


```

# Simulation of the factor x
x <- ESGtoolkit::simdiff(n = n, horizon = horizon,
                        frequency = freq,
                        model = "OU",
                        x0 = 0, theta1 = 0, theta2 = a_opt, theta3 = sigma_opt,
                        eps = eps[[1]])

# Simulation of the factor y
y <- ESGtoolkit::simdiff(n = n, horizon = horizon,
                        frequency = freq,
                        model = "OU",
                        x0 = 0, theta1 = 0, theta2 = b_opt, theta3 = eta_opt,
                        eps = eps[[2]])

# Instantaneous forward rates, with spline interpolation
methodyc <- match.arg(methodyc)
fwdrates <- ESGtoolkit::esgfwdrates(n = n, horizon = horizon,
out.frequency = freq, in.maturities = u,
in.zerorates = txZC, method = methodyc)
fwdrates <- window(fwdrates, end = horizon)

# phi
t.out <- seq(from = 0, to = horizon,
            by = delta_t)
param.phi <- 0.5*(sigma_opt^2)*(1 - exp(-a_opt*t.out))^2/(a_opt^2) +
0.5*(eta_opt^2)*(1 - exp(-b_opt*t.out))^2/(b_opt^2) +
(rho_opt*sigma_opt*eta_opt)*(1 - exp(-a_opt*t.out))*
(1 - exp(-b_opt*t.out))/(a_opt*b_opt)
param.phi <- ts(replicate(n, param.phi),
                start = start(x), deltat = deltat(x))
phi <- fwdrates + param.phi
colnames(phi) <- c(paste0("Series ", 1:n))

# The short rates
r <- x + y + phi
colnames(r) <- c(paste0("Series ", 1:n))

return(r)
}

```

Simulations of G2++ for 4 types of parameters' sets:

```

r.HCSPL <- simG2plus(n = 10000, methodyc = "HCSPL", seed=123)

r.HCSPL2 <- simG2plus(n = 10000, methodyc = "HCSPL", seed=2020)

r.HCSPL3 <- simG2plus(n = 10000, methodyc = "HCSPL", seed=123,
                    randomize_params=TRUE)

r.HCSPL4 <- simG2plus(n = 10000, methodyc = "HCSPL", seed=123,
                    b_opt=1, rho_opt=0, eta_opt=0,
                    randomize_params=FALSE)

```

Stochastic discount factors derived from short rates simulations:

```

deltat_r <- deltat(r.HCSPL)

Dt.HCSPL <- ESGtoolkit::esgdiscountfactor(r = r.HCSPL, X = 1)

```

```

Dt.HCSPL <- window(Dt.HCSPL, start = deltat_r, deltat = 2*deltat_r)

Dt.HCSPL2 <- ESGtoolkit::esgdiscountfactor(r = r.HCSPL2, X = 1)
Dt.HCSPL2 <- window(Dt.HCSPL2, start = deltat_r, deltat = 2*deltat_r)

Dt.HCSPL3 <- ESGtoolkit::esgdiscountfactor(r = r.HCSPL3, X = 1)
Dt.HCSPL3 <- window(Dt.HCSPL3, start = deltat_r, deltat = 2*deltat_r)

Dt.HCSPL4 <- ESGtoolkit::esgdiscountfactor(r = r.HCSPL4, X = 1)
Dt.HCSPL4 <- window(Dt.HCSPL4, start = deltat_r, deltat = 2*deltat_r)

```

Prices (*observed* vs Monte Carlo for previous 4 examples):

```

# Observed market prices
horizon <- 20
marketprices <- p[1:horizon]

# Monte Carlo prices
## Example 1
montecarloprices.HCSPL <- rowMeans(Dt.HCSPL)
## Example 2
montecarloprices.HCSPL2 <- rowMeans(Dt.HCSPL2)
## Example 3
montecarloprices.HCSPL3 <- rowMeans(Dt.HCSPL3)
## Example 4
montecarloprices.HCSPL4 <- rowMeans(Dt.HCSPL4)

```

Plots *observed* prices vs Monte Carlo prices:

```

par(mfrow=c(4, 2))

ESGtoolkit::esgplotbands(r.HCSPL, xlab = 'time', ylab = 'short rate',
                        main="short rate simulations \n for example 1")
plot(marketprices, col = "blue", type = 'l',
     xlab = "time", ylab = "prices", main = "Prices for example 1 \n (observed
vs Monte Carlo)")
points(montecarloprices.HCSPL, col = "red")

ESGtoolkit::esgplotbands(r.HCSPL2, xlab = 'time', ylab = 'short rate',
                        main="short rate simulations \n for example 2")
plot(marketprices, col = "blue", type = 'l',
     xlab = "time", ylab = "prices", main = "Prices for example 2 \n (observed
vs Monte Carlo)")
points(montecarloprices.HCSPL2, col = "red")

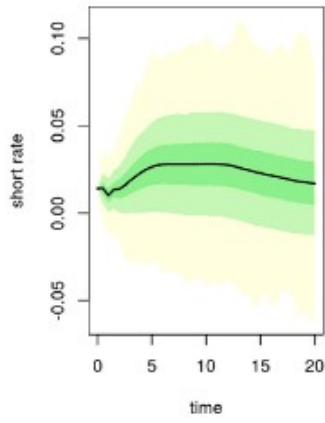
ESGtoolkit::esgplotbands(r.HCSPL3, xlab = 'time', ylab = 'short rate',
                        main="short rate simulations \n for example 3")
plot(marketprices, col = "blue", type = 'l',
     xlab = "time", ylab = "prices", main = "Prices for example 3 \n (observed
vs Monte Carlo)")
points(montecarloprices.HCSPL3, col = "red")

ESGtoolkit::esgplotbands(r.HCSPL4, xlab = 'time', ylab = 'short rate',
                        main="short rate simulations \n for example 4")
plot(marketprices, col = "blue", type = 'l',
     xlab = "time", ylab = "prices", main = "Prices for example 4 \n (observed
vs Monte Carlo)")

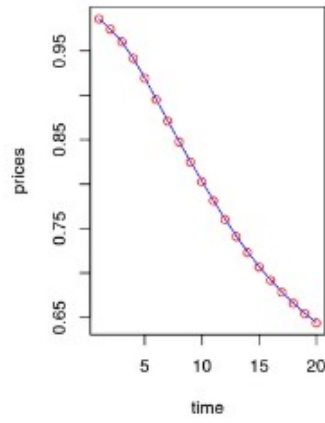
```

```
points(montecarloprices.HCSPL4, col = "red")
```

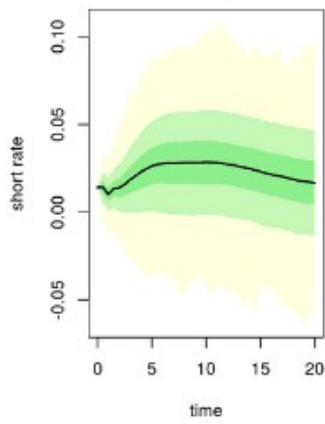
**short rate simulations
for example 1**



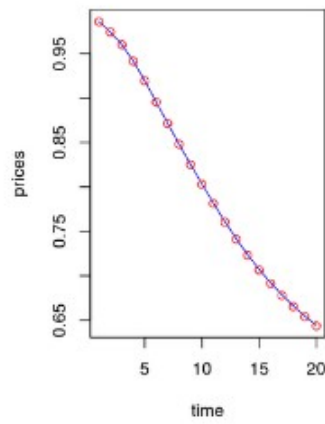
**Prices for example 1
(observed vs Monte Carlo)**



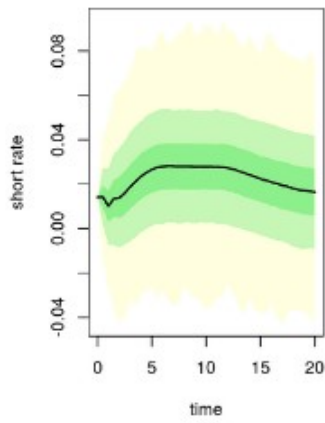
**short rate simulations
for example 2**



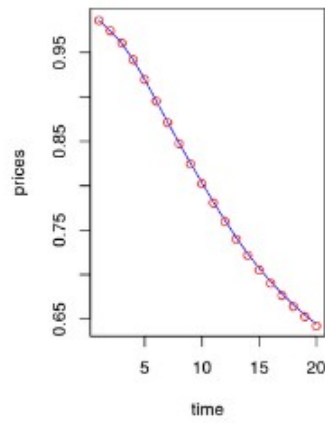
**Prices for example 2
(observed vs Monte Carlo)**



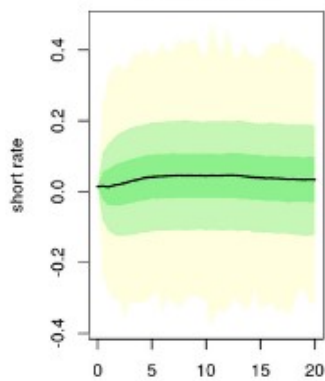
**short rate simulations
for example 3**



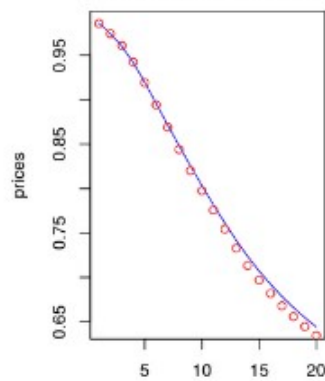
**Prices for example 3
(observed vs Monte Carlo)**



**short rate simulations
for example 4**



**Prices for example 4
(observed vs Monte Carlo)**



What do we **observe** on these graphs, both on simulations and prices? What will happen if we add a **third factor** to this model, meaning, three more parameters; a G3++/any other *hydra*?

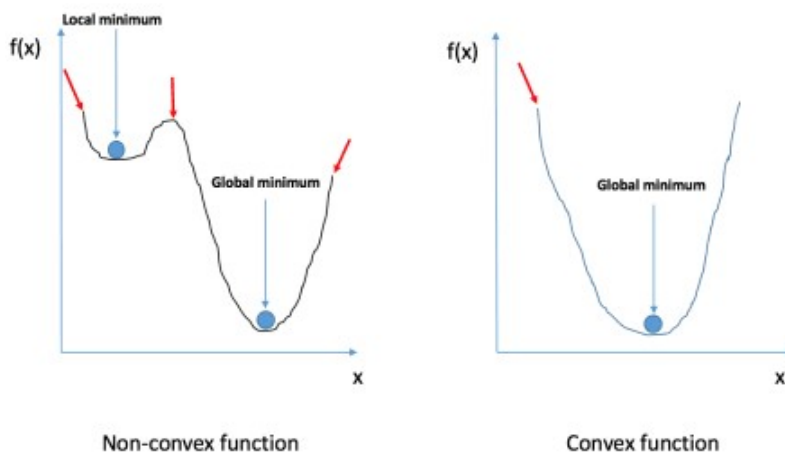
Optimization in Deep learning neural networks

On a different type of question/problem, but still on the subject of model specification, identification, degrees of freedom and regularization: **Deep learning neural networks**. Some people suggest that if you keep adding parameters (degrees of freedom?) to these models, you'll **still obtain a good generalization**. Well, there's this picture that I like a lot:



Source: <https://towardsdatascience.com/optimizers-be-deeps-appetizers-511f3706aa67>

When we optimize the loss function in Deep learning neural networks models, we are most likely using [gradient descent](#), which is **fast and scalable**. Still, no matter how sophisticated the gradient descent procedure we're using, we will likely get stuck into a local minimum – because the loss function is rarely convex.



Stuck is a rather unfortunate term here, because it's not an actual problem, but instead, an indirect way to avoid [overtraining](#). Also, in our gradient descent procedure, we tune the number of epochs (number of iterations in the descent/ascent), the learning rate (how fast we roll in the descent/ascent), in addition to the dropout (randomly dropping out some nodes in networks' layers), etc. These are also ways to **avoid learning too much, to stop the optimization relatively early, and preserve the model's ability to generalize**. They regularize the model, whereas the millions of network nodes serve as degrees of freedom. This is a different problem than the first one we examined, with different objectives, but... still on the subject of model specification, identification, degrees of freedom and regularization.