

Weekly Report

7/5 – 7/11

- Tested ORB-SLAM2 lib with laptop webcam on several places.
 - Map generated correctly.
 - Features could not be detected if the light is too dim or bright.
- Recorded the experiment.
 - Link: <https://youtu.be/7gHCXuydoE0>
- Wrote documentation.

Plans for next week:

- Write Documentation
- Test on Raspberry Pi