# Reproduction of 'Multi-Task Learning using Uncertainty to Weigh Losses'

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## A new approach to multi-task learning

Paper on 'Multi-Task Learning using Uncertainty to Weigh Losses' – Kendall, Gal & Cipolla, 2017.

• Principled approach to multi-task learning, demonstrated on the multi-task problem of semantic segmentation, instance segmentation and depth regression for the Cityscapes dataset

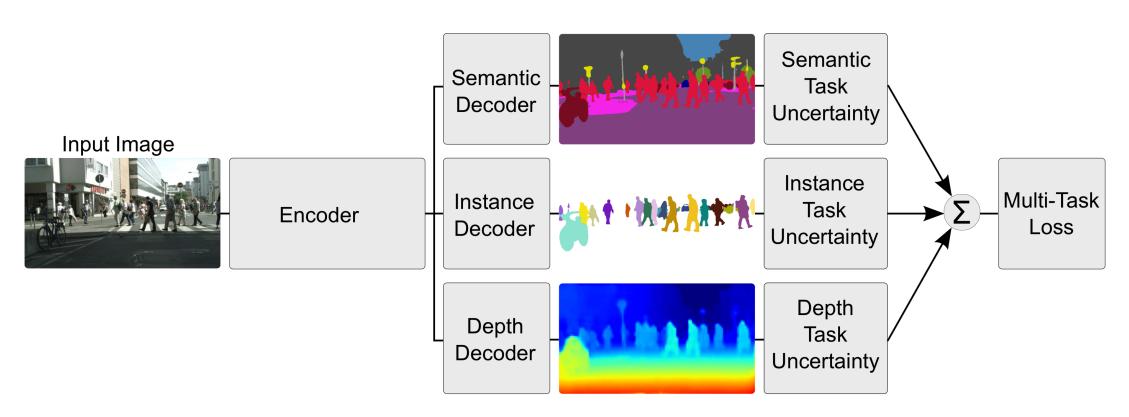


Fig. 1: Model architecture (Kendall et al., 2017)

- Three key contributions:
- 1. Principled method of weighing task losses using aleatoric homoscedastic uncertainty
- 2. Unified architecture for all three tasks with the same encoder for different tasks, with a separate decoder for each task
- 3. Demonstrating that loss weighting is important for performance, and showing how superior performance can be achieved on multi-task models compared to individually trained single-task models
- Overall joint loss function:

$$\mathcal{L} \approx \frac{1}{\sigma_{\text{sem}}^2} \mathcal{L}_{\text{sem}} + \log \sigma_{\text{sem}} + \frac{1}{2\sigma_{\text{ins}}^2} \mathcal{L}_{\text{ins}} + \log \sigma_{\text{ins}} + \frac{1}{2\sigma_{\text{dep}}^2} \mathcal{L}_{\text{dep}} + \log \sigma_{\text{dep}}$$

- Encoder: deep image classification network, ResNet-101, followed by an Atrous Spatial Pooling Pyramid module (based on DeepLabv3)
- Decoders: shallow convolutional network for each task

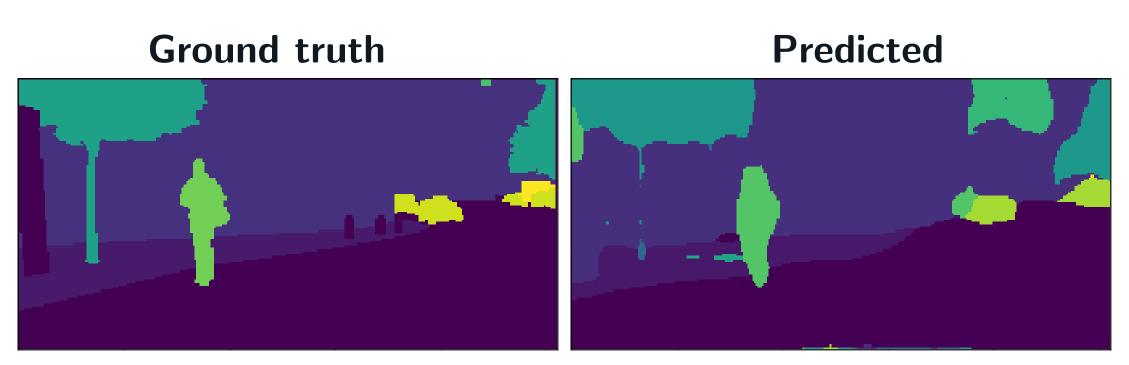
## Selected reproduction objective

- Comparison of multi-task learning with single-task learning and learned loss weights with fixed loss weights
- Subsampled dataset, Tiny Cityscapes, requires less computation time

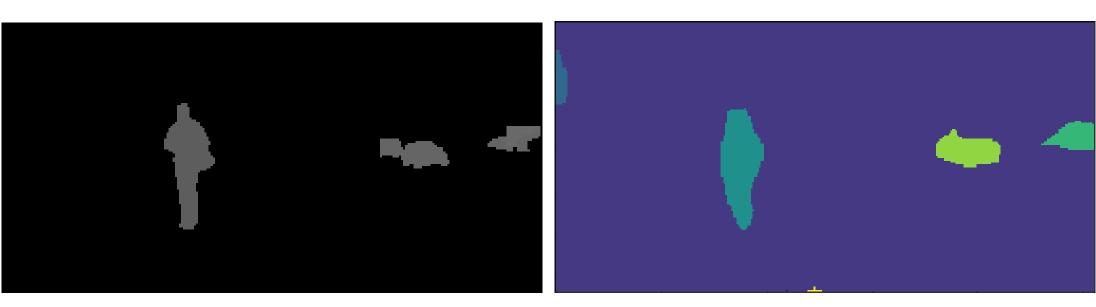
#### Reproduction results

• Quantitative improvement for semantic segmentation and depth regression for multi-task model with learned weights

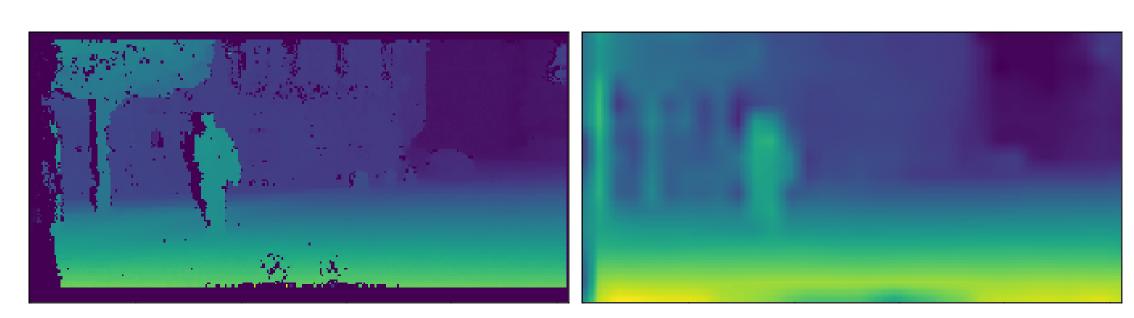
Task Weights			Segment.	Instance Mean	Inverse Depth
Seg.	Inst.	Depth	loU [%]	Error $[px]$	Mean Error $[px]$
1	0	0	33.2%	_	_
0	1	0	_	5.27	_
0	0	1	_	-	0.446
0.333	0.333	0.333	32.3%	5.72	0.459
0.89	0.01	0.1	32.7 %	8.39	0.528
Learned	Learned	_	33.9%	7.17	_
Learned	-	Learned	33.2%	_	0.426
-	Learned	Learned	-	6.26	0.430
Learned	Learned	Learned	34.0%	5.82	0.425



Semantic segmentation



Instance segmentation

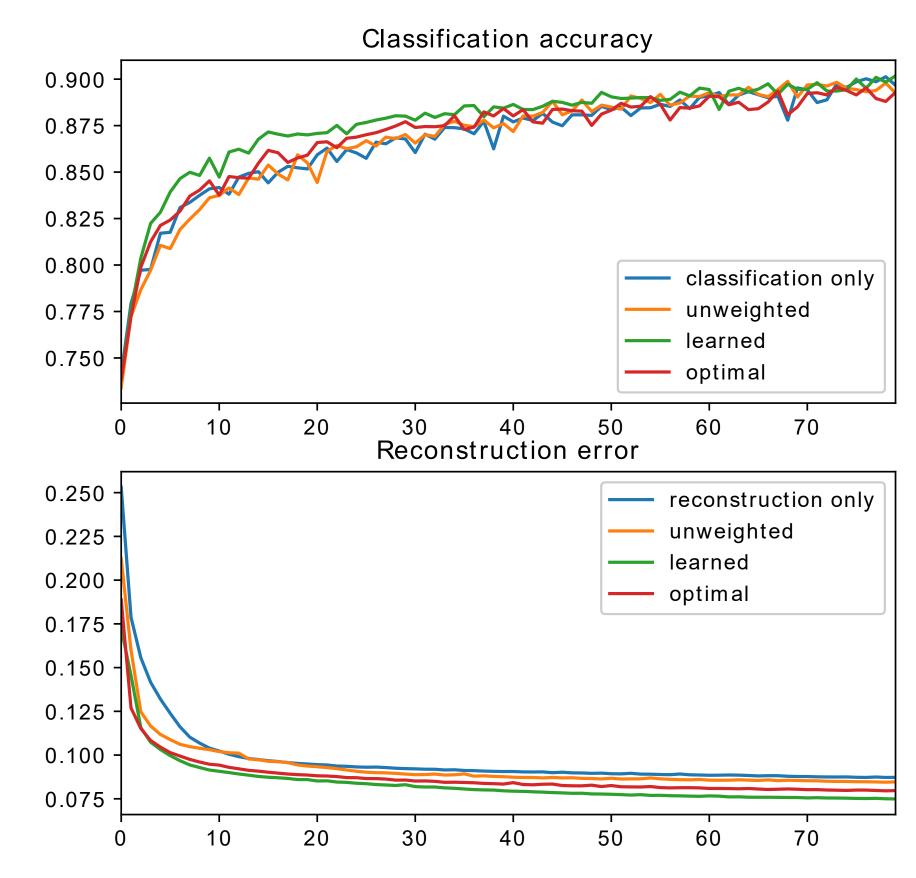


Depth regression

#### Success on other multi-task problems

• The principled approach applied to Fashion MNIST classification and reconstruction successfully yields a learned weights multi-task model which outperforms individually trained models and fixed weights multi-task model

	Task weights		Classification	Reconstruction
	Classif.	Reconstr.	accuracy [%]	error
Classification only	1	0	89.7%	_
Reconstruction only	0	1	_	0.087
Unweighted	0.5	0.5	89.3%	0.085
Optimal	0.4	0.6	89.3%	0.080
	Learned	Learned	90.2%	0.075



Reconstruction output samples from learned weights multi-task model

