Chapter 11: Vector Spaces, Span, and Basis (Part II)

1. Verify that the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1\\1\\1 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 1\\-1\\2 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1\\1\\0 \end{pmatrix}$$

are mutually orthogonal.

2. Are the above vectors orthonormal?

3. Make the vectors v_1 , v_2 , and v_3 into an orthonormal set.

4. Are the vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ a basis for \mathbb{R}^3 ? How about the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

5. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix}$$

onto the basis vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$.

6. Given vectors

$$\mathbf{x}_1 = \begin{pmatrix} -2\\1 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} 1\\1 \end{pmatrix}$$

calculate the vector that is the projection of x_2 onto x_1 .

7. Using your answer to Question 6, find a vector nearest to x_2 that is orthogonal to x_1 .

8. Challenge: Look back at our proof of the theorem for decomposing a vector over an orthonormal basis using dot products. Can we use dot products to decompose over a basis where all vectors are orthogonal but not normalized?

Solutions

1. Verify that the vectors

$$\mathbf{v}_1 = \begin{pmatrix} -1\\1\\1 \end{pmatrix}, \mathbf{v}_2 = \begin{pmatrix} 1\\-1\\2 \end{pmatrix}, \mathbf{v}_3 = \begin{pmatrix} 1\\1\\0 \end{pmatrix}$$

are mutually orthogonal.

The vectors are mutually orthogonal if every vector is orthogonal to every other vector. We can check orthogonality by computing dot products.

$$\mathbf{v}_1 \cdot \mathbf{v}_2 = (-1)(1) + (1)(-1) + (1)(2) = 0$$

$$\mathbf{v}_1 \cdot \mathbf{v}_3 = (-1)(1) + (1)(1) + (1)(0) = 0$$

$$\mathbf{v}_2 \cdot \mathbf{v}_3 = (1)(1) + (-1)(1) + (2)(0) = 0$$

2. Are the above vectors orthonormal?

We know the vectors are mutually orthogonal. For the vectors to be an orthonormal set, every vector needs to be a unit vector.

$$\|\mathbf{v}_1\| = \sqrt{(-1)^2 + 1^2 + 1^2} = \sqrt{3} \neq 1$$

$$\|\mathbf{v}_2\| = \sqrt{1^2 + (-1)^2 + (2)^2} = \sqrt{6} \neq 1$$

$$\|\mathbf{v}_3\| = \sqrt{1^2 + 1^2 + 0^2} = \sqrt{2} \neq 1$$

None of the vectors are unit vectors. We knew the vectors were not an orthonormal set after computing the first magnitude.

3. Make the vectors v_1 , v_2 , and v_3 into an orthonormal set.

We showed that the three vectors are mutually orthogonal. All that remains is to normalize each vector by dividing by its magnitude.

$$\hat{\mathbf{v}}_1 = (1/\sqrt{3})\mathbf{v}_1$$

$$\hat{\mathbf{v}}_2 = (1/\sqrt{6})\mathbf{v}_2$$

$$\hat{\mathbf{v}}_3 = (1/\sqrt{2})\mathbf{v}_3$$

4. Are the vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ a basis for \mathbb{R}^3 ? How about the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 ?

A basis in \mathbb{R}^3 requires three vectors. The vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$ are mutually orthogonal, so they are also linearly independent (see the beginning of § 11.5). Any three linearly independent vectors form a basis in \mathbb{R}^3 . This argument requires only that the vectors be mutually orthogonal, not orthonormal, so the vectors \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 also form a basis in \mathbb{R}^3 .

5. Decompose the vector

$$\mathbf{u} = \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix}$$

onto the basis vectors $\hat{\mathbf{v}}_1$, $\hat{\mathbf{v}}_2$, and $\hat{\mathbf{v}}_3$.

We are looking for coefficients a_1 , a_2 , and a_3 such that

$$\mathbf{u} = a_1 \hat{\mathbf{v}}_1 + a_2 \hat{\mathbf{v}}_2 + a_3 \hat{\mathbf{v}}_3$$

Our basis is orthonormal so we can apply the shortcut formula using dot

products.

$$a_{1} = \mathbf{u} \cdot \hat{\mathbf{v}}_{1}$$

$$= \begin{pmatrix} 3\\4\\-2 \end{pmatrix} \cdot \frac{1}{\sqrt{3}} \begin{pmatrix} -1\\1\\1 \end{pmatrix}$$

$$= (-3 + 4 - 2)/\sqrt{3} = -1/\sqrt{3}$$

$$a_{2} = \mathbf{u} \cdot \hat{\mathbf{v}}_{2}$$

$$= \begin{pmatrix} 3\\4\\-2 \end{pmatrix} \cdot \frac{1}{\sqrt{6}} \begin{pmatrix} 1\\-1\\2 \end{pmatrix}$$

$$= (3 - 4 - 4)/\sqrt{6} = -5/\sqrt{6}$$

$$a_{3} = \mathbf{u} \cdot \hat{\mathbf{v}}_{3}$$

$$= \begin{pmatrix} 3\\4\\-2 \end{pmatrix} \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\1\\0 \end{pmatrix}$$

$$= (3 + 4 + 0)/\sqrt{2} = 7/\sqrt{2}$$

We can confirm that

$$a_{1}\hat{\mathbf{v}}_{1} + a_{2}\hat{\mathbf{v}}_{2} + a_{3}\hat{\mathbf{v}}_{3}$$

$$= -\frac{1}{\sqrt{3}} \times \frac{1}{\sqrt{3}} \begin{pmatrix} -1\\1\\1\\1 \end{pmatrix} - \frac{5}{\sqrt{6}} \times \frac{1}{\sqrt{6}} \begin{pmatrix} 1\\-1\\2 \end{pmatrix} + \frac{7}{\sqrt{2}} \times \frac{1}{\sqrt{2}} \begin{pmatrix} 1\\1\\0 \end{pmatrix}$$

$$= -\frac{1}{3} \begin{pmatrix} -1\\1\\1 \end{pmatrix} - \frac{5}{6} \begin{pmatrix} 1\\-1\\2 \end{pmatrix} + \frac{7}{2} \begin{pmatrix} 1\\1\\0 \end{pmatrix}$$

$$= \begin{pmatrix} 3\\4\\-2 \end{pmatrix} = \mathbf{u}$$

6. Given vectors

$$\mathbf{x}_1 = \begin{pmatrix} -2\\1 \end{pmatrix}, \quad \mathbf{x}_2 = \begin{pmatrix} 1\\1 \end{pmatrix}$$

calculate the vector that is the projection of x_2 onto x_1 .

$$\operatorname{proj}_{\mathbf{x}_{1}}(\mathbf{x}_{2}) = \frac{\mathbf{x}_{2} \cdot \mathbf{x}_{1}}{\mathbf{x}_{1} \cdot \mathbf{x}_{1}} \mathbf{x}_{1}$$

$$= \frac{1 \times -2 + 1 \times 1}{-2 \times -2 + 1 \times 1} \mathbf{x}_{1}$$

$$= \begin{pmatrix} 2/5 \\ -1/5 \end{pmatrix}$$

7. Using your answer to Question 6, find a vector nearest to x_2 that is orthogonal to x_1 .

The vector $\mathbf{x}_2 - \text{proj}_{\mathbf{x}_1}(\mathbf{x}_2)$ is orthogonal to the vector \mathbf{x}_1 .

$$\mathbf{x}_2 - \operatorname{proj}_{\mathbf{x}_1}(\mathbf{x}_2) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2/5 \\ -1/5 \end{pmatrix}$$
$$= \begin{pmatrix} 3/5 \\ 6/5 \end{pmatrix}$$

To verify, we compute the dot product between our new vector and x_1 .

$$\binom{3/5}{6/5} \cdot \binom{-2}{1} = -6/5 + 6/5 = 0$$

8. Challenge: Look back at our proof of the theorem for decomposing a vector over an orthonormal basis using dot products. Can we use dot

products to decompose over a basis where all vectors are orthogonal but not normalized?

We use the normality of the vectors after we show that

$$\mathbf{u} \cdot \hat{\mathbf{v}}_i = a_i \hat{\mathbf{v}}_i \cdot \hat{\mathbf{v}}_i = a_i \|\hat{\mathbf{v}}_i\|^2$$

If the basis vectors were orthogonal but not normalized, we would instead have

$$\mathbf{u} \cdot \mathbf{v}_i = a_i \mathbf{v}_i \cdot \mathbf{v}_i = a_i \|\mathbf{v}_i\|^2$$

Here we are unable to assume that $\|\mathbf{v}_i\|^2 = 1$ since \mathbf{v}_i is not a normal vector. But we can still solve for the coefficient a_i .

$$a_i = (\mathbf{u} \cdot \mathbf{v}_i) / ||\mathbf{v}_i||^2$$

The above formula uses only a dot product and a norm to compute each coefficient. These are far easier calculations than solving the linear system Va = u for non-orthogonal basis vectors. The power of orthonormal basis vectors comes from their orthogonality, not their normality.