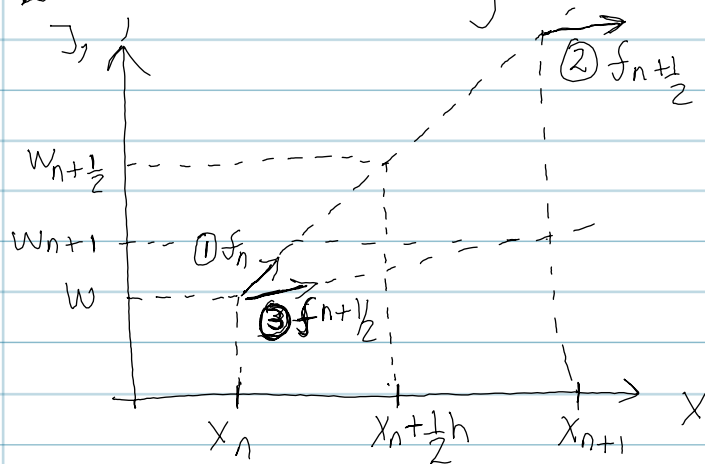


## 2<sup>ND</sup> Order Runge-Kutta Method

15-1



$$K_1 = h f(X_n, w_n)$$

→ slope at  $X_n$

$$K_2 = h f(X_n + 1/2 h, w_n + 1/2 K_1)$$

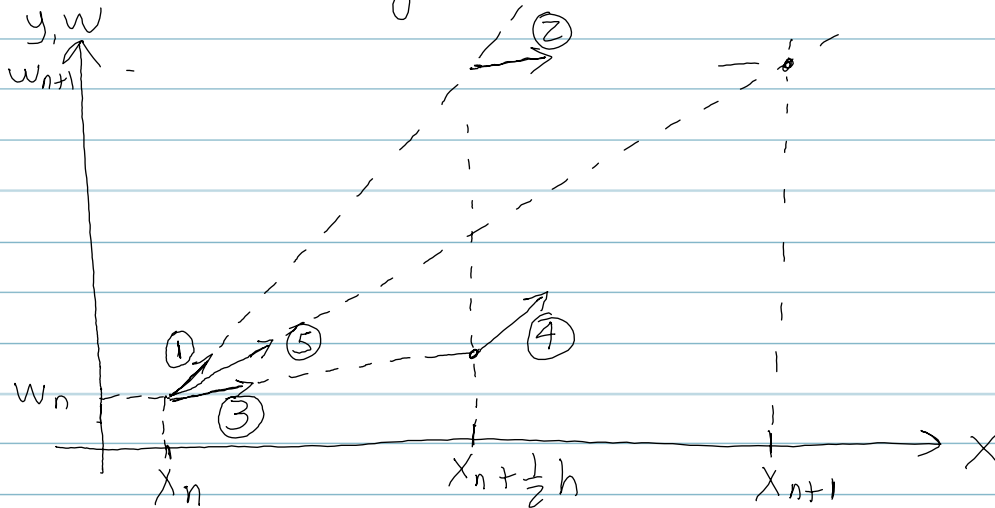
→ slope at midpoint

$$w_{n+1} = w_n + K_2$$

$$\tau = O(h^2)$$

2<sup>ND</sup> order Runge-Kutta

## 4<sup>TH</sup> Order Runge-Kutta



$$K_1 = h f(X_n, w_n)$$

$$K_2 = h f(X_n + 1/2 h, w_n + 1/2 K_1)$$

$$K_3 = h f(X_n + 1/2 h, w_n + 1/2 K_2)$$

$$K_4 = h f(X_n + h, w_n + K_3)$$

$$w_{n+1} = w_n + \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

$$\tau = O(h^4)$$

15-2

Runge-Kutta 4<sup>th</sup> order uses the weighted average of the  $K$ 's to project to the next approximate  $W_{n+1}$ . 4<sup>th</sup> order R-K can be derived from Simpson's Rule for ~~xxxx~~ numerical quadrature.



$$\int_a^b f(x) dx \approx \frac{b-a}{3N} \left[ f(x_0) + 4f(x_1) + 2f(x_2) + 4f(x_3) + 2f(x_4) + \dots + 4f(x_{n-1}) + f(x_n) \right]$$

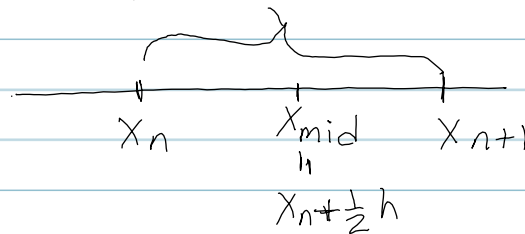
Let  $N=2$ . Then,

$$\int_a^b f(x) dx \approx \frac{b-a}{6} \left[ f(x_0) + 4f(x_1) + f(x_2) \right]$$

Back to  $\frac{dy}{dx} = f(x, y)$ , suppose that  $f$  depends on  $x$  only, so  $\frac{dy}{dx} = f(x)$ . Integrate over  $[x_n, x_{n+1}]$ :

$$y_{n+1} - y_n = \int_{x_n}^{x_{n+1}} f(x) dx$$

Approximate with Simpson's rule ( $N=2$ )



$$\Rightarrow \int_{x_n}^{x_{n+1}} f(x) dx \approx \frac{h}{6} [f(x_n) + 4f(x_{\text{mid}}) + f(x_{n+1})]$$

Using  $K$  definitions from 4<sup>TH</sup> order R-K method described before:

$$\begin{aligned} &= \frac{h}{6} \left[ \frac{K_1}{h} + 4 \left( \frac{K_2}{h} \right) + \frac{K_4}{h} \right] \\ &= \frac{1}{6} [K_1 + 2K_2 + 2K_3 + K_4] \end{aligned}$$

So,  $y_{n+1} - y_n \approx \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$ , or

$$y_{n+1} \approx y_n + \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

which is the same as R-K 4<sup>TH</sup> order.

Note: Simpson rule is a 2<sup>ND</sup> order method.

Notes: An adaptive step size is used when the solution to the ODE has a wide range of slopes.