right_arm 35c_2.15us

		MIN	MAX	REST	
0	shoulder_0	675/1.94	2400/1.94	800	001
1	shoulder_1	1050/ -0.77 $^{x/2}$ [11-1]	~~2025~~ 2025/ (0.7)	1925	00-1
2	shoulder_2	1150/1.94	1825/1.94	1500	001
3	elbow	1200/1.53	1925/ 2.54	1500	001
4	wrist_0	700/1.45	2400/1.6	1500	
5	wrist_1	600/1.75	2125/1.0	1500	

Modify control. (diff. yaml)
 ↳ check motor mode
 ↳ Aus for MX-64 AR

CCW

~~roslaunch~~ my_dynamixel_tutorial controller_manager.launch
~~roslaunch~~ " " start_hand_controller.launch

	color
1	black
2	brown
3	red
4	orange
5	yellow
6	green
7	blue
8	purple
9	grey

B

	Pin color
1	red
2	yellow
3	orange
4	white
5	green
6	blue
7	grey
8	brown
9	black

Pins	1	2
brown		2-3
red	orange	3-c
orange	yellow	4-6+1
yellow	blue/red	
green	green	5-5
green+black	white	6+1-4
blue	brown	
purple	grey	8-7
grey	purple	9-n/c
	grey	

Pumpkin Analog

Pin	MAX	Min
0	922	225
1	~~700~~ ~~800~~ 708 665	348
2	623	378
3	655	400
4	875	152
5	739	178
6	892	203
7	688	383 11 326
8	626	390
9	592	339
10	888	177
11	872	152