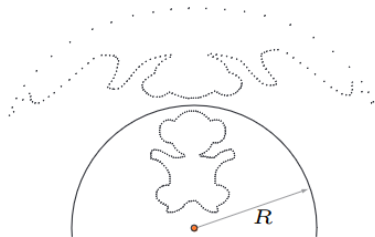
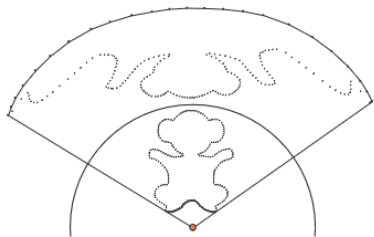


a) input PCD and viewpoint (in orange)



b) inverted pointset



c) convex hull



d) estimated visible points (in blue)