

UNIVERSITY OF OSLO
COMPUTATIONAL PHYSICS

Project 2



UiO : **University of Oslo**

Authors:

Birgitte Madsen

Magnus Isaksen

Soumya Chalakkal

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UiO : University of Oslo

Department of Physics

University of Oslo

Sem Sælands vei 24

0371 Oslo, Norway

+47 22 85 64 28

<http://www.mn.uio.no/fysikk/english/>

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<https://??>

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Project Members:

Birgitte Madsen

Magnus Isaksen

Soumya Chalakkal

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INTRODUCTION

Bla bla bla

The codes written in this project and the results gained from the codes, can be found by following the link:
<https://?> to the GitHub repository. ¹

We can ref. to sections etc. using "secref"-command like: Sec. 2

Vectors can be written using "v"-command like: **v**

.... and a lot of other cool stuff!

¹FiXme Note: correct the these lines

METHOD

Intro to chapter

The source code itself can be found in the GitHub folder <https://??>.¹

2.1 Nature of the problem

This problem..... bla bla bla.....

2.2 Description of the Algorithm

About the algorithm.....

This is how we write c++ code in the report:

```
// I am a comment

double please define me;

for (int i=1 ; i<n ; i++)
{
    I do this for a lot of i's;
}
```

2.2.1 Change in Matrix Elements after Iterations and Choice of θ

The algorithm for solving the eigenvalue problem given in² contains of multiply similarity transformations of the matrix \mathbf{A} , in which we assume a_{kl} to be the largest off-diagonal element. The matrix \mathbf{B} constructed by the similarity transformation is given by

$$\mathbf{B} = \mathbf{S}^T \mathbf{A} \mathbf{S} \quad (2.1)$$

¹Fixme Note: correct the above lines

²Fixme Note: eqref

in which \mathbf{S} is an orthogonal transformation matrix with its non-zero matrix elements:

$$\begin{aligned} s_{kk} &= s_{ll} = \cos \theta \\ s_{kl} &= -s_{lk} = -\sin \theta \\ s_{ii} &= 1, \quad i \neq k, i \neq l \end{aligned}$$

After matrix multiplication with the orthogonal transformation matrix \mathbf{S} and its transverse (as in (2.1)) the entrances of \mathbf{B} becomes

$$\begin{aligned} b_{ii} &= a_{ii}, \quad i \neq k, i \neq l \\ b_{ik} &= a_{ik} \cos \theta - a_{il} \sin \theta, \quad i \neq k, i \neq l \\ b_{il} &= a_{il} \cos \theta + a_{ik} \sin \theta, \quad i \neq k, i \neq l \\ b_{kk} &= a_{kk} \cos^2 \theta - 2a_{kl} \cos \theta \sin \theta + a_{ll} \sin^2 \theta \\ b_{ll} &= a_{ll} \cos^2 \theta + 2a_{kl} \cos \theta \sin \theta + a_{kk} \sin^2 \theta \\ b_{kl} &= (a_{kk} - a_{ll}) \cos \theta \sin \theta + a_{kl} (\cos^2 \theta - \sin^2 \theta) \end{aligned}$$

Due to the symmetry in (2.1) with \mathbf{A} being a tridiagonal symmetric matrix, $b_{lk} = b_{kl}$, $b_{ki} = b_{ik}$, and $b_{li} = b_{il}$.³ Since θ can be chosen arbitrarily, we choose θ to be the angle at which b_{kl} , and hence b_{lk} , becomes zero. In this way, the largest element of \mathbf{A} is eliminated, and it can be shown that this choice of θ reduces the norm of the off-diagonal elements of \mathbf{A} , which ensures that the algorithm terminates towards the eigenvalues.⁴

This yields the equation

$$0 = (a_{kk} - a_{ll}) \cos \theta \sin \theta + a_{kl} (\cos^2 \theta - \sin^2 \theta) \quad (2.2)$$

By introducing $\tan \theta = \sin \theta / \cos \theta$ and the quantity

$$\tau = \frac{a_{ll} - a_{kk}}{2a_{kl}} \quad (2.3)$$

(2.2) can be rewritten as the quadratic equation in $\tan \theta$

$$\tan^2 \theta + 2\tau \tan \theta - 1 = 0 \quad (2.4)$$

which has the solutions

$$\tan \theta = -\tau \pm \sqrt{1 + \tau^2} \quad (2.5)$$

From the solutions for $\tan \theta$ given in (2.7), $\cos \theta$ and $\sin \theta$ can be found using the formulas

$$\cos \theta = \frac{1}{\sqrt{1 + \tan^2 \theta}} \quad \text{and} \quad \sin \theta = \tan \theta \cos \theta$$

If $\tau < 0$, $\tan \theta$ is chosen to be

$$\tan \theta = -\tau - \sqrt{1 + \tau^2} \quad (2.6)$$

³FiXme Note: check that this is actually correct

⁴FiXme Note: this, I can write, right??

whilst if $\tau \geq 0$, $\tan \theta$ is calculated as

$$\tan \theta = -\tau + \sqrt{1 + \tau^2} \quad (2.7)$$

This choice is made to always make $\tan \theta$ the smaller of the two roots given in (2.7). Furthermore, this choice ensures that $|\tan \theta| \leq 1$, yielding that $|\theta| \leq \pi/4$.

This is true since $|\tau| \leq 1$, because $|a_{kl}| \geq |a_{ij}|$ for all i, j , from which it follows that

$$|\tan \theta| = \left| -\tau - \sqrt{1 + \tau^2} \right| \leq 1, \quad \text{for } \tau < 0 \quad (2.8)$$

and

$$|\tan \theta| = \left| -\tau + \sqrt{1 + \tau^2} \right| \leq 1, \quad \text{for } \tau \geq 0 \quad (2.9)$$

since $\sqrt{1 + \tau^2} \leq \sqrt{2}$.

The fact that $|\theta| \leq \pi/4$ ensures that $\cos \theta \geq 0$ which ultimately ensures that the difference between \mathbf{A} and the new matrix \mathbf{B} is minimized, since

$$\|\mathbf{B} - \mathbf{A}\|_F^2 = 4(1 - c) \sum_{i=1, i \neq k, l}^n (a_{ik}^2 + a_{il}^2) + \frac{2a_{kl}^2}{c^2}. \quad (2.10)$$

5

⁵FiXme Note: and why is this minimization a good thing?? :-P

RESULTS

When running the code presented in Chap. 2.... blah blah blah.... Let's have an intro to this chapter...

The results from running the code ... can be found in the GitHub folder <https://??>.¹

3.1 Interpretation of Results

WOW, an awesome interpretation of the results :D

3.1.1 Dependence of ρ_{max} and n on Eigenvalue

² For a single electron moving in a three-dimensional harmonic oscillator potential, the analytical solution for first three eigenvalues to the rewritten Schrödinger's equation ³ is $\lambda_0 = 3$, $\lambda_1 = 7$, and $\lambda_2 = 11$, for $l = 0$.
⁴

In the code given in ?? the two parameters ρ_{max} and n can be modified to give a more or less accurate numerical solution to the problem. If not considering the computational time, limit in memory, and round-off errors, the obvious ⁵ choice of ρ_{max} and n would be to make both numbers infinite. This is, however, not a realistic possibility, and this sections is therefore dedicated to find (discuss) on the optimal choices for ρ_{max} and n to obtain acceptable values for the eigenvalues of ⁶.

Changing ρ_{max} causes the interval $[\rho_{min}, \rho_{max}]$, in which the wave function is considered, to change. Since the wave function goes to zero as the distance goes to infinity, it is acceptable to neglect the contribution from some ρ_{max} . It is a ⁷ to decrease ρ_{max} and hence making the interval smaller, in the sense that a smaller n then is needed to create a sufficient step length and ultimately a good enough "resolution". However, if this ρ_{max} is too close to ρ_{min} the neglected part can actually not be neglected, if an acceptable result is wished for.

¹FiXme Note: correct the above lines

²FiXme Note: include e.g. a section called "1 electron case" or smt similar

³FiXme Note: eq. ref to nature eq

⁴FiXme Note: ref. to project description

⁵FiXme Note: mest fordelagtige

⁶FiXme Note: eqref

⁷FiXme Note: fordel

In the figure below, the dependence of different integer valued ρ_{max} on the three first eigenvalues gained by the algorithm described in ⁸ is plotted for $n = 100$. ⁹

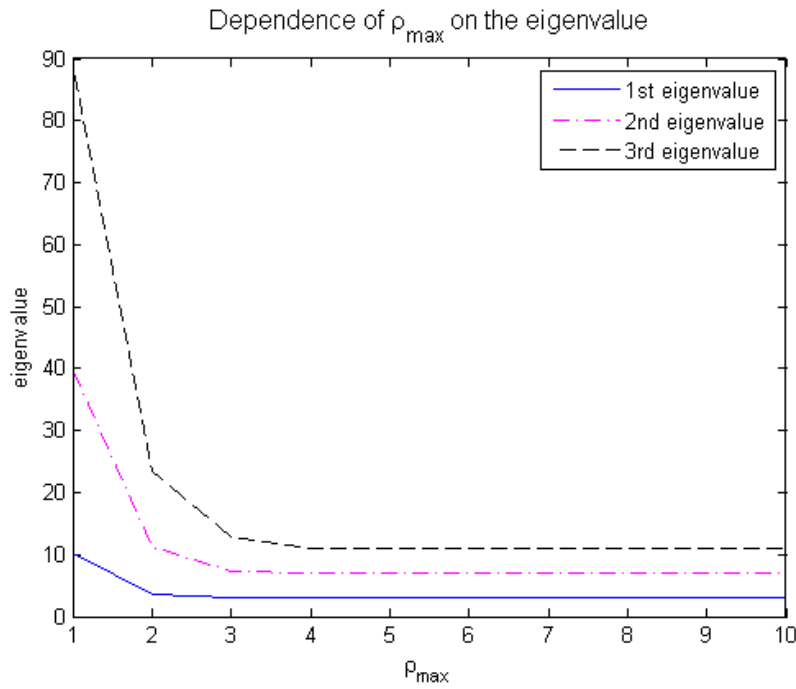


Figure 3.1. Awesome caption

From the figure that if $\rho_{max} < 3$ the eigenvalues are varying dramatically. This happens due to neglection ?? of strongly contributing parts of the eigenfunction. ¹⁰ ¹¹ The ρ_{max} that, with $n = 100$, gives the most accurate result for all three of the first eigenvalues is $\rho_{max} = 5$. Since this ρ_{max} gives the most accurate result for a relatively small n , this is chosen as the optimal ρ_{max} in this and the following sections for this specific problem.

With this ρ_{max} , we wish to find the number of n that gives the first three eigenvalues with four leading digits. This optimal n is found by steady increment of n , as seen in ¹².

⁸FiXme Note: sec ref

⁹FiXme Note: comment on, why we only have integer ρ_{max}

¹⁰FiXme Note: is this ok??

¹¹FiXme Note: comment on the flat part!!

¹²FiXme Note: figref below

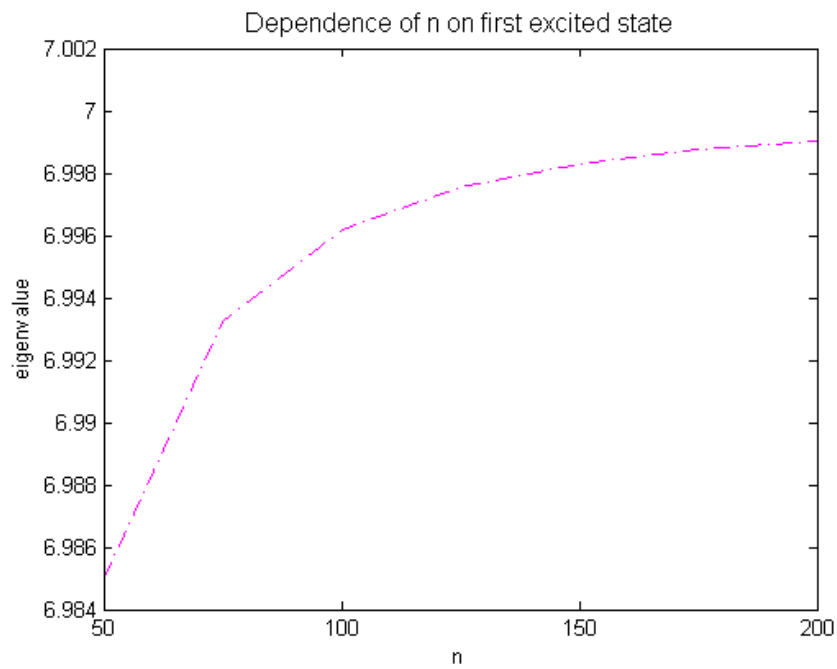


Figure 3.2. Awesome caption

The eigenvalue of the first excited state is seen to be asymptotic to the analytical solution $\lambda_1 = 7$, and at a matrix size of $n = 200$, the eigenvalue of the first excited state has the numerical solution 6.99904. This yields an accuracy up to four leading digits, which is also found to be the case for the ground state and the third eigenstate. Hence, the optimal ρ_{max} and n is 5 and 200, respectively.

3.1.2 Dependence of n on Number of Iterations

In here I want to put the last two figures side by side, but I'm tired now :P

CONCLUSION

Conclude.... conclude.... conclude....



BIBLIOGRAPHY

A

MATLAB CODE FOR SMT....

This is how, we write MatLab code in the report

```
close all
clear all
clc
%I am a comment

filename = 'Results.xlsx';
sheet = 4;
xlRange = 'B3:C12';

[v,T,vT] = xlsread(filename, sheet, xlRange);
x10=v(:,1);y10=v(:,2);

figure
plot(??)
legend(??)

xlim(??)
ylim(??)

title(??)
xlabel('x')
ylabel('y')
```
