

Reproduction of ‘Multi-Task Learning using Uncertainty to Weigh Losses’

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A new approach to multi-task learning

Paper on ‘Multi-Task Learning using Uncertainty to Weigh Losses’ – Kendall, Gal & Cipolla, 2017.

- Principled approach to multi-task learning, demonstrated on the multi-task problem of semantic segmentation, instance segmentation and depth regression for the Cityscapes dataset

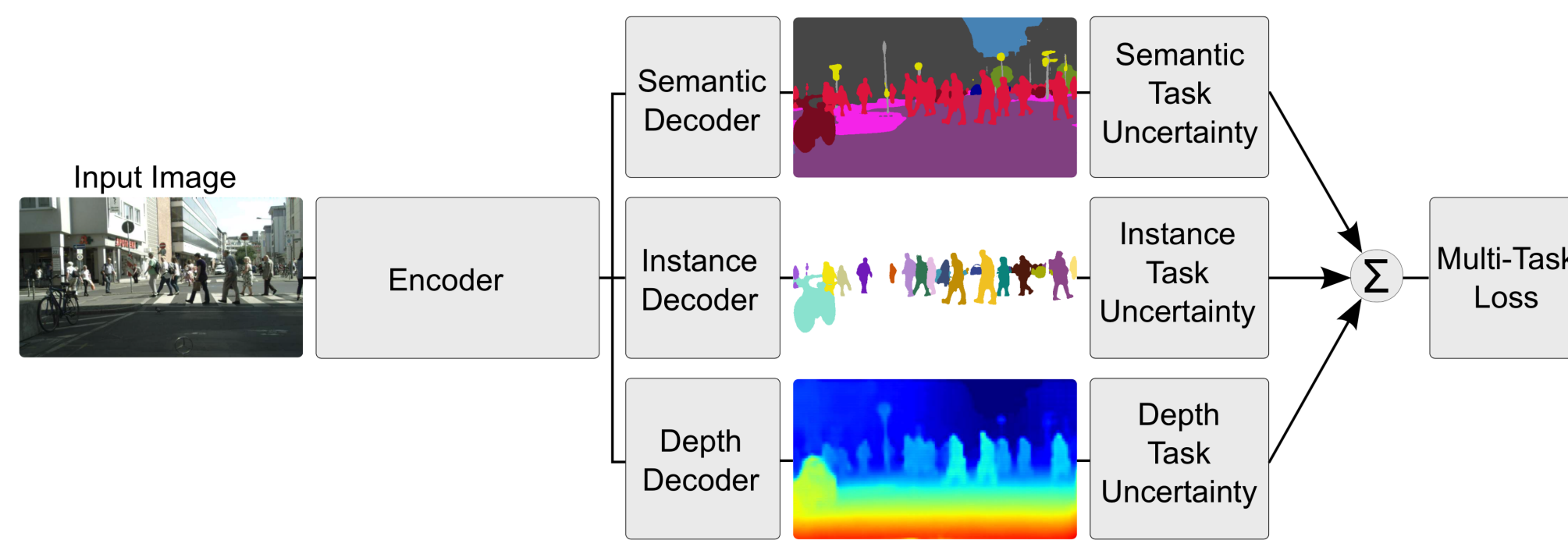


Fig. 1: Model architecture (Kendall et al., 2017)

- Three key contributions:

- Principled method of weighing task losses using aleatoric homoscedastic uncertainty
- Unified architecture for all three tasks with the same encoder for different tasks, with a separate decoder for each task
- Demonstrating that loss weighting is important for performance, and showing how superior performance can be achieved on multi-task models compared to individually trained single-task models

- Overall joint loss function:

$$\mathcal{L} \approx \frac{1}{\sigma_{\text{sem}}^2} \mathcal{L}_{\text{sem}} + \log \sigma_{\text{sem}} + \frac{1}{2\sigma_{\text{ins}}^2} \mathcal{L}_{\text{ins}} + \log \sigma_{\text{ins}} + \frac{1}{2\sigma_{\text{dep}}^2} \mathcal{L}_{\text{dep}} + \log \sigma_{\text{dep}}$$

- Encoder: deep image classification network, ResNet-101, followed by an Atrous Spatial Pooling Pyramid module (based on DeepLabv3)

- Decoders: shallow convolutional network for each task

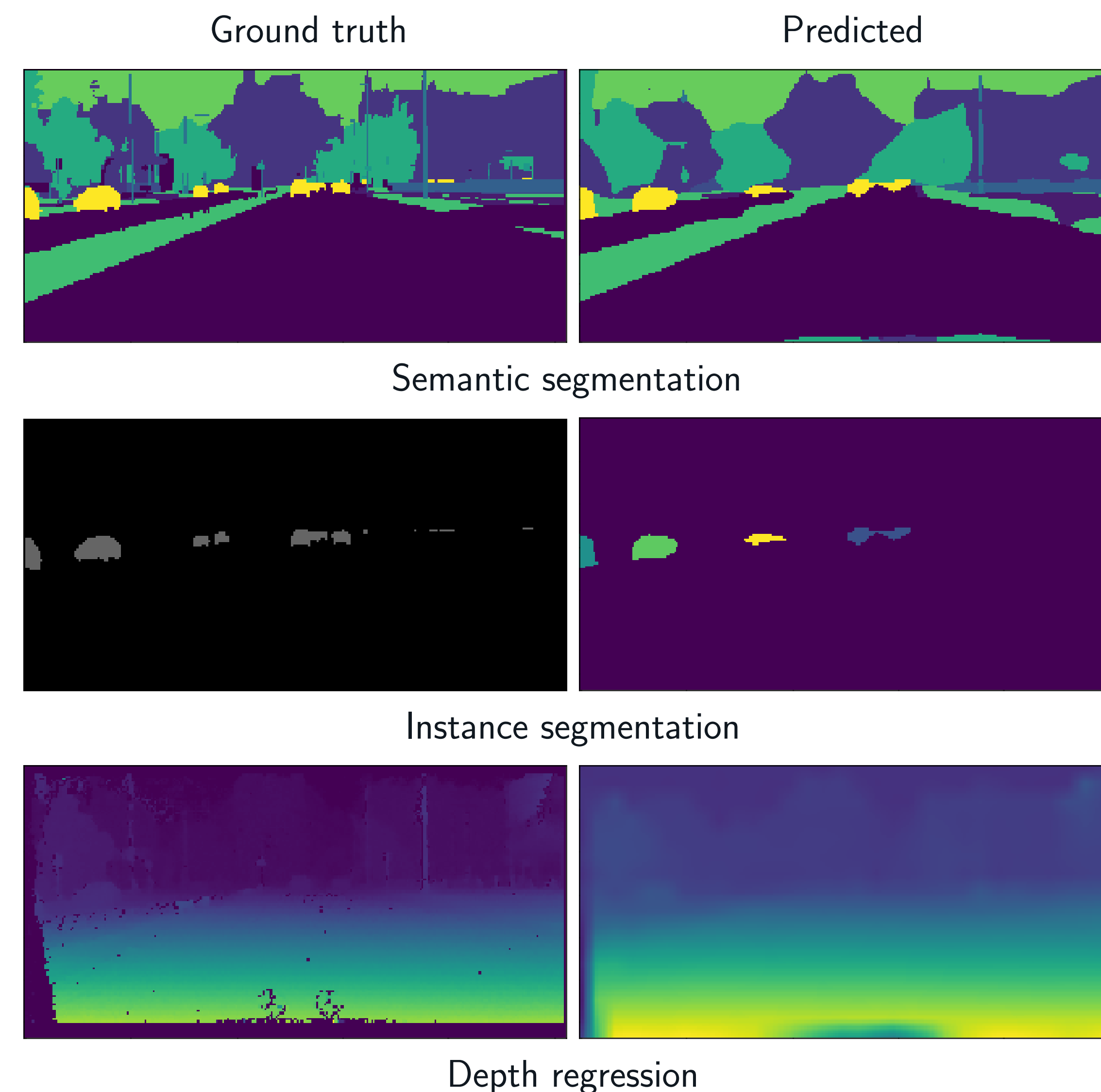
Selected reproduction objective

- Comparison of multi-task learning with single-task learning and learned loss weights with fixed loss weights
- Subsampled dataset, Tiny Cityscapes, requires less computation time

Reproduction results

- Quantitative improvement for semantic segmentation and depth regression for multi-task model with learned weights

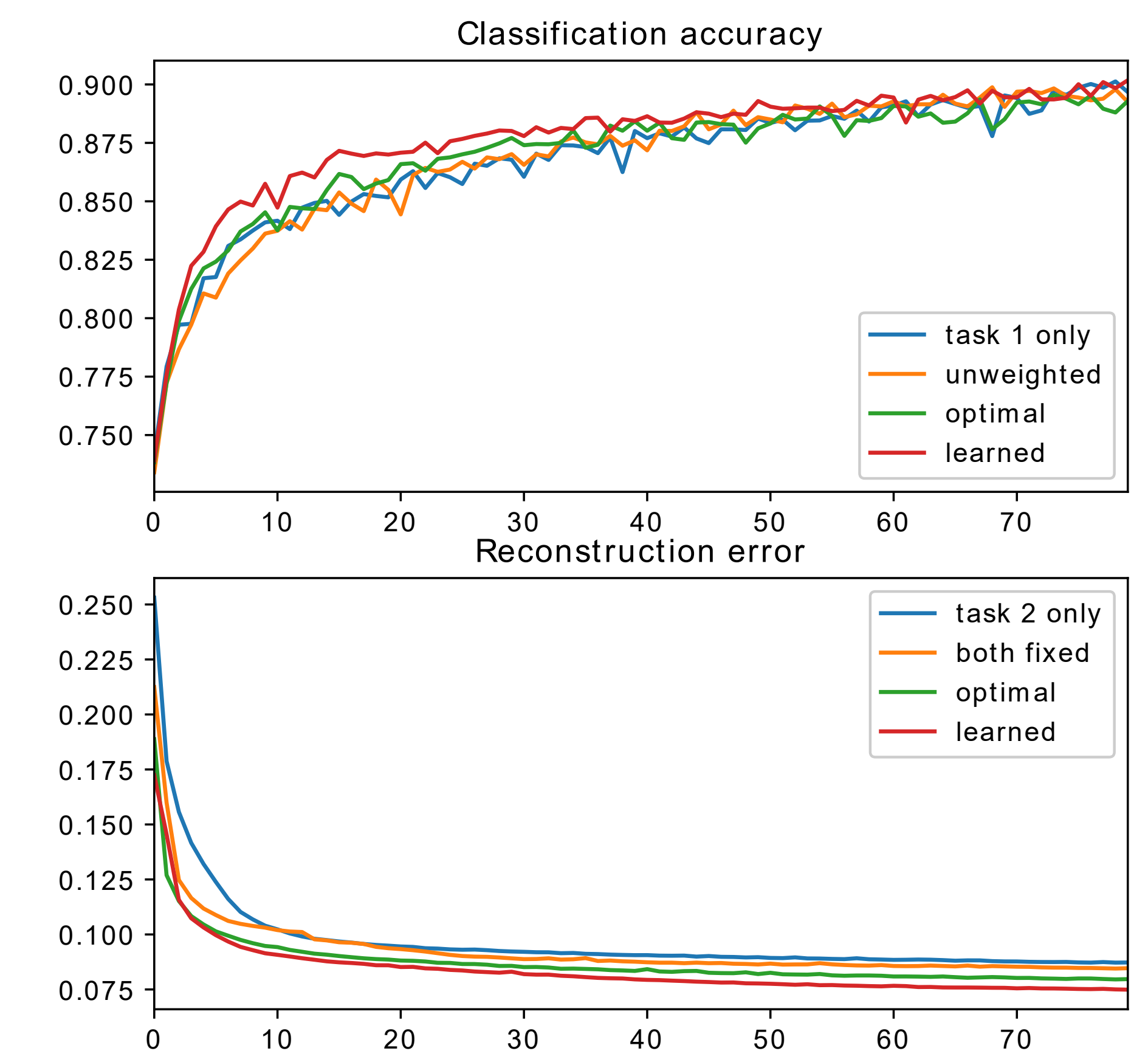
| Task Weights | | | Segment. | Instance Mean | Inverse Depth |
|--------------|---------|---------|--------------|---------------|-----------------|
| Seg. | Inst. | Depth | IoU [%] | Error [px] | Mean Error [px] |
| 1 | 0 | 0 | 33.2% | - | - |
| 0 | 1 | 0 | - | 5.27 | - |
| 0 | 0 | 1 | - | - | 0.446 |
| 0.333 | 0.333 | 0.333 | 32.3% | 5.72 | 0.459 |
| 0.89 | 0.01 | 0.1 | 32.7 % | 8.39 | 0.528 |
| Learned | Learned | - | 33.9% | 7.17 | - |
| Learned | - | Learned | 33.2% | - | 0.426 |
| - | Learned | Learned | - | 6.26 | 0.430 |
| Learned | Learned | Learned | 34.0% | 5.82 | 0.425 |



Success on other multi-task problems

- The principled approach applied to Fashion MNIST classification and reconstruction successfully yields a learned weights multi-task model which outperforms individually trained models and fixed weights multi-task model

| | Task weights | | Classification | Reconstruction |
|---------------------|--------------|-----------|----------------|----------------|
| | Classif. | Reconstr. | accuracy [%] | error |
| Classification only | 1 | 0 | 89.7% | - |
| Reconstruction only | 0 | 1 | - | 0.087 |
| Unweighted | 0.5 | 0.5 | 89.3% | 0.085 |
| Optimal | 0.4 | 0.6 | 89.3% | 0.080 |
| | Learned | Learned | 90.2% | 0.075 |



- Reconstruction output samples from learned weights multi-task model

