# Reproduction of 'Multi-Task Learning using Uncertainty to Weigh Losses'

D. Baerg, O. Key, J. Materzynska, M. Tong Department of Computer Science, University of Oxford



#### A new approach to multi-task learning

Paper on 'Multi-Task Learning using Uncertainty to Weigh Losses' – Kendall, Gal & Cipolla, 2017.

• Principled approach to multi-task learning, demonstrated on the multi-task problem of semantic segmentation, instance segmentation and depth regression for the Cityscapes dataset

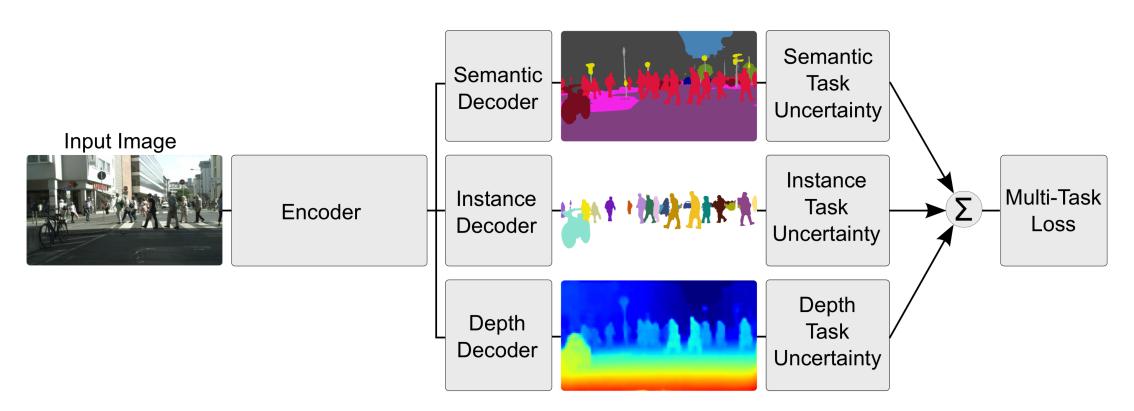


Fig. 1: Model architecture (Kendall et al., 2017)

- 3 key contributions:
- 1. Aleatoric homoscedastic uncertainty to weigh losses in different tasks
- 2. Unified architecture for all three tasks with the same encoder for different tasks, with a separate decoder for each task
- 3. Demonstrating that loss weighting is important for performance, and showing how superior performance can be achieved on multi-task models compared to individually trained single-task models
- Overall joint loss function:

$$\mathcal{L} \approx \frac{1}{\sigma_{\text{sem}}^2} \mathcal{L}_{\text{sem}} + \log \sigma_{\text{sem}} + \frac{1}{2\sigma_{\text{ins}}^2} \mathcal{L}_{\text{ins}} + \log \sigma_{\text{ins}} + \frac{1}{2\sigma_{\text{dep}}^2} \mathcal{L}_{\text{dep}} + \log \sigma_{\text{dep}}$$

• Model consisted of DeepLabv3 encoder architecture, including ResNet-101 layers with dilated convolutions and Atrous Spatial Pooling Pyramid module to increase contextual awareness with a simple decoder architecture with two convolutional layers for each task

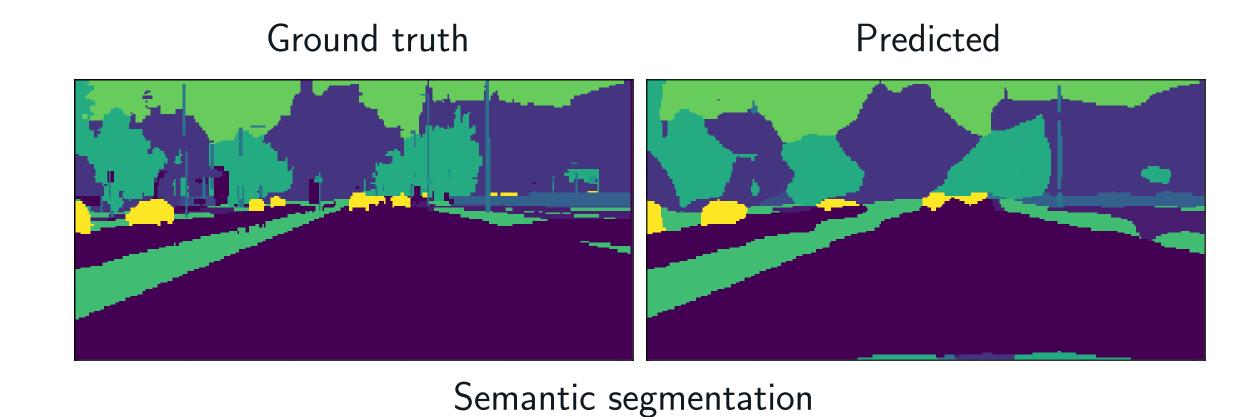
### Selected reproduction objective

- Comparison of multi-task learning with single-task learning and learned loss weights with fixed loss weights
- Subsampled dataset, Tiny Cityscapes, requires less computation time

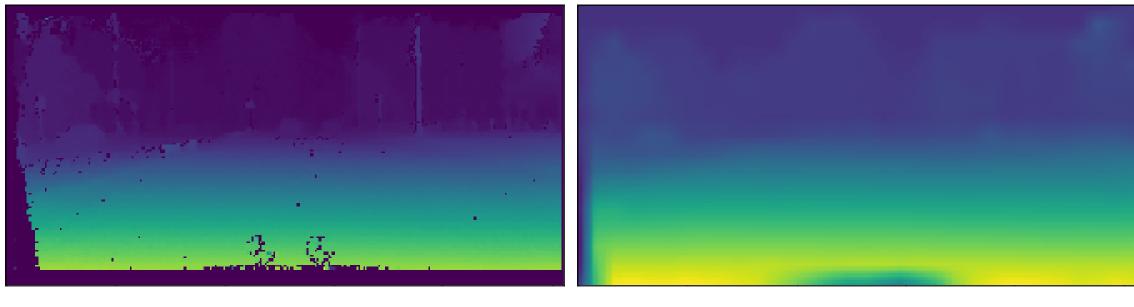
#### Reproduction results

- Quantitative improvement for semantic segmentation and depth regression for multi-task model with learned weights
- Improved baseline for inverse mean depth error from 0.522 to 0.425

_	Task Weights			Segment.	Instance Mean	Inverse Depth
	Seg.	Inst.	Depth	IoU [%]	Error $[px]$	Mean Error $[px]$
_	1	0	0	33.2%	_	_
	0	1	0	_	5.27	_
	0	0	1	_	_	0.446
_	0.333	0.333	0.333	32.3%	5.72	0.459
	0.89	0.01	0.1	32.7 %	8.39	0.528
_	Learned	Learned	-	33.9%	7.17	_
	Learned	-	Learned	33.2%	_	0.426
	_	Learned	Learned	_	6.26	0.430
_	Learned	Learned	Learned	34.0%	5.82	0.425



Instance segmentation

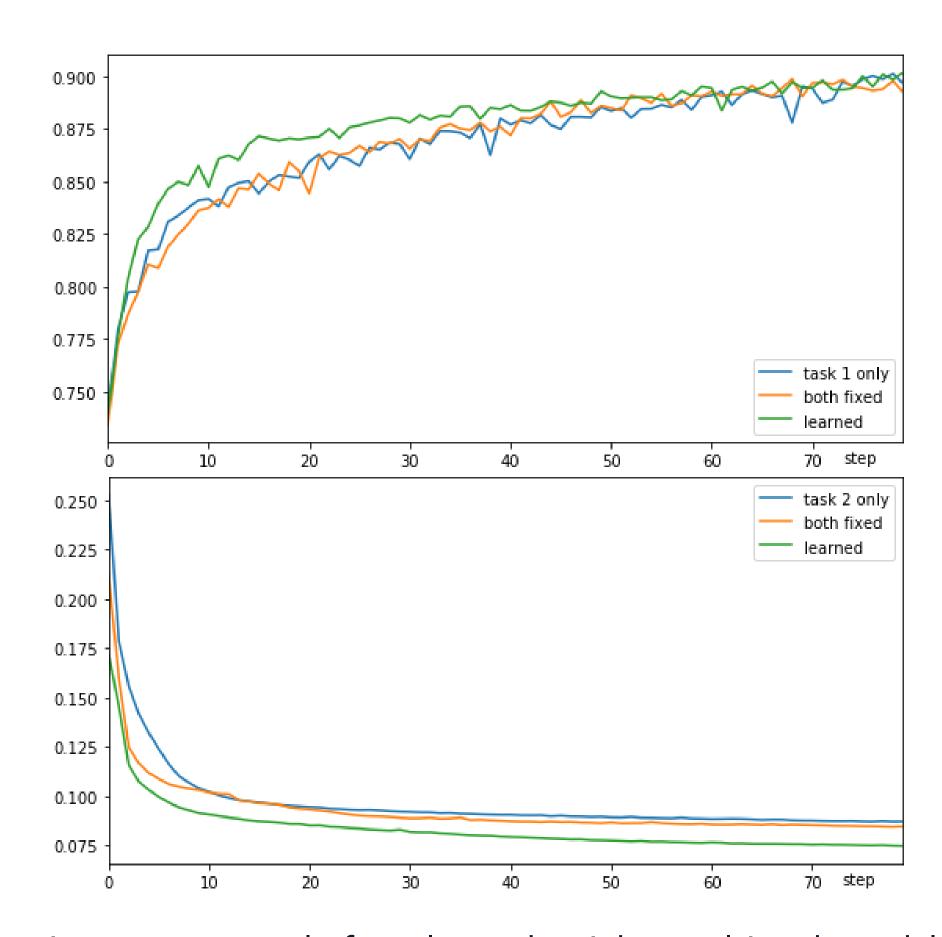


Depth regression

## Success on other multi-task problems

• Applying the principled approach to Fashion MNIST classification and reconstruction yields a learned weights multi-task model which outperforms individually trained models and fixed weights multi-task model

Task v	weights	Classification	Reconstruction
Classif.	Reconstr.	accuracy [%]	error
1	0	89.7%	_
0	1	_	0.087
0.5	0.5	89.3%	0.085
Learned	Learned	90.2%	0.075



Reconstruction output sample from learned weights multi-task model

