#### **Digital Image Processing**

Lecture #5 Ming-Sui (Amy) Lee

#### Announcement

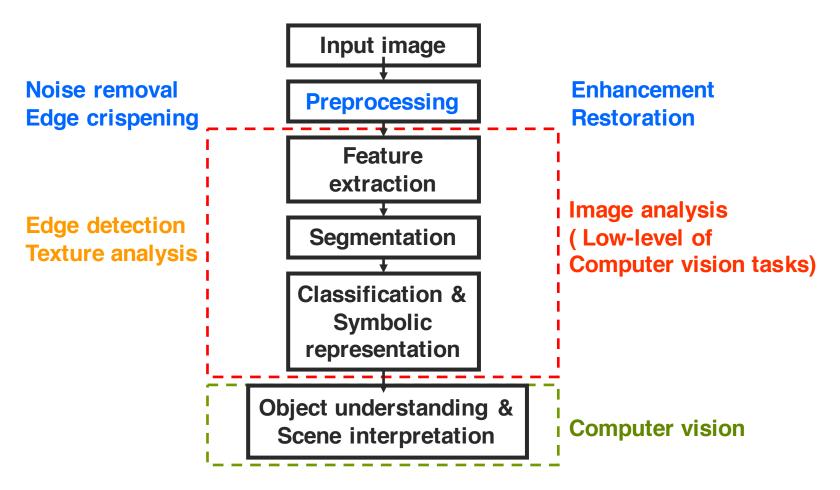
- Class Information
  - Homework #2
    - Due at 11:59 am on Apr. 12, 2016

#### Announcement

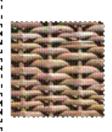
- Seminar Talk
  - "Recreational Graphics: Applications in Life, Art, and Entertainment"
    - 03/25 02:20~03:30 p.m. @ 徳田館 R103
    - Prof. Hung-Kuo Chu (James)
    - Department of Computer Science,National Tsing Hua University



Image analysis and its applications



What is texture?





- What is texture?
  - No mathematical definition
  - Two dimensional arrays of variations
  - Semi-regular structured patterns of object
  - E.g. Surfaces such as sand, grass, wool, cloth, leaves, etc.

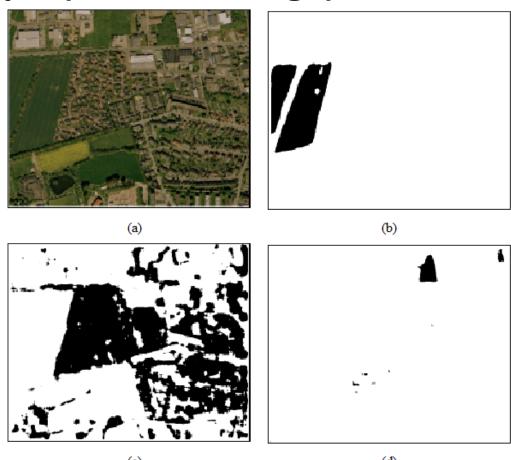


- Why texture analysis?
  - People started to be interested in late 50's and early 60's
    - Analyze aerial images / texture patches



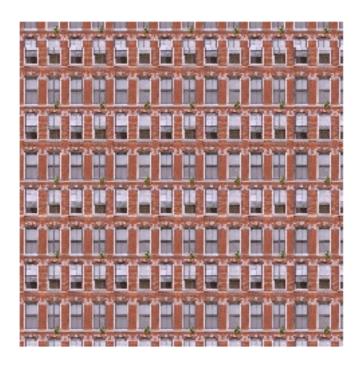


Example (an aerial image)



(

Example (Texture Synthesis)

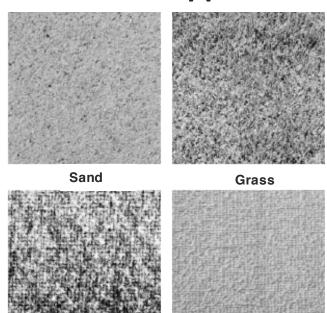




- History of texture analysis
  - Fourier Spectral Methods
  - Edge Detection Methods
  - Autocorrelation Methods
  - Decorrelation Methods
  - Dependency Matrix Method

- Fourier Spectral Methods
  - Right direction but incomplete development
  - No continuous work for a long while
- Edge Detection Methods
  - Edge detection
  - Use edge density and orientation as texture features

- Autocorrelation Methods
  - Treat the texture pattern as a 2D random process, denoted as F(x,y)
  - Statistical approach



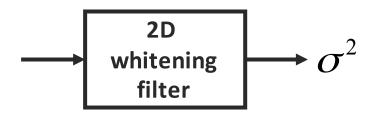
Raffia

Wool

$$E\{F(x, y)F(x - \Delta x, y - \Delta y)\}\$$

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- Decorrelation Methods
  - 2D whitening filter
    - Special type of decorrelation operator



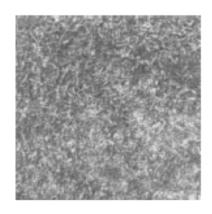
$$\hat{W}(j,k) = F(j,k) \otimes H_W(j,k)$$

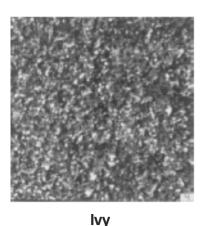
- Spatially decorrelated
  - Form histogram as its feature

- Dependency Matrix Method
  - Joint probability
  - Also called Co-occurrence method

$$P(a,b \mid j,k,\Delta j,\Delta k)$$

$$= \text{Prob}\{F(j,k) = a, F(j-\Delta j,k-\Delta k) = b, 0 \le a,b \le L-1\}$$





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- History of texture analysis
  - Fourier Spectra methods
  - Edge Detection Methods
  - Autocorrelation Methods
  - Decorrelation Methods
  - Dependency Matrix Method
  - → Not successful!!

- Laws' Method
  - Micro-structure (Multi-channel) method
    - **Emphasize** the microstructure of the texture
    - Two steps
      - step 1: Convolution
      - step 2: Energy computation

# Microstructure array $M_i(j,k) = F(j,k) \otimes H_i(j,k)$ Local features $F(j,k) \longrightarrow H_i(j,k) \longrightarrow M_i(j,k)$ Energy computation $T_i(j,k)$ computation $T_i(j,k)$ convolution

#### Laws' Method

- //Step 1// Convolution  $M_i(j,k) = F(j,k) \otimes H_i(j,k)$ 
  - Micro-structure impulse response arrays (a basis set)

$$H_i(j,k)$$

for 3x3 mask, i=1,2,3,...,9

for 5x5 mask, i=1,2,3,...,25

How to choose the mask size?

$$\frac{1}{36} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \\ \text{Laws 1} \end{bmatrix}$$

$$\frac{1}{12} \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix} \qquad \frac{1}{4} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{bmatrix} \qquad \frac{1}{4} \begin{bmatrix} -1 & 2 & -1 \\ 0 & 0 & 0 \\ 1 & -2 & 1 \end{bmatrix} \\
\text{Laws } 4 \qquad \text{Laws } 5$$

$$\frac{1}{12} \begin{bmatrix} -1 & -2 & -1 \\ 2 & 4 & 2 \\ -1 & -2 & -1 \end{bmatrix} \qquad \frac{1}{4} \begin{bmatrix} -1 & 0 & 1 \\ 2 & 0 & -2 \\ -1 & 0 & 1 \end{bmatrix} \qquad \frac{1}{4} \begin{bmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{bmatrix}$$
Laws 7

Laws 8

$$\frac{1}{12} \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$
Laws 2

$$\frac{1}{4} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \\ \text{Laws 5} \end{bmatrix}$$

$$\frac{1}{4} \begin{bmatrix} -1 & 0 & 1 \\ 2 & 0 & -2 \\ -1 & 0 & 1 \end{bmatrix}$$
Laws 8

$$\frac{1}{36} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix} \qquad \frac{1}{12} \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix} \qquad \frac{1}{12} \begin{bmatrix} -1 & 2 & -1 \\ -2 & 4 & -2 \\ -1 & 2 & -1 \end{bmatrix}$$
Laws 1
Laws 2
Laws 3

$$\frac{1}{4} \begin{bmatrix}
-1 & 2 & -1 \\
0 & 0 & 0 \\
1 & -2 & 1
\end{bmatrix}$$
Laws 6

$$\frac{1}{4} \begin{bmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{bmatrix}$$
Laws 9

- Laws' Method
  - Micro-structure impulse response arrays
    - Generated by the tensor product of the 1D horizontal and vertical masks

$$L_3 = \frac{1}{6}[1 \ 2 \ 1]$$

$$E_3 = \frac{1}{2}[-1 \ 0 \ 1]$$

$$L_3 = \frac{1}{6}[1 \ 2 \ 1]$$
  $E_3 = \frac{1}{2}[-1 \ 0 \ 1]$   $S_3 = \frac{1}{2}[1 \ -2 \ 1]$ 

Local averaging

Edge detector

spot detector (1<sup>st</sup>-order gradient) (2<sup>nd</sup>-order gradient)

**E.g.** 
$$L_3^T \otimes E_3 = \frac{1}{6} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \otimes \frac{1}{2} \begin{bmatrix} -1 & 0 & 1 \end{bmatrix} = \frac{1}{12} \begin{bmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{bmatrix}$$
 Laws 2<sup>19</sup>

#### Laws' Method

- Micro-structure impulse response arrays
  - 1979 → 1984,1986 mathematical analysis of Laws' filters
  - **Examine the frequency response of**  $L_3$ ,  $E_3$ , and  $S_3$

$$L_3 = \frac{1}{6}[1 \quad 2 \quad 1]$$

$$Kroneckor Delta$$

$$h[n] = \frac{1}{6}(\delta[n-1] + 2\delta[n] + \delta[n+1]) \quad \delta[n] = \begin{cases} 1 & n=0\\ 0 & otherwise \end{cases}$$

$$H(\omega) = \frac{1}{6}(e^{-j\omega} + 2 + e^{j\omega}) = \frac{2}{6}(1 + \cos\omega)$$

**→** Low-pass filter

- Laws' Method
  - Micro-structure impulse response arrays
    - **Examine the frequency response of**  $L_3$ ,  $E_3$ , and  $S_3$

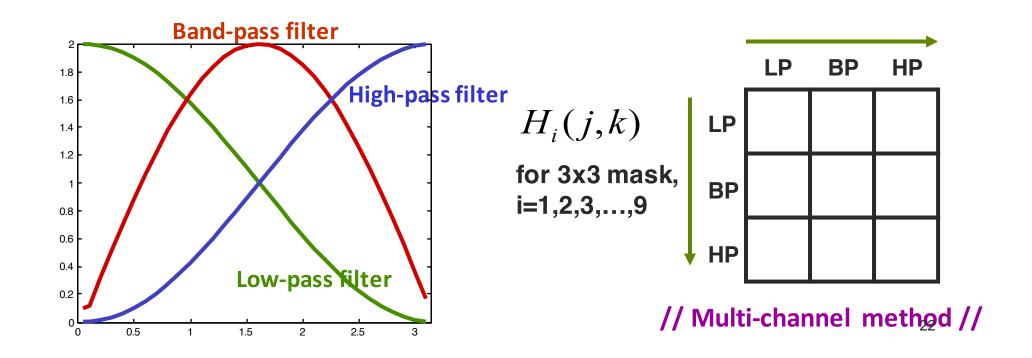
$$E_3 = \frac{1}{2}[-1 \ 0 \ 1]$$
  $h[n] = \frac{1}{2}(-\delta[n-1] + \delta[n+1])$ 

$$H(\omega) = (-e^{-j\omega} + e^{j\omega}) = 2j\sin\omega$$
  $\rightarrow$  Bandpass filter

$$S_3 = \frac{1}{2}[1 - 2 \ 1] \ h[n] = \frac{1}{2} (\delta[n-1] - 2\delta[n] + \delta[n+1])$$

$$H(\omega) = \frac{1}{2} \left( e^{-j\omega} - 2 + e^{j\omega} \right) = \cos \omega - 1 \rightarrow \text{High-pass filter}_{21}$$

- Laws' Method
  - Micro-structure impulse response arrays
    - **Examine the frequency response of**  $L_3$ ,  $E_3$ , and  $S_3$



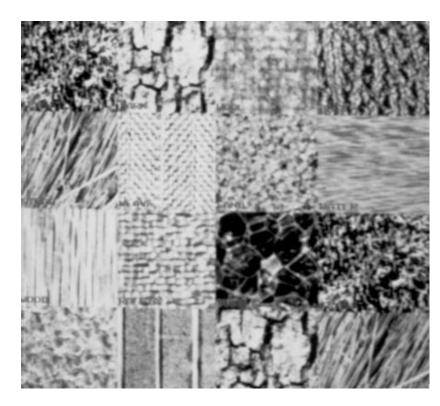
LP BP HP

LP

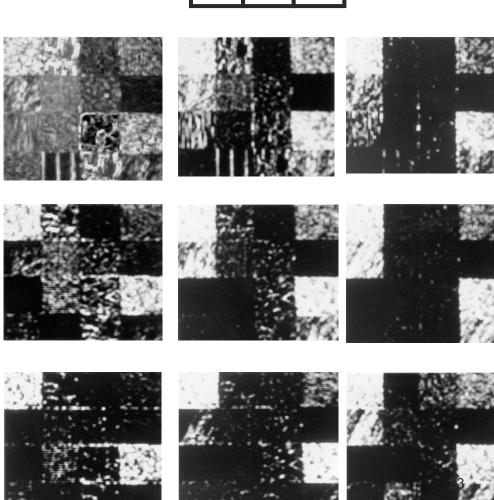
BP

HP

Example

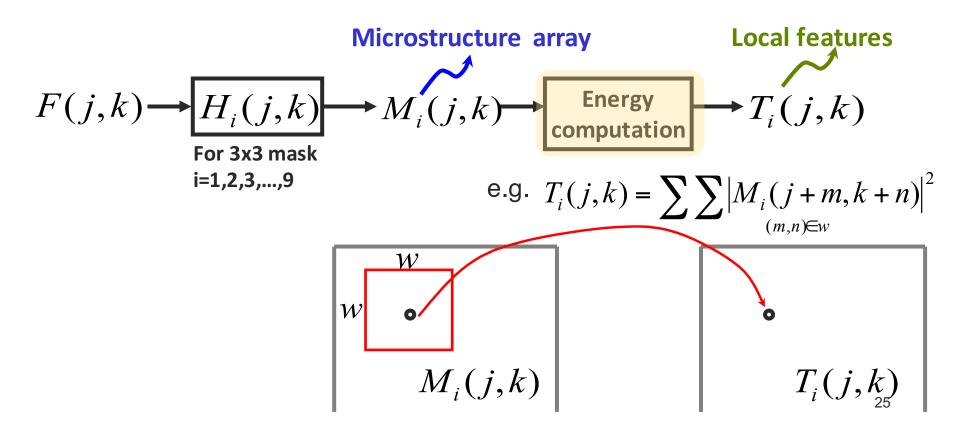


original image



- Laws' Method
  - o //Step 2// Energy Computation  $T_i(j,k)$ 
    - Extract features over a window that has a few cycles of the repetitive texture
    - How to choose the window size?
    - Global/local energy computation
    - 9 energy features correspond to the energy in the 9 subbands. We use the energy distribution in these 9 subbands to differentiate different texture types
    - Features
      - Mean, standard deviation, energy, smoothness etc.

- Laws' Method
  - //Step 2// Energy Computation



- Notes for Laws' method
  - O How to choose the mask size?  $H_i(j,k)$
  - Fixed subband structure vs
     Dynamic subband structure
  - How to choose the window size for energy computation?
    - For texture analysis, window size is usually set to be 13x13 or 15x15

- Texture classification/segmentation
  - O Given 9 feature sets,  $T_1$ ,  $T_2$ ,  $T_3$ ,  $\cdots$   $T_9$ How do we do texture classification?
  - Two cases

- $\bigcirc$
- Each input is homogeneous
- Single input consists of more than one texture
- Two approaches
  - Supervised texture classification
  - Un-supervised texture classification

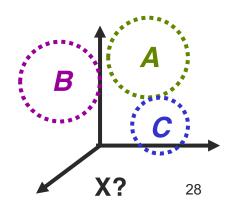
- Texture classification
  - Supervised texture classification
    - For each given texture type

$$textureA \rightarrow T_{A1}, T_{A2}, T_{A3}, \cdots T_{A9} \qquad A \qquad \Box \qquad \Box$$

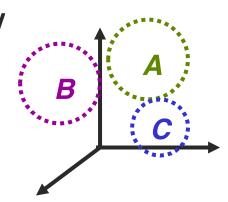
$$textureB \rightarrow T_{B1}, T_{B2}, T_{B3}, \cdots T_{B9} \qquad B \qquad \Box \qquad \Box$$

$$textureC \rightarrow T_{C1}, T_{C2}, T_{C3}, \cdots T_{C9} \qquad C \qquad \Box$$

- Texture space → 9 dimensional
- Given texture XUse nearest neighbor classification rule



- Texture classification
  - Feature space dimension reduction
    - Not considering all 9 features equally
    - More important feature
      - More discriminating power
      - Weighted more
    - Less important feature
      - Weighted less
      - Taken out from the feature set

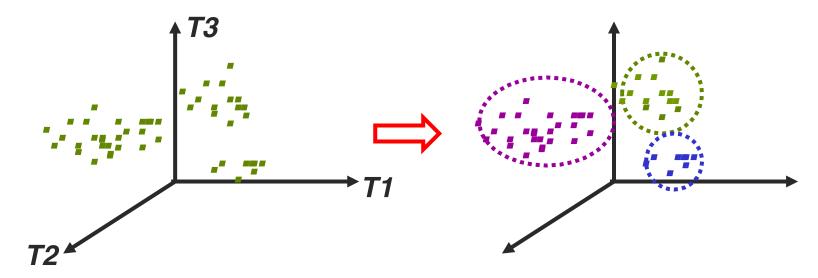


- Texture classification
  - Un-supervised texture classification
    - For several texture patches



- K-means algorithm
  - The famous tool to handle unsupervised classification problem

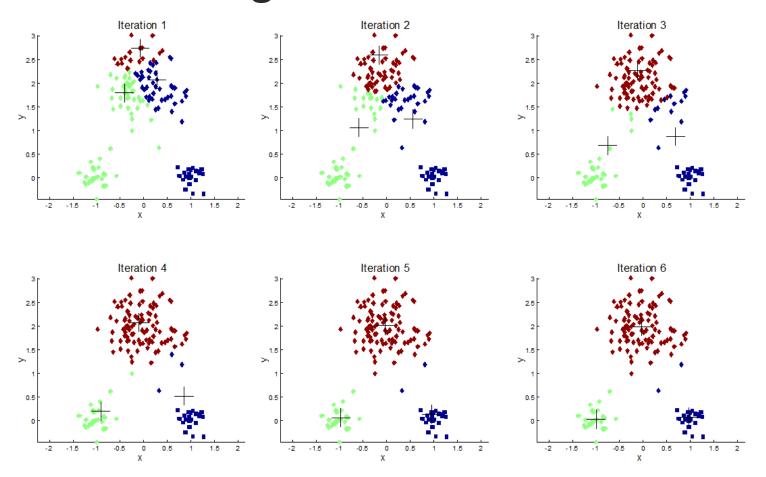
- K-means algorithm
  - K=3



- Good classification
  - Inter-clustering →
  - Intra-clustering →

- K-means algorithm
  - Two issues
    - How to choose k?
       depends on the inter-cluster and intra-cluster statistical analysis
       OR by the problem set-up (domain knowledge)
    - Given k, how to do the clustering?
      - // Initialization //
        - Select k vectors as the initial centroids
        - Do the following iterations
      - // step1 // Form k clusters using the NN rule
      - // step2 // re-compute the centroid of each cluster

#### K-means algorithm demo



#### Texture classification

- Two criterions
  - If pixels belong to the same type of texture, their associated feature vectors are close to each other in the feature space
  - Pixels belong to the same texture type should be close to each other in the space domain
- What is a good segmentation result?
  - Regions of a segment should be homogeneous w.r.t. some properties (i.e. feature vectors are close to each other in the feature space)
  - Region interior should be simple and without many holes
  - Boundaries of each segment should be simple, not ragged