Let us consider the Navier-Stokes problem defined in the domain  $\Omega$  as in the Figure below

$$\begin{cases} \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} - \frac{1}{\mathrm{Re}} \operatorname{div} (\nabla \mathbf{u} + \nabla \mathbf{u}^T) + \nabla p = \mathbf{0}, & \text{in } \Omega, t \in (0, T), \\ \operatorname{div} \mathbf{u} = 0, & \text{in } \Omega, t \in (0, T), \\ \mathbf{u} = \frac{3}{8}(2 - y)(2 + y)\mathbf{i}, & \text{on } \Gamma_{\mathrm{in}} = \{x = -3, \, -2 \le y \le 2\}, t \in (0, T), \\ \left[ \frac{1}{\mathrm{Re}} \left( \nabla \mathbf{u} + \nabla \mathbf{u}^T \right) - pI \right] \mathbf{n} = h_{\mathrm{out}} \mathbf{n}, & \text{on } \Gamma_{\mathrm{out}} = \{x = 12, \, -2 \le y \le 2\}, t \in (0, T), \\ \mathbf{u} = \mathbf{0}, & \text{on } \partial \Omega \backslash (\Gamma_{\mathrm{in}} \cup \Gamma_{\mathrm{out}}), t \in (0, T), \\ \mathbf{u}|_{t=0} = \mathbf{u}_{\mathrm{Stokes}}, & \text{in } \Omega, t = 0, \end{cases}$$

where the Reynolds number Re is equal to 200, boundary conditions are given by:

- no-slip conditions on the lateral boundary of the pipe and on the boundary of the obstacle;
- a parabolic velocity profile on the inlet boundary  $\Gamma_{in}$ ;
- non-homogeneous Neumann boundary conditions at the outlet boundary  $\Gamma_{\text{out}}$ , with an outward-directed normal stress  $h_{\text{N}} = 0.5$ ;

and  $\mathbf{u}_{\text{Stokes}}$  is the solution of the corresponding steady Stokes problem.



Discretize the problem using the stable pair of spaces  $\mathbb{P}_b^1/\mathbb{P}^1$  and solve the problem using the incremental Chorin-Temam projection scheme coupled with the backward Euler semi-implicit scheme.

Given the solution  $\mathbf{u}^n, p^n$  at a certain time instant  $t^n$ , the scheme to compute  $\mathbf{u}^{n+1}, p^{n+1}$  is described by the following steps:

1) Solve the predictor step to obtain a temporary velocity  $\tilde{\mathbf{u}}$ :

$$\begin{cases} \frac{\tilde{\mathbf{u}} - \mathbf{u}^n}{\Delta t} + (\mathbf{u}^n \cdot \nabla)\tilde{\mathbf{u}} - \frac{1}{\text{Re}} \operatorname{div} \left( \nabla \tilde{\mathbf{u}} + \nabla \tilde{\mathbf{u}}^T \right) = -\nabla p^n, & \text{in } \Omega, \\ \tilde{\mathbf{u}} = (1 - y^2)\mathbf{i}, & \text{on } \Gamma_{\text{in}}, \\ \frac{1}{\text{Re}} \left( \nabla \tilde{\mathbf{u}} + \nabla \tilde{\mathbf{u}}^T \right) \mathbf{n} = h_{\text{N}} \mathbf{n}, & \text{on } \Gamma_{\text{out}}, \\ \tilde{\mathbf{u}} = \mathbf{0}, & \text{on } \partial \Omega \backslash (\Gamma_{\text{in}} \cup \Gamma_{\text{out}}). \end{cases}$$

2) Solve the Poisson problem for the pressure increment  $\delta p$ :

$$\begin{cases} -\Delta \delta p = -\frac{1}{\Delta t} \operatorname{div} \tilde{\mathbf{u}}, & \text{in } \Omega, \\ \delta p = 0, & \text{on } \Gamma_{\text{out}}, \\ \nabla \, \delta p \cdot \mathbf{n} = 0, & \text{on } \partial \Omega \backslash \Gamma_{\text{out}}. \end{cases}$$

3) Projection step

$$\mathbf{u}^{n+1} = \tilde{\mathbf{u}} - \Delta t \, \nabla \, \delta p.$$

4) Pressure update

$$p^{n+1} = p^n + \delta p.$$

Compute the drag and lift forces exerted by the fluid on the obstacle at the final time T = 50, defined as follows:

$$F_{\mathrm{D}} = \int_{\Gamma_{\mathrm{obs}}} \left[ p \mathbf{n} - \frac{1}{\mathrm{Re}} (\nabla \, \mathbf{u} + \nabla \, \mathbf{u}^T) \mathbf{n} \right] \cdot \mathbf{i} \, ds, \\ F_{\mathrm{L}} = \int_{\Gamma_{\mathrm{obs}}} \left[ p \mathbf{n} - \frac{1}{\mathrm{Re}} (\nabla \, \mathbf{u} + \nabla \, \mathbf{u}^T) \mathbf{n} \right] \cdot \mathbf{j} \, ds, \\$$

where  $\Gamma_{\rm obs}$  is the boundary of the obstacle.

NB: Use FacetNormal(mesh) to access the normal vector n in Firedrake.

3 Consider now free-slip conditions on the wall boundaries

$$\Gamma_{\rm w} = \{-3 \leq x \leq 4, y = -2, 2\} = \partial \Omega \setminus (\Gamma_{\rm in} \cup \Gamma_{\rm out} \cup \Gamma_{\rm obs}).$$

Rewrite the steps of the projection scheme in this case, modify the implementation and run the simulation. What can you observe?