $w \in \Omega \setminus \{z\}$) under \lim_α , then it must converge uniformly to $\frac{f(w) - f(z)}{w - z}$ since it converges pointwise to $\frac{f(w) - f(z)}{w - z}$ by (a). Then, by Moore-Osgood Thm. 9.28, we have

$$\lim_{w \rightarrow z} \lim_\alpha \frac{f_\alpha(w) - f_\alpha(z)}{w - z} = \lim_\alpha \lim_{w \rightarrow z} \frac{f_\alpha(w) - f_\alpha(z)}{w - z} = \lim_\alpha f'_\alpha(z) = g(z)$$

finishing the proof.

To prove the uniform convergence, by the Cauchy condition on $V^{\Omega \setminus \{z\}}$ (equipped with a complete uniform convergence metric as in Exp. 7.77), it suffices to prove that

$$\sup_{w \in \Omega \setminus \{z\}} \left\| \frac{f_\alpha(w) - f_\alpha(z)}{w - z} - \frac{f_\beta(w) - f_\beta(z)}{w - z} \right\| \quad (11.22)$$

converges to 0 under $\lim_{\alpha, \beta \in I}$. Applying Cor. 11.31 to the function $f_\alpha - f_\beta$, we see

$$\begin{aligned} \|f_\alpha(w) - f_\beta(w) - f_\alpha(z) + f_\beta(z)\| &\leq |w - z| \cdot \sup_{\zeta \in [z, w]} \|f'_\alpha(\zeta) - f'_\beta(\zeta)\| \\ &\leq |w - z| \cdot \|f'_\alpha - f'_\beta\|_{l^\infty(\Omega, V)} \end{aligned} \quad (11.23)$$

Thus, we have

$$(11.22) \leq \|f'_\alpha - f'_\beta\|_{l^\infty(\Omega, V)}$$

where the RHS converges to 0 under $\lim_{\alpha, \beta}$ due to (b). This finishes the proof. \square

We didn't assume the uniform convergence of (f_α) in Thm. 11.33 because it is often redundant:

Lemma 11.34. *Assume that either X is a bounded interval in \mathbb{R} , or $X = \Omega$ where Ω is assumed to be bounded and convex. Then under the assumptions in Thm. 11.33, the net $(f_\alpha)_{\alpha \in I}$ converges uniformly to f .*

Proof. We already know that (f_α) converges pointwise to f . In fact, we shall only use the fact that $\lim_\alpha f_\alpha(z) = f(z)$ for some $z \in X$. Let z be such a point. Motivated by the proof of Thm. 11.33, let us prove the Cauchy condition that

$$\lim_{\alpha, \beta \in I} \sup_{w \in \Omega} \|f_\alpha(w) - f_\beta(w) - f_\alpha(z) + f_\beta(z)\| = 0$$

Then $(f_\alpha - f_\alpha(z))$ converges uniformly, and hence (f_α) converges uniformly. Indeed, the Cauchy condition follows easily from (11.23), in which $\sup_{w \in \Omega} |w - z|$ is a finite number because X is bounded. \square

Thus, whether or not Ω satisfies boundedness and convexity, the net (f_α) must converge locally uniformly to f . Knowing the locally uniform convergence is often enough for applications. And here is another proof of this fact:

Another proof that (f_α) converges locally uniformly to f . We consider the case $X = \Omega$; the other case is similar. For each $z \in X$, choose a convex precompact $U \in \text{Nbh}_X(x)$. (Namely, $\text{Cl}_X(U)$ is compact.) By (b) of Thm. 11.33, there is $\mu \in I$ such that $\sup_{x \in \bar{U}} \|f'_\alpha(x) - f'_\mu(x)\| \leq 1$ for all $\alpha \geq \mu$. Let $h_\alpha = f_\alpha - f_\mu$, and replace I by $I_{\geq \mu}$. By finite-increment Thm. 11.31, for each $x, y \in U$ we have

$$\|h_\alpha(x) - h_\alpha(y)\| \leq \|x - y\|$$

i.e., $(h_\alpha|_U)_{\alpha \in I}$ has uniform Lipschitz constant 1, and hence is an equicontinuous set of functions. Choose a closed ball B centered at z such that $B \subset U$. Then, since $(h_\alpha|_B)_{\alpha \in I}$ is equicontinuous and converges pointwise to $f - f_\mu$ (on B), by Cor. 9.26, $(f_\alpha - f_\mu)_{\alpha \in I}$ converges uniformly on B to $f - f_\mu$. Thus f_α converges uniformly on B to f . \square

11.4.2 An interpretation of Thm. 11.33 in terms of Banach spaces

We give a more concise way of understanding the two conditions in Thm. 11.33.

Corollary 11.35. *Let X be Ω or an interval in \mathbb{R} . Define*

$$l^{1,\infty}(X, V) = \{f \in V^X : f \text{ is differentiable on } X \text{ and } \|f\|_{l^{1,\infty}} < +\infty\}$$

where $\|\cdot\|_{l^{1,\infty}} = \|\cdot\|_{1,\infty}$ is defined by

$$\|f\|_{1,\infty} = \|f\|_{l^\infty} + \|f'\|_{l^\infty} = \sup_{x \in X} \|f(x)\| + \sup_{x \in X} \|f'(x)\|$$

Then $l^{1,\infty}(X, V)$ is a Banach space with norm $\|\cdot\|_{1,\infty}$.

Proof. It is a routine check that $\|f\|_{l^{1,\infty}}$ defines a norm on $l^{1,\infty}(X, V)$. We now prove that $l^{1,\infty}(X, V)$ is complete. Let (f_n) be a Cauchy sequence in $l^{1,\infty}(X, V)$. So (f_n) and (f'_n) are Cauchy sequences in l^∞ , converging uniformly to $f, g \in V^X$ respectively. By Lem. 11.33, f is differentiable, and $f' = g$. (In particular, $\|f'\|_\infty < +\infty$.) So $f'_n \rightrightarrows f'$. Thus

$$\|f_n - f\|_{1,\infty} = \|f_n - f\|_\infty + \|f'_n - f'\|_\infty \rightarrow 0$$

□

Remark 11.36. Thm. 11.33 and Cor. 11.35 are almost equivalent. We have proved Cor. 11.35 using Thm. 11.33. But we can also prove a slightly weaker version of Thm. 11.33 using Cor. 11.35 as follows: In the setting of Thm. 11.33, assume that each $f_\alpha : X \rightarrow V$ is differentiable, and that

$$f_\alpha \rightrightarrows f \quad f'_\alpha \rightrightarrows g \quad (11.24)$$

where $f, g \in l^\infty(X, V)$. Then Cor. 11.35 implies that f is differentiable and $f' = g$.

★ *Proof.* By (11.24), there is $\beta \in I$ such that $\|f_\alpha - f\|_\infty < +\infty$ and $\|f'_\alpha - g\| < +\infty$ for all $\alpha \geq \beta$. Thus, by replacing I with I_β , we assume that f_α and f'_α are bounded on X . So $f_\alpha \in l^{1,\infty}(X, V)$.

By (11.24), both (f_α) and (f'_α) converge in $l^\infty(X, V)$. So they are Cauchy nets under the l^∞ -norm. So (f_α) is a Cauchy net in $l^{1,\infty}(X, V)$. By Cor. 11.35, (f_α) converges to $\tilde{f} \in l^{1,\infty}(X, V)$ under the $l^{1,\infty}$ norm. In particular, $f_\alpha \rightrightarrows \tilde{f}$ and $f'_\alpha \rightrightarrows \tilde{f}'$. Since, by assumption, we have $f_\alpha \rightrightarrows f$ and $f'_\alpha \rightrightarrows g$, we therefore get $f = \tilde{f}$ and $g = \tilde{f}'$. □

It is not surprising that Thm. 11.33 can be rephrased in terms of the completeness of a normed vector space. After all, our proof of Thm. 11.33 uses Cauchy nets in an essential way. In the future, we will use the completeness of $l^{1,\infty}$ to understand the commutativity of derivatives and other limit processes.

11.5 Derivatives of power series

This section is a continuation of the previous one. We shall use Thm. 11.33 to compute derivatives of power series.

11.5.1 General result

Corollary 11.37. Assume that V is over \mathbb{C} . Let $f(z) = \sum_{n=0}^{\infty} v_n z^n$ be a power series in V . Assume that its radius of convergence is $R > 0$. Then f is differentiable on $B_{\mathbb{C}}(0, R)$ and

$$f'(z) = \sum_{n=0}^{\infty} n v_n z^{n-1}$$

Note that since $\lim_n \sqrt[n]{n} = 1$, $(\sqrt[n]{\|v_n\|})_{n \in \mathbb{Z}_+}$ and $(\sqrt[n]{n\|v_n\|})_{n \in \mathbb{Z}_+}$ have the same cluster points. Therefore

$$\limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n\|} = \limsup_{n \rightarrow \infty} \sqrt[n]{n\|v_n\|} \quad (11.25)$$

So $\sum v_n z^n$ and $\sum_{n=0}^{\infty} n v_n z^{n-1}$ have the same radius of convergence.

First proof. For each $n \in \mathbb{N}_+$, let $g_n(z) = v_0 + v_1 z + \cdots + v_n z^n$. Then by Thm. 4.27, for each $0 < r < R$, the sequences (g_n) (resp. (g'_n)) converges uniformly to f (resp. converges uniformly to $h(z) = \sum_0^{\infty} n v_n z^{n-1}$) on $B_{\mathbb{C}}(0, r)$. Therefore, by Thm. 11.33, we have $f'(z) = h(z)$ for all $z \in B_{\mathbb{C}}(0, r)$, and hence all $z \in B_{\mathbb{C}}(0, R)$ since r is arbitrary. \square

Second proof. Choose any $0 < r < R$, and let $X_r = B_{\mathbb{C}}(0, r)$. Consider $\sum v_n z^n$ as a series in the Banach space $l^{1,\infty}(X_r, \mathbb{C})$ (cf. Cor. 11.35). The norm of each term is $\|v_n\| + (n+1)\|v_{n+1}\|$. So the radius of convergence is R . Thus $\sum v_n z^n$ converges in $l^{1,\infty}(X_r, \mathbb{C})$ to some $g \in l^{1,\infty}(X_r, \mathbb{C})$. This means that, on X_r , $\sum v_n z^n$ converges uniformly to g (and hence $f = g$ on X_r) and $\sum n v_n z^{n-1}$ converges uniformly to g' . So $f'(z) = g'(z) = \sum n v_n z^{n-1}$ for all $z \in X_r$. \square

11.5.2 Examples

Example 11.38. By Cor. 11.37, the function $\exp : \mathbb{C} \rightarrow \mathbb{C}$ is differentiable, and

$$\frac{d}{dz} e^z = e^z$$

Thus, if $\gamma : [a, b] \rightarrow \mathbb{C}$ is differentiable, then by chain rule, $\exp \circ \gamma$ is differentiable on $[a, b]$, and

$$\frac{d}{dt} e^{\gamma(t)} = e^{\gamma(t)} \cdot \frac{d}{dt} \gamma(t)$$

For example:

$$(e^{\alpha t})' = \alpha e^{\alpha t} \quad (e^{t^2 + it})' = (2t + i)e^{t^2 + it}$$

Example 11.39. Define functions $\sin : \mathbb{C} \rightarrow \mathbb{C}$ and $\cos : \mathbb{C} \rightarrow \mathbb{C}$ by

$$\cos z = \frac{e^{iz} + e^{-iz}}{2} \quad \sin z = \frac{e^{iz} - e^{-iz}}{2i}$$

It follows from $e^z e^w = e^{z+w}$ that

$$\cos(z+w) = \cos z \cos w - \sin z \sin w \quad \sin(z+w) = \sin z \cos w + \cos z \sin w \quad (11.26)$$

By chain rule, we have $(e^{\alpha z})' = \alpha e^{\alpha z}$. So

$$\sin' z = \cos z \quad \cos' z = -\sin z$$

Remark 11.40. From $e^z = \sum_{n \in \mathbb{N}} z^n/n!$, it is clear that the complex conjugate of e^z is

$$\overline{e^z} = \overline{\sum_{n=0}^{\infty} \frac{z^n}{n!}} = \sum_{n=0}^{\infty} \frac{\overline{z}^n}{n!} = e^{\overline{z}}$$

Here, we have exchanged the order of conjugate and infinite sum, because the function $z \in \mathbb{C} \mapsto \overline{z}$ is continuous. Thus, if $t \in \mathbb{R}$, then

$$\overline{e^{it}} = e^{-it} \quad |e^{it}|^2 = \overline{e^{it}} e^{it} = e^{-it} e^{it} = 1$$

It follows that

$$\begin{aligned} \cos t &= \operatorname{Re}(e^{it}) & \sin t &= \operatorname{Im}(e^{it}) \\ (\cos t)^2 + (\sin t)^2 &= (\operatorname{Re}(e^{it}))^2 + (\operatorname{Im}(e^{it}))^2 = |e^{it}|^2 = 1 \end{aligned}$$

It also follows from $|e^{it}| = 1$ that if $a, b \in \mathbb{R}$ then, by $e^{a+bi} = e^a e^{bi}$, we have

$$e^{a+bi} = e^a \in \mathbb{R}_{>0}$$

Example 11.41. By Prop. 11.13, the function $\log : \mathbb{R}_{>0} \rightarrow \mathbb{R}$ is differentiable, and

$$(\log x)' = \frac{1}{x}$$

Example 11.42. We have

$$\lim_{t \rightarrow 0} \frac{\log(1+t)}{t} = (\log x)'|_{x=1} = 1$$

and hence $\lim_{x \rightarrow +\infty} x \log(1 + 1/x) = 1$ by Def. 7.81-(3) (since $\lim_{x \rightarrow +\infty} 1/x = 0$ as a net limit). Taking exponential, and using the continuity of \exp at 1, we get

$$\lim_{x \rightarrow +\infty} \left(1 + \frac{1}{x}\right)^x = e$$

Example 11.43. If $a > 0$ and $z \in \mathbb{C}$, recalling $a^z = e^{z \log a}$, we use chain rule to find

$$\frac{d}{dz} a^z = a^z \log a$$

Similarly, if $\alpha \in \mathbb{C}$ and $x > 0$, then the chain rule gives the derivative of x^α :

$$\frac{d}{dx} x^\alpha = \alpha \cdot x^{\alpha-1}$$

Example 11.44. Compute $\sum_{n=0}^{\infty} \frac{n^2}{3^n}$

Proof. The series $f(z) = \sum_{n=0}^{\infty} \frac{z^n}{3^n}$ has radius of convergence 3. When $|z| < 3$, it converges absolutely to $(1 - \frac{z}{3})^{-1} = 3(3 - z)^{-1}$. So, by Cor. 11.37, when $|z| < 3$ we have

$$\begin{aligned} \sum_{n=0}^{\infty} \frac{nz^{n-1}}{3^n} &= f'(z) = 3(3 - z)^{-2} \\ \sum_{n=0}^{\infty} \frac{n(n-1)z^{n-2}}{3^n} &= f''(z) = 6(3 - z)^{-3} \end{aligned}$$

So the value of the original series equals

$$f''(1) + f'(1) = \frac{3}{2}$$

□

11.5.3 A proof of (generalized) Leibniz rule

We end this section by giving a fun proof of Leibniz rule for higher derivatives. For simplicity, we consider only scalar-valued functions.

Proposition 11.45 (Leibniz rule). *Let X be either a nonempty interval in \mathbb{R} (resp. a nonempty open subset of \mathbb{C}). Let f, g be functions from X to \mathbb{R} (resp. to \mathbb{C}). Let $z \in X$. Suppose that $f^{(n)}(z)$ and $g^{(n)}(z)$ exist. Then*

$$(fg)^{(n)}(z) = \sum_{j=0}^n \binom{n}{j} f^{(n-j)}(z) g^{(j)}(z) \quad (11.27)$$

The above Leibniz rule is usually proved using the formula

$$\binom{n+1}{j} = \binom{n}{j-1} + \binom{n}{j} \quad (11.28)$$

where $n \in \mathbb{N}$ and $1 \leq j \leq n$. In the following, we give a proof without using this formula. We need the fact that the function

$$\mathbb{C}^n \rightarrow C(\mathbb{R}, \mathbb{C}) \quad (a_0, \dots, a_{n-1}) \mapsto p(x) = \sum_{j=0}^{n-1} a_j x^j \quad (11.29)$$

is injective: this is because $j! \cdot a_j = f^{(j)}(0)$ by Exp. 11.10.

Proof of Prop. 11.45. By induction on n and by the classical Leibniz rule (Prop. 11.8), we have

$$(fg)^{(n)}(z) = \sum_{j=0}^n C_{n,j} \cdot f^{(n-j)}(z)g^{(j)}(z) \quad (11.30)$$

where each $C_{n,j}$ is an integer independent of f and g . (In particular, $C_{n,j}$ is independent of whether the variables are real or complex.) Thus, to determine the value of $C_{n,j}$, we can use some special functions.

We consider $f(x) = e^{sx}$ and $g(x) = e^{tx}$ where $s, t \in \mathbb{R}$. Recall that we have proved that $(e^{\alpha t})' = \alpha e^{\alpha t}$ using chain rule and the derivative formula for exponentials. So (11.30) reads

$$(s+t)^n \cdot e^{(s+t)x} = \sum_{j=0}^n C_{n,j} \cdot s^{n-j} t^j \cdot e^{(s+t)x}$$

Taking $x = 0$ gives

$$(s+t)^n = \sum_{j=0}^n C_{n,j} \cdot s^{n-j} t^j \quad (11.31)$$

Comparing this with the binomial formula (4.5), and noticing the injectivity of (11.29) (first applied to (11.31) for each fixed t , where (11.31) is viewed as a polynomial of s ; then applied to each coefficient before s^{n-j} , which is a polynomial of t), we immediately get $C_{n,j} = \binom{n}{j}$. \square

11.6 Problems and supplementary material

Let Ω be nonempty open subset of \mathbb{C} . Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Assume that $\mathbb{F} = \mathbb{C}$ if we take derivatives with respect to complex variables.

Definition 11.46. Let X be either Ω or an interval in \mathbb{R} . Define

$$C^n(X, V) = \{f \in V^X : f, f', \dots, f^{(n)} \text{ exist and are continuous}\} \quad (\text{if } n \in \mathbb{N})$$

$$C^\infty(X, V) = \bigcap_{n \in \mathbb{N}} C^n(X, V)$$

If $X \subset \mathbb{R}$, elements in $C^\infty(X, V)$ are called **smooth functions**.

Problem 11.1. Let X be either Ω or an interval in \mathbb{R} . For each $n \in \mathbb{N}$, define

$$l^{n,\infty}(X, V) = \{f \in V^X : f, f', \dots, f^{(n)} \text{ exist, and } \|f\|_{n,\infty} < +\infty\}$$

where $\|f\|_{n,\infty} = \|f\|_{l^{n,\infty}}$ is defined by

$$\|f\|_{n,\infty} = \|f\|_\infty + \|f'\|_\infty + \dots + \|f^{(n)}\|_\infty$$

(In particular, we understand $l^{0,\infty}$ as l^∞ .) Clearly $\|\cdot\|_{n,\infty}$ is a norm. We have proved that $l^{n,\infty}(X, V)$ is complete when $n = 0, 1$.

1. Prove by induction on n that $l^{n,\infty}(X, V)$ is complete for every n .
2. Prove that for each $n \in \mathbb{N}$, $C^n(X, V) \cap l^{n,\infty}(X, V)$ is a closed subset of $l^{n,\infty}(X, V)$ (and hence, is a Banach space by Prop. 3.27). Prove that if X is compact then $C^n(X, V) \subset l^{n,\infty}(X, V)$.

Convention 11.47. Unless otherwise stated, when X is compact, we always choose $l^{n,\infty}$ to be the norm on $C^n(X, V)$.

12 More on derivatives

12.1 Cauchy's MVT and L'Hôpital's rule

The goal of this section is to prove L'Hôpital's rule. For that purpose, we first need to prove Cauchy's MVT.

12.1.1 Main theorems

Theorem 12.1 (Cauchy's MVT). *Let $-\infty < a < b < +\infty$. Let $f, g \in C([a, b], \mathbb{R})$ be differentiable on (a, b) . Then there exists $x \in (a, b)$ such that*

$$f'(x)(g(b) - g(a)) = g'(x)(f(b) - f(a))$$

In particular, if $g' \neq 0$ on (a, b) , then g is injective (Cor. 11.21), and we can write the above formula as

$$\frac{f'(x)}{g'(x)} = \frac{f(b) - f(a)}{g(b) - g(a)}$$

Proof. Cauchy's MVT specializes to Lagrange's MVT if we set $g(x) = x$. Moreover, in the proof of Lagrange's MVT (Thm. 11.19), we applied Rolle's MVT to the function $f(x) - kx$ where k is the slope of a line segment. Motivated by this observation, we consider the function $\psi(x) = f(x) - kg(x)$. If one wants $\psi(a) = \psi(b)$, one then solves that $k = \frac{f(b)-f(a)}{g(b)-g(a)}$. But we would rather consider $(g(b)-g(a))\psi$ in order to avoid the issue that the denominator is possibly zero. So we set

$$h(x) = (g(b) - g(a))f(x) - (f(b) - f(a))g(x)$$

Clearly $h(a) = h(b)$. By Rolle's MVT, there exists $x \in (a, b)$ such that

$$0 = h'(x) = (g(b) - g(a))f'(x) - (f(b) - f(a))g'(x)$$

□

Theorem 12.2 (L'Hôpital's rule). *Let $-\infty \leq a < b \leq +\infty$. Let $f, g \in C((a, b), \mathbb{R})$ be differentiable on (a, b) . Assume that g' is nowhere zero on (a, b) . (So g is strictly monotonic, cf. Prop. 11.22.) Assume*

$$\lim_{x \rightarrow a} \frac{f'(x)}{g'(x)} = A \quad \text{exists in } \overline{\mathbb{R}} \quad (12.1)$$

Assume that one of the following two cases are satisfied:

$$\lim_{x \rightarrow a} f(x) = \lim_{x \rightarrow a} g(x) = 0 \quad (\text{Case } \frac{0}{0})$$

$$\lim_{x \rightarrow a} |g(x)| = +\infty \quad (\text{Case } \frac{*}{\infty})$$

Then we have $\lim_{x \rightarrow a} \frac{f(x)}{g(x)} = A$. The same conclusion holds if “ $x \rightarrow a$ ” is replaced by “ $x \rightarrow b$ ”.

Remark 12.3. Since g is strictly monotonic, there is at most one $x \in (a, b)$ such that $g(x) = 0$. So $\lim_{x \rightarrow a} f(x)/g(x)$ means the limit over $x \in (a, b) \setminus g^{-1}(0)$. Alternatively, one can assign an arbitrary value to $f(x)/g(x)$ when $g(x) = 0$, and understand $\lim_{x \rightarrow a}$ as a limit over $x \in (a, b)$.

Example 12.4. Compute $\lim_{x \rightarrow +\infty} \frac{x^n}{e^x}$

Proof. By L'Hôpital's rule in the case $\frac{*}{\infty}$, we have

$$\lim_{x \rightarrow +\infty} \frac{x^n}{e^x} = \lim_{x \rightarrow +\infty} \frac{nx^{n-1}}{e^x} = \lim_{x \rightarrow +\infty} \frac{n(n-1)x^{n-2}}{e^x} = \cdots = \lim_{x \rightarrow +\infty} \frac{n!}{e^x} = 0$$

where the convergence of the limit is derived from right to left. □

12.1.2 Proof of L'Hôpital's rule

We divide the proof of L'Hôpital's rule into several steps. Also, we only treat the case $x \rightarrow a$, since the other case is similar. In the following, (a, b) means an interval, but not an element in the Cartesian product (which will be written as $a \times b$).

Step 1. We let $\frac{f(x) - f(y)}{g(x) - g(y)}$ take value $\frac{f'(x)}{g'(x)}$ if $x = y$. In this step, we prove

$$\lim_{x \times y \rightarrow a \times a} \frac{f(x) - f(y)}{g(x) - g(y)} = A \quad (12.2)$$

where $x \times y$ is defined on $(a, b)^2 = (a, b) \times (a, b)$. In view of Def. 7.81-(3m), we pick any sequence $x_n \times y_n$ in $(a, b)^2$. By Cauchy's MVT, there is $\xi_n \in [x_n, y_n]$ (if $x_n \leq y_n$) or $\xi_n \in [y_n, x_n]$ (if $x_n \geq y_n$) such that

$$f'(\xi_n)(g(x_n) - g(y_n)) = g'(\xi_n)(f(x_n) - f(y_n)).$$

So we have

$$\frac{f'(\xi_n)}{g'(\xi_n)} = \frac{f(x_n) - f(y_n)}{g(x_n) - g(y_n)}$$

Since $\lim_n x_n = \lim_n y_n = a$, we clearly have $\lim_n \xi_n = a$. Therefore, by (12.1) (this is the only place where we use (12.1)), we have

$$\lim_{n \rightarrow \infty} \frac{f(x_n) - f(y_n)}{g(x_n) - g(y_n)} = \lim_{n \rightarrow \infty} \frac{f'(\xi_n)}{g'(\xi_n)} = A$$

This proves (12.2). □

Step 2. It follows from Def. 7.81-(3) that if (x_n) and (y_k) are sequences in (a, b) converging to a , then

$$\lim_{n,k \rightarrow \infty} \frac{f(x_n) - f(y_k)}{g(x_n) - g(y_k)} = A \quad (12.3)$$

In other words, we apply Def. 7.81-(3) to the net $(x_n \times y_k)_{n \times k \in \mathbb{Z}_+^2}$ which replaces the sequence $(x_n \times y_n)_{n \in \mathbb{Z}_+}$ in Step 1. We shall use (12.3) to prove the two cases of L'Hôpital's rule.

Let us prove the case $\frac{0}{0}$. This is the easier case. Choose any sequence (x_n) in (a, b) converging to a . We want to prove that $\lim_n f(x_n)/g(x_n) = A$. So we choose any sequence (y_k) in (a, b) converging to a , and we know that the double limit (12.3) exists. Moreover, if n is fixed, then $\lim_k f(y_k) = \lim_k g(y_k) = 0$ by assumption. Thus

$$\lim_{k \rightarrow \infty} \frac{f(x_n) - f(y_k)}{g(x_n) - g(y_k)} = \frac{f(x_n)}{g(x_n)} \quad (12.4)$$

Thus, by Thm. 5.29, when $n \rightarrow \infty$, the RHS of the above equation converges to (12.3). This finishes the proof for the case $\frac{0}{0}$. \square

Step 3. Finally, we address the (more difficult) case $\frac{*}{\infty}$. Assume $\lim_{x \rightarrow a} |g(x)| = +\infty$. Again, we choose a sequence (x_n) in (a, b) converging to a . To prove $f(x_n)/g(x_n) \rightarrow A$, one may want to pick any sequence (y_k) in (a, b) , and compute the limit on the LHS of (12.4). Unfortunately, in this case, we do not know whether this limit converges or not: As one can compute, it is equal to $\lim_{k \rightarrow \infty} f(y_k)/g(y_k)$, whose convergence is part of the result we need to prove!

It is not hard to address this issue: Since $\overline{\mathbb{R}}$ is (sequentially) compact, by Thm. 3.15, it suffices to prove that any cluster point $B \in \overline{\mathbb{R}}$ of $(f(x_n)/g(x_n))_{n \in \mathbb{Z}_+}$ is equal to A . Thus, we let (y_k) be any subsequence of (x_n) such that $(f(y_k)/g(y_k))_{k \in \mathbb{Z}_+}$ converges to B . Let us prove $A = B$ using the same method as in Step 2. We compute that

$$\frac{f(x_n) - f(y_k)}{g(x_n) - g(y_k)} = \frac{g(y_k)}{g(x_n) - g(y_k)} \cdot \frac{f(x_n) - f(y_k)}{g(y_k)} \quad (12.5)$$

Since $\lim_k |g(y_k)| = +\infty$, we have $\lim_{k \rightarrow \infty} C/g(y_k) \rightarrow 0$ for any $C \in \mathbb{R}$ independent of k . Therefore, as $k \rightarrow \infty$, the first factor on the RHS of (12.5) converges to -1 , and the second factor converges to $-B$. It follows that

$$\lim_{n \rightarrow \infty} \lim_{k \rightarrow \infty} \frac{f(x_n) - f(y_k)}{g(x_n) - g(y_k)} = \lim_{n \rightarrow \infty} B = B$$

Therefore $A = B$ by Thm. 5.29. \square

The proof of L'Hôpital's rule is now complete.

Remark 12.5. The above proof can be easily translated into a language without double limits. We consider the case of $\frac{*}{\infty}$ and assume for example that $-\infty < A < +\infty$ and $a \in \mathbb{R}$, and sketch the proof as follows.

By (12.1) and Cauchy' MVT, for every $\varepsilon > 0$ there is $\delta > 0$ such that for all $a < x, y < a + \delta$ (where $x \neq y$) we have

$$A - \varepsilon \leq \frac{f(x) - f(y)}{g(x) - g(y)} \leq A + \varepsilon$$

Choose any sequence (x_n) in (a, b) converging to a . Let B be any cluster point of $(f(x_n)/g(x_n))_{n \in \mathbb{Z}_+}$ in $\overline{\mathbb{R}}$. We need to prove that $A = B$. Let $(y_k)_{k \in \mathbb{Z}_+}$ be any subsequence of (x_n) such that $\lim_k f(y_k)/g(y_k) = B$. Then there is $N \in \mathbb{N}$ such that for all $n \geq N, k \geq N$ satisfying $x_n \neq y_k$, we have

$$A - \varepsilon \leq \frac{f(x_n) - f(y_k)}{g(x_n) - g(y_k)} \leq A + \varepsilon$$

For each $n \geq N$, apply $\lim_{k \rightarrow \infty}$ to the above inequality, and notice $\lim_k |g(y_k)| = +\infty$. Then we get $A - \varepsilon \leq B \leq A + \varepsilon$, finishing the proof. \square

12.2 Trigonometric functions and π

In this section, we prove that \sin , \cos , and π satisfy the properties we learned in high schools. Some of them have already been proved in Subsec. 11.5.2. We leave the proof of the basic properties of the other trigonometric functions to the reader.

Let x be a real variable. Recall that $\sin, \cos : \mathbb{R} \rightarrow \mathbb{R}$ are determined by the fact that $e^{ix} = \cos x + i \sin x$. In particular, that $|e^{ix}| = 1$ implies $(\cos x)^2 + (\sin x)^2 = 1$. We have proved that

$$\sin' = \cos \quad \cos' = -\sin$$

Since $e^{i \cdot 0} = 1$, we have

$$(\sin x)'|_{x=0} = \cos 0 = 1 \quad (\cos x)'|_{x=0} = -\sin 0 = 0$$

In particular, since $\sin' = \cos$ is strictly positive on a neighborhood of 0, by Cor. 11.20, \sin is strictly increasing on that neighborhood.

We shall define $\frac{\pi}{2}$ to be the smallest positive zero \cos . However, we must first prove the existence of this number:

Lemma 12.6. *There exists $x \geq 0$ such that $\cos x = 0$.*

Proof. Suppose this is not true. Then by $\cos 0 = 1$ and intermediate value theorem, we have $\cos x > 0$ for all $x \geq 0$. In other words, $\sin' > 0$ on $\mathbb{R}_{\geq 0}$. Thus, by Cor.

11.20, \sin is strictly increasing on $\mathbb{R}_{\geq 0}$. Therefore $A = \lim_{x \rightarrow +\infty} \sin x$ exists in $\overline{\mathbb{R}}$. Since $\sin 0 = 0$, we must have $A \in \overline{\mathbb{R}}_{>0}$. By L'Hôpital's rule in case $\frac{*}{\infty}$, we have

$$\lim_{x \rightarrow +\infty} \frac{\cos x}{x} = \lim_{x \rightarrow +\infty} -\sin x = -A < 0$$

contradicting the fact that $\cos x > 0$ if $x \geq 0$. □

Definition 12.7. We define the number π to be

$$\pi = 2 \cdot \inf (\mathbb{R}_{\geq 0} \cap \cos^{-1}(0)) = 2 \cdot \inf \{x \in \mathbb{R}_{\geq 0} : \cos x = 0\}$$

Note that $(\mathbb{R}_{\geq 0} \cap \cos^{-1}(0))$ is a closed subset of \mathbb{R} . So its infimum belongs to this set. Therefore, $\frac{\pi}{2}$ is the smallest $x \geq 0$ satisfying $\cos(x/2) = 0$.

Proposition 12.8. *We have*

$$\sin 0 = 0 \quad \sin \frac{\pi}{2} = 1 \quad \cos 0 = 1 \quad \cos \frac{\pi}{2} = 0 \quad (12.6)$$

On $(0, \pi/2)$, \sin and \cos are strictly positive. On $[0, \pi/2]$, \sin is strictly increasing, and \cos is strictly decreasing.

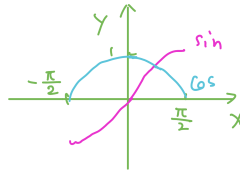
Proof. All the formulas in (12.6), except $\sin(\pi/2) = 1$, has been proved. Since $(\sin \frac{\pi}{2})^2 = 1 - (\cos \frac{\pi}{2})^2$, we have $\sin \frac{\pi}{2} = \pm 1$.

By the definition of π , we know that $\sin' = \cos$ is > 0 on $[0, \frac{\pi}{2})$. So \sin is strictly increasing on $[0, \frac{\pi}{2}]$. Thus, $\sin 0 = 0$ implies that $\sin > 0$ on $(0, \frac{\pi}{2}]$. In particular, $\sin \frac{\pi}{2} = 1$. Since $\cos' = -\sin$ is < 0 on $(0, \frac{\pi}{2})$, \cos is strictly decreasing on $[0, \frac{\pi}{2}]$. □

Proposition 12.9. *We have $\sin(-x) = -\sin x$ and $\cos(-x) = \cos x$.*

Proof. Immediate from $e^{-ix} = 1/e^{ix}$ and the definitions of \sin and \cos . □

From what we have proved, we know that the graph of \sin and \cos on $[-\frac{\pi}{2}, \frac{\pi}{2}]$ looks as follows.



Proposition 12.10. *We have*

$$\sin x = \cos(x - \frac{\pi}{2}) = \cos(\frac{\pi}{2} - x) \quad \cos(x) = \sin(\frac{\pi}{2} - x)$$

Proof. Immediate from (11.26) and (12.6). □

Thus, the graph of \sin is the rightward translation of that of \cos by $\frac{\pi}{2}$. Therefore, the graph of \sin on $[-\frac{\pi}{2}, 0]$ is translated to the graph of \cos on $[-\pi, -\frac{\pi}{2}]$. That $\cos(x) = \cos(-x)$ gives us the graph of \cos on $[\frac{\pi}{2}, \pi]$. Thus, we know the graph of \cos on $[-\pi, \pi]$.

Theorem 12.11 (Euler's formula). *We have $e^{i\pi} = -1$, and hence $e^{2i\pi} = e^{i\pi}e^{i\pi} = 1$.*

Proof. We have $e^{i\pi/2} = \cos(\frac{\pi}{2}) + i\sin(\frac{\pi}{2}) = i$. Hence $e^{i\pi} = i^2 = -1$. □

Proposition 12.12. *We have $\sin x = \sin(x + 2\pi)$ and $\cos x = \cos(x + 2\pi)$*

Proof. Immediate from (11.26) and that $1 = e^{2i\pi} = \cos(2\pi) + i\sin(2\pi)$. □

Thus, \cos and \sin have period 2π . This completes the graphs of $\cos x$ and $\sin x = \cos(x - \frac{\pi}{2})$ on \mathbb{R} .

The fact that 2π is the length of the unit circle will be proved in Exp. 13.39.

12.3 Taylor's theorems

Assume throughout this section that $-\infty < a < b < +\infty$ and V is a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

In this section, we generalize MVTs and finite-increment theorem to higher derivatives. These generalizations are all under the name "Taylor theorem". Recall Def. 11.46 and Pb. 11.1 for the meaning of $l^{n,\infty}, C^n, C^\infty$. We first discuss the generalization of finite-increment theorem, which can be applied to vector-valued functions.

12.3.1 Taylor's theorems for vector-valued functions

Definition 12.13. Let X be a normed vector space. Let $A \subset X$. Let $a \in \text{Cl}_X(A) \setminus A$ (or more generally, assume $a \in \text{Cl}_X(A \setminus \{a\})$). Let $f : A \rightarrow V$. Let $r \in \mathbb{R}_{\geq 0}$.

- We write $f(x) = o(\|x - a\|^r)$ if $\lim_{x \rightarrow a} \frac{f(x)}{\|x - a\|^r} = 0$.
- We write $f(x) = O(\|x - a\|^r)$ if $\limsup_{x \rightarrow a} \frac{\|f(x)\|}{\|x - a\|^r} < +\infty$ where \limsup is the limit superior of a net (cf. Rem. 7.83 and Pb. 8.2). In other words, there exists $U \in \text{Nbh}_X(a)$ such that $\sup_{x \in A \cap U} \|f(x)\|/\|x - a\|^r < +\infty$.

When $r = 0$, we simply write $o(1)$ and $O(1)$. The two symbols o, O are called **Landau symbols**.

In this section, we will frequently use the formula

$$S_n(x) = \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x - a)^k \quad (12.7)$$

whenever the RHS makes sense.

Theorem 12.14 (Taylor's theorem, Peano form). Let $f : [a, b] \rightarrow V$ and $n \in \mathbb{Z}_+$. Assume that $f', f'', \dots, f^{(n)}$ exist at a (resp. at b). Then for each $x \in (a, b)$ we have

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x-a)^k + o((x-a)^n) \quad (12.8a)$$

resp.

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(b)}{k!} (x-b)^k + o((b-x)^n) \quad (12.8b)$$

Expressions of the form (12.8a) are called **Taylor expansions** of f with **center** a .

Remark 12.15. In order for $f^{(n)}(a)$ to exist, it is assumed that $f^{(n-1)}$ exists on a neighborhood of a .

Proof of Peano-form. Since the two cases are similar, we only treat the case at a . Define **remainder** $g(x) = f(x) - S_n(x)$. Then

$$g(a) = g'(a) = \dots = g^{(n)}(a) = 0 \quad (12.9)$$

It suffices to prove Taylor's theorem for g , i.e.

$$g(x) = o((x-a)^n) \quad (12.10)$$

We prove this by induction. The case $n = 1$ is obvious from the definition of derivatives, which says

$$\frac{g(x) - g(a)}{x-a} - g'(a) = o(1) \quad (12.11)$$

and hence $g(x) = (x-a)o(1) = o(x-a)$.

Now assume $n \geq 2$. Assume that Peano form has been proved for case $n-1$. Applying this result to g' . We then get $g'(x) = o((x-a)^{n-1})$. Since $g''(a)$ exists, g' exists on $[a, c]$ where $a < c < b$. In particular, g is continuous on $[a, c]$. Therefore, by finite-increment Thm. 11.29, if $x \in (a, c)$, then

$$\|g(x)\| \leq (x-a) \cdot \sup_{a < t < x} \|g'(t)\|$$

If we can prove $\sup_{a \leq t \leq x} \|g'(t)\| = o((x-a)^{n-1})$, then we immediately have $g(x) = o((x-a)^n)$. Thus, the proof of Peano form is finished by the next lemma. \square

Lemma 12.16. Assume that $f : [a, b] \rightarrow V$ satisfies $f(x) = o((x-a)^r)$. Define

$$\tilde{f}(x) = \sup_{a < t < x} \|f(t)\|$$

Then $\tilde{f}(x) = o((x-a)^r)$.

Proof. Choose any $\varepsilon > 0$. Since $f(x) = o((x - a)^r)$, we know that there is $c \in (a, b)$ such that for all $a < x < c$ we have $\|f(x)\| \leq \varepsilon|x - a|^r$. Thus

$$|\tilde{f}(x)| \leq \sup_{a < t < x} \varepsilon|t - a|^r = \varepsilon|x - a|^r$$

□

Among all the versions of Taylor's theorem discussed in this section, the following one is most useful. (Another useful version, the integral form of Taylor's theorem, will be proved in Thm. 13.32.) Note that if we assume $f \in C^{(n+1)}([a, b], V)$ in Thm. 12.14, then Thm. 12.17 immediately implies Thm. 12.14.

Theorem 12.17 (Higher order finite-increment theorem). *Let $n \in \mathbb{N}$ and $f \in C^n([a, b], V)$. Assume that $f^{(n+1)}$ exists everywhere on (a, b) . Then, for every $x \in (a, b]$ resp. $x \in [a, b)$, we have respectively*

$$\left\| f(x) - \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x - a)^k \right\| \leq \frac{(x - a)^{n+1}}{(n + 1)!} \cdot \sup_{a < t < x} \|f^{(n+1)}(t)\| \quad (12.12a)$$

$$\left\| f(x) - \sum_{k=0}^n \frac{f^{(k)}(b)}{k!} (x - b)^k \right\| \leq \frac{(b - x)^{n+1}}{(n + 1)!} \cdot \sup_{x < t < b} \|f^{(n+1)}(t)\| \quad (12.12b)$$

Proof. We only prove the first formula: applying the first formula to $\tilde{f}(x) = f(-x)$ implies the second one. We prove (12.12a) by induction on n . Moreover, we shall prove (12.12a) for the case $x = b$. The general case follows by restricting f to $[a, x]$. When $n = 0$, (12.12a) is the content of (classical) finite-increment Thm. 11.29. Assume case $n - 1$ has been proved ($n \in \mathbb{Z}_+$). In case n , take $g(x) = f(x) - S_n(x)$. Then (12.9) is true. Let

$$M = \sup_{a < t < b} \|f^{(n+1)}(t)\| = \sup_{a < t < b} \|g^{(n+1)}(t)\|$$

By case $n - 1$, for each $a \leq x \leq b$ we have

$$\|g'(x)\| \leq \frac{(x - a)^n}{n!} \cdot M = h'(x) \quad \text{where } h(x) = \frac{M(x - a)^{n+1}}{(n + 1)!}$$

Thus, by Thm. 11.27, we have

$$\|g(b) - g(a)\| \leq h(b) - h(a) = \frac{M(b - a)^{n+1}}{(n + 1)!}$$

This proves (12.12a) for g , and hence for f . □

12.3.2 Taylor's theorem for real-valued functions

Theorem 12.18 (Taylor's theorem, Lagrange form). Let $n \in \mathbb{N}$ and $f \in C^n([a, b], \mathbb{R})$. Assume that $f^{(n+1)}$ exists everywhere on (a, b) . Then for every $x \in (a, b]$ resp. $x \in [a, b)$, there exists $\xi \in (a, x)$ resp. $\eta \in (x, b)$ such that, respectively,

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x-a)^k + \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1} \quad (12.13a)$$

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(b)}{k!} (x-b)^k + \frac{f^{(n+1)}(\eta)}{(n+1)!} (x-b)^{n+1} \quad (12.13b)$$

Proof. We only prove (12.13a). Applying (12.13a) to $\tilde{f}(x) = f(-x)$ (defined on $[-b, -a]$) implies the second formula. Again, it suffices to prove (12.13a) for $g(x) = f(x) - S_n(x)$, which satisfies (12.9). Thus, we want to find $\xi \in (a, x)$ satisfying

$$g(x) = \frac{g^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1}$$

This can be proved by applying Cauchy's MVT repeatedly:

$$\begin{aligned} & \frac{g(x)}{(x-a)^{n+1}} \stackrel{\exists x_1 \in (a, x)}{=} \frac{g'(x_1)}{(n+1)(x_1-a)^n} \stackrel{\exists x_2 \in (a, x_1)}{=} \frac{g''(x_2)}{(n+1)n(x_2-a)^{n-1}} \\ & = \dots \stackrel{\exists x_n \in (a, x_{n-1})}{=} \frac{g^{(n)}(x_n)}{(n+1)!(x_n-a)} \stackrel{\exists \xi \in (a, x_n)}{=} \frac{g^{(n+1)}(\xi)}{(n+1)!} \end{aligned}$$

□

We will mainly use Thm. 12.17 instead of the Lagrange form, since the latter does not apply directly to vector valued functions. However, Thm. 12.17 can be derived from the Lagrange form and Hahn-Banach theorem. We have used the fact that V^* separates points of V to prove that a function $[a, b] \rightarrow V$ is constant if its derivative exists and is constantly zero. (See Cor. 11.24.) However, to prove Thm. 12.17, we need the stronger fact that for every $v \in V$ there exists a nonzero $\varphi \in V^*$ such that $\langle \varphi, v \rangle = \|\varphi\| \cdot \|v\|$. (See Rem. 11.26.) By scaling φ , we can assume that $\|\varphi\| = 1$ and $\langle \varphi, v \rangle = \|v\|$.

We now give the second proof of Thm. 12.17:

Proof of Thm. 12.17 using Lagrange form and Hahn-Banach. The Lagrange form clearly implies Thm. 12.17 in the special case that $V = \mathbb{R}$. Now consider the general case, and view V as a real Banach space if it was originally over \mathbb{C} . Take $g(x) = f(x) - S_n(x)$. We need to prove $\|g(x)\| \leq \frac{(x-a)^{n+1}}{(n+1)!} M$ where $M = \sup_{a < t < x} \|g^{(n+1)}(t)\|$.

By Hahn-Banach (Rem. 11.26), there exists $\varphi \in V^*$ with $\|\varphi\| = 1$ such that $\varphi \circ g(x) = \|g(x)\|$. Applying the one dimensional special case to $\varphi \circ g$, we have

$$\|g(x)\| = \varphi \circ g(x) \leq \frac{(x-a)^{n+1}}{(n+1)!} \cdot \sup_{a < t < x} |(\varphi \circ g)^{(n+1)}(t)| \quad (12.14)$$

provided that $\varphi \circ g \in C^n([a, b], V)$ and that $(\varphi \circ g)^{(n+1)}$ exists on (a, b) .

By the continuity of φ , we have

$$(\varphi \circ g)'(t) = \lim_{s \rightarrow t} \frac{\varphi \circ g(s) - \varphi \circ g(t)}{s - t} = \varphi \left(\lim_{s \rightarrow t} \frac{g(s) - g(t)}{s - t} \right) = \varphi(g'(t)) \quad (12.15)$$

Applying this formula repeatedly, we see that $\varphi \circ g \in C^n([a, b], V)$, that $(\varphi \circ g)^{(n+1)}$ exists on (a, b) , and that $(\varphi \circ g)^{(n+1)} = \varphi \circ g^{(n+1)}$. By Rem. 10.24, we have

$$\sup_{a < t < x} |(\varphi \circ g)^{(n+1)}(t)| = \sup_{a < t < x} |\langle \varphi, g^{(n+1)}(t) \rangle| \leq \sup_{a < t < x} \|g^{(n+1)}(t)\| = M$$

Combining this result with (12.14) finishes the proof. \square

When V is \mathbb{R}^N equipped with the Euclidean norm, the Hahn-Banach theorem (in the form of Rem. 11.26) is very easy: Define the linear map $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ sending each $v \in \mathbb{R}^N$ to its dot product with $g(x)/\|g(x)\|$. Then φ satisfies $\|\varphi\| = 1$ and $\varphi \circ g(x) = \|g(x)\|$. So there is nothing mysterious in the above proof. (You are encouraged to compare this proof with the one of [Rud-P, Thm. 5.19].)

12.4 Functions approximated by their Taylor series

Taylor's theorems do not imply that a smooth function f on an interval of \mathbb{R} can be approximated by its **Taylor series** (with **center** a):

$$\sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x-a)^k \quad (12.16)$$

The following is a typical example:

Example 12.19. Define $f : \mathbb{R} \rightarrow \mathbb{R}$ by

$$f(x) = \begin{cases} \exp\left(-\frac{1}{x^2}\right) & (\text{if } x > 0) \\ 0 & (\text{if } x \leq 0) \end{cases}$$

Then $f^{(n)}(0) = 0$ for all $n \in \mathbb{N}$. So the Taylor series of f at 0 is 0, which cannot approximate $f(x)$ when $x > 0$.

On the contrary, if f is defined on an open subset of \mathbb{C} , and if f' exists everywhere on its domain, then $f^{(n)}$ exists for all n , and f can be approximated locally uniformly by its Taylor series. This is a deep result in complex analysis. In fact, a thorough understanding of power series is impossible without the help of complex analysis.

In the following, we show that some important real variable functions can be approximated by their Taylor series. Actually, the proof can be simplified by complex analysis, since these examples are the restriction of some differentiable complex variable functions (aka **holomorphic functions**) to the real line.

Example 12.20. Consider the Taylor expansion of $\log : \mathbb{R}_{>0} \rightarrow \mathbb{R}$ at $x = 1$. By induction on $n \in \mathbb{Z}_+$, one computes that

$$\log^{(n)}(x) = (-1)^{n-1} \frac{(n-1)!}{x^n}$$

Therefore, its Taylor expansion in order n is

$$\sum_{k=1}^n \frac{(-1)^{k-1}}{k} (x-1)^k + R_{n+1}(x)$$

where $R_{n+1}(x)$ is the remainder. To show that $\log x$ is approximated uniformly (on certain domain) by its Taylor series, one need to show that R_{n+1} converges uniformly to 0 on that domain.

We would like to prove that for every $0 < r < 1$ we have $R_{n+1} \rightrightarrows 0$ on $[1-r, 1+r]$. This would imply that series on the RHS of the following formula (whose radius of convergence is 1) converges uniformly to f on $[1-r, 1+r]$:

$$\log(x) = \sum_{k=1}^n \frac{(-1)^{k-1}}{k} (x-1)^k \tag{12.17}$$

However, using the Taylor's theorems proved in the previous section, one can prove the uniform convergence only when $0 < r \leq 1/2$. The general case of $0 < r < 1$ should be proved by another method. \square

Proof for the case $0 < r \leq \frac{1}{2}$. In fact, we shall prove the uniform convergence on $[1-r, 2]$. By Thm. 12.17, for all $x \in [1-r, 1+r]$ we have

$$|R_{n+1}(x)| \leq \frac{|x-1|^{n+1}}{(n+1)!} \cdot \sup_{\substack{1 \leq t \leq x \\ \text{or } x \leq t \leq 1}} |\log^{(n+1)}(t)| = \frac{|x-1|^{n+1}}{n+1} \cdot \sup_{\substack{1 \leq t \leq x \\ \text{or } x \leq t \leq 1}} \frac{1}{t^{n+1}}$$

where the sup is over $1 \leq t \leq x$ or $x \leq t \leq 1$, depending on whether $1 \leq x \leq 1+r$ or $1-r \leq x \leq 1$.

If $1 \leq x \leq 1 + r$, then $1 \leq t \leq x$ implies $1/t^{n+1} \leq 1$. So

$$|R_{n+1}(x)| \leq \frac{(x-1)^{n+1}}{n+1} \leq \frac{r^{n+1}}{n+1}$$

where the RHS converges to 0 as $n \rightarrow \infty$ whenever $0 < r \leq 1$. In particular, we get the renowned formula

$$\log 2 = \sum_{n=1}^{\infty} \frac{(-1)^{n-1}}{n} \quad (12.18)$$

If $1 - r \leq x \leq 1$, then $x \leq t \leq 1$ implies $1/t^{n+1} \leq 1/x^{n+1}$. Thus

$$|R_{n+1}(x)| \leq \frac{1}{n+1} \left(\frac{1}{x} - 1 \right)^{n+1} \leq \frac{1}{n+1} \left(\frac{1}{1-r} - 1 \right)^{n+1} = \frac{1}{n+1} \left(\frac{r}{1-r} \right)^{n+1}$$

If $0 < r \leq 1/2$, then $0 < r/(1-r) \leq 1$, and hence the RHS above converges to 0 as $n \rightarrow \infty$. This proves that $R_{n+1} \Rightarrow 0$ on $[1-r, 1+r]$ when $0 < r \leq 1/2$. \square

Proof for the case $0 < r < 1$. Assume $0 < r < 1$. For the convenience of discussion, we prove instead that

$$\sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k} x^k \quad (12.19)$$

the Taylor series of $\log(1+x)$ at 0, converges uniformly to $\log(1+x)$ on $[-r, r]$

The radius of convergence of the series (12.19) is 1. Thus, by Thm. 4.27, (12.19) converges locally uniformly on $(-1, 1)$ to some function $f : (-1, 1) \rightarrow \mathbb{R}$. By Cor. 11.37, f is differentiable on $(-1, 1)$, and the series

$$\sum_{k=0}^{\infty} (-1)^k x^k \quad (12.20)$$

converges locally uniformly on $(-1, 1)$ to f' . But we clearly have

$$(12.20) = \frac{1}{1 - (-x)} = \frac{1}{1+x} \quad (12.21)$$

Thus $f'(x) = \frac{d}{dx}(\log(1+x))$. Now, (12.19) clearly implies that $f(0) = 0 = \log(1+0)$. Therefore, by Cor. 11.24, we obtain $f(x) = \log(1+x)$ on $(-1, 1)$. In other words, (12.19) converges locally uniformly on $(-1, 1)$ (and hence uniformly on $[-r, r]$) to $\log(1+x)$. \square

Example 12.21. Let $\alpha \in \mathbb{C}$. Then

$$\sum_{k=0}^{\infty} \binom{\alpha}{k} x^k \quad (12.22)$$

the Taylor series of $(1+x)^\alpha = \exp(\alpha \log(1+x))$ at $x = 0$, converges locally uniformly on $(-1, 1)$ to $(1+x)^\alpha$.

Proof. Using Prop. 4.23, one easily checks that the radius of convergence of (12.22) is 1. So Thm. 4.27 implies that (12.22) converges locally uniformly on $(-1, 1)$ to some $f : (-1, 1) \rightarrow \mathbb{C}$. Let

$$g(x) = (1 + x)^\alpha$$

Our goal is to prove $f = g$.

It is clear that $(1 + x)g'(x) = \alpha g(x)$. By Cor. 11.37, the series

$$\sum_{k=0}^{\infty} k \binom{\alpha}{k} x^{k-1} = \sum_{k=0}^{\infty} (k+1) \binom{\alpha}{k+1} x^k \quad (12.23)$$

converges locally uniformly on $(-1, 1)$ to f' . Thus, by Cor. 5.60, we have

$$\begin{aligned} (1+x)f'(x) &= \sum_{k=0}^{\infty} \left(k \binom{\alpha}{k} + (k+1) \binom{\alpha}{k+1} \right) x^k \\ &= \sum_{k=0}^{\infty} \alpha \binom{\alpha}{k} x^k = \alpha f(x) \end{aligned}$$

Therefore, f satisfies the same differential equation as g , namely $(1+x)f' = \alpha f$. Moreover, we clearly have $f(0) = 1 = g(0)$. So we have $f = g$ on $(-1, 1)$ if we apply the next lemma to $f - g$. \square

Lemma 12.22. *Let I be an interval of \mathbb{R} (with at least two points) such that $0 \in I$. Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let $\varphi \in C(I, \mathbb{F}^{n \times n})$. Assume that $f \in C^1(I, \mathbb{F}^n)$ satisfies*

$$f'(x) = \varphi(x) \cdot f(x) \quad f(0) = 0 \quad (12.24)$$

Then for all $x \in I$ we have $f(x) = 0$.

Proof. We prove this lemma for the case that I is an open interval. The proof for the other types of intervals is similar. Also, we equip $\mathbb{F}^{n \times n}$ with the operator norm by viewing $n \times n$ matrices as elements of $\mathfrak{L}(\mathbb{F}^n)$. (Recall that the operator norm is equivalent to the Euclidean norm, see Thm. 10.30.) Let

$$\Omega = \{x \in I : f(x) = 0\} = f^{-1}(0)$$

which is a closed subset of I (since the inverse image under a continuous map of a closed set is closed). Clearly Ω is nonempty since $0 \in \Omega$. If we can prove that Ω is open, then we have $\Omega = I$ because I is connected. This will finish the proof.

So let us prove that any $p \in \Omega$ is an interior point of Ω with respect to I . Choose $r > 0$ such that $[p - r, p + r] \subset I$. Let

$$C = \sup_{-r \leq x \leq r} \|\varphi(x)\|$$

which is a finite number by extreme value theorem. Let $\delta = \min\{\frac{1}{2C}, r\}$ which is > 0 . It suffices to prove that

$$M = \sup_{x \in [p-\delta, p+\delta]} \|f(x)\|$$

is zero. (Note that $M < +\infty$ again by EVT.) Then we will have $[p - \delta, p + \delta] \subset \Omega$, finishing the proof.

For each $x \in [p - \delta, p + \delta]$, by Rem. 10.24 for operator norms, we have

$$\|f'(x)\| = \|\varphi(x)f(x)\| \leq \|\varphi(x)\| \cdot \|f(x)\| \leq CM$$

Thus, by finite-increment theorem, we have for all $x \in [p - \delta, p + \delta]$ that

$$\|f(x)\| = \|f(x) - f(p)\| \leq CM|x - p| \leq CM\delta \leq \frac{M}{2}$$

Applying $\sup_{x \in [p-\delta, p+\delta]}$ to $\|f(x)\|$, we get $M \leq M/2$. So $M = 0$. □

Remark 12.23. The above Lemma can also be proved in a similar way as Thm. 11.27: Let $x \in I$. Assume WLOG that $x > 0$. Let $E = f^{-1}(0) \cap [0, x]$, which is a closed subset of $[0, x]$. So $t = \sup E$ is in $[0, x]$. To show $f(x) = 0$, one just need to prove $t = x$. If not, then $t < x$. Then, as in the above proof, one can find $\delta > 0$ such that $\varphi(s) = 0$ whenever $s \in [t, t + \delta]$, impossible.

12.5 Convex functions

In this section, we fix an interval $I \subset \mathbb{R}$ containing at least two points.

Definition 12.24. Let $\mathbf{x} = (x_1, x_2)$, $\mathbf{y} = (y_1, y_2)$, $\mathbf{z} = (z_1, z_2)$ be three points of \mathbb{R}^2 satisfying $x_1 < y_1 < z_1$. We say that the ordered triple $(\mathbf{x}, \mathbf{y}, \mathbf{z})$ is a **convex triple** if the following equivalent conditions are satisfied:

- (1) \mathbf{y} is below or on the interval $[\mathbf{x}, \mathbf{z}]$. In other words, we have $y_2 \leq tx_2 + (1-t)z_2$ if $t \in [0, 1]$ is such that $y_1 = tx_1 + (1-t)z_1$.
- (2) We have $\frac{y_2 - x_2}{y_1 - x_1} \leq \frac{z_2 - y_2}{z_1 - y_1}$.
- (3) We have $\frac{y_2 - x_2}{y_1 - x_1} \leq \frac{z_2 - x_2}{z_1 - x_1}$.
- (4) We have $\frac{z_2 - x_2}{z_1 - x_1} \leq \frac{z_2 - y_2}{z_1 - y_1}$.

Proof of equivalence. The equivalence of these statements is clear from the picture, and is not hard to check rigorously using inequalities. We leave the details to the reader. □

Recall the definition of convex subsets in real vector spaces (Def. 11.30).

Definition 12.25. A function $f : I \rightarrow \mathbb{R}$ is called **convex** if the following equivalent conditions are true:

(1) The set

$$D_f = \{(x, y) \in \mathbb{R}^2 : x \in I, y \geq f(x)\} \quad (12.25)$$

is a convex subset of \mathbb{R}^2 .

(1) For any three points $x < y < z$ of I , the points $(x, f(x)), (y, f(y)), (z, f(z))$ form a convex triple.

Proof of equivalence. Again, the equivalence is clear from the picture. The details are left to the readers. \square

The convexity of differentiable functions is easy to characterize:

Theorem 12.26. Let $f : I \rightarrow \mathbb{R}$ be differentiable. Then f is convex iff f' is increasing. In particular, if f'' exists on I , then f is convex iff $f'' \geq 0$ on I .

Proof. Assume that f' is increasing. Choose $x < y < z$ in I . By Lagrange's MVT, there exist $\xi \in (x, y)$ and $\eta \in (y, z)$ such that the slope of the interval $[(x, f(x)), (y, f(y))]$ equals $f'(\xi)$, and that the slope of $[(y, f(y)), (z, f(z))]$ equals $f'(\eta)$. Since $f'(\xi) \leq f'(\eta)$, the points $(x, f(x)), (y, f(y)), (z, f(z))$ form a convex triple. This proves that f is convex.

Now assume that f is convex. Choose any $x < y$ in I . We need to prove that $f'(x) \leq f'(y)$. Choose any $\varepsilon > 0$. Then there exist x_1 and y_1 such that $x < x_1 < y_1 < y$, that $f'(x) - \varepsilon$ is \leq the slope k_1 of $[(x, f(x)), (x_1, f(x_1))]$, and that $f'(y) + \varepsilon$ is \geq the slope k_2 of $[(y_1, f(y_1)), (y, f(y))]$. Since f is convex, k_1 is \leq the slope k' of $[(x_1, f(x_1)), (y_1, f(y_1))]$, and $k' \leq k_2$. Therefore $k_1 \leq k_2$. Thus $f'(x) - \varepsilon \leq f'(y) + \varepsilon$. Since $\varepsilon > 0$ is arbitrary, we get $f'(x) \leq f'(y)$.

When f'' exists, the equivalence between $f'' \geq 0$ and the increasing monotonicity of f' is due to Cor. 11.20. \square

The most important general property about convex functions is:

Theorem 12.27 (Jensen's inequality). Let $f : I \rightarrow \mathbb{R}$ be a convex function. Let $n \in \mathbb{Z}_+$ and $x_1, \dots, x_n \in I$. Choose $t_1, \dots, t_n \in [0, 1]$ such that $t_1 + \dots + t_n = 1$. Then

$$f(t_1x_1 + \dots + t_nx_n) \leq t_1f(x_1) + \dots + t_nf(x_n) \quad (12.26)$$

Proof. The points $(x_1, f(x_1)), \dots, (x_n, f(x_n))$ are in $D_f = (12.25)$. Therefore, by Lem. 12.28, the point

$$t_1(x_1, f(x_1)) + \dots + t_n(x_n, f(x_n)) = (t_1x_1 + \dots + t_nx_n, t_1f(x_1) + \dots + t_nf(x_n))$$

is in the convex set D_f . \square

Lemma 12.28. Let V be a real vector space. Let E be a convex subset of V . Let $n \in \mathbb{Z}_+$ and $p_1, \dots, p_n \in E$. Any **convex combination** of p_1, \dots, p_n (i.e., any point of the form $t_1 p_1 + \dots + t_n p_n$ where $t_1, \dots, t_n \in [0, 1]$ and $t_1 + \dots + t_n = 1$) is inside E .

The geometric meaning of this lemma is clear: If $V = \mathbb{R}^2$ (which is the main case we are interested in), then $t_1 p_1 + \dots + t_n p_n$ stands for an arbitrary point inside the polygon with vertices p_1, \dots, p_n . So this point is clearly inside E .

Proof. We prove by induction on n . The case $n = 1$ is obvious. Suppose case $n - 1$ has been proved $n \geq 2$. Consider case n . It is trivial when $t_1 + \dots + t_{n-1} = 0$. So let us assume $t_1 + \dots + t_{n-1} > 0$. By case $n - 1$, the point $q = \lambda_1 p_1 + \dots + \lambda_{n-1} p_{n-1}$ is in E where

$$\lambda_i = \frac{t_i}{t_1 + \dots + t_{n-1}}$$

Since E is convex, the point $(t_1 + \dots + t_{n-1})q + t_n p_n$ (which equals $t_1 p_1 + \dots + t_n p_n$) is in E . \square

Example 12.29. Since $(-\log x)'' = x^{-2}$ is positive on $\mathbb{R}_{>0}$, by Thm. 12.26, $-\log$ is a convex function on $\mathbb{R}_{>0}$. Therefore, if $0 < \lambda_1, \dots, \lambda_n \leq 1$ and $\lambda_1 + \dots + \lambda_n = 1$, then by Jensen's inequality, for each $x_1, \dots, x_n > 0$ we have $-\log(\sum_i \lambda_i x_i) \leq -\sum_i \lambda_i \log x_i$. Taking exponentials, we get

$$x_1^{\lambda_1} \dots x_n^{\lambda_n} \leq \lambda_1 x_1 + \dots + \lambda_n x_n$$

for all $x_1, \dots, x_n > 0$, and hence for all $x_1, \dots, x_n \geq 0$. In particular, we get the **inequality of arithmetic and geometric means**

$$(x_1 \dots x_n)^{\frac{1}{n}} \leq \frac{x_1 + \dots + x_n}{n} \quad (12.27)$$

and the **Young's inequality**

$$x^{\frac{1}{p}} y^{\frac{1}{q}} \leq \frac{x}{p} + \frac{y}{q} \quad (12.28)$$

if $p, q > 1$ and $\frac{1}{p} + \frac{1}{q} = 1$.

Definition 12.30. Let $p \in [1, +\infty]$. We say that $q \in [1, +\infty]$ is the **Hölder conjugate** of p if $\frac{1}{p} + \frac{1}{q} = 1$.

12.6 Hölder's and Minkowski's inequalities; l^p spaces

In this section, we use Young's inequality to prove two inequalities that are of vital importance to the development of modern analysis:

Theorem 12.31. Let $x_1, \dots, x_n, y_1, \dots, y_n \in \mathbb{R}_{\geq 0}$. Let $p, q \in (1, +\infty)$ satisfy $\frac{1}{p} + \frac{1}{q} = 1$. Then the following inequalities (called respectively **Hölder's inequality** and **Minkowski's inequality**) are true:

$$x_1 y_1 + \dots + x_n y_n \leq \sqrt[p]{x_1^p + \dots + x_n^p} \cdot \sqrt[q]{y_1^q + \dots + y_n^q} \quad (12.29a)$$

$$\sqrt[p]{(x_1 + y_1)^p + \dots + (x_n + y_n)^p} \leq \sqrt[p]{x_1^p + \dots + x_n^p} + \sqrt[p]{y_1^p + \dots + y_n^p} \quad (12.29b)$$

In the special case that $p = q = 2$, Hölder's inequality is called **Cauchy-Schwarz inequality**

★ *Proof.* Assume WLOG that $x_i > 0$ and $y_j > 0$ for some i, j . Young's inequality implies that for each i ,

$$\frac{x_i}{\sqrt[p]{\sum_k x_k^p}} \cdot \frac{y_i}{\sqrt[q]{\sum_k y_k^q}} \leq \frac{x_i^p}{p \sum_k x_k^p} + \frac{y_i^q}{q \sum_k y_k^q}$$

Taking sum over i gives

$$\sum_i \frac{x_i}{\sqrt[p]{\sum_k x_k^p}} \cdot \frac{y_i}{\sqrt[q]{\sum_k y_k^q}} \leq \frac{1}{p} + \frac{1}{q} = 1$$

This proves Hölder's inequality.

Notice that $pq = p + q$. Let $z_i = x_i + y_i$. By Hölder's inequality, we have

$$x_1 z_1^{p-1} + \dots + x_n z_n^{p-1} \leq \left(\sum_k x_k^p \right)^{\frac{1}{p}} \cdot \left(\sum_k z_k^{(p-1)q} \right)^{\frac{1}{q}} = \left(\sum_k x_k^p \right)^{\frac{1}{p}} \cdot \left(\sum_k z_k^p \right)^{\frac{1}{q}}$$

and similarly

$$y_1 z_1^{p-1} + \dots + y_n z_n^{p-1} \leq \left(\sum_k y_k^p \right)^{\frac{1}{p}} \cdot \left(\sum_k z_k^p \right)^{\frac{1}{q}}$$

Adding up these two inequalities, we get

$$\sum_k z_k^p \leq \left(\left(\sum_k x_k^p \right)^{\frac{1}{p}} + \left(\sum_k y_k^p \right)^{\frac{1}{p}} \right) \cdot \left(\sum_k z_k^p \right)^{\frac{1}{q}}$$

Dividing both sides by $\left(\sum_k z_k^p \right)^{\frac{1}{q}}$ proves Minkowski's inequality. □

Minkowski's inequality is often used in the following way:

Theorem 12.32. Let X be a set, and let V be a normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let $1 \leq p < +\infty$. For each $f \in V^X$, define the **ℓ^p -norm**

$$\|f\|_p \equiv \|f\|_{\ell^p} = \left(\sum_{x \in X} \|f(x)\|^p \right)^{\frac{1}{p}} \quad (12.30)$$

Then for each $f, g \in V^X$ and $\lambda \in \mathbb{F}$ we have

$$\|f + g\|_p \leq \|f\|_p + \|g\|_p \quad \|\lambda f\|_p = |\lambda| \cdot \|f\|_p \quad (12.31)$$

In particular, $\|\cdot\|_p$ is a norm on the l^p -space

$$l^p(X, V) = \{f \in V^X : \|f\|_p < +\infty\} \quad (12.32)$$

If V is Banach space, then so is $l^p(X, V)$.

Recall $0 \cdot (\pm\infty) = 0$.

Proof. Choose any $A \in \text{fin}(2^X)$. By Minkowski's and triangle inequality, we have

$$\begin{aligned} \sum_A |f + g|^p &\leq \sum_A (|f| + |g|)^p \leq \left(\left(\sum_A |f|^p \right)^{\frac{1}{p}} + \left(\sum_B |f|^p \right)^{\frac{1}{p}} \right)^p \\ &\leq \left(\left(\sum_X |f|^p \right)^{\frac{1}{p}} + \left(\sum_X |f|^p \right)^{\frac{1}{p}} \right)^p = (\|f\|_p + \|g\|_p)^p \end{aligned}$$

Taking $\lim_{A \in \text{fin}(2^X)}$ gives $\|f + g\|_p^p \leq (\|f\|_p + \|g\|_p)^p$, proving the first inequality of (12.31). The second of (12.31) clearly holds by taking $\lim_{A \in \text{fin}(2^X)}$ of

$$\sum_A |\lambda f|^p = |\lambda|^p \sum_A |f|^p$$

and noting that the multiplication map $t \in \overline{\mathbb{R}}_{\geq 0} \mapsto |\lambda|t \in \overline{\mathbb{R}}_{\geq 0}$ is continuous.

Suppose that V is complete. Let (f_n) be a Cauchy sequence in $l^p(X, V)$. Then for each $x \in X$, $(f_n(x))$ is a Cauchy sequence in V , converging to some element $f(x) \in V$. By Cauchyness, for each $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that for all $n, k \geq N$ we have $\|f_n - f_k\|_p \leq \varepsilon$, and hence

$$\sum_{x \in A} \|f_n(x) - f_k(x)\|^p \leq \varepsilon^p$$

for all $A \in \text{fin}(2^X)$. Taking \lim_k gives $\sum_A |f_n - f|^p \leq \varepsilon^p$. Taking $\lim_{A \in \text{fin}(2^X)}$ gives $\|f_n - f\|_p \leq \varepsilon$ for all $n \geq N$. (In particular, $\|f\|_p \leq \|f_N\|_p + \varepsilon < +\infty$, and hence $f \in l^p(X, V)$.) This proves that (f_n) converges to f under the l^p -norm. So $l^p(X, V)$ is complete. \square

Theorem 12.33. Let X be a set. Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let $p, q \in [1, +\infty]$ such that $\frac{1}{p} + \frac{1}{q} = 1$. Then there is a linear isometry

$$\Psi : l^p(X, \mathbb{F}) \rightarrow l^q(X, \mathbb{F})^* \quad f \mapsto \Psi(f) \quad (12.33a)$$

where for each $g \in l^q(X, \mathbb{F})$, the value of $\Psi(f)$ at g is

$$\langle \Psi(f), g \rangle = \sum_{x \in X} f(x)g(x) \quad (12.33b)$$

where the RHS converges.

In fact, we will see in Thm. 17.30 that if $q < +\infty$ (and hence $p > 1$), Ψ is surjective, and hence is an isomorphism of normed vector spaces. (This is not a difficult fact. So you can prove it yourself.)

Proof. We treat the case $1 < p, q < +\infty$, and leave the case that $p \in \{1, +\infty\}$ to the readers. Assume $f \in l^p$ and $g \in l^q$, then for each $A \in \text{fin}(2^X)$ we have by Hölder's inequality that

$$\left\| \sum_A fg \right\| \leq \sum_A |fg| \leq \left(\sum_A |f|^p \right)^{\frac{1}{p}} \left(\sum_A |g|^q \right)^{\frac{1}{q}} \leq \|f\|_p \cdot \|g\|_q$$

Applying $\lim_{A \in \text{fin}(2^X)}$ to the second term above implies that $\sum_X |fg| < +\infty$. So $\sum_X fg$ converges absolutely, and hence converges. So (12.33b) makes sense, and hence Ψ is a well-defined linear map. Applying $\lim_{A \in \text{fin}(2^X)}$ to the first term above implies that

$$|\langle \Psi(f), g \rangle| \leq \|f\|_p \cdot \|g\|_q$$

Thus, by Rem. 10.24, we obtain $\|\Psi(f)\| \leq \|f\|_p$.

To show $\|\Psi(f)\| = \|f\|_p$, assume WLOG that $f \neq 0$, and define $g : X \rightarrow \mathbb{R}$ to be $g = \frac{\bar{f}}{|f|} \cdot |f|^{p-1}$, where $g(x)$ is understood as 0 if $f(x) = 0$. Then

$$\langle \Psi(f), g \rangle = \sum_X |f|^p = \|f\|_p^p$$

and $\|g\|_q^q = \sum_X |f|^{pq-q} = \sum_X |f|^p = \|f\|_p^p$. So

$$\|f\|_p \cdot \|g\|_q = \|f\|_p^{1+p/q} = \|f\|_p^p = \langle \Psi(f), g \rangle$$

This proves $\|\Psi(f)\| = \|f\|_p$ by Rem. 10.24. So Ψ is a linear isometry. \square

I do not want to deviate too much from the main purpose of this section, which is to show some important applications of convex functions. I will therefore stop my discussion about l^p spaces, and continue this topic in the future. The crucial role of l^p spaces and their continuous versions (namely L^p spaces) in modern analysis is a long story. The study of these objects constitutes a major part of the second half of this course. Let me mention just one point: the compactness of $\bar{B}_{l^2(\mathbb{Z}, \mathbb{C})}(0, 1)$ under the pointwise convergence topology (by viewing it as a subspace of $\mathbb{C}^{\mathbb{Z}}$) was the most important reason for Hilbert and Schmidt to study the Hilbert space $l^2(\mathbb{Z}, \mathbb{C})$, and it was the crucial property that allowed them to fully solve the eigenvalue problem in integral equations (cf. Subsec. 10.4.1).

12.7 Problems and supplementary material

Let $-\infty < a < b < +\infty$. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 12.1. Let f be the function in Exp. 12.19. Prove that $f^{(n)}(0) = 0$ for all $n \in \mathbb{N}$.

Problem 12.2. Let $n \in \mathbb{N}$. Let $f : [a, b] \rightarrow V$ such that $f, f', \dots, f^{(n)}$ exist everywhere on $[a, b]$. Use the higher order finite-increment theorem to prove that

$$\left\| f(x) - \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x-a)^k \right\| \leq \frac{(x-a)^n}{n!} \cdot \sup_{a < t < x} \|f^{(n)}(t) - f^{(n)}(a)\| \quad (12.34)$$

Remark 12.34. Setting $n = 1$ and dividing both sides by $x - a$, we obtain an especially useful formula for any differentiable $f : [a, b] \rightarrow V$ as follows.

$$\left\| \frac{f(x) - f(a)}{x - a} - f'(a) \right\| \leq \sup_{a < t < x} \|f'(t) - f'(a)\| \quad (12.35)$$

Problem 12.3. Use Thm. 11.33 to prove the following theorem. (Formula (12.35) might be helpful.)

Theorem 12.35. Let $I = [a, b]$ and $J = [c, d]$ be intervals in \mathbb{R} with at least two points. Let $f : I \times J \rightarrow V$ be a function such that $\partial_1 f, \partial_2 f, \partial_2 \partial_1 f$ exist on $I \times J$, and that $\partial_2 \partial_1 f$ is continuous. Then $\partial_1 \partial_2 f$ exists on $I \times J$ and equals $\partial_2 \partial_1 f$.

★ **Problem 12.4.** Prove that, for $x \in (-1, 1]$,

$$\arctan x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k+1}}{2k+1} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots, \quad (12.36)$$

and hence (**Leibniz formula**)

$$\frac{\pi}{4} = \sum_{k=0}^{\infty} \frac{(-1)^k}{2k+1} = 1 - \frac{1}{3} + \frac{1}{5} - \frac{1}{7} + \dots$$

Hint. Use the method in the second proof of Exp. 12.20 to prove (12.36) for $x \in (-1, 1)$. To prove (12.36) for $x = 1$, show that the series on the RHS of (12.36) converges uniformly on $[0, 1]$ to a continuous function using Dirichlet's test for uniform convergence (Thm. 4.29). \square

★ **Problem 12.5.** Let $n \in \mathbb{N}$. Find the radius of convergence of

$$f(z) = \sum_{k=n}^{\infty} \binom{k}{n} z^k \quad (12.37)$$

Find the explicit formula of $f(z)$.

Problem 12.6. Prove the following higher order finite-increment theorem for complex variables. (For simplicity, it suffices prove the case that $z_0 = 0$.)

Theorem 12.36 (Higher order finite-increment theorem). Let V be a Banach space over \mathbb{C} . Let $R > 0$ and $z_0 \in \mathbb{C}$. Let $f : \Omega \rightarrow V$ where

$$\Omega = B_{\mathbb{C}}(z_0, R) = \{z \in \mathbb{C} : |z - z_0| < R\}$$

Assume that $f', f'', \dots, f^{(n+1)}$ exist everywhere on Ω . Then for every $z \in \Omega$ we have

$$\left\| f(z) - \sum_{k=0}^n \frac{f^{(k)}(z_0)}{k!} (z - z_0)^k \right\| \leq \frac{|z - z_0|^{n+1}}{(n+1)!} \cdot \sup_{\xi \in [z_0, z]} \|f^{(n+1)}(\xi)\| \quad (12.38)$$

where $[z_0, z] = \{tz + (1-t)z_0 : 0 \leq t \leq 1\}$.

★ **Problem 12.7.** Let V be a Banach space over \mathbb{C} . Assume that the power series $f(z) = \sum_{k=0}^{\infty} v_k z^k$ (where $v_k \in V$) has radius of convergence $R > 0$. Choose any $z_0 \in B_{\mathbb{C}}(0, R)$. Prove that there exists a neighborhood $\Omega \in \text{Nbh}_{\mathbb{C}}(z_0)$ contained inside $B_{\mathbb{C}}(0, R)$, such that the Taylor series of f at z_0 converges uniformly on Ω to f . Namely, prove that the series $g(z)$ converges locally uniformly to f on Ω where

$$g(z) = \sum_{k=0}^{\infty} \frac{f^{(k)}(z_0)}{k!} (z - z_0)^k \quad (12.39)$$

Hint. Use Thm. 12.36. Pb. 12.5 might also be helpful. □

★ **Problem 12.8.** Let W be a real vector space. Let A be a nonempty subset of W . Define the **convex hull** of A to be the set of all convex combinations (recall Lem. 12.28) of elements of A , i.e.

$$\text{Cvh}(A) = \left\{ \text{convex combinations of } v_1, \dots, v_n : n \in \mathbb{Z}_+ \text{ and } v_1, \dots, v_n \in A \right\} \quad (12.40)$$

Prove that $\text{Cvh}(A)$ is the smallest convex set containing A . In other words, prove that $\text{Cvh}(A)$ is a convex set containing A , and that $\text{Cvh}(A) \subset B$ if B is a convex subset of W containing A .

Problem 12.9. Prove Thm. 12.33 for the case $p = 1$ and $p = +\infty$.

13 Riemann integrals

13.1 Introduction: the origin of integral theory in Fourier series

13.1.1 Antiderivatives VS. approximation by areas of rectangles

Modern people can easily appreciate the importance of giving a rigorous definition to the integral $\int_a^b f(x)dx$ where f is a general (say, continuous) function. And you may already know that this integral is defined by taking the limit of Riemann sums, which are “areas of some rectangles”. This idea sounds so natural to you, because you know that by the time Calculus was invented, people knew very well that $\int_a^b f$ means the area of the region between the graph of f and the x -axis, and that this area can be approximated by the areas of some rectangles or triangles. So why did Riemann integral not appear until 19th century, more than a hundred years after Newton’s and Leibniz’s invention of calculus? And why was the inadequacy of defining integrals by means of antiderivatives not recognized until 19th century?

Beyond the superficial reason that 19th century is the century in which people began to pay attention to the foundations of calculus, there is a deeper reason: the study of **partial differential equations (PDE)** and the introduction of **Fourier series** caused a drastic change in the general view of what functions are. This change of view motivated people to search for a general definition of integrals, in particular one that does not use antiderivatives.

Before the systematic study of PDEs (i.e., before 19th century), functions only mean analytic functions, which means that they can be approximated by their Taylor series. But if f is such a function, then $f(x) = \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!}(x-a)^n$. So the values of f are all determined by $f(a), f'(a), f''(a), \dots$, and hence are determined by $f|_I$ where I is an arbitrary nonempty open interval. (Technically, such functions are called **(real) analytic functions**.) Therefore, periodic functions (except trigonometric functions) were not accepted, because they are not determined by their values on a small interval. (A function with expression $f(x) = x$ on $[0, 1]$ should also have the same expression on \mathbb{R} . So it must not be the periodic function $f(x) = x - n$ where $x \in (n, n+1]$.) The function Exp. 12.19 was not accepted, because it was not determined by $f(0), f'(0), f''(0), \dots$.

Therefore, in these old days, people did not worry about the rigorous definition of integrals, because they can simply define integrals using antiderivatives instead of using the areas of rectangles to approximate the integrals, which is practically less convenient than finding the antiderivatives. In particular, one understood

$$\int_a^b \sum a_n(x-c)^n dx \stackrel{\text{def}}{=} F(b) - F(a) \quad \text{where} \quad F(x) = \sum \frac{a_n}{n+1}(x-c)^{n+1}$$

13.1.2 PDEs and periodic functions

The wonderful dream was shattered when people started working on PDEs. The simplest such example is **wave equation**

$$\partial_x^2 f(x, t) - \partial_t^2 f(x, t) = 0 \quad (13.1)$$

This equation describes the vibration of a string: at time t , the shape of the string is the graph of the function $x \in [a, b] \mapsto f(x, t) \in \mathbb{R}$. (Here, we assume that the two end points of the string are $(a, 0)$ and $(b, 0)$.)

D'Alembert solved the wave equation in the following way. Using the trick

$$\partial_x^2 - \partial_t^2 = 4\partial_u \partial_v \quad \text{where} \quad u = x + t, v = x - t$$

it is not hard to find the general solution of the wave equation:

$$f(x, t) = \frac{1}{2}(g(x+t) + g(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} h(s) ds \quad (13.2)$$

where $g(x) = f(x, 0)$ and $h(x) = \partial_t f(x, 0)$. In particular, if we assume that $h = 0$ (i.e., at time $t = 0$ the string is held in place and does not vibrate), then the solution is

$$f(x, t) = \frac{1}{2}(g(x+t) + g(x-t)) \quad (13.3)$$

Here comes the trouble. If we assume that the two end points of the string are always pinned at $(0, 0)$ and $(1, 0)$ respectively, then we have $f(0, t) = f(1, t) = 0$ for all $t \in \mathbb{R}$. Translating this condition to g , we get $g(t) = -g(-t) = -g(2-t)$ and hence g is a function with period 2, totally unacceptable! Worse still, the derivatives of periodic functions might have points of discontinuities.

13.1.3 Fourier series

The next important progress was made by Fourier in the study of **heat equation**

$$\partial_t f(x, t) - \partial_x^2 f(x, t) = 0 \quad (13.4)$$

where x is defined on a closed interval (say $[-\pi, \pi]$) representing a thin rod, $f(x, t)$ is the temperature of the point x of this rod at time t . Fourier solved the problem by **separation of variables**: He first assumed $f(x, t) = u(x)v(t)$. Then the heat equation implies $u''(x)v(t) = u(x)v'(t)$, and hence

$$\frac{u''(x)}{u(x)} = \frac{v'(t)}{v(t)} \quad (13.5)$$

The LHS is independent of t , and the RHS is independent of x . So (13.5) should be a constant $-\lambda$. The solution is then $u(x) = e^{i\sqrt{\lambda}x}$ and $v(t) = e^{-\lambda t}$. If one assumes that the temperature at the two end points $-\pi, \pi$ are equal, then $\sqrt{\lambda}$ must be an integer $n \in \mathbb{Z}$. So $f(x, t) = e^{inx-n^2t}$. Taking infinite linear combinations, Fourier found the general solution

$$f(x, t) = \sum_{n=-\infty}^{+\infty} a_n e^{inx-n^2t} \quad (13.6)$$

The initial temperature $g(x) = f(x, 0)$ is a **Fourier series**

$$g(x) = \sum_{n=-\infty}^{+\infty} a_n e^{inx} \quad (13.7)$$

and, in particular, a function with period 2π (since each e^{inx} is so).

In order to use (13.6) to determine the solution $f(x, t)$ when the initial condition $f(x, t) = g(x)$ is given, one must first find the values of these **Fourier coefficients** a_n in terms of g . In fact, since

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} e^{ikx} \cdot e^{-inx} dx = \delta_{k,n} \quad (13.8)$$

(recall (0.2)), it is not hard to guess the formula

$$a_n = \frac{1}{2\pi} \int_{-\pi}^{\pi} g(x) e^{-inx} dx$$

(13.9)

since this formula is true when $g(x) = e^{ikx}$.

13.1.4 From Riemann integrals to Lebesgue integrals

Here comes the question that is closely related to integral theory: What is the meaning of the integral (13.9) if g is no longer a real analytic function?

To be more precise, in 19th century there was a long debate about what are (good) functions, and what functions have **Fourier expansions**, i.e., expansions of the form (13.7). Fourier himself believed that all “functions” can be approximated by trigonometric functions (equivalently, functions of the form e^{inx}). But Lagrange did not, partly due to his (and many people’s) insistence that functions must be real analytic (cf. [Kli, Sec. 28.2]). The doubt on whether many functions have Fourier expansions is quite understandable. From the modern perspective, we know that many Lebesgue measurable functions are not approximated by their Fourier series pointwise or uniformly, but are approximated under some

other norms (e.g. the L^2 -norm $\|f\|_{L^2} = \sqrt{\int_{-\pi}^{\pi} |f|^2}$). Indeed, there are many continuous functions $[-\pi, \pi] \rightarrow \mathbb{R}$ whose Fourier series diverge on a dense subset of $[-\pi, \pi]$ (cf. [Rud-R, Thm. 5.12]). Therefore, Fourier's pioneering view that all "reasonable" functions can be approximated by Fourier series is incorrect unless we define what "approximation" means in a new and appropriate way.

In order to understand which functions have Fourier series expansions (in whatever sense), the first step is to understand for which function g the integral (13.9) makes sense. Therefore, the history of extending the class of integrable functions from continuous functions to Riemann integrable functions and finally to Lebesgue integrable functions is also part of the history of understanding which functions can have Fourier expansions and which functions are "reasonable".

The goal of this chapter is to learn Riemann integrals. The construction of Riemann integrals is much easier than Lebesgue theory. But compared to the latter, Riemann integrals have some serious drawbacks.

For example, suppose that a sequence of functions (f_n) on $[-\pi, \pi]$ converges to f in some sense. It is natural to ask whether the Fourier coefficients of (f_n) converge to those of f . (A typical example is $f_n(x) = \sum_{k=-n}^n a_k e^{ikx}$. Then this question asks whether the n -th Fourier coefficient of the series $\sum_{k=-\infty}^{+\infty} a_k e^{ikx}$ is a_n .) In view of (13.9), this problem is reduced to the problem of showing $\int f = \lim_n \int f_n$. If (f_n) is a sequence of Riemann integrable functions converging uniformly to f , then f is Riemann integrable, and $\int f = \lim \int f_n$. (See Cor. 13.21.) However, if (f_n) only converges pointwise to f , then f is not necessarily Riemann integrable. Even if f is Riemann integrable, one does not have a useful criterion for $\int f = \lim \int f_n$ in the framework of Riemann integrals.

But uniform convergence often does not hold in application, and especially in Fourier theory and PDEs. For example, let f be the function on \mathbb{R} with period 2π defined by $f(x) = x$ if $-\pi < x < \pi$ and $f(\pi) = 0$. Then the Fourier series

$$\sum_{n=1}^{\infty} (-1)^{n-1} \frac{2}{n} \sin(nx) \quad (13.10)$$

converges pointwise to f . (See also Pb. 4.3.) It does not converge uniformly to f , because the uniform limit of a sequence of continuous functions is continuous, but f is not continuous.

Lebesgue's integral theory will provide a more satisfying answer to the above problem. We will learn it in the second semester.

13.2 Riemann integrability and oscillation

In this section, we fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and let $I = [a, b]$ where $-\infty < a < b < +\infty$. We understand $|I|$ as $b - a$.

13.2.1 Riemann integrals

Definition 13.1. A **partition** of the interval $I = [a, b]$ is defined to be an element of the form

$$\sigma = \{a_0, a_1, \dots, a_n \in I : a_0 = a < a_1 < a_2 < \dots < a_n = b, n \in \mathbb{Z}_+\} \quad (13.11)$$

Equivalently, this partition can be written as

$$I = I_1 \cup I_2 \cup \dots \cup I_n \quad I_j = [a_{j-1}, a_j] \quad (13.12)$$

If $\sigma, \sigma' \in \text{fin}(2^I)$ are partitions of I , we say that σ' is a **refinement** of σ (or that σ' is **finer than** σ), if $\sigma \subset \sigma'$. In this case, we also write

$$\sigma < \sigma'$$

We define $\mathcal{P}(I)$ or simply \mathcal{P} to be

$$\mathcal{P}(I) = \{\text{partitions of } I\}$$

Remark 13.2. If $\sigma, \sigma' \in \mathcal{P}(I)$, then clearly $\sigma \cup \sigma' \in \mathcal{P}(I)$ and $\sigma, \sigma' < \sigma \cup \sigma'$. Therefore, $<$ is a partial order on $\mathcal{P}(I)$. We call $\sigma \cup \sigma'$ the **common refinement** of σ and σ' .

Definition 13.3. A **tagged partition** of I is an ordered pair

$$(\sigma, \xi_\bullet) = (\{a_0 = a < a_1 < \dots < a_n = b\}, (\xi_1, \dots, \xi_n))$$

where $\sigma \in \mathcal{P}(I)$ and $\xi_j \in I_j = [a_{j-1}, a_j]$ for all $1 \leq j \leq n$. The set

$$\mathcal{Q}(I) = \{\text{tagged partitions of } I\}$$

equipped with the preorder $<$ defined by

$$(\sigma, \xi_\bullet) < (\sigma', \xi'_\bullet) \iff \sigma \subset \sigma' \quad (13.13)$$

is a directed set.

Definition 13.4. Let $f : I \rightarrow V$. For each $(\sigma, \xi_\bullet) \in \mathcal{Q}(I)$, define the **Riemann sum**

$$S(f, \sigma, \xi_\bullet) = \sum_{j \geq 1} f(\xi_j)(a_j - a_{j-1})$$

The **Riemann integral** is defined to be the limit of the net $(S(f, \sigma, \xi_\bullet))_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)}$:

$$\int_a^b f \equiv \int_a^b f(x)dx = \lim_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)} S(f, \sigma, \xi_\bullet)$$

When the RHS exists, we say that f is **Riemann integrable** on I . We let

$$\mathcal{R}(I, V) = \{\text{Riemann integrable } f \in V^I\}$$

Convention 13.5. There are several equivalent ways to write the integrals:

$$\int_a^b f = - \int_b^a f = \int_{[a,b]} f$$

if $a < b$. Also, if $a = b$, the above terms are understood to be 0, and all functions on $[a, b]$ are considered Riemann integrable.

Remark 13.6. It is clear that $\int_a^b f = v \in V$ iff for every $\varepsilon > 0$ there exists $\sigma_0 \in \mathcal{P}(I)$ such that for any partition $\sigma = \{a_0 < \cdots < a_n\}$ finer than σ_0 , and for any $\xi_j \in [a_{j-1}, a_j]$ (for all $1 \leq j \leq n$) we have

$$\left\| v - \sum_{j \geq 1} f(\xi_j)(a_j - a_{j-1}) \right\| < \varepsilon$$

There is not need to tag σ_0 .

13.2.2 Riemann integrability and strong Riemann integrability

In this subsection, we give a useful criterion for Riemann integrability.

Definition 13.7. Let A be a nonempty subset of a metric space Y . The **diameter** of A is defined to be

$$\text{diam}(A) = \sup_{x, y \in A} d(x, y)$$

If $f : X \rightarrow Y$ is a map where X is a set, and if $E \subset X$, the **oscillation** of f on E is defined to be $\text{diam} f(E)$.

The following lemma allows us to control the difference of Riemann sums by means of the oscillation.

Lemma 13.8. Let $f : I = [a, b] \rightarrow V$ and $M = \text{diam}(f(I))$. Then for each $(\sigma, \xi_\bullet), (\sigma', \xi'_\bullet) \in \mathcal{Q}(I)$ we have

$$\|S(f, \sigma, \xi_\bullet) - S(f, \sigma', \xi'_\bullet)\| \leq M(b - a) \quad (13.14)$$

Proof. Write $\sigma \cup \sigma' = \{a_0 = a < a_1 < \cdots < a_n = b\}$. Then there exist $\gamma_1, \dots, \gamma_n \in \{\xi_1, \xi_2, \dots\}$ such that

$$S(f, \sigma, \xi_\bullet) = \sum_{i=1}^n f(\gamma_i)(a_i - a_{i-1})$$

(Here is how to choose γ_i : Let k be the unique number such that the k -th subinterval of σ contains $[a_{i-1}, a_i]$. Then let $\gamma_i = \xi_k$.) Similarly, there exist $\gamma'_1, \dots, \gamma'_n \in \{\xi'_1, \xi'_2, \dots\}$ such that

$$S(f, \sigma', \xi'_\bullet) = \sum_{i=1}^n f(\gamma'_i)(a_i - a_{i-1})$$

Then

$$\begin{aligned} \|S(f, \sigma, \xi_\bullet) - S(f, \sigma', \xi'_\bullet)\| &\leq \sum_{i=1}^n \|f(\gamma_i) - f(\gamma'_i)\| \cdot (a_i - a_{i-1}) \\ &\leq \sum_{i=1}^n M(a_i - a_{i-1}) \leq M(b - a) \end{aligned}$$

□

Definition 13.9. Let $f : I \rightarrow V$. For each $\sigma = \{a_0 < \dots < a_n\} \in \mathcal{P}(I)$, write $I_i = [a_{i-1}, a_i]$ and define the **oscillation of f on σ** to be

$$\omega(f, \sigma) = \sum_{j=1}^n \text{diam}(f(I_j)) \cdot (a_j - a_{j-1}) \quad (13.15)$$

Exercise 13.10. Show that if $\sigma' \supset \sigma$, then $\omega(f, \sigma') \leq \omega(f, \sigma)$. Therefore, $(\omega(f, \sigma))_{\sigma \in \mathcal{P}(I)}$ is a decreasing net in $\overline{\mathbb{R}}_{\geq 0}$.

Now, Lem. 13.8 can be upgraded to the following version.

Lemma 13.11. Let $f : I \rightarrow V$. Let $\sigma \in \mathcal{P}(I)$. Choose $(\sigma', \xi'_\bullet), (\sigma'', \xi''_\bullet) \in \mathcal{Q}(I)$ such that $\sigma \subset \sigma'$ and $\sigma \subset \sigma''$. Then

$$\|S(f, \sigma', \xi'_\bullet) - S(f, \sigma'', \xi''_\bullet)\| \leq \omega(f, \sigma) \quad (13.16)$$

Proof. Write $\sigma = \{a_0 < \dots < a_n\}$ and $I_j = [a_{j-1}, a_j]$. Let $S(f, \sigma', \xi'_\bullet)_{I_j}$ be the **restriction of $S(f, \sigma', \xi'_\bullet)$ to I_j** . Namely,

$$S(f, \sigma', \xi'_\bullet)_{I_j} = \sum_{\substack{\text{all } k \text{ such that} \\ [a_{k-1}, a_k] \subset I_j}} f(\xi'_k)(a_k - a_{k-1}) \quad (13.17)$$

Define $S(f, \sigma'', \xi''_\bullet)_{I_j}$ in a similar way. Then, by Lem. 13.8 we have

$$\|S(f, \sigma', \xi'_\bullet)_{I_j} - S(f, \sigma'', \xi''_\bullet)_{I_j}\| \leq \text{diam}(f(I_j))|I_j|$$

Thus, (13.16) follows immediately from triangle inequality and

$$\sum_{j=1}^n S(f, \sigma', \xi'_\bullet)_{I_j} = S(f, \sigma', \xi'_\bullet) \quad \sum_{j=1}^n S(f, \sigma'', \xi''_\bullet)_{I_j} = S(f, \sigma'', \xi''_\bullet)$$

□

Definition 13.12. We say that $f : I \rightarrow V$ is **strongly Riemann integrable** if

$$\inf_{\sigma \in \mathcal{P}(I)} \omega(f, \sigma) = 0$$

Theorem 13.13. Let $f : I \rightarrow V$. Consider the following statements:

- (1) $f \in \mathcal{R}(I, V)$.
- (2) f is strongly Riemann integrable.

Then (2) \Rightarrow (1). If V is \mathbb{R}^N or \mathbb{C}^N , then (1) \Leftrightarrow (2).

When V is infinite-dimensional, Riemann integrable functions are not necessarily strongly Riemann integrable. See Pb. 13.3.

Proof. Assume (2). Choose any $\varepsilon > 0$. Then there exists $\sigma \in \mathcal{P}(I)$ such that $\omega(f, \sigma) < \varepsilon$. By Lem. 13.11, for every $(\sigma', \xi'_\bullet), (\sigma'', \xi''_\bullet) \in \mathcal{Q}(I)$ satisfying $\sigma \subset \sigma'$ and $\sigma \subset \sigma''$, we have $\|S(f, \sigma', \xi'_\bullet) - S(f, \sigma'', \xi''_\bullet)\| < \varepsilon$. This proves that $(S(f, \sigma, \xi_\bullet))_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)}$ is a Cauchy net in V , and hence $f \in \mathcal{R}(I, V)$.

Now assume that V is \mathbb{R}^N or \mathbb{C}^N . Since $\mathbb{C}^N \simeq \mathbb{R}^{2N}$, it suffices to consider the case $V = \mathbb{R}^N$. Since a net in \mathbb{R}^N converges iff each component of this net converge, and since the strong Riemann integrability can be checked componentwisely, it suffices to prove (1) \Rightarrow (2) for the case $V = \mathbb{R}$.

So let us assume $f \in \mathcal{R}(I, \mathbb{R})$. Then $(S(f, \sigma, \xi_\bullet))_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)}$ is a Cauchy net in \mathbb{R} . Thus, there exists $\sigma = \{a_0 < \dots < a_n\} \in \mathcal{P}(I)$ such that for all $(\sigma', \xi'_\bullet), (\sigma'', \xi''_\bullet) \in \mathcal{Q}(I)$ satisfying $\sigma \subset \sigma'$ and $\sigma \subset \sigma''$, we have $\|S(f, \sigma', \xi'_\bullet) - S(f, \sigma'', \xi''_\bullet)\| < \varepsilon$. To prove (2), we only need to take $\sigma' = \sigma'' = \sigma$. Thus, for any tags $\xi'_\bullet, \xi''_\bullet$ of σ , we have

$$\|S(f, \sigma, \xi''_\bullet) - S(f, \sigma, \xi'_\bullet)\| < \varepsilon$$

Write $I_j = [a_{j-1}, a_j]$. Then

$$\text{diam}(f(I_j)) = \sup f(I_j) - \inf f(I_j)$$

So there exist $\xi'_j, \xi''_j \in I_j$ such that

$$f(\xi'_j) \leq \inf f(I_j) + \varepsilon \quad f(\xi''_j) \geq \sup f(I_j) - \varepsilon$$

It follows that $\text{diam}(f(I_j)) - 2\varepsilon \leq f(\xi''_j) - f(\xi'_j)$. Thus

$$\begin{aligned} \omega(f, \sigma) &= \sum_j \text{diam}(f(I_j)) \cdot |I_j| \leq \sum_j (f(\xi''_j) - f(\xi'_j)) \cdot |I_j| + \sum_j 2\varepsilon \cdot |I_j| \\ &= S(f, \sigma, \xi''_\bullet) - S(f, \sigma, \xi'_\bullet) + 2(b-a)\varepsilon < \varepsilon + 2(b-a)\varepsilon \end{aligned}$$

Since $\varepsilon > 0$ is arbitrary, we have $\inf_{\sigma \in \mathcal{P}(I)} \omega(f, \sigma) = 0$. □

Example 13.14. Every continuous function $f : I \rightarrow V$ is strongly Riemann integrable, and hence Riemann integrable.

Proof. Since $I = [a, b]$ is compact, by Thm. 10.7, $f \in C(I, V)$ is uniformly continuous. Therefore, for every $\varepsilon > 0$, there exists $n \in \mathbb{Z}_+$ such that for all $x, y \in I$ satisfying $|x - y| \leq 1/n$, we have $\|f(x) - f(y)\| < \varepsilon$. Let $\sigma = \{a_0 < a_1 < \cdots < a_n\}$ be the partition of I such that $|I_j| = a_j - a_{j-1} = 1/n$. Then $\text{diam}(f(I_j)) \leq \varepsilon$, and hence

$$\omega(f, \sigma) \leq \sum_j \varepsilon \cdot |I_j| = \varepsilon(b - a)$$

Since ε is arbitrary, we get $\inf_{\sigma \in \mathcal{P}(I)} \omega(f, \sigma) = 0$. □

Example 13.15. The **Dirichlet function** $\chi_{\mathbb{Q}}$ is not (strongly) Riemann integrable on $I = [a, b]$, since for every $\sigma \in \mathcal{P}(I)$ we have $\omega(\chi_{\mathbb{Q}}, \sigma) = b - a$.

13.3 Basic properties of Riemann integrals

Let $I = [a, b]$ be a compact interval in \mathbb{R} . Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. We begin this section with the following fundamental fact, which will be used to prove Fubini's theorem, the second fundamental theorem calculus, and much more.

Theorem 13.16. Let W be also a Banach space over \mathbb{F} . Let $T \in \mathcal{L}(V, W)$. Then for every $f \in \mathcal{R}(I, V)$, we have $T \circ f \in \mathcal{R}(I, W)$ and

$$T\left(\int_a^b f\right) = \int_a^b T \circ f \tag{13.18}$$

In other words, we have a commutative diagram

$$\begin{array}{ccc} \mathcal{R}(I, V) & \xrightarrow{T \circ} & \mathcal{R}(I, W) \\ \downarrow \int_I & & \downarrow \int_I \\ V & \xrightarrow{T} & W \end{array} \tag{13.19}$$

where the top arrow denotes the composition map $f \mapsto T \circ f$.

Proof. By linearity, we have

$$S(T \circ f, \sigma, \xi_{\bullet}) = T(S(f, \sigma, \xi_{\bullet})) \tag{13.20}$$

Since T is continuous, the limit over $(\sigma, \xi_{\bullet}) \in \mathcal{Q}(I)$ of (13.20) is

$$T\left(\lim_{(\sigma, \xi_{\bullet}) \in \mathcal{Q}(I)} S(f, \sigma, \xi_{\bullet})\right) = T\left(\int_a^b f\right)$$

This proves that $\lim S(T \circ f, \sigma, \xi_{\bullet})$ converges to $T(\int_a^b f)$, i.e., $\int_a^b T \circ f$ exists and equals $T(\int_a^b f)$. □

Remark 13.17. Let $f : I \rightarrow V$ and $\varepsilon > 0$. To simplify the following discussion, we say that f is ε -**dominated** by $\sigma \in \mathcal{P}(I)$, if for all $(\sigma', \xi'_\bullet), (\sigma'', \xi''_\bullet) \in \mathcal{Q}([a, b])$ satisfying $\sigma \subset \sigma', \sigma''$, we have $\|S(f, \sigma', \xi'_\bullet) - S(f, \sigma'', \xi''_\bullet)\| < \varepsilon$.

Thus, by Cauchy condition, if f is ε -dominated by some partition for every $\varepsilon > 0$, then $f \in \mathcal{R}(I, V)$. Moreover,

$$\left\| \int_a^b f - S(f, \sigma, \xi_\bullet) \right\| \leq \varepsilon \quad (13.21)$$

for every $(\sigma, \xi_\bullet) \in \mathcal{Q}(I)$ such that f is ε -dominated by σ . \square

13.3.1 Integral operators as bounded linear maps

Proposition 13.18. Let $f \in \mathcal{R}(I, V)$ and $g \in \mathcal{R}(I, \mathbb{R})$. Assume that $|f| \leq g$, i.e., $\|f(x)\| \leq g(x)$ for all $x \in I$. Then $\left\| \int_a^b f \right\| \leq \int_a^b g$.

Proof. Apply $\lim_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)}$ to the obvious inequality $\|S(f, \sigma, \xi_\bullet)\| \leq S(g, \sigma, \xi_\bullet)$. \square

Corollary 13.19. Assume that $f : I \rightarrow V$ is strongly Riemann integrable. Then $|f| : I \rightarrow \mathbb{R}$ is (strongly) Riemann integrable, and $\left\| \int_a^b f \right\| \leq \int_a^b |f|$

Proof. By triangle inequality, for every $\sigma \in \mathcal{P}(I)$ we have $\omega(|f|, \sigma) \leq \omega(f, \sigma)$. So $|f|$ is strongly integrable. The rest of the corollary follows from Prop. 13.18. \square

Theorem 13.20. $\mathcal{R}(I, V)$ is a closed linear subspace of $l^\infty(I, V)$. So $\mathcal{R}(I, V)$ is a Banach space under the l^∞ -norm. Moreover, the map

$$\int : \mathcal{R}(I, V) \rightarrow V \quad f \mapsto \int_a^b f \quad (13.22)$$

is a bounded linear map with operator norm $b - a$ if we equip $\mathcal{R}(I, V)$ with the l^∞ -norm.

Proof. By the basic properties of limits of nets, we know that if $f, g \in \mathcal{R}(I, V)$ and $\alpha, \beta \in \mathbb{F}$, then $\alpha f + \beta g \in \mathcal{R}(I, V)$, and

$$\int_a^b (\alpha f + \beta g) = \alpha \int_a^b f + \beta \int_a^b g \quad (13.23)$$

This proves that $\mathcal{R}(I, V)$ is a linear subspace of V^I , and that (13.22) is linear.

Let us prove $\mathcal{R}(I, V) \subset l^\infty(I, V)$. Choose $f \in \mathcal{R}(I, V)$. Then f is 1-dominated by some $\sigma = \{a_0 < \dots < a_n\} \in \mathcal{P}(I)$. Fix any tag ξ_\bullet on σ . Choose any $x \in X$. Let $[a_{i-1}, a_i]$ be the subinterval containing x . Let $\eta_\bullet = (\xi_1, \dots, \xi_{i-1}, x, \xi_{i+1}, \dots, \xi_n)$. Then $\|S(f, \sigma, \eta_\bullet) - S(f, \sigma, \xi_\bullet)\| < 1$ implies that $\|f(x) - f(\xi_i)\| \leq 1/(a_i - a_{i-1})$. So

$$\|f\|_{l^\infty} \leq \max \{ \|f(\xi_i)\| + (a_i - a_{i-1})^{-1} : 1 \leq i \leq n \} < +\infty$$

Let (f_n) be a sequence in $\mathcal{R}(I, V)$ converging to $f \in l^\infty(I, V)$. Choose any $\varepsilon > 0$. Then there is n such that $\|f - f_n\|_\infty < \varepsilon$. Since f_n is Riemann integrable, f_n is ε -dominated by some $\sigma \in \mathcal{P}(I)$. By triangle inequality, f is $(\varepsilon + (b - a)\varepsilon)$ -dominated by σ . Since ε is arbitrary, we conclude that $f \in \mathcal{R}(I, V)$. This proves that $\mathcal{R}(I, V)$ is closed, and hence is Banach by Prop. 3.27.

Let us prove the claim about the operator norm. Choose any $f \in \mathcal{R}(I, V)$. Let $M = \|f\|_\infty < +\infty$. Then $|f| \leq M$. It is easy to see that $\int_a^b M = M(b - a)$. Thus, by Prop. 13.18, we have $\|\int_a^b f\| \leq M(b - a) = \|f\|_\infty \cdot (b - a)$, where “ \leq ” becomes “ $=$ ” if we let f be a nonzero constant function. This proves that (13.22) has operator norm $b - a$ thanks to Rem. 10.24. \square

Corollary 13.21. *Let $(f_\alpha)_{\alpha \in \mathcal{J}}$ be a net in $\mathcal{R}(I, V)$ converging uniformly to $f \in V^I$. Then $f \in \mathcal{R}(I, V)$ and $\lim_{\alpha \in \mathcal{J}} \int_a^b f_\alpha = \int_a^b f$.*

Proof. This is immediate from Thm. 13.20, which implies that $\mathcal{R}(I, V)$ is closed in $l^\infty(I, V)$ (and hence closed in V^I since $l^\infty(I, V)$ is closed in V^I), and that the map (13.22) is continuous. \square

13.3.2 Some criteria for Riemann integrability

Proposition 13.22. *Let $f, g : I \rightarrow V$. Suppose that $\{x \in I : f(x) \neq g(x)\}$ is a finite set. Suppose that $f \in \mathcal{R}(I, V)$. Then $g \in \mathcal{R}(I, V)$, and $\int_a^b f = \int_a^b g$.*

Proof. By Thm. 13.20, it suffices to prove that $g - f$ is Riemann integrable and $\int_a^b (g - f) = 0$. This is easy to show, since $g - f$ is zero outside finitely many points. \square

Proposition 13.23. *Let $f : [a, b] \rightarrow V$. Let $c \in [a, b]$. Then $f \in \mathcal{R}([a, b], V)$ iff $f|_{[a, c]} \in \mathcal{R}([a, c], V)$ and $f|_{[c, b]} \in \mathcal{R}([c, b], V)$. Moreover, if $f \in \mathcal{R}([a, b], V)$, then*

$$\int_a^b f = \int_a^c f + \int_c^b f \quad (13.24)$$

Proof. This is obvious when $c = a$ or $c = b$ (recall Conv. 13.5). So we assume $a < c < b$.

First, we assume $f \in \mathcal{R}([a, b], V)$. By Cauchy condition, for each $\varepsilon > 0$, f is ε -dominated by some $\sigma \in \mathcal{P}(I)$. By enlarging σ , we assume that $c \in \sigma$. Then it is easy to see that $f|_{[a, c]}$ is ε -dominated by $\sigma \cap [a, c]$, and $f|_{[c, b]}$ is ε -dominated by $\sigma \cap [c, b]$. So $f|_{[a, c]}$ and $f|_{[c, b]}$ are Riemann integrable.

Now assume that $f|_{[a, c]}$ and $f|_{[c, b]}$ are Riemann integrable. Choose any $\varepsilon > 0$. Then $f|_{[a, c]}$ is ε -dominated by some $\tau \in \mathcal{P}([a, c])$, and $f|_{[c, b]}$ is ε -dominated by some $\varrho \in \mathcal{P}([c, b])$. Then f is 2ε -dominated by $\sigma = \tau \cup \varrho$. This proves that $f \in$

$\mathcal{R}(I, V)$. Let α_\bullet be a tag on $[a, c]$, and let β_\bullet be a tag on $[c, b]$. Then $\xi_\bullet = (\alpha_\bullet, \beta_\bullet) = (\alpha_1, \alpha_2, \dots, \beta_1, \beta_2, \dots)$ is a tag on $[a, b]$, and

$$S(f, \sigma, \xi_\bullet) = S(f|_{[a,c]}, \tau, \alpha_\bullet) + S(f|_{[c,b]}, \varrho, \beta_\bullet)$$

By Rem. 13.17, we have

$$\begin{aligned} \left\| \int_a^b f - S(f, \sigma, \xi_\bullet) \right\| &\leq 2\varepsilon \\ \left\| \int_a^c f - S(f|_{[a,c]}, \tau, \alpha_\bullet) \right\| &\leq \varepsilon \\ \left\| \int_c^b f - S(f|_{[c,b]}, \varrho, \beta_\bullet) \right\| &\leq \varepsilon \end{aligned}$$

Therefore, the difference of the LHS and the RHS of (13.24) has norm $\leq 4\varepsilon$. This proves (13.24) since ε can be arbitrary. \square

Example 13.24. Let $f \in l^\infty(I, V)$. Suppose that there exist $\sigma = \{a_0 < a_1 < \dots < a_n\} \in \mathcal{P}(I)$ such that $f|_{(a_{j-1}, a_j)} : (a_{j-1}, a_j) \rightarrow V$ is continuous for each $1 \leq j \leq n$. Then $f \in \mathcal{R}(I, V)$.

Proof. By Prop. 13.23, it suffices to prove that each $f|_{[a_{j-1}, a_j]}$ is Riemann integrable. Thus, we assume WLOG that $M := \|f\|_\infty < +\infty$, and that f is continuous when restricted to (a, b) . Choose any $\varepsilon > 0$. Choose $\delta > 0$ such that $M\delta < \varepsilon$ and $a + \delta < b - \delta$. Let $J = [a + \delta, b - \delta]$. Then $f|_J$ is continuous, and hence Riemann integrable by Exp. 13.14. So $f|_J$ is ε -dominated by some $\varrho \in \mathcal{P}(J)$. Since $\text{diam}(f(I)) \leq 2M$, by Lem. 13.8, $f|_{[a, a+\delta]}$ is 2ε -dominated by $\{a, a + \delta\}$, and $f|_{[b-\delta, b]}$ is 2ε -dominated by $\{b - \delta, b\}$. So f is 5ε -dominated by $\sigma = \varrho \cup \{a, b\}$. Since $\varepsilon > 0$ is arbitrary, we conclude $f \in \mathcal{R}(I, V)$ by Cauchy condition. \square

Example 13.25. The function $f : [0, 1] \rightarrow \mathbb{R}$ defined by $f(x) = \sin(1/x)$ if $0 < x \leq 1$ and $f(0) = 0$ is Riemann integrable, although f is not uniformly continuous on $(0, 1]$.

Example 13.26. Let I_1, \dots, I_n be intervals inside I . Choose $v_1, \dots, v_n \in V$ and set $f = \sum_{j=1}^n v_j \chi_{I_j}$. Then $f \in \mathcal{R}(I, V)$.

Proof. The case of arbitrary n follows from the case $n = 1$ by linearity and Thm. 13.20. Assume $n = 1$, and let $c = \inf I_1$ and $d = \sup I_1$. Then the restriction of f to $[a, c]$ (resp. $[c, d]$ and $[d, b]$) equals a constant function except possibly at the end points of the interval. So $f|_{[a,c]}, f|_{[c,d]}, f|_{[d,b]}$ are Riemann integrable by Prop. 13.22. So f is Riemann integrable by Prop. 13.23. \square

Example 13.27. Let $f \in C(I, V)$. For each $n \in \mathbb{Z}_+$, choose a tag $\xi_{i,n}$ for the partition $\sigma = \{a, a + |I|/n, a + 2|I|/n, \dots, a + (n-1)|I|/n, b\}$ of I . Then

$$\lim_{n \rightarrow \infty} \frac{b-a}{n} \sum_{i=1}^n f(\xi_{i,n}) = \int_a^b f \quad (13.25)$$

Proof. Let $f_n = \sum_{i=1}^n f(\xi_{i,n}) \cdot \chi_{J_{i,n}}$ where $J_{i,n} = (a + \frac{i-1}{n}|I|, a + \frac{i}{n}|I|]$ if $i > 1$, and $J_{1,n} = [a, a + |I|/n]$. Then $f_n \in \mathcal{R}(I, V)$ by Exp. 13.26. Moreover, by Prop. 13.23, the LHS of (13.25) equals $\lim_n \int_a^b f_n$.

By Thm. 10.7, f is uniformly continuous. So for every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and all $x, y \in \text{Cl}_{\mathbb{R}}(J_{i,n})$ we have $\|f(x) - f(y)\| < \varepsilon$. Thus, for all $n \geq N$ we have $\|f - f_n\|_{l^\infty} < \varepsilon$. Therefore $f_n \rightrightarrows f$. Thus, by Cor. 13.21 we have $\int_a^b f_n \rightarrow \int_a^b f$. This proves (13.25). \square

Example 13.28. By Thm. 13.30, we have $\int_1^2 x^{-1} dx = \log 2$. Thus, by Exp. 13.27, we have $\lim_{n \rightarrow \infty} \sum_{i=1}^n \frac{2-i}{n} \cdot (1 + i/n)^{-1} = \log 2$, namely

$$\lim_{n \rightarrow \infty} ((n+1)^{-1} + (n+2)^{-1} + \cdots + (2n)^{-1}) = \log 2$$

13.4 Integrals and derivatives

Let $I = [a, b]$ be an interval in \mathbb{R} . Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

13.4.1 Fundamental theorems of calculus (FTC)

There are two versions of FTC. Roughly speaking, the first FTC says that integrals give antiderivatives. The second FTC says that antiderivatives give integrals. These two FTC are equivalent when the function f to be integrated is continuous. Otherwise, there is a subtle difference (which I can never remember) between these two theorems.

Theorem 13.29 (First FTC). Let $f \in \mathcal{R}(I, V)$. Define

$$F : I \rightarrow V \quad F(x) = \int_a^x f \quad (13.26)$$

Then $F \in C(I, V)$. If f is continuous at x , then $F'(x) = f(x)$.

In particular, if $f \in C(I, V)$, then $F' = f$. Thus, by Cor. 11.24, the antiderivatives of f are precisely of the form $F(x) + v_0$ where $v_0 \in V$ is viewed as a constant function.

Recall Conv. 13.5.

Proof. Recall by Thm. 13.20 that $\|f\|_\infty < +\infty$. For each $x, y \in [a, b]$ we have

$$\|F(y) - F(x)\| = \left\| \int_a^y f - \int_a^x f \right\| = \left\| \int_x^y f \right\| \leq \|f\|_\infty \cdot |y - x|$$

So F has Lipschitz constant $\|f\|_\infty$. Now suppose that f is continuous at x . Then for every $\varepsilon > 0$, there exists $U \in \text{Nbh}_I(x)$ such that $\|f(x) - f(y)\| < \varepsilon$ for every $y \in U$. Thus, for each $y \in U \setminus \{x\}$, since $\int_x^y f(t) dt = f(x)(y - x)$, we have

$$\left\| \frac{F(y) - F(x)}{y - x} - f(x) \right\| = |y - x|^{-1} \left\| \int_x^y (f(t) - f(x)) dt \right\|$$

$$\leq |y - x|^{-1} \int_{[x,y]} \|f(t) - f(x)\| dt \leq |y - x|^{-1} \int_{[x,y]} \varepsilon dt = \varepsilon$$

This proves $F'(x) = f(x)$. □

Theorem 13.30 (Second FTC). *Let $f \in \mathcal{R}(I, V)$. Assume that $F : I \rightarrow V$ is differentiable and $F' = f$. Then*

$$\int_a^b f = F|_a^b \stackrel{\text{def}}{=} F(b) - F(a) \quad (13.27)$$

This theorem is easy when $f \in C(I, V)$: In this case, by Thm. 13.29, we have $F(x) = v_0 + \int_a^x f$ for some $v_0 \in V$. Then (13.27) follows immediately from Prop. 13.23. The proof for the general case is more difficult:

Proof assuming Hahn-Banach. Since \mathbb{R} is a subfield of \mathbb{C} , we may view V as a real Banach space. We first consider the special case that $V = \mathbb{R}$. Let $A = \int_a^b f$. Choose any $\varepsilon > 0$. Since $f \in \mathcal{R}(I, \mathbb{R})$, there exists $\sigma = \{a_0 < \dots < a_n\} \in \mathcal{P}(I)$ such that for every tag ξ_\bullet on σ , we have $|A - S(f, \sigma, \xi_\bullet)| < \varepsilon$. By Lagrange's MVT (Thm. 11.19), there exists $\xi_i \in (a_{i-1}, a_i)$ such that

$$F(a_i) - F(a_{i-1}) = f(\xi_i)(a_i - a_{i-1})$$

Thus, we have a tag ξ_\bullet such that $S(f, \sigma, \xi_\bullet) = F(b) - F(a)$. Hence $|A - F(b) + F(a)| < \varepsilon$. Since ε is arbitrary, we get $A = F(b) - F(a)$.

The case $V = \mathbb{R}^N$ can be reduced to the above special case easily. We now consider the general case that V is a Banach space over \mathbb{R} . Similar to (12.15), for every $\varphi \in V^* = \mathcal{L}(V, \mathbb{R})$, we have that $\varphi \circ F$ is differentiable, and that $(\varphi \circ F)' = \varphi \circ f$. Note that $\varphi \circ f \in \mathcal{R}(I, \mathbb{R})$ by Thm. 13.16. Apply the one-dimensional special case to $\varphi \circ f$. Then by Thm. 13.16, we have

$$\varphi\left(\int_a^b f\right) = \int_a^b \varphi \circ f = \varphi \circ F|_a^b = \varphi(F(b) - F(a))$$

By Hahn-Banach theorem, V^* separates points of V . (See Rem. 11.26.) Therefore $\int_a^b f = F(b) - F(a)$. □

13.4.2 Applications of FTC: integration by parts

Proposition 13.31 (Integration by parts). *Let $f \in C^1(I, V)$ and $g \in C^1(I, \mathbb{F})$. Then*

$$\int_a^b f'g = (fg)|_a^b - \int_a^b fg' \quad (13.28)$$

Proof. $(fg)|_a^b = \int_a^b (fg)' = \int_a^b f'g + \int_a^b fg'$. □

Theorem 13.32 (Taylor's theorem, integral form). Let $n \in \mathbb{N}$ and $f \in C^{n+1}([a, b], V)$. Then for every $x \in [a, b]$ we have

$$f(x) = \sum_{k=0}^n \frac{f^{(k)}(a)}{k!} (x-a)^k + \int_a^x \frac{f^{(n+1)}(t)}{n!} (x-t)^n dt \quad (13.29)$$

Proof. When $n = 0$, (13.29) is just FTC. We now prove (13.29) by induction. Suppose that case $n - 1$ has been proved, then by integration by parts,

$$\begin{aligned} f(x) - \sum_{k=0}^{n-1} \frac{f^{(k)}(a)}{k!} (x-a)^k &= \int_a^x \frac{f^{(n)}(t)}{(n-1)!} (x-t)^{n-1} dt \\ &= \int_a^x -\frac{f^{(n)}(t)}{n!} \partial_t (x-t)^n dt \\ &= -\frac{f^{(n)}(t)}{n!} (x-t)^n \Big|_{t=a}^x + \int_a^x \frac{f^{(n+1)}(t)}{n!} (x-t)^n dt \\ &= \frac{f^{(n)}(a)}{n!} (x-a)^n + \int_a^x \frac{f^{(n+1)}(t)}{n!} (x-t)^n dt \end{aligned}$$

□

Exercise 13.33. Use the integral form of Taylor's theorem to give a quick proof higher order finite-increment Thm. 12.17 under the assumption that $f \in C^{n+1}([a, b], V)$. (This assumption is slightly stronger than that in Thm. 12.17, but is enough for applications.)

In the case that $V = \mathbb{R}$, the integral form of Taylor's theorem actually implies a slightly weaker (but useful enough) version of Lagrange form. This relies on the following easy fact:

Proposition 13.34 (Mean value theorem). Let $f, g \in C([a, b], \mathbb{R})$ such that $g(x) \geq 0$ for all $x \in (a, b)$. Then there exists $\xi \in [a, b]$ such that

$$\int_a^b fg = f(\xi) \int_a^b g \quad (13.30)$$

Moreover, ξ can be chosen to be in (a, b) if $g(x) > 0$ for all $x \in (a, b)$.

Proof. Let $m = \inf f(I)$ and $M = \sup f(I)$. Then $mg \leq fg \leq Mg$, and hence $m \int_I g \leq \int_I fg \leq \int_I Mg$. So there is $y \in [m, M]$ such that $\int_I fg = y \int_I g$. By extreme value theorem, we have $m, M \in f(I)$. Thus, by intermediate value property, we have $y \in f(I)$. So $y = f(\xi)$ for some $\xi \in I$.

Now assume $g(x) > 0$ for all $a < x < b$. Let $\varphi(x) = \int_a^x fg$ and $\psi(x) = \int_a^x g$. By Cauchy's MVT, there exists $\xi \in (a, b)$ such that $g(\xi)(\varphi(b) - \varphi(a)) = f(\xi)g(\xi)(\psi(b) - \psi(a))$. This finishes the proof. □

Remark 13.35. Let $f \in C^{n+1}([a, b], \mathbb{R})$. By the above mean value theorem, for each $x \in (a, b]$ there exists $\xi \in (a, x)$ such that

$$\int_a^x \frac{f^{(n+1)}(t)}{n!} (x-t)^n dt = f^{(n+1)}(\xi) \int_a^x \frac{(x-t)^n}{n!} dt = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-a)^{n+1}$$

Thus, the integral form of Taylor's theorem implies Lagrange's form (Thm. 12.18) in the case that $f \in C^{n+1}(I, \mathbb{R})$.

13.4.3 Application of FTC: change of variables

Proposition 13.36 (Change of variables). Let $\Phi \in C^1(I, \mathbb{R})$ such that $\Phi(I) \subset J = [c, d]$. Let $f \in C(J, V)$. Then

$$\int_{\Phi(a)}^{\Phi(b)} f = \int_a^b (f \circ \Phi) \cdot \Phi' \quad (13.31)$$

Proof. Define $F : J \rightarrow V$ and $G : I \rightarrow V$ by $F(y) = \int_{\Phi(a)}^y f$ and $G(x) = F \circ \Phi(x) = \int_{\Phi(a)}^{\Phi(x)} f$. Then, by chain rule and FTC, $G' = (F' \circ \Phi) \cdot \Phi' = (f \circ \Phi) \cdot \Phi'$. By FTC, we have $G' = H'$ where $H : I \rightarrow V$ is defined by

$$H(x) = \int_a^x (f \circ \Phi) \cdot \Phi'$$

Thus, since $G(a) = F(a) = 0$, by Cor. 11.24 we have $G = H$. Then $G(b) = H(b)$ finishes the proof. \square

The change of variable formula allows us to define the length of a curve:

Definition 13.37. Let γ be a C^1 -curve in V , i.e. $\gamma \in C^1([a, b], V)$. Its **length** is defined to be

$$l(\gamma) = \int_a^b \|\gamma'(t)\| dt$$

Proposition 13.38. The length of γ is invariant under a reparametrization. Namely, if $f : [c, d] \rightarrow [a, b]$ is a bijection and is in $C^1([c, d], \mathbb{R})$, then $l(\gamma) = l(\gamma \circ f)$.

Proof. By Prop. 11.22, f is either increasing or decreasing. We prove the case that f is decreasing; the other case is similar. Then $f(c) = b$ and $f(d) = a$. By chain rule, we have

$$l(\gamma \circ f) = \int_c^d |(\gamma \circ f)'| = \int_c^d |(\gamma' \circ f) \cdot f'| = \int_c^d (|\gamma'| \circ f) \cdot |f'|$$

which equals $-\int_c^d (|\gamma'| \circ f) \cdot f' = \int_d^c (|\gamma'| \circ f) \cdot f'$ because $f' \leq 0$ by Cor. 11.20. This expression equals $\int_a^b |\gamma'| = l(\gamma)$ by Prop. 13.36. \square

Example 13.39. The upper half circle $\mathbb{S}_+^1 = \{z \in \mathbb{C} : |z| = 1, \operatorname{Im} z \geq 0\}$ has a bijective C^∞ -parametrization $\gamma : [0, \pi] \rightarrow \mathbb{C}, \gamma(t) = e^{it}$. Its length is π .

Proof. We have $l(\gamma) = \int_0^\pi |\gamma'| = \int_0^\pi 1 = \pi$. So it remains to prove that γ restricts to a bijection $[0, \pi] \rightarrow \mathbb{S}_+^1$. Clearly $\gamma([0, \pi]) \subset \mathbb{S}^1 = \{z \in \mathbb{C} : |z| = 1\}$. Note that $\gamma(t) = \cos(t) + i \sin(t)$. In Sec. 12.2, we have proved that $\sin(x) \geq 0$ when $x \in [0, \pi]$. So $\gamma([0, \pi]) \subset \mathbb{S}_+^1$.

We have also proved in Sec. 12.2 that $\cos : [0, \pi/2] \rightarrow \mathbb{R}$ is a decreasing (continuous) function such that $\cos(0) = 1$ and $\cos(\pi/2) = 0$, and that $\cos(x) = \cos(\pi - x)$. The last relation shows that $\cos : [0, \pi] \rightarrow \mathbb{R}$ is decreasing, and $\cos(0) = 1, \cos(\pi) = -1$. Therefore, by the intermediate value theorem, we see that \cos sends $[0, \pi]$ bijectively to $[-1, 1]$. Since the projection map onto the x -axis sends \mathbb{S}_+^1 bijectively to $[-1, 1]$, we conclude that γ sends $[0, \pi]$ bijectively to \mathbb{S}_+^1 . \square

Remark 13.40. You may wonder if the above argument really proves that π is the length of \mathbb{S}_+^1 : Suppose that $\lambda : [a, b] \rightarrow \mathbb{C}$ is another C^∞ map restricting to a bijection $[a, b] \rightarrow \mathbb{S}_+^1$, how can we show that $\int_0^\pi |\gamma'| = \int_a^b |\lambda'|$? Clearly, there is a bijection $f : [a, b] \rightarrow [0, \pi]$ such that $\lambda = \gamma \circ f$. Thus, by Prop. 13.38, the two integrals are equal if $f \in C^\infty$, or at least if $f \in C^1$. However, it seems that there is no general argument ensuring that $f \in C^1$.

In the next semester, we will learn that $f \in C^\infty$ if the two C^∞ -parametrizations λ, γ satisfy that λ' and γ' are nowhere zero. (Clearly γ' is nowhere zero if $\gamma(t) = e^{it}$.) Such parametrizations are called **(smooth) immersions**. \square

13.5 Problems and supplementary material

Let $I = [a, b]$ where $-\infty < a < b < +\infty$.

Problem 13.1. Let $f \in l^\infty(I, \mathbb{R})$. Recall from Subsec. 13.2.1 that the refinements of partitions define preorders on $\mathcal{P}(I)$ and $\mathcal{Q}(I)$ so that they are directed sets. For each $\sigma = \{a_0 < a_1 < \dots < a_n\} \in \mathcal{P}(I)$, define the **upper Darboux sum** and the **lower Darboux sum**

$$\begin{aligned} \overline{S}(f, \sigma) &= \sum_{i=1}^n M_i(a_i - a_{i-1}) & \underline{S}(f, \sigma) &= \sum_{i=1}^n m_i(a_i - a_{i-1}) \\ \text{where} \quad M_i &= \sup_{\xi \in [a_{i-1}, a_i]} f(\xi) & m_i &= \inf_{\xi \in [a_{i-1}, a_i]} f(\xi) \end{aligned}$$

Prove that

$$-(b-a)\|f\|_\infty \leq \underline{S}(f, \sigma) < \overline{S}(f, \sigma) \leq (b-a)\|f\|_\infty$$

Choose any tag ξ_\bullet on σ . Prove that

$$\overline{S}(f, \sigma) = \sup_{(\sigma', \xi'_\bullet) > (\sigma, \xi_\bullet)} S(f, \sigma', \xi'_\bullet) \quad \underline{S}(f, \sigma) = \inf_{(\sigma', \xi'_\bullet) > (\sigma, \xi_\bullet)} S(f, \sigma', \xi'_\bullet) \quad (13.32)$$

Pb. 13.1 immediately implies:

Theorem 13.41. Let $f \in l^\infty(I, \mathbb{R})$. Define the **upper Darboux integral** and the **lower Darboux integral** to be

$$\overline{\int}_a^b f = \inf_{\sigma \in \mathcal{P}(I)} \overline{S}(f, \sigma) \quad \underline{\int}_a^b f = \sup_{\sigma \in \mathcal{P}(I)} \underline{S}(f, \sigma)$$

which are elements of $[-(b-a)\|f\|_\infty, (b-a)\|f\|_\infty]$. Then we have (recalling Pb. 8.2)

$$\begin{aligned} \overline{\int}_a^b f &= \limsup_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)} S(f, \sigma, \xi_\bullet) \\ \underline{\int}_a^b f &= \liminf_{(\sigma, \xi_\bullet) \in \mathcal{Q}(I)} S(f, \sigma, \xi_\bullet) \end{aligned}$$

Therefore, by Cor. 8.37, we have

$$f \in \mathcal{R}(I, \mathbb{R}) \quad \Longleftrightarrow \quad \overline{\int}_a^b f = \underline{\int}_a^b f \quad (13.33)$$

Moreover, if $f \in \mathcal{R}(I, \mathbb{R})$, then $\int_a^b f = \overline{\int}_a^b f = \underline{\int}_a^b f$.

Problem 13.2. Let \mathcal{V} be a vector space over \mathbb{C} . Since \mathbb{R} is a subfield of \mathbb{C} , \mathcal{V} can be viewed as a real normed vector space. Let $\Lambda : \mathcal{V} \rightarrow \mathbb{R}$ be a \mathbb{R} -linear map. Recall $\mathbf{i} = \sqrt{-1}$. Define a map

$$\Lambda_{\mathbb{C}} : \mathcal{V} \rightarrow \mathbb{C} \quad \Lambda_{\mathbb{C}}(v) = \Lambda(v) - \mathbf{i}\Lambda(\mathbf{i}v) \quad (13.34)$$

1. Prove that $\Lambda_{\mathbb{C}}$ is \mathbb{C} -linear.
2. Given a \mathbb{C} -linear $\Phi : \mathcal{V} \rightarrow \mathbb{C}$, we define its **real part**

$$\operatorname{Re}\Phi : \mathcal{V} \rightarrow \mathbb{R} \quad v \mapsto \operatorname{Re}(\Phi(v)) \quad (13.35)$$

Then clearly $\operatorname{Re}(\Phi)$ is \mathbb{R} -linear. Prove that $\Phi \mapsto \operatorname{Re}\Phi$ is a bijection from the set of \mathbb{C} -linear maps $\mathcal{V} \rightarrow \mathbb{C}$ to the set of \mathbb{R} -linear maps $\mathcal{V} \rightarrow \mathbb{R}$, and that its inverse is the map $\Lambda \mapsto \Lambda_{\mathbb{C}}$ defined by (13.34).

3. Assume that \mathcal{V} is a (non-necessarily complete) normed \mathbb{C} -vector space. For each \mathbb{C} -linear $\Phi : \mathcal{V} \rightarrow \mathbb{C}$, prove the following equation about operator norms:

$$\|\Phi\| = \|\operatorname{Re}\Phi\| \quad (13.36)$$

(Hint: One of “ \leq ” and “ \geq ” is obvious. To prove the other one, for each $v \in \mathcal{V}$, find some $\theta \in \mathbb{R}$ such that $e^{i\theta}\Phi(v) \in \mathbb{R}$.)

Remark 13.42. The above problem shows how to extend a real-valued integral to a complex-valued one. For example, suppose that we define real-valued Riemann integrals using Darboux integrals. Suppose we have proved that the map $f \in \mathcal{R}(I, \mathbb{R}) \mapsto \int_a^b f$ is \mathbb{R} -linear with operator norm $(b - a)$. Then, applying Pb. 13.2 to the \mathbb{R} -linear map

$$\Lambda : \mathcal{R}(I, \mathbb{C}) \rightarrow \mathbb{R} \quad f \mapsto \int_a^b \operatorname{Re} f(t) dt$$

gives a \mathbb{C} -linear map

$$\begin{aligned} \int_a^b : \mathcal{R}(I, \mathbb{C}) &\rightarrow \mathbb{C} \\ \int_a^b f &= \int_a^b \operatorname{Re} f + i \int_a^b \operatorname{Im} f \end{aligned}$$

since $\operatorname{Re}(if) = -\operatorname{Im} f$. Moreover, this linear map has operator norm $(b - a)$. This defines the complex integral operator by means of real Darboux integrals. In the next semester, we will use the same method to extend real-valued Lebesgue integrals to complex-valued ones. Pb. 13.2 will also be used to prove the Hahn-Banach extension theorem.

Exercise 13.43. Let $u, v \in C(I, \mathbb{R})$. Find the \mathbb{C} -linear map $C(I, \mathbb{C}) \rightarrow \mathbb{C}$ whose real part is $f \in C(I, \mathbb{C}) \mapsto \int_I (u \operatorname{Re} f + v \operatorname{Im} f) \in \mathbb{R}$.

★ **Problem 13.3.** Let $V = l^\infty([0, 1], \mathbb{R})$, equipped with the l^∞ -norm. Define

$$f : [0, 1] \rightarrow V \quad f(x) = \chi_{[x, 1]}$$

Then, for every $x \neq y$ in $[0, 1]$ we have $\|f(x) - f(y)\|_{l^\infty([0, 1], \mathbb{R})} = 1$. This implies $\omega(f, \sigma) = 1$ for every $\sigma \in \mathcal{P}(I)$. So f is not strongly Riemann integrable on any closed subinterval of $[a, b]$.

Define $F : [0, 1] \rightarrow V$ such that for each $x \in [0, 1]$,

$$F(x) : [0, 1] \rightarrow \mathbb{R} \quad t \mapsto \min\{t, x\}$$

Choose any $x \in [0, 1]$. Prove that $f \in \mathcal{R}([0, x], V)$ and $\int_0^x f = F(x)$. (In particular, $\int_0^1 f = \operatorname{id}_{[0, 1]}$.) Prove that $F'(x)$ does not exist. \square

Problem 13.4. Let V be a Banach space. Use the fundamental theorem of calculus to give another proof that $C^1(I, V)$ is complete under the $l^{1, \infty}$ -norm. (Do not use Thm. 11.33.)

★ **Theorem 13.44 (Gronwall's inequality).** Let $f \in C([a, b], \mathbb{R}_{\geq 0})$. Let $\alpha \in \mathbb{R}_{\geq 0}$, and $\beta \in C([a, b], \mathbb{R}_{\geq 0})$. Assume that for each $x \in [a, b]$ we have

$$f(x) \leq \alpha + \int_a^x \beta(t) f(t) dt \tag{13.37}$$

Then for each $x \in [a, b]$ we have

$$f(x) \leq \alpha \cdot \exp \left(\int_a^x \beta(t) dt \right) \quad (13.38)$$

In particular, if β is a constant, then Gronwall's inequality reads

$$f(x) \leq \alpha \cdot e^{\beta(t-a)}$$

★ **Problem 13.5.** Prove Gronwall's inequality. Hint: Let $g(x)$ be the RHS of (13.37). Show that $\exp(-\int_a^x \beta) \cdot g(x)$ is a decreasing function.

★ **Remark 13.45.** Gronwall's inequality is often used in the following way. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let $f \in C(I, V)$, $v \in V$, and $\beta \in C(I, \mathbb{R}_{\geq 0})$. Suppose that for all $x \in [a, b]$ we have

$$\|f(x) - v\| \leq \int_a^x \beta(t) \|f(t)\| dt \quad (13.39)$$

Applying Gronwall's inequality to $|f|$ and $\alpha = \|v\|$, we see that for every $x \in [a, b]$,

$$\|f(x)\| \leq \|v\| \cdot \exp \left(\int_a^x \beta(t) dt \right) \quad (13.40)$$

★ **Problem 13.6.** Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Assume that $\varphi \in C(I \times V, V)$ has Lipschitz constant $L \in \mathbb{R}_{\geq 0}$ over the second variable, i.e., for each $t \in [a, b]$ and $u, v \in V$ we have

$$\|\varphi(t, u) - \varphi(t, v)\| \leq L \|u - v\| \quad (13.41)$$

Use Gronwall's inequality to solve the following problems.

1. Let $f_1, f_2 : I \rightarrow V$ be differentiable and satisfying the differential equation

$$f'_i(t) = \varphi(t, f_i(t)) \quad (\forall t \in I)$$

with the same initial condition $f_1(a) = f_2(a)$. Prove that $f_1 = f_2$ on I .

2. Let X be a topological space. Let $f : I \times X \rightarrow V$ be a function such that $\partial_1 f$ exists everywhere, and that

$$\partial_1 f(t, x) = \varphi(t, f(t, x)) \quad (\forall t \in I, x \in X)$$

Assume that the function $f(a, \cdot) : X \rightarrow V$ (sending x to $f(a, x)$) is continuous. Prove that $f \in C(I \times X, V)$.

Remark 13.46. In practice, V is often \mathbb{R}^N , and φ is a “smooth function”, i.e. a function whose (mixed) partial derivatives of all orders exist and are continuous. It is also common that φ is independent of $t \in I$. (Indeed, a t -dependent differential equation $f' = \varphi(t, f)$ can be transformed into a t -independent one $(t, f)' = (1, \varphi(t, f))$.) However, sometimes f is not defined on \mathbb{R}^N , but on a closed subset of \mathbb{R}^N , for example, on a closed ball. In this case, the uniqueness and the continuity of the solutions of differential equations can be treated by extending φ to a smooth function on \mathbb{R}^N that is zero outside a compact set. (Then the Lipschitz continuity of this extended function will follow automatically.)

In fact, by the **smooth Tietze extension theorem** (cf. [Lee, Lem. 2.26]), every smooth function $A \rightarrow \mathbb{R}^k$ (where A is a compact subset of a smooth real manifold M (such as a Euclidean space, an n -dimensional sphere, etc.)) can be extended to a smooth function $M \rightarrow \mathbb{R}^k$ vanishing outside a compact set. We will study this theorem in the second semester. (The case $A \subset \mathbb{R}$ will be proved in Exp. 15.30.) \square

14 More on Riemann integrals

14.1 Commutativity of integrals and other limit processes

Let $I = [a, b]$ and $J = [c, d]$ where $-\infty < a < b < +\infty$ and $-\infty < c < d < +\infty$. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

14.1.1 Fubini's theorem

Theorem 14.1 (Fubini's theorem for Riemann integrals). *Let $f \in C(I \times J, V)$. Then $\int_I \int_J f = \int_J \int_I f$. More precisely,*

$$\int_I \left(\int_J f(x, y) dy \right) dx = \int_J \left(\int_I f(x, y) dx \right) dy \quad (14.1)$$

Our strategy is to view $\int_I f(x, y) dx$ as the integral of the function $I \rightarrow C(J, V)$ sending x to $f(x, \cdot)$. Then Fubini's theorem follows from the commutativity of integrals and the bounded linear map $\int_J : C(J, V) \rightarrow V$ (cf. Thm. 13.16). We first make some general discussion before giving the rigorous proof.

Let Y be a compact topological space. By Thm. 9.3, we have a canonical equivalence $C(I \times Y, V) \simeq C(I, C(Y, V))$ by viewing $f \in C(I \times Y, V)$ as a map

$$\Phi(f) : I \rightarrow C(Y, V) \quad (14.2a)$$

where

$$\Phi(f)(x) = f(x, \cdot) : Y \rightarrow V \quad y \mapsto f(x, y) \quad (14.2b)$$

Recall that the space of continuous functions on a compact space is equipped with the l^∞ -norm, and $C(Y, V)$ is complete since V is complete (Cor. 3.50).

Lemma 14.2. *The integral $\int_I \Phi(f)$, which is an element of $C(Y, V)$, is the function*

$$\int_I f(x, \cdot) dx : Y \rightarrow V \quad y \mapsto \int_I f(x, y) dx \quad (14.3)$$

In other words, for every $y \in Y$ we have

$$\left(\int_I \Phi(f) \right)(y) = \int_I f(x, y) dx \quad (14.4)$$

Consequently, the function $\int_I f(x, \cdot) dx$ is continuous.

It is easy to show that $\int_I f(x, \cdot) dx$ is continuous without assuming that Y is compact. See Exe. 14.8.

Proof. For each $y \in Y$, define linear map

$$\varphi_y : C(Y, V) \rightarrow V \quad g \mapsto g(y)$$

Then this linear map is clear bounded (with operator norm 1). Thus, by Thm. 13.16, we have

$$\left(\int_I \Phi(f)(x) dx \right)(y) = \varphi_y \left(\int_I \Phi(f)(x) dx \right) = \int_I \varphi_y(\Phi(f)(x)) dx = \int_I f(x, y) dx$$

□

Proof of Thm. 14.1. By Thm. 13.20, the integral operator $\int_J : C(J, V) \rightarrow V$ is a bounded linear map. Therefore, by Thm. 13.16 (and in particular (13.19)), we have a commutative diagram

$$\begin{array}{ccc} C(I, C(J, V)) & \xrightarrow{\int_J \circ} & C(I, V) \\ \int_I \downarrow & & \downarrow \int_I \\ C(J, V) & \xrightarrow{\int_J} & V \end{array}$$

where the top arrow is the map sending $\Phi(f)$ to $\int_J \circ \Phi(f)$, i.e., sending $x \mapsto f(x, \cdot)$ to $x \mapsto \int_J f(x, y) dy$. Thus, the direction $\rightarrow \downarrow$ sends $\Phi(f)$ to $\int_I \int_J f(x, y) dy dx$. By Lem. 14.2, the left downward arrow sends $\Phi(f)$ to the function $y \in J \mapsto \int_I f(x, y) dx$. So $\downarrow \rightarrow$ sends $\Phi(f)$ to $\int_J \int_I f(x, y) dx dy$. Thus, the commutativity of the above diagram proves Fubini's theorem. □

Definition 14.3. Let I_1, \dots, I_N be compact intervals in \mathbb{R} . Let $B = I_1 \times \dots \times I_N$ and $f \in C(B, V)$. We define the **Riemann integral** of f to be

$$\int_B f = \int_{I_1} \cdots \int_{I_N} f(x_1, \dots, x_N) dx_N \cdots dx_1$$

Then, by Fubini's theorem, for any bijection $\sigma : \{1, \dots, N\} \rightarrow \{1, \dots, N\}$ we have

$$\int_B f = \int_{I_{\sigma(1)}} \cdots \int_{I_{\sigma(N)}} f(x_1, \dots, x_N) dx_{\sigma(N)} \cdots dx_{\sigma(1)}$$

14.1.2 Commutativity of integrals and derivatives

Recall from Cor. 11.35 that $l^{1,\infty}(J, V)$ is a Banach space. So its closed linear subspace $C^1(J, V)$ (cf. Pb. 11.1) is a Banach space under the $l^{1,\infty}$ -norm $\|g\|_{1,\infty} = \|g\|_\infty + \|g'\|_\infty$.

Let $f : I \times J \rightarrow V$. Consider f as a map $\Psi(f) : I \rightarrow V^J$ sending x to

$$\Psi(f)(x) = f(x, \cdot) : J \rightarrow V \quad y \mapsto f(x, y) \quad (14.5)$$

Let ∂_J be the (partial) derivative with respect the variable $y \in J$. Clearly

$$\partial_J(\Psi(f)(x)) = \partial_J f(x, \cdot) \quad (14.6)$$

The linear map of derivative

$$\partial_J : C^1(J, V) \rightarrow C(J, V) \quad g \mapsto g' = \partial_J g \quad (14.7)$$

is clearly bounded (with operator norm ≤ 1).

Proposition 14.4. *Let X be a topological space. Let $f : X \times J \rightarrow V$, and define $\Psi(f) : X \rightarrow V^J$ by (14.5). Then the following are equivalent.*

(1) $\Psi(f)$ is an element of $C(X, C^1(J, V))$. In other words:

(1a) For each $x \in X$ we have $\Psi(f)(x) \in C^1(J, V)$.

(1b) The function $x \in X \mapsto \Psi(f)(x) \in C^1(J, V)$ is continuous.

(2) $\partial_J f$ exists everywhere on $X \times J$. Moreover, we have $f, \partial_J f \in C(X \times J, V)$.

Proof. (1a) means that the functions $y \mapsto f(x, y)$ and $y \mapsto \partial_J f(x, y)$ exist and are continuous. (1b) is equivalent to that the maps

$$\begin{aligned} x \in X &\mapsto \Psi(f)(x) = f(x, \cdot) \in C(J, V) \\ x \in X &\mapsto \partial_J \Psi(f)(x) = \partial_J f(x, \cdot) \in C(J, V) \end{aligned}$$

are continuous (under the l^∞ -norm). By Thm. 9.3, this is equivalent to that f and $\partial_J f$ are continuous maps $X \times J \rightarrow V$. So (1) \Leftrightarrow (2). \square

We return to the setting of $f : I \times J \rightarrow V$.

Lemma 14.5. *The integral $\int_I \Psi(f)$, which is an element of $C^1(J, V)$, is the function*

$$\int_I f(x, \cdot) dx : J \rightarrow V \quad y \mapsto \int_I f(x, y) dx \quad (14.8)$$

Consequently, the function $\int_I f(x, \cdot) dx$ is in $C^1(J, V)$.

Proof. This lemma can be proved in the same way as Lem. 14.2, using the fact that for every $y \in J$, the linear map $g \in C^1(J, V) \rightarrow g(y)$ is bounded. \square

Theorem 14.6. *Let $f : I \times J \rightarrow V$. Assume that $\partial_J f$ exists everywhere on $I \times J$. Assume moreover that $f, \partial_J f \in C(I \times J, V)$. Then for each $y \in J$, the LHS of (14.9) exists and equals the RHS of (14.9), where*

$$\partial_J \int_I f(x, y) dx = \int_I \partial_J f(x, y) dx \quad (14.9)$$

First proof. Again, by Thm. 13.16, we have a commutative diagram

$$\begin{array}{ccc} C(I, C^1(J, V)) & \xrightarrow{\partial_J \circ} & C(I, C(J, V)) \\ \downarrow \wr_I & & \downarrow \wr_I \\ C^1(J, V) & \xrightarrow{\partial_J} & C(J, V) \end{array}$$

By Prop. 14.4, $\Psi(f)$ is an element of $C(I, C^1(J, V))$. The map $\Psi(f) : I \rightarrow C^1(J, V)$, composed with ∂_J , gives $x \in I \mapsto \partial_J f(x, \cdot)$. By Lem. 14.2, the direction $\rightarrow \downarrow$ sends $\Psi(f)$ to $\int_I \partial_J f(x, \cdot) dx$. By Lem. 14.5, $\int_I \Psi(f)$ equals $\int_I f(x, \cdot)$. In particular, $\int_I f(x, \cdot)$ is a C^1 -function. So $\downarrow \rightarrow$ sends $\Psi(f)$ to $\partial_J \int_I f(x, \cdot) dx$. This finishes the proof. \square

Second proof. Fix any $y \in J$. In view of Cor. 13.21, it suffices to prove that the limit of the net of functions $(\varphi_p)_{p \in J \setminus \{y\}}$ from I to V converges uniformly to $\partial_J f(\cdot, y)$ under $\lim_{p \rightarrow y}$, where

$$\varphi_p(x) = \frac{f(x, p) - f(x, y)}{p - y}$$

By Rem. 12.34, we have

$$\|\varphi_p(x) - \partial_J f(x, y)\| \leq A(x, p) := \sup_{q \in [p, y] \cup [y, p]} \|\partial_J f(x, q) - \partial_J f(x, y)\|$$

Since $\partial_J f$ is continuous, it can be viewed as a continuous map $J \rightarrow C(I, V)$ by Thm. 9.3. Thus, for every $\varepsilon > 0$ there exists $\delta > 0$ such that for every $p \in J$ satisfying $|p - y| \leq \delta$, we have $\sup_{x \in I} \|\partial_J f(x, q) - \partial_J f(x, y)\| \leq \varepsilon$ for all $q \in [p, y] \cup [y, p]$, and hence $\sup_{x \in I} A(x, p) \leq \varepsilon$. This proves that $A(\cdot, p)$ converges uniformly to 0 (as a net of functions $I \rightarrow \mathbb{R}$) as $p \rightarrow y$, finishing the proof. \square

14.1.3 Commutativity of partial derivatives

We write $\partial_I f(x, y)$ as $\partial_1 f(x, y)$ and $\partial_J f(x, y)$ as $\partial_2 f(x, y)$. In the following, we use Thm. 14.6 to give a new proof of a slightly weaker version of Thm. 12.35 on the commutativity of ∂_1 and ∂_2 . The idea is as follows. Suppose we know that A, B are linear operators on a vector space such that A is invertible and $A^{-1}B = BA^{-1}$. Then one deduces $A^{-1}BA = BA^{-1}A = B$ and hence $BA = AA^{-1}BA = AB$. Now, Thm. 14.6 says that ∂_J commutes with \int_I , the inverse of ∂_I (in a vague sense). So one can use a similar algebraic argument to prove that ∂_J commutes with ∂_I .

Theorem 14.7. *Let $f : I \times J \rightarrow V$ be a function such that $\partial_1 f, \partial_2 f, \partial_2 \partial_1 f$ exist and are continuous on $I \times J$. Then $\partial_1 \partial_2 f$ exists on $I \times J$ and equals $\partial_2 \partial_1 f$. (So $\partial_1 \partial_2 f$ is also continuous.)*

Thm. 14.7 is weaker than Thm. 12.35 in that we assume $\partial_1 f, \partial_2 f$ to be continuous. Indeed, as we shall see in the proof, the continuity of $\partial_2 f$ is not used. However, in concrete examples, it is fairly easy to check the continuity of $\partial_1 f, \partial_2 f$.

Proof. Let $F(x, y) = \int_a^x \partial_2 \partial_1 f(u, y) du$, which can be defined because $\partial_2 \partial_1 f$ is continuous. By FTC, we have $\partial_1 F = \partial_2 \partial_1 f$. On the other hand, by Thm. 14.6 and the continuity of $\partial_1 f, \partial_2 \partial_1 f$, we have

$$F(x, y) = \partial_2 \int_a^x \partial_1 f(u, y) du = \partial_2 (f(x, y) - f(a, y))$$

Therefore $\partial_1 \partial_2 f$ exists and equals $\partial_1 F = \partial_2 \partial_1 f$. □

Exercise 14.8. Let Y be a topological space. Let $f \in C(I \times Y, V)$. Prove that the following function is continuous:

$$I \times Y \rightarrow V \quad (x, y) \mapsto \int_a^x f(u, y) du \quad (14.10)$$

Exercise 14.9. Use Fubini's Thm 14.1 to prove Thm. 14.6.

14.2 Lebesgue's criterion for Riemann integrability

Fix $I = [a, b]$ where $-\infty < a < b < +\infty$. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. The goal of this section is to prove:

Theorem 14.10 (Lebesgue's criterion). *Let $f : I \rightarrow V$. Then the following are equivalent.*

- (1) f is strongly Riemann integrable.
- (2) f is bounded (i.e. $\|f\|_{l^\infty} < +\infty$). Moreover, the set of discontinuities

$$\{x \in I : f \text{ is not continuous at } x\} \quad (14.11)$$

is a null set.

Definition 14.11. A subset E of \mathbb{R} is called a **(Lebesgue) null set** (or a set of **(Lebesgue) measure zero**) if for every $\varepsilon > 0$ there exist countably many closed intervals I_1, I_2, \dots such that $E \subset \bigcup_i I_i$, and that $\sum_i |I_i| < \varepsilon$. Here, $|I_i|$ is the length of I_i .

The word “countably many” can be omitted, because the sum of uncountably many strictly positive reals numbers must be $+\infty$ due to Pb. 5.3.

Remark 14.12. Covering E by open intervals instead of closed ones does not change the definition of null sets. This is because any open/closed interval can be stretched by a factor of $1 + \delta$ to a larger closed/open interval, where δ is any given positive number.

Proposition 14.13. *A countable union of null subsets of \mathbb{R} is a null set.*

Proof. If $E = E_1 \cup E_2 \cup \cdots$ where each E_i is a null set, then for each ε , E_i can be covered by countably many closed intervals of total length $< 2^{-i}\varepsilon$. So E can be covered by countably many closed intervals of total length $< \varepsilon$. \square

Example 14.14. Every interval with at least two points is not a null set.

Proof. Since every such interval contains a closed interval with at least two points, it suffices to prove that the latter is not null. Thus, let us prove that I is not null. Suppose I is covered by some open intervals. Then, since I is compact, I is covered by finitely many of these open intervals, say U_1, \dots, U_n . It is easy to see that $\sum_{i=1}^n |U_i| \geq |I| = b - a$. (For example, let $f = \sum_i \chi_{U_i}$. Then $f \geq \chi_I$. So $\sum_i |U_i| = \sum_i \int \chi_{U_i} = \int f \geq \int \chi_I = b - a$.) \square

Before proving Lebesgue's criterion, let us first see some useful applications. Recall that if $V = \mathbb{R}^N$ then Riemann integrability is equivalent to strong Riemann integrability (Thm. 13.13).

Corollary 14.15. *Let $f \in \mathcal{R}(I, \mathbb{R}^n)$. Let Ω be a subset of \mathbb{R}^n containing $f(I)$. Let $g \in C(\Omega, \mathbb{R}^m)$ such that $\|g\|_\infty < +\infty$. Then $g \circ f \in \mathcal{R}(I, \mathbb{R}^m)$*

Note that if Ω is compact, we automatically have $\|g\|_\infty < +\infty$.

Proof. Clearly $g \circ f$ is bounded. The set of discontinuities of $g \circ f$ is null since it is a subset of the set of discontinuities of f , where the latter is a null set. \square

Corollary 14.16. *Let $f \in \mathcal{R}(I, \mathbb{R}^{m \times n})$ and $g \in \mathcal{R}(I, \mathbb{R}^{n \times k})$. Then $fg \in \mathcal{R}(I, \mathbb{R}^{m \times k})$.*

Proof. This is immediate from Lebesgue's criterion. \square

14.2.1 Proof of Lebesgue's criterion

The first step of proving Lebesgue's criterion is to express the set of discontinuities by the oscillation.

Definition 14.17. Let X be a topological space. Let Y be a metric space. The **oscillation** of a function $f : X \rightarrow Y$ at $x \in X$ is defined to be

$$\omega(f, x) = \inf_{U \in \text{Nbhd}_X(x)} \text{diam}(f(U))$$

Proposition 14.18. *Let X be a topological space, let Y be a metric space, and let $f : X \rightarrow Y$. Then f is continuous at $x \in X$ iff $\omega(f, x) = 0$.*

Proof. Assume that f is continuous at x . Then for every $\varepsilon > 0$, there exists $U \in \text{Nbh}(x)$ such that $d(f(p), f(x)) < \varepsilon/2$ for every $p \in U$. Then clearly $\text{diam}(f(U)) \leq \varepsilon$. So $\omega(f, x) \leq \varepsilon$. Since $\varepsilon > 0$ is arbitrary, we get $\omega(f, x) = 0$.

Conversely, suppose $\omega(f, x) = 0$. Then for every $\varepsilon > 0$ there exists $U \in \text{Nbh}(x)$ such that $\text{diam}(f(U)) < \varepsilon$. So for every $p \in U$ we have $d(f(p), f(x)) < \varepsilon$. \square

Proof of Thm. 14.10, part 1. Let us prove (1) \Rightarrow (2). Assume that f is strongly Riemann integrable. Choose any $\varepsilon > 0$. Let us prove that

$$\Omega_\varepsilon(f) = \{x \in I : \omega(f, x) \geq \varepsilon\} \quad (14.12)$$

is a null set. Then the set of discontinuities, which is $\bigcup_{n \in \mathbb{Z}_+} \Omega_{1/n}(f)$, is a null set by Prop. 14.13.

Since $\inf_{\sigma \in \mathcal{P}(I)} \omega(f, \sigma) = 0$, for every $\delta > 0$, there exists $\sigma = \{a_0 < \dots < a_n\} \in \mathcal{P}(I)$ such that, with $I_i = [a_{i-1}, a_i]$, we have

$$\sum_{i=1}^n \text{diam}(f(I_i)) \cdot |I_i| < \delta\varepsilon \quad (14.13)$$

Note that if $x \in I \setminus \sigma$ is in some I_i where $\text{diam}(f(I_i)) < \varepsilon$, then clearly $\omega(f, x) < \varepsilon$. Thus, if $\omega(f, x) \geq \varepsilon$ (i.e., if $x \in \Omega_\varepsilon(f)$), then either $x \in \sigma$, or $x \in I_i$ for some I_i such that $\text{diam}(f(I_i)) \geq \varepsilon$. We conclude

$$\Omega_\varepsilon(f) \subset \{a_0, \dots, a_n\} \cup \left(\bigcup_{k \in K} I_k \right)$$

where $K = \{1 \leq k \leq n : \text{diam}(f(I_k)) \geq \varepsilon\}$. Clearly $\{a_0, \dots, a_n\}$ can be covered by some intervals with total length $< \delta$. But (14.13) implies that $\sum_{k \in K} \varepsilon |I_k| < \delta\varepsilon$ and hence $\sum_{k \in K} |I_k| < \delta$. So $\Omega_\varepsilon(f)$ can be covered by intervals with total length $< 2\delta$ for every $\delta > 0$. Thus $\Omega_\varepsilon(f)$ is a null set. \square

To prove the other direction, we need some preparation.

Lemma 14.19. *Let $f : X \rightarrow Y$ where X is a topological space and Y is a metric space. Then for every $\varepsilon > 0$, $\Omega_\varepsilon(f) = \{x \in X : \omega(f, x) \geq \varepsilon\}$ is a closed subset of X .*

Proof. Let us prove that each $x \in X \setminus \Omega_\varepsilon(f)$ is an interior point. (Recall Prop. 77.43.) Indeed, since $\inf_{U \in \text{Nbh}(x)} \text{diam}(f(U)) < \varepsilon$, there exists $U \in \text{Nbh}(x)$ such that $\text{diam}(f(U)) < \varepsilon$. Then for each $p \in U$ we have $\inf_{V \in \text{Nbh}(p)} \text{diam}(f(V)) < \varepsilon$ since $U \in \text{Nbh}(p)$. So $U \subset X \setminus \Omega_\varepsilon(f)$. \square

Lemma 14.20. *Let $\varepsilon > 0$. Suppose that for every $x \in I$ we have $\omega(f, x) < \varepsilon$. (Namely, suppose $\Omega_\varepsilon(f) = \emptyset$.) Then there exists a partition $I = I_1 \cup \dots \cup I_n$ satisfying $\text{diam}(f(I_i)) < \varepsilon$ for all i .*

Proof. For every $x \in I$, there exists $U_x \in \text{Nbh}_I(x)$ such that $\text{diam}(f(U_x)) < \varepsilon$. Choose $n \in \mathbb{Z}_+$ such that $1/n$ is a Lebesgue number of the open cover $\mathcal{U} = \{U_x : x \in I\}$ of I . (Recall Thm. 10.8.) Dividing I into $2n$ subintervals with the same length gives the desired partition. \square

Proof of Thm. 14.10, part 2. Let us prove (2) \Rightarrow (1). Suppose that $M = \|f\|_\infty$ is $< +\infty$, and that the set of discontinuities is a null set. Then for each $\varepsilon > 0$, $\Omega_\varepsilon(f)$ is a null set. By Lem. 14.19 and Heine-Borel, $\Omega_\varepsilon(f)$ is compact. Thus, for every $\delta > 0$, $\Omega_\varepsilon(f)$ can be covered by finitely many closed intervals with total length $< \delta$. Let Δ be the union of these closed intervals. Then $\Omega_\varepsilon(f) \subset \Delta$. Clearly, both Δ and $J = I \setminus \text{Int}(\Delta)$ can be written as disjoint unions of finitely many closed intervals, which are their connected components. And Δ has length $|\Delta| < \delta$.

Since $J \cap \Omega_\varepsilon(f) = \emptyset$, applying Lem. 14.20 to each of the components J_1, J_2, \dots of J , we see that J_i has a partition ϱ_i such that the oscillation of f (recall Def. 13.7) on each subinterval cut out by ϱ_i is $< \varepsilon$. Let $\sigma = \varrho_1 \cup \varrho_2 \cup \dots \cup \{a, b\}$, which is a partition of I . Then σ divides I into subintervals I_1, I_2, \dots such that either $I_j \subset J$ or $I_j \subset \Delta$.

- If $I_j \subset J$, then I_j belongs to a subinterval cut out by one of $\varrho_1, \varrho_2, \dots$ in J_1, J_2, \dots . This implies $\text{diam}(f(I_j)) < \varepsilon$ by the construction of $\varrho_1, \varrho_2, \dots$.
- If $I_j \subset \Delta$, then I_j is a component of Δ . We have $\text{diam}(f(I_j)) \leq 2M$. Moreover, the total length of such I_j is equal to $|\Delta|$, which is $< \delta$.

From the discussion of these two cases, we see that

$$\omega(f, \sigma) = \sum_j \text{diam}(f(I_j)) \cdot |I_j| \leq \varepsilon \cdot (b - a) + 2M \cdot \delta$$

Since $b - a$ and M are fixed numbers and ε, δ are arbitrary, we see that $\inf_\sigma \omega(f, \sigma) = 0$. So f is strongly Riemann integrable. \square

14.3 Improper integrals

In this section, all intervals in \mathbb{R} are assumed to contain at least two points. Let I be an interval in \mathbb{R} with $a = \inf I$ and $b = \sup I$. So $-\infty \leq a < b \leq +\infty$. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Definition 14.21. We define

$$\mathcal{R}(I, V) = \{f \in V^I : f|_J \in \mathcal{R}(J, V) \text{ for every compact interval } J \subset I\}$$

Define the **improper integral**

$$\int_I f \equiv \int_a^b f \stackrel{\text{def}}{=} \lim_{\substack{u \rightarrow a \\ v \rightarrow b}} \int_u^v f = \lim_J \int_J f \quad (14.14)$$

Here, the last limit is over the directed set $\{\text{compact intervals in } I\}$ with preorder “ \subset ”. If the above limit exists, we say that $\int_I f$ **exists** or **converges**.

When $f \in \mathcal{R}(I, \mathbb{R})$ and takes values in $\mathbb{R}_{\geq 0}$, we write $f \in \mathcal{R}(I, \mathbb{R}_{\geq 0})$. Then $\int_I f$ clearly exists in $\overline{\mathbb{R}}_{\geq 0}$. We write $\int_I f < +\infty$ if $\int_I f$ converges in \mathbb{R} . \square

In the case that a or b is in I , when taking the limit over $u \rightarrow a$ and $v \rightarrow b$ in (14.14), it is immaterial whether u, v can take values a, b or not, due to the following easy observation:

Lemma 14.22. *Let $f \in \mathcal{R}(I, V)$. If $I = [a, b]$, then the meanings of $\mathcal{R}(I, V)$ and $\int_I f$ are the same as before. If $I = [a, b)$ resp. $I = (a, b]$, then*

$$\int_I f = \lim_{v \rightarrow b} \int_a^v f \quad \text{resp.} \quad \int_I f = \lim_{u \rightarrow a} \int_u^b f$$

where the convergence of the LHS is equivalent to that of the RHS.

Proof. Assume $I = [a, b]$. Then I is a compact interval. The new and old meanings of $\mathcal{R}(I, V)$ are the same by Prop. 13.23. Let $f \in \mathcal{R}(I, V)$. Then by Thm. 13.20, we have $\|f\|_\infty < +\infty$. If $a \leq u < v \leq b$, then Thm. 13.20 and Prop. 13.23 show that

$$\left\| \int_a^b f - \int_u^v f \right\| = \left\| \int_a^u f + \int_v^b f \right\| \leq \|f\|_\infty \cdot ((u - a) + (b - v))$$

which converges to 0 as $u \rightarrow a$ and $v \rightarrow b$, whether u, v take values a, b or not.

Similarly, if $I = [a, b)$, then since f is Riemann integrable on the compact subinterval $J = [a, (a + b)/2]$, we have $M := \|f|_J\|_\infty < +\infty$. This implies that for all u, v such that $a \leq u < v < b$ and $u \leq (a + b)/2$,

$$\left\| \int_a^v f - \int_u^v f \right\| = \left\| \int_a^u f \right\| \leq M(u - a)$$

which converges to 0 as $u \rightarrow a$ and $v \rightarrow b$. So $(\int_a^v f)_{u,v}$ and $(\int_u^v f)_{u,v}$ are Cauchy-equivalent nets. So their convergences and values are equivalent. The case $I = (a, b]$ is similar. \square

Remark 14.23. Let $f \in \mathcal{R}(I, V)$. The Cauchy condition for the convergence of $\int_a^b f$ is easy to describe. In view of $\int_u^v - \int_{u'}^{v'} = \int_u^{u'} + \int_v^{v'}$ (Prop. 13.23), we have:

- For every $\varepsilon > 0$, there exist $u_0 < v_0$ in I such that for all $u, u', v, v' \in I$ satisfying $a \leq u, u' < u_0$ and $v_0 < v, v' \leq b$ we have

$$\left\| \int_u^{u'} f \right\| < \varepsilon \quad \left\| \int_v^{v'} f \right\| < \varepsilon$$

Definition 14.24. Let $f \in \mathcal{R}(I, V)$. We say that $\int_I f$ **converges absolutely** (or that f is **absolutely integrable on I**) if there exists $g \in \mathcal{R}(I, \mathbb{R})$ such that $|f| \leq g$ (i.e., $\|f(x)\| \leq g(x)$ for all $x \in I$, in particular $g(x) \geq 0$) and that $\int_I g < +\infty$. We let

$$\mathcal{R}^1(I, V) = \{f \in \mathcal{R}(I, V) : \int_I f \text{ converges absolutely}\} \quad (14.15)$$

which is clearly a linear subspace of V^I . By the Cauchy condition in Rem. 14.23, it is clear that $\int_I f$ converges if $\int_I f$ converges absolutely. Though $\mathbb{R}_{\geq 0}$ is not a Banach space, we still write

$$\mathcal{R}^1(I, \mathbb{R}_{\geq 0}) = \{f \in \mathcal{R}(I, \mathbb{R}_{\geq 0}) : \int_I f \text{ converges absolutely}\}$$

which is clearly the set of all $f \in \mathcal{R}(I, \mathbb{R}_{\geq 0})$ satisfying $\int_I f < +\infty$.

The superscript 1 of \mathcal{R}^1 has a similar meaning as that of l^1 , but is different from that of C^1 .

Remark 14.25. Assume that $f : I \rightarrow V$ is strongly integrable on each compact subinterval of I . (This is the case, for example, when $f \in C(I, V)$, or when $f \in \mathcal{R}(I, V)$ and $V = \mathbb{F}^N$.) Then $|f| : x \in I \mapsto \|f(x)\| \in \mathbb{R}_{\geq 0}$ is an element of $\mathcal{R}(I, \mathbb{R}_{\geq 0})$ by Cor. 13.19. Thus, in this case,

$$f \in \mathcal{R}^1(I, V) \quad \Longleftrightarrow \quad \int_I |f| < +\infty$$

Example 14.26. We have

$$\int_1^{+\infty} x^{-2} dx = \lim_{v \rightarrow +\infty} \int_1^v x^{-2} dx = \lim_{v \rightarrow +\infty} (-x^{-1}) \Big|_1^v = 1 < +\infty$$

Therefore $\int_1^{+\infty} \frac{e^{ix}}{x^2} dx$ converges absolutely, and hence converges.

The following proposition generalizes Prop. 13.18.

Proposition 14.27. Let $f \in \mathcal{R}^1(I, V)$ and $g \in \mathcal{R}^1(I, \mathbb{R}_{\geq 0})$ such that $|f| \leq g$. Then $\left\| \int_I f \right\| \leq \int_I g$.

Proof. Apply the limit over $u \rightarrow a, v \rightarrow b$ to $\left\| \int_u^v f \right\| \leq \int_u^v g$. □

The next proposition shows that improper integrals are helpful for studying series:

Proposition 14.28. Let $f \in \mathcal{R}([1, +\infty), \mathbb{R}_{\geq 0})$ be decreasing. Then we have

$$\int_1^{+\infty} f < +\infty \quad \Longleftrightarrow \quad \sum_{n=1}^{+\infty} f(n) < +\infty \quad (14.16)$$

Proof. Since f is decreasing, we clearly have $g \leq f \leq h$ where g, h are defined by the series in $l^\infty([0, +\infty), \mathbb{R})$:

$$g = \sum_{n=1}^{+\infty} f(n+1) \cdot \chi_{[n, n+1)} \quad h = \sum_{n=1}^{+\infty} f(n) \cdot \chi_{[n, n+1)}$$

One computes easily that $\int_1^{+\infty} g = \sum_{n=2}^{+\infty} f(n)$ and $\int_1^{+\infty} h = \sum_{n=1}^{+\infty} f(n)$ in $\overline{\mathbb{R}}_{\geq 0}$. Thus

$$\sum_{n=2}^{+\infty} f(n) \leq \int_1^{+\infty} f \leq \sum_{n=1}^{+\infty} f(n)$$

The proposition follows easily. □

Example 14.29. Let $s > 0$. The function $f : [2, +\infty) \rightarrow +\infty$ defined by $f(x) = \frac{1}{x(\log x)^s}$ is decreasing, and

$$\int_2^x f = \begin{cases} (1-x)^{-1}((\log x)^{1-s} - (\log 2)^{1-s}) & \text{if } s \neq 1 \\ \log(\log x) - \log(\log 2) & \text{if } s = 1 \end{cases}$$

So $\sum_{n=2}^{\infty} f(n) < +\infty$ iff $\int_2^{+\infty} f < +\infty$ iff $s > 1$.

14.4 Commutativity of improper integrals and other limit processes

In this section, all intervals in \mathbb{R} are assumed to contain at least two points. Let I be an interval in \mathbb{R} with $a = \inf I$ and $b = \sup I$. Let $J = [c, d]$ be a compact interval. Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

The goal of this section is to generalize the main results of Sec. 14.1 to improper integrals. Namely, we shall prove the commutativity of \int_I with \int_J and with ∂_J under reasonable assumptions. There are three ways to achieve this goal:

- We know that \int_I is the limit of integrals over compact intervals. Therefore, the problem is reduced to that of proving that $\lim_{u \rightarrow a, v \rightarrow b}$ can be moved inside in $\lim \int_J \int_u^v$ and in $\lim \partial_J \int_u^v$.
- We generalize Thm. 13.16 to improper integrals, and use this generalized version to prove the commutativity in a similar way as in Sec. 14.1.
- The commutativity of \int_I with ∂_J can also be studied by generalizing Cor. 13.21 to improper integrals, similar to the second proof of Thm. 14.6.

We will use the second approach because its proof is more conceptual and involves fewer technical calculations, thus making it easier for us to remember the conditions of the theorems to be proved. Nevertheless, we will also give the appropriate generalization of Cor. 13.21, which is helpful for future application. Recall Def. 14.24 for the meaning of \mathcal{R}^1 .

14.4.1 Commutativity of improper integrals and bounded linear maps

Theorem 14.30. *Let W be also a Banach space over \mathbb{F} . Let $T \in \mathcal{L}(V, W)$. Then for every $f \in \mathcal{R}^1(I, V)$ we have $T \circ f \in \mathcal{R}^1(I, W)$ and*

$$T\left(\int_a^b f\right) = \int_a^b T \circ f \quad (14.17)$$

In other words, we have a commutative diagram

$$\begin{array}{ccc} \mathcal{R}^1(I, V) & \xrightarrow{T \circ} & \mathcal{R}^1(I, W) \\ \downarrow \int_I & & \downarrow \int_I \\ V & \xrightarrow{T} & W \end{array} \quad (14.18)$$

Proof. By Thm. 13.16, $T \circ f$ is Riemann integrable on compact subintervals of I . Since $f \in \mathcal{R}^1$, there exists $g \in \mathcal{R}(I, \mathbb{R}_{\geq 0})$ such that $|f| \leq g$ and $\int_I g < +\infty$. Let $M = \|T\|$ be the operator norm, which is a finite number. By Rem. 10.24, for each $x \in I$ we have $\|T \circ f(x)\| \leq M\|f(x)\| \leq Mg(x)$, and hence $|T \circ f| \leq Mg$. This proves $T \circ f \in \mathcal{R}^1(I, W)$. In particular, the integrals of $f, T \circ f$ over I converge. Thus, by the continuity of T and the commutativity of T with \int_u^v (when $a < u < v < b$) due to Thm. 13.16, we have

$$T\left(\int_I f\right) = T\left(\lim_{\substack{u \rightarrow a \\ v \rightarrow b}} \int_u^v f\right) = \lim_{\substack{u \rightarrow a \\ v \rightarrow b}} T\left(\int_u^v f\right) = \lim_{\substack{u \rightarrow a \\ v \rightarrow b}} \int_u^v T \circ f = \int_I T \circ f$$

□

14.4.2 Fubini's theorem

Recall that $J = [c, d]$ is a compact interval but I is not necessarily compact.

Lemma 14.31. *Lem. 14.2 holds verbatim to the current case that I is not necessarily compact.*

Proof. We can prove this general case in the same way as Lem. 14.2, using the commutativity of \int_I and the bounded map $g \in C(Y, V) \mapsto g(y) \in V$, which is available thanks to Thm. 14.30. □

Theorem 14.32 (Fubini's theorem for improper integrals). *Let $f \in C(I \times J, V)$. Assume that there exists $h \in \mathcal{R}^1(I, \mathbb{R}_{\geq 0})$ satisfying*

$$\|f(x, y)\| \leq h(x) \quad (\forall x \in I, y \in J) \quad (14.19)$$

Then the functions $\int_J f(\cdot, y) dy : I \rightarrow V$ and $\int_I f(x, \cdot) dx : J \rightarrow V$ are continuous, and the equation

$$\int_I \left(\int_J f(x, y) dy \right) dx = \int_J \left(\int_I f(x, y) dx \right) dy \quad (14.20)$$

holds where the integral over I on the LHS converges absolutely.

Proof. Let $T : C(J, V) \rightarrow V$ be the bounded linear map \int_J . By Thm. 14.30, we have a commutative diagram

$$\begin{array}{ccc} \mathcal{R}^1(I, C(J, V)) & \xrightarrow{T \circ} & \mathcal{R}^1(I, V) \\ \int_I \downarrow & & \downarrow \int_I \\ C(J, V) & \xrightarrow{T} & V \end{array} \quad (14.21)$$

Since J is compact, by Thm. 9.3, we can view f as a continuous function $\Phi(f) : I \rightarrow C(J, V)$ sending x to $f(x, \cdot)$. Then (14.19) says that $\Phi(f) \leq g$. Since $g \in \mathcal{R}^1$, we conclude $\Phi(f) \in \mathcal{R}^1(I, C(J, V))$.

By Lem. 14.31, $\int_I \Phi(f)$ equals the function $\int_I f(x, \cdot) dx$. In particular, $\int_I f(x, \cdot) dx$ is continuous since $\int_I \Phi(f) \in C(J, V)$ by (14.21). The continuity of $\int_J f(\cdot, y) dy$ is similar, or is even easier because J is compact.

Clearly $T(\int_I \Phi(f))$ is $\int_J \int_I f$. By the top arrow of (14.21), $T \circ \Phi(f)$ belongs to $\mathcal{R}^1(I, V)$. Since $T \circ \Phi(f)$ is the function sending x to $\int_J f(x, \cdot) dy$, the integral of this function over I is absolutely convergent, and $\int_I T \circ \Phi(f) = \int_I \int_J f$. Thus, the commutativity of (14.21) proves (14.20). \square

The continuity of $\int_I f(x, \cdot) dx$ can be generalized: see Cor. 14.36.

14.4.3 Commutativity of improper integrals and partial derivatives

Lemma 14.33. *Lemma 14.5 holds verbatim to the current case that I is not necessarily compact.*

Proof. Again, this is proved in the same way as Lem. 14.2 by applying Thm. 14.30 to the bounded linear functional $g \in C^1(J, V) \rightarrow g(y)$ (where $y \in J$). \square

Theorem 14.34. *Let $f : I \times J \rightarrow V$. Assume that $\partial_J f$ exists everywhere on $I \times J$. Assume that $f, \partial_J f \in C(I \times J, V)$. Assume moreover that there exists $h \in \mathcal{R}^1(I, \mathbb{R}_{\geq 0})$ satisfying*

$$\|f(x, y)\| \leq h(x) \quad \text{and} \quad \|\partial_J f(x, y)\| \leq h(x) \quad (\forall x \in I, y \in J) \quad (14.22)$$

Then for each $y \in J$, the LHS of (14.23) exists and equals the RHS of (14.23), where

$$\partial_J \int_I f(x, y) dx = \int_I \partial_J f(x, y) dx \quad (14.23)$$

Proof. Let $T : C^1(J, V) \rightarrow C(J, V)$ be the bounded linear map ∂_J . By Thm. 14.30, we have a commutative diagram

$$\begin{array}{ccc} \mathcal{R}^1(I, C^1(J, V)) & \xrightarrow{T \circ} & \mathcal{R}^1(I, C(J, V)) \\ \int_I \downarrow & & \downarrow \int_I \\ C^1(J, V) & \xrightarrow{T} & C(J, V) \end{array} \quad (14.24)$$

Define $\Psi(f) : X \rightarrow V^J$ sending x to $f(x, \cdot)$. By Prop. 14.4, $\Psi(f)$ belongs to $C(I, C^1(J, V))$. By (14.22), $\Psi(f)$ belongs to $\mathcal{R}^1(I, C^1(J, V))$. As in the first proof of Thm. 14.6, one can use Lem. 14.31 and 14.33 (the improper version of Lem. 14.2 and 14.5) to show that $\int_I T \circ \Psi(f) = T \int_I \Psi(f)$ (which is a consequence of the commutativity of (14.24)) implies (14.23). \square

14.4.4 Commutativity of improper integrals and net limits

Theorem 14.35. *Let $(f_\alpha)_{\alpha \in \mathcal{J}}$ be a net in $\mathcal{R}^1(I, V)$. Let $f \in V^I$. Assume that the following conditions are true:*

- (1) *On every compact subinterval of I , the net (f_α) converges uniformly to f .*
- (2) *There exists $g \in \mathcal{R}^1(I, \mathbb{R}_{\geq 0})$ such that $|f_\alpha| \leq g$ for all $\alpha \in \mathcal{J}$.*

Then $f \in \mathcal{R}^1(I, V)$, and $\int_I f = \lim_{\alpha \in \mathcal{J}} \int_I f_\alpha$.

Proof. By Cor. 13.21, $f \in \mathcal{R}(I, V)$. Since (f_α) converges pointwise to f , we clearly have $|f| \leq g$. So $f \in \mathcal{R}^1(I, V)$. Choose any $\varepsilon > 0$. Since $\lim_{u \rightarrow a, v \rightarrow b} \int_I g$ converges, there exists u, v such that $a < u < v < b$ and

$$\int_a^u g + \int_v^b g = \int_I g - \int_u^v g < \varepsilon$$

Thus, by Prop. 14.27, for each α we have $\|\int_a^u f_\alpha\| + \|\int_v^b f_\alpha\| < \varepsilon$ and $\|\int_a^u f\| + \|\int_v^b f\| < \varepsilon$. Since f_α converges uniformly to f on $[u, v]$, by Cor. 13.21, we get $\lim_\alpha \|\int_u^v f_\alpha - \int_u^v f\| = 0$. Thus

$$\begin{aligned} \left\| \int_I f - \int_I f_\alpha \right\| &= \left\| \int_a^u f + \int_v^b f - \int_a^u f_\alpha - \int_v^b f_\alpha + \int_u^v (f - f_\alpha) \right\| \\ &\leq 2\varepsilon + \left\| \int_u^v (f - f_\alpha) \right\| \end{aligned}$$

where the \limsup_α of the RHS is 2ε . Thus $\|\int_I f - \int_I f_\alpha\|$ converges to 0 under \limsup_α , and hence under \lim_α . \square

It is a good practice to prove Thm. 14.34 using Thm. 14.35. (See Pb. 14.2.)

Corollary 14.36. *Let Y be a topological space. Let $f \in C(I \times Y, V)$. Assume that there exists $h \in \mathcal{R}^1(I, \mathbb{R}_{\geq 0})$ such that*

$$\|f(x, y)\| \leq h(x) \quad (\forall x \in I, y \in Y) \quad (14.25)$$

Then the map $\int_I f(x, \cdot) dx$ (sending $y \in Y$ to $\int_I f(x, y) dx$) is continuous.

Proof. By Def. 7.56-(1), we need to prove that for every net (y_α) in Y converging to y , we have $\int_I f(x, y)dx = \lim_\alpha \int_I f(x, y_\alpha)dx$. By Thm. 14.35, it suffices to prove that $\lim_\alpha f(\cdot, y_\alpha)$ converges uniformly on any compact subinterval $[u, v] \subset I$ to $f(\cdot, y)$. This is true because, by Thm. 9.3, the restriction of f to $[u, v] \times Y$ can be viewed as an element of $C(Y, C([u, v], V))$. \square

Example 14.37. Compute $F(t) = \int_0^{+\infty} e^{-tx} \cdot \frac{\sin x}{x} dx$ for all $t > 0$.

Solution. We first compute $F'(t)$. Choose any $\delta > 0$. Then for any $t \geq \delta$, the norms of $e^{-tx} \frac{\sin x}{x}$ and $\partial_t(e^{-tx} \frac{\sin x}{x}) = -e^{-tx} \sin x$ are both bounded by $e^{-\delta x}$, where the latter is absolutely integrable since $\int_0^{+\infty} e^{-\delta x} dx = \delta^{-1} < +\infty$. Thus, by Thm. 14.34, we have

$$\begin{aligned} F'(t) &= \int_0^{+\infty} -e^{-tx} \sin x dx = \int_0^{+\infty} \frac{e^{(-t+i)x} - e^{(-t-i)x}}{2i} dx \\ &= \frac{t \sin x + \cos x}{1 + t^2} e^{-tx} \Big|_{x=0}^{+\infty} = -\frac{1}{1 + t^2} \end{aligned}$$

for all $t \geq \delta$ and $\delta > 0$, and hence for all $t > 0$. Therefore $F(t) = C - \arctan t$ for some $C \in \mathbb{R}$. Let us determine C using $C = \lim_{t \rightarrow +\infty} F(t) + \frac{\pi}{2}$.

To compute $\lim_{t \rightarrow +\infty} F(t)$, it suffices to assume $t \geq 1$. Then $|e^{-tx} \frac{\sin x}{x}| \leq e^{-x}$ where $\int_0^{+\infty} e^{-x} < +\infty$. Moreover, on every compact interval $[a, b]$ in $(0, +\infty)$ (where $0 < a < b < +\infty$), $\lim_{t \rightarrow +\infty} e^{-tx} \frac{\sin x}{x}$ converges uniformly to 0 since $|e^{-tx} \frac{\sin x}{x}| \leq e^{-ta}$. Thus, the assumptions in Thm. 14.35 are satisfied, and hence

$$\lim_{t \rightarrow +\infty} F(t) = \int_0^{+\infty} \lim_{t \rightarrow +\infty} e^{-tx} \cdot \frac{\sin x}{x} dx = 0$$

This proves $C = \frac{\pi}{2}$, and hence $F(t) = \frac{\pi}{2} - \arctan t$. \square

14.5 Convolutions and smooth/polynomial approximation

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Definition 14.38. Let X be a topological space. The **support** of a function $f \in V^X$ is defined to be the closure

$$\text{Supp}(f) = \overline{\{x \in X : f(x) \neq 0\}}$$

Define $C_c(X, V)$ to be the set of continuous functions with **compact support**

$$C_c(X, V) = \{f \in C(X, V) : \text{Supp}(f) \text{ is compact}\}$$

Unless otherwise stated, $C_c(X, V)$ is equipped with the l^∞ -norm.

14.5.1 Convolutions and approximation of identity

A goal of this section is to show that the elements of $C_c(\mathbb{R}, V)$ can be approximated by smooth functions with compact supports, i.e., elements in

$$C_c^\infty(\mathbb{R}, V) = C^\infty(\mathbb{R}, V) \cap C_c(\mathbb{R}, V)$$

Indeed, we will do more. We shall prove the celebrated **Weierstrass approximation theorem**, which implies that elements in $C_c(\mathbb{R}, V)$ can be approximated uniformly by polynomials on compact intervals. The proof we will give is also due to Weierstrass, which relies on an important construction called convolution: If $f : \mathbb{R} \rightarrow V$ and $g : \mathbb{R} \rightarrow \mathbb{F}$, then their **convolution** is a functions $f * g : \mathbb{R} \rightarrow V$ defined by

$$(f * g)(x) \equiv (g * f)(x) = \int_{\mathbb{R}} f(x - y)g(y)dy \quad (14.26a)$$

whenever the above integral converges for every $x \in \mathbb{R}$. Taking $y = x - t$, we get $\int_u^v f(x - y)g(y)dy = -\int_{x-u}^{x-v} f(t)g(x - t)dt = \int_{x-v}^{x-u} f(t)g(x - t)dt$. Letting $u \rightarrow -\infty, v \rightarrow +\infty$, we get

$$(f * g)(x) = \int_{\mathbb{R}} f(y)g(x - y)dy \quad (14.26b)$$

The main idea of doing approximation via convolutions is as follows. Suppose that g is smooth, then by (14.26b), one should expect that $(f * g)^{(n)}(x) = \int_{\mathbb{R}} f(y)(\partial_x)^n g(x - y)dy = \int_{\mathbb{R}} f(y)g^{(n)}(x - y)dy$ to be true. Thus $f * g$ is expected to be smooth. Moreover, if g can be approximated by polynomials, for example, if $g(x) = \sum a_n x^n$ on \mathbb{R} , then it is expected that $f * g$ can be approximated by $f * g_n$ where $g_n(x) = a_n x^n$, and it is easy to see that $f * g_n = a_n \int_{\mathbb{R}} f(y)(x - y)^n dy$ is a polynomial of x .

To summarize, one advantage of convolution is that whenever g has a good property, the same is in general true for $f * g$. Another key property of convolution is that f can be approximated by $f * g$ in some sense. The meaning of “approximation” will depend on the analytic property of f , e.g. whether f is continuous, continuous with compact support, or only integrable. In this section, we will only be interested in the case that $f \in C_c(\mathbb{R}, V)$. In this case, the integrals in (14.26) are actually over compact intervals, which makes our lives easier.

We shall show that $f \in C_c(\mathbb{R}, V)$ can be approximated uniformly by $f * g$. More precisely, we shall show that for every absolutely convergent $g \in C(\mathbb{R}, \mathbb{R}_{\geq 0})$ satisfying $\int_{\mathbb{R}} g = 1$, if we define $g_\varepsilon \in C(\mathbb{R}, \mathbb{R})$ (where $\varepsilon \in \mathbb{R}_{>0}$) by

$$g_\varepsilon(x) = \frac{1}{\varepsilon} g\left(\frac{x}{\varepsilon}\right) \quad (14.27)$$

then $(f * g_\varepsilon)$ converges uniformly to f as $\varepsilon \rightarrow 0$. This method is extremely useful and is used widely in analysis. (The assumption that $g \geq 0$ is not necessary. We assume $g \geq 0$ only for simplifying discussions.)

Lemma 14.39. Choose $g \in C(\mathbb{R}, \mathbb{R}_{\geq 0})$ satisfying $\int_{\mathbb{R}} g = 1$, and define g_ε by (14.27). Then $\int_{\mathbb{R}} g_\varepsilon = 1$ for each $\varepsilon > 0$. Moreover, for every $\delta > 0$ we have

$$\lim_{\varepsilon \rightarrow 0} \int_{\delta}^{+\infty} g_\varepsilon = \lim_{\varepsilon \rightarrow 0} \int_{-\infty}^{-\delta} g_\varepsilon = 0 \quad (14.28)$$

Proof. By the change of variable formula we have $\int_u^v \varepsilon^{-1} g(\varepsilon^{-1}x) dx = \int_{u/\varepsilon}^{v/\varepsilon} g(y) dy$. This gives $\int_{\mathbb{R}} g_\varepsilon = 1$. Another change of variable shows $\int_{\delta}^{+\infty} g_\varepsilon = \int_{\delta/\varepsilon}^{+\infty} g = \int_0^{+\infty} g - \int_0^{\delta/\varepsilon} g$, which clearly converges to 0 as $\varepsilon \rightarrow 0$. This proves the first half of (14.28). The second half is similar. \square

Proposition 14.40. Let $f \in C_c(\mathbb{R}, V)$. Choose $g \in C(\mathbb{R}, \mathbb{R}_{\geq 0})$ satisfying $\int_{\mathbb{R}} g = 1$, and define g_ε by (14.27) for each $\varepsilon > 0$. Then $(f * g_\varepsilon)$ converges uniformly on \mathbb{R} to f as $\varepsilon \rightarrow 0$.

In other words, the convolution operator $f \mapsto f * g_\varepsilon$ converges pointwise to the identity map when $\varepsilon \rightarrow 0$.

Proof. Let $M = \|f\|_\infty$, which is $< +\infty$. Since $\int_{\mathbb{R}} g_\varepsilon = 1$, for each $x \in \mathbb{R}$ we have $\int_{\mathbb{R}} f(x) g_\varepsilon(y) dy = f(x)$. Thus

$$\begin{aligned} \|(f * g_\varepsilon)(x) - f(x)\| &= \left\| \int_{\mathbb{R}} (f(x-y) - f(x)) g_\varepsilon(y) dy \right\| \\ &\leq \int_{\mathbb{R}} \|f(x-y) - f(x)\| \cdot g_\varepsilon(y) dy \end{aligned} \quad (14.29)$$

By Thm. 10.7 and the compactness of $\text{Supp}(f)$, f is uniformly continuous on \mathbb{R} . Therefore, for every $e > 0$, there exists $0 < \delta < 1$ such that $\|f(x-y) - f(x)\| \leq e$ for all $x \in \mathbb{R}$ and $y \in (-\delta, \delta)$. Thus, if we let $J_\delta = \mathbb{R} \setminus (-\delta, \delta)$, then

$$\begin{aligned} (14.29) &\leq \int_{J_\delta} \|f(x-y) - f(x)\| \cdot g_\varepsilon(y) dy + e \cdot \int_{-\delta}^{\delta} g_\varepsilon(y) dy \\ &\leq 2M \cdot \int_{J_\delta} g_\varepsilon(y) dy + e \end{aligned}$$

which converges to e under $\limsup_{\varepsilon \rightarrow 0}$ by Lem. 14.39. Since e is arbitrary, we conclude that $\lim_{\varepsilon \rightarrow 0} (14.29) = 0$. \square

Remark 14.41. The uniform continuity of a function $f : \mathbb{R} \rightarrow V$ is equivalent to the continuity of $F : \mathbb{R} \rightarrow C(\mathbb{R}, V)$ defined by $F(t)(x) = f(x-t)$. Note that the continuity of F follows from Thm. 9.3. This means that Prop. 14.40 can also be proved by Thm. 9.3.

Remark 14.42. In analysis, there are two especially important classes of $g \in C(\mathbb{R}, \mathbb{R}_{\geq 0})$ satisfying $\int_{\mathbb{R}} g = 1$. The first class consists of $g \in C_c(\mathbb{R}, \mathbb{R}_{\geq 0})$ satisfying $\int_{\mathbb{R}} g = 1$. Although functions with compact supports are often easy to use, they cannot be approximated by their Taylor series on \mathbb{R} . (See Exp. 12.19 for a related example.) Instead, we should consider another type of function:

14.5.2 Polynomial approximation

Example 14.43. Define the **Gauss function** $g(x) = \frac{1}{\sqrt{\pi}}e^{-x^2}$. Then $g \in C(\mathbb{R}, \mathbb{R}_{\geq 0})$ and $\int_{\mathbb{R}} g = 1$. Thus, g satisfies the assumptions in Prop. 14.40.

Although g does not have compact support, it is a real analytic function. So we can use $f * g_\varepsilon$ to prove Weierstrass approximation theorem.

Proof. It is easy to see that $\int_1^{+\infty} 1/x^2 dx < +\infty$. Thus, since $e^{x^2} \geq x^2$, we get $\int_{\mathbb{R}} e^{-x^2} dx < +\infty$.

It is not so easy to show that

$$\int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi} \quad (14.30)$$

This integral is called **Gauss integral**. In the next semester, we will use the change of variable formula for double integrals to prove (14.30). A more elementary (but also more complicated) proof is given in Pb. 14.3. For the purpose of this section, knowing $\int_{\mathbb{R}} e^{-x^2} dx < +\infty$ is enough, since we can define g to be e^{-x^2} divided by its integral on \mathbb{R} . \square

We now show that if g is the Gauss function, then $f * g_\varepsilon$ can be approximated uniformly by polynomials on every compact interval.

Lemma 14.44. Let $h(x) = \sum_{n=0}^{\infty} a_n x^n$ have radius of convergence $+\infty$, where $a_n \in \mathbb{F}$ for each a_n . Let $h_n(x) = \sum_{j=0}^n a_j x^j$ be the partial sum. Let $f \in C_c(\mathbb{R}, V)$. Then $\lim_{n \rightarrow \infty} f * h_n$ converges uniformly on compact intervals to $f * h$, and each $f * h_n$ is in

$$V[x] = \{v_0 + v_1 x + \cdots + v_k x^k : k \in \mathbb{N}, v_0, v_1, \dots, v_k \in V\} \quad (14.31)$$

Note that we do not need the assumption $\int_{\mathbb{R}} |h| < +\infty$ in this Lemma. So letting $h(x) = e^x$ is also OK. Clearly, if g is the Gauss functions, then g_ε satisfies the assumptions on h . This implies that if $f \in C_c(\mathbb{R}, V)$, then $f * g_\varepsilon$ can be approximated uniformly on compact intervals by polynomials with coefficients in V . Combining this fact with Prop. 14.40, we see that f can be approximated uniformly by polynomials on compact intervals.

Proof. Note that $(f * h)(x) = \int_{\mathbb{R}} h(x-y)f(y)dy$ is well-defined since it is equals $\int_{-a}^a h(x-y)f(y)dy$ if $a > 0$ and if $[-a, a]$ contains $\text{Supp}(f)$. (So this is a usual Riemann integral.) Similarly, $(f * h_n)(x) = \int_{-a}^a h_n(x-y)f(y)dy$. Since h_n is a polynomial, it is obvious that $f * h_n$ is also a polynomial.

We now show that $f * h_n$ converges uniformly to $f * h$ on $[-b, b]$ for any $b > 0$. Let $c = a + b$. Then

$$\sup_{x \in [-b, b]} \|(f * h)(x) - (f * h_n)(x)\| \leq \sup_{x \in [-b, b]} \int_{-a}^a |h(x-y) - h_n(x-y)| \cdot \|f(y)\| dy$$

$$\leq A_n \int_{-a}^a \|f(y)\| dy$$

where $A_n = \sup_{t \in [-c, c]} \|h(t) - h_n(t)\|$. By Thm. 4.27, h_n converges uniformly on $[-c, c]$ to h . So $\lim_{n \rightarrow \infty} A_n = 0$. \square

Theorem 14.45 (Weierstrass approximation theorem). *Let $I = [a, b]$ where $-\infty < a < b < +\infty$. Then $V[x]$ is dense in $C(I, V)$ under the l^∞ -norm.*

Proof. Choose any $f \in C(I, V)$. Then f can be extended to a continuous function $\mathbb{R} \rightarrow V$ with compact support: For example, we let $f(x) = (x - a + 1)f(a)$ if $x \in [a - 1, a]$, let $f(x) = (b + 1 - x)f(b)$ if $x \in [b, b + 1]$, and let $f(x) = 0$ if $x < a - 1$ or $x > b + 1$. Let g be the Gauss function. For every $e > 0$, by Prop. 14.40, there exists $\varepsilon > 0$ such that $\|f - f * g_\varepsilon\|_{l^\infty(\mathbb{R}, V)} < e/2$. By Lem. 14.44, there exists a polynomial $p \in V[x]$ such that $\|f * g_\varepsilon - p\|_{l^\infty(I, V)} < e/2$. So $\|f - p\|_{l^\infty(I, V)} < e$. \square

Corollary 14.46. *Let $I = [a, b]$ where $-\infty < a < b < +\infty$. Then $C([0, 1], \mathbb{R})$ is separable.*

Proof. $\mathbb{Q}[x]$, the set of polynomials with coefficients in \mathbb{Q} , is countable. By Thm. 14.45, $\mathbb{Q}[x]$ is dense in $C([0, 1], \mathbb{R})$. \square

The Weierstrass approximation theorem will be generalized to **Stone-Weierstrass theorem** (cf. Thm. 15.9). Accordingly, Cor. 14.46 will be substantially generalized as an application of (the proof of) Stone-Weierstrass theorem: we will show that $C(X, \mathbb{R})$ is separable if X is a compact metric space. (See Thm. 15.37)

14.5.3 Smooth approximation

By the Weierstrass approximation theorem, we know that any $f \in C_c(\mathbb{R}, V)$ can be approximated uniformly by polynomials on compact intervals. However, unless $f = 0$, f cannot be approximated by polynomials uniformly on \mathbb{R} . (If $p, q \in V[x]$ are different, then $\|p - q\|_{l^\infty(X, V)} = +\infty$. So any Cauchy sequence in $V[x]$ under the $l^\infty(X, V)$ -norm is eventually constant. So its limit is a polynomial, which does not have compact support unless when it is zero.) Nevertheless, we shall show that f can be approximated by smooth compactly supported functions uniformly on \mathbb{R} . This task is not difficult: one simply pick a nonzero $g \in C_c^\infty(\mathbb{R}, \mathbb{R})$ satisfying $g \geq 0$. Dividing g by $\int_{\mathbb{R}} g$, we may assume that $\int_{\mathbb{R}} g = 1$. Then it can be shown that $f * g_\varepsilon \in C_c^\infty(\mathbb{R}, V)$. By Prop. 14.40, $\lim_{\varepsilon \rightarrow 0} f * g_\varepsilon$ converges uniformly on \mathbb{R} to f . This finishes the proof. However, we must first prove the existence of such g :

Proposition 14.47. *Let $0 < a < b$. Then there exists $g \in C_c^\infty(\mathbb{R}, \mathbb{R})$ such that $g(\mathbb{R}) = [0, 1]$, that $g^{-1}(1) = [-a, a]$, and that $g^{-1}(0) = (-\infty, -b] \cup [b, +\infty)$.*

Proof. Let $\alpha : \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$ be the smooth function in Exp. 12.19. Then α is increasing and $\alpha^{-1}(0) = (-\infty, 0]$. Define $\beta : \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$ by $\beta(x) = \alpha(x + b)\alpha(-x + b)$. Then $\beta^{-1}(0) = (-\infty, -b] \cup [b, +\infty)$. In particular, $\beta \in C_c^\infty(\mathbb{R}, \mathbb{R})$. Define $\gamma : \mathbb{R} \rightarrow \mathbb{R}_{\geq 0}$ by $\gamma(x) = \alpha(x - a) + \alpha(-x - a)$. Then $\gamma^{-1}(0) = [-a, a]$. Note that $\beta(x) + \gamma(x) > 0$ for all $x \in \mathbb{R}$, since $\beta^{-1}(0) \cap \gamma^{-1}(0) = \emptyset$.



Then $g = \beta/(\beta + \gamma)$ is a desired function. □

Corollary 14.48. *Let I be an interval in \mathbb{R} with $a = \inf I$ and $b = \sup I$ satisfying $-\infty \leq a < b \leq +\infty$. Then $C_c^\infty(I, V)$ is dense in $C_c(I, V)$ under the l^∞ -norm.*

In the following, we only prove the case that $I = (a, b)$. The other cases can be reduced to this case: For example, the case $[a, b)$ is implied by the case $(a - 1, b)$.

First proof. Let $f \in C_c(\mathbb{R}, V)$ supported in $[u, v]$ where $a < u < v < b$. By Prop. 14.47, there exists a nonzero smooth $g \in C_c(\mathbb{R}, \mathbb{R}_{\geq 0})$ supported in $[-1, 1]$ such that $\int_{\mathbb{R}} g = 1$. Since g_ε is supported in $[-\varepsilon, \varepsilon]$, it is easy to see that $f * g_\varepsilon$ is supported in $[u - \varepsilon, v + \varepsilon]$. By Lem. 14.2, $f * g_\varepsilon$ is continuous. Moreover, one can check that $f * g_\varepsilon$ is smooth (cf. Pb. 14.4). So $f * g_\varepsilon \in C_c^\infty(\mathbb{R}, V)$, and $f * g$ is supported in I when $\varepsilon < \min\{u - a, b - v\}$. By Prop. 14.40, $\lim_{\varepsilon \rightarrow 0} f * g_\varepsilon$ converges uniformly on \mathbb{R} to f . □

Second proof. Let $f \in C_c(\mathbb{R}, V)$ supported in $[u, v]$ where $a < u < v < b$. Choose any $e > 0$. Choose any positive $\varepsilon < \min\{u - a, b - v\}$. By Weierstrass approximation Thm. 14.45, there exists $p \in V[x]$ such that $\|f(x) - p(x)\| \leq e$ for all $x \in [u - \varepsilon, v + \varepsilon]$. In particular, since $f = 0$ on $J = [u - \varepsilon, u] \cup [v, v + \varepsilon]$, we have $\|p(x)\| \leq e$ for all $x \in J$.

By Prop. 14.47, there exists $h \in C_c^\infty(\mathbb{R}, \mathbb{R})$ such that $h(\mathbb{R}) = [0, 1]$, that $h^{-1}(1) = [u, v]$, and that $h^{-1}(0) = (-\infty, u - \varepsilon] \cup [v + \varepsilon, +\infty)$. Then $hp \in C_c^\infty(\mathbb{R}, V)$ is supported in $[u - \varepsilon, v + \varepsilon]$ and hence in $(-a, a)$. One checks easily that $\|f(x) - h(x)p(x)\| \leq e$ for all $x \in (a, b)$. □

Remark 14.49. It should be noted that if I is an open interval, then $C_c^\infty(I, V)$ and $C_c(I, V)$ are naturally subspaces of $C_c(\mathbb{R}, V)$. This is not true when I is a closed or an half-open-half-closed interval. Therefore, Cor. 14.48 implies that any $f \in C(\mathbb{R}, V)$ supported in an open interval I can be uniformly approximated by smooth functions $\mathbb{R} \rightarrow V$ supported in I .

Remark 14.50. The above observation can be generalized: Let X be an LCH space. Assume that Ω is a nonempty open subset of X . Recall that Ω is LCH by Prop. 8.41. Then an element of $C_c(\Omega, V)$ is equivalently an element of $C_c(X, V)$ supported in Ω . The former gives the latter by “extension by zero”; the latter gives the former by restriction to Ω . We will say more about this in Sec. 15.4.

14.6 L^1 -approximation; Riemann-Lebesgue lemma

A non-continuous integrable function cannot be approximated uniformly by smooth functions. However, it can be approximated by the latter under the L^1 -norm. To avoid distraction, in this section we consider \mathbb{C} -valued functions. Fix $I \subset \mathbb{R}$ to be an interval containing at least two points. Then on $\mathcal{R}^1(I, \mathbb{C})$ one can define the L^1 -seminorm to be

$$\|f\|_{L^1} \equiv \|f\|_{L^1(I, \mathbb{C})} = \int_I |f| \quad (14.32)$$

It is easy to check that this is a **seminorm**, i.e., it satisfies the definition of a norm, except the assumption that $\|f\|_{L^1} = 0$ implies $f = 0$.

Proposition 14.51. *Let $f \in \mathcal{R}^1(I, \mathbb{C})$. Choose any $\varepsilon > 0$. Then there exists $g \in C_c^\infty(\mathbb{R}, \mathbb{C})$ supported in I such that $\|f - g\|_{L^1} < \varepsilon$. And there exists a **step function** h supported in I (i.e., a linear combination of functions of the form χ_E where E is a compact interval in I) such that $\|f - h\|_{L^1} < \varepsilon$.*

Note that if E is a bounded interval, then χ_E is clearly a linear combination of characteristic functions over compact intervals (including the single point sets). Thus, in the above definition of step functions, one can just assume that E is a bounded interval whose closure is in I .

The following proof shows that Prop. 14.51 can be easily generalized to the case that $f : I \rightarrow V$ is strongly integrable on compact subintervals of I and $\int_I |f| < +\infty$. (V is a Banach space.)

Proof. Let $a = \inf I, b = \sup I$. Since $\int_I |f| = \lim_{u \rightarrow a, v \rightarrow b} \int_a^b |f|$, there exist u, v such that $a < u < v < b$ and that $\int_a^u |f| + \int_v^b |f| < \varepsilon/2$. We claim that there exists a step function h supported in $J = [u, v]$ such that $\int_J |f - h| < \varepsilon/2$. Then $\int_I |f - h| < \varepsilon$, finishing the proof that f can be L^1 -approximated by step functions supported in I .

Since $f|_J$ is strongly Riemann integrable, there exists $\sigma = \{a_0 < \cdots < a_n\} \in \mathcal{P}(J)$ such that $\omega(f, \sigma) < \frac{\varepsilon}{2}$. Let $J_i = [a_{i-1}, a_i]$. Pick any $\lambda_i \in f(J_i)$. Then $|f - \lambda_i \cdot \chi_{J_i}| \leq \text{diam}(f(J_i))$ on J_i , and hence $\int_{J_i} |f - \lambda_i \cdot \chi_{J_i}| \leq \text{diam}(f(J_i)) \cdot |J_i|$. Let $h = \sum_{i=1}^n \lambda_i \cdot \chi_{J_i}$. It follows that

$$\left| \int_J f - \int_J h \right| \leq \sum_{i=1}^n \int_{J_i} |f - \lambda_i \cdot \chi_{J_i}| \leq \sum_{i=1}^n \text{diam}(f(J_i)) \cdot |J_i| = \omega(f, \sigma) < \frac{\varepsilon}{2}$$

finishing the proof.

Finally, we show that f can be L^1 -approximated by smooth functions supported in I . It suffices to prove that any step function supported in I is so. By linearity and triangle inequality, it suffices to prove that χ_E is so, if E is a nonempty compact interval in I . For each $\varepsilon > 0$, it is easy to construct a piecewise linear

(and hence continuous) function $g_0 : \mathbb{R} \rightarrow \mathbb{R}$ supported in $(a, b) = \text{Int}(I)$ such that $\int_I |\chi_E - g_0| < \varepsilon$. Choose a bounded open interval $(c, d) \subset (a, b)$ containing $\text{Supp}(g_0)$. By Cor. 14.48, there exists $g \in C_c^\infty(\mathbb{R}, \mathbb{R})$ supported in (c, d) such that $|g(x) - g_0(x)| < \varepsilon/(d - c)$ for all $x \in (c, d)$. It follows that

$$\int_I |g - g_0| = \int_c^d |g - g_0| \leq \varepsilon$$

Thus $\int_I |\chi_E - g| < 2\varepsilon$, finishing the proof. \square

We give an application of Prop. 14.51 by proving Riemann-Lebesgue lemma. The RL lemma plays a fundamental role in Fourier analysis, see for instance Pb. 14.6 and Cor. 14.56.

Theorem 14.52 (Riemann-Lebesgue lemma). *Let $f \in \mathcal{R}^1(\mathbb{R}, \mathbb{C})$. Then*

$$\lim_{t \rightarrow +\infty} \int_{\mathbb{R}} f(x) e^{itx} dx = \lim_{t \rightarrow -\infty} \int_{\mathbb{R}} f(x) e^{itx} dx = 0$$

The idea of the proof is the following: We L^1 -approximate f by some compactly supported step function $g \in C_c(\mathbb{R}, \mathbb{C})$. Then it suffices to prove the RL lemma for g . By linearity, it suffices to assume that $g = \chi_{[a,b]}$. This special case can be proved easily.

Proof. By Prop. 14.51, for every $\varepsilon > 0$ there exists a compactly supported step function $g : \mathbb{R} \rightarrow \mathbb{C}$ such that $\int_{\mathbb{R}} |f - g| < \varepsilon$. So $|\int_{\mathbb{R}} f(x) e^{itx} - g(x) e^{itx} dx| < \varepsilon$ by Prop. 14.27. Thus

$$\limsup_{t \rightarrow \pm\infty} \left| \int_{\mathbb{R}} f(x) e^{itx} dx \right| \leq \limsup_{t \rightarrow \pm\infty} \left| \int_{\mathbb{R}} g(x) e^{itx} dx \right| + \varepsilon$$

Since ε is arbitrary, it suffices to prove that $\lim_{t \rightarrow \pm\infty} \int_{\mathbb{R}} g(x) e^{itx} dx = 0$. Since g is a linear combination of functions of the form $\chi_{[a,b]}$ where $-\infty < a < b < +\infty$, it suffices to prove the RL lemma for this function:

$$\int_{\mathbb{R}} \chi_{[a,b]} \cdot e^{itx} dx = \int_a^b e^{itx} dx = \frac{e^{inb} - e^{ina}}{it}$$

converges to 0 as $t \rightarrow \pm\infty$. \square

14.7 Problems and supplementary material

Let V be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 14.1. Solve Exe. 14.8.

Problem 14.2. Prove Thm. 14.34 using Thm. 14.35.

★ **Problem 14.3.** Define $f(x) = \left(\int_0^x e^{-t^2} dt \right)^2$ and $g(x) = \int_0^1 \frac{e^{-x^2(t^2+1)}}{t^2+1} dt$

1. Show that $f' + g' = 0$, and conclude that $f + g = \frac{\pi}{4}$.

2. Use part 1 to prove

$$\int_{-\infty}^{+\infty} e^{-t^2} dt = \sqrt{\pi} \quad (14.33)$$

Problem 14.4. Let $f : \mathbb{R} \rightarrow V$ be strongly integrable on compact intervals, and assume $\int_{\mathbb{R}} |f| < +\infty$. Let $g \in C^1(\mathbb{R}, \mathbb{R})$. Assume that $\|g\|_{\infty}, \|g'\|_{\infty} < +\infty$. (This is automatic when g has compact support.) Use Thm. 14.35 to prove that $f * g$ is well-defined, that $f * g \in C^1(\mathbb{R}, \mathbb{R})$, and that $(f * g)' = f * g'$.

Note. Since f is not assumed to be continuous, you cannot use Thm. 14.34 directly to compute $(f * g)'$ and to show $f * g \in C^1$. You have two options: (1) Use Thm. 14.35. (2) Use Prop. 14.51 to L^1 -approximate f by a continuous compactly-supported function. Then apply Thm. 14.34 (together with Cor. 14.36) to that continuous function. Whichever method you use, I suggest you think about how you can use the other method to solve the problem. \square

Remark 14.53. In particular, if $g \in C_c^{\infty}(\mathbb{R}, \mathbb{R})$, then the above problem shows that $f * g \in C^{\infty}(\mathbb{R}, \mathbb{R})$ and $(f * g)^{(n)} = f * g^{(n)}$ for all $n \in \mathbb{N}$.

★ **Problem 14.5.** The translation of each $f \in \mathcal{R}^1(\mathbb{R}, \mathbb{C})$ by $t \in \mathbb{R}$ is defined to be

$$f_t : \mathcal{R}^1(\mathbb{R}, \mathbb{C}) \rightarrow \mathcal{R}^1(\mathbb{R}, \mathbb{C}) \quad f_t(x) = f(x - t)$$

Prove that the translation map is continuous under the L^1 -seminorm, in the sense that $\lim_{t \rightarrow 0} \|f - f_t\|_{L^1} = 0$. Namely, prove that

$$\lim_{t \rightarrow 0} \int_{\mathbb{R}} |f - f_t| = 0$$

Hint. Use Prop. 14.51 to L^1 -approximate f by compactly supported continuous functions or step functions. (Both types of functions will work.) \square

Definition 14.54. Let $f \in \mathcal{R}([- \pi, \pi], \mathbb{C})$. For each $n \in \mathbb{Z}$, define the n -th **Fourier coefficient** to be

$$\hat{f}(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-inx} dx$$

We call $\sum_{n=-\infty}^{+\infty} \hat{f}(n) e^{inx}$ the **Fourier series** of f .

Definition 14.55. For each $N \in \mathbb{N}$, define the **Dirichlet kernel**

$$D_N(x) = \sum_{n=-N}^N e^{inx} = \frac{\sin(N + \frac{1}{2})x}{\sin(x/2)}$$

(When $x \in 2\pi\mathbb{Z}$, the RHS above should be $2N + 1$.) From $\frac{1}{2\pi} \int_{-\pi}^{\pi} e^{inx} dx = \delta_{n,0}$ we easily see $\frac{1}{2\pi} \int_{-\pi}^{\pi} D_N(x) dx = 1$.

Problem 14.6. Let $f \in \mathcal{R}(\mathbb{R}, \mathbb{C})$ have period 2π . Define $s_N(f; x) = \sum_{n=-N}^N \hat{f}(n) e^{inx}$.

1. Prove that $s_N(f; x) = (f * D_N)(x)$ where the convolution is defined with respect to the integral $\frac{1}{2\pi} \int_I$ where I is any interval of length 2π . (Note that both f and D_N have period 2π . So translating I does not affect the result.) In other words, prove that

$$s_N(f; x) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(t) D_N(x - t) dt = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x - t) D_N(t) dt \quad (14.34)$$

2. Fix $x \in \mathbb{R}$. Assume that there exist $A, B \in \mathbb{C}$ such that

$$\limsup_{t \rightarrow 0^+} \left| \frac{f(x - t) - A}{t} \right| < +\infty \quad \limsup_{t \rightarrow 0^+} \left| \frac{f(x + t) - B}{t} \right| < +\infty \quad (14.35)$$

(In other words, assume that there exist $\delta, M > 0$ such that $|(f(x - t) - A)/t| \leq M$ and $|(f(x + t) - B)/t| \leq M$ for all $0 < t < \delta$.) Prove that

$$\lim_{N \rightarrow +\infty} s_N(f; x) = \frac{A + B}{2} \quad (14.36)$$

Hint for part 2. Choose $g : [-\pi, \pi] \rightarrow \mathbb{C}$ such that $g(t) = B$ if $t < 0$, and $g(t) = A$ if $t > 0$. Prove that

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} g(t) D_N(t) dt = \frac{A + B}{2} \quad (14.37)$$

Let $\varphi : [-\pi, \pi] \rightarrow \mathbb{R}$ such that $\varphi(t) = \frac{f(x - t) - g(t)}{\sin(t/2)}$ if $t \neq 0$. Use Lebesgue's criterion to show that $\varphi \in \mathcal{R}([-\pi, \pi], \mathbb{C})$. Use Riemann-Lebesgue lemma to prove $\lim_{N \rightarrow +\infty} \int_{-\pi}^{\pi} \varphi(t) \sin(N + \frac{1}{2})t \cdot dt = 0$. \square

Corollary 14.56. Let $g \in C^1([a - \pi, a + \pi], \mathbb{C})$. Let $f : \mathbb{R} \rightarrow \mathbb{C}$ be a 2π -periodic function such that $f(x) = g(x)$ if $a - \pi < x < a + \pi$, and that $f(a + \pi) = \frac{g(a - \pi) + g(a + \pi)}{2}$. Clearly $f \in \mathcal{R}(\mathbb{R}, \mathbb{C})$. Then the Fourier series of f converges pointwise to f .

Proof. Immediate from part 2 of Pb. 14.6. □

Example 14.57. If we let $a = 0$ and $g(x) = x$, then one can compute that the Fourier series of f is (13.10). It converges pointwise but not uniformly to f .

15 A topological proof of the Stone-Weierstrass theorem

15.1 *-algebras and subalgebras

Fix $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

Definition 15.1. An \mathbb{F} -**algebra** is defined to be a ring \mathcal{A} (not necessarily having 1) which is at the same time also an \mathbb{F} -vector space (where the vector addition is equal to the ring addition) such that the ring multiplication and the scalar multiplication satisfy the associativity: For every $\lambda \in \mathbb{F}$ and $x, y \in \mathcal{A}$, we have

$$\lambda(xy) = (\lambda x)y = x(\lambda y) \quad (15.1)$$

An \mathbb{F} -algebra is called **unital** if \mathcal{A} , as a ring, has the identity 1. In this case, we write $\lambda \cdot 1$ as λ if $\lambda \in \mathbb{F}$.

An \mathbb{F} -algebra is called **commutative** or **abelian** if $xy = yx$ for all $x, y \in \mathcal{A}$.

If \mathcal{A} is an \mathbb{F} -algebra, then an **(\mathbb{F} -)subalgebra** is a subset \mathcal{B} which is invariant under the ring addition, ring multiplication, and scalar multiplication. (Namely, \mathcal{B} is a subring and also a subspace of \mathcal{A} .) If \mathcal{A} is unital, then a **unital (\mathbb{F} -)subalgebra** of \mathcal{A} is an \mathbb{F} -subalgebra containing the identity of \mathcal{A} . \square

Remark 15.2. A unital \mathbb{F} -algebra \mathcal{A} is equivalently a ring with unit 1, together with a ring homomorphism $\mathbb{C} \rightarrow Z(\mathcal{A})$ where $Z(\mathcal{A})$ is the **center** of \mathcal{A} , i.e.

$$Z(\mathcal{A}) = \{x \in \mathcal{A} : xy = yx \text{ for every } y \in \mathcal{A}\}$$

We leave it to the readers to check the equivalence.

Example 15.3. If V is a \mathbb{F} -vector space, then $\text{End}(V)$, the set of \mathbb{F} linear maps $V \rightarrow V$, is naturally an \mathbb{F} -algebra. If V is a normed vector space, then $\mathcal{L}(V)$ is an \mathbb{F} -algebra.

Definition 15.4. A **(complex) *-algebra** is defined to be a \mathbb{C} -algebra together with an **antilinear map** $*$: $\mathcal{A} \rightarrow \mathcal{A}$ sending x to x^* (where “antilinear” means that for every $a, b \in \mathbb{C}$ and $x, y \in \mathcal{A}$ we have $(ax + by)^* = \bar{a}x^* + \bar{b}y^*$) such that for every $x, y \in \mathcal{A}$, we have

$$(x^*)^* = x \quad (xy)^* = y^*x^*$$

Note that $*$ must be bijective. We call $*$ an **involution**. A ***-subalgebra** \mathcal{B} is defined to be a subalgebra satisfying $x \in \mathcal{B}$ iff $x^* \in \mathcal{B}$. If \mathcal{A} is a unital algebra with unit 1, we say that \mathcal{A} is a **unital *-algebra** if \mathcal{A} is equipped with an involution $*$: $\mathcal{A} \rightarrow \mathcal{A}$ such that \mathcal{A} is a *-algebra, and that

$$1^* = 1$$

A unital *-subalgebra is a unital subalgebra and also a *-subalgebra.

Example 15.5. The set of complex $n \times n$ matrices $\mathbb{C}^{n \times n}$ is naturally a unital $*$ -algebra if for every $A \in \mathbb{C}^{n \times n}$ we define $A^* = \overline{A}^t$, the complex conjugate of the transpose of A .

In this chapter, we are mainly interested in abelian algebras.

Example 15.6. Let X be a set. Then \mathbb{F}^X is naturally a unital \mathbb{F} -algebra, and $l^\infty(X, \mathbb{C})$ is its unital \mathbb{F} -subalgebra. If X is a topological space, then $C(X, \mathbb{F})$ is a unital \mathbb{F} -subalgebra of \mathbb{F}^X . If X is compact, then $C(X, \mathbb{F})$ is a unital \mathbb{F} -subalgebra of $l^\infty(X, \mathbb{F})$.

The following is our main example of this chapter.

Example 15.7. Let X be a set. Then \mathbb{C}^X is a unital $*$ -algebra if for every $f \in \mathbb{C}^X$ we define

$$f^* : X \rightarrow \mathbb{C} \quad f^*(x) = \overline{f(x)} \quad (15.2)$$

Then $l^\infty(X, \mathbb{C})$ is a unital $*$ -subalgebra of \mathbb{C}^X . Assume that X is a compact topological space. Then $C(X, \mathbb{C})$ is a unital $*$ -subalgebra of $l^\infty(X, \mathbb{C})$. If $f_1, \dots, f_n \in C(X, \mathbb{C})$, then $\mathbb{C}[f_1, \dots, f_n]$, the set of polynomials of f_1, \dots, f_n with coefficients in \mathbb{C} , is a unital subalgebra of $C(X, \mathbb{C})$. And $\mathbb{C}[f_1, f_1^*, \dots, f_n, f_n^*]$ is a unital $*$ -subalgebra of $C(X, \mathbb{C})$.

More generally, we have:

Example 15.8. Let \mathcal{A} be an abelian unital \mathbb{F} -algebra. Let $\mathfrak{S} \subset \mathcal{A}$. Then

$$\mathbb{F}[\mathfrak{S}] = \text{Span}_{\mathbb{F}}\{x_1^{n_1} \cdots x_k^{n_k} : k \in \mathbb{Z}_+, x_i \in \mathfrak{S}, n_i \in \mathbb{N}\} \quad (15.3)$$

the set of polynomials of elements in \mathfrak{S} , is the smallest unital \mathbb{F} -subalgebra containing \mathfrak{S} , called the **unital \mathbb{F} -subalgebra generated by \mathfrak{S}** . (Here, we understand $x^0 = 1$ if $x \in \mathcal{A}$.) Thus, if \mathcal{A} is an abelian unital $*$ -algebra, then $\mathbb{C}[\mathfrak{S} \cup \mathfrak{S}^*]$ (where $\mathfrak{S}^* = \{x^* : x \in \mathfrak{S}\}$) is the smallest unital $*$ -algebra containing \mathfrak{S} , called the **unital $*$ -subalgebra generated by \mathfrak{S}** .

15.2 Stone-Weierstrass (SW) theorems

The main goal of this chapter is to prove the following theorem.

Theorem 15.9 (SW theorem, compact real version). *Let X be a compact Hausdorff space. Let \mathcal{A} be unital subalgebra of $C(X, \mathbb{R})$ separating points of X . Then \mathcal{A} is dense in $C(X, \mathbb{R})$ (under the l^∞ -norm).*

Example 15.10. Let $X = [a, b]$ be a compact interval in \mathbb{R} . Then $\mathbb{R}[x]$ is a unital subalgebra of $C(X, \mathbb{R})$. It separates points of $[a, b]$ because it contains id . Thus, by SW theorem, $\mathbb{R}[a, b]$ is dense in $C([a, b], \mathbb{R})$. This special case was proved in Thm. 14.45.

More generally, let $X = I_1 \times \cdots \times I_N$ where each $I_i \subset \mathbb{R}$ is a compact interval. Let $\pi_i : X \rightarrow I_i$ be the projection onto the i -th component, i.e., the i -th coordinate function. Then π_1, \dots, π_N separate points of X , since $\pi_1 \times \cdots \times \pi_N$ is the identity map of X . Thus, by SW theorem, $\mathbb{R}[\pi_1, \dots, \pi_N]$ is dense in $C(X, \mathbb{R})$. In fact, we will first prove this special case before we prove the general SW theorem. \square

From the above version of SW theorem it is easy to prove:

Theorem 15.11 (SW theorem, compact complex version). *Let X be a compact Hausdorff space. Let \mathcal{A} be a unital $*$ -subalgebra of $C(X, \mathbb{C})$ separating points of X . Then \mathcal{A} is dense in $C(X, \mathbb{R})$ (under the l^∞ -norm).*

Proof. Let $\text{Re}\mathcal{A} = \{\text{Re}f = (f + f^*)/2 : f \in \mathcal{A}\}$. Since for each $f \in \mathcal{A}$ we have $f^* \in \mathcal{A}$, we know that $\text{Re}f \in \mathcal{A}$. This proves that $\text{Re}\mathcal{A} \subset \mathcal{A}$. Since $f = \text{Re}(f) - i\text{Re}(if)$, we conclude

$$\mathcal{A} = \text{Re}\mathcal{A} + i\text{Re}\mathcal{A} \quad (15.4)$$

In other words, elements of \mathcal{A} are precisely of the form $\alpha + i\beta$ where $\alpha, \beta \in \text{Re}\mathcal{A}$. From this, it is clear that $\text{Re}\mathcal{A}$ is a unital subalgebra of $C(X, \mathbb{R})$ separating points of X . Thus, by Thm. 15.9, $\text{Re}\mathcal{A}$ is dense in $C(X, \mathbb{R})$. It is clear from (15.4) that \mathcal{A} is dense in $C(X, \mathbb{C})$. \square

Example 15.12. Let $\mathbb{S}^1 = \{z \in \mathbb{C} : |z| = 1\}$. For each $n \in \mathbb{Z}$, let $e_n : \mathbb{S}^1 \rightarrow \mathbb{C}$ be defined by $e_n(e^{ix}) = e^{inx}$. In other words, $e_n(z) = z^n$. Then $\mathbb{C}[e_1, e_{-1}] = \text{Span}_{\mathbb{C}}\{e_n : n \in \mathbb{Z}\}$ is a unital $*$ -subalgebra of $C(\mathbb{S}^1, \mathbb{C})$. It separates points of \mathbb{S}^1 since e_1 does. Therefore, by SW theorem, $\mathbb{C}[e_1, e_{-1}]$ is dense in $C(\mathbb{S}^1, \mathbb{C})$.

One often views

$$C(\mathbb{S}^1, \mathbb{C}) = \{g \in C([- \pi, \pi], \mathbb{C}) : g(-\pi) = g(\pi)\} \quad (15.5)$$

since any g in the RHS corresponds bijectively to f in the LHS by setting $f(e^{it}) = g(t)$. Therefore, the above conclusion is that *any $g \in C([- \pi, \pi], \mathbb{C})$ satisfying $g(-\pi) = g(\pi)$ can be approximated uniformly by functions of the form $\sum_{n=-N}^N a_n \cdot e^{inx}$ where $a_n \in \mathbb{C}$. This property is fundamental to the theory of Fourier series.* \square

Example 15.13. We continue the above discussion. $\mathbb{C}[e_1] = \text{Span}_{\mathbb{C}}\{e_n : n \in \mathbb{N}\}$ is a unital subalgebra (though not a $*$ -subalgebra) of $C(\mathbb{S}^1, \mathbb{C})$ separating points of \mathbb{S}^1 . Let us prove that it is not dense in $C(\mathbb{S}^1, \mathbb{C})$.

Proof. We view functions on \mathbb{S}^1 as those on $[-\pi, \pi]$ having the same values at π and at $-\pi$. We claim that e_{-1} is not in the closure of $\mathbb{C}[e_1]$. Indeed, it can be checked that $\int_{-\pi}^{\pi} e_{-1} e_1 = 2\pi$, and that $\int_{-\pi}^{\pi} p \cdot e_1 = 0$ for every $p \in \mathbb{C}[e_1]$ (since this is true when $p = e_n$ and $n \geq 0$). If e_{-1} is in the closure of $\mathbb{C}[e_1]$, then there is a sequence $(p_k)_{k \in \mathbb{Z}_+}$ in $\mathbb{C}[e_1]$ converging uniformly on $[-\pi, \pi]$ to e_{-1} . By Cor. 13.21, $0 = \int_{-\pi}^{\pi} p_k e_1$ converges to $\int_{-\pi}^{\pi} e_{-1} e_1 = 2\pi$ as $k \rightarrow \infty$, impossible. \square

Example 15.14. Let X, Y be compact metric spaces. Let \mathcal{A} be the subspace of $C(X \times Y, \mathbb{R})$ spanned by elements of the form fg where $f \in C(X, \mathbb{R})$ and $g \in C(Y, \mathbb{R})$. (More precisely, one should understand fg as $(f \circ \pi_X) \cdot (g \circ \pi_Y)$ where π_X, π_Y are the projections of $X \times Y$ onto X and Y respectively.) By the Urysohn functions (cf. Rem. 7.118), we see that $C(X, \mathbb{R})$ resp. $C(Y, \mathbb{R})$ separates points of X resp. Y . (This is in fact also true when X, Y are compact Hausdorff spaces.) Thus \mathcal{A} is a unital subalgebra of $C(X \times Y, \mathbb{R})$ separating points of $X \times Y$. By SW theorem, \mathcal{A} is dense in $C(X \times Y, \mathbb{R})$. Nevertheless, we will prove SW theorem by first proving this special case: see Cor. 15.33.¹

15.3 Proof of SW, I: polynomial approximation on $[0, 1]^{\mathcal{J}}$

Starting from this section, we begin our proof of SW Thm. 15.9. We first explain our strategy of the proof. Let X be a compact Hausdorff space.

We first consider the special case that X is metrizable. Then by Thm. 8.45, X is homeomorphic to a closed (and hence compact) subset of $[0, 1]^{\mathbb{Z}_+}$. Therefore, we may assume that X is a closed subset of $[0, 1]^{\mathbb{Z}_+}$. As we will see, any continuous real-valued function on X can be extended to a continuous function on $[0, 1]^{\mathbb{Z}_+}$. (This is due to **Tietze extension theorem**, which will be proved in the next section.) Thus, it suffices to prove SW theorem for $[0, 1]^{\mathbb{Z}_+}$. In fact, as we will see, it suffices to prove that any element of $C([0, 1]^{\mathbb{Z}_+}, \mathbb{R})$ can be approximated uniformly by polynomials, i.e., by elements of $\mathbb{R}[\pi_1, \pi_2, \dots]$ where $\pi_n : [0, 1]^{\mathbb{Z}_+} \rightarrow [0, 1]$ is the projection onto the n -th component. This task will be achieved in this section.

The above method can be easily generalized to the case that X is not necessarily metrizable. In fact, since $\mathcal{A} \subset C(X, \mathbb{R})$ separates points of X , as in the proof of Thm. 8.45, \mathcal{A} enables us to embed X onto a compact subset of $[0, 1]^{\mathcal{J}}$ where \mathcal{J} is an index set. Therefore, we need to show that $[0, 1]^{\mathcal{J}}$ is compact. This is indeed due to:

Theorem 15.15 (Tychonoff theorem). *Let $(X_\alpha)_{\alpha \in \mathcal{J}}$ be a family of compact topological spaces. Then the product space $S = \prod_{\alpha \in \mathcal{J}} X_\alpha$ (equipped with the product topology) is compact.*

¹More precisely, we don't need Exp. 15.14 to prove SW. But our method of proving SW immediately implies Exp. 15.14. To put it differently, we don't need the full power of the SW theorem to prove Exp. 15.14.

Note that S is obviously Hausdorff if each X_α is Hausdorff. We will prove Tychonoff theorem in Sec. 16.3 using Zorn's lemma. Assuming Tychonoff theorem, we will show that elements of $C([0, 1]^{\mathcal{J}}, \mathbb{R})$ can be approximated uniformly by polynomials. This is the goal of this section:

Proposition 15.16. *Let $(I_\alpha)_{\alpha \in \mathcal{J}}$ be a family of nonempty compact intervals in \mathbb{R} . Let $S = \prod_{\alpha \in \mathcal{J}} I_\alpha$. For each α , define the **coordinate function***

$$\pi_\alpha : S \rightarrow I_\alpha \quad x_\bullet = (x_\mu)_{\mu \in \mathcal{J}} \mapsto x_\alpha$$

Then $\mathbb{R}[\{\pi_\alpha : \alpha \in \mathcal{J}\}]$, the unital subalgebra of $C(S, \mathbb{R})$ generated by all coordinate functions, is dense in $C(S, \mathbb{R})$.

Since the coordinate functions separate points of S , Prop. 15.16 is clearly a special case of SW theorem.

Lemma 15.17. *Prop. 15.16 holds when \mathcal{J} is a finite set.*

Proof. We prove by induction on N that elements of $C(S, \mathbb{R})$, where $S = I_1 \times \cdots \times I_N$, can be approximated uniformly by polynomials (i.e. by elements of $\mathbb{R}[\pi_1, \dots, \pi_N]$). The case $N = 1$ follows from Weierstrass approximation Thm. 14.45. Assume that case $N - 1$ has been proved. Let us prove case N where $N > 1$.

Write $S = I_1 \times Y$ where $Y = I_2 \times \cdots \times I_N$. Then by Thm. 9.3, we have a canonical equivalence of normed vector spaces

$$C(S, \mathbb{R}) \simeq C(I_1, \mathcal{V}) \quad \text{where} \quad \mathcal{V} = C(Y, \mathbb{R})$$

Choose any $f \in C(S, \mathbb{R})$, viewed as an element of $C(I_1, \mathcal{V})$. Then by Thm. 14.45, f can be approximated uniformly on I_1 by elements of $\mathcal{V}[\pi_1]$. Thus, for any $\varepsilon > 0$, there exist $n \in \mathbb{Z}_+$ and $g_0, \dots, g_n \in C(Y, \mathbb{R})$ such that $\|f - \sum_{i=0}^n g_i \cdot \pi_1^i\|_{l^\infty(I_1, \mathcal{V})} < \varepsilon$. Equivalently,

$$\left\| f - \sum_{i=0}^n g_i \cdot \pi_1^i \right\|_{l^\infty(S, \mathbb{R})} < \varepsilon$$

where g_i actually means the composition of g_i with the projection $S \rightarrow Y$. By case $N - 1$, each g_i can be approximated uniformly on Y by elements of $\mathbb{R}[\pi_2, \dots, \pi_N]$. So by triangle inequality, f can be uniformly approximated by elements of the form $\sum_{i=1}^n h_i \cdot \pi_1^i$ where each h_i is a polynomial of π_2, \dots, π_N . This finishes the proof of case N . \square

The key to the transition from finite to general index sets is the following lemma.

Lemma 15.18. Let $(X_\alpha)_{\alpha \in \mathcal{J}}$ be a family of nonempty topological spaces. Let $S = \prod_{\alpha \in \mathcal{J}} X_\alpha$. Let $f \in C(S, \mathbb{R})$. Let $p_\bullet = (p_\alpha)_{\alpha \in \mathcal{J}} \in S$. For each $A \in \text{fin}(2^\mathcal{J})$, define a map $\varphi_A : S \rightarrow S$ such that for each $x_\bullet = (x_\alpha)_{\alpha \in \mathcal{J}}$,

$$\varphi_A(x_\bullet)_\alpha = \begin{cases} x_\alpha & \text{if } \alpha \in A \\ p_\alpha & \text{if } \alpha \notin A \end{cases}$$

Then φ_A is continuous, and hence $f \circ \varphi_A$ is continuous. Moreover, for every $x_\bullet \in S$ we have

$$\lim_{\substack{(A, y_\bullet) \in \text{fin}(2^\mathcal{J}) \times S \\ (A, y_\bullet) \rightarrow (\infty, x_\bullet)}} f \circ \varphi_A(y_\bullet) = f(x_\bullet) \quad (15.6)$$

in the sense of Prop. 9.16. Thus, if each X_α is compact, then S is compact by Tychonoff Thm. 15.15, and hence $\lim_{A \in \text{fin}(2^\mathcal{J})} f \circ \varphi_A$ converges uniformly to f by Thm. 9.12.

In other words, φ_A fixes the α -th component if $\alpha \in A$, and changes the α -th component to p_α if $\alpha \notin A$. (15.6) means that for every $\varepsilon > 0$ there exist $U \in \text{Nbh}(x_\bullet)$ and a finite $A \subset \mathcal{J}$ such that for every $y_\bullet \in U$ and for every finite set B satisfying $A \subset B \subset \mathcal{J}$, we have $|f(x_\bullet) - f \circ \varphi_B(y_\bullet)| < \varepsilon$.

Proof. The proof is similar to that of Pb. 9.6. The continuity of φ_A follows easily from the net-convergence description of product topology in Thm. 7.73. Choose any $x_\bullet \in S$ and $\varepsilon > 0$. Since f is continuous, there exists $U \in \text{Nbh}(x_\bullet)$ such that $|f(x_\bullet) - f(y_\bullet)| < \varepsilon$ for all $y_\bullet \in U$. By the definition of product topology by means of basis (Def. 7.71), we can shrink U to a smaller neighborhood of x_\bullet of the form

$$U = \prod_{\alpha \in \mathcal{J}} V_\alpha$$

where $V_\alpha \in \text{Nbh}_{X_\alpha}(x_\alpha)$ for each $\alpha \in \mathcal{J}$, and $V_\alpha = X_\alpha$ for all α outside some $A \in \text{fin}(2^\mathcal{J})$. Thus, $y_\bullet \in S$ belongs to U iff $y_\alpha \in V_\alpha$ for each $\alpha \in A$. Therefore, if $y_\bullet \in U$, then for each finite B satisfying $A \subset B \subset \mathcal{J}$, we have that

$$\varphi_B(y_\bullet)_\alpha = y_\alpha \in V_\alpha \quad (\forall \alpha \in A)$$

and hence that $\varphi_B(y_\bullet) \in U$. It follows that $|f(x_\bullet) - f \circ \varphi_B(y_\bullet)| < \varepsilon$. □

Proof of Prop. 15.16. Choose any continuous $f : S = \prod_{\alpha \in \mathcal{J}} I_\alpha \rightarrow \mathbb{R}$. By Lem. 15.18, f can be approximated uniformly by functions depending on finitely many variables. In other words, for any $\varepsilon > 0$, there exist $A \in \text{fin}(2^\mathcal{J})$ and a continuous $g : S_A = \prod_{\alpha \in A} I_\alpha \rightarrow \mathbb{R}$ such that $\|f - g \circ \pi_A\|_{l^\infty(S, \mathbb{R})} < \varepsilon$, where $\pi_A : S \rightarrow S_A$ is the natural projection. By Lem. 15.17, g can be approximated uniformly by polynomials of $\{\pi_\alpha : \alpha \in A\}$. This finishes the proof. □

15.4 Partition of unity and the Tietze extension theorem

In this section, we fix a Banach space \mathcal{V} over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and fix a nonempty LCH space X .

Remark 15.19. Let U be an open subset of X . Recall that U is LCH by Prop. 8.41. Let $f \in C_c(U, \mathcal{V})$ supported in U . Then by zero-extension, f can be viewed as an element of $C_c(X, \mathcal{V})$ supported in U .

Proof. Let f take value 0 outside U . Let $A = \{x \in U : f(x) \neq 0\}$ and $K = \text{Cl}_U(A)$, which is compact by assumption. In particular, K is closed in X by Cor. 8.22. Then $X = U \cup K^c$ is an open cover on X . By assumption, $f|_U$ is continuous. Also $f|_{K^c} = 0$ is continuous. So f is continuous by Exe. 7.119. To show that $f \in C_c(X, \mathcal{V})$ and $\text{Supp}(f) \subset U$, it remains to prove that $\bar{A} = \text{Cl}_X(A)$ is compact and is contained in U . This fact follows from Rem. 15.20. \square

Remark 15.20. Let W be a subset of a Hausdorff space Y . (In this section, we are mainly interested in the case that Y is the LCH space X and W is open. In this case, W is LCH by Prop. 8.41.) Let $A \subset W$, and recall $\bar{A} = \text{Cl}_Y(A)$. Then

$$A \text{ is precompact in } W \iff \bar{A} \text{ is compact, and } \bar{A} \subset W \quad (15.7)$$

Moreover, if A is precompact in W , then \bar{A} equals $\text{Cl}_W(A)$.

Note that if W is open, but if A is not precompact in W , then $\text{Cl}_Y(A)$ and $\text{Cl}_W(A)$ are not necessarily equal: take $Y = \mathbb{R}$ and $A = W = \mathbb{R}_{>0}$.

Proof. “ \Leftarrow ” is obvious from the definition of precompactness (recall Def. 8.39).

“ \Rightarrow ”: Clearly $\text{Cl}_W(A) \subset \bar{A}$ in general. Assume that A is a precompact subset of W . By Def. 8.39, we have $A \subset \text{Cl}_W(A) \subset W$ where $\text{Cl}_W(A)$ is compact. In particular, $\text{Cl}_W(A)$ is closed in Y (by Cor. 8.22). So $\bar{A} \subset \text{Cl}_W(A)$. So $\bar{A} = \text{Cl}_W(A)$. Thus \bar{A} is a compact subset of W since $\text{Cl}_W(A)$ is so. \square

Definition 15.21. Let W be a subset of a Hausdorff space Y . We write

$$A \in W \quad (15.8)$$

whenever A is a precompact subset of W , or equivalently, whenever $A \subset Y$ satisfies that $\text{Cl}_Y(A)$ is a compact subset of W .

15.4.1 Tietze extension theorem

The goal of this section is to prove the celebrated

Theorem 15.22 (Tietze extension theorem). *Let K be a compact subset of X . Let $f \in C(K, \mathcal{V})$. Then there exists $\tilde{f} \in C_c(X, \mathcal{V})$ such that $\tilde{f}|_K = f$, and that $\|\tilde{f}\|_{l^\infty(X, \mathcal{V})} = \|f\|_{l^\infty(K, \mathcal{V})}$.*

The reader can first assume this theorem and read Sec. 15.5 about the proof of SW theorem, and then return to this section to read the proof of Tietze extension theorem.

Remark 15.23. Tietze extension theorem is often used in the following form: Suppose that U is an open subset of X containing K . Applying Tietze extension to U (which is LCH by Prop. 8.41) and noticing Rem. 15.19, we see that every $f \in C(K, \mathcal{V})$ can be extended to some $\tilde{f} \in C_c(X, \mathcal{V})$ supported in U such that $\|\tilde{f}\|_{l^\infty(X, \mathcal{V})} = \|f\|_{l^\infty(K, \mathcal{V})}$. In other words, in Tietze extension theorem, we can assume that the extended function is compactly supported in a given open subset.

Corollary 15.24. $C_c(X, \mathbb{R})$ separates points of X .

Proof. Choose distinct points $x, y \in X$. Let $K = \{x, y\}$. Let $f : K \rightarrow \mathbb{R}$ such that $f(x) = 1$ and $f(y) = 0$. By Thm. 15.22, f can be extended to some $\tilde{f} \in C_c(X, \mathbb{R})$ which clearly separates x and y . \square

There is another version of Tietze extension theorem: If A is a closed subset of a normal topological space Y , then any $f \in C(A, \mathbb{R})$ can be extended to some $\tilde{f} \in C(Y, \mathbb{R})$ without increasing the l^∞ -norm. Its proof is not quite the same as the LCH version. See [Mun, Sec. 35]. We will not use this version in our course.

15.4.2 Urysohn's lemma

The proof of Tietze extension theorem involves several steps. The first step is to prove a special case: If $K \subset X$ is compact, then the characteristic function $\chi_K : X \rightarrow \mathbb{R}$ can be extended to a continuous $f \in C_c(X, \mathbb{R})$. Then $f|_K = 1$. Replacing f by $\max\{f, 0\}$, we may assume that $f \geq 0$. Replacing f by $\min\{f, 1\}$, we may assume $0 \leq f \leq 1$. This special case is called

Theorem 15.25 (Urysohn's lemma). *Let K be a compact subset of X . Then there exists f such that*

$$K < f < X \tag{15.9}$$

The meaning of the notations is explained below.

Definition 15.26. Let U be an open subset of X . Let K be a compact subset of X .

- $f < U$ means that $f \in C_c(X, [0, 1])$ (i.e. $f \in C_c(X, \mathbb{R})$ and $f(X) \subset [0, 1]$) and that $\text{Supp}(f) \subset U$.
- $K < f$ means that $f \in C_c(X, [0, 1])$ and that $f|_K = 1$.

The symbol “ $<$ ” is chosen for the following reason. Assume $f \in C_c(X, [0, 1])$. Then $K < f$ means that $\chi_K \leq f$. However, the meaning of $f < U$ is slightly stronger than that of $f \leq \chi_U$: the latter means that U contains $\{x : f(x) \neq 0\}$, but not that U contains its closure $\text{Supp}(f)$.

To prove Urysohn’s lemma we need some elementary observations:

Lemma 15.27. *Let W be an open subset of X . Let K be a compact subset of W . Then there exists an open set U of X such that $K \subset U \subseteq W$.*

By Rem. 15.20, this lemma simply means that every compact $K \subset W$ is contained in a precompact open subset of W . To prove it, it suffices to assume $X = W$.

Proof. We assume $X = W$. Since X is LCH, every $x \in K$ is contained in a precompact open subset U_x . Since K is compact, K is contained in $U = U_{x_1} \cup \cdots \cup U_{x_n}$ for some $x_1, \dots, x_n \in K$. Clearly U is open and precompact. \square

Recall Def. 14.17 for the meaning of $\omega(f, x)$, the oscillation of a function f at x .

Lemma 15.28. *Let Y be a topological space and Z a metric space. Let (f_n) be a sequence in Z^Y converging uniformly to $f \in Z^Y$. Assume that for each $x \in Y$, $\lim_{n \rightarrow \infty} \omega(f_n, x) = 0$. Then f is continuous.*

Note that Thm. 7.79 can be viewed as a special case of this lemma. However, this lemma is not used as often as Thm. 7.79. This is why we call this result only a lemma.

Proof. Choose any $\varepsilon > 0$. Then there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $\|f - f_n\|_\infty < \varepsilon$. Since $\lim_{n \rightarrow \infty} \omega(f_n, x) = 0$, there is $n \geq N$ such that $\omega(f_n, x) < \varepsilon$. Thus there exist $n \geq N$ and $U \in \text{Nbh}_X(x)$ such that $\text{diam}(f_n(U)) < \varepsilon$. Then by triangle inequality, we have $\text{diam}(f(U)) \leq 3\varepsilon$. So $\omega(f, x) \leq 3\varepsilon$. Since ε is arbitrary, we conclude $\omega(f, x) = 0$. So f is continuous at x by Prop. 14.18. \square

★ **Proof of Urysohn’s lemma.** By Lem. 15.27, we can choose $U_1 \subseteq X$ containing K . In the case that X is metrizable, $f(x) = d(x, U_1^c)/(d(x, K) + d(x, U_1^c))$ gives a desired function. However, in the general case, we need to construct f in a different way.

We shall construct inductively a sequence of functions $f_n : X \rightarrow [0, 1]$ such that the following conditions are satisfied:

- (a) $f_n|_K = 1$ and $f_n|_{X \setminus U_1} = 0$.
- (b) $\omega(f_n, x) \leq \frac{1}{2^n}$ for all $x \in X$.
- (c) $\|f_{n+1} - f_n\|_{l^\infty} \leq \frac{1}{2^{n+1}}$ for all n .

Then $\|f_{n+k} - f_n\|_\infty \leq 1/2^n$ for all $n, k > 0$. Thus $(f_n)_{n \in \mathbb{Z}_+}$ is a Cauchy sequence in $l^\infty(X, \mathbb{R})$, converging uniformly to some $f \in l^\infty(X, \mathbb{R})$. Clearly $f(X) \subset [0, 1]$, $f|_K = 1$, and $f|_{X \setminus U_1} = 0$. So f is compactly supported since \bar{U}_1 is compact. By Lem. 15.28, $f \in C_c(X, [0, 1])$, finishing the proof.

In fact, our construction of f_n relies on

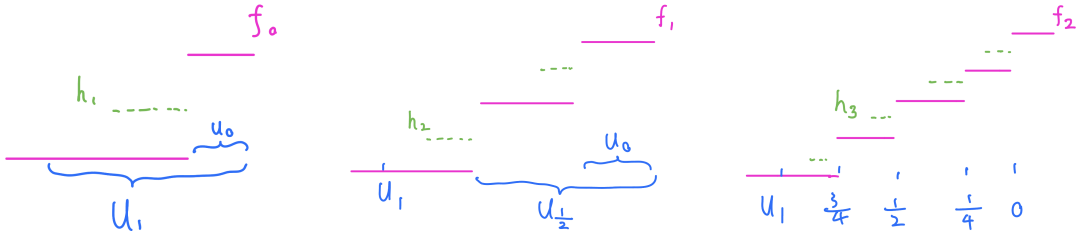
$$K \subset U_0 \subseteq U_{\frac{1}{2^n}} \subseteq U_{\frac{2}{2^n}} \subseteq \cdots \subseteq U_{\frac{2^{n-1}}{2^n}} \subseteq U_1$$

f_0 is simply defined to be χ_{U_0} where U_0 is a precompact open subset of U_1 containing K (which exists due to Lem. 15.27).

Suppose that f_n and $U_{\frac{j}{2^n}}$ (where $0 \leq j < 2^n$) have been constructed. Clearly $U_{\frac{j}{2^{n+1}}}$ already exists when j is even. Suppose that j is odd, let $U_{\frac{j}{2^{n+1}}}$ be a precompact open subset of $U_{\frac{j+1}{2^{n+1}}}$ containing the closure of $U_{\frac{j-1}{2^{n+1}}}$. Then $K \subset U_0 \subseteq U_{\frac{1}{2^{n+1}}} \subseteq U_{\frac{2}{2^{n+1}}} \subseteq \cdots \subseteq U_1$. Let

$$h_{n+1} = \sum_{\substack{0 < j < 2^{n+1} \\ j \text{ is odd}}} 2^{-n-1} \cdot \chi_{\Delta_j} \quad \text{where} \quad \Delta_j = U_{\frac{j}{2^{n+1}}} \setminus U_{\frac{j-1}{2^{n+1}}}$$

and let $f_{n+1} = f_n + h_{n+1}$. The best way to understand this construction is to look at the pictures:



Clearly (a) and (c) are satisfied. Choose any $x \in X$. For each n , let $U_{\frac{2^{n+1}}{2^n}} = X$ and $U_{-\frac{1}{2^n}} = \emptyset$. Then X is a disjoint union of $\Delta_j = U_{\frac{j}{2^{n+1}}} \setminus U_{\frac{j-1}{2^{n+1}}}$ over $0 \leq j \leq 2^{n+1}$, and f_n can be described by $f_n|_{\Delta_j} = \max\{1 - \frac{j}{2^n}, 0\}$. For each $x \in \Delta_j$ (where $1 \leq j \leq 2^n + 1$), let

$$W = U_{\frac{j}{2^n}} \setminus \overline{U_{\frac{j-2}{2^n}}}$$

Then $W \in \text{Nbh}_X(x)$, and $\text{diam}(f_n(W)) \leq \frac{1}{2^n}$ since $W \subset \Delta_j \cup \Delta_{j-1}$. If $x \in \Delta_0$, then $\Delta_0 \in \text{Nbh}(x)$ and $\text{diam}(f_n(\Delta_0)) = 0$. This proves (b). \square

15.4.3 Partition of unity

In the second step of the proof of Tietze extension theorem, we prove the theorem on partition of unity.

Recall that we defined Riemann integrals by partitioning a compact interval into small intervals. Thus, in order to define the integral of a function on \mathbb{R}^2 , one can partition a rectangle into smaller ones. However, it is more difficult to integrate a function defined on a more complicated space (a complicated compact surface M in \mathbb{R}^3 , for example) by dividing M into small pieces, since these small pieces may have complicated shapes.

Instead of partitioning M , a better way to define $\int_M f$ is by partitioning f . Let $f : M \rightarrow \mathbb{R}$ be continuous. Suppose first of all that $\text{Supp}(f)$ is contained in a small enough neighborhood U which can be “parametrized by a rectangle”. (More precisely: we can find a bijection $\varphi : R \rightarrow U$, where $R = (a, b) \times (c, d)$ is an open rectangle in \mathbb{R}^2 , such that φ and φ^{-1} are both smooth. Such φ is called a **diffeomorphism**.) Then we can use integrals on rectangles to define $\int_M f$ by “pulling back f to R ”. Now, in the general case, one can define $\int_M f$ by writing f as $f_1 + \cdots + f_n$ where each $f_i \in C(M, \mathbb{R})$ has a small enough support such that $\int_M f_i$ can be defined. Then $\sum_i \int_M f_i$ gives the formula of $\int_M f$.

Notice that it suffices to write the constant function 1 on M as $h_1 + \cdots + h_n$ where each $\text{Supp}(h_i)$ is small enough. Then $f = fh_1 + \cdots + fh_n$ gives a desired partition of f . Thus, $1 = h_1 + \cdots + h_n$ is called a **partition of unity** (where “unity” means the constant function 1).

Theorem 15.29. *Let K be a compact subset of X . Let $\mathfrak{U} = (U_1, \dots, U_n)$ be a finite set of open subsets of X covering K (i.e. $K \subset U_1 \cup \cdots \cup U_n$). Then there exist $h_1, \dots, h_n \in C_c(X, \mathbb{R})$ such that the following conditions hold:*

(1) *For each $1 \leq i \leq n$, we have $h_i \geq 0$ and $\text{Supp}(h_i) \subset U_i$.*

$$(2) \sum_{i=1}^n h_i|_K = 1.$$

$$(3) 0 \leq \sum_{i=1}^n h_i \leq 1.$$

*Such h_1, \dots, h_n are called a **partition of unity of K subordinate to \mathfrak{U}** .*

In the language of Def. 15.26, the assumptions on h_1, \dots, h_n are that $h_i < U_i$ for all i , and that $K < \sum_i h_i$.

Among the three conditions in Thm. 15.29, (1) and (2) are more important. In fact, many people only assume (1) and (2) in the definition of partition of unity. We assume (3) since it is also useful. (Note also that (3) is automatic when $X = K$.) Looking at the function $\sum_i h_i$, one easily sees that Urysohn’s lemma is a special case of Thm. 15.29. However, we shall prove Thm. 15.29 using Urysohn’s lemma. In fact, h_1, \dots, h_n should be viewed as a *partition of the Urysohn function $\sum_i h_i$* .

Proof. Step 1. Let us construct $G_i \in C_c(U_i, \mathbb{R}_{\geq 0})$ for each $1 \leq i \leq n$ such that $G := \sum_i G_i$ is > 0 on K (i.e., $G(K) \subset \mathbb{R}_{> 0}$).

By Urysohn's lemma, for each $x \in X$ there exists $g_x \in C_c(X, [0, 1])$ supported in U_i such that $g_x(x) \neq 0$. Since K is compact and is contained in $\bigcup_{x \in K} g_x^{-1}(\mathbb{R}_{>0})$, there exists a finite subset $E \subset K$ such that $K \subset \bigcup_{x \in E} g_x^{-1}(\mathbb{R}_{>0})$. So $\sum_{x \in E} g_x|_K > 0$.

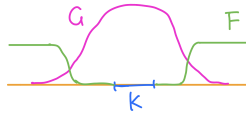
Now, for each $1 \leq i \leq n$, define

$$G_i = \sum_{\substack{x \in E \\ \text{Supp}(g_x) \subset U_i}} g_x \quad (15.10)$$

Since for each $x \in E$ there is some U_i containing $\text{Supp}(g_x)$, when summing up (15.10) over all i , each g_x must appear at least once in the summand. So $G := \sum_i G_i$ is $\geq \sum_i g_i$, and hence $G|_K > 0$. Clearly each G_i is ≥ 0 and is compactly supported in U_i .

Step 2. G_1, \dots, G_n satisfy (1) but not necessarily (2) or (3). It is tempting to define $h_i = G_i/G$. Then h_1, \dots, h_n satisfy all the desired conditions except the continuity. To remedy this issue, we define $h_i = G_i/\tilde{G}$, where $\tilde{G} \in C_c(X, \mathbb{R})$ satisfies that $\tilde{G} > 0$ on X , that $\tilde{G} \geq G$ (so that $0 \leq \sum_i h_i \leq 1$), and that $\tilde{G}|_K = G|_K$ (so that $\sum_i h_i|_K = 1$). Then h_1, \dots, h_n are the desired functions.

Let us prove the existence of such \tilde{G} . Let $W = \{x \in X : G(x) > 0\}$. Let $F \in C(X, [0, 1])$ such that $F|_K = 0$ and that $F|_{X \setminus W} = 1$. The existence of such $1 - F$ is ensured by Urysohn's lemma. Then one can let $\tilde{G} = G + F$.



□

15.4.4 How to use partition of unity

In Sec. 8.2, we have discussed how to use the condition of compactness: Suppose that K is compact and f is a function on K , for instance, a continuous one. To prove that f satisfies a global finiteness condition, we first prove that each $x \in K$ is contained in a neighborhood U_x on which f satisfies this finiteness condition. Then we pick finitely many U_{x_1}, U_{x_2}, \dots covering K , and show that f satisfies the finiteness condition globally.

To summarize, we can use compactness to prove many finiteness properties by a local-to-global argument. As pointed out in Sec. 8.2, usually, these finiteness properties can also be proved by contradiction using net-compactness or sequential compactness.

Now assume that K is a compact subset of the LCH space X , and let f be a function on K . With the help of partition of unity, one can construct new objects from f using a local-to-global argument. Moreover, these constructions are usually very difficult to obtain by using net-compactness or sequential compactness. The following are two typical examples:

1. (**Integral problems**) Construction of an integral $\int_K f$. This was already mentioned in Subsec. 15.4.3.
2. (**Extension problems**) Construct a “good” function \tilde{f} on X extending (or “approximately extending”) f . The idea is simple: Suppose that the extension exists locally, i.e., suppose that for each $x \in K$ there exists $U_x \in \text{Nbh}_X(x)$ such that $f|_{U_x \cap K}$ can be extended to a good function g_x on U_x . By compactness, K is covered by $\bigcup_{x \in E} U_x$ where E is a finite subset of K . Let $(h_x)_{x \in E}$ be a partition of unity of K subordinate to this open cover. Then $\tilde{f} = \sum_{x \in E} h_x \cdot g_x$ gives a good extension.

In the study of measure theory in the second semester, we will use partition of unity extensively. Readers who want to get a head start can do the problems in Subsec. 15.8.2, 15.8.3, and 15.8.4 to see how to build a theory of multivariable Riemann integrals using partitions of unity. For the moment, let's look at a simple example of extension problem before we prove the Tietze extension theorem. This example is not used elsewhere in this chapter, but it serves as a good illustration of how to use partitions of unity.

Example 15.30. Let I be an open interval in \mathbb{R} , and let K be a nonempty compact subset of I . Let $r \in \mathbb{Z}_+ \cup \{\infty\}$. Assume that $f : K \rightarrow \mathbb{R}$ is C^r , which means that for each $x \in K$ there exist an open interval $U_x \subset I$ containing x and $g_x \in C^r(U_x, \mathbb{R})$ extending $f|_{U_x \cap K}$. Then there exists $\tilde{f} \in C^r(I, \mathbb{R})$ extending f and is compactly supported in I .

This example is the **smooth Tietze extension theorem** in dimension 1, as mentioned in Rem. 13.46.

Proof. Let U_x and g_x be as in the example. Since K is compact, it can be covered by U_{x_1}, \dots, U_{x_n} . Call this open cover \mathcal{U} . Similar to the proof of Thm. 15.29, one can find a set of C^r -partition of unities h_1, \dots, h_n of K subordinate to \mathcal{U} . In other words, h_1, \dots, h_n are C^r functions and form a partition of unity. (Similar to the proof of Thm. 15.29, in order to find such h_1, \dots, h_n , it suffices to prove the C^r -version of Urysohn's lemma. But this has been done in Prop. 14.47, noting that K is contained in a compact subinterval of I .) Now each $h_i g_{x_i}$ is an C^r -function on I compactly supported in U_{x_i} . Then $\tilde{f} = \sum_i h_i g_{x_i}$ is a desired extension. \square

You will see many more examples in the future when you study differential manifolds and sheaf theory. It is no exaggeration to say that partition of unity is one of the most important techniques in modern mathematics.

15.4.5 Proof of Tietze extension theorem

Now you may wonder: Under the assumption of Tietze extension Thm. 15.22, we don't even know how to extend $f \in C(K, \mathbb{R})$ locally. Then how can we use

the local-to-global argument? Here is the answer: you can find an *approximate* extension locally. Therefore, you can first find an approximate global extension of f . Then, passing to the limit, you get the desired extension. This will be our strategy of the proof of Thm. 15.22.

Lemma 15.31. *Let K be a compact subset of X , and let $f \in C(K, \mathcal{V})$. Then for every ε , there exists $\varphi \in \text{Span}(C_c(X, \mathbb{R})\mathcal{V})$ such that*

$$\|f - \varphi\|_{l^\infty(K, \mathcal{V})} \leq \varepsilon \quad \|\varphi\|_{l^\infty(X, \mathcal{V})} \leq \|f\|_{l^\infty(K, \mathcal{V})}$$

The meaning of $\text{Span}(C_c(X, \mathbb{R})\mathcal{V})$ is clear: the smallest linear subspace of $C_c(X, \mathcal{V})$ containing $C_c(X, \mathbb{R})\mathcal{V}$. Thus

$$\text{Span}(C_c(X, \mathbb{R})\mathcal{V}) = \{g_1 v_1 + \cdots + g_n v_n : n \in \mathbb{Z}_+, g_i \in C_c(X, \mathbb{R}), v_i \in \mathcal{V}\} \quad (15.11)$$

Proof. Let $M = \|f\|_{l^\infty(K, \mathcal{V})}$. For each $p \in K$, since f is continuous at p , there exists $U_p \in \text{Nbh}_X(p)$ such that $\text{diam}(f(U_p \cap K)) \leq \varepsilon$ (cf. Prop. 14.18). Then the constant function $f(p)$ gives a local approximate extension of $f|_{U_p \cap K}$.

Since K is compact, there exists a finite subset $E \subset K$ such that K is covered by $\mathfrak{U} = \{U_p : p \in E\}$. By Thm. 15.29, there is a partition of unity $(h_p)_{p \in E}$ of K subordinate to \mathfrak{U} . Since $h_p \in C_c(U_p, \mathbb{R})$ can be viewed as a compactly supported continuous function on X (Rem. 15.19), the function $\varphi = \sum_{p \in E} h_p f(p)$ is an element of $C_c(X, \mathcal{V})$.

If $x \in K$, then since $h_p \geq 0$, we have

$$\|f(x) - \varphi(x)\| = \left\| \sum_{p \in E} h_p(x) \cdot (f(x) - f(p)) \right\| \leq \sum_{p \in E} h_p(x) \|f(x) - f(p)\|$$

In the RHS, if $h_p(x) \neq 0$, then $x \in U_p$, and hence $\|f(x) - f(p)\| \leq \varepsilon$. So the RHS is no greater than $\sum_{p \in E} h_p(x) \varepsilon$, and hence no greater than ε since $\sum_{p \in E} h_p(x) = 1$. Finally, for every $x \in X$, we have

$$\|\varphi(x)\| \leq \sum_{p \in E} h_p(x) \|f(p)\| \leq \sum_{p \in E} h_p(x) M = M$$

finishing the proof. □

The following special case of Lem. 15.31 is more useful for application.

Proposition 15.32. *Assume that X is a compact Hausdorff space, and let $f \in C(X, \mathcal{V})$. Then for every $\varepsilon > 0$, there exists $\varphi \in \text{Span}(C_c(X, \mathbb{F})\mathcal{V})$ such that $\|f - \varphi\|_\infty < \varepsilon$.*

Corollary 15.33. *Let X, Y be compact Hausdorff spaces. Then for every $f \in C(X \times Y, \mathbb{F})$ and $\varepsilon > 0$, there exist $g_1, \dots, g_n \in C(X, \mathbb{F})$ and $h_1, \dots, h_n \in C(Y, \mathbb{F})$ such that $\|f - g_1 h_1 - \cdots - g_n h_n\|_{l^\infty(X \times Y, \mathbb{F})} < \varepsilon$.*

Proof. By Thm. 9.3, we view f as an element of $C(X, \mathcal{V})$ where $\mathcal{V} = C(Y, \mathbb{R})$. Then the corollary follows immediately from Prop. 15.32. From this proof, we see that it is not necessarily to assume that Y is Hausdorff. (This is not an important fact anyway.) \square

Now we are ready to finish the

Proof of Tietze extension Thm. 15.22. Recall that K is compact in X and $f \in C(K, \mathcal{V})$, and that our goal is to extend f to $\tilde{f} \in C_c(X, \mathcal{V})$. Moreover, we need that $\|\tilde{f}\|_{l^\infty(X, \mathcal{V})}$ equals $M = \|f\|_{l^\infty(K, \mathcal{V})}$. We first note that the last requirement is easy to meet. Assume WLOG that $M > 0$. Let $\tilde{f} \in C_c(X, \mathcal{V})$ extend f , and define $g : X \rightarrow \mathbb{R}_{\geq 0}$ by $g(x) = \max\{M, \|\tilde{f}(x)\|\}$. Then g is continuous, $g \geq M$, and $g|_K = M$. Then $M\tilde{f}/g$ is an element of $C_c(X, \mathcal{V})$ extending f and is l^∞ -bounded by M , finishing the proof.

Second, note that it suffices to extend f to $\tilde{f} \in C(X, \mathcal{V})$. By Urysohn lemma, there exists h such that $K < h < X$. Then $\tilde{f}h \in C_c(X, \mathcal{V})$ extends f .

We now construct $\tilde{f} \in C(X, \mathcal{V})$ extending f . By Lem. 15.31, there exist $\varphi_1, \varphi_2, \dots \in C_c(X, \mathcal{V})$ such that

$$\begin{aligned} \|f - \varphi_1\|_{l^\infty(K, \mathcal{V})} &\leq \frac{M}{2} & \|\varphi_1\|_{l^\infty(X, \mathcal{V})} &\leq M \\ \|f - \varphi_1 - \varphi_2\|_{l^\infty(K, \mathcal{V})} &\leq \frac{M}{4} & \|\varphi_2\|_{l^\infty(X, \mathcal{V})} &\leq \frac{M}{2} \\ \|f - \varphi_1 - \varphi_2 - \varphi_3\|_{l^\infty(K, \mathcal{V})} &\leq \frac{M}{8} & \|\varphi_3\|_{l^\infty(X, \mathcal{V})} &\leq \frac{M}{4} \\ &\vdots \end{aligned}$$

Then $\sum_{n=1}^{\infty} \|\varphi_n\|_{l^\infty(X, \mathcal{V})} \leq 2M$, and hence $\sum_{n=1}^{\infty} \varphi_n$ converges to some \tilde{f} in the Banach space $C(X, \mathcal{V}) \cap l^\infty(X, \mathcal{V})$ (Cor. 3.50). Clearly \tilde{f} extends f . \square

15.5 Proof of SW, II: embedding into $[0, 1]^{\mathcal{I}}$

In this section, we shall finish the proof of SW Thm. 15.9.

Remark 15.34. Suppose that $\Phi : X \rightarrow Y$ is a homeomorphism of topological spaces. Then X and Y can be “viewed as the same space” via Φ . This means that a point $x \in X$ can be identified with $\Phi(x) \in Y$, that an open or closed subset $A \subset X$ can be identified with $\Phi(A)$, which is open or closed in Y . It also means, for example, that if $A \subset X$, then the closure of A can be identified with the closure of $\Phi(A)$ in Y . More precisely: Φ restricts to a homeomorphism $\text{Cl}_X(A) \rightarrow \text{Cl}_Y(\Phi(A))$.

The continuous functions of X and Y can also be identified: If $g \in C(Y, Z)$ where Z is a topological space (e.g. $Z = \mathbb{R}$), then g is equivalent to its **pullback**

under Φ , which is an element of $C(X, Z)$ given by

$$\Phi^*g := g \circ \Phi \quad \in C(X, Z) \quad (15.12)$$

This equivalence of functions can be illustrated by the commutative diagram

$$\begin{array}{ccc} X & \xrightarrow[\simeq]{\Phi} & Y \\ & \searrow \Phi^*g & \swarrow g \\ & Z & \end{array} \quad (15.13)$$

□

Proof of SW Thm. 15.9. Recall that X is a compact Hausdorff space and \mathcal{A} is a unital subalgebra of $C(X, \mathbb{R})$ separating points of X . For each $f \in \mathcal{A}$, let $M_f = \|f\|_\infty$ and $I_f = [-M_f, M_f]$. Define

$$\Phi : X \rightarrow S = \prod_{f \in \mathcal{A}} I_f \quad x \mapsto (f(x))_{f \in \mathcal{A}}$$

In other words, $\Phi = \bigvee_{f \in \mathcal{A}} f$, using the notation in Pb. 7.8. Thus, by Pb. 7.8 (or by Thm. 7.73), Φ is continuous. The fact that \mathcal{A} separates points of X is equivalent to that Φ is injective. Since X is compact, by Thm. 8.23, Φ restricts to a homeomorphism $\Phi : S \rightarrow \Phi(S)$.

Recall that the coordinate function $\pi_f : S \rightarrow I_f$ is the projection onto the f -component. So $\Phi^*\pi_f = \pi_f \circ \Phi = f$. Therefore, by Rem. 15.34, X is equivalent to $\Phi(X)$ under Φ , and $\pi_f|_{\Phi(X)} \in C(\Phi(X), \mathbb{R})$ is equivalent to $f \in C(X, \mathbb{R})$ under Φ . Therefore, we can identify X with $\Phi(X)$ via Φ so that f is identified with $\pi_f|_{\Phi(X)}$. Thus, in this case, \mathcal{A} is the set of all $\pi_f|_X$, and clearly \mathcal{A} contains all the polynomials of the coordinate functions $\{\pi_f|_X : f \in \mathcal{A}\}$ since \mathcal{A} is a unital subalgebra. Thus, it suffices to prove that the polynomials of coordinate functions are dense in $C(X, \mathbb{R})$.

Choose any $g \in C(X, \mathbb{R})$. Since X is compact, and since S is a compact Hausdorff space (by Tychonoff Thm. 15.15), by Tietze extension Thm. 15.22, g can be extended to $\tilde{g} \in C(S, \mathbb{R})$. By Prop. 15.16, \tilde{g} can be approximated uniformly by the polynomials of coordinate functions of S . □

Remark 15.35. If you feel that identifying X and $\Phi(X)$ is cheating, it is easy to revise the proof without identifying them: Choose any $g \in C(X, \mathbb{R})$. One first concludes that $g \circ \Phi^{-1} \in C(\Phi(X), \mathbb{R})$ can be uniformly approximated by the polynomials of coordinate functions. Then, since the pullback of these polynomials under Φ are elements of \mathcal{A} , one concludes that g can be approximated uniformly by elements of \mathcal{A} .

15.6 Summary of the proof of SW

The key steps of the proof of SW Thm. 15.9 are as follows.

1. We first prove the case that X is a compact interval I and \mathcal{A} is the polynomial algebra: Let $f \in C(I, \mathbb{R})$, and extend f to an element in $C_c(\mathbb{R}, \mathbb{R})$. Let $g(x) = \pi^{-\frac{1}{2}}e^{-x^2}$ and $g_\varepsilon(x) = \varepsilon^{-1}g(x/\varepsilon)$. On the one hand, $\lim_{\varepsilon \rightarrow 0} f * g_\varepsilon$ converges uniformly to f . On the other hand, for each ε , since g_ε is approximated by polynomials uniformly on compact intervals (consider the Taylor series of g_ε), one shows that $f * g_\varepsilon$ is also approximated by polynomials uniformly on compact intervals.
2. When \mathcal{V} is a Banach space, the same method shows that $\mathcal{V}[x]$, the set of polynomials with coefficients in \mathcal{V} , is l^∞ -dense in $C(I, \mathcal{V})$.
3. Taking $\mathcal{V} = C(J, \mathbb{R})$ where J is a compact interval, the above step shows that polynomials are dense in $C(I \times J, \mathbb{R})$.² Similarly, by induction, one sees that polynomials are dense in $C(I_1 \times \cdots \times I_n, \mathbb{R})$ if each I_j is a compact interval.
4. Let $S = \prod_{\alpha \in \mathcal{J}} I_\alpha$ where each I_α is a compact interval. Then S is a compact Hausdorff space by the Tychonoff theorem. One shows that any $f \in C(S, \mathbb{R})$ can be approximated by a function g depending on finitely many variables (Lem. 15.18, or Pb. 9.6 when \mathcal{J} is countable). By the previous step, g can be approximated by polynomials. So f can be approximated by polynomials (of coordinate functions of S).
5. Let X be a compact subset of $S = \prod_{\alpha \in \mathcal{J}} I_\alpha$, and let $f \in C(X, \mathbb{R})$. Then by the Tietze extension theorem, f can be extended to $\tilde{f} \in C(S, \mathbb{R})$ where \tilde{f} can be approximated by polynomials by the previous step. So f can be approximated by polynomials.
6. Now let X be a compact Hausdorff space, and let \mathcal{A} be a unital subalgebra of $C(X, \mathbb{R})$ separating points of X . Then the map $\Phi = \bigvee_{f \in \mathcal{A}} f$ maps X homeomorphically to a compact subspace of $S = \prod_{\alpha \in \mathcal{A}} I_f$ where $I_f = [-\|f\|_\infty, \|f\|_\infty]$. By the previous step, continuous functions on $\Phi(X)$ can be approximated by polynomials of the coordinate functions of S . This is equivalent to the density of \mathcal{A} in $C(X, \mathbb{R})$. The proof is complete.

The proof we have given, which is different from the proofs in most textbooks, has several advantages. First, it clearly shows that " \mathcal{A} separates points of X " is an embedding condition, which ensures that the map $\Phi = \bigvee_{f \in \mathcal{A}} f$ is injective.

²Instead of using step 2, one can also use step 1 and the fact that elements in $C(I \times J, \mathbb{R})$ can be approximated by those of the form $f_1 g_1 + \cdots + f_n g_n$ where $f_i \in C(I, \mathbb{R})$ and $g_i \in C(J, \mathbb{R})$, cf. Cor. 15.33.

The embedding of spaces is a common theme in many branches of mathematics. In differential geometry, one can show that every (second countable) smooth manifold can be smoothly embedded into a Euclidean space. (This is the **Whitney embedding theorem**.) **Projective manifolds**, the compact complex manifolds that can be holomorphically embedded into complex projective spaces \mathbb{CP}^n , are among the most important examples in complex (algebraic) geometry.

Second, Urysohn's lemma and partition of unity are extremely important tools in differential manifolds and in measure theory, both of which will be studied next semester.

Thus, although our proof is longer than those in the other textbooks,³ the methods we used in the proof (convolutions, embedding of spaces, partition of unity, etc.) will appear frequently in the future study. Through our proof, the SW theorem is closely and organically related to other mathematical concepts.

We close this section with an immediate consequence of the proof of SW theorem, which is parallel to Thm. 8.45.

Theorem 15.36. *Let X be a topological space. Then the following are equivalent.*

- (1) X is a compact Hausdorff space.
- (2) X is homeomorphic to a closed subset of $[0, 1]^{\mathcal{J}}$ for some set \mathcal{J} .

Proof. Clearly $[0, 1]^{\mathcal{J}}$ is Hausdorff. By Tychonoff Thm. 15.15, $[0, 1]^{\mathcal{J}}$ is compact. So its closed subsets are compact Hausdorff. Conversely, let X be compact Hausdorff. By Cor. 15.24, $C(X, \mathbb{R})$ separates points of X . Thus there is a subset $\mathcal{J} \subset C(X, \mathbb{R})$ separating points of X such that $f(X) \subset [-1, 1]$ for all $f \in \mathcal{J}$. Therefore $\Phi = \bigvee_{f \in \mathcal{J}} f : X \rightarrow [-1, 1]^{\mathcal{J}}$ is a continuous injective map of X into $[-1, 1]^{\mathcal{J}}$. So it reduces to a homeomorphism $X \rightarrow \Phi(X)$ by Thm. 8.23. \square

15.7 Application: separability of $C(X, \mathbb{R})$

Our proof of SW theorem relies on Tychonoff Thm. 15.15, which in turn relies on Zorn's lemma, an uncountable version of mathematical induction. Though Zorn's lemma is equivalent to the axiom of choice, it is much more difficult to grasp intuitively than mathematical induction. Thus, one would like to find a proof without using Zorn's lemma if possible.

In the following, we will show that when the compact Hausdorff space X is second countable (equivalently, metrizable), in the proof of SW theorem, it suffices

³The proofs in most textbooks (e.g. [Fol-R, Sec. 4.7], [Rud-P, Ch. 7], [Zor-2, Sec. 16.4]) are similar and are due to M. Stone [Sto48], which used the idea of lattices. A lattice is a set L together with operations \wedge, \vee satisfying $a \vee (a \wedge b) = a$ and $a \wedge (a \vee b) = a$. In analysis, one considers $L \subset C(X, \mathbb{R})$ where $f \vee g = \max\{f, g\}$ and $f \wedge g = \min\{f, g\}$. In Stone's day, lattices were relatively popular in functional analysis. But today it seems that they are a bit cold. The shorter proof in [Sto48] is actually not the original proof of SW theorem. The original proof was given in [Sto37] and is much more complicated.

to embed X into a countable product of compact intervals. The latter is compact by countable Tychonoff theorem, whose proof does not rely on Zorn's lemma (cf. Thm. 3.54 or Pb. 8.7).

We first discuss a general fact about countability in compact Hausdorff spaces. The following theorem is one of the most important general properties about separability: It tells us that for a compact Hausdorff space X , the countability property of the topology of X is equivalent to that of the uniform convergence topology of $C(X, \mathbb{R})$. This is in stark contrast to compactness, where the compactness of X does not in general imply the compactness of bounded closed subsets of $C(X, \mathbb{R})$ (cf. Exp. 17.1).

Theorem 15.37. *Let X be a compact Hausdorff space. The following are equivalent.*

- (1) X is metrizable.
- (2) X is second countable.
- (3) $C(X, \mathbb{R})$ is separable (equivalently, second countable, cf. Prop. 8.32).

Here, as usual, $C(X, \mathbb{R})$ is equipped with the l^∞ -norm. See Pb. 15.14 for a generalization of Thm. 15.37 to LCH spaces. Also, assuming (3), one can write down a metric and a countable basis explicitly; see Pb. 15.15 for details.

Proof. By Thm. 8.45, we have $(1) \Leftrightarrow (1')$ where

- (1') X is homeomorphic to a closed subset of $[0, 1]^{\mathbb{Z}_+}$.

Let us prove that (2) and (3) are equivalent to (1').

(1') \Rightarrow (3): By Tietze extension theorem, it suffices to prove that $C(S, \mathbb{R})$ is separable where $S = [0, 1]^{\mathbb{Z}_+}$. Let $\mathcal{E} = \mathbb{Q}[\{\pi_n : n \in \mathbb{Z}_+\}]$ be the set of polynomials of the coordinate functions of S with coefficients in \mathbb{Q} . ($\pi_n : S \rightarrow [0, 1]$ is the projection onto the n -th component.) Then \mathcal{E} is countable (cf. Exe. 15.38), and is clearly dense in $\mathbb{R}[\{\pi_n : n \in \mathbb{Z}_+\}]$. By Prop. 15.16, \mathcal{E} is dense in $C(S, \mathbb{R})$.

(3) \Rightarrow (1'): Let $\mathcal{E} = \{f_1, f_2, \dots\}$ be a countable dense subset of $C(X, \mathbb{R})$. By enlarging \mathcal{E} , we assume WLOG that \mathcal{E} is infinite. By Cor. 15.24, $C(X, \mathbb{R})$ separates points of X . So \mathcal{E} also separates points of X . We scale $f_n \in \mathcal{E}$ by a nonzero real number such that $\|f_n\|_\infty \leq 1$. Then

$$\Phi : X \rightarrow [-1, 1]^{\mathbb{Z}_+} \quad x \mapsto (f_1(x), f_2(x), \dots) \quad (15.14)$$

is a continuous injective map, restricting to a homeomorphism $X \rightarrow \Phi(X)$ where $\Phi(X)$ is a compact (and hence closed) subset of $[-1, 1]^{\mathbb{Z}_+} \simeq [0, 1]^{\mathbb{Z}_+}$.

(1') \Rightarrow (2): Since $[0, 1]$ is separable and hence second countable, by Pb. 8.13, $[0, 1]^{\mathbb{Z}_+}$ is second countable. So its subsets are second countable by Prop. 8.29.⁴

⁴Alternatively, one can also use Thm. 8.34 to prove directly (1) \Rightarrow (3). However, as the reader can feel in Rem. 8.35, I personally don't like the proof of Thm. 8.34. I would rather *define* a metrizable compact space to be a topological space homeomorphic to a closed subset of $[0, 1]^{\mathbb{Z}_+}$: adopting this definition, the proof of second countability will be more intuitive and less tricky. And after all, the method in the proof of Thm. 8.34 will never be used in the future.

(2) \Rightarrow (1'): Let $(U_n)_{n \in \mathbb{Z}_+}$ be an infinite countable basis of the topology of X . For each $m, n \in \mathbb{Z}_+$, if $\overline{U}_n \subset U_m$, we choose $f_{m,n}$ such that $\overline{U}_n < f < U_m$ (which exists by Urysohn lemma); otherwise, we let $f_{m,n} = 0$. Then $\{f_{m,n} : m, n \in \mathbb{Z}_+\}$ separates points of X . (Proof: Choose distinct $x, y \in X$. Since $X \setminus \{y\} \in \text{Nbh}_X(x)$, there exists U_m containing x and is contained in $X \setminus \{y\}$. By Lem. 15.27, there is n such that $\{x\} \subset U_n \subset U_m$. Then $f_{m,n}(x) = 1$ and $f_{m,n}(y) = 0$.) Thus, as in (15.14), the map

$$X \rightarrow [0, 1]^{\mathbb{Z}_+ \times \mathbb{Z}_+} \quad x \mapsto (f_{m,n}(x))_{m,n \in \mathbb{Z}_+}$$

restricts to a homeomorphism from X to a compact subset of $[0, 1]^{\mathbb{Z}_+ \times \mathbb{Z}_+}$. \square

Exercise 15.38. Let \mathcal{A} be a unital \mathbb{R} -algebra (resp. unital \mathbb{C} -algebra). Let \mathbb{K} be \mathbb{Q} (resp. $\mathbb{Q} + i\mathbb{Q}$). Let x_1, x_2, \dots be a possibly finite sequence of elements of \mathcal{A} . Let $\mathcal{E} = \mathbb{K}[x_1, x_2, \dots]$ be the set of polynomials of x_1, x_2, \dots with coefficients in \mathbb{K} . Prove that \mathcal{E} is a countable set.

Remark 15.39. Note that Prop. 15.16 is used (and is only used) in the proof of (1') \Rightarrow (3) of Thm. 15.37. Our proof of Thm. 15.37 relies on Tychonoff theorem, which in turn relies on Zorn's lemma. However, in the proof of (1') \Rightarrow (3) we only consider countable products of integrals. In this special case, the proof of Tychonoff theorem uses mathematical induction but not Zorn's lemma. (See the proof of Thm. 3.54 or Pb. 8.7.) Therefore, our proof of Thm. 15.37 does not rely on Zorn's lemma.

Remark 15.40. Since the proof of Prop. 15.16 uses Weierstrass approximation Thm. 14.45, the proof of " \Rightarrow (3)" in Thm. 15.37 also relies on Thm. 14.45. This is as expected. In fact, even if one wants to prove that $C([0, 1], \mathbb{R})$ is separable, one needs Thm. 14.45. (See Cor. 14.46.) Therefore, it is fair to say that the separability of $C(X, \mathbb{R})$ is one of the most important applications of Weierstrass approximation (or SW) theorem.

Claim 15.41. *If X is a compact Hausdorff space satisfying one of the equivalent conditions in Thm. 15.37, then the SW Thm. 15.9 can be proved without using Zorn's lemma.*

Proof. Let \mathcal{A} be a unital subalgebra of $C(X, \mathbb{R})$ separating points of X . Since $C(X, \mathbb{R})$ is separable (equivalently, second countable), so is \mathcal{A} (by Prop. 8.29). Therefore, \mathcal{A} has a countable dense subset $\mathcal{E} = \{f_1, f_2, \dots\}$ which clearly separates points of X . By enlarging \mathcal{E} we assume that it is infinite. So (15.14) restricts to a homeomorphism from X to a closed subset of $S = [0, 1]^{\mathbb{Z}_+}$. As in the proof of (1') \Rightarrow (3) of Thm. 15.37, the polynomials of the coordinate functions of S , when restricted to $\Phi(X)$, form a dense subset of $C(\Phi(X), \mathbb{R})$. Pulling back this result to X , we conclude that polynomials of f_1, f_2, \dots (which are in \mathcal{A}) form a dense subset of $C(X, \mathbb{R})$. \square

15.8 Problems and supplementary material

We always let \mathcal{V} be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

15.8.1 SW theorems for LCH spaces

Problem 15.1. Let X be an LCH space with topology \mathcal{T} . Define a set $X^* = X \cup \{\infty\}$ where ∞ is a new symbol not in X .

1. Prove that the set

$$\mathcal{U} = \mathcal{T} \cup \{X^* \setminus K : K \subset X \text{ is compact}\}$$

is a basis for a topology on X^* . Let \mathcal{T}^* be the topology on X^* generated by \mathcal{U} . Prove that \mathcal{T} is the subspace topology of \mathcal{T}^* . (Namely, prove that $U \subset X$ is open iff $U = X \cap V$ for some open $V \subset X^*$.)

2. Prove that (X^*, \mathcal{T}^*) is a compact Hausdorff space. We call (X^*, \mathcal{T}^*) (or simply call X^*) the **one-point compactification** of X .
3. Prove that if X is not compact, then X is dense in X^* .

More generally, we define:

Definition 15.42. Let X be LCH. A **one-point compactification (OPC)** of X is a compact Hausdorff space \hat{X} , together with an injective map $\varphi : X \rightarrow \hat{X}$ such that $\hat{X} \setminus \varphi(X)$ has exactly one element, and that φ restricts to a homeomorphism $\varphi : X \rightarrow \varphi(X)$. In particular, the X^* constructed in Pb. 15.1 is a one-point compactification of X .

Problem 15.2. Prove the uniqueness of one-point compactifications in the following sense. Let X be LCH with one-point compactifications (\hat{X}, φ) and (\tilde{X}, ψ) . Then there is a unique homeomorphism $\Phi : \hat{X} \rightarrow \tilde{X}$ such that the following diagram commutes:

$$\begin{array}{ccc} & X & \\ \varphi \swarrow & & \searrow \psi \\ \hat{X} & \xrightarrow[\simeq]{\Phi} & \tilde{X} \end{array} \quad (15.15)$$

Example 15.43. If X is compact Hausdorff and contains at least two points, then for every $p \in X$, the subset $X \setminus \{p\}$ has OPC X (together with the inclusion map). Thus $[0, 1]$ has OPC $[0, 1] \cup \{2\}$. $(0, 1]$ has OPC $[0, 1]$. $(0, 1)$ has OPC \mathbb{S}^1 (the unit circle in \mathbb{C}) together with the map $\varphi : x \in (0, 1) \mapsto e^{2i\pi x} \in \mathbb{S}^1$.

Convention 15.44. Let X be LCH and $f : X \rightarrow \mathcal{V}$. According to part 3 of Pb. 15.1, when X is not compact, the limit of functions $\lim_{x \rightarrow \infty} f$ makes sense. In the case that X is compact, we understand $\lim_{x \rightarrow \infty} f$ as 0.

Definition 15.45. Let X be LCH with one-point compactification X^* . Define

$$C_0(X, \mathcal{V}) = \{f \in C(X, \mathcal{V}) : \lim_{x \rightarrow \infty} f(x) = 0\} \quad (15.16)$$

Since $\{X^* \setminus K : K \subset X \text{ is compact}\}$ is a neighborhood basis of $\infty \in X^*$ (recall Def. 7.115), by Def. 7.81-(2), it is clear that $f \in C(X, \mathcal{V})$ belongs to $C_0(X, \mathcal{V})$ iff

for every $\varepsilon > 0$ there exists a compact $K \subset X$ such that
for each $x \in X \setminus K$ we have $\|f(x)\| < \varepsilon$

For each $f : X \rightarrow \mathcal{V}$ define $\tilde{f} : X^* \rightarrow \mathcal{V}$ where

$$\tilde{f}(x) = \begin{cases} f(x) & \text{if } x \in X \\ 0 & \text{if } x = \infty \end{cases} \quad (15.17)$$

Then by Def. 7.81-(1), \tilde{f} is continuous at ∞ iff $\lim_{x \rightarrow \infty} f(x) = 0$. Thus, we have

$$C_0(X, \mathcal{V}) = \{\tilde{f}|_X : \tilde{f} \in C(X^*, \mathcal{V}) \text{ and } \tilde{f}(\infty) = 0\} \quad (15.18)$$

Proposition 15.46. Let X be LCH with one-point compactification X^* . Then we have an linear isometry of Banach spaces (under the l^∞ -norms)

$$C_0(X, \mathcal{V}) \rightarrow C(X^*, \mathcal{V}) \quad f \mapsto \tilde{f} = (15.17) \quad (15.19)$$

Proof. Clearly $\|f\|_{l^\infty(X, \mathcal{V})} = \|\tilde{f}\|_{l^\infty(X^*, \mathcal{V})}$. So (15.19) is a linear isometry. The range of (15.19) is $\{g \in C(X^*, \mathcal{V}) : g(\infty) = 0\}$, which is clearly a closed subset of the Banach space $C(X, \mathcal{V})$ and hence is complete by Prop. 3.27. \square

Convention 15.47. According to Prop. 15.46, people often identify $C_0(X, \mathcal{V})$ with its image under (15.19), i.e., identify $f \in C_0(X, \mathcal{V})$ with \tilde{f} defined by (15.17).

Problem 15.3. Let Y be a compact Hausdorff space. Let E be a closed subspace of Y . Prove that

$$C_0(Y \setminus E, \mathcal{V}) = \{g|_{Y \setminus E} : g \in C(Y, \mathcal{V}), g|_E = 0\}$$

Theorem 15.48 (SW theorem, LCH real version). Let X be an LCH space. Let \mathcal{A} be a subalgebra of $C_0(X, \mathbb{R})$. Assume that \mathcal{A} separates points of X . Assume that \mathcal{A} *vanishes nowhere on* X (i.e. for every $x \in X$ there is $f \in \mathcal{A}$ such that $f(x) \neq 0$). Then \mathcal{A} is dense in $C_0(X, \mathbb{R})$ (under the l^∞ -norm).

Problem 15.4. Prove the above SW theorem by following the steps below. Let $X^* = X \cup \{\infty\}$ be the one-point compactification of X . By Conv. 15.47, \mathcal{A} is naturally a subalgebra of $C(X^*, \mathbb{R})$. Define

$$\mathcal{B} = \{f + \lambda : f \in \mathcal{A}, \lambda \in \mathbb{R}\}$$

which is a unital subalgebra of $C(X^*, \mathbb{R})$. Use SW Thm. 15.9 to prove that \mathcal{B} is dense in $C(X^*, \mathbb{R})$. Use this fact to prove that \mathcal{A} is dense in $C_0(X, \mathbb{R})$.

Theorem 15.49 (SW theorem, LCH complex version). Let X be an LCH space. Let \mathcal{A} be a $*$ -subalgebra of $C_0(X, \mathbb{C})$. Assume that \mathcal{A} separates points of X . Assume that \mathcal{A} vanishes nowhere on X . Then \mathcal{A} is dense in $C_0(X, \mathbb{C})$ (under the l^∞ -norm).

Proof. This follows from the LCH real version, just as the compact complex version of SW theorem (Thm. 15.11) follows from the compact real version (Thm. 15.9). \square

Problem 15.5. Let X be LCH. Prove that $C_c(X, \mathcal{V})$ is dense in $C_0(X, \mathcal{V})$. (This proves that $C_0(X, \mathcal{V})$ is the Banach space completion of $C_c(X, \mathcal{V})$.) Conclude that $C_0(X, \mathcal{V})$ is separable iff $C_c(X, \mathcal{V})$ is separable.

Hint. Use Urysohn's lemma or Tietze extension. \square

Definition 15.50. Let \mathcal{A} be an \mathbb{F} -algebra. A subset $J \subset \mathcal{A}$ is called an **ideal** if J is an \mathbb{F} -linear subspace of \mathcal{A} such that $\mathcal{A}J \subset J$ (i.e. $xy \in J$ for all $x \in \mathcal{A}, y \in J$).

The following problem gives an interesting application of SW Thm. 15.48.

★ Problem 15.6. (Nullstellensatz) Let X be a compact Hausdorff space. For each closed subset $A \subset X$, let

$$I(A) = \{f \in C(X, \mathbb{R}) : f|_A = 0\}$$

Clearly $I(A)$ is a closed ideal of $C(X, \mathbb{R})$. For each closed ideal J of $C(X, \mathbb{R})$, let

$$N(J) = \{x \in X : f(x) = 0 \text{ for all } f \in J\}$$

which is a closed subset of X . Prove that $A \mapsto I(A)$ gives a bijection between the closed subsets of A and the closed ideals of $C(X, \mathbb{R})$, and that its inverse map is $J \mapsto N(J)$. In other words, for every closed subset $A \subset X$ and every closed ideal $J \subset C(X, \mathbb{R})$, prove that

$$N(I(A)) = A \quad I(N(J)) = J \quad (15.20)$$

Hint. For both parts of (15.20) it is easy to prove " \supset ". To prove $N(I(A)) = A$, use Urysohn's lemma or the Tietze extension theorem. To prove $I(N(J)) = J$, identify $I(N(J))$ with $C_0(X \setminus N(J), \mathbb{R})$ (cf. Pb. 15.3) and apply SW Thm. 15.48 to the LCH space $X \setminus N(J)$. \square

15.8.2 Lebesgue measures of open sets

The theory of Riemann integrals on \mathbb{R} can be easily generalized to \mathbb{R}^N by partitioning boxes, i.e. $I_1 \times \cdots \times I_N$ where each I_j is a compact interval in \mathbb{R} . In the following, we establish the basic theory of Riemann integrals on bounded subsets of \mathbb{R}^N using partitions of unity. Compared to partitioning boxes, the methods provided below are closer to those in measure theory.

Definition 15.51. If $f \in C_c(\mathbb{R}^N, \mathbb{R})$, define $\int f \equiv \int_{\mathbb{R}} f = \int_B f$ where $B \subset \mathbb{R}^N$ is any box containing $\text{Supp}(f)$. (See Def. 14.3.)

Problem 15.7. Let U be an open subset of \mathbb{R}^N . Define the **(Lebesgue) measure** of U to be

$$\mu(U) = \sup \left\{ \int_{\mathbb{R}^N} f : f \in C_c(U, [0, 1]) \right\} \quad (15.21)$$

which is an element of $\overline{\mathbb{R}}_{\geq 0}$. It is clear that if V is an open subset of U then $\mu(V) \leq \mu(U)$.

1. In the case that $N = 1$ and $U = (a, b)$ (where $-\infty \leq a < b \leq +\infty$), prove that $\mu(U) = b - a$.
2. Suppose that U has compact closure. Prove that $\mu(U) < +\infty$. (Hint: use Urysohn's lemma.)
3. Let $(U_\alpha)_{\alpha \in \mathcal{A}}$ be an increasing net of open subsets of \mathbb{R}^N . Prove

$$\mu\left(\bigcup_{\alpha \in \mathcal{A}} U_\alpha\right) = \sup_{\alpha \in \mathcal{A}} \mu(U_\alpha)$$

4. Let $(V_j)_{j \in \mathcal{J}}$ be a (non-necessarily increasing) family of open subsets of \mathbb{R}^N . Prove that

$$\mu\left(\bigcup_{j \in \mathcal{J}} V_j\right) \leq \sum_{j \in \mathcal{J}} \mu(V_j)$$

(Hint: Use part 3 to reduce to the special case $\mu(U \cup V) \leq \mu(U) + \mu(V)$. Prove it using partition of unity.)

5. Let $(V_j)_{j \in \mathcal{J}}$ be a family of *mutually disjoint* open subsets of \mathbb{R}^N . Prove

$$\mu\left(\bigcup_{j \in \mathcal{J}} V_j\right) = \sum_{j \in \mathcal{J}} \mu(V_j)$$

Definition 15.52. A subset $E \subset \mathbb{R}^N$ is called a **(Lebesgue) null set** if for every ε there exists an open $U \subset \mathbb{R}^N$ containing E such that $\mu(U) < \varepsilon$.

Exercise 15.53. Show that a countable union of null sets is null.

Exercise 15.54. (This exercise is not need below.) Show that when $N = 1$, the above definition of null sets agrees with Def. 14.11. More generally, for arbitrary N , show that $E \subset \mathbb{R}^N$ is null iff for every $\varepsilon > 0$, E can be covered by boxes whose total volumes are $< \varepsilon$.

15.8.3 ★ Multiple Riemann integral

Problem 15.8. Let $f \in C_c(\mathbb{R}^N, \mathbb{R}_{\geq 0})$.

1. Let $M \geq 0$. Assume that there is an open $U \subset \mathbb{R}^N$ such that $f|_U \leq M$ and that $\text{Supp}(f) \subset U$. Prove

$$\int_{\mathbb{R}^N} f \leq \mu(U) \cdot M$$

2. Let $\varepsilon \geq 0$. Assume that there is an open $U \subset \mathbb{R}^N$ such that $f|_U \geq \varepsilon$. Prove

$$\int_{\mathbb{R}^N} f \geq \mu(U) \cdot \varepsilon$$

Remark 15.55. Pb. 15.8 is easy but useful. It tells us that the values of $\int f$ and $\mu(U)$ are controlled by each other. For example, part 2 implies that if $\int f$ is small, then the measure of $\{x \in \mathbb{R}^N : f(x) > \varepsilon\}$ cannot be very big, and is converging to 0 as $\varepsilon \rightarrow +\infty$.

Definition 15.56. Let $f \in l^\infty(\mathbb{R}^N, \mathbb{R})$ have compact support. Define **upper integrals** and **lower integrals** to be

$$\begin{aligned} \overline{\int} f &= \inf \left\{ \int g : g \in C_c(\mathbb{R}^N, \mathbb{R}), g \geq f \right\} \\ \underline{\int} f &= \sup \left\{ \int h : h \in C_c(\mathbb{R}^N, \mathbb{R}), h \leq f \right\} \end{aligned}$$

Clearly $\underline{\int} f \leq \overline{\int} f$. Moreover, it is clear that if $f \in C_c(\mathbb{R}^N, \mathbb{R})$ then $\underline{\int} f = \overline{\int} f = \int f$. In general, if $\underline{\int} f = \overline{\int} f$, we say that f is **Riemann integrable**, and define its integral $\int f$ to be $\overline{\int} f$. Let

$$\mathcal{R}_c(\mathbb{R}^N, \mathbb{R}) = \{f \in l^\infty(\mathbb{R}^N, \mathbb{R}) : f \text{ has compact support and is Riemann integrable}\}$$

Remark 15.57. Let $f \in l^\infty(\mathbb{R}^N, \mathbb{R})$ be compactly supported. It is clear from the definition that the following statements are equivalent:

- (1) $f \in \mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$.
- (2) For every $\varepsilon > 0$ there exist $g, h \in C_c(\mathbb{R}^N, \mathbb{R})$ satisfying $h \leq f \leq g$ and $\int(g - h) < \varepsilon$.

In fact, (2) is easier to use than the original definition of Riemann integrability.

Exercise 15.58. (This exercise is not needed below.) Prove that when $N = 1$, the above definition of upper and lower integrals agrees with that in Pb. 13.1.

Problem 15.9. Let $f, g \in l^\infty(\mathbb{R}^N, \mathbb{R})$ have compact supports. Prove

$$\overline{\int}(f+g) \leq \overline{\int}f + \overline{\int}g \quad \underline{\int}(f+g) \geq \underline{\int}f + \underline{\int}g$$

Prove that $\mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$ is a linear subspace of $\mathbb{R}^{\mathbb{R}^N}$. Prove that $\int : \mathcal{R}_c(\mathbb{R}^N, \mathbb{R}) \rightarrow \mathbb{R}$ is linear. Prove that if $f, g \in \mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$ then

$$f \leq g \quad \implies \quad \int f \leq \int g \quad (15.22)$$

Problem 15.10. (Fubini's theorem) Let $X = \mathbb{R}^M, Y = \mathbb{R}^N$. Let $f \in \mathcal{R}_c(X \times Y, \mathbb{R})$. Prove that $x \in X \mapsto \int_Y f(x, y) dy$ and $x \in X \mapsto \bar{\int}_Y f(x, y) dy$ are Riemann integrable, and that $\int_{X \times Y} f = \int_X \int_Y f = \int_X \bar{\int}_Y f$.

Hint. Choose $g, h \in C_c(X \times Y, \mathbb{R})$ such that $g \leq f \leq h$ and $\int_{X \times Y} (h - g) < \varepsilon$. Apply Fubini's theorem for compactly supported continuous functions (available due to Thm. 14.1) to $g, h, h - g$. ((15.22) is also useful.) \square

Remark 15.59. In the next semester, we will prove Fubini's theorem for Lebesgue measurable functions using more complicated methods. The goal of Pb. 15.10 is to show you how to prove Fubini's theorem for a large class of functions (sufficient for many applications) without using those methods. When studying mathematics, it is often important to know how to simplify a proof when the objects studied are simpler.

15.8.4 ★ Lebesgue's criterion for multiple Riemann integrals

Definition 15.60. As in (14.12), for each $f : \mathbb{R}^N \rightarrow \mathbb{R}$ and $\varepsilon > 0$, define

$$\Omega_\varepsilon(f) = \{x \in \mathbb{R}^N : \omega(f, x) \geq \varepsilon\} \quad (15.23)$$

where $\omega(f, x) = \inf_{U \in \text{Nbh}(x)} \text{diam} f(U)$. Note that by Lem. 14.19, $\Omega_\varepsilon(f)$ is a closed subset of $\text{Supp}(f)$, and hence is compact when f is compactly supported.

Problem 15.11. Let $f \in \mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$. Prove that $\Omega_\varepsilon(f)$ is a null set. (Thus, $\bigcup_{n \in \mathbb{Z}_+} \Omega_{1/n}(f)$ is null. This proves that the set of discontinuities of f is null.)

Hint. For each $\delta > 0$, choose $g, h \in C_c(\mathbb{R}^N, \mathbb{R})$ such that $h \leq f \leq g$ and $\int (g - h) \leq \delta \varepsilon$, which exist due to Rem. 15.57. Let $U = \{x \in \mathbb{R}^N : g(x) - h(x) > \varepsilon/2\}$. Use Pb. 15.8 to give a small upper bound of $\mu(U)$. Prove that $\Omega_\varepsilon(f) \subset U$. \square

The following problem can be compared with Lem. 14.20.

Problem 15.12. Let $f \in l^\infty(\mathbb{R}^N, \mathbb{R})$ be supported in a compact set K . Let $W \subset \mathbb{R}^N$ be an open set containing K . Let $\varepsilon > 0$, and assume that for every $x \in \mathbb{R}^N$ we have $\omega(f, x) < \varepsilon$. Prove that there exist $g, h \in C_c(W, \mathbb{R})$ such that

$$g \leq f \leq h \quad 0 \leq g - h \leq \varepsilon$$

Hint. First construct the functions locally. Then pass from local to global functions using a partition of unity of K subordinate to an open cover. \square

Problem 15.13. Let $f \in l^\infty(\mathbb{R}^N, \mathbb{R})$ be compactly supported. Assume that the set of discontinuities of f is a null set. Prove that $f \in \mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$.

Hint. Choose any $\varepsilon, \delta > 0$. Choose an open set U containing the compact set $\Omega_\varepsilon(f)$ such that $\mu(U) < \delta$. Use a partition of unity of $K = \text{Supp}(f)$ subordinate to U and $V = \mathbb{R}^N \setminus \Omega_\varepsilon(f)$ to write $f = f_V + f_U$ where $f_V, f_U \in C_c(\mathbb{R}^N, \mathbb{R})$ are supported in $K \cap V$ and U respectively. Apply Pb. 15.12 to f_V to get $g_V \leq f_V \leq h_V$ with small $\int(h_V - g_V)$. Let $M = \|f\|_\infty$. Find $g_U \in C_c(\mathbb{R}^N, [0, M])$ such that $-g_U \leq f_U \leq g_U$. Show that $\int(g_U + h_V - (-g_U + g_V))$ is small. \square

Definition 15.61. Let Ω be a bounded subset of \mathbb{R}^N . We say that $f : \Omega \rightarrow \mathbb{R}$ is **Riemann integrable** if $\tilde{f} \in \mathcal{R}_c(\mathbb{R}^N, \mathbb{R})$, where \tilde{f} is the zero extension of f (i.e. $\tilde{f}|_\Omega = f$ and $\tilde{f}|_{X \setminus \Omega} = 0$). If f is Riemann integrable, we define

$$\int_\Omega f = \int_{\mathbb{R}^N} \tilde{f}$$

Example 15.62. Let $D = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1\}$ and $f \in C(D, \mathbb{R})$. Then the set of discontinuities of the zero extension \tilde{f} is a subset of $\mathbb{S}^1 = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$. It is not hard to show that \mathbb{S}^1 is a null subset of \mathbb{R}^2 . Since $\|f\|_\infty < +\infty$ by extreme value theorem, we conclude that f is Riemann integrable thanks to Lebesgue's criterion (Pb. 15.13). Clearly $\int_{\mathbb{R}} f(\cdot, y) dy$ is Riemann integrable. By Fubini's theorem (Pb. 15.10), we have

$$\int_D f = \int_{\mathbb{R}^2} \tilde{f} = \int_{-1}^1 \int_{-1}^1 \chi_D \tilde{f}(x, y) dy dx = \int_{-1}^1 \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} f(x, y) dy dx$$

15.8.5 Compactness and countability

The following problem shows that the equivalence (2) \Leftrightarrow (3) in Thm. 15.37 can be generalized to LCH spaces.

Problem 15.14. Let X be an LCH space with one-point compactification X^* . Prove that the following are equivalent:

- (1) X^* is second countable.

(2) X is second countable.

(3) $C_0(X, \mathbb{R})$ is separable (equivalently, second countable).

Here, as usual, $C_0(X, \mathbb{R})$ is equipped with the l^∞ -norm. Note also that by Pb. 15.5, (3) is equivalent to that $C_c(X, \mathbb{R})$ is separable.

★ **Remark 15.63.** By Pb. 15.14 and Thm. 15.37, if an LCH space X is second countable, then X^* is metrizable, and hence X is metrizable. However, a metrizable LCH space is not necessarily second countable. For example, let X be an uncountable set, equipped with the discrete topology $\mathcal{T} = 2^X$. Then \mathcal{T} is induced by a metric d defined by $d(x, y) = 1$ if $x \neq y$ and $d(x, x) = 0$. X is LCH, but not second countable.

Problem 15.15. Let X be a compact Hausdorff space. Suppose that $(f_n)_{n \in \mathbb{Z}_+}$ is a sequence in $C(X, \mathbb{R})$ separating points of X . Assume for simplicity that $\|f_n\|_{l^\infty} \leq 1$ for all n . Use these functions to define an explicit metric on X inducing its topology \mathcal{T} , and construct an explicit countable basis for \mathcal{T} .

Note. This problem tests whether you truly understand the method of embedding and the proof of Thm. 15.37. Hint: How do you construct a metric and a countable basis for $[-1, 1]^{\mathbb{Z}_+}$? What do their pullbacks look like under the embedding $X \rightarrow [-1, 1]^{\mathbb{Z}_+}$ defined by f_1, f_2, \dots ? □

16 Zorn's lemma and applications

The Axiom of Choice is obviously true, the well-ordering principle obviously false, and who can tell about Zorn's lemma?

— Jerry L. Bona

16.1 Zorn's lemma

Theorem 16.1 (Zorn's lemma). *Let (P, \leq) be a nonempty partially ordered set. Suppose that every totally ordered subset of P has an upper bound in P . Then there is a maximal element $p \in P$.*

By a **totally ordered subset** $Q \subset P$, we mean that Q satisfies that for every $x, y \in Q$, either $x \leq y$ or $y \leq x$. An upper bound of Q (in P) means an element $p \in P$ such that $x \leq p$ for all $x \in Q$. A **maximal element** $p \in P$ means that p satisfies $\{x \in P : x \geq p\} = \{p\}$.

Zorn's lemma and the axiom of choice are equivalent. (They are both equivalent to the so called "well-ordering principle".) Although it is easier to prove the axiom of choice from Zorn's lemma than the other way round, one may prefer to take the axiom of choice as the starting point, since axiom of choice is easier to grasp intuitively. Therefore, in the following, I will give a proof of Zorn's lemma under the assumption of axiom of choice, in order to comfort those who are obsessed with building a complete and rigorous mathematical theory in their heads from a few "self-evident" axioms. However, it is recommended that you skip or only skim this proof, since it is safe enough to assume that Zorn's lemma is an axiom that needs no proof. Although Zorn's lemma is far from "self-evident", knowing how to use it is much more important than knowing how to prove it. This is because in most areas of mathematics the ideas in the proof of Zorn's lemma are never used.

★ Proof of Zorn's lemma. Let (P, \leq) satisfy the assumption in Zorn's lemma but has no maximal element. We shall find a contradiction. By assumption, every totally ordered subset $A \subset P$ has an upper bound $p \in P$, and p is not maximal. So there exists $x_A > p$ in P . (Here, $x_A > p$ means that $x_A \geq p$ and $x \neq p$.) Thus, we have a function $A \mapsto x_A$ whose existence is due to axiom of choice.

Step 1. Fix $a \in P$ throughout the proof. For an arbitrary $\mathcal{F} \subset 2^P$, consider the following conditions:

- (a) $\{a\} \in \mathcal{F}$.
- (b) Every $A \in \mathcal{F}$ is a totally ordered subset of P .
- (c) If $A \in \mathcal{F}$ then $A \cup \{x_A\} \in \mathcal{F}$.

- (d) If \mathcal{E} is a nonempty totally ordered subset of \mathcal{F} (under the partial order \subset), then $\bigcup_{A \in \mathcal{E}} A \in \mathcal{F}$. (Note that if every $A \in P$ is a totally ordered subset of P , then so is $\bigcup_{A \in \mathcal{E}} A$.)

There exists at least one \mathcal{F} satisfying the above conditions. For example, one can let \mathcal{F} be the set of all totally ordered subsets of P containing a .

We let \mathcal{F} be the intersection of all the subsets of 2^P satisfying the above four conditions. Then \mathcal{F} clearly also satisfies these conditions. (In particular, $\mathcal{F} \neq \emptyset$ because $\{a\} \in \mathcal{F}$.) So \mathcal{F} is the smallest subset of 2^P satisfying these four conditions.

We claim that \mathcal{F} is a totally ordered subset of 2^P . Suppose this is true. Let $B = \bigcup_{A \in \mathcal{F}} A$. Then $B \in \mathcal{F}$ by condition (d). In particular, by (b), B is a totally ordered subset of P . Then x_B is defined as at the beginning of the proof and satisfies $x_B > B$. By (c), we have $B \cup \{x_B\} \in \mathcal{F}$. By the definition of B , we get $x_B \in B$. This is impossible. So we are done with the proof.

Step 2. Let us prove that \mathcal{F} is totally ordered. Let

$$\mathcal{F}_0 = \{A \in \mathcal{F} : \text{every } B \in \mathcal{F} \text{ satisfies either } A \subset B \text{ or } B \subset A\}$$

It is not hard to check that \mathcal{F}_0 satisfies (a,b,d). It suffices to prove that \mathcal{F}_0 satisfies (c). Then we will have $\mathcal{F}_0 = \mathcal{F}$ and hence that \mathcal{F} is totally ordered.

Let us prove (c) for \mathcal{F}_0 . Choose any $A \in \mathcal{F}_0$. We need to prove that $A \cup \{x_A\} \in \mathcal{F}_0$. It suffices to prove that the following set equals \mathcal{F} :

$$\mathcal{F}_A = \{B \in \mathcal{F} : B \subset A \text{ or } A \cup \{x_A\} \subset B\}$$

One checks easily that \mathcal{F}_A satisfies (a,b,d). To check that \mathcal{F}_A satisfies (c), we choose any $B \in \mathcal{F}_A$. Then there are two possible cases:

- $A \cup \{x_A\} \subset B$ or $B = A$. Then $A \cup \{x_A\} \subset B \cup \{x_B\}$.
- $B \subsetneq A$. Then, since $A \in \mathcal{F}_0$ and since $B \cup \{x_B\} \in \mathcal{F}$ (because $B \in \mathcal{F}$ and \mathcal{F} satisfies (c)), we have either $A \subsetneq B \cup \{x_B\}$ or $B \cup \{x_B\} \subset A$. The former case is clearly impossible. So $B \cup \{x_B\} \subset A$.

Thus, in both cases we have $B \cup \{x_B\} \in \mathcal{F}_A$. This proves that \mathcal{F}_A also satisfies (c). So $\mathcal{F}_A = \mathcal{F}$. □

16.2 Comparison of Zorn's lemma and mathematical induction

Zorn's lemma can be viewed as the uncountable version of mathematical induction. Therefore, the best way to understand Zorn's lemma is to first use it to prove some classical results traditionally proved by mathematical induction.

Example 16.2. Let $n \in \mathbb{N}$ and $s_n = 0 + 1 + 2 + \cdots + n$. Then $s_n = \frac{n(n+1)}{2}$.

Proof. Let $\mathbb{N}^* = \mathbb{N} \cup \{+\infty\}$ with the usual order. Let

$$P = \left\{ n \in \mathbb{N}^* : s_i = \frac{i(i+1)}{2} \text{ for all } i \leq n \text{ and } i < +\infty \right\}$$

P is nonempty since it contains 0. (Checking that P is nonempty is important, since it corresponds to checking the base case in mathematical induction.) P is totally ordered, and clearly every nonempty subset $Q \subset P$ has an upper bound $\sup Q$. Thus, by Zorn's lemma, P has a maximal element.

If $n < +\infty$, then from $s_n = \frac{n(n+1)}{2}$ and $s_{n+1} - s_n = n+1$ we have $s_{n+1} = \frac{(n+1)(n+2)}{2}$. (This step corresponds to checking "case n implies case $n+1$ " in mathematical induction.) So $n+1 \in P$, contradicting the maximality of n . So $n = +\infty$, and hence $+\infty \in P$, finishing the proof. \square

Example 16.3. Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a function not continuous at 0. Assume that $f(0) = 0$. Then there exists $\varepsilon > 0$ and a sequence $(x_n)_{n \in \mathbb{Z}_+}$ in $\mathbb{R} \setminus \{0\}$ converging to 0 such that $|f(x_n)| > \varepsilon$ for all n .

Proof. By assumption, there is $\varepsilon > 0$ such that for every $\delta > 0$, there exists $x \in (-\delta, \delta) \setminus \{0\}$ such that $|f(x)| > \varepsilon$. Let

$$P = \left\{ \begin{array}{l} \text{finite or countably infinite sequence } x_\bullet = (x_1, x_2, \dots) \\ \text{satisfying } 0 < |x_i| < 1/i \text{ and } |f(x_i)| > \varepsilon \text{ for all } i \end{array} \right\}$$

Then P is nonempty. (This corresponds to checking the base case in mathematical induction.) View each element of P as a subset of $\mathbb{Z}_+ \times \mathbb{R}$, and let \subset be the partial order on P . Then every nonempty totally ordered subset $Q \subset P$ has an upper bound (defined by taking union). Thus, by Zorn's lemma, P has a maximal element x_\bullet .

Suppose that x_\bullet has finite length $N \in \mathbb{Z}_+$. (So $x_\bullet = (x_1, \dots, x_N)$) Then by the first sentence of the proof, there exists x_{N+1} satisfying $0 < |x_{N+1}| < 1/(N+1)$ satisfying $|f(x_{N+1})| > 0$. (This step corresponds to checking "case n implies case $n+1$ " in mathematical induction.) Then $(x_1, \dots, x_N, x_{N+1})$ belongs to P and is $> x_\bullet$, contradicting the maximality of x_\bullet . So x_\bullet must be an infinite sequence. This finishes the construction of the sequence (x_n) . \square

16.3 Proof of the Tychonoff theorem

We first recall Pb. 8.6: Assume for simplicity that X, Y are compact spaces. Let $(x_\alpha, y_\alpha)_{\alpha \in \mathcal{J}}$ be a net in $X \times Y$ such that $x \in X$ is a cluster point of (x_α) . Then there exists $y \in Y$ such that (x, y) is a cluster point of (x_α, y_α) .

The proof is easy. By the definition of cluster points (Pb. 7.2-(1)), (x_α) has a subnet $(x_{\alpha_\beta})_{\beta \in \mathcal{J}}$ converging to x . Since Y is net-compact, (y_{α_β}) has a subnet $(y_{\alpha_{\beta_\gamma}})_{\gamma \in \mathcal{K}}$ converging to some $y \in Y$. Then $(x_{\alpha_{\beta_\gamma}}, y_{\alpha_{\beta_\gamma}})$ is a subnet of (x_α, y_α) converging to (x, y) .

In the following, we present a proof of Tychonoff Thm. 15.15 which was due to Chernoff [Che92]. Our method is similar to the proof of the countable Tychonoff theorem (Pb. 8.7) which uses net-compactness. It is strongly recommended that you compare the proof with the one of Pb. 8.7, and even reprove Pb. 8.7 using Zorn's lemma.

Proof of Tychonoff Thm. 15.15. Recall the setting that $(X_\alpha)_{\alpha \in \mathcal{J}}$ is a family of compact topological spaces. Assume WLOG that \mathcal{J} and each X_α are nonempty. We want to prove that $S = \prod_{\alpha \in \mathcal{J}} X_\alpha$ is compact.

We first introduce a few notations. For each $I \subset \mathcal{J}$, let $S_I = \prod_{\alpha \in I} X_\alpha$. If $x \in S_I$, we write x as $(x(\alpha))_{\alpha \in I}$, and view it as a function with domain I and codomain $\mathfrak{X} = \bigcup_{\alpha \in \mathcal{J}} X_\alpha$. We write $\text{Dom}(x) = I$. If $x \in S_I$ and $J \subset I$, the restriction $x|_J = (x(\alpha))_{\alpha \in J}$ is clearly in S_J .

Step 1. Let $(f_\mu)_{\mu \in \mathfrak{M}}$ be a net in S . Let

$$P = \bigcup_{I \subset \mathcal{J}} \{x \in S_I : x \text{ is a cluster point of } (f_\mu|_I)_{\mu \in \mathfrak{M}} \text{ in } S_I\}$$

Let " \subset " be the partial order on P (defined by identifying each element of P with its graph, which is an element of $\mathcal{J} \times \mathfrak{X}$). Thus $x \subset y$ iff $\text{Dom}(x) \subset \text{Dom}(y)$ and $y|_{\text{Dom}(x)} = x$.

Clearly P is nonempty: Choose any $\alpha \in \mathcal{J}$. Since X_α is compact, $(f_\mu(\alpha))_{\mu \in \mathfrak{M}}$ has a cluster point in X_α . This point, viewed as a function from $\{\alpha\}$ to this point, belongs to P .¹

We claim that every totally ordered subset of P has an upper bound. Suppose this is true. Then by Zorn's lemma, there is a maximal element $x \in P$. If $\text{Dom}(x) \neq \mathcal{J}$, then by Pb. 8.6 (applied to $S_{\text{Dom}(x)} \times X_\beta$ where $\beta \in \mathcal{J} \setminus \text{Dom}(x)$), x can be extended to a function with larger domain which is again the cluster point of the restriction of $(f_\mu)_{\mu \in \mathfrak{M}}$ to that domain.² This proves that P has an element strictly larger than x . This is impossible. So we must have $\text{Dom}(x) = \mathcal{J}$, finishing the proof.

Step 2. Let Q be a nonempty totally ordered subset of P . Let x be the union of the elements of Q . Let $K = \text{Dom}(x)$. Then Q can be written in the form

$$Q = \{x|_I : I \in \mathcal{U}\}$$

where \mathcal{U} is a totally ordered subset of 2^K and $K = \bigcup_{I \in \mathcal{U}} I$.

¹This part corresponds to checking the base case in mathematical induction.

²This part corresponds to checking "case n implies case $n+1$ " in mathematical induction. More precisely, it corresponds to constructing $(x(1), \dots, (x(n+1)))$ from $(x(1), \dots, x(n))$ in the proof of Pb. 8.7.

To prove that $x \in P$, let us use Pb. 7.2-(2) to prove that x is a cluster point of $(f_\mu|_K)_{\mu \in \mathfrak{M}}$.³ Let W be a neighborhood of x in S_K . By the definition of product topology (Def. 7.71), we can shrink W to a smaller neighborhood of the form

$$W = \prod_{\alpha \in K} U_\alpha$$

where each U_α is a neighborhood of $x(\alpha)$, and there exists a finite subset $E \subset K$ such that $U_\alpha = X_\alpha$ for all $\alpha \in K \setminus E$. Choose $I \in \mathcal{U}$ containing E . The fact that $x|_I$ is a cluster point of $(f_\mu|_I)_{\mu \in \mathfrak{M}}$ implies (by Pb. 7.2-(2)) that $(f_\mu|_E)_{\mu \in \mathfrak{M}}$ is frequently in $\prod_{\alpha \in E} U_\alpha$. Therefore $(f_\mu|_K)_{\mu \in \mathfrak{M}}$ is frequently in W . This finishes the proof. \square

16.4 Proof of the Hahn-Banach extension theorem

Recall from Rem. 11.25 that a **linear functional** on a vector space V over a field \mathbb{F} is defined to be a linear map $V \rightarrow \mathbb{F}$.

Lemma 16.4. *Let V be a normed vector space over \mathbb{R} , and let M be a linear subspace. Let $\varphi \in M^* = \mathfrak{L}(M, \mathbb{R})$ with operator norm $\|\varphi\| \leq 1$. Assume that $e \in V \setminus M$, and let $\widetilde{M} = M + \mathbb{R}e$. Then φ can be extended to a linear functional $\widetilde{\varphi} : \widetilde{M} \rightarrow \mathbb{R}$ such that $\|\widetilde{\varphi}\| \leq 1$.*

★ *Proof.* Let $A \in \mathbb{R}$ whose value will be determined later. Since any vector in \widetilde{M} can be written uniquely as $x - \lambda e$ where $x \in M$ and $\lambda \in \mathbb{R}$, we can define

$$\widetilde{\varphi} : \widetilde{M} \rightarrow \mathbb{R} \quad \widetilde{\varphi}(x - \lambda e) = \varphi(x) - \lambda A$$

It remains to prove $\|\widetilde{\varphi}\| \leq 1$ (for some A). This means that we want to prove $|\varphi(x) - \lambda A| \leq \|x - \lambda e\|$ for all $x \in M, \lambda \in \mathbb{R}$. Clearly this is true when $\lambda = 0$. Assume $\lambda \neq 0$. Then replacing x by λx and dividing both sides by λ , we see that it suffices to prove

$$|\varphi(x) - A| \leq \|x - e\|$$

for all $x \in V$, or equivalently,

$$\varphi(x) - \|x - e\| \leq A \leq \varphi(x) + \|x - e\|$$

To prove the existence of A satisfying the above inequalities for all $x \in V$, it suffices to prove

$$\sup_{x \in V} (\varphi(x) - \|x - e\|) \leq \inf_{y \in V} (\varphi(y) + \|y - e\|) \quad (16.1)$$

³This part corresponds to showing that x is a cluster point of (f_α) in the proof of Pb. 8.7.

namely, to prove that $\varphi(x) - \|x - e\| \leq \varphi(y) + \|y - e\|$ for all $x, y \in V$. Using $\|\varphi\| \leq 1$, we compute

$$\varphi(x) - \varphi(y) = \varphi(x - y) \leq \|(x - e) - (y - e)\| \leq \|x - e\| + \|y - e\|$$

□

Theorem 16.5 (Hahn-Banach extension theorem). *Let V be a normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let M be an \mathbb{F} -linear subspace of V . Let $\varphi \in M^* = \mathfrak{L}(M, \mathbb{F})$. Then there exists $\Phi \in V^*$ such that $\Phi|_M = \varphi$ and $\|\Phi\| = \|\varphi\|$.*

Proof. We first consider the case $\mathbb{F} = \mathbb{R}$. Assume WLOG that $\varphi \neq 0$. By scaling φ , we assume WLOG that $\|\varphi\| = 1$. Let

$$P = \{(W, \Phi) : W \text{ is a linear subspace of } V \text{ and contains } M \\ \Phi \in \mathbb{R}^W \text{ is linear and satisfies } \Phi|_M = \varphi, \|\Phi\| = 1\}$$

Then P is nonempty since it contains (M, φ) . Define a partial order on P by setting $(W, \Phi) \leq (W', \Phi')$ whenever $W \subset W'$ and $\Phi = \Phi'|_W$.

Suppose that Q is a totally ordered subset of P . Let $\widetilde{W} = \bigcup_{(W, \Phi) \in Q} W$, and let $\widetilde{\Phi}$ be the union of the functions Φ over all $(W, \Phi) \in Q$ (by taking the union of the graphs of the functions). So $\widetilde{\Phi} : \widetilde{W} \rightarrow \mathbb{R}$ is the unique functions satisfying $\widetilde{\Phi}|_W = \Phi$ for all $(W, \Phi) \in Q$. Then it is easy to see that $(\widetilde{W}, \widetilde{\Phi})$ belongs to P and is an upper bound of Q .

Thus, we can use Zorn's lemma, which says that P has a maximal element (W, Φ) . If $W \neq V$, we let $e \in V \setminus W$. Then by Lem. 16.4, Φ can be extended to $\widetilde{\Phi} \in \widetilde{W}^*$ where $\widetilde{W} = W + \mathbb{R}e$, and $\|\widetilde{\Phi}\| = 1$. So $(\widetilde{W}, \widetilde{\Phi})$ belongs to P and is strictly larger than (W, Φ) , impossible. So $W = V$.

We are done with the proof for the case $\mathbb{F} = \mathbb{R}$. Now assume $\mathbb{F} = \mathbb{C}$. By Pb. 13.2, the real part $\text{Re}\varphi : M \rightarrow \mathbb{R}$ sending v to $\text{Re}(\varphi(v))$ is linear with operator norm $\|\text{Re}\varphi\| = \|\varphi\|$. By the real Hahn-Banach, $\text{Re}\varphi$ can be extended to $\Lambda \in \mathfrak{L}(V, \mathbb{R})$ with $\|\Lambda\| = \|\varphi\|$. By Pb. 13.2, there exists a unique $\Phi \in \mathfrak{L}(V, \mathbb{C})$ with real part Λ such that $\|\Phi\| = \|\varphi\|$. Since $\text{Re}\Phi|_M = \Lambda|_M = \text{Re}\varphi$, by Pb. 13.2, we have $\Phi|_M = \varphi$. □

In this course, we only use the following special case of Hahn-Banach theorem.

Corollary 16.6 (Hahn-Banach). *Let V be a nonzero normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Then for every $v \in V$, there exists a nonzero $\varphi \in V^*$ such that $\langle \varphi, v \rangle = \|\varphi\| \cdot \|v\|$. Consequently, the linear map*

$$V \rightarrow V^{**} \quad v \mapsto \langle \cdot, v \rangle \tag{16.2}$$

is an isometry.

More precisely, the map (16.2) sends each $\varphi \in V^*$ to $\langle \varphi, v \rangle$. By scaling φ , Hahn-Banach implies that for each $v \in V$, there is $\varphi \in V^*$ with $\|\varphi\| = 1$ such that $\langle \varphi, v \rangle = \|v\|$.

Proof. Let $v \in V$, and assume WLOG that $v \neq 0$. Let $\varphi : \mathbb{F}v \rightarrow \mathbb{F}$ send λv to $\lambda\|v\|$. Then φ is linear and has operator norm 1, and $\langle \varphi, v \rangle = \|v\|$. By Hahn-Banach Thm. 16.5, φ can be extended to a bounded linear $V \rightarrow \mathbb{F}$ with operator norm 1. This is a desired linear functional.

Denote (16.2) by Ψ . To show that Ψ is an isometry, we need to prove that for every $v \in V$, $\Psi(v) : V^* \rightarrow \mathbb{F}$ has operator norm $\|v\|$. Choose any $\varphi \in V^*$. Then

$$\langle \Psi(v), \varphi \rangle = \langle \varphi, v \rangle \leq \|\varphi\| \cdot \|v\|$$

where “ \leq ” is “=” for some nonzero φ by the first paragraph. Therefore, by Rem. 10.24, we obtain $\|\Psi(v)\| = \|v\|$. \square

16.5 Problems and supplementary material

Problem 16.1. Let V be a vector space over a field \mathbb{F} . Use Zorn’s lemma to prove that V has a basis, i.e. a set E of linearly independent vectors such that any vector of V can be written as a (finite) linear combination of elements of E .

Problem 16.2. Let X be a set. Let $E \subset X$ be an infinite subset such that $X \setminus E$ is countable. (Recall that finite sets are also countable.) Prove that $\text{card}(X) = \text{card}(E)$.

Problem 16.3. Let X be an infinite set. Use Zorn’s lemma to prove that X can be written as a countably infinite union of subsets $X = \bigsqcup_{n=1}^{\infty} X_n$ such that $\text{card}(X_i) = \text{card}(X_j)$ for each i, j .

Hint. Assume WLOG that X is uncountable. Consider

$$P = \left\{ ((A_n)_{n \in \mathbb{Z}_+}, (\varphi_n)_{n \in \mathbb{Z}_+}) : A_1, A_2, \dots \text{ are mutually disjoint subsets of } X \right. \\ \left. \varphi_n : A_n \rightarrow A_{n+1} \text{ is a bijection (for every } n \in \mathbb{Z}_+) \right\}$$

which is nonempty (why?). Define a suitable partial order on P . \square

Theorem 16.7. Let X be an infinite set, and let Y be a nonempty countable set. Then $\text{card}(X) = \text{card}(X \times Y)$

Proof. By Pb. 16.3, we have $X \approx A \times \mathbb{N}$ for some subset $A \subset X$. Since $\mathbb{N} \times Y$ is infinite and countable, we have $\mathbb{N} \times Y \approx \mathbb{N}$. Therefore

$$X \times Y \approx A \times \mathbb{N} \times Y \approx A \times \mathbb{N} \approx X$$

\square

★ **Problem 16.4.** Let E, F be two bases of a vector space V . Use Thm. 16.7 to prove that $\text{card}(E) = \text{card}(F)$. (When one of E, F is finite, this result was proved in linear algebra. You can assume this in your proof.)

Problem 16.5. Let V be a *separable* normed vector space over \mathbb{R} . Prove Hahn-Banach Thm. 16.5 for V using mathematical induction instead of Zorn's lemma. (You will need Prop. 10.28 in the proof.)

17 Compactness and completeness revisited

Tychonoff theorem asserts the compactness of function spaces under the pointwise convergence topology. In application, we are often interested in the compactness of function spaces satisfying certain additional condition such as the continuity.

Example 17.1. $\mathfrak{X} = C([0, 1], [0, 1])$ is not compact under either the pointwise convergence topology or the uniform convergence topology.

Proof. We first choose the pointwise convergence topology. Choose any sequence (f_n) in \mathfrak{X} converging pointwise to a non-continuous function f . Then (f_n) has no subnet converging in \mathfrak{X} , since any subnet converging to $g \in \mathfrak{X}$ must satisfy $f = g$ and hence f is continuous. This is impossible. So \mathfrak{X} is not compact.

Now we choose the uniform convergence topology for \mathfrak{X} , which is metrizable by the l^∞ -norm. Let (f_n) be a sequence in \mathfrak{X} such that $\|f_m - f_n\|_\infty = 1$ whenever $m \neq n$. (For example, one chooses f_n such that $\text{Supp } f_n \subset I_n = (\frac{1}{2n+2}, \frac{1}{2n+1})$ and that $f_n(\xi_n) = 1$ for some $\xi_n \in I_n$.) Then every subsequence of (f_n) is not Cauchy and hence not convergent. Therefore, \mathfrak{X} is not sequentially compact, and hence not compact. \square

Note that this example does not contradict Tychonoff theorem. In fact, if we choose the pointwise convergence topology, then Tychonoff theorem implies that every sequence (f_n) in $C([0, 1], [0, 1])$ has a subnet convergent to some $f \in [0, 1]^{[0, 1]}$. However, one cannot deduce the continuity of f . To prove that the limit function is continuous, we need additional assumptions on the sequence (f_n) . For example, Cor. 9.21 tells us that we need the equicontinuity.

17.1 Precompactness in function spaces

Since $C(X, [0, 1])$ is in general not compact, one should search for compact subsets of $C(X, [0, 1])$, or more generally, subsets with compact closures in $C(X, [0, 1])$. You know what precompact sets mean geometrically: In \mathbb{R}^N , precompact subsets of \mathbb{R}^N are exactly bounded subsets of \mathbb{R}^N . If $\Omega \subset \mathbb{R}^N$, then precompact subsets of Ω are precisely bounded subsets of \mathbb{R}^N whose closures are inside Ω , cf. Rem. 15.20.

However, when studying function spaces, it is often more convenient to use another description of precompactness. As we shall see in Cor. 17.5, saying that $\mathcal{A} \subset C(X, [0, 1])$ is precompact in $C(X, [0, 1])$ is equivalent to saying that every net (f_α) in \mathcal{A} converges to some $f \in C(X, [0, 1])$.

Recall from Def. 8.39 that a subset A of a Hausdorff space X is called **precompact** if A is contained in a compact subset of X , or equivalently, if \overline{A} is compact.

Proposition 17.2. *Let X be a metrizable topological space, and let $A \subset X$. Then the following are equivalent.*

- (1) A is precompact.
- (2) Every net in A has a cluster point in X .
- (3) Every sequence in A has a cluster point in X .

From the following proof, it is clear that (1) \Rightarrow (2) holds even without assuming that X is metrizable.

Proof. (1) \Rightarrow (2): Since \overline{A} is compact, every net in A has a cluster point in \overline{A} and hence in X .

(2) \Rightarrow (3): Obvious.

(3) \Rightarrow (1): See Pb. 8.9. □

17.1.1 * Precompactness in regular spaces

(Since this section is a starred section, I will not use the results proved here in future sections. However, the material of this section is helpful for a better understanding of precompactness in function spaces.)

You may wonder to what general topological space the equivalence (1) \Leftrightarrow (2) generalizes. This equivalence is not true for an arbitrary topological space, but is true for regular spaces (recall Def. 9.20). Metrizable spaces are clearly regular. More generally, we have:

Example 17.3. Every subset of a regular space is regular. Every LCH space is regular. Products of regular spaces are regular.

Proof. Assume that X is regular and $A \subset X$. For each $x \in A$, choose a neighborhood of x in A , which must be of the form $U \cap A$ where $U \in \text{Nbh}_X(x)$. Since X is regular, there is $V \in \text{Nbh}_X(x)$ such that $\overline{V} \subset U$. So $\text{Cl}_A(V \cap A) \subset \overline{V} \cap A \subset U \cap A$. So A is regular. That LCH spaces are regular follows from Lem. 15.27 (together with Rem. 15.20).

Let $S = \prod_{\alpha \in \mathcal{J}} X_\alpha$ where each X_α is regular. Choose $x = (x_\alpha)_{\alpha \in \mathcal{J}}$ in S . Choose a neighborhood of x which, after shrinking, is of the form $\prod_{\alpha} U_\alpha$ where $U_\alpha \in \text{Nbh}_{X_\alpha}(x_\alpha)$, and there is a finite subset $E \subset \mathcal{J}$ such that $U_\alpha = X_\alpha$ if $\alpha \in \mathcal{J} \setminus E$. If $\alpha \in E$, let V_α be a neighborhood of x such that $\overline{V}_\alpha \subset U_\alpha$. If $\alpha \in \mathcal{J} \setminus E$, let $V_\alpha = X_\alpha$. Then one checks easily that $\prod_{\alpha \in \mathcal{J}} V_\alpha$ is a neighborhood of x with closure $\prod_{\alpha \in \mathcal{J}} \overline{V}_\alpha$, which is clearly inside $\prod_{\alpha} U_\alpha$. So S is regular. □

Theorem 17.4. Let X be a regular topological space, and let $A \subset X$. Then the following are equivalent.

- (1) \overline{A} is compact.
- (2) A is contained in a compact subset of X .

(3) Every net in A has a cluster point in X .

Thus, although regular spaces are not necessarily Hausdorff, the two equivalent definitions of precompact subsets of Hausdorff spaces in Def. 8.39 are also equivalent in regular spaces. (However, most important examples of regular spaces are also Hausdorff. Regular Hausdorff spaces are called **T3 spaces**.)

Proof. “(1) \Rightarrow (2)” is obvious. “(2) \Rightarrow (3)” is also obvious: if $X \subset K$ where K is a compact subset of X , then every net in A is a net in K , which has a cluster point in K and hence in X .

Assume (3). Let us show that \bar{A} is compact by showing that every nonempty net $(x_\alpha)_{\alpha \in I}$ in \bar{A} has a cluster point in \bar{A} . For each $\gamma \in I$, let $E_\gamma = \{x_\alpha : \alpha \in I, \alpha \geq \gamma\}$. Define

$$J = \{(U, \gamma) \in 2^X \times I : U \text{ is open and contains } E_\gamma\}$$

It is not hard to check that J is a directed set if we define its preorder “ \leq ” to be

$$(U, \gamma) \leq (U', \gamma') \iff U \supset U', \gamma \leq \gamma'$$

For each $(U, \gamma) \in J$, since $E_\gamma \subset U$, U intersects \bar{A} , and hence intersects A . Therefore, we can choose some $y_{U, \gamma} \in A \cap U$. In this way, we get a net $(y_{U, \gamma})_{(U, \gamma) \in J}$ in A . By (3), this net has a cluster point $x \in X$. So clearly $x \in \bar{A}$. Let us prove that x is also a cluster point of $(x_\alpha)_{\alpha \in I}$.

Assume that x is not a cluster point of $(x_\alpha)_{\alpha \in I}$. Then, by the definition of cluster points (Pb. 7.2-(2)), there exists $\Omega \in \text{Nbh}_X(x)$ such that (x_α) is not frequently in Ω , i.e., eventually outside Ω . So there exists $\gamma \in I$ such that $E_\gamma \subset X \setminus \Omega$. Since X is regular, there exists $V \in \text{Nbh}_X(x)$ such that $\bar{V} \subset \Omega$. Let $U = X \setminus \bar{V}$. Then $E_\gamma \subset U$, and hence $(U, \gamma) \in J$.

Since x is a cluster point of y_\bullet , for the neighborhood V of x , there exists $(U', \gamma') \geq (U, \gamma)$ in J such that $y_{U', \gamma'} \in V$. By the definition of the net y_\bullet , we have $y_{U', \gamma'} \in A \cap U' \subset U$. This is impossible, since $U \cap V = \emptyset$. \square

Corollary 17.5. *Let X be a topological space, and let Y be a metric space. Equip $C(X, Y)$ with either the pointwise convergence topology or the uniform convergence topology. (Note that both topologies are Hausdorff.) Let \mathcal{A} be a subset of $C(X, Y)$. Then the following are equivalent:*

- (1) \mathcal{A} is precompact.
- (2) Every net $(f_\alpha)_{\alpha \in \mathcal{J}}$ in \mathcal{A} has a subnet converging to some $f \in C(X, Y)$.

Proof. If the topology \mathcal{T} on $C(X, Y)$ is the pointwise convergence topology, then $C(X, Y)$ is a subspace of Y^X (equipped with the product topology). By Exp. 17.3, $C(X, Y)$ is regular. So one can use Thm. 17.4 to prove (1) \Leftrightarrow (2). If \mathcal{T} is the uniform convergence topology, then $C(X, Y)$ is metrizable (and hence also regular). So one can also use Thm. 17.4 (or even Prop. 17.2) to prove (1) \Leftrightarrow (2). \square

17.2 Equicontinuity and precompactness; Arzelà-Ascoli theorem

17.2.1 Precompactness under pointwise convergence topology

Definition 17.6. Let X be a set and Y be a metric space. A subset $\mathcal{A} \subset Y^X$ is called **pointwise bounded** if

$$\mathcal{A}(x) = \{f(x) : f \in \mathcal{A}\} \quad (17.1)$$

is a bounded subset of Y for every $x \in X$.

Theorem 17.7. Let X be a topological space, and equip $C(X, \mathbb{R}^N)$ with the pointwise convergence topology. Let \mathcal{A} be an equicontinuous and pointwise bounded subset of $C(X, \mathbb{R}^N)$. Then \mathcal{A} is precompact in $C(X, \mathbb{R}^N)$, and $\overline{\mathcal{A}}$ is equicontinuous.

Proof. Write $Y = \mathbb{R}^N$. Let us show that $\overline{\mathcal{A}} = \text{Cl}_{C(X,Y)}(\mathcal{A})$ is equicontinuous. Since \mathcal{A} is equicontinuous, for every $x \in X$ and $\varepsilon > 0$, there exists $U \in \text{Nbh}(x)$ such that $\text{diam}(f(U)) \leq \varepsilon$ for all $f \in \mathcal{A}$. Since each $g \in \overline{\mathcal{A}}$ is the pointwise limit of a net in \mathcal{A} , we also have $\text{diam}(g(U)) \leq \varepsilon$. This proves that $\overline{\mathcal{A}}$ is equicontinuous at x .

Now let us show that $\overline{\mathcal{A}}$ is compact. Choose any net (f_α) in $\overline{\mathcal{A}}$. It is clear that $\overline{\mathcal{A}}(x)$ is pointwise bounded. By Heine-Borel, for each $x \in X$, $\overline{\mathcal{A}}(x)$ is contained in a compact subset $K_x \subset Y$. So $\overline{\mathcal{A}}$ is contained in $S = \prod_{x \in X} K_x$ where S is compact by Tychonoff theorem. Therefore, (f_α) has a subnet (f_β) converging pointwise to some $f : X \rightarrow Y$. Since (f_β) is equicontinuous (as $\overline{\mathcal{A}}$ is equicontinuous), by Cor. 9.21, $f \in C(X, Y)$.¹ So $f \in \text{Cl}_{C(X,Y)}(\overline{\mathcal{A}}) = \overline{\mathcal{A}}$ since f can be approximated by elements of $\overline{\mathcal{A}}$. This proves that $\overline{\mathcal{A}}$ is compact. \square

Remark 17.8. Theorem 17.7 is of fundamental importance because most compactness results about function spaces (such as Arzelà-Ascoli Thm. 17.15, Banach-Alaoglu Thm. 17.21) are derived from this theorem. As we will see in Claim 17.11, when X is separable, the proof of Thm. 17.7 uses only the countable version of Tychonoff theorem, and hence not using Zorn's lemma. This is in line with the history that Thm. 17.7 (which is implicit in the proof of Arzelà-Ascoli theorem) appeared earlier than Zorn's lemma and was proved using diagonal method. (If you remember, the proof of countable Tychonoff theorem uses diagonal method, cf. Thm. 3.54. And we will use Thm. 3.54 to prove Claim 17.11.)

In the late 19th and early 20th centuries, the diagonal method was often used to derive compactness properties of function spaces. Prominent examples are Hilbert's and Schmidt's solutions of eigenvalue problems in integral equations (cf. Subsect. 10.4.1) and F. Riesz's solution of moment problems (cf. Rem. 17.34). Thus, Thm. 17.7 can be viewed as a summary of this method. \square

The following exercise is a variant of Thm. 17.7. Another variant, the Banach-Alaoglu theorem, will be discussed in the next section.

¹Alternatively, by the argument in the first paragraph, $\{f_\beta : \text{all } \beta\} \cup \{f\}$ is equicontinuous. So f is continuous.

Exercise 17.9. Let X be a metric space, and equip $C(X, \mathbb{R}^N)$ with the pointwise convergence topology. Let \mathcal{A} be a pointwise bounded subset of $C(X, \mathbb{R}^N)$. Assume that \mathcal{A} has a uniform Lipschitz constant $L < +\infty$. (Namely, $\|f(x) - f(y)\| \leq L \cdot d(x, y)$ for all $f \in \mathcal{A}$ and $x, y \in X$.) Prove that \mathcal{A} is precompact in $C(X, \mathbb{R}^N)$, and $\overline{\mathcal{A}}$ has a uniform Lipschitz constant L .²

The proof of Thm. 17.7 uses Tychonoff theorem for uncountable product spaces, and hence relies on Zorn's lemma. In the following, we shall show that Zorn's lemma is not needed when X is separable. We first need a preparatory result: the following proposition is the equicontinuous analog of Prop. 9.27.

Proposition 17.10. *Let \mathcal{V} be a Banach space. Let X be a topological space. Let $(f_\alpha)_{\alpha \in I}$ be an equicontinuous net in $C(X, \mathcal{V})$ converging pointwise on a dense subset E of X . Then (f_α) converges pointwise on X to some $f \in C(X, \mathcal{V})$.*

It follows that if (f_α) also converges pointwise on E to some $g \in C(X, \mathcal{V})$, then (f_α) converges pointwise on X to g . (Indeed, since $f|_E = g|_E$, we have $f = g$ because f, g are continuous and E is dense.)

Proof. Let $x \in X$. Since \mathcal{V} is complete, to show that $(f_\alpha(x))$ converges, it suffices to prove that $(f_\alpha(x))_{\alpha \in I}$ is a Cauchy net. Choose any $\varepsilon > 0$. Since (f_α) is equicontinuous at x , there exists $U \in \text{Nbh}_X(x)$ such that $\text{diam}(f_\alpha(U)) < \varepsilon$ for all α . Since E is dense in X , E intersects U . Pick $p \in E \cap U$. Since $(f_\alpha(p))$ is a Cauchy net, we have $\lim_{\alpha, \beta \in I} \|f_\alpha(p) - f_\beta(p)\| = 0$. Then

$$\begin{aligned} \|f_\alpha(x) - f_\beta(x)\| &\leq \|f_\alpha(x) - f_\alpha(p)\| + \|f_\alpha(p) - f_\beta(p)\| + \|f_\beta(p) - f_\beta(x)\| \\ &\leq \|f_\alpha(p) - f_\beta(p)\| + 2\varepsilon \end{aligned}$$

where the RHS converges to 2ε under $\limsup_{\alpha, \beta \in I}$. Therefore $\limsup_{\alpha, \beta \in I} \|f_\alpha(x) - f_\beta(x)\| \leq 2\varepsilon$. Since ε is arbitrary, we conclude $\limsup_{\alpha, \beta \in I} \|f_\alpha(x) - f_\beta(x)\| = 0$.

We have proved that (f_α) has a pointwise limit $f : X \rightarrow \mathcal{V}$. Since (f_α) is equicontinuous, by Cor. 9.21, f is continuous. \square

Claim 17.11. *When X is a separable topological space, Thm. 17.7 can be proved without using Zorn's lemma.*

We know that separable is equivalent to second countable when X is metrizable, but is slightly weaker in general (cf. Sec. 8.5). In practice, however, almost all separable topological spaces you will encounter are Hausdorff and second countable. So there is no need to count the nuances of separability and second countability.

²In fact, instead of assuming that \mathcal{A} is pointwise bounded, it suffices to assume that $\mathcal{A}(x)$ is bounded for some $x \in X$. Then the pointwise boundedness will follow automatically from the uniform Lipschitz continuity. Can you see why?

Proof. Let $Y = \mathbb{R}^N$. As in the proof of Thm. 17.7, $\overline{\mathcal{A}} = \text{Cl}_{C(X,Y)}(\mathcal{A})$ is equicontinuous and pointwise bounded. Let (f_α) be a net in $\overline{\mathcal{A}}$. Since X is separable, we can choose a countable dense subset $E \subset X$. For each $p \in E$, $\overline{\mathcal{A}}(p)$ is contained in a compact $K_p \subset Y$. By the countable Tychonoff theorem (whose proof does not rely on Zorn's lemma, see Thm. 3.54 or Pb. 8.7), $\prod_{p \in E} K_p$ is compact. Therefore, (f_α) has a subnet (f_β) converging pointwise on E . Since $\overline{\mathcal{A}}$ is equicontinuous, so is (f_β) . Therefore, by Prop. 17.10, (f_β) converges pointwise on X to some $f \in C(X, Y)$. So $f \in \text{Cl}_{C(X,Y)}(\overline{\mathcal{A}}) = \overline{\mathcal{A}}$. This proves that $\overline{\mathcal{A}}$ is compact. \square

Remark 17.12. Claim 17.11 and its proof can be compared with Pb. 16.5. In particular, Prop. 10.28 plays the same role in the solution of Pb. 16.5 as Prop. 17.10 does in the proof of Claim 17.11. In both situations, if one wants to prove the separable case without using Zorn's lemma, one needs an extra analytic step to pass from a dense subset to the original space.

Remark 17.13. The readers may wonder why I often give two proofs of the same theorem, one using Zorn's lemma, which applies to a (slightly) larger setting and is somewhat simpler, and the other not using Zorn's lemma, but requires more extra steps. I have mentioned that Zorn's lemma is equivalent to the axiom of choice. However, whether or not to accept the axiom of choice is a matter of taste (or faith). After all, both the statements and the proof of Zorn's lemma are very hard to understand intuitively (at least to me).

Nowadays, most mathematicians accept it because it often simplifies proofs and theories, it often proves theorems for a larger class of examples, and it is compatible with the theorems proved without using it. Therefore, the more theorems that can be proved both with and without Zorn's lemma, the more reason there is to believe in Zorn's lemma/axiom of choice. If there is any way to understand Zorn's lemma intuitively, it is to compare a proof using Zorn's lemma with a proof of the same theorem without using it, as we did in Sec. 15.7 and Ch. 16 and continue to do in this chapter. \square

17.2.2 Precompactness under uniform convergence topology

In the last subsection, we see that equicontinuity implies precompactness under the pointwise convergence topology. The converse is not necessarily true. In this section, we will see that under reasonable assumptions, equicontinuity is equivalent to precompactness under the uniform convergence topology.

Theorem 17.14. *Let X be a topological space. Let \mathcal{V} be a Banach space. Equip $C(X, \mathcal{V})$ with the uniform convergence metric. Let \mathcal{A} be a precompact subset of $C(X, \mathcal{V})$. Then \mathcal{A} is equicontinuous.*

First proof. It suffices to prove that $\overline{\mathcal{A}}$ is equicontinuous. Thus, by replacing \mathcal{A} with $\overline{\mathcal{A}}$, we assume that \mathcal{A} is compact (under the uniform convergence metric).

Let us prove the equicontinuity of \mathcal{A} at any $x \in X$. Choose any $\varepsilon > 0$. For each $f \in \mathcal{A}$, let U_f be the open ball centered at f with radius ε , i.e.

$$W_f = \{g \in C(X, \mathcal{V}) : \|g - f\|_{l^\infty(X, \mathcal{V})} < \varepsilon\}$$

Since \mathcal{A} is compact, there is a finite subset $\mathcal{E} \subset \mathcal{A}$ such that $\mathcal{A} \subset \bigcup_{f \in \mathcal{E}} W_f$. Since each $f \in \mathcal{E}$ is continuous at x , and since \mathcal{E} is finite, there exists $U \in \text{Nbh}_X(x)$ such that $\text{diam}(f(U)) < \varepsilon$ for all $f \in \mathcal{E}$. Therefore, for each $g \in \mathcal{A}$, choose $f \in \mathcal{E}$ such that $g \in W_f$. Then since $\text{diam}(f(U)) < \varepsilon$ for that particular f , by triangle inequality, we have $\text{diam}(g(U)) < 3\varepsilon$. Thus $\sup_{g \in \mathcal{A}} \text{diam}(g(U)) \leq 3\varepsilon$. Since ε can be arbitrary, we conclude that \mathcal{A} is equicontinuous at x . \square

Second proof. This is a fancy proof, just for entertainment. Again, we assume WLOG that \mathcal{A} is compact. Consider the inclusion map $\mathcal{A} \mapsto C(X, \mathcal{V})$ (sending f to f). By Thm. 9.3, it can be viewed as a continuous map

$$X \times \mathcal{A} \rightarrow \mathcal{V} \quad (x, f) \mapsto f(x)$$

Since \mathcal{A} is compact, by Thm. 9.3, the above map can be viewed as a continuous map

$$\Phi : X \rightarrow C(\mathcal{A}, \mathcal{V})$$

where for each $x \in X$, $\Phi(x) : \mathcal{A} \rightarrow \mathcal{V}$ sends f to $f(x)$. By enlarging the codomain of Φ , we can view Φ as a map $X \rightarrow \mathcal{V}^{\mathcal{A}}$ where $\mathcal{V}^{\mathcal{A}}$ is equipped with the uniform convergence topology. The continuity of Φ means, by the very definition of equicontinuity (cf. Def. 9.6), that \mathcal{A} is equicontinuous. \square

Theorem 17.15 (Arzelà-Ascoli (AA) theorem). *Let X be a compact topological space. Equip $C(X, \mathbb{R}^N)$ with the uniform convergence topology. Let \mathcal{A} be a subset of $C(X, \mathbb{R}^N)$. Then the following are equivalent.*

- (1) \mathcal{A} is a precompact subset of $C(X, \mathbb{R}^N)$.
- (2) \mathcal{A} is pointwise bounded and equicontinuous.

Proof. Assume (1). For each $x \in X$, since the map $f \in \mathcal{A} \mapsto f(x)$ is continuous and \mathcal{A} is compact, by the extreme value theorem, we have $\sup_{f \in \mathcal{A}} \|f(x)\| < +\infty$. So \mathcal{A} is pointwise bounded. By Thm. 17.14, \mathcal{A} is equicontinuous.

Assume (2). Write $Y = \mathbb{R}^N$. Note that the uniform convergence topology is metrizable. Thus, to prove (1), by Prop. 17.2 it suffices to choose an arbitrary net (f_α) in \mathcal{A} and show that it has a cluster point in $C(X, Y)$. By Thm. 17.7, \mathcal{A} is precompact under the pointwise convergence topology. So (f_α) has a subnet (f_β) converging pointwise to some $f \in C(X, Y)$. Since X is compact and (f_β) is equicontinuous, by Cor. 9.26, (f_β) converges uniformly to f . \square

In the next chapter, we will use the AA theorem to study differential equations. See Thm. 18.6.

Remark 17.16. The proof of AA theorem relies on Thm. 17.7, and hence in turn relies on Zorn's lemma. If X is separable, then AA theorem does not rely on Zorn's lemma since Thm. 17.7 does not (cf. Claim 17.11).

★ **Remark 17.17.** One may wonder if AA theorem still holds when \mathbb{R}^N is replaced by an arbitrary normed vector space \mathcal{V} (or even a metric space). In fact, in this case, if we assume that \mathcal{A} is **pointwise precompact** (i.e., for each $x \in X$, $\mathcal{A}(x)$ is precompact in \mathcal{V}), then Thm. 17.7 still holds, as one can check by reading the proof of Thm. 17.7. Therefore, AA theorem also holds if “pointwise bounded” is replaced by “pointwise precompact”. However, in most applications, \mathcal{V} is \mathbb{R}^N .

17.3 Operator norms and compactness: Banach-Alaoglu theorem

Every interesting topological space is a metric space. Every interesting Banach space is separable. Every interesting real-valued function is Baire/Borel measurable.

— Barry Simon [Sim-R, Preface of Part 1]

In this section, we fix a normed vector space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

We are going to apply the results and methods in Sec. 17.2 to linear maps on V . Note that if W is a normed vector space over \mathbb{F} , the operator norm on $\mathcal{L}(V, W)$ is defined to be $\|T\| = \|T\|_{l^\infty(\overline{B}_V(0,1), W)}$. Therefore, if (T_α) is a net in $\mathcal{L}(V, W)$ and $T \in \mathcal{L}(V, W)$, then

$$\lim_{\alpha} \|T_\alpha - T\| = 0 \quad \Longleftrightarrow \quad T_\alpha \rightrightarrows T \text{ on } \overline{B}_V(0,1) \quad (17.2)$$

In other words, operator norms describe the uniform convergence of linear maps on the closed unit balls.

To apply the results in the last section, we must let W be \mathbb{F}^N . Let us consider the case $W = \mathbb{F}$. Then $\mathcal{L}(V, \mathbb{F}) = V^*$. The closed unit ball $\overline{B}_V(0,1)$ is not compact unless when V is finite dimensional. (See Thm. 17.56.) We have seen such an example in Exp. 17.1 where $V = C([0,1], \mathbb{R})$. Therefore, the Arzelà-Ascoli theorem is not available. Thus, one cannot expect general compactness in V^* if the topology on V^* is the uniform convergence topology on $\overline{B}_V(0,1)$, i.e. the topology induced by the operator norm. To get compactness in V^* , one must consider the pointwise convergence topology.

17.3.1 Weak-* topology and Banach-Alaoglu theorem

Definition 17.18. The topology on $V^* = \mathcal{L}(V, \mathbb{F})$ inherited from the product topology on \mathbb{F}^V is called the **weak-* topology**. A net (φ_α) in V^* is said to **converge**

weak-* to $\varphi \in V^*$ if (φ_α) converges to φ under the weak-* topology, equivalently, if (φ_α) converges pointwise to φ when viewed as functions $V \rightarrow \mathbb{F}$. By contrast, the **norm topology** (cf. Def. 7.11) on V^* is the topology induced by the (operator) norm of V^* .

Note that since $\overline{B}_V(0, 1)$ spans V , a net of linear maps converges pointwise on V iff it converges pointwise on $\overline{B}_V(0, 1)$. Therefore, the weak-* topology is also the one induced by the product topology on $\mathbb{F}^{\overline{B}_V(0, 1)}$.

We first prove the normed vector space version of Prop. 17.10.

Proposition 17.19. *Let V and W be normed vector spaces over \mathbb{F} where W is a Banach space. Let $M \in \mathbb{R}_{\geq 0}$, and let (T_α) be a net in $\mathcal{L}(V, W)$ such that $\|T_\alpha\| \leq M$ for all α . Let E be a subset of V spanning a dense subspace of V . Assume that (T_α) converges pointwise on E . Then (T_α) converges pointwise on V to some $T \in \mathcal{L}(V, W)$ satisfying $\|T\| \leq M$.*

It follows that if (T_α) also converges pointwise on E to some $T' \in \mathcal{L}(V, W)$, then (T_α) converges pointwise on V to T' . (This is because both T and T' are bounded linear, and they are equal on the dense subset $\text{Span}_{\mathbb{F}} E$ of V . So $T = T'$.)

Proof. By assumption, $F = \text{Span}_{\mathbb{F}} E$ is dense in V . By linearity, (T_α) converges pointwise on F . By Prop. 10.25, (T_α) has uniform Lipschitz constant M . So (T_α) is an equicontinuous net. By Prop. 17.10 and the completeness of W , (T_α) converges pointwise on V to $T \in C(V, W)$.

For each $u, v \in V, a, b \in \mathbb{F}$ we have

$$T(au + bv) = \lim_{\alpha} T_{\alpha}(au + bv) = \lim_{\alpha} (aT_{\alpha}(u) + bT_{\alpha}(v)) = aT(u) + bT(v)$$

So T is linear. For each $v \in V$, since $\|T_{\alpha}(v)\| \leq \|T_{\alpha}\| \cdot \|v\| \leq M\|v\|$, we have

$$\|T(v)\| = \lim_{\alpha} \|T_{\alpha}(v)\| \leq M\|v\|$$

So $\|T\| \leq M$ by Rem. 10.24. □

Roughly speaking, Prop. 17.19 says that if a net of bounded linear operators have a uniform upper bound for their operator norms, then pointwise convergence on a dense subset (or more generally, on a subset spanning a dense subspace) implies pointwise convergence on the whole space. The assumption on the uniform upper bound cannot be removed:

Example 17.20. For each $n \in \mathbb{Z}_+$, define $T_n : l^1(\mathbb{Z}_+, \mathbb{R}) \rightarrow \mathbb{R}$ sending each f to $n^3 f(n)$. Let $E = \{\chi_{\{k\}} : k \in \mathbb{Z}_+\}$. Then E spans a dense subspace of $l^1(\mathbb{Z}_+, \mathbb{R})$. For each $k \in \mathbb{Z}_+$ we have $\lim_n T_n \chi_k = 0$. However, $\|T_n\| = n^3$ has no uniform upper bounds. Define $f \in l^1(\mathbb{Z}_+, \mathbb{R})$ by $f(n) = n^{-2}$. Then $T_n f = n$ does not converge in \mathbb{R} as $n \rightarrow \infty$. So (T_n) does not converge pointwise on $l^1(\mathbb{Z}_+, \mathbb{R})$, although it converges pointwise on E (and hence on $\text{Span} E$) to 0.

The following Banach-Alaoglu theorem can be viewed as the normed vector space version of Thm. 17.7.

Theorem 17.21 (Banach-Alaoglu theorem). $\overline{B}_{V^*}(0, 1)$ is *weak-* compact*, i.e., it is compact under the weak-* topology.

By our notations, $\overline{B}_{V^*}(0, 1)$ is the set of all $\varphi \in V^*$ satisfying $\|\varphi\| \leq 1$. Note that weak-* topology is clearly Hausdorff.

Proof. Let $\mathcal{A} = \overline{B}_{V^*}(0, 1)$. Since elements in \mathcal{A} have operator norms ≤ 1 , they have Lipschitz constant 1 by Prop. 10.25. So \mathcal{A} is equicontinuous on V . For each $v \in V$, $\mathcal{A}(v)$ is bounded since $\mathcal{A}(v) \subset \overline{B}_{\mathbb{F}}(0, \|v\|)$. Thus, by Thm. 17.7, \mathcal{A} has compact closure in $C(V, \mathbb{F})$ under the pointwise convergence topology. Therefore, to show that \mathcal{A} is compact, it suffices to show that \mathcal{A} is closed in $C(V, \mathbb{F})$. Let (φ_α) be a net in \mathcal{A} converging pointwise to $\varphi \in C(V, \mathbb{F})$. By Prop. 17.19, $\varphi \in V^*$ and $\|\varphi\| \leq 1$. So \mathcal{A} is closed. \square

Remark 17.22. Similar to Arzelà-Ascoli theorem, the proof of the Banach-Alaoglu theorem relies on Thm. 17.7, and hence relies on Zorn's lemma. If V is a separable normed vector space, the Banach-Alaoglu theorem does not rely on Zorn's lemma because the proof of Thm. 17.7 does not, cf. Claim 17.11.

17.3.2 Application: embedding into $C(X, \mathbb{F})$

Recall that V is a normed vector space over \mathbb{F} .

Theorem 17.23. *There is a compact Hausdorff space X and a linear isometry $\Phi : V \rightarrow C(X, \mathbb{F})$. Moreover, if V is separable, then X can be chosen to be metrizable.*³

In other words, V is isomorphic to a linear subspace of $C(X, \mathbb{F})$ (namely, $\Phi(V)$). Clearly, if V is Banach, then $\Phi(V)$ is complete and hence closed. So each Banach space is isomorphic to a closed linear subspace of $C(X, \mathbb{F})$ for some X .

A similar embedding for metric spaces is given in Pb. 17.4.

Proof. We let $X = \overline{B}_{V^*}(0, 1)$, equipped with the weak-* topology. By Banach-Alaoglu, X is a compact Hausdorff space. The linear map $\Phi : V \rightarrow C(X, \mathbb{F})$ is defined by sending each v to the function

$$\Phi(v) : X \rightarrow \mathbb{F} \quad \varphi \mapsto \langle \varphi, v \rangle$$

To check the continuity of $\Phi(v) : X \rightarrow \mathbb{F}$, we let (φ_α) be any net in X converging weak-* to $\varphi \in X$. Then $\Phi(v)(\varphi_\alpha) = \langle \varphi_\alpha, v \rangle$ converges to $\langle \varphi, v \rangle = \Phi(v)(\varphi)$, proving that $\Phi(v)$ is continuous.

³In fact, every separable normed vector space can be embedded into $C([0, 1], \mathbb{F})$. This is called the **Banach-Mazur theorem**, whose proof is more involved. Cf. [AK, Sec. 1.4].

Let $v \in V$. For each $\varphi \in X$, we have

$$|\langle \Phi(v), \varphi \rangle| = |\langle \varphi, v \rangle| \leq \|\varphi\| \cdot \|v\| = \|v\|$$

This proves that $\|\Phi(v)\|_{l^\infty(X, \mathbb{F})} \leq \|v\|$. (Recall Rem. 10.24.) By Hahn-Banach Cor. 16.6, there is $\varphi \in X$ with $\|\varphi\| = 1$ such that $\langle \varphi, v \rangle = \|v\|$. Thus $\|\Phi(v)\|_{l^\infty(X, \mathbb{F})} = \|v\|$. This proves that Φ is a linear isometry.

Suppose that V is separable. Then we can find a sequence $(v_n)_{n \in \mathbb{Z}_+}$ dense in V . It is clear that $\Phi(V)$ separates points of X . So $\Phi(v_1), \Phi(v_2), \dots$ separate points of X . Therefore,

$$X \rightarrow S = \mathbb{F}^{\mathbb{Z}_+} \quad \varphi \mapsto (\Phi(v_n)(\varphi))_{n \in \mathbb{Z}_+} \quad (17.3)$$

is a continuous injective map of X into S . Since X is compact, X is homeomorphic to $\Phi(X)$. Since S is metrizable, so is $X = \overline{B_{V^*}}(0, 1)$. \square

As an immediate consequence of the above proof we have:

Theorem 17.24. *V is separable iff $\overline{B_{V^*}}(0, 1)$ is metrizable (under the weak-* topology).*

Recall Thm. 15.37 for equivalent descriptions of metrizable compact Hausdorff spaces. In fact, Thm. 17.24 is closely related to Thm. 15.37, since the relationship between V and $\overline{B_{V^*}}(0, 1)$ is similar to that between $C(X, \mathbb{R})$ and X , as implied by the proof of Thm. 17.23.

Proof. The proof of Thm. 17.23 shows that if V is separable then $X = \overline{B_{V^*}}(0, 1)$ is metrizable. Conversely, assume that X is metrizable. The proof of Thm. 17.23 shows that V is isomorphic to a linear subspace of $C(X, \mathbb{R})$. By Thm. 15.37, $C(X, \mathbb{R})$ is second countable. So V is second countable, equivalently, separable. \square

Remark 17.25. It follows from Thm. 17.24 that if V is separable then $\overline{B_{V^*}}(0, 1)$ is sequentially compact. In history, at a time when sequential compactness was still the primary way for people to understand compactness, there were good reasons for studying the sequential compactness of $\overline{B_{V^*}}(0, 1)$. This is because early examples of Banach spaces that people focused on were separable.

Remark 17.26. A typical example of a non-separable Banach space is $l^\infty(\mathbb{Z}, \mathbb{F})$, cf. Pb. 17.7. Precisely for this reason, the dual space of $l^\infty(\mathbb{Z}, \mathbb{F})$ is not much studied, and the norm topology on $l^\infty(\mathbb{Z}, \mathbb{F})$ is not good enough. The weak-* topology on (the unit ball of) $l^\infty(\mathbb{Z}, \mathbb{F})$ is more natural since, given the equivalence $l^1(\mathbb{Z}, \mathbb{F})^* \simeq l^\infty(\mathbb{Z}, \mathbb{F})$ (cf. Thm. 17.30) and the separability of $l^1(\mathbb{Z}, \mathbb{F})$, the closed unit ball of $l^\infty(\mathbb{Z}, \mathbb{F})$ is weak-* metrizable (equivalently, second countable).⁴ In the study of modern analysis, it is helpful to keep in mind the following two principles:

⁴If V is infinite dimensional, the weak-* topology of V^* is indeed not first countable, and hence is neither metrizable nor second countable. Therefore, the weak-* topology of $\overline{B_{V^*}}(0, 1)$ is more natural than that of V^* .

- Metrizability and second-countability are tests for whether or not a topological space is natural (e.g. whether or not it is reasonable from a natural science point of view).
- However, proving theorems only for metrizable and second-countable spaces will actually make the theory more complicated. It is mainly for the purpose of simplifying the theory (e.g. making the assumptions in the theorems shorter) that we prove the theorems in general, regardless of whether a topological space is metrizable/second-countable or not.⁵

In Rem. 17.27, I will say more about the significance of Thm. 17.24.

17.4 Banach-Alaoglu for L^p and l^p spaces

So far, we have discussed V^* and its weak-* topology on a very abstract level. In the following, we shall understand the results proved in Sec. 17.3 in a more concrete setting.

17.4.1 Weak-* topology in context

Let $1 < p \leq +\infty$ and $1 \leq q < +\infty$ satisfy $\frac{1}{p} + \frac{1}{q} = 1$. Let I be an interval in \mathbb{R} . Let $L^p(I)$ be the set of Lebesgue measurable functions ⁶ $f \rightarrow \mathbb{C}$ satisfying that the L^p -(semi)norm $\|f\|_p = \sqrt[p]{\int_0^1 |f|^p}$ is finite. A remarkable **representation theorem** of F. Riesz says that we have an (isometric) isomorphism of Banach spaces

$$\Phi : L^p(I) \rightarrow L^q(I)^*$$

such that for each $f \in L^p(I)$, $\Phi(f)$ is the linear map sending each $g \in L^q(I)$ to

$$\langle \Phi(f), g \rangle = \int fg$$

Therefore, if (f_α) is a net in $L^p(I)$ and $f \in L^p(I)$, then (f_α) converges weak-* to f (more precisely, $(\Phi(f_\alpha))$ converges weak-* to $\Phi(f)$) iff $\lim_\alpha \int_I f_\alpha g = \int_I fg$ for all $g \in L^q(I)$.

⁵For example, the fact that $(l^1)^* \simeq l^\infty$ shows that separability is not closed under taking dual. Thus, if we stick to separable Banach spaces, the use of Hahn-Banach and Banach-Alaoglu will be more restricted (e.g. when discussing the relationship between V and V^{**} , see Hahn-Banach Cor. 16.6 and Goldstine's Thm. 17.55).

⁶Lebesgue measurable functions are more general than Riemann integrable functions. We will discuss them in the next semester. To understand the material of this section, it is not important to know the precise meaning of them.

In fact, when $I = [-\pi, \pi]$, using the l^∞ -density of $\text{Span}\{e^{inx} : n \in \mathbb{Z}\}$ in $C([-\pi, \pi])$ (Exp. 15.12), it can be proved that if (f_α) is a net in $L^p([-\pi, \pi])$ satisfying $\sup_\alpha \|f_\alpha\|_p < +\infty$, then (f_α) converges weak-* to $f \in L^p([-\pi, \pi])$ iff

$$\lim_\alpha \int_{-\pi}^{\pi} f_\alpha(x) e^{-inx} dx = \int_{-\pi}^{\pi} f(x) e^{-inx} dx$$

i.e., iff the Fourier coefficients of (f_α) converge to the corresponding ones of f .

Remark 17.27. Let me discuss the importance of Thm. 17.24 in the context of L^p spaces. As we will see in the future, Lebesgue measure (and measure theory in general) is not very compatible with net convergence. The main reason is that measure theory is countable by nature, as one can feel in Sec. 14.2. For example, the pointwise limit of a sequence of Lebesgue measurable functions is Lebesgue measurable, but the pointwise limit of a net of measurable functions is not necessarily so. Lebesgue's dominated convergence theorem, a powerful theorem about the commutativity of limits and integrals, applies only to sequences but not nets of functions.

However, it is true that $L^q(I)$ is separable. Therefore, by Thm. 17.24, the closed unit ball of $L^p(I)$ is a metrizable compact space under the weak-* topology. Therefore, to study the weak-* convergence for functions $f \in L^p(I)$ satisfying $\|f\|_p \leq 1$, it suffices to use sequences instead of nets, because metrizable topologies and their compactness are determined by sequential convergence. Therefore, one can use all the results in measure theory to study the weak-* topology on $\overline{B}_{L^p(I)}(0, 1)$. \square

17.4.2 Weak-* topology on l^p spaces

Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and let X be a set. Recall that $1 < p \leq +\infty$ and $1 \leq q < +\infty$ satisfy $\frac{1}{p} + \frac{1}{q} = 1$.

In this subsection, we prove that the linear isometry Ψ in Thm. 12.33 is surjective, thus establishing the isomorphism $l^p(X, \mathbb{F}) \simeq l^q(X, \mathbb{F})^*$. Using this isomorphism, we give a concrete (and historically important) description of weak-* topology on the norm-bounded subsets of $l^p(X, \mathbb{F})$. We introduce a temporary notation

$$\mathcal{S}(X, \mathbb{F}) = \{f \in \mathbb{F}^X : f = 0 \text{ except at finitely many points}\} \quad (17.4)$$

Then $\mathcal{S}(X, \mathbb{F})$ is clearly a subspace of $l^q(X, \mathbb{F})$.

Lemma 17.28. $\mathcal{S}(X, \mathbb{F})$ is dense in $l^q(X, \mathbb{F})$ under the l^q -norm.

Proof. Let $f \in l^q(X, \mathbb{F})$. Then $\lim_{A \in \text{fin}(2^X)} \sum_A |f|^q = \sum_X |f|^q < +\infty$. Thus, for every $\varepsilon > 0$ there is $A \in \text{fin}(2^X)$ such that $\sum_{X \setminus A} |f|^q < \varepsilon^q$, and hence $\|f - f\chi_A\|_q < \varepsilon$. This finishes the proof, since $f\chi_A \in \mathcal{S}(X, \mathbb{F})$. \square

Exercise 17.29. Show that $\mathcal{S}(X, \mathbb{F})$ is not dense in $l^\infty(X, \mathbb{F})$ if X is an infinite set.

Theorem 17.30. *The linear isometry*

$$\begin{aligned}\Psi : l^p(X, \mathbb{F}) &\rightarrow l^q(X, \mathbb{F})^* \\ \langle \Psi(f), g \rangle &= \sum_{x \in X} f(x)g(x)\end{aligned}$$

in Thm. 12.33 is an isomorphism of Banach spaces.

In the special case that $p = 2$, Thm. 17.30 is called the **Riesz-Fréchet representation theorem**. Recall that we are assuming $1 < p \leq +\infty$ in this theorem. When X is infinite and $p = 1$, Ψ is not surjective. See Pb. 17.8 for details.

Proof. It remains to prove that Ψ is surjective. Choose a nonzero bounded linear $\Lambda : l^q(X, \mathbb{F}) \rightarrow \mathbb{F}$. We want to show that Λ is in the range of Ψ . By scaling Λ we assume for simplicity that $\|\Lambda\| = 1$. Define

$$f : X \rightarrow \mathbb{F} \quad f(x) = \langle \Lambda, \chi_{\{x\}} \rangle \quad (17.5)$$

Let us prove that $f \in l^p(X, \mathbb{F})$. If $p = +\infty$, then $|f(x)| \leq \|\Lambda\| \cdot \|\chi_{\{x\}}\|_q = 1$, and hence $\|f\|_\infty \leq 1$. Assume $p < +\infty$. We understand $\bar{f}(x)/|f(x)|$ as 0 if $f(x) = 0$. Choose any $A \in \text{fin}(2^X)$. Define $g : X \rightarrow \mathbb{F}$ to be $g = (\bar{f}/|f|) \cdot |f|^{p-1} \chi_A$. Then clearly $g \in l^q(X, \mathbb{F})$. We compute

$$\langle \Lambda, g \rangle = \left\langle \Lambda, \sum_{x \in A} g(x) \chi_{\{x\}} \right\rangle = \sum_{x \in A} g(x) \langle \Lambda, \chi_{\{x\}} \rangle = \sum_{x \in A} f(x)g(x) = \sum_A |f|^p$$

On the other hand,

$$\|g\|_q = \left(\sum_A |f|^p \right)^{1/q}$$

Since $|\langle \Lambda, g \rangle| \leq \|\Lambda\| \cdot \|g\|_q = \|g\|_q$, we obtain $(\sum_A |f|^p) \leq (\sum_A |f|^p)^{1/q}$, and hence

$$\sum_A |f|^p \leq 1$$

Applying $\lim_{A \in \text{fin}(2^X)}$, we get $\|f\|_p \leq 1$.

Now choose any $g \in l^q(X, \mathbb{F})$. Since $1 \leq q < +\infty$, as in the proof of Lem. 17.28, it is easy to see that $\sum_{x \in X} g(x) \chi_{\{x\}} = \lim_{A \in \text{fin}(2^X)} \sum_{x \in A} g(x) \chi_{\{x\}}$ converges to g (under the l^q -norm). Thus, since Λ is continuous, we have

$$\begin{aligned}\langle \Lambda, g \rangle &= \left\langle \Lambda, \lim_{A \in \text{fin}(2^X)} \sum_{x \in A} g(x) \chi_{\{x\}} \right\rangle = \lim_{A \in \text{fin}(2^X)} \sum_{x \in A} \langle \Lambda, g(x) \chi_{\{x\}} \rangle \\ &= \lim_{A \in \text{fin}(2^X)} \sum_{x \in A} f(x)g(x) = \sum_X fg\end{aligned}$$

This proves that $\Psi(f) = \Lambda$. □

We are now able to give an explicit characterization of the weak-* topology on norm-bounded subsets (e.g. the unit ball) of $l^p(X, \mathbb{F})$.

Theorem 17.31. *Let (f_α) be a net in $l^p(X, \mathbb{F})$ satisfying $\sup_\alpha \|f_\alpha\|_p < +\infty$, and let $f \in l^p(X, \mathbb{F})$. Then the following are equivalent.*

- (1) (f_α) converges weak-* to f . (More precisely, $(\Psi(f_\alpha))$ converges weak-* to $\Psi(f)$.)
- (2) (f_α) converges pointwise to f as functions $X \rightarrow \mathbb{F}$.

We warn the reader that (1) is not equivalent to (2) if $\sup_\alpha \|f_\alpha\|_p = +\infty$.

Proof. For each $x \in X$ we have $f_\alpha(x) = \langle \Psi(f_\alpha), \chi_{\{x\}} \rangle$ and $f(x) = \langle \Psi(f), \chi_{\{x\}} \rangle$. Therefore, (2) is equivalent to that $\Psi(f_\alpha)$ converges to $\Psi(f)$ when acting on each $\chi_{\{x\}}$. Since Ψ is an isometry, $\sup_\alpha \|\Psi(f_\alpha)\| = \sup_\alpha \|f_\alpha\|_p < +\infty$. Therefore, by Prop. 17.19, (2) is equivalent to that $\Psi(f_\alpha)$ converges pointwise on $l^q(X, \mathbb{F})$ to $\Psi(f)$, because functions of the form $\chi_{\{x\}}$ span $\mathcal{S}(X, \mathbb{F})$, a norm-dense subspace of $l^q(X, \mathbb{F})$ due to Lem. 17.28. \square

Remark 17.32. Weak-* convergence and the Banach-Alaoglu theorem were first studied for (the closed unit ball of) $l^2(\mathbb{Z}, \mathbb{F})$ by Hilbert in his study of integral equations and eigenvalue problem (cf. Ch. 9.23). Of course, Hilbert didn't have the modern definition of weak-* topology. For him, the weak-* convergence on the unit ball simply means condition (2) of Thm. 17.31. Taking Thm. 17.31-(2) as the definition of weak-* convergence, the Banach-Alaoglu theorem can be proved quite easily for $l^2(\mathbb{Z}, \mathbb{F})$ (cf. Pb. 17.5). Therefore, as with many abstract definitions, the notion of weak-* topology has its origins in very concrete forms of expression.

After Hilbert's study of l^2 spaces (a.k.a. Hilbert spaces), F. Riesz generalized weak-* topology and Banach-Alaoglu theorem to l^p and L^p spaces for arbitrary $1 < p \leq +\infty$, as we shall see in the next section.

Remark 17.33. If $1 < p < +\infty$, the weak-* topology on $l^p(X)$ is also called the **weak topology**. See Rem. 21.25.

17.5 The birth of operator norms, I: moment problems

It can be said that F. Riesz made the first crucial contribution to the notion of dual spaces of Banach spaces. According to Riesz, bounded linear functionals on $L^q(I)$ (when $1 < q < +\infty$ and I is an interval in \mathbb{R}) are nothing abstract. They are simply elements of $L^p(I)$. But what is the advantage of viewing $f \in L^p(I)$ not only as a function on I , but also as a linear functional on $L^q(I)$? Why was Riesz interested in characterizing $L^q(I)^*$ at all?

In fact, Riesz's study of dual spaces is related to the **moment problems** which have applications to probability. Around 1910, Riesz studied the following type

of moment problem: Let g_1, g_2, \dots be a sequence in $L^q(I)$, let $c_1, c_2, \dots \in \mathbb{C}$, and find some $f \in L^p(I)$ such that

$$\int f g_j = c_j \quad (\text{for all } j) \quad (17.6)$$

(For example, in the classical moment problem, $g_n(x) = x^n$, and f is understood as a “probability distribution”. Then $\int f(x)x dx = c_1$ is the mean (i.e., expected value) of f , and $\int f(x)(x - c_1)^2 dx$ is the variance of f . The number $c_n = \int f(x)x^n dx$ is called the **n -th moment** of f .)

By Hölder’s inequality, if such f exists, then there must be some $M \in \mathbb{R}_{\geq 0}$ (e.g. $M = \|f\|_{L^p}$), such that

$$|a_1 c_1 + \dots + a_n c_n| \leq M \cdot \|a_1 g_1 + \dots + a_n g_n\|_{L^q} \quad (\forall n \in \mathbb{Z}_+, a_1, \dots, a_n \in \mathbb{C}) \quad (17.7)$$

Riesz proved that the existence of M satisfying (17.7) is also a sufficient condition for the existence of $f \in L^p(I)$ satisfying (17.6).

From the modern viewpoint, Riesz’s result can be proved in the following way: Let V be spanned by g_1, g_2, \dots . By (17.7), there exists a unique linear functional $\varphi : V \rightarrow \mathbb{C}$ with operator norm $\leq M$ satisfying $\varphi(g_j) = c_j$ for all j . By Hahn-Banach Thm. 16.5, φ can be extended to a bounded linear functional $\varphi : L^q(I) \rightarrow \mathbb{C}$ also with operator norm $\leq M$. Then, by the isomorphism $L^p(I) \simeq L^q(I)^*$, φ can be realized by some $f \in L^p(I)$, which is the desired function.

Remark 17.34. In fact, Riesz didn’t find the linear functional $L^q(I) \rightarrow \mathbb{C}$ in this way. He didn’t see this problem as extending linear functionals. And Hahn-Banach theorem didn’t exist before Riesz solved the moment problem. (Riesz’s solution is actually an important motivation for the Hahn-Banach theorem.)

Riesz found $\varphi : L^q(I) \rightarrow \mathbb{C}$ in the following way (cf. [Die-H, Sec. VI.2]). In the first step, by using complicated methods, he could find $f_n \in L^p(I)$ satisfying $\|f_n\|_{L^p} \leq M$ and

$$\int_I f_n g_i = c_i \quad (\text{for every } 1 \leq i \leq n)$$

In Sec. 17.10, we will explain more about how to find these f_n .

In the second step, Riesz considered $\Phi(f_n) : L^q(I) \rightarrow \mathbb{C}$ sending each $g \in L^q(I)$ to $\int f_n g$. Then, for each j , we have $\lim_{n \rightarrow \infty} \langle \Phi(f_n), g_j \rangle = c_j$. Riesz made the following crucial steps:

- He proved the Banach-Alaoglu theorem for $L^q(I)^*$ using diagonal method. Therefore, since $\sup_n \|\Phi(f_n)\| = \sup_n \|f_n\|_p \leq M$, one has a subsequence

$\Phi(f_{n_k})$ converging weak-* to some $\varphi \in L^q(I)^*$.⁷ Then clearly $\langle \varphi, g_j \rangle = c_j$ for all j .⁸

Then φ can be represented by some $f \in L^p(I)$ thanks to $L^p(I) \simeq L^q(I)^*$. \square

Therefore, Riesz's study of moment problems contributed to:

- (a) The discovery of important special cases of Banach-Alaoglu theorem.
- (b) The realization that operator norms play an important role in the compactness of dual Banach spaces.
- (c) The discovery of $L^p(I) \simeq L^q(I)^*$.

After the work of Riesz, operator norms became a central concept in modern analysis.

We refer the readers to [Die-H, Ch. VI] and [NB97] for more details about the relevant history, and to [Sim-R, Sec. 4.17 & 5.6] for a modern treatment of moment problems.

17.6 Operator norms and completeness: functional calculus

In this section, all normed vector spaces are over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

That one can do a lot of analysis on the *linear maps* of function spaces is a remarkable fact. In fact, in the early history of functional analysis, people were more interested in *nonlinear* functionals on function spaces, for example, the expression $S(f)$ in the calculus of variations (cf. (2.1)), for which one searched for the extreme values. The problem of finding extreme values is almost trivial if the functional S is linear and defined on a vector space of functions. Even Hilbert studied the eigenvalue problem for the integral operator $(Tf)(x) = \int_0^1 K(x, y)f(y)dy$ (cf. Subsec. 10.4.1) by transforming it to the extreme value problem of the functional $S(f) = (2.1b)$ defined for all f on the closed unit ball of $L^2([0, 1], \mathbb{C})$, viewing $S(f)$ as an (infinite-dimensional) **quadratic form**.

F. Riesz first recognized the importance of **operator norms**, thus calling people's attention to bounded linear maps of function spaces. Thus, Riesz is undoubtedly one of the most prominent figures in the early history of *linear* functional analysis. We have defined bounded linear maps between arbitrary Banach spaces $V \rightarrow W$. However, to understand the nature of operator norms, we have to look at the following two important special cases:

⁷Since $L^q(I)$ is separable, the closed ball of $L^q(I)^*$ with radius M is compact metrizable by Thm. 17.24, and hence is sequentially compact.

⁸More precisely, the following is what Riesz did: Using the diagonal method as in the proof of Thm. 3.54, he found $\Phi(f_{n_k})$ whose evaluations with the elements in a given countable dense subset of $L^q(I)$ converge. Since $\sup_k \|\Phi(f_{n_k})\| < +\infty$, by Prop. 17.19, one concludes that $(\Phi(f_{n_k}))$ converges weak-* to some $\varphi \in L^q(I)^*$.

- (1) Bounded linear maps $V \rightarrow \mathbb{F}$. By Banach-Alaoglu, one can use the operator norm to get a weak-* compact set $\overline{B}_{V^*}(0, 1)$. This has been discussed in previous sections.
- (2) Bounded linear maps $V \rightarrow V$. As we will see below, the operator norm makes $\mathfrak{L}(V) := \mathfrak{L}(V, V)$ a Banach space which is compatible with its \mathbb{F} -algebra structure. Namely, $\mathfrak{L}(V)$ is a **Banach algebra**. Here, the crucial analytic property is completeness rather than compactness.

Thus, in these two cases, the operator norms are playing different roles: compactness in the first case, and completeness in the second one. For example, as I will argue in the future, Hilbert and Schmidt noticed the importance of $l^2(\mathbb{Z}, \mathbb{C})$ not so much because of its completeness, but because of the weak-* compactness of its closed unit ball.

17.6.1 The Banach algebra $\mathfrak{L}(V)$

Let me explain the meaning of the statement “ $\mathfrak{L}(V)$ is a Banach algebra”. First, we observe:

Theorem 17.35. *Assume that V is a normed vector spaces and W is a Banach space. Recall that $\mathfrak{L}(V, W)$ is a linear subspace of W^V (cf. Prop. 10.27). Then $\mathfrak{L}(V, W)$, equipped with the operator norm, is a Banach space.*

Proof. By Prop. 10.27, it remains to prove that $\mathfrak{L}(V, W)$ is complete. Let (T_n) be a Cauchy sequence in $\mathfrak{L}(V, W)$. So $\lim_{m,n \rightarrow \infty} \|T_m - T_n\| = 0$. For each $v \in V$, we have $\|T_m v - T_n v\| \leq \|T_m - T_n\| \cdot \|v\|$ which converges to 0 under $\lim_{m,n}$. So $(T_n v)$ is a Cauchy sequence in W , converging to a vector $Tv \in W$. Thus, we have proved that (T_n) converges pointwisely to T . Clearly $M := \sup_{n \in \mathbb{Z}_+} \|T_n\|$ is a finite number. Therefore, by Prop. 17.19, we have $T \in \mathfrak{L}(V, W)$ and $\|T\| \leq M$.

Note that $\lim_n \|T - T_n\| = 0$ means precisely that $T_n \rightrightarrows T$ on $B_V(0, 1)$. Since (T_n) converges pointwisely to T , to prove that $\lim_n \|T - T_n\| = 0$, it suffices to prove that (T_n) converges uniformly to some function on $B_V(0, 1)$. This is due to the completeness of $l^\infty(B_V(0, 1), W)$ and the Cauchyness of $(T_n|_{B_V(0,1)})_{n \in \mathbb{Z}_+}$. \square

Definition 17.36. Let \mathcal{A} be an \mathbb{F} -algebra. Suppose that \mathcal{A} , as a vector space, is equipped with a norm $\|\cdot\|$ so that \mathcal{A} is a normed vector space, and that

$$\|xy\| \leq \|x\| \cdot \|y\| \quad (17.8)$$

for all $x, y \in \mathcal{A}$. Then we call \mathcal{A} a **normed algebra** over \mathbb{F} . If the norm is complete, we say that \mathcal{A} is a **Banach algebra** over \mathbb{F} . A **unital Banach algebra** is a unital algebra (with unit 1) which is also a Banach algebra and satisfies

$$\|1\| = 1$$

As mentioned above, the most important reason for considering operator norms on V^* is due to the Banach-Alaoglu theorem. The most important reason for considering operator norms on $\mathfrak{L}(V)$ is due to the following elementary but important fact:

Theorem 17.37. *Let V be a Banach space. Then $\mathfrak{L}(V)$, equipped with the operator norm, is a unital Banach algebra.*

Recall that the multiplication in $\mathfrak{L}(V)$ is defined by the composition of linear operators.

Proof. This is immediate from Thm. 17.35 and Prop. 17.38. □

Proposition 17.38. *Let $S : U \rightarrow V$ and $T : V \rightarrow W$ be linear maps of normed vector spaces. Then*

$$\|TS\| \leq \|T\| \cdot \|S\| \quad (17.9)$$

Proof. For each $u \in U$ we have $\|TSu\| \leq \|T\| \cdot \|Su\| \leq \|T\| \cdot \|S\| \cdot \|u\|$. According to Rem. 10.24, we get (17.9). □

17.6.2 Power series functional calculus

The word “functional calculus” refers in general to the procedure of replacing the variable x or z in the \mathbb{F} -valued function $f(x)$ or $f(z)$ by T to get $f(T)$, where T is an element in a unital Banach algebra \mathcal{A} . The notation T suggests that the most important case is where $T \in \mathfrak{L}(V)$ for some Banach space V . Depending on whether f is a continuous/analytic/integrable/measurable function, $f(T)$ is defined in different ways. Let us consider the simplest case. In the following, we fix a complex unital Banach algebra \mathcal{A} . (For example, $\mathcal{A} = \mathfrak{L}(V)$ where V is a complex Banach space.)

Let $f(z) = \sum_{n=0}^{\infty} a_n z^n$ be a power series in \mathbb{C} with radius of convergence R . If $T \in \mathcal{A}$ and $\|T\| < R$, we can define

$$f(T) = \sum_{n=0}^{\infty} a_n T^n \quad (17.10)$$

By (17.8), we have $\|T^n\| \leq \|T\|^n$. Therefore, by root test, we have $\sum_n |a_n| \cdot \|T^n\| < +\infty$. So the RHS of (17.10) converges absolutely, and hence converges in \mathcal{A} . So (17.10) makes sense.

The most important general fact about functional calculus is that $f \mapsto f(T)$ is a homomorphism of unital algebras:

Proposition 17.39. *If $f(z) = \sum_n a_n z^n$ and $g(z) = \sum_n b_n z^n$ be power series in \mathbb{C} with radius of convergence R_1, R_2 . Let $R = \min\{R_1, R_2\}$. If \mathcal{A} is a complex unital Banach algebra with unit $\mathbf{1}$, and if $T \in \mathcal{A}$ satisfies $\|T\| < R$, then for each $a, b \in \mathbb{C}$ we have*

$$\mathbf{1}(T) = \mathbf{1} \quad (af + bg)(T) = af(T) + bg(T) \quad (fg)(T) = f(T)g(T)$$

Proof. The first two equations are obvious. We prove the last one. Let $c_n = \sum_{k=0}^n a_k b_{n-k}$. Then $h(z) = \sum_n c_n z^n$ equals $f(z)g(z)$ on $B_{\mathbb{C}}(0, R)$. Cor. 5.59 immediately implies $h(T) = f(T)g(T)$. \square

Let me give a simple application of Prop. 17.39. Recall that one can use determinants to prove that the set of $n \times n$ complex matrices is open in $\mathbb{C}^{n \times n}$. However, in the infinite dimensional case one clearly cannot use determinants. Functional calculus provides an easy method to treat this problem.

Example 17.40. Let $T \in \mathcal{A}$ such that $\|T\| < 1$. Then $1 + T$ is invertible.

Proof. Let $f(z) = 1 + z$. Let $g(z) = \sum_{n=0}^{\infty} (-z)^n$, which has radius of convergence 1 and equals $(1 + z)^{-1}$ when $|z| < 1$. Since $fg = gf = 1$, by Prop. 17.39 we have $(1 + T)S = S(1 + T) = 1$ if we let $S = g(T) = \sum_{n=0}^{\infty} T^n$. \square

Proposition 17.41. The set \mathcal{A}^{\times} of invertible elements is an open subset of \mathcal{A} .

Proof. Let $T \in \mathcal{A}$ be invertible. Let $\delta = \|T^{-1}\|^{-1}$. Then for each $S \in \mathcal{A}$ satisfying $\|T - S\| < \delta$ we have

$$\|T^{-1}(S - T)\| \leq \|T^{-1}\| \cdot \|S - T\| < 1$$

Thus, by Exp. 17.40, $1 + T^{-1}(S - T)$ is invertible. So its multiplication with T (which is S) is invertible. \square

Functional calculus is also useful in differential equations, even in the finite dimensional case:

Exercise 17.42. Let $A, B \in \mathcal{A}$. Suppose that $AB = BA$. Show that $e^{A+B} = e^A \cdot e^B$. Show that

$$\frac{de^{At}}{dt} = Ae^{At} = e^{At}A$$

Exercise 17.43. Let V be a complex Banach space. Let $v \in V$. Let $T \in \mathcal{L}(V)$. Show that there is a unique differentiable $f : \mathbb{R} \rightarrow V$ satisfying the differential equation

$$f'(t) = Tf(t) \quad f(0) = v$$

Show that $f(t) = e^{Tt}v$ satisfies this differential equation.

17.7 The birth of operator norms, II: diagonalization

The power series functional calculus is the easiest example of functional calculus. In history, F. Riesz realized that $\mathcal{L}(V)$ is useful because one can use the completeness of $\mathcal{L}(V)$ under the operator norm to establish the **continuous functional calculus**, a more difficult version of functional calculus. Riesz's realization

of the usefulness of operator norms is probably motivated by his study of moment problems, in which he introduced operator norms to V^* . (See Sec. 17.5.)

Let V be the Hilbert space $l^2(\mathbb{Z}, \mathbb{C})$. For each $T \in \mathfrak{L}(V)$, if $m, n \in \mathbb{Z}$, note that $T\chi_{\{n\}}$ is a function $\mathbb{Z} \rightarrow \mathbb{C}$. We let $T_{m,n} = (T\chi_{\{n\}})(m)$, which is a complex number. (You can view T as an $\infty \times \infty$ matrix. Then $T_{m,n}$ is its $m \times n$ entry.) It can be shown by the l^2 -version of Thm. 17.30 that there is a unique $T^* \in \mathfrak{L}(V)$ such that $(T^*)_{m,n} = \overline{T_{n,m}}$. We say that T is **self-adjoint** if $T = T^*$. Then Riesz's continuous functional calculus says that for each self-adjoint T satisfying $\|T\| \leq 1$, if we let $I = [-1, 1]$, then there is continuous unital $*$ -homomorphism

$$C(I, \mathbb{C}) \rightarrow \mathfrak{L}(V) \quad f \mapsto f(T)$$

sending the function $\text{id}_I : x \mapsto x$ to $\text{id}_I(T) = T$. By saying that the above map is a unital $*$ -homomorphism, we mean that for every $a, b \in \mathbb{C}, f, g \in C(I, \mathbb{C})$ we have

$$\begin{aligned} 1(T) &= \text{id}_V & (af + bg)(T) &= af(T) + bg(T) \\ (fg)(T) &= f(T)g(T) & f^*(T) &= f(T)^* \end{aligned}$$

Recall that $f^*(x) = \overline{f(x)}$.

Riesz's continuous functional calculus, together with his characterization of the dual space of $C(I, \mathbb{C})$ (this is the celebrated **Riesz representation theorem**, one of the deepest results in measure theory), enabled him to give an elegant proof of Hilbert's **spectral theorem** for bounded self-adjoint operators on $l^2(\mathbb{Z}, \mathbb{C})$. Riesz's proof by functional calculus is still the standard method today.

Roughly speaking, spectral theorem can be viewed as the continuous version of the diagonalization theorem for complex self-adjoint matrices: If $T \in \mathbb{C}^{n \times n}$ is self-adjoint, then there exists $U \in \mathbb{C}^{n \times n}$ satisfying $U^*U = 1$ (i.e. U is unitary), such that UTU^* is a diagonal matrix. In the case of $l^2(\mathbb{Z}, \mathbb{C})$, the eigenvalues and the diagonalizability of T should be understood in a continuous way. (We will talk more about this in the future.) The spectral theorem generalizes Hilbert's and Schmidt's work on integral equations and paved the way for von Neumann's establishment of abstract Hilbert spaces and their (unbounded) self-adjoint operators as the mathematical foundation of quantum mechanics.

If you remember, when studying the diagonalization and the Jordan forms of (finite dimensional) matrices, you were already using functional calculus: Take $T \in \mathbb{C}^{n \times n}$. Then one has an obvious unital homomorphism of \mathbb{C} -algebras $\Phi : \mathbb{C}[z] \mapsto \mathbb{C}^{n \times n}, f \mapsto f(T)$. Then the set of eigenvalues of T is

$$E(T) = \{\lambda \in \mathbb{C} : f(z) = 0 \text{ for all } f \in \text{Ker}(\Phi)\}$$

the zero set of the ideal $\text{Ker}(\Phi)$. For each $\lambda \in E(T)$, the subspace of the generalized vectors with eigenvalue λ (i.e., the set of all $v \in \mathbb{C}^n$ such that $(T - \lambda)^k v = 0$ for some $k \in \mathbb{N}$) is the range of some projection operator $f(T)$ where $f \in \mathbb{C}[z]$. Thus, it is no surprising that functional calculus is also used to study the diagonalization of bounded linear operators on function spaces.

Remark 17.44. In analysis, the most important reason for studying the topological properties (e.g. compactness, completeness) of a space is to find the solutions. Thus, if the space is a function space \mathfrak{X} (for example, a subspace of $C([0, 1])$), and if $S : \mathfrak{X} \rightarrow \mathbb{R}$ is a *fixed* functional, one can use the topological properties of \mathfrak{X} to find the elements of \mathfrak{X} minimizing or maximizing the value of S . This pattern is deeply influenced by the calculus of variations and is nonlinear by nature. (See Sec. 2.1.)

Riesz's study of operator norms undoubtedly brought a paradigm shift to modern analysis. After Riesz's work on operator norms, dual spaces, and functional calculus, *linear* functionals and *linear* maps⁹ took the stage of analysis. Since then, people were interested not only in the topological properties of function spaces (e.g. $C([0, 1])$, $L^2([0, 1])$, $l^2(\mathbb{Z})$), but also in the topological properties of the spaces of linear functionals and linear maps defined on these function spaces (e.g. $C([0, 1])^*$, $\mathfrak{L}(L^2([0, 1]))$, $\mathfrak{L}(l^2(\mathbb{Z}))$). Since then, functionals and maps on function spaces were not fixed from beginning to end. Instead, one should find the correct functionals or maps that solve the problems by using the topological properties of the spaces of linear functionals or linear maps. \square

Many modern people will have a hard time understanding how nontrivial the notion of operator norms is, since they feel that it follows naturally from the study of the continuity of linear operators $V \rightarrow V$. But these people are probably unaware that the notion of linear operators on a Banach space is nontrivial, and that it is nontrivial to view an integral operator as an operator on the function space but not (for example) as a quadratic form (2.1b). It is precisely because functional calculus depends on operator norms, and operator norms depend on the perspective of linear operators, that the concept of linear operators has received great attention from people. See Fig. 17.1.

17.8 Contraction theorem

Definition 17.45. Let $f : X \rightarrow Y$ be a map of metric spaces. Suppose that f has Lipschitz constant $L \in [0, 1)$, we say that f is a **contraction**.

Theorem 17.46 (Contraction theorem). Let X be a nonempty complete metric space. Let $T : X \rightarrow X$ be a contraction. Then T has a unique **fixed point**, i.e., there exists a unique $x \in X$ satisfying $T(x) = x$.

In the following proof, we let $L \in [0, 1)$ be a Lipschitz constant of T .

Proof. Uniqueness: Suppose $x, y \in X$ satisfy $T(x) = x$ and $T(y) = y$. Then

$$0 \leq d(x, y) = d(T(x), T(y)) \leq Ld(x, y)$$

⁹Even Hilbert did not take the viewpoint of linear maps in his study of integral equations. Instead, he took the viewpoint of quadratic forms (cf. (2.1b)), which was partly influenced by the calculus of variations. We will say more about this in the second semester.

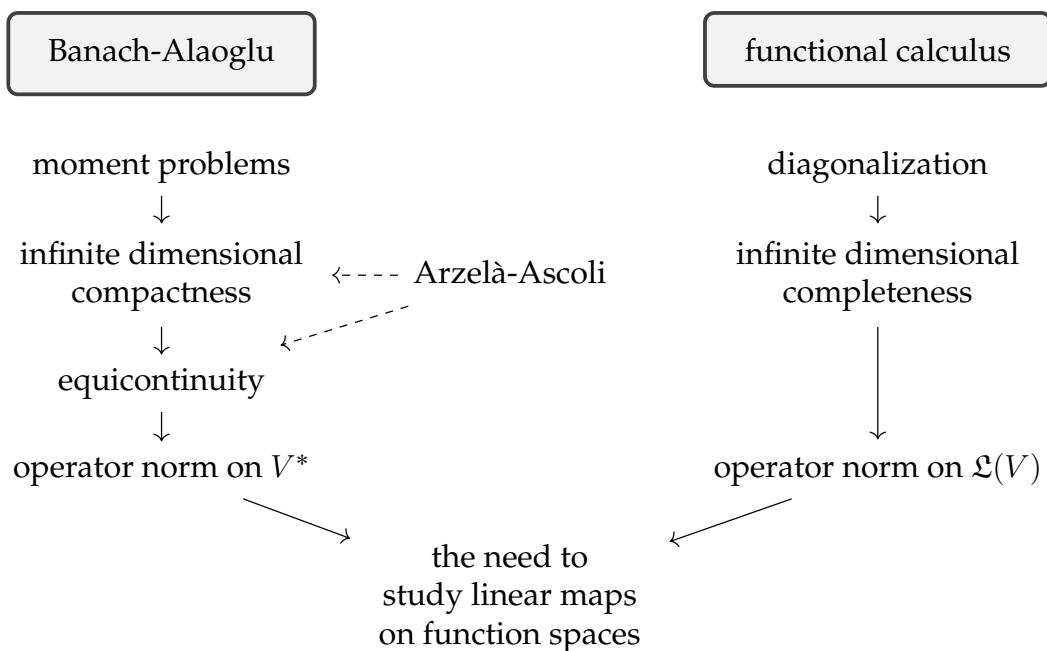


Figure 17.1 The order of motivation in history

showing that $d(x, y)$ must be 0.

Existence: Choose $x_0 \in X$. Define $(x_n)_{n \in \mathbb{N}}$ inductively by $x_{n+1} = T(x_n)$. Then $d(x_{n+1}, x_n) = d(T(x_n), T(x_{n-1})) \leq Ld(x_n, x_{n-1})$. From this, we conclude

$$d(x_{n+1}, x_n) \leq Ld(x_n, x_{n-1}) \leq L^2d(x_{n-1}, x_{n-2}) \leq \cdots \leq L^nd(x_1, x_0)$$

Therefore, for each $k \in \mathbb{Z}_+$ we have

$$\begin{aligned} d(x_{n+k}, x_n) &\leq d(x_{n+k}, x_{n+k-1}) + d(x_{n+k-1}, x_{n+k-2}) + \cdots + d(x_{n+1}, x_n) \\ &\leq (L^{n+k-1} + L^{n+k-2} + \cdots + L^n)d(x_1, x_0) \leq \frac{L^n}{1-L}d(x_1, x_0) \end{aligned}$$

This proves that $(x_n)_{n \in \mathbb{N}}$ is a Cauchy sequence in X . So it converges to some $x \in X$. Since $(T(x_n)) = (x_{n+1})$ also converges to x , by the continuity of T we conclude $T(x) = x$. \square

The contraction theorem is also called the **Banach fixed-point theorem**. In the next chapter, we will use the contraction theorem to study differential equations. In the next semester, we will use the contraction theorem to prove the inverse function theorem for multivariable functions.

17.9 Problems and supplementary material

Let $1 < p, q \leq +\infty$ satisfy $\frac{1}{p} + \frac{1}{q} = 1$. Let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

★ **Problem 17.1.** Let $1 \leq p < +\infty$. Let X be a set. Let \mathcal{A} be a subset of $l^p(X, \mathbb{F})$ equipped with the l^p -norm. Prove that the following are equivalent:

- (1) \mathcal{A} is precompact.
- (2) For each $x \in X$ we have $\sup_{f \in \mathcal{A}} |f(x)| < +\infty$. Moreover, for every $\varepsilon > 0$, there exists a finite subset $K \subset X$ such that for each $f \in \mathcal{A}$ we have $\|f\|_{X \setminus K} < \varepsilon$; in other words,

$$\lim_{K \in \text{fin}(2^X)} \sup_{f \in \mathcal{A}} \sum_{x \in X \setminus K} |f(x)|^p = 0 \quad (17.11)$$

Hint. (1) \Rightarrow (2): Mimic the first proof of Thm. 17.14. (2) \Rightarrow (1): Choose any net (f_α) in \mathcal{A} . First find a subnet (f_μ) converging pointwise to a function $f : X \rightarrow \mathbb{F}$. Then show that $f \in l^p(X, \mathbb{F})$ and $\lim_\mu \|f - f_\mu\|_p = 0$. \square

Pb. 17.1 is the l^p -version of the **Fréchet-Kolmogorov theorem**.

★ **Exercise 17.47.** In Pb. 17.1, assume that \mathcal{A} is precompact. Prove that $E = \bigcup_{f \in \mathcal{A}} \text{Supp}(f) = \bigcup_{f \in \mathcal{A}} \{x \in X : f(x) \neq 0\}$ is a countable set.

Hint. Method 1: Show that \mathcal{A} is separable. Let \mathcal{E} be a countable dense subset of \mathcal{A} . Prove $E = \bigcup_{f \in \mathcal{E}} \text{Supp}(f)$.

Method 2: For each $\varepsilon = 1/n$, write the K in (2) as K_n . Prove $E \subset \bigcup_n K_n$. \square

★ **Problem 17.2.** Let V be a Banach space. Let $\xi \in C(\mathbb{R}, V)$ such that $\|\xi\|_{L^1} = \int_{\mathbb{R}} \|\xi(t)\| dt < +\infty$. Let $\mathfrak{X} = C(\mathbb{R}, \mathbb{R}) \cap l^\infty(\mathbb{R}, \mathbb{R})$, equipped with the l^∞ -norm. Define a linear map

$$\Phi : \mathfrak{X} \rightarrow V \quad f \mapsto \int_{\mathbb{R}} f(t) \xi(t) dt$$

Show that Φ is a bounded linear map. Show that Φ is a **compact operator**, which means that $\Phi(\overline{B}_{\mathfrak{X}}(0, 1))$ is a precompact subset of V .

Hint. By Thm. 17.23, we can view V as a closed linear subspace of $C(X, \mathbb{R})$ where X is a compact Hausdorff space. So ξ can be viewed as a function on $\mathbb{R} \times X$. Use Arzelà-Ascoli to prove that Φ is a compact operator. \square

Problem 17.3. Let V be a separable normed vector space over \mathbb{F} . Let $(v_n)_{n \in \mathbb{Z}_+}$ be a dense sequence in $\overline{B}_V(0, 1)$. (The density is with respect to the norm topology.¹⁰) Use $(v_n)_{n \in \mathbb{Z}_+}$ to construct an explicit metric on $\overline{B}_{V^*}(0, 1)$ inducing its weak-* topology, and construct an explicit countable basis for the weak-* topology on $\overline{B}_{V^*}(0, 1)$.

¹⁰Recall that subsets of separable (equivalently, second countable) metric spaces are separable.

Hint. Check the proof of Thm. 17.24 (or more precisely, Thm. 17.23). This problem is related to Pb. 15.15. \square

Remark 17.48. The metric you are asked to find in Pb. 17.3 can actually be found in many analysis textbooks, although their authors do not tell you how they find it. The point of this problem (together with Pb. 15.15) is to tell you that the correct geometric viewpoint (i.e., embedding into Hilbert cubes) can lead you to the formula of the metric.

Another goal of this problem is to justify the point in Rem. 8.35: For all concrete examples of compact metrizable spaces, you can explicitly construct countable bases for their topologies. Therefore, there is no need to use the indirect proof of the second countability in Thm. 8.34.¹¹ \square

Problem 17.4. Let Y be a metric space. Prove that there is a compact Hausdorff space X and an isometry $\Phi : Y \rightarrow C(X, \mathbb{F})$ following the hint below.

In particular, any metric space can be (isometrically) embedded into a Banach space.¹²

Hint. This problem is similar to Thm. 17.23. Since $C(X, \mathbb{R}) \subset C(X, \mathbb{C})$, it suffices to assume $\mathbb{F} = \mathbb{R}$. In Thm. 17.23, X is constructed to be the set of linear functionals with operator norms ≤ 1 . The assumption on the operator norms ensures the equicontinuity and hence the (pre)compactness of X . Thus, in the current situation, in order to get a compact X , one should consider a pointwise bounded set of functions with a uniform Lipschitz constant (cf. Thm. 17.7 or Exe. 17.9). For example, assume Y is nonempty and fix $a \in Y$, and define

$$X = \{f \in \mathbb{R}^Y : f(a) = 0, \text{ and } f \text{ has Lipschitz constant } 1\} \quad (17.12)$$

equipped with the pointwise convergence topology. \square

Remark 17.49. Similar to the proof of Thm. 17.24, one can show that $X = (17.12)$ is metrizable (equivalently, second countable) iff Y is separable.

Remark 17.50. Pb. 17.4 tells us that any metric space can be embedded into a Banach space. This fact is useful in the same way that the existence of the completions of normed vector spaces is useful, cf. Rem. 10.22. (Interestingly, Pb. 17.4 gives a new proof that every metric space Y has completion, since one can restrict $\Phi : Y \rightarrow V$ to $Y \rightarrow \overline{\Phi(Y)}$.)

For example, assume that X, Y are topological spaces, and Z is a metric space. Equip $C(Y, Z)$ with a uniform convergence metric (cf. Exp. 7.77). By Pb. 17.4, Z

¹¹You can feel how much I hate the proof of Thm. 8.34 :-)

¹²If we simply want to embed Y into a Banach space V , there is a simpler method called **Kuratowski embedding**: Assume Y is nonempty and fix $a \in Y$. Let $V = l^\infty(Y, \mathbb{R})$, and define the embedding sending each $y \in Y$ to the function $p \in Y \mapsto d(y, p) - d(a, p)$.

can be viewed as a metric subspace of a Banach space V . By Thm. 9.3, there is a canonical injection $\Psi : C(X, C(Y, V)) \rightarrow C(X \times Y, V)$ which is bijective when Y is compact. It is easy to see that Ψ restricts to an injective map $C(X, C(Y, Z)) \rightarrow C(X \times Y, Z)$, and that this restriction is surjective when Y is compact. Therefore, Thm. 9.3 can be generalized to the case that the codomain is a metric space, but not necessarily a normed vector space.¹³ Similarly, Thm. 9.12 can be generalized to functions whose codomains are metric spaces, and the Moore-Osgood theorem can be generalized to functions whose codomains are complete¹⁴ metric spaces. \square

Problem 17.5. Let X be a set. By the Banach-Alaoglu theorem and Thm. 17.31, when $1 < p \leq +\infty$, the closed unit ball

$$B = \{f \in l^p(X, \mathbb{F}) : \|f\|_p \leq 1\} \quad (17.13)$$

is compact under the pointwise convergence topology (i.e. the product topology inherited from \mathbb{F}^X). Give a direct proof of this fact for all $1 \leq p \leq +\infty$ (including the case $p = 1$) without using Banach-Alaoglu Thm. 17.21.

Now you may wonder if the pointwise convergence topology on the closed unit ball of l^1 can be realized by a weak-* topology. The answer is yes:

★ **Problem 17.6.** Let X be a set. Let

$$c_0(X, \mathbb{F}) = \{f \in \mathbb{F}^X : \text{for all } \varepsilon > 0 \text{ there exists } A \in \text{fin}(2^X) \text{ such that } \|f\|_{l^\infty(A^c, \mathbb{F})} < \varepsilon\}$$

equipped with the l^∞ -norm. By Prop. 15.46, $c_0(X, \mathbb{F})$ is a Banach space. (You can also check it directly.) Find a natural isomorphism of Banach spaces

$$\Psi : l^1(X, \mathbb{F}) \xrightarrow{\cong} c_0(X, \mathbb{F})^* \quad (17.14)$$

Let (f_α) be a net in $l^1(X, \mathbb{F})$ satisfying $\sup_\alpha \|f_\alpha\|_{l^1} < +\infty$, and let $f \in l^1(X, \mathbb{F})$. Prove that $\Psi(f_\alpha)$ converges weak-* to $\Psi(f)$ iff (f_α) converges pointwise to f as functions $X \rightarrow \mathbb{F}$.

★ **Problem 17.7.** Prove that $l^q(\mathbb{Z}_+, \mathbb{F})$ is separable (where $1 \leq q < +\infty$), and $l^\infty(\mathbb{Z}_+, \mathbb{F})$ is not separable.

Hint. Every subset of a second countable space is second countable and hence Lindelöf. Find an uncountable discrete (and hence non-Lindelöf) subset of $l^\infty(\mathbb{Z}_+, \mathbb{F})$. \square

¹³Of course, we can prove the case of metric spaces for Thm. 9.3 at the very beginning. We didn't do it just to avoid distraction.

¹⁴You need completeness because in the proof you need the fact that Y is closed in V .

★ **Problem 17.8.** By Thm. 12.33, there is a linear isometry

$$\Psi : l^1(\mathbb{Z}_+, \mathbb{F}) \rightarrow l^\infty(\mathbb{Z}_+, \mathbb{F})^* \quad (17.15)$$

such that $\langle \Psi(f), g \rangle = \sum_n f(n)g(n)$. Let $\mathcal{B} = \overline{B}_{l^1(\mathbb{Z}_+, \mathbb{F})}(0, 1)$, the closed unit ball of $l^1(\mathbb{Z}_+, \mathbb{F})$. If Ψ is surjective (and hence an isomorphism), then $\Psi(\mathcal{B})$ is the closed unit ball of $l^\infty(\mathbb{Z}_+, \mathbb{F})^*$, and hence is weak-* compact by Banach-Alaoglu.

Let $f_n = \chi_{\{n\}}$, viewed as an element of \mathcal{B} . Prove that the sequence $(\Psi(f_n))_{n \in \mathbb{Z}_+}$ has no weak-* convergent subnet in $\Psi(\mathcal{B})$.¹⁵ Conclude that the map Ψ is not surjective. \square

17.10 ★ Supplementary material: a discussion of Riesz's treatment of moment problems

Unless otherwise stated, V is a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

17.10.1 Quotient Banach spaces in moment problems

Problem 17.9. Let U be a closed linear subspace of V . Let V/U be its quotient vector space. Prove that V/U has a norm defined by

$$\|v + U\| = \inf_{u \in U} \|v + u\| \quad (17.16)$$

for all $v \in V$. Prove that V/U is complete under this norm. We call V/U the **quotient Banach space** of V by U .

Hint. Use Pb. 4.1 to prove that V/U is complete. \square

Proposition 17.51 (Abstract moment problem, finite version). *Let $\varphi_1, \dots, \varphi_n \in V^*$. Let $c_1, \dots, c_n \in \mathbb{F}$. Suppose that there exists $M \in \mathbb{R}_{\geq 0}$ such that*

$$|a_1 c_1 + \dots + a_n c_n| \leq M \cdot \|a_1 \varphi_1 + \dots + a_n \varphi_n\| \quad (\forall a_1, \dots, a_n \in \mathbb{F}) \quad (17.17)$$

Then for every $\varepsilon > 0$ there exists $v \in V$ satisfying that $\|v\| \leq M + \varepsilon$ and that

$$\langle \varphi_i, v \rangle = c_i \quad (\text{for all } 1 \leq i \leq n) \quad (17.18)$$

The above proposition is credited to Helly.

Problem 17.10. Assume the setting of Prop. 17.51. Define a bounded linear map

$$\Phi : V \rightarrow \mathbb{F}^n \quad v \mapsto (\varphi_1(v), \dots, \varphi_n(v)) \quad (17.19)$$

The following two steps will lead you to prove Prop. 17.51.

¹⁵It is not enough to consider subsequences, since $l^\infty(\mathbb{Z}_+, \mathbb{F})$ is not separable and hence the unit ball of $l^\infty(\mathbb{Z}_+, \mathbb{F})^*$ is not weak-* metrizable, cf. Thm. 17.24.

1. Consider the special case that $\text{Ker}(\Phi) = 0$. In particular, V is a finite dimensional normed vector space, and $\dim V = \dim \text{Span}(\varphi_1, \dots, \varphi_n)$. We have $\dim V^* = \dim V < +\infty$ because all linear maps $V \rightarrow \mathbb{F}$ are bounded. Similarly $\dim V^{**} = \dim V^*$. So the canonical linear isometry

$$V \rightarrow V^{**} \quad v \mapsto \langle \cdot, v \rangle \quad (17.20)$$

(cf. Cor. 16.6) must be bijective. Use this observation to prove that there exists $v \in V$ satisfying $\|v\| \leq M$ and (17.18).

2. Reduce the general case to the special case in part 1 by considering $V/\text{Ker}(\Phi)$ and its bounded linear functionals ψ_1, \dots, ψ_n defined by

$$\langle \psi_i, v + \text{Ker}(\Phi) \rangle = \langle \varphi_i, v \rangle \quad (17.21)$$

(Note that you need to prove $\|\psi_i\| = \|\varphi_i\|$.)

Remark 17.52. Recall from Sec. 17.5 that Riesz wanted to solve the moment problem: Let $I = [a, b]$ be a compact interval in \mathbb{R} . The scalar field is chosen to be \mathbb{C} . Let $g_1, g_2, \dots \in L^q(I) = L^q(I, \mathbb{C})$ (where $1 < q < +\infty$) and $c_1, c_2, \dots \in \mathbb{C}$ satisfying

$$|a_1 c_1 + \dots + a_n c_n| \leq M \cdot \|a_1 g_1 + \dots + a_n g_n\|_{L^q} \quad (\forall n \in \mathbb{Z}_+, a_1, \dots, a_n \in \mathbb{C})$$

The goal is to find $f \in L^p(I)$ (where $p^{-1} + q^{-1} = 1$) satisfying $\int_I f g_j = c_j$ for all $j = 1, 2, \dots$. As mentioned in Rem. 17.34, Riesz's first step in solving this problem is to find $f_n \in L^p(I)$ for each $n \in \mathbb{Z}_+$ satisfying $\|f_n\|_{L^p} \leq M$ and

$$\int_I f_n g_i = c_i \quad (\text{for every } 1 \leq i \leq n) \quad (17.22)$$

The second step is then to find a weak-* convergent subsequence of $(f_n)_{n \in \mathbb{Z}_+}$.

In Sec. 17.5, I didn't explain how Riesz solved step 1. Some of the key ideas can now be explained. (For simplicity, the reader can replace $L^q(I), L^p(I)$ by $l^q(\mathbb{Z}), l^p(\mathbb{Z})$ and replace the integrals by the series. The main idea remains the same.)

Let us slightly weaken the above assumption to $\|f_n\|_{L^p} \leq M + \varepsilon$ where $\varepsilon > 0$ is fixed at the beginning. (Later, I will explain why ε can be chosen to be 0.) Then, in view of the canonical isomorphism $\Psi : L^q(I) \rightarrow L^p(I)^*$, Riesz's first step can be proved by directly applying Prop. 17.51 to the special case that $V = L^p(I)$ and $\varphi_i = \Psi(g_i)$. \square

Remark 17.53. It should be noted that the proof of Prop. 17.51 relies on the fact that $V \rightarrow V^{**}$ is an isometry (cf. Pb. 17.10-1) when V is finite-dimensional. This follows from Hahn-Banach in the general case. As I said in Rem. 17.34, the Hahn-Banach theorem did not exist by the time Riesz was studying the moment problems.

In the case of moment problems, according to Pb. 17.10, one should take V to be $L^p(I)/\text{Ker}(\Phi)$ for some bounded linear $\Phi : L^p(I) \rightarrow \mathbb{C}^n$. In this case, without using Hahn-Banach, one can at least show easily that $V \rightarrow V^{**}$ is bijective. But it is quite hard to give a direct (i.e. function-theoretic) proof that $V \rightarrow V^{**}$ is an isometry. Nevertheless, Riesz circumvented this problem by using a complicated method due to Schmidt (cf. [Die-H, Sec. 6.2 and 5.3]), which was rarely used after the appearance of Hahn-Banach. In some sense, one can say that Riesz proved a weak version of Hahn-Banach theorem for the finite-dimensional Banach space $L^p(I)/\text{Ker}(\Phi)$. Anyway, the infinite-dimensional Hahn-Banach theorem is not needed in Riesz's method. (So Hahn-Banach is nontrivial enough in the finite-dimensional case.) \square

Remark 17.54. The notion of quotient Banach spaces introduced in this section is also implicit in Riesz's work. Indeed, Riesz wanted to find $f_n \in L^p(I)$ satisfying (17.22) for small enough $\|f_n\|_{L^p}$. This amounts to the fact that in (17.16), the value of $\|v + U\|$ can be estimated by finding $u \in U$ such that $\|v + u\|$ is small enough.

In fact, Riesz was able to find f_n satisfying (17.22) and minimizing $\|f_n\|$; moreover, for such f_n , one has $\|f_n\| \leq M$ (but not just $\|f_n\| \leq M + \varepsilon$). This follows from Pb. 17.11, applied to $V = L^q(I)$ and $E = \{g_1, \dots, g_n\}$. \square

Problem 17.11. Let E be a subset of V . Let

$$E^\perp = \{\varphi \in V^* : \varphi|_E = 0\} \quad (17.23)$$

which is clearly a weak-* closed linear subspace of V^* . Let $\varphi \in V^*$. Prove that there exists $\psi \in E^\perp$ such that $\|\varphi + \psi\|$ equals $\|\varphi + E^\perp\| \equiv \inf_{\eta \in E^\perp} \|\varphi + \eta\|$.

It is in fact true that any weak-* closed linear subspace of V^* is of the form E^\perp . To prove it one needs a more general version of the Hahn-Banach theorem. We will not discuss it in our notes.

Hint. Choose a sequence (ψ_n) in V^* such that $\lim_n \|\varphi + \psi_n\| = \|\varphi + E^\perp\|$. Since this sequence is clearly norm-bounded, by Banach-Alaoglu, it has a subnet (ψ_α) converging weak-* to some $\psi \in V^*$. Clearly $\psi \in E^\perp$. For each $\varepsilon > 0$, choose $v \in V$ with $\|v\| = 1$ such that $|\langle \varphi + \psi, v \rangle| \geq \|\varphi + \psi\| - \varepsilon$. Show that $|\langle \varphi + \psi, v \rangle| \leq \lim_\alpha \|\varphi + \psi_\alpha\|$. Conclude that $\|\varphi + \psi\| - \varepsilon \leq \|\varphi + E^\perp\|$ for all $\varepsilon > 0$. \square

17.10.2 Some consequences

The goal of this subsection is to give some quick consequences of the results and the methods introduced in the previous subsections. These important properties are mainly about compactness, and are not difficult to find in many books on functional analysis. The reason I present these results is to show that they can (or should?) be understood in the light of Riesz's treatment of moment problems. (Unfortunately, this point is often not emphasized in many textbooks.)

Theorem 17.55 (Goldstine's theorem). Let $\Gamma : V \rightarrow V^{**}$ be the linear isometry (cf. Cor. 16.6) sending v to the bounded linear functional $\varphi \in V^* \mapsto \langle \varphi, v \rangle$. Then $\Gamma(\overline{B}_V(0, 1))$ is weak-* dense in $\overline{B}_{V^{**}}(0, 1)$.

Consequently, since $\overline{B}_V(0, 1)$ is a compact Hausdorff space by Banach-Alaoglu, we conclude that Γ is bijective iff $\Gamma(\overline{B}_V(0, 1))$ is weak-* compact.¹⁶ A Banach space satisfying these two equivalent conditions is called **reflexive**. For example, if $1 < p < +\infty$, then Thm. 17.30 shows that $l^p(X, \mathbb{F})$ is reflexive. It is also true that $L^p([a, b], \mathbb{F})$ is reflexive.

Proof. Since $\bigcup_{0 < r < 1} \overline{B}_{V^{**}}(0, r)$ is norm dense and hence weak-* dense in $\overline{B}_{V^{**}}(0, 1)$, it suffices to prove that for each $0 < r < 1$ and $\mathbf{v} \in \overline{B}_{V^{**}}(0, r)$, \mathbf{v} can be approximated weak-* by elements of $\Gamma(\overline{B}_V(0, 1))$.

We shall prove that for each $E \in \text{fin}(2^{V^*})$ there exists $v_E \in \overline{B}_V(0, 1)$ such that $\langle \mathbf{v}, \varphi \rangle = \langle v_E, \varphi \rangle$ for all $\varphi \in E$. Then the net $(\Gamma(v_E))_{E \in \text{fin}(2^{V^*})}$ converges weak-* in $\overline{B}_{V^{**}}(0, 1)$ to \mathbf{v} , finishing the proof. To find v_E , we write $E = \{\varphi_1, \dots, \varphi_n\}$. Let $c_i = \langle \mathbf{v}, \varphi_i \rangle$. Since $\|\mathbf{v}\| \leq r$, for each $a_1, \dots, a_n \in \mathbb{F}$ we have

$$|a_1 c_1 + \dots + a_n c_n| = |\langle \mathbf{v}, a_1 \varphi_1 + \dots + a_n \varphi_n \rangle| \leq r \cdot \|a_1 \varphi_1 + \dots + a_n \varphi_n\|$$

Therefore, by Prop. 17.51, there exists $v_E \in \overline{B}_V(0, 1)$ such that $\langle v_E, \varphi_i \rangle = c_i$ for all $1 \leq i \leq n$. This finishes the construction of v_E . \square

Problem 17.12. Let M be a linear subspace of V . Suppose that $e \in V$ is not in $\overline{M} = \text{Cl}_V(M)$. Prove that there exists $\psi \in V^*$ such that $\psi|_M = 0$ and $\psi(e) \neq 0$.

This problem is a special case of the **Hahn-Banach separation theorem**. As a consequence of this exercise, we know that M is dense in V iff every $\psi \in V^*$ vanishing on M is zero.

Hint. Use Hahn-Banach Cor. 16.6 to prove the special case that $M = 0$. Then reduce the general case to the special case by considering V/\overline{M} . \square

Problem 17.13. Let V be a reflexive Banach space. Let U be a closed linear subspace of V . Let $v \in V$. Show that there exists $u \in U$ such that $\|v + U\| = \|v + u\|$.

Hint. The canonical linear isometry $\Gamma : V \rightarrow V^{**}$ is an isomorphism of Banach spaces. Use the Hahn-Banach separation theorem (Pb. 17.12) to show that $\Gamma(U) = W^\perp$ where $W = \{\psi \in V^* : \psi|_U = 0\}$. Then apply Pb. 17.11. \square

Theorem 17.56 (Riesz's theorem). Let V be a Banach space. Then the closed unit ball $\overline{B}_V(0, 1)$ is compact under the norm topology iff $\dim_{\mathbb{F}} V < +\infty$.

¹⁶The **weak topology** on V is defined to be the pullback of the weak-* topology of V^{**} by $V \rightarrow V^{**}$. So a net (v_α) in V converges weakly to $v \in V$ iff $\lim_\alpha \langle v_\alpha, \varphi \rangle = \langle v, \varphi \rangle$ for all $\varphi \in V^*$. Thus, the conclusion is that $\Gamma : V \rightarrow V^{**}$ is bijective iff $\overline{B}_V(0, 1)$ is weakly compact.

Proof. If $\dim_{\mathbb{F}} V < +\infty$, then the norm on V is equivalent to the Euclidean norm by Pb. 10.3. So $\overline{B}_V(0, 1)$ is compact by Bolzano-Weierstrass.

Now we assume $\dim_{\mathbb{F}} V$ is not finite. We fix any $0 < \varepsilon < 1$. (For example, choose $\varepsilon = 1/2$.) Notice that for each closed linear subspace $U \subsetneq V$, there clearly exists $v \in U$ such that $\|v + U\| = 1 - \varepsilon$. By replacing v by $v + u$ for some $u \in U$, we assume moreover that $\|v\| \leq 1$.

Now we construct an infinite linearly-independent sequence $(v_n)_{n \in \mathbb{Z}_+}$ in $\overline{B}_V(0, 1)$ as follows. v_1 is arbitrary. Suppose v_1, \dots, v_n have been constructed. Let $U_n = \text{Span}_{\mathbb{F}}(v_1, \dots, v_n)$. Then U_n is a closed linear subspace of V since U_n is complete. (Any finite dimensional normed vector space is equivalent as a metric space to \mathbb{F}^n by Pb. 10.3, and hence is complete.) Then U_n is a closed proper linear subspace of V since $\dim_{\mathbb{F}} V < +\infty$. Therefore, by the previous paragraph, there exists $v_{n+1} \in \overline{B}_V(0, 1)$ such that $\|v_{n+1} + U_n\| = 1 - \varepsilon$. So $\|v_{n+1} - v_j\| \geq 1 - \varepsilon$ for all $j \leq n$.

The sequence constructed above satisfies that $\|v_m - v_n\| \geq 1 - \varepsilon$ for all $m \neq n$. So $(v_n)_{n \in \mathbb{Z}_+}$ has no Cauchy subsequence, and hence no norm-convergent subsequence. Therefore $\overline{B}_V(0, 1)$ is not sequentially compact under the norm topology, and hence not compact. \square

Remark 17.57. If V is a reflexive infinite dimensional Banach space (i.e. if V is $L^p([0, 1], \mathbb{F})$ or $l^p(X, \mathbb{F})$ where $1 < p < +\infty$), the above proof that $\overline{B}_V(0, 1)$ is not compact can be simplified by choosing $\varepsilon = 0$. This is due to Pb. 17.13.

18 Application to differential equations

18.1 Picard-Lindelöf theorem

We fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let I be an interval in \mathbb{R} containing at least two points.

Definition 18.1. Let T be a set. Let X, Y be metric spaces. We say that a function $f : T \times X \rightarrow Y$ is **Lipschitz continuous on X** if there exists $L \in \mathbb{R}_{\geq 0}$ (called the **Lipschitz constant**) such that for every $t \in T$ and $x_1, x_2 \in X$ we have

$$d(f(t, x_1), f(t, x_2)) \leq Ld(x_1, x_2)$$

Theorem 18.2. Let $E \subset V$. Let $\varphi \in C(I \times E, V)$ be Lipschitz continuous on E . Fix $t_0 \in I, \xi \in E$. Then there exists at most one differentiable $f : I \rightarrow E$ satisfying

$$f'(t) = \varphi(t, f(t)) \quad f(t_0) = \xi \quad (18.1)$$

for all $t \in I$.

Proof. This theorem generalizes Lem. 12.22. In fact, we will prove this theorem in a similar way as we proved Lem. 12.22. Let $f, g : I \rightarrow E$ be differentiable and assume that they both satisfy (18.1). Then $\Omega = \{t \in I : f(t) = g(t)\}$ is a closed subset of I since f, g are continuous. Ω is nonempty since $t_0 \in \Omega$. Since I is connected, to prove that $\Omega = I$, it suffices to prove that Ω is open.

Choose any $x \in \Omega$. We want to prove that $x \in \text{Int}_I(\Omega)$. Let us prove that if $x < \sup I$ then there exists $\delta > 0$ such that $[x, x + \delta) \subset \Omega$. Then a similar argument shows that if $x > \inf I$ then there exists $\delta > 0$ such that $(x - \delta, x] \subset \Omega$. This proves $x \in \text{Int}_I(\Omega)$ whether x is an endpoint of I or not.

We first choose $\delta > 0$ such that $[x, x + \delta] \subset I$. Since f, g are continuous, both $\varphi(t, f(t))$ and $\varphi(t, g(t))$ are continuous in t . Therefore, by the fundamental theorem of calculus, we have

$$f(t) = f(x) + \int_x^t \varphi(s, f(s)) ds \quad g(t) = g(x) + \int_x^t \varphi(s, g(s)) ds$$

Since $f(x) = g(x)$, we have

$$\|f(t) - g(t)\| \leq \int_x^t \|\varphi(s, f(s)) - \varphi(s, g(s))\| ds \leq L \int_x^t \|f(s) - g(s)\| ds$$

where $L \in \mathbb{R}_{\geq 0}$ is a Lipschitz constant of φ on E . Let $A = \sup_{t \in [x, x + \delta]} \|f(t) - g(t)\|$.

Then the above inequality implies $\|f(t) - g(t)\| \leq LA\delta$ for all $t \in [x, x + \delta]$, and hence $A \leq LA\delta$. Now we shrink δ so that $L\delta < 1$. Then we must have $A = 0$. So $f = g$ on $[x, x + \delta]$, and hence $[x, x + \delta) \subset \Omega$. \square

Example 18.3. The function $\varphi(x) = x^{\frac{1}{3}}$ is not Lipschitz continuous on any compact interval containing 0. For every $c \geq 0$, the function

$$f(x) = \begin{cases} \left(\frac{2}{3}(x-c)\right)^{\frac{3}{2}} & \text{if } x \geq c \\ 0 & \text{if } x < c \end{cases}$$

is differentiable on \mathbb{R} and satisfies the differential equation

$$f'(t) = (f(t))^{\frac{1}{3}} \quad f(0) = 0$$

Therefore, Thm. 18.2 does not hold without assume the Lipschitz continuity.

Theorem 18.4 (Picard-Lindelöf theorem). Let $\xi \in V$ and $0 < R < +\infty$. Let $I = [a, b]$ where $-\infty < a < b < +\infty$. Assume that $\varphi \in C(I \times \overline{B}_V(\xi, R), V)$ satisfies the following conditions:

- (1) φ is Lipschitz continuous on $\overline{B}_V(\xi, R)$.
- (2) $M = \|\varphi\|_{l^\infty}$ is $< +\infty$.

Assume that

$$|I| \leq \frac{R}{M} \tag{18.2}$$

where $|I| = b - a$. Then there exists a unique differentiable function $f : I \rightarrow \overline{B}_V(\xi, R)$ satisfying the differential equation

$$f'(t) = \varphi(t, f(t)) \quad f(a) = \xi \tag{18.3}$$

for all $t \in I$. The same conclusion holds if $f(a) = \xi$ is replaced by $f(b) = \xi$.

Note that the assumption $M < +\infty$ is automatic when $V = \mathbb{F}^N$, since in that case $I \times \overline{B}_V(\xi, R)$ is compact.

Proof. We only prove the existence, since the uniqueness follows from Thm 18.2. We treat the case $f(a) = \xi$. The other case is similar. Also, by translating f , it suffices to assume $a = 0$. So we let $I = [0, b]$. Then $bM \leq R$. Let L be the Lipschitz constant of φ on $\overline{B}_V(\xi, R)$. Note that if we can find $f \in C(I, \overline{B}_V(\xi, R))$ satisfying the integral equation

$$f(t) = \xi + \int_0^t \varphi(s, f(s)) ds \tag{18.4}$$

for all $t \in I$, then f clearly satisfies (18.3).

Step 1. We first consider the special case that $bL < 1$. Define a map

$$T : C(I, \overline{B}_V(\xi, R)) \rightarrow C(I, V)$$

$$(Tf)(t) = \xi + \int_0^t \varphi(s, f(s)) ds$$

Then T has range inside $X = C(I, \overline{B}_V(\xi, R))$ since for each $f \in X$ and $t \in I = [0, b]$ we have

$$\|(Tf)(t) - \xi\| \leq \int_0^t \|\varphi(s, f(s))\| ds \leq bM \leq R \quad (18.5)$$

by (18.2). Therefore, T can be viewed as a map $X \rightarrow X$.

Any fixed point of T satisfies (18.4). Therefore, by the contraction Thm. 17.46, it suffices to prove that T is a contraction. Here, the metric on X is defined by the l^∞ -norm on $C(I, V)$. Then for each $f, g \in X$. We compute that for each $t \in [0, b]$,

$$\begin{aligned} \|(Tf)(t) - (Tg)(t)\| &= \left\| \int_0^t \varphi(s, f(s)) ds - \int_0^t \varphi(s, g(s)) ds \right\| \\ &\leq \int_0^t \|\varphi(s, f(s)) - \varphi(s, g(s))\| ds \leq L \int_0^t \|f(s) - g(s)\| ds \leq bL \|f - g\|_\infty \end{aligned}$$

Applying $\sup_{t \in [0, b]}$ to the LHS, we get $\|Tf - Tg\|_\infty \leq bL \|f - g\|_\infty$. Since $bL < 1$, T is a contraction.

Step 2. We consider the general case. Choose $N \in \mathbb{Z}_+$ such that $bL/N < 1$. Let us prove by induction that for each $n = 0, 1, \dots, N$ there exists

$$f_n \in C([0, nb/N], \overline{B}_V(\xi, nR/N))$$

satisfying (18.4) for all $t \in [0, nb/N]$. Then f_N gives the desired function satisfying (18.4) for all $t \in I = [0, b]$.

The case $n = 0$ is obvious. Assume that case $n - 1$ has been proved where $1 \leq n \leq N$. Let $\xi_{n-1} = f_{n-1}((n-1)b/N)$, which is inside $\overline{B}_V(\xi, (n-1)R/N)$. Now we apply step 1, but replace the I in step 1 by $I_n = [(n-1)b/N, nb/N]$ and replace the $\overline{B}_V(\xi, R)$ by $\overline{B}_V(\xi_{n-1}, R/N)$. Note that by triangle inequality we have

$$\overline{B}_V(\xi_{n-1}, R/N) \subset \overline{B}_V(\xi, nR/N)$$

Note also that assumption (18.2) becomes $b/N \leq R/NM$, which is still satisfied. Thus, according to step 1, there exists $g_n \in C(I_n, \overline{B}_V(\xi_{n-1}, R/N))$ satisfying

$$g_n(t) = \xi_{n-1} + \int_{(n-1)b/N}^t \varphi(s, g(s)) ds$$

for all $t \in I_n$. Then (the graph of) f_n is defined to be the union of (the graphs of) f_{n-1} and g_n . \square

Thm. 18.4 still holds if we assume $R = +\infty$ and $I = \mathbb{R}$:

Corollary 18.5. *Let $\xi \in V$. Assume that $\varphi \in C(\mathbb{R} \times V, V)$ satisfies the following conditions:*

- (1) φ is Lipschitz continuous on V .
- (2) $M = \|\varphi\|_{l^\infty}$ is $< +\infty$.

Choose any $t_0 \in \mathbb{R}$. Then there exists a unique differentiable $f : \mathbb{R} \rightarrow V$ satisfying

$$f'(t) = \varphi(t, f(t)) \quad f(t_0) = \xi \quad (18.6)$$

for all $t \in \mathbb{R}$.

Proof. By Thm. 18.4, for each $a > 0$ there exists a unique differentiable $f : [t_0 - a, t_0 + a] \rightarrow V$ satisfying (18.6). The union of the graphs of these f_a (for all $a > 0$) gives the graph of the desired function. \square

18.2 Peano's existence theorem

Theorem 18.6. *Let $\xi \in \mathbb{R}^N$. Let $\varphi \in C(\mathbb{R} \times \mathbb{R}^N, \mathbb{R}^N)$ satisfy $M := \|\varphi\|_\infty < +\infty$. Let $t_0 \in \mathbb{R}$. Then there exists a differentiable $f : \mathbb{R} \rightarrow \mathbb{R}^N$ satisfying*

$$f'(t) = \varphi(t, f(t)) \quad f(t_0) = \xi \quad (18.7)$$

for all $t \in \mathbb{R}$.

Proof. Assume WLOG that $t_0 = 0$. It suffices to find $f \in C([0, 1], \mathbb{R}^N)$ satisfying

$$f(t) = \xi + \int_0^t \varphi(s, f(s)) ds \quad (18.8)$$

on $[0, 1]$. Then f is differentiable and satisfies (18.7). Then we can similarly find $f_1 : [1, 2] \rightarrow \mathbb{R}^N$ satisfying $f'_1(t) = \varphi(t, f_1(t))$ and $f_1(1) = f(1)$. Namely, f can be extended to a function $[0, 2] \rightarrow \mathbb{R}^N$ satisfying (18.7). Repeating this argument, we get $f : [0, +\infty) \rightarrow \mathbb{R}^N$ satisfying (18.7), and similarly $f : \mathbb{R} \rightarrow \mathbb{R}^N$ satisfying (18.7).

Step 1. Let $X = \overline{B}_{\mathbb{R}^N}(\xi, M)$. Since $I \times X$ is compact Hausdorff, by Stone-Weierstrass Thm. 15.9, we have a sequence of multivariable polynomials $(\varphi_n)_{n \in \mathbb{Z}_+}$ (where $\varphi_n \in \mathbb{R}^N[t, x_1, \dots, x_N]$) converging uniformly on $[0, 1] \times X$ to φ . Since $M = \|\varphi\|_\infty$, we have $\lim_n \|\varphi_n\|_{l^\infty(I \times X, \mathbb{R}^N)} = M$. Therefore, by scaling each φ_n , we assume that $\|\varphi_n\|_{l^\infty(I \times X, \mathbb{R}^N)} \leq M$. Since polynomials are clearly Lipschitz continuous, by Picard-Lindelöf Thm. 18.4, for each n there exists a differentiable $f_n : [0, 1] \rightarrow X$ satisfying $f'_n(t) = \varphi_n(t, f_n(t))$ and $f_n(0) = \xi$. Equivalently, $f_n \in C([0, 1], X)$ and

$$f_n(t) = \xi + \int_0^t \varphi_n(s, f_n(s)) ds \quad (18.9)$$

for all $t \in [0, 1]$.

Step 2. Recall that $\|\varphi_n\| \leq M$. For each $0 \leq t_1 \leq t_2 \leq 1$, by (18.9) we have

$$\|f_n(t_2) - f_n(t_1)\| \leq \int_{t_1}^{t_2} \|\varphi_n(s, f_n(s))\| ds \leq M(t_2 - t_1)$$

Therefore $(f_n)_{n \in \mathbb{Z}_+}$ is an equicontinuous sequence in $C([0, 1], \mathbb{R}^N)$ and is uniformly bounded because $f_n([0, 1]) \subset X$. By Arzelà-Ascoli Thm. 17.15, $\{f_n : n \in \mathbb{Z}_+\}$ is a precompact subset of $C([0, 1], \mathbb{R}^N)$. Thus, by Prop. 17.2, (f_n) has a uniformly convergent subsequence. By replacing (f_n) with this subsequence, we assume WLOG that (f_n) converges uniformly to some $f \in C([0, 1], \mathbb{R}^N)$. Since $f_n \in C([0, 1], X)$, we have $f \in C([0, 1], X)$.

To prove (18.8), in view of (18.9), it suffices to prove for each $t \in [0, 1]$ that

$$\lim_{n \rightarrow \infty} \int_0^t \varphi_n(s, f_n(s)) ds = \int_0^t \varphi(s, f(s)) ds$$

By Cor. 13.21, it suffices to prove $\lim_n \varphi_n(\cdot, f_n(\cdot)) = \varphi(\cdot, f(\cdot))$ in $C([0, 1], \mathbb{R}^N)$ under the l^∞ -norm. Note that

$$\|\varphi(\cdot, f(\cdot)) - \varphi_n(\cdot, f_n(\cdot))\| \leq \|\varphi(\cdot, f(\cdot)) - \varphi(\cdot, f_n(\cdot))\| + \|\varphi(\cdot, f_n(\cdot)) - \varphi_n(\cdot, f_n(\cdot))\|$$

The first term on the RHS converges uniformly to 0 since $f_n \rightrightarrows f$ and since φ is uniformly continuous (Thm. 10.7). The second term converges uniformly to 0 since $\varphi_n \rightrightarrows \varphi$ on $[0, 1] \times X$. So the LHS converges uniformly to 0. \square

Thm. 18.6 is parallel to Cor. 18.5 since φ is defined on the whole space $\mathbb{R} \times \mathbb{R}^N$. However, in applications it is common that φ is only defined on a subset of $\mathbb{R} \times \mathbb{R}^N$. Thus, we want to prove an existence theorem similar to Thm. 18.4 without assuming the Lipschitz continuity, and hence without concluding the uniqueness. We shall state this result for a finite dimensional real Banach space V . This means that we consider $V = \mathbb{R}^N$, but not necessarily equipped with the Euclidean norm. Since all norms on \mathbb{R}^N are equivalent (cf. Pb. 10.3), we conclude that the closed balls under any norm of \mathbb{R}^N is compact (since they are closed subsets of standard closed balls of \mathbb{R}^N). In practice, it is useful to consider non-Euclidean norms of \mathbb{R}^N . For example, under the l^∞ -norm on $\mathbb{R}^N = l^\infty(\{1, \dots, N\}, \mathbb{R})$, the closed balls are actually the cubes.

Theorem 18.7 (Peano's existence theorem). *Let V be a finite-dimensional real Banach space. Let $\xi \in V$ and $0 < R < +\infty$. Let $I = [a, b]$ where $-\infty < a < b < +\infty$. Let $\varphi \in C(I \times \overline{B}_V(\xi, R), V)$. Assume*

$$|I| \leq \frac{R}{M} \tag{18.10}$$

where $|I| = b - a$ and $M = \|\varphi\|_\infty$. Then there exists a differentiable function $f : I \rightarrow \overline{B}_V(\xi, R)$ satisfying the differential equation

$$f'(t) = \varphi(t, f(t)) \quad f(a) = \xi \quad (18.11)$$

for all $t \in I$. The same conclusion holds if $f(a) = \xi$ is replaced by $f(b) = \xi$.

Proof. Since $\mathbb{R} \times V \simeq \mathbb{R}^{N+1}$ is LCH and $I \times \overline{B}_V(\xi, R)$ is compact, by Tietze extension Thm. 15.22, φ can be extended to an element in $C_c(I \times V, V)$ still satisfying $\|\varphi\|_\infty = M$. Therefore, by Thm. 18.6, there exists a differentiable $\xi : \mathbb{R} \rightarrow V$ satisfying (18.11). It remains to check that $f(I) \subset \overline{B}_V(\xi, R)$: For each $t \in I = [a, b]$, since $f(t) = \xi + \int_a^t \varphi(s, f(s))ds$, we have

$$\|f(t) - \xi\| \leq \int_a^t \|\varphi(s, f(s))\|ds \leq (t - a)M \leq |I| \cdot M \leq R$$

and hence $f(t) \in \overline{B}_V(\xi, R)$. □

19 Differential calculus on \mathbb{R}^N

In this chapter, we fix a Banach space V over \mathbb{R} . However, we will be mainly interested in the case that V is finite dimensional.

19.1 Differentiability and C^1

A motivating question of this short chapter is the following: Suppose that f is a function on an open subset $\Omega \subset \mathbb{R}^N$, and $\gamma : (a, b) \rightarrow \Omega$ is differentiable. How to calculate $(f \circ \gamma)'$? The key to the answer of this question is the following definition:

Definition 19.1. Let $\Omega \subset \mathbb{R}^N$ be open. Let $p \in \Omega$. Let $f : \Omega \rightarrow V$. Assume that there is an \mathbb{R} -linear map $A : \mathbb{R}^N \rightarrow V$ such that for all $v \in \mathbb{R}^N$ we have

$$f(p + v) = f(p) + Av + o(\|v\|)$$

(recall Def. 12.13 for the meaning of $o(\|v\|)$). Namely,

$$\lim_{v \rightarrow 0} \frac{\|f(p + v) - f(p) - Av\|}{\|v\|} = 0 \quad (19.1)$$

Then we say that f is **differentiable at p** . We write

$$A = df|_p = df(p) : \mathbb{R}^N \rightarrow V$$

and call A the **differential** of f at p . If f is differentiable at every point of Ω , we simply say that f is **differentiable on Ω** .

Remark 19.2. Every linear map $A : \mathbb{R}^N \rightarrow V$ is bounded since, if $v = a_1 e_1 + \cdots + a_N e_N$ where e_1, \dots, e_N are the standard basis of \mathbb{R}^N , then

$$\|Av\| \leq \sum_i |a_i| \cdot \|Ae_i\| \leq \|v\| \left(\sum_i \|Ae_i\|^2 \right)^{\frac{1}{2}}$$

by Minkowski's inequality.

Remark 19.3. If f is differentiable at p , then f is continuous at p since, by the continuity of A , we have $\lim_{v \rightarrow 0} (Av + o(\|v\|)) = 0$.

Whenever f is differentiable at p , its differential can be computed explicitly:

Proposition 19.4. Let $\Omega \subset \mathbb{R}^N$ be open. Let $f : \Omega \rightarrow V$ be differentiable at $p \in \Omega$. Then $\partial_1 f, \dots, \partial_N f$ exist at p . Define the **Jacobian (matrix)**

$$\text{Jac}f|_p = (\partial_1 f(p), \dots, \partial_N f(p)) \quad (19.2)$$

viewed as an $1 \times N$ matrix with entries in V . (When $V = \mathbb{R}^M$, we view $\text{Jac}f|_p$ as an $M \times N$ real matrix.) Then for each $v = (a_1, \dots, a_N)^t \in \mathbb{R}^N$ (viewed as an $N \times 1$ matrix) we have

$$df|_p \cdot v = \text{Jac}f|_p \cdot v = \sum_{i=1}^N a_i \partial_i f(p) \quad (19.3)$$

Note that when $V = \mathbb{R}^M$ and $f = (f^1, \dots, f^N)^t$, (19.3) reads

$$df|_p \cdot v = \begin{pmatrix} \partial_1 f^1 & \cdots & \partial_N f^1 \\ \vdots & & \vdots \\ \partial_1 f^M & \cdots & \partial_N f^M \end{pmatrix}_p \cdot \begin{pmatrix} a_1 \\ \vdots \\ a_N \end{pmatrix} \quad (19.4)$$

Proof. Let $e_1, \dots, e_N \in \mathbb{R}^N$ be the standard basis of \mathbb{R}^N . So $v = a_1 e_1 + \cdots + a_N e_N$. Let $A = df|_p$. By (19.1), we have

$$\lim_{t \rightarrow 0} \left\| \frac{f(p + te_i) - f(p)}{t} - Ae_i \right\| = \lim_{t \rightarrow 0} \frac{\|f(p + te_i) - f(p) - tAe_i\|}{\|te_i\|} = 0$$

which shows that $\partial_i f(p) = Ae_i$. Therefore

$$Av = \sum_i a_i Ae_i = \sum_i a_i \partial_i f(p)$$

□

Corollary 19.5. f has at most one differential at a point p .

Proof. Immediate from (19.3). □

Example 19.6. When $N = 1$, the above definition of differentiability in Def. 19.1 agrees with the one in Sec. 11.1. Moreover, we clearly have $\text{Jac}f|_p = f'(p)$.

Theorem 19.7 (Chain rule). Let $\Gamma \subset \mathbb{R}^M$ and $\Omega \subset \mathbb{R}^N$ be open. Let $g : \Gamma \rightarrow \Omega$ be differentiable at $p \in \Gamma$. Let $f : \Omega \rightarrow V$ be differentiable at $g(p)$. Then $f \circ g : \Gamma \rightarrow V$ is differentiable at p , and

$$d(f \circ g)|_p = df|_{g(p)} \cdot dg|_p \quad (19.5)$$

Equivalently, we have

$$\text{Jac}(f \circ g)|_p = \text{Jac}f|_{g(p)} \cdot \text{Jac}g|_p \quad (19.6)$$

Note that when $V = \mathbb{R}^L$, (19.6) is of type $L \times M = (L \times N)(N \times M)$, and reads

$$\begin{pmatrix} \partial_1(f \circ g)^1 & \cdots & \partial_M(f \circ g)^1 \\ \vdots & & \vdots \\ \partial_1(f \circ g)^L & \cdots & \partial_M(f \circ g)^L \end{pmatrix}_p = \begin{pmatrix} \partial_1 f^1 & \cdots & \partial_N f^1 \\ \vdots & & \vdots \\ \partial_1 f^L & \cdots & \partial_N f^L \end{pmatrix}_{g(p)} \cdot \begin{pmatrix} \partial_1 g^1 & \cdots & \partial_M g^1 \\ \vdots & & \vdots \\ \partial_1 g^N & \cdots & \partial_M g^N \end{pmatrix}_p \quad (19.7)$$

Proof. We write

$$g(p + v) = g(p) + Bv + \beta(v) \quad f(g(p) + w) = f \circ g(p) + Aw + \alpha(w)$$

where $A : \mathbb{R}^N \rightarrow V$ and $B : \mathbb{R}^M \rightarrow \mathbb{R}^N$ are linear, and

$$\lim_{v \rightarrow 0} \beta(v)/\|v\| = \lim_{w \rightarrow 0} \alpha(w)/\|w\| = 0 \quad (19.8)$$

Then

$$\begin{aligned} f \circ g(p + v) &= f(g(p) + Bv + \beta(v)) = f \circ g(p) + A(Bv + \beta(v)) + \alpha(Bv + \beta(v)) \\ &= f \circ g(p) + ABv + A\beta(v) + \alpha(g(p + v) - g(p)) \end{aligned}$$

Note that A, B are bounded by Rem. 19.2. So $\|A\beta(v)\| \leq \|A\| \cdot \|\beta(v)\|$, and hence $\lim_{v \rightarrow 0} \|A\beta(v)\|/\|v\| = 0$. To finish the proof, it remains to prove

$$\lim_{v \rightarrow 0} \|\alpha(g(p + v) - g(p))\|/\|v\| = 0$$

Since g is continuous at p , there is a neighborhood Δ of $0 \in \mathbb{R}^M$ such that $g(p + v) - g(p)$ is defined and is in the domain of α (which is $\{q - g(p) : q \in \Omega\}$) for every $v \in \Delta$. Define $\gamma : \Delta \rightarrow V$ to be

$$\gamma(v) = \begin{cases} \frac{\alpha(g(p + v) - g(p))}{\|g(p + v) - g(p)\|} & \text{if } g(p + v) - g(p) \neq 0 \\ 0 & \text{otherwise} \end{cases}$$

Then γ is continuous at $v = 0$ and $\gamma(0) = 0$ by (19.8). (This part is similar to the construction (11.5).) Thus

$$\begin{aligned} \frac{\|\alpha(g(p + v) - g(p))\|}{\|v\|} &= \|\gamma(v)\| \cdot \frac{\|g(p + v) - g(p)\|}{\|v\|} \\ &= \|\gamma(v)\| \cdot \frac{\|Bv + \beta(v)\|}{\|v\|} \leq \|\gamma(v)\| \cdot \|B\| + \|\gamma(v)\| \cdot \frac{\|\beta(v)\|}{\|v\|} \end{aligned}$$

where the RHS converges to 0 as $v \rightarrow 0$. □

Corollary 19.8 (Chain rule). *Let I be an interval. Let $\Omega \subset \mathbb{R}^N$ be open. Let $t_0 \in I$. Let $\gamma : I \rightarrow \Omega$ be differentiable at t_0 . Let $f : \Omega \rightarrow V$ be differentiable at $p = \gamma(t_0)$. Then $f \circ \gamma$ is differentiable at t_0 , and*

$$(f \circ \gamma)'(t_0) = \text{Jac} f|_{\gamma(t_0)} \cdot \gamma'(t_0) = \sum_{i=1}^N (\gamma^i)'(t_0) \cdot \partial_i f(\gamma(t_0)) \quad (19.9)$$

Proof. This follows easily from Thm. 19.7 when t_0 is an interior point of I . Suppose that t_0 is an end point of I . For example, consider $t_0 = b$ where I is $[a, b]$ or $(a, b]$. Then we can easily extend γ to a function on $[a, b + 1)$ or $(a, b + 1]$ which is differentiable at t_0 . (For example, if $t \in (b, b + 1)$, we can define $\gamma(t) = \gamma(b) + (t - b)\gamma'(b)$.) Then we can apply Thm. 19.7 again to finish the proof. \square

Example 19.9. Let $\Omega \subset \mathbb{R}^N$ be open. Let $f : \Omega \rightarrow V$ be differentiable at $p \in \Omega$. Then for each $v \in \mathbb{R}^N$, the **directional derivative**

$$(\nabla_v f)(p) = \lim_{t \rightarrow 0} \frac{f(p + tv) - f(p)}{t}$$

exists and equals $df|_p \cdot v = \text{Jac}f|_p \cdot v$.

Proof. Apply the chain rule to $\gamma(t) = p + tv$. \square

We have thus proved the chain rule, one of the most important reasons for introducing differentiability on \mathbb{R}^N . We know that differentiable functions have partial derivatives of first order. However, having first order partial derivatives does not imply differentiability or even continuity:

Example 19.10. Let $f(x, y) = \frac{xy}{x^2 + y^2}$ when $(x, y) \neq (0, 0)$, and $f(0, 0) = 0$. Then $\lim_{r \rightarrow 0} f(r, r) = \frac{1}{2}$ and $\lim_{r \rightarrow 0} f(r, 0) = 0$, showing that f has no limit and is not continuous $(0, 0)$ at. However, $f(x, 0) = f(0, y) = 0$. So $\partial_1 f$ and $\partial_2 f$ are both equal to 0 at $(0, 0)$.

Example 19.11. Let $f(x, y) = \frac{x^3}{x^2 + y^2}$ when $(x, y) \neq (0, 0)$, and $f(0, 0) = 0$. Since $|f(x, y)| \leq |x|$ and $\lim_{(x, y) \rightarrow (0, 0)} |x| = 0$, we conclude that f is continuous at $(0, 0)$ (and hence is continuous everywhere). We have $\partial_1 f|_{(0, 0)} = \frac{d}{dx} x|_{x=0} = 1$ and $\partial_2 f|_{(0, 0)} = 0$. Let $\gamma(t) = (at, bt)$ where $(a, b) \in \mathbb{R}^2 \setminus \{(0, 0)\}$. Then

$$(\nabla_{(a, b)} f)(0) = (f \circ \gamma)'(0) = \frac{a^3}{a^2 + b^2}$$

is not equal to $\text{Jac}f|_{(0, 0)} \cdot (a, b)^t = a$. Thus, by Exp. 19.9, f is not differentiable at $(0, 0)$.

To have differentiability, we need the continuity of partial derivatives of first order.

Definition 19.12. Let $\Omega \subset \mathbb{R}^N$ be open. For each $r \in \mathbb{N}$, we let

$$C^r(\Omega, V) = \left\{ f \in C(\Omega, V) : \partial_{i_1} \cdots \partial_{i_k} f \text{ exists and is in } C(\Omega, V) \right. \\ \left. \text{for all } 0 \leq k \leq r \text{ and } 1 \leq i_1, \dots, i_k \leq N \right\}$$

In particular, we understand $C^0(\Omega, V)$ as $C(\Omega, V)$, and

$$C^\infty(\Omega, V) = \bigcap_{r \in \mathbb{N}} C^r(\Omega, V)$$

Elements in $C^\infty(\Omega, V)$ are called **smooth functions**.

It is clear that $C^r(\Omega, V) \subset C^q(\Omega, V)$ if $r \geq q$.

Remark 19.13. Suppose that $r \in \mathbb{Z}_+$ and $f \in C^r(\Omega, V)$. Let $1 \leq k \leq r$, and let $\sigma : \{1, \dots, k\} \rightarrow \{1, \dots, k\}$ be a bijection. Then by Thm. 12.35 or 14.7, for each $1 \leq i_1, \dots, i_k \leq N$ we have

$$\partial_{i_1} \cdots \partial_{i_k} f = \partial_{i_{\sigma(1)}} \cdots \partial_{i_{\sigma(k)}} f$$

Theorem 19.14. Let Ω be an open subset of \mathbb{R}^N . Let $f \in C^1(\Omega, V)$. Then f is differentiable on Ω .

Proof. We prove this by induction. The case $N = 1$ is obvious. Assume that the case N is true where $N \in \mathbb{Z}_+$. Let $\Omega \subset \mathbb{R}^{N+1}$ be open, and let $(p_0, p_1, \dots, p_N) = (p_0, p_\bullet) \in \Omega$. Let $v = (a_0, a_\bullet) = (a_0, a_1, \dots, a_N) \in \Omega$. Then

$$\begin{aligned} & f(p_0 + a_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet) \\ &= f(p_0 + a_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet + a_\bullet) + f(p_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet) \\ &= \int_0^{a_0} \partial_0 f(p_0 + t, p_\bullet + a_\bullet) dt + f(p_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet) \end{aligned}$$

By case N , there exist $\lambda_1, \dots, \lambda_N \in \mathbb{R}$ such that

$$f(p_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet) = \sum_{i=1}^N \lambda_i a_i + o(\|a_\bullet\|)$$

(In fact, $\lambda_i = \partial_i f(p_0, p_\bullet)$ by Prop. 19.4.) Let

$$\begin{aligned} h(a_0, a_\bullet) &= \int_0^{a_0} \partial_0 f(p_0 + t, p_\bullet + a_\bullet) dt - \partial_0 f(p_0, p_\bullet) \cdot a_0 \\ &= \int_0^{a_0} (\partial_0 f(p_0 + t, p_\bullet + a_\bullet) - \partial_0 f(p_0, p_\bullet)) dt \end{aligned}$$

Since $\partial_0 f$ is continuous, for every $\varepsilon > 0$ there exists $\delta > 0$ such that for all $(t, a_\bullet) \in \mathbb{R}^N$ with norm $\leq \delta$ we have

$$\|\partial_0 f(p_0 + t, p_\bullet + a_\bullet) - \partial_0 f(p_0, p_\bullet)\| \leq \varepsilon$$

and hence $\|h(a_0, a_\bullet)\| \leq \varepsilon |a_0|$ for all (a_0, a_\bullet) with norm $\leq \delta$. Thus $h(a_0, a_\bullet) = o(|a_0|)$. Therefore

$$\begin{aligned} & f(p_0 + a_0, p_\bullet + a_\bullet) - f(p_0, p_\bullet) - \partial_0 f(p_0, p_\bullet) \cdot a_0 - \sum_{i=1}^N \lambda_i a_i \\ &= o(|a_0|) + o(\|a_\bullet\|) = o(\|(a_0, a_\bullet)\|) \end{aligned}$$

□

19.2 Applications of the chain rule

Example 19.15. Let I, J be nonempty open intervals in \mathbb{R} . Choose $f \in C(I \times J, V)$ such that $\partial_2 f$ exists and is in $C(I \times J, V)$. Let $\alpha, \beta \in C^1(J, \mathbb{R})$ such that $\alpha(J) \subset I, \beta(J) \subset I$. Then

$$\frac{d}{dy} \int_{\alpha(y)}^{\beta(y)} f(x, y) dx = \int_{\alpha(y)}^{\beta(y)} \partial_2 f(x, y) dx + f(\beta(y), y) \beta'(y) - f(\alpha(y), y) \alpha'(y) \quad (19.10)$$

Proof. Define $F : I \times I \times J \rightarrow V$ by

$$F(r, s, t) = \int_r^s f(x, t) dx = \int_e^s f(x, t) dx - \int_e^r f(x, t) dx$$

where e is any element of I . By Exe. 14.8, F is continuous. Since $\partial_2 f$ is assumed to be continuous, by Thm. 14.6, we have

$$\partial_3 F(r, s, t) = \int_r^s \partial_2 f(x, t) dx$$

By the fundamental theorem of calculus, we have

$$\partial_1 F(r, s, t) = -f(r, t) \quad \partial_2 F(r, s, t) = f(s, t)$$

By Exe. 14.8, $\partial_1 F, \partial_2 F, \partial_3 F$ are continuous, and hence F is a C^1 -function. Therefore, by the chain rule (Cor. 19.8), the LHS of (19.10) can be calculated by setting $(r, s, t) = (\alpha(y), \beta(y), y)$:

$$\begin{aligned} & \frac{d}{dy} F(\alpha(y), \beta(y), y) \\ &= \partial_1 F(\alpha(y), \beta(y), y) \alpha'(y) + \partial_2 F(\alpha(y), \beta(y), y) \beta'(y) + \partial_3 F(\alpha(y), \beta(y), y) \end{aligned}$$

which equals the RHS of (19.10). □

Example 19.16. Fix $v \in V$ and $\varphi \in C(\mathbb{R}, V)$. Let $A \in \mathfrak{L}(V)$. Then $\frac{d}{dt} e^{At} = A e^{At} = e^{At} A$ by Exe. 17.42. By Exp. 19.15 and Thm. 13.16, we have

$$\frac{d}{dt} \int_0^t e^{A(t-s)} \varphi(s) ds = \varphi(t) + \int_0^t A e^{A(t-s)} \varphi(s) ds = \varphi(t) + A \int_0^t e^{A(t-s)} \varphi(s) ds$$

It follows that

$$f(t) = e^{At} v + \int_0^t e^{A(t-s)} \varphi(s) ds \quad (19.11)$$

is a solution of the differential equation

$$f'(t) = A f(t) + \varphi(t) \quad f(0) = v$$

It is the unique solution by Picard-Lindelöf Cor. 18.5.

Theorem 19.17 (Finite-increment theorem). Let Ω be an open subset of \mathbb{R}^N . Assume that $f : \Omega \rightarrow V$ is differentiable. Assume that $x, y \in \Omega$ satisfy $[x, y] \subset \Omega$ where

$$[x, y] = \{(1 - t)x + ty : 0 \leq t \leq 1\}$$

Then

$$\|f(y) - f(x)\| \leq \left(\sup_{z \in [x, y]} \|df|_z\| \right) \cdot \|y - x\| \quad (19.12)$$

where $\|df|_z\|$ is the operator norm of $df|_z$.

Proof. This can be proved in a similar way as Cor. 11.31. Let $\gamma : [0, 1] \rightarrow \Omega$ be $\gamma(t) = (1 - t)x + ty$. Then by chain rule we have $(f \circ \gamma)'(t) = df|_{\gamma(t)} \cdot \gamma'(t) = df|_{\gamma(t)} \cdot (y - x)$. Thus $\|(f \circ \gamma)'(t)\|$ is \leq the RHS of (19.12). Therefore, by the single-variable finite-increment Thm. 11.29, we have

$$\|f(y) - f(x)\| = \|f \circ \gamma(1) - f \circ \gamma(0)\| \leq \sup_{t \in [0, 1]} \|(f \circ \gamma)'(t)\|$$

which is \leq the RHS of (19.12). □

The following corollary provides a lot of examples satisfying the assumptions on φ in Picard-Lindelöf Thm. 18.4. Recall Def. 11.30 for the meaning of convex sets.

Corollary 19.18. Let Ω be an open subset of \mathbb{R}^N . Let $f \in C^1(\Omega, V)$. Let K be a compact convex subset of Ω . Then $f|_K$ is Lipschitz continuous.

Proof. Since $df : \Omega \rightarrow \mathfrak{L}(\mathbb{R}^N, V)$ is continuous (because it is essentially $\text{Jac} f$ by Prop. 19.4), there exists $L \in \mathbb{R}_{\geq 0}$ such that $\|df|_x\| \leq L$ for all $x \in K$. By Thm. 19.17, L is a Lipschitz constant of $f|_K$. □

Corollary 19.19. Let Ω be a nonempty open connected subset of \mathbb{R}^N . Assume that $f : \Omega \rightarrow V$ satisfies that $df = 0$ everywhere on Ω . Then f is a constant.

Proof. Fix $p \in \Omega$, and let $v = f(p)$. Let us prove that $f = v$ on Ω . Let $\Delta = \{x \in \Omega : f(x) = v\}$, which is a closed subset of Ω by the continuity of f (Rem. 19.3). Δ is nonempty since $p \in \Delta$. Thus, if we can show that Δ is open in Ω , then $\Delta = \Omega$ because Ω is connected, and hence the proof is complete.

To see that Δ is open, we choose any $x \in \Delta$, and choose $r > 0$ such that $U = B_{\mathbb{R}^N}(x, r)$ is contained in Ω . Since U is path-connected and hence connected, by Thm. 19.17 and the fact that $df = 0$, for every $y \in U$ we have $\|f(x) - f(y)\| = 0$ and hence $f(y) = v$. So $U \subset \Delta$. This proves that x is an interior point of Δ . □

20 Inner product spaces

Hilbert spaces and measure theory are two parallel but deeply connected theories that arose in the study of Fourier series and differential equations. We will spend half the semester learning these two theories in turn. The climax of this entire story is the Riesz-Fischer theorem, which establishes a connection between these two theories.

In the following three chapters, we develop the basic theory of Hilbert spaces. A Hilbert space is defined to be a complete inner product space. This definition indicates that Hilbert spaces have two important aspects:

- Geometry: orthogonal and orthonormal vectors.
- Analysis: completeness, and more.

We will focus on the geometric aspect in this chapter, and leave the discussion of the analytic aspect to the next chapter. As we shall see, the geometry of orthogonal vectors (together with the powerful **Gram-Schmidt process**) provides a uniform understanding of many identities and inequalities: Bessel's inequality (and its special case, Cauchy-Schwarz inequality), Parseval's identity. We will apply this geometric understanding to Fourier series. Surprisingly, the geometry of inner product spaces provides an elegant proof of the following analytic result: Every Riemann integrable function on $[-\pi, \pi]$ is the limit of its Fourier series under the L^2 -norm.

When referring to Hilbert spaces and inner product spaces, it is usually assumed that the field is \mathbb{C} , since complex Hilbert spaces are more useful than real ones. We will present the theory only for complex Hilbert spaces, although it can be easily adapted to real ones.

Starting from this chapter, we adopt the notations

$$l^p(X) = l^p(X, \mathbb{C}) \quad C(X) = C(X, \mathbb{C}) \quad C_c(X) = C_c(X, \mathbb{C}) \quad (20.1)$$

20.1 Inner product spaces

We fix a complex vector space V .

Definition 20.1. A map of complex vector spaces $T : V \rightarrow W$ is called **antilinear** or **conjugate linear** if for every $a, b \in \mathbb{C}$ and $u, v \in V$ we have

$$T(au + bv) = \bar{a}u + \bar{b}v$$

where \bar{a}, \bar{b} are the complex conjugates of a, b .

For example, the involution $*$: $\mathcal{A} \rightarrow \mathcal{A}$ of a $*$ -algebra is antilinear (recall Def. 15.4).

Definition 20.2. A function $\langle \cdot | \cdot \rangle : V \times V \rightarrow \mathbb{C}$ (sending $u \times v \in V^2$ to $\langle u | v \rangle$) is called a **sesquilinear form** if it is linear on the first variable, and antilinear on the second one.¹ Namely, for each $a, b \in \mathbb{C}$ and $u, v, w \in V$ we have

$$\langle au + bv | w \rangle = a\langle u | w \rangle + b\langle v | w \rangle \quad \langle w | au + bv \rangle = \bar{a}\langle w | u \rangle + \bar{b}\langle w | v \rangle$$

More generally, if V, W are complex vector spaces, a map $V \times W \rightarrow \mathbb{C}$ is also called **sesquilinear** if it is linear on the V -component and antilinear on the W -component.

Notice the difference between the notations $\langle u | v \rangle$ and $\langle u, v \rangle$: the latter always means a bilinear form, i.e., a function which is linear on both variables.

Proposition 20.3. Suppose that $\langle \cdot | \cdot \rangle$ and $(\cdot | \cdot)$ are sesquilinear forms on V satisfying $\langle v | v \rangle = (v | v)$ for all $v \in V$. Then $\langle u | v \rangle = (u | v)$ for all $u, v \in V$.

Proof. Let us prove that $\langle u | v \rangle$ can be written in terms of expressions of the form $\langle \xi | \xi \rangle$ where $\xi \in V$. Choose any $t \in [-\pi, \pi]$. Let

$$f(t) := \langle u + e^{it}v | u + e^{it}v \rangle = \langle u | u \rangle + \langle v | v \rangle + e^{-it}\langle u | v \rangle + e^{it}\langle v | u \rangle$$

Then $\langle u | v \rangle$ is a Fourier coefficient of f . Namely, using the fact that $\frac{1}{2\pi} \int_{-\pi}^{\pi} e^{int} dt = \delta_{n,0}$ (where $n \in \mathbb{Z}$), we have

$$\langle u | v \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} \langle u + e^{it}v | u + e^{it}v \rangle e^{it} dt \quad (20.2)$$

This finishes the proof. □

Remark 20.4. In practice, it is sometimes more convenient to have a discrete version of (20.2): We view $f(t)$ as a function on the finite abelian group $\{0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}\} \simeq \mathbb{Z}/4\mathbb{Z}$. Then $\langle u | v \rangle$ is a coefficient of the “discrete Fourier transform” of f :

$$\begin{aligned} \langle u | v \rangle &= \frac{1}{4} \sum_{t=0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}} \langle u + e^{it}v | u + e^{it}v \rangle e^{it} \\ &= \frac{1}{4} \left(\langle u + v | u + v \rangle - \langle u - v | u - v \rangle + \mathbf{i} \langle u + \mathbf{i}v | u + \mathbf{i}v \rangle - \mathbf{i} \langle u - \mathbf{i}v | u - \mathbf{i}v \rangle \right) \end{aligned} \quad (20.3)$$

We call (20.3) the **polarization identity**.

Definition 20.5. A function $\langle \cdot | \cdot \rangle : V \times V \rightarrow \mathbb{C}$ is called a **Hermitian form** if it is linear on the first variable and satisfies $\overline{\langle u | v \rangle} = \langle v | u \rangle$ for all $u, v \in V$. Then $\langle \cdot | \cdot \rangle$ is automatically antilinear on the second variable, i.e., a Hermitian form is automatically a sesquilinear form.

¹Physicists prefer the opposite convention, i.e., their sesquilinear forms are antilinear on the first variables.

Example 20.6. Let $A \in \mathbb{C}^{N \times N}$ be a complex $N \times N$ matrix. Define $\langle \cdot | \cdot \rangle : \mathbb{C}^N \times \mathbb{C}^N \rightarrow \mathbb{C}$ by $\langle u | v \rangle = \overline{v^t} \cdot A \cdot u$ where u, v are viewed as column vectors. Then $\langle \cdot | \cdot \rangle$ is a sesquilinear form on \mathbb{C}^N . (It is an easy linear algebra exercise that every sesquilinear form on \mathbb{C}^N is of this form.) Moreover, $\langle \cdot | \cdot \rangle$ is a Hermitian form iff A is a **Hermitian matrix**, i.e., $A = \overline{A^t}$.

The following is our first application of the polarization identity:

Proposition 20.7. Let $\langle \cdot | \cdot \rangle$ be a sesquilinear form on V . The following are equivalent:

- (1) $\langle \cdot | \cdot \rangle$ is a Hermitian form.
- (2) For each $v \in V$ we have $\langle v | v \rangle \in \mathbb{R}$.

Proof. (1) \Rightarrow (2): Obvious. (2) \Rightarrow (1): Let $\langle u | v \rangle = \overline{\langle v | u \rangle}$. Then $(\cdot | \cdot)$ is a sesquilinear form on V . Assuming (2), we have $\langle v | v \rangle = \overline{\langle v | v \rangle}$ for all $v \in V$. Therefore, by Prop. 20.3, we have $\langle u | v \rangle = \overline{\langle v | u \rangle}$ for all u, v . So (1) is true. \square

Definition 20.8. A sesquilinear form $\langle \cdot | \cdot \rangle$ on V is called **positive semi-definite** (or simply **positive**), if $\langle v | v \rangle \geq 0$ for all $v \in V$. If a positive sesquilinear form $\langle \cdot | \cdot \rangle$ on V is fixed, we define

$$\|v\| = \sqrt{\langle v | v \rangle} \quad \text{for all } v \in V \quad (20.4)$$

A vector $v \in V$ satisfying $\|v\| = 1$ is called a **unit vector**.

By Prop. 20.7, a positive sesquilinear form is Hermitian.

Definition 20.9. Let $\langle \cdot | \cdot \rangle$ be a positive sesquilinear form on V . By sesquilinearity, we clearly have $\langle 0 | 0 \rangle = 0$. We say that $\langle \cdot | \cdot \rangle$ is an **inner product** if it is also **non-degenerate**, i.e., if the only $v \in V$ satisfying $\langle v | v \rangle = 0$ is $v = 0$. We call the pair $(V, \langle \cdot | \cdot \rangle)$ (or simply call V) an **inner product space** or a **pre-Hilbert space**.

Example 20.10. \mathbb{C}^N , equipped with the Euclidean inner product $\langle u | v \rangle = \overline{v^t} u$, is an inner product space.

Example 20.11. Let X be a set. Then $l^2(X, \mathbb{C})$, together with the standard inner product

$$\langle f | g \rangle = \sum_{x \in X} f(x) \overline{g(x)} \quad (20.5)$$

(where the RHS converges by Thm. 12.33), is an inner product space.

Example 20.12. Let $-\infty < a < b < +\infty$. Then $C([a, b], \mathbb{C})$, together with the inner product

$$\langle f | g \rangle = \int_a^b f g^* = \int_a^b f(x) \overline{g(x)} dx \quad (20.6)$$

is an inner product space.

The gap between positive forms and inner products is not very big:

Proposition 20.13. *Let $\langle \cdot | \cdot \rangle$ be a positive sesquilinear form on V . Let*

$$\mathcal{N} = \{v \in V : \|v\| = 0\} \quad (20.7)$$

Then \mathcal{N} is a linear subspace of V . Moreover, there is an inner product $(\cdot | \cdot)$ on the quotient space V/\mathcal{N} satisfying

$$(u + \mathcal{N} | v + \mathcal{N}) = \langle u | v \rangle \quad \text{for all } u, v \in V \quad (20.8)$$

Proof. (20.8) suggests that if $\|v\| = 0$, then $\langle u | v \rangle = (u + \mathcal{N} | v + \mathcal{N}) = (u + \mathcal{N} | \mathcal{N}) = \langle u | 0 \rangle = 0$ for all $u \in V$. Motivated by this observation, let us prove

$$\mathcal{N} = \{v \in V : (u | v) = 0 \text{ for all } u \in V\} \quad (20.9)$$

Then the linearity of \mathcal{N} follows immediately from (20.9). Moreover, if we define a function $(\cdot | \cdot)$ on V/\mathcal{N} by (20.8), then it is well-defined: If $v + \mathcal{N} = v' + \mathcal{N}$, then $v - v' \in \mathcal{N}$. Thus, by (20.9), we have $\langle u | v - v' \rangle = 0$. So

$$(u + \mathcal{N} | v + \mathcal{N}) = \langle u | v \rangle = \langle u | v' \rangle = (u + \mathcal{N} | v' + \mathcal{N})$$

A similar argument shows that if $u + \mathcal{N} = u' + \mathcal{N}$ then $(u + \mathcal{N} | v + \mathcal{N}) = (u' + \mathcal{N} | v + \mathcal{N})$. This proves the well-definedness. It is easy to check that $(\cdot | \cdot)$ is sesquilinear and positive. If $(v + \mathcal{N} | v + \mathcal{N}) = 0$, then $\langle v | v \rangle = 0$ and hence $v \in \mathcal{N}$. This proves that $(\cdot | \cdot)$ is non-degenerate.

Let us prove (20.9). Clearly $\|v\| = \sqrt{\langle v | v \rangle} = 0$ holds whenever $\langle u | v \rangle = 0$ for all u . Conversely, suppose that $\|v\| = 0$, i.e., $\langle v | v \rangle = 0$. Choose any $u \in V$. Then for each $t \in \mathbb{R}$ we have

$$0 \leq \langle u + tv | u + tv \rangle = \|u\|^2 + 2t \cdot \operatorname{Re} \langle u | v \rangle$$

where the RHS is a linear function of t . Any linear function which is always ≥ 0 must be zero. So $\operatorname{Re} \langle u | v \rangle = 0$. Similarly, $\operatorname{Im} \langle u | v \rangle = -\operatorname{Re} \langle iu | v \rangle = 0$. So $\langle u | v \rangle = 0$. \square

Example 20.14. Let $-\infty < a < b < +\infty$ and $\mathcal{V} = \mathcal{R}[a, b] = \mathcal{R}([a, b], \mathbb{C})$ (the space of Riemann integrable complex functions on $[a, b]$). Then \mathcal{V} has a positive sesquilinear form defined by (20.6). Let $\mathcal{N} = \{f \in \mathcal{V} : \langle f | f \rangle = 0\}$. Then

$$\mathcal{N} = \{f \in \mathcal{V} : f \text{ is zero outside a null subset of } [a, b]\} \quad (20.10)$$

Thus, $V = \mathcal{V}/\mathcal{N}$ is the set of all $f \in \mathcal{R}[a, b]$ such that $f, g \in \mathcal{R}[a, b]$ are viewed as the same element of V iff $f = g$ almost everywhere (i.e. $\{x : f(x) \neq g(x)\}$ is null).

Proof. Let $g = |f|^2$. We want to show that $\int g = 0$ iff $\Delta = \{x \in [a, b] : g(x) > 0\}$ is null. Assume that $\int g > 0$. Then f has a strictly positive lower Darboux sum (recall Thm. 13.41). This implies that there exist c, d satisfying $a \leq c < d \leq b$ such that $(d - c) \cdot \inf_{\xi \in [c, d]} g(\xi) > 0$. So $g > 0$ on $[c, d]$. So Δ contains $[c, d]$, and hence is not null.

Assume that $\int g = 0$. By Lebesgue's criterion 14.10, g is continuous outside a null subset of $[a, b]$. Thus, it suffices to prove that $g(p) = 0$ for any $p \in [a, b]$ at which g is continuous. Suppose that $\varepsilon := g(p) > 0$. Then by the continuity, there is an interval $I \subset [a, b]$ containing p with $|I| > 0$ such that $g > \varepsilon/2$ on I . Thus $g \geq \frac{\varepsilon}{2} \cdot \chi_I$, and hence $0 = \int g \geq \frac{\varepsilon}{2} \cdot |I|$, impossible. \square

We close this section with an elementary but important fact. It says that linear maps are determined by their associated sesquilinear forms.

Exercise 20.15. Suppose that $S, T : U \rightarrow V$ are linear maps of inner product spaces.

1. Prove that $S = T$ iff $\langle Su|v \rangle = \langle Tu|v \rangle$ for all $u \in U, v \in V$.
2. Assume that $U = V$. Prove that $S = T$ iff $\langle Sv|v \rangle = \langle Tv|v \rangle$ for all $v \in V$.

20.2 Pythagorean and Gram-Schmidt

Unless otherwise stated, we fix an inner product $\langle \cdot | \cdot \rangle$ on a complex vector space V so that V is an inner product space.

Definition 20.16. A set \mathfrak{S} of vectors of V are called **orthogonal** if $\langle u|v \rangle = 0$ for any distinct $u, v \in \mathfrak{S}$. An orthogonal set \mathfrak{S} is called **orthonormal** if $\|v\| = 1$ for all $v \in \mathfrak{S}$.

Remark 20.17. We will also talk about an **orthogonal** resp. **orthonormal family of vectors** $(e_i)_{i \in I}$. This means that $\langle e_i|e_j \rangle = 0$ for any distinct $i, j \in I$ (resp. $\langle e_i|e_j \rangle = \delta_{i,j}$ for any $i, j \in I$).

In particular, two vectors $u, v \in V$ are called orthogonal when $\langle u|v \rangle = 0$. A fundamental fact about orthogonal vectors is

Proposition 20.18 (Pythagorean identity). Suppose that $u, v \in V$ are orthogonal. Then

$$\|u + v\|^2 = \|u\|^2 + \|v\|^2 \quad (20.11)$$

In particular,

$$\|v\| \leq \|u + v\| \quad (20.12)$$

Proof. $\|u + v\|^2 = \langle u + v | u + v \rangle = \langle u | u \rangle + \langle v | v \rangle + 2\operatorname{Re}\langle u | v \rangle = \langle u | u \rangle + \langle v | v \rangle.$ \square

Note that by applying (20.11) repeatedly, we see that if $v_1, \dots, v_n \in V$ are orthogonal, then

$$\|v_1 + \dots + v_n\|^2 = \|v_1\|^2 + \dots + \|v_n\|^2 \quad (20.13)$$

Remark 20.19. Suppose that \mathfrak{S} is an orthonormal set of vectors of V . Then \mathfrak{S} is clearly linearly independent. (If $e_1, \dots, e_n \in \mathfrak{S}$ and $\sum_i a_i e_i = 0$, then $a_j = \sum_i \langle a_i e_i | e_j \rangle = \langle 0 | e_j \rangle = 0$.) Thus, by linear algebra, if $\mathfrak{S} = \{e_1, \dots, e_n\}$ is finite, then one can find uniquely $a_1, \dots, a_n \in \mathbb{C}$ and $u \in V$ such that $v = a_1 e_1 + \dots + a_n e_n + u$ and that u is orthogonal to e_1, \dots, e_n . The expressions of a_1, \dots, a_n, u can be expressed explicitly:

Proposition 20.20 (Gram-Schmidt). *Let e_1, \dots, e_n be orthonormal vectors in V . Let $v \in V$. Then*

$$v - \sum_{i=1}^n \langle v | e_i \rangle \cdot e_i \quad (20.14)$$

is orthogonal to e_1, \dots, e_n .

Proof. This is a direct calculation and is left to the readers. \square

Remark 20.21. “Gram-Schmidt” usually refers to the following process. Let v_1, \dots, v_n be a set of linearly independent vectors of V . Then there is an algorithm of finding an orthonormal basis of $U = \operatorname{Span}\{v_1, \dots, v_n\}$: Let $e_1 = v_1 / \|v_1\|$. Suppose that a set of orthonormal vectors e_1, \dots, e_k in U have been found. Then e_{k+1} is defined by $\tilde{v}_{k+1} / \|\tilde{v}_{k+1}\|$ where $\tilde{v}_{k+1} = v_{k+1} - \sum_{i=1}^k \langle v_{k+1} | e_i \rangle \cdot e_i$.

Combining Pythagorean with Gram-Schmidt, we have:

Corollary 20.22 (Bessel’s inequality). *Let $(e_i)_{i \in I}$ be a family of orthonormal vectors of V . Then for each $v \in V$ we have*

$$\sum_{i \in I} |\langle v | e_i \rangle|^2 \leq \|v\|^2 \quad (20.15)$$

In particular, the set $\{i \in I : \langle v | e_i \rangle \neq 0\}$ is countable.

Proof. The LHS of (20.15) is $\lim_{J \in \operatorname{fin}(2^I)} \sum_{j \in J} |\langle v | e_j \rangle|^2$. Thus, it suffices to that for each $J \in \operatorname{fin}(2^I)$ we have $\sum_{j \in J} |\langle v | e_j \rangle|^2 \leq \|v\|^2$. Let

$$u_1 = \sum_{j \in J} \langle v | e_j \rangle \cdot e_j \quad u_2 = v - u_1$$

(Namely, $v = u_1 + u_2$ is the orthogonal decomposition of v with respect to $\text{Span}\{e_j : j \in J\}$.) By Gram-Schmidt, we have $\langle u_1 | u_2 \rangle = 0$. By Pythagorean, we have $\|u_1\|^2 \leq \|v\|^2$. But Pythagorean (20.13) also implies

$$\|u_1\|^2 = \sum_{j \in J} |\langle v | e_j \rangle|^2$$

The last statement about countability follow from Pb. 5.3. □

Theorem 20.23 (Cauchy-Schwarz inequality). *For each $u, v \in V$ we have*

$$|\langle u | v \rangle| \leq \|u\| \cdot \|v\| \quad (20.16)$$

Proof. If $v = 0$, then the inequality trivially holds. Assume $v \neq 0$. Then $\|v\| \neq 0$. By dividing v by $\|v\|$, we assume $\|v\| = 1$. Then $\{v\}$ is a set of orthonormal vector. By Bessel's inequality, we have $|\langle u | v \rangle| \leq \|u\|$. □

Remark 20.24. In the general case that $\langle \cdot | \cdot \rangle$ is a positive sesquilinear form, the Cauchy-Schwarz inequality $|\langle u | v \rangle|^2 \leq \langle u | u \rangle \cdot \langle v | v \rangle$ still holds.

Proof. We use the notations in Prop. 20.13. Applying Thm. 20.23 to V/\mathcal{N} , we have $|(u + \mathcal{N} | v + \mathcal{N})|^2 \leq (u + \mathcal{N} | u + \mathcal{N}) \cdot (v + \mathcal{N} | v + \mathcal{N})$. This proves $|\langle u | v \rangle|^2 \leq \langle u | u \rangle \cdot \langle v | v \rangle$. □

Corollary 20.25. *V is a normed vector space if we define $\|v\| = \sqrt{\langle v | v \rangle}$.*

Proof. By Cauchy-Schwarz, we have

$$\|u + v\|^2 = \|u\|^2 + \|v\|^2 + 2\text{Re}\langle u | v \rangle \leq \|u\|^2 + \|v\|^2 + 2\|u\| \cdot \|v\| = (\|u\| + \|v\|)^2$$

This proves the triangle inequality. The other conditions are obvious. □

Corollary 20.26. *The map $\langle \cdot | \cdot \rangle : V \times V \rightarrow \mathbb{C}$ is continuous if V is equipped with the norm topology.*

Proof. For each $u, u_0, v, v_0 \in V$ such that $\|u - u_0\| \leq \varepsilon$, $\|v - v_0\| \leq \varepsilon$ where $0 < \varepsilon < 1$, we have by Cauchy-Schwarz that

$$|\langle u | v \rangle - \langle u_0 | v_0 \rangle| \leq |\langle u - u_0 | v \rangle| + |\langle u_0 | v - v_0 \rangle| \leq \varepsilon(\|v_0\| + 1) + \varepsilon\|u_0\|$$

□

Remark 20.27. Since V is a normed vector space, V is also a metric space with $d(u, v) = \|u - v\| = \sqrt{\langle u - v | u - v \rangle}$. Now, the polarisation identity (Prop. 20.3) says that for inner product spaces, norms determine inner products, and hence metrics determine inner products. Therefore, if W is an inner product space, and if $T : V \rightarrow W$ is a linear isometry, then

$$\langle Tu | Tv \rangle = \langle u | v \rangle$$

for all $u, v \in V$. In particular, if T is an isomorphism of normed vector spaces (i.e., T is a linear surjective isometry, cf. Def. 9.2), then T is an equivalence of inner product spaces. In this case, we say that T is a **unitary map**, and say that V, W are **isomorphic inner product spaces** (or that V, W are **unitarily equivalent**). □

20.3 Orthogonal decompositions

Fix an inner product space V . In the last section, we used Gram-Schmidt process and Pythagorean inequality (20.12) to derive many useful inequalities. In this section, we will have a deeper understanding of the geometry behind Gram-Schmidt process and orthogonal projections.

Definition 20.28. Let U be a linear subspace of V . Let $v \in V$. An **orthogonal decomposition** of v with respect to U is an expression of the form $v = u + w$ where $u \in U$ and $w \perp U$ (i.e. w is orthogonal to every vector of U). Orthogonal decompositions of v are unique if exist. We call u the **orthogonal projection** of v onto U .

Proof of uniqueness. Suppose that $v = u' + w'$ is another orthogonal decomposition. Then $u - u'$ equals $w' - w$. Let $\xi = u - u'$. Then $\xi \in U$ and $\xi \perp U$. So $\langle \xi | \xi \rangle = 0$, and hence $\xi = 0$. So $u = u'$ and $w = w'$. \square

Example 20.29. Let e_1, \dots, e_n be orthonormal vectors of V . Let $U = \text{Span}\{e_1, \dots, e_n\}$. Choose any $v \in V$. Then by Gram-Schmidt, $v = u + w$ is the orthogonal decomposition if we let $u = \sum_{i=1}^n \langle v | e_i \rangle e_i$ and $w = v - u$.

The inequalities in the last section relies on the Pythagorean inequality $\|u\| \leq \|v\|$ for an orthogonal decomposition $v = u + w$. In this section, we need an optimization property about orthogonal decompositions:

Proposition 20.30. Let U be a linear subspace of V . Suppose that $v \in V$ has orthogonal decomposition $v = u + w$ with respect to U . Then

$$\|v - u\| = \inf_{\xi \in U} \|v - \xi\| \quad (20.17)$$

Proof. Clearly “ \geq ” holds. Choose any $\xi \in U$. Then $v - \xi = v - u + u - \xi = w + (u - \xi)$. Since $u - \xi \in U$, we have $w \perp u - \xi$. Thus, by Pythagorean, we have $\|w\| \leq \|v - \xi\|$. \square

Corollary 20.31. Let e_1, \dots, e_n be orthonormal vectors of V . For each $v \in V$ and $\lambda_1, \dots, \lambda_n \in \mathbb{C}$ we have

$$\|v\|^2 - \sum_{i=1}^n |\langle v | e_i \rangle|^2 = \left\| v - \sum_{i=1}^n \langle v | e_i \rangle e_i \right\|^2 \leq \left\| v - \sum_{i=1}^n \lambda_i e_i \right\|^2 \quad (20.18)$$

Proof. By Gram-Schmidt, we have orthogonal decomposition $v = u + w$ where $w = \sum_i \langle v | e_i \rangle e_i$. The Pythagorean identity $\|v\|^2 - \|u\|^2 = \|w\|^2$ proves the first equality. Prop. 20.30 proves the “ \leq ”. \square

We now give several applications of Cor. 20.31.

Definition 20.32. A set \mathfrak{S} (or a family $(e_i)_{i \in I}$) of orthonormal vectors of V is called an **orthonormal basis** of V if it spans a dense subspace of V .

Example 20.33. If X is a set, by Lem. 17.28, $l^2(X)$ has an orthonormal basis $(\chi_{\{x\}})_{x \in X}$.

Example 20.34. If V is separable, then V has a countable orthonormal basis.

Proof. Let $\{v_1, v_2, \dots\}$ be a dense subset of V where $v_1 \neq 0$. Then by Gram-Schmidt (Rem. 20.21), we can find $e_1, e_2, \dots \in V$ such that the set $\{e_1, e_2, \dots\}$ is orthonormal (after removing the duplicated terms), and that $\text{Span}\{v_1, \dots, v_n\} = \text{Span}\{e_1, \dots, e_n\}$ for each n . Then $\{e_1, e_2, \dots\}$ clearly spans a dense subspace of V . \square

We remark that there are non-separable and non-complete inner product spaces that do not have orthonormal bases. See [Gud74].

Theorem 20.35. Suppose that $(e_i)_{i \in I}$ is an orthonormal basis of V . Then for each $v \in V$, the RHS of the following converges (under the norm of V) to the LHS:

$$v = \sum_{i \in I} \langle v | e_i \rangle \cdot e_i \quad (20.19)$$

Proof. Note that for $J \in \text{fin}(2^I)$, the expression

$$\left\| v - \sum_{j \in J} \langle v | e_j \rangle e_j \right\|^2 = \|v\|^2 - \sum_{j \in J} |\langle v | e_j \rangle|^2$$

decreases when J increases. Thus, it suffices to prove that the $\inf_{J \in \text{fin}(2^I)}$ of this expression is 0. This follows immediately from Cor. 20.31 and the fact that we can find J and $(\lambda_j)_{j \in J}$ in \mathbb{C} such that $\|v - \sum_{j \in J} \lambda_j e_j\|$ is small enough. \square

Corollary 20.36 (Parseval's identity). Suppose that $(e_i)_{i \in I}$ is an orthonormal basis of V . Then for each $u, v \in V$ we have

$$\langle u | v \rangle = \sum_{i \in I} \langle u | e_i \rangle \cdot \langle e_i | v \rangle \quad (20.20)$$

In particular,

$$\|v\|^2 = \sum_{i \in I} |\langle v | e_i \rangle|^2 \quad (20.21)$$

Proof. By Thm. 20.35, $u = \lim_{J \in \text{fin}(2^I)} u_J$ where $u_J = \sum_{j \in J} \langle u | e_j \rangle \cdot e_j$. By the continuity of $\langle \cdot | \cdot \rangle : V \times V \rightarrow \mathbb{C}$ (Cor. 20.26), we have

$$\langle u | v \rangle = \lim_{J \in \text{fin}(2^I)} \langle u_J | v \rangle = \lim_{J \in \text{fin}(2^I)} \sum_{j \in J} \langle u | e_j \rangle \cdot \langle e_j | v \rangle = \sum_{i \in I} \langle u | e_i \rangle \cdot \langle e_i | v \rangle$$

\square

Remark 20.37. In Hilbert's original definition, an orthonormal basis $(e_i)_{i \in I}$ (called by Hilbert a complete orthogonal system of functions) is a set of orthonormal vectors satisfying Parseval's identity (20.20) for all $u, v \in V$. Hilbert did not have the topological understanding of orthonormal basis as in Def. 20.32 (i.e., a set of orthonormal vectors spanning a *dense* subspace of V). See [BK84, Sec. 8].

Corollary 20.38. Suppose that $(e_x)_{x \in X}$ is an orthonormal basis of V . Then there is a linear isometry

$$\Phi : V \rightarrow l^2(X) \quad v \mapsto (\langle v | e_x \rangle)_{x \in X} \quad (20.22)$$

whose range is dense in $l^2(X)$.

Since $l^2(X)$ is complete (Thm. 12.32), it follows that Φ gives a Banach space completion of V , cf. Def. 10.18.

Proof. Parseval's identity shows that $(\langle v | e_x \rangle)_{x \in X}$ has finite l^2 -norm $\|v\|$. So the map Φ defined by (20.22) is clearly a linear isometry. \square

20.4 Application to Fourier series

In this section, we apply the results about inner product spaces to the study of Fourier series.

Let $\mathcal{V} = \mathcal{R}[-\pi, \pi] = \mathcal{R}([-\pi, \pi], \mathbb{C})$, the vector space of (strongly) Riemann integrable complex valued functions on $[-\pi, \pi]$. For each $f \in \mathcal{V}$ and $n \in \mathbb{Z}$, define its n -th **Fourier coefficient** to be

$$\hat{f}(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) e^{-inx} dx = \frac{1}{2\pi} \int_{-\pi}^{\pi} f e_{-n} \quad (20.23)$$

where $e_n(x) = e^{inx}$. Then the **Fourier series** of f is

$$\sum_{n \in \mathbb{Z}} \hat{f}(n) e_n \quad (20.24)$$

We view \hat{f} as a function on \mathbb{Z} .

In Fourier analysis, one asks whether the Fourier series of f converges to f , and if so, in which sense does it converge? We have seen in Subsec. 13.1.4 that (20.24) might not converge uniformly to f . We have also mentioned there that (20.24) might be divergent at many points of $[-\pi, \pi]$, although in many cases it converges pointwise to f (cf. Pb. 14.6). In this section, we will see that (20.24) converges to f under the L^2 -norm. Another important result of this section is the classification of all f whose Fourier modes are all 0.

Let V be the vector space of all $f \in \mathcal{R}[-\pi, \pi]$, where $f, g \in \mathcal{R}[-\pi, \pi]$ are equal elements in V iff $\{x \in [-\pi, \pi] : f(x) \neq g(x)\}$ is null. By Exp. 20.14, V is an inner product space whose inner product $\langle \cdot | \cdot \rangle$ is defined by

$$\langle f | g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f g^* = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) \overline{g(x)} \quad (20.25)$$

It follows that

$$\hat{f}(n) = \langle f | e_n \rangle \quad (20.26)$$

Proposition 20.39. $\{e_n : n \in \mathbb{Z}\}$ is an orthonormal basis of V .

Proof. Clearly $\{e_n : n \in \mathbb{Z}\}$ is an orthonormal set of vectors. By Stone-Weierstrass, $\text{Span} \mathfrak{S}$ is l^∞ -dense in $C(\mathbb{S}^1)$, the space of 2π -periodic continuous functions (cf. Exp. 15.12). So $\text{Span} \mathfrak{S}$ is L^2 -dense in $C(\mathbb{S}^1)$. Indeed, for any $f \in C(\mathbb{S}^1)$, pick a sequence $(f_k)_{k \in \mathbb{Z}_+}$ of elements in $\text{Span} \mathfrak{S}$ converging uniformly on $[-\pi, \pi]$ to f . Therefore $\lim_{k \rightarrow \infty} \int |f - f_k|^2 = 0$ by Cor. 13.21.

To show that $\text{Span} \mathfrak{S}$ is dense in V , it remains to prove that $C(\mathbb{S}^1)$ is L^2 -dense in V . Let $\mathcal{S} = \text{Span}\{\chi_I : I \text{ is an interval in } [-\pi, \pi]\}$. It is easy to see that each χ_I can be L^2 -approximated by elements of $C(\mathbb{S}^1)$. Therefore, it suffices to prove that \mathcal{S} is L^2 -dense in V .

Let $f \in \mathcal{R}[-\pi, \pi]$. We want to show that f can be L^2 -approximated by elements of \mathcal{S} . By considering the real part and the imaginary part separately, we assume that f is real. Let $M = \|f\|_{l^\infty}$, which is finite. By the proof of Prop. 14.51 (or by approximating $\int f$ by upper Darboux sums, cf. Thm. 13.41), we can find a sequence (f_n) in \mathcal{S} such that $\lim_n \int_{-\pi}^{\pi} |f - f_n| = 0$, and that $|f_n| \leq M$ for all n . Therefore

$$\int_{-\pi}^{\pi} |f - f_n|^2 \leq 2M \int_{-\pi}^{\pi} |f - f_n|$$

where the RHS converges to 0 as $n \rightarrow \infty$. □

Corollary 20.40. Let $f \in \mathcal{R}[-\pi, \pi]$. Then the following are equivalent

- (1) Each Fourier coefficient $\hat{f}(n)$ is 0.
- (2) f is zero outside a null set.

Proof. This is immediate from Prop. 20.39 and the obvious fact that a vector in an inner product space (equipped with an orthonormal basis) is zero iff its inner product with any element in the orthonormal basis (or more generally, any element in a densely-spanning subset) is zero. □

Theorem 20.41. Let $f, g \in \mathcal{R}[a, b]$. Then we have **Parseval's identity**

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} f g^* = \sum_{n=-\infty}^{+\infty} \hat{f}(n) \overline{\hat{g}(n)} \quad (20.27)$$

where the RHS converges absolutely. In particular,

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} |f|^2 = \sum_{n=-\infty}^{+\infty} |\hat{f}(n)|^2 \quad (20.28)$$

Moreover, we have

$$\lim_{m, n \rightarrow +\infty} \int_{-\pi}^{\pi} \left| f - \sum_{k=-m}^n \hat{f}(k) e_k \right|^2 = 0 \quad (20.29)$$

Proof. Immediate from Cor. 20.36 and Thm. 20.35. □

The following result was mentioned in Subsec. 10.4.1.

Corollary 20.42. The space $C[-\pi, \pi]$, under the inner product (20.25), has a Banach space completion

$$C[-\pi, \pi] \rightarrow l^2(\mathbb{Z}) \quad f \mapsto \hat{f} \quad (20.30)$$

The same is true if $C[-\pi, \pi]$ is replaced by V .

Proof. Prop. 20.39 implies that $\{e_n : n \in \mathbb{Z}\}$ is also an orthonormal basis of $C[-\pi, \pi]$. Thus, the corollary follows from Cor. 20.38. □

20.5 Problems and supplementary material

20.5.1 ★ The Sobolev space $H^s(\mathbb{S}^1)$

For each $s \geq 0$, and for each $\varphi : \mathbb{Z} \rightarrow \mathbb{C}$, let

$$\|\varphi\|_{h^s} = \sum_{n \in \mathbb{Z}} (1 + n^2)^s |\varphi(n)|^2 \quad (20.31)$$

It is clear that $\|\varphi\|_{h^0} = \|\varphi\|_2$, and that

$$s \leq t \quad \implies \quad \|\varphi\|_{h^s} \leq \|\varphi\|_{h^t}$$

Define

$$h^s(\mathbb{Z}) = \{\varphi \in \mathbb{C}^{\mathbb{Z}} : \|\varphi\|_{h^s} < +\infty\} \quad (20.32)$$

which is clearly a subset of $l^2(\mathbb{Z})$. Clearly $h^s(\mathbb{Z}) \supset h^t(\mathbb{Z})$ if $s \leq t$.

Problem 20.1. Prove that $h^s(\mathbb{Z})$ is a linear subspace of $l^2(\mathbb{Z})$, that $h^s(\mathbb{Z})$ has a well-defined inner product described by

$$\langle \varphi | \psi \rangle_{h^s} = \sum_{n \in \mathbb{Z}} (1 + n^2)^s \varphi(n) \overline{\psi(n)} \quad (20.33)$$

and that $h^s(\mathbb{Z})$ is complete under this inner product.

Let $C(\mathbb{S}^1)$ be the set of complex continuous functions on \mathbb{S}^1 , equivalently, continuous 2π -periodic functions on \mathbb{R} . More generally, for each $n \in \mathbb{N} \cup \{\infty\}$, let

$$C^n(\mathbb{S}^1) = \{2\pi\text{-periodic } f \in C^n(\mathbb{R})\} \quad (20.34)$$

Equip $C(\mathbb{S}^1)$ with the inner product $\langle f | g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f g^*$. The norm determined by this inner product is called the L^2 -norm. By Cor. 20.42, we have a Hilbert space completion

$$\Phi : C(\mathbb{S}^1) \rightarrow l^2(\mathbb{Z}) \quad f \mapsto \hat{f} \quad (20.35)$$

Recall that $e_n(x) = e^{inx}$.

Problem 20.2. Prove that $l^1(\mathbb{Z}) \subset \Phi(C(\mathbb{S}^1))$, and that the linear injection

$$\Phi^{-1} : l^1(\mathbb{Z}) \rightarrow C(\mathbb{S}^1) \quad (20.36)$$

can be described by

$$\Phi^{-1}(\varphi) = \sum_{n \in \mathbb{Z}} \varphi(n) e_n \quad (20.37)$$

where the RHS converges under the $l^\infty(\mathbb{S}^1)$ -norm (and hence under the L^2 -norm).

Problem 20.3. Let $s > \frac{1}{2}$. Prove that $h^s(\mathbb{Z}) \subset l^1(\mathbb{Z})$.

Hint. Use Cauchy-Schwarz or Hölder's inequality. □

Definition 20.43. Let $s > \frac{1}{2}$. Define

$$H^s(\mathbb{S}^1) \stackrel{\text{def}}{=} \Phi^{-1}(h^s(\mathbb{Z})) \quad (20.38)$$

According to Pb. 20.2 and 20.3, we have

$$H^s(\mathbb{S}^1) \subset \Phi^{-1}(l^1(\mathbb{Z})) \subset C(\mathbb{S}^1) \quad (20.39)$$

and Φ restricts to a linear bijection

$$\Phi : H^s(\mathbb{S}^1) \xrightarrow{\sim} h^s(\mathbb{Z}) \quad (20.40)$$

whose inverse sends

$$\varphi \mapsto \sum_{n \in \mathbb{Z}} \varphi(n) e_n$$

where the RHS converges uniformly. Define inner product $\langle \cdot | \cdot \rangle_{H^s}$ on $H^s(\mathbb{S}^1)$ to be the pullback of h^s , i.e.

$$\langle f | g \rangle_{H^s} = \langle \hat{f} | \hat{g} \rangle_{h^s} = \sum_{n=-\infty}^{+\infty} (1 + n^2)^s \hat{f}(n) \overline{\hat{g}(n)} \quad (20.41)$$

Then $H^s(\mathbb{S}^1)$ is a Hilbert space since $h^s(\mathbb{Z})$ is so. We call $H^s(\mathbb{S}^1)$ a **Sobolev space** of \mathbb{S}^1 . Thus Φ is a unitary map.

Problem 20.4. Let $k \in \mathbb{Z}_+$. Prove that $C^k(\mathbb{S}^1) \subset H^k(\mathbb{S}^1)$. Prove for each $f \in C^{2k}(\mathbb{S}^1), g \in H^k(\mathbb{S}^1)$ that

$$\langle f | g \rangle_{H^k} = \frac{1}{2\pi} \int_{-\pi}^{\pi} (1 - \partial^2)^k f \cdot g^* \quad (20.42)$$

where $\partial f = f'$.

Hint. For each $f \in C^k(\mathbb{S}^1)$, prove by induction on k that

$$\widehat{f^{(k)}}(n) = (in)^k \hat{f}(n) \quad (20.43)$$

Apply Parseval's identity to $\int |f^{(k)}|^2$ and to the RHS of (20.42). \square

As an application, we obtain a useful criterion for the uniform convergence of Fourier series:

Corollary 20.44. *If $f \in C^1(\mathbb{S}^1)$, then $\sum_{n \in \mathbb{Z}} \hat{f}(n) e_n$ converges uniformly to f .*

Proof. By Pb. 20.4 and (20.39), we have $f \in C^1(\mathbb{S}^1) \subset H^1(\mathbb{S}^1) \subset \Phi^{-1}(l^1(\mathbb{Z}))$. Since $\hat{f} = \Phi(f)$ and hence $f = \Phi^{-1}(\hat{f})$, by Pb. 20.2 (the description of Φ^{-1} on $l^1(\mathbb{Z})$), $\sum_{n \in \mathbb{Z}} \hat{f}(n) e_n$ converges uniformly to f . \square

Theorem 20.45. *Let $k \in \mathbb{Z}_+$. Then $H^k(\mathbb{S}^1)$ is the Hilbert space completion of $C^\infty(\mathbb{S}^1)$ under the inner product defined by (20.42) for all $f, g \in C^\infty(\mathbb{S}^1)$.*

Proof. Equip $C^\infty(\mathbb{S}^1)$ with the inner product defined by (20.42). We know that

$$\Phi : C^\infty(\mathbb{S}^1) \rightarrow h^k(\mathbb{Z}) \quad f \mapsto \hat{f} \quad (20.44)$$

is a linear isometry. Since $\Phi(e_n) = \delta_{\{n\}}$, the range of Φ contains $\text{Span}\{\chi_{\{n\}} : n \in \mathbb{Z}\}$. From this it follows easily that the range is dense in $h^k(\mathbb{Z})$. Thus, Φ gives a completion of $C^\infty(\mathbb{S}^1)$. This is equivalent to saying that the inclusion map $C^\infty(\mathbb{S}^1) \hookrightarrow H^k(\mathbb{S}^1)$ is a completion of $C^\infty(\mathbb{S}^1)$ (since (20.44) extends to a unitary map $\Phi : H^k(\mathbb{S}^1) \rightarrow h^k(\mathbb{Z})$). \square

Problem 20.5. Suppose that $s > \frac{3}{2}$. Prove that the map of derivative $\partial : C^1(\mathbb{S}^1) \rightarrow C(\mathbb{S}^1)$, $f \mapsto f'$ restricts to

$$\partial : H^s(\mathbb{S}^1) \rightarrow H^{s-1}(\mathbb{S}^1) \quad (20.45)$$

(Namely, each $f \in H^s(\mathbb{S}^1)$ is differentiable, and has derivative in $H^{s-1}(\mathbb{S}^1)$.) Prove for each $f \in H^s(\mathbb{S}^1)$ that

$$\Phi(f')(n) = \text{in} \hat{f}(n) \quad (20.46)$$

Hint. By Pb. 20.2, we have uniform convergence $f = \sum_{n \in \mathbb{Z}} \hat{f}(n)e_n$ where $\hat{f} \in h^s(\mathbb{Z})$. Show that $\sum_{n \in \mathbb{Z}} \text{in} \hat{f}(n)e_n$ converges uniformly. Then use Thm. 11.33. \square

Theorem 20.46 (Sobolev embedding). If $s > \frac{1}{2}$, then $H^s(\mathbb{S}^1) \subset C^{\lceil s - \frac{3}{2} \rceil}(\mathbb{S}^1)$ where $\lceil s - \frac{3}{2} \rceil$ is the smallest integer $\geq s - \frac{3}{2}$.

Proof. Choose $f \in H^s(\mathbb{S}^1)$. By (20.39) we have $f \in C(\mathbb{S}^1)$. Thus the theorem is proved when $\frac{1}{2} < s \leq \frac{3}{2}$. Suppose that $s > \frac{3}{2}$. Let $k = \lceil s - \frac{3}{2} \rceil$. Then $\frac{1}{2} < s - k \leq \frac{3}{2}$. By Pb. 20.5, we have $f' \in H^{s-1}(\mathbb{S}^1)$, $f'' \in H^{s-2}(\mathbb{S}^1)$, \dots , and hence $f^{(k)} \in H^{s-k}(\mathbb{S}^1) \subset C(\mathbb{S}^1)$. This proves $f \in C^k(\mathbb{S}^1)$. \square

Corollary 20.47. We have $C^\infty(\mathbb{S}^1) = \bigcap_{k \in \mathbb{Z}_+} H^k(\mathbb{S}^1) = \bigcap_{s > \frac{1}{2}} H^s(\mathbb{S}^1)$.

Proof. By Pb. 20.4, Thm. 20.46, and the fact that $H^s(\mathbb{S}^1)$ decreases as s increases. \square

21 Hilbert spaces

Definition 21.1. An inner product space \mathcal{H} is called a **Hilbert space** if it is complete under the norm defined by $\|\xi\| = \sqrt{\langle \xi | \xi \rangle}$.

Remark 21.2. Let \mathcal{H} be a Hilbert space. Since a subset of a complete metric space is complete iff it is closed (Prop. 3.27), the phrases “closed linear subspaces of \mathcal{H} ” and “Hilbert subspaces of \mathcal{H} ” are synonymous.

Example 21.3. If \mathcal{H} is a finite-dimensional inner product space, then \mathcal{H} is a Hilbert space.

Proof. Since \mathcal{H} is spanned by finitely many vectors, by Gram-Schmidt process, \mathcal{H} has an orthonormal basis $(e_x)_{x \in X}$ where X is a finite set. The canonical linear isometry $\Phi : \mathcal{H} \rightarrow l^2(X)$ in Cor. 20.38 must be surjective. So $\mathcal{H} \simeq l^2(X)$. Hence \mathcal{H} is complete. \square

Theorem 21.4. Let V be an inner product space. Then V has a **Hilbert space completion**, i.e., a Hilbert space \mathcal{H} and a linear isometry $\Phi : V \rightarrow \mathcal{H}$ with dense range.

Moreover, Hilbert space completions are unique up to unitary equivalences: If $\Psi : V \rightarrow \mathcal{K}$ is another Hilbert space completion, then there is a unitary $\Gamma : \mathcal{H} \rightarrow \mathcal{K}$ such that the following diagram commutes:

$$\begin{array}{ccc} & V & \\ \Phi \swarrow & & \searrow \Psi \\ \mathcal{H} & \xrightarrow[\simeq]{\Gamma} & \mathcal{K} \end{array} \quad (21.1)$$

When no confusion arises, we identify V with $\Phi(V)$ so that V can be viewed as a dense inner product subspace of \mathcal{H} .

Proof. Since V is a normed vector space, by Thm. 10.19, we have a Banach space \mathcal{H} (with norm $\|\cdot\|_{\mathcal{H}}$) and a linear isometry $\Phi : V \rightarrow \mathcal{H}$ with dense range. We assume WLOG that V is a normed vector subspace of \mathcal{H} so that the norm $\|\cdot\|_{\mathcal{H}}$ restricts to that of V . Define a function $\langle \cdot | \cdot \rangle_{\mathcal{H}} : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{C}$ using the polarization identity (20.3), i.e., for each $\xi, \eta \in \mathcal{H}$ we set

$$\langle \xi | \eta \rangle_{\mathcal{H}} = \frac{1}{4} \sum_{t=0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}} \|\xi + e^{it}\eta\|_{\mathcal{H}}^2 \cdot e^{-it}$$

Then $\langle \cdot | \cdot \rangle_{\mathcal{H}}$ restricts to the inner product $\langle \cdot | \cdot \rangle$ of V . Moreover, the function $\langle \cdot | \cdot \rangle_{\mathcal{H}}$ is continuous (with respect to the norm $\|\cdot\|_{\mathcal{H}}$), and $V \times V$ is a dense subset of $\mathcal{H} \times \mathcal{H}$. Therefore, as in the proof of Thm. 10.19, we can use the fact that $\langle \cdot | \cdot \rangle$ is an inner product on V to prove that $\langle \cdot | \cdot \rangle_{\mathcal{H}}$ is a positive sesquilinear form on \mathcal{H} , and we can use the fact that the norm of V is defined by the inner product of V to prove that

$\|\xi\|_{\mathcal{H}}^2 = \langle \xi | \xi \rangle_{\mathcal{H}}$. Therefore, $\langle \cdot | \cdot \rangle_{\mathcal{H}}$ is non-degenerate, i.e., an inner product, and this inner product defines the complete norm $\|\cdot\|_{\mathcal{H}}$. It follows that \mathcal{H} is a Hilbert space, and hence a Hilbert space completion of V .

The uniqueness of Hilbert space completions (up to unitary equivalences) follows directly from that of Banach space completions, cf. Thm. 10.19. \square

21.1 Introduction: completeness, the most familiar stranger

What is familiar is what we are used to; and what we are used to is most difficult to “know”—that is, to see as a problem; that is, to see as strange, as distant, as “outside us”.

— Friedrich Nietzsche (cf. [Nie, Sec. 355])

We introduced completeness at the beginning of last semester and applied it to function spaces. It has allowed us to give a unified understanding of many analytic problems, especially those related to uniform convergence: the uniform convergence of series of functions, the commutativity of two limit processes and its relationship with uniform convergence, etc.. In fact, the vast majority of Banach spaces we considered last semester were defined by the l^∞ -norm.

From this perspective, it is perfectly natural to consider completeness for inner product spaces. However, we refuse to take lightly the consideration of completeness as natural for the following reasons:

- The notion of completeness was originally applied only to \mathbb{R} . Historically, however, the idea of applying completeness to function spaces was not entirely inspired by the study of uniform convergence, since uniform convergence is not too far from pointwise convergence.¹ The apparently successful application of l^∞ -completeness to the problems of uniform convergence does not justify the *a priori* value of completeness in the study of other norms (such as the L^2 -norm).²
- For inner product spaces, some analytic properties are equivalent to completeness. The most important one is the weak (or weak-*) compactness of the unit ball.³ The main reason that the Hilbert space $l^2(\mathbb{Z})$ was introduced in history by Hilbert is due to this compactness rather than completeness.

¹As a matter of fact, most results learned in the last semester can be formulated and proved without introducing completeness to function spaces, as implied by history and by many analysis textbooks.

²That l^∞ and L^2 are both called “norms” is a *result*, not a starting point, of the observation in history that different types of problems can be treated in a similar fashion.

³We have learned that $l^2(X)$ satisfies this property due to $l^2(X) \simeq l^2(X)^*$ (cf. Thm. 17.30) and Banach-Alaoglu, or more directly, by Pb. 17.5.

As I will explain below, the Hilbert space techniques based on completeness were developed much later: F. Riesz made the first systematic use of completeness with the help of his novel (at his time) idea of operator norms.

21.1.1 The late-coming concept of completeness

The modern definition of Hilbert spaces as complete inner product spaces was due to von Neumann [vNeu30] in late 1920s, many years after the introduction of $l^2(\mathbb{Z})$ by Hilbert and Schmidt (same person as the Schmidt in the Gram-Schmidt process!⁴) to the study of integral equations in 1900s. We will see in this chapter that all separable Hilbert spaces are isomorphic to \mathbb{C}^N or $l^2(\mathbb{Z})$, and that all Hilbert spaces are isomorphic to $l^2(X)$. Therefore, one can equivalently define a Hilbert space to be an inner product space isomorphic to $l^2(X)$ for some set X . This is indeed closer to how people originally understood Hilbert spaces than the modern definition.

As opposed to 1900s, by the time von Neumann gave Def. 21.1, the importance of completeness in function spaces was fully recognized. One of the most important contributors to this change of ideas is F. Riesz, who applied the completeness of function spaces to the study of the following problems in 1910s:

- (a) The completeness of $\mathfrak{L}(l^2(\mathbb{Z}))$ (relying on the completeness of $l^2(\mathbb{Z})$) makes possible the technique of continuous functional calculus and its application to the problem of diagonalizing self-adjoint operators on $l^2(\mathbb{Z})$. See Sec. 17.6 and 17.7.
- (b) The study of eigenvalue problems of compact operators between Banach spaces such as $C(X)$, $l^p(X)$, $L^p(X)$, generalizing Hilbert-Schmidt's results on the Hilbert space $l^2(\mathbb{Z})$.

Of course, the second problem is a mixture of completeness and compactness. We will not study the second problem in this course. (But see Sec. 22.7 for a discussion of how the notion of compact operators evolved from Hilbert's original definition of completely continuous forms during Riesz's study of problem (b).) However, to show you at least one application of completeness to l^2 and L^2 norms, we will discuss the first problem in the middle of this semester. (Surprisingly, as we will see, the first problem is also related to the moment problems.)

21.1.2 Scalar-valued functions vs. vector-valued functions, compactness vs. completeness, Hilbert vs. Riesz

It is worth noting that the idea of completeness in function spaces (especially under the L^2 and l^2 norms) is related to the recognition of the importance of study-

⁴Thus, the discovery of Gram-Schmidt process is not only for the purpose of solving linear algebra problems. It has a deep background in analysis.

ing linear maps between function spaces. Given inner product spaces U, V , a bounded linear map $T : U \rightarrow V$ can also be viewed as a continuous sesquilinear map

$$\omega_T : U \times V \rightarrow \mathbb{C} \quad (u, v) \mapsto \langle Tu|v \rangle \quad (21.2)$$

In the special case that $U = V$, T can be viewed as a continuous **quadratic form**

$$V \times V \rightarrow \mathbb{C} \quad v \mapsto \langle Tv|v \rangle \quad (21.3)$$

(Note that (21.3) completely determines (21.2) by the polarization identity (Prop. 20.3), and hence determines T .) This viewpoint, insisting on the study of scalar-valued functions, was held by people before Riesz, especially by Hilbert (and his students).

In Hilbert's scalar-valued function viewpoint, completeness plays a very marginal role (with very few exceptions, see Rem. 21.41), and emphasis was put on the compactness. To empathize with this phenomenon, compare it with the equivalence $C(X, C(Y)) \simeq C(X \times Y)$ in Thm. 9.3 (where Y is compact): If we take the viewpoint of $C(X \times Y)$, we put more emphasis on the compactness of Y . However, if we take the viewpoint of $C(X, C(Y))$, we view $C(Y)$ as an abstract Banach space V . Therefore, we forget about the compactness of Y and focus on the completeness of V .

Riesz's systematic use of the completeness of l^2 and L^2 spaces goes hand in hand with his emphasis on the viewpoint of vector-valued functions. Thus, the following three ideas were intertwined in Riesz's hands:

- (1) The completeness of function spaces.
- (2) The study of linear maps between function spaces $U \rightarrow V$, as opposed to the study of scalar-valued functions on $U \times V$.
- (3) The operator norm on $\mathfrak{L}(U, V)$.

We have mentioned the relationship between (1) and (3) in Sec. 17.6 and 17.7. Here, let me briefly explain why (1) and (2) are related by recalling two fundamental facts learned before:

Suppose that U, V are normed vector spaces and U_0 is a dense linear subspace of U . To extend a bounded linear map $T : U_0 \rightarrow V$ to a bounded linear $U \rightarrow V$, one needs the completeness of V . (Cf. Prop. 10.28.) Given a net of bounded linear maps (T_α) from U to V satisfying $\sup_\alpha \|T_\alpha\| < +\infty$, to show that the pointwise convergence of (T_α) on U_0 implies the pointwise convergence on U , one also needs the completeness of V . (Cf. Prop. 17.19.)

21.2 Key property 1: convergence of summing orthogonal vectors

In this section, we fix a Hilbert space \mathcal{H} .

Hilbert and Schmidt introduced $l^2(\mathbb{Z})$ to the study of integral equations. As we have mentioned, the main interesting analytic property for them is not completeness. Indeed, they mainly used the following conditions, both equivalent to the completeness:

1. If $\sum_i |a_i|^2 < +\infty$ and if $(e_i)_{i \in I}$ is orthonormal, then $\sum a_i e_i$ converges.
2. The weak(-*) compactness of the closed unit ball.

(We will show the equivalence in Thm. 21.5 and Cor. 21.34.) In this section, we study the first property. The second property will be studied in the next section. The first property is indeed a direct consequence of the second one; see Thm. 21.33. Thus, one may also say that the second property is the main analytic property used by Hilbert and Schmidt. In the next chapter, we will see how these two properties are used to study integral equations.

Theorem 21.5. *Let V be an inner product space. The following are equivalent.*

- (1) V is complete.
- (2) For each orthonormal family $(e_i)_{i \in I}$ in V , and for each $(a_i)_{i \in I}$ in \mathbb{C} satisfying $\sum_{i \in I} |a_i|^2 < +\infty$, the discrete integral $\sum_{i \in I} a_i e_i$ converges (under the norm of V).
- (3) V is isomorphic to $l^2(X)$ for some X .

Proof. (3) \Rightarrow (1): This is because $l^2(X)$ is complete, cf. Thm. 12.32.

(1) \Rightarrow (2): Since $\sum_i |a_i|^2 < +\infty$, by Rem. 5.43, for each $\varepsilon > 0$ there exists $J \in \text{fin}(2^I)$ such that for all finite $K \subset I \setminus J$ we have $\sum_{k \in K} |a_k|^2 < \varepsilon$, and hence, by the Pythagorean identity,

$$\left\| \sum_{k \in K} a_k e_k \right\|^2 = \sum_{k \in K} |a_k e_k|^2 < \varepsilon$$

By Rem. 5.43 again and the completeness of V , we see that $\sum_{i \in I} a_i e_i$ converges.

(2) \Rightarrow (3): Assume (2). We first show that V has an orthonormal basis. By Zorn's lemma, we can find a maximal (with respect to the partial order \subset) set of orthonormal vectors, written as a family $(e_i)_{i \in I}$. The maximality implies that every nonzero vector $\xi \in V$ is not orthogonal to some e_i . (Otherwise, $\{e_i : i \in I\}$ can be extended to $\{e_i : i \in I\} \cup \{\xi/\|\xi\|\}$.)

Let us prove that $(e_i)_{i \in I}$ is an orthonormal basis. Suppose not. Then $U = \text{Span}\{e_i : i \in I\}$ is not dense in X . Let $\xi \in X \setminus \overline{U}$. By Bessel's inequality, we have

$$\sum_{i \in I} |\langle \xi | e_i \rangle|^2 < +\infty$$

Therefore, by (2),

$$\sum_{i \in I} \langle \xi | e_i \rangle \cdot e_i \quad (21.4)$$

converges to some vector $\eta \in V$. By the continuity of $\langle \cdot | \cdot \rangle$, we see that $\langle \eta | e_i \rangle = \langle \xi | e_i \rangle$ for all i , and hence

$$\langle \xi - \eta | e_i \rangle = 0 \quad \text{for all } i \in I \quad (21.5)$$

Since $\eta \in \overline{U}$ and $\xi \notin \overline{U}$, we conclude that $\xi - \eta$ is a nonzero vector orthogonal to all e_i . This contradicts the maximality of $(e_i)_{i \in I}$.

Now we have an orthonormal basis $(e_i)_{i \in I}$. By Cor. 20.38, we have a linear isometry

$$\Phi : V \rightarrow l^2(I) \quad \xi \mapsto (\langle \xi | e_i \rangle)_{i \in I}$$

with dense range. If $(a_i)_{i \in I}$ belongs to $l^2(I)$, by (2), the discrete integral $\sum_{i \in I} a_i e_i$ converges to some $\xi \in V$. Clearly $\Phi(\xi) = (a_i)_{i \in I}$. This proves that Φ is surjective, and hence is a unitary map. So $V \simeq l^2(I)$. \square

Condition (2) of Thm. 21.5 is the main subject of this section. From the above proof, we see that this condition is an easy special case of the completeness. This special case is often sufficient for applications without fully utilizing the completeness of $l^2(\mathbb{Z})$. (To understand how nontrivial the direction (2) \Rightarrow (1) is even in the separable case, try to give a direct proof of it!)

In the following, we show that many well-known properties about Hilbert spaces follow Thm. 21.5-(2). Recall that we have fixed a Hilbert space \mathcal{H} .

Corollary 21.6. *\mathcal{H} has an orthonormal basis. Moreover, \mathcal{H} is separable iff the orthonormal basis can be chosen to be countable.*

Proof. That \mathcal{H} has an orthonormal basis follows from the proof of Thm. 21.5 or from the fact that $l^2(X)$ has an orthonormal basis $(\chi_{\{x\}})_{x \in X}$. If X is countable, then $l^2(X)$ has dense subset $\text{Span}_{\mathbb{Q} + i\mathbb{Q}}\{\chi_{\{x\}} : x \in X\}$ (by Lem. 17.28) and hence is separable. Conversely, we have proved in Exp. 20.34 that every separable inner product space has a countable orthonormal basis. \square

Theorem 21.7. *Let $(e_x)_{x \in X}$ be an orthonormal basis of \mathcal{H} . Then we have a unitary map*

$$\mathcal{H} \xrightarrow{\simeq} l^2(X) \quad \xi \mapsto (\langle \xi | e_x \rangle)_{x \in X} \quad (21.6)$$

Proof. This is clear from the proof of Thm. 21.5. \square

Definition 21.8. If \mathcal{K} is a linear subspace of \mathcal{H} , we define its **orthogonal complement**

$$\mathcal{K}^\perp = \{\xi \in \mathcal{H} : \langle \xi | \eta \rangle = 0 \text{ for all } \eta \in \mathcal{K}\}$$

It is clear that

$$\mathcal{K}^\perp = \overline{\mathcal{K}}^\perp \quad (21.7)$$

Proof of (21.7). If $\xi \in \mathcal{H}$ is orthogonal to $\overline{\mathcal{K}}$, then ξ is clearly orthogonal to \mathcal{K} . Conversely, if ξ is orthogonal to \mathcal{K} , the continuity of $\eta \in \mathcal{H} \mapsto \langle \xi | \eta \rangle$ implies that $\xi \perp \overline{\mathcal{K}}$. \square

Definition 21.9. Let $\mathcal{H}_1, \mathcal{H}_2$ be Hilbert spaces. Consider the direct sum of vector spaces $\mathcal{H}_1 \oplus \mathcal{H}_2$. Namely, $\mathcal{H}_1 \oplus \mathcal{H}_2$ equals $\mathcal{H}_1 \times \mathcal{H}_2$ as a set, (ξ, η) is also written as $\xi \oplus \eta$, and the linear structure is defined by $(\xi \oplus \eta) + (\xi' \oplus \eta') = (\xi + \xi') \oplus (\eta + \eta')$ and $\lambda(\xi \oplus \eta) = \lambda\xi \oplus \lambda\eta$ (where $\xi, \xi' \in \mathcal{H}_1, \eta, \eta' \in \mathcal{H}_2, \lambda \in \mathbb{C}$), and the zero vector is $0 \oplus 0$. Equip $\mathcal{H}_1 \oplus \mathcal{H}_2$ with inner product defined by

$$\langle \xi \oplus \eta | \xi' \oplus \eta' \rangle = \langle \xi | \xi' \rangle \oplus \langle \eta | \eta' \rangle$$

Then $\mathcal{H}_1 \oplus \mathcal{H}_2$ is clearly a Hilbert space. We call $\mathcal{H}_1 \oplus \mathcal{H}_2$ the **(Hilbert space) direct sum** of $\mathcal{H}_1, \mathcal{H}_2$.

Remark 21.10. In Def. 21.9, we clearly have linear isometries

$$\begin{aligned} \mathcal{H}_1 &\rightarrow \mathcal{H}_1 \oplus \mathcal{H}_2 & \xi &\mapsto \xi \oplus 0 \\ \mathcal{H}_2 &\rightarrow \mathcal{H}_1 \oplus \mathcal{H}_2 & \eta &\mapsto 0 \oplus \eta \end{aligned}$$

with ranges $\mathcal{H}_1 \oplus 0$ and $0 \oplus \mathcal{H}_2$ respectively. It is clear that $\mathcal{H}_1 \oplus 0$ and $0 \oplus \mathcal{H}_2$ are orthogonal complements of each other. We often identify \mathcal{H}_1 with $\mathcal{H}_1 \oplus 0$ and \mathcal{H}_2 with $0 \oplus \mathcal{H}_2$. Then \mathcal{H}_1 and \mathcal{H}_2 are Hilbert subspaces of $\mathcal{H}_1 \oplus \mathcal{H}_2$, and are orthogonal complements of each other.

Theorem 21.11. Let \mathcal{K} be a closed linear subspace of \mathcal{H} . Note that \mathcal{K} and \mathcal{K}^\perp are both Hilbert subspaces of \mathcal{H} . Then there is a unitary map

$$\Psi : \mathcal{K} \oplus \mathcal{K}^\perp \xrightarrow{\cong} \mathcal{H} \quad \xi \oplus \eta \mapsto \xi + \eta \quad (21.8)$$

Proof. It is a routine check that Ψ is a linear isometry. It remains to prove that Ψ is surjective. This means that we need to write each $\psi \in \mathcal{H}$ in the form $\psi = \xi + \eta$ where $\xi \in \mathcal{K}, \eta \in \mathcal{K}^\perp$. Thus, the surjectivity of Ψ means that every $\psi \in \mathcal{H}$ has an orthogonal decomposition with respect to \mathcal{K} (recall Def. 20.28).

Let $\psi \in \mathcal{H}$. By Cor. 21.6, \mathcal{K} has an orthonormal basis $(e_i)_{i \in I}$. As in the proof of (2) \Rightarrow (3) of Thm. 21.5, Bessel's inequality implies that $\sum_{i \in I} \langle \psi | e_i \rangle \cdot e_i$ converges to some vector $\xi \in \mathcal{K}$. Then one checks easily that $\eta = \psi - \xi$ is orthogonal to all e_i , and hence is orthogonal to $\mathcal{K}_0 = \text{Span}\{e_i : i \in I\}$. Thus $\eta \perp \mathcal{K}$ by (21.7). \square

Remark 21.12. Due to Thm. 21.11, given a Hilbert subspace \mathcal{K} , people often write

$$\mathcal{H} = \mathcal{K} \oplus \mathcal{K}^\perp \quad (21.9)$$

Corollary 21.13. *Let \mathcal{K} be a closed linear subspace of \mathcal{H} . Then every vector $\psi \in \mathcal{H}$ has an orthogonal decomposition with respect to \mathcal{K} . Moreover, we have $(\mathcal{K}^\perp)^\perp = \mathcal{K}$.*

Proof. The existence of the orthogonal decomposition follows from Thm. 21.11. Clearly $\mathcal{K} \subset (\mathcal{K}^\perp)^\perp$. By Thm. 21.11 (applied to \mathcal{K}^\perp instead of \mathcal{K}), there is a unitary $\mathcal{K}^\perp \oplus (\mathcal{K}^\perp)^\perp \rightarrow \mathcal{H}$ sending $\eta \oplus \xi \mapsto \eta + \xi$, and hence a unitary $\Gamma : (\mathcal{K}^\perp)^\perp \oplus \mathcal{K}^\perp \rightarrow \mathcal{H}$ sending $\xi \oplus \eta \mapsto \xi + \eta$. By Thm. 21.11 again, Γ restricts to the unitary map $\Psi = (21.8)$. So we must have $(\mathcal{K}^\perp)^\perp \oplus \mathcal{K}^\perp = \mathcal{K} \oplus \mathcal{K}^\perp$, and hence $\mathcal{K} = (\mathcal{K}^\perp)^\perp$. \square

Corollary 21.14. *Let V be a linear subspace of \mathcal{H} . Then V is dense iff the only vector of \mathcal{H} orthogonal to V is 0.*

This corollary gives a useful criterion for the density of linear subspaces.

Proof. Cor. 21.13 implies for every closed linear subspaces $\mathcal{K}_1, \mathcal{K}_2$ that

$$\mathcal{K}_1 = \mathcal{K}_2 \iff \mathcal{K}_1^\perp = \mathcal{K}_2^\perp \quad (21.10)$$

Therefore $\overline{V} = \mathcal{H}$ iff $\overline{V}^\perp = \mathcal{H}^\perp = 0$ iff (by (21.7)) $V^\perp = 0$. \square

Remark 21.15. The existence of orthogonal decompositions with respect to closed linear subspaces (Thm. 21.11 or Cor. 21.13) is a key feature of Hilbert spaces that is not satisfied by general inner product spaces. A different (and fancier) proof can be found in many textbooks which proves the existence of the orthogonal decomposition $\psi = \xi + \eta$ by defining ξ to be the vector in \mathcal{K} such that $\|\psi - \xi\|$ attains its minimum: the existence of such ξ relies on the completeness of \mathcal{H} and the parallelogram law

$$\|u + v\|^2 + \|u - v\|^2 = 2\|u\|^2 + 2\|v\|^2 \quad (21.11)$$

cf. [Fol-R, Thm. 5.24] or [Rud-R, Thm. 4.11] for instance.⁵

The proof we give here is closer to Schmidt's method in that we used the Gram-Schmidt process instead of the parallelogram law. With this proof, we want to convey the idea that the existence of orthogonal decompositions is a direct consequence of the convergence of summing orthogonal vectors (condition (2) of Thm. 21.5). \square

⁵The proof of the existence of this minimizing ξ makes use of the convexity of \mathcal{K} and thus holds for \mathcal{K} being an arbitrary closed convex subset. Convexity in Banach spaces is a very important topic, but its importance was not realized until long after the birth of Hilbert spaces and much of F. Riesz's work. We believe that introducing convexity (even if secretly introduced) at the first encounter with Hilbert spaces is off-topic and distracting, because it hinders the understanding of the roles played by the other central properties in Hilbert spaces, especially the analytic properties.

21.3 Key property 2: weak(-*) compactness of the closed unit balls

We fix Hilbert spaces \mathcal{H}, \mathcal{K} in this section.

Lemma 21.16. *For each $\xi \in \mathcal{H}$, we have*

$$\|\xi\| = \sup_{\eta \in \overline{B}_{\mathcal{H}}(0,1)} |\langle \xi | \eta \rangle| \quad (21.12)$$

Proof. Clearly “ \geq ” holds by Cauchy-Schwarz. To prove “ \leq ”, assume WLOG that $\xi \neq 0$. Then $\|\xi\| = \langle \xi | \eta \rangle$ if we choose $\eta = \xi / \|\xi\|$. \square

Recall that if $T : V \rightarrow W$ is a linear map of normed vector spaces, its operator norm is $\|T\| = \sup_{v \in \overline{B}_V(0,1)} \|Tv\|$. Operator norms describe uniform convergence on $\overline{B}_V(0,1)$: If (T_α) is a net of bounded linear operators $V \rightarrow W$, then $\lim_\alpha \|T - T_\alpha\| = 0$ iff T_α converges uniformly on $\overline{B}_V(0,1)$ to T .

We now show that in the case of Hilbert spaces, the operator norms of linear maps can be translated to certain upper bounds about sesquilinear forms, which are closer in spirit to Hilbert’s original understanding of “boundedness” (cf. Pb. 21.7 and Rem. 21.38).

Proposition 21.17. *Let $T : \mathcal{H} \rightarrow \mathcal{K}$ be a linear map. Then*

$$\|T\| = \sup_{\substack{\xi \in \overline{B}_{\mathcal{H}}(0,1) \\ \eta \in \overline{B}_{\mathcal{K}}(0,1)}} |\langle T\xi | \eta \rangle| \quad (21.13)$$

Proof. By Lem. 21.16, the RHS of (21.13) equals $\sup_{\xi \in \overline{B}_{\mathcal{H}}(0,1)} \|T\xi\| = \|T\|$. \square

Corollary 21.18. *Let $T : \mathcal{H} \rightarrow \mathcal{K}$, and let (T_α) be a net of linear maps $\mathcal{H} \rightarrow \mathcal{K}$. Define their associated sesquilinear maps $\omega_T, \omega_{T_\alpha} : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C}$ by*

$$\omega_T(\xi | \eta) = \langle T\xi | \eta \rangle \quad \omega_{T_\alpha}(\xi | \eta) = \langle T_\alpha \xi | \eta \rangle \quad (21.14)$$

Then $\lim_\alpha \|T - T_\alpha\| = 0$ iff (ω_{T_α}) converges uniformly on $\overline{B}_{\mathcal{H}}(0,1) \times \overline{B}_{\mathcal{K}}(0,1)$ to ω_T .

21.3.1 Weak topology

We know that, contrary to the norm topology, the weak-* topology describes pointwise convergence. Let us recall several basic facts about weak-* topology.

Recall from Def. 17.18 that if V is a normed vector space, the weak-* topology of V^* is the unique topology such that a net (φ_α) in V^* converges to φ under this topology iff $\lim_\alpha \langle \varphi_\alpha, v \rangle = \langle \varphi, v \rangle$ for all $v \in V$. It is more important to study the weak-* topology on $\overline{B}_{V^*}(0,1)$ (or on any bounded closed ball of V^*): By Banach-Alaoglu Thm. 17.21, the closed unit ball $\overline{B}_{V^*}(0,1)$ is weak-* compact. Moreover, the following elementary fact allows for a flexible characterization of weak-* topology:

Lemma 21.19. *Let V be a normed vector space. Assume that $E \subset V$ spans a dense subspace of V . Let (φ_α) be a net in $\overline{B}_{V^*}(0, 1)$, and let $\varphi \in \overline{B}_{V^*}(0, 1)$. Then (φ_α) converges weak-* to φ iff $\lim_\alpha \langle \varphi_\alpha, v \rangle = \langle \varphi, v \rangle$ for all $v \in E$.*

Proof. Immediate from Prop. 17.19. □

The most relevant example of this chapter is $l^2(X)$, which can be viewed as the dual space of $l^2(X)$ through the Banach space isomorphism (cf. Thm. 17.30)

$$\Psi : l^2(X) \rightarrow l^2(X)^* \quad f \mapsto \langle \cdot | f^* \rangle \quad (21.15)$$

(Recall that $f^*(x) = \overline{f(x)}$. So $\langle g | f^* \rangle = \sum_{x \in X} f(x)g(x)$.) In this case, one can choose $E = \{\chi_{\{x\}} : x \in X\}$. Then Lem. 21.19 says that for any net (f_α) in $l^2(X)$ satisfying $\|f_\alpha\|_{l^2} \leq 1$ and any $f \in l^2(X)$ satisfying $\|f\|_{l^2} \leq 1$,

$$f_\alpha \xrightarrow{\text{weak-}^*} f \quad \Longleftrightarrow \quad \lim_\alpha f_\alpha(x) = f(x) \text{ for all } x \in X \quad (21.16)$$

This is the content Thm. 17.31. In view of (21.16), the Banach-Alaoglu for $l^2(X)$ says that any net (f_α) in $\overline{B}_{l^2(X)}(0, 1)$ has a subnet converging pointwise on X to some $f \in \overline{B}_{l^2(X)}(0, 1)$, which can be checked directly using the Tychonoff theorem. (You were asked to give this direct proof in Pb. 17.5.)

It should be kept in mind that whenever talking about the weak-* topology on a Banach space V , we should specify a normed vector space U and an isomorphism of Banach spaces $\Psi : V \rightarrow U^*$ so that V can be viewed as a dual Banach space. The data (Ψ, U) (or simply written as U) is called a **predual** of V . It is customary to write a predual U of V as V_* .

Since we know that every Hilbert space \mathcal{H} is isomorphic to $l^2(X)$ for some X , the isomorphism (21.15) suggests that we can talk about the weak-* topology of \mathcal{H} , which should be the unique topology whose convergence $\xi_\alpha \rightarrow \xi$ means that $\langle \xi_\alpha | \eta \rangle \rightarrow \langle \xi | \eta \rangle$ for all η . However, calling this topology a weak-* topology is confusing. In fact, there is no standard choice of isomorphism $\mathcal{H} \rightarrow \mathcal{H}^*$. The isomorphism (21.15) relies on the antiunitary map $f \mapsto f^*$.

Definition 21.20. A linear map of inner product spaces $T : U \rightarrow V$ is called **antiunitary** if it is an antilinear surjective isometry.

There is no canonical antiunitary operator on a Hilbert space: any antiunitary operator, composed with a unitary one, is again antiunitary. However, we do have a canonical antiunitary map $\mathcal{H} \rightarrow \mathcal{H}^*$:

Theorem 21.21 (Riesz-Fréchet representation theorem). *For any Hilbert space \mathcal{H} , the (operator) norm of the dual Banach space \mathcal{H}^* is induced by a unique inner product. (So \mathcal{H}^* is a Hilbert space.) Moreover, we have an antiunitary map*

$$\Phi : \mathcal{H} \rightarrow \mathcal{H}^* \quad \xi \mapsto \langle \cdot | \xi \rangle \quad (21.17)$$

Proof. Define a linear map Φ by (21.17). By Thm. 21.5-(3), we assume WLOG that $\mathcal{H} = l^2(X)$. Then Φ is related to the Banach space isomorphism (21.15) by $\Phi(\xi) = \Psi(\xi^*)$. Since $\xi \mapsto \xi^*$ is antiunitary, Φ must be an antilinear surjective isometry. Define an inner product on \mathcal{H}^* by

$$\langle \varphi | \mu \rangle = \langle \Phi^{-1} \mu | \Phi^{-1} \psi \rangle \quad (\forall \varphi, \mu \in \mathcal{H}^*) \quad (21.18)$$

Then this inner product induces the operator norm $\| \cdot \|$ on \mathcal{H}^* because

$$\| \varphi \|^2 = \| \Phi^{-1} \varphi \|^2 = \langle \Phi^{-1} \varphi | \Phi^{-1} \varphi \rangle = \langle \varphi | \varphi \rangle$$

where the first identity is due to the fact that Φ is an isometry. The uniqueness of the inner product follows from the polarization identity (20.3). \square

Recall that any linear map $T : \mathcal{H} \rightarrow \mathcal{K}$ is determined by the expressions $\langle T\xi | \eta \rangle$.

Corollary 21.22. *For every $T \in \mathcal{L}(\mathcal{H}, \mathcal{K})$ there is a unique bounded linear map $T^* : \mathcal{K} \rightarrow \mathcal{H}$ (called the **adjoint** of T) satisfying for all $\xi \in \mathcal{H}, \eta \in \mathcal{K}$ that*

$$\langle T\xi | \eta \rangle = \langle \xi | T^* \eta \rangle \quad (21.19)$$

Moreover, we have $\|T\| = \|T^*\|$, and $(T^*)^* = T$.

Proof. For each $\eta \in \mathcal{K}$, the linear map $\xi \in \mathcal{H} \mapsto \langle T\xi | \eta \rangle \in \mathbb{C}$ is bounded since $|\langle T\xi | \eta \rangle| \leq \| \xi \| \cdot \| T \| \cdot \| \eta \|$. Therefore, by Riesz-Fréchet, there is a unique $\psi \in \mathcal{H}$ such that $\langle T\xi | \eta \rangle = \langle \xi | \psi \rangle$ for all $\xi \in \mathcal{H}$. We let $T^* \eta = \psi$. This gives a map $T^* : \mathcal{K} \rightarrow \mathcal{H}$ satisfying (21.19) for all $\xi \in \mathcal{H}, \eta \in \mathcal{K}$. The formula (21.19) clearly shows that T^* is linear, and that $T^{**} = T$ if T^* is bounded. That $\|T\| = \|T^*\|$ (and in particular, the boundedness of T^*) follows from Prop. 21.17. \square

★ **Exercise 21.23.** Recall that for every normed vector space V there is a canonical bounded linear map $V \rightarrow V^{**}, v \mapsto \langle v, \cdot \rangle$ which is a linear isometry by Hahn-Banach Cor. 16.6. Now let $V = \mathcal{H}$. Show that this map $\mathcal{H} \rightarrow \mathcal{H}^{**}$ is equal to the composition of the antiunitary maps $\mathcal{H} \rightarrow \mathcal{H}^*$ and $\mathcal{H}^* \rightarrow \mathcal{H}^{**}$, both defined by Riesz-Fréchet. Conclude that the canonical linear isometry $\mathcal{H} \rightarrow \mathcal{H}^{**}$ is unitary.

Hint. You may prove it in a general fashion. But the easiest way to think about this question is to assume WLOG that $\mathcal{H} = l^2(X)$. \square

According to this exercise, we can view \mathcal{H} as the dual space of \mathcal{H}^* , and talk about the weak-* topology of \mathcal{H} . Indeed, it is more customary to call it weak topology in this case:

Definition 21.24. For any normed vector space V , the **weak topology** of V is defined to be the pullback of the weak-* topology of V^{**} through the canonical linear

isometry $V \rightarrow V^{**}$. Convergence under the weak topology is called **weak convergence**. Thus, weak topology is described by the condition that for every net (v_α) in V and every $v \in V$,

$$v_\alpha \xrightarrow{\text{weakly}} v \iff \lim_\alpha \langle v_\alpha, \varphi \rangle = \langle v, \varphi \rangle \text{ for all } \varphi \in V^* \quad (21.20)$$

If (ξ_α) is a net in \mathcal{H} and $\xi \in \mathcal{H}$, then by Riesz-Fréchet,

$$\xi_\alpha \xrightarrow{\text{weakly}} \xi \iff \lim_\alpha \langle \xi_\alpha | \eta \rangle = \langle \xi | \eta \rangle \text{ for all } \eta \in \mathcal{H} \quad (21.21)$$

Remark 21.25. Assume that $1 < p, q < +\infty$ and $p^{-1} + q^{-1} = 1$. The weak-* topology on $l^p(X)$ defined by the isomorphism $l^q(X)^* \simeq l^p(X)$ in Thm. 17.30 is clearly equal to the weak topology of $l^p(X)$. Therefore:

We will not distinguish between weak topology and weak-* topology for $l^p(X)$ where $1 < p < +\infty$.

Corollary 21.26. *The closed unit ball $\overline{B}_{\mathcal{H}}(0, 1)$ of \mathcal{H} is weakly compact. Moreover, \mathcal{H} is separable iff $\overline{B}_{\mathcal{H}}(0, 1)$ is weakly metrizable.*

It follows that if \mathcal{H} is separable, then $\overline{B}_{\mathcal{H}}(0, 1)$ is sequentially compact.

Proof. By Cor. 21.6, we may assume $\mathcal{H} = l^2(X)$ where X is countable if \mathcal{H} is separable. By Banach-Alaoglu and $l^2(X) \simeq l^2(X)^*$, or by Pb. 17.5 and Thm. 17.31, $\overline{B}_{\mathcal{H}}(0, 1)$ is weakly compact. By $l^2(X) \simeq l^2(X)^*$ and Thm. 17.24, $l^2(X)$ is separable iff $\overline{B}_{l^2(X)}(0, 1)$ is metrizable under the weak(-*) topology. \square

★ **Remark 21.27.** Assume that X is countable, say, X is $\{1, 2, \dots, n\}$ or \mathbb{Z}_+ . Then explicit metrics of $\overline{B}_{l^2(X)}(0, 1)$ can be found, e.g., d and δ defined by

$$d(f, g) = \sup_n n^{-1} |f(n) - g(n)| \quad \delta(f, g) = \sum_n 2^{-n} |f(n) - g(n)|$$

for each $f, g \in \overline{B}_{l^2(X)}(0, 1)$. This is because, by Cor. 7.76, both d and δ induce the pointwise convergence topology, and hence the weak topology on $\overline{B}_{l^2(X)}(0, 1)$ by Thm. 17.31. (Compare also Pb. 17.3 or Pb. 15.15.)

★ **Remark 21.28.** A normed vector space V is called **reflexive** if the canonical linear isometry $V \rightarrow V^{**}$ is surjective (and hence an isomorphism). A reflexive space must be complete since V^{**} is complete by Thm. 17.35. By Thm. 17.30, if $1 < p < +\infty$ then $l^p(X)$ is reflexive. In particular, every Hilbert space is reflexive.

If V is reflexive, the canonical isomorphism $V \simeq V^{**}$ allows us to view V as a dual space of V^* , and talk about its weak-* topology. This is clearly equal to the

weak topology. If V is not reflexive, we do not view the weak topology of V as the weak-* topology, since V might have a meaningful predual such that the weak-* topology defined by this predual is different from the weak topology.

For example, consider $V = l^\infty(\mathbb{Z})$ with predual $l^1(\mathbb{Z})$. The weak-* topology defined by $l^1(\mathbb{Z})$ is different from the weak topology (which is defined by elements of $l^\infty(\mathbb{Z})^*$), cf. Pb. 17.8. \square

21.3.2 Strong and weak convergence

The following proposition clarifies the relationship between norm and weak convergence in Hilbert spaces:

Proposition 21.29. *Let (ξ_α) be a net in an inner product space V , and let $\xi \in V$. The following are equivalent:*

- (1) $\lim_\alpha \xi_\alpha = \xi$.
- (2) (ξ_α) converges weakly to ξ , and

$$\lim_\alpha \langle \xi_\alpha | \xi_\alpha \rangle = \langle \xi | \xi \rangle \quad (21.22)$$

Proof. By the (norm-)continuity of $\langle \cdot | \cdot \rangle$ we clearly have (1) \Rightarrow (2). Assume (2). Then

$$\langle \xi - \xi_\alpha | \xi - \xi_\alpha \rangle = \langle \xi | \xi \rangle + \langle \xi_\alpha | \xi_\alpha \rangle - \langle \xi | \xi_\alpha \rangle - \langle \xi_\alpha | \xi \rangle$$

converges to $\langle \xi | \xi \rangle + \langle \xi | \xi \rangle - \langle \xi | \xi \rangle - \langle \xi | \xi \rangle = 0$ by (21.22) and the weak convergence. So (1) is true. \square

That (21.22) does not always hold means that the norm function $\| \cdot \|$ is not continuous under the weak topology:

Example 21.30. Suppose that $(e_n)_{n \in \mathbb{Z}_+}$ is an orthonormal sequence in an inner product space V . Then $\lim_n e_n$ converges weakly to 0, for instance, by the fact that $\sum_n |\langle \xi | e_n \rangle|^2 < +\infty$ for all $\xi \in \mathcal{H}$ (which implies $\lim_n \langle \xi | e_n \rangle = 0$). However, $\lim_n \|e_n\| = 1 \neq 0$.

Prop. 21.29 will be used to prove Thm. 21.33, the main result of the next section.

21.4 ★ Key property 1 is a direct consequence of key property 2

In this starred section, we shall give a direct proof that an inner product space V satisfies Condition (2) of Thm. 21.5 (the convergence of summing orthogonal vectors) if $\overline{B}_V(0, 1)$ is weakly compact. The word “direct” means that the proof will clearly show how weak compactness leads almost directly to the conclusion. Let us begin the discussion by an easy observation:

Remark 21.31. If W is a normed vector space and V is a linear subspace, then we have a canonical linear map $W^* \rightarrow V^*, \varphi \mapsto \varphi|_V$. It is easy to see (cf. Prop. 10.28) that this map is an isomorphism of Banach spaces if V is dense in W . In particular, if V is an inner product space with completion \mathcal{H} , there is a canonical isomorphism $V^* \simeq \mathcal{H}^*$.

The following lemma tells us that given an inner product space V with completion \mathcal{H} , the weak topology of $\overline{B}_V(0, 1)$ can be described in terms of the vectors of V but not necessarily of \mathcal{H} or V^* . Thus, you may take Lem. 21.32-(2) as the *definition* of the weak compactness of $\overline{B}_V(0, 1)$ if you want to invoke Occam's razor.

Lemma 21.32. *Let V be an inner product space. Let (v_α) be a net in $\overline{B}_V(0, 1)$ and $v \in \overline{B}_V(0, 1)$. Then the following are equivalent.*

- (1) (v_α) converges weakly to v .
- (2) $\lim_\alpha \langle v_\alpha | w \rangle = \langle v | w \rangle$ for all $w \in V$.

Similar to Thm. 17.31, this lemma is not true if $\overline{B}_V(0, 1)$ is replaced by V .

Proof. Let \mathcal{H} be the Hilbert space completion of V . So $V^* \simeq \mathcal{H}^*$. By Riesz-Fréchet, (1) means that $\lim \langle v_\alpha | \xi \rangle = \langle v | \xi \rangle$ for all $\xi \in \mathcal{H}$. Thus, one checks easily that (1) \Leftrightarrow (2) using the density of V in \mathcal{H} . \square

Theorem 21.33. *Let V be an inner product space. Suppose that the unit ball $\overline{B}_V(0, 1)$ is weakly compact. Then V satisfies condition (2) of Thm. 21.5.*

Proof. Let $(e_i)_{i \in I}$ be an orthonormal family of vectors in V . Let $(a_i)_{i \in I}$ be in \mathbb{C} satisfying $\lambda := \sum_i |a_i|^2 < +\infty$. By scaling $(a_i)_{i \in I}$, assume WLOG that $\lambda = 1$. For each $J \in \text{fin}(2^I)$, let $v_J = \sum_{j \in J} a_j e_j$. Then $\|v_J\|^2 = \sum_{j \in J} |a_j|^2$. Therefore, $(v_J)_{J \in \text{fin}(2^I)}$ is a net in $\overline{B}_V(0, 1)$, and $\lim_{J \in \text{fin}(2^I)} \|v_J\|^2 = 1$.

Since $\overline{B}_V(0, 1)$ is weakly compact, (v_J) has a subnet (v_{J_β}) converging weakly to some $v \in \overline{B}_V(0, 1)$. In particular, $\|v\|^2 \leq 1$. For each $i \in I$ we have

$$\langle v | e_i \rangle = \lim_\beta \langle v_{J_\beta} | e_i \rangle = \lim_J \langle v_J | e_i \rangle = a_i$$

Therefore, by Bessel's inequality (Cor. 20.22), we have $\|v\|^2 \geq \sum_{i \in I} |a_i|^2 = 1$. Thus $\|v\|^2 = 1 = \lim_\beta \|v_{J_\beta}\|^2$. Therefore, by Prop. 21.29, we have $\lim_\beta v_{J_\beta} = v$. It is now easily to see (e.g. by Prop. 5.35) that $\lim_J v_J = v$, i.e., $\sum_{i \in I} a_i e_i$ converges to v . \square

Corollary 21.34. *Let V be an inner product space. Then V is a Hilbert space iff $\overline{B}_V(0, 1)$ is weakly compact.*

Proof. Cor. 21.26 implies " \Rightarrow ". Thm. 21.33 and 21.5 imply " \Leftarrow ". \square

21.5 Problems and supplementary material

Fix Hilbert spaces \mathcal{H}, \mathcal{K} .

21.5.1 Basic facts about Hilbert spaces

★ **Problem 21.1.** Prove that any two orthonormal bases of \mathcal{H} have the same cardinality.

Hint. The case $\dim \mathcal{H} < +\infty$ is obvious by linear algebra. In the case that either one of the two orthonormal bases is infinite, use Thm. 16.7. \square

Problem 21.2. Assume that \mathcal{K} is a closed linear subspace of \mathcal{H} . Define a map $P : \mathcal{H} \rightarrow \mathcal{H}$ such that for each $\xi \in \mathcal{H}$, $\xi = P\xi + (1 - P)\xi$ is the orthogonal decomposition with respect to \mathcal{K} . (So $P\xi \in \mathcal{K}$ and $(1 - P)\xi \in \mathcal{K}^\perp$.) Prove that P is a bounded linear map, and $P^2 = P$, $P^* = P$. We call P the **projection operator** of \mathcal{K} .

★ **Problem 21.3.** Let $P \in \mathcal{L}(\mathcal{H})$ satisfying $P^2 = P$ and $P = P^*$. Prove that $P(\mathcal{H})$ is a closed linear subspace of \mathcal{H} , and P is the projection operator of $P(\mathcal{H})$.

Recall Pb. 8.2 for the basic properties of \limsup and \liminf .

Problem 21.4. (Fatou's lemma for Hilbert spaces) Prove that the norm function $\xi \in \mathcal{H} \mapsto \|\xi\| \in \mathbb{R}_{\geq 0}$ is lower semicontinuous if \mathcal{H} is equipped with the weak topology. In other words, prove that if (ξ_α) is a net in \mathcal{H} converging weakly to ξ , then $\liminf_\alpha \|\xi_\alpha\| \geq \|\xi\|$.

Note. Give a general argument using the Cauchy-Schwarz inequality. Do not identify \mathcal{H} with $l^2(X)$. \square

Remark 21.35. The reader may try to prove the following Fatou's lemma for dual Banach spaces (which is not difficult to prove): Let V be a normed vector space. Then the map $\varphi \in V^* \mapsto \|\varphi\| \in \mathbb{R}_{\geq 0}$ is lower semicontinuous, where V^* is equipped with the weak-* topology.

Problem 21.5. Let $(e_i)_{i \in I}$ be an orthonormal basis of \mathcal{H} .

1. For each $A \in \text{fin}(2^X)$, let $P_A \in \mathcal{L}(\mathcal{H})$ be defined by $P_A \xi = \sum_{i \in A} \langle \xi | e_i \rangle e_i$. Prove that $\lim_{A \in \text{fin}(2^X)} P_A$ converges pointwise to the identity operator.
2. Let $T \in \mathcal{L}(\mathcal{H}, \mathcal{K})$. Use part 1 to prove that for every $\xi \in \mathcal{H}$, the RHS of the following equation converges to the LHS:

$$T\xi = \sum_{i \in I} \langle \xi | e_i \rangle T e_i \quad (21.23)$$

21.5.2 Hilbert's notion of boundedness

Let X, Y be sets.

Problem 21.6. Let $T : l^2(Y) \rightarrow l^2(X)$ be a bounded linear map. Prove that T is uniquely determined by its **matrix representation**

$$K : X \times Y \rightarrow \mathbb{C} \quad K(x, y) = \langle T\chi_{\{y\}} | \chi_{\{x\}} \rangle \quad (21.24)$$

Prove that for each $x \in X$, the RHS of the following converges to the LHS:

$$(T\xi)(x) = \sum_{y \in Y} K(x, y)\xi(y) \quad (21.25)$$

Hint. Show that the RHS of (21.25) (together with its convergence) is equal to $\lim_{B \in \text{fin}(2^Y)} \langle T(\chi_B \xi) | \chi_{\{x\}} \rangle$. \square

Let's study the question of which $\infty \times \infty$ matrices are the matrix representations of bounded linear maps. We first consider the special case that $l^2(X) = \mathbb{C}$, and write K as a function $f : Y \rightarrow \mathbb{C}$:

Exercise 21.36. Let $f \in \mathbb{C}^Y$. Prove that

$$\|f\|_{l^2(Y)} = \sup_{B \in \text{fin}(2^Y)} \sup_{g \in \overline{B}_{l^2(Y)}(0,1)} \langle f\chi_B | g \rangle \quad (21.26)$$

In particular, we have $f \in l^2(Y)$ iff the RHS of (21.26) is finite.

Hint. Use Lem. 21.16 to prove $\sum_{y \in B} |f(y)|^2 = \sup_{g \in \overline{B}_{l^2(B)}(0,1)} \langle f\chi_B | g \rangle$. \square

★ **Remark 21.37.** There is indeed a stronger criterion:

$$f \in l^2(Y) \iff \sup_{B \in \text{fin}(2^Y)} \langle f\chi_B | g \rangle < +\infty \text{ for all } g \in l^2(Y)$$

You can think about how to prove it if you know Baire's category theorem. (If you want to know the answer directly, search for "Banach-Steinhaus theorem".)

Now, we consider the general case.

Problem 21.7. Let $K : X \times Y \rightarrow \mathbb{C}$. For each $A \in \text{fin}(2^X)$, $B \in \text{fin}(2^Y)$, define

$$M_{A,B} = \sup_{\substack{\psi \in \overline{B}_{l^2(X)}(0,1) \\ \xi \in \overline{B}_{l^2(Y)}(0,1)}} \left| \sum_{x \in A, y \in B} K(x, y)\xi(y)\overline{\psi(x)} \right| \quad (21.27)$$

Assume that $M < +\infty$ where

$$M = \sup_{A \in \text{fin}(2^X), B \in \text{fin}(2^Y)} M_{A,B} \quad (21.28)$$

In the following, $\lim_{A,B}$ means $\lim_{A \in \text{fin}(2^X), B \in \text{fin}(2^Y)}$.

1. For each $A \in \text{fin}(2^X)$, $B \in \text{fin}(2^Y)$, define

$$T_{A,B} : l^2(Y) \rightarrow l^2(X) \quad \xi \mapsto \sum_{x \in A, y \in B} K(x, y) \xi(y) \cdot \chi_{\{x\}} \quad (21.29)$$

Prove that $\|T_{A,B}\| = M_{A,B}$.

2. For each $y \in Y$, prove that $\lim_{A,B} T_{A,B} \chi_{\{y\}}$ converges in $l^2(X)$.
3. Prove that $\lim_{A,B} T_{A,B}$ converges pointwise on $l^2(Y)$ to some bounded linear

$$T : l^2(Y) \rightarrow l^2(X)$$

satisfying $\|T\| = M$.

4. Prove that K is the matrix representation of T , i.e., (21.24) is satisfied.

Hint. Part 2: Use Exe. 21.36. Part 3: Use Prop. 17.19 and the fact that $\{\chi_y : y \in Y\}$ spans a dense subspace of $l^2(Y)$. \square

Remark 21.38. If $T : l^2(Y) \rightarrow l^2(X)$ is a bounded linear map, then its matrix representation K clearly satisfies (21.28) $< +\infty$ by Prop. 21.17. Therefore, Pb. 21.7 gives a description of bounded linear maps $l^2(Y) \rightarrow l^2(X)$ in terms of an explicit analytic condition on the matrix representations, and (21.28) gives an equivalent definition of operator norms.

Indeed, the above definitions of bounded “linear maps” and their “operator norms” (21.28) were introduced by Hilbert in an influential paper published in 1906, i.e., the fourth part (vierter Abschnitt) of [Hil12] (cf. also [Die-H, Sec. 5.2]). If you compare them with the modern definitions of bounded linear maps and operator norms in Sec. 10.6 (which are due to F. Riesz), you will notice two features.

First, of course, Hilbert’s definition is more explicit and easier to calculate. Through learning this definition, we know that mathematicians never invent abstract definitions (such as those of Riesz) out of thin air.

The second and more important aspect is that Hilbert’s definitions are not really about linear operators (i.e. maps from $l^2(Y)$ to $l^2(X)$), but are about sesquilinear forms. To illustrate this point, let’s start with some preparation. \square

Definition 21.39. For each linear map $T : \mathcal{H} \rightarrow \mathcal{K}$, define a sesquilinear map

$$\omega_T : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C} \quad \omega_T(\xi, \eta) = \langle T\xi | \eta \rangle \quad (21.30)$$

Problem 21.8. Let $\omega(\cdot | \cdot) : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C}$ be sesquilinear. Define its norm

$$\|\omega\| = \sup_{\substack{\xi \in \overline{B}_{\mathcal{H}}(0,1) \\ \eta \in \overline{B}_{\mathcal{K}}(0,1)}} |\omega(\xi | \eta)| \quad (21.31)$$

Clearly $\|\omega\|$ is the smallest element in $[0, +\infty]$ satisfying

$$|\omega(\xi|\eta)| \leq \|\omega\| \cdot \|\xi\| \cdot \|\eta\| \quad (\forall \xi \in \mathcal{H}, \forall \eta \in \mathcal{K})$$

We say that ω is **bounded** if $\|\omega\| < +\infty$. Prove that the following are equivalent.

- (1) ω is bounded.
- (2) There exists a (necessarily unique) $T \in \mathcal{L}(\mathcal{H}, \mathcal{K})$ such that $\omega = \omega_T$.
- (3) ω is continuous.
- (4) ω is continuous at $(0, 0)$.

Hint. (1) \Rightarrow (2): Mimic the proof of Cor. 21.22. (4) \Rightarrow (1): Mimic the proof of Prop. 10.25. □

Remark 21.40. Pb. 21.8 suggests that Riesz's language of bounded linear maps can be translated into Hilbert's language of bounded sesquilinear forms, and vice versa. Let us now translate Pb. 21.7 into the language of sesquilinear forms.

Hilbert's goal is to find a general condition ensuring the existence of a bounded form $\omega : l^2(Y) \times l^2(X) \rightarrow \mathbb{C}$ satisfying $\omega(\chi_y|\chi_x) = K(x, y)$ for all $x \in X, y \in Y$. For each $A \in \text{fin}(2^X), B \in \text{fin}(2^Y)$, one defines the truncated form $\omega_{A,B} : l^2(Y) \times l^2(X) \rightarrow \mathbb{C}$ by

$$\omega_{A,B}(\xi|\psi) = \sum_{x \in A, y \in B} K(x, y) \xi(y) \overline{\psi(x)}$$

(Namely, $\omega_{A,B}$ is defined to be $\omega_{T_{A,B}}$ where $T_{A,B} = (21.29)$.) One wants to find a condition so that $\lim_{A,B} \omega_{A,B}$ converges pointwise to some continuous function ω (which is clearly sesquilinear).

The condition found by Hilbert, namely $M < +\infty$ in Pb. 21.7, is a condition of equicontinuity⁶: Clearly $M_{A,B} = \|\omega_{A,B}\|$. Thus, $M < +\infty$ means that $\sup_{A,B} \|\omega_{A,B}\| < +\infty$. This implies that $(\omega_{A,B})_{A \in \text{fin}(2^X), B \in \text{fin}(2^Y)}$ is an equicontinuous family of functions when restricted to $\Delta_R = \overline{B}_{l^2(Y)}(0, R) \times \overline{B}_{l^2(X)}(0, R)$ for every $R > 0$. Moreover, this family clearly converges pointwise on the dense subset $\Delta_R \cap E$ where $E = \text{Span}\{\chi_{\{y\}} : y \in Y\} \times \text{Span}\{\chi_{\{x\}} : x \in X\}$. Therefore, by Prop. 17.10, $\lim_{A,B} \omega_{A,B}$ converges pointwise on each Δ_R to some continuous function.⁷ By considering all R , we get the desired function ω on $l^2(Y) \times l^2(X)$. □

★ **Remark 21.41.** Soon after Hilbert's work, in 1906, Hellinger and Toeplitz simplified Hilbert's boundedness condition by proving that $\sup_{A,B} \|\omega_{A,B}\| < +\infty$ iff $\sup_{A,B} |\omega_{A,B}(\xi|\psi)| < +\infty$ for all $\xi \in l^2(Y), \psi \in l^2(X)$. Similar to Rem. 21.37, this

⁶Recall that operator norms are also related to equicontinuity!

⁷This part is similar to the proof of Pb. 21.7-3, which uses Prop. 17.19, a special case of Prop. 17.10.

result is nowadays proved using Baire's category theorem (or its consequence, the Banach-Steinhaus theorem). To my knowledge, this **Hellinger-Toeplitz theorem** (in its original form) is one of the very few theorems before Riesz's work that made full use of the *completeness* of $l^2(X)$ without adopting the viewpoint of linear operators (cf. [Die-H, Sec. 6.4]).

21.5.3 Direct sums of Hilbert spaces

A tip for solving the problems in this subsection: Use cleverly Prop. 10.28 or Prop. 17.19 or other "reduction to densely-spanning subsets" tricks to simplify the proof. (We have already used such tricks in the solution of Pb. 21.7.)

Problem 21.9. Let $(\mathcal{H}_i)_{i \in I}$ be a family of Hilbert spaces. Recall that elements of $\prod_{i \in I} \mathcal{H}_i$ are of the form $\xi_\bullet = (\xi_i)_{i \in I}$ where $\xi_i \in \mathcal{H}_i$. Then $\prod_{i \in I} \mathcal{H}_i$ is a vector space whose linear structure is defined componentwise. Define

$$\bigoplus_{i \in I} \mathcal{H}_i = \left\{ (\xi_i)_{i \in I} \in \prod_{i \in I} \mathcal{H}_i : \sum_{i \in I} \|\xi_i\|^2 < +\infty \right\} \quad (21.32)$$

equipped with the inner product

$$\langle \xi_\bullet | \eta_\bullet \rangle = \langle (\xi_i)_{i \in I} | (\eta_i)_{i \in I} \rangle = \sum_{i \in I} \langle \xi_i | \eta_i \rangle \quad (21.33)$$

Prove that the rightmost term of (21.33) converges (absolutely). Prove that the inner product space $\bigoplus_{i \in I} \mathcal{H}_i$ is complete. (So $\bigoplus_{i \in I} \mathcal{H}_i$ is a Hilbert space, called the **(Hilbert space) direct sum** of $(\mathcal{H}_i)_{i \in I}$.) An element (x_\bullet) in $\bigoplus_{i \in I} \mathcal{H}_i$ is also written as $\bigoplus_{i \in I} \xi_i$.

Problem 21.10. Let $(\mathcal{H}_i)_{i \in I}$ be a family of Hilbert spaces. For each $i \in I$, choose $T_i \in \mathcal{L}(\mathcal{H}_i)$. Assume that

$$\sup_{i \in I} \|T_i\| < +\infty \quad (21.34)$$

Prove that there is a unique bounded linear operator T on $\mathcal{H} := \bigoplus_{i \in I} \mathcal{H}_i$ such that for each $\bigoplus_i \xi_i \in \mathcal{H}$,

$$T(\bigoplus_i \xi_i) = \bigoplus_i (T_i \xi_i) \quad (21.35)$$

We write $T = \bigoplus_{i \in I} T_i$ and call it the **direct sum** of $(T_i)_{i \in I}$. Prove that

$$(\bigoplus_i T_i)^* = \bigoplus_i (T_i^*) \quad (21.36)$$

Problem 21.11. Let $(\mathcal{H}_i)_{i \in I}$ be a mutually orthogonal family of closed linear subspaces of \mathcal{H} . Assume that this family spans a dense subspace of \mathcal{H} . Prove that there is a unitary map

$$\Phi : \bigoplus_{i \in I} \mathcal{H}_i \xrightarrow{\simeq} \mathcal{H} \qquad \bigoplus_{i \in I} \xi_i \mapsto \sum_{i \in I} \xi_i \tag{21.37}$$

Hint. Once you have proved that Φ is a linear isometry, to prove that Φ is surjective, you only need to show that Φ has dense range. (Why?) \square

Problem 21.12. In Pb. 21.11, choose $T \in \mathcal{L}(\mathcal{H})$ such that each \mathcal{H}_i is T -invariant, i.e., $T\mathcal{H}_i \subset \mathcal{H}_i$. Thus, the restriction of T to each \mathcal{H}_i gives $T_i \in \mathcal{L}(\mathcal{H}_i)$. Clearly $\sup_i \|T_i\| \leq \|T\| < +\infty$. Prove that the following diagram commutes:

$$\begin{array}{ccc} \bigoplus_{i \in I} \mathcal{H}_i & \xrightarrow{\bigoplus_i T_i} & \bigoplus_{i \in I} \mathcal{H}_i \\ \Phi \downarrow \simeq & & \simeq \downarrow \Phi \\ \mathcal{H} & \xrightarrow{T} & \mathcal{H} \end{array} \tag{21.38}$$

In other words, Φ implements a **unitary equivalence** of $\bigoplus_i T_i$ and T .

22 The birth of Hilbert spaces

22.1 From Dirichlet problems to integral equations

Around 1906, the Hilbert space $l^2(\mathbb{Z})$ was introduced by Hilbert and Schmidt to the study of integral equations. As mentioned in the previous chapter, the main analytic properties of $l^2(\mathbb{Z})$ attracting Hilbert and Schmidt are the two key properties studied in Sec. 21.2 and 21.3 respectively: 1. The norm convergence (equivalently, the weak convergence, by Prop. 21.29) of $\sum_i a_i e_i$ when $\sum_i |a_i|^2 < +\infty$ and $(e_i)_{i \in I}$ is orthonormal. 2. The weak compactness of the closed unit ball.

22.1.1 Dirichlet problems

The goal of this chapter is to learn how Hilbert and Schmidt used $l^2(\mathbb{Z})$ and the above mentioned properties to study integral equations. A main source of integral equations comes from solving the **Poisson equation with Dirichlet boundary condition**:

- Let $\bar{\Omega}$ be a compact region in \mathbb{R}^N with interior Ω and smooth boundary $\partial\Omega$.¹ Given good enough (say C^r , or C^∞) functions g on $\partial\Omega$ and φ on Ω , find good enough u on Ω satisfying

$$-\Delta u|_{\Omega} = \varphi \quad u|_{\partial\Omega} = g \quad (22.1)$$

Here, Δ is the Laplacian $\partial_1^2 + \cdots + \partial_N^2$.

In the following, we abbreviate $-\Delta u|_{\Omega}$ to $-\Delta u$.

The Tietze type extension gives a good \tilde{g} on $\bar{\Omega}$ with $\tilde{g}|_{\partial\Omega} = g$. Then (22.1) becomes $-\Delta(u - \tilde{g}) = \varphi + \Delta\tilde{g}$ with $(u - \tilde{g})|_{\partial\Omega} = 0$. Therefore, (22.1) can be reduced to the special case

$$-\Delta u = \varphi \quad u|_{\partial\Omega} = 0 \quad (22.2)$$

By replacing $\bar{\Omega}$ with a more general smooth compact manifold with (or without) boundary, this problem, and also the **Helmholtz equation**

$$-\Delta u = \lambda u \quad u|_{\partial\Omega} = 0 \quad (22.3)$$

have wide applications in differential geometry and in other types of differential equations. (For example, let $v = v(t, x_1, \dots, x_N)$, then the **heat equation** $\partial_t v = \Delta v$ and the **wave equation** $\partial_t^2 v = \Delta v$ can be solved by $v = \sum_j e^{-\lambda_j t} u_j$ and $v = \sum_j e^{\pm i\sqrt{\lambda_j} t} u_j$ where $-\Delta u_j = \lambda_j u_j$.)

¹Technically speaking, $\bar{\Omega}$ is a compact smooth n -dimensional submanifold of \mathbb{R}^N with boundary

22.1.2 Compact operators (i.e. completely continuous operators)

The following is roughly the modern treatment of the **Dirichlet problem** (22.2): Let $L^2(\bar{\Omega})$ be the Hilbert space of Lebesgue integrable functions $u : \bar{\Omega} \rightarrow \mathbb{C}$ satisfying $\int_{\bar{\Omega}} |u|^2 < +\infty$. The inner product is given by $\langle u|v \rangle = \int_{\bar{\Omega}} uv^*$. One shows that $-\Delta$, defined on a suitable dense linear subspace of $L^2(\bar{\Omega})$, has a bounded inverse $T \in \mathfrak{L}(L^2(\bar{\Omega}))$ satisfying $\langle T\xi|\xi \rangle \geq 0$ for all $\xi \in L^2(\bar{\Omega})$.² (Namely, T is a bounded **positive operator**.) Thus, the problem (22.2) has solution $u = T\varphi$ in $L^2(\bar{\Omega})$. An analysis of regularity (with the help of Sobolev spaces) then shows that u is good enough.

Moreover, one shows that T is a compact operator (equivalently, a completely continuous operator, cf. Def. 22.3):

Definition 22.1. A linear map $T : V \rightarrow W$ of Banach spaces is called **compact** if $T(\bar{B}_V(0, 1))$ is precompact in W (under the norm topology).

According to the **Hilbert-Schmidt theorem** (to be learned in this chapter), T has countably many eigenvalues $\lambda_1 \geq \lambda_2 \geq \dots \geq 0$ satisfying $\lim_n \lambda_n = 0$, and the (normalized) eigenvectors of T form an orthonormal basis of $L^2(\bar{\Omega})$. The regularity analysis also shows that the eigenvectors of T are smooth. Thus, the eigenvalue problem (22.3) can be fully solved.

We refer the interested readers to [Eva, Ch. 6], [Tay] (especially Sec. 5.1), [Yu] (especially Sec. 78-80) for a detailed study of this topic.

22.1.3 From Dirichlet problems to integral equations

In the days of Hilbert and Schmidt, the Dirichlet problem (22.1) was understood in a different way by transforming it to a problem about integral equations. It was in the process of solving these integral equations that the Hilbert space $l^2(\mathbb{Z})$ was discovered. In the following, I will sketch how to transform Dirichlet problems to integral equations using “double layer potentials”. Cf. [Fol-P, Sec. 3C] (where all the statements are accompanied by detailed proofs), [Sim-O, Sec. 3.3], or [RN, Sec. 81]. A discussion of the history of this method can be found in [Die-H, Sec. 2.5].

Set $x = (x_1, \dots, x_N)$. Without imposing the boundary condition $u|_{\partial\Omega}$, and assuming that the φ in $-\Delta u = \varphi$ can be extended to a good function on \mathbb{R}^N with compact support, then $-\Delta u = \varphi$ has a solution

$$u(x) = (\Phi * \varphi)(x) = \int_{\mathbb{R}^N} \Phi(x - y) \varphi(y) dy$$

²In the case that $\bar{\Omega}$ is a compact manifold without boundary, $-\Delta$ should be replaced by $C - \Delta$ where $C > 0$.

where Φ , called the **fundamental solution**, is defined by

$$\Phi(x) = \begin{cases} -\frac{1}{2\pi} \log \|x\| & \text{if } N = 2 \\ \frac{1}{(N-2)\sigma_{N-1} \cdot \|x\|^{N-2}} & \text{if } N \geq 3 \end{cases} \quad (22.4)$$

where $\sigma_{N-1} = 2\pi^{\frac{N}{2}} \Gamma(N/2)^{-1}$ is the volume of $\mathbb{S}^{N-1} = \{x \in \mathbb{R}^N : \|x\| = 1\}$. $\Delta\Phi$ is the delta function at 0. In particular, it is zero outside 0. Cf. [Eva, Sec. 2.2.1].

By replacing u with $u - \Phi * \varphi$, (22.1) is transformed to the **harmonic equation** (with Dirichlet boundary condition)

$$-\Delta u = 0 \quad u|_{\partial\Omega} = g \quad (22.5)$$

Write $\nabla v = (\partial_1 v, \dots, \partial_N v)$ for each differentiable function v on subsets of \mathbb{R}^N . For each $y \in \partial\Omega$ we let \mathbf{n}_y be the outward pointing unit vector at y orthogonal to (the tangent space of) $\partial\Omega$ at y . Define $G(x, y)$ for each $x \in \mathbb{R}^N$, $y \in \partial\Omega$ by

$$G(x, y) = \langle (\nabla\Phi)(x - y), \mathbf{n}_y \rangle = \frac{\langle y - x, \mathbf{n}_y \rangle}{\sigma_{N-1} \|x - y\|^N} \quad (22.6)$$

For each $x \in \mathbb{R}^N$ and continuous function f on $\partial\Omega$, define $(\mathcal{D}f)(x) = \int_{\partial\Omega} f(y) (\nabla\Phi)(x - y) \cdot d\mathbf{S}$ where the RHS is a “surface integral of second type”, i.e.

$$(\mathcal{D}f)(x) = \int_{\partial\Omega} G(x, y) f(y) dy \quad (22.7)$$

When $x \in \partial\Omega$, this is an improper integral, which converges because

$$G(x, y) \sim \|x - y\|^{2-N} \quad (22.8)$$

when $x \in \partial\Omega$ approaches y . (Note that $\int_U \|y\|^{2-N} dy$ converges if $U \subset \mathbb{R}^{N-1}$ is a bounded neighborhood of 0.)

$\mathcal{D}f$ is not continuous at the points of $\partial\Omega$. However, if we define $u : \bar{\Omega} \rightarrow \mathbb{C}$ by

$$u(x) = \begin{cases} (\mathcal{D}f)(x) & \text{if } x \in \Omega \\ f(x) + (\mathcal{D}f)(x) & \text{if } x \in \partial\Omega \end{cases} \quad (22.9)$$

then u is continuous on $\bar{\Omega}$. Moreover, $\Delta u = 0$ on Ω since $\Delta G(x, y) = 0$ when $x \neq y$. Therefore, the Dirichlet problem (22.5) can be solved if there exists a good function f on $\partial\Omega$ such that $f + \mathcal{D}f|_{\partial\Omega} = g$.

To summarize, define an integral operator T on the space $L^2(\partial\Omega)$ of Lebesgue square integrable functions by

$$(Tf)(x) = \int_{\partial\Omega} G(x, y) f(y) dy \quad (22.10)$$

The equation (22.5) has solution (22.9) if there is an (at least continuous) $f : \partial\Omega \rightarrow \mathbb{C}$ satisfying $f + Tf = g$. The problem is then reduced to finding such f for a given g .

22.1.4 Summary of the problem of integral equations

Given a function g on $\partial\Omega$, we want to find a function f on $\partial\Omega$ satisfying

$$f + Tf = g \quad (22.11a)$$

Moreover, we shall consider the case that $N = 2$ and hence $\dim \partial\Omega = 1$. Let us assume that $\partial\Omega$ has only one connected component so that $\partial\Omega \simeq \mathbb{S}^1$. So we view f, g also as 2π -periodic functions with L^2 -norms $\|f\| = \sqrt{\frac{1}{2\pi} \int_{-\pi}^{\pi} |f|^2}$ and $\|g\| = \sqrt{\frac{1}{2\pi} \int_{-\pi}^{\pi} |g|^2}$. Then

$$(Tf)(x) = \frac{1}{2\pi} \int_{-\pi}^{\pi} K(x, y) f(y) dy \quad (22.11b)$$

where $K(x, y) = G(x, y) \cdot \lambda(y)\lambda(x)$ for some $\lambda \in C^\infty(\mathbb{S}^1, \mathbb{R})$ defined by the change of variable from $\partial\Omega$ to \mathbb{S}^1 (similar to the function Φ' in (13.31)).

Since G takes real values, so does K . (22.8) suggests that K is uniformly bounded on $\mathbb{S}^1 \times \mathbb{S}^1$. Indeed, K is continuous (cf. [RN, Sec. 81]). However, we will only need the weaker fact that $K \in L^2(\mathbb{S}^1 \times \mathbb{S}^1)$, i.e.

$$\|K\|_{L^2} = \frac{1}{(2\pi)^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} |K(x, y)|^2 dy dx < +\infty \quad (22.12)$$

In finite-dimensional linear algebra, we know that a linear operator is surjective iff it is injective. If this is the case for $1 + T$, then solving $(1 + T)f = g$ can be reduced to the easier task of proving that -1 is not an eigenvalue of T . However, there are bounded linear operators on infinite dimensional function spaces that are injective but not surjective: Consider the right translation operator on $l^2(\mathbb{N})$, which is the bounded linear operator sending each $\chi_{\{n\}}$ to $\chi_{\{n+1\}}$.

To understand the behavior of T , and to solve other problems leading to integral equations, it turns out that we must have a good understanding of the eigenvalues and eigenvectors of T . As soon as we understand the eigenvalue problem of T very well, we can prove the theorem of **Fredholm alternative**, which says that $\text{Ker}(1 + T) = 0$ iff $1 + T$ is surjective.

22.2 Discretizing the integral equations

Fix $K \in L^2(\mathbb{S}^1 \times \mathbb{S}^1)$. (The readers can assume for simplicity that K is continuous, which is often the case when K is defined by the 2d Dirichlet problem as in Subsec. 22.1.4.) Define the integral operator T sending each 2π -periodic function f to Tf , where

$$(Tf)(x) = \frac{1}{2\pi} \int_{-\pi}^{\pi} K(x, y) f(y) dy \quad (22.13)$$

K is called the **kernel** of T . Our goal is to understand the eigenvalues and eigenvectors of T .

Hilbert's idea is to use Fourier series. Functions on $\mathbb{S}^1 \times \mathbb{S}^1$ have Fourier series of the form $\sum_{m,n} a_{m,n} e^{i(-nx+my)}$ in a similar way as functions on \mathbb{S}^1 . Therefore, for each $m, n \in \mathbb{Z}$, define the Fourier coefficient

$$\hat{K}(m, n) = \langle T e_n | e_m \rangle = \frac{1}{(2\pi)^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} K(x, y) e^{i(nx-my)} dx dy \quad (22.14)$$

Then, by Thm. 20.35, we get $f = \sum_n \hat{f}_n e_n$ and $g = \sum_m \hat{g}_m e_m$, and hence

$$\langle T f | g \rangle = \sum_{m,n} \hat{K}(m, n) \hat{f}(n) \overline{\hat{g}(m)} = \langle \hat{T} \hat{f} | \hat{g} \rangle$$

if we view \hat{f}, \hat{g} as in $l^2(\mathbb{Z})$ and define a linear map $\hat{T} : l^2(\mathbb{Z}) \rightarrow l^2(\mathbb{Z})$ by

$$(\hat{T} \hat{f})(m) = \sum_{n \in \mathbb{Z}} \hat{K}(m, n) \hat{f}(n) \quad (22.15)$$

By applying Parseval's identity to K , we obtain $\sum_{m,n} |\hat{K}(m, n)|^2 = (2\pi)^{-2} \iint K(x, y) dx dy$ (which is a finite number), and hence

$$\hat{K} \in l^2(\mathbb{Z} \times \mathbb{Z}) \quad (22.16)$$

Thus, to understand the original integral equation, one must first understand the equation

$$\hat{f} + \hat{K} \hat{f} = \hat{g} \quad (22.17)$$

In fact, at this point, Hilbert did not have the notion of $l^2(\mathbb{Z})$ and L^2 yet. However, the idea of transforming the eigenvalue problem about T to that about the matrix \hat{K} without introducing $l^2(\mathbb{Z})$ is conceivable. After all, almost every mathematical progress leaves some questions about rigor until the end.

Remark 22.2. Parseval's identity $\frac{1}{2\pi} \int_{-\pi}^{\pi} |f|^2 = \sum_n |\hat{f}(n)|^2$ is well-known by the time Hilbert studied integral equations around 1906. However, Parseval's identity is far from enough to motivate the notion of $l^2(\mathbb{Z})$: Unlike the completeness of $l^2(\mathbb{Z})$ or the weak compactness of $\overline{B}_{l^2(\mathbb{Z})}(0, 1)$, Parseval's identity is a property about individual functions, not about the set of all functions *and their interactions*.

In the remaining sections, we will forget the original function K on $\mathbb{S}^1 \times \mathbb{S}^1$, as Hilbert did, and focus on the matrix $\hat{K} \in l^2(\mathbb{Z} \times \mathbb{Z})$. Thus, we will let K denote \hat{K} , or denote a general function $X \times Y \rightarrow \mathbb{C}$ where X, Y are sets.

22.3 Hilbert's complete continuity

We fix Hilbert spaces \mathcal{H} and \mathcal{K} . Let X, Y be sets. For each linear map $T : \mathcal{H} \rightarrow \mathcal{K}$ we let

$$\omega_T : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C} \quad \omega_T(\xi|\eta) = \langle T\xi|\eta \rangle \quad (22.18)$$

In his important 1906 paper, Hilbert introduced two crucial analytic properties about sesquilinear forms. The first one is boundedness (i.e., the condition $M < +\infty$ in Pb. 21.7), which is equivalent to the boundedness of linear maps between Hilbert spaces. See Subsec. 21.5.2 for details. In particular, we have the obvious fact

$$T \in \mathcal{L}(\mathcal{H}, \mathcal{K}) \quad \Rightarrow \quad \omega_T \text{ is continuous} \quad (22.19)$$

The second condition is stronger than the first one (cf. [Hil12, p.147]): A sesquilinear $\omega : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C}$ is called **completely continuous** if ω is weakly continuous when restricted to $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$. It is easy to adapt this definition to linear maps:

Definition 22.3. A linear map $T : \mathcal{H} \rightarrow \mathcal{K}$ is called **completely continuous** if ω_T is continuous on $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$ where $\overline{B}_{\mathcal{H}}(0, 1)$ and $\overline{B}_{\mathcal{K}}(0, 1)$ are equipped with their weak topologies.

Thus, complete continuity means that if (ξ_α) converges weakly in $\overline{B}_{\mathcal{H}}(0, 1)$ to ξ and (η_α) converges weakly in $\overline{B}_{\mathcal{K}}(0, 1)$ to η , then $\lim_\alpha \langle T\xi_\alpha|\eta_\alpha \rangle = \langle T\xi|\eta \rangle$.

Completely continuous sesquilinear forms are clearly continuous (i.e., bounded, cf. Pb. 21.8). Thus, it is not hard see:

Lemma 22.4. *A completely continuous linear map $T : \mathcal{H} \rightarrow \mathcal{K}$ is bounded.*

Proof. ω_T is weakly continuous and hence continuous on $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$. Since $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$ is a neighborhood of $(0, 0)$ in $\mathcal{H} \times \mathcal{K}$, the function $\omega_T : \mathcal{H} \times \mathcal{K} \rightarrow \mathbb{C}$ is continuous at $(0, 0)$. Thus, there exists $\varepsilon > 0$ such that $|\omega_T(\xi|\eta)| \leq 1$ whenever $\|\xi\| \leq \varepsilon, \|\eta\| \leq \varepsilon$. Thus, whenever $\|\xi\| \leq 1, \|\eta\| \leq 1$, we have

$$|\omega_T(\xi|\eta)| = \varepsilon^{-2} |\omega_T(\varepsilon\xi|\varepsilon\eta)| \leq \varepsilon^{-2}$$

By Prop. 21.17, we have $\|T\| \leq \varepsilon^{-2} < +\infty$. □

Example 22.5. Assume that \mathcal{H} is an infinite-dimensional Hilbert space. Then its identity operator 1 is not completely continuous. This is because ω_1 is the inner product function $(\xi, \eta) \in \mathcal{H} \times \mathcal{H} \mapsto \langle \xi|\eta \rangle \in \mathbb{C}$, which is not weakly continuous by Exp. 21.30.

Exercise 22.6. Show that a finite linear combination of completely continuous operators is continuous. Show that the adjoint of a completely continuous operator is completely continuous. Show that if $T \in \mathfrak{L}(\mathcal{H}_1, \mathcal{H}_2)$ and $S \in \mathfrak{L}(\mathcal{H}_2, \mathcal{H}_3)$ where each \mathcal{H}_i is a Hilbert space, and if one of T and S is completely continuous, then $ST : \mathcal{H}_1 \rightarrow \mathcal{H}_3$ is completely continuous. In particular, the set of completely continuous operators on \mathcal{H} is a two-sided ideal of $\mathfrak{L}(\mathcal{H})$.

The easiest examples of completely continuous maps are finite-rank operators:

Definition 22.7. A linear map of vector spaces is said to have **finite rank** if its range is finite-dimensional.

Proposition 22.8. Let $T \in \mathfrak{L}(\mathcal{H}, \mathcal{K})$. The following are equivalent:

- (1) T has finite rank.
- (2) There exist finitely many vectors $\mu_1, \dots, \mu_n \in \mathcal{H}$ and $\eta_1, \dots, \eta_n \in \mathcal{K}$ such that for all $\xi \in \mathcal{H}$,

$$T\xi = \sum_{i=1}^n \langle \xi | \mu_i \rangle \eta_i \quad (22.20)$$

Note that without assume that T is bounded, (1) does not imply (2).

Proof. “(2) \Rightarrow (1)” is obvious. Assume (1). Restrict the inner product of \mathcal{K} to the finite-dimensional $V = T(\mathcal{H})$. By Gram-Schmidt, V is spanned by an orthonormal set of vectors η_1, \dots, η_n . Then, for each $\psi \in V$ we have (by Thm. 20.35) $\psi = \sum_{i=1}^n \langle \psi | \eta_i \rangle \eta_i$. Therefore

$$T\xi = \sum_i \langle T\xi | \eta_i \rangle \eta_i = \sum_i \langle \xi | \mu_i \rangle \eta_i$$

where $\mu_i = T^* \eta_i$. □

Example 22.9. If $T \in \mathfrak{L}(\mathcal{H}, \mathcal{K})$ has finite rank, then T is completely continuous.

Proof. By Prop. 22.8, and by linearity, it suffices to assume that T takes the form $T\xi = \langle \xi | \mu \rangle \eta$ for some $\mu \in \mathcal{H}, \eta \in \mathcal{K}$. Then $\omega_T(\xi | \psi) = \langle \xi | \mu \rangle \langle \eta | \psi \rangle$ is clearly weakly continuous with respect to ξ and ψ . □

In order to have nontrivial examples of completely continuous operators, we need the following simple fact:

Theorem 22.10. Let (T_α) be a net of completely continuous maps $\mathcal{H} \rightarrow \mathcal{K}$. Assume that $T : \mathcal{H} \rightarrow \mathcal{K}$ is linear and $\lim_\alpha \|T - T_\alpha\| = 0$. Then T is completely continuous.

Proof. By Cor. 21.18, ω_{T_α} converges uniformly on $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$ to ω_T . Since the uniform limit of a net of continuous functions is continuous, we conclude that ω_T is weakly continuous on $\overline{B}_{\mathcal{H}}(0, 1) \times \overline{B}_{\mathcal{K}}(0, 1)$. \square

Motivated by the above theorem, we make the following definition:

Definition 22.11. We say that a linear map $T : \mathcal{H} \rightarrow \mathcal{K}$ is **approximable** if there exists a net (equivalently, a sequence) of finite-rank operators (T_α) in $\mathcal{L}(\mathcal{H}, \mathcal{K})$ such that $\lim_\alpha \|T - T_\alpha\| = 0$. Approximable operators are clearly bounded.

Theorem 22.12. *Let $T : \mathcal{H} \rightarrow \mathcal{K}$. Then T is approximable iff T is completely continuous.*

★ *Proof.* Since finite-rank bounded linear operators are completely continuous, by Thm. 22.10, approximability implies complete continuity. Conversely, assume that T is completely continuous. Assume WLOG that $\mathcal{H} = l^2(Y)$ and $\mathcal{K} = l^2(X)$. For each $A \in \text{fin}(2^X)$ and $B \in \text{fin}(2^Y)$ we set

$$T_{A,B} : l^2(Y) \rightarrow l^2(X) \quad T_{A,B}\xi = \chi_A \cdot T(\chi_B\xi) \quad (22.21)$$

which is a bounded linear map of finite rank. We claim that $\lim_{A,B} \|T - T_{A,B}\| = 0$.

By Cor. 21.18, we need to show that $(\omega_{T_{A,B}})_{A \in \text{fin}(2^X), B \in \text{fin}(2^Y)}$ converges uniformly on $\Omega = \overline{B}_{l^2(Y)}(0, 1) \times \overline{B}_{l^2(X)}(0, 1)$ to ω_T . We equip Ω with the product weak topology, which is compact by Cor. 21.26. Since each $\omega_{T_{A,B}}$ is (weakly) continuous, by Thm. 9.12 and Prop. 9.16, it suffices to prove that

$$\lim_{A,B,\xi',\eta'} |\omega_T(\xi'|\eta') - \omega_{T_{A,B}}(\xi'|\eta')| = |\omega_T(\xi|\eta) - \omega_T(\xi|\eta)| = 0$$

where ξ' converges weakly to ξ and η' converges weakly to η . Equivalently, it suffices to prove that for each net $(\xi_i, \eta_i)_{i \in I}$ in Ω converging to $(\xi, \eta) \in \Omega$, we have

$$\lim_{A,B,i} |\langle (T - T_{A,B})\xi_i | \eta_i \rangle| = 0$$

Clearly $\lim \langle T\xi_i | \eta_i \rangle = \langle T\xi | \eta \rangle$ since T is completely continuous. Note that $\langle T_{A,B}\xi_i | \eta_i \rangle = \langle T\chi_B\xi_i | \chi_A\eta_i \rangle$. It remains to show that this expression also converges to $\langle T\xi | \eta \rangle$. Since T is completely continuous, it suffices to prove that $\lim_{B,i} \chi_B\xi_i$ converges weakly to ξ and $\lim_{A,i} \chi_A\eta_i$ converges weakly to η .

By Thm. 17.31, we know for each $y \in Y$ that $\lim_i \xi_i(y) = \xi(y)$ and hence $\lim_{B,i} \chi_B(y)\xi_i(y) = \xi(y)$. By Thm. 17.31 again, we conclude that $\lim_{B,i} \chi_B\xi_i$ converges weakly to ξ . The second (weak) limit can be proved in the same way. \square

Remark 22.13. Since the proof of the direction “ \Leftarrow ” in Thm. 22.12 is slightly more complicated (although the main idea is clear), we will not use this direction in the future. Note that the direction “ \Leftarrow ” relies on the weak compactness of the closed unit balls, whereas the easy direction “ \Rightarrow ” does not.

Remark 22.14. In the proof of Thm. 22.12 we have shown that if $T : l^2(Y) \rightarrow l^2(X)$ is completely continuous, then

$$\lim_{A \in \text{fin}(2^X), B \in \text{fin}(2^Y)} \|T - T_{A,B}\| = 0 \quad (22.22)$$

In contrast, if T is only bounded, then it is easy to see that $\lim_{A,B} T_{A,B}$ converges pointwise to T .

22.4 Hilbert-Schmidt operators

Let X and Y be sets. Recall Pb. 21.6 for the basic facts about matrix representations.

Theorem 22.15. *Let $K \in l^2(X \times Y)$. Then K is the matrix representation of a (necessarily unique) completely continuous $T : l^2(Y) \rightarrow l^2(X)$. Moreover, we have*

$$\|T\| \leq \|K\|_{l^2} \quad (22.23)$$

Such T is called a **Hilbert-Schmidt operator**. See Pb. 22.3 for the general definition of Hilbert-Schmidt operators.

Lemma 22.16. *Thm. 22.15 is true when X, Y are finite sets.*

Proof. The only nontrivial part is $\|T\| \leq \|K\|_{l^2}$. By Prop. 21.17, it suffices to prove for all $f \in \overline{B}_{l^2(Y)}(0, 1)$ and $g \in \overline{B}_{l^2(X)}(0, 1)$ that $|\langle Tf|g \rangle| \leq \|K\|_2$. But

$$|\langle Tf|g \rangle| = \left| \sum_{x,y} K(x,y) f(y) \overline{g(x)} \right| = |\langle K|\Gamma \rangle| \leq \|K\|_2 \cdot \|\Gamma\|_2$$

where $\Gamma : X \times Y \rightarrow \mathbb{C}$ is defined by $\Gamma(x,y) = \overline{f(y)}g(x)$. Since

$$\|\Gamma\|_2^2 = \sum_{x,y} |f(y)^2 g(x)^2| = \sum_y |f(y)|^2 \cdot \sum_x |g(x)|^2 \leq 1$$

we have $|\langle Tf|g \rangle| \leq \|K\|_2$. □

Proof of Thm. 22.15. For each $\Omega \in \text{fin}(2^{X \times Y})$, let $K_\Omega : X \times Y \rightarrow \mathbb{C}$ be $K_\Omega = K \chi_\Omega$. Let $T_\Omega : l^2(Y) \rightarrow l^2(X)$ be the finite rank operator whose matrix representation is K_Ω , namely,

$$T_\Omega \xi = \sum_{(x,y) \in \Omega} K(x,y) \xi(y) \cdot \chi_{\{x\}} \quad (22.24)$$

Since $K \in l^2(X \times Y)$, we know that $\lim_\Omega \|K - K_\Omega\|_2 = 0$, and hence $(K_\Omega)_{\Omega \in \text{fin}(2^{X \times Y})}$ is a Cauchy net in $l^2(X \times Y)$. For each $\Omega, \Gamma \in \text{fin}(2^{X \times Y})$, since $T_\Omega - T_\Gamma$ has matrix representation $K_\Omega - K_\Gamma$, by Lem. 22.16 we have

$$\|T_\Omega - T_\Gamma\| \leq \|K_\Omega - K_\Gamma\|_{l^2}$$

Therefore $\lim_{\Omega, \Gamma} \|T_\Omega - T_\Gamma\| = 0$, i.e., (T_Ω) is a Cauchy net in $\mathfrak{L}(l^2(Y), l^2(X))$. By Thm. 17.35, $\mathfrak{L}(l^2(Y), l^2(X))$ is complete. So $\lim_\Omega T_\Omega$ converges under the operator norm to some $T \in \mathfrak{L}(l^2(Y), l^2(X))$.

Clearly T has matrix representation K . Since each T_Ω has finite rank, by Thm. 22.12, T is completely continuous. Finally, by Lem. 22.16, $\|T_\Omega\| \leq \|K_\Omega\|_2 \leq \|K\|_2$ for all Ω . Taking \lim_Ω , we get $\|T\| \leq \|K\|_2$. \square

Remark 22.17. In the above proof, we have used the completeness of $\mathfrak{L}(l^2(Y), l^2(X))$, which relies on the completeness of $l^2(X)$. This seems contradictory to our earlier statement that Hilbert and Schmidt did not rely on the completeness of l^2 spaces to study integral equations. In fact, there is no contradiction since Hilbert took the sesquilinear form perspective: One can modify the above proof by showing that for every $R > 0$, ω_{T_Ω} converges uniformly on $\overline{B}_{l^2(X)}(0, R) \times \overline{B}_{l^2(X)}(0, R)$ to some function ω . This gives the desired completely continuous sesquilinear form for T without using the completeness of l^2 spaces.

22.5 The triumph of weak(-*) compactness: Hilbert-Schmidt theorem

Fix a Hilbert space \mathcal{H} . For each $T \in \mathfrak{L}(\mathcal{H})$, let $\omega_T : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{C}$ be $\omega_T(\xi|\eta) = \langle T\xi|\eta \rangle$ as usual.

Recall from linear algebra that $\lambda \in \mathbb{C}$ is called an **eigenvalue** of T if there is a nonzero $\xi \in \mathcal{H}$ such that $T\xi = \lambda\xi$. In this case, ξ is called the **λ -eigenvector** of T .

22.5.1 Self-adjoint operators and positive operators

Definition 22.18. Let $T \in \mathfrak{L}(\mathcal{H})$. We say that T is **self-adjoint** if one of the following conditions hold:

- (1) $T = T^*$.
- (2) $\langle T\xi|\eta \rangle = \langle \xi|T\eta \rangle$ for all $\xi, \eta \in \mathcal{H}$.
- (3) The sesquilinear form ω_T is a Hermitian.
- (4) $\langle T\xi|\xi \rangle \in \mathbb{R}$ for all $\xi \in \mathcal{H}$.

Proof of equivalence. Since we always have $\langle T\xi|\eta \rangle = \langle \xi|T^*\eta \rangle$, the equivalence (1) \Leftrightarrow (2) is obvious. Recall that ω_T is Hermitian iff $\omega_T(\xi|\eta) = \overline{\omega_T(\eta|\xi)}$. But $\omega_T(\eta|\xi) = \langle T\eta|\xi \rangle = \langle \xi|T\eta \rangle$, which equals $\langle T\xi|\eta \rangle$ for all ξ, η iff (2) is true. This proves (2) \Leftrightarrow (3). By Prop. 20.7, we have (3) \Leftrightarrow (4). \square

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