Dynamics II Plan

George
Identify material
Acquire material
Construct prototype
Weigh each link, measure thickness - density

Chris
Design test stand
Design servo horns
Use density and SW - Mass and Inertia properties

Lien
Identify motor/servo
Motor mount (to test stand)

Future:

Link stiffness
Joint stiffness
Joint damping

Actuator modeling
Input signal
Aerodynamics