

# **Weekly Report**

## **5/31 – 6/6**

- Ran ORB\_SLAM2 library with datasets (video sequences).
  - Mapping and localizing were smooth
- Used OpenCV to get frames from webcam.
- Ran ORB\_SLAM2 library with webcam.
  - Sometimes frames were froze and it was not smooth

Plans for next week:

- Figure out how to run the library with webcam smoothly.