P. 404 do livro

$$\overline{R}_{1} = \begin{bmatrix} x_{0} - x \\ y_{0} - y \\ \overline{D} - \overline{\epsilon} \end{bmatrix} \quad \overline{R}_{2} = \overline{R}_{1} - 2\overline{D}^{2} = \begin{bmatrix} x_{0} - x \\ y_{0} - y \\ -\overline{D} - \overline{\epsilon} \end{bmatrix}$$

$$\overline{u} = \frac{G_{12.39}}{4\pi} \left\{ \frac{\overline{R_{1}}}{R_{1}^{3}} + (3-4\nu) \frac{\overline{R_{2}}}{R_{2}^{3}} - 6\overline{z}(3+0) \frac{\overline{R_{2}}}{R_{2}^{3}} \right\} \sqrt{\alpha}$$

$$+\frac{2^{\frac{2}{7}}}{R_{2}^{\frac{3}{7}}}\left[(3-4\nu)(\overline{z}+D)-\overline{z}\right]^{\frac{1}{7}}\sqrt{\alpha}\Delta p_{4}$$

$$\boxed{1} \quad \overline{R_1} = \frac{1}{R_1^3} \begin{bmatrix} x_0 - X \\ y_0 - X \\ D - \overline{Z} \end{bmatrix} = \overline{V} V_1 = \begin{bmatrix} \partial_1 V_1 \\ \partial_2 V_1 \end{bmatrix}, \quad V_1 = \frac{1}{R_1}$$

DERIVADAS EM
RELAÇÃO AO PONTO
DE OBSERVAÇÃO

(X, Y, Z)

(3-4v)
$$\frac{R_2}{R_2^3} = (3-4v) \frac{1}{R_2^3} \begin{bmatrix} x_0 - x \\ y_0 - y \end{bmatrix} \begin{bmatrix} x_0 - x \\ y_0 - y \end{bmatrix} \begin{bmatrix} x_0 - x \\ y_0 - y \end{bmatrix}$$

$$V_2 = \frac{1}{R_2}$$

$$V_2 = \frac{1}{R_2}$$

$$V_3 = \frac{1}{R_2}$$

$$V_4 = \frac{1}{R_2}$$

$$V_5 = \frac{1}{R_2}$$

$$V_6 = \frac{1}{R_2}$$

$$V_7 = \frac{1}{R_2}$$

$$V_8 = \frac{$$

$$\boxed{II} = \frac{6z(z+D)}{R_z^5} \overline{R_z} = 2z \frac{3(-D-z)}{R_z^5} \begin{bmatrix} x_0 - x \\ y_0 - y \\ -D - \overline{z} \end{bmatrix} = 2z \frac{\partial x_z \sqrt{z}}{\partial y_z \sqrt{z}}$$

$$\boxed{1} \frac{2^{\frac{2}{7}}}{R_{12}^{3}} \left[(3-4\nu)(3+\nu) - 7 \right] = -2(3-4\nu) \frac{1}{R_{12}^{3}}$$

$$= -2(3-4v) \frac{1}{R_{2}^{3}} \begin{bmatrix} 0 \\ -D-2 \end{bmatrix} + \frac{2}{R_{2}^{3}} \begin{bmatrix} 0 \\ -\overline{Z} \end{bmatrix} =$$

$$= -(3(-4\nu)) \begin{bmatrix} 0 \\ 0 \\ 2 \partial_{7} \sqrt{2} \end{bmatrix} + 27 \begin{bmatrix} 0 \\ 0 \\ -\frac{1}{R_{2}^{3}} \end{bmatrix}$$

$$-(3-4v)\begin{bmatrix} 0 \\ -2\partial_{3}V_{2} \end{bmatrix} + 2\overline{c} \begin{bmatrix} \partial_{xz}V_{2} \\ \partial_{yz}V_{2} \\ \partial_{zz}V_{2} \end{bmatrix}$$

$$=\frac{Cm}{4\pi}\left[\frac{\partial_{x}V_{1}}{\partial_{y}V_{1}}\right]+(3-4y)\left[\frac{\partial_{x}V_{2}}{\partial_{y}V_{2}}\right]+\frac{2}{2}\left[\frac{\partial_{x}^{2}V_{2}}{\partial_{z}^{2}V_{2}}\right]V\propto\Delta\rho_{1}^{2}$$