# SENSORS!!!!!!!!!!!!

OU ROBOTICS CLUB - SPRING 2015

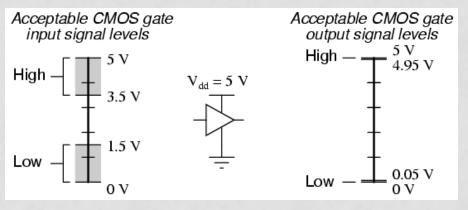
#### WHAT ARE SENSORS?

- Used to measure the real world
  - Temperature
  - Ambient light
  - Pressure
  - Object proximity
  - Color
  - Angle / Orientation
  - Magnetic field strength
  - Rotation speed

- Sensors can be simple or extremely complex
  - Simple
    - Bump sensor
    - Pressure sensor
    - Reflected/Ambient light
  - Complex
    - Camera module
    - Accelerometer

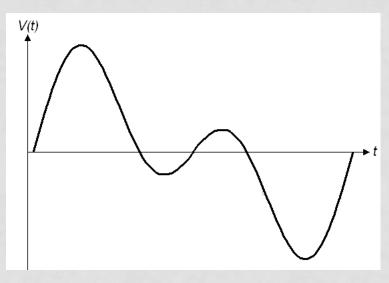
### DIGITAL VS. ANALOG

- Digital
  - 2 states/values
    - 0, 1
    - Low, High
    - Off, On
    - False, True



Source: http://www.allaboutcircuits.com/vol\_4/chpt\_3/10.html

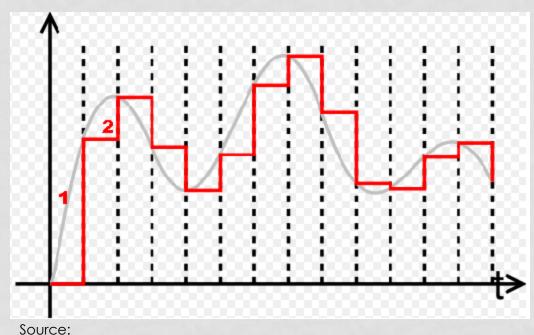
- Analog
  - Many values
  - 0, 0.01, 0.02, 0.03, ...



Source: http://www.beatstamm.com/scienceorsnakeoil.htm

## ANALOG TO DIGITAL CONVERSION

$$Voltage = \frac{Max\ Voltage}{\#\ of\ bins} \times ADC\ Value$$



http://automationprimer.com/2012/07/08/the-basics-analog-and-digital/

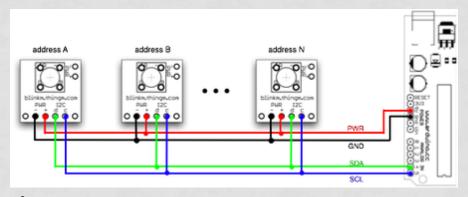
#### Example:

- 5V max
- 8 bits of data (256 bins)
- ADC Value of 128
- Measured Voltage:
  - 2.5V
- Usually need another formula to get a meaningful value
  - Temperature
  - Distance

#### DATA COMMUNICATION

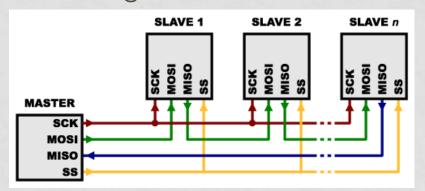
Some sensors can communicate directly to give you real values or to reconfigure their settings.

- 12C
  - Sends commands to all sensors with an address to select which sensor



Source: http://todbot.com/blog/2008/06/17/get-on-the-blinkm-bus-witha-blinkm-cylon/

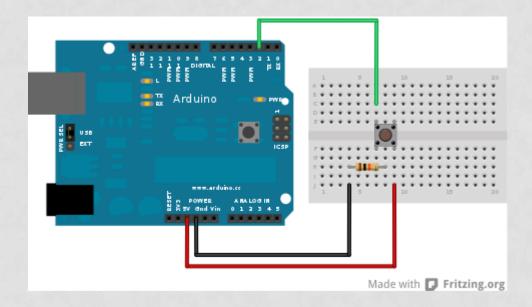
- · SPI
  - Uses a "chip select" to tell which sensor should be listening for commands



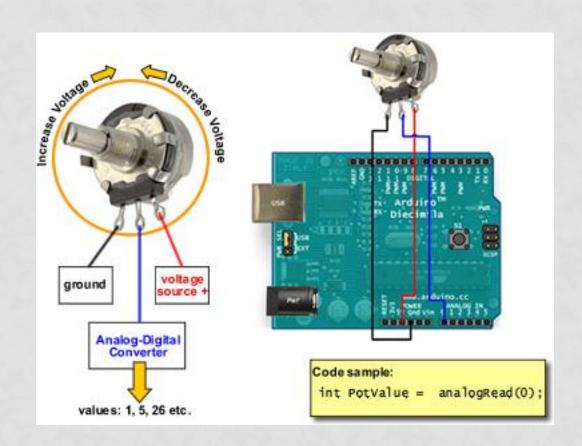
Source:

https://learn.sparkfun.com/tutorials/serial-peripheral-interface-spi

# HANDS ON: DIGITAL



## HANDS ON: ANALOG



# SENSOR FREE FOR ALL!!



# **QUESTIONS**

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