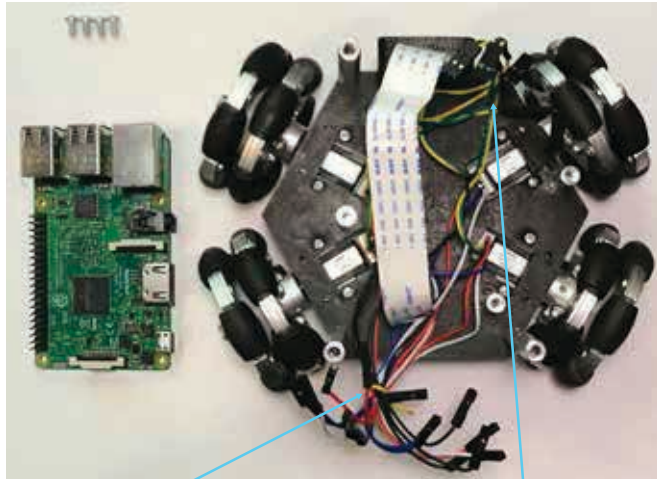
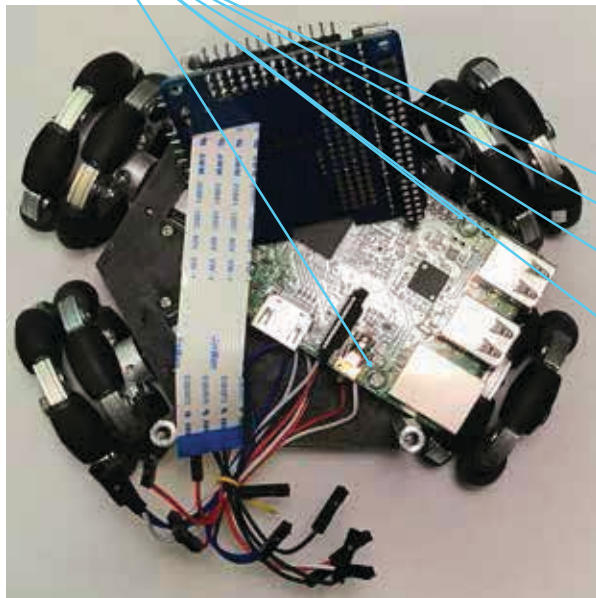


Raspberry Pi and MotorHat



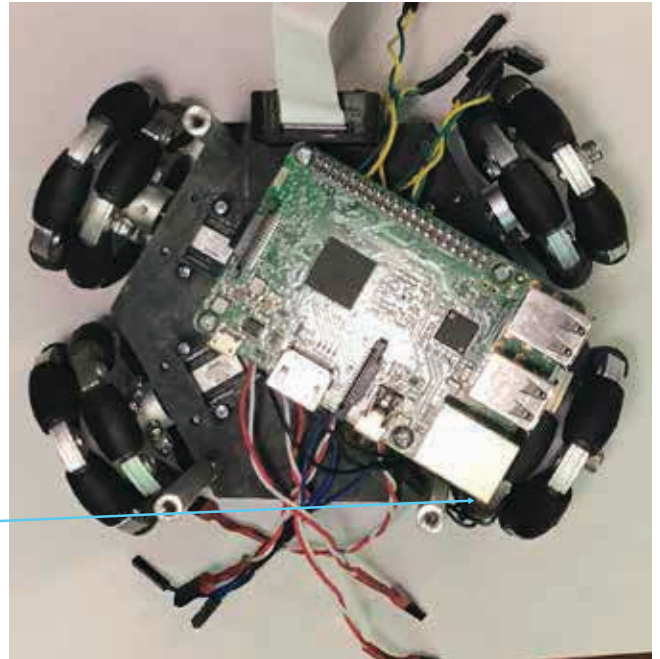
ASSEMBLY

- Ensure the red white and blue wires are oriented towards the back of the robotito and the green and yellow are oriented towards the front
- Orient the Pi on the 4 1in spacers with the USB ports facing the back right wheel
- Fasten the Pi to the spacers with the 4 1/4in screws

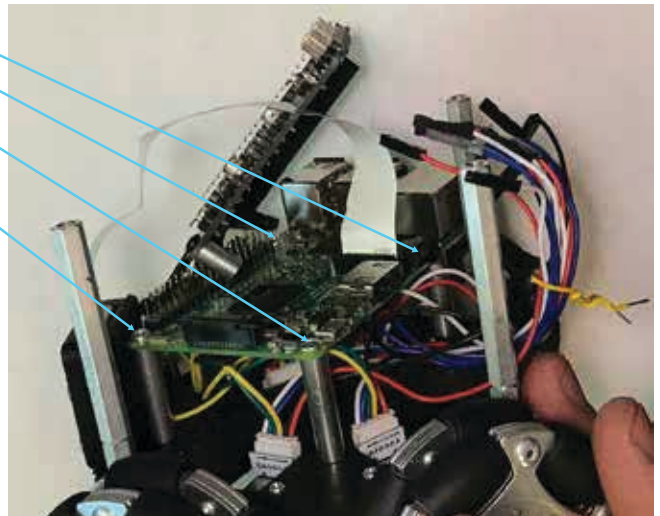


PARTS

- Chassis Assembly	x	1
- Raspberry Pi 3	x	1
- 1/4in x 7/64in	x	4



- Orient the Adafruit Motorhat so that its female header pins will align with the Pi's male header pins.



- Place camera ribbon through the Adafruit Motorhat and into the Pi's Camera port. Secure cable in port fastener.