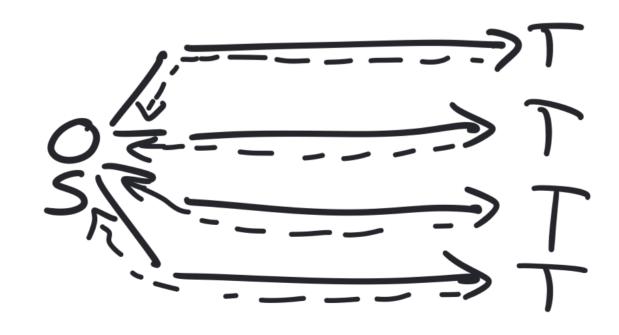
Function Approximation
BLOE 498/598

Value functions vs. Policies Policy: TT(s) -> a Difficult to Engineer from Scratch. - Value functions are often more important than policies. - We can 'lasily' construct TT from V.

- It's Easy to come up with a starting policy.

| How Do | res Alpha Go | work? | | | | |
|--------|--------------|-----------|------|--------|-----|----|
| | n with a | | | | | |
| | 1 -> VTh | | | | | |
| Kno | wladge Snao | lient" is | Valy | flat i | for | Go |
| | XIO | | | | | |

Monte Carlo true scarch.



RL for AlphaGo

Alpha Go Zerzo No human policy

Why was Go so hard? The state space is smormous. Go is 19×19 grid. Each square can have no, black, or white stones => # of possible states is 3 192 > Evseything V(s) -> SRi STT choose the best action for sweey state

=> Function Approximention.

Aetificial Neural Networks

-ANN is an "overefitted" linear model with a nonlinearly transformed rusponse.

$$\frac{X \rightarrow AX + b \rightarrow y \rightarrow z}{\mathbb{R}^{p}}$$

In AlphaGo: V(s) is a deep NN TT(s) 15 also a deep NN 5->[m)->...->[m]->a The Value function 15 king. Rad-world R2. - Self-obriving Cars
- Chat bots - "Play" 15 Expensive. - How do we construct V(s) from minimal data?