

AUTOTUNING NVCC COMPILER PARAMETERS IN THE JULIA LANGUAGE

Pedro Bruel and Alfredo Goldman

{phrb, gold}@ime.usp.br

August 24, 2017



Instituto de Matemática e Estatística
Universidade de São Paulo



The slides and all source code are hosted at [GitHub](#):

- `github.com/phrb/nvidia-workshop-autotuning`

1. Introduction to Autotuning
2. Examples & Results on Different Domains
3. An Autotuning Library in the Julia Language
4. NVCC Flag Autotuner

Casting program optimization as a **search problem**:

Search Spaces:

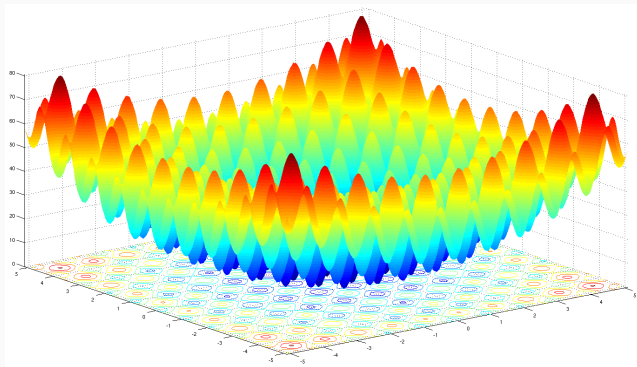
- Algorithm Selections
- Program Configurations
- ...

Search Objectives:

- Minimize **execution time**
- Maximize **usage of resources**
- ...

SEARCH SPACES & TECHNIQUES

The **search spaces** created by program optimization problems can be **difficult to explore**



Rastrigin function, with **global minimum** $f(0, 0) = 0$

SEARCH SPACES & TECHNIQUES

| System | Domain | Technique |
|----------------|----------------------|------------------------|
| ATLAS | Dense Linear Algebra | Exhaustive |
| Insieme | Compiler | Genetic Algorithm |
| SPIRAL | DSP Algorithms | Pareto Active Learning |
| Active Harmony | Runtime | Nelder-Mead |
| Periscope | HPC Applications | Various |
| OpenTuner | Domain-Agnostic | Ensemble |

Table 1: Some autotuning systems, their domains and techniques

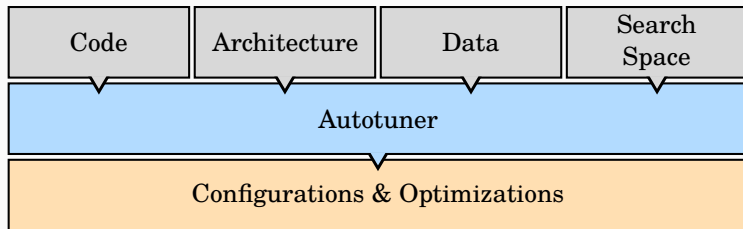
SEARCH SPACES & TECHNIQUES

| System | Domain | Technique |
|----------------|----------------------|------------------------|
| ATLAS | Dense Linear Algebra | Exhaustive |
| Insieme | Compiler | Genetic Algorithm |
| SPIRAL | DSP Algorithms | Pareto Active Learning |
| Active Harmony | Runtime | Nelder-Mead |
| Periscope | HPC Applications | Various |
| OpenTuner | Domain-Agnostic | Ensemble |

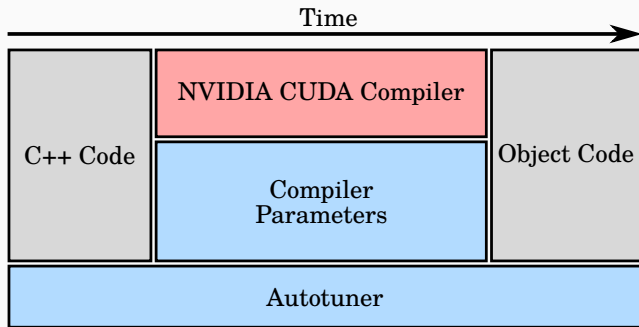
Table 1: Some autotuning systems, their domains and techniques

- Different **problem domains** generate different **search spaces**
- **No single solution** for all domains
- Search techniques can be composed: **OpenTuner**
- Independent searches can be **parallelized and distributed**

AUTOTUNING: ABSTRACT MODEL



NVIDIA CUDA COMPILER: FROM CUDA C++ TO OBJECT CODE



- We tuned applications from the [Rodinia Benchmark Suite](#)
- C++ → Object Code: takes [seconds](#)

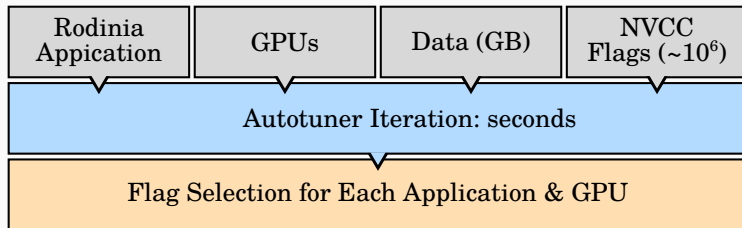
RESULTS

Flags in the [search space](#):

| <i>Flag</i> | <i>Step</i> |
|-------------------------|-------------|
| no-align-double | NVCC |
| use_fast_math | NVCC |
| gpu-architecture | NVCC |
| relocatable-device-code | NVCC |
| ftz | NVCC |
| prec-div | NVCC |
| prec-sqrt | NVCC |

| <i>Flag</i> | <i>Step</i> |
|-------------------------------|-------------|
| def-load-cache | PTX |
| opt-level | PTX |
| fmad | PTX |
| allow-expensive-optimizations | PTX |
| maxrregcount | PTX |
| preserve-relocs | NVLINK |

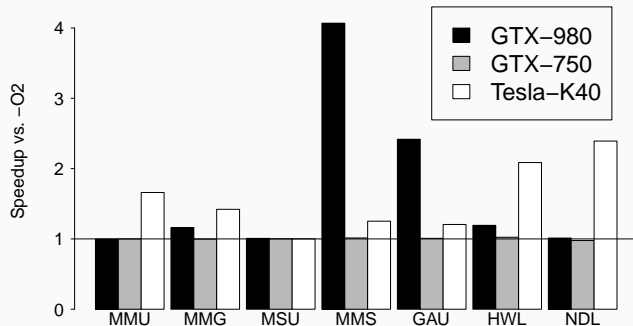
AUTOTUNING: GPUS



1h of tuning $\rightarrow \approx 10^3$ iterations

RESULTS

Most significant speedups for Rodinia applications and matrix multiplication optimizations, after 1.5h of tuning:



We found no globally good parameter selections for specific GPUs or applications



StochasticSearch

We are developing an autotuning library:

- In the [Julia](#) language
- [Domain-Agnostic](#)
- [Parallel and distributed autotuning](#)
- github.com/phrb/StochasticSearch.jl

Multiple [simultaneous search techniques](#) share a search space, but not results:

[Implemented](#) techniques:

- Simulated Annealing
- Iterated Local Search
- Randomized First Improvement
- Iterative First Improvement
- Iterative Probabilistic Improvement
- Iterative Greedy Construction

Multiple [simultaneous search techniques](#) share a search space, but not results:

[Implemented](#) techniques:

- Simulated Annealing
- Iterated Local Search
- Randomized First Improvement
- Iterative First Improvement
- Iterative Probabilistic Improvement
- Iterative Greedy Construction

[Future](#) techniques:

- Iterative Best Improvement
- Randomized Best Improvement
- Dynamic Local Search
- Tabu Search
- Ant Colony Optimization
- ...

WHY USE THE JULIA LANGUAGE?



Why the [Julia Language](#)?

- [High-Level abstractions](#)
- [Simple interface](#) for parallel and distributed programming
- [Better performance](#) than Python, Matlab, R, . . .

Parallel and Distributed programming:

- [Process-based](#) parallelism
- [Communication](#) between processes uses [channels](#)
- [Serialize/Deserialize](#) complex data types

Parallel and Distributed programming:

- [Process-based](#) parallelism
- [Communication](#) between processes uses [channels](#)
- [Serialize/Deserialize](#) complex data types
- Works on [many-core and clouds](#) using an MPI-like [machinefile](#)
- [No shared memory](#) yet, with [experimental native threading](#)

PARALLEL AND DISTRIBUTED PROGRAMMING IN JULIA

Parallel and Distributed programming:

- [Process-based](#) parallelism
- [Communication](#) between processes uses [channels](#)
- [Serialize/Deserialize](#) complex data types
- Works on [many-core and clouds](#) using an MPI-like [machinefile](#)
- [No shared memory](#) yet, with [experimental native threading](#)

Simple interface:

- [Remote execution](#) on a [new process](#): `remotecall(·)` and `@spawn`
- [Channels](#): `put!(·)` and `take!(·)`

STOCHASTICSEARCH EXAMPLE: THE ROSEN BROCK FUNCTION

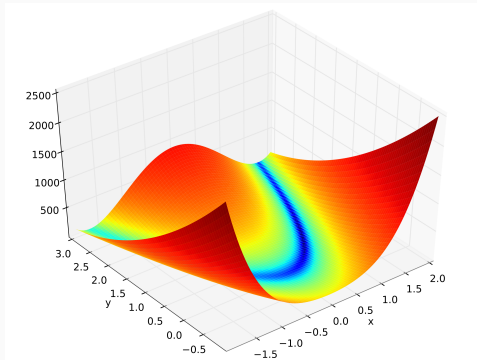
Let's create a [Tuning Run](#) using [StochasticSearch](#):

The Rosenbrock function:

- [Global minimum](#) $f(1, 1) = 0$
- Many [local minima](#)

Components:

- [Parameters](#)
- [Configurations](#)
- [Cost Function](#)



Parameters:

- Represent **individual optimizations**
- Determine **ranges** and **initial values**
- Integers, Booleans, Permutations, Strings, Enumerations, . . .

Parameters:

- Represent individual optimizations
- Determine ranges and initial values
- Integers, Booleans, Permutations, Strings, Enumerations, . . .

Example:

```
FloatParameter(-2.0, 2.0, 0.0, "i0")
```

Configurations:

- Contain parameters
- Describe the search space
- Associate optimizations with metrics

Configurations:

- Contain **parameters**
- Describe the **search space**
- Associate **optimizations** with **metrics**

Example:

```
configuration = Configuration([FloatParameter(-2.0, 2.0, 0.0, "i0"),  
                             FloatParameter(-2.0, 2.0, 0.0, "i1")],  
                             "rosenbrock_config")
```


Cost Function:

- Computes **costs** for each **configuration**
- **Costs** are usually expressed in **floating point values**

Cost Function:

- Computes **costs** for each **configuration**
- **Costs** are usually expressed in **floating point values**

Example:

```
function rosenbrock(x::Configuration, parameters::Dict{Symbol, Any})  
    return (1.0 - x["i0"].value)^2 + 100.0 * (x["i1"].value - x["i0"].value^2)^2  
end
```

Tuning Run:

- Selection of search techniques
- Duration & communication

STOCHASTICSEARCH: DEFINING SEARCH SPACES & TUNING RUNS

Tuning Run:

- Selection of [search techniques](#)
- [Duration](#) & [communication](#)

Example:

```
tuning_run = Run(cost           = rosenbrock,  
                 starting_point = configuration,  
                 stopping_criterion = elapsed_time_criterion,  
                 report_after    = 10,  
                 reporting_criterion = elapsed_time_reporting_criterion,  
                 duration        = 60,  
                 methods         = [[:simulated_annealing 1];  
                                   [[:iterated_local_search 1];  
                                   [[:randomized_first_improvement 1];]])
```

Short [practical examples](#) at `github.com/phrb/StochasticSearch.jl`:

- Rosenbrock
- Sorting Algorithm Cutoff
- Travelling Salesperson Problem
- [NVCC Flags](#)

AUTOTUNING NVCC COMPILER PARAMETERS IN THE JULIA LANGUAGE

Pedro Bruel and Alfredo Goldman

{phrb, gold}@ime.usp.br

August 24, 2017



Instituto de Matemática e Estatística
Universidade de São Paulo