...If you want to recreate elements of the rest of the post, you'll need the following packages installed:

```
## Packages
library('ggplot2')
library('tibble')
library('tidyr')
library('dplyr')
library('mgcv')
library('gratia')
library('patchwork')

## remotes::install_github("clauswilke/colorblindr")
library('colorblindr')
## remotes::install_github("clauswilke/relayer")
library('relayer')
```

The last two are used for plotting and the **relayer** package in particular is needed as I'm going to be using two separate colour scales on the plots. If you don't have these installed, you can install them using the **remotes** package and the code in commented lines above.

The example data set used in the comparsion had been posted to the preprint's GitHub repo, so it was easy to grab them and start playing with. To load the data into R we can use

```
load(url("https://bit.ly/gprocdata"))
ls()
[1] "f true"
```

where the Bitly short link just links to the <code>.Rdata</code> file stored on GitHub. This creates an object, <code>f_true</code>, in the workspace. We'll look at the true function in a minute. Following the preprint, a data set of noisy observations is simulated from the true function by adding Gaussian noise ($\mu = 0$, $\sigma = 0.2$)

```
seed <- 1234
set.seed(seed)
gp_data <- tibble(truth = unname(f_true), x = seq(-1, 1, by = 0.002))
%>%
    mutate(y = truth + rnorm(length(truth), 0, 0.2))
```

From that noisy set, we sample 250 observations at random, and indicate some of the observations as being in a test set that we won't use when fitting GAMs

Finally we visualize the true function and the noisy observations we sampled from it

```
ggplot(r_samp, aes(x = x, y = y, colour = data_set)) +
    geom_line(aes(y = truth, colour = NULL), show.legend = FALSE,
alpha = 0.5) +
    geom_point() +
    scale_colour_brewer(palette = "Set1", name = "Data set")
```

The true function and noisy observations drawn from it. The blue dots are the training observations that we'll use to fit models, while the red dots are test observations used to investigate how the models interpolate and extrapolate.

The red points are the test observations and will be used to look at the behaviour of the splines under interpolating and extrapolating conditions.

Thin Plate splines

Firstly, we'll look at how the thin plate splines behave under extrapolation, recreating the behaviour from the preprint. I start by fitting two GAMs where we use 50 basis functions (k=50) from the TPRS basis (bs = "tp"). The argument m controls the order of the derivative penalty; the default is m=2, for a second derivative penalty (penalising the curvature fo the spline). For the second model, we use m=1, indicating a penalty on the first derivative of the TPRS, which penalises deviations from a flat function. Note that we filter the sample of noisy data to include only the training observations.

I won't worry about looking at model diagnostics in this post, and instead skip to the looking at how these two models behave when we predict beyond the limits of the training data.

Next I define some new observations to predict at from the two models

```
new data <- tibble(x = seq(-1.5, 1.5, by = 0.002))
```

Remember the training data covered the interval -0.8–0.8, so we're extrapolating quite far proportionally from the support of the training data. Now we can predict from the two models

```
p_tprs2 <- as_tibble(predict(m_tprs2, new_data, se.fit = TRUE)) %>%
    rename(fit_tprs_2 = fit, se_tprs_2 = se.fit)
p_tprs1 <- as_tibble(predict(m_tprs1, new_data, se.fit = TRUE)) %>%
    rename(fit_tprs_1 = fit, se_tprs_1 = se.fit)
```

Note we have named the two columns of data with some information that we'll need for plotting, so the underscores are important.

Next we do some data wrangling to get the predictions into a tidy format suitable for plotting

The basic idea here is that we cast the data to a very general long-and-thin version and pull out variables indicating the type of value (fit = fitted and se = standard error), the type of spline, and the order of the penalty, by splitting on the underscore in each of the input columns. Then we cast the long-and-thin data frame to a slightly wider version where we have access to the fit and se variables, before calculating a 89% credible interval on the predicted values.

Now we can plot the data plus the predicted values

```
ggplot(mapping = aes(x = x, y = y)) +
```

```
geom_ribbon(data = new_data_tprs,
               mapping = aes(ymin = lwr_ci, ymax = upr_ci, x = x,
                             fill = order),
                inherit.aes = FALSE, alpha = 0.2) +
   geom point(data = r samp, aes(colour = data set)) +
   geom line(data = new data tprs, aes(y = fit, x = x, colour2 =
order),
              size = 1) %>%
   rename_geom aes(new_aes = c("colour" = "colour2")) +
   scale colour brewer(palette = "Set1", aesthetics = "colour",
                        name = "Data set") +
   scale_colour_OkabeIto(aesthetics = "colour2", name = "Penalty") +
   scale_fill_OkabeIto(name = "Penalty") +
   coord cartesian(ylim = c(-2, 2)) +
   labs(title = "Extrapolating with thin plate splines",
         subtitle = "How behaviour varies with derivative penalties of
different order")
```

Posterior predictive means for the two thin plate regression spline models showing the interpolation and extrapolation behaviour with first and second derivative penalties.

With the default, second derivative penalty we see that under extrapolation, the spline exhibits linear behaviour. For the first derivative penalty model, the behaviour is to predict a constant value. The credible intervals are also unrealistically narrow in the case of the TPRS model with the first derivative penalty. Neither does a particularly good job of estimating any of the test samples outside the range of x in the training data. The models do better when interpolating, except for the section around x = 0.5.

B splines

OK. What about B splines? With the B spline constructor in **mgcv** we have a lot of control over how we set up the basis and the wiggliness penalty. We'll look at more of these options later, but first, we'll look at the default behaviour where the penalty only operates over the range of the training observations.

Here we asked for a cubic B spline with a second order penalty — this is your common or garden cubic B spline where the wigglines penalty over covers the range of *x* in the training data. Ignore the warning; this is just because we have many functions and some aren't supported by any of the data because of the holes due to the test observations.

If we want to have the penalty extend some way beyond the range of x, we need to pass in a set of end points over which knots will be defined. We need to specify the two extreme end points that enclose the region we want to predict over, and two interior knots that cover the range of the data, plus a little. We specify these knots below

```
knots <- list(x = c(-2, -0.9, 0.9, 2))
```

and then pass ${\tt knots}$ to the ${\tt knots}$ argument when fitting the model

```
m_bs_extrap <- gam(y \sim s(x, k = 50, bs = "bs", m = c(3, 2)), method = "REML", data = filter(r_samp, data_set == "train"), knots = knots)
```

```
Warning in smooth.construct.bs.smooth.spec(object, dk$data, dk$knots): there is *no* information about some basis coefficients
```

The only difference here is how we have specified we want the penalty to extend away from the limits of the training observations. You'll get another warning here. This will always happen when you set outer knots beyond the range of the data; it is harmless.

We can visualize the differences in the bases using basis () from the gratia package

Cubic B spline bases with knots covering the range of training observations (A) and with outer knots covering the range of the training data plus the region where we want to extrapolate. Using the outer knots has the effect of extending the wigliness penalty over the region we want to predict for. The dashed lines are drawn at x = -0.8 and x = 0.8, the limits of the training observations.

Technically, the basis functions in the top panel would extend a little into the prediction region, but basis () can't yet handle using one data set to set up the basis and another at which to evaluate it. Because we have basis functions extending over the interval for prediction, the wiggliness penalty can apply in this region too.

Now we predict from both the models as before and repeat the data wrangling

The only difference here is that I encoded in the variable names whether we used the default penalty or the one extended beyond the limits of the data. We plot the fits with

Posterior predictive means for the two B spline models showing the interpolation and extrapolation behaviour when the penalty over covers the range of the data and when it extends by ond that range.

As both these models used second derivative penalties, they both extrapolate linearly beyond the range of the training observations. Importantly however, we get very different behaviour of the credible intervals, especially at the low end of x, where the wide interval is a better representation of the uncertainty that we have in the extrapolated predictions. This is better behaviour, as at least we're being honest about the uncertainty when extrapolating.

Comparing different bases

So far, so uninteresting. Before we get to the good stuff and demonstrate other features of the B spline basis in *mgcv*, let's just quickly compare the TPRS and B spline models with a Gaussian process smooth that is designed to closesly match the data generating function. Note that this GP is fitted using **mgcv** where we have to specify the length scale, and as such isn't meant to be directly comparable with either the exact or the low-rank GP models of Riutort-Mayol et al. (2020).

In **mgcv** a GP can be fit using bs = "gp". When we do this, the meaning of the m argument changes. Here we are asking for a Matérn covariance function with v = 3/2 and length scale of 0.15. These values were chosen to match those of the true function.

```
m_gp \leftarrow gam(y \sim s(x, k = 50, bs = "gp", m = c(3, 0.15)), data = filter(r_samp, data_set == "train"), method = "REML")
```

Again we have some wrangling to do to pull all these together into an object we can plot easily

And finally we plot using

Posterior predictive means for three GAMs; a thin plate spline with 2nd derivative penalty, a B spline with 2nd derivative penalty extended over the interval for prediction, and a Gaussian process with a Matérn(v = 3/2) covariance function with length scale = 0.15

Clearly the GP gets closer to the test data when extrapolating, but that's not really a fair comparison as I told the model what the correct length scale was! We could try to estimate that from the data, by fitting models over a grid of likely values for the length scale parameter and using the model with the lowest REML score, but I won't show how to do that here; I have example code in the supplements for Simpson (2018) showing how to do this is you're keen.

More with B splines

We're not restricted to using the second derivative penalty with B splines; we can use third, second, first or even zeroth order penalties with cubic B splines. How does their behaviour vary when interpolating and extrapolating?

For convenience I'll just fit all three models with a common format, even though we've already seen and fitted the first model with the second derivative penalty. Notice how we specify the order of the derivative penalty by passing a second value to the argument m; m=1 is a first derivative penalty, m=0 a zeroth derivative penalty, etc.

Again we repeat the data wrangling need to get something we can plot

```
p_bs_2 <- as_tibble(predict(m_bs_2, new_data, se.fit = TRUE)) %>%
    rename(fit_bs_2 = fit, se_bs_2 = se.fit)

p_bs_1 <- as_tibble(predict(m_bs_1, new_data, se.fit = TRUE)) %>%
    rename(fit_bs_1 = fit, se_bs_1 = se.fit)

p_bs_0 <- as_tibble(predict(m_bs_0, new_data, se.fit = TRUE)) %>%
    rename(fit_bs_0 = fit, se_bs_0 = se.fit)

new_data_order <- bind_cols(new_data, p_bs_2, p_bs_1, p_bs_0) %>%
```

Note again how I'm defining the names of the columns containing fitted values and their standard errors to make it easy to pull out this data during the pivot longer() step.

We plot the predicted values with

```
qqplot(mapping = aes(x = x, y = y)) +
    geom ribbon(data = new_data_order,
               mapping = aes(ymin = lwr ci, ymax = upr ci, x = x,
fill = order),
                inherit.aes = FALSE, alpha = 0.2) +
    geom point(data = r samp, aes(colour = data set)) +
    geom line(data = new data order, aes(y = fit, x = x, colour2 =
order),
             size = 1) %>%
    rename geom aes(new aes = c("colour" = "colour2")) +
    scale colour_brewer(palette = "Set1", aesthetics = "colour", name
= "Data set") +
   scale colour OkabeIto(aesthetics = "colour2", name = "Penalty") +
    scale fill OkabeIto(name = "Penalty") +
    coord cartesian(ylim = c(-2, 2)) +
    labs(title = "Extrapolating with B splines",
         subtitle = "How behaviour varies with penalties of different
order")
```

Posterior predictive means for three GAMs using B splines with different orders of derivative penalty, all covering the region where we want to predict for the test samples; a B spline with 2nd derivative penalty, a B spline with 1st derivative penalty, and a B spline with zeroth derivative penalty.

The plot shows the different penalties leading to quite a wide range of behaviour. The spline with the zeroth order penalty interpolates poorly, seemingly heading towards the overall mean of the data during each of the test section within the range of x. When extrapolating, we again see this "mean reversion" behaviour, which means it does well when extrapolating for large values of x, but it does extremely poorly at the low end of x. The credible intervals for this model are also unrealistically narrow, like those of the TPRS model with 1st derivative penalty that we saw earlier on.

The model with the first derivative penalty has reaonable behaviour; it extrapolates as largely a flat function continuing from the min and maximum values of x, as with the TPRS fit with a first derivative penalty we saw above, but the credible intervals are much more realistic for the B spline than for the TPRS. Note also that the intervals for the B spline with the first derivative penalty don't explode as quickly as those for the B spline fit with the second derivative penalty.

Multiple penalties

One final trick that the B spline basis in **mgcv** has up its sleve is that you can combine multiple penalties in a single spline. We could fit cubic B splines with one, two, three, or even four penalties. The additional penalties are specified by passing more values to m: m = c(3, 2, 1) would be a cubic B spline with both a second derivative and a first derivative penalty, while m = c(3, 2, 1, 0) would get you a cubic spline with all three penalties. You can mix and match as much as you like with a couple of exceptions:

- you can only have one penalty for each order, so no, you can't penalise one of the derivative more stringly by adding more than one penalty for it; m = c(3, 2, 1) for example isn't allowed, and
- you can only have values for m[i] (where i > 1) that exist for the given order of B spline, i.e. where

```
m[i] \leq m[1].
```

In the code below I fit two additional models with mixtures of penalties, and then compare these with the default second derivative penalty (fitted earlier). In each case, I'm again using the knots argument to extend the penalties over the range we might want to predict over.

Again, we do the same wrangling, this time encoding the mixtures of orders in the column names

The last step here uses <code>case_when()</code> to write out nicer formatting for the penalties, so we get a nicer legend on the plot, which we produce with

```
ggplot(mapping = aes(x = x, y = y)) +
    geom ribbon(data = new data multi,
                mapping = aes(ymin = lwr ci, ymax = upr ci, x = x,
fill = penalty),
                inherit.aes = FALSE, alpha = 0.2) +
    geom point(data = r_samp, aes(colour = data_set)) +
    geom_line(data = new_data_multi, aes(y = fit, x = x, colour2 =
penalty),
              size = 1) %>%
    rename geom aes(new aes = c("colour" = "colour2")) +
    scale_colour_brewer(palette = "Set1", aesthetics = "colour", name
= "Data set") +
    scale colour OkabeIto(aesthetics = "colour2", name = "Penalty") +
    scale fill OkabeIto(name = "Penalty") +
    coord cartesian(ylim = c(-2, 2)) +
    labs(title = "Extrapolating with B splines",
         subtitle = "How behaviour changes when combining multiple
```

penalties")

Posterior predictive means for three GAMs using B splines with mixtures of derivative penalties, all covering the region where we want to predict for the test samples; a B spline with single 2nd derivative penalty, a B spline with a 2nd and 1st derivative penalties, and a B spline with 2nd, 1st and 0th derivative penalties.

By mixing the penalties, we mix some of the behaviour features. For example, the weird interpolation behaviour of the B spline with zeroth derivative penalty is essentially removed when combined with second and first derivative penalties.

Given the data, the predictions that essentially predict constant functions beyond the range of the data, but with wide credible intervals are probably the most realistic; in each case where we used a B spline that included a first derivative penalty has at least covered most of the test observation beyond the range of *x*.

However, in none of the fits do we get behaviour that get close to fitting the test observations beyond the training of *x* in the training data, even when using a Gaussian process that supposedly matches at least the general form of the true function.