

Qiuzhen Lectures on Analysis

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1 Basic set theory and numbers

In this chapter, we discuss informally some of the basic notions in set theory and basic properties about numbers. A more thorough treatment can be found in [Mun, Ch. 1] (for set theory) and [Rud-P, Ch. 1] (for numbers).

Let me first list the notations and conventions that will be used throughout the notes. We use frequently the abbreviations:

iff=if and only if
 LHS=left hand side RHS=right hand side
 \exists =there exists \forall =for all
 i.e.=in other words e.g.=for example
 cf.=compare/check/see/you are referred to
 resp.=respectively WLOG=without loss of generality

If P, Q are properties, then

$$P \wedge Q = P \text{ and } Q \quad P \vee Q = P \text{ or } Q \quad \neg P = \text{Not } P$$

When we write $A := B$ or $A \stackrel{\text{def}}{=} B$, we mean that A is defined by the expression B . When we write $A \equiv B$, we mean that A and B are different symbols of the same object.

If \mathbb{F} is any field (e.g. $\mathbb{Q}, \mathbb{R}, \mathbb{C}$), we let $\mathbb{F}^\times = \mathbb{F} \setminus \{0\}$. If α is a complex number and $n \in \mathbb{N}$, we define the **binomial coefficient**

$$\binom{\alpha}{n} = \begin{cases} \frac{\alpha \cdot (\alpha - 1) \cdots (\alpha - n + 1)}{n!} & \text{if } n \geq 1 \\ 1 & \text{if } n = 0 \end{cases} \quad (1.1)$$

where $n! = n(n-1)(n-2) \cdots 2 \cdot 1$ and $0! = 1$. The bold letter **i** means

$$\mathbf{i} = \sqrt{-1}$$

If $z = a + bi$ where $a, b \in \mathbb{R}$, we let

$$\text{Re}(z) = a \quad \text{Im}(z) = b$$

Topics marked with ****** are technical and/or their methods are rarely used in later studies. Topics marked with ***** are interesting, but not necessarily technical or difficult. They are not essential for understanding the rest of the notes. You can skim or skip the starred topics on first reading. When a chapter/section/subsection is starred, it means that all of the material in that chapter/section/subsection is starred.

1.1 Basic operations and axioms

Intuitively, a set denotes a collection of elements. For instance:

$$\mathbb{Z} = \{\text{all integers}\} \quad \mathbb{N} = \mathbb{Z}_{\geq 0} = \{n \in \mathbb{Z} : n \geq 0\} \quad \mathbb{Z}_+ = \{n \in \mathbb{Z} : n > 0\}$$

have infinitely many elements. (In this course, we will not be concerned with the rigorous construction of natural numbers and integers from Peano axioms.) We also let

$$\mathbb{Q} = \{\text{all rational numbers}\} \quad \mathbb{R} = \{\text{all real numbers}\}$$

if we that rational and real numbers exist and satisfy the properties we are familiar with in high school mathematics. (We will construct \mathbb{Q} and \mathbb{R} rigorously, by the way.)

Set theory is the foundation of modern mathematics. It consists of several Axioms telling us what we can do about the sets. For example, the following way of describing sets

$$\{x : x \text{ satisfies property...}\} \tag{1.2}$$

is illegal, since it gives **Russell's paradox**: Consider

$$S = \{A : A \text{ is a set and } A \notin A\} \tag{1.3}$$

If S were a set, then $S \in S \Rightarrow S \notin S$ and $S \notin S \Rightarrow S \in S$. This is something every mathematician doesn't want to happen.

Instead, the following way of defining sets is legitimate:

$$\{x \in X : x \text{ satisfies property } \dots\} \tag{1.4}$$

where X is a given set. For instance, we can define the **difference** of two sets:

$$A \setminus B = A - B = \{x \in A : x \notin B\}$$

So let us figure out the legal way of defining unions and intersections of sets. The crucial point is that we assume the following axiom:

Axiom. If \mathcal{A} is a set of sets, then there exists a set X such that $A \subset X$ for all $A \in \mathcal{A}$.

Thus, if \mathcal{A} is a set of sets, let X satisfy $A \subset X$ for all $A \in \mathcal{A}$, then we can define the **union** and the **intersection**

$$\bigcup_{A \in \mathcal{A}} A = \{x \in X : \text{there exists } A \in \mathcal{A} \text{ such that } x \in A\} \tag{1.5a}$$

$$\bigcap_{A \in \mathcal{A}} A = \{x \in X : \text{for all } A \in \mathcal{A} \text{ we have } x \in A\} \tag{1.5b}$$

It is clear that this definition does not rely on the particular choice of X .

Remark 1.1. In many textbooks, it is not uncommon that sets are defined as in (1.2). You should interpret such definition as (1.4), where the set X is omitted because it is clear from the context. For instance, if the context is clear, the set $\{x \in \mathbb{R} : x \geq 0\}$ could be simply written as $\{x : x \geq 0\}$ or even $\{x \geq 0\}$. By the same token, the phrase “ $\in X$ ” in (1.5) could be omitted. So we can also write

$$A \cup B = \{x : x \in A \text{ or } x \in B\} \quad A \cap B = \{x : x \in A \text{ and } x \in B\}$$

which are special cases of (1.5).

Remark 1.2. In the same spirit, when discussing subsets of a given “large” set X , and if X is clear from the context, we shall write $X \setminus A$ (where $A \subset X$) as A^c and call it the **complement** of A .

Example 1.3. We have

$$\bigcup_{x \in (1, +\infty)} [0, x) = [0, +\infty) \quad \bigcap_{n \in \mathbb{Z}_+} (0, 1 + 1/n) = (0, 1] \quad \bigcup_{n \in \mathbb{N}} (0, 1 - 1/n] = (0, 1)$$

The readers may notice that these examples are not exactly in the form (1.5). They are actually unions and intersections of indexed families of sets. (See Def. 1.10.) We need some preparation before discussing this notion.

Axiom. If A_1, \dots, A_n are sets, their **Cartesian product** exists:

$$A_1 \times \cdots \times A_n = \{(a_1, \dots, a_n) : a_i \in A_i \text{ for all } 1 \leq i \leq n\}$$

where two elements (a_1, \dots, a_n) and (b_1, \dots, b_n) of the Cartesian product are regarded equal iff $a_1 = b_1, \dots, a_n = b_n$. We also write

$$(a_1, \dots, a_n) = a_1 \times \cdots \times a_n$$

especially when a, b are real numbers and (a, b) can mean an open interval. We understand $A_1 \times \cdots \times A_n$ as \emptyset if some A_i is \emptyset .

If $A_1 = \cdots = A_n = A$, we write the Cartesian product as A^n . □

Example 1.4. Assume that the set of real numbers \mathbb{R} exists. Then the set of complex numbers \mathbb{C} is defined to be $\mathbb{R}^2 = \mathbb{R} \times \mathbb{R}$ as a set. We write $(a, b) \in \mathbb{C}$ as $a + bi$ where $a, b \in \mathbb{R}$. Define

$$\begin{aligned} (a + bi) + (c + di) &= (a + c) + (b + d)i \\ (a + bi) \cdot (c + di) &= (ac - bd) + (ad + bc)i \end{aligned}$$

Define the zero element 0 of \mathbb{C} to be $0 + 0i$. More generally, we consider \mathbb{R} as a subset of \mathbb{C} by viewing $a \in \mathbb{R}$ as $a + 0i \in \mathbb{C}$. This defines the usual arithmetic of complex numbers.

If $z = a + bi$, we define its **absolute value** $|z| = \sqrt{a^2 + b^2}$. Then $z = 0$ iff $|z| = 0$. We define the **(complex) conjugate** of z to be $\bar{z} = a - bi$. Then $|z|^2 = z\bar{z}$.

If $z \neq 0$, then there clearly exists a unique $z^{-1} \in \mathbb{C}$ such that $zz^{-1} = z^{-1}z = 1$: $z^{-1} = |z|^{-2} \cdot \bar{z}$. Thus, using the language of modern algebra, \mathbb{C} is a **field**.¹ \square

The axiom of Cartesian product allows us to define relations and functions:

Definition 1.5. If A, B are sets, a subset R of $A \times B$ is called a **relation**. For $(a, b) \in A \times B$, we write aRb iff $(x, y) \in R$. We understand “ aRb ” as “ a is related to b through the relation R ”.

Definition 1.6. A relation f of A, B is called a **function** or a **map** (or a **mapping**), if for every $a \in A$ there is a unique $b \in B$ such that afb . In this case, we write $b = f(a)$.

When we write $f : A \rightarrow B$, we always mean that A, B are sets and f is a function from A to B . A and B are called respectively the **domain** and the **codomain** of f . (Sometimes people also use the words “source” and “target” to denote A and B .)

If $E \subset A$ and $F \subset B$, we define the **image under f** of E and the **preimage under f** of F to be

$$f(E) = \{b \in B : \exists a \in E \text{ such that } b = f(a)\}$$

$$f^{-1}(F) = \{a \in A : f(a) \in F\}.$$

$f(A)$ is simply called the **image** of f , or the **range** of f . If $b \in B$, $f^{-1}(\{b\})$ is often abbreviated to $f^{-1}(b)$. The function

$$f|_E : E \rightarrow B \quad x \mapsto f(x)$$

is called the **restriction** of f to E . \square

The intuition behind the definition of functions is clear: we understand functions as the same as their graphs. So a subset f of the “coordinate plane” $A \times B$ is the graph of a function iff it “intersects every vertical line precisely once”.

Remark 1.7. According to our definition, \emptyset (as a subset of $\emptyset \times B$) is the only function from \emptyset to B . (A false assumption implies any statement.) If $A \neq \emptyset$, there are no functions $A \rightarrow \emptyset$.

Definition 1.8. A function $x : \mathbb{Z}_+ \rightarrow A$ is called a **sequence in A** . We write $x(n)$ as x_n , and write this sequence as $(x_n)_{n \in \mathbb{Z}_+}$ (or simply $(x_n)_n$ or (x_n)).

¹See Rem. 6.7 or [Rud-P, Def. 1.12] for the definition of fields. Rather than memorizing the full definition of fields, it is more important to keep in mind some typical (counter)examples: $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ are fields. \mathbb{Z} is not a field, because not every non-zero element of \mathbb{Z} has an inverse. The set of quaternions $\{a + bi + cj + dk : a, b, c, d \in \mathbb{R}\}$ is not a field because it is not commutative ($ij = -ji = k$). The set of rational functions $P(x)/Q(x)$, where P, Q are polynomials with coefficients in \mathbb{R} and $Q \neq 0$, is a field.

Many people write such a sequence as $\{x_n\}_{n \in \mathbb{Z}_+}$. We do not use this notation, since it can be confused with $\{x_n : n \in \mathbb{Z}_+\}$ (the range of the function x).

Axiom. If X is a set, then the **power set** 2^X exists, where

$$2^X = \{\text{Subsets of } X\}$$

Example 1.9. The set $2^{\{1,2,3\}}$ has 8 elements: $\emptyset, \{1\}, \{2\}, \{3\}, \{1, 2\}, \{1, 3\}, \{2, 3\}, \{1, 2, 3\}$. Surprisingly, $8 = 2^3$. As we shall see in Exp. 1.54 and Cor. 1.57, this relationship holds more generally, which explains the terminology 2^X .

Now we are ready to define indexed families of sets.

Definition 1.10. An **indexed family of sets** $(S_i)_{i \in I}$ is defined to be a function $S : I \rightarrow 2^X$ for some sets I, X . We write $S(i)$ as S_i . (So S_i is a subset of X .) I is called the **index set**. Define

$$\bigcup_{i \in I} S_i = \bigcup_{T \in S(I)} T \quad \bigcap_{i \in I} S_i = \bigcap_{T \in S(I)} T$$

Note that $S(I)$ is the image of the function S .

Example 1.11. In the union $\bigcup_{x \in (1, +\infty)} [0, x)$, the index set is $I = (1, +\infty)$, and X can be the set of real numbers \mathbb{R} . Then $S : I \rightarrow 2^X$ is defined to be $S_i = S(i) = [0, i)$.

Exercise 1.12. Let $f : A \rightarrow B$ be a function. We say that f is **injective** if for all $a_1, a_2 \in A$ satisfying $a_1 \neq a_2$ we have $f(a_1) \neq f(a_2)$. We say that f is **surjective** if for each $b \in B$ we have $f^{-1}(b) \neq \emptyset$. f is called **bijective** if it is both surjective and injective. Define the **identity maps** $\text{id}_A : A \rightarrow A, a \mapsto a$ and id_B in a similar way. Prove that

$$f \text{ is injective} \iff \text{there is } g : B \rightarrow A \text{ such that } g \circ f = \text{id}_A \quad (1.6a)$$

$$f \text{ is surjective} \iff \text{there is } g : B \rightarrow A \text{ such that } f \circ g = \text{id}_B \quad (1.6b)$$

$$f \text{ is bijective} \iff \text{there is } g : B \rightarrow A \text{ such that } g \circ f = \text{id}_A \text{ and } f \circ g = \text{id}_B \quad (1.6c)$$

Show that the g in (1.6a) (resp. (1.6b), (1.6c)) is surjective (resp. injective, bijective).

The equivalence (1.6b) is subtler, since its proof requires Axiom of Choice.

Axiom. Let $(S_i)_{i \in I}$ be an indexed family of sets. The **Axiom of Choice** asserts that if $S_i \neq \emptyset$ for all $i \in I$, then there exists a function (the **choice function**)

$$f : I \rightarrow \bigcup_{i \in I} S_i$$

such that $f(i) \in S_i$ for each $i \in I$.

Intuitively, the axiom of choice says that for each $i \in I$ we can choose an element $f(i)$ of S_i . And such choice gives a function f .

Example 1.13. Let $f : A \rightarrow B$ be surjective. Then each member of the family $(f^{-1}(b))_{b \in B}$ is nonempty. Thus, by axiom of choice, there is a choice function g defined on the index set B such that $g(b) \in f^{-1}(b)$ for each b . Clearly $f \circ g = \text{id}_B$.

Remark 1.14. Suppose that each member S_i of the family $(S_i)_{i \in I}$ has exactly one element. Then the existence of a choice function does not require Axiom of Choice: Let $X = \bigcup_{i \in I} S_i$ and define relation

$$f = \{(i, x) \in I \times X : x \in S_i\}$$

Then one checks easily that this relation between I and X is a function, and that it is the (necessarily unique) choice function of $(S_i)_{i \in I}$.

According to the above remark, one does not need Axiom of Choice to prove (1.6a) and (1.6c). Can you see why?

1.2 Partial and total orders, equivalence relations

Definition 1.15. Let A be a set. A **partial order** (or simply an **order**) \leq on A is a relation on $A \times A$ satisfying for all $a, b, c \in A$ that:

- (Reflexivity) $a \leq a$.
- (Antisymmetry) If $a \leq b$ and $b \leq a$ then $a = b$.
- (Transitivity) If $a \leq b$ and $b \leq c$ then $a \leq c$.

We write $b \geq a$ iff $a \leq b$. Write $a > b$ iff $a \geq b$ and $a \neq b$. Write $a < b$ iff $b > a$. So \geq is also an order on A . The pair (A, \leq) is called a **partially ordered set**, or simply a **poset**. A partial order \leq on A is called a **total order**, if for every $a, b \in A$ we have either $a \leq b$ or $b \leq a$.

Example 1.16. The following are examples of orders.

- Assume that \mathbb{R} exists. Then \mathbb{R} has the canonical total order, which restricts to the total order of \mathbb{Z} . This is the total order that everyone is familiar with.
- Let X be a set. Then $(2^X, \subset)$ is a poset.
- \mathbb{R}^2 is a poset, if we define $(a, b) \leq (c, d)$ to be $a \leq c$ and $b \leq d$.

Definition 1.17. A relation \sim on a set A is called an **equivalence relation**, if for all $a, b, c \in A$ we have

- (Reflexivity) $a \sim a$.
- (Symmetry) $a \sim b$ iff $b \sim a$.
- (Transitivity) If $a \sim b$ and $b \sim c$ then $a \sim c$.

Later, we will use the notions of partial orders and equivalence relation not just for a set, but for a collection of objects “larger” than a set. See Sec. 1.4.

Definition 1.18. Let A be a set, together with an equivalence relation \sim . Define a new set

$$A/\sim = \{[a] : a \in A\}$$

where the notion $[a]$ can be understood in the following two equivalent ways (we leave it to the readers to check the equivalence):

- (1) $[a]$ is a new symbol. We understand $[a]$ and $[b]$ as equal iff $a \sim b$.
- (2) $[a] = \{x \in A : x \sim a\}$

We call $[a]$ the **equivalence class** (or the **residue class**) of a , and call A/\sim the **quotient set** of A under \sim . The surjective map $\pi : a \in A \mapsto [a] \in A/\sim$ is called the **quotient map**.

Exercise 1.19. Prove that every surjective map is equivalent to a quotient map. More precisely, prove that for every surjection $f : A \rightarrow B$, there is an equivalence relation \sim on A and a bijective map $\Phi : A/\sim \rightarrow B$ such that the following diagram commutes (i.e. $f = \Phi \circ \pi$):

$$\begin{array}{ccc} & A & \\ \pi \swarrow & & \searrow f \\ A/\sim & \xrightarrow{\Phi} & B \end{array} \quad (1.7)$$

This is the first time we see commutative diagrams. Commutative diagrams are very useful for indicating that certain maps between sets are “equivalent” or are satisfying some more general relations. For example, (1.7) shows that the maps f and π are equivalent, and that this equivalence is implemented by the bijection Φ . The formal definition of commutative diagrams is the following:

Definition 1.20. A diagram (i.e. some sets denoted by symbols, and some maps denoted by arrows) is called a **commutative diagram**, if all directed paths in the diagram with the same start and endpoints lead to the same result.

Here is an example of commutative diagram in linear algebra. This example assumes some familiarity with the basic properties of vector spaces and linear maps.²

Example 1.21. Let V, W be vector spaces over a field \mathbb{F} with finite dimensions m, n respectively. Let e_1, \dots, e_m be a basis of V , and let $\varepsilon_1, \dots, \varepsilon_n$ be a basis of W . We know that there are unique linear isomorphisms $\Phi : \mathbb{F}^m \xrightarrow{\cong} V$ and $\Psi : \mathbb{F}^n \xrightarrow{\cong} W$ such that

$$\Phi(a_1, \dots, a_m) = a_1 e_1 + \dots + a_m e_m \quad \Psi(b_1, \dots, b_n) = b_1 \varepsilon_1 + \dots + b_n \varepsilon_n$$

Let $T : V \rightarrow W$ be a **linear map**, i.e., a map satisfying $T(a\xi + b\eta) = aT\xi + bT\eta$ for all $a, b \in \mathbb{F}, \xi, \eta \in V$. Then there is a unique $n \times m$ matrix $A \in \mathbb{F}^{n \times m}$ (viewed as a linear map $\mathbb{F}^m \rightarrow \mathbb{F}^n$ defined by matrix multiplication) such that the following diagram commutes:

$$\begin{array}{ccc} \mathbb{F}^m & \xrightarrow[\cong]{\Phi} & V \\ A \downarrow & & \downarrow T \\ \mathbb{F}^n & \xrightarrow[\cong]{\Psi} & W \end{array} \quad (1.8)$$

namely, $T\Phi = \Psi A$. This commutative diagram tells us that T is equivalent to its **matrix representation** A under the bases $e_\bullet, \varepsilon_\star$, and that this equivalence is implemented by the linear isomorphisms Φ (on the sources) and Ψ (on the targets).

Commutative diagrams are ubiquitous in mathematics. You should learn how to read commutative diagrams and understand their intuitive meanings. We will see more examples in the future of this course.

1.3 \mathbb{Q}, \mathbb{R} , and $\overline{\mathbb{R}} = [-\infty, +\infty]$

Using equivalence classes, one can construct rational numbers from integers, and real numbers from rationals. We leave the latter construction to the future, and discuss the construction of rationals here.

Example 1.22 (Construction of \mathbb{Q} from \mathbb{Z}). Define a relation on $\mathbb{Z} \times \mathbb{Z}^\times$ (where $\mathbb{Z}^\times = \mathbb{Z} \setminus \{0\}$) as follows. If $(a, b), (a', b') \in \mathbb{Z} \times \mathbb{Z}^\times$, we say $(a, b) \sim (a', b')$ iff $ab' = a'b$. It is a routine check that \sim is an equivalence relation. Let $\mathbb{Q} = (\mathbb{Z} \times \mathbb{Z}^\times) / \sim$, and write the equivalence class of (a, b) as a/b or $\frac{a}{b}$. Define additions and multiplications in \mathbb{Q} to be

$$\frac{a}{b} + \frac{c}{d} = \frac{ad + bc}{bd} \quad \frac{a}{b} \cdot \frac{c}{d} = \frac{ac}{bd}$$

²Again, we refer the readers to Internet or any Linear Algebra textbook (e.g. [Axl]) for the definition of vector spaces and linear maps.

We leave it to the readers to check that this definition is **well-defined**: If $(a, b) \sim (a', b')$ and $(c, d) \sim (c', d')$ then $(ad + bc, bd) \sim (a'd' + b'c', b'd')$ and $(ac, bd) \sim (a'c', b'd')$.

We regard \mathbb{Z} as a subset of \mathbb{Q} by identifying $n \in \mathbb{Z}$ with $\frac{n}{1}$. (This is possible since the map $n \in \mathbb{Z} \mapsto \frac{n}{1} \in \mathbb{Q}$ is injective.) Each $a/b \in \mathbb{Q}$ has additive inverse $\frac{-a}{b}$. If $a/b \in \mathbb{Q}$ is not zero (i.e. $(a, b) \not\sim (0, 1)$), then a/b has multiplicative inverse b/a . This makes \mathbb{Q} a field: the field of **rational numbers**.

If $a/b \in \mathbb{Q}$, we say $a/b \geq 0$ if $ab \geq 0$. Check that this is well-defined (i.e., if $(a, b) \sim (a', b')$, then $ab \geq 0$ iff $a'b' \geq 0$). More generally, if $a/b, c/d \in \mathbb{Q}$, we say $\frac{a}{b} \geq \frac{c}{d}$ if $\frac{a}{b} - \frac{c}{d} \geq 0$. Check that \geq is a total order on \mathbb{Q} . Check that \mathbb{Q} is an Archimedean ordered field, defined below. \square

Definition 1.23. A field \mathbb{F} , together with a total order \leq , is called an **ordered field**, if for every $a, b, c \in \mathbb{F}$ we have

- (Addition preserves \leq) If $a \leq b$ then $a + c \leq b + c$.
- (Multiplication by $\mathbb{F}_{\geq 0}$ preserves ≥ 0) If $a, b \geq 0$ then $ab \geq 0$.

These two properties relate \leq to $+$ and \cdot respectively.

Remark 1.24. Many familiar properties about inequalities in \mathbb{Q} hold for an ordered field. For instance:

$$\begin{aligned}
 a \geq b \wedge c \geq d &\implies a + c \geq b + d \\
 a \geq 0 &\iff -a \leq 0 \\
 a \geq 0 \wedge b \geq c &\iff ab \geq ac \\
 a \leq 0 \wedge b \geq c &\iff ab \leq a \\
 &a^2 \geq 0 \\
 0 < a \leq b &\implies 0 < b^{-1} \leq a^{-1}
 \end{aligned}$$

Check them yourself, or see [Rud-P, Prop. 1.18].

Definition 1.25. We say that an ordered field \mathbb{F} satisfies **Archimedean property** if for each $a, b \in \mathbb{F}$ we have

$$a > 0 \implies \exists n \in \mathbb{N} \text{ such that } na > b$$

where na means $\underbrace{a + \cdots + a}_n$.

Example 1.26. \mathbb{Q} satisfies Archimedean property. Indeed, let $a, b \in \mathbb{Q}$ and $a > 0$. Then $a = p/q$ and $b = r/s$ where $p, q, s \in \mathbb{Z}_+$ and $r \in \mathbb{Z}$. So $na > b$ where $n = q|r| + q$.

Prop. 1.29 gives an important application of Archimedean property. We will use this in the construction of \mathbb{R} from \mathbb{Q} , and in the proof that \mathbb{Q} is dense in \mathbb{R} .

Definition 1.27. Let \mathbb{F} be a field. A subset $\mathbb{E} \subset \mathbb{F}$ is called a **subfield** of \mathbb{F} , if \mathbb{E} contains the 1 of \mathbb{F} , and if \mathbb{E} is closed under the operations of addition, multiplication, taking negative, and taking inverse in \mathbb{F} (i.e. if $a, b \in \mathbb{E}$ then $a + b, ab, -a \in \mathbb{E}$, and $a^{-1} \in \mathbb{E}$ whenever $a \neq 0$). We also call \mathbb{F} a **field extension** of \mathbb{E} , since \mathbb{E} is clearly a field.

Note that if \mathbb{E} is a subfield of \mathbb{F} , the 0 of \mathbb{F} is in \mathbb{E} since $0 = 1 + (-1) \in \mathbb{E}$.

Definition 1.28. Let \mathbb{E} be an ordered field. A field extension \mathbb{F} of \mathbb{E} is called an **ordered field extension**, if \mathbb{F} is equipped with a total order \leq such that \mathbb{F} is an ordered field, and if the order \leq of \mathbb{F} restricts to that of \mathbb{E} . We also call \mathbb{E} an **ordered subfield** of \mathbb{F} .

Our typical example of ordered field extension will be $\mathbb{Q} \subset \mathbb{R}$.

Proposition 1.29. *Let \mathbb{F} be an ordered field extension of \mathbb{Q} . Assume that \mathbb{F} is Archimedean. Then for every $x, y \in \mathbb{F}$ satisfying $x < y$, there exists $p \in \mathbb{Q}$ such that $x < p < y$.*

Proof. Assume $x, y \in \mathbb{F}$ and $x < y$. Then $y - x > 0$ (since $y - x \neq 0$ and $-x + x \leq -x + y$). By Archimedean property, there exists $n \in \mathbb{Z}_+$ such that $n(y - x) > 1$. So $y - x > \frac{1}{n}$ and hence $x + \frac{1}{n} < y$.

Let us prove that the subset

$$A = \left\{ k \in \mathbb{Z} : \frac{k}{n} \leq x \right\}$$

is nonempty and bounded from above in \mathbb{Z} . By Archimedean property, there is $m \in \mathbb{Z}_+$ such that $m > nx$, i.e. $\frac{m}{n} > x$. So for each $k \in \mathbb{Z}_+$ satisfying $k \geq m$, we have $\frac{k}{n} = \frac{m}{n} + \frac{k-m}{n} > x$. Therefore, for each $k \in A$ we have $k < m$. So A is bounded above. By Archimedean property again, there is $l \in \mathbb{Z}_+$ such that $\frac{l}{n} > -x$. So $-\frac{l}{n} < x$, and hence A is nonempty.

We now use the fact that *every nonempty subset of \mathbb{Z} bounded above has a maximal element*. Let $k = \max A$. Since $k + 1 \notin A$, we have $x < \frac{k+1}{n}$. Since $\frac{k}{n} \leq x$, we have

$$\frac{k+1}{n} = \frac{k}{n} + \frac{1}{n} \leq x + \frac{1}{n} < y$$

This proves $x < p < y$ with $p = \frac{k+1}{n}$. □

To introduce \mathbb{R} formally, we need more definitions:

Definition 1.30. Let (X, \leq) be a poset and $E \subset X$. An **upper bound of E in X** is an element $x \in X$ satisfying $e \leq x$ for all $e \in E$. An upper bound $x \in X$ of E is called a **least upper bound** or a **supremum** if $x \leq y$ for every upper bound $y \in X$ of E . In this case, we write the supremum as $\sup E$. It is not hard to check that supremums are unique if they exist.

We leave it to the readers to define **lower bounds** and the **greatest lower bound** (if exists) of E , also called the **infimum** and is denoted by $\inf E$. \square

Definition 1.31. Let (X, \leq) be a poset. We say that X satisfies the **least-upper-bound property**, if every every nonempty subset $E \subset X$ which is bounded above (i.e. E has an upper bound) has a supremum in X . The **greatest-lower-bound property** is defined in the opposite way.

Example 1.32. \mathbb{Z} satisfies the least-upper-bound and the greatest-lower-bound property: Let $A \subset \mathbb{Z}$. If A is bounded above (resp. below), then the maximum $\max A$ (resp. minimum $\min A$) exists and is the supremum (resp. infimum) of A .

Example 1.33. Let X be a set. Then $(2^X, \subset)$ satisfies the least-upper-bound and the greatest-lower-bound property: Let $\mathcal{A} \subset 2^X$, i.e., \mathcal{A} is a set of subsets of X . Then \mathcal{A} is bounded from above by X , and is bounded from below by \emptyset . Moreover,

$$\sup \mathcal{A} = \bigcup_{A \in \mathcal{A}} A \quad \inf \mathcal{A} = \bigcap_{A \in \mathcal{A}} A$$

Theorem 1.34. *There is an ordered field extension of \mathbb{Q} which is Archimedian and satisfies the least-upper-bound property. This field is denoted by \mathbb{R} . Its elements are called **real numbers**.*

Thm. 1.34 will be proved in Ch. 6. Note that by taking negative, we see that \mathbb{R} also satisfies the greatest-lower-bound property.

Remark 1.35. The ordered field extensions satisfying the conditions in Thm. 1.34 are unique “up to isomorphisms”. (The words “**isomorphism**” and “equivalence” are often interchangeable, though “isomorphism” is more often used in the algebraic setting, whereas “equivalence” can be used in almost every context. For example, in point-set topology, “equivalence” means “homeomorphism”.) We leave it to the readers to give the precise statement. We will not use this uniqueness in this course.

Note that to compare two extensions \mathbb{F}, \mathbb{R} of \mathbb{Q} , it is very confusing to regard \mathbb{Q} as a subset of both \mathbb{F} and \mathbb{R} . You’d better consider two different injective maps $\tau : \mathbb{Q} \rightarrow \mathbb{F}$ and $\iota : \mathbb{Q} \rightarrow \mathbb{R}$ preserving the algebraic operations and the order of \mathbb{Q} , and use a commutative diagram to indicate that τ and ι are equivalent. (Thus, what’s happening here is that we have an equivalence of maps, not just an equivalence of the fields \mathbb{F} and \mathbb{R} .) \square

Definition 1.36. Let $-\infty, +\infty$ be two different symbols, and extend the total order \leq of \mathbb{R} to the **extended real line**

$$\overline{\mathbb{R}} = \mathbb{R} \cup \{-\infty, +\infty\}$$

by letting $-\infty < x < +\infty$ for all $x \in \mathbb{R}$. Define for each $x \in \mathbb{R}$ that

$$\begin{aligned} x \pm \infty &= \pm \infty + x = \pm \infty & +\infty - (-\infty) &= +\infty \\ x \cdot (\pm \infty) &= \pm \infty \cdot x = \begin{cases} \pm \infty & \text{if } x > 0 \\ \mp \infty & \text{if } x < 0 \end{cases} \\ \frac{x}{\pm \infty} &= 0 \\ \frac{\pm \infty}{x} &= x^{-1} \cdot (\pm \infty) \quad \text{if } x \neq 0 \end{aligned}$$

If $a, b \in \overline{\mathbb{R}}$ and $a \leq b$, we define **intervals** with endpoints a, b :

$$\begin{aligned} [a, b] &= \{x \in \overline{\mathbb{R}} : a \leq x \leq b\} & (a, b) &= \{x \in \overline{\mathbb{R}} : a < x < b\} \\ (a, b] &= \{x \in \overline{\mathbb{R}} : a < x \leq b\} & [a, b) &= \{x \in \overline{\mathbb{R}} : a \leq x < b\} \end{aligned} \tag{1.9}$$

So $\mathbb{R} = (-\infty, +\infty)$ and $\overline{\mathbb{R}} = [-\infty, +\infty]$. If a, b are in \mathbb{R} , we say that the corresponding interval is **bounded**.

In this course, unless otherwise stated, an interval always means one of the four sets in (1.9). The first two intervals are called respectively a **closed interval** and an **open interval**.

Remark 1.37. Clearly, every subset E of $\overline{\mathbb{R}}$ is bounded and has a supremum and an infimum. We have that $\sup E = +\infty$ iff E is not bounded above in \mathbb{R} , and that $\inf E = -\infty$ iff E is not bounded below in \mathbb{R} .

1.4 Cardinalities, countable sets, and product spaces Y^X

Definition 1.38. Let A and B be sets. We say that A and B have the same **cardinality** and write $\text{card}(A) = \text{card}(B)$ (or simply $A \approx B$), if there is a bijection $f : A \rightarrow B$. We write $\text{card}(A) \leq \text{card}(B)$ (or simply $A \lesssim B$) if A and a subset of B have the same cardinality.

Exercise 1.39. Show that $\text{card}(A) \leq \text{card}(B)$ iff there is an injection $f : A \rightarrow B$, iff there is a surjection $g : B \rightarrow A$. (You need either Axiom of Choice or its consequence (1.6b) to prove the last equivalence.)

It is clear that \approx is an equivalence relation on the collection of sets. It is also true that \lesssim is a partial order: Reflexivity and transitivity are easy to show. The proof of antisymmetry is more involved:

Theorem 1.40 (Schröder-Bernstein). *Let A, B be two sets. If $A \lesssim B$ and $B \lesssim A$, then $A \approx B$.*

★★ *Proof.* Assume WLOG that $A \subset B$. Let $f : B \rightarrow A$ be an injection. Let $A_n = f^n(A)$ defined inductively by $f^0(A) = A$, $f^n(A) = f(f^{n-1}(A))$. Let $B_n = f^n(B)$. Then

$$B_0 \supset A_0 \supset \cdots \supset B_n \supset A_n \supset B_{n+1} \supset \cdots$$

In particular, $C = \bigcap_{n \in \mathbb{N}} A_n$ equals $\bigcap_{n \in \mathbb{N}} B_n$. Note that f gives a bijection $B_n \setminus A_n \rightarrow B_{n+1} \setminus A_{n+1}$ (since f gives bijections $B_n \rightarrow B_{n+1}$ and $A_n \rightarrow A_{n+1}$). Therefore, we have a bijection $g : B \rightarrow A$ defined by

$$g(x) = \begin{cases} f(x) & \text{if } x \in B_n \setminus A_n \text{ for some } n \in \mathbb{N} \\ x & \text{otherwise} \end{cases}$$

where “otherwise” means either $x \in C$ or $x \in A_n \setminus B_{n+1}$ for some n . □

Intuition about the above proof: View B as an onion. The layers of B are $B_n \setminus A_n$ (the odd layers) and $A_n \setminus B_{n+1}$ (the even layers). The bijection g maps each odder layer to the subsequent odd one, and fixes the even layers and the core C .

Example 1.41. If $-\infty < a < b < +\infty$, then $(0, 1) \approx (a, b)$.

Proof. $f : (0, 1) \rightarrow (a, b)$ sending x to $(b - a)x + a$ is a bijection. □

Example 1.42. If $-\infty < a < b < +\infty$, then $\mathbb{R} \approx (a, b)$

Proof. By the previous example, it suffices to prove $\mathbb{R} \approx (-1, 1)$. The function

$$f : \mathbb{R} \rightarrow (-1, 1) \quad f(x) = \begin{cases} \frac{x}{1+x} & \text{if } x \geq 0 \\ -f(-x) & \text{if } x < 0 \end{cases} \quad (1.10)$$

is bijective. □

Alternatively, one may use the tangent function to give a bijection between $(-\pi/2, \pi/2)$ and \mathbb{R} . I have avoided this method, since (1.10) is more elementary than trigonometric functions. The mathematically rigorous definition of trigonometric functions and the verification of their well-known properties are far from easy tasks.

Proposition 1.43. *Let I be an interval with endpoints $a < b$ in $\overline{\mathbb{R}}$. Then $I \approx \mathbb{R}$.*

Proof. Let $A = (0, 1) \cup \{-\infty, +\infty\}$. By Exp. 1.42, we have

$$(a, b) \subset I \lesssim \overline{\mathbb{R}} \approx A \approx [0, 1] \subset (-2, 2) \approx (a, b)$$

So $I \approx \overline{\mathbb{R}}$ by Schröder-Bernstein Thm. 1.40. In particular, $\mathbb{R} = (-\infty, +\infty) \approx \overline{\mathbb{R}}$. □

Our next goal is to prove an exponential law $a^{b+c} = a^b \cdot a^c$ for cardinalities. For that purpose, we first need to define the set-theoretic operations that correspond to the summation $b + c$ and the exponential a^b .

Definition 1.49. We write $X = \bigsqcup_{\alpha \in \mathcal{A}} A_\alpha$ and call X the **disjoint union** of $(A_\alpha)_{\alpha \in \mathcal{A}}$, if $X = \bigcup_{\alpha \in \mathcal{A}} A_\alpha$ and $(A_\alpha)_{\alpha \in \mathcal{A}}$ is a family of pairwise disjoint sets (i.e. $A_\alpha \cap A_\beta = \emptyset$ if $\alpha \neq \beta$). If moreover $\mathcal{A} = \{1, \dots, n\}$, we write $X = A_1 \sqcup \dots \sqcup A_n$.

Definition 1.50. Let X, Y be sets. Then

$$Y^X = \{\text{functions } f : X \rightarrow Y\} \quad (1.11)$$

A more precise definition of Y^X (in the spirit of (1.4)) is $\{f \in X \times Y \mid f : X \rightarrow Y \text{ is a function}\}$. Note that by Rem. 1.7,

$$Y^\emptyset = \{\emptyset\} \quad (1.12)$$

This new notation is compatible with the old one $Y^n = Y \times \dots \times Y$:

Example 1.51. Let $n \in \mathbb{Z}_+$. We have $Y^{\{1, \dots, n\}} \approx Y^n$ due to the bijection

$$Y^{\{1, \dots, n\}} \rightarrow Y^n \quad f \mapsto (f(1), \dots, f(n))$$

Remark 1.52. The above example suggests that in the general case that X is not necessarily finite, we can view each function $f : X \rightarrow Y$ as $(f(x))_{x \in X}$, an **indexed family of elements** of Y with index set X . Thus, intuitively and hence not quite rigorously,

$$Y^X = \underbrace{Y \times Y \times \dots}_{\text{card}(X) \text{ pieces}} \quad (1.13)$$

This generalizes the intuition in Def. 1.8 that a function $f : \mathbb{Z}_+ \rightarrow Y$ is equivalently a sequence $(f(1), f(2), f(3), \dots)$.

The viewpoint that Y^X is a **product space** with index set X is very important and will be adopted frequently in this course. More generally, we can define: \square

Definition 1.53. Let $(X_i)_{i \in I}$ be a family of sets with index set I . Their **product space** is defined by

$$\prod_{i \in I} X_i = \{f \in \mathfrak{X}^I : f(i) \in X_i \text{ for all } i \in I\}$$

where $\mathfrak{X} = \bigcup_{i \in I} X_i$. If each X_i is nonempty, then $\prod_{i \in I} X_i$ is nonempty by Axiom of Choice. An element of $\prod_{i \in I} X_i$ is also written as $(f_i)_{i \in I}$ when the i -th component of it is $f_i \in X_i$.

In particular, if all X_i are equal to X , then $X^I = \prod_{i \in I} X$.

Example 1.54. Let X be a set. For each $A \subset X$, define the **characteristic function** $\chi_A : X \rightarrow \{0, 1\}$ to be

$$\chi_A(x) = \begin{cases} 1 & \text{if } x \in A \\ 0 & \text{if } x \notin A \end{cases}$$

Then we have

$$2^X \approx \{0, 1\}^X$$

since the following map is bijective:

$$2^X \rightarrow \{0, 1\}^X \quad A \mapsto \chi_A$$

Its inverse is $f \in \{0, 1\}^X \mapsto f^{-1}(1) \in 2^X$.

Proposition 1.55 (Exponential Law). *Suppose that $X = A_1 \sqcup \cdots \sqcup A_n$. Then*

$$Y^X \approx Y^{A_1} \times \cdots \times Y^{A_n}$$

Proof. We have a bijection

$$\begin{aligned} \Phi : Y^X &\rightarrow Y^{A_1} \times \cdots \times Y^{A_n} \\ f &\mapsto (f|_{A_1}, \dots, f|_{A_n}) \end{aligned} \tag{1.14}$$

where we recall that $f|_{A_i}$ is the restriction of f to A_i . □

Exercise 1.56. Assume that A_1, \dots, A_n are subsets of X . Define Φ by (1.14). Prove that Φ is injective iff $X = A_1 \cup \cdots \cup A_n$. Prove that Φ is surjective iff A_1, \dots, A_n are pairwise disjoint.

Corollary 1.57. *Let X, Y be finite sets with cardinalities $m, n \in \mathbb{N}$ respectively. Assume that $Y \neq \emptyset$. Then Y^X is a finite set with cardinality n^m .*

Proof. The special case that $m = 0$ (i.e. $X = \emptyset$, cf. (1.12)) and $m = 1$ is clear. When $m > 1$, assume WLOG that $X = \{1, \dots, m\}$. Then $X = \{1\} \sqcup \cdots \sqcup \{m\}$. Apply Prop. 1.55 to this disjoint union. We see that $Y^X \simeq Y \times \cdots \times Y \simeq \{1, \dots, n\}^m$ has n^m elements. □

We end this section with some (in)equalities about the cardinalities of product spaces. To begin with, we write $X \lesssim Y$ (or $\text{card}(X) < \text{card}(Y)$) if $X \lesssim Y$ and $X \not\approx Y$.

Proposition 1.58. *Let X, Y be sets with $\text{card}(Y) \geq 2$ (i.e. Y has at least two elements). Then $X \lesssim Y^X$. In particular, $X \lesssim 2^X$.*

Proof. The case $X = \emptyset$ is obvious since $0 < 1$. So we assume $Y \neq \emptyset$. Clearly $2^X \simeq \{0, 1\}^X$ is $\lesssim Y^X$. So it suffices to prove $X \lesssim 2^X$. Since the map $X \rightarrow 2^X$ sending x to $\{x\}$ is injective, $X \lesssim 2^X$. Let us prove $X \approx 2^X$.

Assume that $X \approx 2^X$. So there is a bijection $\Phi : X \rightarrow 2^X$ sending each $x \in X$ to a subset $\Phi(x)$ of X . Motivated by Russell's Paradox (1.3), we define

$$S = \{x \in X : x \notin \Phi(x)\}$$

Since Φ is surjective, there exists $y \in X$ such that $S = \Phi(y)$. If $y \in \Phi(y)$, then $y \in S$, and hence $y \notin \Phi(y)$ by the definition of S . If $y \notin \Phi(y)$, then $y \notin S$, and hence $y \in \Phi(y)$ by the definition of S . This gives a contradiction. \square

Remark 1.59. Write $\{1, \dots, n\}^X$ as n^X for short. Assuming that real numbers have decimal, binary, or (more generally) base- n representations where $n \in \mathbb{Z}_{\geq 2}$, then $\mathbb{R} \approx n^{\mathbb{N}}$. So by Prop. 1.58, $\mathbb{N} \lesssim \mathbb{R}$, i.e. \mathbb{R} is *uncountable*. The base- n representations of real numbers suggest that $\text{card}(n^{\mathbb{N}})$ is independent of n . This fact can be proved by elementary methods without resorting to the analysis of real numbers:

Theorem 1.60. *Let X be an infinite set. Then*

$$2^X \approx 3^X \approx 4^X \approx \dots \approx \mathbb{N}^X$$

Proof. First, we assume that $X = \mathbb{N}$. Clearly, for each $n \in \mathbb{Z}_{\geq 2}$ we have $2^X \lesssim n^X \lesssim \mathbb{N}^X$. Since elements of \mathbb{N}^X are subsets of $X \times \mathbb{N}$ (i.e. elements of $2^{X \times \mathbb{N}}$), we have

$$\mathbb{N}^X \subset 2^{X \times \mathbb{N}} \simeq 2^X$$

since $X \times \mathbb{N} \approx X$ by Thm. 1.46. So $2^X \approx n^X \approx \mathbb{N}^X$ by Schröder-Bernstein.

As pointed out earlier (cf. Thm. 1.48), it can be proved by Zorn's Lemma that $X \times \mathbb{N} \approx X$ for every infinite set X . So the same conclusion holds for such X . \square

2 Metric spaces

We first give an informal introduction to metric spaces, hoping to motivate the readers from a (relatively) historical perspective. It is okay if you do not understand all of the concepts mentioned in the introduction on the first read. Simply return to this section when you feel unmotivated while formally studying these concepts in later sections. (The same suggestion applies to all the introductory sections and historical comments in our notes.)

2.1 Introduction: what is point-set topology?

The method which has been used with success by Volterra and Hilbert consists in observing that a function (for instance a continuous one) can be replaced by a countable infinity of parameters. One treats the problem first as though one had only a finite number of parameters and then one goes to the limit... We believe that this method has played a useful role because it followed intuition, but that its time has passed... The most fruitful method in functional analysis seems to us to treat the element of which the functional depends directly as a variable and in the form in which it presents itself naturally.

— Fréchet, 1925 (cf. [Jah, Sec. 13.8])

In this chapter, we begin the study of point-set topology by learning one of its most important notions: metric spaces. Similar to [Rud-P], we prefer to introduce metric spaces and basic point-set topology at the early stage of our study. An obvious reason for doing so is that metric spaces provide a uniform language for the study of basic analysis problems in $\mathbb{R}, \mathbb{R}^n, \mathbb{C}^n$, and more generally in function spaces such as the space of continuous functions $C([a, b])$ on the interval $[a, b] \subset \mathbb{R}$. With the help of such a language, for example, many useful criteria for the convergence of series in \mathbb{R} and \mathbb{C} (e.g. root test, ratio test) are generalized straightforwardly to criteria for the *uniform* convergence of series of functions in $C([a, b])$.

Point-set topology was born in 1906 when Fréchet defined metric spaces, motivated mainly by the study of function spaces in analysis (i.e. *functional analysis*). Indeed, point-set topology and functional analysis are the two faces of the same coin: they both originated from the study of **functionals**, i.e., functions of functions. See for example (2.1). The core ideas of point-set topology are as follows:

- (1) Take X to be a set of functions defined on a “classical space” (e.g. the set of all continuous functions $f : [a, b] \rightarrow \mathbb{C}$). Then a functional is a function $S : X \rightarrow \mathbb{C}$. This is a generalization of functions on $\mathbb{R}, \mathbb{C}, \mathbb{R}^n, \mathbb{C}^n$ or on their subsets.

- (2) Unlike \mathbb{R}^n , a function space X is usually “infinite dimensional”. Thus, one may think that a functional S is a function with infinite variables. In point-set topology, this viewpoint is abandoned; the philosophy of point-set topology is diametrically opposed to that of multivariable calculus.³ Instead, one should view a functional S as a function with one variable x , where x denotes a general point of the function space X .
- (3) Rather than looking at each variable/component and doing explicit multivariable calculations, one uses geometric intuitions to study the analytic properties of functionals.⁴ These geometric intuitions (e.g. distances, open balls, convergence) are borrowed from \mathbb{R} and \mathbb{R}^n and are mostly irrelevant to dimensions or numbers of variables.

(Sequential) **compactness**, **completeness**, and **separability** are prominent geometric properties that are useful in the study of the analytic properties of functionals. The importance of these three notions was already recognized by Fréchet by the time he defined metric spaces. The study of these three properties will be a main theme of our course.

Consider sequential compactness for example. The application of compactness to function spaces originated from the problems in calculus of variations. For instance, let $L(x, y, z)$ be a polynomial or (more generally) a continuous function in 3 variables. We want to find a “good” (e.g. differentiable) function $f : [0, 1] \rightarrow \mathbb{R}$ minimizing or maximizing the expression

$$S(f) = \int_0^1 L(t, f(t), f'(t)) dt \quad (2.1a)$$

This is the general setting of Lagrangian mechanics. In the theory of integral equations, one considers the extreme values and points of the functional

$$S(f) = \int_0^1 \int_0^1 f(x) K(x, y) \overline{f(y)} dx dy \quad (2.1b)$$

where $K : [0, 1]^2 \rightarrow \mathbb{R}$ is continuous and $f : [0, 1] \rightarrow \mathbb{C}$ is subject to the condition $\int_0^1 |f(x)|^2 dx \leq 1$. Any f maximizing (resp. minimizing) $S(f)$ is an eigenvector of the linear operator $g \mapsto \int_0^1 K(x, y) g(y) dy$ with maximal (resp. minimal) eigenvalue.

As we shall learn, (sequential) compactness is closely related to the problem of finding (or proving the existence of) maximal/minimal values of a continuous

³Very often, the formula of $S(f)$ involves an integral. See e.g. (2.1). Mathematicians (e.g. Volterra, Lévy, Fredholm, and early Hilbert) used to study $S(f)$ by discretizing $S(f)$, i.e., by approximating integrals by finite sums. Thus, S is approximated by a sequence of functions with n variables where $n \rightarrow \infty$. This viewpoint is abandoned in point-set topology.

⁴This is similar to linear algebra where one prefers vectors, linear subspaces, and linear operators to n -tuples, sets of solutions, and matrices.

function and the points at which the function attains its maximum/minimum. So, in 19th century, when people were already familiar with sequential compactness in \mathbb{R}^n (e.g. Bolzano-Weierstrass theorem, Heine-Borel theorem), they applied compactness to function spaces and functionals. The idea is simple: Suppose we are given X , a set of functions (say continuous and differentiable) from $[a, b]$ to \mathbb{R} . We want to find $f \in X$ maximizing $S(f)$. Here is an explicit process (see also the proof of Lem. 3.2):

- (A) Find a sequence $(f_n)_{n \in \mathbb{Z}_+}$ in X such that $S(f_n)$ increases to $M = \sup S(X)$.
- (B) Define convergence in X in a suitable way, and verify that $S : X \rightarrow \mathbb{R}$ is continuous (i.e. if f_n converges to f in the way we define, then $S(f_n) \rightarrow S(f)$).
- (C) Suppose we can find a subsequence $(f_{n_k})_{k \in \mathbb{Z}_+}$ converging to some $f \in X$, then S attains its maximum at f . In particular, $S(f) = M$ and hence $M < +\infty$.

To carry out step (B), we need to define suitable geometric structures for a function space X so that the convergence of sequences in X and the continuity of functions $S : X \rightarrow \mathbb{R}$ can be defined and studied in a similar pattern as that for \mathbb{R}^n . **Metric** (of a metric space) and **topology** (of a topological space) are such geometric structures. As we shall learn, the topology of a metric space is uniquely determined by the convergence of sequences in this space.

Step (C) can be carried out if every sequence in X has a convergent subsequence, i.e., if X is sequentially compact. Thus, we need a good criterion for sequential compactness for subsets of a function space. Arzelà-Ascoli theorem, the $C([a, b])$ -version of Heine-Borel theorem, is such a criterion. This famous theorem was proved in late 19th century (and hence before the birth of point-set topology), and it gave an important motivation for Fréchet to consider metric spaces in general. We will learn this theorem at the end of the first semester.

To summarize: Metric spaces are defined not just for fun. We introduce such geometric objects because we want to study the convergence of sequences and the analytic properties of continuous functions using geometric intuitions. And moreover, the examples we are interested in are not just subsets of \mathbb{R}^n , but also subsets of function spaces. With this in mind, we now begin our journey into point-set topology.

2.2 Basic definitions and examples

Definition 2.1. Let X be a set. A function $d : X \times X \rightarrow \mathbb{R}_{\geq 0}$ is called a **metric** if for all $x, y, z \in X$ we have

$$(1) \quad d(x, y) = d(y, x).$$

(2) $d(x, y) = 0$ iff $x = y$.

(3) (Triangle inequality) $d(x, z) \leq d(x, y) + d(y, z)$.

The pair (X, d) , or simply X , is called a **metric space**. If $x \in X$ and $r \in (0, +\infty]$,⁵ the set

$$B_X(x, r) = \{y \in X : d(x, y) < r\}$$

often abbreviated to $B(x, r)$, is called the **open ball** with center x and radius r . If $r \in [0, +\infty)$,

$$\overline{B}_X(x, r) = \{y \in X : d(x, y) \leq r\}$$

also abbreviated to $\overline{B}(x, r)$, is called the **closed ball** with center x and radius r .

We make some comments on this definition.

Remark 2.2. That “ $d(x, y) = 0$ iff $x = y$ ” is very useful. Think about X as a set of functions $[0, 1] \rightarrow \mathbb{R}$ and d is a metric on X . To show that $f, g \in X$ are equal, instead of checking that infinitely many values are equal (i.e. $f(t) = g(t)$ for all $t \in \mathbb{R}$), it suffices to check that one value (i.e. $d(f, g)$) is zero.

Remark 2.3. Triangle inequality clearly implies “polygon inequality”:

$$d(x_0, x_n) \leq \sum_{j=1}^n d(x_{j-1}, x_j) \quad (2.2)$$

Remark 2.4. Choose distinct points $x, y \in X$. Then x, y are separated by two open balls centered at them: there exists $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$. This is called the **Hausdorff property**.

To see this fact, note that $d(x, y) > 0$. Choose r, ρ such that $r + \rho \leq d(x, y)$. If $z \in B(x, r) \cap B(y, \rho)$, then $d(x, z) + d(y, z) < r + \rho \leq d(x, y)$, contradicting triangle inequality.

We will see (cf. Prop. 2.19) that Hausdorff property guarantees that any sequence in a metric space cannot converge to two different points. Intuition: one cannot find a point which is very close to x and y at the same time. \square

We give some examples, and leave it to the readers to check that they satisfy the definition of metric spaces. We assume that square roots of positive real numbers can be defined. (We will rigorously define square roots after we define e^x using the series $\sum_{n \in \mathbb{N}} x^n / n!$.)

Example 2.5. \mathbb{R} is a metric space if we define $d(x, y) = |x - y|$

⁵We want open and closed balls to be nonempty. So we assume $r \neq 0$ only for open balls.

Example 2.6. On \mathbb{R}^n , we can define **Euclidean metric**

$$d(x, y) = \sqrt{(x_1 - y_1)^2 + \cdots + (x_n - y_n)^2}$$

if x_\bullet, y_\bullet are the components of x, y . The following are also metrics:

$$\begin{aligned} d_1(x, y) &= |x_1 - y_1| + \cdots + |x_n - y_n| \\ d_\infty(x, y) &= \max\{|x_1 - y_1|, \dots, |x_n - y_n|\} \end{aligned}$$

Example 2.7. The **Euclidean metric** on \mathbb{C}^n is

$$d(z, w) = \sqrt{|z_1 - w_1|^2 + \cdots + |z_n - w_n|^2}$$

which agrees with the Euclidean metric on \mathbb{R}^{2n} . The following are also metrics:

$$\begin{aligned} d_1(z, w) &= |z_1 - w_1| + \cdots + |z_n - w_n| \\ d_\infty(z, w) &= \max\{|z_1 - w_1|, \dots, |z_n - w_n|\} \end{aligned}$$

Convention 2.8. Unless otherwise stated, the metrics on \mathbb{R}^n and \mathbb{C}^n (and their subsets) are assumed to be the Euclidean metrics.

Remark 2.9. One may wonder what the subscripts $1, \infty$ mean. This notation is actually due to the general fact that

$$d_p(z, w) = \sqrt[p]{|z_1 - w_1|^p + \cdots + |z_n - w_n|^p}$$

is a metric where $1 \leq p < +\infty$, and $d_\infty = \lim_{q \rightarrow +\infty} d_q$. It is not easy to prove that d_p satisfies triangle inequality: one needs Minkowski inequality. For now, we will not use such general d_p . And we will discuss Minkowski inequality in later sections.

Example 2.10. Let $X = X_1 \times \cdots \times X_N$ where each X_i is a metric space with metric d_i . Write $x = (x_1, \dots, x_N) \in X$ and $y = (y_1, \dots, y_N) \in Y$. Then the following are metrics on X :

$$\begin{aligned} d(x, y) &= d_1(x_1, y_1) + \cdots + d_N(x_N, y_N) \\ \delta(x, y) &= \max\{d_1(x_1, y_1), \dots, d_N(x_N, y_N)\} \\ \rho(x, y) &= \sqrt{d_1(x_1, y_1)^2 + \cdots + d_N(x_N, y_N)^2} \end{aligned}$$

With respect to the metric δ , the open balls of X are “polydisks”

$$B_X(x, r) = B_{X_1}(x_1, r) \times \cdots \times B_{X_N}(x_N, r)$$

There is no standard choice of metric on the product of metric spaces. d, δ, ρ are all good, and they are equivalent in the following sense:

Definition 2.11. We say that two metrics d_1, d_2 on a set X are **equivalent** and write $d_1 \approx d_2$, if there exist $\alpha, \beta > 0$ such that for any $x, y \in X$ we have

$$d_1(x, y) \leq \alpha d_2(x, y) \quad d_2(x, y) \leq \beta d_1(x, y)$$

This is an equivalence relation. More generally, we may write $d_1 \lesssim d_2$ if $d_1 \leq \alpha d_2$ for some $\alpha > 0$. Then $d_1 \approx d_2$ iff $d_1 \lesssim d_2$ and $d_2 \lesssim d_1$.

Example 2.12. In Exp. 2.10, we have $\delta \leq \rho \leq d \leq N\delta$. So $\delta \approx \rho \approx d$.

Convention 2.13. Given finitely many metric spaces X_1, \dots, X_N , the metric on their product space $X = X_1 \times \dots \times X_N$ is chosen to be any one that is equivalent to the ones defined in Exp. 2.10. In the case that each X_i is a subset of \mathbb{R} or \mathbb{C} , we follow Convention 2.8 and choose the metric on X to be the Euclidean metric (unless otherwise stated).

Definition 2.14. Let (X, d) be a metric space. Then a **metric subspace** is denoted an object $(Y, d|_Y)$ where $Y \subset X$ and $d|_Y$ is the restriction of d to Y , namely, for all $y_1, y_2 \in Y$ we set

$$d|_Y(y_1, y_2) = d(y_1, y_2)$$

Convention 2.15. Suppose Y is a subset of a given metric space (X, d) . Unless otherwise stated, the metric of Y is chosen to be $d|_Y$ whenever Y is viewed as a metric space. For example, the metric of any subset of \mathbb{R}^n is assumed to be the Euclidean metric, unless otherwise stated.

2.3 Convergence of sequences

Definition 2.16. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X . Let $x \in X$. We say that x is the **limit** of x_n and write $\lim_{n \rightarrow \infty} x_n = x$ (or $x_n \rightarrow x$), if:

- For every real number $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for every $n \geq N$ we have $d(x_n, x) < \varepsilon$.

Equivalently, this means that every (nonempty) open ball centered at x contains **all but finitely many** x_n .⁶

Remark 2.17. The negation of $x_n \rightarrow x$ is clear:

- There exists $\varepsilon > 0$ such that for all $N \in \mathbb{Z}_+$ there exists $n \geq N$ such that $d(x_n, x) \geq \varepsilon$.

⁶“All but finitely many x_n satisfies...” means “for all but finitely many n , x_n satisfies...”. It does NOT mean that “all but finitely many elements of the set $\{x_n : n \in \mathbb{Z}_+\}$ satisfies...”.

Namely, one changes each “for all” to “there exists”, changes each “there exists” to “for all”, and negate the last sentence.

Exercise 2.18. Show that in the above definition of limits, it suffices to consider rational numbers $\varepsilon > 0$. (Note: You need to use Prop. 1.29.)

This exercise implies that the definition of limits does not require the existence of real numbers, i.e., does not assume Thm. 1.34. Indeed, we will use limits of sequences (and “double sequences”) to prove Thm. 1.34.

In many textbooks and research papers, you will see phrases such as

$$x_n \text{ satisfies property } P \text{ for sufficiently large } n \quad (2.3)$$

This means that “there exists $N \in \mathbb{Z}_+$ such that P holds for all $n \geq N$ ”. (We also say that x_n **eventually** satisfies P .) Then $\lim_{n \rightarrow \infty} x_n = x$ means that “for every $\varepsilon > 0$, we have $d(x_n, x) < \varepsilon$ for sufficiently large n ”.

Proposition 2.19. Any sequence $(x_n)_{n \in \mathbb{Z}_+}$ in a metric space X has at most one limit.

Proof. Suppose $(x_n)_{n \in \mathbb{Z}_+}$ converges to $x, y \in X$ where $x \neq y$. By Hausdorff property (Rem. 2.4), there exist $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$. By the definition of $x_n \rightarrow x$, there exists $N_1 \in \mathbb{Z}_+$ such that $x_n \in B(x, r)$ for all $n \geq N_1$. Similarly, $x_n \rightarrow y$ means that there is $N_2 \in \mathbb{Z}_+$ such that $x_n \in B(y, \rho)$ for all $n \geq N_2$. Choose any $n \geq N_1, N_2$ (e.g. $n = \max\{N_1, N_2\}$). Then $x_n \in B(x, r) \cap B(y, \rho) = \emptyset$, impossible. \square

2.3.1 Methods for proving convergence and computing limits

Example 2.20. $\lim_{n \rightarrow \infty} \frac{1}{n} = 0$.

Proof. Choose any $\varepsilon \in \mathbb{Q}_{>0}$. By Archimedean property, there exists $N \in \mathbb{Z}_+$ such that $N\varepsilon > 1$, i.e. $1/N < \varepsilon$. Thus, for all $n \geq N$ we have $1/n < \varepsilon$. \square

Proposition 2.21. Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}\}$ and $(x_n), (y_n)$ be sequences in \mathbb{F} converging to $x, y \in \mathbb{R}$. If $x_n \leq y_n$ for all n , then $x \leq y$.

Proof. If $y < x$, let $\varepsilon = x - y$. Then all but finitely many members of (x_n) are in $(x - \varepsilon/2, x + \varepsilon/2)$, and all but finitely many members of (y_n) are in $(y - \varepsilon/2, y + \varepsilon/2)$. Since $y + \varepsilon/2 < x - \varepsilon/2$, there must exist n such that $y_n < x_n$. \square

Definition 2.22. If A and B are posets (or more generally, preordered sets, see Def. 5.1), we say a function $f : A \rightarrow B$ is **increasing** (resp. **strictly increasing**), if for each $x, y \in A$ we have

$$x \leq y \quad \implies \quad f(x) \leq f(y)$$

$$\begin{array}{ccc} & \text{resp.} & \\ x < y & \implies & f(x) < f(y) \end{array}$$

We leave the definitions of **decreasing** and **strictly decreasing** to the readers. We say that f is **monotonic** (resp. **strictly monotonic**), if f is either increasing or decreasing (resp. either strictly increasing or strictly decreasing).

Proposition 2.23. *Let $(x_n)_{n \in \mathbb{Z}}$ be a sequence in $[a, b] \subset \mathbb{R}$. If (x_n) is increasing (resp. decreasing), then $\lim_{n \rightarrow \infty} x_n$ equals $\sup\{x_n : n \in \mathbb{Z}_+\}$ (resp. $\inf\{x_n : n \in \mathbb{Z}_+\}$).*

Proof. Assume (x_n) increases. (The case of decreasing is similar and hence its proof is omitted.) Let $A = \sup\{x_n : n \in \mathbb{Z}_+\} < +\infty$. Then for each $\varepsilon > 0$ there is N such that $x_N > A - \varepsilon$ (since $A - \varepsilon$ is not an upper bound). Since (x_n) is increasing, for all $n \in \mathbb{N}$ we have $A - \varepsilon < x_n \leq A$ and so $|x_n - A| < \varepsilon$. \square

Example 2.24. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X , and let $x \in X$. It is easy to see that

$$\lim_{n \rightarrow \infty} x_n = x \iff \lim_{n \rightarrow \infty} d(x_n, x) = 0$$

Example 2.25. Suppose that (a_n) and (b_n) are sequences in $\mathbb{R}_{\geq 0}$, that $a_n \leq b_n$ for all n , and that $b_n \rightarrow 0$. Then $a_n \rightarrow 0$.

Proof. For each $\varepsilon > 0$, $[0, \varepsilon)$ contains all but finitely many b_n , and hence all but finitely many a_n . \square

More generally, we have:

Proposition 2.26 (Squeeze theorem). *Suppose that (x_n) is a sequence in a metric space X . Let $x \in X$. Suppose that there is a sequence (a_n) in $\mathbb{R}_{\geq 0}$ such that $\lim_{n \rightarrow \infty} a_n = 0$ and that $d(x_n, x) \leq a_n$ for all n . Then $\lim_{n \rightarrow \infty} x_n = x$.*

Proof. This follows immediately from Exp. 2.24 and 2.25. \square

The above proposition explains why many people say that “analysis is the art of inequalities”: It transforms the problem of convergence to the problem of finding a sequence $(a_n) \in \mathbb{R}_{\geq 0}$ converging to 0 such that the inequality $d(x_n, x) \leq a_n$ holds. And very often, a good (hard) analyst is one who knows how to find such good sequences!

Proposition 2.27. *Let $X = X_1 \times \cdots \times X_N$ be a product of metric spaces (X_i, d_i) . Let d be any of the three metrics of X in Exp. 2.10. Let $\mathbf{x}_n = (x_{1,n}, \dots, x_{N,n})$ be a sequence in X . Let $\mathbf{y} = (y_1, \dots, y_N)$. Then*

$$\lim_{n \rightarrow \infty} \mathbf{x}_n = \mathbf{y} \iff \lim_{n \rightarrow \infty} x_{i,n} = y_i \quad (\forall 1 \leq i \leq N)$$

Proof. We let d be the metric δ in Exp. 2.10, i.e. defined by $\max_j d_j(x_j, y_j)$. Now choose a sequence (x_n) and an element y in X . Then

$$x_n \rightarrow y \iff d_X(x_n, y) \rightarrow 0 \iff \max_{1 \leq j \leq N} d_j(x_{j,n}, y_j) \rightarrow 0 \quad (2.4)$$

Suppose that the RHS of (2.4) is true. Fix any $1 \leq i \leq N$. Then $d_i(x_{i,n}, y_i) \leq \max_j d_j(x_{j,n}, y_j)$. So $x_{i,n} \rightarrow y_i$ by Prop. 2.26.

Conversely, assume that for every i we have $x_{i,n} \rightarrow y_i$. Then for every $\varepsilon > 0$ there is $K_i \in \mathbb{Z}_+$ such that $d_i(x_{i,n}, y_i) < \varepsilon$ for every $n \geq K_i$. Let $K = \max\{K_1, \dots, K_N\}$. Then for all $n \geq K$ we have $\max_j d_j(x_{j,n}, y_j) < \varepsilon$. This proves the RHS of (2.4).

If d is one of the other two metrics in Exp. 2.10, one can either use a similar argument, or use the following important (but easy) fact. \square

Proposition 2.28. *Let d, δ be two equivalent metrics on a set X . Let $(x_n)_{n \in \mathbb{Z}_+}$ and x be in X . Then (x_n) converges to x under the metric d iff (x_n) converges to x under δ . Namely, $d(x_n, x) \rightarrow 0$ iff $\delta(x_n, x) \rightarrow 0$.*

Proof. Prove it yourself. (Or see Prop. 2.62.) \square

More useful formulas about limit will be given in Exp. 4.24.

2.3.2 Criteria for divergence

Definition 2.29. A subset E of a metric space (X, d) is called **bounded** if either $E = \emptyset$ or there exist $p \in X$ and $R \in \mathbb{R}_{>0}$ such that $E \subset B_X(p, R)$. If X is bounded, we also say that d is a **bounded metric**.

Remark 2.30. Note that if E is bounded, then for any $q \in X$ there exists $\tilde{R} \in \mathbb{R}_{>0}$ such that $E \subset B_X(q, \tilde{R})$. (Indeed, choose $\tilde{R} = R + d(p, q)$, then by triangle inequality, $B(p, R) \subset B(q, \tilde{R})$.)

Some easy examples are as follows.

Example 2.31. In a metric space X , if $x \in X$ and $0 < r < +\infty$, then $B(x, r)$ is bounded. Hence $\overline{B}(x, r)$ is bounded (since it is inside $B(x, 2r)$).

Also, it is easy to see:

Example 2.32. A finite union of bounded subsets is bounded.

Proposition 2.33. *Let $(x_n)_{n \in \mathbb{Z}_+}$ be a convergent sequence in a metric space X . Then $(x_n)_{n \in \mathbb{Z}_+}$ is bounded.*

By saying that a sequence $(x_n)_{n \in \mathbb{Z}_+}$ in X is **bounded**, we mean that its range in X (namely $\{x_n : n \in \mathbb{Z}_+\}$) is bounded.

Proof. Suppose that $x_n \rightarrow x$. Then for each $\varepsilon > 0$, say $\varepsilon = 1$, all but finitely many elements of x_n (say x_1, \dots, x_N) are in $B(x, 1)$. So this whole sequence is in $A = \{x_1\} \cup \dots \cup \{x_N\} \cup B(x, 1)$. Since each $\{x_i\}$ is bounded, and since $B(x, 1)$ is bounded, A is bounded by Exp. 2.32. \square

Remark 2.34. Prop. 2.33 gives our first criterion on divergence: If a sequence is unbounded (e.g. $x_n = n^2$), then it does not converge. But there are many bounded and divergent sequences. (See Exp. 2.37.) In this case, we need the second criterion: If a sequence has two subsequences converging to two different points, then this sequence diverge. (See Prop. 2.36)

Definition 2.35. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a set X . If $(n_k)_{k \in \mathbb{Z}_+}$ is a strictly increasing sequence in \mathbb{Z}_+ , we say that $(x_{n_k})_{k \in \mathbb{Z}_+}$ is a **subsequence** of $(x_n)_{n \in \mathbb{Z}_+}$.

Thus, a subsequence of $(x_n)_{n \in \mathbb{Z}_+}$ is equivalently the restriction of the function $x : \mathbb{Z}_+ \rightarrow X$ to an infinite subset of \mathbb{Z}_+ .

Proposition 2.36. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in a metric space X converging to $x \in X$. Then every subsequence $(x_{n_k})_{k \in \mathbb{Z}_+}$ converges to x .

Proof. For every $\varepsilon > 0$, $B(x, \varepsilon)$ contains all but finitely many $\{x_n : n \in \mathbb{Z}_+\}$, and hence all but finitely many $\{x_{n_k} : k \in \mathbb{Z}_+\}$. \square

Example 2.37. The sequence $x_n = (-1)^n$ in \mathbb{R} is divergent, because the subsequence $(x_{2k})_{k \in \mathbb{Z}_+}$ converges to 1, whereas $(x_{2k-1})_{k \in \mathbb{Z}_+}$ converges to -1 .

One may wonder if the two criteria in Rem. 2.34 are complete in order to determine whether a sequence diverges. This is true for sequences in \mathbb{R}^n . We will discuss this topic later. (See Cor. 3.17.)

2.4 Continuous maps of metric spaces

Continuous maps are a powerful tool for showing that a sequence converges.

Definition 2.38. Let $f : X \rightarrow Y$ be a map of metric spaces. Let $x \in X$. We say that f is **continuous at x** if one of the following equivalent conditions hold:

(1) For every sequence $(x_n)_{n \in \mathbb{Z}_+}$ in X , we have

$$\lim_{n \rightarrow \infty} x_n = x \quad \implies \quad \lim_{n \rightarrow \infty} f(x_n) = f(x)$$

(2) For every $\varepsilon > 0$, there exists $\delta > 0$ such that for every $p \in X$ satisfying $d(p, x) < \delta$, we have $d(f(p), f(x)) < \varepsilon$.

(2') For every $\varepsilon > 0$, there exists $\delta > 0$ such that $B_X(x, \delta) \subset f^{-1}(B_Y(f(x), \varepsilon))$.

We say that f is a **continuous map/function**, if f is continuous at every point of X .

Proof of the equivalence. (2) \Leftrightarrow (2'): Obvious.

(2) \Rightarrow (1): Assume (2). Assume $x_n \rightarrow x$. For every $\varepsilon > 0$, let $\delta > 0$ be as in (2). Then since $x_n \rightarrow x$, there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $d(x_n, x) < \delta$. By (2), we have $d(f(x_n), f(x)) < \varepsilon$ for all $n \geq N$. This proves $f(x_n) \rightarrow f(x)$.

$\neg(2) \Rightarrow \neg(1)$: Assume that (2) is not true. Then there exists $\varepsilon > 0$ such that for every $\delta > 0$, there exists $p \in X$ such that $d(p, x) < \delta$ and $d(f(p), f(x)) \geq \varepsilon$. Thus, for every $n \in \mathbb{Z}_+$, by taking $\delta = 1/n$, we see that there exists $x_n \in X$ such that $d(x_n, x) < 1/n$ and $d(f(x_n), f(x)) \geq \varepsilon$. By Squeeze theorem (Prop. 2.26), $x_n \rightarrow x$. But $f(x_n) \not\rightarrow f(x)$ (i.e. $d(f(x_n), f(x)) \not\rightarrow 0$). So (1) is not true. \square

Remark 2.39. One can compare Def. 2.38-(1) to the definition of linear maps. A map is continuous iff it *preserves the convergence of sequences*, i.e., iff it maps convergent sequences to convergent ones. A map (between vector spaces) is linear iff it preserves the addition and the scalar multiplication of vectors. In general, a good map between two sets with “structures” is a map which preserves the structures. (Thus, linear combinations encode the linear structures of vector spaces. Similarly, the convergence of sequences remembers the “topological” structures of metric spaces.) As another example, we will define an isometry of metric spaces to be one that preserves the metrics (the structures of metric spaces), see Exe. 2.63.

Remark 2.40. In this section, we mainly use Def. 2.38-(1) to study continuity. But in later sections we will also use Def. 2.38-(2'). An advantage of (2') is that it is more geometric. Indeed, if X is a metric space and $E \subset X$, we say that $x \in E$ is an **interior point of E in X** if there exists $\delta > 0$ such that $B_X(x, \delta) \subset E$. For example, a point $z \in \mathbb{C}$ is an interior point of the closed unit disk $\overline{B}_{\mathbb{C}}(0, 1) = \{w \in \mathbb{C} : |w| \leq 1\}$ iff $|z| < 1$.

Thus, Def. 2.38-(2') says that for any map of metric spaces $f : X \rightarrow Y$ and $x \in X$, the following are equivalent:

- (a) f is continuous at x .
- (b) For each $\varepsilon > 0$, every $x \in X$ is an interior point of $f^{-1}(B_Y(f(x), \varepsilon))$.

We say that a subset $U \subset X$ is **open** if each point of U is an interior point. For example, by triangle inequality, every open ball in a metric space is an open set. Thus, we have:

- A map of metric spaces $f : X \rightarrow Y$ is continuous iff the preimage under f of every open ball of Y is an open subset of X .

In the study of point-set topology, we will see that many properties can be studied in two approaches: using sequences (or using nets, the natural generalizations of sequences) and their convergence, and using open sets. The first example

of such property is continuity, as we have seen in Def. 2.38. Another prominent example is sequential compactness vs. compactness. These two approaches represent two (very) different intuitions: one is dynamic, while the other is static and more geometric. (So it is surprising that these two very things are actually equivalent!) Sometimes both approaches work for a problem, but sometimes only one of them works, or one of them is much simpler. If you are a beginner in analysis and point-set topology, I suggest that whenever you see one approach applied to a problem, try to think about whether the other approach also works and which one is better. \square

2.4.1 Methods for proving continuity

Lemma 2.41. *Let $f : X \rightarrow Y$ be a map of metric spaces. Let $(B_i)_{i \in I}$ be a collection of open balls in X such that $X = \bigcup_{i \in I} B_i$. Suppose that for each i , the restriction $f|_{B_i} : B_i \rightarrow Y$ is continuous. Then f is continuous.*

This lemma shows that if we can prove that f is “locally” continuous, then f is globally continuous.

Proof. Choose (x_n) in X converging to $x \in X$. We shall show $f(x_n) \rightarrow f(x)$. Choose i such that $x \in B_i$. Then one can find $\delta > 0$ such that $B(x, \delta) \subset B_i$. (In the language of point-set topology: x is an interior point of B_i .) To see this, write $B_i = B(y, r)$. Since $x \in B(y, r)$, we have $r - d(x, y) > 0$. Choose $0 < \delta \leq r - d(x, y)$. Then triangle inequality implies $B(x, \delta) \subset B(y, r)$.

Since $x_n \rightarrow x$, there is $N \in \mathbb{Z}_+$ such that $x_n \in B(x, \delta)$ for all $n \geq N$. Thus, $(x_{k+N})_{k \in \mathbb{Z}_+}$ converges in B_i to x . Since $f|_{B_i}$ is continuous, $\lim_{k \rightarrow \infty} f(x_{k+N}) = f(x)$. So $f(x_n) \rightarrow f(x)$. \square

Definition 2.42. A map of metric spaces $f : X \rightarrow Y$ is called **Lipschitz continuous** if there exists $L \in \mathbb{R}_{>0}$ (called **Lipschitz constant**) such that for all $x_1, x_2 \in X$,

$$d_Y(f(x_1), f(x_2)) \leq L \cdot d_X(x_1, x_2) \quad (2.5)$$

Lemma 2.43. *Lipschitz continuous maps are continuous.*

Proof. Suppose that $f : X \rightarrow Y$ is Lipschitz continuous with Lipschitz constant L . Suppose $x_n \rightarrow x$ in X . Then $L \cdot d(x_n, x) \rightarrow 0$. By (2.5) and Squeeze theorem (Prop. 2.26), $f(x_n) \rightarrow f(x)$. (You can also use Def. 2.38-(2) to prove this lemma.) \square

Example 2.44. Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. The map $z \in \mathbb{F} \setminus \{0\} \mapsto z^{-1} \in \mathbb{F}$ is continuous.

Proof. Let this map be f . Since \mathbb{F} is covered by open balls $B(z, \delta)$ where $z \in \mathbb{F} \setminus \{0\}$ and $0 < \delta < |z|$, by Lem. 2.41, it suffices to prove that f is continuous when restricted to every such $B(z, \delta)$. Let $\varepsilon = |z| - \delta > 0$. Choose $x, y \in B(z, \delta)$. Then $|x| = |x - z + z| \geq |z| - |z - x| > \varepsilon$ by triangle inequality. Similarly, $|y| > \varepsilon$. So

$$|f(x) - f(y)| = |x^{-1} - y^{-1}| = |x - y|/|xy| \leq \varepsilon^{-2}|x - y|$$

So $f|_{B(z, \delta)}$ has Lipschitz constant ε^{-2} , and hence is continuous. \square

(Question: in the above proof, is the map $f : \mathbb{F} \setminus \{0\} \rightarrow \mathbb{F}$ Lipschitz continuous?)

We have given a fancy way of proving that if (z_n) is a sequence in $\mathbb{F} \setminus \{0\}$ converging to $z \in \mathbb{F} \setminus \{0\}$, then $z_n^{-1} \rightarrow z^{-1}$. You should think about how to prove this fact directly using $\varepsilon - N$ language, and compare your proof with the above proof to find the similarities!

Proposition 2.45. *Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. Then the following maps are continuous:*

$$\begin{aligned} + : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto x + y \\ - : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto x - y \\ \times : \mathbb{F} \times \mathbb{F} &\rightarrow \mathbb{F} & (x, y) &\mapsto xy \\ \div : \mathbb{F} \times \mathbb{F}^\times &\rightarrow \mathbb{F} & (x, y) &\mapsto x/y \end{aligned}$$

Recall our Convention 2.13 on the metrics of finite product spaces.

Proof. We only prove that the last two are continuous: the first two can be treated in a similar (and easier) way.

Denote the multiplication map by μ . We choose the metric on \mathbb{F}^2 to be $d(\mathbf{x}, \mathbf{x}') = \max\{|x_1 - x'_1|, |x_2 - x'_2|\}$. Since $\mathbb{F} \times \mathbb{F}$ is covered by open balls of the form $B(0, r) = \{(x, y) \in \mathbb{F}^2 : |x| < r, |y| < r\}$ where $0 < r < +\infty$, by Lem. 2.41 and 2.43, it suffices to show that $\mu|_{B(0, r)}$ is Lipschitz continuous. This is true, since for each $(x, y), (x', y') \in B(0, r)$, we have

$$\begin{aligned} |\mu(x, y) - \mu(x', y')| &= |xy - x'y'| \leq |(x - x')y| + |x'(y - y')| \\ &< 2r \cdot \max\{|x - x'|, |y - y'|\} = 2r \cdot d((x, y), (x', y')) \end{aligned} \quad (2.6)$$

By Exp. 2.44 and Prop. 2.47, the map $(x, y) \in \mathbb{F} \times \mathbb{F}^\times \mapsto (x, y^{-1}) \in \mathbb{F} \times \mathbb{F}$ is continuous. So its composition with the continuous map μ is continuous, thanks to Prop. 2.46. So \div is continuous. \square

Proposition 2.46. *Suppose that $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ are continuous maps of metric spaces. Then $g \circ f : X \rightarrow Z$ is continuous.*

Proposition 2.47. *Suppose that $f_i : X_i \rightarrow Y_i$ is a map of metric spaces, where $1 \leq i \leq N$. Then the product map*

$$\begin{aligned} f_1 \times \cdots \times f_N : X_1 \times \cdots \times X_N &\rightarrow Y_1 \times \cdots \times Y_N \\ (x_1, \dots, x_N) &\mapsto (f_1(x_1), \dots, f_N(x_N)) \end{aligned}$$

is continuous if and only if f_1, \dots, f_N are continuous.

Proof of Prop. 2.46 and 2.47. Immediate from Def. 2.38-(1) and Prop. 2.27. \square

Corollary 2.48 (Squeeze theorem). *Let $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}\}$ and $(x_n), (y_n), (z_n)$ be sequences in \mathbb{R} . Assume that $x_n \leq y_n \leq z_n$ for all n . Assume that x_n and z_n both converge to $A \in \mathbb{R}$. Then $\lim_{n \rightarrow \infty} y_n = A$.*

Proof. Let $a_n = y_n - x_n$ and $b_n = z_n - x_n$. Then $0 \leq a_n \leq b_n$, and $\lim_n b_n = \lim_n z_n - \lim_n x_n = 0$ because the subtraction map is continuous (Prop. 2.45). By Exp. 2.25, $a_n \rightarrow 0$. Since $x_n \rightarrow A$, $y_n = x_n + a_n$ converges to A , since the addition map is continuous by Prop. 2.45. \square

Again, this is a fancy way of proving Squeeze theorem. The readers should know how to prove it directly from the definition of limits of sequences.

We give some more examples of continuous maps.

Example 2.49. By Prop. 2.45, $f(x, y, z) = x^2y + 5y^4z^7 - 3xyz^2$ is a continuous function on \mathbb{C}^3 . Clearly $z \in \mathbb{C} \mapsto \bar{z} \in \mathbb{C}$ is continuous. So $g(x, y, z) = f(\bar{x}, \bar{y}, z) + 2f(z, x^2, xy^{-9}) - 5xy^{-2}z^{-3}$ is a continuous function on $\mathbb{C} \times \mathbb{C}^\times \times \mathbb{C}^\times$.

Example 2.50. Let $f, g : X \rightarrow \mathbb{F}$ be continuous functions where $\mathbb{F} \in \{\mathbb{Q}, \mathbb{R}, \mathbb{C}\}$. Then by Prop. 2.45 and 2.46, $f \pm g$ and fg are continuous, and f/g is continuous when $0 \notin g(X)$. Here

$$(f \pm g)(x) = f(x) \pm g(x) \quad (fg)(x) = f(x)g(x) \quad (f/g)(x) = f(x)/g(x) \quad (2.7)$$

Example 2.51. Let $f : X \rightarrow Y$ be a map of metric spaces. Let E, F be subsets of X, Y respectively. (Recall that the metrics of subsets are chosen as in Def. 2.14.)

- The inclusion map $\iota_E : E \rightarrow X, x \mapsto x$ is clearly continuous. Thus, if f is continuous, then $f|_E : E \rightarrow Y$ is continuous, since $f|_E = f \circ \iota_E$.
- If $f(X) \subset F$, then we can restrict the codomain of f from Y to F : let $\tilde{f} : X \rightarrow F$ be $\tilde{f}(x) = f(x)$. Then it is clear that f is continuous iff \tilde{f} is continuous.

Proposition 2.52. Let X_1, \dots, X_N be metric spaces. The following projection is clearly continuous:

$$\pi_{X_i} : X_1 \times \dots \times X_N \rightarrow X_i \quad (x_1, \dots, x_N) \mapsto x_i$$

Proposition 2.53. Let $f_i : X \rightarrow Y_i$ be maps where X, Y_1, \dots, Y_N are continuous. Then

$$f_1 \vee \dots \vee f_N : X \rightarrow Y_1 \times \dots \times Y_N \quad x \mapsto (f_1(x), \dots, f_N(x))$$

is continuous iff f_1, \dots, f_N are continuous.

Example 2.54. Let X be a metric space. Then $d : X \times X \rightarrow \mathbb{R}, (x, y) \mapsto d(x, y)$ is Lipschitz continuous with Lipschitz constant 1 (by triangle inequality). So d is continuous.

Proposition 2.55. Let X be a metric space and $E \subset X$ is nonempty. Define **distance function**

$$d(\cdot, E) : X \rightarrow \mathbb{R}_{\geq 0} \quad d(x, E) = \inf_{e \in E} d(x, e)$$

Then $d(\cdot, E)$ has Lipschitz constant 1. So $d(\cdot, E)$ is continuous.

Proof. Choose any $x, y \in X$. By triangle inequality, for each $e \in E$ we have $d(x, e) \leq d(x, y) + d(y, e)$. Since $d(x, E) \leq d(x, e)$, we get $d(x, E) \leq d(x, y) + d(y, e)$. Applying $\inf_{e \in E}$ to the RHS gives $d(x, E) \leq d(x, y) + d(y, E)$. Hence $d(x, E) - d(y, E) \leq d(x, y)$. Exchanging x and y gives

$$|d(x, E) - d(y, E)| \leq d(x, y) \quad (2.8)$$

This proves that $d(\cdot, E)$ has Lipschitz constant 1. \square

Definition 2.56. More generally, if E, F are subsets of a metric space E , we can define

$$d(E, F) = \inf_{e \in E, f \in F} d(e, f) \quad (2.9)$$

to be the **distance between E and F** .

Exercise 2.57. Let $E, F \subset X$. Prove that

$$d(E, F) = \inf_{f \in F} d(E, f) \quad (2.10)$$

Example 2.58. If X is a metric space and $p \in X$, then by Prop. 2.55 (or simply by triangle inequality), the function $d_p : x \in X \mapsto d(x, p) \in \mathbb{R}$ has Lipschitz constant 1 and hence is continuous. In particular, if $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, the function $z \in \mathbb{F} \mapsto |z|$ is continuous (since $|z| = d_{\mathbb{F}}(z, 0)$). Thus, if $f : X \rightarrow \mathbb{F}$ is continuous, then $|f| : X \rightarrow \mathbb{R}_{\geq 0}$ is continuous where

$$|f|(x) = |f(x)| \quad (2.11)$$

Example 2.59. Let $N \in \mathbb{Z}_+$. Then the following function is continuous:

$$\max : \mathbb{R}^N \rightarrow \mathbb{R} \quad (x_1, \dots, x_N) \mapsto \max\{x_1, \dots, x_N\} \in \mathbb{R}$$

Similarly, the minimum function is continuous.

Proof. To avoid confusion, we write \max as \max_N . The case $N = 1$ is obvious. When $N = 2$, we have

$$\max(x_1, x_2) = \frac{x_1 + x_2 + |x_1 - x_2|}{2} \quad (2.12)$$

So \max_2 is continuous by Exp. 2.50 and 2.58.

We use induction. Suppose we have proved that \max_N is continuous. Then $\max_N \times \text{id}_{\mathbb{R}} : \mathbb{R}^N \times \mathbb{R} \rightarrow \mathbb{R} \times \mathbb{R}$ is continuous. So $\max_{N+1} = \max_2 \circ (\max_N \times \text{id}_{\mathbb{R}})$ is continuous. \square

2.5 Homeomorphisms and isometric isomorphisms; convergence in $\overline{\mathbb{R}}$

2.5.1 General theory

Definition 2.60. A bijection of metric spaces $f : X \rightarrow Y$ is called a **homeomorphism** if one of the following equivalent (cf. Def. 2.38) statements holds:

- (1) $f : X \rightarrow Y$ and its inverse map $f^{-1} : Y \rightarrow X$ are continuous.
- (2) For each sequence (x_n) in X and each $x \in X$, we have $\lim_{n \rightarrow \infty} x_n = x$ iff $\lim_{n \rightarrow \infty} f(x_n) = f(x)$.

If such f exists, we say that X, Y are **homeomorphic**.

A special case of the above definition is:

Definition 2.61. Let X be a set with metrics d, δ . We say that d and δ induce the **same topology** on X (or that d, δ are **topologically equivalent**) if one of the following clearly equivalent statements holds:

- (1) The map $(X, d) \rightarrow (X, \delta), x \mapsto x$ is a homeomorphism.⁷
- (2) For each sequence (x_n) in X and each $x \in X$, (x_n) converges to x under the metric d iff (x_n) converges to x under δ .

Proposition 2.62. Suppose that d, δ are equivalent metrics on a set X . Then d, δ are topologically equivalent.

Proof. Suppose $\delta \leq \alpha d$ and $d \leq \beta \delta$ for some $\alpha, \beta > 0$. Then the map $f : (X, d) \rightarrow (X, \delta), x \mapsto x$ and its inverse f^{-1} have Lipschitz constants α and β respectively. So f, f^{-1} are continuous. \square

Exercise 2.63. Let $f : X \rightarrow Y$ be a map of metric spaces. We say that $f : X \rightarrow Y$ is an **isometry** (or is **isometric**) if for all $x_1, x_2 \in X$ we have

$$d_Y(f(x_1), f(x_2)) = d_X(x_1, x_2) \quad (2.13)$$

Show that an isometry is injective and continuous.

We say that f is an **isometric isomorphism** if f is a surjective isometry. If an isometric isomorphism between two metric spaces X, Y exists, we say that X and Y are **isometric metric spaces**. Show that an isometric isomorphism is a homeomorphism. \square

⁷We prefer not to call this map the identity map, because the metrics on the source and on the target are different.

Remark 2.64. Isometric isomorphisms are important examples of homeomorphisms. That $f : X \rightarrow Y$ is an isometric isomorphism means that X and Y are equivalent as metric spaces, and that this equivalence can be implemented by the bijection f .

We now look at isometric isomorphisms in a different direction. Suppose that $f : X \rightarrow Y$ is a bijection of sets. Suppose that Y is a metric space. Then there is unique metric d_X on X such that f is an isometric isomorphism: one defines d_X using (2.13). We write such d_X as f^*d_Y , i.e.,

$$f^*d_Y(x_1, x_2) = d_Y(f(x_1), f(x_2))$$

and call f^*d_Y the **pullback metric** of d_Y by f . □

Pullback metrics are a very useful way of constructing metrics on a set. We consider some examples below.

Exercise 2.65. Two metrics inducing the same topology are not necessarily equivalent metrics. For example, let $f : [0, 1] \rightarrow [0, 1]$ be $f(x) = x^2$. Let $X = [0, 1]$, and let d_X be the Euclidean metric: $d_X(x, y) = |x - y|$. So

$$f^*d_X(x, y) = |x^2 - y^2|$$

is a metric on X . It is not hard to check that $f : (X, d_X) \rightarrow (X, d_X)$ is a homeomorphism. So d_X and f^*d_X give the same topology on $[0, 1]$ (cf. Exe. 2.66). Show that f^*d_X and d_X are not equivalent metrics.

Exercise 2.66. Let $f : X \rightarrow Y$ be a bijection of sets with metrics d_X, d_Y . Show that d_X and f^*d_Y give the same topology on X iff $f : (X, d_X) \rightarrow (Y, d_Y)$ is a homeomorphism.

In particular, if $f : X \rightarrow X$ is a bijection, and d_X is a metric on X . Then d_X and f^*d_X give the same topology on X iff $f : (X, d_X) \rightarrow (X, d_X)$ is a homeomorphism.

2.5.2 Convergence in $\overline{\mathbb{R}}$

Our second application of pullback metrics is the convergence in $\overline{\mathbb{R}}$.

Definition 2.67. We say that a sequence (x_n) in $\overline{\mathbb{R}}$ **converges to** $+\infty$ (resp. $-\infty$), if for every $A \in \mathbb{R}$ there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $x_n > A$ (resp. $x_n < A$).

Suppose $x \in \mathbb{R}$. We say that a sequence (x_n) in $\overline{\mathbb{R}}$ **converges to** x , if there is $N \in \mathbb{Z}_+$ such that $x_n \in \mathbb{R}$ for all $n \geq N$, and that the subsequence $(x_{k+N})_{k \in \mathbb{Z}_+}$ converges in \mathbb{R} to x . □

This notion of convergence is weird: it is not defined by a metric. So one wonders if there is a metric d on $\overline{\mathbb{R}}$ such that convergence of sequences under d agrees with that in Def. 2.67. We shall now find such a metric.

Lemma 2.68. Let $-\infty \leq a < b \leq +\infty$ and $-\infty \leq c < d \leq +\infty$. Then there is a strictly increasing bijective map $[a, b] \rightarrow [c, d]$.

Note that this map clearly sends a to c and b to d . So it restricts to strictly increasing bijections $(a, b) \rightarrow (c, d)$, $(a, b] \rightarrow (c, d]$, $[a, b) \rightarrow [c, d)$.

Proof. We have a strictly increasing bijection $f : \mathbb{R} \rightarrow (-1, 1)$ defined by (1.10). f can be extended to a strictly increasing bijective map $\overline{\mathbb{R}} \rightarrow [-1, 1]$ if we set $f(\pm\infty) = \pm 1$. Thus, f restricts to a strictly increasing bijection $[a, b] \rightarrow [f(a), f(b)]$. Choose a linear function $g(x) = \alpha x + \beta$ (where $\alpha > 0$) giving an increasing bijection $[f(a), f(b)] \rightarrow [0, 1]$. Then $h = g \circ f : [a, b] \rightarrow [0, 1]$ is a strictly increasing bijection. Similarly, we have a strictly increasing bijection $k : [c, d] \rightarrow [0, 1]$. Then $k^{-1} \circ h : [a, b] \rightarrow [c, d]$ is a strictly increasing bijection. \square

Theorem 2.69. Let $\varphi : \overline{\mathbb{R}} \rightarrow [a, b]$ be a strictly increasing bijective map where $[a, b] \subset \mathbb{R}$ is equipped with the Euclidean metric $d_{[a,b]}$. Then a sequence (x_n) in $\overline{\mathbb{R}}$ converges to $x \in \overline{\mathbb{R}}$ in the sense of Def. 2.67 iff $\varphi(x_n)$ converges to $\varphi(x)$ under the metric $d_{[a,b]}$. In other words, the convergence in $\overline{\mathbb{R}}$ is given by the metric $\varphi^* d_{[a,b]}$.

Proof. Let $y = \varphi(x)$ and $y_n = \varphi(x_n)$. We need to prove that $x_n \rightarrow x$ (in the sense of Def. 2.67) iff $y_n \rightarrow y$ (under the Euclidean metric). Write $\psi = \varphi^{-1}$, which is a strictly increasing map $[a, b] \rightarrow \overline{\mathbb{R}}$. Note that $\varphi(+\infty) = b$ and $\varphi(-\infty) = a$.

Case 1: $x \in \mathbb{R}$. By discarding the first several terms, we may assume that (x_n) is always in \mathbb{R} . If $x_n \rightarrow x$, then for every $\varepsilon > 0$, all but finitely many x_n are inside the open interval $(\psi(y - \varepsilon), \psi(y + \varepsilon))$. So all but finitely many y_n are inside $(y - \varepsilon, y + \varepsilon)$. So $y_n \rightarrow y$. That $y_n \rightarrow y$ implies $x_n \rightarrow x$ is proved in a similar way.

Case 2: $x = \pm\infty$. We consider $x = +\infty$ only; the other case is similar. Note that if $0 < \varepsilon < b - a$, then $B_{[a,b]}(b, \varepsilon) = (b - \varepsilon, b]$. If $x_n \rightarrow +\infty$, then for each $0 < \varepsilon < b - a$, all but finitely many x_n are $> \psi(b - \varepsilon)$. So all but finitely many y_n are inside $(b - \varepsilon, b]$. This proves $y_n \rightarrow b$. Conversely, if $y_n \rightarrow b$, then for each $A \in \mathbb{R}$, all but finitely many y_n are inside $(\varphi(A), b]$ and hence $> \varphi(A)$. So all but finitely many x_n are $> A$. \square

Convention 2.70. Unless otherwise stated, a metric on $\overline{\mathbb{R}}$ is one that makes Def. 2.67 true, for instance $\varphi^* d_{[a,b]}$ in Thm. 2.69. Unless otherwise stated, we do NOT view \mathbb{R} (or any subset of \mathbb{R}) as a metric subspace of $\overline{\mathbb{R}}$. Namely, we do not follow Convention 2.15 for $\mathbb{R} \subset \overline{\mathbb{R}}$, or more generally for $\mathbb{R}^N \subset \overline{\mathbb{R}}^N$. Instead, we choose Euclidean metrics on \mathbb{R}^N , following Convention 2.8.

The main reason for not following Convention 2.15 here is that metrics on $\overline{\mathbb{R}}$ are all bounded (by Prop. 3.7). Thus, every subset of \mathbb{R} is bounded if we view \mathbb{R} as a metric subspace of $\overline{\mathbb{R}}$. However, we want a subset of \mathbb{R} to be bounded precisely when it is contained in $[a, b]$ for some $-\infty < a < b < +\infty$. (Recall also Def. 1.36.)

After learning topological spaces, we shall forget about the metrics on $\overline{\mathbb{R}}$ and only care about its topology. (See Conv. 7.18.)

Remark 2.71. By Thm. 2.69, the properties of $[a, b]$ about convergence of sequences and inequalities can be transported to $\overline{\mathbb{R}}$, for example:

1. If $(x_n), (y_n)$ are sequences in $\overline{\mathbb{R}}$ converging to $A, B \in \overline{\mathbb{R}}$, and if $x_n \leq y_n$ for all n , then $A \leq B$.
2. **Squeeze theorem:** Suppose that $(x_n), (y_n), (z_n)$ are sequences in $\overline{\mathbb{R}}$, $x_n \leq y_n \leq z_n$ for all n , and x_n and z_n both converge to $A \in \overline{\mathbb{R}}$. Then $y_n \rightarrow A$.
3. Prop. 2.23 also holds for $[-\infty, +\infty] = \overline{\mathbb{R}}$: if (x_n) is an increasing resp. decreasing sequence in $\overline{\mathbb{R}}$, then $\lim_n x_n$ exists in $\overline{\mathbb{R}}$ and equals $\sup_n x_n$ resp. $\inf_n x_n$.

We will see more examples when studying \limsup and \liminf in the future.

We have shown that there is a metric on $\overline{\mathbb{R}}$ which defines the convergence in Def. 2.67. However, there is no standard choice of such a metric on $\overline{\mathbb{R}}$. Even worse, two possible choices of metrics might not be equivalent: Let $\varphi, \psi : \overline{\mathbb{R}} \rightarrow [0, 1]$ be a strictly increasing bijections where $\psi \circ \varphi^{-1} : [0, 1] \rightarrow [0, 1]$ is $x \mapsto x^2$. Then by Exe. 2.65, $\varphi^*d_{[0,1]}$ and $\psi^*d_{[0,1]}$ are non-equivalent but topologically equivalent metrics on $\overline{\mathbb{R}}$. This is the first example that metrics are not convenient for the description of convergence. When studying the convergence in $\overline{\mathbb{R}}$, thinking about metrics is distracting. In the future, we will see a better notion for the study of convergence: the notion of topological spaces.

We end this section with a generalization of Thm. 2.69.

Theorem 2.72. Let φ be a strictly increasing bijection in one of the following forms

$$\begin{array}{ll} [a, b] \rightarrow [c, d] & (a, b) \rightarrow (c, d) \\ (a, b] \rightarrow (c, d] & [a, b) \rightarrow [c, d) \end{array}$$

where $-\infty \leq a \leq b \leq +\infty$ and $-\infty \leq c \leq d \leq +\infty$. Then φ is a homeomorphism, i.e., if (x_n) and x are in the domain, then $x_n \rightarrow x$ iff $\varphi(x_n) \rightarrow \varphi(x)$ (in the sense of Def. 2.67).

Proof. The case $a = b$ is obvious. So we consider $a < b$, and hence $c < d$. We consider the left-open-right-closed case for example. The other cases are treated in a similar way. If the theorem can be proved for $(-\infty, +\infty] \rightarrow (c, d]$, then it can also be proved $(-\infty, +\infty] \rightarrow (a, b]$. By composing the inverse of the second map with the first map, we see that the theorem holds for $(a, b] \rightarrow (c, d]$.

Let us consider $\varphi : (-\infty, +\infty] \rightarrow (c, d]$. φ can be extended to a strictly increasing bijection $\varphi : \overline{\mathbb{R}} \rightarrow [c, d]$ by letting $\varphi(-\infty) = c$. It suffices to prove that this φ is a homeomorphism. When $-\infty < c < d < +\infty$, then the theorem holds by Thm. 2.69. If one of c, d is $\pm\infty$, the same argument as in the proof of Thm. 2.69 proves that φ is a homeomorphism. We leave it to the readers to fill in the details. \square

2.6 Problems and supplementary material

Definition 2.73. Let A be a subset of \mathbb{R} satisfying $x + y \in A$ for all $x, y \in A$. (Or more generally, let A be an abelian semigroup.) We say that a function $f : A \rightarrow \mathbb{R}$ is **subadditive** if for every $x, y \in A$ we have $f(x + y) \leq f(x) + f(y)$.

Problem 2.1. Consider the following increasing functions:

$$\begin{aligned} f_1 : \mathbb{R}_{\geq 0} &\rightarrow [0, 1) & f_1(x) &= \frac{x}{1+x} \\ f_2 : \mathbb{R}_{\geq 0} &\rightarrow [0, 1] & f_2(x) &= \min\{x, 1\} \end{aligned}$$

Prove that they are subadditive functions.

Problem 2.2. Let $f : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ be an increasing subadditive function satisfying the following conditions:

- (1) $f^{-1}(0) = \{0\}$.
- (2) For any $(x_n)_{n \in \mathbb{Z}_+}$ in $\mathbb{R}_{\geq 0}$ we have $x_n \rightarrow 0$ iff $f(x_n) \rightarrow 0$.

Let (X, d) be a metric space. Define

$$\delta : X \times X \rightarrow [0, A) \quad \delta(x, y) = f \circ d(x, y)$$

Prove that δ is a metric, and that δ and d are topologically equivalent.

Proposition 2.74. Let (X, d) be a metric space. Then there is a bounded metric δ on X such that d and δ are topologically equivalent.

Proof. Let f be either f_1 or f_2 defined in Pb. 2.1. Then f satisfies the assumptions in Pb. 2.2. So $\delta = f \circ d$ is a desired metric due to Pb. 2.2. We write down the formulas explicitly:

$$\delta_1(x, y) = \frac{d(x, y)}{1 + d(x, y)} \quad \delta_2(x, y) = \min\{d(x, y), 1\}$$

□

Problem 2.3. Let $(X_i, d_i)_{i \in \mathbb{Z}_+}$ be a sequence of metric spaces. Assume that $d_i \leq 1$ for each i . Let $S = \prod_{i \in \mathbb{Z}_+} X_i$. For each elements $f = (f(i))_{i \in \mathbb{Z}_+}$ and $g = (g(i))_{i \in \mathbb{Z}_+}$ of S , define

$$d(f, g) = \sup_{i \in \mathbb{Z}_+} \frac{d_i(f(i), g(i))}{i} \tag{2.14}$$

Prove that d is a metric on S . Let $f_n = (f_n(i))_{i \in \mathbb{Z}_+}$ be a sequence in S . Let $g \in S$. Prove that the following are equivalent:

(a) $\lim_{n \rightarrow \infty} f_n = g$ under the metric d .

(b) f_n **converges pointwise** to g , namely, $\lim_{n \rightarrow \infty} f_n(i) = g(i)$ for every $i \in \mathbb{Z}_+$.

Remark 2.75. The above problem gives our first non-trivial example of function spaces as metric spaces, where the domain of functions is a countable set. After learning series, the readers can check that

$$\delta(f, g) = \sum_{i \in \mathbb{Z}_+} 2^{-i} d_i(f(i), g(i)) \quad (2.15)$$

also defines a metric, and that (a) (with d replaced by δ) and (b) are equivalent. So δ and d (defined by (2.14)) induce the same topology on X , called the **pointwise convergence topology** or simply **product topology**. Unfortunately, if the index set \mathbb{Z}_+ is replaced by an uncountable set, there is in general no metric inducing the product topology. We will prove this in Pb. 7.9.

★ **Problem 2.4.** Let $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ be a disjoint union of metric spaces (X_α, d_α) . Assume that $d_\alpha \leq 1$ for all i . For each $x, y \in X$, define

$$d(x, y) = \begin{cases} d_\alpha(x, y) & \text{if } x, y \in X_\alpha \text{ for some } \alpha \in \mathcal{A} \\ \frac{1}{2} & \text{otherwise} \end{cases}$$

1. Prove that d defines a metric on X .
2. Choose $(x_n)_{n \in \mathbb{Z}_+}$ in X and $x \in X$. What does $\lim_{n \rightarrow \infty} x_n = x$ mean in terms of the convergence in each X_α ?

Think about the question: Let X be a set. For each $x, y \in X$ define $d(x, y) = 0$ if $x = y$, and $d(x, y) = 1$ if $x \neq y$. What does convergence in (X, d) mean?

3 Sequential compactness and completeness

3.1 Sequential compactness

3.1.1 Basic properties of sequentially compact spaces

Definition 3.1. Let X be a metric space. We say that X is **sequentially compact** if every sequence in X has a subsequence converging to some point of X .

The notion of sequential compactness is extremely useful for finding solutions in an analysis problem. In general, suppose we want to find a point $x \in X$ which makes a property $P(x)$ to be true. Suppose that we can find an “approximate solution”, i.e. an $y \in X$ such that $P(y)$ is close to being true. Thus, we can find a sequence (x_n) in X such that $P(x_n)$ is closer and closer to being true when $n \rightarrow \infty$. Now, if X is sequentially compact, then (x_n) has a subsequence (x_{n_k}) converging to $x \in X$. Then $P(x)$ is true, and hence x is a solution for the problem. (See also Sec. 2.1.) Let us see an explicit example:

Lemma 3.2 (Extreme value theorem). *Let X be a sequentially compact metric space. Let $f : X \rightarrow \mathbb{R}$ be a continuous function. Then f attains its maximum and minimum at points of X . In particular, $f(X)$ is a bounded subset of \mathbb{R} .*

This extremely important result is the main reason for introducing sequentially compact spaces. We call this a lemma, since we will substantially generalize this result later. (See Exe. 3.6.)

Note that the **boundedness** of subsets of \mathbb{R} (or more generally, of \mathbb{R}^N) is always understood under the Euclidean metric of \mathbb{R} , not under any metric of $\overline{\mathbb{R}}$ or $\overline{\mathbb{R}}^N$. (Recall Convention 2.70.)

Proof. We show that f attains its maximum on X . The proof for minimum is similar. Let $A = \sup f(X)$. Then $A \in (-\infty, +\infty]$. If $A < +\infty$, then for each $n \in \mathbb{Z}_+$ there is $x_n \in X$ such that $A - 1/n < f(x_n) \leq A$ (since $A - 1/n$ is not an upper bound of $f(X)$). If $A = +\infty$, then for each n there is $x_n \in X$ such that $f(x_n) > n$. In either case, we have a sequence (x_n) in X such that $f(x_n) \rightarrow A$ in $\overline{\mathbb{R}}$.

Since X is sequentially compact, (x_n) has a subsequence $(x_{n_k})_{k \in \mathbb{Z}_+}$ converging to some $x \in X$. Now, consider f as a map $f : X \rightarrow \overline{\mathbb{R}}$, which is continuous (cf. Exp. 2.51). Since $f(x_n) \rightarrow A$, its subsequence $f(x_{n_k})$ also converges to A . But since $x_{n_k} \rightarrow x$ and f is continuous at x , we have $A = f(x)$. So f attains its maximum at x . Since $f(X) \subset \mathbb{R}$, we have $A \in \mathbb{R}$. \square

The following are some elementary examples of sequential compactness:

Exercise 3.3. Show that finite unions of sequentially compact spaces is sequentially compact. (In particular, a finite set is sequentially compact.)

More precisely, let X be a metric space. Assume $X = A_1 \cup \cdots \cup A_N$ where each metric subspace A_i is sequentially compact. Show that X is sequentially compact.

Proposition 3.4. Let X_1, \dots, X_N be sequentially compact metric spaces. Then $X = X_1 \times \dots \times X_N$ is sequentially compact.

Proof. Since $X = (X_1 \times \dots \times X_{N-1}) \times X_N$, by induction, it suffices to assume $N = 2$. So we write $X = A \times B$ where A, B are sequentially compact. Let (a_n, b_n) be a sequence in X . Since A is sequentially compact, (a_n) has a convergent subsequence (a_{n_k}) . Since B is sequentially compact, (b_{n_k}) has a convergent subsequence $(b_{n_{k_l}})$. So $(a_{n_{k_l}}, b_{n_{k_l}})$ is a convergent subsequence of (a_n, b_n) . \square

Proposition 3.5. Let $f : X \rightarrow Y$ be a continuous map of metric spaces. Assume that X is sequentially compact. Then $f(X)$, as a metric subspace of Y , is sequentially compact.

Proof. Choose any sequence (y_n) in $f(X)$. We can write $y_n = f(x_n)$ where $x_n \in X$. Since X is sequentially compact, (x_n) has a subsequence (x_{n_k}) converging to some $x \in X$. Since f is continuous, $y_{n_k} = f(x_{n_k})$ converges to $f(x)$. \square

Exercise 3.6. Prove that if Y is a sequentially compact subset of \mathbb{R} , then $\sup Y \in Y$ and $\inf Y \in Y$. Therefore, Prop. 3.5 generalizes Lem. 3.2.

Proposition 3.7. Let X be a sequentially compact metric space. Then X is bounded under its metric d .

Proof. Choose any $p \in X$. The function $d_p : x \in X \mapsto d(x, p) \in \mathbb{R}_{\geq 0}$ is continuous by Exp. 2.58. So, by Lem. 3.2, d_p is bounded by some $0 < R < +\infty$. So $X = \overline{B_X(p, R)} \subset B_X(p, 2R)$. \square

3.1.2 Limits inferior and superior, and Bolzano-Weierstrass

The goal of this subsection is to prove that closed intervals are sequentially compact.

Definition 3.8. Let (x_n) be a sequence in a metric space X . We say that $x \in X$ is a **cluster point** of (x_n) , if (x_n) has a subsequence (x_{n_k}) converging to x .

Warning: In a general topological space, the cluster points of a sequence will be defined in a different way. (See Pb. 7.2 and Rem. 7.115.)

Definition 3.9. Let (x_n) be a sequence in $\overline{\mathbb{R}}$. Define

$$\alpha_n = \inf\{x_k : k \geq n\} \quad \beta_n = \sup\{x_k : k \geq n\} \quad (3.1)$$

It is clear that $\alpha_n \leq x_n \leq \beta_n$, that (α_n) is increasing and (β_n) is decreasing. Define

$$\liminf_{n \rightarrow \infty} x_n = \sup\{\alpha_n : n \in \mathbb{Z}_+\} = \lim_{n \rightarrow \infty} \alpha_n \quad (3.2a)$$

$$\limsup_{n \rightarrow \infty} x_n = \inf\{\beta_n : n \in \mathbb{Z}_+\} = \lim_{n \rightarrow \infty} \beta_n \quad (3.2b)$$

(cf. Rem. 2.71), called respectively the **limit inferior** and the **limit superior** of (x_n) .

Remark 3.10. Let $(x_n), (y_n)$ be sequences in $\overline{\mathbb{R}}$. Suppose that $x_n \leq y_n$ for every n . It is clear that

$$\liminf_{n \rightarrow \infty} x_n \leq \limsup_{n \rightarrow \infty} x_n \quad \liminf_{n \rightarrow \infty} x_n \leq \liminf_{n \rightarrow \infty} y_n \quad \limsup_{n \rightarrow \infty} x_n \leq \limsup_{n \rightarrow \infty} y_n$$

Theorem 3.11. Let (x_n) be a sequence in $\overline{\mathbb{R}}$, and let S be the set of cluster points of (x_n) . Then $\liminf_{n \rightarrow \infty} x_n$ and $\limsup_{n \rightarrow \infty} x_n$ belong to S . They are respectively the minimum and the maximum of S .

In particular, every sequence in $\overline{\mathbb{R}}$ has at least one cluster point.

Proof. We use the notations in Def. 3.9. Let $A = (3.2a)$ and $B = (3.2b)$. If $x \in S$, pick a subsequence (x_{n_k}) converging to x . Since $\alpha_{n_k} \leq x_{n_k} \leq \beta_{n_k}$, we have $A \leq x \leq B$ by Rem. 2.71. It remains to show that $A, B \in S$. We prove $B \in S$ by constructing a subsequence (x_{n_k}) converging to B ; the proof of $A \in S$ is similar.

Consider first of all the special case that (x_n) is bounded, i.e., is inside $[a, b] \subset \mathbb{R}$. Choose an arbitrary $n_1 \in \mathbb{Z}_+$. Suppose $n_1 < \dots < n_k$ have been constructed. By the definition of β_{1+n_k} , there is $n_{k+1} \geq 1 + n_k$ such that $x_{n_{k+1}}$ is close to β_{1+n_k} , say

$$\beta_{1+n_k} - \frac{1}{k} < x_{n_{k+1}} \leq \beta_{1+n_k} \quad (3.3)$$

Since the left most and the right most of (3.3) both converge to B as $k \rightarrow \infty$, by Squeeze theorem (Cor. 2.48) we conclude $\lim_k x_{n_k} = B$.

In general, by Lem. 2.68 and Thm. 2.72, there is an increasing (i.e. order-preserving) homeomorphism (i.e. topopogy-preserving map) $\varphi : \overline{\mathbb{R}} \rightarrow [0, 1]$. Then $\varphi(\beta_n) = \sup\{\varphi(x_k) : k \geq n\}$ (cf. Exe. 3.13) and $\varphi(B) = \lim_n \varphi(\beta_n)$. So $\varphi(B) = \limsup_n \varphi(x_n)$. By the above special case, $(\varphi(x_n))$ has a subsequence $(\varphi(x_{n_k}))$ converging to $\varphi(B)$. So (x_{n_k}) converges to B . \square

Remark 3.12. One can also prove the above general case directly using a similar idea as in the special case. And you are encouraged to do so! (Pay attention to the case $B = \pm\infty$.)

The proof given above belongs to a classical proof pattern: To prove that a space X satisfies some property, one first prove it in a convenient case. Then, in the general case, one finds an “isomorphism” (i.e. “equivalence” in a suitable sense) $\varphi : X \rightarrow Y$ where Y is in the convenient case. Then the result on Y can be translated via φ^{-1} to X , finishing the proof.

For example, to solve a linear algebra problem about linear maps between finite-dimensional vector spaces V, W , one first proves it in the special case that $V = \mathbb{F}^m$ and $W = \mathbb{F}^n$. Then, the general case can be translated to the special case via an equivalence as in Exp. 1.21. \square

Exercise 3.13. Let X, Y be posets. Let $\varphi : X \rightarrow Y$ be an increasing bijection whose inverse is also increasing. (Namely, φ induces an equivalence of posets). Suppose $E \subset X$ has supremum $\sup E$. Explain why $\varphi(E)$ has supremum $\varphi(\sup E)$.

It is now fairly easy to prove the famous

Theorem 3.14 (Bolzano-Weierstrass). *Let $[a_1, b_1], \dots, [a_N, b_N]$ be closed intervals in $\overline{\mathbb{R}}$. Then $[a_1, b_1] \times \dots \times [a_N, b_N]$ is sequentially compact.*

Proof. By Prop. 3.4, it suffices to assume $N = 1$. Write $a_1 = a, b_1 = b$. Let (x_n) be a sequence in $[a, b]$. By Thm. 3.11, (x_n) has a subsequence (x_{n_k}) converging to some $x \in \overline{\mathbb{R}}$. (E.g. $x = \limsup_n x_n$.) Since $a \leq x_{n_k} \leq b$, we have $a \leq x \leq b$ by Rem. 2.71. \square

Bolzano-Weierstrass theorem illustrates why we sometimes prefer to work with $\overline{\mathbb{R}}$ instead of \mathbb{R} : $\overline{\mathbb{R}}$ is sequentially compact, while \mathbb{R} is not. That every sequence has limits superior and inferior in $\overline{\mathbb{R}}$ but not necessarily in \mathbb{R} is closely related to this fact. In the language of point-set topology, $\overline{\mathbb{R}}$ is a **compactification** of \mathbb{R} .

Bolzano-Weierstrass theorem (restricted to \mathbb{R}^N) will be generalized to **Heine-Borel theorem**, which says that a subset of \mathbb{R}^N is sequentially compact iff it is bounded and closed (cf. Def. 3.26 for the definition of closed subsets). See Thm. 3.54.

3.1.3 A criterion for convergence in sequentially compact spaces

At the end of Sec. 2.3, we have raised the following question: Suppose that (x_n) is a bounded sequence in a metric space X such that any two convergent subsequences converge to the same point. Does (x_n) converge?

When X is sequentially compact, (x_n) is automatically bounded due to Prop. 3.7. The answer to the above question is yes:

Theorem 3.15. *Let X be a sequentially compact metric space. Let (x_n) be a sequence in X . Then the following are equivalent.*

- (1) *The sequence (x_n) converges in X .*
- (2) *Any two convergent subsequences of (x_n) converge to the same point. In other words, (x_n) has only one cluster point.*

Proof. (1) \Rightarrow (2): By Prop. 2.36.

(2) \Rightarrow (1): Assume that (x_n) has at most one cluster point. Since X is sequentially compact, (x_n) has at least one cluster point $x \in X$. We want to prove $\lim_{n \rightarrow \infty} x_n = x$. Suppose not. Then there exists $\varepsilon > 0$ such that for every $N \in \mathbb{Z}_+$ there is $n \geq N$ such that $d(x_n, x) \geq \varepsilon$. Thus, one can inductively construct a subsequence (x_{n_k}) of (x_n) such that $d(x_{n_k}, x) \geq \varepsilon$ for all k . Since X is sequentially compact, (x_{n_k}) has a subsequence x'_n converging to $x' \in X$. So $d(x'_n, x) \geq \varepsilon$ for all n . Since the function $y \in X \mapsto d(y, x)$ is continuous (Exp. 2.58), we have $\lim_{n \rightarrow \infty} d(x'_n, x) = d(x', x)$. This proves that $d(x', x) \geq \varepsilon > 0$. However, x', x are both cluster points of (x_n) , and so $x = x'$. This gives a contradiction. \square

Remark 3.16. Thm. 3.15 can be used in the following way. Suppose that we want to prove that a given sequence (x_n) in a sequentially compact space X converges to x . Then it suffices to prove that if (x'_n) is a subsequence of (x_n) converging to some $y \in X$, then $y = x$. This is sometimes easier to prove than directly proving the convergence of (x_n) . We will use this strategy in the proof of L'Hôpital's rule, for example.

Corollary 3.17. *Let (x_n) be a sequence in \mathbb{R}^N . The following are equivalent.*

- (1) *The sequence (x_n) converges in \mathbb{R}^N .*
- (2) *The sequence (x_n) is bounded. Moreover, any two convergent subsequences of (x_n) converge to the same point of \mathbb{R}^N .*

Proof. (1) \Rightarrow (2): By Prop. 2.33 and 2.36.

(2) \Rightarrow (1): Assume (2). Since (x_n) is bounded, it can be contained in $X = I_1 \times \cdots \times I_N$ where each I_i is a closed interval in \mathbb{R} . Clearly, any two cluster points of (x_n) are inside X , and are equal by (2). By Bolzano-Weierstrass, X is sequentially compact. Thus, by Thm. 3.15, (x_n) converges in X and hence in \mathbb{R}^N . \square

Corollary 3.18. *The following are true.*

1. *Let (x_n) be a sequence in $\overline{\mathbb{R}}$. Then (x_n) converges in $\overline{\mathbb{R}}$ iff $\limsup_{n \rightarrow \infty} x_n$ equals $\liminf_{n \rightarrow \infty} x_n$.*
2. *Let (x_n) be a sequence in \mathbb{R} . Then (x_n) converges in \mathbb{R} iff $\limsup_{n \rightarrow \infty} x_n$ equals $\liminf_{n \rightarrow \infty} x_n$ and (x_n) is bounded.*

Note that if (x_n) converges in $\overline{\mathbb{R}}$, we must have $\lim x_n = \limsup x_n = \liminf x_n$ by Thm. 3.11.

Proof. 1. Let $A = \liminf x_n$ and $B = \limsup x_n$. Let S be the set of cluster points of (x_n) . By Thm. 3.11, $A = \min S, B = \max S$. So $A = B$ iff S has only one element. This is equivalent to the convergence of (x_n) in $\overline{\mathbb{R}}$ due to Thm. 3.15 (since $\overline{\mathbb{R}}$ is sequentially compact by Bolzano-Weierstrass.)

2. If (x_n) converges, then $A = B$ by part 1. And (x_n) is bounded due to Prop. 2.33. Conversely, if $A = B$ and if (x_n) is bounded, say $\alpha \leq x_n \leq \beta$ for all n where $-\infty < \alpha < \beta < +\infty$. Then $\alpha \leq A \leq B \leq \beta$. So $A, B \in \mathbb{R}$. By part 1, (x_n) converges to $A \in \mathbb{R}$. \square

3.2 Outlook: sequentially compact function spaces

In Sec. 2.1, we mentioned that metric spaces and (more generally) point-set topology were introduced by mathematicians in order to study (typically infinite dimensional) function spaces with the help of the geometric intuition of \mathbb{R}^N . Now we have learned a couple of important results about sequentially compact spaces. But we have not met any example arising from function spaces. So let me show one example to the curious readers: The product space $[0, 1]^{\mathbb{Z}_+}$, equipped with the metric defined in Pb. 2.3, is sequentially compact. We will prove this result at the end of this chapter. (Indeed, we will prove a slightly more general version. See Thm. 3.53.) This is a famous result, not only because it has many important applications (some of which will be hinted at in this section), but also because its proof uses the clever “diagonal method”.

Moreover, we will later prove an even more surprising fact: every sequentially compact metric space is homeomorphic to a closed subset of $[0, 1]^{\mathbb{Z}_+}$. (See Thm. 8.43.) Thus, all sequentially compact metric spaces can be constructed explicitly, in some sense.

The readers may still complain that functions on \mathbb{Z}_+ are very different from those we often see and use in analysis and (especially) in differential equations: We are ultimately interested in functions on \mathbb{R} or on $[a, b]$, but not on countable sets. This is correct. But $[0, 1]^{\mathbb{Z}_+}$ (and its closed subsets) are in fact very helpful for the study of spaces of functions on \mathbb{R} and on $[a, b]$. In this course, we shall learn two major examples that the sequential compactness of $[0, 1]^{\mathbb{Z}_+}$ helps with:

1. $A = \mathbb{Q} \cap [a, b]$ is a countable dense subset of $[a, b]$. Thus, if we let $C([a, b])$ denote the set of continuous \mathbb{R} -functions on $[a, b]$, then the restriction map $f \in C([a, b]) \mapsto f|_A \in \mathbb{R}^A$ is injective. In many applications, we are interested in a subset $\mathcal{X} \subset C([a, b])$ of uniformly bounded functions, say all $f \in \mathcal{X}$ take values in $[-1, 1]$. Then we have an injective map

$$\Phi : \mathcal{X} \rightarrow [-1, 1]^A \quad f \mapsto f|_A$$

If \mathcal{X} satisfies a condition called “**equicontinuous**”, then a sequence f_n in \mathcal{X} converges *uniformly* to $f \in C([a, b])$ iff $f_n|_A$ converges *pointwise* to $f|_A$. (See Rem. 3.61.) Thus, from the sequential compactness of $[-1, 1]^A$ under pointwise convergence topology, one concludes that every sequence in \mathcal{X} has a subsequence converging uniformly in $C([a, b])$. This remarkable sequential compactness result on (the closure of) \mathcal{X} is called **Arzelà-Ascoli theorem**, and will be used to prove the fundamental Peano existence theorem in ordinary differential equations. We also see that the fact that $[a, b]$ has a countable dense subset A plays a crucial role. This property of metric spaces is called “**separable**” and will be studied later.

2. **Fourier series** are powerful for the study of partial differential equations. A continuous function $f : [-\pi, \pi] \rightarrow \mathbb{C}$ satisfying $f(-\pi) = f(\pi)$ has Fourier

series expansion $f(x) = \sum_{n \in \mathbb{Z}} a_n e^{inx}$ where $a_n \in \mathbb{C}$. However, for the sake of studying differential equations, one needs to consider series $\sum_{n \in \mathbb{Z}} a_n e^{inx}$ converging to a function much worse than a continuous function. For example, in the study of integral equations (which are closely related to certain partial differential equations), Hilbert and Schmidt discovered that one has to consider all $f(x) = \sum_{n \in \mathbb{Z}} a_n e^{inx}$ satisfying $\sum_n |a_n|^2 \leq 1$. Therefore, one lets $\overline{B} = \{z \in \mathbb{C} : |z| \leq 1\}$ and considers $\hat{f} : n \in \mathbb{Z} \mapsto a_n \in \mathbb{C}$ as an element of $\overline{B}^{\mathbb{Z}}$. The sequential compactness of $\overline{B}^{\mathbb{Z}}$ helps one find the \hat{f} such that the corresponding $f(x) = \sum_n \hat{f}(n) \cdot e^{inx}$ is a desired solution of the integral equation.

3.3 Complete metric spaces and Banach spaces

In this section, we let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$, and assume that all vector spaces are over \mathbb{F} .

3.3.1 Cauchy sequences and complete metric spaces

Definition 3.19. A sequence (x_n) in a metric space X is called a **Cauchy sequence**, if:

- For every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $m, n \geq N$ we have $d(x_m, x_n) < \varepsilon$.

Here, “ $\varepsilon > 0$ ” can mean either “ $\varepsilon \in \mathbb{R}_{>0}$ ” or “ $\varepsilon \in \mathbb{Q}_{>0}$ ”. The choice of this meaning does not affect the definition. The above definition can be abbreviated to “for every $\varepsilon > 0$, we have $d(x_m, x_n) < \varepsilon$ for sufficiently large m, n ”.

Remark 3.20. It is an easy consequence of triangle inequality that (x_n) is a Cauchy sequence iff

- For every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ we have $d(x_n, x_N) < \varepsilon$.

Also, it is clear that every Cauchy sequence is bounded.

Proposition 3.21. *Every convergent sequence in a metric space X is a Cauchy sequence.*

Proof. Assume (x_n) converges to x in X . Then for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that $d(x, x_n) < \varepsilon/2$ for all $n \geq N$. Since this is true for every $m \geq N$, we have $d(x_m, x_n) \leq d(x, x_n) + d(x, x_m) < \varepsilon/2 + \varepsilon/2 = \varepsilon$. \square

Definition 3.22. A metric space X is called **complete** if every Cauchy sequence in X converges.

We have many examples of complete metric spaces:

Theorem 3.23. *If (x_n) is a Cauchy sequence in a metric space X with at least one cluster point, then (x_n) converges in X . Consequently, every sequentially compact metric space is complete.*

Proof. Let (x_n) be a Cauchy sequence in X with subsequence (x_{n_k}) converging to $x \in X$. Let us show that $x_n \rightarrow x$.

Since (x_n) is Cauchy, for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that $d(x_n, x_m) < \varepsilon/2$ for all $m, n \geq N$. Since $x_{n_k} \rightarrow x$, there is $k \geq N$ such that $d(x_{n_k}, x) < \varepsilon/2$. Since n_k is strictly increasing over k , we have $n_k \geq k$. So $n_k \geq N$. So we can let $m = n_k$. This gives $d(x_n, x_{n_k}) < \varepsilon/2$. Therefore $d(x_n, x) \leq d(x_n, x_{n_k}) + d(x_{n_k}, x) < \varepsilon$ for all $n \geq N$. \square

Example 3.24. Let $X = [a_1, b_1] \times \cdots \times [a_N, b_N]$ where each $[a_i, b_i]$ is a closed interval in \mathbb{R} , then X is sequentially compact by Bolzano-Weierstrass. Thus, by Thm. 3.23, X is complete.

Corollary 3.25. \mathbb{R}^N and \mathbb{C}^N are complete (under the Euclidean metrics).

Proof. Since \mathbb{C}^N is isometrically isomorphic to \mathbb{R}^{2N} , it suffices to prove that \mathbb{R}^N is complete. Choose a Cauchy sequence (x_n) in \mathbb{R}^N . Since (x_n) is bounded, (x_n) is contained inside $X = I_1 \times \cdots \times I_N$ where each $I_i = [a, b]$ is in \mathbb{R} . By Exp. 3.24, X is complete. So (x_n) converges to some $x \in X$. \square

Definition 3.26. We say that a subset A of a metric space X is **closed** if the following condition is true: For every sequence (x_n) in A converging to a point $x \in X$, we have $x \in A$.

Thus, the word “closed” here means “closed under taking limits”.

Proposition 3.27. *Let A be a metric subspace of a metric space X . Recall that the metric of A inherits from that of X (cf. Def. 2.14). Consider the statements:*

- (1) A is complete.
- (2) A is a closed subset of X .

Then (1) \Rightarrow (2). If X is complete, then (2) \Rightarrow (1).

Proof. First, assume that X is complete and (2) is true. Let (x_n) be a Cauchy sequence in A . Then it is a Cauchy sequence in X . So $x_n \rightarrow x \in X$ because X is complete. So $x \in A$ by the definition of closedness. This proves (1).

Next, we assume (1). Choose a sequence (x_n) in A converging to a point $x \in X$. By Prop. 3.21, (x_n) is a Cauchy sequence in X , and hence a Cauchy sequence in A . Since A is complete, there is $a \in A$ such that $x_n \rightarrow a$. So we must have $x = a$ because any sequence has at most one limit in a metric space. This proves $x \in A$. So (2) is proved. \square

A similar result holds for sequential compactness. See Pb. 3.4.

Example 3.28. Let $-\infty < a < b < +\infty$. Then (a, b) is not complete (under the Euclidean metric), because (a, b) is not closed in the metric space \mathbb{R} . (For sufficiently large n , $b - 1/n$ is in (a, b) , but $\lim_{n \rightarrow \infty} (b - 1/n) = b$ is not in b .)

Example 3.29. By Prop. 1.29, for each $x \in \mathbb{R} \setminus \mathbb{Q}$, we can choose an increasing sequence in \mathbb{Q} converging to x . So \mathbb{Q} is not closed in \mathbb{R} . So \mathbb{Q} is not complete under the Euclidean topology.

Example 3.30. Let X be a metric space. Let $p \in X$ and $0 \leq R < +\infty$. Then $\overline{B}_X(x, R)$ is a closed subset of X . Therefore, if X is complete, then $\overline{B}_X(p, R)$ is complete by Prop. 3.27.

Proof of closedness. Let (x_n) be a sequence in $\overline{B}(p, R)$ converging to $x \in X$. Then $d(p, x_n) \leq R$. Since the function $y \in X \mapsto d(p, y) \in \mathbb{R}$ is continuous (Exp. 2.58), we have $d(p, x) = \lim_{n \rightarrow \infty} d(p, x_n) \leq R$. So $x \in \overline{B}(p, R)$. \square

Exercise 3.31. Let d, δ be two equivalent metrics on a set X . Show that a sequence (x_n) in X is Cauchy under d iff (x_n) is Cauchy under δ .

Note that if, instead of assuming d, δ are equivalent, we only assume that d, δ are topologically equivalent. Then the above conclusion is not necessarily true:

Exercise 3.32. Find a non-complete metric δ on \mathbb{R} topologically equivalent to the Euclidean metric.

3.3.2 Normed vector spaces and Banach spaces

A major application of complete metric spaces is to show that many series converge without knowing to what exact values these series converge. A typical example is the convergence of $\sum_{n \in \mathbb{Z}_+} \sin(\sqrt{2}n)/n^2$ in \mathbb{R} . We are also interested in the convergence of series in function spaces, for instance: the uniform convergence of $f(x) = \sum_{n \in \mathbb{Z}_+} \sin(\sqrt{2}nx^3)/n^2$ on \mathbb{R} ; a suitable convergence of the Fourier series $\sum_{n \in \mathbb{Z}} a_n e^{inx}$. But we cannot take sum in a general metric space since it has no vector space structures. Therefore, we need a notion which combines complete metric spaces with vector spaces. Banach spaces are such a notion.

Definition 3.33. Let V be a vector space over \mathbb{F} with zero vector 0_V . A function $\|\cdot\|: V \rightarrow \mathbb{R}_{\geq 0}$ is called a **norm** if for every $u, v \in V$ and $\lambda \in \mathbb{F}$, the following hold:

- (Subadditivity) $\|u + v\| \leq \|u\| + \|v\|$.
- (Absolute homogeneity) $\|\lambda v\| = |\lambda| \cdot \|v\|$. In particular, (by taking $\lambda = 0$) we have $\|0_V\| = 0$.
- If $\|v\| = 0$ then $v = 0_V$.

We call $(V, \|\cdot\|)$ (often abbreviated to V) a **normed vector space**.

Remark 3.34. Let V be a vector space. If V is a normed vector space, then

$$d(u, v) = \|u - v\| \quad (3.4)$$

clearly defines a metric. (Note that triangle inequality follows from subadditivity.) Unless otherwise stated, we always assume that the metric of a normed vector space is defined by (3.4).

Definition 3.35. Let V be a normed vector space. We say that V is a **Banach space** if V is a complete metric space where the metric is the canonical one (3.4). If V is over the field \mathbb{C} (resp. \mathbb{R}), we call V a **complex** (resp. **real**) **Banach space**.

Example 3.36. We always assume that the norm on \mathbb{F}^N is the **Euclidean norm**

$$\|(a_1, \dots, a_N)\| = \sqrt{|a_1|^2 + \dots + |a_N|^2} \quad (3.5)$$

The canonical metric it gives is the Euclidean metric. Thus, by Cor. 3.25, \mathbb{F}^N is a Banach space.

If (λ_n) is a sequence in \mathbb{F} converging to λ , and if (x_n) is a sequence in \mathbb{F}^N converging to x , then one can show that $\lambda_n x_n$ converges to λx by checking that each component of $\lambda_n x_n$ converges to the corresponding component of λx . This is due to Prop. 2.27. However, if (x_n) is in general a sequence in a normed vector space, this method fails. So we need a different argument:

Proposition 3.37. *Let V be a normed vector space. The following maps are continuous*

$$\begin{aligned} + : V \times V &\rightarrow V & (u, v) &\mapsto u + v \\ - : V \times V &\rightarrow V & (u, v) &\mapsto u - v \\ \times_{\mathbb{F}} : \mathbb{F} \times V &\rightarrow V & (\lambda, v) &\mapsto \lambda v \\ \|\cdot\| : V &\rightarrow \mathbb{R}_{\geq 0} & v &\mapsto \|v\| \end{aligned}$$

We didn't mention the continuity of the division map $(\lambda, v) \in \mathbb{F}^\times \times V \mapsto \lambda^{-1}v$ since it follows from that of $\times_{\mathbb{F}}$ and of the inversion map $\lambda \mapsto \lambda^{-1}$ by Exp. 2.44.

Proof. One can check that the addition map, the subtraction map, and the last map $\|\cdot\|$ are Lipschitz continuous.

Define metric $d((\lambda, v), (\lambda', v')) = \max\{|\lambda - \lambda'|, \|v - v'\|\}$ on $\mathbb{F} \times V$. Then $\mathbb{F} \times V$ is covered by open balls of the form $B(0, r) = \{(\lambda, v) \in \mathbb{F} \times V : |\lambda| < r, \|v\| < r\}$. Similar to the argument in (2.6), one uses subadditivity (i.e. triangle inequality) and absolute homogeneity to show that $\times_{\mathbb{F}}$ has Lipschitz constant $2r$ on $B(0, r)$. So $\times_{\mathbb{F}}$ is continuous by Lem. 2.41 and 2.43. \square

3.4 The Banach spaces $l^\infty(X, V)$ and $C(X, V)$

In this section, we let $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$ and assume that the vector spaces V are over \mathbb{F} . As the title suggests, in this section we shall introduce two important examples of Banach spaces: the space of bounded functions $l^\infty(X, V)$ and its subspace of continuous functions $C(X, V)$ (when X is a sequentially compact metric space). In order for these two spaces to be Banach spaces, we must assume that V is also Banach.

In application, the main examples are $V = \mathbb{R}, \mathbb{C}, \mathbb{R}^N, \mathbb{C}^N$. Indeed, $C([a, b], \mathbb{R}^N)$ is one of the main examples of function spaces considered by Fréchet when he defined metric spaces. Therefore, the readers can assume that V is one of such spaces if they want to make life easier. Just keep in mind that we sometimes also consider the case where V itself is a function space.

Definition 3.38. Let X be a set and let V be a vector space. The set V^X is a vector space if we define for each $f, g \in V^X$ and $\lambda \in \mathbb{F}$:

$$\begin{aligned} f + g : X &\rightarrow V & (f + g)(x) &= f(x) + g(x) \\ \lambda f : X &\rightarrow V & (\lambda f)(x) &= \lambda f(x) \end{aligned}$$

We also define the **absolute value function**

$$|f| : X \rightarrow \mathbb{R}_{\geq 0} \quad x \in X \mapsto \|f(x)\| \quad (3.6)$$

The symbol $|f|$ is sometimes also written as $\|f\|$ when it will not be confused with $\|f\|_\infty$ or other norms of f .

Definition 3.39. Let X be a set and let V be a normed vector space. For each $f \in V^X$, define the **l^∞ -norm**

$$\|f\|_{l^\infty(X, V)} \equiv \|f\|_{l^\infty} \equiv \|f\|_\infty = \sup_{x \in X} \|f(x)\| \quad (3.7)$$

where $\|f(x)\|$ is defined by the norm of V . Define the **l^∞ -space**

$$l^\infty(X, V) = \{f \in V^X : \|f\|_\infty < +\infty\} \quad (3.8)$$

which is a vector subspace of V^X . Then $l^\infty(X, V)$ is a normed vector space under the l^∞ -norm. A function $f : X \rightarrow V$ is called **bounded** if $f \in l^\infty(X, V)$.

Exercise 3.40. Prove that for every $f, g \in V^X$ and $\lambda \in \mathbb{F}$ we have

$$\begin{aligned} \|f + g\|_\infty &\leq \|f\|_\infty + \|g\|_\infty \\ \|\lambda f\|_\infty &= |\lambda| \cdot \|f\|_\infty \end{aligned} \quad (3.9)$$

(Note that clearly we have that $\|f\|_\infty = 0$ implies $f = 0$.) Here, we understand $0 \cdot (+\infty) = 0$. Use these relations to verify that $l^\infty(X, V)$ is a linear subspace of V^X (i.e. it is closed under addition and scalar multiplication) and that $\|\cdot\|_\infty$ is a norm on $l^\infty(X, V)$. \square

Definition 3.41. Let V be a normed vector space. We say that a sequence (f_n) in V^X **converges uniformly** to $f \in V^X$ if $\lim_{n \rightarrow \infty} \|f - f_n\|_\infty = 0$. In this case, we write $f_n \rightrightarrows f$.

We say that (f_n) **converges pointwise** to $f \in V^X$ if for every $x \in X$ we have $\lim_{n \rightarrow \infty} f_n(x) = f(x)$, i.e. $\lim_{n \rightarrow \infty} \|f_n(x) - f(x)\| = 0$.

The same definition will be applied to nets $(f_\alpha)_{\alpha \in I}$ in V^X after learning net convergence in Sec. 5.2. \square

In more details, the uniform convergence of f_n to f means that “for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and for all $x \in X$, we have $\|f_n(x) - f(x)\| < \varepsilon$ ”. If we place the words “for all $x \in X$ ” at the very beginning of the sentence, we get pointwise convergence.

Uniform convergence implies pointwise convergence: If $\|f - f_n\|_\infty \rightarrow 0$, then for each $x \in X$ we have $\|f_n(x) - f(x)\| \rightarrow 0$ since $\|f(x) - f_n(x)\| \leq \|f - f_n\|_\infty$.

Example 3.42. Let $f_n : (0, 1) \rightarrow \mathbb{R}$ be $f_n(x) = x^n$. Then f_n converges pointwise to 0 (cf. Exp. 4.10). But $\sup_{x \in (0,1)} |x^n - 0| = 1$ does not converge to 0. So f_n does not converge uniformly to 0.

Remark 3.43. The uniform convergence of sequences in $l^\infty(X, V)$ is induced by the l^∞ -norm, and hence is induced by the metric $d(f, g) = \|f - g\|_\infty$. However, this formula cannot be extended to a metric on V^X , since for arbitrary $f, g \in V^X$, $\|f - g\|_\infty$ is possibly $+\infty$.

In fact, it is true that the uniform convergence of sequences in V^X is induced by a metric, see Pb. 3.6. When X is countable, we have seen in Pb. 2.3 that the pointwise convergence in V^X is also given by a metric. \square

Theorem 3.44. Let X be a set, and let V be a Banach space (over \mathbb{F}). Then $l^\infty(X, V)$ is a Banach space (over \mathbb{F}).

Proof. Let (f_n) be a Cauchy sequence in $l^\infty(X, V)$. Then for every $\varepsilon > 0$ there is $N \in \mathbb{Z}_+$ such that for all $m, n \geq N$ we have that $\sup_{x \in X} \|f_n(x) - f_m(x)\| < \varepsilon$, and hence $\|f_n(x) - f_m(x)\| < \varepsilon$ for each $x \in X$. This shows that for each $x \in X$, $(f_n(x))$ is a Cauchy sequence in V , which converges to some element $f(x) \in V$ because V is complete.

We come back to the statement that for each $\varepsilon > 0$, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and all x ,

$$\|f_n(x) - f_m(x)\| < \varepsilon$$

for every $m \geq N$. Let $m \rightarrow \infty$. Then by the continuity of subtraction and taking norm (cf. Prop. 3.37.), we obtain $\|f_n(x) - f(x)\| \leq \varepsilon$ for all $n \geq N$ and $x \in X$. In other words, $\|f_n - f\|_\infty \leq \varepsilon$ for all $n \geq N$. In particular, $\|f\|_\infty \leq \|f_N\|_\infty + \|f_N - f\|_\infty < +\infty$ by (3.9). This proves $f \in l^\infty(X, V)$ and $f_n \rightrightarrows f$. \square

Mathematicians used to believe that “if a sequence of continuous functions $f_n : [0, 1] \rightarrow \mathbb{R}$ converges pointwise to a function $f : [0, 1] \rightarrow \mathbb{R}$, then f is continuous”. Cauchy, one of the main figures in 19th century working on putting analysis on a rigorous ground, has given a problematic proof of this wrong statement. Counterexamples were later found in the study of Fourier series: Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be a function with period 2π such that $f(x) = x$ when $-\pi < x < \pi$, and $f(x) = 0$ when $x = \pm\pi$. Then the Fourier series of this noncontinuous function f converges pointwise to f , yet the partial sums of this series are clearly continuous functions. Later, it was realized that uniform convergence is needed to show the continuity of the limit function. (See Thm. 3.47.) This was the first time the importance of uniform convergence was realized.

The following discussions about (resp. sequentially compact) metric spaces also apply to general (resp. compact) topological spaces. The reader can come back and check the proofs for these more general spaces after studying them in the future.

Definition 3.45. Let X, Y be metric spaces (resp. topological spaces). Then $C(X, Y)$ denotes the set of continuous functions from X to Y .

Lemma 3.46. Let X be a metric space (resp. a topological space), and let V be a normed vector space. Then $C(X, V)$ is a linear subspace of V^X . If X is sequentially compact (resp. compact), then $C(X, V)$ is a linear subspace of $l^\infty(X, V)$.

Proof. Using Prop. 3.37, one checks easily that $C(X, V)$ is a linear subspace of V^X . For any $f \in C(X, V)$, the absolute value function $|f| : x \in X \mapsto \|f(x)\|$ is continuous. Thus, assuming that X is sequentially compact, then by Lem. 3.2, $|f|$ is bounded on X . This proves that $\|f\|_\infty < +\infty$. Thus $C(X, V)$ is a subset (and hence a linear subspace) of $l^\infty(X, V)$. \square

Theorem 3.47. Let X be a metric space (resp. a topological space), and let V be a normed vector space. Then $C(X, V) \cap l^\infty(X, V)$ is a closed linear subspace of $l^\infty(X, V)$. In particular, if X is sequentially compact (resp. compact), then $C(X, V)$ is a closed linear subspace of $l^\infty(X, V)$.

Proof. Choose a sequence (f_n) in $C(X, V) \cap l^\infty(X, V)$ converging in $l^\infty(X, V)$ to f . Namely, $f_n \rightrightarrows f$. We want to prove that f is continuous. We check that f satisfies Def. 2.38-(2'). (One can also use Def. 2.38-(1). The proofs using these two definitions are not substantially different.)

Fix $p \in X$. Choose any $\varepsilon > 0$. Since $f_n \rightrightarrows f$, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$ and we have $\|f - f_n\|_\infty < \varepsilon$. Since f_N is continuous, there exists $r > 0$ such that for each $x \in B_X(p, r)$ we have $\|f_N(x) - f_N(p)\| < \varepsilon$. Thus, for each $x \in B_X(p, r)$ we have

$$\|f(x) - f(p)\| \leq \|f(x) - f_N(x)\| + \|f_N(x) - f_N(p)\| + \|f_N(p) - f(p)\| < 3\varepsilon$$

This finishes the proof. \square

Convention 3.48. Unless otherwise stated, if X is sequentially compact metric space (or more generally, a compact topological space to be defined latter), and if V is a normed vector space, the norm on $C(X, V)$ is chosen to be the l^∞ -norm.

Corollary 3.49. Let X be a metric space (resp. a topological space), and let V be a Banach space. Then $C(X, V) \cap l^\infty(X, V)$ is a Banach space under the l^∞ -norm. In particular, if X is sequentially compact (resp. compact), then $C(X, V)$ is a Banach space.

Proof. This follows immediately from Prop. 3.27, Thm. 3.47, and the fact that $l^\infty(X, V)$ is complete (Thm. 3.44). \square

3.5 Problems and supplementary material

Problem 3.1. Let (x_n) be a sequence in a metric space X . Let $x \in X$. Prove that the following are equivalent.

- (1) x is a cluster point of (x_n) , i.e., the limit of a convergent subsequence of (x_n) .
- (2) For each $\varepsilon > 0$ and each $N \in \mathbb{Z}_+$, there exists $n \geq N$ such that $d(x_n, x) < \varepsilon$.

(Note: in a general topological space, these two statements are not equivalent.)

Remark 3.50. Condition (2) is often abbreviated to “for each $\varepsilon > 0$, the sequence (x_n) is frequently in $B(x, \varepsilon)$ ”. In general, we say “ (x_n) **frequently** satisfies P” if for each $N \in \mathbb{Z}_+$ there is $n \geq N$ such that x_n satisfies P. We say that “ (x_n) **eventually** satisfies P” if there exists $N \in \mathbb{Z}_+$ such that for every $n \geq N$, x_n satisfies P.

Thus “ (x_n) eventually satisfies P” means the same as “all but finitely many x_n satisfies P”. Its negation is “ (x_n) frequently satisfies $\neg P$ ”. \square

Remark 3.51. Condition (2) of Pb. 3.1 is sometimes easier to use than (1). For example, compared to the original definition of cluster points, it is much easier to find an explicit negation of (2) by using the rule suggested in Rem. 2.17: There exist $\varepsilon > 0$ and $N \in \mathbb{Z}_+$ such that $d(x_n, x) \geq \varepsilon$ for all $n \geq N$. (Or simply: there exists $\varepsilon > 0$ such that x_n is eventually not in $B(x, \varepsilon)$.)

Problem 3.2. Use Pb. 3.1-(2) to prove that if (x_n) is a sequence in $\overline{\mathbb{R}}$, then $\limsup_{n \rightarrow \infty} x_n$ is a cluster point of (x_n) .

Remark 3.52. You will notice that your proof of Pb. 3.2 is slightly simpler than the proof we gave for Thm. 3.11. This is because our construction of subsequence as in (3.3) has been incorporated into your proof of (2) \Rightarrow (1) in Pb. 3.1.

Problem 3.3. Let $f : X \rightarrow Y$ be a continuous map of metric spaces. Assume that f is bijective and X is sequentially compact. Prove that f is a homeomorphism using the following hint.

Hint. You need to prove that if (y_n) is a sequence in Y converging to $y \in Y$, then $x_n = f^{-1}(y_n)$ converges to $x = f^{-1}(y)$. Prove that (x_n) has only one cluster point, and hence converges to some point $x' \in X$ (why?). Then prove $x' = x$. (In the future, we will use the language of open sets and closed sets to prove this result again. Do not use this language in your solution.) \square

Theorem 3.53 (Tychonoff theorem, countable version). *Let $(X_n)_{n \in \mathbb{Z}_+}$ be a sequence of sequentially compact metric spaces. Then the product space $S = \prod_{n \in \mathbb{Z}_+} X_n$ is sequentially compact under the metric defined as in Pb. 2.3.*

The method of choosing subsequence in the following proof is the reknowned **diagonal method**.

Proof. Let $(x_m)_{m \in \mathbb{Z}_+}$ be a sequence in S . Since $(x_m(1))_{m \in \mathbb{Z}_+}$ is a sequence in the sequentially compact space X_1 , $(x_m)_{m \in \mathbb{Z}_+}$ has a subsequence $x_{1,1}, x_{1,2}, x_{1,3} \dots$ whose value at $n = 1$ converges in X_1 . Since X_2 is sequentially compact, we can choose a subsequence $x_{2,1}, x_{2,2}, x_{2,3}, \dots$ of the previous subsequence such that its values at $n = 2$ converge in X_2 . Then pick a subsequence from the previous one whose values at 3 converge in X_3 .

By repeating this process, we get an $\infty \times \infty$ matrix $(x_{i,j})_{i,j \in \mathbb{Z}_+}$:

$$\begin{array}{cccc} x_{1,1} & x_{1,2} & x_{1,3} & \cdots \\ x_{2,1} & x_{2,2} & x_{2,3} & \cdots \\ x_{3,1} & x_{3,2} & x_{3,3} & \cdots \\ \vdots & \vdots & \vdots & \ddots \end{array} \tag{3.10}$$

such that the following hold:

- The 1-st line is a subsequence of the original sequence $(x_m)_{m \in \mathbb{Z}_+}$.
- The $(i + 1)$ -th line is a subsequence of the i -th line.
- For each n , $\lim_{j \rightarrow \infty} x_{n,j}(n)$ converges in X_n .

Then the diagonal line $(x_{i,i})_{i \in \mathbb{Z}_+}$ is a subsequence of the original sequence $(x_m)_{m \in \mathbb{Z}_+}$. Moreover, for each n , $(x_{i,i})_{i \geq n}$ is a subsequence of the n -th line, whose value at n therefore converges in X_n . Thus $\lim_{i \rightarrow \infty} x_{i,i}(n)$ converges in X_n . Thus, by Pb. 2.3, $(x_{i,i})_{i \in \mathbb{Z}_+}$ converges under any metric inducing the product topology. \square

Problem 3.4. Let X be a sequentially compact metric space. Let $A \subset X$ be a metric subspace. Consider the statements:

- (1) A is sequentially compact.

(2) A is a closed subset of X .

Prove that (1) \Rightarrow (2). Prove that if X is sequentially compact, then (2) \Rightarrow (1).

The above problem implies immediately:

Theorem 3.54 (Heine-Borel theorem). *Let A be a subset of \mathbb{R}^N . Then A is sequentially compact iff A is a bounded closed subset of \mathbb{R}^N .*

Proof. Suppose that A is sequentially compact. Then A is bounded under the Euclidean metric by Prop. 3.7. By Pb. 3.4, A is a closed subset of \mathbb{R}^N .

Conversely, assume that A is a bounded and closed subset of \mathbb{R}^N . Then $A \subset B$ where B is the product of N pieces of closed intervals in \mathbb{R} . Then B is sequentially compact by Bolzano-Weierstrass. Since A is closed in \mathbb{R}^N , it is not hard to check that A is closed in B .⁸ Thus A is sequentially compact by Pb. 3.4. \square

Example 3.55. Choose any $p \in \mathbb{R}^N$ and $0 \leq R < +\infty$. Then $\overline{B}_{\mathbb{R}^N}(p, R)$ is a bounded closed subset of \mathbb{R}^N (Exp. 3.30), and hence is sequentially compact by Heine-Borel.

Remark 3.56. Think about the question: Equip $\mathbb{R}^{\mathbb{Z}_+}$ with metric

$$d(x, y) = \sup_{n \in \mathbb{Z}_+} \frac{\min\{|x(n), y(n)|, 1\}}{n}$$

What are the sequentially compact subsets of $\mathbb{R}^{\mathbb{Z}_+}$? (Namely, think about how to generalize Heine-Borel theorem to $\mathbb{R}^{\mathbb{Z}_+}$.)

Problem 3.5. Do Exercise 3.40.

Problem 3.6. Let V be a normed vector space. For every $f, g \in V^X$ define

$$d(f, g) = \min\{1, \|f - g\|_\infty\} \quad (3.11)$$

1. Show that d defines a metric on V^X .
2. Show that for every sequence (f_n) in V^X and every $g \in V^X$, we have $f_n \rightarrow g$ under the metric d iff $f_n \rightrightarrows g$.

Definition 3.57. Let X be a set, and let V be a normed vector space. A metric on V^X is called a **uniform convergence metric** if it is topologically equivalent to (3.11). Thus, by Def. 2.61, a uniform convergence metric is one such that a sequence (f_n) in V^X converges to f under this metric iff $f_n \rightrightarrows f$.

⁸If Z is a metric space, if $X \subset Y \subset Z$, and if X is closed in Z , then it is easy to check that X is closed in Y .

Problem 3.7. Let X, Y be metric spaces, and assume that Y is sequentially compact. Let V be a normed vector space. Choose $f \in C(X \times Y, V)$, i.e., $f : X \times Y \rightarrow V$ is continuous. For each $x \in X$, let

$$f_x : Y \rightarrow V \quad y \mapsto f(x, y)$$

Namely $f_x(y) = f(x, y)$. It is easy to check that $f_x \in C(Y, V)$. Define a new function

$$\Phi(f) : X \rightarrow C(Y, V) \quad x \mapsto f_x \quad (3.12)$$

Recall that $C(Y, V)$ is equipped with the l^∞ -norm.

1. Prove that $\Phi(f)$ is continuous. In other words, prove that if (x_n) is a sequence in X converging to $x \in X$, then $f_{x_n} \rightrightarrows f_x$ on Y , i.e.

$$\lim_{n \rightarrow \infty} \|f_{x_n} - f_x\|_{l^\infty(Y, V)} = 0$$

- ★ 2. Give an example of $f \in C(X \times Y, \mathbb{R})$ where Y is not sequentially compact, (x_n) converges to x in X , and f_{x_n} does not converge uniformly to f_x . (Note: you may consider $X = Y = \mathbb{R}$.)

Hint. In part 1, to prove that $\Phi(f)$ is continuous, one can prove the equivalent fact that for every fixed $x \in X$ the following is true:

- For every $\varepsilon > 0$ there exists $\delta > 0$ such that for all $p \in B_X(x, \delta)$, we have $\sup_{y \in Y} \|f(p, y) - f(x, y)\| < \varepsilon$.

(Cf. Def. 2.38.) Prove this by contradiction and by using the sequential compactness of Y appropriately. □

Remark 3.58. Let $X = \mathbb{Z}_+ \cup \{\infty\}$, equipped with the metric

$$d(m, n) = |m^{-1} - n^{-1}|$$

In other words, the metric on X is $\tau^* d_{\mathbb{R}}$ where $d_{\mathbb{R}}$ is the Euclidean metric on \mathbb{R} , and $\tau : X \rightarrow \mathbb{R}, n \mapsto n^{-1}$. It is not hard to show that X is sequentially compact: either prove it directly, or apply Heine-Borel to $\tau(X)$.

Let Y be a metric space. Let $(y_n)_{n \in \mathbb{Z}_+}$ be a sequence in Y , and let $y_\infty \in Y$. It is not hard to see that the following two statements are equivalent:

- (1) The function $F : X \rightarrow Y, n \mapsto y_n$ is continuous.
- (2) The sequence $(y_n)_{n \in \mathbb{Z}_+}$ converges to y_∞ .

The following problem is a generalization of this equivalence. □

★ **Problem 3.8.** Let V be a normed vector space. Let Y be a metric space. Let $X = \mathbb{Z}_+ \cup \{\infty\}$ with metric defined as in Rem. 3.58. Let $(f_n)_{n \in \mathbb{Z}_+}$ be a sequence in $C(Y, V)$. Let $f_\infty \in V^Y$. Prove that the following are equivalent:

(1) The following function is continuous:

$$F : X \times Y \rightarrow V \quad (n, y) \mapsto f_n(y) \quad (3.13)$$

In particular, by restricting F to $\infty \times Y$, we see that $f_\infty \in C(Y, V)$.

(2) $(f_n)_{n \in \mathbb{Z}_+}$ converges pointwise to f_∞ . Moreover, $(f_n)_{n \in \mathbb{Z}_+}$ is **pointwise equicontinuous**, which means the following:

- For every $y \in Y$ and every $\varepsilon > 0$, there exists $\delta > 0$ such that for all $p \in B_Y(y, \delta)$ we have

$$\sup_{n \in \mathbb{Z}_+} \|f_n(p) - f_n(y)\| < \varepsilon$$

Note. In part (1), the only nontrivial thing to prove is that F is continuous at (∞, y) for every $y \in Y$.

Remark 3.59. There is a concise way to define pointwise equicontinuity: a sequence $(f_n)_{n \in \mathbb{Z}_+}$ in V^Y is pointwise equicontinuous iff the function

$$Y \mapsto V^{\mathbb{Z}_+} \quad y \mapsto (f_1(y), f_2(y), \dots) \quad (3.14)$$

is continuous, where $V^{\mathbb{Z}_+}$ is equipped with any uniform convergence metric (cf. Def. 3.57).

★ **Remark 3.60.** In Pb. 3.8, there is a quick and tricky way to conclude (1) \Rightarrow (2): Use Pb. 3.7 and the sequential compactness of X . (Do not use this method in your solution. Prove (1) \Rightarrow (2) directly; it is a good exercise and is not difficult.)

★ **Remark 3.61.** Pb. 3.7 and 3.8, together with Thm. 3.47, imply the following fact (can you see why?):

- Let Y be a sequentially compact metric space. Let V be a normed vector space. Let $(f_n)_{n \in \mathbb{Z}_+}$ be a pointwise equicontinuous sequence of functions $Y \rightarrow V$ converging pointwise to some $f : Y \rightarrow V$. Then $f_n \rightrightarrows f$ on Y .

You can also try to give a straightforward proof of this fact without using Pb. 3.7 and 3.8.

4 Series

In this chapter, we assume that vector spaces are over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$ unless otherwise stated.

4.1 Definitions and basic properties

Definition 4.1. Let V be a Banach space (over \mathbb{F}). A **series** in V is an expression of the form

$$\sum_{i=1}^{\infty} v_i \quad (4.1)$$

where $(v_i)_{i \in \mathbb{Z}_+}$ is a sequence in V . If $s \in V$, we say that the series (4.1) **converges to s** if

$$s = \lim_{n \rightarrow \infty} \sum_{i=1}^n v_i$$

namely, $s_n \rightarrow s$ where s_n is the **partial sum** $s_n = \sum_{i=1}^n v_i$. In this case, we write

$$s = \sum_{i=1}^{\infty} v_i$$

Remark 4.2. Since V is complete, the series (4.1) converges iff the sequence of partial sum (s_n) is a Cauchy sequence: for every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n > m \geq N$ we have $\|s_n - s_m\| < \varepsilon$, i.e.,

$$\left\| \sum_{i=m+1}^n v_i \right\| < \varepsilon \quad (4.2)$$

Proposition 4.3. Suppose that $\sum_{i=1}^{\infty} v_i$ is a convergent series in a Banach space V . Then $\lim_{n \rightarrow \infty} v_n = 0$.

Proof. Let $s_n = v_1 + \cdots + v_n$, which converges to $s \in V$. Then $\lim_{n \rightarrow \infty} s_{n+1} = s$. So $v_n = s_{n+1} - s_n \rightarrow s - s = 0$ since subtraction in continuous (Prop. 3.37). \square

Thus, for example, $\sum_{n=1}^{\infty} (-1)^n$ diverges in the Banach space \mathbb{R} since $\lim_{n \rightarrow \infty} (-1)^n$ does not converge to 0.

Definition 4.4. Consider a **series** in $\overline{\mathbb{R}}_{\geq 0}$:

$$\sum_{i=1}^{\infty} a_i \quad (4.3)$$

namely, each a_i is in $\overline{\mathbb{R}}_{\geq 0}$. Note that the partial sum $s_n = \sum_{i=1}^n a_i$ is increasing. We say that $\lim_{n \rightarrow \infty} s_n$ (which exists in $\overline{\mathbb{R}}_{\geq 0}$ and equals $\sup\{s_n : n \in \mathbb{Z}_+\}$, cf. Rem. 2.71) is the value of the series (4.3) and write

$$\sum_{i=1}^{\infty} a_i = \lim_{n \rightarrow \infty} s_n$$

Definition 4.5. We say that a series $\sum_{i=1}^{\infty} a_i$ in $\mathbb{R}_{\geq 0}$ **converges** if it converges in \mathbb{R} (but not just converges in $\overline{\mathbb{R}}_{\geq 0}$, which is always true). Clearly, $\sum_{i=1}^{\infty} a_i$ converges iff

$$\sum_{i=1}^{\infty} a_i < +\infty$$

More generally, we say that a series $\sum_{i=1}^{\infty} v_i$ in a Banach space V **converges absolutely**, if

$$\sum_{i=1}^{\infty} \|v_i\| < +\infty$$

Remark 4.6. By the Cauchy condition of convergence, $\sum_{i=1}^{\infty} v_i$ converges absolutely iff for every $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that for all $n > m \geq N$ we have

$$\sum_{i=m+1}^n \|v_i\| < \varepsilon \quad (4.4)$$

By comparing (4.4) with (4.2) and using the subadditivity of the norm (recall Def. 3.33), we immediately see:

Proposition 4.7. Let $\sum_{i=1}^{\infty} v_i$ be a series in a Banach space. The following are true.

1. If $\sum_{i=1}^{\infty} v_i$ converges absolutely, then it converges.
2. For each i we choose $a_i \in \mathbb{R}_{\geq 0}$ satisfying $\|v_i\| \leq a_i$. Suppose that $\sum_{i=1}^{\infty} a_i < +\infty$. Then $\sum_{i=1}^{\infty} v_i$ converges absolutely.

Proof. Part 1 has been explained above. In part 2, we have $\sum \|v_i\| \leq \sum a_i < +\infty$. So $\sum v_i$ converges absolutely. \square

Exercise 4.8. Suppose that $\sum_{i=1}^{\infty} u_i$ and $\sum_{i=1}^{\infty} v_i$ are convergent (resp. absolutely convergent) series in a Banach space V . Let $\lambda \in \mathbb{F}$. Show that the LHS of the following equations converges (resp. converges absolutely) in V , and that the following equations hold:

$$\begin{aligned} \sum_{i=1}^{\infty} (u_i + v_i) &= \sum_{i=1}^{\infty} u_i + \sum_{i=1}^{\infty} v_i \\ \sum_{i=1}^{\infty} \lambda v_i &= \lambda \cdot \sum_{i=1}^{\infty} v_i \end{aligned}$$

Remark 4.9. We have seen that absolute convergence implies convergence. In fact, at least when $V = \mathbb{F}^N$, absolute convergence is in many ways more natural than convergence. For example, we will learn that if a series $\sum_i v_i$ in \mathbb{F}^N converges absolutely, then the value of $\sum_i v_i$ is invariant under rearrangement of the series: for every bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$ we have $\sum_i v_i = \sum_i v_{\varphi(i)}$. In the next semester, we shall learn Lebesgue integral theory and, more generally, measure theory. When applying measure theory to infinite sums over the countable set \mathbb{Z}_+ , many good results (e.g. dominated convergence theorem, Fubini theorem) hold only for absolute convergence series, but not for arbitrary convergent series in general. In fact, there is no analog of convergent (but not absolutely convergent) series in measure theory at all!

When V is not necessarily finite-dimensional, the situation is subtler: there is a version of convergence which lies between the usual convergence and absolute convergence, and which coincides with absolute convergence when $V = \mathbb{F}^N$. This version of convergence is defined using nets instead of sequences. Moreover, many good properties (as mentioned above) hold for this convergence, and these properties can be proved in a very conceptual way (rather than using brute-force computation). We will learn this convergence in the next chapter. \square

4.2 Basic examples

Let us study the **geometric series** $\sum_{n=0}^{\infty} z^n$ where $z \in \mathbb{C}$. We first note the useful formula: for each $z, w \in \mathbb{C}$ and $n \in \mathbb{N}$,

$$(z + w)^n = \sum_{k=0}^n \binom{n}{k} z^k w^{n-k} \quad (4.5)$$

In particular,

$$(1 + z)^n = 1 + nz + \frac{n(n-1)}{2} z^2 + \frac{n(n-1)(n-2)}{6} z^3 + \cdots + nz^{n-1} + z^n \quad (4.6)$$

Example 4.10. Assume $z \in \mathbb{C}$ and $|z| < 1$. Then $\lim_{n \rightarrow \infty} z^n = 0$.

Proof. If $z = 0$ then it is obvious. Assume that $0 < |z| < 1$. Choose $\delta > 0$ such that $|z| = 1/(1 + \delta)$. By (4.6), $(1 + \delta)^n \geq 1 + n\delta$. So

$$0 \leq |z^n| \leq (1 + n\delta)^{-1}$$

Since $\lim_{n \rightarrow \infty} (1 + n\delta)^{-1} = 0$, we have $|z^n| \rightarrow 0$ by squeeze theorem. Hence $z^n \rightarrow 0$. \square

Example 4.11. Let $z \in \mathbb{C}$. If $|z| < 1$, then $\sum_{n=0}^{\infty} z^n$ converges absolutely, and

$$\sum_{n=0}^{\infty} z^n = \frac{1}{1 - z} \quad (4.7)$$

where 0^0 is understood as 1. If $|z| \geq 1$, then $\sum_{n=0}^{\infty} z_n$ diverges in \mathbb{C} .

Proof. The partial sum $s_n = 1 + z + z^2 + \cdots + z^n$ equals $(1 - z^{n+1})/(1 - z)$ when $z \neq 1$. Therefore, when $|z| < 1$, $s_n \rightarrow 1/(1 - z)$. When $|z| \geq 1$, we have $|z^n| \geq 1$ and hence $z^n \not\rightarrow 0$. So $\sum_{n=0}^{\infty} z^n$ diverges by Prop. 4.3. \square

Example 4.12. The harmonic series $\sum_{n=1}^{\infty} \frac{1}{n}$ diverges (in \mathbb{R}).

Proof. We want to show that the Cauchy condition (cf. Rem. 4.2) does not hold. Thus, we want to prove that there exists $\varepsilon > 0$ such that for every $N \in \mathbb{Z}_+$ there exist $n > m \geq N$ such that $|(m+1)^{-1} + (m+2)^{-1} + \cdots + n^{-1}| \geq \varepsilon$.

To see this, for each N we choose $m = 2^N$ and $n = 2^{N+1}$. Then $n > m > N$, and

$$\begin{aligned} \left| \sum_{i=m+1}^n i^{-1} \right| &= \left| \frac{1}{2^N+1} + \frac{1}{2^N+2} + \cdots + \frac{1}{2^N+2^N} \right| \\ &\geq \underbrace{\left| \frac{1}{2^{N+1}} + \frac{1}{2^{N+1}} + \cdots + \frac{1}{2^{N+1}} \right|}_{2^N \text{ terms}} = \varepsilon \end{aligned}$$

where $\varepsilon = \frac{1}{2}$. \square

Exercise 4.13. Choose any $p \in \mathbb{Z}$. Prove that $\sum_{n=1}^{\infty} n^{-p}$ converges iff $p \geq 2$.

Hint. Use Prop. 4.7 and Exp. 4.12 to reduce the problem to the case $p = 2$. Prove this case by proving $\sum_{n=1}^{\infty} 1/n(n+1) = 1 < +\infty$. \square

Definition 4.14. Let V be a Banach space, let X be a set, and let (f_n) be a sequence in $l^\infty(X, V)$, and let $g \in l^\infty(X, V)$. We say that the series of functions $\sum_{i=1}^{\infty} f_i$ **converges uniformly to g (on X)** if it converges to g as a series in the Banach space $l^\infty(X, V)$ and under the l^∞ -norm. Equivalently, this means that the partial sum function $s_n = f_1 + \cdots + f_n$ converges uniformly to g as $n \rightarrow \infty$.

Example 4.15. The series of functions $\sum_{n=1}^{\infty} \frac{\sin |nz^3|}{n^2}$ converges uniformly on \mathbb{C} to a continuous function $g : \mathbb{C} \rightarrow \mathbb{R}$ which is bounded (i.e. $\sup_{z \in \mathbb{C}} |g(z)| < +\infty$).

Proof. Let $f_n(z) = \sin |nz^3|/n^2$. Then each f_n is in $\mathfrak{X} = C(\mathbb{C}, \mathbb{R}) \cap l^\infty(\mathbb{C}, \mathbb{R})$ where \mathfrak{X} is a real Banach space under the l^∞ -norm by Cor. 3.49. Note that $\|f_n\|_\infty \leq n^{-2}$. By Exe. 4.13, $\sum_{n=1}^{\infty} n^{-2} < +\infty$. Therefore, by Prop. 4.7, the series $\sum_n f_n$ converges in \mathfrak{X} , i.e., it converges uniformly to an element $g \in \mathfrak{X}$. (In particular, $\sum_n f_n(z) = g(z)$ for all $z \in \mathbb{C}$.) \square

4.3 Root test and ratio test; power series; construction of e^z

Root test and ratio test are useful criteria for proving the convergence or divergence of series, especially power series. In addition, the method of power series provides a unified and elegant proof for many useful formulas about limit (see Prop. 4.23 and Exp. 4.24). We begin our discussion with the following easy observation:

Remark 4.16. Let (x_n) be a sequence in $\overline{\mathbb{R}}$, and let $A \in \overline{\mathbb{R}}$. The following are true.

1. If $\limsup_{n \rightarrow \infty} x_n < A$, then $x_n < A$ is eventually true.
2. If $\limsup_{n \rightarrow \infty} x_n > A$, then $x_n > A$ is frequently true.

By taking negative, we obtain similar statements for \liminf .

Proof. Recall that $\limsup x_n = \inf_{n \in \mathbb{Z}_+} \alpha_n$ where $\alpha_n = \sup\{x_n, x_{n+1}, \dots\}$.

Assume that $\inf_{n \in \mathbb{Z}_+} \alpha_n < A$. Then A is not a lower bound of $\{\alpha_n : n \in \mathbb{Z}_+\}$. Thus, there exists $N \in \mathbb{Z}_+$ such that $\alpha_N < A$. Then $x_n < A$ for all $n \geq N$.

Assume that $\inf_{n \in \mathbb{Z}_+} \alpha_n > A$. Then for each $N \in \mathbb{Z}_+$ we have $\alpha_N > A$. So A is not an upper bound of $\{x_n, x_{n+1}, \dots\}$. So there is $n \geq N$ such that $x_n > A$. \square

We will heavily use $\sqrt[n]{x}$ (where $x \geq 0$ and $n \in \mathbb{Z}_+$) in the following discussions. $\sqrt[n]{x}$ will be rigorously constructed in Exp. 7.106, whose proof does not rely on the results of this section.

Proposition 4.17 (Root test). Let $\sum_{n=1}^{\infty} v_n$ be a series in a Banach space V . Let $\beta = \limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n\|}$. Then:

1. If $\beta < 1$, then $\sum v_n$ converges absolutely, and hence converges in V .
2. If $\beta > 1$, then $\sum v_n$ diverges in V .

Proof. Suppose $\beta < 1$. Then we can choose γ such that $\beta < \gamma < 1$. So $\limsup \sqrt[n]{\|v_n\|} < \gamma$. By Rem. 3.8, there exists $N \in \mathbb{Z}_+$ such that for all $n \geq N$, we have $\sqrt[n]{\|v_n\|} < \gamma$, and hence $\|v_n\| < \gamma^n$. Since $\sum_{n=0}^{\infty} \gamma^n = (1 - \gamma)^{-1} < +\infty$ (Exp. 4.11), the series $\sum_{n=N}^{\infty} v_n$ converges absolutely by Prop. 4.7. So the original series converges absolutely.

Assume that $\beta > 1$. Then by Rem. 4.16, for each N there is $n \geq N$ such that $\sqrt[n]{\|v_n\|} > 1$ and hence $\|v_n - 0\| > 1$. So $v_n \not\rightarrow 0$. So $\sum v_n$ diverges by Prop. 4.3. \square

Example 4.18. Let $V = \mathbb{R}$ and $v_n = 1/n$ resp. $v_n = 1/n^2$. Then $\beta = 1$, and $\sum v_n$ diverges resp. converges absolutely due to Exe. 4.13. So Root test gives no information on the convergence of series when $\beta = 1$. The same can be said about ratio test.

Proposition 4.19 (Ratio test). Let $\sum_{n=1}^{\infty} v_n$ be a series in a Banach space V such that $v_n \neq 0$ for all n . Let $\alpha = \liminf_{n \rightarrow \infty} \frac{\|v_{n+1}\|}{\|v_n\|}$ and $\beta = \limsup_{n \rightarrow \infty} \frac{\|v_{n+1}\|}{\|v_n\|}$. Then:

1. If $\beta < 1$, then $\sum v_n$ converges absolutely, and hence converges in V .
2. If $\alpha > 1$, then $\sum v_n$ diverges in V .

Proof. Suppose $\beta < 1$. Choose γ such that $\beta < \gamma < 1$. Then by Rem. 4.16, there is N such that for all $n \geq N$ we have $\|v_{n+1}\|/\|v_n\| < \gamma$. So $\|v_n\| < \gamma^{n-N} \|v_N\|$. So $\sum_{n \geq N} \|v_n\| \leq \|v_N\| \cdot \sum_{n \geq N} \gamma^{n-N} = \|v_N\| \cdot (1 - \gamma)^{-1} < +\infty$. So $\sum v_n$ converges absolutely.

Suppose $\alpha > 1$. Then by Rem. 4.16, there is N such that for all $n \geq N$ we have $\|v_{n+1}\|/\|v_n\| > 1$. So $\|v_n\| \geq \|v_N\| > 0$ for all $n \geq N$. So $v_n \not\rightarrow 0$ and hence $\sum v_n$ diverges, as in the proof of root test. \square

Definition 4.20. A **power series** in a complex Banach space V is an expression of the form $\sum_{n=0}^{\infty} v_n z^n$ where the **coefficients** v_0, v_1, v_2, \dots are elements of V , and z is a **complex variable**, i.e., a symbol which can take arbitrary values in \mathbb{C} . If the power series $\sum v_n z^n$ converges at $z_0 \in \mathbb{C}$, we often let $\sum v_n z_0^n$ denote this limit.

Proposition 4.21. Let $\sum v_n z^n$ be a power series in a complex Banach space V . Then there is a unique $0 \leq R \leq +\infty$ satisfying the following properties:

- (a) If $z \in \mathbb{C}$ and $|z| < R$, then $\sum v_n z^n$ converges absolutely in V .
- (b) If $z \in \mathbb{C}$ and $|z| > R$, then $\sum v_n z^n$ diverges in V .

Such R is called the **radius of convergence** of $\sum v_n z^n$. Moreover, we have

$$R = \frac{1}{\limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n\|}} = \liminf_{n \rightarrow \infty} \frac{1}{\sqrt[n]{\|v_n\|}} \quad (4.8)$$

Proof. Clearly, there are at most one R satisfying (a) and (b). Let us define R using (4.8) (note that the second and the third terms of (4.8) are clearly equal), and prove that R satisfies (a) and (b). Let

$$\beta(z) = \limsup_{n \rightarrow \infty} \sqrt[n]{\|v_n z^n\|}$$

Then $\beta(z) = |z|/R$. So (a) and (b) follow immediately from root test. \square

Remark 4.22. Note that if one can find $0 \leq r \leq R$ such that $\sum v_n z^n$ converges whenever $|z| < r$, then $r \leq R$ where R is the radius of convergence: otherwise, the series diverges for any positive z satisfying $R < z < r$, impossible.

It follows that if $\sum v_n z^n$ converges for all $|z| < r$, then $\sum v_n z^n$ converges *absolutely* for all $|z| < r$. \square

Prop. 4.21 provides a useful method for computing limits of a positive sequence:

Proposition 4.23. *Let (λ_n) be a sequence in $\mathbb{R}_{>0}$. Then*

$$\liminf_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \leq \liminf_{n \rightarrow \infty} \sqrt[n]{\lambda_n} \leq \limsup_{n \rightarrow \infty} \sqrt[n]{\lambda_n} \leq \limsup_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \quad (4.9)$$

In particular, (by Cor. 3.18) we have

$$\lim_{n \rightarrow \infty} \sqrt[n]{\lambda_n} = \lim_{n \rightarrow \infty} \frac{\lambda_{n+1}}{\lambda_n} \quad (4.10)$$

provided that the limit on the RHS of (4.10) exists in $\overline{\mathbb{R}}$.

The four numbers in (4.9) can be completely different. See [Rud-P, Exp. 3.35].

Proof. Let R be the radius of convergence of $\sum \lambda_n z^n$. Then $R = 1/\limsup \sqrt[n]{\lambda_n}$ by (4.10). Thus, by Prop. 4.21, if $|z| > R$ then $\sum \lambda_n z^n$ diverges, and hence $\limsup |\lambda_{n+1} z^{n+1}|/|\lambda_n z^n| \geq 1$ by ratio test. Therefore,

$$|z| > \frac{1}{\limsup \sqrt[n]{\lambda_n}} \implies |z| \cdot \limsup \frac{\lambda_{n+1}}{\lambda_n} \geq 1$$

This proves

$$\limsup \sqrt[n]{\lambda_n} \leq \limsup \frac{\lambda_{n+1}}{\lambda_n}$$

Replacing λ_n by λ_n^{-1} , we get

$$\frac{1}{\liminf \sqrt[n]{\lambda_n}} = \limsup \sqrt[n]{\lambda_n^{-1}} \leq \limsup \frac{\lambda_n}{\lambda_{n+1}} = \frac{1}{\liminf \frac{\lambda_{n+1}}{\lambda_n}}$$

This proves (4.9). □

Example 4.24. Let $a \in \mathbb{R}_{>0}$ and $p \in \mathbb{Z}$. The following formulas follow immediately from Prop. 4.23 (especially, from (4.10)):

$$\lim_{n \rightarrow \infty} \sqrt[n]{a} = 1 \quad (4.11a)$$

$$\lim_{n \rightarrow \infty} \sqrt[n]{n!} = +\infty \quad (4.11b)$$

$$\lim_{n \rightarrow \infty} \sqrt[n]{n^p} = 1 \quad (4.11c)$$

Note that (4.11c) follows from

$$\lim_{n \rightarrow \infty} \left(\frac{n}{n+1} \right)^p = 1 \quad (4.11d)$$

(This is clearly true when $p = \pm 1$, and hence is true for any p by induction.) By (4.11c), the radius of convergence of $\sum_n n^p z^n$ is 1. Therefore, by Prop. 4.21, $\sum n^p A^{-n}$ converges absolutely when $A > 1$. Thus, by Prop. 4.3,

$$\lim_{n \rightarrow \infty} \frac{n^p}{A^n} = 0 \quad (\text{if } A > 1) \quad (4.11e)$$

This means that “polynomials grow slower than exponentials”.

The same conclusions hold for arbitrary $p \in \mathbb{R}$ once we know how to define x^p and prove the continuity of $x \in \mathbb{R}_{>0} \mapsto x^p$. (See Sec. 7.8.) \square

★ **Exercise 4.25.** Prove (4.11a) directly. Then use (4.11a) to give a direct proof of Prop. 4.23. Do not use root test, ratio test, or any results about power series.

Definition 4.26. By (4.11b), the power series

$$\exp(z) \equiv e^z = \sum_{n=0}^{\infty} \frac{z^n}{n!}$$

has radius of convergence $+\infty$, and hence converges absolutely on \mathbb{C} . (In particular, $\lim_{n \rightarrow \infty} z^n/n! = 0$ for all $z \in \mathbb{C}$.) This gives a function $\exp : \mathbb{C} \rightarrow \mathbb{C}$, called the **exponential function**.

Part (a) of Prop. 4.21 can be strengthened in the following way.

Theorem 4.27. Let $\sum v_n z^n$ be a power series with coefficients in a complex Banach space V . Let R be its radius of convergence, and assume that $0 < R \leq +\infty$. For each $z \in B_{\mathbb{C}}(0, R)$, let $f(z)$ denote the value of this series at z (which is an element of V). Then $f : B_{\mathbb{C}}(0, R) \rightarrow V$ is continuous. Moreover, for each $0 < \rho < R$, the series of functions $\sum v_n z^n$ converges uniformly on $\overline{B}_{\mathbb{C}}(0, \rho)$ to f .

Note that by calling $\sum v_n z^n$ a series of functions, we understand each term $v_n z^n$ as a function $\mathbb{C} \rightarrow V$.

Proof. For each $0 < \rho < R$, let $X_\rho = \overline{B}_{\mathbb{C}}(0, \rho)$. Then X_ρ is clearly a bounded closed subset of \mathbb{C} , and hence is sequentially compact by Heine-Borel Thm. 3.54. Let $g_n = v_n z^n$, which is a continuous function $X_\rho \rightarrow V$. We view g_n as an element of the Banach space (cf. Cor. 3.49) $C(X_\rho, V)$. Then $\|g_n\|_\infty = \rho^n \|v_n\|$. Thus

$$\limsup_{n \rightarrow \infty} \sqrt[n]{\|g_n\|_\infty} = \limsup_{n \rightarrow \infty} \rho \sqrt[n]{\|v_n\|} = \rho/R < 1$$

Therefore, by root test, the series $\sum g_n$ converges in the Banach space $C(X_\rho, V)$ to some $f_\rho \in C(X_\rho, V)$.

We have proved that for each $0 < \rho < R$, the series of functions $\sum v_n z^n$ converges uniformly on X_ρ to a continuous function f_ρ . Let $f : B_{\mathbb{C}}(0, R) \rightarrow V$ whose value at each z is the value of the original series at z . Thus, if $|z| \leq \rho$, then

$f_\rho(z) = f(z)$. Namely, $f|_{X_\rho} = f_\rho$. This shows that $\sum v_n z^n$ converges uniformly on X_ρ to f . It also shows that $f|_{B_{\mathbb{C}}(0,\rho)}$ is continuous (because f_ρ is continuous). Therefore, since $B_{\mathbb{C}}(0, R)$ is covered by all open disks $B_{\mathbb{C}}(0, \rho)$ (where $0 < \rho < R$), we conclude from Lem. 2.41 that f is continuous on $B_{\mathbb{C}}(0, R)$. \square

Example 4.28. By Thm. 4.27, the exponential function $\exp : \mathbb{C} \rightarrow \mathbb{C}$ is continuous; moreover, $\sum_{n=0}^{\infty} z^n/n!$ converges uniformly to e^z on $\overline{B_{\mathbb{C}}}(0, R)$ for every $0 < R < +\infty$, and hence on every bounded subset of \mathbb{C} .

5 Nets and discrete integrals

5.1 Introduction: why do we need nets?

Nets were introduced by Moore and Smith in 1922 as a generalization of sequences. The most well-known motivation for introducing nets is that sequences are not enough for the study of non-metrizable topological spaces (i.e. topological spaces whose topologies are not induced by metrics). Here are two examples:

- In a general topological space, the definition of continuous maps using sequential convergence (as in Def. 2.38-(1)) is weaker than the definition using interior points and open sets (as in Def. 2.38-(2')), see also Rem. 4.23). Therefore, the dynamic intuition of sequences is not equivalent to the static intuition of open sets.
- Some important topological spaces are compact (i.e. every open cover has a finite subcover) but not sequentially compact. $[0, 1]^I$ (where I is uncountable), equipped with the “product topology” (i.e. “pointwise convergence topology”), is such an example.

As we shall see, nets provide a remedy for these issues: For a general topological space, the definition of continuity using net convergence is equivalent to that using open sets; compactness is equivalent to “net-compactness”, where the latter means that every net has a convergent subnet. Thus, by generalizing sequences to nets, the dynamic intuition and the static and geometric intuition are unified again.

Nevertheless, the most common topological spaces appearing in analysis are metrizable. This raises the question: Why should we care about nets, given that our primary interest is in metrizable topological spaces? Here is my answer: Even though we are mainly interested in metrizable spaces, we can still find nets helpful in the following aspects.

First of all, many convergence processes cannot be described by sequential convergence, but can be described by net convergence. For example, the following limits can be formulated and understood in the language of net convergence:

- (1) The limit of a function $\lim_{x \rightarrow x_0} f(x)$ where $f : X \rightarrow Y$ is a map of metric spaces and $x_0 \in X$.
- (2) The limit $\lim_{m, n \rightarrow \infty} a_{m, n}$ where $(a_{m, n})_{m, n \in \mathbb{Z}_+}$ is a **double sequence** in a metric space X . Note that this is not the same as (but is more natural than) the **iterated limit** $\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} a_{m, n}$. Moreover, the limit $\lim_{m, n \rightarrow \infty} a_{m, n}$ is the key to understanding the problem of commutativity of iterated integrals:

$$\lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} a_{m, n} \stackrel{?}{=} \lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} a_{m, n}$$

- (3) The Riemann integral $\int_a^b f(x)dx$. This is the limit of the Riemann sum $\lim \sum f(\xi_i)(a_i - a_{i-1})$ as the partition of the interval $[a, b]$ is getting finer and finer.

Moreover, as for (3), we shall see that the net version of Cor. 3.18 provides a quick and conceptual proof of the following fact: If the upper and lower Darboux integrals are equal, then the Riemann integral exists and are equal to the two Darboux integrals. Indeed, the upper and lower Darboux integrals are respectively the \limsup and \liminf of a net in \mathbb{R} .

Second, nets provide a conceptual solution to many problems about **double series**. Let $(a_{m,n})_{m,n \in \mathbb{Z}_+}$ be a double sequence in \mathbb{R} . Think about the following questions, which arise naturally when one is trying to prove $e^z e^w = e^{z+w}$.

- (a) When is it true that $\sum_{n=1}^{\infty} \sum_{m=1}^{\infty} a_{m,n} = \sum_{m=1}^{\infty} \sum_{n=1}^{\infty} a_{m,n}$?
- (b) Since $\text{card}(\mathbb{Z}_+ \times \mathbb{Z}_+) = \text{card}(\mathbb{Z}_+)$, why not use an ordinary series to study a double series? So let us **parametrize** $\mathbb{Z}_+ \times \mathbb{Z}_+$ by \mathbb{Z}_+ : choose a bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+ \times \mathbb{Z}_+$. When is it true that $\sum_{k=1}^{\infty} a_{\varphi(k)} = \sum_{n=1}^{\infty} \sum_{m=1}^{\infty} a_{m,n}$?
- (c) Choose another parametrization (i.e. bijection) $\psi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+ \times \mathbb{Z}_+$. When is it true that $\sum_{k=1}^{\infty} a_{\varphi(k)} = \sum_{k=1}^{\infty} a_{\psi(k)}$?
- (d) More generally, let X be a countably infinite set, and let $f : X \rightarrow \mathbb{R}$. Intuitively, we can take an infinite sum $\sum_{x \in X} f(x)$. How to define it rigorously? One may think about choosing a parametrization, i.e., a bijection $\varphi : \mathbb{Z}_+ \rightarrow X$. Then one defines the infinite sum by $\sum_{k=1}^{\infty} f(\varphi(k))$. Is this definition independent of the choice of parametrization?
- (e) As a special case of (d), when is a series invariant under **rearrangement**? Namely, choose a bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$, and choose a sequence (a_n) in \mathbb{R} , when is it true that $\sum_{n=1}^{\infty} a_n = \sum_{n=1}^{\infty} a_{\varphi(n)}$?

Modern differential geometry (whose “intrinsic” spirit stems from Gauss’s Theorema Egregium) teaches us that in order to answer these questions, one should first define the infinite sum $\sum_{x \in X} f(x)$ in a parametrization-independent way. (The reason we call a bijection $\varphi : \mathbb{Z}_+ \rightarrow X$ a parametrization is that we want the readers to compare it with the parametrizations of curves, surfaces, and more generally manifolds.) We will call this sum a **discrete integral**. Then, one tries to answer when this definition agrees with those that depend on parametrizations

(such as the sums in (a)-(e) above). These goals can be achieved with the help of nets.

5.2 Nets

5.2.1 Directed sets and nets

Definition 5.1. A relation \leq on a set I is called a **preorder** if for all $\alpha, \beta, \gamma \in I$, the following are satisfied:

- (Reflexivity) $\alpha \leq \alpha$.
- (Transitivity) If $\alpha \leq \beta$ and $\beta \leq \gamma$ then $\alpha \leq \gamma$.

The pair (I, \leq) (or simply I) is called a **preordered set**.

Therefore, a partial order is a preorder satisfying antisymmetry: $(\alpha \leq \beta) \wedge (\beta \leq \alpha) \Rightarrow (\alpha = \beta)$.

Definition 5.2. A preordered set (I, \leq) is called a **directed set** if

$$\forall \alpha, \beta \in I \quad \exists \gamma \in I \quad \text{such that } \alpha \leq \gamma, \beta \leq \gamma \quad (5.1)$$

If I is a directed set and X is a set, then a function $x : I \rightarrow X$ is called a **net** with directed set/index set I . We often write $x(\alpha)$ as x_α if $\alpha \in I$, and write x as $(x_\alpha)_{\alpha \in I}$.

Example 5.3. (\mathbb{Z}_+, \leq) is a directed set. A net with index set \mathbb{Z}_+ in a set X is precisely a sequence in X .

Definition 5.4. Suppose that (I, \leq_I) and (J, \leq_J) are preordered set (resp. directed set), then the **product** $(I \times J, \leq)$ is a preordered set (resp. directed set) if for every $\alpha, \alpha' \in I, \beta, \beta' \in J$ we define

$$(\alpha, \beta) \leq (\alpha', \beta') \iff \alpha \leq_I \alpha' \text{ and } \beta \leq_J \beta' \quad (5.2)$$

Unless otherwise stated, the preorder on $I \times J$ is assumed to be defined by (5.2).

Example 5.5. $\mathbb{Z}_+ \times \mathbb{Z}_+$ (or similarly, $\mathbb{N} \times \mathbb{N}$) is naturally a directed set whose preorder is defined by (5.2). A net $(x_{m,n})_{(m,n) \in \mathbb{Z}_+ \times \mathbb{Z}_+}$ with index set $\mathbb{Z}_+ \times \mathbb{Z}_+$ is called a **double sequence** and is written as $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ or simply $(x_{m,n})$. (We will even write it as (x_{mn}) when no confusion arises.)

More generally, we call $(x_{\alpha,\beta})_{(\alpha,\beta) \in I \times J} = (x_{\alpha,\beta})_{\alpha \in I, \beta \in J}$ a **double net** if its index set is $I \times J$ for some directed sets I, J . \square

Example 5.6. If X is a set, then $(2^X, \subset)$ and $(\text{fin}(2^X), \subset)$ are directed sets where

$$\text{fin}(2^X) = \{A \subset X : A \text{ is a finite set}\} \quad (5.3)$$

We will use nets with index set $\text{fin}(2^X)$ to study infinite sums.

Example 5.7. Let X be a metric space and $x \in X$. Then $X_x = (X, \leq)$ is a directed set if for each $p_1, p_2 \in X$ we define

$$p_1 \leq p_2 \text{ in } X_x \iff d(p_1, x) \geq d(p_2, x) \quad (5.4)$$

(Namely, a larger element of X_x is one closer to x .) Nets with this directed set can be used to study the limits of functions (cf. Rem. 7.81). Note that X_x is our first example of directed set which is not a poset! ($d(p_1, x) = d(p_2, x)$ does not imply $p_1 = p_2$.)

5.2.2 Limits of nets

If I is an preordered set and $\beta \in I$, we write

$$I_{\geq \beta} = \{\alpha \in I : \alpha \geq \beta\} \quad (5.5)$$

Definition 5.8. Let P be a property about elements of a set X , i.e., P is a function $X \rightarrow \{\text{true}, \text{false}\}$. Let $(x_\alpha)_{\alpha \in I}$ be a net in X .

We say that x_α **eventually** satisfies P (equivalently, we say that x_α satisfies P for **sufficiently large** α) if:

- There exists $\beta \in I$ such that for every $\alpha \in I_{\geq \beta}$, the element x_α satisfies P .

“Sufficiently large” is also called “**large enough**”.

We say that x_α **frequently** satisfies P if:

- For every $\beta \in I$ there exists $\alpha \in I_{\geq \beta}$ such that x_α satisfies P .

□

Remark 5.9. Note that unlike sequences, for a general net, “ x_α eventually satisfies P ” does not imply “all but finitely many x_α satisfy P ” because the complement of $I_{\geq \beta}$ is not necessarily a finite set.

Remark 5.10. Let P and Q be two properties about elements of X . Then

$$\neg(x_\alpha \text{ eventually satisfies } P) = (x_\alpha \text{ frequently satisfies } \neg P) \quad (5.6a)$$

By the crucial condition (5.1) for directed sets, we have

$$\begin{aligned} (x_\alpha \text{ eventually satisfies } P) \wedge (x_\alpha \text{ eventually satisfies } Q) \\ \Downarrow \\ x_\alpha \text{ eventually satisfies } P \wedge Q \end{aligned} \quad (5.6b)$$

By taking contraposition and replacing P, Q by $\neg P, \neg Q$, we have

$$\begin{aligned} x_\alpha \text{ frequently satisfies } P \vee Q \\ \Downarrow \\ (x_\alpha \text{ frequently satisfies } P) \vee (x_\alpha \text{ frequently satisfies } Q) \end{aligned} \quad (5.6c)$$

Definition 5.11. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space X . Let $x \in X$. We say that (x_α) **converges to** x and write

$$\lim_{\alpha \in I} x_\alpha \equiv \lim_{\alpha} x_\alpha = x$$

or simply $x_\alpha \rightarrow x$ if the following statement holds:

- For every $\varepsilon > 0$, x_α is eventually in $B_X(x, \varepsilon)$.

Clearly, $x_\alpha \rightarrow x$ iff $d(x_\alpha, x) \rightarrow 0$.

Definition 5.12. Let $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ be a double sequence in a metric space. Then we write

$$\lim_{(m,n) \in \mathbb{Z}_+ \times \mathbb{Z}_+} x_{m,n} \equiv \lim_{m,n \rightarrow \infty} x_{m,n} \quad (5.7)$$

and call it the **(double) limit** of $(x_{m,n})$.

Remark 5.13. Let us spell out the meaning of $\lim_{m,n \rightarrow \infty} x_{m,n} = x$: For each $\varepsilon > 0$ there exists $M, N \in \mathbb{Z}_+$ such that $d(x_{m,n}, x) < \varepsilon$ for all $m \geq M$ and $n \geq N$. Clearly, this is equivalent to the statement:

- For each $\varepsilon > 0$ there exists $N \in \mathbb{Z}_+$ such that $d(x_{m,n}, x) < \varepsilon$ for all $m, n \geq N$.

Therefore, if (x_n) is a sequence in X , then

$$(x_n) \text{ is a Cauchy sequence} \iff \lim_{m,n \rightarrow \infty} d(x_m, x_n) = 0 \quad (5.8)$$

Thus, the Cauchy-ness of sequences can be studied in terms of double limits, and hence in terms of nets.

Proposition 5.14. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space X converging to x, y . Then $x = y$.

Proof. Suppose that $x \neq y$. Then there are $r, \rho > 0$ such that $B(x, r) \cap B(y, \rho) = \emptyset$, say $r = \rho = d(x, y)/2$. Since $x_\alpha \rightarrow x$, the point x_α is eventually in $B(x, r)$. Since $x_\alpha \rightarrow y$, the point x_α is eventually in $B(y, \rho)$. Therefore, by the logic (5.6b), x_α is eventually in $B(x, r) \cap B(y, \rho)$, impossible. \square

Theorem 5.15. Let $f : X \rightarrow Y$ be map of metric spaces continuous at $x \in X$. Let $(x_\alpha)_{\alpha \in I}$ be a net in X converging to x . Then $\lim_{\alpha} f(x_\alpha) = f(x)$.

Proof. Choose any $\varepsilon > 0$. By Def. 2.38-(2) and the continuity of f at x , there exists $\delta > 0$ such that for all $p \in B(x, \delta)$ we have $f(p) \in B(f(x), \varepsilon)$. Since $x_\alpha \rightarrow x$, x_α is eventually in $B(x, \delta)$. Therefore $f(x_\alpha)$ is eventually in $B(f(x), \varepsilon)$. \square

This theorem implies, for example, that if (v_α) is a net in a complex normed vector space converging to v , and if (λ_α) is a net in \mathbb{C} converging to λ , then $\lambda_\alpha v_\alpha$ converges to λv because the scalar multiplication map is continuous (Prop. 3.37).

Exercise 5.16. Prove the generalization of Rem. 2.71:

1. If $(x_\alpha)_{\alpha \in I}, (y_\alpha)_{\alpha \in I}$ are nets in $\overline{\mathbb{R}}$ converging to $A, B \in \overline{\mathbb{R}}$, and if $x_\alpha \leq y_\alpha$ for all α , then $A \leq B$.
2. **Squeeze theorem:** Suppose that $(x_\alpha)_{\alpha \in I}, (y_\alpha)_{\alpha \in I}, (z_\alpha)_{\alpha \in I}$ are nets in $\overline{\mathbb{R}}$, $x_\alpha \leq y_\alpha \leq z_\alpha$ for all α , and x_α and z_α both converge to $A \in \overline{\mathbb{R}}$. Then $y_\alpha \rightarrow A$.
3. If (x_α) is an increasing resp. decreasing net in $\overline{\mathbb{R}}$, then $\lim_\alpha x_\alpha$ exists in $\overline{\mathbb{R}}$ and equals $\sup_\alpha x_\alpha$ resp. $\inf_\alpha x_\alpha$.

5.2.3 Subnets (in the sense of Willard)

Definition 5.17. A subset E of a directed set I is called **cofinal** if:

$$\forall \alpha \in I \quad \exists \beta \in E \quad \text{such that } \alpha \leq \beta$$

By the transitivity in Def. 5.1 and property (5.1), we clearly have

$$\forall \alpha_1, \dots, \alpha_n \in I \quad \exists \beta \in E \quad \text{such that } \alpha_1 \leq \beta, \dots, \alpha_n \leq \beta$$

Definition 5.18. Let $(x_\alpha)_{\alpha \in I}$ be a net in a set X . A **subnet** of $(x_\alpha)_{\alpha \in I}$ is, by definition, of the form $(x_{\alpha_s})_{s \in S}$ where S is a directed set, and

$$(\alpha_s)_{s \in S} : S \rightarrow I \quad s \mapsto \alpha_s$$

is an increasing function whose range $\{\alpha_s : s \in S\}$ is cofinal in I .

Remark 5.19. There are several different definitions of subnets that are equivalent for proving the main results in point-set topology. Unfortunately, there is no common agreement on the standard definition of subnets. The definition we gave is due to Willard [Wil], and is also the one given in the famous textbook of Munkres [Mun]. Some famous analysis and topology textbooks (e.g. [Fol, Kel, RS]) use a weaker definition, which does not assume that the map $S \rightarrow I$ is increasing.

Example 5.20. A subsequence is a subnet.

Example 5.21. Let $(x_{m,n})_{m,n \in \mathbb{Z}_+}$ be a net with index set $\mathbb{Z}_+ \times \mathbb{Z}_+$. Then $(x_{k,k})_{k \in \mathbb{Z}_+}$ and $(x_{2k,k})_{k \in \mathbb{Z}_+}$ are subnets. $(x_{k,1})_{k \in \mathbb{Z}_+}$ is not a subnet, because the cofinal condition is not satisfied. More generally, it is not hard to show that for every function $\varphi, \psi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$, $(x_{\varphi(k), \psi(k)})_{k \in \mathbb{Z}_+}$ is a subnet iff φ, ψ are increasing and $\lim_{k \rightarrow \infty} \varphi(k) = \lim_{k \rightarrow \infty} \psi(k) = +\infty$.

Exercise 5.22. Prove the following facts:

- The cofinal subset of a cofinal subset of a directed set I is a cofinal subset of I .
- The subnet of a subnet of a net (x_α) is a subnet of (x_α) .

Note that in your proof you need to use the transitivity in Def. 5.1.

The biggest difference between subnets and subsequences is that the index set of a subnet is not necessarily a subset of the index set of the original net. Indeed, subnets are defined in this way mainly because we want to have a net version of Pb. 3.1 in any topological space. (This will be achieved in Pb. 7.2.) Let us see an elementary example of subnet whose index set is larger than that of the original net. Its importance is justified by the proofs of Exp. 5.28 and Prop. 5.34.

Example 5.23. Let J be a directed set. Then every net $(x_\alpha)_{\alpha \in I}$ has subnet $(x_\alpha)_{(\alpha, \beta) \in I \times J}$. The corresponding increasing map of directed sets is the projection $I \times J \rightarrow I$ onto the first component.

To appreciate the importance of cofinality (as well as transitivity), we prove the following generalization of Prop. 2.36. This result has a wide range of surprising applications that are unavailable when one only considers sequences. (We will see them soon in this chapter. For instance, this result explains why the values of absolutely convergent series are invariant under rearrangement.) So I call this result a theorem, even though its proof is simple.

Theorem 5.24. Let $(x_\alpha)_{\alpha \in I}$ be a net in a metric space (or more generally, a topological space) X converging to $x \in X$. Then every subnet $(x_{\alpha_s})_{s \in S}$ converges to x .

The following proof for metric spaces can be generalized straightforwardly to topological spaces. The readers can come back and check the details after learning topological spaces.

Proof. Choose any $\varepsilon > 0$. Since $x_\alpha \rightarrow x$, there exists $\beta \in I$ such that for all $\alpha \geq \beta$ we have $d(x_\alpha, x) < \varepsilon$. By the cofinality, there exists $t \in S$ such that $\alpha_t \geq \beta$. Thus, since $s \in S \mapsto \alpha_s \in I$ is increasing, for every $s \geq t$, we have $\alpha_s \geq \alpha_t \geq \beta$ and hence $\alpha_s \geq \beta$ by the transitivity in Def. 5.1. So $d(x_{\alpha_s}, x) < \varepsilon$ for all $s \geq t$. This finishes the proof. \square

This proposition does not hold if one does not assume cofinality in the definition of subnets:

Example 5.25. Let (x_n) be a sequence in \mathbb{R} converging to $x \in \mathbb{R}$. Since (x_n) is a Cauchy sequence, we know that $\lim_{m, n \rightarrow \infty} x_m - x_n = 0$. We have seen in Exp. 5.21 that $(x_{2k} - x_k)_{k \in \mathbb{Z}_+}$ is a subnet of $(x_{m, n})$. Therefore, $\lim_{k \rightarrow \infty} x_{2k} - x_k = 0$. But

$(x_k - x_1)_{k \in \mathbb{Z}_+}$ is not a subnet since the cofinal condition is not satisfied. And if $x \neq x_1$, then $\lim_k (x_k - x_1) = x - x_1 \neq 0$, i.e.,

$$\lim_{k \rightarrow \infty} (x_k - x_1) \neq \lim_{m, n \rightarrow \infty} (x_m - x_n)$$

In Subsec. 2.3.2, we have seen two criteria for the divergence of sequence: a sequence diverges if it is unbounded, or if it has two subsequences converging to different points. By Thm. 5.24, the second criterion can be generalized to nets. However, the following example shows that the first criterion does not have its net version:

Example 5.26. A convergent net $(x_\alpha)_{\alpha \in I}$ in a metric space X is not necessarily **bounded**. Namely, it is not necessarily true that $\{x_\alpha : \alpha \in I\}$ is a bounded subset of X . Let $f : \mathbb{R}_{>0} \rightarrow \mathbb{R}$ be $f(x) = 1/x$. Then f is net in \mathbb{R} with directed set $(\mathbb{R}_{>0}, \leq)$. This net is not bounded, although $\lim f(x) = 0$.

Example 5.27. The double sequence $x_{m,n} = n/(m+n)$ in \mathbb{R} has subnets $x_{n,n} = n/(n+n) = 1/2$ and $x_{2n,n} = 1/3$. Since these two subnets converge to different values, Thm. 5.24 implies that $\lim_{m,n} x_{m,n}$ does not exist. However, the **iterated limits** exist and take different values:

$$\lim_{m \rightarrow \infty} \lim_{n \rightarrow \infty} \frac{n}{m+n} = 1 \quad \lim_{n \rightarrow \infty} \lim_{m \rightarrow \infty} \frac{n}{m+n} = 0$$

As we shall see, this gives another criterion for the divergence of double series: If the two iterated limits exist and are different, then the double series diverge.

Finally, we do an example of convergent double sequence:

Example 5.28. Let $x_{m,n} = (m^{-2} - n^{-1}) \sin \frac{\pi(m + \sqrt{n})}{4}$. Then $\lim_{m,n \rightarrow \infty} x_{m,n} = 0$.

Proof. The sequence $(m^{-2})_{m \in \mathbb{Z}_+}$ converges to 0. By Exp. 5.23, the double sequence $(m^{-2})_{m,n \in \mathbb{Z}_+}$ is its subnet, and hence converges to 0 by Thm. 5.24. Similarly, the double sequence $(n^{-1})_{m,n \in \mathbb{Z}_+}$ converges to 0. Therefore, $m^{-2} + n^{-1}$ converges to 0 due to Thm. 5.15 and the continuity of the addition map $(x, y) \in \mathbb{R} \rightarrow x + y \in \mathbb{R}$ (Prop. 2.45). Since $0 \leq |x_{m,n}| \leq m^{-2} + n^{-1}$, we conclude $|x_{m,n}| \rightarrow 0$ (and hence $x_{m,n} \rightarrow 0$) by squeeze theorem (Exe. 5.16). \square

5.2.4 Double limits and iterated limits

Theorem 5.29. Let $(x_{\alpha,\beta})_{\alpha \in I, \beta \in J}$ be a double net in a metric space X . Assume that the following are true:

- (1) The limit $\lim_{(\alpha,\beta) \in I \times J} x_{\alpha,\beta}$ exists in X .

(2) For each $\alpha \in I$, the limit $\lim_{\beta \in J} x_{\alpha, \beta}$ exists in X .

Then the LHS limit in the following equation exists and equals the RHS:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{(\alpha, \beta) \in I \times J} x_{\alpha, \beta} \quad (5.9)$$

In particular, suppose that the following is also true:

(3) For each $\beta \in J$, the limit $\lim_{\alpha \in I} x_{\alpha, \beta}$ exists in X .

Then the following limits exist and are equal:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{\beta \in J} \lim_{\alpha \in I} x_{\alpha, \beta} \quad (5.10)$$

Proof. Let $x_\alpha = \lim_{\beta} x_{\alpha, \beta}$ and $x = \lim_{\alpha, \beta} x_{\alpha, \beta}$. We want to show that $\lim_{\alpha} x_\alpha = x$. Choose any $\varepsilon > 0$. Then there exist $A \in I, B \in J$ such that for every $\alpha \geq A$ and $\beta \geq B$ we have $d(x_{\alpha, \beta}, x) < \varepsilon/3$. In particular, $d(x_{\alpha, \beta}, x) \leq \varepsilon/2$. Using Thm. 5.15 and the fact that $p \in X \mapsto d(p, x) \in \mathbb{R}$ is continuous (Exp. 2.58), we see that for every $\alpha \geq A$ we have $d(x_\alpha, x) = \lim_{\beta \in J_{\geq B}} d(x_{\alpha, \beta}, x) \leq \varepsilon/2 < \varepsilon$. \square

The readers may skip the next remark and proof and come back to them when they have learned about topological spaces.

★ **Remark 5.30.** Thm. 5.29 can be generalized to the case that X is a regular topological space. By saying that the topological space X is **regular**, we mean that for every $x \in X$ and every open set U containing x , there is a smaller open set V containing x such that the closure \overline{V} (cf. Def. 7.28) is contained in U .

★ *Proof.* Let $x_\alpha = \lim_{\beta} x_{\alpha, \beta}$ and $x = \lim_{\alpha, \beta} x_{\alpha, \beta}$. Choose any open set U containing x . We want to prove that x_α is eventually in U . Choose an open set V containing x such that $\overline{V} \subset U$. Then there are $A \in I, B \in J$ such that for all $\alpha \geq A$ and $\beta \geq B$ we have $x_{\alpha, \beta} \in V$. Thus, for each $\alpha \geq A$, since $x_{\alpha, \beta}$ approaches x_α , we have $x_\alpha \in \overline{V}$ and hence $x_\alpha \in U$. \square

Corollary 5.31. Let $(x_{\alpha, \beta})_{\alpha \in I, \beta \in J}$ be a double net in $\overline{\mathbb{R}}$. Assume that $x_{\bullet, \bullet}$ is increasing, i.e., $x_{\alpha, \beta} \leq x_{\alpha', \beta'}$ if $\alpha \leq \alpha'$ and $\beta \leq \beta'$. Then the following equation (5.11) hold, where all the limits (5.11) exist in $\overline{\mathbb{R}}$:

$$\lim_{\alpha \in I} \lim_{\beta \in J} x_{\alpha, \beta} = \lim_{\beta \in J} \lim_{\alpha \in I} x_{\alpha, \beta} = \lim_{(\alpha, \beta) \in I \times J} x_{\alpha, \beta} = \sup\{x_{\alpha, \beta} : \alpha \in I, \beta \in J\} \quad (5.11)$$

Clearly, a similar result holds for decreasing double nets in $\overline{\mathbb{R}}$.

Proof. By Exe. 5.16, the three limits $\lim_{\alpha} x_{\alpha, \beta}$, $\lim_{\beta} x_{\alpha, \beta}$, and $\lim_{\alpha, \beta} x_{\alpha, \beta}$ exist in $\overline{\mathbb{R}}$. Therefore, by Thm. 5.29, the three limits in (5.11) exist and are equal. The last equality in (5.11) is also due to Exe. 5.16. \square

5.2.5 Cauchy nets

Definition 5.32. A net $(x_\alpha)_{\alpha \in I}$ in a metric space X is called a Cauchy net if

$$\lim_{\alpha, \beta \in I} d(x_\alpha, x_\beta) = 0$$

Equivalently, this means that

$$\forall \varepsilon > 0 \quad \exists \gamma \in I \quad \text{such that } \forall \alpha, \beta \geq \gamma \quad \text{we have } d(x_\alpha, x_\beta) < \varepsilon \quad (5.12)$$

Exercise 5.33. Show that the subnet of a Cauchy net is Cauchy.

Proposition 5.34. A convergent net in a metric space is a Cauchy net.

Proof. Let $(x_\alpha)_{\alpha \in I}$ converge to x in a metric space X . Then $\lim_\alpha d(x_\alpha, x) = 0$. Since $(d(x_\alpha, x))_{\alpha, \beta \in I}$ is a subnet (cf. Exp. 5.23), we have $\lim_{\alpha, \beta} d(x_\alpha, x) = 0$ by Thm. 5.24. Similarly, we have $\lim_{\alpha, \beta} d(x, x_\beta) = 0$. Since $0 \leq d(x_\alpha, x_\beta) \leq d(x_\alpha, x) + d(x, x_\beta)$, by Squeeze theorem (Exe. 5.16) we have $\lim_{\alpha, \beta} d(x_\alpha, x_\beta) = 0$. \square

Proposition 5.35. Let $(x_\alpha)_{\alpha \in I}$ be a Cauchy net in a metric space X . Suppose that $(x_\alpha)_{\alpha \in I}$ has a convergent subnet $(x_{\alpha_s})_{s \in S}$ converging to $x \in X$. Then $(x_\alpha)_{\alpha \in I}$ converges to x .

Proof. Choose any $\varepsilon > 0$. Since (x_α) is a Cauchy net, there exists $\gamma \in I$ such that $d(x_\alpha, x_\beta) \leq \varepsilon$ for all $\alpha, \beta \geq \gamma$. Since $(\alpha_s)_{s \in S}$ has cofinal range, $\alpha_{s_0} \geq \gamma$ for some $s_0 \in S$. Thus $\alpha_s \geq \gamma$ for all $s \geq s_0$ because $(\alpha_s)_{s \in S}$ is increasing and because of the transitivity in Def. 5.1. Thus, for every $\beta \geq \gamma$, $d(x_{\alpha_s}, x_\beta) \leq \varepsilon$ for sufficiently large s . By taking limit over s and using the continuity of $y \in X \mapsto d(y, x_\beta)$ as well as Thm. 5.15, we get $d(x, x_\beta) \leq \varepsilon$ for all $\beta \geq \gamma$. \square

Definition 5.36. Two nets $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ in a metric space X are called **Cauchy-equivalent** if

$$\lim_{\alpha \in I} d(x_\alpha, y_\alpha) = 0$$

Two Cauchy nets are simply called **equivalent** if they are Cauchy-equivalent. It is not hard to see that Cauchy-equivalence is an equivalence relation (recall Def. 1.17) on X^I .

Exercise 5.37. Let $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ be nets in a metric space X .

1. Assume that $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ are Cauchy-equivalent. Prove that (x_α) is a Cauchy net iff (y_α) is a Cauchy net.
2. Assume that $(x_\alpha)_{\alpha \in I}$ converges to x . Prove that $(y_\alpha)_{\alpha \in I}$ converges to x iff $(x_\alpha)_{\alpha \in I}$ and $(y_\alpha)_{\alpha \in I}$ are Cauchy-equivalent.

Theorem 5.38. Every Cauchy net $(x_\alpha)_{\alpha \in I}$ in a complete metric space X is convergent.

We give a hint of the proof and leave the details to the readers as an exercise.

Hint. Construct an increasing sequence $(\alpha_n)_{n \in \mathbb{Z}_+}$ in I such that for every $\beta, \gamma \geq \alpha_n$ we have $d(x_\beta, x_\gamma) < 1/n$. Prove that $(x_{\alpha_n})_{n \in \mathbb{Z}_+}$ is a Cauchy sequence, and hence converges to some $x \in X$. Prove that $(x_\alpha)_{\alpha \in I}$ converges to x . (Warning: $(x_{\alpha_n})_{n \in \mathbb{Z}_+}$ is not necessarily a subnet of $(x_\alpha)_{\alpha \in I}$.) \square

5.3 Discrete integrals $\sum_{x \in X} f(x)$

In this section, we fix V to be a Banach space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. We fix a (non-necessarily countable) set X . Note that if $f : X \rightarrow V$ is a function and X is finite, then $\sum_{x \in X} f(x)$ can be understood in its most obvious way.

Definition 5.39. Let $f : X \rightarrow V$ be a map. The expression

$$\sum_{x \in X} f(x)$$

(or simply $\sum_X f$) is called a **discrete integral**. If $v \in V$, we say that $\sum_{x \in X} f(x)$ equals (or converges to) v , if

$$\lim_{A \in \text{fin}(2^X)} \sum_{x \in A} f(x) = v \quad (5.13)$$

In this case, we write

$$\sum_{x \in X} f(x) = v \quad (5.14)$$

Remark 5.40. Recall from Exp. 5.6 that $\text{fin}(2^X)$ is the directed set of finite subsets of 2^X . Its preorder is “ \subset ”. So (5.14) means more precisely that:

- For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for every finite set A satisfying $B \subset A \subset X$, we have $\|v - \sum_{x \in A} f(x)\| < \varepsilon$.

Remark 5.41. Discrete integrals are one of the most important and representative examples in Moore and Smith’s original paper on nets (cf. [MS22]), explaining why nets are called nets: Imagine an infinitely large *fishing net* whose vertices form the set $X = \mathbb{Z}^2$. You grab the net with your hands and pull it up. As you pull it up, the lifted part $A \in \text{fin}(2^X)$ becomes larger and larger.

Remark 5.42. One of the advantages of discrete integrals over series is that discrete integrals are clearly invariant under rearrangement: For every bijection $\varphi : X \rightarrow X$, if one side of the following equation converges in V , then the other side converges, and the equation holds true:

$$\sum_{x \in X} f(x) = \sum_{x \in X} f(\varphi(x)) \quad (5.15)$$

or simply $\sum_X f = \sum_X f \circ \varphi$.

Remark 5.43. Let us spell out what Cauchyness means for the net $(\sum_A f)_{A \in \text{fin}(2^X)}$:

- (1) For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for any finite sets A_1, A_2 satisfying $B \subset A_1 \subset X, B \subset A_2 \subset X$, we have

$$\left\| \sum_{A_1 \setminus A_2} f - \sum_{A_2 \setminus A_1} f \right\| < \varepsilon$$

Note that the term inside the norm is $\sum_{A_1} f - \sum_{A_2} f$. This is also equivalent to:

- (2) For every $\varepsilon > 0$, there exists a finite set $B \subset X$ such that for any finite set $E \subset X \setminus B$, we have

$$\left\| \sum_E f \right\| < \varepsilon$$

We shall mainly use (2) as the Cauchy criterion for the convergence of $\sum_X f$.

Proof of the equivalence. (2) follows from (1) by taking $A_1 = B$ and $A_2 = B \cup E$. (1) follows from (2) by taking $E_1 = A_1 \setminus A_2$ and $E_2 = A_2 \setminus A_1$ and then concluding $\|\sum_{E_1} f - \sum_{E_2} f\| < 2\varepsilon$. \square

Definition 5.44. Let $g : X \rightarrow \overline{\mathbb{R}}_{\geq 0}$ be a map. Note that the net $(\sum_A g)_{A \in \text{fin}(2^X)}$ is increasing. Hence, its limit exists in $\overline{\mathbb{R}}$ and equals $\sup_{A \in \text{fin}(2^X)} \sum_A g$ (by Exe. 5.16). We write this as $\sum_X g$, or more precisely:

$$\sum_X g \equiv \sum_{x \in X} g(x) \stackrel{\text{def}}{=} \lim_{A \in \text{fin}(2^X)} \sum_A g = \sup_{A \in \text{fin}(2^X)} \sum_A g \quad (5.16)$$

We say that $\sum_X g$ **converges** or **converges absolutely**, if $\sum_X g < +\infty$.

It is clear that $\sum_X g < +\infty$ iff there exists $C \in \mathbb{R}_{\geq 0}$ such that $\sum_A g < C$ for all $A \in \text{fin}(2^X)$.

Remark 5.45. Note that when $g : X \rightarrow \mathbb{R}_{\geq 0}$, the convergence in Def. 5.44 agrees with that in Def. 5.39. Therefore, Rem. 5.43 still gives a Cauchy criterion for convergence.

Definition 5.46. Let $f : X \rightarrow V$. We say that $\sum_X f$ **converges absolutely** if

$$\sum_{x \in X} \|f(x)\| < +\infty$$

Proposition 5.47. Let $f : X \rightarrow V$. If $\sum_X f$ converges absolutely, then it converges, and

$$\left\| \sum_{x \in X} f(x) \right\| \leq \sum_{x \in X} \|f(x)\| \quad (5.17)$$

We write this simply as $\|\sum_X f\| \leq \sum_X |f|$. (Recall Def. 3.38.)

Proof. (5.17) clearly holds when X is finite. In the general case, assume that $\sum_X f$ converges absolutely. Then by Cauchy criterion (Rem. 5.43-(2)), for every $\varepsilon > 0$ there is $A \in \text{fin}(2^X)$ such that for each finite $E \subset X \setminus A$ we have $\sum_E |f| < \varepsilon$, and hence $\|\sum_E f\| < \varepsilon$. Therefore $\sum_X f$ converges by Cauchy criterion again.

By the continuity of the norm function $v \in V \mapsto \|v\| \in \mathbb{R}_{\geq 0}$, and by Thm. 5.15, we have

$$\left\| \sum_X f \right\| = \left\| \lim_A \sum_A f \right\| = \lim_A \left\| \sum_A f \right\|$$

Since $\|\sum_A f\| \leq \sum_A |f|$, by Exe. 5.16, the above expression is no less than

$$\lim_A \sum_A |f| = \sum_X |f|$$

□

The following proposition gives another demonstration that discrete integrals are more natural than series. We leave the proof to the readers.

Proposition 5.48. *Let $f : X \rightarrow \mathbb{R}^N$ where $N \in \mathbb{Z}_+$. Then*

$$\sum_{x \in X} f(x) \text{ converges} \iff \sum_{x \in X} f(x) \text{ converges absolutely}$$

Hint. Reduce to the case $N = 1$. Consider $A = \{x \in X : f(x) \geq 0\}$ and $B = X \setminus A$. □

When \mathbb{R}^N is replaced by an infinite-dimensional Banach space, the convergence of a discrete integral may not imply absolute convergence. See Pb. 5.6.

5.4 Fubini theorem for discrete integrals

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. Let X, Y be sets.

Theorem 5.49 (Fubini theorem-A). *Let $f : X \times Y \rightarrow V$. Assume that $\sum_{X \times Y} f$ converges. Then $\sum_Y f(x, \cdot)$ converges for each $x \in X$, and $\sum_X f(\cdot, y)$ converges for each $y \in Y$, and*

$$\sum_{x \in X} \sum_{y \in Y} f(x, y) = \sum_{y \in Y} \sum_{x \in X} f(x, y) = \sum_{(x, y) \in X \times Y} f(x, y) \quad (5.18)$$

where all discrete integrals converge in V .

We abbreviate (5.18) to $\sum_X \sum_Y f = \sum_Y \sum_X f = \sum_{X \times Y} f$.

Proof. For each $x \in X$, let $f_x(y) = f(x, y)$. Let us prove that $\sum_Y f_x$ converges. Choose any $\varepsilon > 0$. Since $\sum_{X \times Y} f$ converges, by Cauchy criterion (Rem. 5.43-(2)), there exists a finite $S \subset X \times Y$ such that the sum of f over any finite subset outside S has norm $< \varepsilon$. The projection $X \times Y \rightarrow Y$ maps S to a finite set $B \subset Y$. Thus, for each finite $E \subset Y \setminus B$, we have $\|\sum_E f_x\| < \varepsilon$ since $x \times E$ is outside S . Therefore $\sum_Y f_x$ converges. By the same reasoning, $\sum_X f(\cdot, y)$ converges for all y .

Recall that $\sum_{X \times Y} f$ is the limit of the net $(\sum_S f)_{S \in \text{fin}(2^{X \times Y})}$. This net has subnet

$$\left(\sum_{(x,y) \in A \times B} f(x, y) \right)_{A \in \mathcal{I}, B \in \mathcal{J}} \quad \text{where } \mathcal{I} = \text{fin}(2^X) \quad \mathcal{J} = \text{fin}(2^Y)$$

(Its index set is $\mathcal{I} \times \mathcal{J}$.) Thus, by Thm. 5.24,

$$\sum_{(x,y) \in X \times Y} f(x, y) = \lim_{A \in \mathcal{I}, B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) \quad (5.19)$$

We are now going to use Thm. 5.29 to show that

$$\lim_{A \in \mathcal{I}, B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) = \lim_{A \in \mathcal{I}} \lim_{B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) \quad (5.20)$$

where the RHS limit exists. For that purpose, we need to check for each $A \in \mathcal{I}$ the convergence of $\lim_B \sum_{(x,y) \in A \times B} f(x, y)$. Since $\sum_Y f_x$ converges, we have

$$\begin{aligned} \lim_{B \in \mathcal{J}} \sum_{(x,y) \in A \times B} f(x, y) &= \lim_{B \in \mathcal{J}} \sum_{x \in A} \sum_{y \in B} f(x, y) \\ &= \sum_{x \in A} \lim_{B \in \mathcal{J}} \sum_{y \in B} f(x, y) = \sum_{x \in A} \sum_{y \in Y} f(x, y) \end{aligned} \quad (5.21)$$

(Note that \sum_A is a finite sum and hence commutes with \lim_B .) Thus, the assumption in Thm. 5.29 ensuring (5.20) has now been proved true. So (5.20) is true. Moreover, combining (5.19), (5.20), (5.21) together, we get

$$\sum_{(x,y) \in X \times Y} f(x, y) = \lim_{A \in \mathcal{I}} \sum_{x \in A} \sum_{y \in Y} f(x, y) = \sum_{x \in X} \sum_{y \in Y} f(x, y)$$

where the second and the third limits exist. This proves a half of (5.18). The other half can be proved in the same way. \square

Theorem 5.50 (Fubini theorem-B). Let $g : X \times Y \rightarrow \overline{\mathbb{R}}_{\geq 0}$. Then the five discrete integrals in (5.22) exist in $\overline{\mathbb{R}}_{\geq 0}$, and equations (5.22) hold in $\overline{\mathbb{R}}_{\geq 0}$:

$$\sum_{x \in X} \sum_{y \in Y} f(x, y) = \sum_{y \in Y} \sum_{x \in X} f(x, y) = \sum_{(x,y) \in X \times Y} f(x, y) \quad (5.22)$$

Proof. The existence in $\overline{\mathbb{R}}_{\geq 0}$ of the five discrete integrals is clear. (Recall Def. 5.44.) Formula (5.22) can be proved in the same way as (5.18). Note that when applying Thm. 5.29 to prove (5.22), the assumption in Thm. 5.29 on the existence of limits is satisfied because all nets involved are increasing in $\overline{\mathbb{R}}$. (Recall Exe. 5.16.) \square

Corollary 5.51 (Fubini theorem-C). *Let $f : X \times Y \rightarrow V$. Then the following are equivalent.*

- (1) $\sum_{X \times Y} f$ converges absolutely.
- (2) $\sum_{x \in X} \sum_{y \in Y} \|f(x, y)\| < +\infty$.
- (3) $\sum_{y \in Y} \sum_{x \in X} \|f(x, y)\| < +\infty$.

Proof. Immediate from Thm. 5.50. It is also not hard to prove it directly. \square

5.5 Parametrization theorem for discrete integrals

We fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$. In the following sections, we shall apply the results about discrete integrals to the study of series and double series. For the convenience of applications (e.g. the proof of $e^z e^w = e^{z+w}$), we enlarge the concept of series a little:

5.5.1 Series over \mathbb{Z}

Definition 5.52. A **series over \mathbb{Z}** is an expression

$$\sum_{n=-\infty}^{+\infty} f(n)$$

where f is a function from \mathbb{Z} to either V or $\overline{\mathbb{R}}_{\geq 0}$. We say that this series **converges to** (or equals) $\mu \in V$ resp. equals $\mu \in \overline{\mathbb{R}}_{\geq 0}$, if

$$\lim_{m, n \rightarrow +\infty} \sum_{i=-m}^n f(i) = \mu \quad (5.23)$$

In this case, we write

$$\sum_{n=-\infty}^{+\infty} f(n) = \mu$$

We say that $\sum_{n=-\infty}^{+\infty} f(n)$ **converges absolutely** if $\sum_{n=-\infty}^{+\infty} \|f(n)\| < +\infty$.

Remark 5.53. Note that in the case of $\overline{\mathbb{R}}_{\geq 0}$, the limit on the LHS of (5.23) must exist in $\overline{\mathbb{R}}_{\geq 0}$. Again, this is due to the fact that the involved net is increasing, and so one can use Exe. 5.16.

Exercise 5.54. Let $\sum_{n=-\infty}^{+\infty} f(n)$ be a series in either V or $\overline{\mathbb{R}}_{\geq 0}$.

1. Fix $k \in \mathbb{Z}$. Prove that $\sum_{n=-\infty}^{+\infty} f(n)$ converges iff the following limits converge:

$$\sum_{n=k}^{+\infty} f(n) = \lim_{n \rightarrow +\infty} \sum_{i=k}^n f(i) \quad (5.24a)$$

$$\sum_{n=-\infty}^{k-1} f(n) = \lim_{m \rightarrow +\infty} \sum_{i=-m}^{k-1} f(i) \quad (5.24b)$$

Moreover, if these limits converge, then

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=k}^{+\infty} f(n) + \sum_{n=-\infty}^{k-1} f(n) \quad (5.25)$$

2. In the case that f has codomain V , prove that $\sum_{n=-\infty}^{+\infty} f(n)$ converges if it converges absolutely.
3. Prove that if f is zero outside \mathbb{Z}_+ , then

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=1}^{+\infty} f(n) \quad (5.26)$$

Thus, by (5.26), our following results about series over \mathbb{Z} can be directly applied to series over \mathbb{Z}_+ (or over $\mathbb{Z}_{\geq k}$ where $k \in \mathbb{Z}$).

5.5.2 Parametrization theorem

The following theorem relates series and discrete integrals. The structure of this theorem is similar to that of Fubini theorem-A,B,C in Sec. 5.4.

Theorem 5.55 (Parametrization theorem). *Let X be an infinite countable set. Let $\varphi : \mathbb{Z} \rightarrow X$ be a bijection (called a **parametrization** of X). The following are true.*

1. *Let $f : X \rightarrow V$. If the RHS of (5.27) converges in V , then the LHS converges, and (5.27) holds:*

$$\sum_{n=-\infty}^{+\infty} f \circ \varphi(n) = \sum_{x \in X} f(x) \quad (5.27)$$

2. *Let $f : X \rightarrow \overline{\mathbb{R}}_{\geq 0}$. Then (5.27) holds in $\overline{\mathbb{R}}_{\geq 0}$.*

3. Let $f : X \rightarrow V$. Then the discrete integral $\sum_{x \in X} f(x)$ converges absolutely iff the

series $\sum_{n=-\infty}^{+\infty} f \circ \varphi(n)$ converges absolutely.

The same conclusions hold if we assume that $\varphi : \mathbb{Z}_+ \rightarrow X$ is a bijection.

Proof. We prove the case $\varphi : \mathbb{Z} \rightarrow X$; the other case is similar.

Assume that $\sum_X f$ converges, which means that the limit of the net $(\sum_A f)_{A \in \text{fin}(2^X)}$ converges to some $v \in V$. Therefore, by Thm. 5.24, the subnet

$$\left(\sum_{x \in A_{m,n}} f(x) \right)_{m,n \in \mathbb{Z}_+} = \left(\sum_{i=-m}^n f \circ \varphi(i) \right)_{m,n \in \mathbb{Z}_+}$$

converges to v , where $A_{m,n} = \{\varphi(i) : i \in \mathbb{Z}, -m \leq i \leq n\}$. This proves part 1. The same method proves part 2. Part 3 follows directly from part 2. \square

5.6 Application to (double) series and power series; $e^z e^w = e^{z+w}$

Fix a Banach space V over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$.

5.6.1 General results about series and double series

Corollary 5.56. Let $f : \mathbb{Z} \rightarrow V$, and let $\psi : \mathbb{Z} \rightarrow \mathbb{Z}$ be a bijection. Suppose that

$$\sum_{n=-\infty}^{+\infty} \|f(n)\| < +\infty \quad (5.28)$$

Then (5.29) holds true, where the RHS of (5.29) converges absolutely:

$$\sum_{n=-\infty}^{+\infty} f(n) = \sum_{n=-\infty}^{+\infty} f \circ \psi(n) \quad (5.29)$$

The same conclusion clearly holds if \mathbb{Z} is replaced by \mathbb{Z}_+ .

Proof. By (5.28) and Thm. 5.55-3, the discrete integral $\sum_{\mathbb{Z}} f$ converges absolutely, and hence converges. By Thm. 5.55-1, the LHS resp. RHS of (5.29) converges to the value of $\sum_{\mathbb{Z}} f$ if we choose the parametrization to be $\text{id}_{\mathbb{Z}}$ resp. ψ . This proves (5.29) and the convergence of the RHS of (5.29). Applying the same conclusion to $\|f(\cdot)\|$ proves the absolute convergence of the RHS of (5.29). \square

Corollary 5.57. Let $f : \mathbb{Z}^2 \rightarrow V$. Let $\Phi : \mathbb{Z}^2 \rightarrow \mathbb{Z}^2$ be a bijection. Suppose that

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} \|f(m,n)\| < +\infty \quad (5.30)$$

Then (5.31) holds true, where the six series involved in (5.31) converge absolutely.

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} f(m, n) = \sum_{n=-\infty}^{+\infty} \sum_{m=-\infty}^{+\infty} f(m, n) = \sum_{k=-\infty}^{+\infty} \sum_{l=-\infty}^{+\infty} f \circ \Phi(k, l) \quad (5.31)$$

Similar results clearly hold if \mathbb{Z}^2 is replaced by \mathbb{Z}_+^2 : One extends the domain of f and the domain and codomain of Φ from \mathbb{Z}_+^2 to \mathbb{Z}^2 . Then one apply Cor. 5.57.

Also, note that the second term of (5.31) is redundant: it follows from the equality of the first and the third terms of (5.31) if we choose $\Phi(k, l) = (l, k)$.

Proof. By Thm. 5.55-2 and Thm. 5.50, we have

$$\sum_{m=-\infty}^{+\infty} \sum_{n=-\infty}^{+\infty} \|f(m, n)\| = \sum_{x \in \mathbb{Z}} \sum_{y \in \mathbb{Z}} \|f(x, y)\| = \sum_{(x, y) \in \mathbb{Z}^2} \|f(x, y)\| \quad (5.32)$$

where all the limits exist in $\overline{\mathbb{R}}_{\geq 0}$. Therefore, by (5.30), the discrete integral $\sum_{\mathbb{Z}^2} f$ is absolutely convergent and hence convergent.

Similar to the argument for (5.32), Thm. 5.55-1 and Thm. 5.49 imply that the first two terms of (5.31) exist and are both equal to the discrete integral $\sum_{\mathbb{Z}^2} f$. Since $\sum_{\mathbb{Z}^2} f = \sum_{\mathbb{Z}^2} f \circ \Phi$ (recall Rem. 5.42), by Thm. 5.55-1 and Thm. 5.49 again, the last term of (5.31) converges to $\sum_{\mathbb{Z}^2} f \circ \Phi$.

We have proved that the six series in (5.31) converge, and (5.31) holds. Replacing $f(\cdot, \cdot)$ with $\|f(\cdot, \cdot)\|$ and applying a similar argument, we see that the six series in (5.31) converge absolutely. \square

Remark 5.58. Using the same method as in the above proof, one can easily prove a more general version of Cor. 5.57: Let $N \in \mathbb{Z}_+$. Let $f : \mathbb{Z}^2 \rightarrow V$ such that (5.30) holds true. Let $\Psi : \mathbb{Z}^N \rightarrow \mathbb{Z}^2$ be a bijection. Then the N series involved in the expression of (5.33) (from innermost to outermost) converge absolutely:

$$\sum_{n_1=-\infty}^{+\infty} \cdots \sum_{n_N=-\infty}^{+\infty} f \circ \Psi(n_1, \dots, n_N) \quad (5.33)$$

Moverover, the outermost series of (5.33) converges to (5.31). And of course, a similar result holds if \mathbb{Z}^2 is replaced by \mathbb{Z}^M for every $M \in \mathbb{Z}_+$. We leave it to the readers to fill in the details.

Corollary 5.59. Assume that

$$A = \sum_{n=-\infty}^{+\infty} a_n \quad B = \sum_{n=-\infty}^{+\infty} b_n$$

are absolutely convergent series in \mathbb{C} . Then for each $k \in \mathbb{Z}$, the series

$$c_k = \sum_{l=-\infty}^{+\infty} a_{k-l} b_l$$

converges absolutely. Moreover, the LHS of the (5.34) converges absolutely to the RHS:

$$\sum_{k=-\infty}^{+\infty} c_k = AB \quad (5.34)$$

Proof. Apply Cor. 5.57 to the case that $f(m, n) = a_m b_n$ and $\Phi(k, l) = (k - l, l)$. \square

5.6.2 Application to power series

Corollary 5.60. Let $f(z) = \sum_{n=0}^{+\infty} a_n z^n$ and $g(z) = \sum_{n=0}^{+\infty} b_n z^n$ be power series in \mathbb{C} with radii of convergence R_1, R_2 respectively. Let $R = \min\{R_1, R_2\}$. For each $k \in \mathbb{Z}_+$, let

$$c_k = \sum_{l=0}^k a_{k-l} b_l$$

Then the power series $h(z) = \sum_{k=0}^{+\infty} c_k z^k$ has radius of convergence $\geq R$. Moreover, for each $z \in \mathbb{C}$ satisfying $0 \leq |z| < R$, we have

$$h(z) = f(z) \cdot g(z)$$

Proof. For each $0 \leq |z| < R$, apply Cor. 5.59 by replacing the a_n, b_n, c_k of Cor. 5.59 with $a_n z^n, b_n z^n, c_k z^k$. This shows that $h(z)$ converges absolutely to $f(z) \cdot g(z)$. Since this is true for all $|z| < R$, $h(z)$ must have radius of convergence at least R by Rem. 4.21. \square

The above result also holds more generally for Laurent series. See Exe. 5.66.

Corollary 5.61. For each $z, w \in \mathbb{C}$ we have

$$e^z e^w = e^{z+w}$$

Proof. Apply Cor. 5.59 to the case $a_n = z^n/n!$ and $b_n = w^n/n!$. (We set $a_n = b_n = 0$ if $n < 0$.) Then

$$c_k = \sum_{l=0}^k \frac{z^{k-l}}{(k-l)!} \cdot \frac{w^l}{l!} = \sum_{l=0}^k \binom{k}{l} \frac{z^{k-l} w^l}{k!} = \frac{(z+w)^k}{k!}$$

by (4.5). \square

5.7 Summary

The following are some fundamental questions about series and double series:

- (a) Are they invariant under rearrangement? (Cf. (5.29).)
- (b) Does the value of an iterated double series remain unchanged if the order of the two infinite sums is changed? (Cf. the first equality in (5.31).)
- (c) A mixture of the above two questions. (Cf. the last term of (5.31).)

We address these questions by relating them to discrete integral, a version of infinite sums which is parametrization-independent. The following are some key features of this theory.

- 1. (General principle) A discrete integral is to a series (defined by parametrization) as a net to a subnet.
- 2. (Net \Rightarrow Subnet) All subnets of a convergent net converge to the same value: the limit of the original net.
- 3. (Discrete integral \Rightarrow Series) Therefore, different series converge to the same value if they are different parametrizations of the same convergent discrete integral.
- 4. (Discrete integrals \Rightarrow Series) Fubini-type theorems (any theorems about exchanging the orders of iterated sums/integrals) hold for convergent double discrete integrals. Therefore, they hold when passing to subnets, in particular, when passing to double series.
- 5. (Subnet \Rightarrow Net) Every increasing net in $\overline{\mathbb{R}}_{\geq 0}$ has a limit in $\overline{\mathbb{R}}_{\geq 0}$. Therefore, if an increasing net in $\mathbb{R}_{\geq 0}$ has a subnet converging to a number $< +\infty$, then the original net converges in $\mathbb{R}_{\geq 0}$ (to a finite number).
- 6. (General principle) The discrete integral $\sum_{x \in X} \|f(x)\|$ is defined by the limit of an increasing net in $\overline{\mathbb{R}}_{\geq 0}$.
- 7. (Series \Rightarrow Discrete integral) Therefore, if any series or double series corresponds in a reasonable way to a discrete integral, then the absolute convergence of this (double) series (more specifically: (5.28) or (5.30)) implies the absolute convergence (and hence convergence) of the original discrete integral. This implies the absolute convergence of any other (double) series arising from that discrete integral.
- 8. (Conclusion) Thus, when a (double) series converges absolutely (in the form of (5.28) or (5.30)), the three problems (a), (b), (c) have satisfying answers. The reason absolutely convergent (double) series are so good is because increasing nets in $\overline{\mathbb{R}}_{\geq 0}$ are very good!

9. (Counterexamples) Non-absolutely convergent series in \mathbb{R} have rearrangements converging to different values. This is because non-convergent nets may have two subnets converging to different values, cf. Pb. 5.5. (Recall from Prop. 5.48 that for discrete integrals in \mathbb{R} , absolute convergence is equivalent to convergence.)

5.8 Problems and supplementary material

Let X be a set, and let V be a Banach space over $\mathbb{R} \in \{\mathbb{R}, \mathbb{C}\}$.

Problem 5.1. Compute $\lim_{p,q \rightarrow +\infty} a_{p,q}$ where $(a_{p,q})_{p,q \in \mathbb{Z}_+}$ are given below. Or explain why the limit does not exist.

$$a_{p,q} = \frac{(-1)^p \cdot p}{p+q} \quad a_{p,q} = \frac{(-1)^p}{p} \quad a_{p,q} = \frac{\cos(p\pi/4)}{p+q}$$

Problem 5.2. Prove Thm. 5.38. (Every Cauchy net in a complete metric space converges.)

Problem 5.3. Let $f : X \rightarrow V$. Define the **support** of f to be

$$\text{Supp}(f) = \{x \in X : f(x) \neq 0\} \quad (5.35)$$

Prove that if $\sum_X f$ converges absolutely, then $\text{Supp}(f)$ is a countable set.

Hint. Consider $\{x \in X : |f(x)| \geq \varepsilon\}$ where $\varepsilon > 0$. □

Problem 5.4. Prove Prop. 5.48.

★ **Problem 5.5.** Prove **Riemann rearrangement theorem**, which says the following: Let $\sum_{n=1}^{+\infty} x_n$ be a series in \mathbb{R} which converges and which does not converge absolutely. Choose any $A \in \mathbb{R}$. Then $\sum_{n=1}^{+\infty} x_n$ has a rearrangement converging to A (i.e., there is bijection $\varphi : \mathbb{Z}_+ \rightarrow \mathbb{Z}_+$ such that $\sum_{n=1}^{+\infty} f \circ \varphi(n) = A$).

Remark 5.62. By Riemann rearrangement theorem, it is clear that every convergent series in \mathbb{R}^N which is not absolutely convergent must have two rearrangements converging to two different points. However, when \mathbb{R}^N is replaced by an infinite dimensional Banach space, one may find a series $\sum_{n=1}^{+\infty} v_n$ which does not converge absolutely but converge to some v , and every rearrangement of $\sum_{n=1}^{+\infty} v_n$ converges to v . See Pb. 5.6.

Problem 5.6. Consider the case that V is the real Banach space $V = l^\infty(\mathbb{Z}_+, \mathbb{R})$. For each $n \in \mathbb{Z}_+$, let $e_n \in V$ be the characteristic function $\chi_{\{n\}}$. Namey, e_n takes value 1 at n , and takes 0 at the other points. Prove that the discrete integral

$$\sum_{n \in \mathbb{Z}_+} \frac{1}{n} e_n \quad (5.36)$$

converges in V , and find the limit. Prove that (5.36) does not converge absolutely.

Remark 5.63. A more important example that will be considered later is $V = l^2(\mathbb{Z}_+, \mathbb{C})$, the set of all functions $f : \mathbb{Z}_+ \rightarrow \mathbb{C}$ satisfying that the **l^2 -norm** $\|f\|_{l^2} = \sqrt{\sum_{n \in \mathbb{Z}_+} |f(n)|^2}$ is finite. Then V is in fact a Banach space. (Actually, it is a so-called **Hilbert space**.) Again, let $e_n = \chi_{\{n\}}$. (These e_n will be called an **orthonormal basis** of V .) Then for each $f \in V$, the discrete integral $\sum_{n \in \mathbb{Z}_+} f(n) \cdot e_n$ converges to f . But it does not converge absolutely if $\sum_{n \in \mathbb{Z}_+} |f(n)| = +\infty$. Take for example $f(n) = n^{-1}$. We will study these objects in the second semester.

Problem 5.7. Define $(x_{j,k})_{(j,k) \in \mathbb{Z}_+ \times \mathbb{Z}_+}$ to be

$$x_{j,k} = \begin{cases} \frac{1}{j^2 - k^2} & \text{if } j \neq k \\ 0 & \text{if } j = k \end{cases}$$

Prove that the discrete integral $\sum_{(j,k) \in \mathbb{Z}_+^2} x_{j,k}$ does not converge in \mathbb{R} .

Hint. Consider $(x_{j,k})$ as a net over \mathbb{Z}^2 . Find a good bijection $\Phi : \mathbb{Z}^2 \rightarrow \mathbb{Z}^2$. □

Definition 5.64. For each $f \in V^X$, define the **l^1 -norm**

$$\|f\|_{l^1(X,V)} \equiv \|f\|_{l^1} \equiv \|f\|_1 = \sum_{x \in X} \|f(x)\|$$

Define the l^1 -space

$$l^1(X, V) = \{f \in V^X : \|f\|_{l^1} < +\infty\}$$

Namely, $l^1(X, V)$ is the set of all $f \in V^X$ where $\sum_X f$ converges absolutely. In particular, $\sum_X f$ converges for such f .

Exercise 5.65. Prove that for each $f, g \in V^X$ and $\lambda \in \mathbb{F}$, we have

$$\|f + g\|_1 \leq \|f\|_1 + \|g\|_1 \quad \|\lambda f\|_1 = |\lambda| \cdot \|f\|_1 \quad (5.37)$$

Show that $l^1(X, V)$ is a linear subspace of $l^\infty(X, V)$, and that $\|\cdot\|_{l^1}$ is a norm on $l^1(X, V)$

Problem 5.8. Prove that $l^1(X, V)$ is a Banach space. Namely, prove that the metric on $l^1(X, V)$ defined by the l^1 -norm is complete.

Problem 5.9. Prove the **dominated convergence theorem** for discrete integrals: Let $(f_\alpha)_{\alpha \in I}$ be a net in V^X satisfying the following conditions:

- (1) There exists $g \in l^1(X, \mathbb{R})$ satisfying $g \geq 0$ (i.e. $g(x) \geq 0$ for all $x \in X$) such that for every $\alpha \in I$, $x \in X$ we have

$$\|f_\alpha(x)\| \leq g(x)$$

We simply write the above condition as $|f_\alpha| \leq g$.

- (2) $(f_\alpha)_{\alpha \in I}$ converges pointwise some $f \in V^X$. Namely, $\lim_\alpha f_\alpha(x) = f(x)$ for every $x \in X$.

Prove that $f \in l^1(X, V)$. Prove that the LHS of (5.38) exists and equals the RHS:

$$\lim_{\alpha \in I} \sum_{x \in X} f_\alpha(x) = \sum_{x \in X} f(x) \quad (5.38)$$

★ **Problem 5.10.** Assume $v_n \in V$ for each n . Let z be a complex variable. Then the expression

$$f(z) = \sum_{n=-\infty}^{+\infty} v_n z^n$$

is called a **Laurent series** in V .

Prove that there exist unique $r, R \in \overline{\mathbb{R}}_{\geq 0}$ such that $f(z)$ converges absolutely when $|r| < |z| < |R|$, and that $f(z)$ diverges when $|z| < r$ or $|z| > R$. Prove that

$$r = \limsup_{n \rightarrow +\infty} \sqrt[n]{\|v_{-n}\|} \quad R = \frac{1}{\limsup_{n \rightarrow +\infty} \sqrt[n]{\|v_n\|}} \quad (5.39)$$

(Recall that by Exe. 5.54, $f(z)$ diverges iff either $\sum_{n=0}^{\infty} v_n z^n$ or $\sum_{n=-\infty}^{-1} v_n z^n$ diverges.) We call r and R the **radii of convergence** of $f(z)$. \square

★ **Exercise 5.66.** Consider Laurent series $f(z) = \sum_{n=-\infty}^{+\infty} a_n z^n$ (with radii of convergence $r_1 < R_1$) and $g(z) = \sum_{n=-\infty}^{+\infty} b_n z^n$ (with radii of convergence $r_2 < R_2$) in \mathbb{C} . Let

$$r = \max\{r_1, r_2\} \quad R = \min\{R_1, R_2\}$$

Assume that $r < R$. Prove that for each $k \in \mathbb{Z}$, the series

$$c_k = \sum_{l=-\infty}^{+\infty} a_{k-l} b_l$$

converges absolutely. Prove that for each $z \in \mathbb{C}$ satisfying $r < |z| < R$, the LHS of the following equation converges absolutely to the RHS:

$$\sum_{k=-\infty}^{+\infty} c_k z^k = f(z)g(z) \quad (5.40)$$

6 ★ Construction of \mathbb{R} from \mathbb{Q}

The goal of this chapter is to construct real numbers from rationals. More precisely, our goal is to prove Thm. 1.34. We use the method of Cantor to construct real numbers using equivalence classes of Cauchy sequences in \mathbb{Q} . The idea is quite simple: If we admit the existence of \mathbb{R} satisfying Thm. 1.34, then by Prop. 1.29, each $x \in \mathbb{R}$ is the limit of a sequence (x_n) in \mathbb{Q} , which must be a Cauchy sequence. Moreover, if (y_n) is a sequence in \mathbb{Q} converging to $y \in \mathbb{R}$, then by Exe. 5.37 we have $x = y$ iff (x_n) and (y_n) are Cauchy equivalent. Motivated by this, we now do not assume the existence of \mathbb{R} , and make the following definition:

Definition 6.1. We let \mathcal{R} be the set of Cauchy sequences in \mathbb{Q} ,⁹ namely, the set of $(x_n)_{n \in \mathbb{Z}_+} \in \mathbb{Q}^{\mathbb{Z}_+}$ satisfying

$$\lim_{m,n \rightarrow +\infty} (x_m - x_n) = 0$$

We say that two elements $(x_n), (y_n)$ of \mathcal{R} are Cauchy-equivalent and write $(x_n) \sim (y_n)$ if $\lim_{n \rightarrow \infty} (x_n - y_n) = 0$.

Note that the above definition does not rely on the existence of \mathbb{R} , because the limit of nets in \mathbb{Q} can be defined using only rational numbers: a net $(\xi_\alpha)_{\alpha \in I}$ converges to ξ iff for every $\varepsilon \in \mathbb{Q}_{>0}$, ξ_α is eventually satisfies $|\xi_\alpha - \xi| < \varepsilon$. The readers can check that all the properties about limit used in this chapter does not rely on the existence of \mathbb{R} .

Cauchy-equivalence is clearly an equivalence condition on \mathcal{R} : For example, if $\lim(x_n - y_n) = \lim(y_n - z_n) = 0$ then $|x_n - z_n| \leq |x_n - y_n| + |y_n - z_n| \rightarrow 0$. So $|x_n - z_n| \rightarrow 0$. This proves the transitivity. The other two conditions are obvious. Therefore, we can define:

Definition 6.2. We let $\mathbb{R} = \mathcal{R} / \sim$ where \sim is the Cauchy-equivalence relation. (Recall Def. 1.18). The equivalence class of $(x_n)_{n \in \mathbb{Z}_+}$ is denoted by $[x_n]_{n \in \mathbb{Z}_+} = [x_1, x_2, \dots]$, simply written as $[x_n]$. The zero element 0 of \mathbb{R} is defined to be $[0, 0, \dots]$.

Exercise 6.3. Choose $[x_n] \in \mathbb{R}$ (i.e. $(x_n) \in \mathcal{R}$). The following are equivalent:

- (1) $[x_n] \neq 0$. Namely, $\lim_n x_n$ does not converge to 0.
- (2) There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that either $x_n > \varepsilon$ eventually, or $x_n < -\varepsilon$ eventually. In particular, $x_n \neq 0$ eventually.

Consequently, the map $a \in \mathbb{Q} \mapsto [a, a, \dots] \in \mathbb{R}$ is injective. With the help of this injective map, \mathbb{Q} can be viewed as a subset of \mathbb{R} .

⁹Only in this chapter do we use \mathcal{R} for this meaning.

Exercise 6.4. Let $[x_n] \in \mathbb{R}$ and $a \in \mathbb{Q}$. Suppose that $x_n \geq a$ (resp. $x_n \leq a$) frequently. Then for every $\varepsilon \in \mathbb{Q}_{>0}$, we have that $x_n \geq a - \varepsilon$ (resp. $x_n \leq a + \varepsilon$) eventually.

Definition 6.5. If $\xi, \eta \in \mathbb{R}$, write $\xi = [x_n]$ and $\eta = [y_n]$. In the case that $\eta \neq 0$, we assume $y_n \neq 0$ for all n , which is possible by Exe. 6.3. Define

$$\begin{aligned} [x_n] + [y_n] &= [x_n + y_n] \\ -[x_n] &= [-x_n] \\ [x_n] \cdot [y_n] &= [x_n y_n] \\ 1/[y_n] &= [1/y_n] \quad (\text{if } [y_n] \neq 0) \end{aligned}$$

Exercise 6.6. Prove that the above formulas are well-defined: For example, if $(x_n) \sim (x'_n)$ in \mathcal{R} , then $(x_n y_n) \sim (x'_n y_n)$. (You may need the easy fact that every Cauchy sequence is bounded.)

Remark 6.7. It is clear that Def. 6.5 makes \mathbb{R} a **field**, which means that for every $\alpha, \beta, \gamma \in \mathbb{R}$, the following are satisfied:

$$\begin{aligned} \alpha + \beta &= \beta + \alpha & (\alpha + \beta) + \gamma &= \alpha + (\beta + \gamma) & 0 + \alpha &= \alpha & \alpha + (-\alpha) &= 0 \\ \alpha\beta &= \beta\alpha & (\alpha\beta)\gamma &= \alpha(\beta\gamma) & 1 \cdot \alpha &= \alpha & (\alpha + \beta)\gamma &= \alpha\gamma + \beta\gamma \\ \alpha \cdot \frac{1}{\alpha} &= 1 & & & & & & (\text{if } \alpha \neq 0) \end{aligned}$$

Moreover, \mathbb{Q} is a subfield of \mathbb{R} where the addition, taking negative, multiplication, and inverse of \mathbb{R} restrict to those of \mathbb{Q} .

Definition 6.8. Let $[x_n], [y_n] \in \mathbb{R}$. We write $[x_n] < [y_n]$ if one of the following equivalent (due to Exe. 6.4) statements hold:

- There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that $y_n - x_n > \varepsilon$ eventually.
- There exists $\varepsilon \in \mathbb{Q}_{>0}$ such that $y_n - x_n > \varepsilon$ frequently.

It is not hard show that “ $<$ ” is well-defined, and that (by Exe. 6.3) if $[x_n] < [y_n]$ then $[x_n] \neq [y_n]$. We write $[x_n] \leq [y_n]$ if $[x_n] < [y_n]$ or $x_n = y_n$.

Lemma 6.9. (\mathbb{R}, \leq) is a totally ordered set.

Proof. Choose $[x_n], [y_n], [z_n] \in \mathbb{R}$. If $[x_n] < [y_n]$ and $[y_n] < [z_n]$, then clearly $[x_n] < [z_n]$. This proves that \leq is a preorder.

Suppose $[x_n] \leq [y_n]$ and $[y_n] \leq [x_n]$. Let us prove $[x_n] = [y_n]$. Suppose not. Then $[x_n] < [y_n]$ and $[y_n] < [x_n]$ by the definition of “ \leq ”. So there is $\varepsilon > 0$ such that $y_n - x_n > \varepsilon$ eventually, and $x_n - y_n > \varepsilon$ eventually. Impossible. So \leq is a partial order.

Suppose $[x_n] \neq [y_n]$. Then $(x_n - y_n) \not\sim 0$. So Exe. 6.3 implies that either $[x_n] < [y_n]$ or $[y_n] < [x_n]$. So \leq is a total order. \square

Lemma 6.10. Let $[x_n], [y_n] \in \mathbb{R}$. Then the following are equivalent.

- $[x_n] \geq [y_n]$.
- For every $\varepsilon \in \mathbb{Q}_{>0}$, $x_n - y_n \geq -\varepsilon$ frequently.
- For every $\varepsilon \in \mathbb{Q}_{>0}$, $x_n - y_n \geq -\varepsilon$ eventually.

Proof. Since \leq is a total order, the negation of $>$ is \leq . So the statements follow immediately by negating Def. 6.8. \square

Lemma 6.11. \mathbb{R} is an ordered field extension of \mathbb{Q} , and \mathbb{R} is Archimedean.

Proof. The order of \mathbb{R} clearly restricts to that of \mathbb{Q} . We want to prove that \mathbb{R} is an ordered field. (Recall Def. 1.23). Clearly, if $[x_n] < [y_n]$ and $[z_n] \in \mathbb{R}$, then $[x_n] + [z_n] = [x_n + z_n] < [y_n + z_n] = [y_n] + [z_n]$. If $[x_n] > 0$ and $[y_n] > 0$, then there are $\varepsilon > 0$ such that $x_n > \varepsilon$ eventually and $y_n > \varepsilon$ eventually. So $x_n y_n > \varepsilon^2$ eventually. So $[x_n][y_n] > 0$. This proves that \mathbb{R} is an ordered field.

Now let $[x_n] > 0$ and $[y_n] \in \mathbb{R}$. So there exist $\varepsilon \in \mathbb{Q}_{>0}$ such that $x_n > \varepsilon$ eventually. Since (y_n) is Cauchy, one checks easily that (y_n) is bounded. So there is $M \in \mathbb{Q}_{>0}$ such that $|y_n| \leq M$ for all n . Since \mathbb{Q} is Archimedean, there exists $k \in \mathbb{Z}_+$ such that $k\varepsilon > M + 1$. So $kx_n > M + 1$ eventually. So $k[x_n] > M$. This proves that \mathbb{R} is Archimedean. \square

To finish the proof of Thm. 1.34, it remains to prove that \mathbb{R} satisfies the least-upper-bound property.

Lemma 6.12. Thm. 1.34 holds if every bounded increasing sequence in \mathbb{R} converges.

Proof. Suppose that every bounded increasing sequence in \mathbb{R} converges. Choose any nonempty $E \subset \mathbb{R}$ bounded from above. We shall show that E has a least upper bound.

Let F be the set of upper bounds of E . Namely, $F = \{\eta \in \mathbb{R} : \eta \geq \xi, \forall \xi \in E\}$. So $F \neq \emptyset$. We construct an increasing sequence (ξ_k) in E and an decreasing sequence (η_k) in F as follows. Since E, F are nonempty, we choose arbitrary $\xi_1 \in E$ and $\eta_1 \in F$. Then $\xi_1 \leq \eta_1$. Suppose $\xi_1 \leq \dots \leq \xi_k \in E$ and $\eta_1 \geq \dots \geq \eta_k \in F$ have been constructed. Let $\psi_k = (\xi_k + \eta_k)/2$. Let

$$\begin{cases} \xi_{k+1} = \psi_k, \eta_{k+1} = \eta_k & \text{if } \psi_k \in E \\ \xi_{k+1} = \xi_k, \eta_{k+1} = \psi_k & \text{if } \psi_k \in F \end{cases}$$

Then the sequences we have constructed satisfy $\lim_{k \rightarrow \infty} (\eta_k - \psi_k) = 0$.

By assumption, $\alpha = \lim_{k \rightarrow \infty} \xi_k$ exists, and it equals $\lim_k \eta_k$. So α is an upper bound of E . (If $\lambda \in E$, then $\lambda \leq \eta_k$ for all k since $\eta_k \in F$. So $\lambda \leq \lim_k \eta_k = \alpha$.) We now show that α is the least upper bound. Let $\varepsilon > 0$. Since $\xi_k \rightarrow \alpha$, there is k such that $\alpha - \xi_k < \varepsilon$. So $\xi_k > \alpha - \varepsilon$, and hence $\alpha - \varepsilon$ is not an upper bound of E . \square

Lemma 6.13. *Thm. 1.34 holds if every bounded increasing sequence in \mathbb{Q} converges to an element of \mathbb{R} .*

Proof. Suppose that every increasing sequence in \mathbb{Q} converges in \mathbb{R} . By Lem. 6.12, it suffices to prove that every increasing sequence (ξ_k) in \mathbb{R} converges. If $\{\xi_k : k \in \mathbb{Z}_+\}$ is a finite subset of \mathbb{R} , then (ξ_k) clearly converges. If $\{\xi_k : k \in \mathbb{Z}_+\}$ is infinite, then (ξ_k) clearly has a strictly increasing subsequence (ξ_{k_l}) . If we can prove that (ξ_{k_l}) converges to some $\psi \in \mathbb{R}$, then (ξ_k) converges to ψ . (Choose any $\varepsilon > 0$. Choose $L \in \mathbb{Z}_+$ such that $|\psi - \xi_{k_L}| < \varepsilon$ and hence $0 \leq \psi - \xi_{k_L} < \varepsilon$. Then for all $k \geq k_L$ we have $0 \leq \psi - \xi_k < \varepsilon$.)

Thus, it remains to prove that every strictly increasing sequence (η_k) in \mathbb{R} converges. Since we have proved that \mathbb{R} is an Archimedean ordered field extension of \mathbb{Q} , by Prop. 1.29, for each k , there exists $a_k \in \mathbb{Q}$ such that $\xi_k < a_k < \xi_{k+1}$. By assumption, (a_k) converges to some $\alpha \in \mathbb{R}$. Since $a_{k-1} < \xi_k < a_k$, by squeeze theorem, (ξ_k) converges to α . \square

Proof of Thm. 1.34. By Lem. 6.13, it suffices to show that every bounded increasing sequence (a_k) in \mathbb{Q} converges in \mathbb{R} . Let $M \in \mathbb{Q}$ such that $a_k \leq M$ for all k .

We first prove that (a_k) is a Cauchy sequence. If not, then there exists $\varepsilon \in \mathbb{Q}_{>0}$ such that for every $K \in \mathbb{Z}_+$ there is $k > K$ such that $|a_k - a_K| > \varepsilon$, and hence $a_k - a_K > \varepsilon$. Thus, we can find a subsequence (a_{k_l}) such that $a_{k_{l+1}} - a_{k_l} > \varepsilon$. By the Archimedean property for \mathbb{Q} , there is $l \in \mathbb{Z}_+$ such that $a_{k_1} + l \cdot \varepsilon > M$. So $a_{k_{l+1}} > M$, impossible.

Note that each a_k is identified with $\xi_k = [a_k, a_k, \dots]$. Let $\psi = [a_1, a_2, a_3, \dots]$, which is an element of \mathbb{R} since we just proved that $(a_n) \in \mathcal{R}$. Then for each k , $\psi - \xi_k = [a_1 - a_k, a_2 - a_k, \dots]$, where the terms are eventually ≥ 0 . So $\xi_k \leq \psi$ by Lem. 6.10. We have proved that ψ is an upper bound for the sequence (ξ_k) .

Let us prove that $\lim_k \xi_k = \psi$. Choose any $\varepsilon \in \mathbb{Q}_{>0}$. Let us prove that there exists k such that $\psi - \varepsilon < \xi_k$. Then for every $k' \geq k$ we have $\psi - \varepsilon < \xi_{k'} \leq \psi$, finishing the proof of $\lim_k \xi_k = \psi$.

We have proved that a_1, a_2, \dots is a Cauchy sequence in \mathbb{Q} . So there exists k such that $a_l - a_k < \varepsilon/2$ for all $l \geq k$. Thus, for all $l \geq k$ we have $a_k - (a_l - \varepsilon) > \varepsilon/2$. Thus, the l -th term of $\xi_k = [a_k, a_k, \dots]$ minus that of $\psi - \varepsilon = [a_1 - \varepsilon, a_2 - \varepsilon, \dots]$ is $> \varepsilon/2$ for sufficiently large l . By Def. 6.8, we have that $\psi - \varepsilon < \xi_k$. \square

7 Topological spaces

7.1 The topologies of metric spaces

In this chapter, we begin our study of topological spaces, which were introduced by Hausdorff in 1914 [Hau14] as a generalization of metric spaces. As we have seen, focusing on metrics in order to study convergence and continuity is often distracting. For example, in \mathbb{R} , we only care about how the convergence of sequences look like, but not about the particular metrics. The same is true about the countable product of metric spaces $S = \prod_{i \in \mathbb{Z}_+} X_i$: the metrics (2.14) and (2.15) give the same topology, although they look very different. Moreover, the shapes of the open balls defined by these two metrics are not very simple. This makes it more difficult to study the continuity of functions on S by using (2) or (2') of Def. 2.38.

Topological spaces generalize metric spaces by giving a set of axioms satisfied by the open sets of the spaces.

Definition 7.1. Let X be a metric space, and let $E \subset X$. A point $x \in E$ is called an **interior point** of E if $B_X(x, r) \subset E$ for some $r > 0$. We say that E is an **open (sub)set** of X , if every point of E is an interior point.

Definition 7.2. Let \mathcal{T} be the set of open sets of X . We call \mathcal{T} the **topology of the metric space** X .

Example 7.3. By triangle inequality, every open ball of a metric space X is open. \emptyset and X are open subsets of X . If $p, q \in \mathbb{R}^N$ and $d(p, x) = r$ (where $0 \leq r < +\infty$), then p is not an interior point of $\overline{B}_{\mathbb{R}^N}(x, r)$. So the closed balls of \mathbb{R}^N are not open sets. In particular, $[a, b]$ are not open subsets of \mathbb{R} since a, b are not interior points.

Example 7.4. It is not hard to see that a finite intersection of open sets is open.

In topological spaces, open sets play the role of open balls in metric spaces due to the following facts:

Exercise 7.5. Let (x_n) be a sequence in a metric space X . Let $x \in X$. Show that the following are equivalent:

- (1) (x_n) converges to x .
- (2) For every **neighborhood** U of x (i.e. every open set containing x) there is $N \in \mathbb{Z}_+$ such that for every $n \geq N$ we have $x_n \in U$.

Exercise 7.6. Let $f : X \rightarrow Y$ be a map of metric spaces. Let $x \in X$ and $y = f(x)$. Prove that the following are equivalent.

- (1) f is continuous at x .

- (2) For every neighborhood V of y there is a neighborhood U of x such that $f(U) \subset V$ (equivalently, $U \subset f^{-1}(V)$.)

But there is an important difference between the intuitions of open sets and open balls: We want the open balls at a point x to be small so that they can be used to describe the approximation to x . However, an arbitrary open set can be very large. For example, when studying convergence and continuity in \mathbb{R} , we really want a neighborhood of 1 to be $(1 - \varepsilon, 1 + \varepsilon)$ but not the more complicated and bigger one $(-\infty, -2) \cup (0, 100 - \varepsilon)$. Indeed, open sets can be very big:

Lemma 7.7. *Let X be a metric space. If $(U_\alpha)_{\alpha \in I}$ is a family of open subsets of X , then $W = \bigcup_{\alpha \in I} U_\alpha$ is open in X .*

Proof. Choose $x \in W$. Then $x \in U_\alpha$ for some α . So $B_X(x, r) \subset U_\alpha$ for some $r > 0$. So x is an interior point of W . \square

Thus, people very often choose a class \mathcal{B} of smaller open sets (such as the set of open balls) to study the analytic properties of a topological space.

Definition 7.8. Let \mathcal{B} be a set of open sets of a metric space (or more generally, a topological space) X . We say that \mathcal{B} is a **basis for the topology** \mathcal{T} of X if one of the following (clearly) equivalent statements holds:

- For every point $x \in X$ and every neighborhood W of x there exists $U \in \mathcal{B}$ such that $x \in U$ and $U \subset W$.
- Every open subset of X is a union of some members of \mathcal{B} .

Thus, according to Def. 7.1, the set of open balls of a metric space X form a basis for the topology of X . Nevertheless, even in the case of metric spaces, we sometimes consider more convenient bases than the set of open balls. We will see this when we study the topologies of infinite product spaces.

7.2 Topological spaces

7.2.1 Definitions and basic examples

Definition 7.9. We say that a pair (X, \mathcal{T}) (or simply X) is a **topological space** if X is a set, and if \mathcal{T} (called the **topology** of X) is a set of subsets of X satisfying the following conditions

- $\emptyset \in \mathcal{T}$ and $X \in \mathcal{T}$.
- (Union property) If $(U_\alpha)_{\alpha \in I}$ is a family of elements of \mathcal{T} , then $\bigcup_{\alpha \in I} U_\alpha$ is an element of \mathcal{T} .

- (Finite intersection property) If $n \in \mathbb{Z}_+$ and $U_1, \dots, U_n \in \mathcal{T}$, then $U_1 \cap \dots \cap U_n$ is an element of \mathcal{T} .

Elements of \mathcal{T} are called **open (sub)sets** of X .

Definition 7.10. Let X be a topological space, and $x \in X$. A subset $U \subset X$ is called a **neighborhood** of x , if U is an open subset of X containing x .¹⁰ We define $(\text{Nbh}_X(x), \leq)$, the **directed set of neighborhoods of x** , to be

$$\begin{aligned} \text{Nbh}_X(x) &= \{\text{neighborhoods of } x \text{ in } X\} \\ U &\leq U' \iff U \supset U' \end{aligned} \tag{7.1}$$

(Note that one needs the finite intersection property to show that $\text{Nbh}_X(x)$ is a directed set.) We abbreviate this set to $\text{Nbh}_X(x)$ or simply $\text{Nbh}(x)$.

Example 7.11. In Subsec. 7.1, we have proved that the topology of a metric space satisfies the above axioms of a topological space.

In particular, if X is a normed vector space, the topology induced by the metric $d(x, x') = \|x - x'\|$ is called the **norm topology**. If X is a subset of \mathbb{R}^N or \mathbb{C}^N , the topology on X induced by the Euclidean metric is called the **Euclidean topology**. \square

Definition 7.12. A topological space (X, \mathcal{T}) is called **metrizable**, if there is a metric on X inducing the topology \mathcal{T} .

We have seen that the open balls of a metric space generate a topology. In general, one may ask what possible subsets of 2^X generate a topology on a set X . Here is a description, whose proof is left to the readers as an exercise.

Proposition 7.13. Let X be a set, and let $\mathcal{B} \subset 2^X$. Define

$$\mathcal{T} = \{\text{Unions of elements of } \mathcal{B}\} \tag{7.2}$$

The following are equivalent.

(1) (X, \mathcal{T}) is a topological space.

(2) The following are satisfied:

(2-a) $X = \bigcup_{U \in \mathcal{B}} U$.

(2-b) If $U_1, U_2 \in \mathcal{B}$, then $U_1 \cap U_2 \in \mathcal{T}$ (i.e., for each $x \in U_1 \cap U_2$ there exists $V \in \mathcal{B}$ such that $x \in V$ and $V \subset U_1 \cap U_2$).

¹⁰We are following the convention in [Mun, Rud-R]. But many people refer to the word "neighborhood" with slightly different meaning: a subset A is called a neighborhood of x if there is an open set U such that $x \in U \subset A$. And our neighborhoods are called "open neighborhoods" by them.

When (1) or (2) holds, we call \mathcal{T} the **topology generated by \mathcal{B}** . Clearly, \mathcal{B} is a basis for \mathcal{T} (cf. Def. 7.8).

Exercise 7.14. Let X be a set. Let $\mathcal{B}, \mathcal{B}'$ be subsets of 2^X generating topologies $\mathcal{T}, \mathcal{T}'$ respectively. Prove that the following are equivalent.

- (1) $\mathcal{T} = \mathcal{T}'$.
- (2) Each $U \in \mathcal{B}$ is a union of elements of \mathcal{B}' . Each $U' \in \mathcal{B}'$ is a union of elements of \mathcal{B} .
- (3) For each $U \in \mathcal{B}$ and $x \in U$, there exists $U' \in \mathcal{B}'$ such that $x \in U' \subset U$. For each $U' \in \mathcal{B}'$ and $x \in U'$, there exists $U \in \mathcal{B}$ such that $x \in U \subset U'$.

Example 7.15. If (X, \mathcal{T}) is a topological space, then \mathcal{T} is a basis for \mathcal{T} .

Example 7.16. Let (X, d) be a metric space with topology \mathcal{T} . Let $\mathcal{B} = \{B_X(x, r) : x \in X, 0 < r < +\infty\}$. Then \mathcal{B} is a basis for \mathcal{T} . For each $\varepsilon > 0$, the set $\mathcal{B}' = \{B_X(x, r) : x \in X, 0 < r < \varepsilon\}$ is also a basis for \mathcal{T} .

Example 7.17. Let $\mathcal{B} \subset 2^{\overline{\mathbb{R}}}$ be defined by

$$\mathcal{B} = \{(a, b), (c, +\infty], [-\infty, d) : a, b, c, d \in \mathbb{R}\} \quad (7.3)$$

Using Prop. 7.13, one easily checks that \mathcal{B} is a basis for a topology \mathcal{T} . We call this the **standard topology** of $\overline{\mathbb{R}}$.

Let $\varphi : \overline{\mathbb{R}} \rightarrow [u, v]$ be a strictly increasing bijection where $-\infty < u < v < +\infty$. Let $d_{[u, v]}$ be the Euclidean metric, and let \mathcal{T}' be the topology on $\overline{\mathbb{R}}$ defined by $d_{\overline{\mathbb{R}}} = \varphi^* d_{[u, v]}$. Then the set of open balls under \mathcal{T}' is

$$\mathcal{B}' = \{(\varphi^{-1}(y - \varepsilon), \varphi^{-1}(y + \varepsilon)), (\varphi^{-1}(v - \varepsilon'), +\infty], [-\infty, \varphi^{-1}(u + \varepsilon'')) : y \in (u, v) \text{ and } \varepsilon, \varepsilon', \varepsilon'' \in \mathbb{R}_{>0}\}$$

(Note that the three types of intervals in the definition of \mathcal{B}' are open balls centered at $\varphi^{-1}(y)$, $+\infty$, $-\infty$ respectively.) Using Exe. 7.14, one easily checks $\mathcal{T} = \mathcal{T}'$. \square

Convention 7.18. Unless otherwise stated, the topology on $\overline{\mathbb{R}}$ is defined to be the standard one, i.e., the one generated by (7.3). We shall forget about the metric on $\overline{\mathbb{R}}$, and view $\overline{\mathbb{R}}$ only as a (metrizable) topological space.

Definition 7.19. Let A be a subset of a topological space (X, \mathcal{T}_X) . Then

$$\mathcal{T}_A = \{U \cap A : U \in \mathcal{T}_X\}$$

is clearly a topology on A , called the **subspace topology**. Unless otherwise stated, when viewing a subset as a topological subspace, we always choose the subspace topology for the subset.

Exercise 7.20. Let (X, d_X) be a metric space, inducing a topology \mathcal{T}_X . Let A be a metric subspace of X . (So $A \subset X$, and d_X restricts to d_A .) Prove that the topology on A induced by d_A is the subspace topology.

According to the above exercise, if X is a metric space, then viewing a subset A as a topological subspace is compatible with viewing A as a metric subspace.

Exercise 7.21. Let A be a subset of a topological space X . Let \mathcal{B} be a basis for the topology of X . Show that $\{U \cap A : U \in \mathcal{B}\}$ is a basis for the subspace topology of A .

7.2.2 Convergence of nets

Definition 7.22. Let $(x_\alpha)_{\alpha \in I}$ be a net in a topological space X . Let $x \in X$. We say that (x_α) **converges to** x and write

$$\lim_{\alpha \in I} x_\alpha \equiv \lim_{\alpha} x_\alpha = x$$

or simply write $x_\alpha \rightarrow x$, if the following statement holds:

- For every $U \in \text{Nbh}_X(x)$, we have that x_α is eventually in U .

Clearly, if \mathcal{B} is a basis for the topology, then $x_\alpha \rightarrow x$ iff:

- For every $U \in \mathcal{B}$ containing x , we have that x_α is eventually in U .

In the case that X is a metric space (and the topology of X is induced by the metric), the definition here agrees with Def. 5.11.

Exercise 7.23. Let (x_α) be a net in X converging to $x \in X$. Prove that every subnet of (x_α) converges to x .

Exercise 7.24. Let A be a subset of a topological space X , equipped with the subspace topology. Let (x_α) be a net in A , and let $x \in A$. Show that $x_\alpha \rightarrow x$ in A iff $x_\alpha \rightarrow x$ in X .

Example 7.25. Let X be a set. Let $\mathcal{T} = \{\emptyset, X\}$. Then every net in X converges to every point of X . Thus, if X has at least two elements, then the limit of a net in X is not unique. Therefore, a general topological space might be very pathological. To avoid this uniqueness issue, we introduce the following notion:

Definition 7.26. Let X be a topological space with a basis for the topology \mathcal{B} . We say that X is a **Hausdorff space** if the following equivalent conditions are satisfied:

- (1) (Hausdorff condition) If $x, y \in X$ and $x \neq y$, then there exist neighborhoods U of x and V of y such that $U \cap V = \emptyset$.

- (1') If $x, y \in X$ and $x \neq y$, then there exist $U \in \mathcal{B}$ containing x and $V \in \mathcal{B}$ containing y such that $U \cap V = \emptyset$.
- (2) If $(x_\alpha)_{\alpha \in I}$ is a net in X converging to both x and y , then $x = y$.

Proof of the equivalence. (1) \Leftrightarrow (1'): Obvious.

(1) \Rightarrow (2): Suppose that (x_α) converges to x and y . Suppose $x \neq y$. By (1), we have disjoint neighborhoods $U \ni x$ and $V \ni y$. Since $x_\alpha \rightarrow x$, x_α is eventually in U . Similarly, x_α is eventually in V . Therefore, by the logic (5.6b), x_α is eventually in $U \cap V = \emptyset$, impossible.

$\neg(1) \Rightarrow \neg(2)$: Suppose that (1) is not true. Then there exist $x \neq y$ such that every neighborhood of x intersects every neighborhood of y . Let $I = \text{Nbh}_X(x) \times \text{Nbh}_X(y)$. For each $\alpha = (U, V) \in I$, by assumption, there exists $x_\alpha \in U \cap V$. Then $(x_\alpha)_{\alpha \in I}$ is a net in X . We leave it to the readers to check that $x_\alpha \rightarrow x$ and $x_\alpha \rightarrow y$. \square

Remark 7.27. In Hausdorff's 1914 paper introducing topological spaces, the Hausdorff condition is one of the axioms of topological spaces. Non-Hausdorff topological spaces were studied much later. The reason that Hausdorff spaces appeared first may be as follows: The original motivation for topological spaces lies in the study of analysis (especially functional analysis). But in analysis, most spaces are Hausdorff, because we want the limits of sequences or nets to be unique.

In differential geometry and in topology¹¹, people are also mainly concerned with topological spaces that are Hausdorff. This is related to the fact that in these areas people often use tools from analysis. But in algebraic geometry, the main examples of topological spaces (e.g. varieties and schemes, whose topologies are called **Zariski topology**) are not Hausdorff. As a related fact, sequences and nets are not effective tools in the study of algebraic geometry. \square

7.3 Closures, interiors, and closed sets

In this section, we fix a topological space X .

7.3.1 Closure points; dense subsets

Definition 7.28. Let A be a subset of X . We say that $x \in X$ is a **closure point** of A , if the following equivalent conditions hold:

- (1) There is a net $(x_\alpha)_{\alpha \in I}$ in A converging to x .
- (2) Each $U \in \text{Nbh}_X(x)$ intersects A .

¹¹Here, I mean genuine topology, such as algebraic topology, differential topology, geometric topology, etc., but not point-set topology, which is analysis under the guise of topology.

The **closure** of A is defined to be

$$\overline{A} \equiv \text{Cl}(A) \equiv \text{Cl}_X(A) = \{\text{closure points of } A\}$$

Clearly $A \subset \overline{A}$. Clearly, if $A \subset B \subset X$, then $\overline{A} \subset \overline{B}$.

Unless otherwise stated, if several subsets are involved, we always understand \overline{A} as $\text{Cl}_X(A)$ where X is the ambient topological space.

Proof of equivalence. (1) \Rightarrow (2): Assume (1). Choose any $U \in \text{Nbh}_X(x)$. Since $x_\alpha \rightarrow x$, we have that x_α is eventually in U . So U must contain some x_α . But $x_\alpha \in A$. So $U \cap A \neq \emptyset$.

(2) \Rightarrow (1): By (2), for each $U \in \text{Nbh}_X(x)$ we can choose $x_U \in U \cap A$. Then $(x_U)_{U \in \text{Nbh}_X(x)}$ is a net in A converging to x . \square

Exercise 7.29. Let \mathcal{B} be a basis for the topology of X . Show that $x \in X$ is a closure point of A iff every $U \in \mathcal{B}$ containing x must intersect A .

Exercise 7.30. Let A be a subset of a metric space. Show that $x \in X$ is a closure point of A iff there is a sequence $(x_n)_{n \in \mathbb{Z}_+}$ in A converging to x .

Remark 7.31. Our proof of (2) \Rightarrow (1) in Def. 7.28 is an indirect proof, because it uses axiom of choice. (Given $U \in \text{Nbh}_X(x)$, the choice of $x_U \in U \cap A$ is highly arbitrary.) Here is a direct proof: Assume (2). Define a direct set (I, \leq) where

$$\begin{aligned} I &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U \cap A\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned}$$

The fact that I is a directed set is due to (2). Then $(p)_{(p,U) \in I}$ is a net in A converging to x .

We will often prove results about nets in topological spaces using axiom of choice, not only because it is simpler than direct proofs (as above), but also because it is parallel to our use of sequences in metric spaces. (For example, see the proof of (1) \Rightarrow (2) in Def. 2.38.) However, it is important to know how to give a direct proof. This is because the studies of topological spaces using nets and using open sets are often equivalent, and direct proofs using nets can be more easily translated into proofs using open sets and vice versa. \square

Exercise 7.32. Prove $\neg(1) \Rightarrow \neg(2)$ of Def. 7.26 without using axiom of choice.

Remark 7.33. There is a notion closely related to closure points, called accumulation points. Let A be a subset of X . A point $x \in X$ is called a **accumulation point** (or **limit point** or **cluster point**) of A , if x is a closure point of $A \setminus \{x\}$.

We will not use the notion of accumulation points, although this concept is widely used in many textbooks on analysis or point-set topology. We use closure points instead. (But note that if $x \notin A$, then x is a closure point iff x is an accumulation point.) On the other hand, the following opposite notion of accumulation points is important and has a clear geometric picture: \square

Definition 7.34. We say that $x \in X$ is an **isolated point** of X , if the following (clearly) equivalent conditions hold:

- (1) $x \notin \overline{X \setminus \{x\}}$.
- (2) There is no net in $X \setminus \{x\}$ converging to x .
- (3) There is a neighborhood of x disjoint from $X \setminus \{x\}$.

If X is a metric space, then x is an isolated point iff there is no sequence in $X \setminus \{x\}$ converging to x .

We return to the study of closures.

Proposition 7.35. Let A be a subset of X . Then $\overline{\overline{A}} = \overline{A}$.

Proof. Choose any $x \in \overline{\overline{A}}$. To prove $x \in \overline{A}$, we choose any $U \in \text{Nbh}_X(x)$, and try to prove $U \cap A \neq \emptyset$. Since x is a closure point of \overline{A} , U intersects \overline{A} . Pick $y \in U \cap \overline{A}$. Then y is a closure point of A , and $U \in \text{Nbh}_X(y)$. So U intersects A . \square

One should think of $\overline{\overline{A}} = \overline{A}$ not only as a “geometric” fact about closures. Instead, one should also understand its analytic content: A closure point of A is a point which can be approximated by elements of A . Thus, $\overline{\overline{A}} = \overline{A}$ says that “approximation is transitive”: If x can be approximated by some elements which can be approximated by elements of A , then x can be approximated by elements of A . Alternatively, one can use the language of density:

Definition 7.36. A subset A of X is called **dense** (in X) if $\overline{A} = X$.

Exercise 7.37. Show that A is dense in X iff every nonempty open subset of X intersects A .

Remark 7.38. Let $A \subset B \subset X$. From Def. 7.28-(1), it is clear that

$$\text{Cl}_B(A) = \text{Cl}_X(A) \cap B \tag{7.4}$$

Thus, A is dense in B iff $B \subset \text{Cl}_X(A)$.

Thus, the following property has the same meaning as $\overline{\overline{A}} = A$.

Corollary 7.39. Let $A \subset B \subset X$. Assume that A is dense in B , and B is dense in X , then A is dense in X .

Proof. Choose any $x \in X$. Then $x \in \text{Cl}_X(B)$ since B is dense in X . Since A is dense in B , we have $B \subset \text{Cl}_X(A)$. Therefore $x \in \text{Cl}_X(\text{Cl}_X(A))$, and hence $x \in \text{Cl}_X(A)$ by Prop. 7.35. \square

Example 7.40. Let $X = C([0, 1], \mathbb{R})$, equipped with the l^∞ -norm. Let B be the set of polynomials with real coefficients, regarded as continuous functions on $[0, 1]$. By Weierstrass approximation theorem (which will be studied in the future), B is a dense subset of X . Then the set A of polynomials with rational coefficients is clearly a dense subset of B under the l^∞ -norm. (Proof: Let $f(x) = a_0 + a_1x + \cdots + a_kx^k$. For each $0 \leq i \leq k$, choose a sequence $(a_{i,n})_{n \in \mathbb{Z}_+}$ in \mathbb{Q} converging to a_i . Let $f_n(x) = a_{0,n} + a_{1,n}x + \cdots + a_{k,n}x^k$. Then $f_n \Rightarrow f$ on $[0, 1]$.) Therefore, A is dense in X . To summarize:

- Since each continuous function on $[0, 1]$ can be uniformly approximated by polynomials with \mathbb{R} -coefficients, and since each polynomial can be uniformly approximated polynomials with \mathbb{Q} -coefficients, therefore each continuous function on $[0, 1]$ can be uniformly approximated by polynomials with \mathbb{Q} -coefficients.

7.3.2 Interior points

Interior points are dual to closure points:

Definition 7.41. Let A be a subset of X . A point $x \in X$ is called an **interior point** of A if the following equivalent conditions hold:

- (1) There exists $U \in \text{Nbh}_X(x)$ such that $U \subset A$.
- (2) x is not a closure point of $X \setminus A$.

The set of interior points of A is called the **interior** of A and is denoted by $\text{Int}_X(A)$ or simply $\text{Int}(A)$. So

$$X \setminus \text{Int}(A) = \overline{X \setminus A} \quad (\text{or simply } \text{Int}(A)^c = \overline{A^c}) \quad (7.5)$$

according to (2). In particular, $\text{Int}(A) \subset A$.

Proof of equivalence. A contains no neighborhoods of x with respect to X iff A^c intersects every neighborhood of x iff x is a closure point of A^c . \square

It is clear that if \mathcal{B} is a basis for the topology, then $x \in \text{Int}(A)$ iff there exists $U \in \mathcal{B}$ such that $x \in U \subset A$.

In analysis, interior points are not as commonly used as closure points. The following property is an important situation where interior points are used:

Proposition 7.42. Let U be a subset of X . Then U is open iff every point of U is an interior point.

In other words, U is open iff $U = \text{Int}_X(U)$.

Proof. If U is open and $x \in U$, then $U \in \text{Nbh}_X(x)$. So x is an interior point of U .

Conversely, suppose that each $x \in U$ is interior. Choose $V_x \in \text{Nbh}_X(x)$. Then $U = \bigcup_{x \in U} V_x$. So U is open by the union property in Def. 7.9. \square

Note that this is the first time we seriously use the fact that a union of open sets is open.

7.3.3 Closed sets and open sets

Definition 7.43. We say that $A \subset X$ is a **closed (sub)set** of X if $\overline{A} = A$.

Exercise 7.44. Show that the above definition of closed subsets agrees with Def. 3.26 when X is a metric space.

Exercise 7.45. Show that a finite subset of a Hausdorff space is closed. Give an example of non-closed finite subset of a non-Hausdorff topological space.

Remark 7.46. The closure \overline{A} is the smallest closed set containing A . (Proof: By Prop. 7.35, \overline{A} is closed. If B is closed and contains A , then $\overline{A} \subset \overline{B} = B$.)

Theorem 7.47. Let A be a subset of X . Then A is closed iff $X \setminus A$ is open.

Proof. Let $B = X \setminus A$. Then A is closed iff every closure point of A is in A , iff every non-interior point of B is not in B , iff every point in B is an interior point of B . By Prop. 7.42, this is equivalent to that B is open. \square

Corollary 7.48. \emptyset and X are closed subsets of X . An intersection of closed subsets is closed. A finite union of closed subsets is closed.

Proof. Take the complement of Def. 7.9, and apply Thm. 7.47. (Of course, they can also be proved directly using the condition $A = \overline{A}$ for closedness.) \square

Corollary 7.49. X is Hausdorff iff for every distinct $x, y \in X$ there exists $U \in \text{Nbh}_X(x)$ such that $y \notin \overline{U}$.

Proof. “ \Leftarrow ”: Let $x \neq y$. Choose $U \in \text{Nbh}(x)$ such that $y \notin \overline{U}$. Then $X \setminus \overline{U} \in \text{Nbh}(y)$ by Thm. 7.47. So x and y are separated by neighborhoods $U, X \setminus \overline{U}$.

“ \Rightarrow ”: Let $x \neq y$. Choose disjoint $U \in \text{Nbh}(x)$ and $V \in \text{Nbh}(y)$. Then $X \setminus V$ is closed by Thm. 7.47. So $\overline{U} \subset X \setminus V$ by Rem. 7.46. So $y \notin \overline{U}$. \square

Corollary 7.50. Let Y be a subset of X , and let $A \subset Y$. Then the following are equivalent.

- (1) A is a closed subset of Y .
- (2) $A = B \cap Y$ for some closed subset B of X .

Note that the “open subset” version of this corollary is true due to the definition of the subspace topology of Y (cf. Def. 7.19).

First proof. A is closed in Y iff $Y \setminus A = Y \cap A^c$ is open in Y , iff $Y \cap A^c$ equals $Y \cap U$ for some open subset $U \subset X$, iff $Y \cap A$ (which is A) equals $Y \cap U^c$ for some open subset $U \subset X$. This finishes the proof, thanks to Thm. 7.47. \square

Second proof. Recall by (7.4) that $\overline{A} \cap Y$ is the closure of A in Y . Then A is closed in Y iff $A = \overline{A} \cap Y$. This proves (1) \Rightarrow (2) since \overline{A} is closed by Prop. 7.35. Assume (2). Then $A = B \cap Y$ where $B = \overline{B}$. So $\overline{A} \cap Y = \overline{B \cap Y} \cap Y \subset \overline{B} \cap Y = B \cap Y = A$. This proves (1). \square

As an immediate consequence of Def. 7.9 and Cor. 7.50, we have:

Exercise 7.51. Let $A \subset B \subset X$.

1. Prove that if B is open in X , then A is open in B iff A is open in X .
2. Prove that if B is closed in X , then A is closed in B iff A is closed in X .

Remark 7.52. Many people define a closed set to be the complement of an open set, and then proves that a set A is closed iff $A = \overline{A}$. I went the other way because I believe that $A = \overline{A}$ is more essential for understanding of closedness from the viewpoint of analysis. In Thm. 3.47, we have already seen a classical example of closed set in analysis: $C([0, 1], \mathbb{R})$ is a closed subset of $l^\infty([0, 1], \mathbb{R})$, which has the clear analytic meaning that the uniform limit of a sequence/net of continuous functions $[0, 1] \rightarrow \mathbb{R}$ is continuous. And we will see many more examples of this type in the future.

Remark 7.53. I defined closedness using $A = \overline{A}$, and hence using the limits of nets. This is because the intuition of closed sets is very closely related to the intuition of limits of nets/sequences. On the other hand, the intuition of open sets is very different. Let me say a few words about this.

Without a doubt, the keyword I give for the intuition of limits of nets is “approximation”: Limit is not only a dynamic process, but also gives an impression of “getting smaller and smaller”. When dealing with closed sets, we often do the same thing! We take an intersection of possibly infinitely many closed subsets, and the result we get is still a closed set (cf. Cor. 2.4).

The keyword I give for open sets is “local”, or more precisely, “local-to-global” (as opposed to “getting smaller and smaller”!). This is not only because a union of open sets is open, but also because open sets are very often used to prove a global result by reducing to local problems. One easy example is Exe. 7.117, which says that in order to prove that a function is continuous on the whole space X , it suffices to prove this locally. (We have already used this strategy in Sec. 2.4.) Here is a more advanced example: to define the integral for a function on a large set, one can first define it locally (i.e. on small enough open subsets), and then patch these local values together. We will see many examples in the future, for example, in the following chapter about compactness.

Remark 7.54. Very often, a theorem is an important result establishing two seemingly different (systems of) intuitions, and hence two different ways of mathematical thinking. This is why I call “closed sets are the complements of open sets” a theorem. The term “complement” implies that this theorem often manifests itself in the following way: If solving a problem using open sets is a direct proof, then solving the problem using limits of sequences/nets is a proof by contradiction/contrapositive. And vice versa.

7.4 Continuous maps and homeomorphisms

Unless otherwise stated, X and Y are topological spaces.

7.4.1 Continuous maps

Definition 7.55. Let $f : X \rightarrow Y$ be a map. Let $x \in X$. We say that f is **continuous at x** if the following equivalent conditions hold:

- (1) For every net $(x_\alpha)_{\alpha \in I}$ in X converging to x , we have $\lim_{\alpha \in I} f(x_\alpha) = f(x)$.
- (2) For every $V \in \text{Nbh}_Y(f(x))$, there exists $U \in \text{Nbh}_X(x)$ such that for every $p \in U$ we have $f(p) \in V$.
- (2') For every $V \in \text{Nbh}_Y(f(x))$, the point x is an interior point of $f^{-1}(V)$.

We say that f is a **continuous function/map**, if f is continuous at every point of X .

It is clear that “for every $V \in \text{Nbh}_Y(f(x))$ ” in (2) and (2') can be replaced by “for every $V \in \mathcal{B}$ containing $f(x)$ ” if \mathcal{B} is a basis for the topology of Y .

Note that in the case that (x_α) or $(f(x_\alpha))$ has more than one limits (which could happen when X or Y is not Hausdorff), condition (1) means that $f(x)$ is one of the limits of $(f(x_\alpha))_{\alpha \in I}$ if x is one of the limits of (x_α) .

Proof of equivalence. Clearly (2) is equivalent to (2'). The proof of (2) \Rightarrow (1) is similar to the case of sequences in metric spaces. (See Def. 2.38.) We leave the details to the reader.

$\neg(2) \Rightarrow \neg(1)$: Assume that (2) is not true. Then there is a neighborhood V of $f(x)$ such that for every neighborhood U of x there exists $x_U \in U$ such that $f(x_U) \notin V$. Then $(x_U)_{U \in \text{Nbh}_X(x)}$ is a net in X , and $\lim_U x_U = x$ since $x_U \in U$. However, for each U we have $f(x_U) \in Y \setminus V$. So $\lim_U f(x_U)$ cannot converge to $f(x)$. \square

Exercise 7.56. Show that when X, Y are metric spaces, Def. 7.55 agrees with Def. 2.38.

Exercise 7.57. Let $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ be maps of topological spaces. Assume that f is continuous at $x \in X$, and g is continuous at $f(x)$. Prove that $g \circ f : X \rightarrow Z$ is continuous at x .

The proof of (1) \Rightarrow (2) in Def. 7.55 is indirect, since it uses the axiom of choice. (The merit of this proof is that it is parallel to the proof for metric spaces in Sec. 2.4.) One can also give a direct proof. Indeed, there is a particular net (x_α) converging to x such that $\lim f(x_\alpha) = f(x)$ iff (2) is true:

Exercise 7.58. Define $(\text{PNbh}_X(x), \leq)$, the **directed set of pointed neighborhoods** of x , to be

$$\begin{aligned} \text{PNbh}_X(x) &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned} \quad (7.6)$$

For each $\alpha = (p, U) \in \text{PNbh}_X(x)$, let $x_\alpha = p$. Then $(x_\alpha)_{\alpha \in \text{PNbh}_X(x)}$ is a net in X converging to x . Prove that f is continuous at x iff $\lim_\alpha f(x_\alpha) = f(x)$.

Proposition 7.59. Let $f : X \rightarrow Y$ be a map. The following are equivalent:

- (1) f is continuous.
- (2) If $V \subset Y$ is open in Y , then $f^{-1}(V)$ is open in X .
- (3) If $F \subset Y$ is closed in Y , then $f^{-1}(F)$ is closed in X .

Proof. (1) \Leftrightarrow (2): By Def. 7.55-(2') and Prop. 7.42. (2) \Leftrightarrow (3): By Thm. 7.47 and the fact that $f^{-1}(B^c) = f^{-1}(B)^c$ for every $B \subset Y$. \square

Remark 7.60. We first defined the continuity of f at a point, and then used this to define a continuous function f to be one continuous at every point. However, it seems that the notion of continuity at a point is used only in analysis. In geometry and in topology, only continuous maps (but not a map continuous at a point) are used, and they are defined by Prop. 7.59-(2).

One might think that continuous functions are special cases of functions which are continuous at given points. But in fact, the latter notion can also be derived from the former: \square

Exercise 7.61. Let $f : (X, \mathcal{T}) \rightarrow (Y, \mathcal{T}')$ be a map of topological spaces. Let $x \in X$. Define a new topological space (X_x, \mathcal{T}_x) as follows. X_x equals X as a set. The topology \mathcal{T}_x of X_x is generated by the basis

$$\mathcal{B}_x = \text{Nbh}_X(x) \cup \{\{p\} : p \neq x\} \quad (7.7)$$

Prove that if X is Hausdorff, then X_x is Hausdorff. Prove that the following are equivalent:

- (1) $f : X \rightarrow Y$ is continuous at x .
- (2) $f : X_x \rightarrow Y$ is continuous.

Continuous functions are determined by their values on a dense subset:

Proposition 7.62. *Let A be a subset of X , and let $f, g : \bar{A} \rightarrow Y$ be continuous. Then*

$$f(\bar{A}) \subset \overline{f(A)} \quad (7.8a)$$

If Y is moreover Hausdorff, then

$$f = g \quad \Longleftrightarrow \quad f|_A = g|_A \quad (7.8b)$$

Proof. If $y \in f(\bar{A})$, then $y = f(x)$ for some $x \in \bar{A}$. Choose a net (x_α) in A converging to x . Then $\lim_\alpha f(x_\alpha) = f(x)$, and hence $f(x) \in \overline{f(A)}$.

Assume that Y is Hausdorff. If $f = g$ then clearly $f|_A = g|_A$. Assume that $f|_A = g|_A$. For each $x \in \bar{A}$, choose a net (x_α) in A converging to x . Then $f(x) = \lim f(x_\alpha) = \lim g(x_\alpha) = g(x)$. So $f = g$. \square

You are encouraged to prove Prop. 7.62 using open sets instead of using nets.

7.4.2 Homeomorphisms

Definition 7.63. A map $f : X \rightarrow Y$ is called **open** (resp. **closed**) if for every open (resp. closed) subset $A \subset X$, the image $f(A)$ is open (resp. closed) in Y .

Definition 7.64. A bijection $f : X \rightarrow Y$ is called a **homeomorphism** if the following clearly equivalent conditions hold:

- (1) f and f^{-1} are continuous.
- (2) For every net (x_α) in X and each $x \in X$, we have that $\lim_\alpha x_\alpha = x$ iff $\lim_\alpha f(x_\alpha) = f(x)$.
- (3) f is continuous and open.
- (4) f is continuous and closed.

If a homeomorphism $f : X \rightarrow Y$ exists, we say that X, Y are **homeomorphic**.

Recall from Def. 2.60 that when X, Y are metric spaces, the sequential version of (2) holds.

Remark 7.65. Let $\mathcal{T}_1, \mathcal{T}_2$ be two topologies on a set X . Clearly, we have $\mathcal{T}_1 = \mathcal{T}_2$ iff

$$\varphi : (X, \mathcal{T}_1) \rightarrow (X, \mathcal{T}_2) \quad x \mapsto x \quad (7.9)$$

is a homeomorphism. Thus, the following are equivalent:

$$(1) \mathcal{T}_1 = \mathcal{T}_2.$$

(2) For every net (x_α) in X and $x \in X$, we have that $\lim_\alpha x_\alpha = x$ under \mathcal{T}_1 iff $\lim_\alpha x_\alpha = x$ under \mathcal{T}_2 .

This equivalence implies that

topologies are determined by net convergence

Therefore, instead of using open sets or bases of topologies to describe a topology, one can also describe a topology \mathcal{T} on a set X in the following way:

$$\begin{aligned} \mathcal{T} \text{ is the unique topology on } X \text{ such that} \\ \text{a net } (x_\alpha) \text{ in } X \text{ converges to } x \in X \text{ iff ...} \end{aligned} \quad (7.10)$$

Similarly, by Def. 2.60, metrizable topologies are determined by sequential convergence. Therefore, metrizable topologies can be described in the following way:

$$\begin{aligned} \mathcal{T} \text{ is the unique metrizable topology on } X \text{ such that} \\ \text{a sequence } (x_n) \text{ in } X \text{ converges to } x \in X \text{ iff ...} \end{aligned} \quad (7.11)$$

7.5 Examples of topological spaces described by net convergence

Example 7.66. Let A be a subset of a topological space (X, \mathcal{T}_X) . Then the subspace topology \mathcal{T}_A of A is the unique topology such that a net (x_α) in A converges to $x \in A$ under \mathcal{T}_A iff it converges to x under \mathcal{T}_X .

★ **Example 7.67.** Let $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ be a disjoint union where each $(X_\alpha, \mathcal{T}_\alpha)$ is a topology space. Then

$$\mathcal{B} = \bigcup_{\alpha \in \mathcal{A}} \mathcal{T}_\alpha$$

is clearly a basis generating a topology \mathcal{T} on X , called **disjoint union topology**. \mathcal{T} is the unique topology on X such that for every net $(x_\mu)_{\mu \in I}$ in X and any $x \in X$, the following are equivalent:

- (1) $(x_\mu)_{\mu \in I}$ converges to x under \mathcal{T} .
- (2) There exists $\nu \in I$ such that for every $\mu \geq \nu$, the element x_μ belongs to the unique X_α containing x . Moreover, $\lim_{\mu \in I, \mu \geq \nu} x_\mu = x$ in X_α .

We call (X, \mathcal{T}) the **disjoint union topological space** of $(X_\alpha)_{\alpha \in \mathcal{A}}$.

The following exercise says that “disjoint union of topological spaces” is synonymous with “disjoint union of open subsets”.

★ **Exercise 7.68.** Assume that $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$. Assume that X has a topology \mathcal{T} , and equip each X_α with the subspace topology. Show that (X, \mathcal{T}) is the disjoint union topological space of $(X_\alpha)_{\alpha \in \mathcal{A}}$ iff each X_α is an open subset of (X, \mathcal{T}) .

Thus, for example, $\bigcup_{n \in \mathbb{N}} [2n, 2n+1)$ (under the Euclidean topology) is the disjoint union topological space of the family $([2n, 2n+1))_{n \in \mathbb{N}}$.

★ **Exercise 7.69.** In Exp. 7.67, assume that each $(X_\alpha, \mathcal{T}_\alpha)$ is metrizable. Prove that (X, \mathcal{T}) is metrizable. More precisely: Choose a metric d_α inducing \mathcal{T}_α , and assume that $d_\alpha \leq 1$ (cf. Prop. 2.74). Define a metric d on X as in Pb. 2.4. Solve the *net version* of part 2 of Pb. 2.4. Conclude from this that d induces the topology \mathcal{T} . (Warning: we cannot conclude this from the original sequential version of Pb. 2.4-2.)

Definition 7.70. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ be a family of topological spaces. Elements of the product space

$$S = \prod_{\alpha \in \mathcal{A}} X_\alpha$$

are denoted by $x = (x(\alpha))_{\alpha \in \mathcal{A}}$. One checks easily that

$$\begin{aligned} \mathcal{B} = \left\{ \prod_{\alpha \in \mathcal{A}} U_\alpha : \text{each } U_\alpha \text{ is open in } X_\alpha, \right. \\ \left. U_\alpha = X_\alpha \text{ for all but finitely many } \alpha \right\} \end{aligned} \quad (7.12)$$

is a basis for a topology \mathcal{T} , called the **product topology** or **pointwise convergence topology** of S . We call (S, \mathcal{T}) the **product topological space**.

Equivalently, let

$$\pi_\alpha : S \rightarrow X_\alpha \quad x \mapsto x(\alpha) \quad (7.13)$$

be the **projection map onto the X_α component**. Then

$$\mathcal{B} = \left\{ \bigcap_{\alpha \in E} \pi_\alpha^{-1}(U_\alpha) : E \in \text{fin}(2^{\mathcal{A}}), U_\alpha \text{ is open in } X_\alpha \text{ for each } \alpha \in E \right\} \quad (7.14)$$

Unless otherwise stated, a product of topological spaces is equipped with the product topology. \square

Example 7.71. Let $S = X_1 \times \cdots \times X_N$ be a finite product of topological spaces. Then the product topology has a basis

$$\mathcal{B} = \{U_1 \times \cdots \times U_N : \text{each } U_i \text{ is open in } X_i\} \quad (7.15)$$

Theorem 7.72. Let $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ be a product of topological spaces, equipped with the product topology. Then each projection map π_α is continuous. Moreover, for every net $(x_\mu)_{\mu \in I}$ in S and every $x \in S$, the following are equivalent.

- (1) $\lim_{\mu \in I} x_\mu = x$ in S .
- (2) For every $\alpha \in \mathcal{A}$, we have $\lim_{\mu \in I} x_\mu(\alpha) = x(\alpha)$ in X_α .

If (x_μ) satisfies (1) or (2), we say that x_μ **converges pointwise** to x if we view (x_μ) as a net of functions with domain \mathcal{A} .

Proof. We leave the proof to the readers. Note that the continuity of π_α follows easily from the basis-for-topology version of Prop. 7.59-(2). And from the continuity of π_α one easily deduce (1) \Rightarrow (2). \square

Remark 7.73. In the spirit of (7.10), one says that:

- The product topology \mathcal{T} on $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ is the unique topology such that a net (x_μ) converges to x under \mathcal{T} iff x_μ converges pointwise to x as a net of functions on \mathcal{A} .

Corollary 7.74. If each X_α is a Hausdorff space, then $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ is Hausdorff.

Proof. Either prove this directly using the basis for the topology, or prove that any net cannot converge to two different values using Thm. 7.72. \square

Corollary 7.75. Let X_1, X_2, \dots be a possibly finite sequence of metric spaces. Then $S = \prod_i X_i$ is metrizable. More precisely, for each i , choose a metric d_i on X_i topologically equivalent to the original one such that $d_i \leq 1$ (cf. Prop. 2.4). Then the metric d on S defined by

$$d(f, g) = \sup_i \frac{d_i(f(i), g(i))}{i} \quad (7.16)$$

induce the product topology.

We note that the product topology is also induced by

$$\delta(f, g) = \sum_i 2^{-i} d_i(f(i), g(i)) \quad (7.17)$$

Proof. The same method for solving Pb. 2.3 also applies to its net version: One shows that a net (f_α) in S converges to f under d (or under δ) iff (f_α) converges pointwise to f . Thus, by Thm. 7.72, d and δ induce the product topology. \square

The next example discusses the topologies induced by uniform convergence metrics. (Recall Def. 3.57.) In this example, Y is usually a normed vector space.

Example 7.76. Let X be a set, and let (Y, d_Y) be a metric space. Then there is a unique topology \mathcal{T} on Y^X such that for every net $(f_\alpha)_{\alpha \in I}$ in Y^X and every $f \in Y^X$, the following are equivalent:

- (1) The net (f_α) converges to f under \mathcal{T} .
- (2) We have $\lim_{\alpha \in I} \sup_{x \in X} d_Y(f_\alpha(x), f(x)) = 0$.

(If (f_α) satisfies (2), we say that f_α **converges uniformly** to f .) For example, one checks easily that \mathcal{T} is induced by any **uniform convergence metric**, i.e., any metric on Y^X topologically equivalent to d where

$$d(f, g) = \min \left\{ 1, \sup_{x \in X} d_Y(f(x), g(x)) \right\} \quad (7.18)$$

So \mathcal{T} is metrizable. We call \mathcal{T} the **uniform convergence topology** on Y^X .

Theorem 7.77. Let V be a normed vector space over \mathbb{R} or \mathbb{C} . Let X be a topological space. Equip V^X with the uniform convergence topology. Then $C(X, V)$ is a closed subset of V^X .

Proof. This is similar to the proof of Thm. 3.47. Let (f_α) be a net $C(X, V)$ converging uniformly to $f : X \rightarrow V$. Choose any $x \in X$ and $\varepsilon > 0$. Then there is $\alpha \in I$ such that $\sup_{p \in X} \|f(x) - f_\alpha(x)\| < \varepsilon$. Since f_α is continuous, there is $U \in \text{Nbh}_X(x)$ such that for each $p \in U$ we have $\|f_\alpha(x) - f_\alpha(p)\| < \varepsilon$. Thus, for each $p \in U$ we have

$$\|f(x) - f(p)\| \leq \|f(x) - f_\alpha(x)\| + \|f_\alpha(x) - f_\alpha(p)\| + \|f_\alpha(p) - f(p)\| < 3\varepsilon$$

So f is continuous. □

Remark 7.78. Note that the uniform convergence topology depends on the equivalence class (not just the topological equivalence class) of d_Y . Thus, one needs metrics when talking about uniform convergence. On the other hand, the study of pointwise convergence does not require metrics.

7.6 Limits of functions

By Prop. 7.62, if $A \subset X$, and if $f : \bar{A} \rightarrow Y$ is continuous, then the value of f is uniquely determined by $f|_A$ provided that Y is Hausdorff (cf. Prop. 7.62). We now consider the opposite question of extension of continuous functions: Suppose that $f : A \rightarrow Y$ is continuous. Can we extend f to a continuous function $f : \bar{A} \rightarrow Y$? (We know that such extension must be unique if it exists.) The classical concept of the limits of functions can be understood in this light.

Definition 7.79. Let A be a subset of X . Let $f : A \rightarrow Y$ be a map. Let $x \in \bar{A} \setminus A$. Let $y \in Y$. We say that the **limit of the function** f at x is y and write

$$\lim_{\substack{p \in A \\ p \rightarrow x}} f(p) \equiv \lim_{p \rightarrow x} f(p) = y$$

if the following equivalent conditions hold:

- (1) If we extend f to a function $A \cup \{x\} \rightarrow Y$ satisfying $f(x) = y$, then $f : A \cup \{x\} \rightarrow Y$ is continuous at x .
- (2) For every $V \in \text{Nbh}_Y(y)$, there exists $U \in \text{Nbh}_X(x)$ such that for every $p \in U \cap A$, we have $f(p) \in V$.
- (3) For every net $(x_\alpha)_{\alpha \in I}$ in A converging to x , we have $\lim_{\alpha \in I} f(x_\alpha) = y$.

When X, Y are metric spaces, the above three conditions and the following two are equivalent:

- (2m) For every $\varepsilon > 0$, there exists $\delta > 0$ such that for every $p \in A$, if $d(p, x) < \delta$ then $d(f(p), y) < \varepsilon$.
- (3m) For every sequence $(x_n)_{n \in \mathbb{Z}_+}$ in A converging to x , we have $\lim_{n \rightarrow \infty} f(x_n) = y$.

Recall that by the definition of subspace topology, we have

$$\text{Nbh}_A(x) = \{U \cap A : A \in \text{Nbh}_X(x)\} \quad (7.19)$$

Proof of equivalence. Extend f to $\tilde{f} : A \cup \{x\} \rightarrow Y$ by setting $\tilde{f}(x) = y$. Then by Def. 7.55-(2), condition (1) of Def. 7.79 means that for every $V \in \text{Nbh}_Y(y)$ there is a neighborhood of x in $A \cup \{x\}$ (which, by (7.19), must be of the form $U \cap (A \cup \{x\})$ where $U \in \text{Nbh}_X(x)$) such that for every $p \in U \cap (A \cup \{x\})$ we have $\tilde{f}(p) \in V$. This is clearly equivalent to (2), since $\tilde{f}(x) = y \in V$. The equivalence (2) \Leftrightarrow (3) can be proved in a similar way as the equivalence of (1) and (2) in Def. 7.55. We leave the details to the readers. When X, Y are metric spaces, (2) is clearly equivalent to (2m). The equivalence (2m) \Leftrightarrow (3m) can be proved in a similar way as the equivalence of (1) and (2) in Def. 2.38. \square

The following remarks show that the limit of a function at a point is the limit of a single net, rather than the limit of many nets (as in Def. 7.79-(3)).

Remark 7.80. Assume the setting of Def. 7.79. In the same spirit of Exe. 7.58, define a directed set $(\text{PNbh}_A(x), \leq)$ where

$$\begin{aligned} \text{PNbh}_A(x) &= \{(p, U) : U \in \text{Nbh}_X(x), p \in U \cap A\} \\ (p, U) &\leq (p', U') \iff U \supset U' \end{aligned} \quad (7.20)$$

(That it is a directed set is due to $x \in \overline{A}$.) We have seen this directed set in Rem. 7.31. Then $(p)_{(p, U) \in \text{PNbh}_A(x)}$ is a net converging to x , and

$$\lim_{p \rightarrow x} f(p) = \lim_{(p, U) \in \text{PNbh}_A(x)} f(p) \quad (7.21)$$

where the convergence of the LHS is equivalent to that of the RHS.

Remark 7.81. In the setting of Def. 7.79, assume moreover that X is a metric space, then $\lim_{p \rightarrow x} f(p)$ can be described by the limit of a simpler net. Define a directed set (A_x, \leq) where

$$\begin{aligned} A_x &= A \text{ as sets} \\ p \leq p' &\iff d(p', x) \geq d(p, x) \end{aligned} \tag{7.22}$$

Then $(p)_{p \in A_x}$ is a net in A converging to x , and

$$\lim_{p \rightarrow x} f(p) = \lim_{p \in A_x} f(p) \tag{7.23}$$

where the convergence of the LHS is equivalent to that of the RHS.

Remark 7.82. Thanks to the above two remarks, limits of functions enjoy all the properties that limits of nets enjoy. For example, they satisfy Squeeze theorem; if $f : A \rightarrow \mathbb{F}$ and $g : A \rightarrow V$ (where V is a normed vector space over $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}\}$), if $x \in \overline{A} \setminus A$, and if $\lambda = \lim_{p \rightarrow x} f(p)$ and $v = \lim_{p \rightarrow x} g(p)$ exist, then $\lim_{p \rightarrow x} f(p)g(p)$ converges to λv .

Of course, you can also conclude them by using Def. 7.79-(3) instead of Rem. 7.80. In practice, it makes no difference whether you view $\lim_{p \rightarrow x} f(p)$ as the limit of $f(x_\alpha)$ for an arbitrary net x_α in A converging to x , or whether you view $\lim_{p \rightarrow x} f(p)$ as the limit of the particular net in Rem. 7.80 or Rem. 7.81. The explicit constructions of nets in these two remarks are not important for proving results about limits of functions. \square

Remark 7.83. Let $f : A \rightarrow Y$, and let $x \in \overline{A} \setminus A$. Suppose that Y is Hausdorff. Assume that there exist two nets $(x_\alpha)_{\alpha \in I}$ and $(y_\beta)_{\beta \in J}$ in A converging to x such that $(f(x_\alpha))$ and $(f(y_\beta))$ converge to two different values. Then by Def. 7.79-(2), the limit $\lim_{p \rightarrow x} f(p)$ does not exist.

The above remark gives a useful criterion for the non-convergence of limits of functions. The following proposition, on the other hand, gives a method of computing limits of functions by decomposing the domain into (non-necessarily mutually disjoint) subsets.

Proposition 7.84. Assume the setting of Def. 7.79. Assume that $A = A_1 \cup \dots \cup A_N$. Then the following are equivalent.

- (1) We have $\lim_{p \rightarrow x} f(p) = y$.
- (2) For every $1 \leq i \leq N$ such that $x \in \overline{A_i}$, we have $\lim_{p \rightarrow x} f|_{A_i}(p) = y$

Proof. (1) \Rightarrow (2): Assume (1). Extend $f : A \rightarrow Y$ to a function $\tilde{f} : A \cup \{x\} \rightarrow Y$ by setting $\tilde{f}(x) = y$. Then \tilde{f} is continuous by (1). Thus, if $x \in \overline{A_i}$, then $\tilde{f}|_{A_i \cup \{x\}}$ is continuous. This proves (2).

(2) \Rightarrow (1): Assume (2). Choose any $V \in \text{Nbh}_Y(y)$. By (2), for each i , either $x \in \overline{A_i}$ so that there is $U_i \in \text{Nbh}_X(x)$ satisfying $U_i \cap A_i \subset f^{-1}(V)$ (recall (7.19)), or that $x \notin \overline{A_i}$ so that there is $U_i \in \text{Nbh}_X(x)$ disjoint from A_i . In either case, we have $U_i \cap A_i \subset f^{-1}(V)$. Let $U = U_1 \cap \cdots \cap U_N$. Then

$$U \cap A = U \cap (A_1 \cup \cdots \cup A_N) = \bigcup_i U \cap A_i \subset \bigcup_i U_i \cap A_i$$

which is therefore a subset of $f^{-1}(V)$.

Another proof of $\neg(1) \Rightarrow \neg(2)$: Assume (1) is not true. Then there is a net $(x_\alpha)_{\alpha \in I}$ in A converging to x such that $f(x_\alpha)$ does not converge to y . So there exists $V \in \text{Nbh}_Y(y)$ such that $f(x_\alpha)$ is not eventually in V , i.e., $f(x_\alpha)$ is frequently in V^c . Then $(f(x_\alpha))$ has a subnet $(f(x_\beta))_{\beta \in J}$ which is always in V^c . For example, take

$$J = \{\beta \in I : f(x_\beta) \in V^c\}$$

Since $(x_\beta)_{\beta \in J}$ is always in A , by the logic (5.6c), there is $1 \leq i \leq N$ such that (x_β) is frequently in A_i . Thus, by the same argument as above, (x_β) has a subnet $(x_\gamma)_{\gamma \in K}$ which is always in A_i . Since $x_\alpha \rightarrow x$, we have $x_\gamma \rightarrow x$, and hence $x \in \overline{A_i}$. But $f(x_\gamma) \in V^c$. So we have found a net (x_γ) in A_i converging to x such that $(f(x_\gamma))$ does not converge to y . This disproves (2). \square

Remark 7.85. In many textbooks, $\lim_{p \rightarrow x} f(x)$ is also defined more generally when x is an accumulation point of A , i.e., when $x \in \overline{A \setminus \{x\}}$. In this case, the limit of f at x simply means

$$\lim_{p \rightarrow x} f(p) \stackrel{\text{def}}{=} \lim_{p \rightarrow x} f|_{A \setminus \{x\}}(p) \quad (7.24)$$

This more general case is important in classical analysis, but is less useful in abstract analysis. (As a matter of fact, accumulation points are less convenient than closure points.) In order not to deviate too far from the traditional analysis textbooks, let's take a look at some examples.

Definition 7.86. Let $A \subset \mathbb{R}$ and $x \in \mathbb{R}$. Let $f : A \rightarrow Y$ be a function. If x is a closure point of $A \cap \mathbb{R}_{<x}$ resp. $A \cap \mathbb{R}_{>x}$, we define the **left limit** resp. **right limit** to be

$$\lim_{t \rightarrow x^-} f(t) = \lim_{t \rightarrow x} f|_{A \cap \mathbb{R}_{<x}}(t) \quad (7.25a)$$

$$\lim_{t \rightarrow x^+} f(t) = \lim_{t \rightarrow x} f|_{A \cap \mathbb{R}_{>x}}(t) \quad (7.25b)$$

If $x \in \overline{\mathbb{R}}$ and x is a closure point of $A \setminus \{x\}$, then $\lim_{t \rightarrow x} f(t)$ is understood by (7.24).

Remark 7.87. In Def. 7.86, if $x \in \mathbb{R}$ is a closure point of $A \setminus \{x\}$, then by Prop. 7.84,

$$\lim_{p \rightarrow x} f(p) = y \quad \Longleftrightarrow \quad \lim_{p \rightarrow x^-} f(p) = \lim_{p \rightarrow x^+} f(p) = y \quad (7.26)$$

In particular, the existence of the limit on the LHS is equivalent to the existence and the equality of the two limits on the RHS.

Example 7.88. Let $g, h : \mathbb{R} \rightarrow \mathbb{R}$ be continuous functions. Let $c \in \mathbb{R}$. Define $f : \mathbb{R} \rightarrow \mathbb{R}$ to be

$$f(x) = \begin{cases} g(x) & \text{if } x < 0 \\ c & \text{if } x = 0 \\ h(x) & \text{if } x > 0 \end{cases}$$

Since $g|_{(-\infty, 0]}$ is continuous, by Def. 7.79-(1) we have that $\lim_{x \rightarrow 0^-} f(x) = \lim_{x \rightarrow 0, t < 0} g(t) = g(0)$. Similarly, $\lim_{x \rightarrow 0^+} f(x) = h(0)$. Therefore, by Rem. 7.87, $\lim_{x \rightarrow 0} f(x)$ exists iff $g(0) = h(0)$, and it converges to $g(0)$ if $g(0) = h(0)$. The value c is irrelevant to the limits.

Example 7.89. Let $f : X = \mathbb{R}^2 \setminus \{(0, 0)\} \rightarrow \mathbb{R}$ be $f(x, y) = \frac{x}{x+y}$. Then $(1/n, 0)$ and $(0, 1/n)$ are sequences in X converging to 0. But $f(1/n, 0) = 1$ and $f(0, 1/n) = 0$. So $\lim_{(x,y) \rightarrow (0,0)} f(x, y)$ does not exist by Rem. 7.83.

7.7 Connected spaces

Let X be a topological space. In this section, we shall define a notion of connected space. Based on our usual geometric intuition, one might attempt to define a connected space as one satisfying that any two points can be linked by a path. Such spaces are actually called **path-connected spaces** and is stronger than connected spaces. In fact, connected spaces arise from the study of intermediate value problem.

7.7.1 Connected \Leftrightarrow IVP

Definition 7.90. We say that the topological space X is **connected** if X can not be written as the disjoint of two nonempty open sets. Namely, if $X = U \sqcup V$ where U, V are open subsets of X , then either $U = \emptyset$ (and hence $V = X$) or $V = \emptyset$ (and hence $U = X$).

Equivalently (by Thm. 7.47), X is connected iff every $U \subset X$ which is both closed and open must be \emptyset or X .

Definition 7.91. We say that X satisfies the **intermediate value property** (abbreviated to **IVP**) if for every continuous function $f : X \rightarrow \mathbb{R}$ and every $x, y \in X$ we have

$$f(x) < f(y) \implies [f(x), f(y)] \subset f(X) \quad (7.27)$$

Theorem 7.92. X is connected iff X satisfies IVP. Moreover, if X is not connected, then there is a continuous $f : X \rightarrow \mathbb{R}$ such that $f(X) = \{0, 1\}$.

Proof. First, assume that X does not satisfy IVP. Choose a continuous $f : X \rightarrow \mathbb{R}$ with real numbers $a < b < c$ such that $a, c \in f(X)$ but $b \notin f(X)$. So $U = f^{-1}(-\infty, b)$ and $V = f^{-1}(b, +\infty)$ are disjoint non-empty open subsets of X , and $X = U \sqcup V$. They are open, because f is continuous (cf. Prop. 7.59). So X is not connected.

Next, assume that X is not connected. Then $X = U \sqcup V$ where U, V are open subsets of X . Define $f : X \rightarrow \mathbb{R}$ to be constantly 0 on U and constantly 1 on V . It is easy to check that f is continuous. (See also Rem. 7.118.) That $f(X) = \{0, 1\}$ means that X does not satisfy IVP. \square

We now give a couple of elementary examples.

7.7.2 Connected subsets of $\overline{\mathbb{R}}$ are precisely intervals

Proposition 7.93. *Let A be a dense subset of X . Assume that A is connected. Then X is connected.*

Proof. If $X = \overline{A}$ is not connected, then by Thm. 7.92, there exists a continuous surjection $f : \overline{A} \rightarrow \{0, 1\}$. By Prop. 7.62, $\overline{f(A)}$ contains $f(\overline{A})$. So $f(A)$ has closure $\{0, 1\}$. So $f(A) = \{0, 1\}$. A does not satisfy IVP, and hence is not connected. \square

Theorem 7.94. *Let A be a subset of $\overline{\mathbb{R}}$. Then A is connected iff A is an interval.*

Proof. Step 1. Suppose that A is connected. Let $a = \inf A$ and $b = \sup A$. To show that A is one of (a, b) , $(a, b]$, $[a, b)$, $[a, b]$, it suffices to show that every $c \in (a, b)$ belongs to A . Suppose that some $c \in (a, b)$ does not belong to A . Then A is the disjoint union of two nonempty open subsets $A \cap [-\infty, c)$ and $A \cap (c, +\infty]$, impossible.

Step 2. Every single point is clearly connected. Since every interval containing at least two points is homeomorphic to one of $[0, 1]$, $(0, 1]$, $[0, 1)$, $(0, 1)$, it suffices to prove that these four intervals are connected. Since $(0, 1)$ is dense in the other three intervals, by Prop. 7.93, it suffices to prove that $(0, 1)$ is connected.

Suppose that $(0, 1)$ is not connected. Then $(0, 1) = U \sqcup V$ where U, V are disjoint open nonempty subsets. Choose $x_1 \in U$ and $y_1 \in V$, and assume WLOG that $x_1 < y_1$. In the following, we construct an increasing sequence (x_n) in U and a decreasing one (y_n) in V satisfying $x_n < y_n$ for all n by induction. Suppose x_n, y_n has been constructed. Let $z_n = (x_n + y_n)/2$.

- If $z_n \in U$, then let $x_{n+1} = z_n$ and $y_{n+1} = y_n$.
- If $z_n \in V$, then let $x_{n+1} = x_n$ and $y_{n+1} = z_n$.

Then $y_n - x_n$ converges to 0. So x_n and y_n converge to the same point $\xi \in \mathbb{R}$. We have $\xi \in (0, 1)$ since $x_1 < \xi < y_1$. Since V is open, $U = (0, 1) \setminus V$ is closed in $(0, 1)$ by Thm. 7.47. So $\xi \in \text{Cl}_{(0,1)}(U) = U$. Similarly, $\xi \in \text{Cl}_{(0,1)}(V) = V$. This is impossible. \square

7.7.3 More examples of connected spaces

Definition 7.95. Let $x, y \in X$. A **path** in X from x to y is defined to be a continuous map $\gamma : [a, b] \rightarrow X$ where $-\infty < a < b < +\infty$, such that $\gamma(a) = x$ and $\gamma(b) = y$. Unless otherwise stated, we take $[a, b]$ to be $[0, 1]$. We call x and y respectively the **initial point** and the **terminal point** of γ .

Definition 7.96. We say that X is **path-connected** if for every $x, y \in X$ there is a path in X from x to y .

Example 7.97. \mathbb{R}^N is path-connected. $B_{\mathbb{R}^N}(0, R)$ and $\overline{B}_{\mathbb{R}^N}(0, R)$ (where $R < +\infty$) are path connected. $\{x \in \mathbb{R}^N : r < x < R\}$ (where $0 \leq r < R < +\infty$) are path connected. The region enclosed by a triangle is a connected subset of \mathbb{R}^2 . $[0, 1]^N$ is connected.

Theorem 7.98. Assume that X is path-connected. Then X is connected.

Proof. If X is not connected, then $X = U \sqcup V$ where U, V are nonempty open subsets of X . Since X is path-connected, there is a path γ from a point of U to a point of V . So $[0, 1] = \gamma^{-1}(U) \sqcup \gamma^{-1}(V)$ where $\gamma^{-1}(U), \gamma^{-1}(V)$ are open (by Prop. 7.59) and nonempty. This contradicts the fact that $[0, 1]$ is connected (cf. Thm. 7.94). \square

Proposition 7.99. Let $f : X \rightarrow Y$ be a continuous map of topological spaces. Suppose that X is connected. Then $f(X)$ is connected.

Proof. By replacing $f : X \rightarrow Y$ by the restricted continuous map $f : X \rightarrow f(X)$, it suffices to assume $Y = f(X)$. If Y is not connected, then $Y = U \sqcup V$ where U, V are open and nonempty. Then $X = f^{-1}(U) \sqcup f^{-1}(V)$ are open (by Prop. 7.59) and nonempty subsets of X . So X is not connected, impossible. (One can also use Thm. 7.92 to prove that $f(X)$ is connected.) \square

Remark 7.100. When $Y = \mathbb{R}$, Prop. 7.99 and Thm. 7.94 imply that $f(X)$ is an interval. So f satisfies (7.27). Therefore, Prop. 7.99 can be viewed as a generalization of IVP for connected spaces.

Corollary 7.101. Let I be an interval, and let $f : I \rightarrow \overline{\mathbb{R}}$ be a strictly increasing continuous map. Then $J = f(I)$ is an interval, and the restriction $f : I \rightarrow J$ is a homeomorphism.

Proof. By Thm. 7.94 and Prop. 7.99, J is connected and hence is an interval. Therefore, by Thm. 2.72, f is a homeomorphism. \square

★ **Example 7.102.** Not all connected spaces are path-connected. Let $f : (0, 1] \rightarrow \mathbb{R}^2$ be defined by $f(x) = (x, \sin(x^{-1}))$. Then the range $f((0, 1])$ is connected by Prop. 7.99. Since $f((0, 1])$ is a dense subset of $X = f((0, 1]) \cup \{(0, 0)\}$, by Prop. 7.93, X is connected. However, it can be checked that X is not path-connected. (Prove it yourself, or see [Mun, Sec. 24].) X is called the **topologist's sine curve**.

The following proposition can be used to decompose (for example) an open subset of \mathbb{R}^N into open connected subsets. (See Pb. 7.12.)

Proposition 7.103. *Assume that $X = \bigcup_{\alpha \in \mathcal{A}} X_\alpha$ where each X_α is connected. Assume that $\bigcap_{\alpha \in \mathcal{A}} X_\alpha \neq \emptyset$. Then X is connected.*

Proof. Suppose that X is not connected. By Thm. 7.92, there is a continuous surjection $f : X \rightarrow \{0, 1\}$. Let $p \in \bigcap_{\alpha} X_\alpha$. Then $f(p)$ is 0 or 1. Assume WLOG that $f(p) = 0$. Choose $x \in X$ such that $f(x) = 1$. Choose α such that $x \in X_\alpha$. Then $f|_{X_\alpha} : X_\alpha \rightarrow \{0, 1\}$ is a continuous surjection. So X_α does not satisfy IVP, and hence is not connected. \square

Exercise 7.104. Prove a path-connected version of Prop. 7.103.

Exercise 7.105. Prove Prop. 7.93 and 7.103 directly using Def. 7.90 (but not using IVP).

7.8 Rigorous constructions of $\sqrt[n]{x}$, $\log x$, and a^x

With the help of Cor. 7.101, one can construct a lot of well-known functions rigorously.

Example 7.106. Let $f : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ be $f(x) = x^n$ where $n \in \mathbb{Z}_+$. Then by Cor. 7.101, $J = f(\mathbb{R}_{\geq 0})$ is an interval. Clearly $J \subset [0, +\infty)$. Since $0 \in J$ and $\sup J = +\infty$, we have $J = [0, +\infty)$. Therefore f is a homeomorphism. Its inverse function is a homeomorphism: the n -th root function

$$\sqrt[n]{} : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0} \quad x \mapsto \sqrt[n]{x}$$

This gives the rigorous construction of $\sqrt[n]{x}$.

A similar method gives the rigorous construction of \log .

Example 7.107. By Exp. 4.28, the exponential function $\exp : \mathbb{R} \rightarrow \mathbb{R}$ is continuous. We claim that \exp is a strictly increasing homeomorphism from \mathbb{R} to $\mathbb{R}_{>0}$. Its inverse function is called the **logarithmic function**

$$\log : \mathbb{R}_{>0} \rightarrow \mathbb{R} \quad x \mapsto \log x$$

Proof. From $e^x = \sum_{n=0}^{\infty} x^n/n!$ we clearly have $e^0 = 1$ and $e^x > 1$ if $x > 0$. From $e^{x+y} = e^x e^y$ proved in Cor. 5.61, we have $e^x e^{-x} = e^0 = 1$, which shows that $e^x \in \mathbb{R}_{>0}$ for all $x \in \mathbb{R}$. If $x < y$, then $e^y > e^x > 0$ since $e^y = e^{y-x} e^x$ and $e^{y-x} > 1$. So \exp is strictly increasing. Thus, by Cor. 7.101, \exp is a homeomorphism from \mathbb{R} to $J = \exp(\mathbb{R})$, and J is an interval.

When $x \geq 0$, we have $e^x \geq x$ from the definition of e^x . So $\sup_{x \geq 0} e^x = +\infty$. When $x \leq 0$, since $e^x e^{-x} = 1$, we have $\inf_{x \leq 0} e^x = 1/\sup_{x \geq 0} e^x = 0$. So $\sup J = +\infty$ and $\inf J = 0$. Since $0 \notin \exp(\mathbb{R})$ (if $e^x = 0$, then $1 = e^x e^{-x} = 0$, impossible), we have $J = \mathbb{R}_{>0}$. \square

Example 7.108. Let $a \in \mathbb{R}_{>0}$. For each $z \in \mathbb{C}$, define

$$a^z = e^{z \log a} \quad (7.28)$$

By Exp. 7.107, if $a > 1$ (resp. $0 < a < 1$), the map

$$\mathbb{R} \rightarrow \mathbb{R}_{>0} \quad x \mapsto a^x \quad (7.29)$$

is an increasing (resp. decreasing) homeomorphism, since it is the composition of the increasing (resp. decreasing) homeomorphism $x \in \mathbb{R} \mapsto x \log a \in \mathbb{R}$ and the increasing one $\exp : \mathbb{R} \rightarrow \mathbb{R}_{>0}$. By the proof of Exp. 7.107, we have

$$a^0 = 1 \quad a^x a^{-x} = 1 \quad a^x a^y = a^{x+y} \quad (7.30)$$

And clearly

$$a^1 = a. \quad (7.31)$$

It follows that for every $n \in \mathbb{Z}_+$, $a^n = a^{1+\dots+1} = a \cdot \dots \cdot a$. Namely, $a^n = e^{n \log a}$ agrees with the usual understanding of a^n . Thus, since $(a^{1/n})^n$ equals $a^{1/n} \cdot \dots \cdot a^{1/n} = a^{1/n+\dots+1/n} = a^1 = a$, we conclude

$$a^{\frac{1}{n}} = \sqrt[n]{a}$$

Example 7.109. By Exp. 7.107, if $p > 0$ (resp. $p < 0$), then

$$\mathbb{R}_{>0} \rightarrow \mathbb{R}_{>0} \quad x \mapsto x^p = e^{p \log x} \quad (7.32)$$

is an increasing (resp. decreasing) homeomorphism, since it is the composition of the increasing (resp. decreasing) homeomorphism $x \in \mathbb{R}_{>0} \mapsto p \log x \in \mathbb{R}$ and the increasing homeomorphism $\exp : \mathbb{R} \rightarrow \mathbb{R}_{>0}$.

7.9 Problems and supplementary material

Let X and Y be topological spaces.

7.9.1 Open sets, closed sets, closures

Problem 7.1. Let $A, B \in X$. Let $(A_\alpha)_{\alpha \in \mathcal{A}}$ be a family of subsets of X . Prove that

$$\overline{A \cup B} = \overline{A} \cup \overline{B} \quad (7.33a)$$

$$\overline{\bigcap_{\alpha \in \mathcal{A}} A_\alpha} \subset \bigcap_{\alpha \in \mathcal{A}} \overline{A_\alpha} \quad (7.33b)$$

Problem 7.2. Let $(x_\alpha)_{\alpha \in I}$ be a net in X . Let $x \in X$. Prove that the following statements are equivalent:

- (1) $(x_\alpha)_{\alpha \in I}$ has a subnet converging to x .
- (2) For every neighborhood U of x , we have that x_α is frequently in U .
- (3) x belongs to $\bigcap_{\alpha \in I} \overline{\{x_\beta : \beta \geq \alpha\}}$.

Any $x \in X$ satisfying one of these three conditions is called a **cluster point** of $(x_\alpha)_{\alpha \in I}$. (Compare Pb. 3.1.)

Hint. (2) \Leftrightarrow (3) is a direct translation. Assume (2). To prove (1), show that (J, \leq) is a directed set, where

$$\begin{aligned} J &= \{(\alpha, U) \in I \times \text{Nbh}_X(x) : x_\alpha \in U\} \\ (\alpha, U) \leq (\alpha', U') &\iff \alpha \leq \alpha' \text{ and } U \supset U' \end{aligned} \tag{7.34a}$$

Prove that $(x_\mu)_{\mu \in J}$ is a subnet of $(x_\alpha)_{\alpha \in I}$ if for each $(\alpha, U) \in J$ we set

$$x_{(\alpha, U)} = x_\alpha \tag{7.34b}$$

(Namely, the increasing map $J \rightarrow I$ is defined to be $(\alpha, U) \mapsto \alpha$.) Prove that $(x_\mu)_{\mu \in J}$ converges to x . You should point out where (2) is used in your proofs. \square

Remark 7.110. By Pb. 7.2-(3), the set of cluster points of (x_α) is a closed subset, since intersections of closed subsets are closed (cf. Cor. 7.48, or by (7.33b)).

For the reader's convenience, we present below the sequential version of Pb. 7.2. "(1) \Leftrightarrow (2)" is due to Pb. 3.1. "(2) \Leftrightarrow (3)" is due to Pb. 7.2.

Proposition 7.111. Assume that X is a metric space. Let $(x_n)_{n \in \mathbb{Z}_+}$ be a sequence in X . Let $x \in X$. The following statements are equivalent:

- (1) $(x_n)_{n \in \mathbb{Z}_+}$ has a subsequence converging to x .
- (2) For every neighborhood U of x , we have that x_n is frequently in U .
- (3) x belongs to $\bigcap_{n \in \mathbb{Z}_+} \overline{\{x_k : k \geq n\}}$.

Any $x \in X$ satisfying one of these three conditions is called a **cluster point** of $(x_n)_{n \in \mathbb{Z}_+}$.

Prop. 7.111-(3) should remind you of the definitions of \limsup and \liminf .

★ **Remark 7.112.** It is not hard to show that the (1,2,3) of Prop. 7.111 are equivalent in the more general case that X is a first countable topological space (see below for the definition). The proof is similar to that for metric spaces, and is left to the readers as an exercise.

Definition 7.113. Let X be a topological space. A subset \mathcal{B}_x of $\text{Nbh}_X(x)$ is called a **neighborhood basis** of x , if for every $U \in \text{Nbh}_X(x)$ there exists $V \in \mathcal{B}_x$ such that $V \subset U$. We say that X **first countable** if every point x has a neighborhood basis \mathcal{B}_x which is a countable set.

Example 7.114. If X is a metric space, then X is first countable, since for every $x \in X$, $\{B_X(x, 1/n) : n \in \mathbb{Z}_+\}$ is a neighborhood basis of x .

Remark 7.115. By Pb. 7.2-(2) and Prop. 7.111-(2), if (x_n) is a sequence in a metric space X , then (x_n) has a subsequence converging to $x \in X$ iff (x_n) has a subnet converging to x . This is not necessarily true when X is a general topological space. Note that in the general case, cluster points of a sequence (x_n) mean cluster points of (x_n) as a net. Thus, they are not the limits of convergent *subsequences* of (x_n) .

Problem 7.3. Assume that X is a metric space. Let $E \subset X$. Recall that $d(x, E) = d(E, x) = \inf_{e \in E} d(e, x)$. Prove that

$$\{x \in X : d(x, E) = 0\} = \overline{E} \quad (7.35)$$

Remark 7.116. If E, F are disjoint subsets of a metric space X , a continuous function $f : X \rightarrow [0, 1]$ is called an **Urysohn function** with respect to E, F , if

$$f^{-1}(1) = E \quad f^{-1}(0) = F$$

For example, it is easy to check that

$$f : X \rightarrow [0, 1] \quad f(x) = \frac{d(x, F)}{d(x, E) + d(x, F)} \quad (7.36)$$

is an Urysohn function.

★ **Problem 7.4.** A topological space X is called **normal** if for every disjoint $E, F \subset X$, there exist disjoint open subsets $U, V \subset X$ such that $E \subset U$ and $F \subset V$.

1. Prove that X is normal iff for each $E \subset W \subset X$ where E is closed and W is open, there exists an open subset $U \subset X$ such that $E \subset U \subset \overline{U} \subset W$.
2. Prove that if X is metrizable, then X is normal.

7.9.2 Continuous maps

Exercise 7.117. Let $f : X \rightarrow Y$ be a map.

1. Suppose that F is a subset of Y containing $f(X)$. Show that $f : X \rightarrow Y$ is continuous iff $f : X \rightarrow F$ is continuous.

2. (Local to global principle) Suppose that $X = \bigcup_{\alpha \in I} U_\alpha$ where each U_α is an open subset of X , Prove that f is continuous iff $f|_{U_\alpha} : U_\alpha \rightarrow Y$ is continuous for every α .

Remark 7.118. The above local-to-global principle for continuous functions can be rephrased in the following way. Suppose that $X = \bigcup_{\alpha \in I} U_\alpha$ where each U_α is an open subset of X . Suppose that for each α we have a continuous map $f_\alpha : U_\alpha \rightarrow Y$. Assume that for each $\alpha, \beta \in I$ we have

$$f_\alpha|_{U_\alpha \cap U_\beta} = f_\beta|_{U_\alpha \cap U_\beta}$$

Then there is a (necessarily unique) continuous function $f : X \rightarrow Y$ such that $f|_{U_\alpha} = f_\alpha$ for every α .

Problem 7.5. Let $f : X \rightarrow Y$ be a map. Suppose that $X = A_1 \cup \dots \cup A_N$ where $N \in \mathbb{Z}_+$ and A_1, \dots, A_N are closed subsets of X . Suppose that $f|_{A_i} : A_i \rightarrow Y$ is continuous for each $1 \leq i \leq N$. Prove that f is continuous.

Does the conclusion remain true if A_1, \dots, A_N are not assumed closed? If no, find a counterexample. \square

Note. Do not use Prop. 7.84 in your proof. But you can think about how this problem is related to Prop. 7.84. \square

Definition 7.119. Let (I, \leq) be a directed set. Let ∞_I (often abbreviated to ∞) be a new symbol not in I . Then

$$I^* = I \cup \{\infty_I\}$$

is also a directed set if we extend the preorder \leq of I to I^* by setting

$$\alpha \leq \infty_I \quad (\forall \alpha \in I^*)$$

For each $\alpha \in I$, let

$$I_{\geq \alpha}^* = \{\beta \in I^* : \beta \geq \alpha\}$$

The **standard topology** on I^* is defined to be the one induced by the basis

$$\mathcal{B} = \{\{\alpha\} : \alpha \in I\} \cup \{I_{\geq \alpha}^* : \alpha \in I\} \quad (7.37)$$

Problem 7.6. Let (I, \leq) be a directed set. Let I^* be as in Def. 7.119.

1. Check that \mathcal{B} (defined by (7.37)) is a basis for a topology. (Therefore, \mathcal{B} generates a topology \mathcal{T} on I^* .)
2. Let $(x_\alpha)_{\alpha \in I}$ be a net in a topological space X . Let $x_\infty \in X$. (So we have a function $x : I^* \rightarrow X$.) Prove that

$$x \text{ is a continuous function} \quad \Longleftrightarrow \quad \lim_{\alpha \in I} x_\alpha = x_\infty \quad (7.38)$$

3. Is I^* Hausdorff? Prove it, or find a counterexample.

7.9.3 Product spaces

Problem 7.7. Prove Thm. 7.72.

Problem 7.8. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ and $(Y_\alpha)_{\alpha \in \mathcal{A}}$ be families of nonempty topological spaces. Let Z be a nonempty topological space. For each $\alpha \in \mathcal{A}$, choose maps $f_\alpha : X_\alpha \rightarrow Y_\alpha$ and $g_\alpha : Z \rightarrow X_\alpha$.

1. Use Thm. 7.72 to prove that

$$\prod_{\alpha \in \mathcal{A}} f_\alpha : \prod_{\alpha} X_\alpha \rightarrow \prod_{\alpha} Y_\alpha \quad (x(\alpha))_{\alpha \in \mathcal{A}} \mapsto (f_\alpha(x(\alpha)))_{\alpha \in \mathcal{A}} \quad (7.39)$$

is continuous iff each f_α is continuous.

2. Use Thm. 7.72 to prove that

$$\bigvee_{\alpha \in \mathcal{A}} g_\alpha : Z \rightarrow \prod_{\alpha} X_\alpha \quad z \mapsto (g_\alpha(z))_{\alpha \in \mathcal{A}} \quad (7.40)$$

is continuous iff each g_α is continuous.

Problem 7.9. Let $(X_\alpha)_{\alpha \in \mathcal{A}}$ be an uncountable family of metric spaces, where each X_α has at least two elements. Let $S = \prod_{\alpha \in \mathcal{A}} X_\alpha$ be the product space, equipped with the product topology. Prove that S is not first countable (recall Def. 7.113), and hence not metrizable.

7.9.4 Limits of functions

Problem 7.10. Prove the equivalence of (2) and (3) in Def. 7.79.

Problem 7.11. Find $\lim_{(x,y) \rightarrow (0,0)} f(x,y)$, or explain why it does not exist:

$$\begin{aligned} f(x,y) &= \frac{x^2 - y^2}{x^2 + y^2} \\ f(x,y) &= \frac{(xy)^2}{(xy)^2 + (x-y)^2} \\ f(x,y) &= \frac{x^6 y^2}{(x^4 + y^2)^2} \end{aligned}$$

7.9.5 Connectedness

Definition 7.120. A topological space X is called **locally connected** if every $x \in X$ has a neighborhood basis \mathcal{B}_x (recall Def. 7.113) whose members are all connected.

Example 7.121. Every open subset of a locally connected space is clearly locally connected.

Example 7.122. \mathbb{R}^N is locally connected, since open balls are path-connected and hence connected (by Thm. 7.98). Therefore, every open subset of \mathbb{R}^N is locally connected.

Problem 7.12. Suppose that X is locally connected. Prove that X has a unique (disjoint) decomposition $X = \bigsqcup_{\alpha \in \mathcal{A}} X_\alpha$ where each X_α is a nonempty connected open subset of X . (Each X_α is called a **connected component** of X .)

Hint. For each $x \in X$, consider the union of all connected neighborhoods containing x . □

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YAU MATHEMATICAL SCIENCES CENTER, TSINGHUA UNIVERSITY, BEIJING, CHINA.

E-mail: binguimath@gmail.com bingui@tsinghua.edu.cn