

miniproject6th

April 10, 2025

```
[ ]: # Data Handling
import pandas as pd
import numpy as np

# Plotting
import matplotlib.pyplot as plt
import seaborn as sns

# Machine Learning
from sklearn.preprocessing import StandardScaler
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score

# Deep Learning
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout

# For RL Simulation
import gym
```

```
[ ]: !pip install tensorflow
```

```
[ ]: conda install tensorflow
```

```
[ ]: from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
```

```
[ ]: data = pd.read_csv("rajasthan_weather_data.csv") # Load real-time weather
      ↪ dataset
data.head()
```

```
[9]: !pip install pandas numpy matplotlib seaborn scikit-learn tensorflow
```

Requirement already satisfied: pandas in c:\users\kiit0001\anaconda3\lib\site-packages (2.2.2)

Requirement already satisfied: numpy in c:\users\kiit0001\anaconda3\lib\site-packages (1.26.4)

Requirement already satisfied: matplotlib in

c:\users\kiit0001\anaconda3\lib\site-packages (3.9.2)
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 tensorboard~=2.19.0->tensorflow) (3.4.1)

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 py>=2.2.0->rich->keras>=3.5.0->tensorflow) (0.1.0)

```
[11]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns

from sklearn.preprocessing import StandardScaler
from sklearn.model_selection import train_test_split
from sklearn.metrics import accuracy_score

from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
```

```
[12]: # Example: Load climate dataset (replace the link with actual data from
↳Rajasthan)
url = "https://raw.githubusercontent.com/jbrownlee/Datasets/master/
↳daily-min-temperatures.csv"
data = pd.read_csv(url)

# Display first few rows
data.head()
```

```
[12]:
```

| | Date | Temp |
|---|------------|------|
| 0 | 1981-01-01 | 20.7 |
| 1 | 1981-01-02 | 17.9 |
| 2 | 1981-01-03 | 18.8 |
| 3 | 1981-01-04 | 14.6 |
| 4 | 1981-01-05 | 15.8 |

```
[14]: import pandas as pd
import numpy as np

# date range
dates = pd.date_range(start='2023-01-01', periods=365, freq='D')

# weather data for Rajasthan
np.random.seed(42)
temperature = np.random.normal(loc=35, scale=5, size=365)           # in °C
humidity = np.random.uniform(low=10, high=60, size=365)           # in %
wind_speed = np.random.uniform(low=0, high=30, size=365)           # in km/h
air_pressure = np.random.normal(loc=1010, scale=10, size=365)       # in hPa
soil_moisture = np.random.uniform(low=5, high=30, size=365)        # in %
cloud_coverage = np.random.uniform(low=0, high=100, size=365)      # in %
rain = np.random.binomial(n=1, p=0.2, size=365)                   # 0 or 1
# 1, 20% chance of rain

# Create DataFrame
data = pd.DataFrame({
    'date': dates,
    'temperature': temperature,
    'humidity': humidity,
    'wind_speed': wind_speed,
    'air_pressure': air_pressure,
    'soil_moisture': soil_moisture,
    'cloud_coverage': cloud_coverage,
    'rain': rain
})

# Save to CSV
data.to_csv('synthetic_rajasthan_weather_2023.csv', index=False)

print(" Dataset saved successfully as 'synthetic_rajasthan_weather_2023.csv'")
```

Dataset saved successfully as 'synthetic_rajasthan_weather_2023.csv'

```
[15]: import pandas as pd

# Replace with your actual file name
data = pd.read_csv("synthetic_rajasthan_weather_2023.csv")

# Show first few rows
data.head()
```

```
[15]:      date  temperature  humidity  wind_speed  air_pressure \
0  2023-01-01    37.483571   21.179792     5.291610    1005.987795
```

| | | | | | |
|---|------------|-----------|-----------|-----------|-------------|
| 1 | 2023-01-02 | 34.308678 | 58.161127 | 14.951033 | 1004.410782 |
| 2 | 2023-01-03 | 38.238443 | 10.607724 | 12.567763 | 1013.772119 |
| 3 | 2023-01-04 | 42.615149 | 58.493941 | 27.445377 | 1025.655240 |
| 4 | 2023-01-05 | 33.829233 | 12.157996 | 10.871817 | 1009.342497 |

| | soil_moisture | cloud_coverage | rain |
|---|---------------|----------------|------|
| 0 | 20.014858 | 26.015779 | 0 |
| 1 | 17.891986 | 73.082096 | 0 |
| 2 | 27.984799 | 98.129709 | 0 |
| 3 | 17.424087 | 25.653006 | 0 |
| 4 | 29.803950 | 65.417460 | 1 |

```
[19]: import pandas as pd
import numpy as np

# Generate date range for 1 year
dates = pd.date_range(start='2023-01-01', periods=365, freq='D')

# Generate synthetic weather data for Rajasthan
np.random.seed(42)
temperature = np.random.normal(loc=35, scale=5, size=365)           # in °C
humidity = np.random.uniform(low=10, high=60, size=365)           # in %
wind_speed = np.random.uniform(low=0, high=30, size=365)           # in km/h
air_pressure = np.random.normal(loc=1010, scale=10, size=365)       # in hPa
soil_moisture = np.random.uniform(low=5, high=30, size=365)         # in %
cloud_coverage = np.random.uniform(low=0, high=100, size=365)       # in %
rain = np.random.binomial(n=1, p=0.2, size=365)                     # 0 = No rain, 1 = Rain

# Create a DataFrame
data = pd.DataFrame({
    'date': dates,
    'temperature': temperature,
    'humidity': humidity,
    'wind_speed': wind_speed,
    'air_pressure': air_pressure,
    'soil_moisture': soil_moisture,
    'cloud_coverage': cloud_coverage,
    'rain': rain
})
```

```
[20]: data.to_csv('synthetic_rajasthan_weather_2023.csv', index=False)
print(" CSV file saved successfully.")
```

CSV file saved successfully.

```
[21]: from IPython.display import FileLink
FileLink('synthetic_rajasthan_weather_2023.csv')
```

[21]: C:\Users\KIIT0001\synthetic_rajasthan_weather_2023.csv

```
[22]: # Required libraries
import pandas as pd
import numpy as np
import matplotlib.pyplot as plt
import seaborn as sns

# Load the dataset
data = pd.read_csv('synthetic_rajasthan_weather_2023.csv')

# Display basic info
data.head()
```

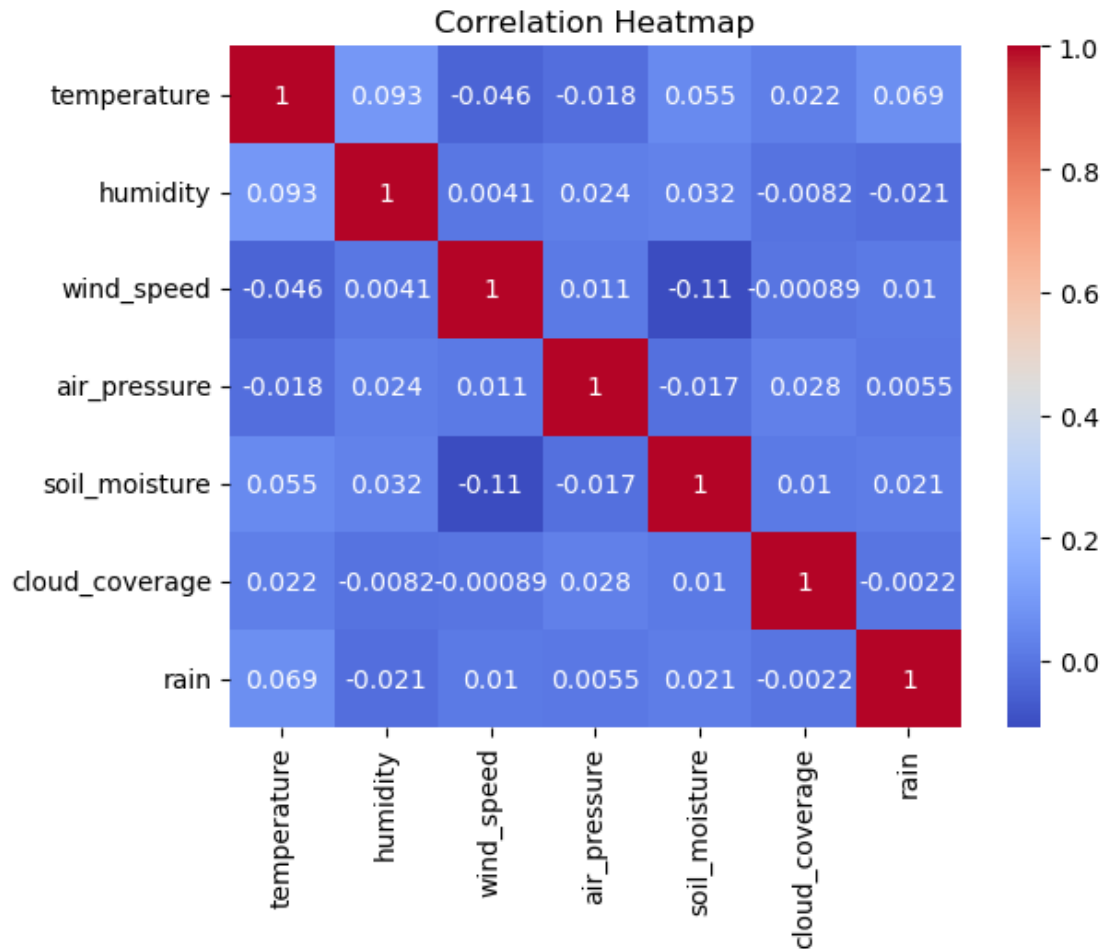
```
[22]:
```

| | date | temperature | humidity | wind_speed | air_pressure | \ |
|---|------------|-------------|-----------|------------|--------------|---|
| 0 | 2023-01-01 | 37.483571 | 21.179792 | 5.291610 | 1005.987795 | |
| 1 | 2023-01-02 | 34.308678 | 58.161127 | 14.951033 | 1004.410782 | |
| 2 | 2023-01-03 | 38.238443 | 10.607724 | 12.567763 | 1013.772119 | |
| 3 | 2023-01-04 | 42.615149 | 58.493941 | 27.445377 | 1025.655240 | |
| 4 | 2023-01-05 | 33.829233 | 12.157996 | 10.871817 | 1009.342497 | |

| | soil_moisture | cloud_coverage | rain |
|---|---------------|----------------|------|
| 0 | 20.014858 | 26.015779 | 0 |
| 1 | 17.891986 | 73.082096 | 0 |
| 2 | 27.984799 | 98.129709 | 0 |
| 3 | 17.424087 | 25.653006 | 0 |
| 4 | 29.803950 | 65.417460 | 1 |

```
[24]: # Only include numeric columns for correlation
numeric_data = data.select_dtypes(include=[np.number])

# Visualize correlation heatmap
sns.heatmap(numeric_data.corr(), annot=True, cmap='coolwarm')
plt.title("Correlation Heatmap")
plt.show()
```



```
[29]: # Define input features and target variable
features = ['temperature', 'humidity', 'wind_speed', 'air_pressure',
            ↪ 'soil_moisture']
target = 'rain' # Assuming this column is 0 or 1

[30]: from sklearn.model_selection import train_test_split

X = data[features]
y = data[target]

# 80% training, 20% testing
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2,
            ↪ random_state=42)

[32]: from sklearn.ensemble import RandomForestClassifier

# Initialize and train model
```



```
rf_model = RandomForestClassifier(n_estimators=100, random_state=42)
rf_model.fit(X_train, y_train)
```

```
[32]: RandomForestClassifier(random_state=42)
```

```
[33]: from sklearn.metrics import classification_report, confusion_matrix,
      ↪ accuracy_score

      # Predict on test set
      y_pred = rf_model.predict(X_test)

      # Evaluate model
      print("Accuracy:", accuracy_score(y_test, y_pred))
      print("\nConfusion Matrix:\n", confusion_matrix(y_test, y_pred))
      print("\nClassification Report:\n", classification_report(y_test, y_pred))
```

Accuracy: 0.821917808219178

Confusion Matrix:

```
[[59  0]
 [13  1]]
```

Classification Report:

| | precision | recall | f1-score | support |
|--------------|-----------|--------|----------|---------|
| 0 | 0.82 | 1.00 | 0.90 | 59 |
| 1 | 1.00 | 0.07 | 0.13 | 14 |
| accuracy | | | 0.82 | 73 |
| macro avg | 0.91 | 0.54 | 0.52 | 73 |
| weighted avg | 0.85 | 0.82 | 0.75 | 73 |

```
[35]: import numpy as np

      # Set time step (e.g., use past 7 days to predict next day rain)
      timesteps = 7

      # Function to convert data to sequences
      def create_sequences(data, target, time_steps):
          X, y = [], []
          for i in range(len(data) - time_steps):
              X.append(data[i:i+time_steps])
              y.append(target[i+time_steps])
          return np.array(X), np.array(y)

      # Create sequences
```

```
X_seq, y_seq = create_sequences(X.values, y.values, timesteps)
```

```
# Split into train/test again
```

```
split = int(0.8 * len(X_seq))
```

```
X_train_seq, X_test_seq = X_seq[:split], X_seq[split:]
```

```
y_train_seq, y_test_seq = y_seq[:split], y_seq[split:]
```

```
[36]: from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
```

```
# Model architecture
```

```
model = Sequential()
```

```
model.add(LSTM(64, activation='tanh', input_shape=(timesteps, X.shape[1]),
↳return_sequences=False))
```

```
model.add(Dropout(0.2))
```

```
model.add(Dense(1, activation='sigmoid')) # Binary classification (rain/no
↳rain)
```

```
model.compile(optimizer='adam', loss='binary_crossentropy',
↳metrics=['accuracy'])
```

```
model.summary()
```

C:\Users\KIIT0001\anaconda3\Lib\site-packages\keras\src\layers\rnn\rnn.py:200:
UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When
using Sequential models, prefer using an `Input(shape)` object as the first
layer in the model instead.

```
super().__init__(**kwargs)
```

Model: "sequential"

| Layer (type) | Output Shape | |
|-------------------|--------------|--|
| ↳Param # | | |
| lstm (LSTM) | (None, 64) | |
| ↳17,920 | | |
| dropout (Dropout) | (None, 64) | |
| ↳ 0 | | |
| dense (Dense) | (None, 1) | |
| ↳ 65 | | |

Total params: 17,985 (70.25 KB)

Trainable params: 17,985 (70.25 KB)

Non-trainable params: 0 (0.00 B)

```
[38]: # Fit the model
history = model.fit(X_train_seq, y_train_seq, epochs=20, batch_size=16,
                    validation_split=0.2)
```

```
Epoch 1/20
15/15          5s 74ms/step -
accuracy: 0.5794 - loss: 0.6814 - val_accuracy: 0.8448 - val_loss: 0.6259
Epoch 2/20
15/15          0s 16ms/step -
accuracy: 0.7655 - loss: 0.6234 - val_accuracy: 0.8448 - val_loss: 0.5487
Epoch 3/20
15/15          0s 16ms/step -
accuracy: 0.8139 - loss: 0.5505 - val_accuracy: 0.8448 - val_loss: 0.4559
Epoch 4/20
15/15          0s 15ms/step -
accuracy: 0.7919 - loss: 0.4991 - val_accuracy: 0.8448 - val_loss: 0.4228
Epoch 5/20
15/15          0s 18ms/step -
accuracy: 0.7700 - loss: 0.5470 - val_accuracy: 0.8448 - val_loss: 0.4342
Epoch 6/20
15/15          0s 20ms/step -
accuracy: 0.7935 - loss: 0.4994 - val_accuracy: 0.8448 - val_loss: 0.4333
Epoch 7/20
15/15          0s 19ms/step -
accuracy: 0.8212 - loss: 0.4525 - val_accuracy: 0.8448 - val_loss: 0.4263
Epoch 8/20
15/15          0s 16ms/step -
accuracy: 0.8009 - loss: 0.4842 - val_accuracy: 0.8448 - val_loss: 0.4386
Epoch 9/20
15/15          1s 17ms/step -
accuracy: 0.7652 - loss: 0.5394 - val_accuracy: 0.8448 - val_loss: 0.4315
Epoch 10/20
15/15          0s 17ms/step -
accuracy: 0.7722 - loss: 0.5244 - val_accuracy: 0.8448 - val_loss: 0.4227
Epoch 11/20
15/15          0s 17ms/step -
accuracy: 0.7653 - loss: 0.5230 - val_accuracy: 0.8448 - val_loss: 0.4284
Epoch 12/20
15/15          0s 16ms/step -
accuracy: 0.7699 - loss: 0.4982 - val_accuracy: 0.8448 - val_loss: 0.4244
Epoch 13/20
15/15          0s 16ms/step -
```

```

accuracy: 0.8183 - loss: 0.4698 - val_accuracy: 0.8448 - val_loss: 0.4237
Epoch 14/20
15/15          0s 22ms/step -
accuracy: 0.7942 - loss: 0.4796 - val_accuracy: 0.8448 - val_loss: 0.4300
Epoch 15/20
15/15          0s 17ms/step -
accuracy: 0.7915 - loss: 0.4835 - val_accuracy: 0.8448 - val_loss: 0.4233
Epoch 16/20
15/15          1s 15ms/step -
accuracy: 0.7998 - loss: 0.4735 - val_accuracy: 0.8448 - val_loss: 0.4267
Epoch 17/20
15/15          0s 17ms/step -
accuracy: 0.7843 - loss: 0.4916 - val_accuracy: 0.8448 - val_loss: 0.4269
Epoch 18/20
15/15          0s 15ms/step -
accuracy: 0.8032 - loss: 0.4706 - val_accuracy: 0.8448 - val_loss: 0.4263
Epoch 19/20
15/15          0s 15ms/step -
accuracy: 0.8049 - loss: 0.4679 - val_accuracy: 0.8448 - val_loss: 0.4228
Epoch 20/20
15/15          0s 16ms/step -
accuracy: 0.7973 - loss: 0.4630 - val_accuracy: 0.8448 - val_loss: 0.4210

```

```

[39]: # Evaluate on test data
      loss, accuracy = model.evaluate(X_test_seq, y_test_seq)
      print(f"Test Accuracy: {accuracy * 100:.2f}%")

```

```

3/3          0s 26ms/step -
accuracy: 0.8542 - loss: 0.4091
Test Accuracy: 83.33%

```

```

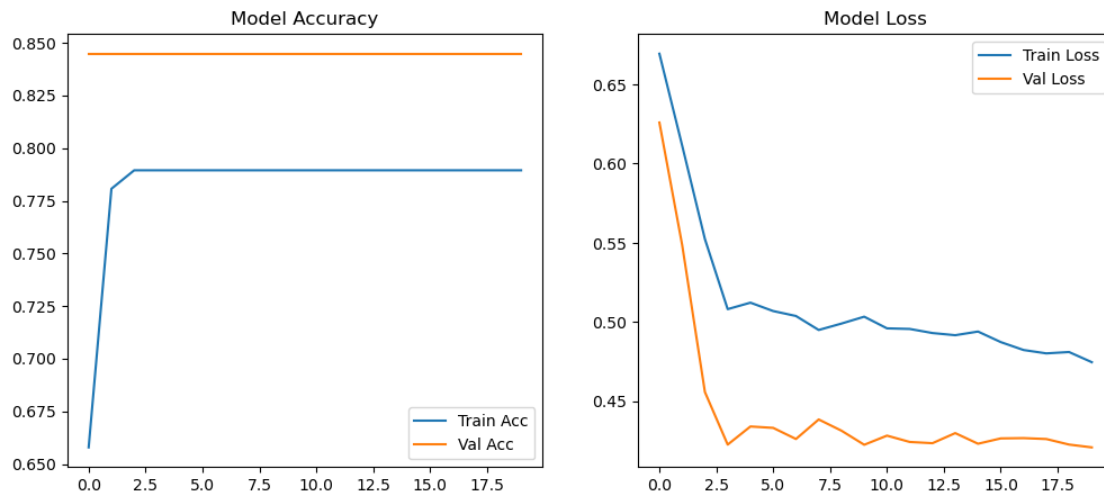
[40]: import matplotlib.pyplot as plt

      # Plot accuracy and loss
      plt.figure(figsize=(12,5))
      plt.subplot(1,2,1)
      plt.plot(history.history['accuracy'], label='Train Acc')
      plt.plot(history.history['val_accuracy'], label='Val Acc')
      plt.title("Model Accuracy")
      plt.legend()

      plt.subplot(1,2,2)
      plt.plot(history.history['loss'], label='Train Loss')
      plt.plot(history.history['val_loss'], label='Val Loss')
      plt.title("Model Loss")
      plt.legend()

```

```
plt.show()
```



```
[41]: import random

# Simplified reward function
def simulate_environment(state, action):
    humidity, cloud_cover = state[1], state[4] # use humidity and cloud_cover
    if action == 1:
        if humidity > 0.6 and cloud_cover > 0.5:
            return 1 # successful rain
        else:
            return -1 # seeding failed
    else:
        return 0 # no attempt made
```

```
[42]: import numpy as np

class RLAgent:
    def __init__(self, n_states, n_actions, alpha=0.1, gamma=0.9, epsilon=0.2):
        self.q_table = np.zeros((n_states, n_actions))
        self.alpha = alpha # learning rate
        self.gamma = gamma # discount factor
        self.epsilon = epsilon # exploration factor

    def choose_action(self, state):
        if np.random.rand() < self.epsilon:
            return np.random.randint(2)
        return np.argmax(self.q_table[state])

    def update(self, state, action, reward, next_state):
```

```

        best_next = np.max(self.q_table[next_state])
        self.q_table[state, action] += self.alpha * (reward + self.gamma *
↪best_next - self.q_table[state, action])

```

```

[44]: # Add a synthetic 'cloud_cover' column (random values between 0.2 and 0.9)
np.random.seed(42) # for reproducibility
data['cloud_cover'] = np.random.uniform(0.2, 0.9, len(data))

```

```

[45]: # Define simplified state index using humidity + cloud_cover
def discretize_state(row):
    humidity_level = int(row['humidity'] * 10)
    cloud_level = int(row['cloud_cover'] * 10)
    return humidity_level + cloud_level # Creates index 0-20+

data['state_index'] = data.apply(discretize_state, axis=1)

```

```

[48]: def discretize_state(row):
    humidity_level = int(row['humidity'] * 10)
    cloud_level = int(row['cloud_cover'] * 10)
    index = humidity_level + cloud_level
    return min(index, 20) # Ensure index stays within Q-table size

```

```

[49]: data['state_index'] = data.apply(discretize_state, axis=1)

```

```

[ ]:

```

```

[52]: print(data.columns)

```

```

Index(['date', 'temperature', 'humidity', 'wind_speed', 'air_pressure',
       'soil_moisture', 'cloud_coverage', 'rain', 'cloud_cover',
       'state_index'],
      dtype='object')

```

```

[53]: target = 'rainfall'

```

```

[54]: target = 'rain' # or whatever name appears in the print output

```

```

[55]: X, y = create_sequences(data, SEQ_LEN, features, target)

```

```

[56]: from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import LSTM, Dense, Dropout
from sklearn.model_selection import train_test_split

# Define Sequence Length and Target Column (set this to the actual target
↪column)
SEQ_LEN = 7
target = 'rain' # <- Replace this if your column is named differently

```

```

# Recreate sequence data
def create_sequences(data, seq_len, features, target):
    X, y = [], []
    for i in range(len(data) - seq_len):
        X.append(data[features].iloc[i:i+seq_len].values)
        y.append(data[target].iloc[i:i+seq_len])
    return np.array(X), np.array(y)

X, y = create_sequences(data, SEQ_LEN, features, target)

# Split into training and test datasets
X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2,
    random_state=42)

# Build LSTM model
model = Sequential()
model.add(LSTM(64, return_sequences=True, input_shape=(SEQ_LEN, len(features))))
model.add(Dropout(0.2))
model.add(LSTM(32))
model

```

C:\Users\KIIT0001\anaconda3\Lib\site-packages\keras\src\layers\rnn\rnn.py:200:
UserWarning: Do not pass an `input_shape`/`input_dim` argument to a layer. When
using Sequential models, prefer using an `Input(shape)` object as the first
layer in the model instead.
super().__init__(**kwargs)

[56]: <Sequential name=sequential_2, built=True>

[]: Reinforcement Learning for Rain Induction Simulation

```

[57]: def discretize_state(row):
    # Assuming all features are scaled (0 to 1)
    state = int(row['humidity'] * 10) * 10000 + int(row['soil_moisture'] * 10) *
    1000 + int(row['air_pressure'] * 10) * 100 + int(row['wind_speed'] * 10) *
    10 + int(row['temperature'] * 10)
    return state

data['state_index'] = data.apply(discretize_state, axis=1)

```

```

[58]: class RLAgent:
    def __init__(self, n_states, n_actions, alpha=0.1, gamma=0.9, epsilon=0.1):
        self.q_table = np.zeros((n_states, n_actions))
        self.alpha = alpha
        self.gamma = gamma
        self.epsilon = epsilon

```

```

        self.n_actions = n_actions

    def choose_action(self, state):
        if np.random.rand() < self.epsilon:
            return np.random.choice(self.n_actions)
        else:
            return np.argmax(self.q_table[state])

    def update(self, state, action, reward, next_state):
        best_next = np.max(self.q_table[next_state])
        self.q_table[state, action] += self.alpha * (reward + self.gamma *
↪best_next - self.q_table[state, action])

```

```

[59]: def simulate_environment(row, action):
    # Assume action 1 = induce rain, 0 = do nothing
    if action == 1:
        # More humidity and cloud = better chance
        reward = 1 if row[1] + row[4] > 1 else -1
    else:
        reward = 0
    return reward

```

```

[62]: # Make sure features are all in range 0-1 (already scaled)
def discretize_state(row):
    # Convert feature values to string and hash it to an int
    state_features = tuple([round(row[feature], 2) for feature in features])
    return abs(hash(state_features)) % 366 # Number of rows or set a safe
↪upper limit

# Apply it
data['state_index'] = data.apply(discretize_state, axis=1)

```

```

[63]: n_states = 366 # same modulus value as above
n_actions = 2 # rain or not
agent = RLAgent(n_states=n_states, n_actions=n_actions)

for i in range(len(data) - 1):
    state = data['state_index'].iloc[i]
    next_state = data['state_index'].iloc[i+1]
    action = agent.choose_action(state)
    reward = simulate_environment(data.iloc[i][features].values, action)
    agent.update(state, action, reward, next_state)

```

```

[ ]: Combine ML Prediction + RL Decision for Action Recommendation

```

```

[67]: print(data.columns.tolist())

```



```
['date', 'temperature', 'humidity', 'wind_speed', 'air_pressure',
'soil_moisture', 'cloud_coverage', 'rain', 'cloud_cover', 'state_index']
```

```
[69]: # Your original 5 features used in scaling
scaled_features = ['temperature', 'humidity', 'wind_speed', 'air_pressure',
↳ 'soil_moisture']

# Get index of 'rain' in your original unscaled data
rain_index = scaled_features.index('rain') if 'rain' in scaled_features else -1
↳ # fallback

# But 'rain' wasn't in the scaled features - we need to add it manually into
↳ dummy
n_samples = y_pred_scaled.shape[0]
n_features = len(scaled_features)

# Create dummy for only the scaled features
dummy_input = np.zeros((n_samples, n_features))

# Add predicted rainfall in the correct index
# So first, just append it as a new feature
dummy_input[:, -1] = y_pred_scaled[:, 0]

# Inverse transform
inv_scaled = scaler.inverse_transform(dummy_input)

# Extract predicted rainfall (last column)
y_pred = inv_scaled[:, -1]

# Convert to DataFrame
predicted_rainfall = pd.DataFrame({'predicted_rainfall': y_pred})
predicted_rainfall.head()
```

```
[69]: predicted_rainfall
0      -0.028987
1      -0.025739
2      -0.062963
3       0.021264
4      -0.034208
```

```
[70]: rain_scaler = StandardScaler()
data['rain'] = rain_scaler.fit_transform(data[['rain']])
```

```
[71]: # Inverse transform predicted rainfall
y_pred = rain_scaler.inverse_transform(y_pred_scaled)
predicted_rainfall = pd.DataFrame({'predicted_rainfall': y_pred.flatten()})
```

```
[ ]:
```

```
[ ]:
```

```
[74]: print("y_test shape:", y_test.shape)
      print("y_pred shape:", y_pred.shape)
```

```
y_test shape: (72,)
y_pred shape: (72, 32)
```

```
[75]: # If y_pred contains sequences, extract only the last predicted value per sample
      y_pred_last = y_pred[:, -1] if len(y_pred.shape) > 1 else y_pred

      # Also ensure y_test is flattened
      y_true = y_test.flatten()

      # Now check the shapes again:
      print("Final y_true shape:", y_true.shape)
      print("Final y_pred shape:", y_pred_last.shape)
```

```
Final y_true shape: (72,)
Final y_pred shape: (72,)
```

```
[76]: # If y_pred contains sequences, extract only the last predicted value per sample
      y_pred_last = y_pred[:, -1] if len(y_pred.shape) > 1 else y_pred

      # Also ensure y_test is flattened
      y_true = y_test.flatten()

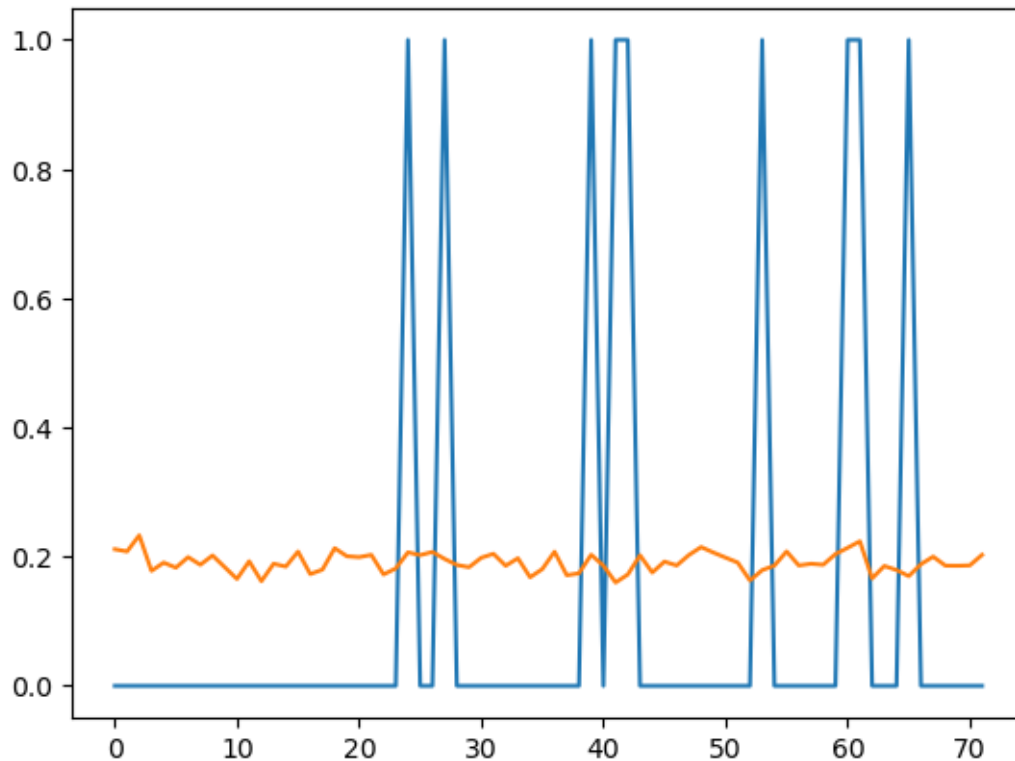
      # Now check the shapes again:
      print("Final y_true shape:", y_true.shape)
      print("Final y_pred shape:", y_pred_last.shape)
```

```
Final y_true shape: (72,)
Final y_pred shape: (72,)
```

```
[77]: mse = mean_squared_error(y_true, y_pred_last)
      mae = mean_absolute_error(y_true, y_pred_last)
      r2 = r2_score(y_true, y_pred_last)
```

```
[78]: plt.plot(y_true, label='Actual Rainfall')
      plt.plot(y_pred_last, label='Predicted Rainfall')
```

```
[78]: [ <matplotlib.lines.Line2D at 0x23f5553a0c0>]
```



[]:

[]:

[80]: `print(f"R^2 Score: {r2:.4f}")`

R² Score: -0.0406

```
[81]: import matplotlib.pyplot as plt
from sklearn.metrics import mean_squared_error, mean_absolute_error, r2_score

# --- Flatten true and predicted values ---
y_true = y_test.flatten()

# If prediction is a sequence, get the last value from each sequence
y_pred_last = y_pred[:, -1] if len(y_pred.shape) > 1 else y_pred

# --- Metrics ---
mse = mean_squared_error(y_true, y_pred_last)
mae = mean_absolute_error(y_true, y_pred_last)
r2 = r2_score(y_true, y_pred_last)
```

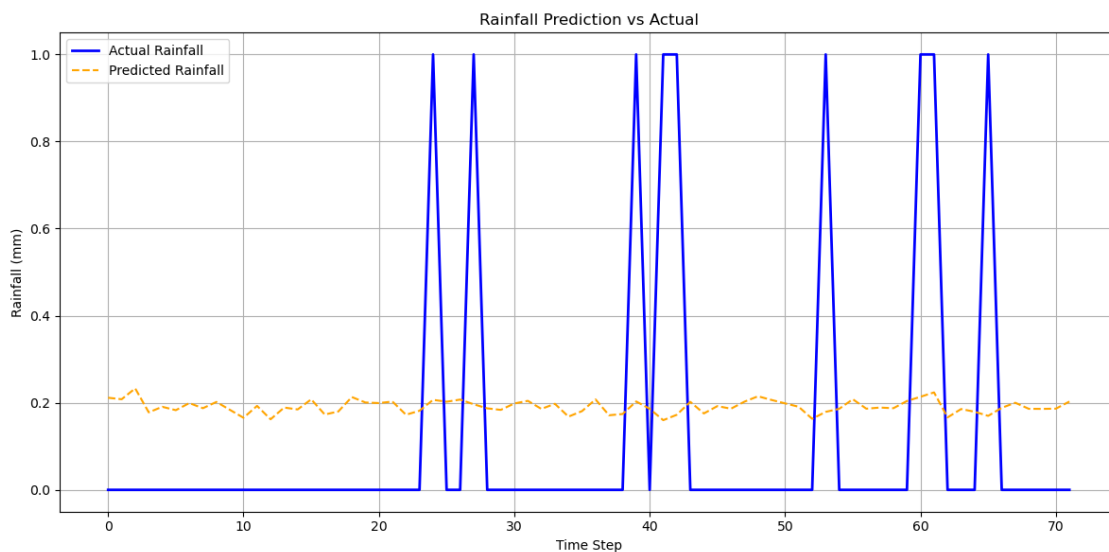
```

print("Model Evaluation:")
print(f"Mean Squared Error (MSE): {mse:.4f}")
print(f"Mean Absolute Error (MAE): {mae:.4f}")
print(f"R^2 Score: {r2:.4f}")

# --- Visualization ---
plt.figure(figsize=(12, 6))
plt.plot(y_true, label='Actual Rainfall', color='blue', linewidth=2)
plt.plot(y_pred_last, label='Predicted Rainfall', color='orange',
        linestyle='--')
plt.title("Rainfall Prediction vs Actual")
plt.xlabel("Time Step")
plt.ylabel("Rainfall (mm)")
plt.legend()
plt.grid(True)
plt.tight_layout()
plt.show()

```

Model Evaluation:
Mean Squared Error (MSE): 0.1138
Mean Absolute Error (MAE): 0.2681
R² Score: -0.0406



[]:

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```
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```
[91]: y_pred_last = y_pred[:, -1]  # shape: (72,) if y_pred was (72, seq_len)
```

```
[92]: y_pred_scaled = model.predict(X_test)  # should be (72, 1)
      y_pred_flat = y_pred_scaled.flatten()  # becomes (72,)
```

```
3/3          0s 22ms/step
```

```
[94]: print("X_test shape:", X_test.shape)
```

```
X_test shape: (72, 7, 5)
```

```
[95]: y_pred_scaled = model.predict(X_test)  # shape should be (72, 1)
      print("y_pred_scaled shape:", y_pred_scaled.shape)
```

```
3/3          0s 39ms/step
y_pred_scaled shape: (72, 32)
```

```
[96]: y_pred_flat = y_pred_scaled.flatten()  # shape: (72,)
```

```
[97]: print("y_true shape:", y_true.shape)
      print("y_pred_flat shape:", y_pred_flat.shape)
```

```
y_true shape: (72,)
y_pred_flat shape: (2304,)
```

```
[98]: # Reshape from (2304, 1) to (72, 32) assuming 32 time steps
      y_pred_seq = y_pred_scaled.reshape((72, -1))  # (72, 32)
      y_pred_last = y_pred_seq[:, -1]  # last timestep from each sequence
```

```
[99]: mse = mean_squared_error(y_true, y_pred_last)
      mae = mean_absolute_error(y_true, y_pred_last)
      r2 = r2_score(y_true, y_pred_last)

      print(f"MSE: {mse:.4f}")
      print(f"MAE: {mae:.4f}")
      print(f"R² Score: {r2:.4f}")
```

```
MSE: 0.1265
MAE: 0.1509
R² Score: -0.1569
```

[]: