Let us consider the stationary Navier-Stokes problem defined in the unit square $\Omega := [0,1]^2$

$$\begin{cases} (\mathbf{u} \cdot \nabla)\mathbf{u} - \frac{1}{\text{Re}} \Delta \mathbf{u} + \nabla p = 0, & \text{in } \Omega, \\ \text{div } \mathbf{u} = 0, & \text{in } \Omega, \\ \mathbf{u} = 1\mathbf{i} + 0\mathbf{j}, & \text{on } \Gamma^{\text{up}} = \{0 \le x \le 1, y = 1\}, \\ \mathbf{u} = \mathbf{0}, & \text{on } \partial \Omega \backslash \Gamma^{\text{up}}. \end{cases}$$
(1)

- Using the stable pair of spaces $\mathbb{P}^2/\mathbb{P}^1$, solve the problem using the Newton method. Each nonlinear iteration should be solved using the UMFPACK solver applied to the monolithic system, and the stop criterion should be based on the relative increment. Solve the problem with Re = 30. Does the solver converge to a proper solution?
- 2 Repeat the previous point using the mean-null projection of the pressure, defined as

$$\bar{p} = p - \int_{\Omega} p \, d\mathbf{x}.$$

Do you notice any difference?

- 3 Consider now different values of the Reynolds number: Re = 3, 30, 300, 3000. Comment on the differences in the results.
- 4 If the pair of spaces $\mathbb{P}^1/\mathbb{P}^1$ is considered, then the SUPG-stabilized version of the linearized problem can be written as follows:

$$a(\mathbf{u}_{k}, \mathbf{v}) + c(\mathbf{u}_{k}, \mathbf{u}_{k-1}, \mathbf{v}) + c(\mathbf{u}_{k-1}, \mathbf{u}_{k}, \mathbf{v}) + b(\mathbf{v}, p) - b(\mathbf{u}, q) +$$

$$+ \sum_{K \in \mathcal{T}_{h}} \delta_{K}((\mathbf{u}_{k} \cdot \nabla)\mathbf{u}_{k-1} + (\mathbf{u}_{k-1} \cdot \nabla)\mathbf{u}_{k} + \nabla p, (\mathbf{v} \cdot \nabla)\mathbf{u}_{k-1} + (\mathbf{u}_{k-1} \cdot \nabla)\mathbf{v} + \nabla q)_{K} +$$

$$+ \sum_{K \in \mathcal{T}_{h}} \delta_{K}(\operatorname{div} \mathbf{u}_{k}, \operatorname{div} \mathbf{v})_{K} =$$

$$= c(\mathbf{u}_{k-1}, \mathbf{u}_{k-1}, \mathbf{v}) + \sum_{K \in \mathcal{T}_{h}} \delta_{K}((\mathbf{u}_{k-1} \cdot \nabla)\mathbf{u}_{k-1}, (\mathbf{v} \cdot \nabla)\mathbf{u}_{k-1} + (\mathbf{u}_{k-1} \cdot \nabla)\mathbf{v} + \nabla q)_{K},$$

where $(\cdot, \cdot)_K$ denotes the L^2 inner product over the element K. The stabilization parameter should depend on the local Reynolds number Re_K : ¹

$$\delta_K = \begin{cases} \delta \frac{h_K}{\overline{u}_K}, & \text{for } \text{Re}_K \ge 1, \\ \delta h_K^2 \text{ Re}, & \text{for } \text{Re}_K < 1, \end{cases}$$

where δ is a given scalar and

$$\operatorname{Re}_K = \frac{\overline{u}_K h_k}{\nu}, \qquad \overline{u}_K = \frac{1}{|K|} \int_K |\mathbf{u}_k| \, d\mathbf{x},$$

or, for brevity, $\delta_K = \delta \frac{h_K}{\overline{u}_K} \min\{1, \text{Re}_K\}$. Implement this stabilization, with $\delta = 1$ and compare the results with the ones obtained in the previous points.

Beware that $|\mathbf{u}|$ can reach very small values, thus the computation of δ_K should be carefully dealt with.

¹Notice that, for the problem at hand, $\nu = \frac{1}{Re}$.

For the same problem of the previous exercise:

- Using the stable pair of spaces $\mathbb{P}^2/\mathbb{P}^1$, solve the problem using the fixed-point iteration method. Use the skew-symmetric version of the trilinear form associated to advection. Each nonlinear iteration should be solved using the UMFPACK solver applied to the monolithic system, and the stop criterion should be based on the residual. Try to solve the problem with different values of Reynolds number (Re = 3, 30, 300, 3000). Does the solver converge to a proper solution?
- 2 Introduce the SUPG stabilization for the solution of the linearized problem.

The stabilization parameter should depend on the local Reynolds number Re_K : ²

$$\delta_K = \begin{cases} \delta \frac{h_K}{\overline{u}_K}, & \text{for } \text{Re}_K \ge 1, \\ \delta h_K^2 \text{ Re}, & \text{for } \text{Re}_K < 1, \end{cases}$$

where δ is a given scalar and

$$\operatorname{Re}_K = \frac{\overline{u}_K h_k}{\nu}, \qquad \overline{u}_K = \frac{1}{|K|} \int_K |\mathbf{u}_k| \, d\mathbf{x},$$

or, for brevity, $\delta_K = \delta \frac{h_K}{\overline{u}_K} \min \{1, \text{Re}_K\}.$

Compare the solutions of the previous point with the solutions obtained with the SUPG stabilization, with $\delta = 0.25$.

3 Repeat the exercise using the pair of spaces $\mathbb{P}^1/\mathbb{P}^1$ and compare the SUPG stabilization with the Brezzi-Pitkäranta stabilization.

Exercise 3

We want to compare different choices for the diffusion term and the boundary conditions in the following problem: $\Omega := [0,3] \times [0,1]$

$$\begin{cases} (\mathbf{u} \cdot \nabla)\mathbf{u} - \frac{1}{\text{Re}} \operatorname{div} G(\mathbf{u}) + \nabla p = 0, & \text{in } \Omega, \\ \operatorname{div} \mathbf{u} = 0, & \text{in } \Omega, \\ \mathbf{u} = 6y(1 - y)\mathbf{i}, & \text{on } \Gamma_{\text{left}} = \{x = 0, \, 0 \le y \le 1\}, \\ \frac{1}{\text{Re}} G(\mathbf{u})\mathbf{n} - p\mathbf{n} = \mathbf{0}, & \text{on } \Gamma_{\text{right}} = \{x = 3, \, 0 \le y \le 1\}, \\ \mathbf{u} = \mathbf{0}, & \text{on } \Gamma_{\text{bottom}} = \{0 \le x \le 3, \, y = 0\}, \\ \star, & \text{on } \Gamma_{\text{top}} = \{0 \le x \le 3, \, y = 1\}, \end{cases}$$

$$(2)$$

where the possible choices for the operator G and the boundary condition \star are:

²Notice that, for the problem at hand, $\nu = \frac{1}{\text{Re}}$.

$$\begin{split} G(\mathbf{u}) &= \nabla \mathbf{u} \quad \text{vs.} \qquad G(\mathbf{u}) = \varepsilon(\mathbf{u}) = \frac{1}{2}(\nabla \mathbf{u} + \nabla \mathbf{u}^T) \\ \star : \text{no-slip} \quad \text{vs.} \qquad \star : \text{free slip} \\ \mathbf{u} &= \mathbf{0} \qquad \mathbf{u} \cdot \mathbf{n} = 0, \quad [\frac{1}{\text{Re}}G(\mathbf{u}) - pI]\mathbf{n} \cdot \mathbf{t} = 0 \end{split}$$

- 1 For each combined choice of G and \star , derive the weak form of the problem.
- 2 Modify the code of the previous lab session (lab4ex1.edp) to solve problem (2) and compare the results outcoming from the different choices. How would you model the flow between two infinite, rough planes?