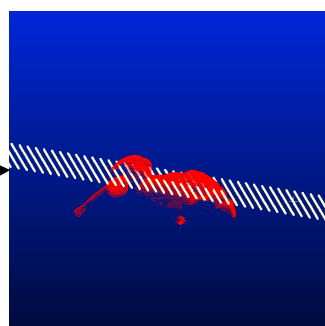
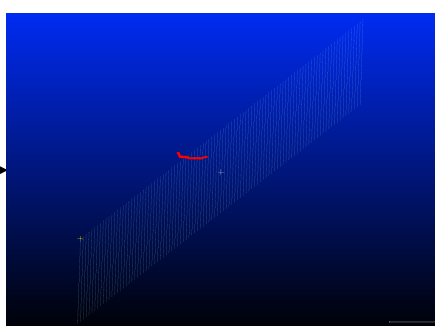


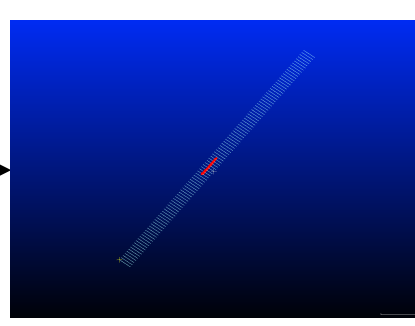
(a)



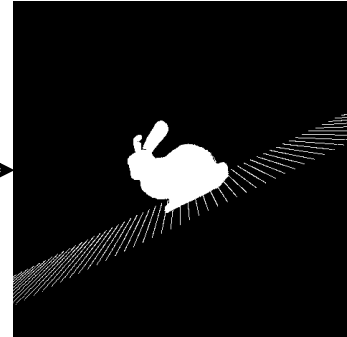
(b)



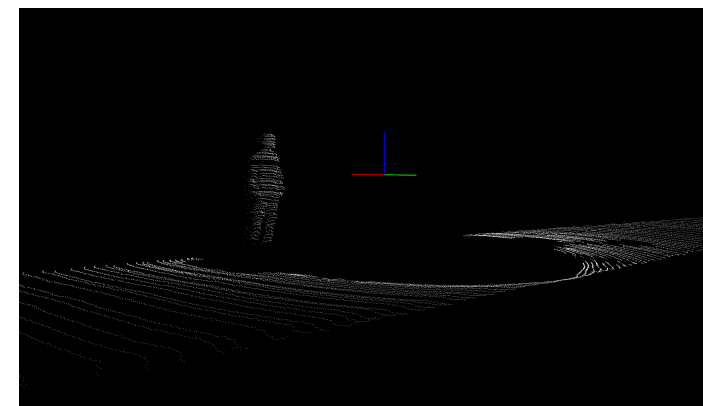
(c)



(d)

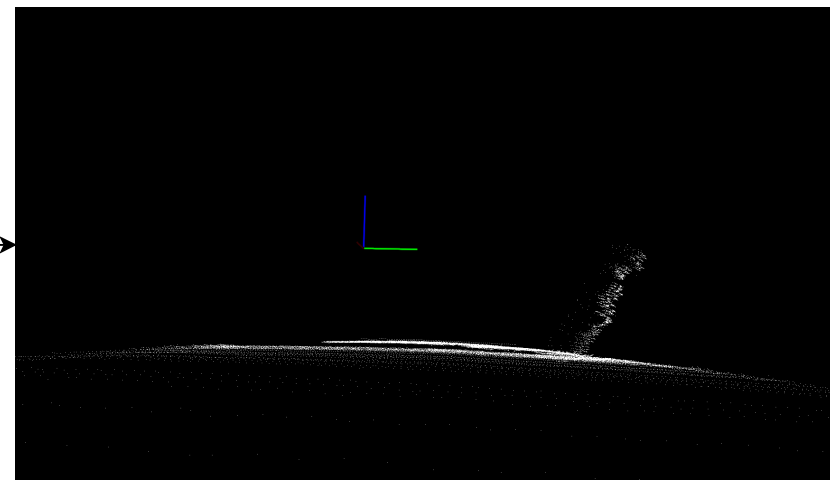


(e)



(f)

Subsampling points with lower z-values, performing ICP registration of sub-sampled points with target plane to find transformation matrix and transforming the complete point cloud



(g)