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Weekly Report
5/17 – 5/23

- Decided to use ORB_SLAM2 C++ library for Raspberry Pi after researching.
  - ROS is optional for running ORB_SLAM2
- Built all the required dependencies including:
  - OpenCV
  - Eigen3
  - Pangolin
  - DBoW2
  - g2o
- Recorded the compilation errors and how to fix the errors when building the dependencies.
- Worked on building ORB_SLAM2.
  - There are still some compilation errors need to be resolved.

Plans for next week:
- Keep working on building the library.
- Run the library with webcam.