HIS+BVAE+more

Chris

April 20, 2017

1   2D Plots

Here is the text of your introduction.

$$q_T(z_T) = E_{q(v_T)} \left[\frac{q_0(T_1^{-1}(...(T_T^{-1}(z_T, v_T)))}{q(v_T)} \right] \tag{1}$$