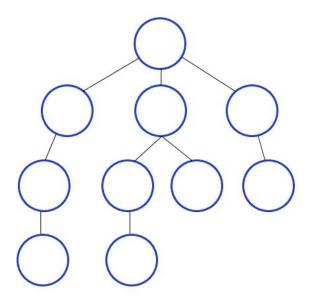
DFS



Lecture Flow

- 1) Pre-requisites
- 2) Problem definitions and uses
- 3) Different approaches
- 4) Checkpoint
- 5) Applications of DFS
- 6) Pair Programming
- 7) Things to pay attention (common pitfalls)
- 8) Practice questions
- 9) Resources
- 10) Quote of the day

Prerequisites

- Introduction to Graph
- Recursion
- Stack

Definition

- DFS is a graph **traversal algorithm**.
- It aims to visit all nodes or vertices of a graph in depth first manner.

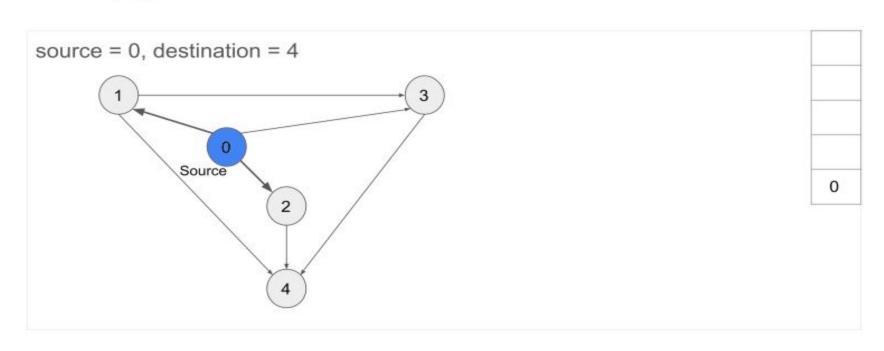
Definition

- The algorithm starts at a particular node, known as the source or starting node, and explores as far as possible along each branch before backtracking.
- This means that the algorithm will visit a node and then recursively visit all its adjacent nodes before moving on to the next node.

Tab space

Visualization

Visited = { 0, }

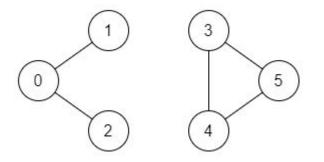


Implementation

```
def dfs(vertex, visited):
    # base case
    visited.add(vertex)
    for neighbour in graph[vertex]:
       if neighbour not in visited:
           dfs(neighbour, visited)
```

Recursive and Iterative Approach of Implementing DFS

Find if Path Exists in Graph





There is a **bi-directional** graph with n vertices, where each vertex is labeled from 0 to n-1 (**inclusive**). The edges in the graph are represented as a 2D integer array edges, where each edges $[i] = [u_i, v_i]$ denotes a bi-directional edge between vertex u_i and vertex v_i . Every vertex pair is connected by **at most one** edge, and no vertex has an edge to itself.

You want to determine if there is a **valid path** that exists from vertex source to vertex destination.

Given edges and the integers n, source, and destination, return true if there is a **valid path** from source to destination, or false otherwise.

Recursive Approach

Recursive Implementation

 Since it's a recursive implementation we have to obey the 3 rules of recursive functions.

What are those 3 rules?



Rule 1: State

 We need to know what node we are on. def dfs(node, visited):

 We need to keep track of the visited nodes.

Rule 2: Base case

 For the base case, when should we stop the recursion when the current node is our target. if node == destination:
 return True

 Alternatively, we can also finish when we have traversed over all the nodes.

Rule 3: Recurrence relation

We want to traverse all the adjacent nodes.

```
for neighbour in graph[node]:
    found = dfs(neighbour)

if found:
    return True
```

```
def validPath(self, n, edges,
                                         def dfs(node):
    source, destination):
                                              if node == destination:
                                                   return True
    graph = defaultdict(list)
                                              for neighbour in graph[node]:
                                                  found = dfs(neighbour)
    for node1, node2 in edges:
        graph[node1].append(node2)
                                                  if found:
        graph[node2].append(node1)
                                                       return True
    return dfs(source)
                                              return False
```

What's wrong with the above code?

```
def validPath(n, edges,
                                     def dfs(node, visited):
    source, destination)
                                         if node == destination:
                                              return True
    graph = defaultdict(list)
                                         visited.add(node)
    for node1, node2 in edges:
        graph[node1].append(node2)
        graph[node2].append(node1)
                                         for neighbour in graph[node]:
                                             if neighbour not in visited:
    visited = set()
                                                  found = dfs(neighbour, visited)
    return dfs(source, visited)
                                                  if found:
                                                      return True
                                         return False
```

Time Complexity

- We have V nodes and E edges
- We will only visit a node once, and if it's a complete graph we will also use every edge.

Time Complexity = O(V + E)

Space Complexity

- We have V nodes and E edges
- We will store the nodes, and also the edges.

Space Complexity = O (V + E)

Why O(V + E) and not O(V)?

Iterative Approach

"The Iterative implementation is just the recursive implementation done iteratively."

- Mahatma Gandhi

As such it obeys the 3 rules as well.

Rule 1: State

 Since we don't have access to the call stack we need our own stack to keep track of the current state.

```
stack = [source]
visited = set([source])
```

 For the state, we need to keep track of the node and the visited set.

Rule 2: Base case

 The base case is similar to the recursive implementation.

 We only need to know if the current node is the target node.

 Alternatively, we can also finish when we have visited all the nodes. if node == destination:
 return True

Rule 3: Iteration relation

 We visit any adjacent vertices that have not yet been visited.

 For each unvisited adjacent vertex, we mark it as visited and push it onto the stack.

```
for neighbour in graph[node]:
    if neighbour not in visited:
        stack.append(neighbour)
        visited.add(neighbour)
```

we can visit by starting from the source node.

We will continue to run the loop until we reach the base case or until we

visit all the nodes

Implementation

```
Class Solution:
      def validPath(self, n: int, edges: List[List[int]], source: int, destination: int) -> bool:
             graph = defaultdict(list)
             for node1, node2 in edges:
                    graph[node1].append(node2)
                    graph[node2].append(node1)
             stack = [source]
             visited = set([source])
             while stack:
                    node = stack.pop()
                    if node == destination:
                           return True
                    for neighbour in graph[node]:
                           if neighbour not in visited:
                                  stack.append(neighbour)
                                  visited.add(neighbour)
```

return False

Time Complexity

- We have V nodes and E edges
- We will only visit a node once, and if it's a complete graph we will also use every edge.

Time Complexity = O (V + E)

Space Complexity

- We have V nodes and E edges
- We will store the nodes, and also the edges.

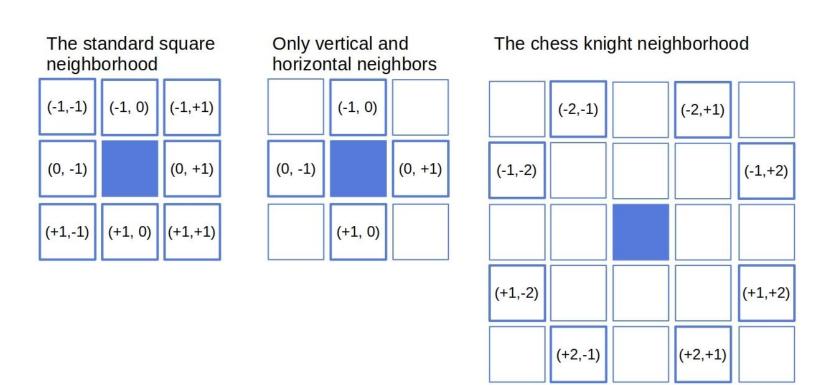
Space Complexity = O (V + E)

DFS on grid

DFS on grid

- Grid vertices are cells, and edges connect adjacent ones.
- DFS on a grid starts at a cell, visits its neighbors, and repeats.
- The process continues until all cells are visited.

Direction vectors

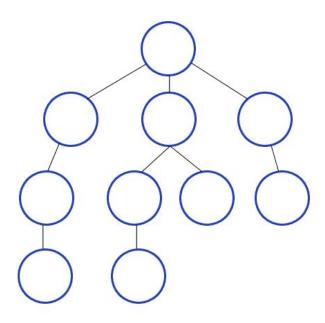


Code

```
directions = [(0, 1), (0, -1), (1, 0), (-1, 0)]
visited = [[0 for i in range(len(grid[0]))] for j in range(len(grid))]
def inbound(row, col):
      return (0 <= row < len(grid) and 0 <= col < len(grid[0]))</pre>
def dfs(grid, visited, row, col):
    # base case
    visited[row][col] = True
    for row_change, col_change in directions:
        new_row = row + row_change
        new_col = col + col_change
        if inbound(new_row, new_col) and not visited[new_row][new_col]:
                dfs(grid, visited, new_row, new_col)
```

Practice Problem

DFS on Tree



DFS on Tree

- Tree traversals (preorder, inorder, postorder) are **DFS algorithms**.
 - Preorder visits current, left, right
 - inorder visits left, current, right
 - postorder visits left, right, current.

Applications

- Finding Connected Components
- Detecting Cycles
- Path Finding
- Maze Solving
- Solving Puzzles
- Generating Permutations
- Topological Sorting

Path Finding

- DFS is a graph traversal algorithm that can be used for pathfinding.
- DFS works by starting at a vertex and exploring as far as possible along each branch before backtracking.

Path Finding

- It is possible that DFS will find a longer path before finding the shortest one.
- While DFS can be used for pathfinding, it may not always be the most efficient or accurate method.

CHECK IF THERE IS A VALID PATH IN A GRID

You will initially start at the street of the upper-left cell (0, 0). A valid path in the grid is a path that starts from the upper left cell (0, 0) and ends at the bottom-right cell (m - 1, n - 1). The path should only follow the streets.

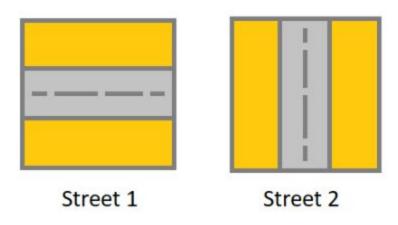
Notice that you are not allowed to change any street.

Return true if there is a valid path in the grid or false otherwise.

Medium ₼ 705 🗗 285 ♡ Add to List 🗂 Share

You are given an $m \times n$ grid. Each cell of grid represents a street. The street of grid[i][j] can be:

- 1 which means a street connecting the left cell and the right cell.
- · 2 which means a street connecting the upper cell and the lower cell.
- 3 which means a street connecting the left cell and the lower cell.
- 4 which means a street connecting the right cell and the lower cell.
- 5 which means a street connecting the left cell and the upper cell.
- 6 which means a street connecting the right cell and the upper cell.



Implementation

```
def dfs(row, col):
def hasValidPath(self, grid):
       destination = (len(grid)-1, len(grid[0]) -
1)
       directions =
              \{1: [(0,-1),(0,1)],
              2: \lceil (-1,0), (1,0) \rceil,
              3: \lceil (0,-1),(1,0) \rceil,
              4: \lceil (0,1), (1,0) \rceil,
              5: \lceil (0,-1), (-1,0) \rceil,
              6: [(0,1),(-1,0)]
       def inbound(row, col):
              return 0 <= row < len(grid)</pre>
              and 0 <= col < len(grid[0])
       visited = set([(0, 0)])
       return dfs(0, 0)
```

```
if (row, col) == destination:
       return True
for row_change, col_change in directions[grid[row][col]]:
       new_row= row + row_change
      new col = col + col change
       if (inbound(new_row, new_col) and
          (new_row, new_col) not in visited and
           (-row_change, -col_change) in
             directions[grid[new_row][new_col]]):
              visited.add((new row, new col))
              found = dfs(new_row, new_col)
              if found:
                     return True
```

return False

Time Complexity

- We have V nodes and E edges
- We will only visit a node once, and if it's a complete graph we will also use every edge.

Time Complexity = O (V + E)

Space Complexity

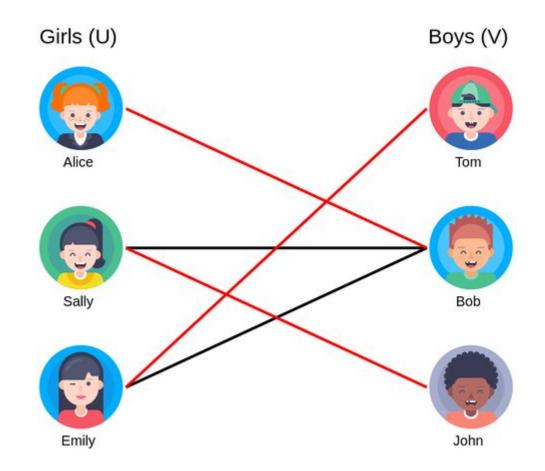
- We have V nodes and E edges
- We will store the nodes, and also the edges.

Space Complexity = O (V + E)

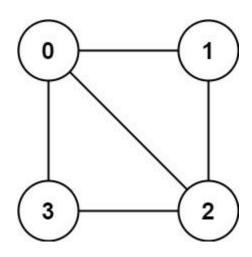
Determine if a graph is bipartite or not?

Bipartite Graph

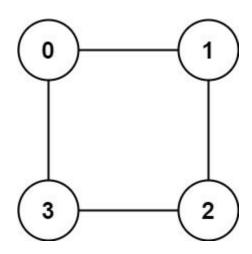
- Bipartite graphs have two sets of nodes.
- Each edge connects nodes from different sets.



Is this graph Bipartite?



Is this graph bipartite?



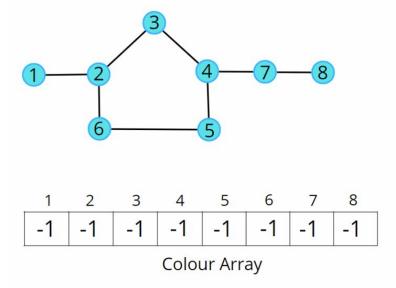
How do we identify if a graph is bipartite or not using

dfs?

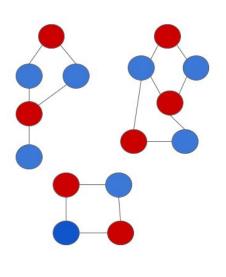
We use DFS Coloring.

DFS Coloring

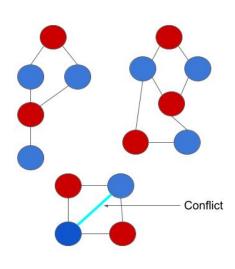
 Assign a color to each vertex of a graph in such a way that no two adjacent vertices have the same color.



Is a graph bipartite?



Bipartite Graph



No possible way to split

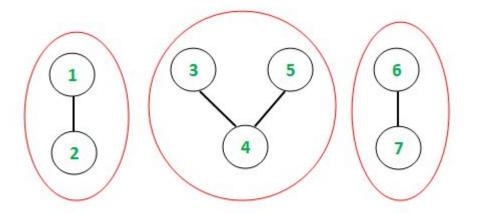
Practice Problem

Implementation

```
def isBipartite(self, graph):
                                                              def dfs(node):
      color = {}
                                                                    for neighbour in graph[node]:
                                                                           if neighbour in color:
      for node in range(len(graph)):
                                                                                  if color[neighbour] == color[node]:
             If neighbour not in color:
                                                                                         return False
                    color[node] = 0
                    if not dfs(node):
                                                                                  else:
                           return False
                                                                                         color[neighbour] = 1 - color[node]
                                                                                         if not dfs(neighbour):
      return True
                                                                                                return False
                                                                           return True
```

Connected components

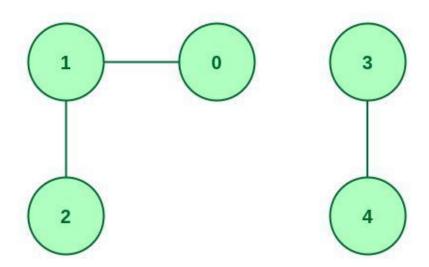
The connected parts of a graph are called its **components**



The counts of connected components are - 2, 3 and 2

Finding Connected Components

A connected component of a graph is a subset of vertices in the graph such that there is a path between any two vertices in the subset.



Brainstorm on how to find connected components.



Number of Islands

200. Number of Islands

Medium

(water), return the number of islands.

Given an m x n 2D binary grid grid which represents a map of '1's (land) and '0's

An **island** is surrounded by water and is formed by connecting adjacent lands horizontally or vertically. You may assume all four edges of the grid are all surrounded by water.

Example 1:

```
Input: grid = [
  ["1","1","1","1","0"],
  ["1","1","0","1","0"],
  ["1","1","0","0","0"],
  ["0","0","0","0","0"]
Output: 1
```

Here's how we can use DFS:

1. **Initialize** all **vertices** as unvisited.

0	Tor occle unvisited workey, performed DEC eleviting from the city ortox	
۷.	For each unvisited vertex , perform a DFS starting from that vertex	

3.	Mark all visited vertices as part of the same connected component as the starting vertex.

4.	Repeat steps 2-3 for any remaining unvisited vertices until all vertices have
	been visited.

After this process, the set of marked vertices for each DFS traversal will give you the **connected components** of the graph.

Visualization



count = 0

Call stack



Implementation

```
class Solution:
    def numIslands(self, grid: List[List[str]]) -> int:
       m, n= len(grid), len(grid[0])
       visited = set()
       direction = [(0,-1),(0,1),(-1,0),(1,0)]
       isValid = lambda row, col : 0 <= row < m and 0 <= col < n and (row, col) not in visited and grid[row][col] == "1"
       def dfs(row,col):
            visited.add((row, col))
            for dr in direction:
                new row, new col = row + dr[0], col + dr[1]
                if isValid(new row, new col):
                    dfs(new row, new col)
        ans = 0
       for i in range(m):
            for j in range(n):
                if isValid(i, j):
                    dfs(i,j)
                    ans += 1
```

return ans

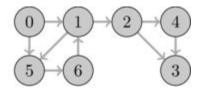
How can we detect cycles in directed

graph using dfs?

Cycle detection

- We will run a series of DFS in the graph.
- Initially all vertices are colored white (0)
- From each unvisited (white) vertex, start the DFS, mark it gray (1) while entering and mark it black (2) on exit
- If DFS moves to a gray vertex, then we have found a cycle

Visualization



- open node
- O closed node
- O unvisited node
- Current node
- \longrightarrow tree edge
- --> cross edge
- --> cycle edge
- --> forward edge
- \longrightarrow unvisited edge

starting dfs

Cycle detection

```
WHITE = 1
GRAY = 2
BLACK = 3
# By default all vertces are WHITE
color = {k: WHITE for k in range(num_nodes)}
is_possible = True
def dfs(node):
    nonlocal is_possible
   # Don't recurse further if we found a cycle already
   if not is possible:
        return
   # Start the recursion
    color[node] = GRAY
    # Traverse on neighboring vertices
   if node in adj_list:
        for neighbor in adj_list[node]:
           if color[neighbor] == WHITE:
                dfs(neighbor)
           elif color[neighbor] == GRAY:
               # An edge to a GRAY vertex represents a cycle
               is_possible = False
    # Recursion ends. We mark it as black
    color[node] = BLACK
```

Practice problem

Infinite loops: DFS can get stuck in an infinite loop if it encounters a cycle in the graph. To avoid this, it is important to keep track of visited nodes and avoid revisiting them.

Stack overflow & Exceeding Maximum Recursion Depth

- DFS uses a stack to keep track of nodes to visit. If the graph is very deep or has a large number of branches, the stack can become very large and cause a stack overflow.

 If you are using Python you are aware that the maximum recursion depth is around 1000, in some cases we might have more than 1000 nodes in our call stack in these cases we might be faced by maximum recursion depth exceeded error

 To fix the maximum recursion depth exceeded error we can manually increase the recursion limit.

 To fix the stack overflow error we can manually increase the stack size for our python program.
 Taken together it will look like the image on the right.

```
import sys, threading
def main():
    # your code goes here
sys.setrecursionlimit(1 << 30)
threading.stack size(1 << 27)
main thread = threading. Thread(target=main)
main thread.start()
main thread.join()
```

Choosing the wrong starting node: The output of DFS can depend on the starting node. If the starting node is not chosen carefully, it may not be possible to reach some nodes in the graph. It is important to consider the structure of the graph and the problem at hand when choosing the starting node.

Recap

Recap Points

- DFS Definition and Algorithm
- DFS Applications
- Visual: summary of DFS algorithm on a graph

Resources

GeeksForGeeks
Leetcode solution
Chat GPT

Practice Problems

Number-of-provinces ✓

Sum-of-nodes-with-even-valued-grandparent ✓

Max-area-of-island ✓

Evaluate-division ✓

Sum-root-to-leaf-numbers ✓

<u>Detonate-the-maximum-bombs</u> ✓

Surrounded-regions ✓

Minesweeper ✓

Lowest-common-ancestor-of-deepest-leaves ✓

recover-binary-search-tree

You have to write your own story, your own graph and rhythm.